

Laser Beam Welding for in-Space Joining Demonstrated Under Vacuum on the Ground and By Parabolic Flight Experiments

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The Ohio State University

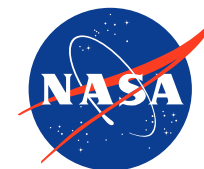
W. Evans, A. O'Connor, Z. Courtright, J.W. Sowards

NASA Marshall Space Flight Center

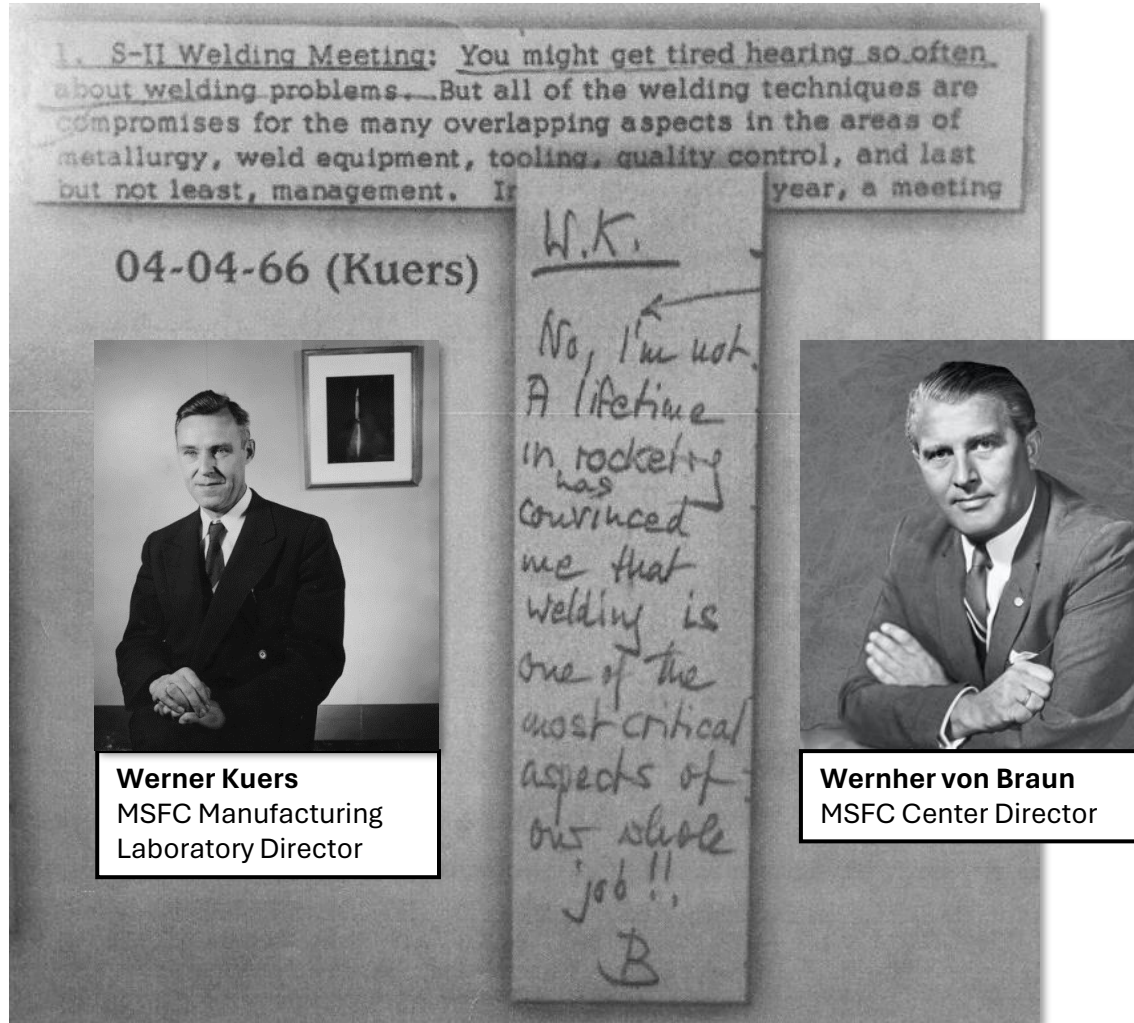


THE OHIO STATE UNIVERSITY

COLLEGE OF ENGINEERING



Welding enables space exploration



Werner Kuers
MSFC Manufacturing
Laboratory Director

Wernher von Braun
MSFC Center Director

“The complexity of welding is readily apparent when one considers that fusion welding involves temperature gradients of thousands of degrees, over distances of less than a centimeter, occurring on a time scale of seconds, involving multiple phases of solids, liquids, gases, and plasma.”

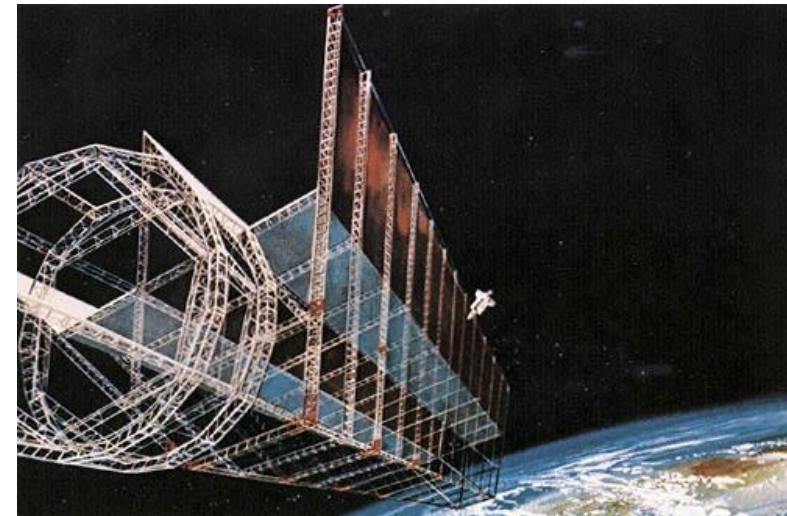
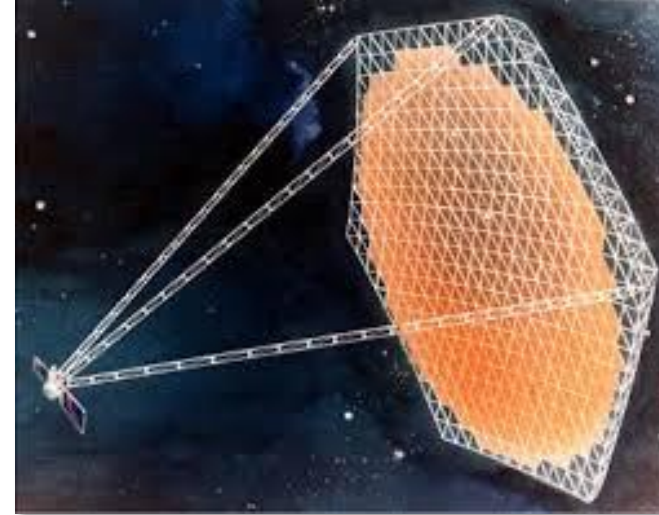
Thomas Eagar, MIT, 1990

Quoted in North, Ed., *Advanced joining technologies: proceedings of the International Institute of Welding Congress on Joining Research*, 1990.

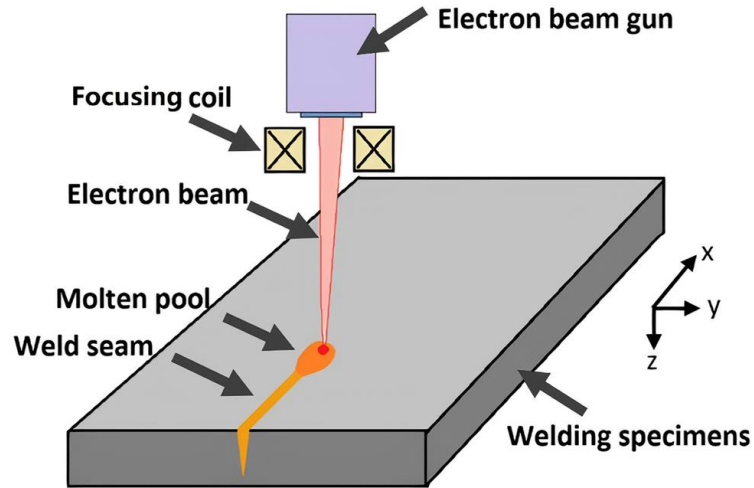
1966 correspondence between Wernher von Braun and Werner Kuers

Why welding in space?

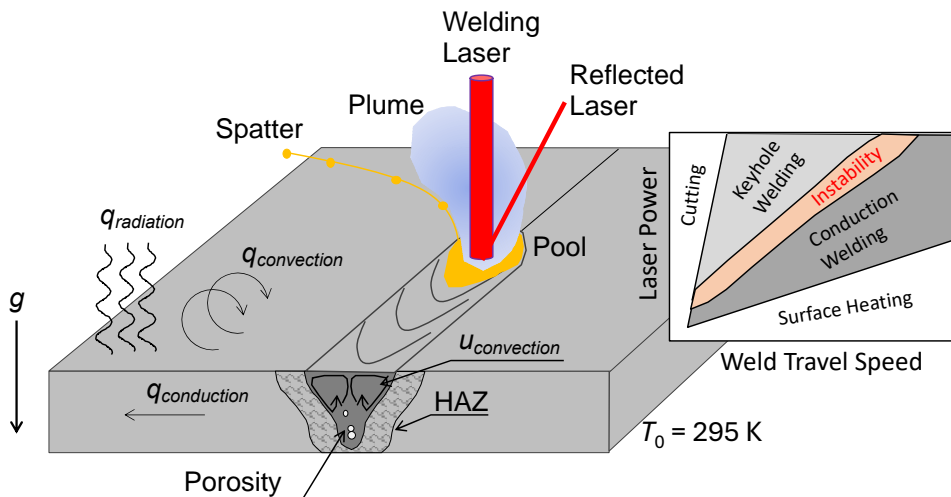
Method → ↓ Criteria	Fasteners/ rivets	In-Space Welding (ISW)
Joint strength & rigidity	⊖	○
Joint hermeticity	●	○
Joint mass	●	○
Joint design & manufacturing simplicity	⊖	○
Joint reliability	⊖	○
Repair versatility	●	○
Associated cost & upmass	⊖	○
● - Poor	⊖ - Satisfactory	○ - Good



Why laser beam welding in space?



