

Hermes Environment Risk Mitigation Executive System (HERMES)

Applications for safe autonomous aircraft operations

2026 NASA Core Flight Systems (cFS) Symposium

By:

Cuong C. Quach “Patrick” (Presenter)

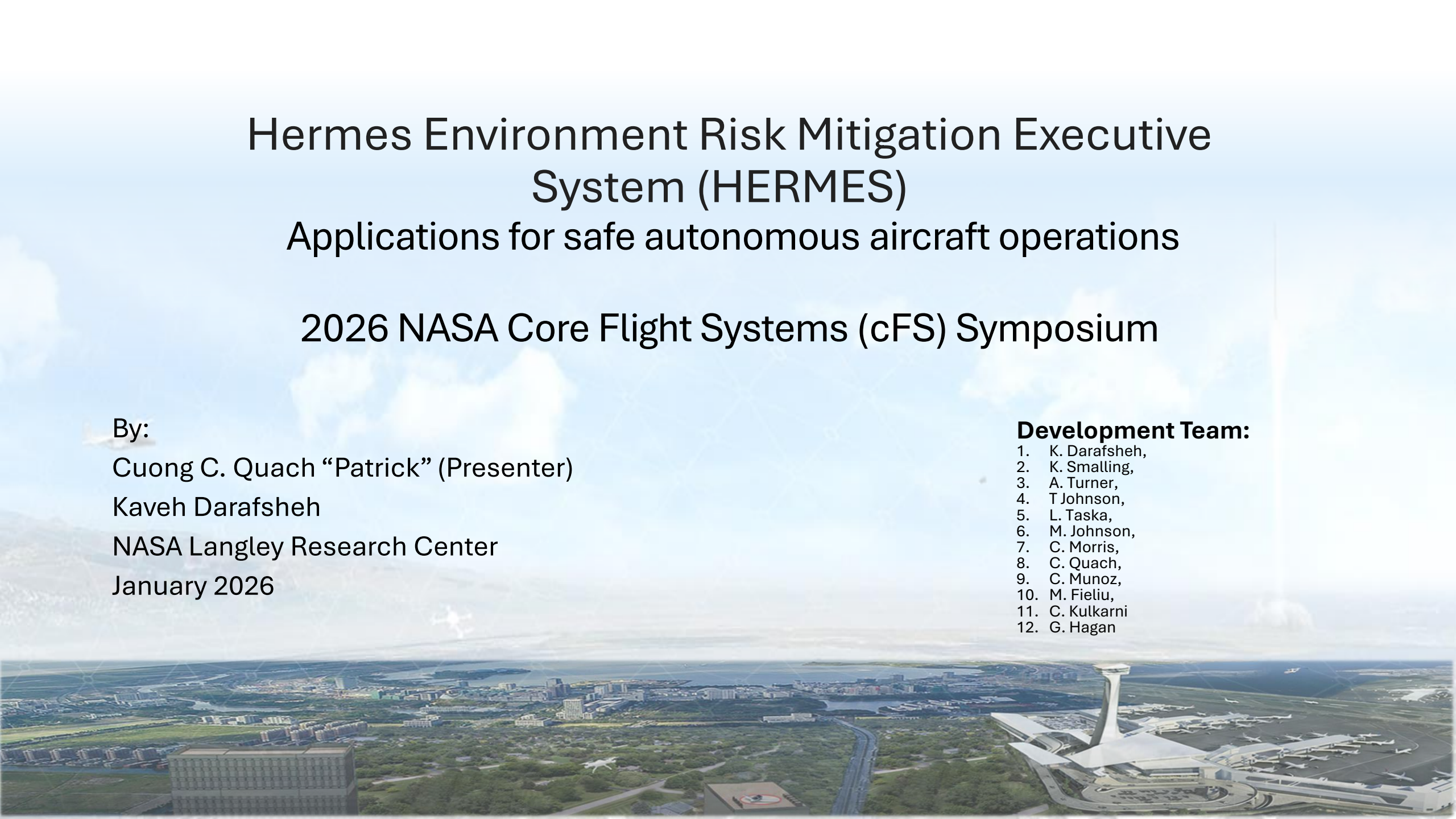
Kaveh Darafsheh

NASA Langley Research Center

January 2026

Development Team:

1. K. Darafsheh,
2. K. Smalling,
3. A. Turner,
4. T Johnson,
5. L. Taska,
6. M. Johnson,
7. C. Morris,
8. C. Quach,
9. C. Munoz,
10. M. Fieliu,
11. C. Kulkarni
12. G. Hagan



Safety functions to facilitate urban drone operations for commercial and first responder use cases.

