RADIATIVE COUPLED VISCOUS FLOW WITH MASSIVE BLOWING

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An analysis of the fully-coupled viscous, radiating flow past an ablating blunt body at hyperbolic entry conditions is presented. A detailed thermodynamics computation, as well as a realistic radiation transport model, is included. A locally nonsimilar approach is employed to solve the conservation equations away from the stagnation point. The validity of the locally nonsimilar approach is demonstrated for some nonablating cases. Sample calculations are made for the typical flight condition of a Jovian entry probe. The effects of the downstream injection of the ablation products of a carbon heat shield on the flux distribution around the body are discussed in detail. It is found that most of the radiative energy is absorbed by the injected carbon gas and dumped into the wake.
An analysis of the fully coupled viscous, radiating flow past an ablating blunt body at hyperbolic entry conditions is presented. A detailed thermodynamics computation, as well as a realistic radiation transport model, is included in this analysis. A locally nonsimilar approach is employed to solve the conservation equations away from the stagnation point. The validity of the locally nonsimilar approach is demonstrated for some nonablatlng cases. Sample calculations are made for the typical flight condition of a Jovian entry probe. The effects of the downstream injection of the ablation products of a carbon heat shield on the flux distribution around the body are discussed in detail. It is found that most of the radiative energy is absorbed by the injected carbon gas and dumped into the wake. A companion report, (NASA CR-2235) is available of the SL-4 Code and instructions for operation.
NOMENCLATURE

\( B(y, v) \)  Planck function
\( C_v \)  Mass fraction of the ablation gas
\( C_{v\xi} \)  \( \frac{\partial C_v}{\partial \xi} \)
\( \bar{C}_v \)  \( \beta_{lv\xi} \)
\( D \)  Effective binary diffusion coefficient
\( D_{s(o)} \)  Binary diffusion coefficient behind the shock at stagnation point
\( f \)  \( u/u_s \), normalized tangential velocity
\( f_{\xi} \)  \( \frac{\partial f}{\partial \xi} \)
\( F \)  \( \beta_{lf\xi} \)
\( F_r \)  Radiative flux
\( F_{rw} \)  Radiative flux at wall
\( F_{rw}(\dot{M}=0) \)  Radiative flux at wall when injection rate is zero
\( H \)  Total enthalpy, also normalized total enthalpy, normalized by \( H_s \)
\( H_{\xi} \)  \( \frac{\partial H}{\partial \xi} \)
\( \bar{H} \)  \( \beta_{lH\xi} \)
\( h \)  Static enthalpy, also normalized static enthalpy, normalized by \( H_s \)
\( I(v, y, \Omega) \)  Spectral radiation intensity
\( \tilde{K} \)  \( 1-k_y \)
\( k \)  Shock curvature
\[ \dot{M} \quad \text{Total injected mass flow per unit area as a function of } r_w \]

\[ p \quad \text{Pressure} \]

\[ Pr \quad \text{Prandtl number} \]

\[ Q \quad \text{Radiative flux divergence} \]

\[ r \quad \text{Distance measured from axis of symmetry} \]

\[ R_s \quad \text{Shock radius of curvature at stagnation point} \]

\[ Re \quad \text{Reynolds number } \rho \infty u R / \mu_s (o) \]

\[ Sc \quad \text{Schmidt number } \mu_s (o) / \rho \infty D_s (o) \]

\[ T \quad \text{Temperature} \]

\[ T_s (o) \quad \text{Temperature behind the shock at stagnation point} \]

\[ u \quad \text{Tangential velocity, velocity component parallel to the shock} \]

\[ U_\infty \quad \text{Free stream velocity} \]

\[ v \quad \text{Velocity component perpendicular to the shock} \]

\[ x \quad \text{Distance parallel to the shock measured from stagnation line} \]

\[ y \quad \text{Distance normal to the shock} \]

\[ z \quad \text{Distance along the line of symmetry from the shock stagnation point} \]

\[ \mu \quad \text{Viscosity} \]

\[ \mu_s (o) \quad \text{Viscosity behind the shock at stagnation point} \]

\[ \alpha (v,y) \quad \text{Absorption coefficient} \]

\[ \alpha_i \quad \text{Elemental gas mass fraction} \]

\[ \beta_1 \ldots \beta_5 \quad \text{Parameters defined by Eqs. (11) and (12)} \]

\[ \Delta \quad \text{Shock layer thickness} \]

\[ \xi \quad \text{Transformed variable } \xi = x \]

\[ \eta \quad \text{Normalized stream function defined by Eq. (7)} \]
Stream function

$\psi$  
Stagnation point density ratio across the shock

$\epsilon$  
Frequency

$\nu$  
Density

$\omega$  
Parametric variable defined by Eq. (21)

Subscripts

$s$  
Quantities at shock

$b$  
Quantities at body

$w$  
Quantities at wall

$\infty$  
Freestream conditions

$\xi$  
Partial derivative with respect to variable $\xi$. 

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1.0 INTRODUCTION

The purpose of the present study is to investigate the effect of surface blowing on the thermal environment of a vehicle entering planetary atmospheres at hyperbolic speed. Most of the earlier studies which included the effect of ablation products are confined to the stagnation region (Refs. 1-5). The only solutions obtained away from the stagnation region appear to be that of Olsted's (Ref. 6). Olsted adapted a two layer inviscid model and treated air to air surface injection only. Since no diffusion mechanism is allowed in the inviscid model, it probably is too crude an approximation for treating the effect of ablation products. In the present report, we study the thin-radiating shock layer about blunt bodies with surface mass injection, and do not restrict the analysis to the stagnation region. Viscous effects, as well as diffusion of the injected materials, will be considered.

In our previous work, reported in Ref. 7, solutions for a thin radiating shock layer about blunt bodies without blowing were obtained by a locally nonsimilar approach. Perfect gas and constant transport properties were assumed and only the continuum radiation was considered. Due to these simplifications, especially the nonblowing restriction, the results were not quantitatively realistic. Validity of the locally nonsimilar approach in solving the thin shock layer problem was sufficiently demonstrated, however. The work reported herein is a continuation of that of Ref. 7. The additional tasks were to incorporate a realistic radiation transport model as well as more detailed thermodynamic properties; to allow the ablation products to diffuse into the shock layer and to rederive the governing equations so that mass injection rates variable with distance around the body could be treated.

The approximate but still complete treatment of the radiative transport in mixtures of hydrogen, helium, carbon, nitrogen and oxygen developed by Wilson (Ref. 5) was adapted to the present work. In this treatment, continuum radiation is approximated by a twenty-six-band model and atomic line radiation is represented by eleven-line groups. The radiation field, i.e., the flux
and its divergence, is determined by the solution to the one-dimensional radiative transfer equation. The validity of using one-dimensional radiative transfer equations for thin shock layer problems has been demonstrated as adequate in Ref. 8.

The shock layer is assumed to be in thermochemical equilibrium. Hence, given pressure, temperature (or enthalpy) and elemental species concentration at any point in the shock layer, other thermodynamic variables can be completely determined by a Free Energy Minimization procedure. This is implemented in the present work by the FEMP Computer Program, described in detail in Ref. 9. Transport properties for a gas mixture, such as viscosity and heat conductivity, are computed by the approximate formulas of Refs. 10 and 11.

The method of solution employed here is an inverse one, that is to say, the shock is completely specified and the body shape is a part of the solution. For a specific body shape, therefore, iterations would have to be performed on the given shock shape. Fortunately, the problems we will be interested in are thin shock layer problems; namely, the shock shape does not deviate much from the body shape. A good first guess on shock shape can be made and iteration largely can be avoided.