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High-energy Beam Process → ↓ Criteria	Electron	Laser	Status
IVA flexibility (e.g. in habitat) & EVA flexibility (e.g. in vacuum, Lunar surface, on Mars)	●	○	Capability available after planned development
Workpiece variety (e.g. geometry, material)	◐	○	
Suitable for operation on end effector of robotic arm (e.g. EMI, mass, power delivery, heat rejection)	●	○	
Compatible with inspection tools & able to repair welds	●	○	
Power requirements & energy efficiency	○	◐	Commercial lasers
Suitable for additive manufacturing	◐	○	Future work (GCD, etc.)
Perform subtractive manufacturing – cutting, drilling, etc.	●	○	
Capable of bending/forming structures	●	○	
● - Poor ◐ - Satisfactory ○ - Good			

Timeline of in-space joining

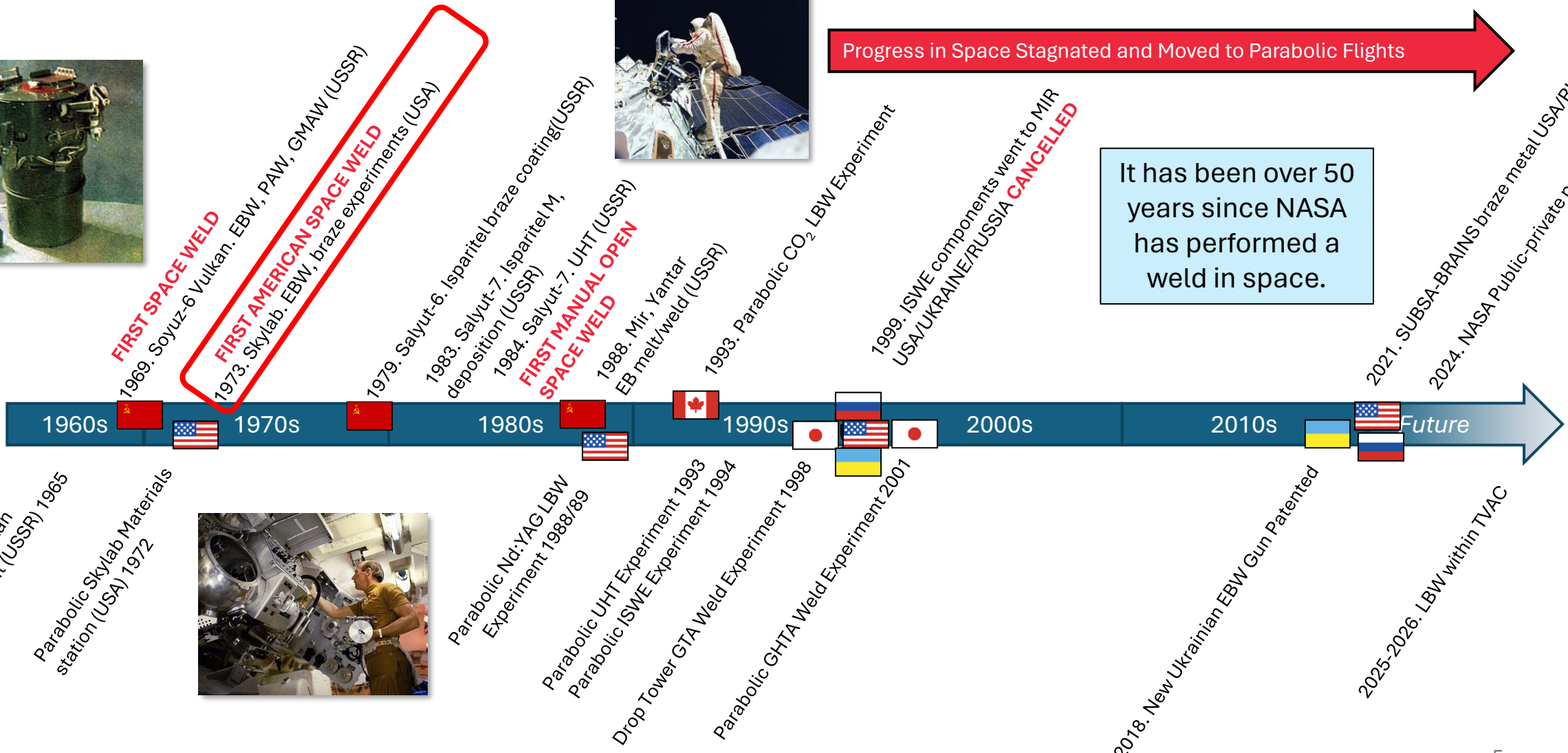


FIRST SPACE WELD
1969. Soyuz-6 Vulkan. EBW, PAW, GMAW (USSR)

FIRST AMERICAN SPACE WELD
1973. Skylab. EBW, braze experiments (USA)

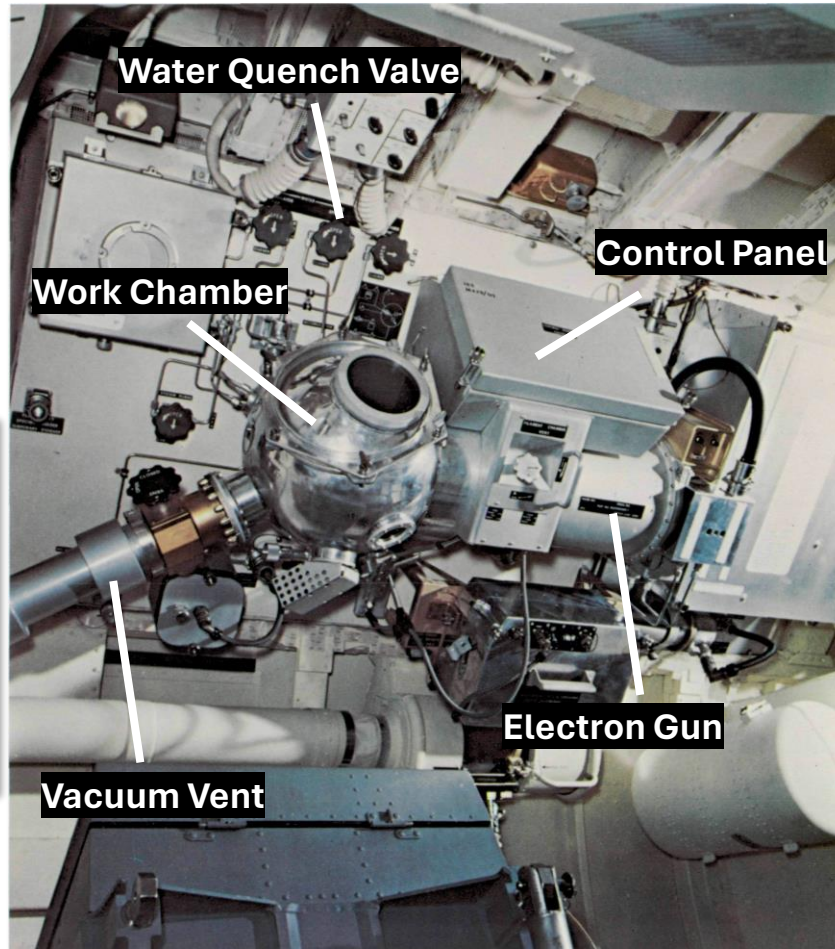
Progress in Space Stagnated and Moved to Parabolic Flights

It has been over 50 years since NASA has performed a weld in space.



Skylab experiments (1973)

Skylab M512 Materials Processing Experiment

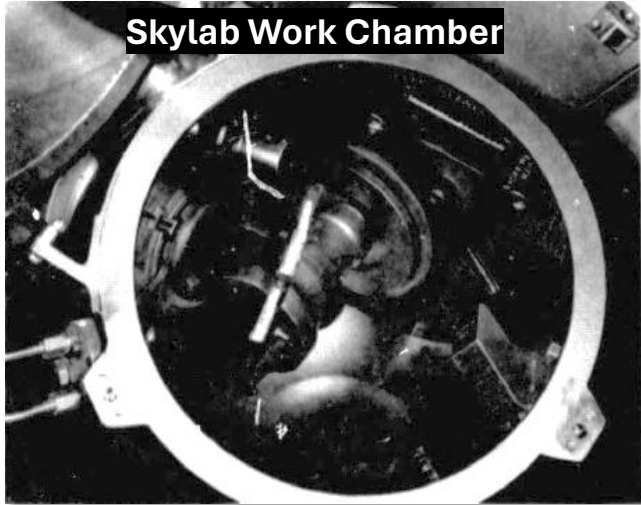


Outcome: Demonstrated physical and metallurgical behavior of electron beam welds and brazes in microgravity/vacuum.

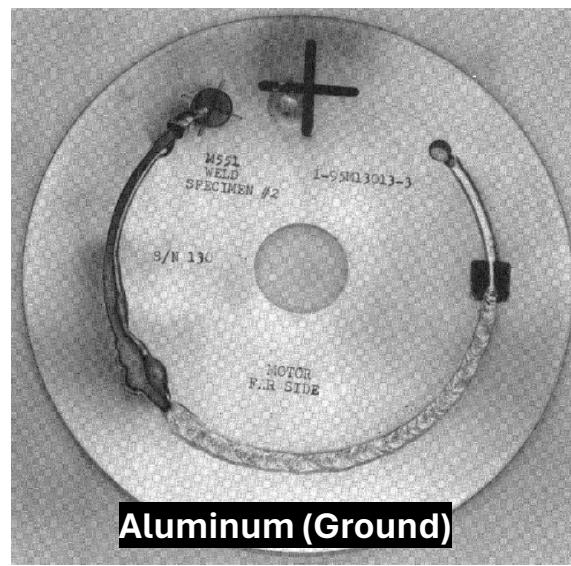
- Electron Beam Welding was proposed at a S-IVB Workshop in 1964 and Westinghouse developed a portable system.
- The M493 EBW experiment was formally approved in 1966 and eventually redesignated as the M551 Metals Melting Experiment.
- Skylab materials experiments were tested in 1972 aboard an Air Force KC-135.
 - 15-25 s was not enough time to complete melting and solidification cycle.
- **Materials Science and Manufacturing in Space:**
 - M551 Metals Melting experiment
 - M552 Exothermic Brazing experiment
 - M553 Sphere Forming experiment
- **Welding Chamber Details:**
 - 40 cm spherical vacuum chamber connected to space by a 10.2 cm diameter, 1 m long tube.
 - An electron beam was used as the welding heat source. It had focusing and deflecting coils operated from a control panel. System was powered by a battery.
 - Contained a light, a 16 mm camera, vacuum cleaner and water spray for metal quenching.

NASA-SP-401
Hooper, Contractor report NAS8-37756, 1989, <https://ntrs.nasa.gov/citations/19900006115>
Siewert et al., *Welding Journal*, 1977.

Skylab M551 Metals Melting Experiment



- Skylab published far more detail on experimental results than Soviet experiments.
- Three discs with tapered thickness were processed by the stationary EBW gun.
 - **Alloys:** Stainless Steel (304), Aluminum (2219-T87), CP Tantalum
- Weld started at the thin section and thickness increased with rotation of the disc (from 0.64 to 6.4 mm).
 - **Parameters:** Travel speed = 89 cm/min, E = 10 kV, I = 80 mA
 - **Pressure:** After 2 hr space vent, Vacuum = 10^{-4} torr (1.3×10^{-4} mbar)
- Differences in solidification and grain structure in the welds.
- Experiments were deemed a major success.

