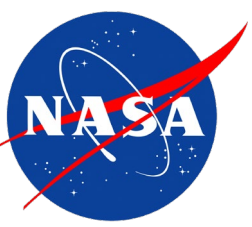


Conjunction Assessment Risk Analysis

Conjunction Sensitivity to Atmospheric Density Modeling

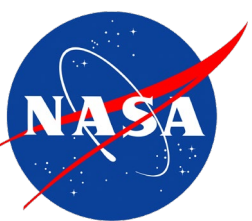
Dolan E. Highsmith, Ph.D.
NASA CARA Chief Engineer
The Aerospace Corporation



Agenda



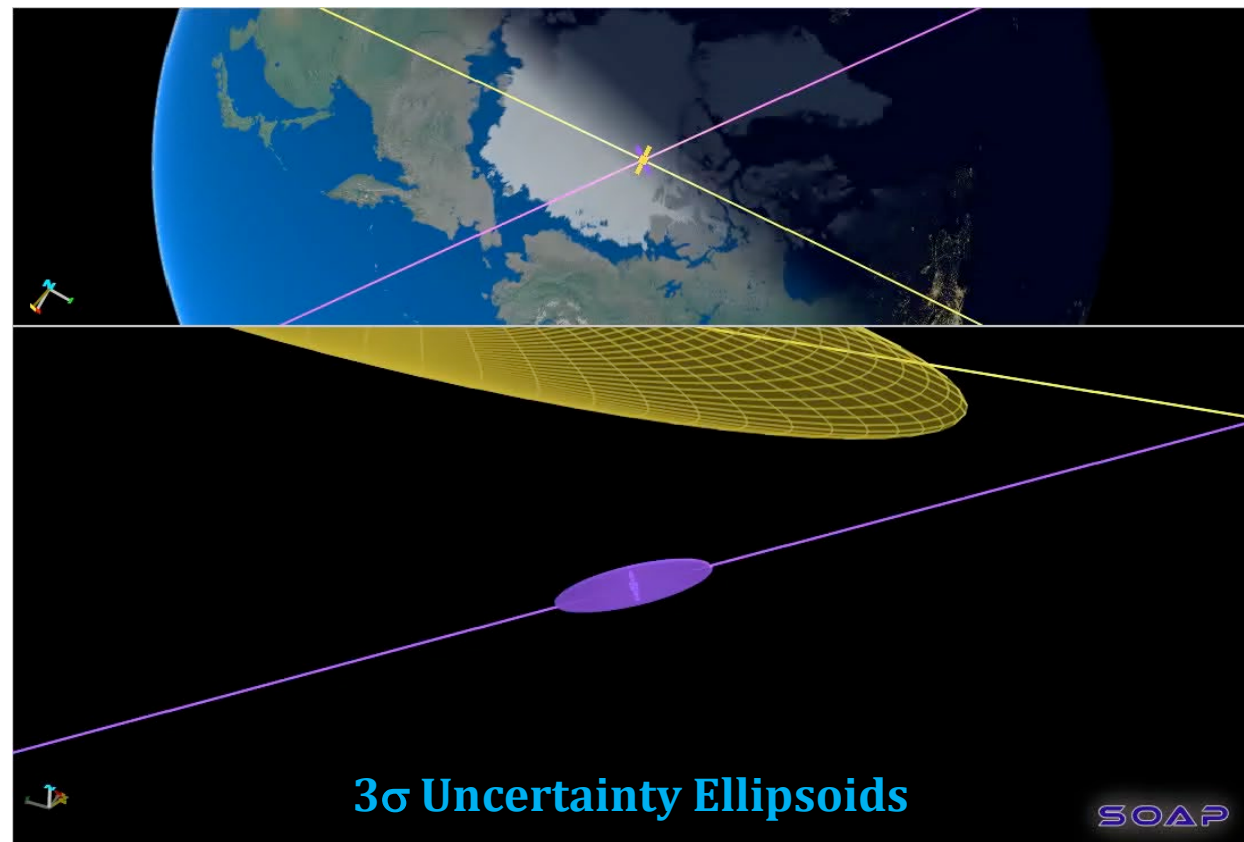
- **Conjunction Assessment Overview**
- **Ephemeris Generation**
- **Probability of Collision Sensitivity to Density Accuracy & Uncertainty**
- **Conclusion & Way Forward**