- Monitoring vehicle states such as battery usage, navigation status, link status, autopilot status.
- Monitor flight path for terrestrial obstructions hazards, traffic, and staying in operating area.
- Risk based assessment and contingency decision making.
- Integrates with ground systems for data exchange and test tools interaction.

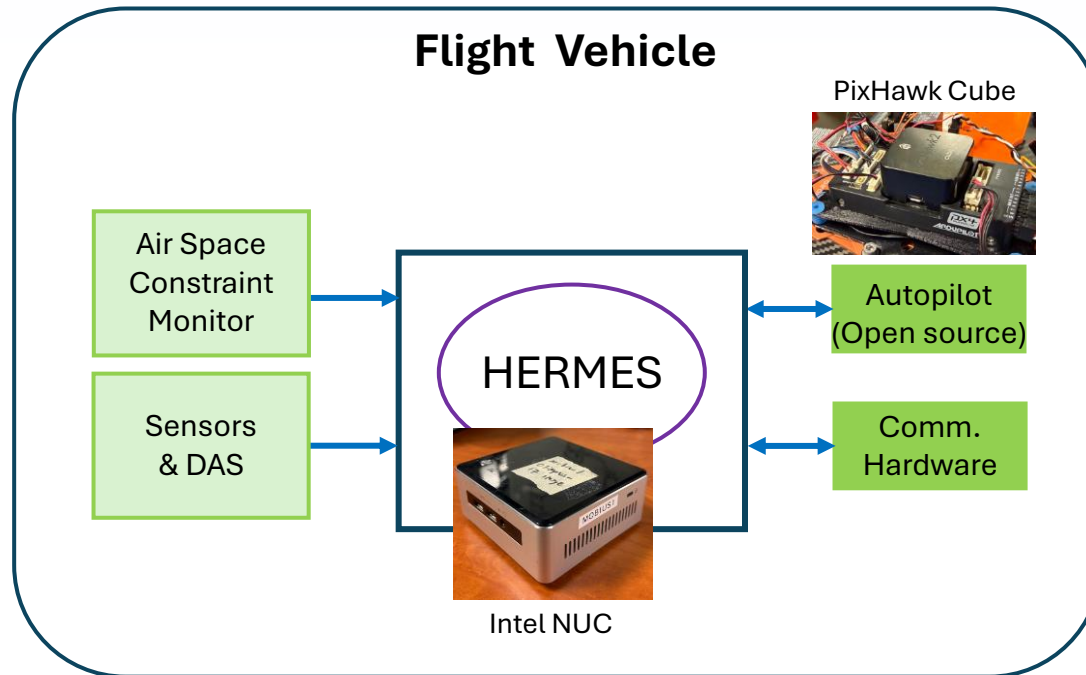
Historical Context

- **~2009-2014:** Integrate diagnostic and prognostic with multi-layer supervisory control.
- **~2012-2016:** Integrating prognostics with spacing and sequencing algorithms, during airport approach pattern. Testing with Robot Operating System(ROS), Internet Computing Engine(ICE). Migrate to cFS for flexibility to expand on-board capability.
- **~2016-present:** Safety functions to facilitate urban drone operations. Building on cFS application suite.

Extra 260 (40%, 10' span)