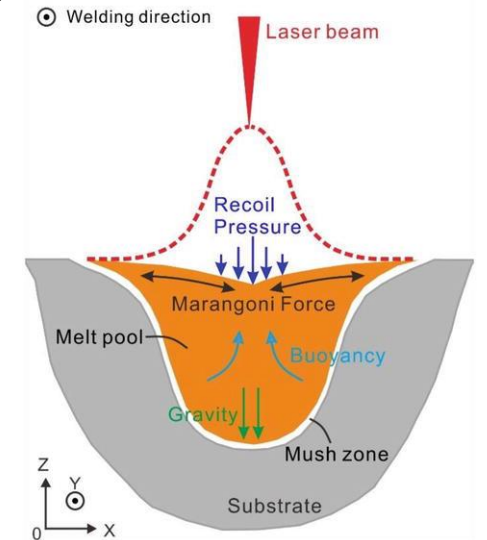


Condition	Weld Macro	Fusion Boundary	Weld Microstructure
Ground			
	<ul style="list-style-type: none"> • Weld shape is similar • Major differences in solidification structure were due to convection effect • Hardness (strength) was similar under both conditions 		
Skylab			

In-space effects that influence welding

Variable	Case 1: In Space	Case 2: Chamber Inside Habitat	Case 3: Inside Habitat	Case 4: Lunar Surface	Case 5: Martian Surface	Baseline: Earth	Capabilities Needed at Present
Gravity	μg	μg	μg	0.17 g	0.38 g	1 g	μg to 0.38 g
Atmosphere	Vacuum	Vacuum / Pressurized	Air	Vacuum	95CO ₂ -2.6N ₂ - 1.9Ar-0.2O ₂ - 0.06CO	78N ₂ -21O ₂ - 0.9Ar- 0.1other	HV (10 ⁻³ mbar) UHV (10 ⁻⁷ mbar) XUHV (10 ⁻¹¹ mbar)
Temperature	Extreme Low ISS Exterior: 120 K – 395K	~ 295 K	~ 295 K	40 K – 396 K	133 K – 300 K	~ 295 K	40 K – 400 K
Space Suit	Yes	No	No	Yes	Yes	No	

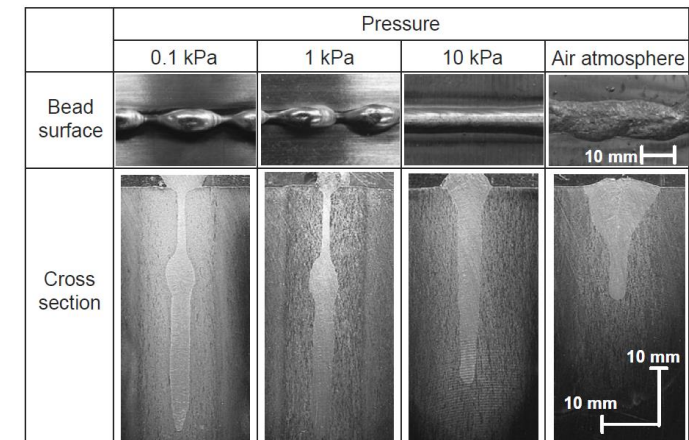
Table adapted and expanded from original source: Masubuchi, 1990, doi: [10.2207/qjwsws1943.59.421](https://doi.org/10.2207/qjwsws1943.59.421)



Licensed under CC BY 3.0 from Xiao et al., 2021, doi: [10.5772/intechopen.97205](https://doi.org/10.5772/intechopen.97205)

Reduced gravity is unique among the above effects in that it cannot be reproduced for prolonged periods on earth.

Current Work: Integrate existing capabilities across academia, government, and industry to investigate space environmental effects on welding processes to inform computational models, and to create public-private partnerships to develop and implement space welding technologies.



Licensed under CC BY-NC-ND 3.0 from Katayama et al., 2011, doi: [10.1016/j.phpro.2011.03.010](https://doi.org/10.1016/j.phpro.2011.03.010)

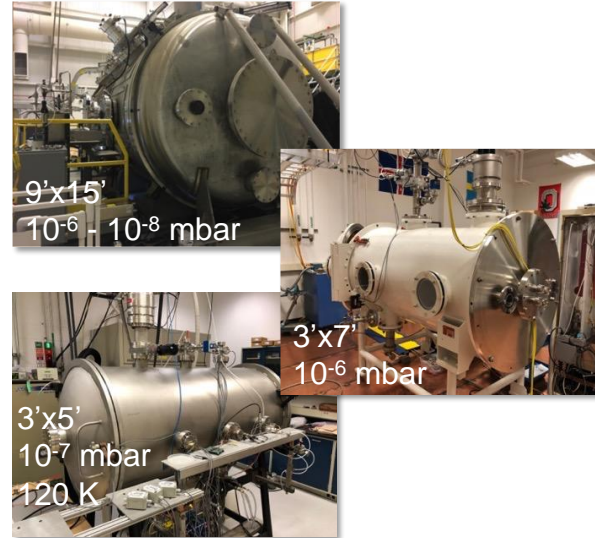
Adapted in part from: Sowards, *American Welding Society Professional Program*, 2023.

Simulating space conditions for welding

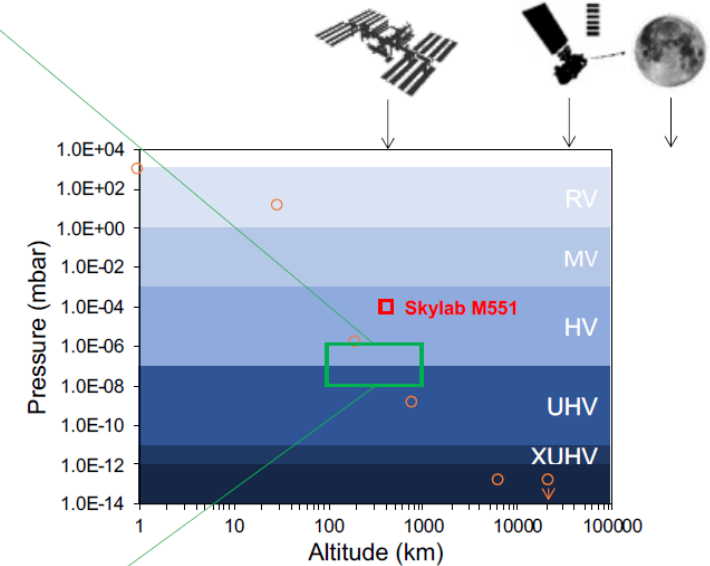
Microgravity / Reduced Gravity

Experimental platform → ↓ Criteria	Drop tower	Parabolic flight	Suborbital flight
Length of microgravity [s]	<5	20-25	>180
Gravity (quality) [g]	10^{-5}	10^{-3} - 10^{-2} (up to 2.0)	10^{-4}
Mass allowed [kg]	10^2	10^2	10^1
Cost [\$]	\$	\$\$	\$\$\$

Vacuum and Reduced Temperature



Example of MSFC capabilities to simulate reduced pressure / vacuum at 100 to 1000 km altitude.



Drop tower

Suborbital flight

Parabolic flight

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Low Earth Orbit (LEO)
 μg

Lunar surface
0.17 g

Martian surface
0.38 g

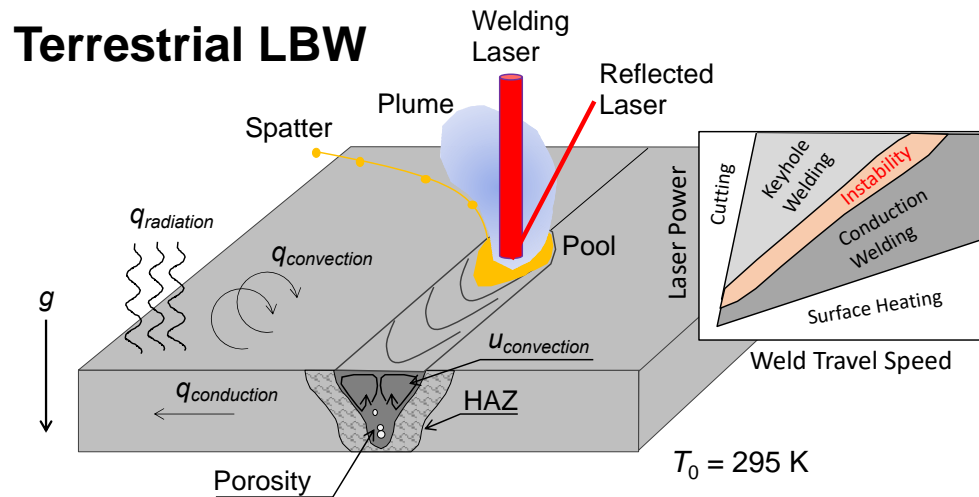


Numerous experiments have placed welding systems in vacuum chambers on parabolic flights.

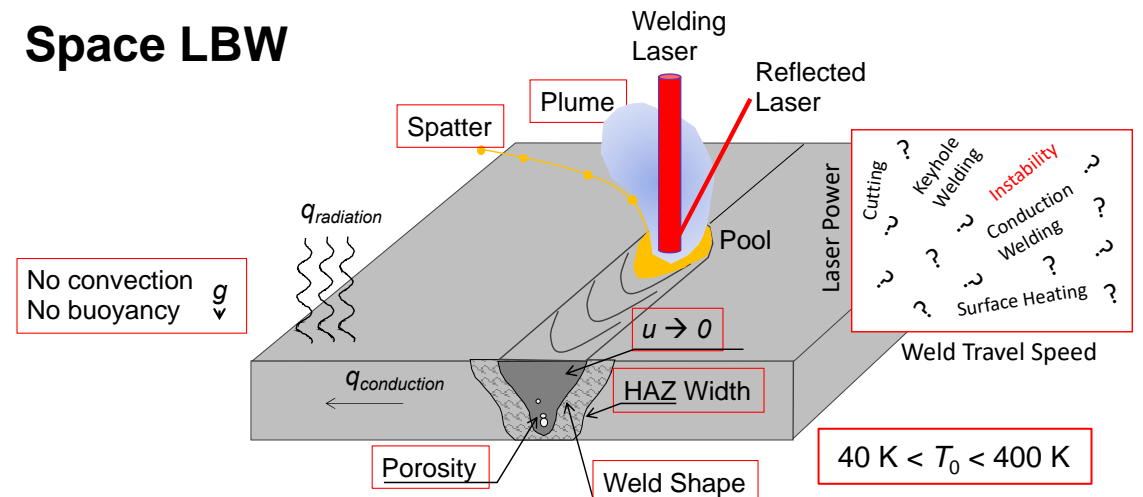
Mladenov, Koleva, and Trushnikov, *E+E*, 2019.

Key effects to consider for in-space LBW

Red boxes indicate instrumentation and modeling opportunities.