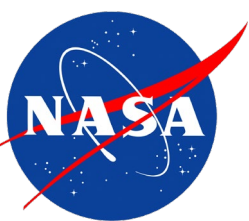
Probability of Collision (P_c)



- **CARA screens fleet against resident space object (RSO) catalog for close approaches**
- **Risk expressed as P_c**
 - Likelihood that, given the uncertainties in the two satellites' predicted trajectories, actual miss distance will be less than combined size of satellites
- **Both propagation accuracy and uncertainty are important**



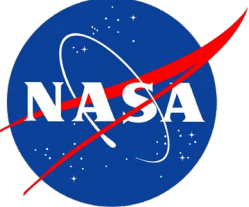
- **Example:**
 - Close approach distance = 185 m
 - $P_c = 9.51E-04$ (1 in 1051)



Ephemeris Generation



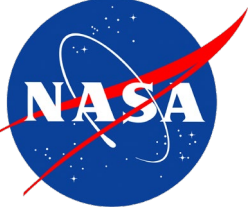
- **Two ephemeris sources for CARA supported missions:**
 - USSPACECOM high accuracy catalog (HAC) (all missions)
 - Owner/operator (O/O) navigation teams (maneuverable missions)
- **Various tools & mission requirements**
 - e.g., gravity recovery (precision OD) vs. astronomical observatory (precision pointing)
 - Some missions' performance driven by conjunction assessment requirements
- **Accurate conjunction assessment requires *prediction accuracy***
 - Position & velocity at TCA with realistic covariance that fairly represents expected uncertainties
 - For LEO satellites, neutral density models drive both prediction accuracy and covariance realism



State Estimate Errors: Atmospheric Drag



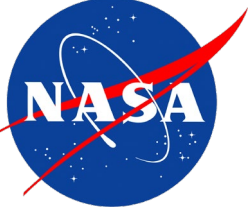
- **Atmospheric drag magnitude:** $a_{drag} = \frac{1}{2}\beta\rho v^2$
- **Ballistic coefficient ($\beta=C_D A/M$) solved for in OD; included in covariance**
 - Accounts for errors in C_D , Area, Mass, and ρ by scaling entire drag acceleration
- **Errors in ρ can be considerable**
 - In general not characterized well and not separately included in covariance
 - Some improvement with inclusion of dynamic consider parameter (DCP) in covariance to compensate for atmospheric density prediction error
- **Errors in ρ become drag acceleration errors, which cause in-track (primarily) and radial (secondarily) errors in the orbit**
- **While state estimate accuracy desirable, probably more important to conjunction assessment to have good state error estimate**
 - With this, meaningful Pc can be calculated and enable decisions
- **Increased focus needed on density model error analysis**



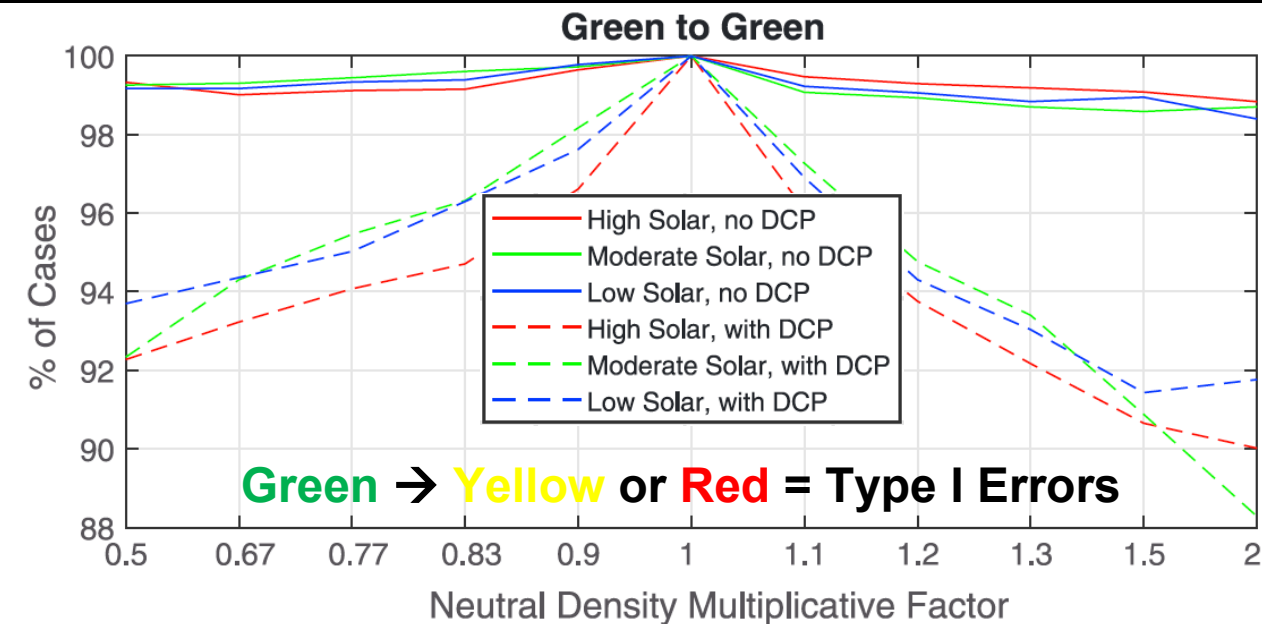
Atmospheric Density Error Experiment: Effect on Calculated P_c