Calculations for a body shape and flight condition, which represents a typical entry of a Jupiter probe, were made. The injected gas is assumed to be pure carbon, and the injection rate is a monotonically decreasing function of shock radius. The radiative heating distribution around the body is presented. This distribution is compared with that of no surface mass injection.
2.0  MATHEMATICAL DEVELOPMENT

2.1  Governing Equations

The conservation equations for an axisymmetric thin shock layer, written in a shock oriented coordinate system (Fig. 1) are:

Continuity
\[
\frac{\partial \rho u r}{\partial x} + \frac{\partial \rho v r}{\partial y} = 0
\]

x-momentum
\[
\rho \frac{\partial}{\partial y} (\mu \frac{\partial u}{\partial y}) - \rho u \frac{\partial u}{\partial x} - \rho v k \frac{\partial u}{\partial y} + \rho k u v \frac{\partial r}{\partial x} = 0
\]

y-momentum
\[
k u \frac{\partial r}{\partial y} + \frac{\partial p}{\partial y} = 0
\]

energy
\[
\frac{\partial}{\partial y} \left[ \mu \frac{\partial H}{\partial y} + \frac{\mu}{2} (1 - \frac{1}{\gamma}) \frac{\partial u}{\partial y}^2 \right] - \rho u \frac{\partial H}{\partial x} - \tilde{k} p v \frac{\partial H}{\partial y} + Q = 0
\]

specie
\[
\frac{\partial}{\partial y} \left( \rho D \frac{\partial C_v}{\partial y} \right) - \rho u \frac{\partial C_v}{\partial x} - \tilde{k} p v \frac{\partial C_v}{\partial y} = 0
\]

The y-momentum equation, Eq. (3), has been simplified according to Maslen's approximation (Ref. 12). The validity of Maslen's approximation has been examined in Ref. 7. In the energy equation, Eq. (4), the Lewis number is assumed to be unity. The symbol \( Q \) represents the radiative flux divergence, the precise form of \( Q \) will be discussed in the next section.

In the specie conservation equation, Eq. (5), \( C_v \) denotes the mass fraction of the ablation gas. Here we have assumed a binary diffusion process, i.e., the ablation gas diffuses as a whole into the shock heated atmospheric gas. The detailed derivation of Eq. (5) can be found in Ref. 1 or Ref. 4. This binary diffusion model will be valid if the gas mixture can be divided into two groups of species, each with about the same atomic or molecular weight and about the same mutual collision cross section. Otherwise, multicomponent diffusion should be considered. For the sake of simplicity, the binary model was used in this study.
Fig. 1. Sketch of Geometry
Once the mass fraction for ablation gas $C_v$ is known, the mass fraction for elemental gas $i$ is given by

$$\alpha_i = (\alpha_{v,i})C_v + (\alpha_{a,i})(1-C_v)$$

(6)

Where $(\alpha_{v,i})$ is the mass fraction of element $i$ in the ablation gas, and $(\alpha_{a,i})$ is the mass fraction of element $i$ in the atmospheric gas. Furthermore, given the $\alpha_i$'s, the species mass fraction can be determined by FEMP.

We now proceed to normalize the variables. The distance $x,y$ and the distance from the axis are normalized by the stagnation point shock radius of curvature $R_s^*$, the velocity $u$ by the freestream velocity $u_\infty$, the density $\rho$ by the freestream density $\rho_\infty$, the pressure $p$ by twice the freestream dynamic pressure $p_\infty u_\infty^2$, the shock curvature $k$ by $1/R_s^*$, the total enthalpy $H$ as well as the static enthalpy $h$ by the total enthalpy immediately behind the shock $H_s^*$, the stream function $\psi$ by $\rho_\infty u_\infty R_s^*$, the viscosity by its value immediately behind the normal shock $\mu_s(0)$, and finally, the radiative flux $Q$ by

$$\frac{2R_s^*}{\rho_\infty u_\infty^3}$$

From here on, the equations are all written in nondimensional form.

Let us divide the shock layer into two sublayers, one is the layer dominated by the atmospheric gas where $\psi > 0$. The other is the layer dominated by the ablation gas where $\psi < 0$. We introduce new independent variables $\xi$ and $\eta$, defined as:

$$\xi(x) = x, \quad \eta(x,y) = \frac{\psi}{\beta_0 r_s^*}$$

$$d\psi = -\rho u r_k dx$$

(7)

where

$$\beta_0 = 1 \text{ for } \psi > 0, \quad \beta_0 = \dot{\mu} \text{ for } \psi < 0$$

$$\dot{\mu} = \frac{1}{2} \left( \int_0^{r_w} (\rho v) w w dr_w - r_s^* \right)$$

$$\dot{\mu} = \frac{1}{2} \left( \int_0^{r_s} (\rho v) w s dr_s - r_s^* \right)$$

(8)
Hence, $\dot{M}$ is the total injected mass flow per unit area as a function of $r_w$. For a thin shock layer we approximate $r_w \approx r_s$. In Eq. (8), $(\rho v)_w$ is the local injection rate which remains to be specified. (Note that $(\rho v)_w$ will be negative according to the present coordinate system.)

By definition, the stream function at shock is $\psi_s = \frac{1}{2} r_s^2$ and at wall is

$$\psi_w = \int_0^{r_s} (\rho v)_w r_s dr_s.$$ Hence the range of our new variable $\eta$ will be from $\frac{1}{2}$ to $-\frac{1}{2}$.

It should be noted that by choosing new variables $\xi$ and $\eta$ the continuity equation, Eq. (1), is satisfied automatically, and the $y$-momentum equation can be integrated to give the pressure field as

$$p = p_s + (\beta_0 \eta - \frac{1}{2}) k_s u_s r_s$$

(9)

Let us now define $f = \frac{u}{u_s}$, then, from the $x$-momentum equation (Eq. (2)), we obtain an equation for $f$ as

$$\frac{f}{2} \frac{\partial}{\partial \eta} \left( \rho u \frac{\partial f}{\partial \eta} \right) + Re \beta_0 \left[ \eta \frac{\partial f}{\partial \eta} - \beta_1 f \frac{\partial \xi}{\partial \eta} - \beta_2 \left( f^2 - \frac{1}{2} \right) \right] = 0$$

(10)

where $f_\xi = \frac{\partial f}{\partial \xi}$ and the superscript of (1) indicates that different $\beta$'s should be used dependent on whether $\eta$ is greater or less than zero. The $\beta$'s are given as the following:

for $\eta \geq 0$

$$\beta_1^+ = \frac{dr_s}{d\xi}, \quad \beta_2^+ = \frac{\beta_1^+ du_s}{d\xi},$$

$$\beta_3^+ = \frac{r_s k_s}{u_s} (\beta_1^+ - 1) + \beta_1^+ \frac{r_s}{u_s} \frac{dk_s}{d\xi},$$

$$\beta_4^+ = \frac{\beta_3^+}{2} + \frac{k r_s}{u_s},$$

$$\beta_5^+ = \frac{r_s}{u_s} \frac{dr_s}{d\xi}$$

(11)
for \( \eta \leq 0 \)

\[
\beta^-_1 = \frac{r M}{s} \frac{d r_s}{d \eta} + \frac{r_s d M}{2 d \eta}, \quad \beta^-_2 = \frac{r_s}{u_s} \frac{d u_s}{d \eta}
\]

\[
\beta^-_3 = M \frac{r_s k_s}{u_s} (\beta^-_2 - 1) + \beta^-_1 \frac{r_s}{u_s} \frac{d k_s}{d \eta} + \frac{r_s}{u_s} \frac{d M}{d \eta}
\]

\[
\beta^-_4 = \frac{\beta^-_3}{2} + \frac{k_s r_s}{u_s}
\]

\[
\beta^-_5 = M \beta^-_2 + \frac{r_s}{2 u_s} \frac{d M}{d \eta}
\]

