

RAYTHEON COMPANY

EQUIPMENT DIVISION

RAYTHEON

NASA CR-132441

RELIABILITY MODEL DERIVATION OF A
FAULT-TOLERANT, DUAL, SPARE-SWITCHING,
DIGITAL COMPUTER SYSTEM

FINAL REPORT

ER74-4108

25 MARCH 1974

PREPARED UNDER

NASA CONTRACT NAS1-12668

FOR

NASA LANGLEY RESEARCH CENTER

HAMPTON, VIRGINIA

RAYTHEON COMPANY

EQUIPMENT DEVELOPMENT LABORATORY

SUDBURY, MASSACHUSETTS 01776

ER74-4108

RELIABILITY MODEL DERIVATION OF A FAULT-TOLERANT,
DUAL, SPARE-SWITCHING, DIGITAL COMPUTER SYSTEM

ABSTRACT

A computer based reliability projection aid, tailored specifically for application in the design of fault-tolerant computer systems, is described. Its more pronounced characteristics include the facility for modeling systems with two distinct operational modes, measuring the effect of both permanent and transient faults, and calculating conditional system coverage factors. The underlying conceptual principles, mathematical models and computer program implementation, are presented in considerable detail.

March 1974

TABLE OF CONTENTS

ABSTRACT	ii
LIST OF ILLUSTRATIONS	vi
LIST OF TABLES	vii
PART I	1
.1 - Overview	2
.2 - Dual Mode Model	4
.3 - Coverage Model	6
PART II	1-1
1 - INTRODUCTION	1-1
2 - CONCEPTUAL DEVELOPMENT	2-1
2.1 GROUND RULES AND ASSUMPTIONS	2-2
2.1.1 Fault Simultaneity	2-2
2.1.2 Failure Rate	2-3
2.1.3 Coverage	2-3
2.1.4 Coverage Conditions	2-4
2.1.5 Systems Failure	2-5
2.1.6 Spares Reassignment	2-5
2.1.7 Spares Failure	2-6
2.1.8 Fault Classification	2-6
2.1.9 Fault Detection	2-7
2.1.10 Fault Isolation	2-9
2.1.11 Fault Recovery	2-9
2.1.12 D/I/R Mechanisms	2-11
2.1.13 Performance Characterization	2-12
2.1.14 DIET vs D/I/R Process Representation	2-14
2.2 SAMPLE FUNCTION SELECTIONS	2-15
2.2.1 Detection Function Rationale	2-19
2.2.2 Isolation Function Rationale	2-26
2.2.3 Fault Propagation Recovery Function Rationale	2-27
2.2.4 Time Lost Recovery Function Rationale	2-28
2.3 TERMINOLOGY DEFINITIONS	2-29

TABLE OF CONTENTS (Cont.)

3 - MATHEMATICAL MODELS	3-1
3.1 DUAL MODE RELIABILITY MODEL	3-1
3.1.1 G: Fortran DCG	3-2
3.1.2 R_u : Fortran DCRU	3-4
3.1.3 H: Fortran DCH	3-4
3.1.4 S: Fortran DCS	3-5
3.1.5 T: Fortran DCT	3-6
3.1.6 T_2 : Fortran DCT2	3-7
3.1.7 R: Fortran DCR	3-7
3.2 COVERAGE MODEL	3-8
3.2.1 Subscripts and Simple Variables	3-10
3.2.2 C: Fortran COVAGE	3-10
3.2.3 $C(i,s)$: Fortran COVAGE	3-11
3.2.4 $g_i(\tau)$: Fortran CVGS, CVG2 and CVG1	3-11
3.2.5 $g_i^!(\tau)$: Fortran CVGP4 and CVGP3	3-14
3.3 PARAMETER DEFINITIONS AND APPLICABILITY	3-17
4 - SOFTWARE	4-1
4.1 PROGRAMMING CONSIDERATIONS	4-1
4.2 SUBPROGRAM DESCRIPTIONS	4-3
4.2.1 Altered Subprograms	4-7
4.2.2 New Utility Subprograms	4-11
4.2.3 Dual Mode Model Implementation Subprograms	4-13
4.2.4 Coverage Model Implementation Subprograms	4-14
4.3 MAJOR ARRAYS AND COVERAGE DATA BASE	4-26
4.3.1 Reliability Parameters	4-26
4.3.2 Reduced Field Length CARE2	4-27
5 - PROGRAM OPERATION	5-1
5.1 USER'S GUIDE	5-1
5.1.1 Processing Order	5-2
5.1.2 Use of the Input Algorithm	5-3
5.1.3 Specific Input Information	5-24
5.2 OPERATIONAL LIMITS	5-31

6 - EXAMPLES AND TEST CASE DATA	6-1
6.1 JOB #1 - PRODUCT OF EQUATIONS 4 AND 2	6-2
6.2 JOB #2 - PRODUCT OF EQUATION 4 AND 2, WITH CALCULATED COVERAGE	6-2
6.3 JOB #3 - DUAL MODE MODEL (DUAL CHANNEL) WITH PRESET COVERAGE	6-3
6.4 JOB #4 - DUAL MODE MODEL (DUAL CHANNEL) WITH PRESET COVERAGE, MULTIPLE RUNS WITHIN RUNSET AND SPARES REASSIGNMENT	6-4
6.5 JOB #5 - DUAL MODE MODEL (DUAL CHANNEL) WITH CALCULATED COVERAGE AND MULTIPLE RUNSETS	6-5
6.6 JOB #6 - DUAL MODE MODEL (HYBRID CHANNEL) WITH CALCULATED COVERAGE AND MULTIPLE RUNSETS	6-5
6.7 JOB #7 - PRODUCT OF EQUATIONS 7, 4 AND 2	6-7
7 - SUMMARY AND CONCLUSIONS	7-1
APPENDIX A - FLOW DIAGRAMS	A-1
APPENDIX B - PROGRAM SOURCE LISTING	B-1



LIST OF ILLUSTRATIONS

FIGURES

2-1	DUAL CHANNEL SYSTEM RELIABILITY DIAGRAM	2-16
4-1	SAMPLE FUNCTION SELECTION CHART	4-17
5-1	INPUT ALGORITHM	5-5
6-1	JOB #1 INPUT/OUTPUT LISTINGS	6-8
6-2	JOB #2 INPUT/OUTPUT LISTINGS	6-19
6-3	JOB #3 INPUT/OUTPUT LISTINGS	6-30
6-4	JOB #4 INPUT/OUTPUT LISTINGS	6-34
6-5	JOB #5 INPUT/OUTPUT LISTINGS	6-40
6-6	JOB #6 INPUT/OUTPUT LISTINGS	6-51
6-7	JOB #7 INPUT/OUTPUT LISTINGS	6-63

LIST OF TABLES

2-1	SAMPLE COVERAGE MODEL SELECTIONS	2-18
3-1	PARAMETER/MODEL APPLICABILITY	3-18
3-2	PARAMETER DEFINITIONS	3-21
4-1	CROSS-REFERENCE LISTING OF CARE2 SUBPROGRAMS	4-4
4-2	PCW AND DEFAULTS	4-28
4-3	DIMENSION CHANGES FOR REDUCED FIELD LENGTH CARE2	4-30
5-1	DEFINITIONS OF LOGICAL AND CONTROL VARIABLES	5-15
5-2	CONTROL CARDS	5-17
5-3	INPUT FORMATS AND EXAMPLES	5-19
5-4	FUNCTION SPECIFICATIONS	5-25
5-5	FUNCTION SELECTIONS BY FAULT SUBCLASS	5-26
5-6	COVERAGE MODEL PARAMETERS	5-27
5-7	OPERATIONAL LIMITATIONS	5-32

Page Intentionally Left Blank

PART I

The task of predicting computer reliability, and in particular that of fault tolerant configurations, is unfortunately a rather complex one that, of necessity, is performed with ever increasing frequency. The complexity therein arises primarily as a consequence of the rather large set of interactive factors that must be contended with if the prediction is to be meaningful. The quickening pace is the result of both increased application as, for example, in long life satellites and all digital flight control systems, as well as the general recognition that a multitude of reliability enhancement techniques are available and that the proper subset for a given application is best selected on a scientific rather than intuitive basis.

In recent years, a variety of computerized reliability models have been developed in order to minimize both the difficulty and the attendant inaccuracy long associated with such prediction. One or another of these gives proper recognition to such individual factors as coverage, multiple system operating modes, transient versus permanent failure, and so on. What is required, however, and not so readily available, is a unified model set incorporating the sum total of these, as well as a means of quantifying, rather than simply measuring the impact of, the most elusive of these, coverage. (This latter term represents the fact that the measure of reliability transcends hardware availability, and must in addition account for such issues as fault recognition, reconfiguration delay and application imposed time and accuracy constraints.)

The purpose of this report, then, is to describe the development and software implementation of a new series of mathematical models which are specifically designed to contend with these items. It thus portrays a reliability assessment system that provides a unique capacity both for calculating coverage and for measuring reliability as it relates to the totality of these factors. As such, hopefully, the system will serve as a moderate step forward in the

evolution of a scientific approach to fault tolerant computer analysis.

.1 OVERVIEW.

The computer program itself, designated CARE2, is designed to run on a 60 bit CDC 6000 series computer system, using the RUN Fortran compiler, under either the KRONOS 2.1 or SCOPE 3.0 operating system. It is available in two versions, the first of which requires a field length of approximately 130K octal to load and execute and the second, approximately 100 K. The versions differ only with regard to their ability to provide output data in the form of reliability plots.

The program is based, in part, on an earlier version entitled CARE*. The latter is somewhat characteristic of its generation in that, although it calculates computer system reliability for a variety of possible configurations, it does not provide an accounting for the effects of transient faults, multiple system operating modes and most aspects of coverage.

The current program, with regard to its modelling capability, is comprised of three major and relatively independent portions. The first of these, designated "equations 1-6", is the collection of specialized reliability models included in original CARE. The second, referred to as either "equation 7" or the "dual mode model", is unique to CARE2, and provides the capability for assessing system reliability as it relates to the set of aforementioned factors. The third, known as the "coverage model", enables the calculation of this commodity under a variety of conditions, and thus serves as input for the dual mode model and, where applicable, equations 1-6.

*F.P. Mathur, "CARE Program (Computer-Aided Reliability Estimation)", Technical Memo No. 361-10, Jet Propulsion Laboratory, Pasadena, California, February 24, 1971

CARE2, like its predecessor, portrays a computer system as a series of one or more independent subsystems or stages, wherein system reliability, by definition, is equal to the product of stage reliabilities. In turn, a stage is comprised of a quantity of identical units, termed LRU's, a portion of which serve as active or on-line devices and the remainder, as standby spares. Each stage is then represented by a single equation (i.e., model), selected on the basis of its ability to adequately represent the required physical configuration.

By way of illustration, a typical computer system might be viewed as consisting of four stages representing, respectively, the input, central processing, memory and output functions. In turn, the input stage, for example, might itself consist of three units, whose outputs are majority voted, and a single standby spare. Given then certain simplifying assumptions, the stage can be characterized by equation 4, which represents a "hybrid/simplex" configuration as defined by Mathur*.

In addition, however, the current program also provides the means for analyzing a computer system (or portion thereof) in which the component stages are interdependent such that total reliability is not a simple product of stage reliabilities. This situation is typified by a multi-stage computer wherein, given insufficient LRU's to constitute a fully operational system, a portion of those that remain are switched off and a backup or degenerate mode of operation is entered (cf. Figure 2-1). In this instance, the failure of an LRU in one stage has a conditional effect on the quantity of on-line versus spare LRU's in a second and thus, given unequal failure rates in the two states, a reliability impact on the second stage.

This capability, as well as certain others, is unique to the dual mode model (equation 7). As a consequence of this, and the additional fact that the majority of equation 1-6 configurations

* op. cit.

are but specialized subsets of equation 7, the majority of systems can, in practice, be modelled without reliance on the original six. The following summary discussion thus centers solely on the dual mode and coverage models which, together, constitute both a complete evaluation system and the new modelling portion of CARE2.

.2 DUAL MODE MODEL

This model, which is appended to the original CARE program as the seventh of seven equations, to a large degree supplants the preceding six, and thus serves as the focal point for the majority of reliability evaluations performed within CARE2. The mathematical model which underlies it, though beyond the scope of this summary, is presented in detail in Section 3.1. The capabilities which the model provides, from the perspective of the user, are highlighted in the following paragraphs.

As noted previously, CARE2 represents a computer system as a series of stages, each corresponding to a single class of functional LRU's. The dual mode model, in terms of its software implementation, has a capacity for up to eight such stages, wherein each represents a grouping of like LRU's consisting of zero or more each of on-line and spare units.

The phrase dual mode is, itself, a reference to an ability to model a system comprised of two distinct quantities of on-line LRU's per stage, which correspond, respectively, to the number required for operation in each of two system modes. Thus, the object computer system is represented by two separately specified configurations which, in turn, characterize its hardware complement in both an initial and backup state.

This dual mode provision enables the representation of computer systems which, confronted with critical equipment failures, are designed to reconfigure into a second, and less demanding state. For example, in Figure 2-1, mode 1 is the preferred operating state as a consequence of its provision for rapidly discerning faults via the comparator. Given, however, a permanent failure in either the

comparator or all but one of the LRU's of a particular stage, operation can no longer continue in that state. At this point, the object computer system is designed to reconfigure into its mode 2 state wherein sufficient hardware, barring further critical failure, is available to maintain a "degenerate" form of operation.

In addition to stages and their component LRU's, the model also provides for the representation of two object system "single point failure mechanisms." The first of these corresponds to the class of switch and comparator/voter failures which, on occurrence, unconditionally cause degeneration from mode 1 to mode 2. The second represents the class of failures, termed catastrophic, which cause immediate and total loss of the system. Each is expressed, within the model, solely in terms of its corresponding permanent failure rate.

LRU's, on the other hand, are considered subject to both transient and permanent faults, wherein the rate of the latter is, in addition, conditioned by LRU status. As a consequence, the model provides for a separate LRU failure rate specification for each of three failure classifications i.e., transient, on-line permanent and standby permanent.

Given the occurrence of mode degeneration in a computer system, it is typically accompanied by a partial equipment shutdown in which one or more fully functional LRU's are released from active service. These units then, as a function of computer design specifics, either re-enter the spares pool or, conversely, are not re-assignable and thus, from a computer reliability viewpoint, are purged from the system. The model provides for either possibility, in accordance with a user controlled software switch setting.

In total then, the dual mode model has the capacity for representing a computer system with either one or two distinct hardware configurations, and consisting of one to eight functional stages. In practice, the system is defined in terms of these stages, wherein the user specifies, for each stage, the mode 1, mode 2 and spare LRU

count, as well as the applicable transient, on-line and standby failure rates. Additionally, the two single point failure rates and the spares reassignment method (on degeneration) are user specified at the system level.

.3 COVERAGE MODEL

For purposes of this study, coverage is defined as "the conditional probability, given a fault and sufficient hardware replacements to remedy it, that the system is returned to operational status in a form consistent with external time and accuracy needs." In other words, it is a measure of the reduction in system reliability due to issues other than those of hardware availability, and thus serves as an accounting for such factors as the inability to either detect, isolate and/or recover from, certain classes of faults. For example, given both a permanent fault in an on-line memory and a fully operational spare, the conditions of hardware success are, for the moment, met. Those of coverage, however, further dictate that the fault be correctly attributed to the memory, and that the replacement unit then be "reloaded" within certain time constraints.

It follows that coverage is not single valued for a given computer system. For instance, the ability to detect a fault is clearly a function of its location within that system. Further, the ability to recover, as from a memory fault, may depend on the presence of a second unit with identical storage contents, and this may be available in only one of the mode configurations.

From a system perspective then, coverage is readily seen to depend on fault subclass (location, as within an LRU), fault type (permanent or transient) and operating configuration (mode). In addition, it is related to at least two other factors; i.e., whether the fault results in a mode change (which may entail certain risk), and the status of spare LRU's (which are subject to prior failure, thus presenting a possible requirement for trial selection and testing in order to locate an operational unit).

The model provides for the calculation of a single conditional coverage value for each valid combination of these conditions. In turn, the set of computed values are then supplied to the appropriate reliability equation for inclusion in the system reliability assessment. Since, in practice, the original six equations are, at best, ill equipped to contend with coverage, the normal recipient is the dual mode model.

Since the same methodology is utilized to compute each of the conditional coverage values, the remainder of this discussion is addressed to the rationale underlying the modelling and calculation of a single value (i.e., for a fixed set of conditions). It should be specifically noted, however, that each of the parameters referenced therein has a potentially unique value for each set of conditions.

Given the occurrence of a fault, the object system is presumed to be equipped with more or less suitable defense mechanisms to contend with it. The coverage model is based on the assumption that, in all but the unprotected case, these consist of one or more fault detectors (e.g., memory parity and software selftest) as well as associated fault isolation and recovery techniques. In this sense, conditional coverage is but an overall performance measure of these, as a group, and as they pertain solely to the fixed conditions.

In addition, it is assumed that, given multiple fault detectors (within the fixed conditions set), they are best represented as statistically independent processes. (Conversely, members of separate sets are treated as mutually exclusive). As such, on occurrence of a fault, they can be viewed as competing with one another, though not necessarily with equal vigor. The "winner", if in fact there is one, then calls into play, in sequence, its associated isolation and recovery processes.

Given the detection of fault in the object computer system, the ability to identify the responsible detector can prove instrumental in constraining the isolation and recovery tasks which follow

(i.e., individual detectors have more or less unique properties with respect to the type of faults they detect and when they detect them). As a consequence, the coverage model is designed to provide for the calculation of the conditional detection probability associated with each of the competing detectors, given its presence in a competitive situation.

In turn, these values are highly dependent on the following factors:

- The stand-alone success probability of each fault detector (i.e., the percentage of faults it would discern if it were the only detector present).
- The corresponding stand-alone detection rate associated with each.
- The complete time base or schedular interrelationship between each (i.e., individual repetition rates, where applicable, zero-offset delays, etc.).

Given this data as input, the model performs the calculations necessary (cf. Section 3.2) in order to establish the interrelationship that exists between the detectors, and thus provide the conditional detection probability and rate of each, when in competition with the others.

This information is then utilized, in conjunction with corresponding fault isolation and fault recovery time profiles, in order to produce the contribution to coverage (for the fixed condition set) associated with each of the individual detectors. Thus, their sum is the conditional coverage value associated with the set of conditions.

In this regard, the isolation profile is a rate (i.e., probability density) function which represents the performance characteristics of the isolation process corresponding to the particular detector. The referenced recovery profile is, in fact, two separate characterizations, both measured in terms probability (rather than probability density) versus time. The first of these, referred to

as the error propagation function, is indicative of the reduction in recovery probability due to the potentially unconstrained propagation of erroneous data, throughout the computer system, during the interval between fault occurrence and fault detection. The second, known as the time delay function, corresponds to the potential diminishment of recovery probability as a function of effective computer down time, and as measured from fault occurrence on through detection, isolation and, where required, trial selection and testing of spares, until such time as the true recovery process is initiated. (The time delay impact associated with the recovery process itself is handled implicitly in the recovery probability function.)

Again, it should be emphasized that the above discussion describes the coverage calculation process associated with a single subclass location, while operating in a particular mode, and when confronted by a specific type of fault. Also, it should be noted that each of the fault detectors has a unique description, both within and between condition sets, and further that the isolation and two recovery processes also have unique descriptions for each possible combination of detectors and condition sets.

In perspective, then, the repetition of this process, once for each of the possible condition sets, constitutes the process referred to as coverage calculation.

Page Intentionally Left Blank

PART II

SECTION IINTRODUCTION

The purpose of this combined study and software development effort was to provide an advanced analytical tool for use in estimating the reliability of various fault-tolerant, dual, spare-switching digital computer systems. As such, it was to include a means of accounting not only for permanent (i.e., hard) faults, but also transient faults (i.e., faults which do not persist, but whose effects can) and coverage factor (i.e., the conditional probability of system recovery given that sufficient operational hardware is available).

As originally conceived, the phrase "dual system" was in reference to a configuration comprised of two identical computers, operating in parallel, and joined following their digital output stage by a comparator. Further, each computer was partitioned into four switchably replaceable units, and these in turn were backed up, at the system level, by a variable quantity of spares.

In the course of developing the accompanying mathematical models, an opportunity for increasing the problem solving capability rather significantly became apparent, but with it, a practical necessity that it be incorporated prior to any further software development. The resulting change, subsequently agreed to by both parties, amounted to substitution of the phrase "dual mode" for "dual system" in the original work statement. With it, however, came a revision of the mathematical models and software so as to include a capability for evaluating virtually any configuration involving sparing at the unit level, and accompanied by any kind of fault detection, isolation and recovery procedures, provided that only two system operating modes are required and that software based numeric limits are not exceeded. The resultant modeling capability thereby extends, for example, to the majority of both "N-modular-redundant" and "hybrid" systems.

The software phase of the effort was specified to be implemented as an addition to an existing statistical reliability prediction program entitled CARE*. This program was developed, by the Jet Propulsion Laboratory, to "serve as a computer aided reliability design tool to designers of ultra-reliable fault-tolerant systems, by facilitating reliability computation, data generation, and comparative evaluation".

CARE's rather singular emphasis on permanent faults and one mode system operation was seen, however, as a rather significant shortcoming with respect to the defined programmatic requirements, and thus indicative of the need either for a serious revision or a nearly stand-alone addition to the existing base.

As a practical matter the latter course was selected, and with it, the corollary development of a dichotomy between old and new halves of the program. This division, though most pronounced in the inner workings of the software, also evidences itself in both the input/output structure and the frequent overlapping of capabilities wherein a given system can be evaluated with either half, though with rather marked differences in terms of modeling depth.

The new portion of this program, at times supplemented by the old, can be used as a reasonably sophisticated analytical tool to assess the reliability of a wide variety of fault-tolerant computer configurations. In addition, it is particularly attuned to the needs of performing sensitivity analyses on variations of a single configuration including, for example, measuring the effect of changes in schedule on the usefulness of a software self-test routine.

* F.P. Mathur, "CARE Program (Computer-Aided Reliability Estimation)", Technical Memo No. 361-10, Jet Propulsion Laboratory, Pasadena, California, February 24, 1971

It should be specifically noted, however, that the necessary inputs to the program include a statistical specification of all significant fault detection, isolation, and recovery mechanisms within the system, i.e., it must be furnished data describing the properties of the various coverage features included in the object computer. The generation of this data is, in some cases, quite difficult, and the values obtained, often subjective. This is seen, however, not as a shortcoming of the study, but rather as an indication that reliability prediction is, itself, a difficult undertaking, and that much additional work remains before it can truly become a science.

The following sections describe the results of the subject effort, including development of the conceptual base, its implementation in terms of mathematical models and subsequently software, and instructions on its utilization in the form of a "users guide" for operation of the program.

SECTION 2

CONCEPTUAL DEVELOPMENT

The achievement of fault tolerance in a reconfigurable computer system transcends the issue of hardware survivability; a second and equally essential prerequisite is that of fault awareness and the consequent ability to re-establish control successfully in a properly reconfigured system. This necessitates that the system include a methodology for detecting, isolating, and ultimately recovering from any of a necessarily large percentage of faults. Collectively, these methods are referred to herein as "fault tolerant features" (FTF's), and their integrated function is to provide "coverage".

At issue then, in a properly directed system design process, is the selection of an effective FTF set for a particular configuration, with the limiting constraint being that each provides a degree of coverage only at the expense of additional hardware and/or reduction in effective computational throughput. Up to a point therefore, the addition of FTF's enhances the probability of successful operation; beyond that, the ever decreasing gain in coverage (via overlap of faults covered) is quickly overshadowed by the failure mechanisms inherent in the FTF implementation hardware.

This study, which is itself the outgrowth of a current necessity for quantifying fault tolerant computer performance has, therefore, as its fundamental objective, the development of a computer based method for assessing system reliability as it relates to both hardware configuration and FTF's employed therein.

Of the three main tasks in this effort, deriving the mathematical reliability model for a dual mode system, providing for calculation of the coverage factor, and extending the existing CARE program accordingly, the second is undoubtedly the most complex, and necessarily the most open to question. Consequently, much of the following discussion centers on this particular aspect of the study.

2.1 GROUND RULES AND ASSUMPTIONS

In order to place bounds on both the magnitude of the study and the execution time required for the resulting computer program, certain simplifying assumptions must necessarily be made. At the same time, however, it is of even greater importance that all governing performance factors be properly accounted for. What is called for, then, is a somewhat delicate balance between too much and too little. Unfortunately, as is often the case when developing models, the quantitative information most desired for the decision making process is available only as an output from, rather than input to, the modeling task. As a consequence, therefore, it is necessary to rely rather heavily on intuitive processes rather than known phenomena.

In this study, the following considerations were judged to be both necessary and sufficient in order to provide for a representative reliability assessment:

2.1.1 Fault Simultaneity

Independent and simultaneous, or near simultaneous, fault occurrences are assumed to be sufficiently improbable as to justify ignoring them, both for the purpose of system evaluation and for that of system design as well.

2.1.2 Failure Rate

Constant values are assumed throughout. In particular, three separately specified quantities are provided for each of a quantity of LRU (line replaceable unit) types:

- λ - the permanent-failure rate of on-line (i.e., active) LRU's
- μ - the permanent-failure rate of standby (i.e., spare) LRU's
- γ' - the transient-failure rate of on-line LRU's.

In addition, two single-valued system level rates are included:

- $\hat{\lambda}_2$ - the permanent-failure rate of system components whose loss forces an immediate degeneration in operating mode (e.g., certain non-catastrophic failures in an output voter or comparator)
- $\hat{\lambda}_3$ - the permanent-failure rate of system components whose loss is catastrophic (e.g., loss of all input power to the system).

2.1.3 Coverage

For purposes of this study, coverage is defined as "the conditional probability, given a fault and sufficient hardware replacements to remedy it, that the system is returned to operational status in a form consistent with external time and accuracy needs". In turn, its value is viewed as functionally dependent on three conditional probabilities:

- The probability, given a fault, that it is detected
- The probability, given a detected fault, that it is properly isolated

- The probability, given a properly isolated fault and sufficient spares to remedy it, that a satisfactory cure is effected.

2.1.4 Coverage Conditions

Though often discussed as though it were a single valued quantity for a given system operating in a given environment, coverage is more accurately a set of values, each of which corresponds to a specific situation. In particular, the degree of coverage offered is, at a minimum, dependent on the following conditions:

- operating mode - whether the system is fully operational (e.g., 2 out of 2 channels functioning) or degenerate (e.g., 1 out of 2 channels functioning)
- fault location - whether the fault lies, for example, in the system's input, CPU, memory bit plane, memory word electronics or output area
- fault type - whether the fault is permanent or transient
- spares status - whether initial replacement units, as selected from the spares pool to remedy a fault, are themselves operational or faulty
- degeneration requirements - whether or not it is necessary, as a function of spares status, to change operating mode (i.e., to undergo transition) in the event of a fault.

As a consequence, a unique coverage value exists for each combination of conditions, and must therefore be accounted for in the reliability assessment.

2.1.5 System Failure

It is assumed throughout this study that a coverage failure inevitably results in total system failure. Specifically, this includes:

- failure to detect a fault
- failure to correctly isolate a detected fault
- failure to recover from a correctly isolated fault.

(In addition, of course, lack of sufficient hardware to constitute an operational, degenerate system also leads to the same consequence.)

While this is in general a reasonable assumption, it is possible to conceive of reconfiguration strategies that recover from certain transients, which would otherwise be disabling, by changing to a degenerate mode of operation (e.g., by entering a simplex mode). Similarly, in certain situations, other forms of coverage failure could conceivably also lead to a degenerate mode rather than to system failure.

2.1.6 Spares Reassignment

Given a degenerative failure, a quantity of fully operational on-line LRU's are typically released from active service. Depending on system architecture specifics, those so released may or may not be available for use as spares in the event of subsequent failure. Since either situation may prevail, it is necessary that both be accounted for in the model, with the determination of which is most appropriate for representing a given configuration left to the discretion of the user.

2.1.7 Spares Failure

Since spare LRU's are themselves subject to failure (at rate μ), it is necessary to provide for situations in which the spare selected to replace a failed on-line LRU has itself failed, and must consequently be replaced by yet a second (or, in the general case, nth) spare. In the model, this is provided for in the form of a single delta coverage value per fault classification per operating mode, wherein the as calculated value is a measure of the reduction in recovery probability resulting from incurred downtime during the conditional trial and error replacement period. In calculating this, it is assumed that failed spares are purged from the system in bulk on the occurrence of mode degeneration, and as individuals following their selection as a replacement unit.

2.1.8 Fault Classification

The ability of a given detector to recognize a specific fault is, in most instances, highly dependent on the precise nature of the fault. For purposes of this study, it is assumed that two levels of classification are adequate for the purpose of so categorizing faults. The first of these, referred to as fault class, is the LRU type (e.g., CPU or memory) in which the fault occurs. The second, or fault subclass, is an arbitrarily selected portion of an LRU (e.g., arithmetic unit in a CPU).

Thus, by proper partitioning of the object system representation, first into LRU's or classes, and then into subclasses, the various faults can be categorized according to their specific detection characteristics.

2.1.9 Fault Detection

The representation of an object computer system as a series of fault subclasses underlies the approach to coverage measurement utilized in this study. Specifically, each subclass is by design a grouping of possible faults, so categorized solely on the basis of their common susceptibility to one or more fault detectors. In other words, the set of fault detectors associated with a particular subclass is, by definition of the subclass itself, comprised wholly of statistically independent members. In turn, such independence implies that each member detector has a finite probability of detecting any of the possible faults within the subclass, and that it therefore competes with all other members toward the objective of being first to detect a local fault.

This concept of competing fault detectors should not be construed to imply that a degree of equality need exist between them; on the contrary, the contest is of necessity as imbalanced as reality dictates.

For a moment perhaps, it is useful to look at the performance characteristics of a stand-alone detector i.e., one which has no competitors within the subclass. Given both singular occurrences of random faults and infinite time, the detector has an associated non-zero probability of detection. This value, as well as the corresponding detection rate profile, forms a substantial portion of the detectors' characterization.

In addition however, it is necessary to consider the occurrence rate of the detector itself i.e., the timing basis or schedule on which it executes. Two basic categories are apparent: periodic and aperiodic. The former is populated, in the main, by software based detectors (e.g., software selftest), whereas the

latter group consists primarily of hardware detectors (e.g., memory parity). (In both of these cases, it is assumed that the initial execution of the test, if unsuccessful in detecting a specific previous fault, precludes any possibility of later detection, i.e., the fault is transparent to the test.)

Returning then to a competitive situation, and given each detector characterized in terms of its stand-alone detection probability, detection rate and schedule, it would be a relatively simple task to compute an overall subclass detection probability and expected time, based on the interaction (i.e., competition) between detectors. It would not be sufficient, however, for the following reasons:

- knowledge of the specific test by which a fault is detected is frequently utilized, in the object computer, to constrain the isolation process
- individual detectors vary in their ability to either prevent or minimize fault propagation (i.e., contamination of correct information via improper processing). Since this can have major influence on the probability of recovery, knowledge of the specific detector involved must be made available.

It is necessary, therefore, that a conditional detection probability and rate be computed for each subclass member, as the values relate to the totality of competitive detectors.

2.1.10 Fault Isolation

Unlike fault detection, the isolation of faults is assumed to be a single-threaded process in which a lone isolator seeks out the source of difficulty. Since the object system, in all probability however, incorporates multiple isolators (each tailored to a specific task), it is necessary to provide accordingly in the model.

In particular, it is assumed that each detection process is uniquely linked to an isolator such that, given detection of a fault by it, the corresponding isolator is unconditionally brought into play. In turn the isolator, by virtue of its tailored design, inherently capitalizes on whatever unique characteristics the detector may possess in order to constrain the bounds of the search.

By way of example, the isolation process associated with detection by memory parity is clearly minimal (if in fact it exists at all), whereas detection by an external voter implies nothing in the way of fault location, thus mandating a far-ranging and potentially time-consuming search.

As in the case of fault detectors, fault isolators are seldom, if ever, perfect, and thus have both a non-unity success probability and a finite process rate. For analogous reasons then, this must be accounted for in the impending fault recovery process.

2.1.11 Fault Recovery

The hardware aspects of fault recovery are reasonably well disciplined. Either a spare hardware unit and the needed switching apparatus are available, in which case that portion of the cure can be effected, or they are not, in which case the system either degenerates or fails completely (barring the use of techniques such as those of "graceful degradation" in the event of partial memory loss, etc.).