Space LBW



Issue #1 Weld heat transport has profound effect on size of a weld and its metallurgical transformations and hence weld properties:

Temperature gradient and cooling rate are proportional to thermal conductivity and T_0^2

Issue #2 Reduced gravity reduces buoyancy-induced convection:

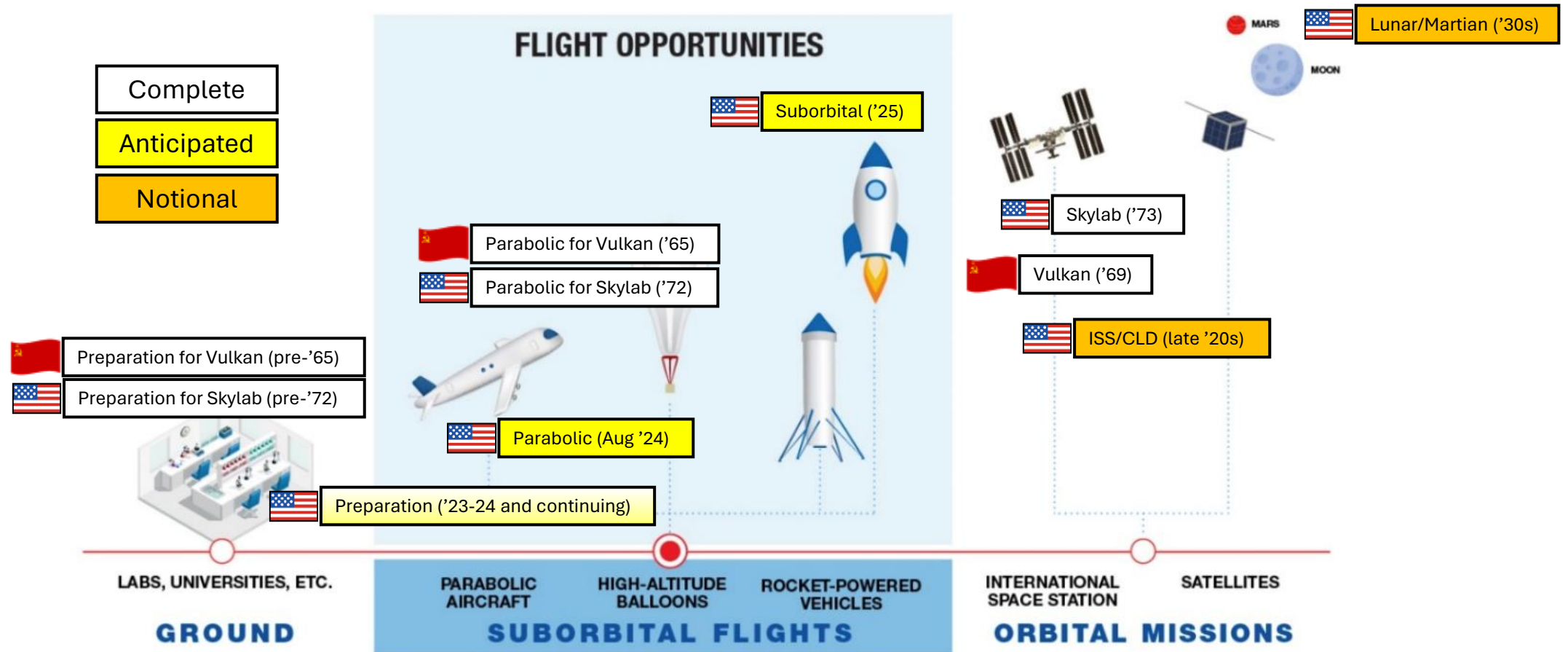
Development of weld pool shape and porosity evolution are altered, and chemical effects become dominant, e.g., surface-active elements influence weld penetration due to thermocapillary flow. (minute alloy chemistry changes are important)

Issue #3 Reduced pressure/vacuum in space:

Heat transport is dominated by radiation and conduction rather than by convection. Weld shape and width, and weld strength will be influenced by change in weld cooling.

Reduced pressure influences laser beam keyhole stability, evaporation of volatile species, safety issues, etc.

Progression of flight experiments



Underlying graphic from Kelly *et al.* in *ASCEND 2020*, 2020. doi: 10.2514/6.2020-4135. USG work.

Ground testing: 3 degree-of-freedom welding

Handheld Laser

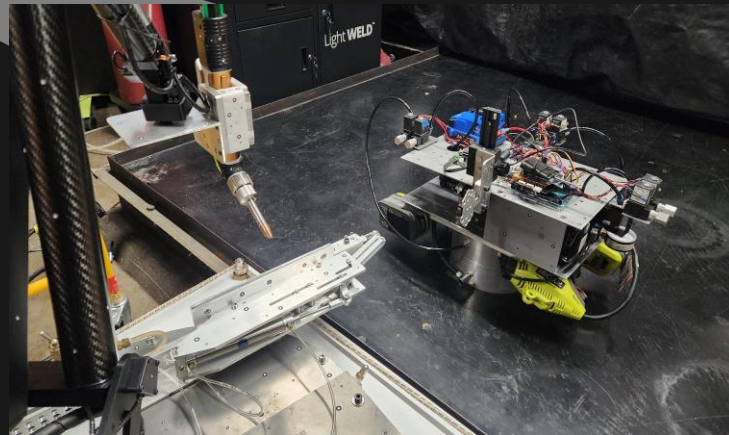


Courtesy: IPG

Integration and development of 3DOF welding system.

Flat Floor Integration

- Integrate laser onto robotic fixturing.
- First demonstration of laser in 3 degrees-of-freedom space simulator
- Identify challenges by investigating fitup, mismatch, weld quality, kinematics of welding recoil forces
- Augment Digital Twin model development.

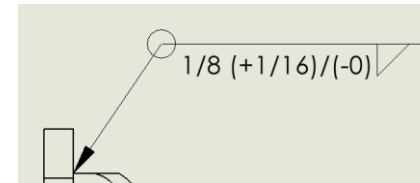


- Portable laser that cuts, cleans, and welds
- Process demonstrated on most important space alloys in a lab setting (aluminum, stainless steel, titanium)

Digital Twin Modeling

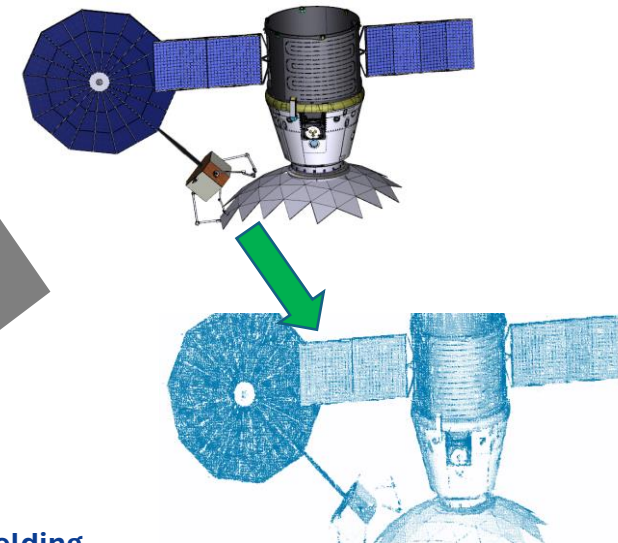
3D scanning and 3D model comparisons will allow us to:

- Build a virtual counterpart of in-space weld.
- Determine and document defects and tolerances to inform requirements and further 3D simulations.



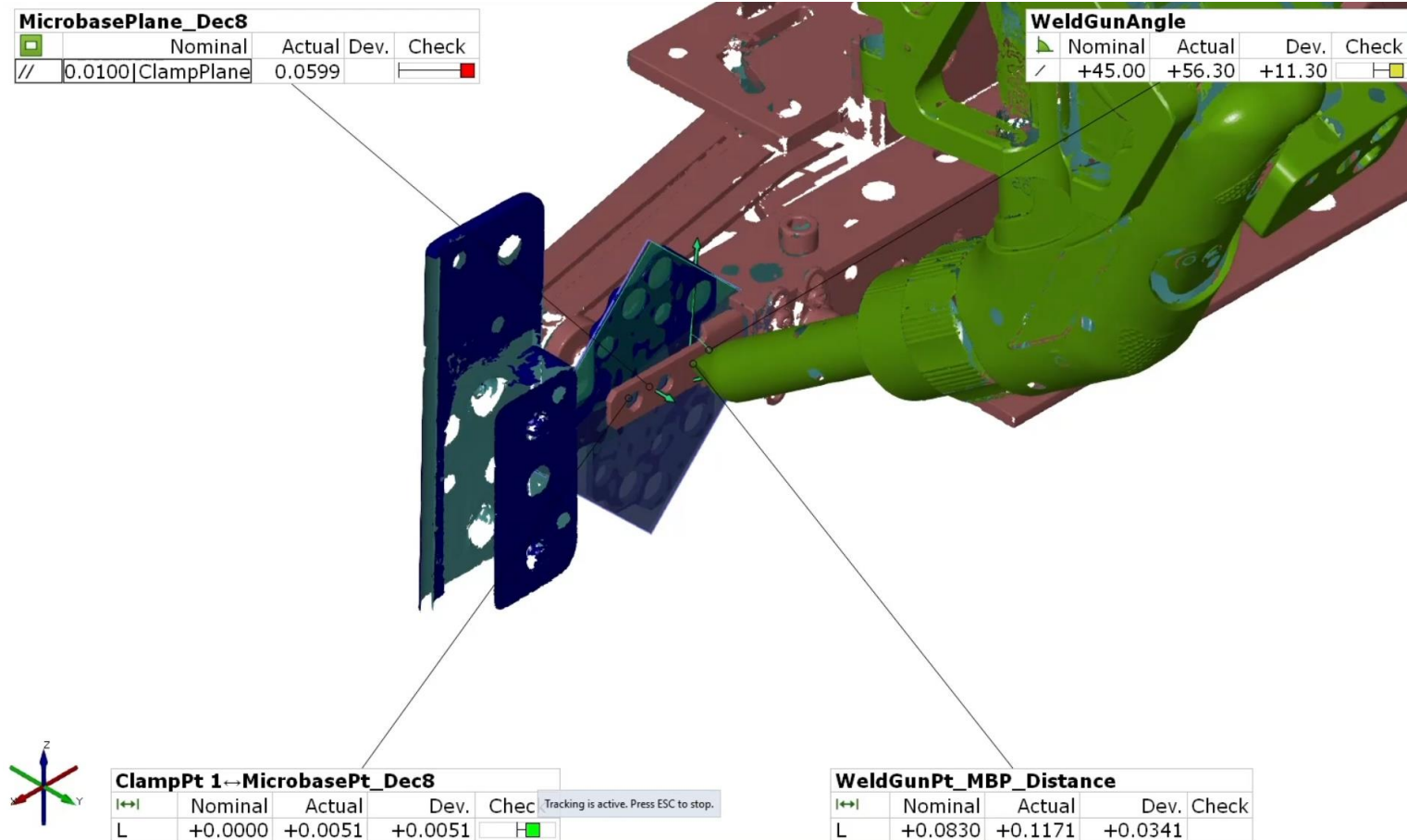
End Goals:

- 1) Identify manufacturing challenges with autonomous in-space laser welding.
- 2) Demonstrate a digital twin modeling capability for in-space welding.
- 3) Demonstrate laser beam welding technology as viable approach for in-space manufacturing.



Digital Twin of In-space Welding

Real-time capture of process geometry



2024 Parabolic Flight of Laser Beam Welding

Integration and Ground Demonstration of Self-contained Laser Welding System for Parabolic Microgravity Experiments.

