# The Interacting Roles of Attention Allocation and Trust in Highly Automated AAM Environments

Yusuke Yamani



#### Who I am

- M.S. in Human Factors (Institute of Aviation) and Ph.D. in Psychology (Visual Cognition and Human Performance) from the University of Illinois at Urbana-Champaign
- Post-doc in Industrial Engineering (Surface Transportation Human Factors) at the University of Massachusetts at Amherst and Liberty Mutual Research Institute of Safety
- Associate Professor in the Department of Psychology and the Department of Civil and Environmental Engineering at ODU
- Collaborating with NASA LaRC since 2021

#### Program of Research

Mechanisms of attentive visual processing

- Attention control
- Visual search
- Eye movement
- Aging and Individual differences

Limits of human performance in applied environment

- Complex displays
- Machine operation
- Surface transportation
- Advanced air mobility
- Nuclear operation

Methods to ameliorate human cognitive performance

- Human-Machine Interface
- Human-Autonomy/Al Teaming
- Human-Systems Integration
- Training

Basic

**Applied** 

Theory-Inspired Applied Research

#### History of ODU-NASA LaRC Collaboration

2021
Foundational
Research
Using MATB-II

2022
2 HFES
Proceedings
MATB-II
experiments
with eye
tracking

2023

NSF REU

2 HFES

Proceedings

Trust &
Attention
Experiment
NSF REU
Tetsuya Sato,
Ph.D.

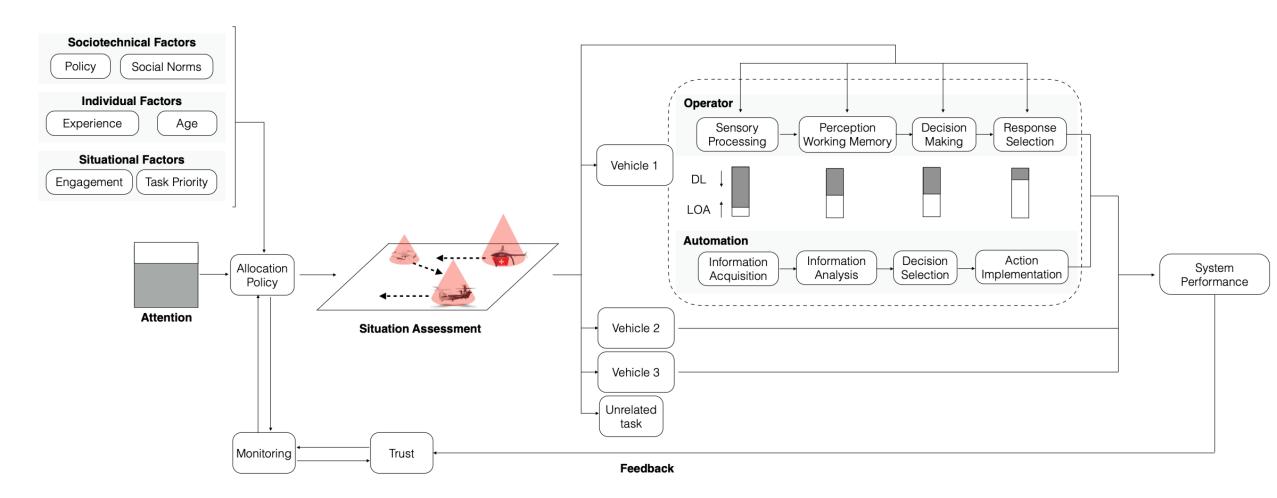
2025 **ISAP** 2 HF Journal **Publications** 1 Book Chapter HFES **Proceedings** Prospective MS (Austin Jackson) More to come...

"Foundational human-autonomy teaming research to enable advanced air mobility operations"





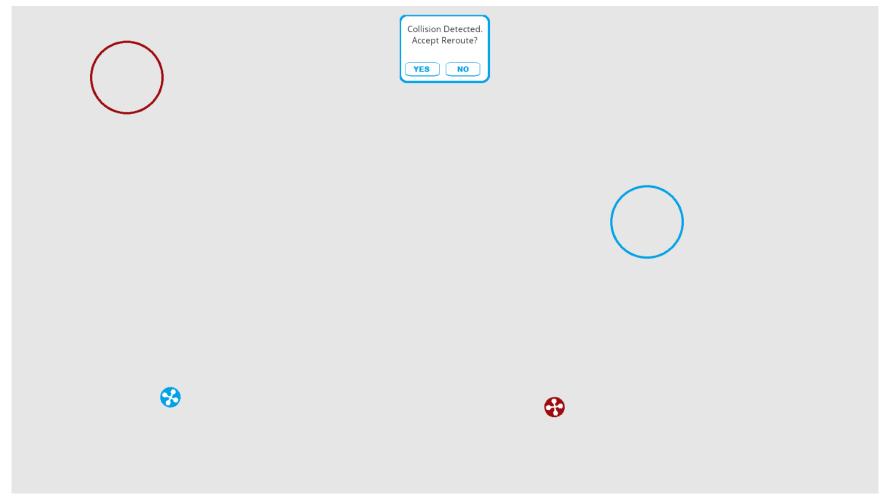
## Human-Technology Interaction in AAM



Yamani et al. (2024)