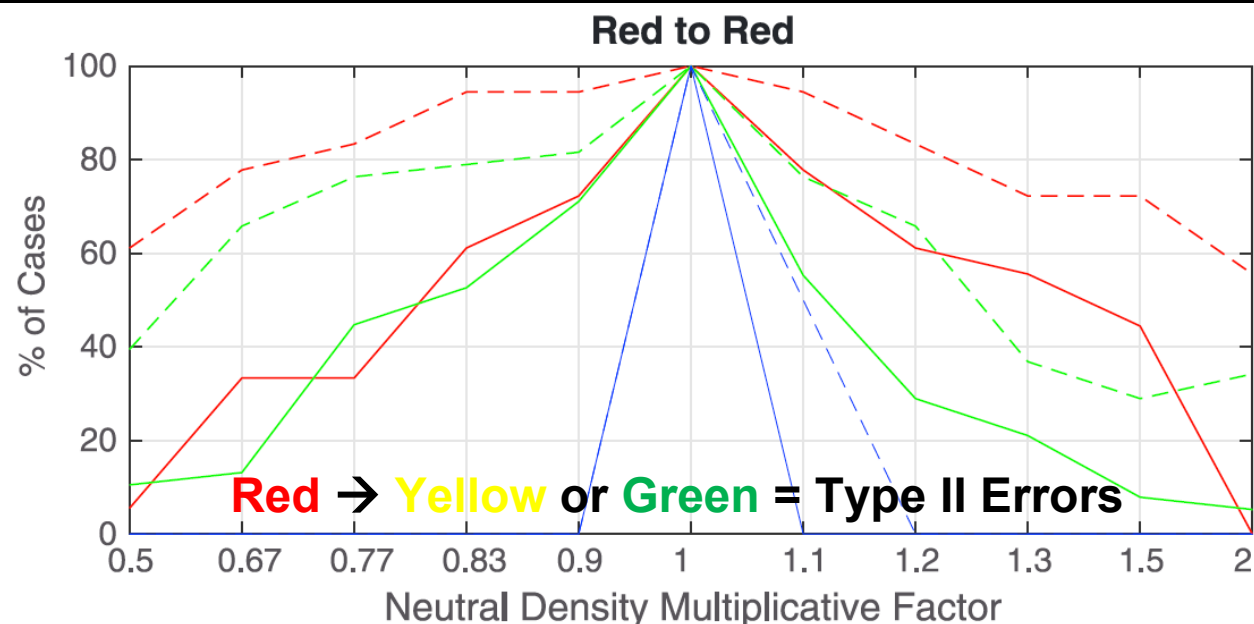
- **Reprocess historical conjunctions, introducing error into ρ**
 - Reduce and increase ρ by up to 100%
- **Observe change in calculated P_c , in two modes**
 - Covariance unaltered
 - Covariance altered to account for introduced error
 - Emulates case in which expected error in ρ known
- **Best way to summarize results is by event “color,” which gives severity**
 - **Red**: $P_c \Rightarrow 1E-04$; most serious event—remediation usually pursued
 - **Yellow**: $1E-07 \leq P_c < 1E-04$; can become serious—event monitored
 - **Green**: $P_c < 1E-07$; event essentially ignored
- **Event color changes examined as error in ρ introduced**
- **Effect on event stability if amount of ρ error known *a priori***