The coverage portion of fault recovery, on the other hand, must contend with all issues save those of hardware availability, and is thus confronted with a rather unwieldy grouping of considerations which, in turn, are considerably more difficult to deal with, both in the object system itself and, consequently, in the model as well.

In particular, it is felt that each of the following are of sufficient importance as to necessitate inclusion in the model:

- the subclass in which the fault is located (for reason of its potential influence on recovery difficulty)
- the time delay between fault occurrence and fault recovery, as it relates to the issue of system downtime. (Of necessity, this incorporates any time devoted to spares checkout including repetitions, where required, to locate a functional spare)
- the degree and location(s) to which fault propagation was contained, and the corresponding time interval during which it was unconstrained. (The model assumes here, as a first order approximation, that this interval starts on occurrence of the fault and ends on its detection. Compensatory adjustments, where called for, can be achieved by modifying the degree of sensitivity)
- the detector responsible for finding the fault, as it relates both to the degree of fault propagation and the time required for detection
- the system operating mode at the time of fault occurrence
- the type of fault involved (permanent or transient)
- the need, or lack of it, for mode degeneration.

In addition, successful recovery is assumed to be conditioned by the following:

- successful detection of the fault
- successful isolation of the fault
- in the case of a permanent fault, availability of a spare LRU or, barring that, sufficient on-line LRU's to maintain operation in a degenerate mode
- in the case of a permanent fault, successful detection of any failure present in a selected spare LRU.

2.1.12 D/I/R Mechanisms

Since each of the object system fault detection (D), isolation (I) and recovery (R) processes has the potential for reacting differently to a fault as a function of its location (subclass), the type of fault (permanent or transient), the system operating mode (fully operational or degenerate) and any requirement for degeneration (given certain hardware losses in a fully operational system), it is necessary to provide a means for modeling each possible reaction separately. The total set of system reaction descriptions corresponding to detection by a particular detector is then referred to as a D/I/R mechanism.

By way of illustration, take the case of a CPU selftest fault detector. As its name implies, it is most proficient at detecting fault which occur in the CPU; nonetheless, it exhibits a finite capacity to detect those in other subclasses as well. For instance, given that the test executes out of memory, it follows

that certain faults located therein will cause it to misexecute, thus resulting in an eventual fault indication (albeit for the wrong reason). Similarly, though the test is reasonably adept at detecting permanent CPU faults, its capacity in the presence of transients is, at best, marginal.

It follows then, in the general case, that a detectors' performance may be expected to vary as a function of all the aforementioned environmental conditions. In analogous fashion, the isolation and recovery processes associated with that detector may likewise be expected to exhibit similar dependencies.

In context, then, a D/I/R mechanism is the total set of performance descriptors pertaining to a particular fault detector. As such, it consists of separate detection, isolation and recovery performance characterizations, one each for every meaningful combination of conditions.

2.1.13 Performance Characterization

As noted, each of the object system fault detectors, together with its associated fault isolation and fault recovery techniques, is represented in the model as a D/I/R mechanism. Each mechanism is then represented by a set of performance characterizations, one each for all combinations of detection, isolation and recovery processes across a spectrum of conditions.

In turn, each of the individual performance characterizations is expressed in terms of a function specification and a referenced

function model. The latter are parametrically expressed probability and probability density functions which serve as a representative form or pattern for the characterization, and the former provide specific numeric details to round out the characterization. The end object of these (i.e., a fully described process representation) is then referred to as a function.

In particular, the following set of function models is viewed as sufficient to enable adequate characterization of the majority of known processes:

- Impulse - a burst of zero duration with finite integral, representing an instantaneous process
- Constant - a pulse with finite duration, representing a constant process
- Finite Pulse String - a series of equally spaced pulses, representing a discontinuous process
- Exponential - a decaying exponential, representing a continuous, but ever decreasing, process.

In practice (i.e., in the software implementation of the model), each function specification is identified, for reason of user convenience, by means of a unique function number. As a consequence, like process characterizations, once defined, can be elicited repeatedly via their identifying number.

Viewed as a whole, D/I/R mechanisms are utilized, on a one for one basis, to describe the totality of performance characteristics associated with each fault detector. In turn, mechanisms are defined in terms of function numbers, one each for all combinations of conditions and processes. Each function number corresponds directly to a function specification which, in turn, contains both quantitative data and a reference to a particular function model. The latter then is a parametric expression which describes the general form of the performance characterization.

2.1.14 DIET vs. D/I/R Process Representation

In previous sections, frequent reference has been made to the detection, isolation and recovery process representations which constitute a D/I/R mechanism. In particular, the requirements for modeling each were developed in sections 2.1.9, 10 and 11 respectively, their relation to a D/I/R mechanism presented in section 2.1.12, and the general method utilized to specify them described in section 2.1.13.

As a final note, however, it should be recognized first, that given both a particular detector and set of environmental conditions, there exists a singular set of process representations which describe the corresponding detection/isolation/recovery sequence and second, that the set consists of four representations, one each describing the detection (D), isolation (I), error-propagation-recovery (E) and time-lost-recovery (T) facets of the

corresponding mechanism. The latter subdivision (of recovery into components I and E) is a direct consequence of the rationale presented on page 2-10, second and third items respectively.

2.2 SAMPLE FUNCTION SELECTIONS

Although the objective of this study is to develop a relatively general-purpose system reliability prediction tool, an underlying goal is its application to a specific fault tolerant computer configuration; a dual channel system consisting of input, CPU, memory and output LRU's, plus an external comparator (cf. figure 2-1).

To this end, D/I/R mechanism definitions and performance characterizations have been made for a set of fault detectors, each member of which has potential application in the subject system. Table 2-1 summarizes these, wherein the reader's leftmost column is a list of the detectors (and equivalently, the D/I/R mechanisms). The double row to the right of each detector defines the mechanism as it relates to varying environmental conditions, the latter consisting of combinations of fault subclass (Input vs. CPU etc., across the top heading row), fault type (Permanent vs. Transient, across the second heading row), and system operating mode (2 channel vs. 1 channel, down the second column from the left). In turn, each rectangle (representing a single mechanisms performance under specific conditions) contains either a zero (representing a null

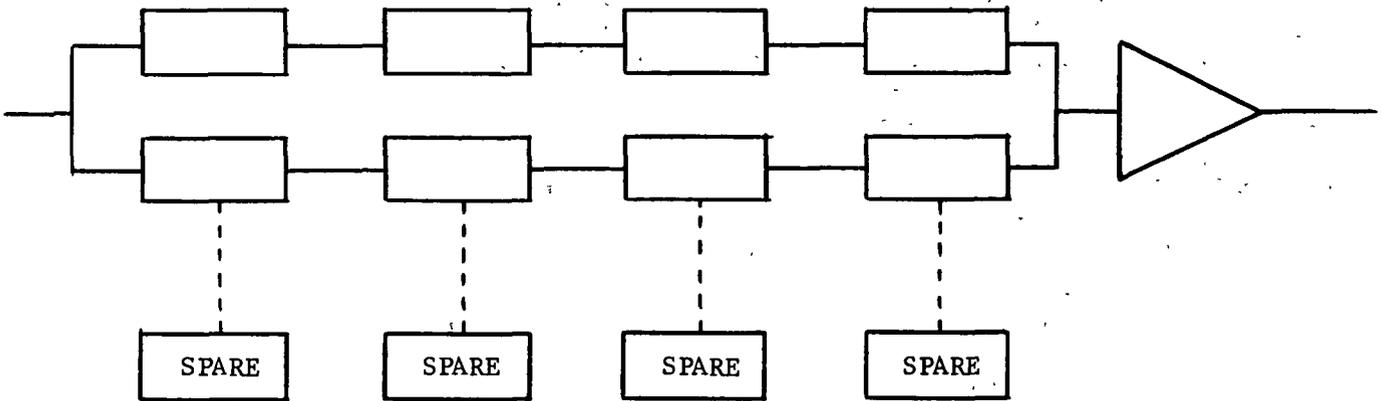
LRU TYPE

INPUT CPU MEMORY OUTPUT (COMPARATOR)

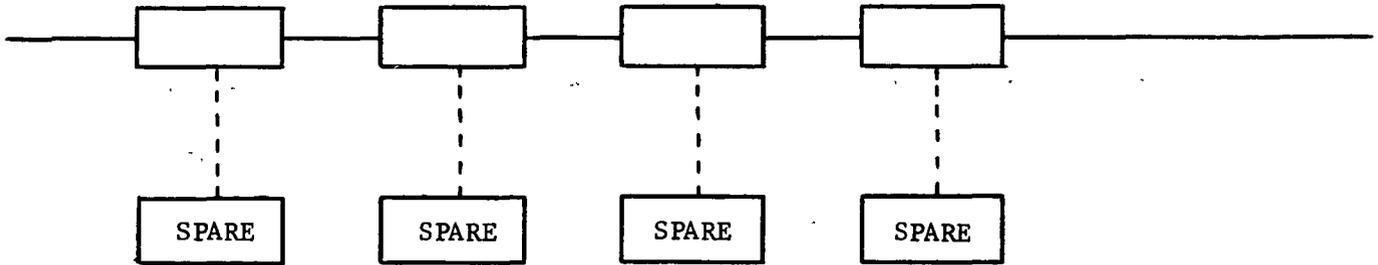
FAULT SUBCLASS

INPUT CPU BIT WORD OUTPUT

PLANE ELECT.



MODE 1 CONFIGURATION (FULLY OPERATIONAL)



MODE 2 CONFIGURATION (DEGENERATE)

FIGURE 2-1
DUAL CHANNEL SYSTEM
RELIABILITY DIAGRAM

response) or a series of four numbers. In the latter case, the four correspond to detection (D), isolation (I), error-propagation-recovery (E) and time-lost-recovery (T) function numbers, respectively, as indicated by the third heading row.

The function numbers referred in Table 2-1 are defined, in Table 5-4, in terms not yet presented. The rationale leading to their specification and selection, however, is discussed at length in the remainder of this section. Prior to initiating this, though, the following points should be noted:

- individual detectors have been purposely interpreted, in terms of their scope, in a somewhat restrictive fashion. For example, software selftest can be viewed as including some form of memory addressing scheme check; in terms of this study, however, each has been interpreted to be a separate and distinct test, and categorized accordingly.



	INPUT			CPU			MEMORY BIT PLANE			MEMORY WORD SELECT			OUTPUT		
	DIET	TRANS.	PERM.	DIET	TRANS.	PERM.	DIET	TRANS.	PERM.	DIET	TRANS.	PERM.	DIET	TRANS.	PERM.
MEMORY CODE	0	0	0	0	0	0	1 1 1 1	1 1 1 1	1 1 1 1	0	0	0	0	0	0
1 ch.	0	0	0	0	0	0	1 1 1 2	1 1 1 2	1 1 1 2	0	0	0	0	0	0
OUTPUT	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	9 2 1 2
COMPARE/VOTE	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1 ch.	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
I/O WRAP-AROUND	1 1 1 1	0	1 2 2 1	0	1 2 2 1	0	1 2 2 1	0	1 2 2 1	0	1 3 2 1	0	1 1 1 1	0	0
1 ch.	1 1 1 2	0	1 2 2 2	0	1 2 2 2	0	1 2 2 2	0	1 2 2 2	0	1 3 2 2	0	1 1 1 2	0	0
CPU SOFTWARE	0	0	1 0 1 1	0	1 0 1 1	0	1 4 2 1	0	1 4 2 1	0	1 5 2 1	0	0	0	0
SELFTTEST	0	0	1 0 1 2	0	1 0 1 2	0	1 4 2 2	0	1 4 2 2	0	1 5 2 2	0	0	0	0
1 ch.	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
REASONABLE-NESS TESTS	2 1 1 1	2 1 1 1	1 6 2 1	1 6 3 1	1 6 2 1	1 6 3 1	1 6 2 1	1 6 3 1	1 6 2 1	1 6 3 1	1 6 2 1	1 6 3 1	1 6 2 1	1 6 3 1	1 6 2 1
1 ch.	2 1 1 2	2 1 1 2	1 6 2 2	1 6 3 2	1 6 2 2	1 6 3 2	1 6 2 2	1 6 3 2	1 6 2 2	1 6 3 2	1 6 2 2	1 6 3 2	1 6 2 2	1 6 3 2	1 6 2 2
TIMEOUT	3 1 1 1	3 1 1 1	1 7 2 1	1 7 3 1	1 7 2 1	1 7 3 1	0	0	0	0	3 1 1 1	3 1 1 1	3 1 1 1	3 1 1 1	3 1 1 1
COUNTERS	3 1 1 2	3 1 1 2	1 7 2 2	1 7 3 2	1 7 2 2	1 7 3 2	0	0	0	0	3 1 1 2	3 1 1 2	3 1 1 2	3 1 1 2	3 1 1 2
1 ch.	0	0	2 1 1 1	2 1 1 1	2 1 1 1	2 1 1 1	0	0	0	0	0	0	0	0	0
CPU CODE	0	0	2 1 1 2	2 1 1 2	2 1 1 2	2 1 1 2	0	0	0	0	0	0	0	0	0
1 ch.	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
MEMORY	0	0	4 2 1 1	0	1 8 1 1	1 8 3 1	1 9 1 1	0	0	0	0	0	0	0	0
SUMCHECK	0	0	4 2 2 2	0	1 8 1 2	1 8 3 2	1 9 1 2	0	0	0	0	0	0	0	0
1 ch.	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
INVALID INST	0	0	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1
1 ch.	0	0	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2
READ/WRITE	0	0	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1
PROTECT	0	0	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2
1 ch.	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ADDRESS	0	0	0	0	0	0	0	0	0	0	6 1 1 1	6 1 1 1	0	0	0
FEEDBACK	0	0	0	0	0	0	0	0	0	0	6 1 1 2	6 1 1 2	0	0	0
1 ch.	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ADDRESSING	0	0	7 2 1 1	0	7 2 1 1	0	7 2 1 1	0	8 1 1 1	0	8 1 1 1	0	0	0	0
SCHEME	0	0	7 2 2 2	0	7 2 2 2	0	7 2 2 2	0	8 1 2 2	0	8 1 2 2	0	0	0	0
CHECK	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1 ch.	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

TABLE 2-1
SAMPLE COVERAGE MODEL SELECTIONS

- certain detectors, in the process of searching out faults in a particular unit, have an inherent capacity to detect faults in others as well. This capacity, though perhaps beyond the intended scope of the test is, in many cases, significant enough to warrant inclusion in the model set.
- in many instances, the ability of a detector to find faults in a particular unit, though possibly non-zero, is of insufficient magnitude to warrant consideration in the study.
- the time at which a fault actually occurs is viewed as immaterial and, in its place, emphasis is placed on the time at which it can first affect other processes.

2.2.1 Detection Function Rationale

The following subsections describe the reasoning behind the detection function selections shown in Table 2-1:

2.2.1.1 Memory Code

Any such code, for example, Hamming or simple parity, offers the same form albeit not the same degree of protection. This can be characterized by noting that:

- in a typical implementation, only memory bit plane (i.e., data) faults are protected
- the degree of protection offered is independent of the quantity of channels operating and independent of whether the fault is permanent or transient
- to the extent that a given faulty bit pattern is covered, the fault will be detected on reading the cell and, thus,

given a reasonable computer and software design, mission computation will cease prior to any consequent incorrect processing.

The latter gives rise to a belief that any such code can be modeled via an impulse. Further, since error propagation is precluded, the effective delay time between fault occurrence and fault detection is zero.

2.2.1.2 Output Compare/Vote

The technique requires the presence of at least two operating and fully synchronized channels and is, therefore, inoperative in all one-channel situations. Given two or more, it is capable of detecting all faults save those in the output unit, on their passage from channel to comparator (cf. Figure 2-1).

On the assumption that the comparator/voter receives all digital output commands, but no others, its detection rate can be characterized as a decaying exponential training off eventually to zero. (The presumption here is that all meaningful faults ultimately result in the output of erroneous values, and that the probability as to when is highest immediately following fault occurrence and ever diminishing thereafter.)

Since detection is presumed to occur on output, external, but not internal, faults are precluded from propagating.

2.2.1.3 I/O Wraparound

Test performance is independent of the quantity of channels operating. In effect, only permanent faults are detected in that transients can be observed only in the situation where they occur during performance of the test case. Such faults affect only test data.

The test, by design, checks out portions of the input and output units; indirectly, however, it affords some detection of faults in the remaining units by virtue of its dependence on them for operation of its software-based implementation.

The detection rate can be characterized as a pulse (i.e., a constant detection rate over its operating interval) in that the test consists primarily of the sequential checkout of multiple channels, each with equal likelihood of having failed. Because it is a periodic (i.e., scheduled) test, it affords little protection against fault propagation. Similarly, the delay time between fault occurrence and fault detection is dependent on when the fault occurs with respect to the scheduled test time.

2.2.1.4 CPU Software Selftest

The expression software selftest often implies a medley of assorted tests. For purposes of clarity, all but one of these, CPU test, have been broken out and categorized separately.

The residual test is seen as offering no protection against meaningful transient faults and no protection against input or output faults. By design, it detects the majority of CPU faults, with the rate function seen as a truncated decaying exponential. In this sense, the cutoff portion represents those faults which are not detected, and the non-zero duration of the truncated exponential corresponds to the run time of the test. The decaying exponential form represents a belief that the majority of faults (for reason both of test design and hardware requirements to run the test) are detected near the beginning of the test and that, from there on, it is a fight against ever-diminishing returns up through test end.

The test, by nature of its being a scheduled event, precludes

little in the way of fault propagation and, for the same reason, varies in its detect time as a function of the relationship between fault occurrence time and test run time.

Since the test operates out of memory, it offers a degree of fault detection with respect to memory-based faults.

2.2.1.5 Reasonableness Tests

The tests are interpreted to be a series of short duration checks, primarily on the validity of recently calculated data, which are performed throughout the epoch cycle. As such, their performance is unaffected by the quantity of channels operating, as well as by whether the fault is permanent or transient. By reason of inaccessibility to internal processes, output faults cannot be detected.

The use of a zero delay impulse model to characterize its detection rate function for input faults, is based on the inherent capacity of the test to preclude certain faults from entering the system. This in turn is seen as equivalent to a zero detection time.

On the other hand, CPU and memory are provided with unscheduled pulse rate functions, as warranted by their aperiodic characteristics (with respect to fault occurrence) and the consequent variant time interval prior to detection.

2.2.1.6 Timeout Counters

Such counters can be incorporated in any or all channel subunits, though incorporation in memory is viewed as offering word select protection only. In all cases, other than CPU, the tests can be adequately characterized by means of an unscheduled zero-delay impulse, due to their essentially instantaneous service. The CPU counter, on the other hand, is presumably a watchdog timer and, thus,

has a delay time measured in milliseconds. Since the time of detection is independent of when the fault occurs (within the timeout interval), the test appears as an unscheduled pulse. Consequently, little protection against fault propagation is offered.

All forms of the test are relatively insensitive to whether the fault is permanent or transient, and totally insensitive to the quantity of operating channels.

2.2.1.7 CPU Codes

Though other forms are possible, this class of test is typically implemented as a residue or product code applied to the ALU, data path and register portions of a CPU. As such, it offers singular protection against a large subclass of CPU faults, and does so independent of whether the fault is permanent or transient. The quantity of computers operating has no impact.

Since faults are detected on occurrence, all forms of fault propagation are precluded, and, thus, the proper model is an unscheduled impulse of zero delay.

(Note that the existence of fault partitions within the CPU (from the view of this particular test) suggests rather strongly that the CPU might better have been treated as two subclasses for coverage computation purposes (i.e., one containing the ALU and the other, the control unit.))

2.2.1.8 Memory Sumcheck

The technique, which consists of occasional exclusive-or sumchecks on the contents of invariant subportions of memory, offers a significant degree of memory bit plane and word select fault detection. In the case of bit plane faults, the protection afforded is unaffected

by whether the perturbation was transient or permanent, whereas in the word select case, only permanent faults (in any meaningful sense) are detected. In both cases, the quantity of computers operating has no impact.

Since the test, by virtue of its rather excessive run time, is typically partitioned into a series of N subtests, each operating on a portion of memory, it can be characterized by a string of N impulses, typically extending beyond a single epoch cycle. Due to the scheduled nature of the test, detection time is aperiodic with respect to fault occurrence, and little protection is offered against either form of fault propagation.

As a consequence of the test being implemented in software, a small degree of protection is offered against CPU faults.

2.2.1.9 Invalid Instruction

This test, in many respects, serves more as an indicator of software errors than hardware faults. For completeness it is, however, included.

To the degree that faults are in fact detected, the protection is independent of both the quantity of operating computers, and whether the fault is permanent or transient. No protection against input and output faults is offered. The detection of CPU and memory faults, though severely limited in scope, is instantaneous and independent of the time of fault occurrence.

2.2.1.10 Read/Write Protect

The test, assumed to be implemented in hardware, serves primarily as a software error detector. It does, however, have limited hardware fault detection capabilities, and is, therefore, included.

No protection is offered in the case of input and output faults. CPU and memory faults are in select cases detectable and, to this extent, the protection is independent of the quantity of computers operating and also independent of whether the fault is permanent or transient.

Detection, when it occurs, is instantaneous and, thus, the appropriate model is the zero delay impulse.

The following, severely limited, classes of faults are detectable by this technique:

- CPU - limited instances of incorrect memory address computation
- Memory bit plane - situations where the address portion of an instruction stored in memory is, on access, incorrect to the extent of crossing a protection boundary
- Memory word select - instances where an instruction fetch is performed on an incorrect memory cell, which itself contains an out-of-range address.

In these situations, fault propagation is precluded.

2.2.1.11 Address Feedback

The technique, though seldom discussed, offers a significant degree of singular protection against memory word select faults. Implementation techniques vary, with one of the more straightforward methods consisting of the encoding of address and data, rather than merely data, on storage of a word into memory. Given then a reasonably strong code, for example, six-bit Hamming, a high percentage of addressing faults can be detected on readout via the decoding process.

Protection is instantaneous, and independent of fault occurrence time, quantity of operating computers, and whether the fault is permanent or transient. Fault propagation is precluded.

2.2.1.12 Addressing Scheme Check

Given either a 2½D or 3D memory addressing scheme (preferably the latter), this technique offers a reasonable form of memory word select verification. Its methodology, which is based on the use of coincidence for word selection, enables the bulk of the memory addressing circuitry to be verified (the exception being that fraction which is unique to the variable portion of storage).

The technique, which relies on the exclusive or sumcheck testing of a specific small subset of memory locations, detects addressing faults by virtue of the implication that correct sumcheck signifies correct addressing. The test is implemented in software and, thus, also offers a small degree of CPU and memory bit plane checkout. The latter is supplanted, to a minor extent, via the sumcheck process itself which verifies the contents of the memory subset.

Because of its software basis, the test is necessarily periodic and, therefore, incapable of precluding fault propagation. Similarly, the time required to detect is dependent on the relationship between fault occurrence time and test run time. The test is not dependent on the quantity of computers running. Little or no practical protection is offered against transient faults.

2.2.2 Isolation Function Rationale

Three functions have been selected to represent the isolation process for this particular implementation of the four LRU, dual-channel system (cf. Table 5-4).

2.2.2.1 Primary Isolation Processes

This isolator, represented as a slightly delayed impulse with unity coefficient, typifies the situation in which the fault location implied by the initiating detector was, in fact, the actual location. For example, in the case of CPU selftest, the implied location is the CPU itself and, as a consequence, the first area searched in the isolation process.

Given that the implication is correct, the corresponding determination of this fact is made after a short delay (as measured from the end of the detection process) which itself represents the duration of the isolation function.

2.2.2.2 Secondary Isolation Processes

In the situation where the fault location lies other than in the detector implied LRU, the search is both misguided (initially) and, of necessity, quite extensive in domain. Correspondingly, it is best modeled as a pulse of long duration which, in turn, represents a process with constant isolation probability throughout the total interval.

2.2.2.3 Tertiary Isolation Processes

The isolation process is most complex, and least likely prone to success, in situations where either a transient fault has occurred, or where the fault is totally unlocalized (as with detection by a comparator external to the channel). Consequently, an impulse model, with long initial delay, has been selected as reasonably representative.

2.2.3 Fault Propagation Recovery Function Rationale

Two functions have been selected to represent the fault propa-

gation aspect of the recovery process. The first of these is a pulse of long duration, and represents a situation in which the recovery probability is undiminished, from this effect, up through the end point of the pulse. It corresponds to either of two situations:

- the associated fault detector precludes any appreciable form of fault propagation
- fault propagation is of little consequence, due to the presence of an operational second channel which can be utilized for update purposes

The second function corresponds to the opposite situation, in which fault propagation is of considerable potential effect, and the function is, thus, provided in the form of a decaying exponential, whose diminishment with time represents a like decrease in recovery probability. It is utilized primarily in the combined situation of degenerate system operation and the presence of fault propagation.

2.2.4 Time Lost Recovery Function Rationale

The time lost aspect of fault recovery contends with the effect, on external-to-the-system operational requirements, of channel loss during a "fault-present" interval. In the situation where both channels were operative prior to the fault, one channel normally continues servicing external needs, and, thus, the overall effect is minimal. A long duration pulse is applied in this case.

In the situation either of previous degenerate operation or fault detection by the comparator, however, the total system is temporarily out of service, and, thus, no external processing requirements are met. (Detection by the comparator is assumed to require that both channels cease normal operation and enter into the

isolation phase concurrently.) The function selected to represent this situation is a decaying exponential with cutoff in the region of mission critical time.

2.3 TERMINOLOGY DEFINITIONS

Batch Run - The total data processing task performed at one time. It may consist of one or more run-sets.

Category 1 Switch Failure - A failure, typically of spares-switching-hardware, such as to prevent proper operation of a single unit. This possibility must be accounted for in estimating the failure rate of the unit.

Category 2 Switch Failure - A failure, typically of spares-switching-hardware, such as to force degeneration of the system from mode M to mode M+1.

Category 3 Switch Failure - A failure, typically of comparator or voter hardware, such as to disable the entire system.

Channel - The minimum complement of operational hardware required to perform the system computational task.

Coverage - The conditional probability, given both an on-line unit failure and sufficient spare hardware to maintain computational processes, that the failure is detected and operation is successfully re-established, consistent with application imposed time constraints.

Coverage Model - A set of equations for evaluating the ability of a system to recover from permanent or transient hardware faults in a spares-switching environment. Also, the implementation of this model in CARE2.

Degenerative Failure - Any condition which necessitates reconfiguration of the system, from Mode M to Mode M+1, in order to regain full processing capabilities.

D/I/R Mechanism - (Detection/Isolation/Recovery Mechanism) - A coverage model representation of the conditional performance characteristics of all detection, isolation and recovery processes associated with a particular fault detector. In turn, the conditions are comprised of valid combinations of fault subclass, mode, fault type and potential requirement for mode degeneration.

Dual Mode Reliability Model - A set of equations for evaluating the reliability of a system, given that the system has no more than two distinct and relevant operating modes. Also, the implementation of this model in CARE2.

Fault - An event which perturbs computational processes within the computer system and, as a consequence, requires remedial action, in the form of detection, isolation and recovery, in order to preclude an operational anomaly.

Fault Class - The total set of possible faults associated with a single stage of a computer system.

Fault Detector - A hardware or software process whose function is to recognize the occurrence of certain classes or subclasses of faults within a system.

Fault Isolator - A hardware or software process whose function is to isolate a detected fault to the responsible LRU.

Fault Recovery Process - A hardware or software process whose function is to minimize or eliminate the potentially harmful effects of a fault, given that it is properly isolated, by means of appropriate remedial actions.

Fault Subclass - A fractional portion of a fault class, distinguished from other subclasses within the stage by either its unique susceptibility, or lack thereof, to recognition and treatment by one or more fault detection, isolation and/or recovery processes.

FTF - (Fault Tolerant Feature) - A hardware or software based process included in the system for the purpose of detecting, isolating or recovering from certain classes or subclasses of faults.

Hybrid Channel - A fault tolerant computer system in which the component stages contain unequal quantities of on-line LRU's, thereby precluding division of the system into discrete channels.

LRU - (Least Replaceable Unit) - The smallest system component which may be switchably replaced by an equivalent spare, in the event of its failure.

Major Cycle - The time interval between repetitions of the total set of scheduled detectors (i.e., the time after which the total set is repeated).

Note: In CARE2, this value is calculated internally.

Minor Cycle - The time interval between repetitions of the most frequent scheduled detector.

Note: In CARE2, all scheduled detector periods must be integer multiples of the minor cycle.

Mode - One of the possible hardware configurations in which the system can operate. In general, mode M requires more on-line units than mode M+1, and is the preferred operating configuration.

Operational Anomaly - The consequence of a fault which for reason of non-detection, incorrect isolation or unsuccessful recovery, is not remedied and therefore manifests itself in the issuance of improper control signals from the computer system.

Parameter - A variable, either defaulted, input, or precalculated, which is meaningful in either the reliability or coverage model description.

Note: In CARE2, certain parameters, such as the inverse dormancy factor K, cannot be directly input by the user.

Parameter Vector - A one dimensional Fortran array which contains the values of a single parameter for all stages in the system.

Permanent Fault - A fault which, because of its permanent nature, requires either the use of a spare LRU or degeneration in the process of recovering from its effects.

Run - The process of computing system reliability, versus time, for a given list of equation numbers (models) and a fixed set of model parameters.

Run-set - One or more runs, with possible variation of one reliability parameter type (for all stages), through the use of array PARAM. (Coverage parameters may not be varied in this way, for reason of the data base format structure.) Data base management operations take place between run-sets.

Scheduled Detector - A fault detector, usually software, which is initiated at regular periodic intervals.

Spare LRU - A single LRU contained in the spares pool. Equivalent to the term 'standby spare'.

Spares Checkout - The process of testing a standby spare, for proper operation, during the interval between occurrence of a permanent fault and commitment of the particular spare as the replacement.

Spares Pool - The total set of standby LRU's available for substitution in the event of permanent failure in one of the on-line LRU's. Note that substitution is conditioned by a requirement that both the failed LRU and its replacement be contained in the same stage.

Spares Reassignment - The process of releasing the operational LRU's in a defunct channel to the spares pool. Given that the specific computer system design allows for reassignment, the process takes place at the time of degeneration from Mode M to Mode M+1.

Stage - The total set of identical LRU's, including both on-line and standby devices, contained in the system (cf. page 4-2).

Standby Spare - A single LRU contained in the spares pool. Equivalent to the term 'spare LRU'.

System - The full complement of hardware and software comprising a fault tolerant computer configuration. In CARE2, the complex of coverage and hardware reliability data associated with a single execution run defines the current system.

TMR - (Triple Modular Redundancy)- A fault tolerant computer system consisting, initially, of three parallel and active channels in series with a majority voting element. In the event of a singular channel failure, the voter maintains correct system outputs.

Transient Fault - A fault which, because of its temporary nature, requires neither the use of a spare LRU nor degeneration in the process of recovering from its effects.

Transition - The process of switching the computer system operating mode (from Mode M to Mode M+1).

Unit Time - An arbitrary time interval, as for example seconds or hours, used in conjunction with failure rates, detection rates, reliability, etc.. Although consistent units must be utilized within a model (i.e., Reliability or Coverage), there is no need to use common units in separate models.

Unscheduled Detector - A fault detector, usually hardware, in which the detection process is triggered either directly, or effectively in outward appearance, by the occurrence of a fault.

Page Intentionally Left Blank

SECTION 3

MATHEMATICAL MODELS

The total system reliability of a redundant computer configuration can be expressed mathematically in a number of ways. These expressions all tend to be rather cumbersome, however, and therefore one of the objectives of this study was to devise formulations that can be evaluated efficiently by computer. A second, and equally important goal, was that the formulations be of a sufficiently general nature as to provide considerable design flexibility to the user. The following sections present both the end result of these efforts and, as an interpretation aid, a listing and definition of all parameters.

3.1 DUAL MODE RELIABILITY MODEL

The Dual Mode Reliability Model subprogram, with respect to initial plans, has been extended in scope significantly such that it now includes not only dual channel capability, but a variety of others as well. These include both N channel (where N is a user specified integer) and Hybrid configuration (where the quantity of active units differs between stages).

The reliability equations utilized in encoding the model, as well as a functional description of each, are presented in this section. Subscripts and other simple variables used therein are as follows:

- x - Refers to the set of LRU's which constitute a particular stage of the reliability model
- y - Refers to the operating mode
- t - Either the independent time variable or a dummy time variable (made clear by context)
- τ - A dummy time variable for integration or function referencing
- i, j, l - Dummy integer variables for counting or function referencing.