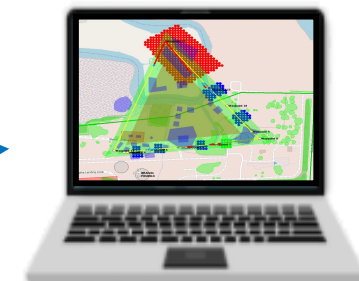
Tarot T-18



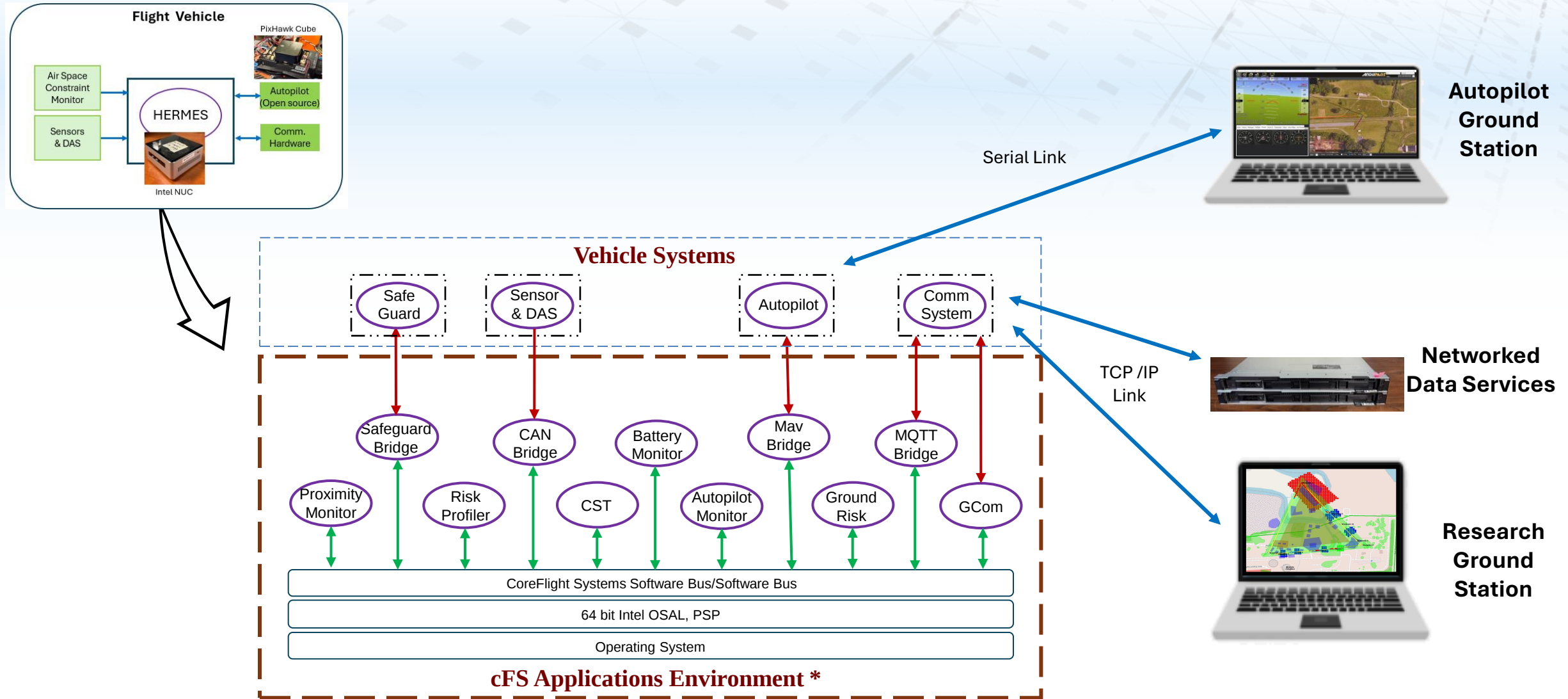
**Autopilot
Ground
Station**



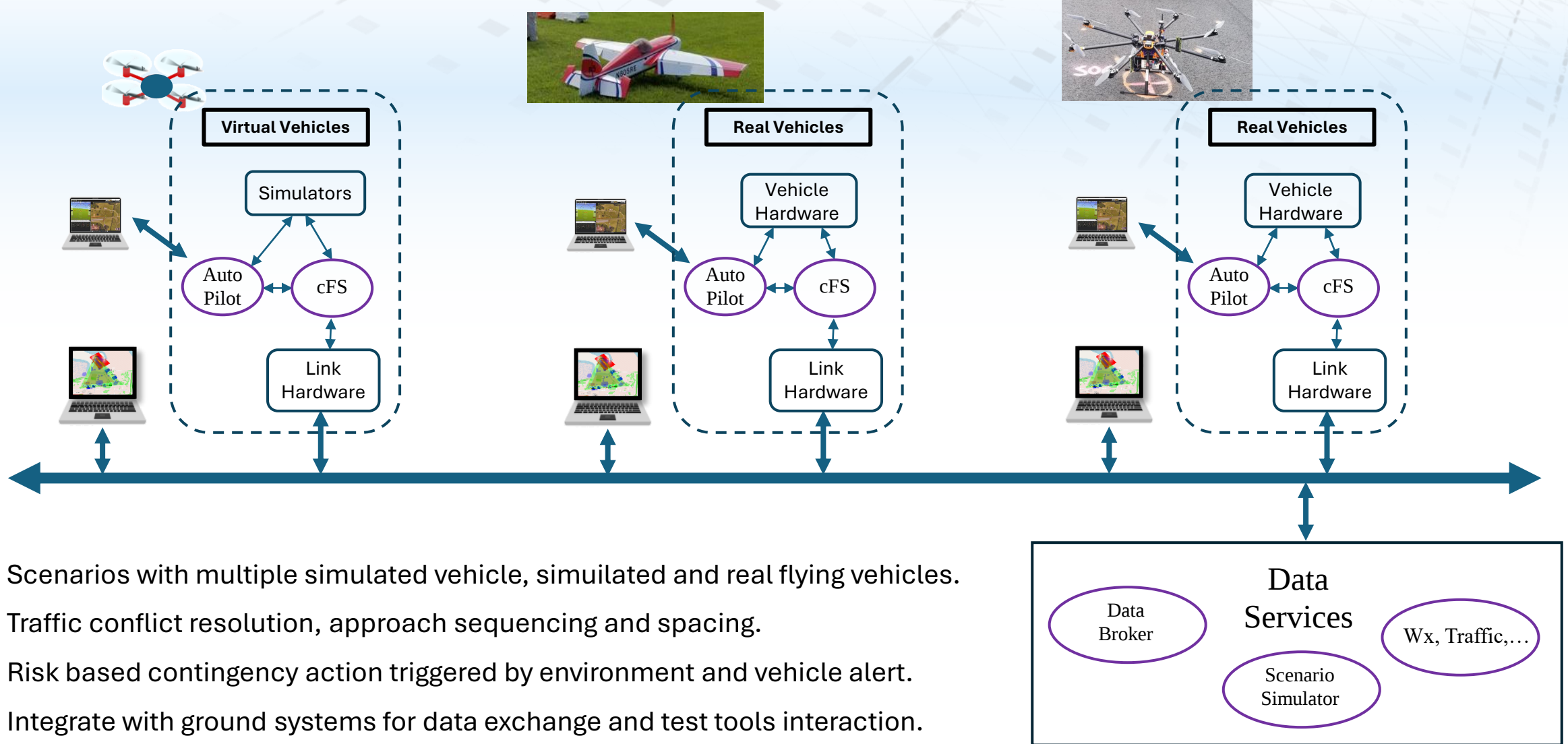
**Networked
Data Services**



**Research
Ground
Station**



** Recent cFS applications testing. Past collaborative work (Sequencing and spacing, PLEXIL integration, ...) not shown.*



- Scenarios with multiple simulated vehicle, simulated and real flying vehicles.
- Traffic conflict resolution, approach sequencing and spacing.
- Risk based contingency action triggered by environment and vehicle alert.
- Integrate with ground systems for data exchange and test tools interaction.

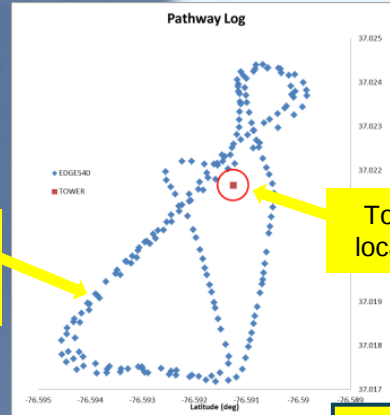
Early Augmented Reality (AR) Flights – State based separation testing



On-board software de-conflicts using state based solver.



