

Aviary: An Open-Source Multidisciplinary Design, Analysis, and Optimization Tool for Modeling Aircraft with Analytic Gradients

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National Aeronautics and Space Administration



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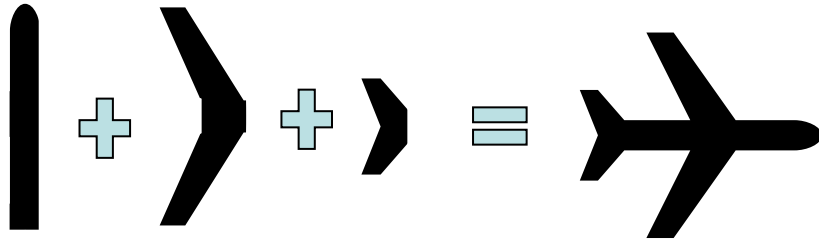
Today's Roadmap

This presentation covers:

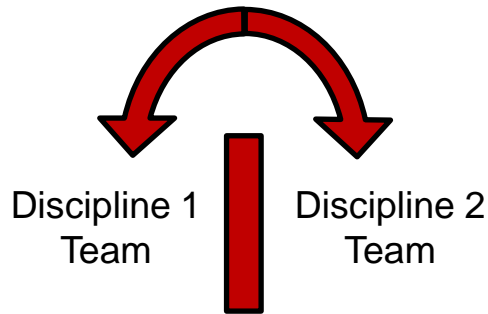
- Historic and future aircraft modeling needs
- The Aviary tool meets these needs
- How Aviary works
 - The structure of Aviary
 - The calculation methods in Aviary
 - The verification of Aviary
 - The user's interaction with Aviary

Historic Aircraft Modeling and the Need for a New Tool

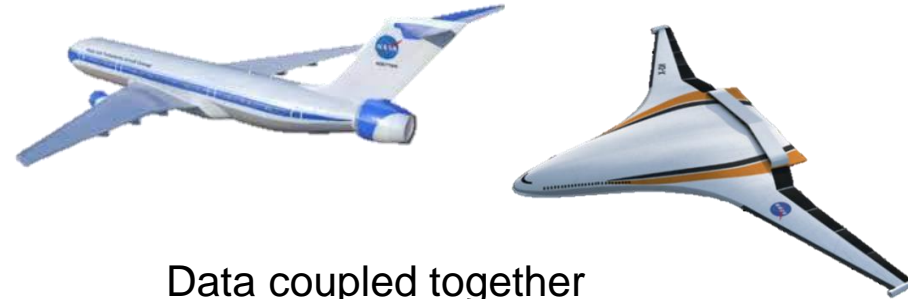
Traditional Design Method



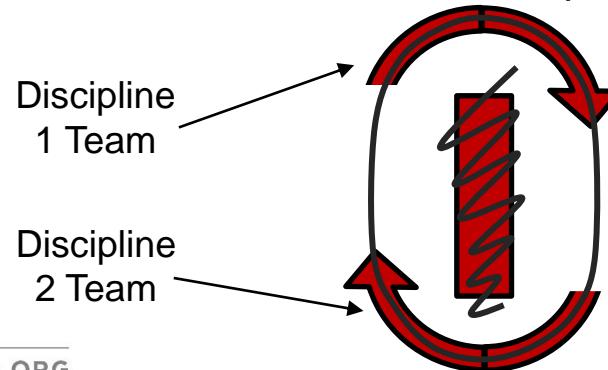
Data thrown “over-the-wall”
Manual iteration required



New Advanced Digital Design Method



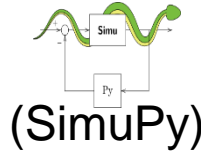
Data coupled together
No manual iteration required