## Multi-Action Planning Task



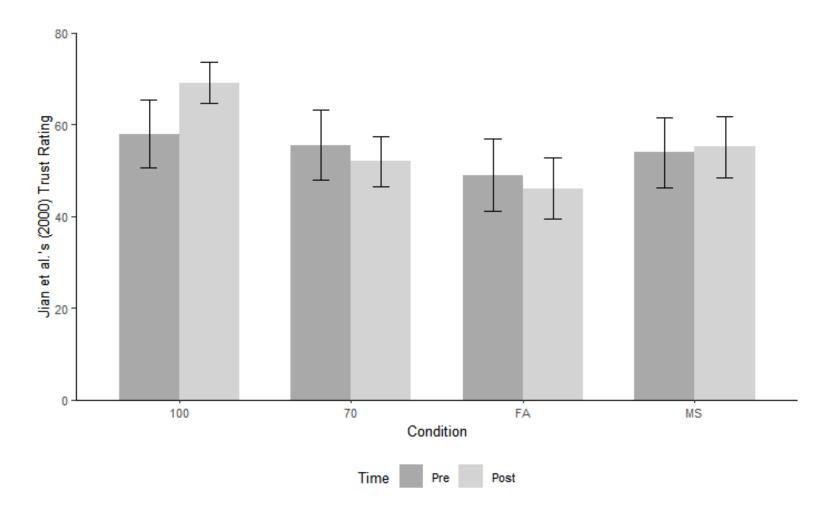


### **Experimental Design**

- IV
  - Reliability
    - 100, 70, 70FA, 70MS
- DV
  - Performance
  - Trust (Jian et al., 2000; Chancey et al., 2017)
  - Dependency
    - Compliance: Operator's agreement with automation when there is a signal
    - Reliance: Operator's agreement with automation when there is no signal

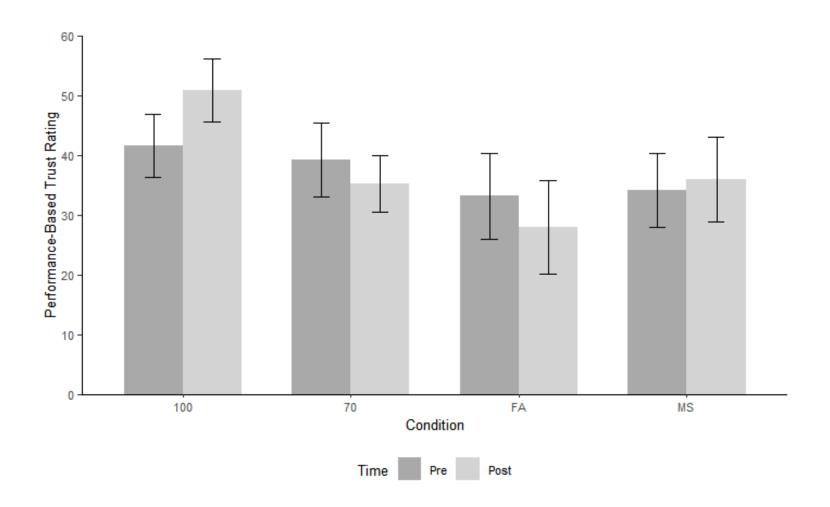


# Results: Jian et al. (2000) Trust



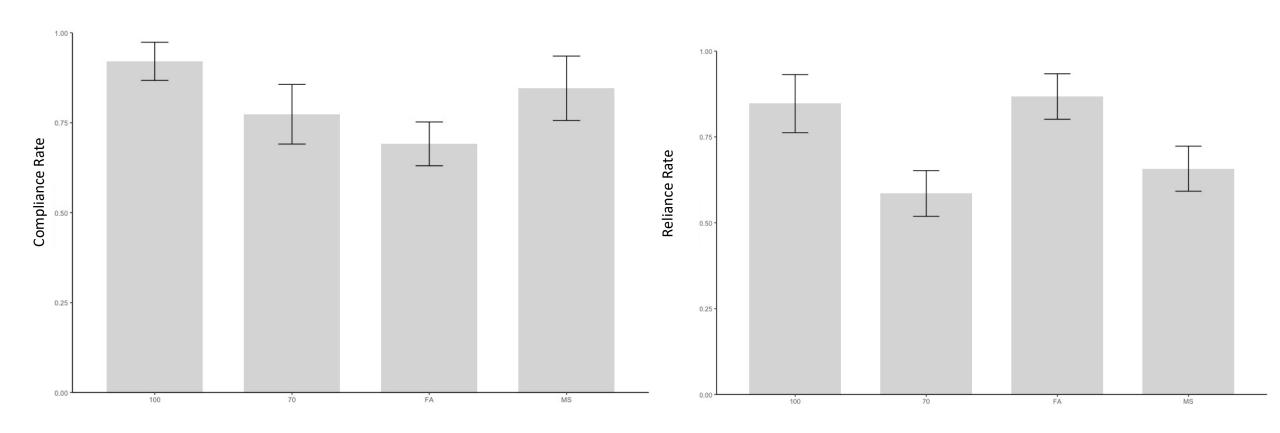


## Results: Chancey et al. (2000) Trust





# Results: Dependency Behavior



#### Discussion

- Automation aids with 70% reliability, regardless of error bias, led to lower levels
  of trust than 100% reliable automation
- False alarms and misses influenced trust similarly across different dimensions
- The experiment replicated asymmetrical effects of automation errors types on compliance and reliance (Chancey et al., 2017)
- Automation designers should consider that error bias can systematically modulate dependency behavior, and work to create transparent systems that properly calibrate operator trust to the automated system

### **Current Experiment**

 Previous experiments featured unrealistically high error rates (~30%)

 Can we measure changes in operator workload and readiness to intervene highly automated and reliable AAM

in a monitoring task?

Scenarios in MPATH

• Data entry task + DRT (Stojmenova & Sodnik, 2018)