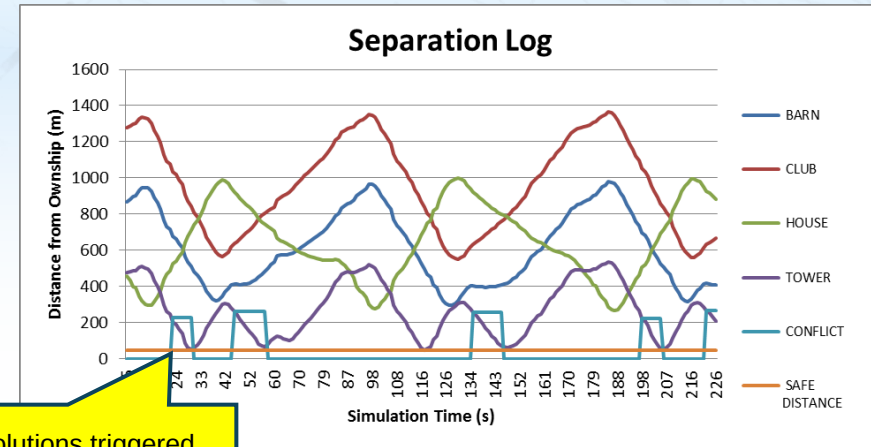
Ownship
GPS
History



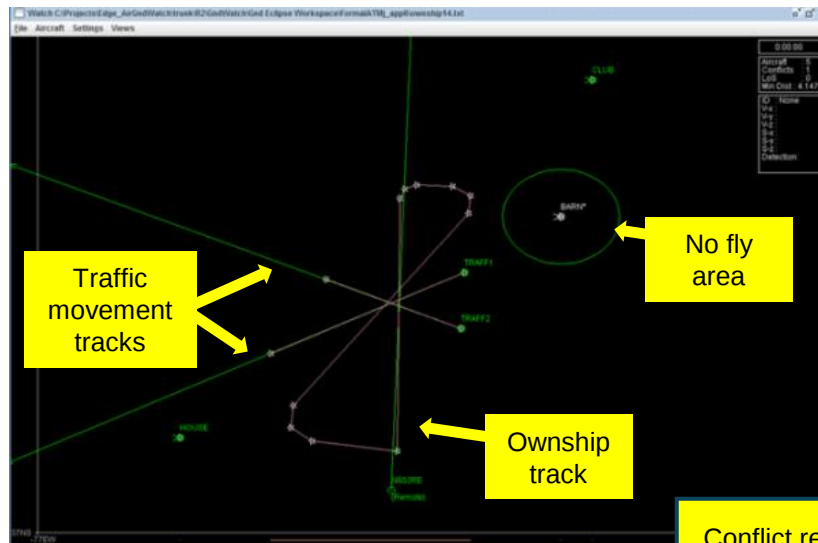
Tower
location

Conflict resolutions triggered

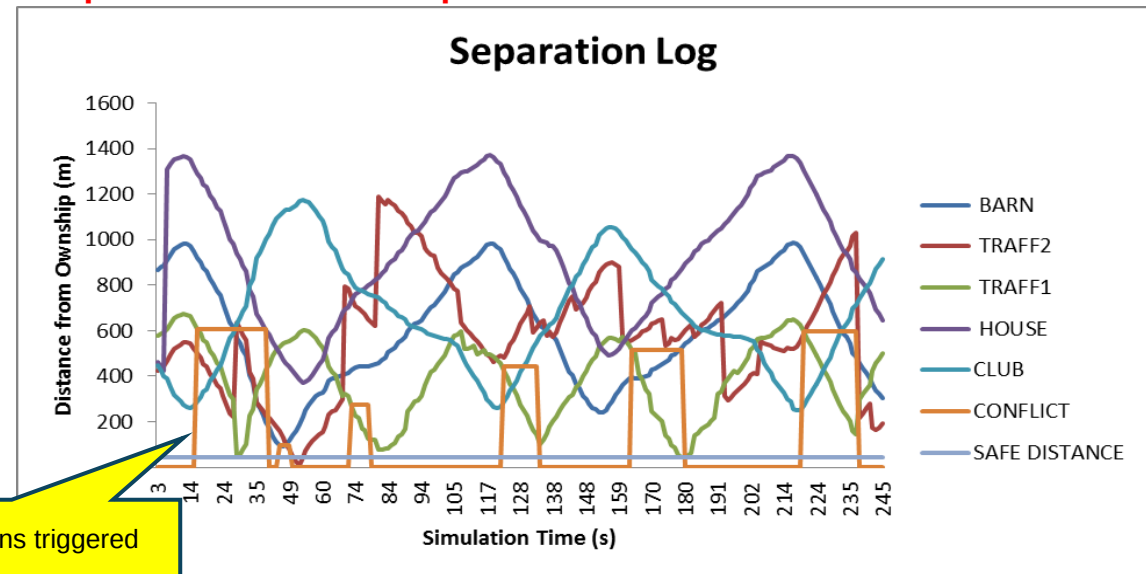
Tower Separation Scenario – Track variance