- OSU. Profs. Ramirez, Panton, Horack, Nassiri, Williams, Nate Ames, Bob Rhoads. Multidisciplinary capstone team.
- NASA. Jeff Sowards, Karen Taminger (LaRC), Eugene Choi (WE intern), Will Evans, Zach Courtright, Louise Littles, Andrew O'Connor, Emma Jaynes, Tom Bryan.

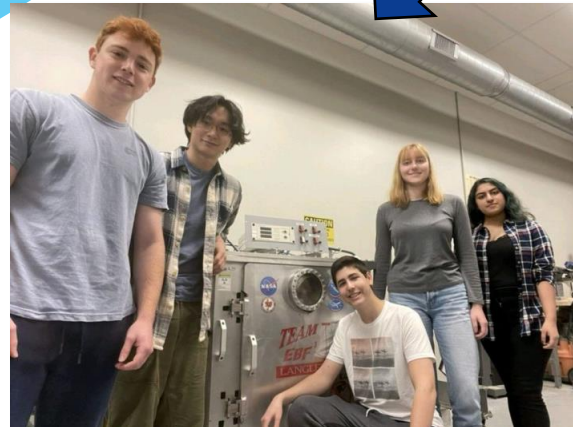
Heritage Vacuum Chamber



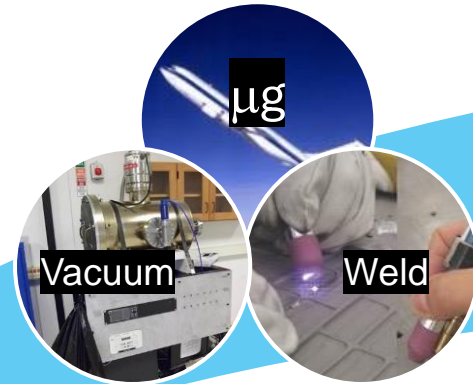
Laser Beam Welding



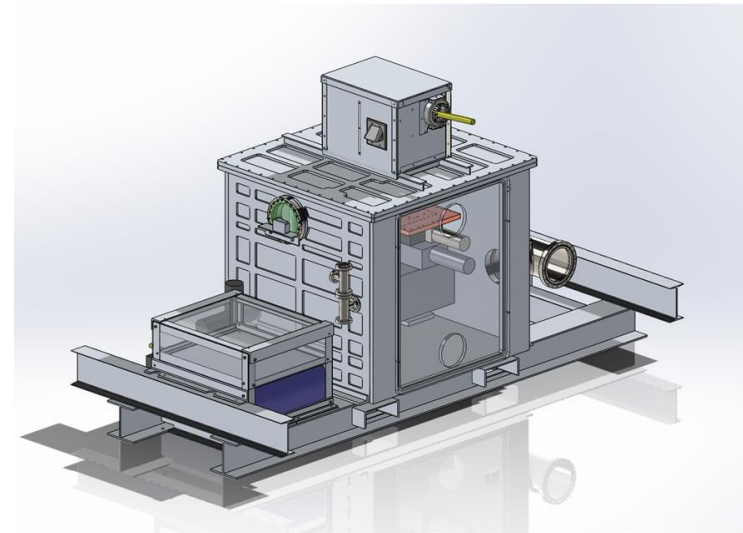
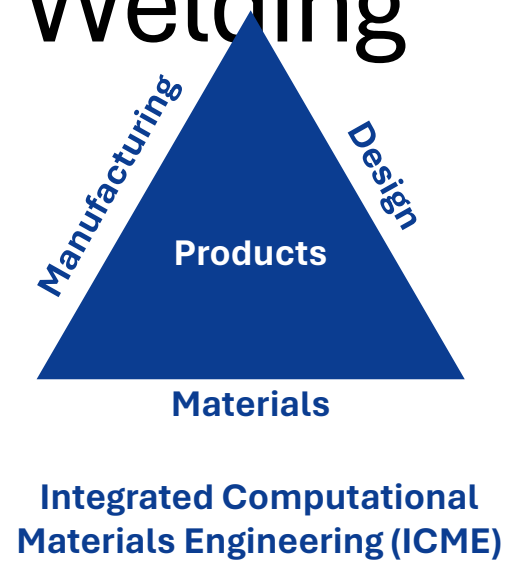
Cycle times of fiber Laser Beam Welding are shorter than 15 to 25 s parabolic arcs that were too brief for Skylab experiments.



Generate Model Calibration Data



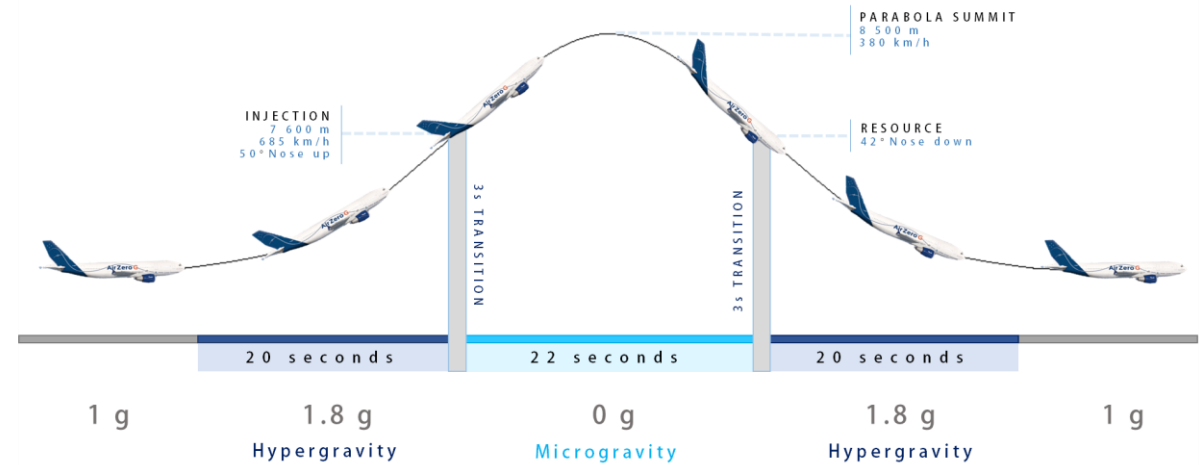
OSU-NASA CAN



Retrofitted Vacuum Chamber

Development of self-contained laser welding system to achieve space-like conditions

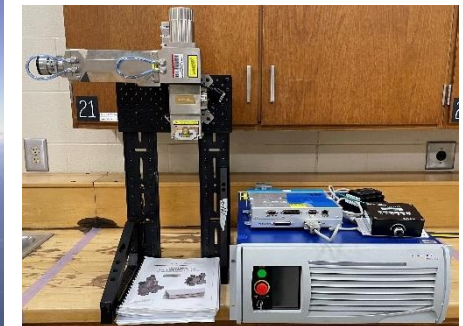
- Comparison analysis between on earth & In-Space Laser Beam Weld
 - Reduced gravity (Parabolic Flight)
 - Vacuum (Vacuum Chamber)
- Various reduced gravity conditions
 - Micro-gravity (0.001~0.01 g)
 - Lunar gravity (0.17 g)
 - Martian gravity (0.38 g)
- In-Situ Data Acquisition
 - Optical videography and thermography
 - Thermocouple for validation of thermography
 - Accelerometer for gravity



Parabolic profile for micro-gravity environment Credit: ESA



Cutaway of parabolic plane Credit: ESA/Novespace



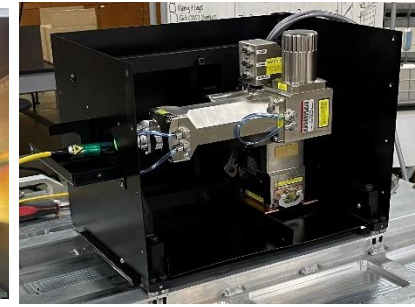
IPG D30 Wobble head & YLR-150/1500-QCW-AC

Retrofit for LBW

- 2007 EBF³ (Electron Beam FreeForm Fabrication) parabolic flight test chamber from NASA Langley (NASA/LaRC)
 - Flown on NASA C-9B parabolic plane
- Laser integration
- New axial control system
- New electrical breakout box
 - Different plane, different electrical supply
- Vacuum pump system check
- Axial motor check
- Laser-safe viewing window



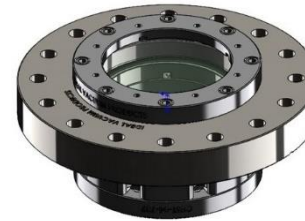
Motor functionality check



Laser and sensor integration (DAQ)



Vacuum pump check & automation



Laser passthrough



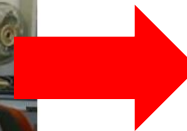
Laser and sensor integration (DAQ)