Similarly, the energy and specie conservation equations can be written as

\[
\frac{\partial}{\partial \eta} \left[ \frac{\mu u_s}{Pr} \frac{\partial H}{\partial \eta} \right] + 2 u_s^2 \frac{\partial}{\partial \eta} \left[ \mu (1 - \frac{1}{Pr}) \frac{\partial f}{\partial \eta} \right] = 0
\]

\[
+ \text{Re} \beta^-_5 \left[ 2 \eta \frac{\partial H}{\partial \eta} - \beta^-_4 \frac{\partial f}{\partial \eta} \right] = 0
\]

where \( Pr \) is the Prandtl number and \( \text{Re} \) is the Reynolds number

\[
\text{Re} = \frac{u_s}{\mu_s(0)} \quad \text{and} \quad H_\xi = \frac{\partial H}{\partial \xi}
\]

The specie conservation equation becomes

\[
\frac{\partial}{\partial \eta} \left[ \rho^2 f D \frac{\partial C_v}{\partial \eta} \right] + S_c \text{Re} \beta^-_5 \left[ 2 \eta \frac{\partial C_v}{\partial \eta} - \beta^-_4 C_v \right] = 0
\]

where \( C_v \equiv \frac{\partial C_v}{\partial \xi} \) and \( D \) is the effective binary diffusion coefficient. An explicit formula for \( D \) will be discussed in Section 4. \( S_c \) is the Schmit number defined as

\[
S_c = \frac{\mu_s(0)}{\rho D_s(0)}
\]
We note that the nonsimilar terms in Eqs. (10), (13) and (14) are $\beta_1^+ f_\xi$, $\beta_1^+ H_\xi$ and $\beta_1^+ C_\nu$, respectively. Without these terms, Eqs. (10) to (14) become locally similar equations and $\xi$ appears only as a parameter. The concept of the locally nonsimilar approach is to define those nonsimilar terms as new variables and derive equations for them. We thus define

$$F = \beta_1^+ f_\xi, \quad H = \beta_1^+ H_\xi, \quad C = \beta_1^+ C_\nu$$

Equations for $F$, $H$ and $C$ are derived in the following manner. For $F$ we first differentiate Eq. (10) with respect to $\xi$, then multiply it by $\beta_1^+$. An equation for $F$ results. In this equation, however, another nonsimilar term $\beta_1^+ f_\xi$ is introduced. Theoretically one can define this term as another new variable and derive an equation for it. A set of an infinite number of equations will then result. Truncation must therefore be performed in order to obtain a closed set of equations. For the sake of simplicity we will simply neglect the term $\beta_1^+ f_\xi$ in the $F$ equation. We will call this level of approximation the two-equation model. The validity of this two-equation model has been demonstrated partially in Ref. 7. In the present work more comparisons will be made with some available numerical solutions to examine the validity of the two-equation model in treating thin shock layer problems.

Similarly, the equation for $H$ is obtained by differentiating Eq. (13) with respect to $\xi$, multiplying it by $\beta_1^+$ and neglecting the term $\beta_1^+ H_\xi$; the equation for $C_\nu$ is obtained by differentiating Eq. (14) with respect to $\xi$, multiplying it by $\beta_1^+$ and neglecting the term $\beta_1^+ C_\nu$. These equations are given as the following

$$f \frac{\partial}{\partial \eta} (\mu \frac{\partial F}{\partial \eta}) + f \beta_1 \left[ (\mu) \xi \frac{\partial F}{\partial \eta} + \left( \frac{F}{r^2} - \frac{\beta_1^+ \xi}{\beta_1^+} \right) \frac{\partial}{\partial \eta} (\mu \frac{\partial F}{\partial \eta}) \right] + Re \beta_1^+ \left[ 2\eta \frac{\partial F}{\partial \eta} - \beta_1^+ \beta_2^+ (r^2 - \frac{2}{\rho}) - 2\beta_2^+ \left( F + \frac{\beta_1^+ \rho \xi}{\rho^2} \right) \right]$$

$$- \frac{\beta_1^+ \rho \xi}{\rho^2} \left( \beta_4^+ - \eta \beta_3^+ \right) + \frac{\beta_1^+}{\rho} \left( \beta_4^+ - \eta \beta_3^+ \right) = 0$$

(16)
where

\[ (\rho_\mu)_\xi = \frac{\partial \rho_\mu}{\partial \xi} , \quad \rho_\xi = \frac{\partial \rho}{\partial \xi} , \quad \beta^\pm_\xi = \frac{\partial \beta^\pm}{\partial \xi} \]

\[ \beta^+_\xi = \frac{\partial \beta^+_\xi}{\partial \xi} , \quad \beta^-_\xi = \frac{\partial \beta^-_\xi}{\partial \xi} \]

\[
\frac{\partial}{\partial \eta}\left[ \frac{\omega}{F} \frac{\partial H}{\partial \eta} \right] + \frac{\partial}{\partial \eta}\left[ \frac{\omega}{F} \frac{\partial H}{\partial \eta} \right] + \beta^+_1 \frac{\partial}{\partial \eta}\left[ \frac{(\omega)(1 - \frac{1}{F})}{F} \frac{\partial f}{\partial \eta} \right] \\
+ 4u_s(u_s) \beta^+_1 \frac{\partial}{\partial \eta}\left[ \rho_\mu(1 - \frac{1}{F}) \frac{\partial f}{\partial \eta} \right] + 2u_s \beta^+_1 \frac{\partial}{\partial \eta}\left[ \rho_\mu(1 - \frac{1}{F}) \frac{\partial f}{\partial \eta} \right] \\
+ 2u_s \frac{\partial}{\partial \eta}\left[ \rho_\mu(1 - \frac{1}{F}) \frac{\partial f}{\partial \eta} \right] + 2u_s \frac{\partial}{\partial \eta}\left[ \rho_\mu(1 - \frac{1}{F}) \frac{\partial f}{\partial \eta} \right] \\
+ \text{Re} \beta^+_5 \beta^+_1 \left[ 2\eta \frac{\partial H}{\partial \eta} - \beta^+_1 \frac{\partial f}{\partial \eta} \right] + \text{Re} \beta^+_5 \left[ 2\eta \frac{\partial H}{\partial \eta} - \beta^+_1 \frac{\partial f}{\partial \eta} \right] = 0 \quad (17)
\]

\[
\frac{\partial}{\partial \eta}\left[ \rho^2 \frac{\partial c^V}{\partial \eta} \right] + \frac{\partial}{\partial \eta}\left[ \rho^2 \frac{\partial c^V}{\partial \eta} \right] + \beta^+_1 \frac{\partial}{\partial \eta}\left[ \rho^2 \frac{\partial c^V}{\partial \eta} \right] \\
+ 2 \text{Sc} \Re \beta^+_c \frac{\partial c^V}{\partial \eta} + \text{Sc} \Re \beta^+_c \beta^+_5 \left[ 2\eta \frac{\partial c^V}{\partial \eta} - c^V \right] = 0 \quad (18)
\]

In Eq. (17) the further approximation of neglecting \( \frac{\partial Q}{\partial \xi} \) has been made. The explicit formula for the radiative flux divergence will be given in Section 3. Needless to say, it will be a strong function of the absorption coefficients. To evaluate \( \frac{\partial Q}{\partial \xi} \) requires the \( \xi \)-derivative of the absorption coefficients. Since a multiband model of the continuum and atomic line radiation are being treated, it would have been extremely complicated to obtain the \( \xi \)-derivative of the absorption coefficients. By neglecting \( \frac{\partial Q}{\partial \xi} \), we greatly simplify
the analysis. An examination of this simplification in terms of the effect of \( \frac{\partial Q}{\partial \xi} \) on the radiative wall flux is considered in Section 5.