Density Error Effect on Pc: Experimental Results

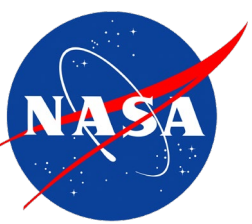


- **Type I error: green events that, with error, misclassified as yellow or red (“false alarm”)**
 - Percent of affected events small (only a few percent)
 - Compensated covariance produces more deviation, but at least in conservative direction



- **Type II error: red events that, with error, misclassified as green or yellow (“missed detection”)**
 - Uncompensated covariance pushes a larger number to green or yellow
 - Much more problematic, as these events not likely to be remediated

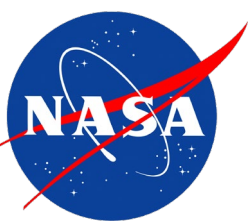
Density model accuracy matters significantly, but knowledge of model error can blunt effect substantially



Conclusion



- **Conjunction assessment mission substantially affected by accuracy of atmospheric modeling**
 - More accurate modeling allows more actionable P_c
- **However, simply knowing expected model error allows error compensation and both a correct and more stable P_c**
- **Important to pursue both, but accuracy improvements without error statement much less useful than if active error modeling included**



Way Forward



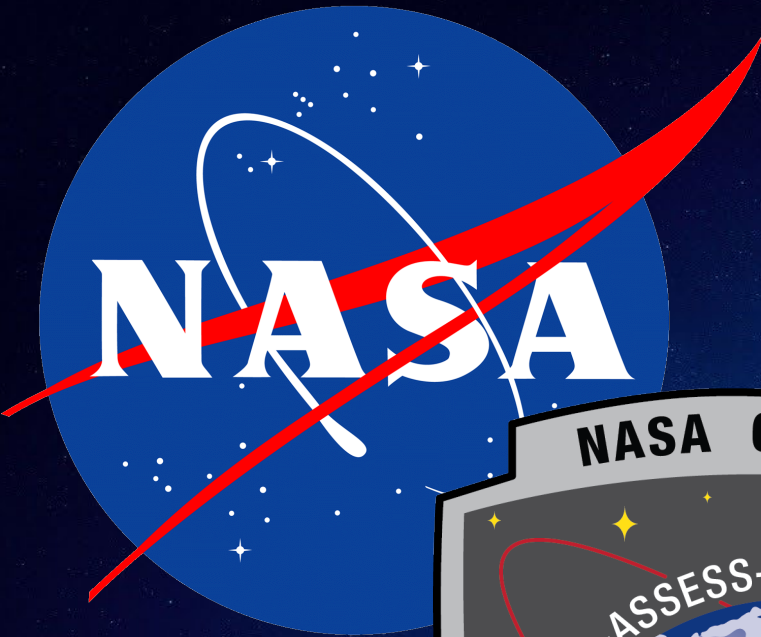
- **Develop error budget for density prediction**

- Quantitatively account for uncertainty in each contribution to enable roll-up of a total density uncertainty value
 - Distinguish biases from time-dependent errors (i.e., rates of error growth)
 - As modeling improvements are made to a specific contributor, its error budget amount can be reduced
- Include solar & geomagnetic indices/proxies, winds, atm constituents, etc.

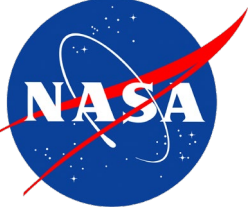
- **Result could be separately accounted in drag uncertainty**

- Spacecraft team would provide uncertainty on ballistic coefficient, strictly for uncertainties in C_D , area, and mass (i.e., not a *drag* scale factor)
- Would enable more refined tuning of predicted covariance to achieve better realism

Conjunction Assessment Risk Analysis



Questions?



Conjunction Event Pc Progression

- **Conjunction usually first discovered 7 days before time of closest approach (TCA)**
 - Covariances large, so typically Pc well below maximum (**A**)
- **As event tracked and updated, changes to state estimate are relatively small, but covariance shrinks**
 - Because closer to TCA, less uncertainty in projecting positions to TCA (**B**)
- **Theoretical maximum Pc encountered when 1-sigma covariance size to miss distance ratio is $1/\sqrt{2}$ (**C**)**
 - After this, Pc usually decreases rapidly (**D**)
- **Improving position accuracy thus has effect on Pc that is difficult to predict**
 - More accurate calculation, but Pc could increase or decrease
 - Covariance realism critical for accurate calculation of Pc