3.1.1 G: Fortran DCG(IUN,MD,I,T) - "The probability of using exactly i spares by time t."

$$G(x,y,i,t) = \begin{cases} e^{-(\gamma_{x,y})t} * (\delta_{x,y})^i * \binom{(K_x) (Q_{x,y}) (C_{x,y}) (\delta_{x,y})^{-1+i-1}}{i} & \text{for } K < \infty \\ (1 - e^{-(\mu_x)t})^i * e^{-(Q_{x,y})t} (\lambda_x)^t & \\ e^{-(\gamma_{x,y})t} * \frac{((Q_{x,y}) (C_{x,y}) (\lambda_x)^t)^i}{i!} * e^{-(Q_{x,y})t} (\lambda_x)^t & \text{for } K = \infty \end{cases}$$

This function expresses the probability of using exactly i of the available spares by time t under the following assumptions:

- $Q_{x,y}$ LRU's are required, with standby and active LRU's having the constant failure rates μ_x and $\lambda_x = K_x \mu_x$, respectively.
- The coverage factor, given that the l th spare tested following a detected failure is the first operational spare, is $C_{x,y} \delta_{x,y}^{l-1}$. (Note: coverage is defined here as the conditional probability of successful recovery given that an error occurs and sufficient hardware is available. If recovery is possible, the system operational mode is determined solely by the remaining available hardware.)
- Non-recoverable transients occur at the rate $\gamma_{x,y} = \gamma'_{x,y} * (1 - P_{r_{x,y}})$ per second. In the case of recoverable transients, the system resumes operation in the same mode as was in effect prior to the transient.

The first term in the above expression, then, is the probability that no non-recoverable transients occur by time t . The product of the remaining terms is the probability that exactly i LRU's sustain failures by time t , either while operating or prior to the time they are needed. (Notice that a failure in a spare LRU is not counted here until that spare would have been used following a failure in an operating LRU.) To verify this, we observe that the reliability of an r -on- m configuration (r spares on m operating elements) having active and standby failure rates λ and μ , respectively, is equivalent to that of an r on $\lambda m/\mu$ configuration having a constant failure rate μ for both active and standby elements.* Further, since with probability $C_{x,y}/\delta_{x,y}$, the system can recover from a failure on the condition that it can also find and successfully activate a standby spare, the rate of such recovered failures is $\lambda C_{x,y}/\delta_{x,y}$, and hence the effective number of active elements is $K Q_{x,y} C_{x,y}/\delta_{x,y} \triangleq M$. The probability that exactly i spares are used by time t is thus the product of the probability

$$\binom{M+i-1}{i} (1 - e^{-\mu_x t})^i e^{-(M-1)\mu_x t}$$

that exactly i recoverable failures occur in the first $M+i-1$ LRU's, the probability $e^{-\mu_x t}$ that the i^{th} spare is operational, the probability $\delta_{x,y}^i$ that i spares are successfully tested, and the probability

$$\exp \left[-Q_{x,y} \left(1 - C_{x,y}/\delta_{x,y} \right) \lambda_{x,y} t \right] \quad \text{that no non-}$$

recoverable failures occur during this period.

* C.F. J. J. Stiffler, "On the Efficacy of R-on-M Redundancy", IEEE Trans. on Reliability, (to appear).

3.1.2 R_u : Fortran DCRU (IUN, MD, L, TAU) - "The probability of using at most l spares by time τ ."

$$R_u(x, y, l, \tau) = \sum_{i=0}^l G(x, y, i, \tau)$$

The probability of using at most l spares is clearly the sum of the mutually exclusive probabilities that exactly i spares are used, for $i = 0, 1, \dots, l$.

3.1.3 H : Fortran DCH (IUN, TAU) - "The probability density of a degenerative failure in stage x at time τ ."

$$H(x, \tau) = \begin{cases} Q_{x,1} \lambda_x \sum_{i=0}^{(S_x)} \left\{ G(x, y=1, [(S_x)-i], \tau) * (C'_x) (\delta'_x)^i * (1-e^{-(\mu_x)\tau})^i \right\}, & \text{for } K < \infty \\ \lambda_x Q_{x,1} (C'_x) * G(x, y=1, (S_x), \tau), & \text{for } K = \infty \end{cases}$$

The conditional probability density of a degenerative failure at time τ , given exactly $S_x - i$ prior failures, is equal to the product of the probability density $Q_{x,1} \lambda_x$ of a failure in an operational unit and the probability $(1-e^{-\mu_x \tau})^i$ that the i remaining spares have failed by time τ , times the probability $C'_x (\delta'_x)^i$ that it is possible to recover from this event. The product of this conditional probability density with the probability that exactly $S_x - i$ failures have occurred by time τ , summed over all $i = 0, 1, \dots, S_x$, is thus the desired probability density.

3.1.4 S: Fortran DCS(IUN,T,TAU) - "The conditional probability that the set of units in stage x can remain operational in mode y = 2, from time τ to time t, given that the mode changed from 1 to 2 at exactly time τ."

$$S(x,t,\tau) = \left\{ \begin{array}{l} \sum_{\ell=0}^{(S_x)} \left[\sum_{j=0}^{(S_x-\ell)} \left\{ \binom{(S_x)-\ell}{j} * (1-e^{-(\mu_x)\tau}) * ((S_x)-\ell-j) * \right. \right. \\ \left. \left. e^{-j(\mu_x)\tau} * G(x,y=1,\ell,\tau) * R_u(x,y=2,j',(t-\tau)) \right\} \right] \\ \text{for } K < \infty \\ \\ \sum_{\ell=0}^{(S_x)} \left[G(x,y=1,\ell,\tau) * R_u(x,y=2, [(S_x)-\ell]', (t-\tau)) \right], \\ \text{for } K = \infty \end{array} \right.$$

$$\text{where } j' \equiv \begin{cases} j, \text{ no spares reassignment} \\ j + Q_{x,y=1} - Q_{x,y=2}, \text{ reassignment allowed} \end{cases}$$

$$[(S_x)-\ell]' \equiv \begin{cases} [(S_x)-\ell], \text{ no spares reassignment} \\ [(S_x)-\ell] + Q_{x,1} - Q_{x,2}, \text{ reassignment allowed} \end{cases}$$



The product of the first three terms in the summand is the probability that exactly j of the $S_x - \ell$ unused spares are still operational at time τ . The fourth term is the probability that exactly ℓ spares have been used in mode 1 by time τ , and the fifth term the probability that the remaining j' spares are sufficient to keep the unit operating in mode 2 for the next $(t-\tau)$ seconds. The sum over all $\ell = 0, 1, \dots, S_x$ and $j = 0, 1, \dots, S_x - \ell$ is thus the probability of the event described.

3.1.5 T: Fortran DCT(IUN,J) - "The probability that the system will survive until time t , and that a failure in the set of units in stage x will have forced degeneration from mode $y = 1$ to mode $y = 2$."

$$T(x,t) = \begin{cases} \int_0^t \left[\prod_{\bar{x} \neq x} \{S(\bar{x}, t, \tau)\} * R_u(x, y=2, \tau, (t-\tau)) * H(x, \tau) * e^{-(\hat{\lambda}_2)\tau} \right] d\tau, & \text{for } Q(x,1) > Q(x,2) \\ 0, & \\ \int_0^t \left[\prod_{\bar{x} \neq x} \{S(\bar{x}, t, \tau)\} * R_u(x, y=2, \tau, (t-\tau)) * H(x, \tau) * e^{-(\hat{\lambda}_2)\tau} \right] d\tau, & \text{for } Q(x,1) \leq Q(x,2) \end{cases}$$

The integrand is the product of the probability density of a failure in unit x at time τ (3rd term), the probability that the unit functions successfully for the next $t-\tau$ seconds in mode 2 (2nd term), the probability that all other units remain in operation until time τ in mode 1 and from time τ to time t in mode 2 (1st term), and the probability that no category-two failures occur during this time (4th term). Since a degenerative failure can occur any time during the interval $0 < \tau < t$, $T(x,t)$ is the integral of this density function over that interval.

- 3.1.6 T_2 : Fortran DCT2(J) - "The probability that the system will survive until time t, and that a category 2 switch failure will have forced degeneration from mode y = 1 to mode y = 2."

$$T_2(t) = (\hat{\lambda}_2) (C_2) \int_0^t \left[\left\{ S(x, t, \tau) \right\} * e^{-(\hat{\lambda}_2)\tau} \right] d\tau$$

Here the 1st term in the integral is the probability that all units function successfully in mode 1 until time τ and in mode 2 from time τ to time t. The product $\hat{\lambda}_2 C_2 e^{-(\hat{\lambda}_2)\tau}$ is the probability density of a category-two failure at time τ times the conditional probability C_2 that recovery from such a failure is successful. The integral of this quantity over all τ , $0 < \tau < t$, is therefore the result sought.

- 3.1.7 R: Fortran DCR(J,UNITR, RELM1, RSYS) - "The system reliability at time t."

$$R(t) = \left[\prod_x \left\{ R_u(x, y=1, S_x, t) \right\} * e^{-(\hat{\lambda}_2)t} + T_2(t) + \sum_x \left\{ T(x, t) \right\} \right] e^{-(\hat{\lambda}_3)t}$$

The first term here is the product of the probability that each of the units function until time t in mode 1 and that no category-two failures occur during that time. The remaining two terms represent the probabilities that the system successfully survives until time t, with a degeneration occurring sometime during that interval because of a category-two switch failure, and because of a degenerative failure in one of the units,



respectively. The sum of these three terms multiplied by the probability that no category-three failures occur during the period in question is thus the probability that the system operates successfully over the entire t-second interval.

The function also computes system and stage reliabilities, assuming mode 1 operation alone, and returns the values as RELM1 and array UNITR, respectively. The expressions for these values are subsets of the above equation:

$$R(t, y=1) = \left[\prod_x R_u(x, y=1, S_x, t) \right] e^{-(\hat{\lambda}_2 + \hat{\lambda}_3)t}$$

$$R_x(t, y=1) = R_u(x, y=1, S_x, t)$$

3.2 COVERAGE MODEL

The function subprogram COVAGE, in concert with certain other routines, is utilized to calculate coverage for application in both the dual mode reliability model and original CARE equations 2 and 3. This section presents the equations utilized therein, as well as corresponding functional descriptions.

The basic coverage calculation described herein returns a single value C(s) corresponding to a specific system operating mode, fault type (permanent or transient), quantity of spares tested, and fault subclass. The calculative process is then iterated, via separate calls to COVAGE, for each combinatorial set of conditions.

Since the ensuing reliability model accepts coverage values at the stage rather than subclass level, it is necessary to preprocess the above according to the relation

$$C(I) = \sum_{\sigma, L_\sigma = I} (d_\sigma C_\sigma)$$

where C(I) is a coverage factor

of stage I*, and is computed as an average of the C_σ factors returned, as $C(s)$, by COVAGE (cf. section 3.2.2), weighted by the fractional fault occurrence rate d_σ for each fault subclass σ associated with the stage. The association of stage and fault subclass is specified by the user when selecting input values for the linkage variable L_σ (IFSC), and the relative fault rate d_σ (FRAC), for each subclass used.

In turn, the required delta coverage inputs (representing the diminished recovery probability arising from trial repair with a previously failed spare), are computed in accordance with the expression

$$\delta(I) = C(I, s=2) / C(I, s=1)$$

where s is the quantity of spare LRU's which must be trial tested during the recovery process (i.e., $s-1$ having failed the test).

In perspective then, it should be noted that the following coverage and delta coverage values are computed, and delivered to the reliability model, for each stage of the object computer system:

- Coverage - $C(I)$
 - $C_{x,y=1}$ - permanent fault, continued Mode 1 operation
 - $C_{x,y=2}$ - permanent fault, continued Mode 2 operation
 - C'_x - permanent fault, transitional from Mode 1 to 2
 - P_r - transient fault, continued Mode 1 operation
 - $P_{r,x,y=1}$ - transient fault, continued Mode 2 operation
 - $P_{r,x,y=2}$
- Delta Coverage - $\delta(I)$
 - $\delta_{x,y=1}$ - permanent fault, continued Mode 1 operation
 - $\delta_{x,y=2}$ - permanent fault, continued Mode 2 operation
 - δ'_x - permanent fault, transitional from Mode 1 to 2

* Note that, in the reliability model, x was used to denote a stage.



3.2.1 Subscripts and Simple Variables

- $t, \tau, \alpha, \nu, \eta$ - dummy variables for integration, summation and substitution.
- i, j, k, ℓ - detector number. The choice of variable is determined as:
- i - general-purpose detector symbol (used on either side of an equation)
 - j - scheduled detector symbol (right side of equation only)
 - k - non-scheduled detector symbol (right side of equation only)
 - ℓ - non-scheduled impulse detector symbol (right side of equation only). Specifically, $\ell_1, \ell_2, \dots, \ell_{m_i}$ comprises the set of non-scheduled impulse detectors, excluding the i^{th} , which have the same delay (t_{d_i}) as detector i , given m_i such detectors.

3.2.2 C: Fortran COVAGE - "The sum of coverage contributions of all competing D/I/R mechanisms given that s spares must be checked prior to recovery."

$$C(s) = \sum_i C(i,s)$$

The coverage value $C(s)$ associated with a single fault subclass under given spares status and computer system operating conditions is clearly the summation of individual D/I/R mechanism contributions ($C(i,s)$) over all i .

3.2.3 C(i,s): Fortran COVAGE - "The coverage contribution of the D/I/R mechanism associated with detector i, when all competing detectors are accounted for and when s spares must be checked during the recovery process."

$$C(i,s) = p_i p'_i p_s^s \int_0^{\infty} g_i(\tau') r'_i(\tau') \int_0^{\infty} h_i(\tau'' - s\tau_s) r''(\tau' + \tau'') d\tau'' d\tau'$$

The detection probability density function for the i^{th} detector is $p_i g_i(\tau')$ and the associated isolation density function is, by definition, $p'_i h_i(\tau'')$. If s spares must be checked in order to recover successfully from a fault, the overall recovery probability is decreased by the factor p_s^s (with p_s the probability of successfully checking out a spare) and the isolation delay is effectively increased by the factor $s\tau_s$. The term C(i,s) is thus equal to the conditional probability that the system can still recover given a τ' -second detection delay times the detection probability density function, multiplied by the conditional probability that the system can recover given that it has survived a τ' -second detection delay and must in addition undergo a total of $(\tau' + \tau'')$ seconds down-time, times the corresponding isolation density function, the whole thing integrated over all τ' and τ'' , and multiplied by p_s^s .

3.2.4 $g_i(\tau)$: Fortran CVGS, CVG2 and CVG1 - "The conditional detection rate of the i^{th} detector when in competition with all other detectors."

The function $g_i(\tau)$ represents the i^{th} detectors' conditional detection rate when competitive processes are taken into account. In turn, the corresponding detection probability density function

is then expressed as $p_i g_i(\tau)$. The rate itself is determined by using one of three equations depending on the nature of the i^{th} detection process, i.e., whether it is scheduled or unscheduled and, in the latter case, whether it is a finite or impulse detector.

- Scheduled $g_i(\tau)$: Fortran CVGS

$$g_i(\tau) = \begin{cases} \prod_k \left[1 - p_k F_k(\tau - t_{d_k}) \right] g'_i(\tau), & \text{for } 0 \leq \tau \leq n_i T_{mr} \\ 0, & \text{otherwise} \end{cases}$$

The product over k represents the probability that none of the non-scheduled detectors has detected the fault by time τ (note that $F_k(t) = 0$ for all $t < 0$). The function $g'_i(\tau)$ is the conditional detection rate of the i^{th} scheduled detector when competing with the other operative scheduled detectors only (see Section 3.3.4).

- Finite Non-Scheduled $g_i(\tau)$: Fortran CVG2

$$g_i(\tau) = \prod_{k \neq i} \left[1 - p_k F_k(\tau - t_{d_k}) \right] * \left[1 - \sum_j p_j \int_0^\tau g'_j(\eta) d\eta \right] * f_i(\tau - t_{d_i})$$

The product over k is the probability that none of the other non-scheduled detectors has sensed the fault by time τ . Similarly, the second term is the probability that none of the scheduled detectors has succeeded by time τ . The last term is, of course, the detection rate of the detector in question in the absence of any competition.

- Non-Scheduled Impulse $g_i(\tau)$: Fortran CVG1

$$g_i(\tau) = \left[1 - \sum_{v=1}^{m_i} \frac{(-1)^{v+1}}{v+1} \sum_{l_1 < l_2 < \dots < l_v} p^{l_1} p^{l_2} \dots p^{l_v} \right] *$$

$$\prod_{\substack{k \neq i \\ k \neq l_1, l_2, \dots, l_{m_i}}} \left[1 - p_k F_k(t_{d_i} - t_{d_k}) \right] * \left[1 - \sum_j p_j \int_0^{t_{d_i}} g_j'(\eta) d\eta \right] * \mu_0(\tau - \tau_{d_i}),$$

for $f_i(\tau) = \mu_0(\tau - \tau_{d_i})$

where $\mu_0(x)$ is a unit impulse at $x = 0$

This expression has the same interpretation as the previous one except that the $f_i(\tau)$ is an impulse function. The first term assumes a different form here, reflecting the fact that if v impulse detectors having simultaneous delays τ_d all detect the same fault, only one of them is declared the winner. In this event, it is assumed that each of the successful detectors has the probability $1/v$ of being declared the victor. The first term in this expression, then, is the conditional probability that the impulse detector in question is declared the winner over its simultaneously occurring impulse competitors, given that it is, in fact, successful in detecting the error. The second term is the probability that none of the other non-scheduled detectors finds the error prior to time τ_{d_i} . The remaining terms are as previously defined.

3.2.5 $g'_i(\tau)$: Fortran CVGP4 and CVGP3 - "The conditional detection rate of the i^{th} scheduled detector when in competition with all other scheduled detectors."

The function $g'_i(\tau)$ represents the i^{th} scheduled detectors' conditional detection rate when competitive scheduled processes only are taken into account. It is determined using either of two equations depending on the nature of the i^{th} detection process, i.e., whether it is a finite or impulse detector.

- Finite $g'_i(\tau)$: Fortran CVGP4

$$g'_i(\tau) = \left\{ \begin{array}{l} \frac{1-F_i(\tau)}{n_i T_{mr}} + \frac{n_i}{n_c} \sum_{l=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \int_0^{\tau} \prod_{j \neq i} \left[1 - p_j \bar{F}_j^l(\eta - \tau + n_i T_{mr} + t_{d_i} - t_j^l) \right] * f_i(\eta) d\eta \\ \text{for } 0 \leq \tau \leq \Delta t_i \\ \\ \frac{n_i}{n_c} \sum_{l=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \int_0^{\Delta t_i} \prod_{j \neq i} \left[1 - p_j \bar{F}_j^l(\eta - \tau + n_i T_{mr} + t_{d_i} - t_j^l) \right] * f_i(\eta) d\eta \\ \text{for } \Delta t_i < \tau \leq n_i T_{mr} \\ \\ 0, \text{ otherwise} \end{array} \right.$$

The first term in the expression for $g'_i(\tau)$ when $0 \leq \tau \leq \Delta t_i$ represents the conditional detection rate of the i^{th} scheduled detector given that the error occurs sometime during the period during which that detector is active (e.g., while the associated diagnostic program is running).

Note: It is assumed here, and throughout this discussion, that the probability that an error is detected by a given detector during a given interval is equal to the integral of its probability density function over that interval. Furthermore, each portion of a scheduled test is assumed to have a probability of detecting a particular fault only during its first exposure to that fault. Thus, for example, if a fault occurs when a given scheduled program of T_0 seconds duration is in progress and has t_0 seconds left to run, and if the fault is not detected during those t_0 seconds, the fault has a chance of being detected only during the first $T_0 - t_0$ seconds of that program when it is next run, and if it is not detected then, it will not be detected by that program during any subsequent runs.

The l^{th} term in the summation in both expressions for $g_i'(\tau)$ (i.e., for $0 \leq \tau \leq \Delta t_i$ and for $\Delta t_i < \tau \leq n_i T_{mr}$) is the conditional detection rate of the i^{th} scheduled detector, given that the fault occurs either during or following the l^{th} scheduling of that detector, but is not detected during that scheduled run. Accordingly, the product denotes the probability that none of the other scheduled detectors exposed to the fault during the τ seconds prior to its detection is successful in detecting it. This product, multiplied by the detection rate function $f_i(\eta)$ associated with the i^{th} detector and averaged over all η gives the desired result. Summing these conditional detection rates over a major cycle then yields the desired detection rate for the i^{th} scheduled detector when competing only with other scheduled detectors. Note that there are exactly n_c/n_i repetitions of the i^{th} detector during one major cycle. (A major cycle is defined as the overall period of the combined scheduled tests.)

- Impulse $g'_i(\tau)$: Fortran CVGP3

$$g'_i(\tau) = \begin{cases} \frac{n_i}{n_c} \sum_{l=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \prod_{j \neq i} \left[1 - p_j F_j^{-l} \left(-\tau + n_i T_{mr} + t_{d_i} - t_j^l \right) \right] \\ \text{for } 0 \leq \tau \leq n_i T_{mr} \text{ and } f_i(\tau) = \mu_0 t_{d_i} \\ 0, \text{ otherwise} \end{cases}$$

This expression is simply a specialization of the previous expression for the case in which $f_i(\tau)$ represents a scheduled impulse detector (i.e., $f_i(\tau)$ is an impulse function).

3.3 PARAMETER DEFINITIONS AND APPLICABILITY

The quantity of parameters contained in CARE2, with reference to the original CARE program, has of necessity increased rather significantly. In particular, the total set now consists of:

- CARE/CARE2 compatible parameters - Variables retained from the original CARE program for use in CARE2
- Dual Mode Reliability Model parameters - Variables which were introduced to allow implementation of Equation #7
- Coverage Model parameters- Variables which were introduced to allow calculation of coverage.

Table 3-1 lists the major parameters currently utilized in both the models and their Fortran implementation, and denotes their applicability with respect to both coverage and each of the seven basic reliability forms (i.e., equations 1-6 of original CARE and equation 7 as added in CARE2). In addition, it provides a categorization of each with respect either to its source or its use as a model output.

These same parameters are then defined, in Table 3-2, in the form a , $A(N)$, α , where:

- a - is the symbol used in analytic expressions
- $A(N)$ - is the Fortran mnemonic, with subscripts where applicable
- α - is the parameter name.

TABLE 3-1

PARAMETER/MODEL APPLICABILITY

Parameter	Coverage Model	Reliability Model/ Equation Number						
		1	2	3	4	5	6	7
C	R	-	I*	I*	-	-	-	I*
C'	R	-	-	-	-	-	-	I*
C ₂	-	-	-	-	-	-	-	I
C _σ	C	-	-	-	-	-	-	- Note 1
d _σ	I	-	I	I	-	-	-	I Note 1
δ	R	-	-	-	-	-	-	I*
δ'	R	-	-	-	-	-	-	I*
F _i (n)	C	-	-	-	-	-	-	-
$\overline{F}_i^l(n)$	C	-	-	-	-	-	-	-
F _j ^l (n, i)	C	-	-	-	-	-	-	-
f _i (τ)	I	-	-	-	-	-	-	-
g _i (τ)	C	-	-	-	-	-	-	-
g _i [!] (τ)	C	-	-	-	-	-	-	-
h _i (τ)	I	-	-	-	-	-	-	-
γ	-	-	-	-	-	-	-	C
γ'	-	-	-	-	-	-	-	I
IET	S	-	-	-	-	-	-	-
IGENC	I	-	-	-	-	-	-	-
IGENP	I	-	-	-	-	-	-	-
K	-	C	C	C	C	-	-	C
L _σ	I	-	I	I	-	-	-	I Note 1
γ	-	I	I	I	I	I	I	I
Σλ	-	-	-	-	-	-	-	C

cf. continuation sheet 2 of this table for explanatory symbols and notes.



TABLE 3-1 (Cont.)

<u>Parameter</u>	<u>Coverage Model</u>	<u>Reliability Model/ Equation Number</u>						
		<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>	<u>6</u>	<u>7</u>
$\hat{\lambda}_2$	-	-	-	-	-	-	-	I
$\hat{\lambda}_3$	-	-	-	-	-	-	-	I
MD	S	-	-	-	-	-	-	S
μ	-	I	I	I	I	-	-	I
N	-	I	-	-	-	-	-	-
n_c	C	-	-	-	-	-	-	-
n_i	I	-	-	-	-	-	-	-
P	-	-	-	-	-	I	-	-
P_i	I	-	-	-	-	-	-	-
P'_i	I	-	-	-	-	-	-	-
$P_i f_i(\tau)$	C	-	-	-	-	-	-	-
$P'_i h_i(\tau)$	C	-	-	-	-	-	-	-
P_r	R	-	-	-	-	-	-	I*
P_s	I	-	-	-	-	-	-	-
Q	-	-	I	I	-	-	-	I
R	-	R	R	R	R	R	R	R
$r_i(\tau', \tau'')$	C	-	-	-	-	-	-	-
$r'_i(\tau')$	I	-	-	-	-	-	-	-
$r''_i(\tau'+\tau'')$	I	-	-	-	-	-	-	-
RSGN	-	-	-	-	-	-	-	I
RV	-	I	I	I	I	I	-	-
S or r	-	I	I	I	I	-	-	I

TABLE 3-1 (Cont.-2)

<u>Parameter</u>	<u>Coverage Model</u>	<u>Reliability Model/ Equation Number</u>						
		<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>	<u>6</u>	<u>7</u>
s	S	-	-	-	-	-	-	-
σ	S	-	-	-	-	-	-	- Note 1
t_{d_i}	I	-	-	-	-	-	-	-
Δt_i	I	-	-	-	-	-	-	-
$t_{d_i} + \Delta t_i$	C	-	-	-	-	-	-	-
T_i	C	-	-	-	-	-	-	-
$t_j^{l(i)}$	C	-	-	-	-	-	-	-
T_{mr}	I	-	-	-	-	-	-	-
τ_s	I	-	-	-	-	-	-	-
W	-	I	I	I	I	I	I	-
Z	-	I	I	I	I	I	I	-

C - computed by program

I - input by user or default table

I*- input by user, default table, or coverage model

R - result (i.e., output) of model

S - subscript used for summation, selection, etc.

- - not applicable

Note 1: These parameters are used to specify the relationship between coverage subclasses and reliability stages for equations 2, 3 and 7. They are included in the table for reason of completeness although, as a consequence, the relationship to column headings is somewhat strained.

TABLE 3-2

PARAMETER DEFINITIONS

<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
C	C1(I), C2(I)	Coverage factor	The conditional probability, for mode equals 1, 2 respectively, that the system can recover from a permanent hardware failure in an LRU of stage I, given that sufficient spare hardware is available.
C'	CTR(I)	Transitional coverage factor	The conditional probability that the system can recover from a permanent failure in an LRU of Stage I, given that no spares are available and hence that the system must degenerate from Mode M to Mode M+1.
C ₂	CCSF	Switch failure coverage factor	The coverage factor associated with recovery via degeneration, due to a category 2 switch failure.
C _σ	COVAGE	COVAGE returned valve	The coverage factor for fault subclass σ under a given set of conditions i.e., given values of MD, IET and JS in the COVAGE argument list.
d _σ	FRAC	-	The fraction of class (i.e., stage) faults which are attributed to member subclass σ.
δ	CD1(I), CD2(I)	Delta coverage factor	A term defined by the equation $C_i = C_i \delta_i$, with C_i the conditional probability, for Mode equals 1, 2 respectively, that the system can recover given that the first i of i+1 or more spares has failed in the idle state, that the next has not, and that recovery is initially attempted utilizing the i failed spares.

<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
δ'	CDTR(I)	Delta transitional coverage factor	A term, defined by the equation $C_i = C_i' (\delta')^i$, with C_i' the conditional probability of recovery given that all i of the remaining spares have failed and that all i are tested to ascertain this prior to degeneration.
$F_i(\eta)$	--	Cumulative detection probability function	The integral of the function $f_i(\tau)$, i.e., the probability that an ideal detector will detect an error within $\eta + \tau_{d_i}$ time units after its occurrence. Note: It is recommended that the user formulate the integrals for any general function models created, and provide these as associated integral models.
$\overline{F}_i^l(\eta) = (1 - F_i^l(\eta))$	--	--	Probability of non-detection (with $F_i^l(\eta) \stackrel{\Delta}{=} F_i(\eta)$).
$F_j^l(\eta, i)$	--	--	The probability that an ideal scheduled detector (with a detection rate identical to that of detector j) will detect a fault within η time units after the initial delay, when detector j is scheduled to begin $t_j^l(i)$ time units after the occurrence of a fault.
$f_i(\tau)$	--	--	The user specified conditional detection rate of detector i in the absence of any competitive detection processes.
$g_i(\tau)$	CVGS, CVG1, CVG2	--	The conditional detection rate of the i^{th} detector when in competition with all other detectors.



<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
g_i' (τ)	CVGP3, CVGP4	--	The conditional detection rate of the i^{th} scheduled detector when in competition with all other scheduled detectors.
h_i (τ)	-	Isolation rate function	The user specified isolation rate of isolator i .
γ	GM1(I), GM2(I)	System transient failure rate	The product γ' . $(1-P_i)$ for a unit of stage I, and for mode equals 1,2 respectively.
γ'	GMP(I)	Transient failure rate	The rate at which transient hardware errors take place in on-line units of stage I. Expressed in failures per unit time.
--	IET	Fault type code	A code which specifies the "duration" of a fault. Equal to: - 1 for permanent faults - 2 for transient faults.
--	IGENC(I)	Coverage calculation flag	An integer variable which conditionally specifies the source of permanent fault coverage factors for stage I: - for IGENC < 0, coverage is calculated prior to each run-set - for IGENC = 0, coverage is not calculated (i.e., either input or defaulted) - for IGENC > 0, coverage is calculated prior to the first run-set only.

Note: A negative coverage value input by the user serves as a higher precedence command, and forces calculation of a "replacement" value, given only that coverage itself is applicable to the corresponding reliability model.

<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
--	IGENP(I)	Transient recovery calculation flag	An integer variable similar to IGENC, except that transient fault recovery probabilities (P _r) are the candidates for calculation.
K	K(I)	Inverse dormancy factor	The ratio of λ/μ for LRU's of stage I.
L_σ	IFSC	Fault class indicator	A pointer or linkage to fault subclass σ , wherein the subclass accounts for a fractional portion (d_σ) of the faults which occur in stage L_σ of the system.
λ	LAM(I)	On-line failure rate	The rate at which permanent hardware failures take place in on-line units of stage I. Expressed in failures per unit time.
$\Sigma \lambda$	SUMLAM	Simplex on-line failure rate	The sum of on-line failure rates over units of all stages, for the purpose of calculating simplex reliability.
$\hat{\lambda}_2$	SLH2	Category 2 switch failure rate	The occurrence rate of permanent hardware failures which cause degeneration from mode M to mode M+1. Expressed in failures per unit time.
$\hat{\lambda}_3$	SLH3	Category 3 switch failure rate	The occurrence rate of permanent hardware failures which cause total system failure. Expressed in failures per unit time.
--	MD	Mode	The computer system operating mode. In the Dual Mode model, modes are distinguished by the quota of on-line units for each stage. In the Coverage model, D/I/R



<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
			<p>processes are defined separately for modes 1 and 2, as well as dummy mode 0. MD is equal to:</p> <ul style="list-style-type: none"> - 1 for full up - 2 for degenerate - 0 for transitional (coverage only, during transition from MD=1 to MD=2).
μ	MU(I)	Stand-by failure rate	The rate at which permanent hardware failures take place in stand-by LRU's (spares) of stage I. Expressed in failures per unit time.
N	N(I)	Modular redundancy factor	The number of identical active units in a fully operational NMR system.
n_c	LCM	--	The least common multiple of the n_i 's where n_i is the repetition factor (where applicable) of the i th detector, in terms of minor cycles.
n_i	IREP(I)	Repetition factor	The integer ratio of the repetition period of the i th scheduled detector to the minor cycle duration, i.e., $T_i = n_i T_{mr}$.
P	P(I)	--	The probability of stage I failing with a logical zero output.
p_i	--	--	The conditional probability that the i th detector will detect an arbitrary fault, given infinite time and no competitive detection processes.
p'_i	---	--	The probability that the i th isolator is able to isolate a fault.