Equations (10), (13), (14), (16), (17) and (18) provide six equations for \( f, H, C_v, F, \overline{H}, \overline{C}_v \), six unknowns. These equations can be considered as ordinary differential equations with \( \xi \) as a parameter and their solutions can be sought locally. They are fully coupled with the radiation field, the mixture thermodynamics and the mixture transport properties. Methods of computing the radiation field and the thermodynamics will be described in the next two sections.

2.2 Boundary Conditions

The boundary conditions for \( f, H, C_v, F, \overline{H}, \overline{C}_v \) should be given both at wall and at shock. By the definition of \( f \) and \( F \), it is clear that at shock \( f = 1 \) and \( F = 0 \). At the wall, a no slip condition holds for the high Reynolds number cases of interest. Hence, we find that \( f = 0 \) and \( F = 0 \). We will assume that the shock itself is not radiating and the precursor radiation is negligible, then at shock \( H = 1 \) and \( \overline{H} = 0 \). At the wall the enthalpy is assumed to be given. Thus \( H = H_w \) and \( \overline{H} = \overline{H}_w \). Again, due to the high Reynolds numbers of interest, the diffusion layer will be much thinner than the shock layer. Unless the injection rate is extremely high such that the viscous layer is pushed outward near the shock, one would expect that no ablation gas will reach the shock. Assuming the injection rate \((\rho v)_w\) is order of \( \rho u_w \), then at shock \( C_v = 0 \) and \( \overline{C}_v = 0 \).

At the wall, the diffusion current for the mass fraction of the atmospheric gas must exactly equal the convection current of the mass fraction of the atmospheric gas created by the surface mass injection. Hence, at wall we have the relation (in dimensionless form) \( \rho D \frac{\partial C_a}{\partial \eta} = (\rho v)_w C_{ReSc} \) where \( C_a \) is the mass fraction of atmospheric gas. Note that \( C_a = 1 - C_v \). We have, in the \( \eta \) coordinate, the boundary condition at wall for \( C_v \) as

\[
 f \rho D \frac{\partial C_v}{\partial \eta} = \frac{\dot{M}_r}{\rho} \frac{ReSc}{u_s} (\rho v)_w (1 - C_v) \tag{19}
\]
The condition at wall for $\bar{C}_V$ is found by simply differentiating (19) by $\xi$ then multiplying by $\beta_1^-$. We obtain

$$
\int \rho \frac{\partial C_v}{\partial \eta} \, d\eta = - \frac{\text{Re} \text{Sc} \dot{M}(\rho v) w^r_s}{u_s} + \beta_1^- \text{Re} \text{Sc} \left( \frac{\dot{M}(\rho v) w^r_s}{u_s} \right) \xi (1 - C_V)
$$

(20)

2.3 Method of Solution

In attempting to solve Eqs. (10)-(18), it was found convenient to transform the independent variable from $\eta$ to a new coordinate

$$
\eta = w \int f \mu d\omega - \frac{1}{2}
$$

(21)

where $w$ is assigned the value zero at the wall and unity at the shock.

From Eq. (21) we obtain

$$
\eta = w \int f \mu d\omega - \frac{1}{2}
$$

(22)

therefore

$$
w = \frac{1}{\int f \mu d\omega}
$$

(23)

We define the point $w = w_o$ as the value of $w$ at $\eta = 0$. Then the atmospheric gas layer as defined before extends from $w = w_o$ to $w = 1$. The injected gas layer extends from $w = w_o$ to $w = 0$. The integration of Eqs. (10)-(18) was performed in two different directions from $w_o$ toward 1 ($\beta^+$'s are to be used) and from $w$ to 0 ($\beta^-$'s are to be used). The conditions at the junction $w = w_o$ were determined by requiring that the values of $f, F, H, \bar{H}, C_v, \bar{C}_V$ and their slope in the physical plane be continuous. Hence we require

$$
\frac{\partial f}{\partial y}, \frac{\partial F}{\partial y}, \frac{\partial H}{\partial y}, \frac{\partial \bar{H}}{\partial y}, \frac{\partial C_v}{\partial y}, \frac{\partial \bar{C}_V}{\partial y}
$$

and $\frac{\partial \bar{C}_V}{\partial y}$ be continuous at $w = w_o$.

After Eqs. (10) to (18) were transformed with $w$ as the independent variable and the junction conditions applied, the following formal solutions were obtained.
For velocity:

\[ f^\pm = G_1^\pm(\omega) + C_f^\pm G_2^\pm(\omega) + f(\omega_0) \]  

\[ f = f^+ \text{ when } \omega_0 < \omega < 1, \quad f = f^- \text{ when } 0 \leq \omega \leq \omega_0 \]

with

\[ G_1^\pm(\omega) = \Re \beta_2^\pm \int_{\omega_0}^{\omega} e^{\int_{\omega_0}^{\omega} \left(-2\Re \beta_2^\pm \omega \eta \right) d\omega'} \frac{\rho \left(F + \beta_2^\pm \left(1 - \frac{2}{\rho} - \frac{\beta_3^+ - \beta_3^-}{\rho} \right) \right)}{\omega} d\omega \]

\[ G_2^\pm(\omega) = \int_{\omega_0}^{\omega} e^{\int_{\omega_0}^{\omega} \left(-2\Re \beta_2^\pm \omega \eta \right) d\omega'} d\omega \]

\[ f(\omega_0) = \frac{[1-G^+(1)]G_2^-(0)\dot{M} + G_2^+(1)G_1^-(0)}{\dot{M}G_2^+(0) - G_2^+(1)} \]

\[ C_f^+ = \frac{1 - f(\omega_0) - G_1^+(1)}{G_2^+(1)}, \quad C_f^- = \dot{M}C_f^- \]

For enthalpy profile:

\[ H^\pm = G_3^\pm(\omega) + C_H^\pm G_4^\pm(\omega) + \dot{H}(\omega_0) \]  

\[ H = H^+ \text{ when } \omega_0 < \omega < 1, \quad H = H^- \text{ when } 0 \leq \omega \leq \omega_0 \]

with

\[ G_3^\pm(\omega) = \int_{\omega_0}^{\omega} e^{\int_{\omega_0}^{\omega} \left(-2\Re \beta_2^\pm \omega \eta \right) d\omega'} \left\{ \Re \beta_2^\pm \left(\omega \dot{u} \dot{f} + \frac{\omega \mu \beta_1^+ Q}{u_s} \right) + 4u_s^2 \eta(Pr-1)f \frac{\partial f}{\partial \omega} \right\} d\omega' \]

\[ G_4^\pm(\omega) = 2u_s^2 \int_{\omega_0}^{\omega} (Pr-1)f \frac{\partial f}{\partial \omega} d\omega \]
\[ G^+_5(w) = \int_{w_0}^{w} \text{Pr} e^{\text{Re} \beta^+_5 w} \int_{w_0}^{w} \text{Pr} \eta dw \]

\[ H(w_0) = \frac{G^+_5(1)[H - G^+_3(0) + G^-_4(0)] - G^-_5(0)[1-G^+_3(1) + G^+_4(1)]}{G^+_5(1) - G^-_5(0)} \]

\[ C^+_H = \frac{1-G^+_3(1) + G^+_4(1) - H(w_0)}{G^+_5(1)} \quad \quad C^-_H = \dot{M}G^+_H \]