New axial motor controller

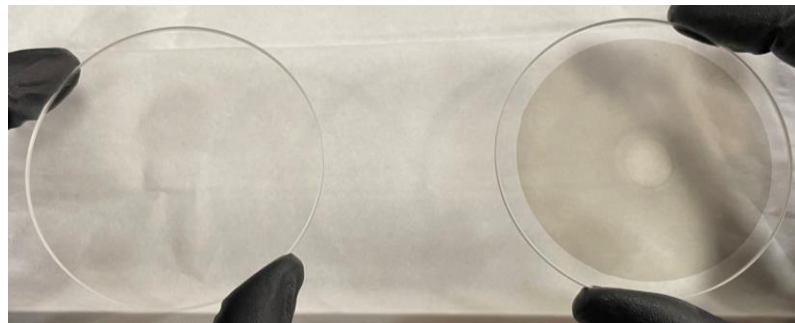


EBF³ system developed by NASA/LaRC and flown 2007



Laser integration

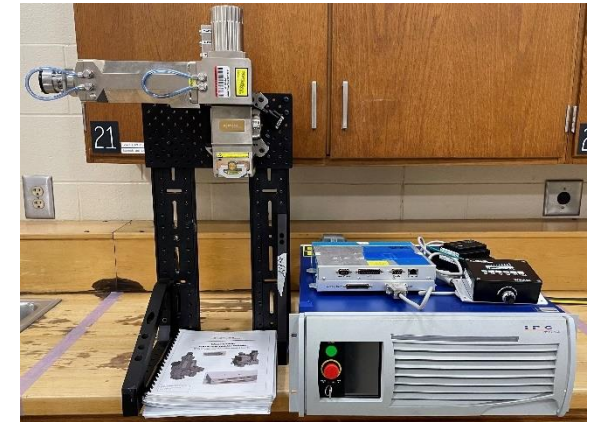
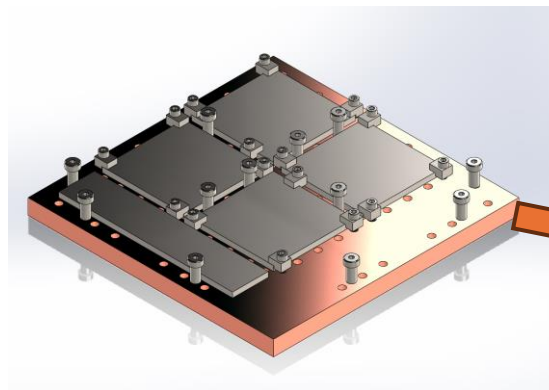
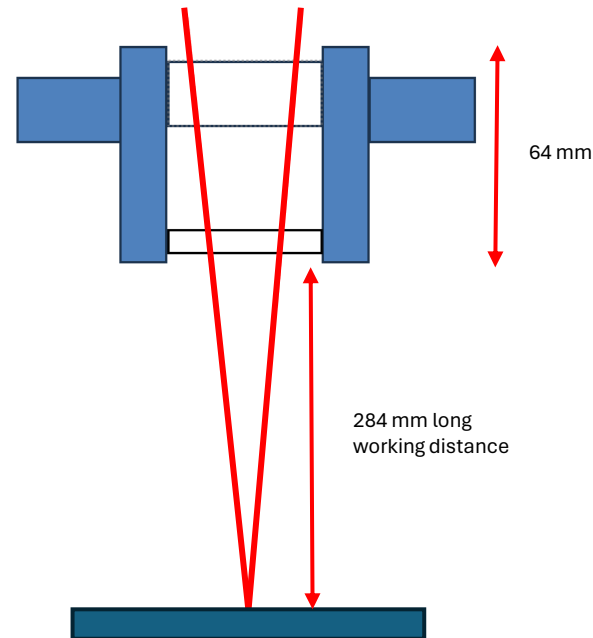
- Power: IPG YLR -150/1500-QCW-AC
 - 1070nm Nd:YAG fiber laser
 - CW Mode= 250W, Pulse Mode= 150-1500W
- Wobble-head laser focusing system
- Metallization concern on inner vacuum lens
 - Increase focus; Focus= 400mm
 - Working distance = 284mm (13.7")
- Increase Power density; Collimator= 200 mm
 - Focus power density = $318.31 \frac{W}{mm^2}$



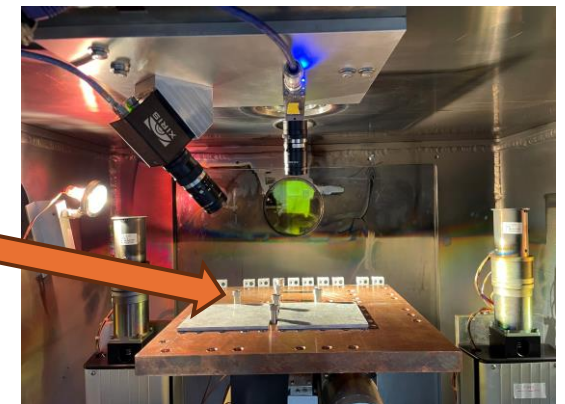
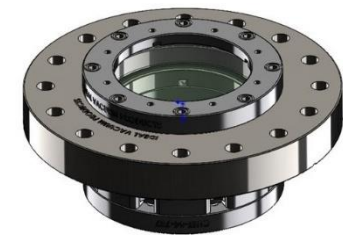
Metal deposition observed during testing

Increasing metal vapor deposition on optical passthrough (<65 mm distance to workpiece) from atmospheric pressure to ~10 Pa and below

Suita et al., 2005, [doi:10.2322/tjsass.48.86](https://doi.org/10.2322/tjsass.48.86)

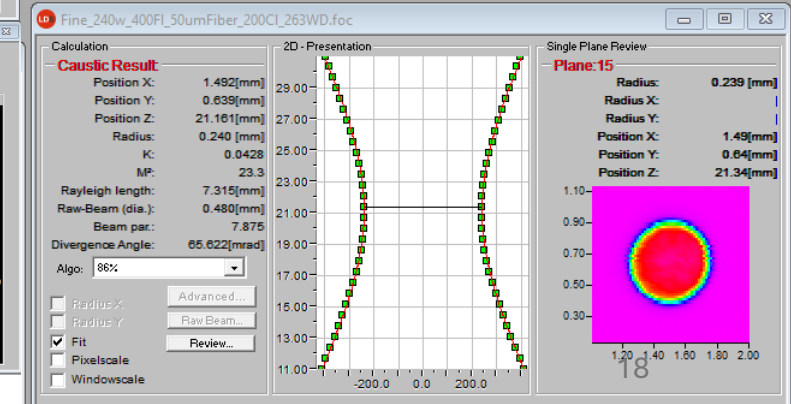
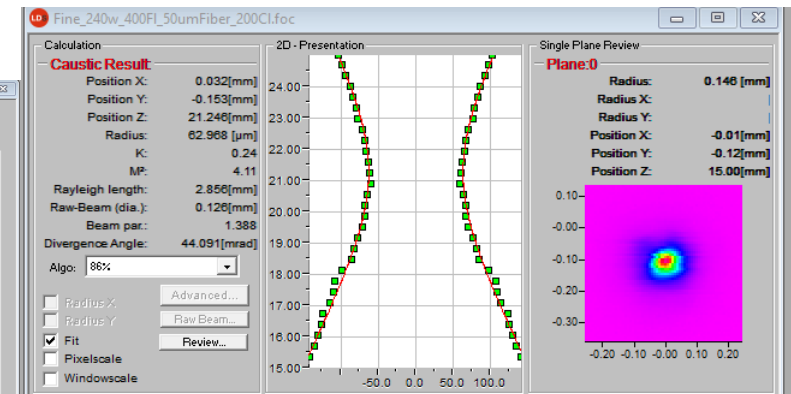
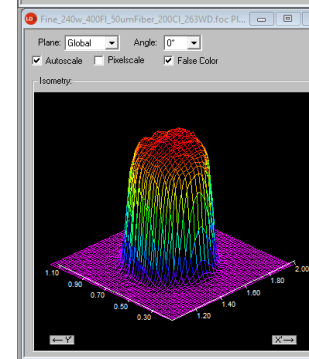
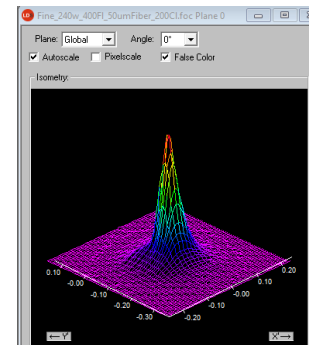
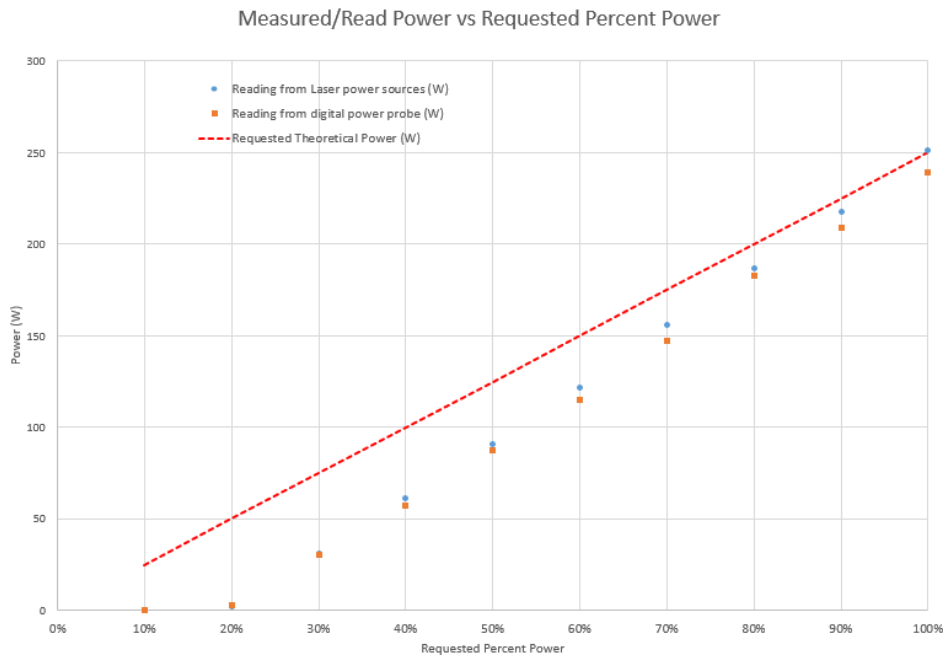


IPG D30 Wobble head & YLR-150/1500-QCW-AC

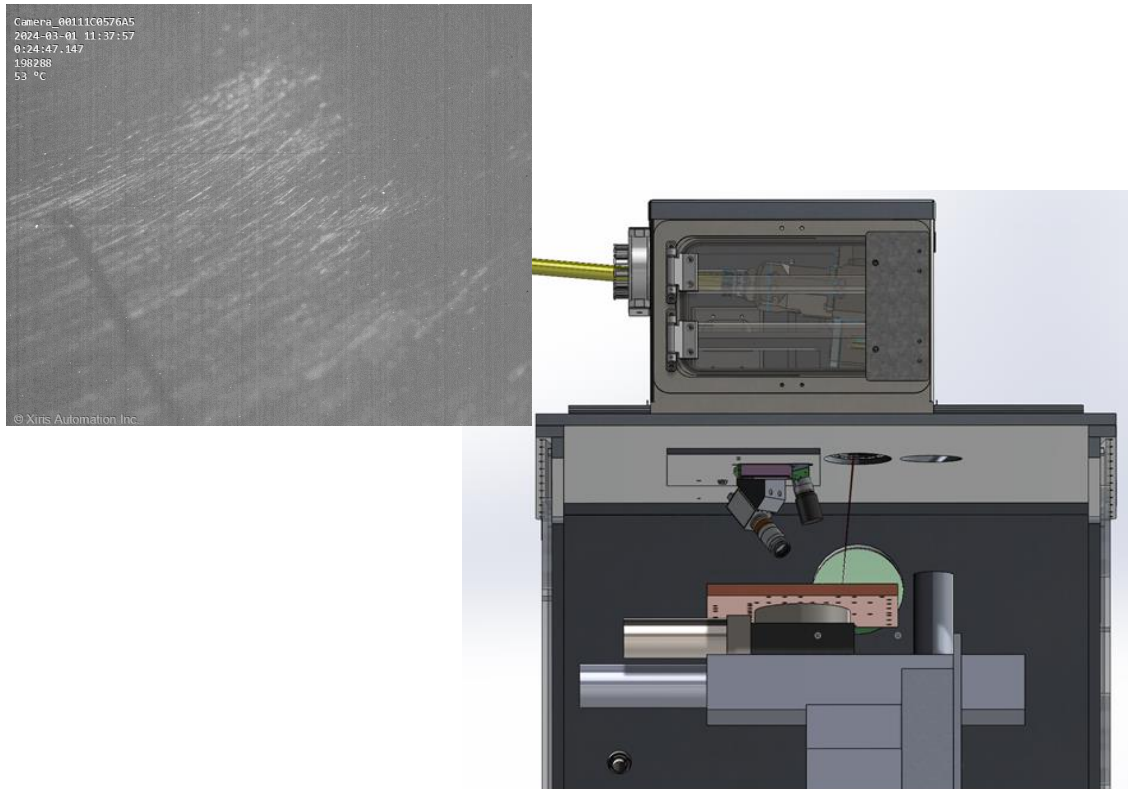


Laser beam diagnostics

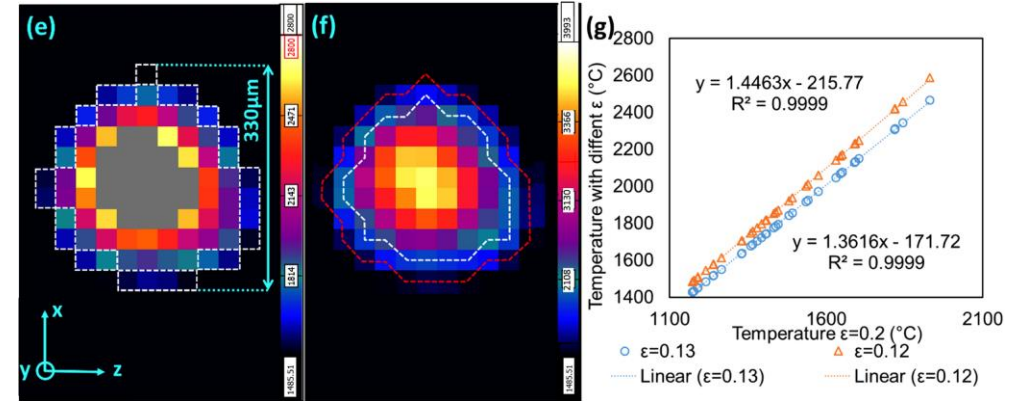
- Macken Instruments digital power probe confirms power profile – reduction due to optical passthrough
- PRIMES laser beam focus monitor defines caustics and focus of beam after passing into vacuum chamber