<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
$p_i f_i(\tau)$	--	--	The detection probability density function of detector i in a non-competitive environment (i.e., when no other detectors are operative). The value of p_i and the function $f_i(\tau)$ are defined explicitly, as is the initial detection delay t_{d_i} . The "rate function" $f_i(\tau)$, then, represents the rate of detection for an ideal detector, i.e., one which guarantees detection, given an adequate amount of time. Since τ_{d_i} is explicit, $f_i(\tau)$ must be defined so that $f_i(0^+) \neq 0$. The duration of the function is defined as the value of τ after which detection cannot occur.
$p_i h_i(\tau)$	--	--	The isolation probability density function of the process associated with detector i . Note also $h_i(\tau)$ is a rate function defined similarly to $f_i(\tau)$.
P_r	PRC1(I), PRC2(I)	Transient recovery probability	The probability, for mode equals 1, 2 respectively, that the system can recover from a transient fault occurring in an LRU of stage I.



<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
p_s	PFDS (ISU)	--	Probability of detecting a failure in a failed spare during checkout. Note that this has the effect of directly reducing the final coverage result, since no provision is made for subsequent recovery from undetected failures in spares. The value selected must therefore account for all secondary recovery capabilities of the computer system. Note also that the value is, for reason of its inclusion in the coverage model, assigned to a fault subclass rather than an LRU.
Q	Q1(I), Q2(I)	Quota	The number of on-line LRU's required in stage I for system operation in mode equals 1, 2 respectively.
R (t)	R	Reliability	The probability that the system is operational at time t given that it was operational at time 0.
$r_i(\tau', \tau'')$	--	Recovery probability function	The conditional probability of system recovery, given detection and isolation delays of τ' and τ'' , respectively. $r_i(\tau', \tau'') \equiv r_i'(\tau') \cdot r_i''(\tau' + \tau'')$
$r_i'(\tau')$	--	Fault propagation recovery function	The conditional probability of system recovery, given detection time τ' for the i^{th} detector at the end of which, fault propagation ceases.

<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
$r_i''(\tau'+\tau'')$	--	Time lost recovery function	The conditional probability of system recovery, given total detection and isolation delay of $(\tau'+\tau'')$ for the i^{th} detector, isolator pair at the end of which, fault recovery is initiated.
--	RSGN	Reassignment flag	A logical variable which for RSGN =.TRUE., enables operational LRU's in a failed channel to be reassigned i.e., released to the spares pool =.FALSE., precludes reassignment (Note: RSGN must be set true if the quota in mode M+1 is greater than in mode M).
RV	RV(I)	Restoring organ reliability	An overall limiting probability of success applied to stage I.
S or r	S(I)	Spares	The number of spare LRU's available in stage I at time $t = 0$.
s	JS	--	The quantity of spare LRU's which must be checked out before recovery can proceed. (normally 0 or 1).
σ	ISU	Fault subclass	An integer subscript ($0 < ISU \leq 8$) which identifies a set of competitive D/I/R processes (i.e., a fault subclass). One or more such sets may be assigned to a single stage of the reliability model.



<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
t_{d_i}	TDEL	Delay time	The delay time associated with initiation of detection process i . For scheduled detectors, it is measured relative to the beginning of a major cycle; for non-scheduled detectors, it is the interval between occurrence of a fault and the instant it can first be detected.
Δt_i	TDUR	Duration time	The time interval during which a detection function is non-zero.
$t_{d_i} + \Delta t_i$	--	--	Finishing time for detector i , i.e., the time relative to the start of a major cycle (scheduled detectors) or the occurrence of a fault (non-scheduled detectors) after which detector i is not effective. Note: $\int_0^{\infty} f_i(\tau) d\tau = \int_0^{\Delta t_i} f_i(\tau) d\tau \equiv 1.0$ (delay is external to function)
T_i	--	--	The repetition period of the i^{th} scheduled detector.
$t_j^{\ell(i)}$	CYTJL(J,L,I)	--	Largest solution t to the equation $t = t_j + \nu T_j - (\ell-1) T_i, \nu = 0, 1, 2, \dots$, in the range $(t_i, t_i + T_i)$. (If there is no

<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
			<p>solution in this range, $F_j^l(\eta) = 1$.) Thus, t_j^l represents the starting time of the last occurrence of the j^{th} scheduled test in the interval $(t_i + (l-1)T_i, t_i + lT_i)$.</p>
T_{mr}	TMINOR	Minor Cycle	The minor cycle duration, i.e., the greatest common divisor of the repetition period T_i .
τ_s	TFDS (ISU)	Checkout Time	The average on-line time required to test a single spare, given an accompanying test success probability of p_s . Note that the value is, for reason of its inclusion in the coverage model, assigned to a fault subclass rather than an LRU.
W	W(I)	Division factor	The number of identical sub-units which comprise one unit in stage I. The sub-unit failure rate λ_s thus relates to the unit failure rate λ as $\lambda_s = \lambda / W$.
Z	Z (I)	Iteration factor	The number of identical units operating in series which comprise stage I. The reliability of the stage is thus the product of the reliabilities of the Z sub-stages.

SECTION 4

SOFTWARE

CARE2 was developed using the CDC RUN76 compiler, under the KRONOS 2.1 Operating System, on the CDC 6700 Time-sharing Computer at Raytheon MSD, Bedford, Massachusetts. The program is essentially UNSI Fortran IV, with the exception that, like original CARE, it is designed for execution on a 60 bit CDC computer. The field length required for the complete program version is less than 130K (octal), and for the reduced version (without plotting options) less than 100K.

Program modules added were designed to be of comparable scope with existing modules as far as programming efficiency and run time considerations would permit. The statistical, mathematical or implementation significance of each revised or added subprogram is described in this section.

4.1 PROGRAMMING CONSIDERATIONS

The task of including both a dual mode reliability model and a model for the calculation of coverage factors, was originally expected to entail additions to CARE only. Ideally, the former would replace dummy subprogram NEQ7, and the latter would require one additional CALL statement in the main program, plus the implementing code. However, the relatively complex method of passing statistical parameters to the reliability models, combined with the need for communication between stages of the dual mode model, disallowed this ideal. Simply stated, the CARE program requires 1) that an equation use at most one parameter of each type, and 2) that individual systems be evaluated serially. Thus major revisions of the data base structure were undertaken. The possibility of expanding the existing structure to accommodate a large number of additional parameters was rejected in favor of a simpler format.

In CARE2, a computer system is represented as a series of one or more stages, each of which is comprised of identical subunits including one or more optional spares. Each invocation of equations 1-6 corresponds to the definition of a single such stage, whereas equation 7 has internal provision for representing up to eight stages.

For the group of up to 10 stages which can be modelled at one time, there exists a base run vector (i.e., an array of dimension 10) for each parameter type. In addition, any one of 19 parameter types may be selected for variation (cf. sheet 2 of Table 4-2), which is accomplished internally by alternately refreshing the selected run vector from a single 10 x 16 iteration array and evaluating the system. (The latter process, consisting of up to 16 evaluations or runs, is termed a run-set.) Optionally, run-sets may also be repeated, following user changes to run vectors, iteration data and iteration parameter.

Coverage factors are treated the same as other parameters when input directly by the user. Conversely, however, they can be computed, for equations to which they apply, provided that separate coverage input data is supplied. These inputs, because of their relative diversity, cannot be varied as described above. Most, with the exception of the flags which request calculation and the linkage table which unites the two halves of the program data base, can be changed at the run-set level.

In structuring the input algorithms for CARE2, it was apparent that both the size of the data base and the assumption that the program would be used for sensitivity analyses, indicated an "inputs only for changes" rule should apply throughout. Thus program defaults, where provided, are initiated prior to user inputs (except in unaltered portions of READIN). The default values themselves, in the case of basic reliability model parameters, may optionally be input early in the batch run. In addition, by setting LSTCH to true (cf. Table 5-1), the

inputs required for parameter variation can often be minimized. In this case, non-default inputs to the iteration array PARAM will be extended upward along the iteration dimension, replacing only default values.

The development of CARE2 was performed using MODIFY, a system level program on the Bedford 6700. MODIFY facilitates the manipulation of source code by representing the original and subsequent versions as card deck images stored in disk files. Cards and decks are inserted, moved or deleted, by introducing directives in groups which are also represented as card decks, and are saved with the source for future reference.

The identifying names seen in columns 73-80 of the CARE2 source code refer to the origin of the card. Thus cards bearing the subprogram name, in the case of original CARE subprograms, were in fact in the original program. The modification set name, where it appears, in general refers to the reason for the card's replacement or addition.

For example, CAREFIX cards arose from early modifications which were required to enable the CARE program to operate properly on the Bedford computer. MAINLOG cards indicate basic logic modifications, and PARMOD cards refer to the restructured parameter data base.

4.2 SUBPROGRAM DESCRIPTIONS

This section describes, in paragraph form, each of the new and altered subprograms, as they exist in the "complete" version of the CARE2 program. Each is also described in flow diagram form (cf. Appendix A) as well as in the source listing itself (cf. Appendix B). Table 4-1 is provided in order to aid in their location.



TABLE 4-1

CROSS-REFERENCE LISTING OF CARE2 SUBPROGRAMS

<u>Subprogram Name</u>	<u>Source Listing S/R Order #</u>	<u>Paragraph #</u>	<u>Flowchart #</u>	<u>Comments</u>
BISECT	2	-	-	Original
*CARE2	1	4.2.1.1	A-1	Modified CARE main program
COVAGE	47	4.2.4.1	A-18	Added
COVGEN	37	4.2.2.3	A-8	Added
CVGPI	54	4.2.4.8	A-25	Added
CVGP3	51	4.2.4.5	A-22	Added
CVGP4	52	4.2.4.6	A-23	Added
CVGS	50	4.2.4.4	A-21	Added
CVG1	48	4.2.4.2	A-19	Added
CVG2	49	4.2.4.3	A-20	Added
CVTJL	53	4.2.4.7	A-24	Added
DCG	45	4.2.3.7	A-16	Added
DCH	43	4.2.3.5	A-14	Added
DCOMB	46	4.2.3.8	A-17	Added
DCR	39	4.2.3.1	A-10	Added
DCRU	44	4.2.3.6	A-15	Added
DCS	42	4.2.3.4	A-13	Added
DCT	41	4.2.3.3	A-12	Added
DCT2	40	4.2.3.2	A-11	Added
*EQUAL	3	-	-	Original
FEVAL	56	4.2.4.10	A-27	Added
FFAC	4	-	-	Original
FINTEG	57	4.2.4.11	A-28	Added
FNCK	5	-	-	Original

*Affected by array dimension modifications, as required for optional reduced field length execution.

TABLE 4-1 (cont.)

<u>Subprogram Name</u>	<u>Source Listing S/R Order #</u>	<u>Paragraph #</u>	<u>Flowchart #</u>	<u>Comments</u>
FN1	61	4.2.4.15	A-32	Added
FN1I	62	4.2.4.16	A-33	Added
FN2	63	4.2.4.17	A-34	Added
FN2I	64	4.2.4.18	A-35	Added
FN3	65	4.2.4.19	A-36	Added
FN3I	66	4.2.4.20	A-37	Added
FN4	67	4.2.4.21	-	Added (dummy routine)
FN4I	68	4.2.4.22	-	Added (dummy routine)
FN5	69	4.2.4.23	-	Added (dummy routine)
FN5I	70	4.2.4.24	-	Added (dummy routine)
FN6	71	4.2.4.25	-	Added (dummy routine)
FN6I	72	4.2.4.26	-	Added (dummy routine)
IGET	58	4.2.4.12	A-29	Added
INTEGR	6	-	-	Original
IPUT	59	4.2.4.13	A-30	Added
ISHIFT	60	4.2.4.14	A-31	Added
MOV C	26	4.2.1.4	A-4	Modified to use ISHIFT
NEQ1A	9	4.2.1.2	A-2	Corrected logic error
NEQ1B	10	-	-	Original
NEQ2A	7	-	-	Original
NEQ2B	8	-	-	Original
NEQ3	11	-	-	Original
NEQ4A	12	-	-	Original
NEQ4B	13	-	-	Original
NEQ5	14	-	-	Original
NEQ6	15	-	-	Original



TABLE 4-1 (cont.-2)

<u>Subprogram Name</u>	<u>Source Listing S/R Order #</u>	<u>Paragraph #</u>	<u>Flowchart #</u>	<u>Comments</u>
*NEQ7	16	4.2.1.3	A-3	Replaced dummy
PARAR1	17	-	-	Original
PGET	38	4.2.2.4	A-9	Added
PLOTN	24	-	-	Original
*PLOTTR	22	-	-	Original
*PLOTTRV	18	-	-	Original
*PLOTT	23	-	-	Original
PROD	20	-	-	Original
PROD1	21	-	-	Original
RCOMB	19	-	-	Original
*READIN	34	4.2.1.5	A-5	Modified
READIN2	35	4.2.2.1	A-6	Added
REDUC	27	-	-	Original
RELATE	28.5	-	-	Deleted
RELEQS	30	-	-	Original
*RIFDIF	29	-	-	Original
RITE	30.5	-	-	Deleted
ROMBD	28	-	-	Original
ROWPLT	31	-	-	Original
SCAN	33.5	-	-	Deleted
SEARCH	31.5	-	-	Deleted
SIMPLE	33	-	-	Original
SIMPRI	32	-	-	Original
SPECIT	55	4.2.4.9	A-26	Added
TRANSFR	36	4.2.2.2	A-7	Added
WRNR	25	-	-	Original

*Affected by array dimension modifications, as required for optional reduced field length execution.

4.2.1 Altered Subprograms

4.2.1.1 CARE2 (Main subprogram)

The basic order of processing is the same as that of CARE. All output options which were allowed in CARE exist unchanged in CARE2, with the exception of simultaneously varying more than one parameter type and automatically obtaining all possible combinations. The current ability to repetitively input changes to both parameter and coverage data provides an equivalent capability and, in addition, allows for direct user selection of the combinations to be evaluated. The restrictions on plotting options which applied to evaluations of a product of reliabilities now apply, analogously, to evaluation of a dual mode system (Eq. 7) with more than one stage.

A dual mode system of up to 8 stages can be modelled in series with other computer models, by declaring array PROD as a like quantity of 7's, followed by the numbers of the other desired equations.

As in CARE, the invariant data for a batch run is specified via READIN. The additional data now contained in this category, as included in Figure 5-1 and Table 3-1, consists of:

- flags which enable the calculation of coverage and the display of intermediate coverage results
- a flag enabling the display of mode 1 reliability of the dual mode system model and its individual stages
- a flag enabling display of the reliability model parametric inputs; iteration array and dual mode system special data (defaulted to .TRUE.).

- linkage data to allow calculated coverage values to be applied to reliability models
- a flag to specify the method used to fill the iteration array
- a debug flag (see below).

Following READIN, the variant data is input via READIN2. (The data following READIN, is termed variant because the call to this subprogram is the beginning of a main subprogram loop which may be continued indefinitely.) All inputs to READIN2 are made via control cards, which determine the data to be input as well as the format to be used. This data includes both parameters for the reliability models and inputs to the coverage model.

After all data has been processed, the coverage driver, COVGEN, is called to effect all requested coverage calculations and transfer their result to the run vectors, using the linkage algorithm. The iteration array, PARAM, is then adjusted as required, and the prepared inputs to the reliability models are (optionally) displayed.

If the DEBUG flag has been set, control passes directly back to READIN2, and no reliability model evaluation occurs. This is useful 1) for checking data cards for validity, and 2) when coverage analyses only are desired.

If DEBUG is not set, reliability equations are evaluated sequentially, and reliability versus the independent variable, followed by the selected computational and plot options, are printed. In the case of dual mode system, the independent variable must be time and must begin at zero, due to the use of structured numerical integration.

An additional, more specific, overview of CARE2 is provided in Appendix A (cf. flow diagram A-1).

4.2.1.2 NEQ1A

A simple correction was made to this routine during the initial investigation of CARE. Specifically, a card sequence error was found in the algorithms' source listing which in turn caused the summation on L (or LX) to be set equal to its last term. (cf. flow diagram A-2)

4.2.1.3 NEQ7

As mentioned in Section 4.1, the data available to this sub-routine via its argument list is inadequate for evaluation of the dual mode model. The model is thus referenced separately by the main program, with parameters held in common blocks.

NEQ7 is capable of interpolating the results stored in array R(121,25), when referenced via RELEQS by subprograms which perform secondary calculations (e.g., MTF). It uses a 2nd order (parabolic) integration technique. (cf. flow diagram A-3)

4.2.1.4 MOVG

This routine, which transfers six-bit characters between words of memory, originally required a Langley installation routine called SETBIT. It now uses ISHIFT, which is written in COMPASS and included in the source code. (cf. flow diagram A-4)

4.2.1.5 READIN

The basic input package provided by READIN remains unaltered with the exception that the reliability model parameters (Q, N, LAM, etc.) have been removed from namelist \$VAR. As in CARE, READIN is referenced once by CARE2, and thus data processed by it cannot be changed during later execution.

Since CARE inputs were originally based on a time-sharing question and answer format, they are rather awkward for use in batch mode, and for clarity require the use of either a standardized procedure or analysis of subprogram READIN. The substantial number of new inputs now required to accommodate the dual mode and coverage models complicate this matter further. In an attempt to clarify the issue somewhat, the current input algorithm is shown in Figure 5-1, in flowchart form.

The essential differences between CARE and CARE2 in this context are:

- A number of logical variables have been added to Namelist \$OPTSON, including DEFCHNG and COVPRC.
- Two additional Namelists, \$DEFAULT and \$COVCAL, are read following \$VAR, conditional on their respective flags, DEFCHNG and COVPRC, being set .TRUE.
- As in CARE, the inputs to READIN are invariant for the entire batch run. The addition of subprogram READIN2 allows most parametric data to be altered between run-sets
- The basic reliability model parameters (Q, S, LAM, etc.) have been moved from Namelist \$VAR in READIN to Namelist \$PARVEC in READIN2.

More detailed information on the current complement of variables and flags, as well as an overview of the revised READIN flow and the context of how it is used in CARE2, is provided in Sections 2.3, 4.2.1.1 and 5.1.2 and flow diagram A-5.

4.2.2 New Utility Subprograms

4.2.2.1 READIN2 (NRS,DMFLG,IRES,LVARY,DVAL,DEBUG)

This subroutine is called by CARE2 directly after READIN, and again after completing evaluation of the reliability models and secondary calculations. It is thus possible to continue altering the parametric and/or coverage data base, and in turn re-evaluating the models, indefinitely.

Due to the "inputs only for changes" rule, extensive use is made of the Namelist feature of Fortran. Also, for this reason, all input processing is carried out in direct response to control cards. The routine continuously reads these cards, using a standard format, and processes them along with other indicated data, such as namelist inputs, until such time as a return to model evaluation is specifically requested.

The control cards contain an identifying code in columns 1-3 which indicates one or more of the following:

- a reference to a particular Namelist follows in the input stream
- the control card contains specific information in a fixed format
- the subroutine is to perform a specific processing task.

A code which begins with "I" requests the reading of a Namelist, and those beginning with "P" cause the immediate printing of a portion of the data base. A general description of each of the 12 control codes is contained in table 5-2. (cf. flow diagram A-6)

4.2.2.2 TRANSFR(X,I)

This subroutine conditionally prints a line of parametric input data starting at the address of X. I is the element of array PCW(22), which contains applicability information concerning the parameter vector to be printed. Only those values pertaining to the applicable reliability model are printed. (cf. flow diagram A-7)

4.2.2.3 COVGEN

If one or more of the coverage factors are to be calculated, this routine is called by CARE2 directly after return from READIN2. COVGEN responds to requests for coverage calculation from both the IGENC(10) and IGENP(10) flags (which correspond to stages of the reliability models) and to individual requests initiated by setting coverage parameters to negative values. For each request, the routine determines applicability by testing the proper element of PCW(22).

Since delta coverage is computed using corresponding basic coverage, the order of calculation is by parameter type, with subclass linkage tests secondary. A fault subclass is linked to a stage if the corresponding element in IFSC(8) is the stage number. The corresponding fractional fault rate in FRAC(8) is then applied. (cf. flow diagram A-8)

4.2.2.4 PGET(IR,I,NPROD)

PGET refreshes the run vector of the parameter to be varied with NPROD values from row I of the iteration array PARAM (16,10). IR indicates the parameter of interest. (cf. flow diagram A-9)

4.2.3 Dual Mode Model Implementation Subprograms

4.2.3.1 DCR(J,UNITR,RELM1,RSYS)

This subroutine, driven by the time step counter J, computes the dual mode system (eq. 7) reliability RSYS at the point in time $t = \text{STEP} * (J-1)$. It also evaluates the system and individual stage reliabilities as they apply to mode 1 operation alone (RELM1,UNITR(8)). (cf. section 3.1.7 and flow diagram A-10)

4.2.3.2 DCT2(J)

This function computes the probability that the system will have survived to time $t = \text{STEP} * (J-1)$, having degraded due to a category 2 switch failure. (cf. section 3.1.6 and flow diagram A-11)

4.2.3.3 DCT(IUN,J)

This function computes the probability that the system will have survived to time $t = \text{STEP} * (J-1)$, having degraded due to a failure in stage IUN. (cf. section 3.1.5 and flow diagram A-12)

4.2.3.4 DCS(IUN,T,TAU)

This function computes the conditional probability that stage IUN can survive in mode 2 from time TAU to time T,

given that a degenerative failure occurred in the stage at time TAU. (cf. section 3.1.4 and flow diagram A-13)

4.2.3.5 DCH(IUN,TAU)

This function computes the probability density of a degenerative failure in stage IUN of the system at time TAU. (cf. section 3.1.3 and flow diagram A-14)

4.2.3.6 DCRU(IUN,MD,L,TAU)

This function computes the probability of using at most L spare units in stage IUN by time TAU, given the system is operating in mode MD. (cf. section 3.1.2 and flow diagram A-15)

4.2.3.7 DCG(IUN,MD,I,T)

This function computes the probability of using exactly I spare units in stage IUN by time T, given the system is operating in mode MD. (cf. section 3.1.1 and flow diagram A-16)

4.2.3.8 DCOMB(TOP,K)

This function computes the binomial coefficient of the expression:

$$\binom{TOP}{K}$$

It is equivalent to the RCOMB function except for the case when K=0. (cf. flow diagram A-17)

4.2.4 Coverage Model Implementation Subprograms

4.2.4.1 COVAGE (ISU, MD, IET, JS)

This function returns a single value, either a coverage factor or transient recovery probability, for each reference. (Since little sharing of intermediate variables is possible in

coverage calculations, efficiency is not lost by the single value format.) The routine is driven by COVGEN, which provides the proper arguments for the type of coverage value required for the reliability models.

The Fortran statement for referencing COVAGE is:

```
CVAL = COVAGE(ISU,MD,IET,JS)
```

where

- ISU is the fault class or subclass
- MD is the computer system operational mode
- IET is the major fault type, either a permanent or transient failure
- JS is the number of spare units which must be checked out during the recovery process.

With reference to the definition of coverage (cf. section 2.3) as a conditional probability, the arguments MD and IET can be taken as the "given" conditions, i.e., coverage input data may be entirely different for differing values of these variables. In addition, a coverage factor is computed independently for each class or subclass of faults, where a class is defined as those faults occurring in a specific stage of the computer model. Within the fault class, faults may arbitrarily be divided into subclasses, provided that a decimal fraction, specifying the relative rate of fault occurrence, is assigned to each subclass. A subclass may be those faults occurring in a specific part, or subunit of an LRU, or those having a certain characteristic, such as "easy to find", etc.. The coverage factor applied to a computer stage is the average of the factors calculated for the applicable subclasses, weighted by the rela-

tive rates of occurrence assigned by the user.

Each call to the COVAGE sub-program results in a calculation of the systems' conditional ability to detect, isolate (to a specific LRU) and recover from the specified subclass of faults (ISU), under given conditions of mode, fault type and quantity of spares checked (as defined by MD, IET and JS respectively). To accomplish this, it is necessary that the components of the recovery system (i.e., the FTF's) be described, as input to the model, in terms of their stand-alone capacity to contribute. The model evaluation then combines the effects of these by statistically accounting for the competitive nature of the detectors, and the conditional isolation and recovery success probability associated with each.

The quantity of the data required by the model, due to its flexibility, is necessarily large. The user can, however, do much to simplify the corresponding data specification task by approaching it systematically. A convenient (although not necessary) starting point for this is to first list the names of all hardware and software fault detection devices available in the computer system. If there are 20 or less, a unique number is then assigned to each name which, in turn, represents the D/I/R mechanism corresponding to that detector. (If there are more than 20, sharing of numbers is required.)

Figure 4-1, by way of example, represents the processes (for all valid combinations of mode and fault type) which deal with faults of subclass 3. Each row therein represents the portion of a D/I/R mechanism corresponding to a single detector and each column, the set of coexistent processes which compete for detection of (and subsequent recovery from) faults of a particular type and occurring during a particular mode of operation. The four numbers



Coverage Mechanisms for Fault Subclass

3 - MEMORY BIT PLANE

Mechanism Number	Detector Name	Fault type/mode					
		PERM/1 D I E T	PERM/2 D I E T	TRANS/1 D I E T	TRANS/2 D I E T	PERM/0 D I E T	
1	6 BIT MEMORY CODE (Hamming)	1, 1, 1, 1	1, 1, 1, 2	1, 1, 1, 1	1, 1, 1, 2	1, 1, 1, 1	
2	OUTPUT COMPARATOR	9, 2, 1, 2	Not Applicable	9, 3, 1, 2	N/A	9, 2, 1, 2	
3	I/O WRAPAROUND	12, 2, 1, 1	12, 2, 2, 2	N/A	N/A	12, 2, 1, 1	
4	CPU SELFTEST	14, 2, 1, 1	14, 2, 2, 2	N/A	N/A	14, 2, 1, 1	
20	unused						

FIGURE 4-1

SAMPLE FUNCTION SELECTION CHART

contained in each intersect, designated function numbers, specify the detection, isolation, and 2 recovery characteristic functions selected to represent the components of the corresponding mechanism. Each such number designates a fully specified time function whose parameters are contained in one of four specification arrays, corresponding respectively to detection (D), isolation (I), error-propagation-recovery (E) and time-delay-recovery (T) functions (cf. Table 5-4). Each array has sufficient room for a number of specification lists which, in turn, are common to the entire model.

Looking again at figure 4-1, it should be noted that the only restrictions placed on the selection of function numbers is that a non-zero (i.e., enabled) detector be accompanied by non-zero function numbers for isolation and recovery, and that all 4 functions be properly defined.

In order to generate a characteristic curve versus time (or its integral), the coverage model uses an evaluation sub-program which applies the specifications of the selected function number to one of several common function models. Each model, in turn, is a Fortran sub-program, in the form of a generalized equation with one independent variable and up to 3 fixed parameters, as for example:

$$f(t) = a(e^{-bt} + c).$$

The user generates specifications at run time, in part, by linking each function number to a particular function model, and

in part, by selecting appropriate values for a, b and c. He may also alter, or add to, the set of function models, recompiling only the corresponding model sub-programs. Once specification lists have been input, the D/I/R sequences (i.e., mechanism portions corresponding to specific conditions) can be defined, one at a time or in groups, by selecting 4 function numbers for each.

It should be noted that the functions selected are characteristic curves which describe detection, isolation and recovery capabilities under a given set of conditions. A software detection device which is good at finding permanent failures in a CPU register may perform poorly when the register simply "drops a bit." The characteristic curves, and thus the functions (numbers) selected, will be different even though the same detector is used.

The 4 processes comprising a D/I/R sequence must be clearly understood, from a statistical point of view, before a realistic recovery system can be modelled. Up to this point, these functions have not been given a physical significance in order to avoid confusion. Although the 4 functions are implemented in the same manner, the detection and isolation functions have units of probability density, whereas the 2 recovery functions have units of probability. More specifically, the detection and isolation functions are rate functions, which for the present purposes means that the shape and coefficient of each detection and isolation function is provided and utilized separately. These rate functions (exclusive of the coefficient) are required by the model to have an integral of 1.0, with the co-

efficient then lying between 0.0 and 1.0. A normalization routine is provided in READIN2 to assure that the rate functions are correct.

The error-propagation-recovery and time-delay-recovery functions give the probability of successful recovery versus the time 1) that errors are allowed to propagate through the system and 2) that is required for detection plus isolation of a fault. The model treats these probabilities as conditional upon each other, such that the success probability for a given detection time and a given isolation time is the product of the two recovery functions.

Other data items which affect coverage are the probability of recognizing a failure in a spare LRU, as selected to replace a failed active unit, and the time required to test such a spare, whether or not it has failed. (cf. section 3 and flow diagram A-18)

4.2.4.2 CVG1(I,T)

This function computes the coefficient of the function for unscheduled impulse detector I, at time T units after the occurrence of a fault. The g function is an impulse in this case, and its coefficient indicates the competitive effectiveness of the detector. (cf. section 3.2.4 and flow diagram A-19)

4.2.4.3 CVG2(I,T)

This function computes the value of the g function for unscheduled finite detector I , at time T units after the occurrence of a fault. The g function is a measure of the competitive effectiveness of the detector. (cf. section 3.2.4 and flow diagram A-20)

4.2.4.4 CVGS(I,T)

This function computes the value of the g function for scheduled detector I , at time T units into the period of the test (detector). The detector may be either an impulse or finite function, and the calculation is based in part on the sample g' values saved in array GPAR(20,101). The g function is a measure of the competitive effectiveness of the detector. (cf. section 3.2.4 and flow diagram A-21)

4.2.4.5 CVGP3(I)

This subroutine computes and stores $N+1$ samples of the g' function for scheduled impulse detector I , over its period (i.e., the time between successive runnings of the test). The assumption is made that no detection can be made after one such period, measured from the occurrence of a fault. The g' function is a measure of the effectiveness of the test, in competition with other scheduled detectors. (cf. section 3.2.5 and flow diagram A-22)

4.2.4.6 CVGP4(I)

This subroutine computes and stores $N+1$ samples of the g' function for scheduled finite detector I , over its period (i.e., the time between successive runnings of the test). The

assumption is made that no detection can be made after one such period, measured from the occurrence of a fault. The g' function is a measure of the effectiveness of the test, in competition with other scheduled detectors. (cf. section 3.2.5 and flow diagram A-23)

4.2.4.7 CVTJL(J,L,I)

This function returns the time difference value $t_j^{l(i)}$ for use by CVGP3 and CVGP4 in evaluating the competition between scheduled detectors, i.e., the effect of detector J on detector of interest I. (cf. flow diagram A-24)

4.2.4.8 CVGPI(I,T)

This function interpolates the sample g' values (for detector I) which have been saved in array GPAR(20,101) by CVGP3 and CVGP4. The result is used by CVGS in determining the effectiveness of scheduled detectors in competition. (cf. flow diagram A-25)

4.2.4.9 SPECIT(FLIST,NUM,IGFT,ISCH,IREF,INTF,COEF,TDEL,P1,P2,P3,TDUR)

This subroutine sets up a specification list (in one of four arrays) which defines a characteristic curve (function) versus time for either a detection, isolation, error-propagation-recovery or time-lost-recovery process. The respective specification arrays which receive this data are FDET(7,200), FISO(7,50), FEPR(7,25), or FTLR(7,25). FLIST is the address of one of these arrays, and NUM the column position within it where the data will be stored. The remaining arguments are the function specifications:

- IGFT The identification number of the function model to be employed in evaluating the curve
- ISCH The scheduling indicator. Equal to 0 for unscheduled, or 1 for scheduled detectors. Does not apply to other processes
- IREP The repetition factor of scheduled detectors only, i.e., the number of minor cycles in the detector period
- INTF The integral-defined indicator. Equal to 0 if the integral model corresponding to IGFT above does not exist, and 1 if it does
- COEF The explicit coefficient of the function. For detection and isolation, it is also the infinite-time success probability
- TDEL The delay time associated with a detector or isolator. For detectors, it is measured either from the occurrence of a fault (unscheduled), or from the beginning of the test period (scheduled)
- P1,P2,P3 Arbitrary parameters which are passed to function model number IGFT via COMMON block CVB4, and used for the evaluation of the process characteristic. If normalization is to be performed using the routine in READIN2, P1 must be an internal coefficient in the function model selected to represent either a detection or isolation rate function

- TDUR The duration of any finite process, including recovery. This is used to determine upper limits for numerical integrations, and for reasonableness sampling when requested.