For specie profiles

\[ C^+_V = G^+_6(w) + C^+_c G^+_7(w) + C^+_V(w_0) \quad (26) \]

\[ C^-_V = C^+_V \quad \text{when} \quad w_0 < w \leq 1 \quad , \quad C^-_V = C^{-}_V \quad \text{when} \quad 0 \leq w \leq w_0 \]

with

\[ G^+_6 = \omega^2 \text{ScRe} \beta^+_5 \int_{w_0}^{w} \frac{\mu}{\rho D} dw \int_{w_0}^{w} e^{-2\text{ScRe} \beta^+_5 w} \int_{w_0}^{w} \frac{\mu}{\rho D} \eta dw \int_{w_0}^{w} \eta dw' \]

\[ G^-_7(w) = \int_{w_0}^{w} \frac{\mu}{\rho D} e^{-2\text{ScRe} \beta^+_5 w} \int_{w_0}^{w} \frac{\mu}{\rho D} \eta dw \int_{w_0}^{w} \eta dw' \]

\[ C^+_V(w_0) = \frac{G^+_7 \frac{\partial G^+_6}{\partial w} - \dot{M} G^+_6 \frac{\partial G^+_7}{\partial w}}{G^+_7 \frac{\partial G^+_6}{\partial w} - \dot{M} G^+_6 \frac{\partial G^+_7}{\partial w}} - \frac{\mu}{\rho D} \frac{\dot{M} \text{ReSc} \mu}{u_s} \frac{\partial G^+_7(1)}{\partial w} \left[ G^+_7(1) - G^+_6(0) + \dot{M} G^+_6(1) G^+_7(0) \right] \]

\[ \dot{M} \frac{\partial G^+_7}{\partial w} + \frac{\mu}{\rho D} \frac{\dot{M} \text{ReSc} \mu}{u_s} \frac{\partial G^+_7(0)}{\partial w} \left[ G^+_7(0) - \dot{M} - G^+_7(1) \right] \]

and

\[ C^+_C = - \frac{G^+_6(1) + C^+_V(w_0)}{G^+_7(1)} \quad , \quad C^-_C = \dot{M}C^+_C \]

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Similar expressions can be obtained for $\bar{H}$, $F$ and $\bar{C}_v$ as follows

\[ F^\pm = G^\pm_8(w) + G^\pm_9(w) + C^\pm_F G^\pm_{10}(w) + F(w_o) \]  

(27)

$F = F^+$ when $w_o \leq w \leq 1$, $F = F^-$ when $0 \leq w \leq w_o$

\[ G^\pm_8(w) = -\beta^\pm_1 \int_{w_o}^{w} \frac{(\mu \Gamma)}{\mu} \frac{\partial f}{\partial \omega} d\omega \]

\[ G^\pm_9(w) = \int_{w_o}^{w} \int_{w_o}^{w} e^{-2w_s \text{Re} \beta^\pm_5 \int_{w_o}^{w} \partial f d\omega} \left\{ 2w_s \text{Re} \beta^\pm_5 \frac{\partial f}{\partial \omega} \frac{(\mu \Gamma)}{\mu} \frac{\partial f}{\partial \omega} \right\} d\omega' \]

\[ G^\pm_{10} = \int_{w_o}^{w} e^{-2w_s \text{Re} \beta^\pm_5 \int_{w_o}^{w} \partial f d\omega} d\omega \]

\[ F(w_o) = \frac{G^+_10(0) \mathcal{M}[G^+_8(1) + G^+_9(1)] - G^+_10(1)[G^+_8(0) + G^+_9(0)]}{G^+_10(1) - G^+_10(0) \mathcal{M}} \]

\[ C^+_F = \frac{G^+_8(1) + G^+_9(1) + F(w_o)}{G^+_10(1)} \]

\[ \bar{H}^\pm = G^\pm_{10}(w) + G^\pm_{12}(w) + C^\pm_F G^\pm_{13}(w) + \bar{H}(w_o) \]

(28)

$\bar{H} = \bar{H}^+$ when $w_o \leq w \leq 1$, $\bar{H} = \bar{H}^-$ when $0 \leq w \leq w_o$
with

\[ G_{11}^+ = -\int I_1(\omega) d\omega \]

\[ I_1(\omega) = \frac{F}{\omega^2} \frac{\delta H}{\delta \omega} + 2u_2^2(Pr-1) \left( \frac{f}{\omega} \frac{\delta f}{\delta \omega} + \frac{\delta F}{\delta \omega} \right) + \beta_1 \left( \frac{\rho \mu}{Pr} \right) \frac{Pr}{\omega} \frac{\delta H}{\delta \omega} \]

\[ + 4u_2 u_5 Pr(Pr-1) \frac{\delta f}{\delta \omega} + 2u_2^2 \rho \mu \left( \frac{1}{Pr} \right) \frac{\delta f}{\delta \omega} \left( \frac{\rho \mu}{Pr} \right) \frac{Pr}{\omega} \frac{\delta H}{\delta \omega} \]

\[ G_{12}^+ = \int Pr \omega \int e^{-2Re} \beta^+ \eta \omega \int Pr \eta \omega \int I_2(\omega') d\omega' \]

\[ I_2(\omega') \right) = 2Re \beta^+ \eta(\omega) \left[ \beta^+ \beta^+ \eta(\omega) \right] + Re \beta^+ \iota \omega \beta^+ \eta \omega \left[ \beta^+ \beta^+ \right] \frac{\delta H}{\delta \omega} \left( \frac{\rho \mu}{Pr} \right) \frac{Pr}{\omega} \frac{\delta H}{\delta \omega} \]

\[ \mathcal{H}(\omega) = \frac{G_{13}^+ \left[ \mathcal{H}_w - G_{11}^-(0) + G_{12}^-(0) \right] + G_{10}^+(0) \left[ G_{11}^+(1) + G_{12}^+(1) \right]} {G_{13}^+(1) - G_{13}^-(0)} \]

\[ C_{\mathcal{H}}^- = C_{\mathcal{H}}^+ \quad \text{and} \quad C_{\mathcal{H}}^+ = \frac{G_{11}^+(1) + G_{12}^+(1) + \mathcal{H}(\omega)} {G_{13}^+(1)} \]

Finally

\[ C_{V}^+ = G_{14}^+(\omega) + G_{15}^+(\omega) + C_c^+ G_{16}^+(\omega) + \mathcal{C}_V(\omega) \quad \text{(29)} \]

\[ \mathcal{C}_V = \mathcal{C}_V^+ \text{ when } \omega < \omega \leq 1 \quad \text{and} \quad \mathcal{C}_V = \mathcal{C}_V^- \text{ when } 0 < \omega < \omega_0 \]
The formal solutions given by Eqs. (24)-(29) are in fact integral equations. All the G's are integrals and their integrands are functions of the unknowns $f$, $H$, $C_v$, $F$, $H_v$, $C_v$; the thermodynamics and the radiative flux divergence $Q$. The advantages of writing the governing equations into the form of Eqs. (24)-(29) are the following: First, the boundary conditions are satisfied exactly by Eqs. (24)-(29). Second, Eqs. (24) to (29) can be solved by iteration. The iteration scheme is more stable than the integration of a second order differential equation with two point boundary conditions.
To solve Eqs. (24)-(29) we first guess profiles for $f$, $H$, $C_v$, $F$, $\overline{H}$ and $\overline{C}_v$. Then, from the thermodynamics subroutine, we obtain the thermodynamic properties as well as the transport properties: density, temperature, species concentration, viscosity, Prandtl number, and diffusion coefficient. With this complete thermodynamic information, the radiative transport subroutine will provide the radiative flux divergence $Q$. Also, once $f$, $\rho$, $\mu$ are known, $\omega_s$, $\omega_o$, as well as $\eta$ can be determined. Consequently, all the $G$ functions can be evaluated and a new (i.e., calculated) value for $f$, $H$, $C_v$, $F$, $\overline{H}$, $\overline{C}_v$ obtained. These calculated profiles will then be compared with the guessed ones. If the profiles do not agree within a specified convergence criterion, new profiles will be chosen and the iteration continued until the profiles hopefully converge to a solution.
3.0 RADIATION TRANSPORT