Aviary Builds on Legacy Tools and Meets this Need

```
FFFFFFFF LL      000000 FFFFFFFFFP SSSSSSSS  
FF       LL      00  00  PP  PP  SS  SS  
FF       LL      00  00  PP  PP  SS  SS  
FF       LL      00  00  PP  PP  SS  SS  
FFFFFFFF LL      00  00  FFFFFFFFFP SSSSSSSS  
FF       LL      00  00  PP  PP  SS  SS  
FF       LL      00  00  PP  PP  SS  SS  
FF       LL      00  00  PP  SS  SS  SS  
FF       LL      00  00  PP  SS  SS  SS  
FF       LLLLLLLL 000000 PP  SSSSSSSS
```

General Aviation
Synthesis Program



(SimuPy)



AVIARY

Combine legacy
tools

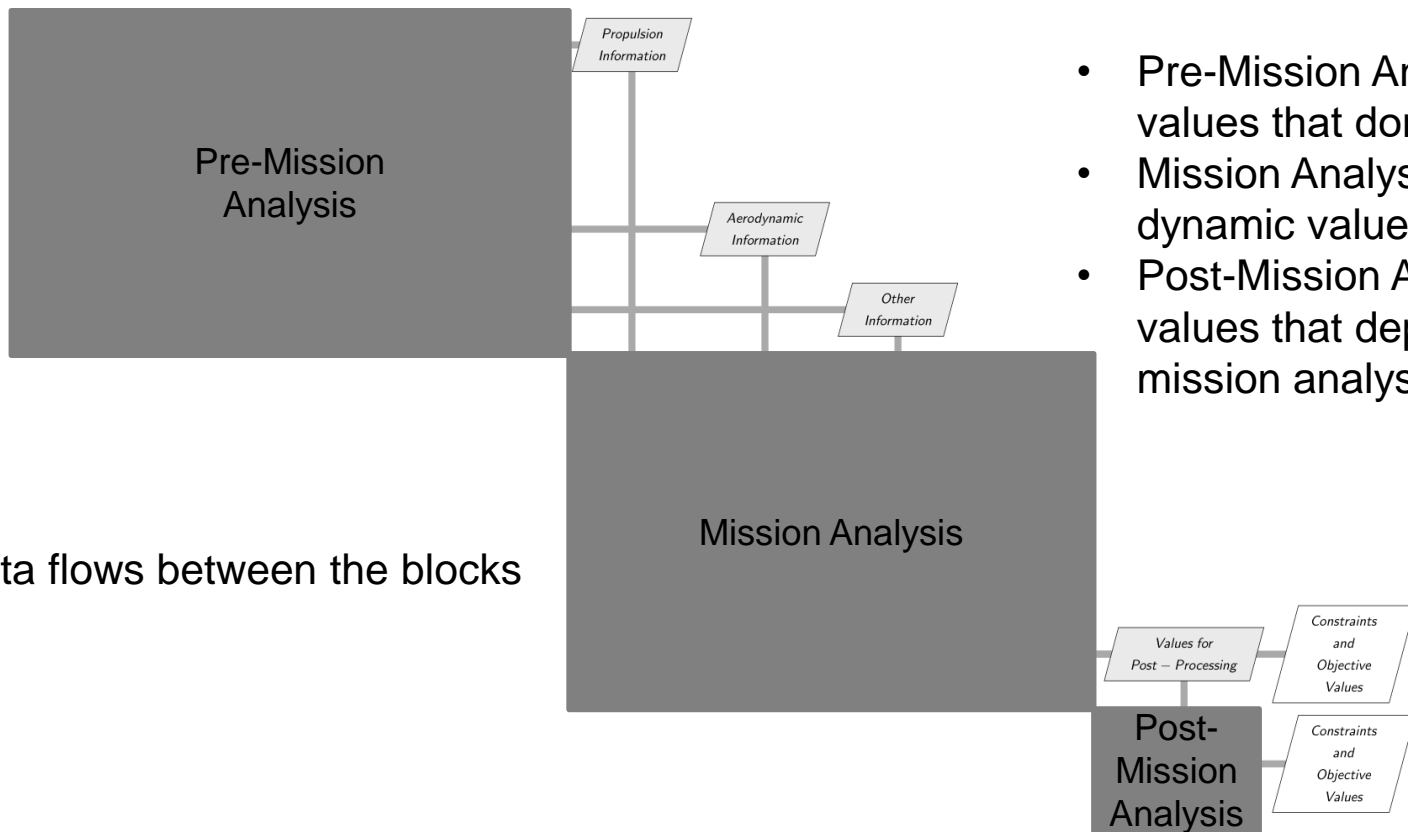
Coupled
Optimizations

Open-source
software

Modular for
modification and
substitution

Analyze advanced
concepts

The Structure of Aviary



- Pre-Mission Analysis calculates values that don't change in time
- Mission Analysis calculates dynamic values
- Post-Mission Analysis calculates values that depend on the mission analysis

- Data flows between the blocks

The Subsystems of Aviary

Pre-Mission Analysis

Propulsion

Geometry

Weights

Aerodynamics

Other Subdisciplines

Mission Analysis

EOMs

Integration Tools

Mission Building

Post-Mission Analysis

The Subsystems of Aviary

Pre-Mission Analysis

Propulsion

Tabular
Propulsion

Geometry

FLOPS-based
Geometry

GASP-based
Geometry

Weights

FLOPS-based
Empirical
Weights

GASP-based
Empirical
Weights

Aerodynamics

FLOPS-based
Empirical Aero

GASP-based
Empirical Aero

Other Subdisciplines

Mission Analysis

EOMs

2DOF EOMs
(GASP)

Height Energy
EOMs (FLOPS)