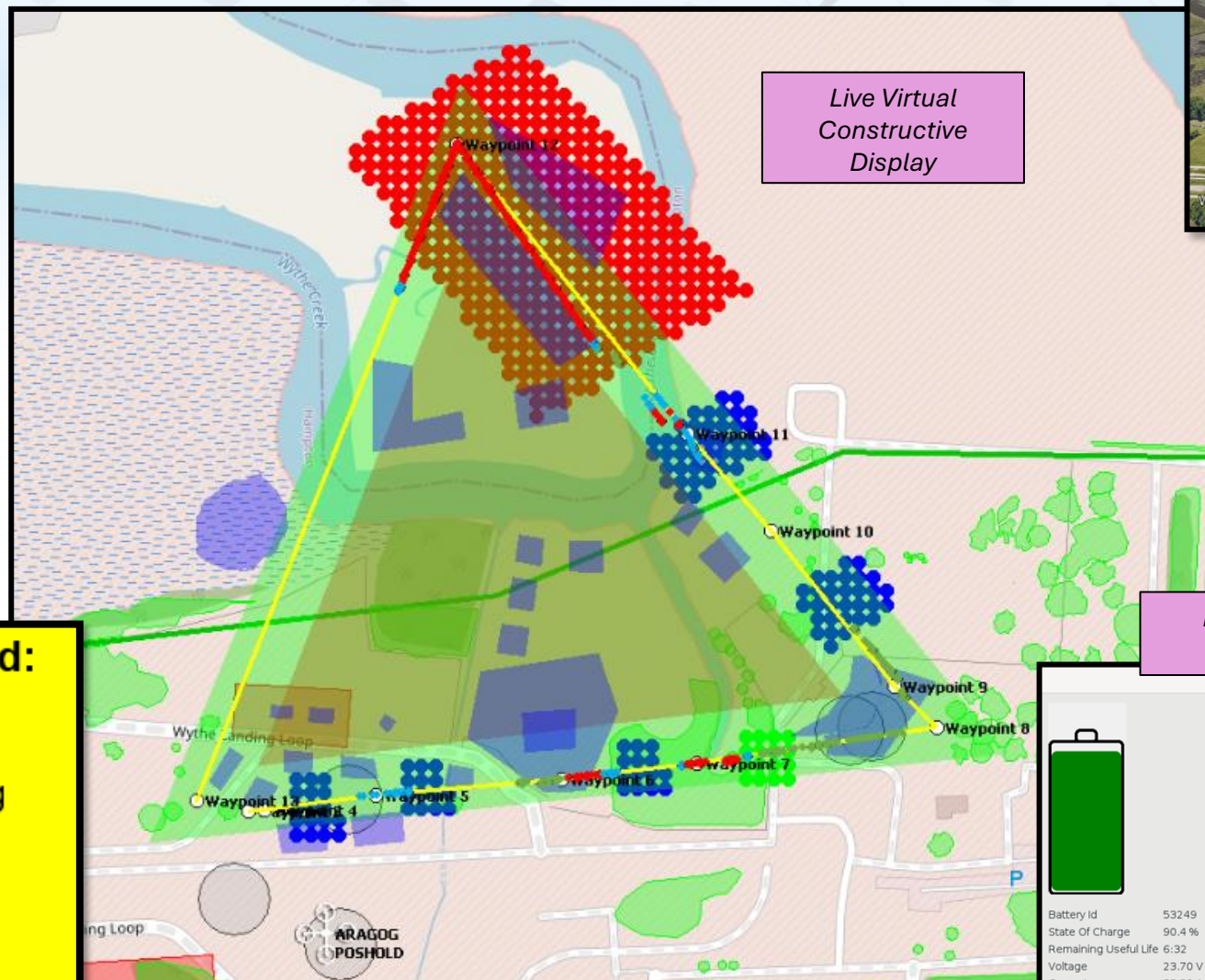
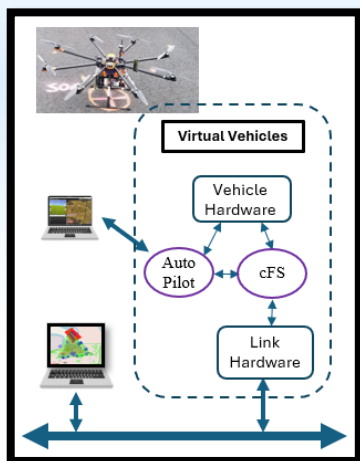
Forward and broad side separation Scenario – Speed variance



Conflict resolutions triggered



Single agent decision testing.