Instrumentation for thermal history

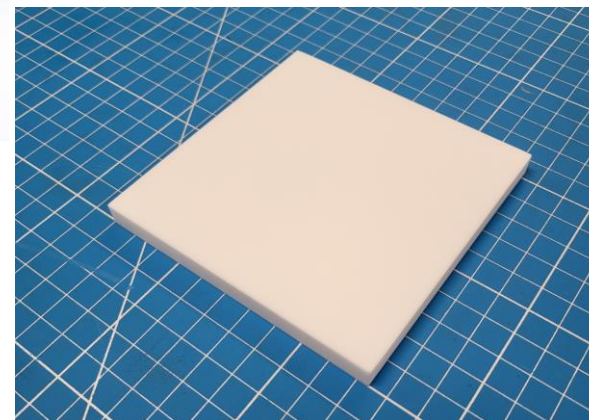


Example of *in situ* temperature monitoring for laser melting



Licensed under CC BY 4.0 from Wang *et al.*, 2022, doi: [10.1038/s41598-022-18096-w](https://doi.org/10.1038/s41598-022-18096-w)

- Xiris XVC-700 weld camera
 - Monitors melt pool size and morphology
- Xiris XIR-1800 thermal-weld camera
 - Short-wave infrared suitable for varying emissivity metals



High-temp glass-mica ceramic thermocouple & K-type connectors

Semi-automated operation during parabolas

- Manual start/stop upon μg call
- G-code for positioning and remote laser control

The screenshot shows a GCode File editor with the following code:

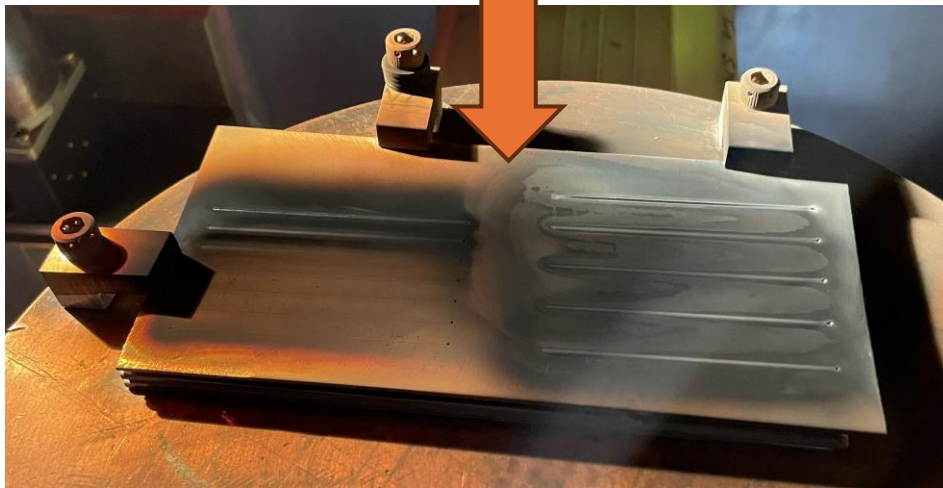
```
1 G21 // Switch to mm units
2
3
4 G92 X0 Y0 Z0 // Set current position as X=0, Y=0, Z=0
5 G90 // Set code to absolute positioning
6
7 // First Weld
8 M3 O30 // Turn laser on, 30%
9 G1 X0 Y60 // Do a weld to X0 Y60
10 M5 // Turn laser off
11
12 G0 X5 Y0 // Return to X5 Y0 for next weld, laser off
13
14 M3 O50 // Turn laser on, 50%
15 G1 X5 Y60 // Do a weld to X5 Y60
16 M5 // Turn laser off
17
18 G0 X10 Y0 // Return to X10 Y0 for next weld, laser off
19
20 // Etc etc for more welds
```

The plot on the right shows a 2D coordinate system with a grid. A red horizontal line is at Y=0. A blue vertical line is at X=0. A green vertical line is at X=5. An orange parabolic curve starts at (0,0), reaches a peak at (5,60), and ends at (10,0). A red horizontal line is at the bottom of the plot.

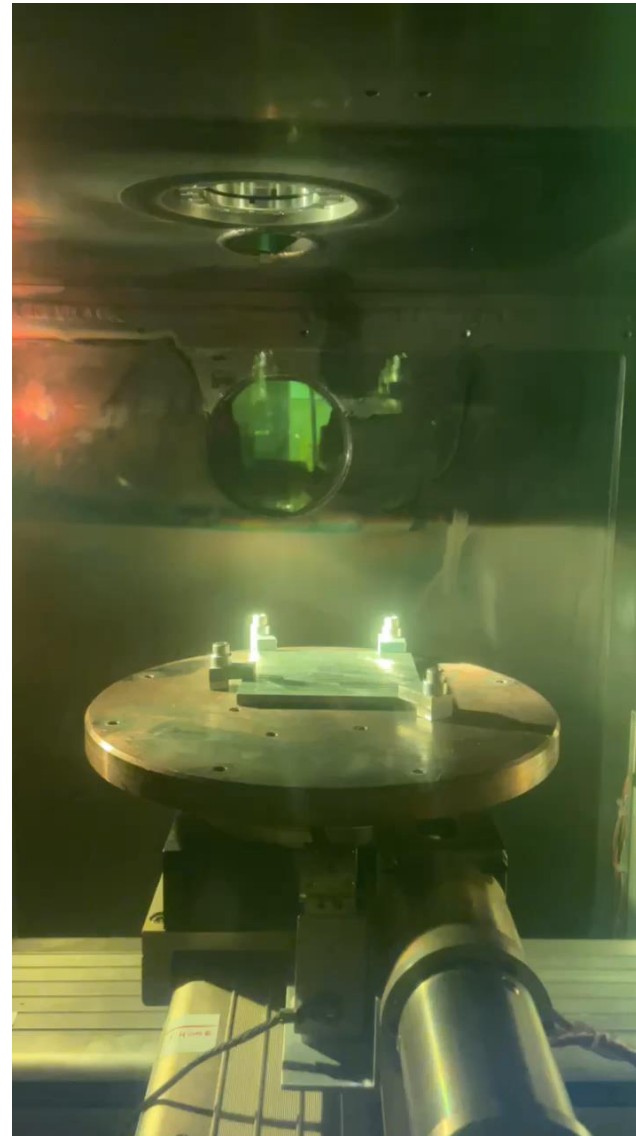
The screenshot shows a CNC control interface with the following sections:

- Start G-code:** Start button.
- Stop G-code:** Stop button.
- G-code File Path (.txt):** Input field with a file icon.
- Valid G-code:** Radio button (selected).
- Invalid Pulse Parameters:** Radio button.
- Includes Laser Moves, Laser Not Active:** Radio button.
- Motor Controllers Connected:** Section with Start Move, Stop Move, Home and Move to Origin, and Zero All buttons. Includes input fields for X, Y, and Z Target and Position (mm), and Velocity (mm/s). Status indicators for X Moving, Y Moving, Z Moving, and Brake Active.
- Laser Connected:** Section with Start Move with Laser ON, Stop Move and Laser, and Set Laser Parameters buttons. Includes input fields for Set Current (%), Current (%), Pulse Mode, Pulse Rate (Hz), Aiming Beam, Output Power (W), Set Pulse Rate (Hz), Pulse Width (ms), Laser Temp (C), and Peak Power (W). Status indicators for Pulse Mode Enabled, Aiming Beam ON, Power Supply ON, and Keyswitch in REM Position.
- Status:** Section with indicators for Emission ON or Starting, Emission Starting, and Pulse Mode Enabled.
- Errors:** Section with indicators for Critical Error, Overheat, Low Temperature, Pulse Too Long, Duty Cycle Error, Optical Interlock, High Back Reflection Level, Module Disconnected, and Power Supply Failure.
- G-code Plot:** A 2D plot showing a parabolic path.
- Output Data Folder Name:** Input field with "outputdata" entered.
- Acceleration (g):** Input fields for X Accel, Y Accel, and Z Accel.
- Pressure (torr):** Input fields for P1, P2, and P3.
- Temperature (F):** Input fields for TC 0 through TC 9.