Integration Tools

Collocation
Integration

Explicit Shooting
Integration

Mission Building

Pre-built
Aviary-based
Mission

Post-Mission Analysis

The Subsystems of Aviary

Pre-Mission Analysis

Propulsion

Tabular
Propulsion

User-defined
Subsystems

Geometry

FLOPS-based
Geometry

User-defined
Subsystems

GASP-based
Geometry

Weights

FLOPS-based
Empirical
Weights

GASP-based
Empirical
Weights

User-defined
Subsystems

Aerodynamics

FLOPS-based
Empirical Aero

User-defined
Subsystems

GASP-based
Empirical Aero

Other Subdisciplines

Battery
Modeling

Thermal
Modeling

Stability and
Control Modeling

User-defined
Subsystems

Mission Analysis

EOMs

2DOF
EOMs

Height Energy
EOMs

Integration Tools

Collocation
Integration

Explicit Shooting
Integration

Mission Building

Pre-built
Aviary-based
Mission

User-built
Aviary-based
Mission

Post-Mission Analysis

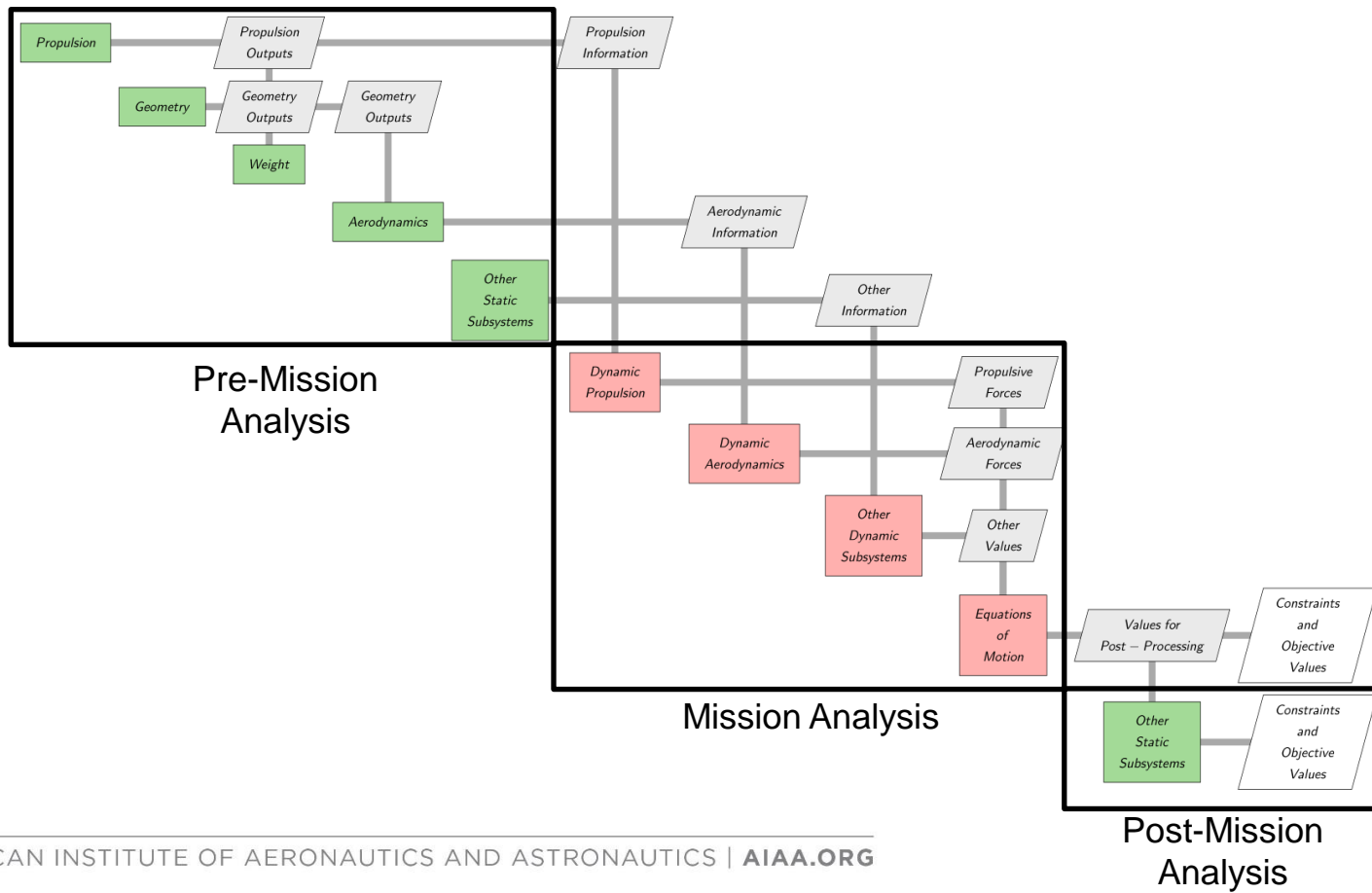
Emissions
Modeling

Cost
Modeling

Acoustics
Modeling

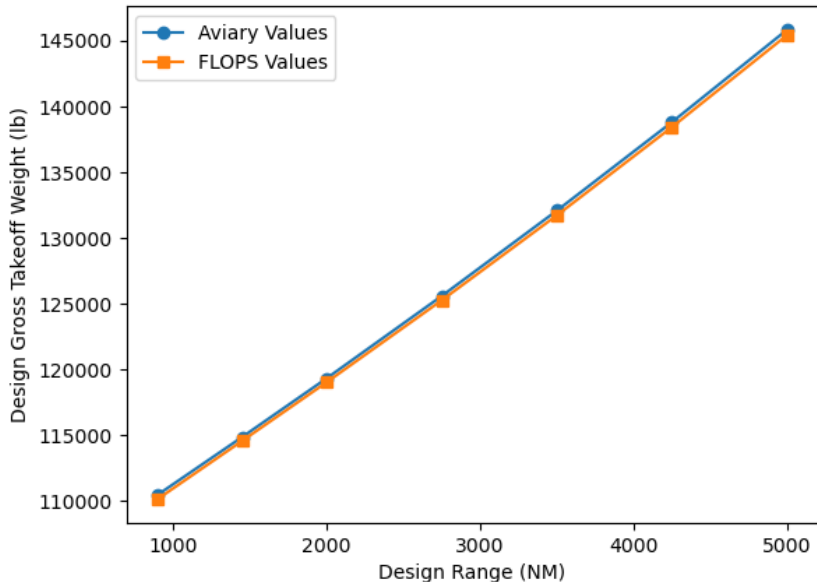
User-defined
Subsystems

Revisit The Structure of Aviary



Verification of Aviary

Design Gross Takeoff Weight for Different Design Ranges



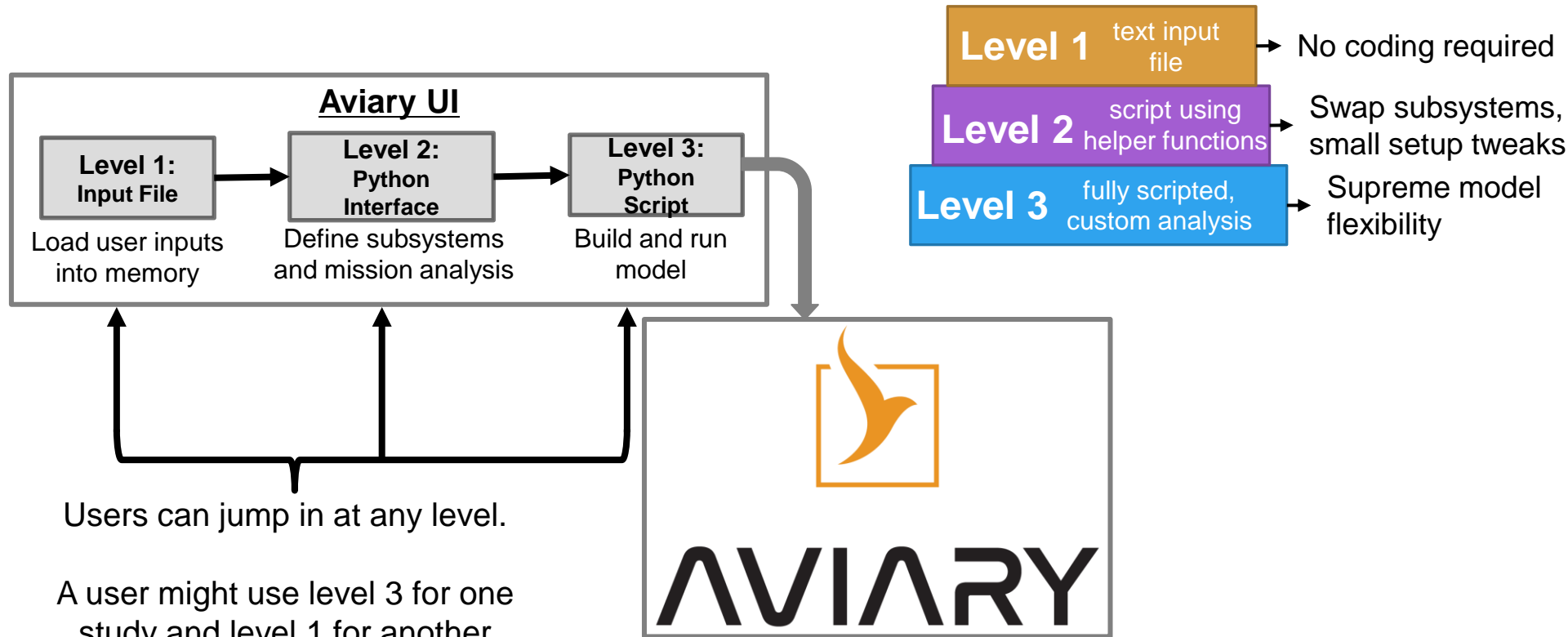
Aviary includes integration (benchmark) testing...

...and unit (component and subsystem level) testing.