The radiation transport model employed in this study is that of Wilson (Refs. 4 and 5). In those references, both the continuum and atomic line transport are considered for a system consisting of H, He C, N, O atoms and significant molecular species. Since helium has high energy level, few helium atoms will be excited in the present shock layer problem; their contribution to the total radiative flux will be small. The presence of helium, however, will affect the composition of gas mixture. Hence, the radiation field will be affected by the presence of helium only through the thermodynamics.

The detailed analysis of Wilson's radiation transport model can be found in Ref. 4. We will not reproduce it here, but will only briefly outline the model below.

It is the radiative flux and the flux divergence that are of interest to us. By definition, they are given as:

\[ F_r = \iiint_{\Omega=\Omega_0} I(y, \nu, \Omega) \cos \theta d\Omega d\nu \quad (30) \]

\[ Q = \nu \cdot F_r = \iiint_{\Omega=\Omega_0} \mu(y, \nu) [I(y, \nu, \Omega) - B(y, \nu)] d\Omega d\nu \quad (31) \]

Where \( I(y, \nu, \Omega) \) is the monochromatic intensity at frequency \( \nu \) and in the direction \( \Omega \), \( B(y, \nu) \) is the Planck function. For the present thin shock layer problem, the radiation field is assumed to be one-dimensional. The intensity \( I(y, \nu, \Omega) \) can therefore be determined from the one-dimensional radiative transfer equations. They are given as: (with the help of the exponential approximation

\[ I^+(\nu, y) = \int_0^\infty \mu(\nu, y) B(\nu, y') e^{ -\int_0^y \mu(\nu, y'') dy''} dy' \]
I_+(v,y) = \int_y^\Delta \mu(v,y') B(v,y') e^{-\int_y^{y'} \mu(v,y'') dy''} dy'

Where I_+ is the intensity in the positive y direction and I_- in the negative y direction. \Delta is the dimensional shock layer thickness, \ell is the reciprocal direction cosine, and \mu(v,y) the absorption coefficient. With a given thermodynamic field and \mu(v,y), the intensity field can be determined.

The absorption coefficient is separated into continuum and line contributions.

\mu(v,y) = \mu^c(v,y) + \mu^L(v,y)

The flux may then be expressed as the sum of a contribution due to continuum only process \( F^C_r \) and a contribution due to lines but corrected by continuum attenuation.

\[ F_r = F^C_r + F^L_r \quad \quad (32) \]

with

\[ F^C_r = \pi \int_0^\infty \left\{ \int_0^\infty B(v,y') dE_v(y,y') - \int_0^\infty B(v,y) dE(y,y') \right\} dv \quad \quad (33) \]

where the emissive function \( E_v(y,y') \) is defined as

\[ E_v(y,y') = 1 - \exp[\int_y^{y'} \mu^c(v,y'') dy''] \]

and

\[ F^L_r = \pi \sum_{i=1}^{\text{all lines}} \left\{ \int_0^\infty B_i(y') dW_i(y,y') - \int_0^\Delta B_i(y') dW_i(y,y') \right\} \quad \quad (34) \]

where the equivalent width \( W_i(y,y') \) is defined as

\[ W_i(y,y') = e^{\int_y^{y'} \mu^c_i(y''') dy'''} \sum_{\text{all lines}} \left\{ \int_0^\infty B_i(y') dW_i(y,y') - \int_0^\Delta B_i(y') dW_i(y,y') \right\} \]

\[ -19- \]
Similarly, we can write the flux divergence $Q$ into two parts

$$Q \equiv \nabla \cdot \mathbf{F} = Q^C + Q^L$$

where

$Q^C$ is the energy emitted and absorbed by the continuum

$$Q^C = 2\pi \int_0^\infty \int B(v,y')dE_v(yy') + \int B(v,y')dE_v(yy') - 2B(v,y)dv$$

and

$Q^L$ is the energy emitted and absorbed by the lines. $Q^L$ is computed by numerical differentiation of the line flux $F^L$.

The remaining task is to determine the continuum absorption coefficient $\mu^C(v,y)$ and the line absorption coefficient $\mu^L(v,y)$ for a particular gas mixture. In Ref. 5, twenty-six-band-grey absorption coefficient is modeled for the continuum, and eleven "effective lines" are treated for each atom. The detailed frequency range and their expressions for the continuum absorption and the definition of "effective line" as well as their frequency ranges will not be given here. They are listed in Refs. 4 and 5.
4.0 THERMODYNAMIC AND TRANSPORT PROPERTIES

4.1 Thermodynamic Properties

Thermodynamic variables such as density, temperature and species concentrations are needed at each point of the shock layer to solve the conservation equations and to calculate the radiative flux. Hence, a relation between these variables and the pressure, enthalpy and elemental mass fraction is required. For a reacting gas mixture, simple state equations are not available. A complete thermochemical equilibrium calculation is necessary to provide the needed thermodynamic properties. A free energy equilibrium program (FEMP) is therefore incorporated in our computer code as a subroutine to provide thermodynamic information. The analysis underlying this program is described in Ref. 9. The original version of FEMP as described in Ref. 9 does not give thermodynamic derivatives. In the present study, certain thermodynamic derivatives are required to provide the $\xi$-derivatives of the thermodynamic variables involved in the governing equations. For example, $\rho_\xi$ appeared in Eq. (16). Applying the chain rule, we can write this derivative as

$$\rho_\xi = \frac{\partial \rho}{\partial \xi} = \frac{\partial \rho}{\partial p} \frac{\partial p}{\partial \xi} + \frac{\partial \rho}{\partial h} \frac{\partial h}{\partial \xi} + \sum_i \frac{\partial \rho}{\partial \alpha_i} \frac{\partial \alpha_i}{\partial \xi}$$  (37)

where $\alpha_i$ is the mass fraction of elemental gas $i$.

Equation (37) indicates that we need $\frac{\partial \rho}{\partial p}, \frac{\partial \rho}{\partial h}, \frac{\partial \rho}{\partial \alpha_i}$ and $\frac{\partial \rho}{\partial \alpha_i}$.

We have extended the original FEMP code so that, upon input of $p, h$ and elemental gas mass fraction $\alpha_i$, we obtain not only the thermodynamic variables but also the thermodynamic derivatives.

4.2 Transport Properties

Similar to Ref. 4, simplified transport equations of Ref. 10 and 11 have also been used in this study. The approximate viscosity of a gas mixture is given by

$$\mu = \sum_i \frac{\chi_i \mu_i}{\sum_j \chi_j \eta_{ij}}$$  (38)
where \( \chi_i \) is the mole fraction and \( \mu_i \) is the viscosity of the species \( i \).

\[
\varphi_{ij} = \frac{1}{2 \sqrt{2}} \left( 1 + \frac{M_i}{M_j} \right)^{-\frac{1}{2}} \left[ 1 + \left( \frac{\mu_i}{\mu_j} \right)^{\frac{1}{2}} \left( \frac{M_j}{M_i} \right)^{\frac{1}{2}} \right]^2
\]

The total thermal conductivity can be written as

\[
k_T = \sum_{i} \chi_i k_i - \sum_{j} \sum_{i} \frac{Dh_i}{\partial T} \frac{\partial C_i}{\partial T}
\]

(39)

where \( D \) is the effective binary diffusion coefficient and \( h_i \) is the enthalpy of the species \( i \).