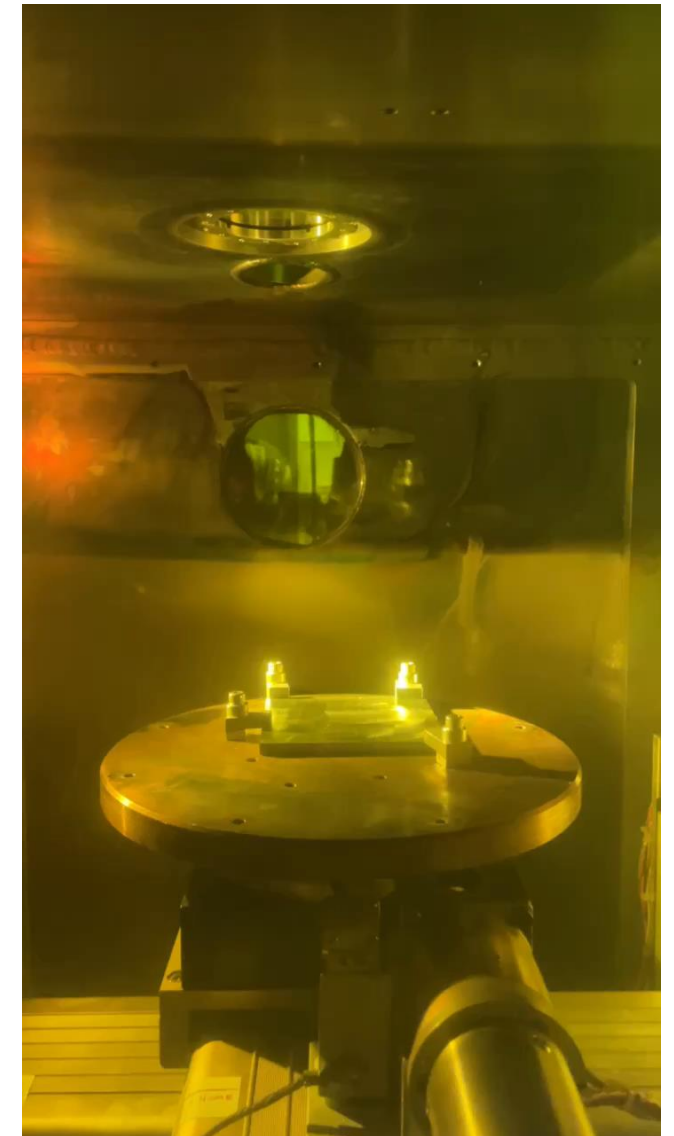
Initial LBW trials



In air



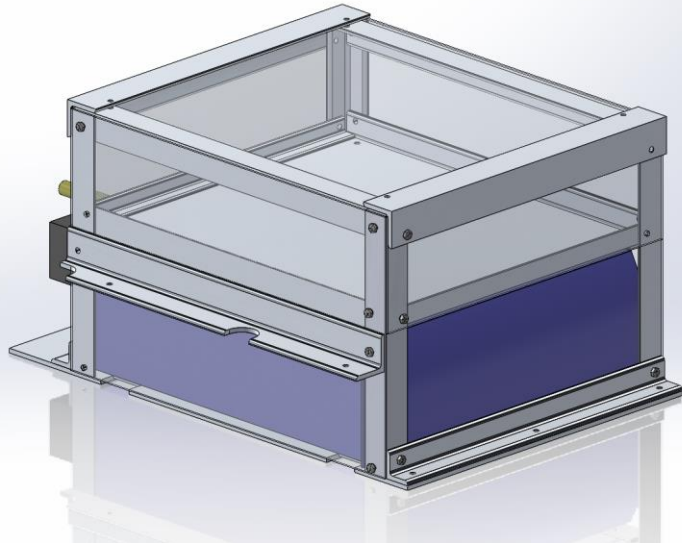
Under high vacuum (~mPa)



n.b. parameters not exactly same, illustrative only

Safety is critical!

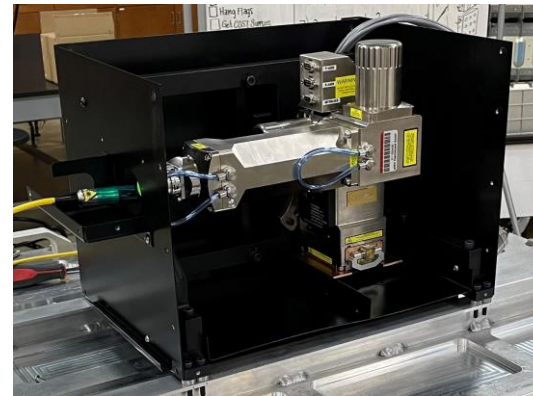
As NASA-funded payload, satisfy both NASA/AFRC and Zero-G requirements



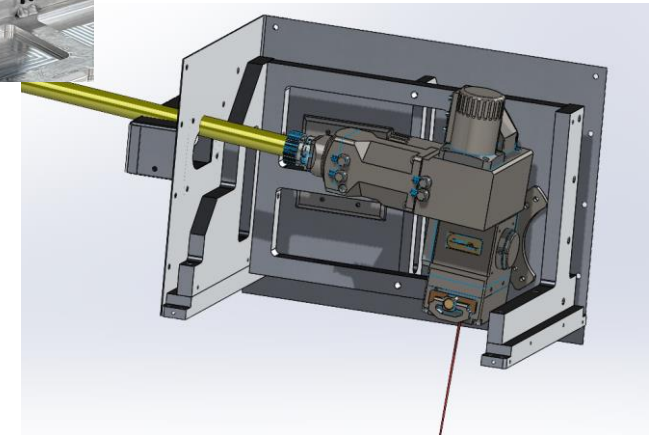
Example: electrical box and laser generator

Failure Type	Factor of Safety
Tensile Ultimate	+8.268
Tensile Yield	+3.617
Shear Ultimate	+9.794
Fastener Pullout	+3.141
Bearing Stress	+7.211
Shear Tearout	+12.129
Net Section	+5.66

Re-wire, re-wrap electrical cabling to reduce flammability risk



Laser-safe enclosure with laser optics rotated off-axis and window anti-reflective coated to reduce back-reflection



Parabolic flight expected August 2024

During flight

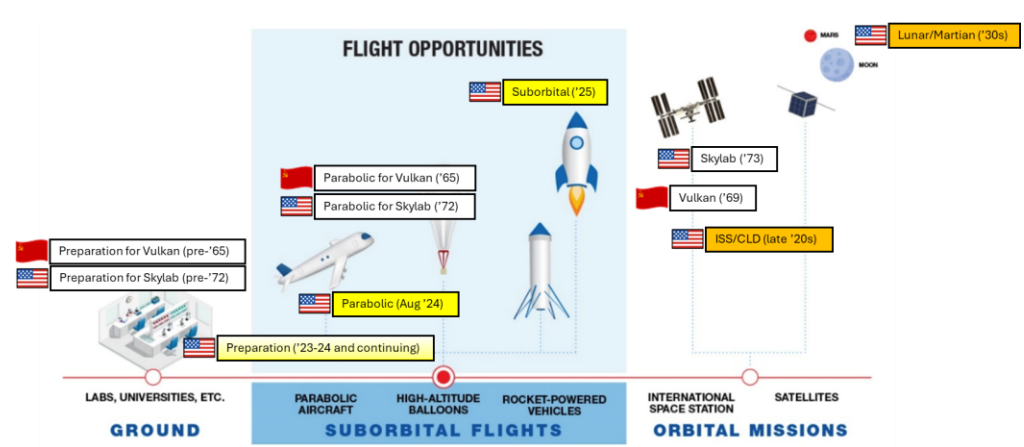
- Two flight days consisting of lunar and microgravity profiles
- Engineering alloys:
 - Aluminum 2219-T87 (Al-Cu-)
 - Stainless steel 316L
 - Ti64 (Titanium-6wt% Al-4wt% V)
- Considering Al-Cu binaries
 - More tractable for computational models
 - Similar to previous flight experiments investigating solidification

Post-flight

- *in situ* data analyzed
 - Melt pool size and morphology
 - Thermal imaging
- Post-flight characterization
 - Cross-section of weldment for metallography
 - Hardness, mechanical testing
- Detailed interpretation of data to determine suitability as validation datasets for computational modeling

Beyond parabolic: an in-space laser beam ecosystem

Progression of ground to flight experiments for all aspects of ISAM laser beam ecosystem?



Underlying graphic from Kelly et al. in ASCEND 2020, 2020. doi: 10.2514/6.2020-4135.

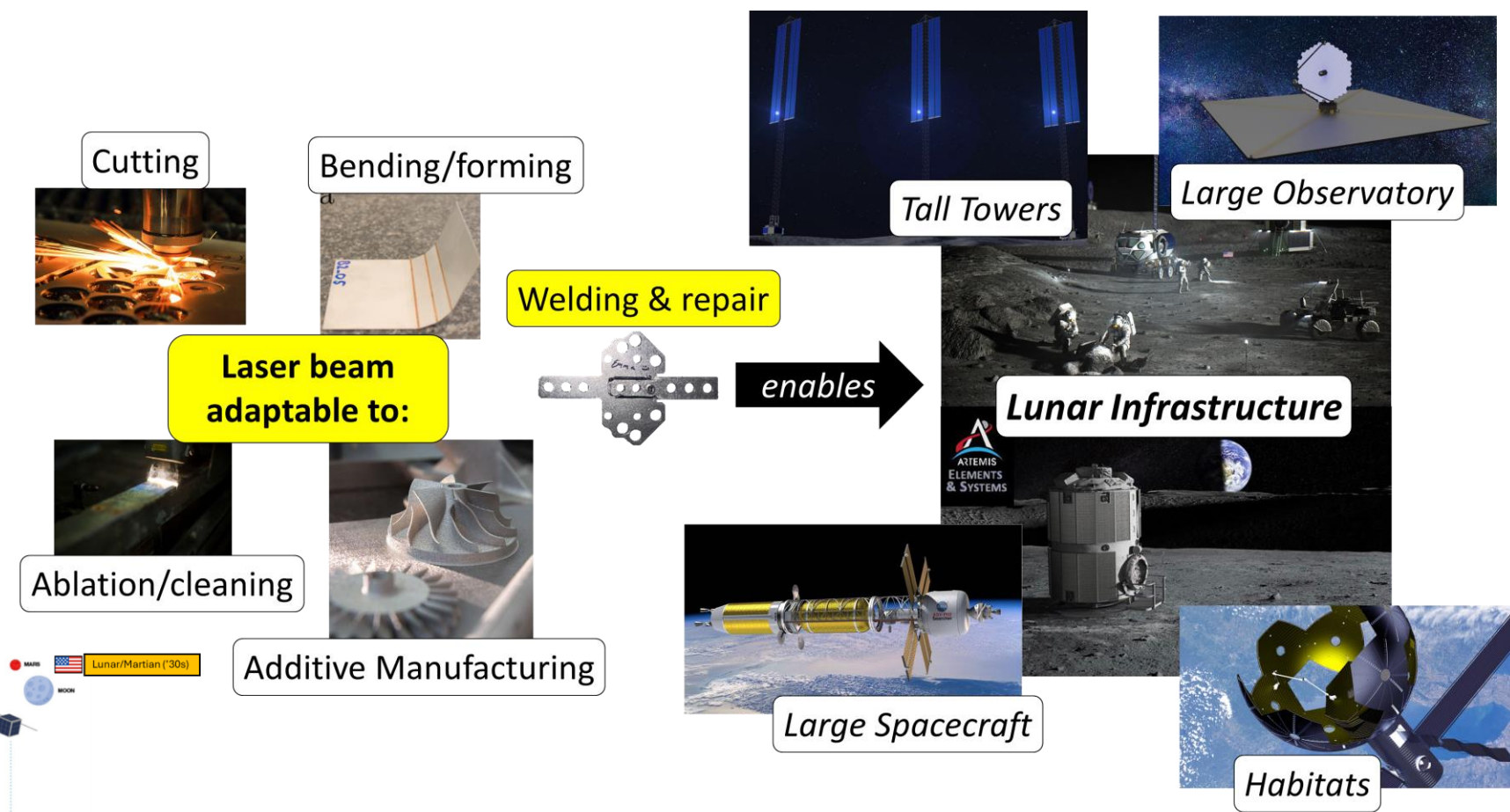


Image credit: ThinkOrbital, www.mechanicalcaveman.com, Thomsen, et al., "2019, doi: 10.1016/j.promfg.2019.08.025 (CC BY-NC-ND 4.0)

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