(cf. flow diagram A-26)

4.2.4.10 FEVAL(FLIST,NUM,T)

This function evaluates the characteristic function representing a detection, isolation, error-propagation-recovery, or time-lost-recovery process. The function specifications are retrieved from the array position indicated by FLIST (which may stand for FDET, FISO, FEPR, or FTLR) and NUM (the column position within the array). The independent variable T is passed to the function model. (cf. flow diagram A-27)

4.2.4.11 FINTEG(FLIST,NUM,T)

This function evaluates the time integral of the characteristic function representing detection (although it could be used for another process). The function specifications are retrieved as in FEVAL, and the integral-defined indicator is tested. If it is greater than 0, the independent variable is passed to the proper integral model. Otherwise, a numerical integration (Simpson 3 point) is performed using N+1 samples of the function, which are returned by FEVAL. N is a local variable which may be altered by the user, via a recompilation of FINTEG alone. (cf. flow diagram A-28)

4.2.4.12 IGET(IWORD,INDEX)

This function returns the INDEX'ed 12 bit field of IWORD (one of 5 in the 60 bit word), as a right justified integer. (cf. flow diagram A-29)

4.2.4.13 INPUT(IWORD,INDEX,ICODE)

This subroutine packs the rightmost 12 bits of ICODE into the INDEX'ed 12 bit field of IWORD, after first clearing the field. (cf. flow diagram A-30)

4.2.4.14 ISHIFT(IWORD,NBITS)

This COMPASS function returns, as an integer, the result of performing a left circular shift of NBITS on IWORD. (cf. flow diagram A-31)

4.2.4.15-16 FN1(T) and FN1I(T)

This function model and corresponding integral model represent the characteristics of a "single pulse" or constant amplitude function. General parameter P1 is the amplitude, and the only parameter used in this case. It is important to note that the model does not incorporate a cutoff of its own, but is defined simply as FN1=P1. The coverage model applies the TDEL and TDUR values in its evaluation, in such a way as to properly service the numerical integral routines. (cf. flow diagrams A-32 and A-33)

4.2.4.17-18 FN2(T) and FN2I(T)

This function model and corresponding integral model represent the characteristics of a "pulse train" function, with amplitude P1, pulse width P2, and pulse repetition period P3.

Due to the discontinuities inherent in this function, it is not recommended for general use, except on an experimental basis. (cf. flow diagrams A-34 and A-35)

4.2.4.19-20 FN3(T) and FN3I(T)

This function model and corresponding integral model represent the characteristics of an exponential function. The equation is:

$$FN3(T) = P1(e^{-P2*T} + P3)$$

(cf. flow diagrams A-36 and A-37)

4.2.4.21-26 FN4(T), FN4I(T), FN5(T), FN5I(T), FN6(T) and FN6I(T)

These dummy functions are provided to allow the user to expand the inventory of models, as more complex systems for coverage modelling are evolved.

4.3 MAJOR ARRAYS AND COVERAGE DATA BASE

The following sections describe both the new format of the reliability model parameter arrays, and the changes in dimension needed to run the reduced field length version of CARE2.

4.3.1 Reliability Parameters

As mentioned previously, the original 16X10 parameter arrays proved too cumbersome for use with the dual mode model, due to the complex method employed for extracting individual elements. The new version of this data base consists of a set of 19 independent and 3 dependent parameter vectors, of dimension 10. Each vector holds the inputs, for up to 10 computer stages, for one parameter (e.g., Q, LAM etc.).

A parameter control array, PCW(22), contains applicability and other information in packed format, with one element of the array corresponding to each parameter. The first part of table 4-2 shows the fields within a word, and the second part of the table gives the parameter order and association of parameters with default variables.

4.3.2 Reduced Field Length CARE2

In the course of debugging the program with the new models included, the dimensions of certain of the plotting arrays not required for reliability computation, were temporarily reduced in size. The result was a 30K (octal) savings in required field length for execution. The user who wishes to obtain only tables of reliability can convert the complete program version by making the changes shown in table 4-3.

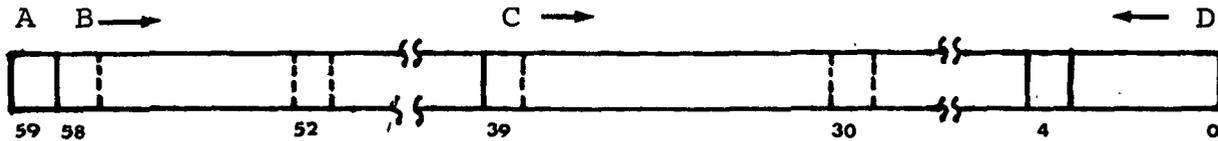


TABLE 4-2

PCW AND DEFAULTS

-ARRAY PCW (22)-

PCW contains packed information pertaining to the type and usage of each parameter in the reliability model. The fields within each word (one per parameter) are as follows:



<u>Field</u>	<u>Meaning if bit position is equal to one</u>
A	Parameter is represented in real format (as is default), otherwise it is in integer format
B_i	Parameter is used in the i^{th} reliability equation, and B_i is located at (59-i)
C_i	Parameter is used in the reliability equation associated with the i^{th} stage, and C_i is located at (40-i). (These bits are set by READIN for use by COVGEN & RITE2)
D	5 bit right justified integer giving the subscript of the default value in either INTDFS(4) or RLDFS(10), depending on field A (bit 59).

TABLE 4-2 (Cont.)

-Parameter Names, Defaults and Usage-

PCW SUBSCRIPT	NAME	DEFAULT	ARRAY POSITION	DEFAULT VALUE	EQUATION							
					1	2	3	4	5	6	7	
1	Q=Q1	Q1DEFr	RLDFS (1)	2.0		X	X					X
2	Q2	Q2DEFr	RLDFS (2)	1.0								X
3	N	NDEFi	INTDFS (1)	3	X							
4	S	SDEFi	INTDFS (2)	0	X	X	X	X				X
5	W	WDEFi	INTDFS (3)	1	X	X	X	X	X	X		
6	Z	ZDEFi	INTDFS (4)	1	X	X	X	X	X	X		
7	LAM	LAMDEFr	RLDFS (3)	10 ⁻⁶	X	X	X	X	X	X	X	X
8	MU	MUDEFr	RLDFS (4)	10 ⁻⁶	X	X	X	X				X
9	GMP	GMPDEFr	RLDFS (5)	10 ⁻⁶								X
10	C=CI	CDEFr	FLDFS (6)	1.0		X	X					X
11	CD1	CDEFr	RLDFS (6)	1.0								X
12	C2	"	"	"								X
13	CD2	"	"	"								X
14	CTR	CTRDEFr	RLDFS (7)	"								X
15	CDTR	"	"	"								X
16	PRC1	PRCDEFr	RLDFS (8)	"								X
17	PRC2	"	"	"								X
18	RV	RVDEFr	RLDFS (9)	"	X	X	X	X	X			
19	P	PDEFr	RLDFS (10)	0.5						X		
20	K		"	N/A	X	X	X	X				X
21	GM1		"	N/A								X
22	GM2		"	N/A								X

Note:

- other parameters (scalars) are printed when DCFLG = .TRUE.
- internal representation is denoted by subscript r for real and i for integer.

TABLE 4-3

DIMENSION CHANGES FOR REDUCED FIELD LENGTH CARE2

Subroutines affected:

- * CARE2 (main subprogram)
- * EQUAL
- * NEQ7
- * PLOTR
- * PLOTRV
- * PLOTT
- * READIN
- * RIFDIF

Arrays affected:

Complete version	Reduced version
R(121,25)	R(121,10)
DIFF(121,15)	DIFF(1,1)
RIF(121,15)	RIF(1,1)
GAIN(121,15)	GAIN(1,1)
ABSC(121,3)	ABSC(1,1)
G(121,16)	G(1,1)
XY(121,19)	XY(1,4)
RLRV(210,17)	RLRV(1,2)
FDUM(3233)	FDUM(1)

SECTION 5

PROGRAM OPERATION

CARE2 is designed to run on a 60 bit CDC 6000 Series computer system, using the RUN Fortran compiler in batch mode, under either the KRONOS 2.1 or SCOPE 3.0 operating system. Source and data input are nominally provided on punched cards, and output is nominally produced on a line printer. However, both operating systems allow reassignment of input/output devices with little effort.

In modifying and adding to the Fortran source code, care was taken to avoid using features of extended Fortran versions which were not used in the original CARE program. Reliance on library routines was also held to a minimum. The SETBIT routine is no longer required, and the ISHIFT function is included in the source as a Fortran callable COMPASS program. Other library references are to long-time standards such as AMIN1, OR, etc..

In comparison with CARE, which requires about 110K octal field length to load and execute, CARE2 runs in slightly under 130K (the precise figures depend somewhat on the compiler and operating system used). The reduced version of CARE2 runs in about 100K.

5.1 USER'S GUIDE

This section, although intended for those familiar with the operation of CARE, provides the information required for compiling all the input data to model computer systems and coverage systems with CARE2. An input algorithm, in flowchart form, is included to simplify usage. The use of the Fortran Name-

list feature and control cards on input facilitates sensitivity analyses, which is an expected mode of operation.

5.1.1 Processing Order

The general processing order of the program as a whole is as follows:

- 1) Input the computer configuration to be modelled, using one or more equation numbers to represent stages in series or, in the case of the dual mode model, a number of 7's to represent the stages within that model.
- 2) Input the upper limit of the independent variable and the step size to be used to generate reliability tables.
- 3) Input data to specify the desired computational and plotting options, changes to defaults (optional), and linkage data for the subsequent transfer of calculated coverage values to the reliability model data base.
- 4) Input non-default values for parameter base run vectors, coverage function selection and specification data, and special dual mode and coverage model variable data, as required.
- 5) Input iteration data, if any. (Enables the re-running of computer model evaluations with variations in a single parameter).
- 6) Print out selected parts of the coverage data base, if requested.

- 7) Compute any requested (and applicable) coverage factors, optionally displaying intermediate results (conditional D/I/R mechanism contributions).
- 8) Optionally print out parametric data to be used in reliability model evaluations, including calculated coverage and special variables.
- 9) Compute and print tables of reliability versus the selected independent variable, sequentially for each equation in the configuration list. If the dual mode model (equation 7) is evaluated, optionally print the mode 1 system and stage reliabilities versus time (ahead of the standard reliability table).
- 10) Compute product, MTF and other selected options, including plots.
- 11) Repeat steps 4 through 10, changing only the desired variant data. (Note that the iteration parameter and data will remain the same if not actively altered or defeated.)

5.1.2 Use of the Input Algorithm

Figure 5-1 is a working guide for the creation of an input deck. The requirements are unusually complex, partly due to the volume and variety of data, and partly since the input routine was originally written in a question-and-answer format for use in a time-sharing environment.

Each input record must of course contain the proper information in the proper format. Thus the algorithm, in flow chart form, covers all possible inputs in both READIN (invariant data) and READIN2 (variant data). It is not intended as a complete

flow diagram for either of these subroutines.

In following the diagram, note that a decision block contains either the name of a logical variable or shows some test of a variable. Input blocks which refer to Namelist names (designated by \$) have comments showing the names and dimensions of its contained variables.

Table 5-1 describes many of these variables in operational terms. The 12 possible control cards which initiate processing tasks in READIN2 are described in Table 5-2. Input blocks which show fixed format cards refer to format entries in Table 5-3.

FIGURE 5-1

INPUT ALGORITHM

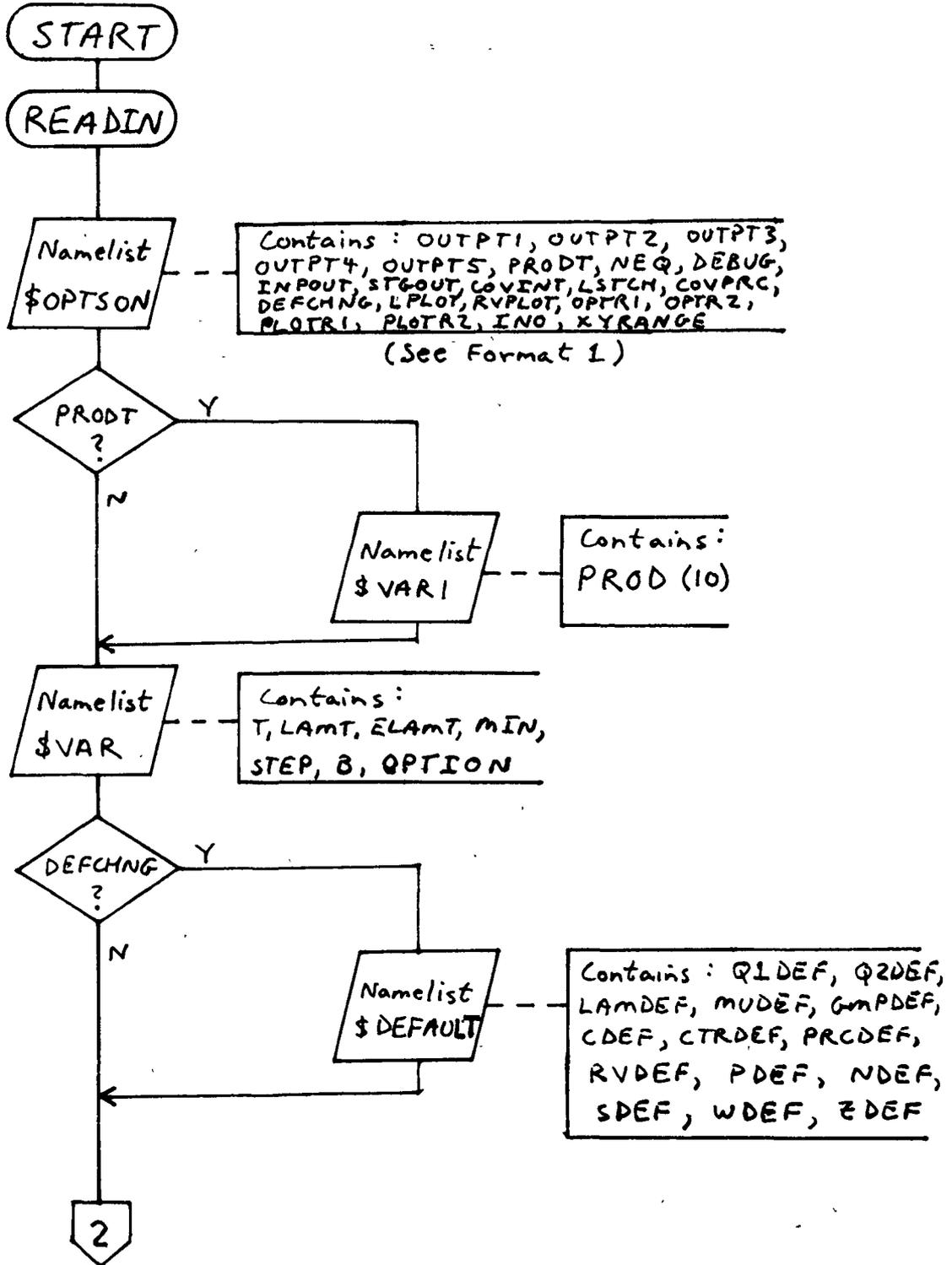


FIGURE 5-1 (Cont.)

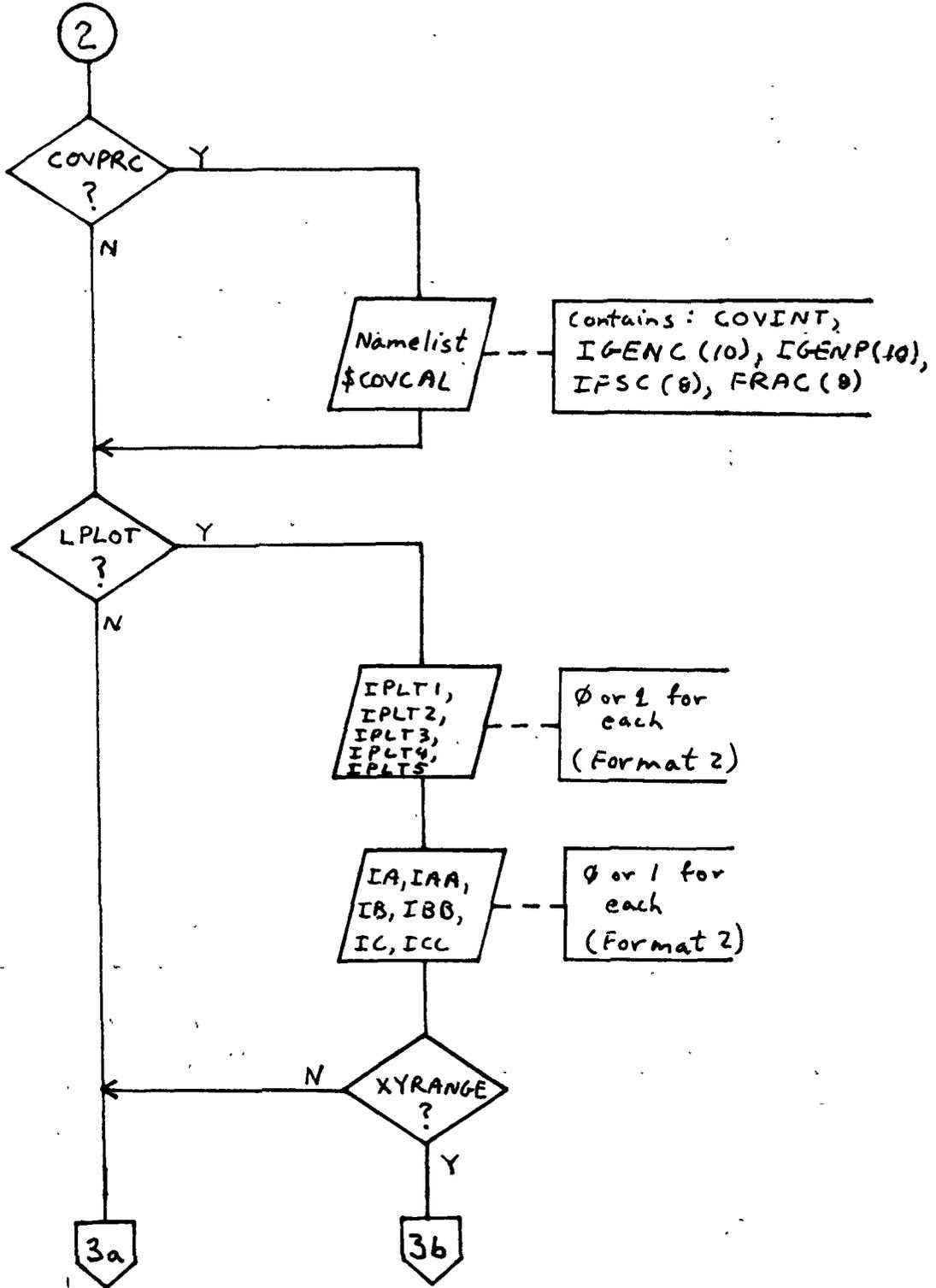


FIGURE 5-1 (Cont.-2)

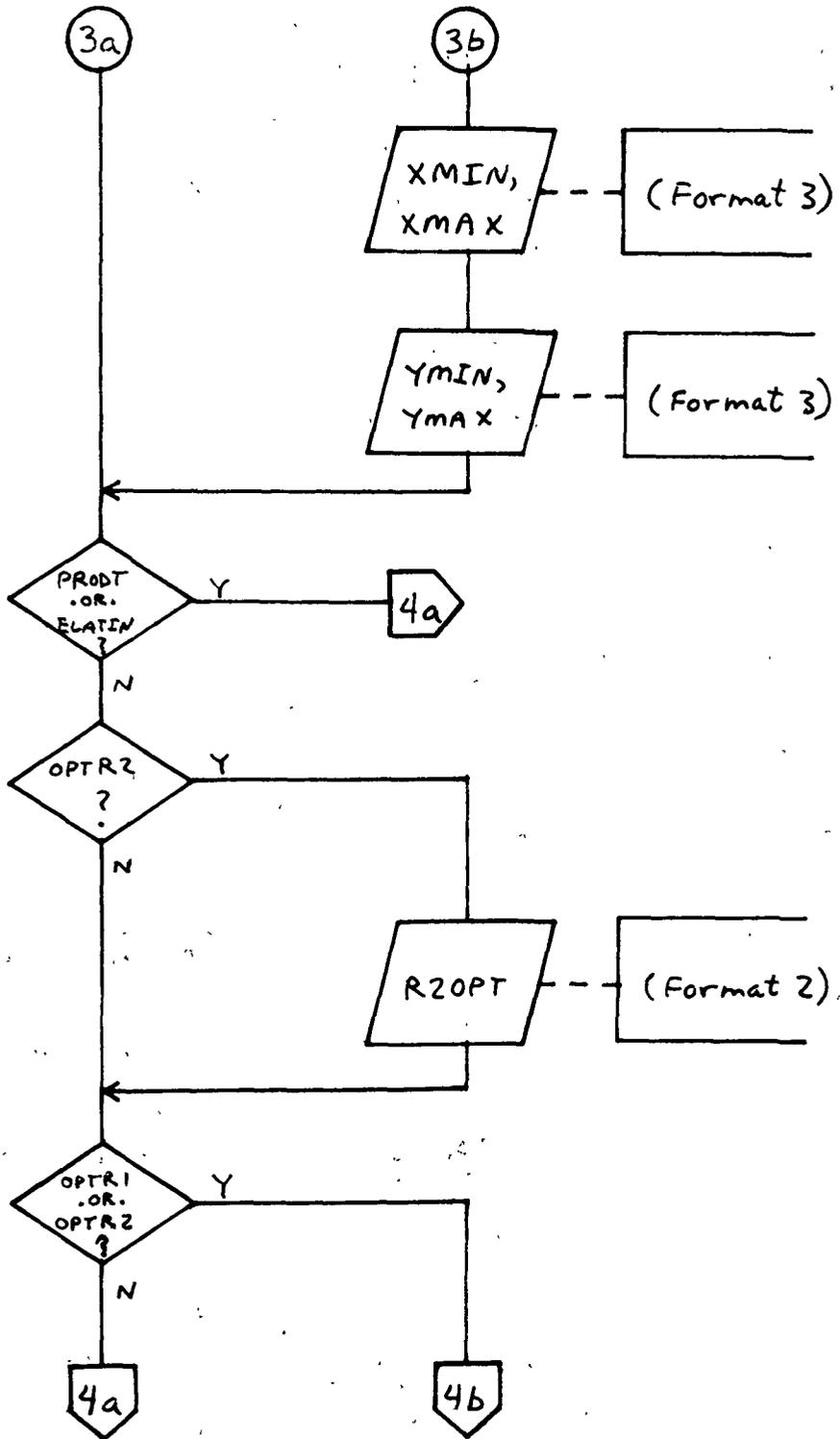




FIGURE 5-1 (Cont.-3)

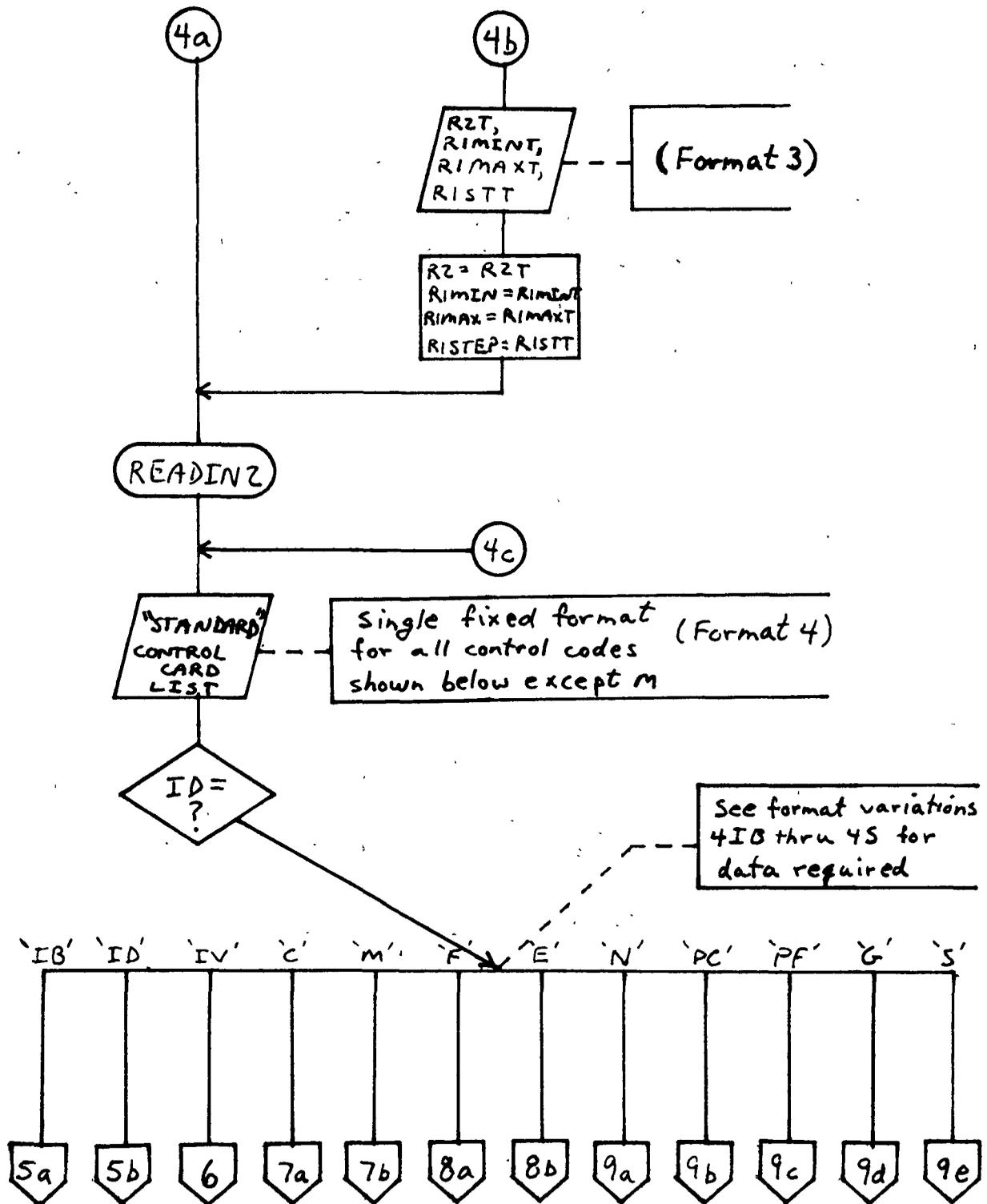


FIGURE 5-1 (Cont.-4)

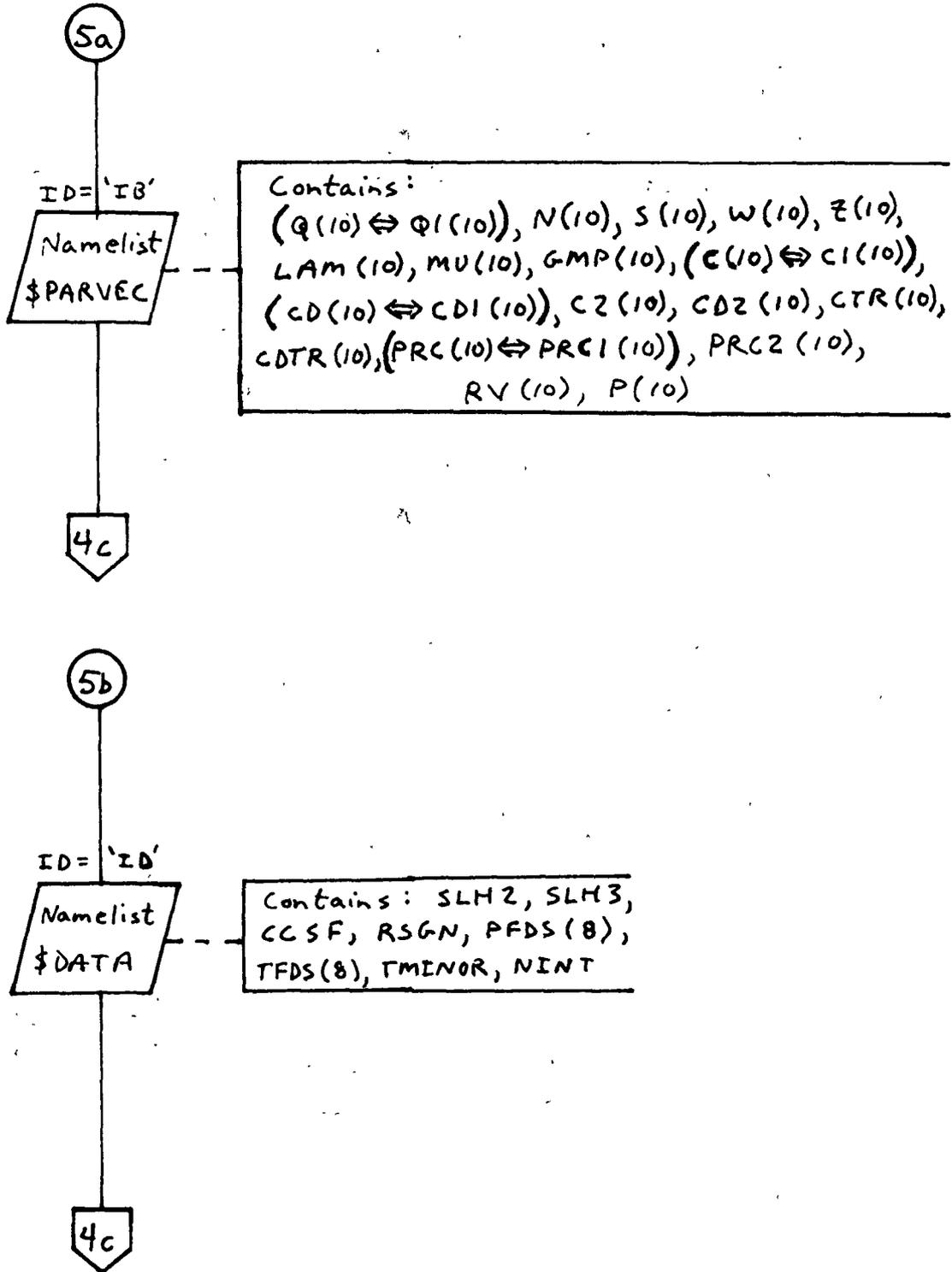


FIGURE 5-1 (Cont.-5)

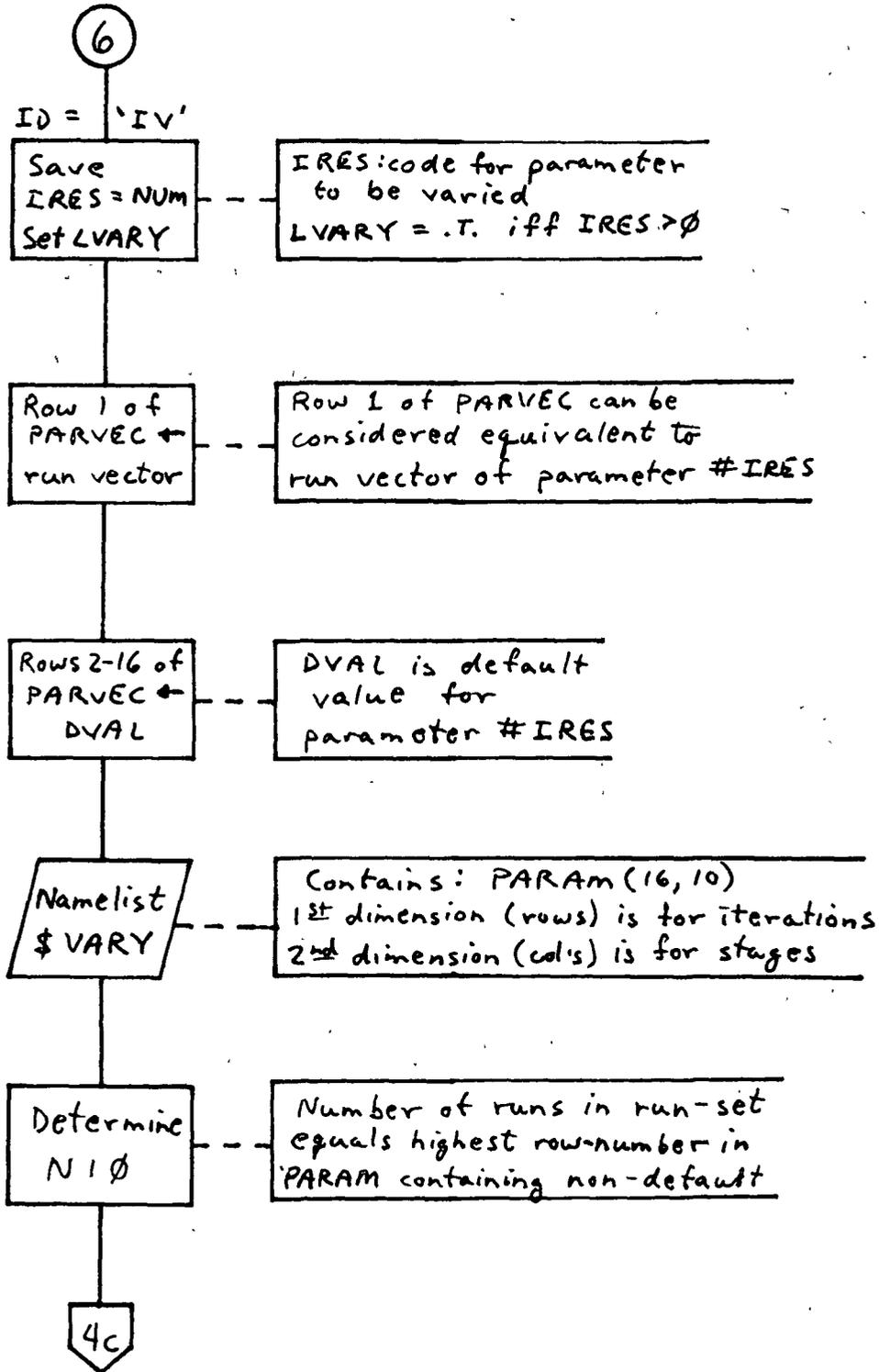


FIGURE 5-1 (Cont.-6)