Table 2 A summary of the subsystem unit test cases for each subsystem included in Aviary that are compared against legacy tools' results for verification.

| Subsystem Tested | Unit Test Tolerance | Derivative Test Tolerance | Test Case Notes |
|--------------------------|---------------------|---------------------------|-----------------------------------------------------------------------------------------------|
| GASP-based aerodynamics | 1.5e-3 | N/A | Derivatives only checked in the component unit tests (same for FLOPS aerodynamics). |
| FLOPS-based aerodynamics | 5e-3 | N/A | Some extrapolated points require looser tolerance due to difference in interpolation methods. |
| GASP-based geometry | 5e-4 | 1e-9 | Some values slightly altered to account for intentional changes in the code. |
| FLOPS-based geometry | 1e-2 | 1e-6 | Does not test canard features. Loose tolerance primarily due to roundoff error in FLOPS data. |
| GASP-based mass | 5e-4 | 3e-9 | Some values slightly altered to account for intentional changes in the code. |
| FLOPS-based mass | 1e-4 | 1e-10 | |
| Propulsion | 1e-10 | 1e-10 | This tests the scaled sea-level static thrust from pre-mission. |

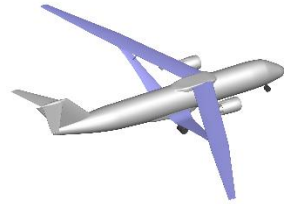
How the User Interacts with Aviary



Summary

This presentation covered:

- Historic and future aircraft modeling needs
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<https://github.com/OpenMDAO/Aviary>

Related Works

Papers Using Aviary:

- “Multidisciplinary Optimization of a Transonic Truss-Braced Wing Aircraft using Aviary” by Eliot Aretskin-Hariton et al. Published at AIAA SciTech 2024.
- “Noise Reduction Trajectory Analysis of a Supersonic Business Jet using Novel Optimization Tools” by Jeshurun Horton et al. Published at AIAA Aviation 2024.
- “Impacts of Hybrid-Electric Propulsion on a Transonic Truss-Braced Wing Aircraft” by Mark Leader et al. Published at AIAA Aviation 2024.
- “Studying the Usability of an Open-source Aircraft Design Tool” by John Jasa et al. Abstract submitted to AIAA SciTech 2025.
- “Optimization of a Multi-Mission Hybrid-Electric Propeller Regional Aircraft using Aviary” by Jason Kirk et al. Abstract submitted to AIAA SciTech 2025.

Additional examples and studies exist on the Aviary github repository.

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Acknowledgements: The Aviary Team

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- Xun Jiang (LaRC)
- Jason Kirk (LaRC)
- Kenneth (Ken) Moore (GRC)
- Carl Recine (ARC)
- Herb Schilling (GRC)
- Chris Bennett (LaRC)
- Kaushik Ponnappalli (GRC)

Past Members

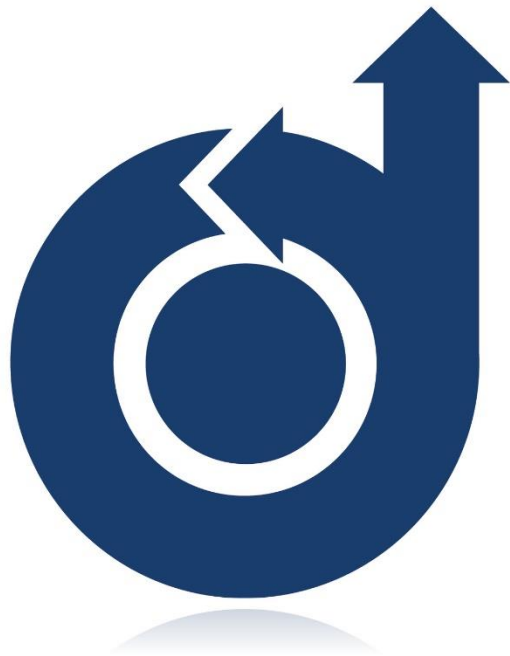
- Darrell (DJ) Caldwell (LaRC)
- Jeff Chapman (GRC)
- Jennifer Gratz (GRC)
- Kenneth (Kenny) Lyons (ARC)

Past Members continued

- Ben Margolis (ARC)
- Samara Murri (formerly LaRC)
- Erik Olson (formerly LaRC)
- Dahlia Pham (ARC)
- Janet Ross (LaRC)
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- Eric Hendricks (GRC)
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