The specific heat at constant pressure of the mixture is

\[
C_p = \sum_{i} \left( C_{pi} + h_i \frac{\partial C_i}{\partial T} \right)
\]

(40)

where \( C_{pi} \) is the frozen specific heat of each species. For air, Blake (Ref. 13) has shown that those approximate equations are valid up to temperatures of 10,000°K.

The temperature dependent diffusion coefficient \( D \) used for the C, H, N, O system was that selected by Hoshizaki and Lasher (Ref. 1). This curve-fitted diffusion coefficient may not be adequate when helium is included in the system. The effect of this uncertainty on the radiative wall flux has not been evaluated.
5.0 RESULTS

5.1 Comparisons with Other Solutions

In order to examine the validity of present locally nonsimilar solutions for thin shock layers, we will make comparisons with other available solutions. Unfortunately there is no solution with massive blowing available for comparison. The important question of the validity of the locally nonsimilar solution for shock layer with mass injection is therefore yet to be answered.

The following comparisons are made:
(a) Adiabatic inviscid flow behind a $45^\circ$ blunted conic shock is compared with Olstad's solution (Ref. 6).
(b) Adiabatic inviscid flow behind a parabolic shock at high Mach number is compared with a solution by Schneider (Ref. 14), and
(c) Viscous, nonradiating flow over a paraboloid at high Mach and high Reynolds number is compared with the boundary layer solution by Davis and Flugge-Lutz (Ref. 15). All these comparisons are based on perfect gas. The results of the comparisons are present in Fig. 2-5. In Fig. 2, the tangential velocity profiles across the shock layer behind the $45^\circ$ conic shock are shown at various locations downstream. In Fig. 3, the body shapes behind the parabolic shock are shown. In Fig. 4, the tangential velocity, pressure, as well as the density profiles at $z = 10$, are shown. Figure 5 shows the convective heat flux and the skin friction distribution around the paraboloid. From these comparisons it seems that the validity of the present locally nonsimilar solution for nonradiating nonblowing thin shock layers has been sufficiently demonstrated.

5.2 Viscous Shock Layer with Blowing— but without Radiation

We present here a typical solution for viscous nonradiating flow behind a blunted $45^\circ$ conic shock with variable surface mass injection. The purpose of presenting this solution is to examine the change of velocity and enthalpy
SHOCK SHAPE \[ Z_s = \frac{r_s^2}{1 + 1.036 r_s} \]

Fig. 2. Inviscid Adiabatic Velocity Profiles for Shock Layer Behind a 45° Conical Shock
Fig. 3. Inviscid Adiabatic Body Shape Behind a Parabolic Shock at Mach \infty.
Fig. 4. Profiles Behind a Parabolic Shock
PRESENT SOLUTION

\[ q = \frac{K (\frac{\partial T}{\partial y})_b}{\rho_\infty U_\infty^3} \quad \tau = \frac{\mu (\frac{\partial u}{\partial y})_b}{\rho_\infty U_\infty^2} \]

\[ M_\infty = \infty, \quad Pr = 0.7, \quad T_w/T_o = 0.2 \]

\[ \mu \sim \sqrt{T}, \quad Re = \frac{\rho_\infty U \frac{R_S}{\mu_S(0)}} = 10^6 \]

Fig. 5. Convective Heat Flux and Skin Friction Around a Paraboloid at Hypersonic Speed
profiles as the flow flows downstream.

Thermodynamic as well as transport properties are calculated by the extended FEMP routine in this solution. We list the necessary input quantities as follows:

**Flight Conditions**

\[ \rho_\infty = 4.21 \times 10^{-7} \text{gr/cm}^3, \quad u_\infty = 1.6 \times 10^6 \text{cm/sec} \]

**Shock Shape**

\[ Z = \frac{r^2}{2 + 1.19 r_s} \]

**Shock Nose Radius**

\[ R_s = 234 \text{ cm} \]

**Reynolds Number**

\[ Re = 2.48 \times 10^5 \]

**Wall Enthalpy**

\[ H_w = 0.2, \quad \bar{H}_w = 0 \]

**Surface Mass Injection Rate**

\[ (p\nu)_w = \frac{-0.3}{1 + r_s^2} \]

The results are plotted in Figs. 6 and 7. Figure 6 shows the shock and body shapes. Also plotted in the figure is the interface between the atmospheric gas and the injected gas. This interface is defined as the surface where the stream function is zero. We see that the body shape is not significantly different from the shock shape. The injected gas layer grows but at a slower pace than the growth of the total shock layer. This is because of the decreasing surface injection rate around the body. Figure 7 shows the tangential velocity and static enthalpy profiles. It is seen that the viscous layer is detached from the wall due to mass injection. Hence, both the convective heat transfer and the skin friction are practically zero. The inviscid layer near the wall becomes thinner as the flow flows far downstream.

Atmosherical Gas: Air

Injected Gas: Air

5.3 **Inviscid Shock Layer with Radiation but without Blowing—Evaluating the \( Q_s \) Effect**

In the derivation of the equation for \( \bar{H} \) we have neglected the term
Fig. 6. Shock and Body Shapes for a Blowing Case
Fig. 7. Enthalpy and Velocity Profiles for a Blowing Case
\[ \frac{\partial Q}{\partial \xi} \], namely, we have neglected the contribution of the streamwise rate of change of radiative flux divergence to the energy equation. In order to assess the effect of \( \frac{\partial Q}{\partial \xi} \) on the radiative wall flux we have made computations with and without this term. The computation is for an inviscid, nonblowing case; the flight condition and shock shape are the same as given by Eq. (41) and the shock nose radius is 100 cm. The three-band radiation transport model for air continuum as described in Ref. 7 is employed for this particular case. Figure 8 shows the result for radiative wall flux, the dotted line is the result for \( \frac{\partial Q}{\partial \xi} = 0 \), while the solid line represents the result for \( \frac{\partial Q}{\partial \xi} \neq 0 \). We see that the result for \( \frac{\partial Q}{\partial \xi} = 0 \) is always higher than for \( \frac{\partial Q}{\partial \xi} \neq 0 \). The maximum difference between these two results in this case is about 15%. A 15% inaccuracy seems to be reasonable to accept in view of the simplification it will introduce by neglecting this \( \frac{\partial Q}{\partial \xi} \) term. To evaluate \( \frac{\partial Q}{\partial \xi} \) in the present study would require the \( \xi \)-derivatives of Eq. (35). It involves, first, the transformation of those equations from \((x,y)\) plane to \((\xi,\eta)\) plane, then taking partial derivatives with \( \xi \) by keeping \( \eta \) fixed. A tremendous amount of algebraic manipulation would have to be made in this process, and this can all be avoided by simply neglecting \( \frac{\partial Q}{\partial \xi} \) in the \( \overline{H} \) equation. Although the effect of \( \frac{\partial Q}{\partial \xi} \) on the wall flux is not negligible, we have demonstrated for the case of three-band radiation models that the effect is on the conservative side and is reasonably small.