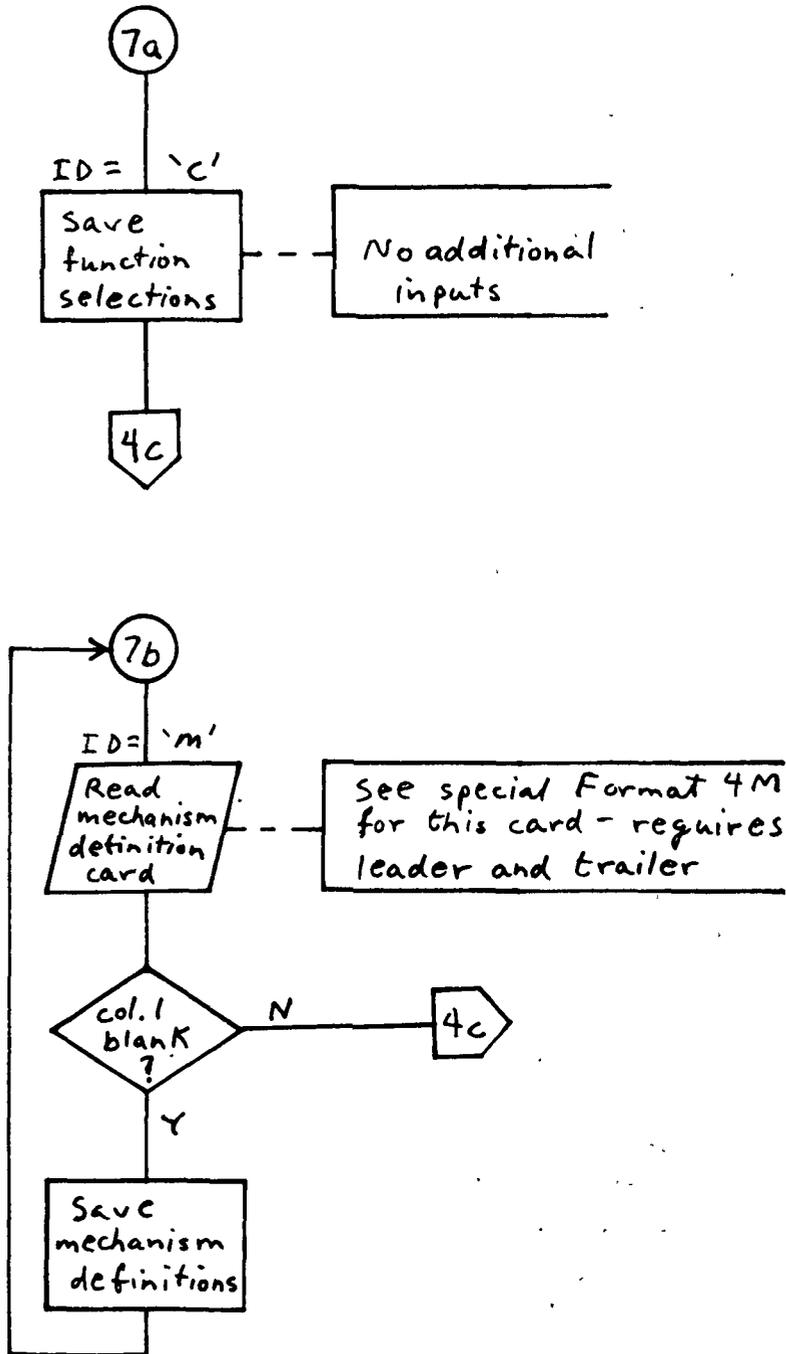


FIGURE 5-1 (Cont.-7)

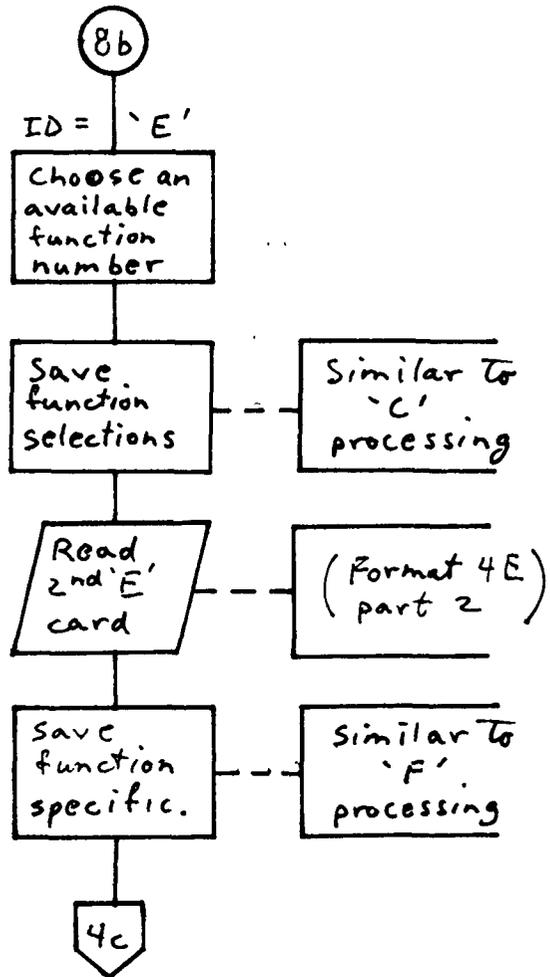
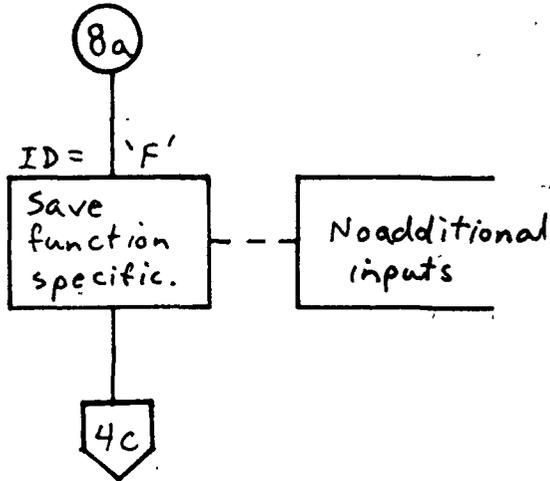


FIGURE 5-1 (Cont.-8)

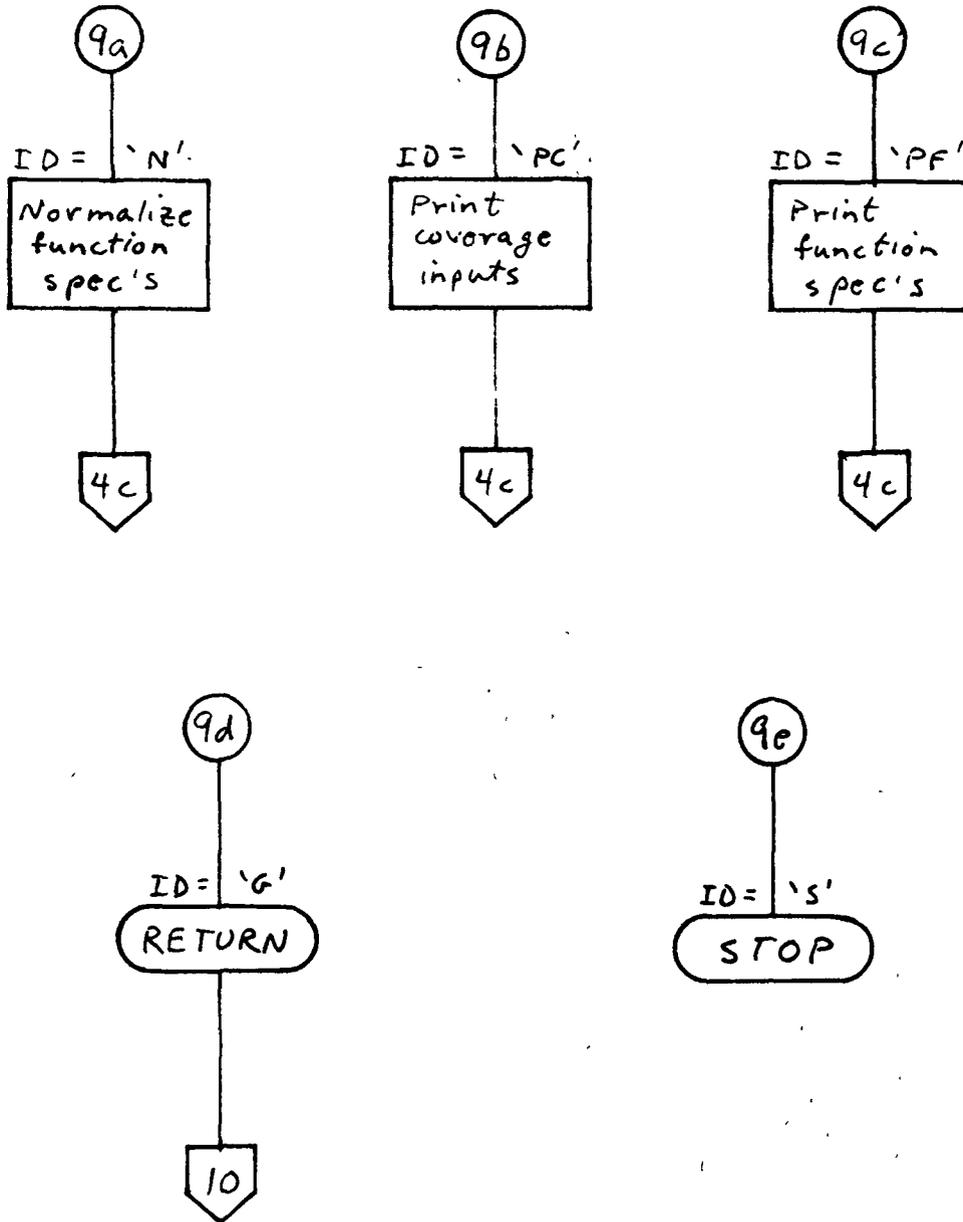


FIGURE 5-1 (Cont.-9)

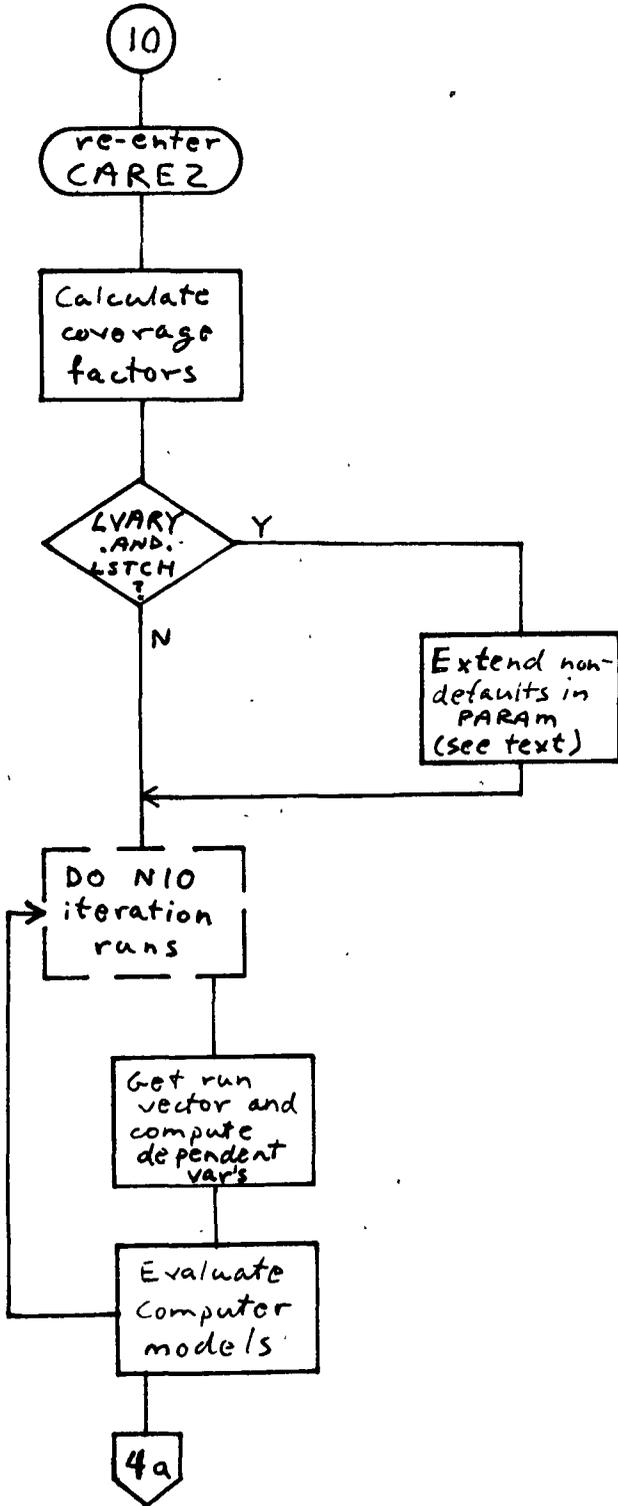


TABLE 5-1

DEFINITIONS OF LOGICAL AND CONTROL VARIABLES

PRODT	Logical: Specifies whether a list of equation numbers is desired rather than a single equation.
NEQ	Control: Specifies the single equation to be evaluated.
DEBUG	Logical: Specifies (if TRUE) that input format errors detected in READIN2 will not cause the job to abort, and that the reliability models will not be exercised.
INPOUT	Logical: Specifies (if TRUE) that a table of parameter values to be used for the subsequent run-set will be printed (regardless of the setting of DEBUG)
STGOUT	Logical: Specifies (if TRUE) that mode 1 reliability results for the dual mode model are to be printed.
COVINT	Logical: Specifies (if TRUE) that individual mechanism contributions are to be printed during the calculation of coverage.
LSTCH	Logical: Determines the convention used in the pre-processing of parameter iteration data in array PARAM. If TRUE, non-default elements replace default elements along the iteration dimension (those of increasing row subscript are replaced). For example, if the parameter default is 0, and a 1 is placed in PARAM (1,3), 0's in positions (2,3), (3,3), etc. will be replaced by 1's, up to the next non-default.
COVPRC	Logical: Specifies (if TRUE) that some coverage factors will be calculated (under the condition that subsequent requirements are met).
DEFCHNG	Logical: Specifies (if TRUE) that some default values for parameter vector initialization are to be changed.

TABLE 5-1 (cont.)

L PLOT	Logical: Specifies (if TRUE) that the reliability product table is to be plotted on the line printer.
PROD(10)	Control: The list of equation numbers for a product of reliabilities, to specify the number of stages in the dual mode model, or both.
T	Control: The upper limit for reliability tables when the independent variable is time. Time must be used when the dual mode model is evaluated.
LAMT	Control: The upper limit for reliability tables when the independent variable is failure rate * time.
ELAMT	Control: The upper limit for reliability tables when the independent variable is the exponential of (failure rate * time).
MIN	Control: The lower limit of the independent variable. This must be 0.0 when the dual mode model is evaluated.
STEP	Control: The increment of the independent variable.
ID	Control: The 1 or 2 letter code beginning in column 1 of a READIN2 control card, which identifies an input or processing request.
XYRANGE, OPTR2	See original CARE documentation.

TABLE 5-2
CONTROL CARDS

<u>Identifier</u>	<u>Control Function</u>
IB	- Input the base-run parameter vectors (for reliability models) via namelist PARVEC
ID	- Input system data via namelist DATA, specifically: SLH2, SLH3, CCSF, RSGN, PFDS, TFDS, TMINOR, and NINT.
IV	- Input the variation parameter type code, followed by namelist VARY with changed values for array PARAM.
C	- Read a subset of the D/I/R mechanism data base (function number arrays). One function number is specified for one process (detection, isolation, recovery (1 of 2)), but the number may be distributed over any or all of 4 dimensions: <ul style="list-style-type: none"> ● subclass of faults (1 thru 8) ● mode (0, 1 or 2) ● error type (1 = permanent, 2 = transient) ● mechanism (1 thru 20)
M	- Begin reading D/I/R mechanism definitions (function number selections) at the rate of one mechanism (for one fault subclass) per card. The selections must completely define the characteristics of the 4 processes comprising the mechanism, for all conditions of mode and error type.
F	- Read one function specification for one process (detection, isolation, recovery) of the recovery system. Function number and specifications use a common fixed format (based on the scheduled detection function), but fields which do not apply may be left blank.

TABLE 5-2 (Cont.)

<u>Identifier</u>	<u>Control Function</u>
E	- Read an explicitly defined subset of the D/I/R mechanism data base. This is a combination of the C and F control cards, in which the function number selection is automatic. The formats for the auxiliary information (on 2 cards) are identical to those of the C and F cards.
N	- Normalize the function specifications. The normalization involves all defined functions for all 4 processes. A trial integration is performed for detection and isolation rate functions over their specified non-zero ranges. The respective P1 values are then adjusted to obtain an integral value of 1.0 (P1 is assumed to be an internal coefficient of each function). The recovery probability functions are sampled over their specified ranges, and must be ≤ 1.0 at each sample point. Finally, the explicit coefficients for all functions (each of 4 specification arrays) are tested, and must be ≤ 1.0 . Appropriate messages are printed during or after normalization.
PC	- Display the contents of the D/I/R mechanism data base. The function numbers selected to define recovery subsystems are printed, with conditions which may cause errors flagged with the letter X.
PF	- Display the specifications of all defined functions,
G	- Exit READIN2 and execute the run-set. Coverage and reliability models will be exercised if the DEBUG flag is not set. Otherwise, the requested coverage calculations are performed and the selected runset input data is printed (including coverage and iteration values), prior to re-entering READIN2.
S	- Stop the program (optional, equivalent to an end-of-file on input).



1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80
Format 1 - Sample Namelist Reference		\$NAME FIRSTV=1.0, NEXT=2, ARRAY(1,1)=3, 0.4*4, ARRAY(1,3)=6\$		<p>some operating systems require array subscripts repetition shown by '*'</p> <p>separate entries or values with commas</p> <p>any variable included in the Namelist</p> <p>Namelist identifier as given in Fortran Namelist declaration</p> <p>'\$' in column 2 of first input record, and after last data item</p> <p>column 1 blank on all input records</p>		Format 2 - (IG)		IJKLMN		one digit integers, one per column		Format 3 - (4F8.0)		AA.BB XXX C.DDYY.Z		method 1 - decimal point assumed after last digit in field		method 2 - decimal point shown overrides format specification																																																													

TABLE 5-3
INPUT FORMATS AND EXAMPLES

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80
Format 4IB - Input base run vectors																																																																															
'A' - 'IB' in cols 1 + 2																																																																															
Format 4IDI - Input system data																																																																															
'A' - 'ID' in cols 1 + 2																																																																															
Format 4IV - Input variation data																																																																															
'A' - 'IV' in cols 1 + 2																																																																															
Parameter vector to be replaced prior to each run. Specificity:																																																																															
1 ⇒ Q = Q1 (10)																				6 ⇒ Z (10)																				11 ⇒ (D1) (10)																				16 ⇒ PR C1 (10)																			
2 ⇒ Q2 (10)																				7 ⇒ LAM (10)																				12 ⇒ (C2) (10)																				17 ⇒ AR C2 (10)																			
3 ⇒ N (10)																				8 ⇒ MU (10)																				13 ⇒ CD2 (10)																				18 ⇒ RV (10)																			
4 ⇒ S (10)																				9 ⇒ GMP (10)																				14 ⇒ CTR (10)																				19 ⇒ P (10)																			
5 ⇒ W (10)																				10 ⇒ C = C1 (10)																				15 ⇒ CDR (10)																																							

TABLE 5-3 (Cont. -2)

5.1.3 Specific Input Information

Inputs for the dual mode model are described in Sections 2.3 and 3.3, and are relatively easy to comprehend. For reason of its greater flexibility, coverage model input requirements are considerably more complex, and thus additional learning aids might well prove useful.

In particular, it is felt that preliminary experimentation, by the user, may be required in order to become sufficiently familiar with the tool to use it effectively. For this reason, a set of input values is provided (cf. Tables 5-4 and 5-5) which reflect the coverage system described in Section 2.2.

Table 5-4 gives specifications for the above referenced detection, isolation and recovery characteristics, which, in turn, may then be applied to measure the effects of these processes on different subclasses of faults, under various conditions, e.g., permanent versus transient faults, mode 1 versus mode 2 operation, etc.. Table 5-6 defines the individual variables which comprise the specification of a single function, (cf. Format 4F in Table 5-3 for individual specification requirements of the 4 processes) as well as the other important variables in the coverage model.

Table 5-5 gives the function selection data for a complete system of fault coverage. For example, the 4 numbers in the upper right hand corner of the table (under the heading "Permanent Fault/ Mode 0") indicate the non-competitive (i.e., stand-alone) effectiveness of detector #2 and its associated isolation and recovery processes, under a particular set of specified conditions (i.e., that a permanent failure has occurred in the stage linked with fault subclass 1, and that the recovery is predicted on degenerating from mode 1 to mode 2 operation (shown as mode 0)).

TABLE 5-4

FUNCTION SPECIFICATIONS

FUNCTION	#	IGFT	ISCH	I REP	INTF	COEF	TDEL	A≡P1	B≡P2	C≡P3	TDUR
DETECTION (D)	1	0	0	-	1	1	0	-	-	-	-
"	2	0	0	-	1	0.25	0	-	-	-	-
"	3	0	0	-	1	0.1	0	-	-	-	-
"	4	0	1	1	1	0.05	19.3	-	-	-	-
"	5	0	0	-	1	0.025	0	-	-	-	-
"	6	0	0	-	1	.9844	0	-	-	-	-
"	7	0	1	1	1	0.05	19.7	-	-	-	-
"	8	0	1	1	1	1	19.7	-	-	-	-
"	9	3	0	-	1	1	0	.0910	0.09	0	50
"	10	3	1	1	1	0.95	0	.7218	0.7	0	5
"	11	1	1	1	1	0.8	5	0.5	-	-	2
"	12	1	1	1	1	0.05	5	0.5	-	-	2
"	13	1	1	1	1	0.2	5	0.5	-	-	2
"	14	1	1	1	1	0.05	0	0.2	-	-	5
"	15	1	1	1	1	0.2	0	0.2	-	-	5
"	16	1	0	-	1	0.1	0	0.1	-	-	10
"	17	1	0	-	1	0.25	0	0.1	-	-	10
"	18	0	1	4	1	1	19.3	-	-	-	0
"	19	0	1	4	1	0.8	19.3	-	-	-	0
ISOLATION (I)	1	0	-	-	1	1	0.5	-	-	-	-
"	2	1	-	-	1	0.99	0	0.04	-	-	25
"	3	0	-	-	1	0.8	20	-	-	-	-
RECOVERY (E)	1	1	-	-	1	1	-	1	-	-	10,000
"	2	3	-	-	1	1	-	1	.0063	0	200
RECOVERY (T)	1	1	-	-	1	.9999	-	1	-	-	10,000
"	2	3	-	-	1	.9999	-	1	0.023	-	200

Note: column heading mnemonics are defined on the second sheet of Table 5-6.

TABLE 5-5
FUNCTION SELECTIONS - BY FAULT SUBCLASS

Mechanism Number	Permanent Fault/Mode 1	Permanent Fault/Mode 2	Transient Fault/Mode 1	Transient Fault/Mode 2	Permanent Fault/Mode 0 (Transitional)
	D I E T	D I E T	D I E T	D I E T	D I E T
Subclass 1					
2	9 2 1 2	0 ---*	9 3 1 2	0 ---	9 2 1 2
3	11 1 1 1	11 1 2 2	0 ---	0 ---	11 1 1 1
5	2 1 1 1	2 1 1 2	2 1 1 1	2 1 1 2	2 1 1 1
6	3 1 1 1	3 1 1 2	3 1 1 1	3 1 1 2	3 1 1 1
Subclass 2					
2	9 2 1 2	0 ---	9 3 1 2	0 ---	9 2 1 2
3	12 2 1 1	12 2 2 2	0 ---	0 ---	12 2 1 1
4	10 1 1 1	10 1 2 2	0 ---	0 ---	10 1 1 1
5	16 2 1 1	16 2 1 2	16 3 1 1	16 3 1 2	16 2 1 1
6	17 2 1 1	17 2 2 2	17 3 1 1	17 3 2 2	17 2 1 1
7	2 1 1 1	2 1 1 2	2 1 1 1	2 1 1 2	2 1 1 1
8	4 2 1 1	4 2 2 2	0 ---	0 ---	4 2 1 1
9	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
10	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
12	7 2 1 1	7 2 2 2	0 ---	0 ---	7 2 1 1
Subclass 3					
1	1 1 1 1	1 1 1 2	1 1 1 1	1 1 1 2	1 1 1 1
2	9 2 1 2	0 ---	9 3 1 2	0 ---	9 2 1 2
3	12 2 1 1	12 2 2 2	0 ---	0 ---	12 2 1 1
4	14 2 1 1	14 2 2 2	0 ---	0 ---	14 2 1 1
5	16 2 1 1	16 2 1 2	16 3 1 1	16 3 1 2	16 2 1 1
8	18 1 1 1	18 1 2 2	18 3 1 1	18 3 2 2	18 1 1 1
9	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
10	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
12	7 2 1 1	7 2 2 2	0 ---	0 ---	7 2 1 1
Subclass 4					
2	9 2 1 2	0 ---	9 3 1 2	0 ---	9 2 1 2
3	13 2 1 1	13 2 2 2	0 ---	0 ---	13 2 1 1
4	15 2 1 1	15 2 2 2	0 ---	0 ---	15 2 1 1
5	16 2 1 1	16 2 1 2	16 3 1 1	16 3 1 2	16 2 1 1
6	3 1 1 1	3 1 1 2	3 1 1 1	3 1 1 2	3 1 1 1
8	19 1 1 1	19 1 2 2	0 ---	0 ---	19 1 1 1
9	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
10	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
11	6 1 1 1	6 1 1 2	6 1 1 1	6 1 1 2	6 1 1 1
12	8 1 1 1	8 1 2 2	0 ---	0 ---	8 1 1 1
Subclass 5					
3	11 1 1 1	11 1 2 2	0 ---	0 ---	11 1 1 1
6	3 1 1 1	3 1 1 2	3 1 1 1	3 1 1 2	3 1 1 1

*0 --- represents a null contribution to coverage. Accordingly, when setting up program input data, no entry need be provided.

TABLE 5-6

COVERAGE MODEL PARAMETERS

COVAGE Arguments

- ISU - Fault subclass number (1-8)
- MD - Mode of operation:
 - 1 for full up
 - 2 for degenerate
 - 0 for transitional (from MD = 1 to MD = 2)
- IET - Fault type code:
 - 1 for permanent
 - 2 for transient
- JS - Number of spare LRU's which must be checked out before recovery can proceed. (normally 0 or 1).

Basic Working Variables

- Function Pointer Arrays (Common Block CVB1).
 - NDET(20,8) - Detection rate function numbers
 - NISO(20,8) - Isolation rate function numbers
 - NEPR(20,8) - Error propagation recovery function numbers
 - NTLR(20,8) - Time lost recovery function numberswhere:
 - o 1st subscript is D/I/R mechanism
 - o 2nd subscript is fault subclass number
- Function Specification Arrays (Common Block CVB2)
 - FDET(7,200) - Detection function specifications
 - FISO(7,50) - Isolation function specifications
 - FEPR(7,25) - Error propagation recovery function specifications
 - FTLR(7,25) - Time lost recovery function specificationswhere:
 - o 1st subscript is word within a specification
 - o 2nd subscript is function number within the specification array.

TABLE 5-6 (Cont.)

Function Specification Element Descriptors

- - CODES - (Word #1) - contains 5 packed integer codes:
 - IGFT - Function Model Identifier (specifies a characteristic curve), (0 = impulse, 1 = constant, 2 = pulse train, 3 = decaying exponential), (0 not applicable for recovery)
 - ISCH - Scheduling code (0 = no, 1 = yes), (detectors only)
 - IREP - Repetition factor in minor cycles, (scheduled detectors only)
 - IDEF - Function defined flag (0 = no, 1 = yes), (set automatically when specifications are input)
 - INTF - Integral defined flag (0 = no, 1 = yes).
- COEF - (Word #2) - Explicit function multiplier
- TDEL - (Word #3) - Delay before the function becomes non-zero (must be zero for recovery functions)
- P1, P2, P3 - (Word #4, 5, 6) - Arbitrary parameters passed to the function model for evaluation. Note that if automatic normalization is requested by the user, all function models used by detection or isolation functions must use P1 as the normalizing coefficient
- TDUR - (Word #7) - Time during which the function is non-zero (must be zero for impulse functions).
- Computer System Dependent Variables (Common Blocks CVB0, CVB5 and CVB6)
 - PFDS(8) - Probability of detecting a failure in a spare LRU during initial checkout, for each of 8 fault subclasses
 - TFDS(8) - Time delay incurred in checking out a spare LRU, for each of 8 fault subclasses

TABLE 5-6 (Cont. -2)

- LCM - Least common multiple of the n_i 's where n_i is the repetition factor (where applicable) of the i th detector, expressed in terms of minor cycles, and automatically generated by CARE2
- TMINOR - Duration of a minor cycle, in units compatible with all rate functions
- IFSC(8) - Reliability model stage in which the a fault subclass is located, for each of 8 subclasses
- FRAC(8) - Fraction of total stage (class) faults which occur in a fault subclass, for each of 8 subclasses. (Used in conjunction with IFSC to specify the relationship between subclasses and stages, thus enabling calculation of stage coverage values on the basis of weighted average subclass coverages)

COVAGE Call Level Intermediate Variables

- NDSAV(20) - Detector rate function numbers
- NISAV(20) - Isolation rate function numbers
- NR1SAV(20) - Error Propagation recovery function numbers
- NR2SAV(20) - Time lost recovery function numbers
- ICHAR(20) - Characteristic of detection/recovery mechanism:
 - 0 if mechanism is inoperative
 - 1 if detector is unscheduled - impulse
 - 2 if detector is unscheduled - finite
 - 3 if detector is scheduled-impulse
 - 4 if detector is scheduled-finite
- IREPAR(20) - Repetition rate of detector (if applicable)

TABLE 5-6 (Cont. -3)

- PERIAR(20) - Period of repetition (if applicable) of detection functions
- TDELAR(20) - Delay times for detection functions
- PDIRAR(20) - Non-competitive probability of detection, isolation, and recovery, given that JS spares must be checked before recovery can proceed

- INDEX - Function of arguments IET and MD as follows:

<u>IET</u>	<u>MD</u>	<u>INDEX</u>
-	0	5
1	1	1
1	2	2
2	1	3
2	2	4

- GPFLG - Flag indicating the meaning of array CVGP:
when .FALSE., $GPAR = g'(i, \tau)$
when .TRUE., $GPAR = G'(i, \tau)$

D/I/R Evaluation Level Intermediate Variables

- IMPG (logical) - = .TRUE. when detector is an impulse
- IMPH (logical) - = .TRUE. when isolator is an impulse
- GPAR(N) - one row of the GPAR(20,N) array, which is alternately used to hold values of $g'(i, \tau)$ and $G'(i, \tau)$
- INDEX - (constant for COVAGE call) - function of MD and IET
- TGFIN - Last time at which $g(t)$ is non-zero
- THFIN - Last time at which $h(t')$ is non-zero
- TR1FIN - Last time at which $r'(\tau')$ is non-zero
- TR2FIN - Last time at which $r'(\tau + \tau')$ is non-zero

5.2 OPERATIONAL LIMITS

The numerical limits of CARE2 are shown in Table 5-7. Most of these are self explanatory, however particular attention is directed to the last item, entitled numerical integration steps. As noted, there are three independent step-size controls, applicable to the various integration algorithms, all of which use the Simpson 3-point parabolic integration scheme. (This standard numerical integration method was chosen because of its affinity for exponential curves).