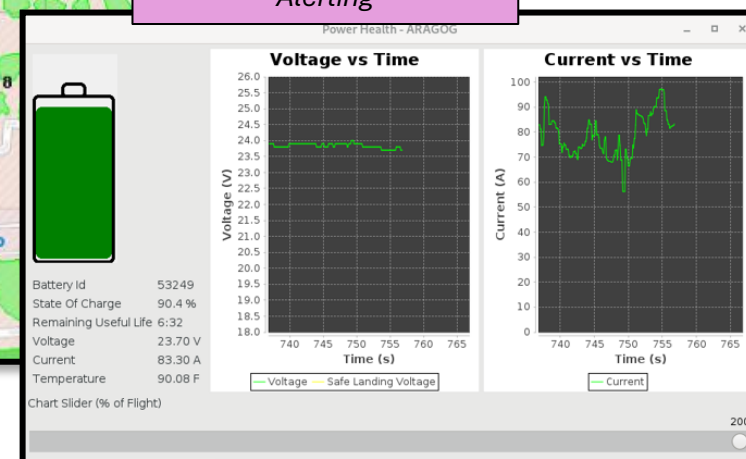


Simulated city created for risk based decision algorithm test

cFS Applications Tested:

- Proximity alerting
- Ground population alert
- Airspace constrain alerting
- Battery alerting
- Risk assessment
- Autopilot state transition monitoring
- Decision execution

Battery Monitor and Alerting



- cFS is key enabler for UAS safety applications development and flight testing.
- cFS applications developed over several projects being updated for release.
- Current work focused on cFS applications for pro-active decision support with more emphasis on air traffic management use cases.

References:

1. “Architecture and Information Requirements to Assess and Predict Flight Safety Risks During Highly Autonomous Urban Flight Operations,” Young, S. D., Et Al., NASA TM-2020-220440, 2020
2. “Computing Proximity to Threat Along Uncertain Trajectory to Support Urban Air Mobility”, L. Spirkovska, I. Roychoudhury, C. C. Quach, NASA/TM–20240000892, 2024.
3. “Testing of Advanced Capabilities to Enable In-time Safety Management and Assurance for Future Flight Operations”, A. J. Moore, Et Al., NASA/TM–2023001866, 2023.
4. “Testing a Run-Time Assurance Framework Coupled with Integrated Risk Mitigation Capabilities for Autonomous Urban UAS Flights”, Ancel, E., Moore, Et Al., AIAA DATC/IEEE 43rd Digital Avionics Systems Conference (DASC).
5. “Performance of Two Battery Prognostic Applications used by Two Octocopters for Safe Low Altitude Autonomous Flight Operations”, Hogge, E. F., Kulkarni, C. S., Eure, K., Darafsheh, K., Vazquez, S. L., Smalling, K. M., Quach, C. C., NASA/TM-2023-0012868, June 2023.
6. “Flight Testing In-Time Safety Assurance Technologies for UAS Operations”, Young, S. D., Ancel, E., Dill, E. T., Moore, A. J., Quach, C. C., Smalling, K. M., and Ellis, K. K., Aviation Forum 2022, American Institute of Aeronautics and Astronautics, Chicago, IL, 2022 (submitted for publication).
7. “Design and Testing of an Approach to Automated In-Flight Safety Risk Management for sUAS Operations”, Ancel, Ersin, Young, Steven D., Quach, Cuong C., Haq, Rafia F., Darafsheh, K., Smalling, K. M., Vazquez, S. L., Dill, E. T., AIAA Aviation Forum 2022. Chicago, IL June 27 to July 1, 2022.
8. “GroundWatch: Ground Station Tool for UAS Autonomy Research Flight Operations”, A. Turner, C. C. Quach, Y. E. Santiago, K. Smalling, S. L. Vazquez, L. Smith, NASA/TM-20250005489, 2025.