5.4 Completely-Coupled Radiating Shock Layer with Blowing

A sample calculation is made for the shock layer problem of a Jupiter probe. The flight conditions, as well as other necessary input data, are listed below:

- Flight Conditions: \( \rho = 6.9 \times 10^{-7} \text{ gr/cm}^3 \), \( u_w = 4 \times 10^6 \text{ cm/sec} \)
- Shock Shape: \( Z = \frac{r_s^2}{2 + 1.88 r_s} \)
- Shock Nose Radius: \( R_s = 20 \text{ cm} \)
- Wall Temperature: \( T_w = 4500 ^\circ \text{K} \)
Fig. 8. Effect of Streamwise Derivative of Flux Divergence on the Surface Radiative Flux
Surface Mass Injection Rate \( (\rho v) = \frac{-0.4}{1 + 0.1 R_s^2} \)

Atmospherical Gas: 74% Hydrogen, 26% Helium; by mass. Injected Gas: Carbon

Radiative Model: Given by Refs. 4 and 5.

Based on the flight conditions listed above, the Reynolds number as calculated by FEMP is \( 9.267 \times 10^4 \) and the density ratio \( (\rho_\infty/\rho_s) \) across the normal shock is 0.0964.

In this calculation, the \( \xi \)-derivatives of the thermodynamic transport such as \( \frac{\partial u}{\partial \xi}, \frac{\partial P}{\partial \xi}, \) and \( \frac{\partial D}{\partial \xi} \) are neglected for the following two reasons:

(a) Those derivatives turn out to be very sensitive to the local gas composition due to the very steep gradient of the ablating product concentration profile near the interface (the viscous layer). This sensitivity causes the iteration to become unstable.

(b) The effect of \( \frac{\partial u}{\partial \xi}, \frac{\partial P}{\partial \xi}, \) and \( \frac{\partial D}{\partial \xi} \) should be confined within the viscous layer; in the present high Reynolds number cases this layer is indeed very thin. Hence, the effect of neglecting \( \frac{\partial u}{\partial \xi}, \frac{\partial P}{\partial \xi}, \) and \( \frac{\partial D}{\partial \xi} \) on the wall radiative flux should be small.

In order to examine the effect of ablation on the radiative wall flux, we also take a calculation for the nonblowing case. The results are shown in Figs. 9 - 14.

In Fig. 9, the shock shape, body shape, as well as the interface, are shown. The interface is defined as the surface where the stream function is zero. It is found that \( R_b/R_s \approx 0.42 \). In the present case, \( R_s = 20 \text{ cm} \). Hence, the body nose radius of curvature \( R_b \) is approximately 8.2 cm. The asymptotic body half cone angle is approximately 57°. Also shown in Fig. 9 is the body shape when there is no blowing. This body shape is practically identical to the interface shape for the blowing case. The last point in the present calculation is at \( r_b/R_s \approx 2, r_b/R_s \approx 1.85 \). At this point we see that the shock angle is close to its asymptotic angle which is 62°. Also, we see that, at this point, the shock layer is not exactly a thin layer.
Fig. 9. Shock and Body Shapes for a Radiative Coupled Viscous Shock Layer with Blowing
Figure 10 shows the surface radiative flux for both blowing and no blowing cases. A drastic reduction in radiative flux due to mass injection is seen. The flux distribution for the no blowing case shows an anomalous behavior, namely, the maximum heating is not at the stagnation point. For the present particular case, the downstream flux maintains at a higher level than that at the stagnation point. In order to explain this behavior, we have plotted the shock layer thickness distribution and the temperature profiles in Fig. 11. The shock layer thickness increases rapidly near the nose followed by an almost constant rate downstream. By comparing the temperature profiles at \( Z = 0 \) and \( Z = 0.03 \), we see that the temperature changes very little. On the other hand, the shock layer thickness increases by about 40% from 1.2 to 1.8 cm. This results in a higher flux at \( Z = 0.03 \) than that at \( Z = 0 \). The temperature decreases as \( Z \) increases, but remains at a high level as one can see from the profiles. The decreases in shock layer temperature will result in a lower surface flux, but it is compensated by a thicker shock layer. Hence, the net result is the flux maintains at a nearly constant level which is higher than the stagnation value. For blowing cases, the flux decreases monotonically as can be seen from Fig. 10. The heating level for a blowing case is mostly controlled by the injected gas layer. A monotonically increasing injected gas layer should result in a monotonically decreasing flux distribution.

Figure 12 shows the flux reduction due to the mass injection. The reduction ranges from about 40% at stagnation region to about 70% far downstream. This indicates that injected carbon gas is an effective heat shield in the sense that most of the shock layer hot gas is dumped into the wake. A detailed examination of the spectral distribution of surface radiative flux reveals that most of the continuum flux reduction occurs in the carbon molecular bands of \( \text{C}_2 \) and \( \text{C}_3 \). The reduction in line flux is also a significant portion of the total flux reduction. It is interesting to note that from Fig. 10 one sees that at the stagnation point, the line reduction accounts for about 60% of the total flux reduction.

Figure 13 shows the typical profiles for tangential velocity, enthalpy and injected gas mass fraction profiles at \( r_s = 1.22 \). It is seen that about 35% of the shock layer is an injected gas layer. The shear layer is thin, about 10% of the shock layer. Most of the injected gas layer is inviscid. The temperature profile and the \( \text{C}_1, \text{C}_2, \text{C}_3 \) concentration profiles are shown in Fig. 14.
Fig. 10. Surface Radiative Flux for Both Blowing and No Blowing Cases
Fig. 11. Shock Layer Thickness and Temperature Profiles for the No Blowing Case
Fig. 12. Surface Flux Reduction Due to Blowing
Fig. 13. Temperature, Velocity and Injected Gas Mass Fraction Profiles at $Z = 0.35$
Fig. 14. Enthalpy, $C_1$, $C_2$ and $C_3$ Profiles at $Z = 0.35$
6.0 CONCLUDING REMARKS

Viscous radiating shock layer flow over a blunt body with massive blowing has been solved by a locally nonsimilar approach. Detailed equilibrium computations for the thermodynamic and transport properties are included in the solution. Molecular band and atomic line, as well as continuum radiation, are considered.

Comparisons with prior inviscid solutions for flow behind blunted conic shocks and flow behind parabolic shocks show the present solution method adequately treats nonsimilar aspects of flow around blunt bodies. A sample calculation for a typical Jovian entry problem has been made. A 40% reduction in total radiative flux is found at stagnation point due to the injection of carbon gas. The reduction increases to about 70% at about four body nose radius downstream. This increase of flux reduction indicates that most of the radiative energy is absorbed by the injected carbon gas and dumped into the wake.

An examination of the spectral distribution of the radiative flux reveals that most of the flux reduction occurs in molecular bands of C\textsubscript{2} and C\textsubscript{3}. Due to the large Reynolds number and massive local blowing rate, the solutions indicate that the shear layer remains thin (about 10\% of the shock layer). The injected gas layer is mostly inviscid.

Due to the very steep gradient of the ablating product concentration profile near the interface (the viscous layer), the ??-derivatives of the thermodynamic transport such as \( \frac{\partial u}{\partial \xi} \), \( \frac{\partial Pr}{\partial \xi} \), and \( \frac{\partial D}{\partial \xi} \) are very sensitive to the local gas composition. This sensitivity causes the iteration in the numerical computation to become unstable. Therefore, in the sample calculation for the Jovian entry problem, ??-derivatives of the thermodynamic transport have been neglected. In the present higher Reynolds number and massive blowing case, the effect of neglecting those derivatives on the wall radiative flux should be small.
7.0 REFERENCES


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—National Aeronautics and Space Act of 1958

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