For the dual mode model, the integrations performed in subprograms DCT and DCT2 divide the integrand into 3-point Simpson's Rule segments, with a base width of STEP time units. Optimal condition accuracy tests performed here show minor variation in the 8th decimal digit, given a T/STEP ratio of 10 or more.

The integrations performed in COVAGE, and its secondary subprograms, use a fixed number of 3-point segments controlled by NINT, and pre-determine the non-zero portion of the integrands for optimum efficiency. Since new function models, of any form, may be added to the current set (cf. section 4.2.4.21), it necessarily falls to the user to determine their accuracy. This may be accomplished by experimenting with NINT, which may be set at run time via control card ID in READIN2.

The last integration control is variable N in FINTEG (the coverage characteristic curve (function) integrator). N may be altered by recompiling FINTEG.

The user is encouraged to provide a corresponding integral model for each function model that is added, thereby precluding the need for numerical integration (cf. Section 4.2.4.15). Otherwise, the corresponding function specifications must be tagged as "integral not defined" (INTF=0), and the attendant inaccuracies of an additional integration contended with (cf. INTF discussion in section 4.2.4.9).



TABLE 5-7

OPERATIONAL LIMITATIONS

<u>Item</u>	<u>Upper Limit</u>	<u>Comment</u>
Stages per equation type		
- equations 1 thru 6	1	
- equation 7	8	
Stages per system	10	
Total Equations of type		
- 1 thru 6 per system	10	
- 7 per system	1	
Fault classes/subclasses		
- per stage (equations 1,4,5,6)	0	
- per stage (equations 2,3,7)	8	
- per system	8	
Fault types		
- equations 1 thru 6	1	(permanent)
- equation 7	2	(permanent and transient)
Fault rates per stage		
- equations 1,2,3,4	2	(on-line and standby)
- equations 5,6	1	(on-line)
- equation 7	3	(on-line, standby and transient)
Modes		
- equations 1,2,3,5,6	1	(full-up)
- equation 4	2	(triplex, simplex)
- equation 7	2	(full-up, degenerate)
Calculated Coverage types		
- equations 1,4,5,6	0	
- equations 2,3	1	(permanent)
- equation 7	5	(permanent modes 1 and 2, transient modes 1 and 2, transitional)



TABLE 5-7 (Cont.)

<u>Item</u>	<u>Upper Limit</u>	<u>Comment</u>
Detectors per fault subclass		
- equations 1,4,5,6	0	
- equations 2,3,7	20	
D/I/R mechanisms per system	20	
Function specifications per system		
- Detection	200	
- Isolation	50	
- Recovery type E	25	
- Recovery type T	25	
Function models	4096	(4 currently defined)
Variable parameters per function model	3	
Time steps	121	
Parameter variations in run-set	16	
Run-sets per batch run	No limit	
Finite K	$<10^5$	(higher value, specified as λ/μ , calls $K=\infty$ model)
Numerical integration steps		
- Equation 7	$2*[T/STEP]$	
- Coverage model	100	(may be changed between run-sets)
- Function models with undefined integrals	20	(may be increased w/o limit by changing data statement)

SECTION 6

EXAMPLES AND TEST CASE DATA

The test case data contained in this section was submitted to Langley Research Center, under separate cover, in compliance with Work Statement Paragraph 9.0. The sample problems so outlined were executed, first at the Raytheon computer facility and second at the Langley computer facility, in order to demonstrate both proper program execution and transferability between sites.

Test cases and data were selected on the combined basis of reflecting realistic problem input situations, and exercising both new interface code and new subroutines as supplied by Raytheon. In addition, the cases were chosen to serve as a tutorial base both for new users of CARE/CARE2 and also for those with previous experience in original CARE, but unfamiliar with the changes incorporated in the revised program.

Each of the listings is annotated in order to facilitate in its interpretation. In the interest of brevity, all but the first reliability plot has been deleted.

6.1 JOB #1 - PRODUCT OF EQUATIONS 4 AND 2

Specifics:

- The first stage is a hybrid/simplex configuration consisting of 3 active LRU's and 1 spare LRU.
- The second stage is a standby replacement configuration consisting of 2 series LRU's, each with a single dedicated spare LRU.
- Lambda, for both stages, equals 1.0×10^{-4} failures per hour per LRU.
- Mu, for the first stage, equals 1.0×10^{-4} failures per hour per LRU initially and then, in sequence, takes on the values 5.0×10^{-5} and 0.0 respectively.
- Mu, for the second stage, is held constant at 0.0.
- Mission time equals 3×10^4 hours.
- Time step (for print and plot purposes) equals 10^3 hours.
- Coverage and Voter Reliability are defaulted.
- Output request is for both tabular reliability print-out and plot.

6.2 JOB #2 - PRODUCT OF EQUATION 4 AND 2, WITH CALCULATED
COVERAGE

Specifics:

- Same as Job #1 except for Coverage values as related to permanent faults.
- Coverage for the second stage is to be calculated.

- Two stage 2 detectors are employed, each with the following characteristics:
 - Scheduled
 - Truncated exponential distribution
 - 95% detection probability
 - Run time of 0.01 seconds
 - One repetition per second
 - First delayed 0.0 seconds, second delayed 0.5 seconds
- Given detection of the fault, isolation and recovery probabilities are unity.

6.3 JOB #3 - DUAL MODE MODEL (DUAL CHANNEL) WITH PRESET COVERAGE

Specifics:

- Dual Channel configuration with two stages.
- Each stage has a single spare LRU.
- Spares reassignment, in the event of a single channel loss, is not allowed.
- Operation in degenerate mode (mode 2) is allowed, and requires one fully operational channel.
- Lambda, for both stages, is equal to 1×10^{-4} failures per hour.
- Mu, for both stages, is equal to 5.0×10^{-5} failures per hour.
- The transient error rate, for both stages, equals 1.1×10^{-5} per hour.
- Category 2 and 3 switch failure rates are 1.0×10^{-7} and 2.0×10^{-8} per hour respectively.

- Coverage values for the first stage are unity.
- Coverage values for the second stage, for full-up/
degenerate operation respectively, are:
 - Permanent - 0.999/0.98, with deltas of
0.999/0.998
 - Transitional - 0.999, with delta of 0.999
 - Transient - 0.99/0.95
- Mission time equals 10^4 hours.
- Time step equals 10^3 hours.
- Output request is for both tabular reliability
printout and plot.

6.4 JOB #4 - DUAL MODE MODEL (DUAL CHANNEL) WITH PRESET COVERAGE,
MULTIPLE RUNS WITHIN RUNSET, AND SPARES REASSIGNMENT

Specifics:

- Same as Job #3 except for run time variation in
spares quantity, and allowance of spares reassignment.
- Parameter selected for variation is the quantity of
spare LRU's associated with Stage 1.
- This quantity takes on the values 0, 1 and 2 for
runs 1, 2 and 3 respectively.
- Reassignment of spares, in the event of singular
channel loss, is allowed.

6.5 JOB #5 - DUAL MODE MODEL (DUAL CHANNEL) WITH CALCULATED
COVERAGE AND MULTIPLE RUNSETS

Specifics:

- Same as Job #3 except for Stage 2 coverage and multiple Stage 1 parameter variations.
- Lambda/Mu values, for the first stage, are as follows:
 - Run 1, Runset 1 - $1.0 \times 10^{-4} / 5.0 \times 10^{-5}$ failures per hour.
 - Run 2, Runset 1 - $1.0 \times 10^{-4} / 1.0 \times 10^{-4}$ failures per hour.
 - Run 1, Runset 2 - $1.0 \times 10^{-3} / 5.0 \times 10^{-4}$ failures per hour.
 - Run 2, Runset 2 - $1.0 \times 10^{-3} / 1.0 \times 10^{-3}$ failures per hour.
- Coverage, for Stage 2, is to be calculated based on the presence of Output Compare and CPU Selftest D/I/R mechanisms, using default data values.

6.6 JOB #6 - DUAL MODE MODEL (HYBRID CHANNEL) WITH CALCULATED
COVERAGE AND MULTIPLE RUNSETS

Specifics:

- The first stage requires 3 operating LRU's in mode 1, 2 in mode 2, and has 1 spare LRU.
- The second stage requires 1 operating LRU in both modes, and has 2 spare LRU's.
- The third stage requires 2 operating LRU's in mode 1, 1 in mode 2, and has 1 spare LRU.

- Lambda, for stages 1, 2 and 3, equals $1.0 \cdot 10^{-5}$, $2.5 \cdot 10^{-4}$ and $0.5 \cdot 10^{-4}$ failures per hour per LRU, respectively.
- K, for all stages, equals 2.0.
- Spares reassignment is allowed.
- Coverage values for the first stage, for mode 1/mode 2 operation respectively, are
 - Permanent - 0.998/0.99, with deltas of 0.995/0.99
 - Transitional - 0.996, with delta of 0.995
 - Transient - 0.99/0.97
- Coverage for the second stage is to be calculated based on the presence of CPU Selftest, Invalid Instruction and CPU Code, D/I/R mechanisms, using default data values.
- Coverage for the third stage is to be calculated assuming 2 fault subclasses, as described in succeeding line items.
- The first fault subclass accounts for 63% of LRU faults, and employs memory code as the sole D/I/R mechanism. Default data values are to be used.
- The second fault subclass accounts for 37% of LRU faults, and employs address feedback as the sole D/I/R mechanism. Default data values are to be used only where not over-ridden by the following:

- o Checkout time, for a spare, equals 0.1 seconds
- o Detection probability equals 0.9996
- o Isolation probability equals 0.99985 and has a pulse distribution of length 0.2 seconds
- o Error propagation recovery coefficient equals 0.96 for mode 2 operation
- A second run to be performed, in which CPU Selftest for Stage 2 is to be executed every 0.4 seconds.
- Mission time equals $16 \cdot 10^3$ hours.
- Time step equals $2 \cdot 10^3$ hours.
- Output request is for tabular reliability data only.

6.7 JOB #7 - PRODUCT OF EQUATIONS 7, 4 AND 2

Specifics:

- Run consists of producing a product reliability, assuming the configurations of Job #3 and Job #1 to be in series in a reliability block diagram.
- All data values are as defined in the respective jobs with the exception of Mission time, which is set equal to 10^4 hours for the combined configuration.

FIGURE 6-1
JOB #1 INPUT/OUTPUT LISTINGS

SOPTSON OUTPT1=T,OUTPT3=T,LPLOT=T,PRODT=TS

SVAR1 PROD(1)=4,2\$

SVAR T=3.0E4,STEP=1.0E3,OPTION=1\$

10000

100000

IB

SPARVEC Q(2)=1,Z(2)=2,S(1)=1,1,LAM(1)=2*1.0E-4,MU(1)=1.0E-4,0.0\$

IV 8

SVARY PARAM(1,1)=1.0E-4,5.0E-5,0.0, PARAM(1,2)=3*0.0\$

G

S

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

```

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION,
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.
                                OUTPT3= T
                                PRODT= T

SVARI
PROD      = 4, 2, 0, 0, 0, 0, 0, 0, 0, 0,
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS=
INPUT A 1 IN THE COLUMN SPECIFIED BELOW IF YOU WISH
THE CORRESPONDING PLOT OPTION, OTHERWISE INPUT 0.
NOTE: WHEN PERFORMING PRODUCT OF RELIABILITIES, NO OTHER
PLOT OPTION BESIDES PRODUCT OF RELIABILITIES MAY BE SPECIFIED.
COLUMN 1 - PLOTS PRODUCT OF RELIABILITIES
COLUMN 2 - PLOTS RELIABILITY
COLUMN 3 - PLOTS DIFF, RIF, AND GAIN
COLUMN 4 - PLOTS MTF AND RELIABILITY AT MTF
COLUMN 5 - PLOTS UNRELIABILITY
10000
FOR ABSCISSA, INPUT 1 IN COLUMN 1 IF ABSCISSA IS T,
1 IN COLUMN 2 IF ABSCISSA IS LOG(T) - BASE 10,
1 IN COLUMN 3 IF ABSCISSA IS LAMT,
1 IN COLUMN 4 IF ABSCISSA IS LOG(LAMT) - BASE 10,
1 IN COLUMN 5 IF ABSCISSA IS EXP(-LAMDA(T)),
1 IN COLUMN 6 IF ABSCISSA IS LOG(EXP(-LAMT)) - BASE 10.
100000
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
AND GAIN RESULTS -
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS -
                                OUTPT1= T
                                OUTPT2= F
                                OUTPT4= F
                                OUTPT5= F

                                LPL0T= T

```

FIGURE 6-1 (Cont.-3)

DATA BASE FOR RUN=SET

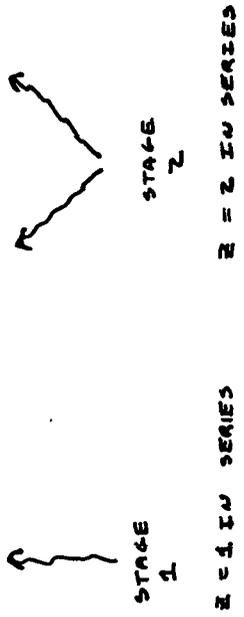
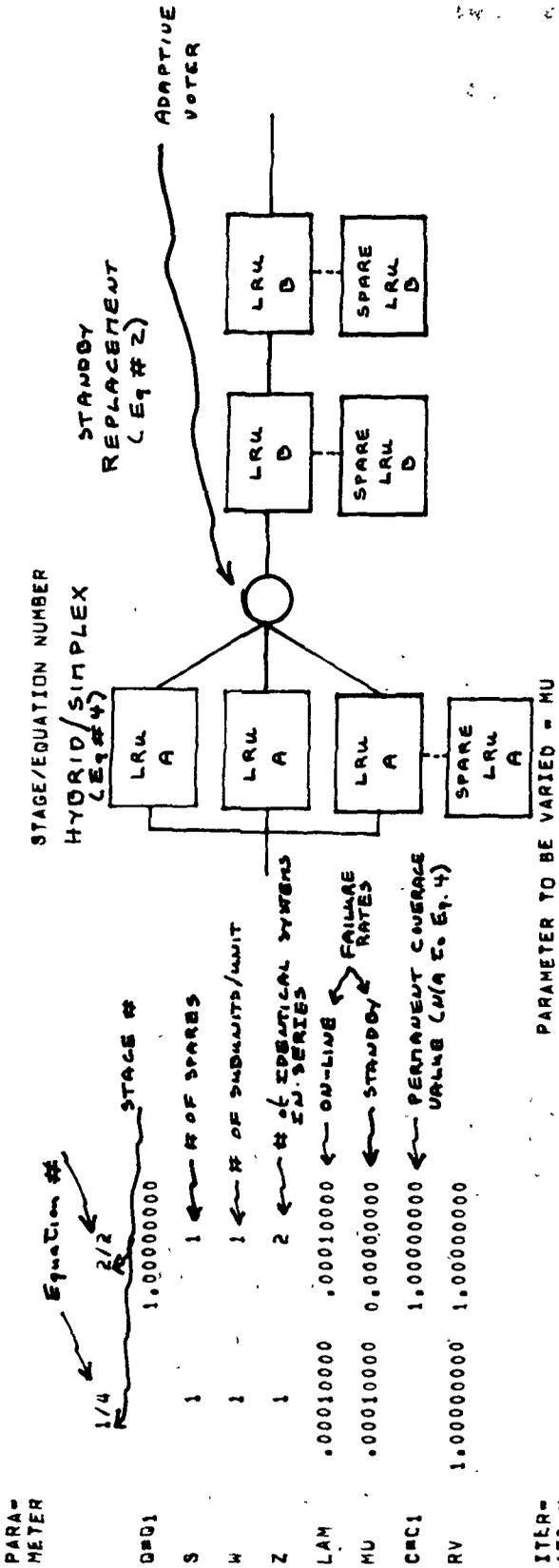


FIGURE 6-1 (Cont.-4)

VALUES OF μ USED ARE
AS SPECIFIED IN ITERATION
1 ABOVE

RUN 1 RELIABILITY RESULTS

STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF	RELIABILITY, ETC. OF FIRST STAGE AS FCT)
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35	
1000.000	.9983584	.0016416	.9048374	1.1033567E+00	5.7970848E+01	
2000.000	.9991672	.0108328	.8187308	1.2081715E+00	1.6733367E+01	
3000.000	.9986913	.0303087	.7408182	1.3089464E+00	8.5914083E+00	
4000.000	.9401482	.0598518	.6703200	1.4025363E+00	5.5082701E+00	
5000.000	.9021363	.0978637	.6065307	1.4873713E+00	4.0205844E+00	
6000.000	.8577434	.1422566	.5488116	1.5629105E+00	3.1716526E+00	
7000.000	.8050678	.1909322	.4965853	1.6292629E+00	2.6366152E+00	
8000.000	.7579842	.2420158	.4493290	1.6869249E+00	2.2753518E+00	
9000.000	.7060520	.2939480	.4065697	1.7366077E+00	2.0188277E+00	
10000.000	.6505004	.3454996	.3678794	1.7791165E+00	1.8295840E+00	
11000.000	.6042532	.3957468	.3328711	1.8152769E+00	1.6837467E+00	
12000.000	.5559707	.4440293	.3011942	1.8458878E+00	1.5737831E+00	
13000.000	.5100963	.4899037	.2725318	1.8716948E+00	1.4849209E+00	
14000.000	.4689006	.5310994	.2465976	1.8933755E+00	1.4132807E+00	
15000.000	.4285211	.5734789	.2231302	1.9115349E+00	1.3546615E+00	
16000.000	.3889951	.6110049	.2018965	1.9267053E+00	1.3062145E+00	
17000.000	.3542873	.6457127	.1826835	1.9393502E+00	1.2657588E+00	
18000.000	.3223112	.6776888	.1652989	1.9498691E+00	1.2316879E+00	
19000.000	.2929458	.7070342	.1495686	1.9586044E+00	1.2027810E+00	
20000.000	.2660485	.7339513	.1353353	1.9658475E+00	1.1780952E+00	
21000.000	.2414651	.7585349	.1224564	1.9718452E+00	1.1568928E+00	
22000.000	.2190362	.7809637	.1108032	1.9768097E+00	1.1385892E+00	
23000.000	.1988032	.8013988	.1002588	1.9809041E+00	1.1227161E+00	
24000.000	.1800105	.8199895	.0907180	1.9842871E+00	1.1088947E+00	
25000.000	.1631092	.8368908	.0820850	1.9870772E+00	1.0968158E+00	
26000.000	.1477581	.8522419	.0742736	1.9893766E+00	1.0862250E+00	
27000.000	.1338243	.8661757	.0672055	1.9912704E+00	1.0769115E+00	
28000.000	.1211841	.8788159	.0608101	1.9928291E+00	1.0686993E+00	
29000.000	.1097224	.8902776	.0550232	1.9941115E+00	1.0614406E+00	
30000.000	.0993335	.9006665	.0497871	1.9951659E+00	1.0550108E+00	

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF	RELIABILITY, ETC. OF SECOND STAGE AS FCT)
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35	
1000.000	.9986642	.0093358	.9048374	1.0948533E+00	1.0193309E+01	
2000.000	.9652609	.0347391	.8187308	1.1789723E+00	5.2180129E+00	
3000.000	.9274917	.0725083	.7408182	1.2519828E+00	3.5745101E+00	
4000.000	.8806848	.1193152	.6703200	1.3138273E+00	2.7631003E+00	
5000.000	.8277287	.1722713	.6065307	1.3646940E+00	2.2840104E+00	
6000.000	.7710572	.2289428	.5488116	1.4049578E+00	1.9707470E+00	
7000.000	.7126652	.2873348	.4965853	1.4351319E+00	1.7520149E+00	
8000.000	.6541447	.3458553	.4493290	1.4558298E+00	1.5922007E+00	
9000.000	.5987290	.4032710	.4065697	1.4677165E+00	1.4715483E+00	
10000.000	.5433411	.4586599	.3678794	1.4715178E+00	1.3781933E+00	
11000.000	.4886419	.5113581	.3328711	1.4679615E+00	1.3046219E+00	
12000.000	.4390749	.5609251	.3011942	1.4577800E+00	1.2458094E+00	
13000.000	.3929072	.6070928	.2725318	1.4416932E+00	1.1982818E+00	
14000.000	.3502660	.6497340	.2465970	1.4203985E+00	1.1595560E+00	
15000.000	.3111692	.6888308	.2231302	1.3945635E+00	1.1278093E+00	
16000.000	.2755525	.7244475	.2018965	1.3648205E+00	1.1016719E+00	
17000.000	.2432911	.7567089	.1826835	1.3317629E+00	1.0800937E+00	

18000.000	.2142180	.7857820	.1632989	1.2959433E+00	1.0622555E+00
19000.000	.1881382	.8118618	.1495686	1.2578721E+00	1.0475076E+00
20000.000	.1648407	.8351593	.1353353	1.2180175E+00	1.0353292E+00
21000.000	.1441075	.8558925	.1224564	1.1768063E+00	1.0252965E+00
22000.000	.1257200	.8742800	.1108032	1.1348243E+00	1.0170618E+00
23000.000	.1094645	.8905355	.1002588	1.0918188E+00	1.0103372E+00
24000.000	.0951359	.9048641	.0907180	1.0486995E+00	1.0048824E+00
25000.000	.0822399	.9174601	.0820650	1.0055412E+00	1.0004958E+00
26000.000	.0714947	.9285053	.0742736	9.6258597E-01	9.9700712E-01
27000.000	.0619320	.9381680	.0672055	9.2009347E-01	9.9427833E-01
28000.000	.0533972	.9466028	.0608101	8.7809730E-01	9.9216893E-01
29000.000	.0460491	.9539509	.0550232	8.3699318E-01	9.9059269E-01
30000.000	.0396600	.9603400	.0497871	7.96559309E-01	9.8945474E-01

SYSTEM RELIABILITY (E PRODUCT OF
STAGE RELIABILITIES) AS FCT)

T	REL PRODUCT
0.000	1.0000000
1000.000	.9890380
2000.000	.9548044
3000.000	.8993806
4000.000	.8279742
5000.000	.7467241
6000.000	.6613692
7000.000	.5765945
8000.000	.4958314
9000.000	.4213217
10000.000	.3543080
11000.000	.2952634
12000.000	.2441128
13000.000	.2004205
14000.000	.1635394
15000.000	.1327202
16000.000	.1071886
17000.000	.0861950
18000.000	.0690449
19000.000	.0551143
20000.000	.0436556
21000.000	.0347969
22000.000	.0275372
23000.000	.0217400
24000.000	.0171255
25000.000	.0134630
26000.000	.0105639
27000.000	.0082746
28000.000	.0064709
29000.000	.0050526
30000.000	.0039396

FIGURE 6-1 (Cont.-7)

*0001000000000000000000000000000000
 00009987654332211000000000000000
 0000950356802504063197643322111

CONTENTS OF CHANNELS FOR HISTOGRAM A FOLLOW

*1000000000000000000000000000000000
 0998876543322211000000000000000000
 085924679259406308654322110000
 0949761651454032769534717308653
 0083973583321457110188571452409
 0408727932161242994160443667754

CONT
 UF
 CHAN

PRODUCT OF RELIABILITY VS MISSION TIME T
 PLOT FOR EQUATIONS 4 2

LAMBDA MU (NI MEANS NOT INPUTED OR DEFAULT VALUE USED) C RV Z W P MUT

1 PLOT(S) COMPLETED

FIGURE 6-1 (Cont.-8)

WITH SECOND VALUE OF μ

RUN 2 RELIABILITY RESULTS

STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9985462	.0014538	.9048374	1.1035642E+00	6.5458799E+01
2000.000	.9902986	.0097014	.8187308	1.2095334E+00	1.8684824E+01
3000.000	.9725751	.0274249	.7408182	1.3128390E+00	9.4505842E+00
4000.000	.9453251	.0546749	.6703200	1.4102935E+00	6.0298192E+00
5000.000	.9098163	.0901837	.6065307	1.5000335E+00	4.3629757E+00
6000.000	.8678538	.1321462	.5488116	1.5813326E+00	3.4143109E+00
7000.000	.8213362	.1786638	.4965853	1.6539681E+00	2.8176655E+00
8000.000	.7720221	.2279779	.4493290	1.7181669E+00	2.4154884E+00
9000.000	.7214221	.2785779	.4065697	1.7744120E+00	2.1302132E+00
10000.000	.6707658	.3292342	.3678794	1.8233305E+00	1.9199724E+00
11000.000	.6210096	.3789904	.3328711	1.8656198E+00	1.7602790E+00
12000.000	.5728642	.4271358	.3011942	1.9019761E+00	1.6360272E+00
13000.000	.5268314	.4731686	.2725318	1.9331006E+00	1.5374396E+00
14000.000	.4832409	.5167591	.2465970	1.9596385E+00	1.4579386E+00
15000.000	.4422859	.5577141	.2231302	1.9821879E+00	1.3929935E+00
16000.000	.4040534	.5959466	.2018965	2.0012898E+00	1.3392199E+00
17000.000	.3685508	.6314492	.1826835	2.0174277E+00	1.2943503E+00
18000.000	.3357268	.6642732	.1652989	2.0310266E+00	1.2565629E+00
19000.000	.3054889	.6945111	.1495686	2.0424664E+00	1.2245036E+00
20000.000	.2777170	.7222830	.1353353	2.0520663E+00	1.1971273E+00
21000.000	.2522737	.7477263	.1224864	2.0601098E+00	1.1736160E+00
22000.000	.2290121	.7709879	.1108032	2.0668376E+00	1.1533214E+00
23000.000	.2077822	.7922178	.1002588	2.0724572E+00	1.1357244E+00
24000.000	.1884343	.8115657	.0907180	2.0771449E+00	1.1204048E+00
25000.000	.1708230	.8291770	.0820850	2.0810503E+00	1.1070194E+00
26000.000	.1548084	.8451916	.0742736	2.0843003E+00	1.0952899E+00
27000.000	.1402580	.8597420	.0672055	2.0870021E+00	1.0849703E+00
28000.000	.1270472	.8729528	.0608101	2.0892460E+00	1.0758771E+00
29000.000	.1150595	.8849405	.0550232	2.0911080E+00	1.0678422E+00
30000.000	.1041870	.8958130	.0497871	2.0926518E+00	1.0607269E+00

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9906642	.0093358	.9048374	1.0948533E+00	1.0193309E+01
2000.000	.9852609	.0347391	.8187308	1.1789723E+00	5.2180129E+00
3000.000	.9274917	.0725083	.7408182	1.2519828E+00	3.5749101E+00
4000.000	.8806848	.1193152	.6703200	1.3138273E+00	2.7631003E+00
5000.000	.8277287	.1722713	.6065307	1.3646940E+00	2.2840104E+00
6000.000	.7710572	.2289428	.5488116	1.4049578E+00	1.9707470E+00
7000.000	.7126652	.2873348	.4965853	1.4351315E+00	1.7520145E+00
8000.000	.6541447	.3458553	.4493290	1.4558258E+00	1.5922007E+00
9000.000	.5967290	.4032710	.4065697	1.4677169E+00	1.4715423E+00
10000.000	.5413411	.4586589	.3678794	1.4715178E+00	1.3781933E+00
11000.000	.4886419	.5113581	.3328711	1.4679615E+00	1.3046219E+00
12000.000	.4390749	.5609251	.3011942	1.4577800E+00	1.2458094E+00
13000.000	.3929072	.6070928	.2725318	1.4416932E+00	1.1982818E+00
14000.000	.3502660	.6497340	.2465970	1.4203985E+00	1.1595560E+00
15000.000	.3111692	.6888308	.2231302	1.3945635E+00	1.1278093E+00
16000.000	.2755525	.7244475	.2018965	1.3648208E+00	1.1016719E+00
17000.000	.2432911	.7567089	.1826835	1.3317629E+00	1.0800937E+00

FIGURE 6-1 (Cont.-9)

18000.000	.2142180	.7857820	.1652989	1.2959433E+00	1.0622553E+00
19000.000	.1861382	.8118618	.1495686	1.2578721E+00	1.0473076E+00
20000.000	.1648407	.8351593	.1353353	1.2180175E+00	1.0353292E+00
21000.000	.1441075	.8558925	.1224564	1.1768063E+00	1.0252965E+00
22000.000	.1257200	.8742800	.1108032	1.1346243E+00	1.0170618E+00
23000.000	.1094645	.8905355	.1002588	1.0918188E+00	1.0103372E+00
24000.000	.951359	.9048641	.0907180	1.0486995E+00	1.0048824E+00
25000.000	.825399	.9174601	.0820850	1.0055412E+00	1.0004958E+00
26000.000	.714947	.9285053	.0742736	9.6258557E-01	9.9700712E-01
27000.000	.618320	.9381680	.0672055	9.2004347E-01	9.9427233E-01
28000.000	.531392	.9466028	.0608101	8.7809730E-01	9.9216893E-01
29000.000	.460491	.9539509	.0550232	8.3690318E-01	9.9059269E-01
30000.000	.3966600	.9603400	.0497871	7.9659309E-01	9.8949474E-01

T
REL. PRODUCT

0.000	1.0000000
1000.000	.9892240
2000.000	.9558965
3000.000	.9020553
4000.000	.8325334
5000.000	.7530811
6000.000	.6691649
7000.000	.5853378
8000.000	.5050142
9000.000	.4304935
10000.000	.3631131
11000.000	.3034513
12000.000	.2515303
13000.000	.2069959
14000.000	.1692628
15000.000	.1376257
16000.000	.1113379
17000.000	.0896651
18000.000	.0719187
19000.000	.0574741
20000.000	.0457791
21000.000	.0363545
22000.000	.0287914
23000.000	.0227448
24000.000	.0179269
25000.000	.0140997
26000.000	.0110680
28000.000	.0086724
29000.000	.0067840
30000.000	.0052984
	.0041321

FIGURE 6-1 (Cont.-10)

RUN 3 RELIABILITY RESULTS

WITH THIRD VALUE
OF μ

STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9987387	.0012613	.9048374	1.1037769E+00	7.5046916E+01
2000.000	.9914862	.0085138	.8187308	1.2110039E+00	2.1891182E+01
3000.000	.9756726	.0243274	.7408182	1.3170202E+00	1.0653893E+01
4000.000	.9510108	.0489892	.6703200	1.4187414E+00	6.7296472E+00
5000.000	.9184337	.0815663	.6065307	1.5142411E+00	4.8239183E+00
6000.000	.8794336	.1205664	.5488116	1.6024324E+00	3.7422368E+00
7000.000	.8356671	.1643329	.4965853	1.6828270E+00	3.0633844E+00
8000.000	.7887312	.2112688	.4493290	1.7553355E+00	2.6064946E+00
9000.000	.7400474	.2599526	.4065697	1.8202229E+00	2.2828406E+00
10000.000	.6908143	.3091857	.3678794	1.8778280E+00	2.0444690E+00
11000.000	.6419988	.3580012	.3328711	1.9286708E+00	1.8634821E+00
12000.000	.5943496	.4056504	.3011942	1.9733102E+00	1.7226800E+00
13000.000	.5484224	.4515776	.2725318	2.0123245E+00	1.6109483E+00
14000.000	.5046080	.4953920	.2465970	2.0462663E+00	1.5208219E+00
15000.000	.4631614	.5368386	.2231302	2.0757453E+00	1.4471199E+00
16000.000	.4242286	.5757714	.2018965	2.1012180E+00	1.3861464E+00
17000.000	.3878703	.6121297	.1826635	2.1231816E+00	1.3352015E+00
18000.000	.3540820	.6459180	.1652989	2.1420713E+00	1.2922710E+00
19000.000	.3228109	.6771891	.1495686	2.1582798E+00	1.2558256E+00
20000.000	.2939697	.7060303	.1353353	2.1721585E+00	1.2246850E+00
21000.000	.2674772	.7325528	.1224564	2.1840195E+00	1.1979254E+00
22000.000	.2431174	.7568826	.1108032	2.1941381E+00	1.1748148E+00
23000.000	.2206458	.7791542	.1002588	2.2027564E+00	1.1547665E+00
24000.000	.2004945	.7995055	.0907180	2.2100857E+00	1.1373055E+00
25000.000	.1819258	.8180742	.0820850	2.2163103E+00	1.1220437E+00
26000.000	.1650054	.8349946	.0742736	2.2215897E+00	1.1086616E+00
27000.000	.1496056	.8503964	.0672055	2.2260621E+00	1.0968938E+00
28000.000	.1355971	.8644029	.0608101	2.2298466E+00	1.0865187E+00
29000.000	.1228694	.8771306	.0550232	2.2330457E+00	1.0773501E+00
30000.000	.1113113	.8886887	.0497871	2.2357472E+00	1.0692303E+00

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9906642	.0093358	.9048374	1.0948533E+00	1.0193309E+01
2000.000	.952609	.037391	.8187308	1.1789723E+00	5.2180129E+00
3000.000	.8274917	.0725083	.7408182	1.2519828E+00	3.5745101E+00
4000.000	.8086848	.1193152	.6703200	1.3138273E+00	2.7631003E+00
5000.000	.8277287	.1722713	.6065307	1.3646940E+00	2.2840104E+00
6000.000	.7710572	.2289428	.5488116	1.4049578E+00	1.9707470E+00
7000.000	.7126652	.2873348	.4965853	1.4351315E+00	1.7520149E+00
8000.000	.6541447	.3458553	.4493290	1.4558258E+00	1.5922007E+00
9000.000	.5967290	.4032710	.4065697	1.4677165E+00	1.4715423E+00
10000.000	.5413411	.4586589	.3678794	1.4715178E+00	1.3781933E+00
11000.000	.4886419	.5113581	.3328711	1.4679615E+00	1.3046219E+00
12000.000	.4390749	.5609251	.3011942	1.4577800E+00	1.2458094E+00
13000.000	.3929072	.6070928	.2725318	1.4416932E+00	1.1982818E+00
14000.000	.3502660	.6497340	.2465970	1.4203985E+00	1.1595560E+00
15000.000	.3111692	.6888308	.2231302	1.3945635E+00	1.1278093E+00
16000.000	.2755525	.7244475	.2018965	1.3648205E+00	1.1016719E+00
17000.000	.2432911	.7567089	.1826635	1.3317629E+00	1.0800937E+00

FIGURE 6-1 (Cont.-11)

16000.000	.2142180	.7657620	.1652989	1.2999433E+00	1.0622553E+00
19000.000	.1881382	.8118618	.1495686	1.2378721E+00	1.0475076E+00
20000.000	.1648407	.8351993	.1353353	1.2180175E+00	1.0353292E+00
21000.000	.1441075	.8558925	.1224564	1.1768063E+00	1.0252965E+00
22000.000	.1257200	.8742800	.1108032	1.1346243E+00	1.0170618E+00
23000.000	.1094645	.8905355	.1002588	1.0918188E+00	1.0103372E+00
24000.000	.0951359	.9048641	.0907180	1.0486995E+00	1.0048824E+00
25000.000	.0825399	.9174601	.0820850	1.0055412E+00	1.0004958E+00
26000.000	.0714947	.9285033	.0742736	9.6256557E-01	9.9700712E-01
27000.000	.0618320	.9381680	.0672055	9.2004347E-01	9.9427233E-01
28000.000	.0533972	.9466028	.0608101	8.7809730E-01	9.9216893E-01
29000.000	.0460491	.9539509	.0550232	8.3690318E-01	9.9059269E-01
30000.000	.0396600	.9603400	.0497871	7.9659309E-01	9.8945474E-01

T	REL PRODUCT
0.000	1.0000000
1000.000	.9894147
2000.000	.9570428
3000.000	.9049282
4000.000	.8375407
5000.000	.7602139
6000.000	.6780936
7000.000	.5955509
8000.000	.5159443
9000.000	.4416077
10000.000	.3739662
11000.000	.3137075
12000.000	.2609640
13000.000	.2154791
14000.000	.1767470
15000.000	.1441215
16000.000	.1168972
17000.000	.0943654
18000.000	.0758507
19000.000	.0607331
20000.000	.0484582
21000.000	.0385411
22000.000	.0305647
23000.000	.0241748
24000.000	.0190742
25000.000	.0150161
26000.000	.0117970
27000.000	.0092503
28000.000	.0072405
29000.000	.0056580
30000.000	.0044146

FIGURE 6-2
JOB #2 INPUT/OUTPUT LISTINGS

\$OPTSON OUTPT1=T,OUTPT3=T,COVINT=T,PRODT=T,COVPRC=TS

\$VAR1 PRUD(1)=4,2\$

\$VAR T=3.0E4,STEP=1.0E3,OPTION=1\$

\$COVVAL IGENC(2)=1,IFSC(1)=2,FRAC(1)=1.0\$

ID

\$DATA PFDS(1)=1.0,TFDS(1)=0.0,TMINOR=1.0\$

IB

\$PARVEC Q(2)=1,Z(2)=2,S(1)=1,1,LAM(1)=2*1.0E-4,MU(1)=1.0E-4,0.0\$

IV 8

\$VARY PARAM(1,1)=1.0E-4,5.0E-5,0.0,PARAM(1,2)=3*0.0\$

F	D	1	311	1	0.95	0.0	1.0	100.0	0.0	0.01
F	D	2	311	1	0.95	0.5	1.0	100.0	0.0	0.01
F	I	1	010		1.0	0.0	1.0	0.0	0.0	0.0



FIGURE 6-2 (Cont.-2)

F E	1	110	1.0	0.0	1.0	0.0	0.0	100.0
F T	1	110	1.0	0.0	1.0	0.0	0.0	100.0
C D	1	111	1					
C D	2	111	2					
C I	1	111	50					
C E	1	111	50					
C T	1	111	50					
PC								
N								
PF								
G								
S								

FIGURE 6-2 (Cont.-4)

COVERAGE FUNCTION SPECIFICATIONS

PROBABILITY OF DETECTING FAULT IF THIS WERE THE ONLY DETECTOR

FUNCTION PARAMETERS -
FOR THIS FUNCTION (TYPE #3)
 $M = P1 (E - P1MT + P2)$

FUNCTION NUMBER	IGFT	INTF	ISCH	IREP	COEF	TDEL	P1	P2	TOUR
1	3	1	1	1	.95000	0.	1.5820E+02	1.0000E+02	0.
2	3	1	1	1	.95000	5.0000E+01	1.5820E+02	1.0000E+02	0.

FUNCTION TYPE (3 = DECAYING EXPONENTIAL) = ISOLATION = ZERO OFFSET OF FUNCTION ON TIME SCALE

FUNCTION NUMBER	IGFT	INTF	COEF	TDEL	P1	P2	TOUR
1	0	1	1.00000	0.	1.0000E+00	0.	0.

FUNCTION TYPE (0 = FAULT PROPAGATION RECOVERY = IMPULSE)

FUNCTION NUMBER	IGFT	INTF	COEF	P1	P2	P3	TOUR
1	1	1	1.00000	1.0000E+00	0.	0.	1.0000E+02

FUNCTION TYPE (4 = CONSTANT)

FUNCTION NUMBER	IGFT	INTF	COEF	P1	P2	P3	TOUR
1	1	1	1.00000	1.0000E+00	0.	0.	1.0000E+02

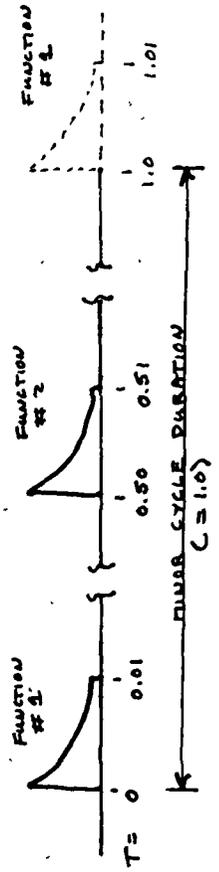
COVERAGE CONTRIBUTIONS MECHANISM CONTRIBUTION

1 .49875
2 .49875

OPERATING MODE OF SYSTEM:
1 FOR FULLY OPERATIONAL
2 FOR DEGRADED
3 FOR TRANSITIONAL
4 FOR PERMANENT, 2 FOR TRANSIENT FAULT
OF SPARES CHECKED BETWEEN FAULT TIME AND RECOVERY TIME (A CONSTANT)
DURATION OF CONSTANT = 100 TIME UNITS (I.E. A PULSE)

IN THIS SITUATION, FAULT ISOLATION AND RECOVERY PROCESSES WERE DEFINED TO BE PERFECT. THUS COVERAGE = DETECTION PROBABILITY. GIVEN TWO DETECTORS, IN COMPETITION, EACH WITH DETECTION PROBABILITY OF 0.95 (COEF VALUE) AND GIVEN A SYMMETRICAL SCHEDULE AS BELOW, THEN TOTAL DETECTION CAPABILITY = COVERAGE = $1 - (1 - 0.95)^2 = 0.9975$, WITH EACH MECHANISM CONTRIBUTING HALF OR 0.49875

TWO EQUAL (EXCEPT FOR DELAY TIME) DETECTORS ARE DEFINED. WITH RESPECT TO THE MINOR CYCLE, THEY APPEAR AS FOLLOWS:



VIEW IS OF DETECTION RATE FUNCTION
C AREA = 1.0 FOR ALL DETECTORS AND ISOLATORS (DETECTION OCCURS ONLY WHEN NON-ZERO)

PARAMETER STAGE/EQUATION NUMBER

Q=01	1/4	2/2	1.00000000
S	1	1	
W	1	1	
Z	1	2	
LAH	.00010000	.00010000	
MU	.00010000	0.00000000	
CRCI		.99750000	
HV	1.00000000	1.00000000	

NOTE THAT, GIVEN A STAGE COMPRISED OF 2 IDENTICAL SUBSTAGES IN SERIES, COVERAGE FOR EACH OF THE SUBSTAGES, AS WELL AS FOR THE STAGE AS A WHOLE, IS A SINGLE VALUE. THUS, THE COMPUTED VALUE OF C APPLIED EQUALLY, IN THIS EXAMPLE, TO EACH OF THE TWO SUBSTAGES AND TO THE ENTIRE STAGE. NOTE ALSO THAT THE SAME REASONING APPLIES TO NON-UNITY VALUES OF W.

PARAMETER TO BE VARIED = MU

ITERATION	1	.00010000	0.00000000
	2	5.0000E-05	0.
	3	0.00000000	0.00000000

THESE VALUES ARE COMPUTED VIA ITERATIONS OF THE EQUATION SHOWN IN SECTION 3.2.3. THEY ARE THEN SUMMED, AS PER THE EQUATION IN 3.2.2, TO FORM SUBCLASS COVERAGES FOR THE STATED CONDITIONS (ISK=1, ND=1, ETC.). STAGE COVERAGE, IN TURN, IS COMPUTED VIA THE FIRST EQUATION IN SECTION 3.2, BY MEANS OF WEIGHTING AND TOTALING APPLICABLE SUBCLASS COVERAGES, AND IS THEN PRINTED OUT HERE.

NOTE THAT IN THIS PARTICULAR EXAMPLE, THE USER HAS SPECIFIED C AS INDICATED BY THE LINKAGE TABLE ON PAGE 6-2(i) THAT THE STAGE CONTAINS ONLY ONE FAULT SUBCLASS. AS A CONSEQUENCE, SUBCLASS AND STAGE COVERAGES ARE EQUAL. IN A LESS TRIVIAL SITUATION, THIS IS FREQUENTLY NOT THE CASE.

RUN 1 RELIABILITY RESULTS

STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIP
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.993584	.0016416	.9048374	1.1033567E+00	5.7970848E+01
2000.000	.9891672	.0108328	.8187308	1.2081719E+00	1.6733367E+01
3000.000	.9866913	.0303087	.7408182	1.3089464E+00	8.5514083E+00
4000.000	.9401482	.0598518	.6703200	1.4029533E+00	5.5082701E+00
5000.000	.9021363	.0978637	.6065307	1.4873713E+00	4.0205844E+00
6000.000	.8574334	.1422566	.5488116	1.5629105E+00	3.1716526E+00
7000.000	.8090678	.1909322	.4965853	1.6292625E+00	2.6366192E+00
8000.000	.7579842	.2420158	.4493290	1.6869249E+00	2.2753918E+00
9000.000	.7050520	.2939480	.4065697	1.7366077E+00	2.0188277E+00
10000.000	.6545004	.3454996	.3678794	1.7791165E+00	1.8295840E+00
11000.000	.6042532	.3957468	.3328711	1.8152769E+00	1.6857467E+00
12000.000	.5559707	.4440293	.3011942	1.8458878E+00	1.5737831E+00
13000.000	.5100963	.4899037	.2725318	1.8716948E+00	1.4849209E+00
14000.000	.4690006	.5330994	.2465970	1.8933755E+00	1.4132507E+00
15000.000	.4285211	.5734789	.2231302	1.9115349E+00	1.3546612E+00
16000.000	.3889951	.6110049	.2018965	1.9267053E+00	1.3062143E+00
17000.000	.352873	.6457127	.1826835	1.9393502E+00	1.2657588E+00
18000.000	.3223112	.6776888	.1652989	1.9498691E+00	1.2316879E+00
19000.000	.2929458	.7070542	.1495686	1.9586044E+00	1.2027810E+00
20000.000	.2660485	.7339515	.1353353	1.9658475E+00	1.1780952E+00
21000.000	.2414651	.7585349	.1224564	1.9718452E+00	1.1568928E+00
22000.000	.2190363	.7809637	.1108032	1.9768057E+00	1.1385892E+00
23000.000	.1986032	.8013968	.1002588	1.9809041E+00	1.1227161E+00
24000.000	.1800105	.8199895	.0907180	1.9842874E+00	1.1088947E+00
25000.000	.1631092	.8368908	.0820850	1.9870772E+00	1.0968158E+00
26000.000	.1477581	.8522419	.0742736	1.9893766E+00	1.0862250E+00
27000.000	.1338243	.8661737	.0672055	1.9912704E+00	1.0769115E+00
28000.000	.1211841	.8788159	.0608101	1.9928291E+00	1.0686993E+00
29000.000	.1097224	.8902776	.0550232	1.9941115E+00	1.0614406E+00
30000.000	.0993335	.9006665	.0497871	1.9951659E+00	1.0550108E+00

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIP
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9902140	.0097860	.9048374	1.0943557E+00	9.7243202E+00
2000.000	.9644566	.0355434	.8187308	1.1779900E+00	5.0999482E+00
3000.000	.9264218	.0735782	.7408182	1.2505386E+00	3.5225345E+00
4000.000	.8794271	.1205729	.6703200	1.3119511E+00	2.7342790E+00
5000.000	.8263498	.1736502	.6065307	1.3624204E+00	2.2658728E+00
6000.000	.7696121	.2303879	.5488116	1.4023247E+00	1.9583859E+00
7000.000	.7111987	.2888013	.4965853	1.4321784E+00	1.7431100E+00
8000.000	.6526919	.3473081	.452925E+00	1.4525925E+00	1.5659403E+00
9000.000	.5933165	.4046835	.4065697	1.4642424E+00	1.4664061E+00
10000.000	.5399886	.4600114	.3678794	1.4678413E+00	1.4664061E+00
11000.000	.4873630	.5126370	.3328711	1.4641193E+00	1.3013671E+00
12000.000	.4378782	.5621218	.3011942	1.4538069E+00	1.2431973E+00
13000.000	.3917976	.6082024	.2725318	1.4376217E+00	1.1960956E+00
14000.000	.3492451	.6507549	.2465970	1.4162587E+00	1.1577370E+00
15000.000	.3102364	.6897636	.2231302	1.3903829E+00	1.1262841E+00
16000.000	.2747053	.7252947	.2018965	1.3606242E+00	1.1003851E+00
17000.000	.2425258	.7574742	.1826835	1.3275736E+00	1.0790024E+00

FIGURE 6-2 (Cont.-7)

18000.000	.2135300	.7864700	.1652989	1.2917811E+00	1.0613260E+00
19000.000	.1675224	.8124776	.1495686	1.2537548E+00	1.0467136E+00
20000.000	.1642917	.8357083	.1353353	1.2139609E+00	1.0346490E+00
21000.000	.1436198	.8563802	.1224564	1.1728237E+00	1.0247126E+00
22000.000	.1252882	.8747118	.1108032	1.1307274E+00	1.0165598E+00
23000.000	.1090834	.8909166	.1002388	1.0880173E+00	1.0099050E+00
24000.000	.0948004	.9051996	.0907180	1.0450015E+00	1.0045100E+00
25000.000	.0822453	.9177547	.0820850	1.0019532E+00	1.0001747E+00
26000.000	.0716066	.9287633	.0742736	9.5911271E-01	9.9673023E-01
27000.000	.0616066	.9383934	.0672055	9.1668962E-01	9.9403351E-01
28000.000	.0532006	.9467994	.0608101	8.7486519E-01	9.9196297E-01
29000.000	.0458781	.9541219	.0550232	8.3379451E-01	9.9041510E-01
30000.000	.0395114	.9604886	.0497871	7.9360867E-01	9.8930167E-01

T
REL PRODUCT

0.000	1.0000000
1000.000	.9885885
2000.000	.9540089
3000.000	.8983432
4000.000	.8267918
5000.000	.7454801
6000.000	.6601298
7000.000	.5754080
8000.000	.4947301
9000.000	.4203244
10000.000	.3534228
11000.000	.2944906
12000.000	.2434475
13000.000	.1998545
14000.000	.1630628
15000.000	.1323224
16000.000	.1068590
17000.000	.0859238
18000.000	.0688231
19000.000	.0549339
20000.000	.0437096
21000.000	.0346792
22000.000	.0274427
23000.000	.0216643
24000.000	.0170651
25000.000	.0134150
26000.000	.0105258
27000.000	.0082445
28000.000	.0064471
29000.000	.0050339
30000.000	.0039248

RUN 2 RELIABILITY RESULTS

STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9985462	.0014538	.9048374	1.1035642E+00	6.5458759E+01
2000.000	.9902986	.0097014	.8187308	1.2095534E+00	1.8684834E+01
3000.000	.9725751	.0274249	.7408182	1.3128390E+00	9.4505842E+00
4000.000	.9453251	.0546749	.6703200	1.4102593E+00	6.0298192E+00
5000.000	.9098163	.0901837	.6065307	1.5000335E+00	4.3629757E+00
6000.000	.8678538	.1321462	.5488116	1.5813326E+00	3.4143109E+00
7000.000	.8213362	.1786638	.4965853	1.6539681E+00	2.8176639E+00
8000.000	.7720221	.2279779	.4493290	1.7181669E+00	2.4154584E+00
9000.000	.7214221	.2785779	.4065697	1.7744120E+00	2.1302132E+00
10000.000	.6707658	.3292342	.3678794	1.8233309E+00	1.9199724E+00
11000.000	.6210096	.3789904	.3328711	1.8656158E+00	1.7602790E+00
12000.000	.5728642	.4271358	.3011942	1.9019761E+00	1.6360272E+00
13000.000	.5268314	.4731688	.2725318	1.9331006E+00	1.5374396E+00
14000.000	.4832409	.5167591	.2465970	1.9596385E+00	1.4579386E+00
15000.000	.4422859	.5577141	.2231302	1.9821879E+00	1.3929535E+00
16000.000	.4040534	.5959466	.2012898E+00	2.0012898E+00	1.3392199E+00
17000.000	.3685508	.6314492	.1822683	2.0174277E+00	1.2943503E+00
18000.000	.3357268	.6642732	.1652989	2.0310286E+00	1.2565629E+00
19000.000	.3054889	.6945111	.1495686	2.0424664E+00	1.2245036E+00
20000.000	.2777170	.7222830	.1353353	2.0520663E+00	1.1971273E+00
21000.000	.2522737	.7477263	.1224564	2.0601095E+00	1.1736160E+00
22000.000	.2290121	.7709879	.1108032	2.0668376E+00	1.1533214E+00
23000.000	.2077822	.7922178	.1002588	2.0724572E+00	1.1357244E+00
24000.000	.1884343	.8115657	.0907180	2.0771449E+00	1.1204048E+00
25000.000	.1708230	.8291770	.0820850	2.0810503E+00	1.1070194E+00
26000.000	.1548084	.8451916	.0742736	2.0840003E+00	1.0952859E+00
27000.000	.1402580	.8597420	.0672055	2.0870021E+00	1.0849703E+00
28000.000	.1270472	.8729528	.0608101	2.0892460E+00	1.0758771E+00
29000.000	.1150595	.8849405	.0550232	2.0911080E+00	1.0678422E+00
30000.000	.1041870	.8958130	.0497871	2.0926518E+00	1.0607269E+00

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9902140	.0097860	.9048374	1.0943557E+00	9.7243202E+00
2000.000	.9844566	.0355434	.8187308	1.1779900E+00	5.0999482E+00
3000.000	.9264218	.0735782	.7408182	1.2505386E+00	3.9225345E+00
4000.000	.8794271	.1205729	.6703200	1.3119511E+00	2.7342790E+00
5000.000	.8263498	.1736502	.6065307	1.3624204E+00	2.2658728E+00
6000.000	.7696121	.2303879	.5488116	1.4023247E+00	1.9583859E+00
7000.000	.7111987	.2888013	.4965853	1.4321784E+00	1.7431180E+00
8000.000	.6526919	.3473081	.4493290	1.4525925E+00	1.5855403E+00
9000.000	.5933165	.4046835	.4065697	1.4642424E+00	1.4664061E+00
10000.000	.5399886	.4600114	.3678794	1.4678413E+00	1.3741412E+00
11000.000	.4873630	.5126370	.3328711	1.4641193E+00	1.3013671E+00
12000.000	.4378782	.5621218	.3011942	1.4538069E+00	1.2431573E+00
13000.000	.3917976	.6082024	.2725318	1.4376217E+00	1.1960956E+00
14000.000	.3492451	.6507349	.2465970	1.4162587E+00	1.1577370E+00
15000.000	.3102364	.6897636	.2231302	1.3903829E+00	1.1262841E+00
16000.000	.2747053	.7252947	.2018965	1.3606242E+00	1.1003851E+00
17000.000	.2425258	.7574742	.1826835	1.3275736E+00	1.0790024E+00

FIGURE 6-2 (Cont.-9)

18000.000	.2135300	.7864700	.1652989	1.2917811E+00	1.0613260E+00
19000.000	.1875224	.8124776	.1495686	1.2537548E+00	1.0467136E+00
20000.000	.1642917	.8357083	.1353353	1.2139609E+00	1.0346490E+00
21000.000	.1436198	.8563802	.1224564	1.1728237E+00	1.0247126E+00
22000.000	.1252882	.8747118	.1108032	1.1307274E+00	1.0165598E+00
23000.000	.1090834	.8909166	.1002588	1.0880173E+00	1.0099050E+00
24000.000	.0948004	.9051996	.0907180	1.0450015E+00	1.0045100E+00
25000.000	.0822453	.9177547	.0820850	1.0019532E+00	1.0001747E+00
26000.000	.0712367	.9287633	.0742736	9.5911271E-01	9.9673023E-01
27000.000	.0616066	.9383934	.0672055	9.1668962E-01	9.9403351E-01
28000.000	.0532006	.9467994	.0608101	8.7486519E-01	9.9196297E-01
29000.000	.0459781	.9541219	.0550232	8.3379451E-01	9.9041510E-01
30000.000	.0395114	.9604886	.0497871	7.9360867E-01	9.8930167E-01

REL PRODUCT

Y	0.000
1000.000	1.0000000
2000.000	.9887744
3000.000	.9551001
4000.000	.9010147
5000.000	.8313445
6000.000	.7518265
7000.000	.6679108
8000.000	.5841333
9000.000	.5038926
10000.000	.4294745
11000.000	.3622059
12000.000	.3026571
13000.000	.2508448
14000.000	.2064113
15000.000	.1687695
16000.000	.1372132
17000.000	.1109956
18000.000	.0893831
19000.000	.0716877
20000.000	.0572860
21000.000	.0456266
22000.000	.0362315
23000.000	.0286925
24000.000	.0226656
25000.000	.0178636
26000.000	.0140494
27000.000	.0110280
28000.000	.0086408
29000.000	.0067590
30000.000	.0052787
	.0041166

RUN 3 RELIABILITY RESULTS

STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9987387	.0012613	.9048374	1.1037769E+00	7.50446916E+01
2000.000	.9914862	.0085138	.8187308	1.2110039E+00	2.1291123E+01
3000.000	.9756726	.0243274	.7408182	1.3170202E+00	1.0653893E+01
4000.000	.9510108	.0488892	.6703200	1.4187414E+00	6.7296472E+00
5000.000	.9184337	.0815663	.6065307	1.5142411E+00	4.8239183E+00
6000.000	.8794336	.1205664	.5488116	1.6024324E+00	3.7422388E+00
7000.000	.8356671	.1643329	.4965853	1.6828270E+00	3.0653384E+00
8000.000	.7887312	.2112688	.4493290	1.7553535E+00	2.6064946E+00
9000.000	.7400474	.2599526	.4065697	1.8202229E+00	2.2828406E+00
10000.000	.6908143	.3091857	.3678794	1.8778280E+00	2.0444690E+00
11000.000	.6419988	.3580012	.3328711	1.9286708E+00	1.8634821E+00
12000.000	.5943496	.4056504	.3011942	1.9733102E+00	1.7226800E+00
13000.000	.5484224	.4515776	.2725318	2.0132324E+00	1.6109485E+00
14000.000	.5046080	.4953920	.2465970	2.0482863E+00	1.5208219E+00
15000.000	.4631614	.5368386	.2211302	2.0757453E+00	1.4471199E+00
16000.000	.4242286	.5757714	.2018965	2.1012180E+00	1.3861464E+00
17000.000	.3878703	.6121297	.1826835	2.1231816E+00	1.3352015E+00
18000.000	.3540820	.6459180	.1652989	2.1420713E+00	1.2922710E+00
19000.000	.3228109	.6771891	.1495686	2.1582798E+00	1.2558256E+00
20000.000	.2939697	.7060303	.1353353	2.1721585E+00	1.2246850E+00
21000.000	.2674472	.7325528	.1224564	2.1840195E+00	1.1979254E+00
22000.000	.2431174	.7568826	.1108032	2.1941381E+00	1.1748148E+00
23000.000	.2208458	.7791524	.1002588	2.2027564E+00	1.1547665E+00
24000.000	.2004945	.7995055	.0907180	2.2100857E+00	1.1373055E+00
25000.000	.1819258	.8180742	.0820850	2.2163103E+00	1.1220437E+00
26000.000	.1650054	.8349946	.0742736	2.2215897E+00	1.1086616E+00
27000.000	.1496036	.8503964	.0672055	2.2260621E+00	1.0968938E+00
28000.000	.1355971	.8644029	.0608101	2.2298466E+00	1.0865187E+00
29000.000	.1228694	.8771306	.0550232	2.2330457E+00	1.0773501E+00
30000.000	.1113113	.8886887	.0497871	2.2357472E+00	1.0692303E+00

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9902140	.0097860	.9048374	1.0943557E+00	9.7243202E+00
2000.000	.9644566	.0355434	.8187308	1.1779900E+00	5.0999482E+00
3000.000	.9254218	.0735782	.7408182	1.2505386E+00	3.5225345E+00
4000.000	.8794271	.1205729	.6703200	1.3119511E+00	2.7342790E+00
5000.000	.8253498	.1736502	.6065307	1.3624204E+00	2.2658728E+00
6000.000	.7696121	.2303879	.5488116	1.4023247E+00	1.9583859E+00
7000.000	.7111987	.2888013	.4965853	1.4321784E+00	1.7431180E+00
8000.000	.6526919	.3473081	.4493290	1.4525925E+00	1.5655403E+00
9000.000	.5933165	.4046835	.4065697	1.4642424E+00	1.4664061E+00
10000.000	.5399886	.4600114	.3678794	1.4678413E+00	1.3741412E+00
11000.000	.4873630	.5126370	.3328711	1.4641193E+00	1.3013671E+00
12000.000	.4378782	.5621218	.3011942	1.4538069E+00	1.2431573E+00
13000.000	.3917976	.6082024	.2725318	1.4376217E+00	1.1960956E+00
14000.000	.3482451	.6507549	.2465970	1.4162567E+00	1.1577370E+00
15000.000	.3082364	.6897636	.2211302	1.3903829E+00	1.1262841E+00
16000.000	.2747053	.7252947	.2018965	1.3606242E+00	1.1003851E+00
17000.000	.2425258	.7574742	.1826835	1.3275736E+00	1.0790024E+00

FIGURE 6-2 (Cont.-11)

18000.000	.2135300	.7864700	.1652989	1.2917811E+00	1.0613260E+00
19000.000	.1875254	.8124776	.1495686	1.2537548E+00	1.0467136E+00
20000.000	.1642917	.8357083	.1353353	1.2139609E+00	1.0346490E+00
21000.000	.1436198	.8563802	.1224564	1.1728237E+00	1.0247126E+00
22000.000	.1252882	.8747118	.1108032	1.1307274E+00	1.0165598E+00
23000.000	.1090834	.8909166	.1002588	1.0880173E+00	1.0099050E+00
24000.000	.0948004	.9051996	.0907180	1.0450015E+00	1.0045100E+00
25000.000	.0822453	.9177547	.0820850	1.0019332E+00	1.0001747E+00
26000.000	.0712367	.9287633	.0742736	9.5911271E-01	9.9673023E-01
27000.000	.0616086	.9383934	.0672055	9.166882E-01	9.9403351E-01
28000.000	.0532006	.9467994	.0608101	8.7486519E-01	9.9196297E-01
29000.000	.0458781	.9541219	.0550232	8.3379451E-01	9.9041510E-01
30000.000	.0395114	.9604886	.0497871	7.9360867E-01	9.8930167E-01

REL PRODUCT

T	0.000
1000.000	1.0000000
2000.000	.9889650
3000.000	.9562454
4000.000	.9038843
5000.000	.8363447
6000.000	.7589474
7000.000	.6768227
8000.000	.5943254
9000.000	.5147984
10000.000	.4405624
11000.000	.3730319
12000.000	.3128864
13000.000	.2602528
14000.000	.2148706
15000.000	.1762319
16000.000	.1436895
17000.000	.1165378
18000.000	.0940686
19000.000	.0756071
20000.000	.0605343
21000.000	.0482968
22000.000	.0384107
23000.000	.0304597
24000.000	.0240906
25000.000	.0190070
26000.000	.0149625
27000.000	.0117544
28000.000	.0092166
29000.000	.0072138
30000.000	.0056370
	.0043981

FIGURE 6-3
JOB #3 INPUT/OUTPUT LISTINGS

```
$OPTSON OUTPT1=T,OUTPT3=T,LPLOT=T,PRODT=T,STGOUT=TS  
  
$VAR1 PRD(1)=7,7$  
  
$VAR T=1.0E4,STEP=1.0E3,OPTION=1$  
  
10000  
  
100000  
  
IB  
  
$PARVEC Q1(1)=2,2, Q2(1)=1,1, S(1)=1,1,  
  
LAM(1)=2*1.0E-4, MU(1)=2*5.0E-5, GMP(1)=2*1.1E-5,  
  
C1(1)=1.0,0.999,CD1(1)=1.0,0.999,C2(1)=1.0,0.98,CD2(1)=1.0,0.998,  
  
CTR(1)=1.0,0.999,CDTR(1)=1.0,0.999,PRC1(1)=1.0,0.99,PRC2(1)=1.0,0.95$  
  
ID  
  
$DATA SLH2=1.0E-7, SLH3=2.0E-8, RSGN=FS  
  
G  
  
S
```

FIGURE 6-3 (Cont.-2)

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

```

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.
                                OUTPUT3= T
                                PRODT=  T

SVARI
PRDD  = 7, 7, 0, 0, 0, 0, 0, 0, 0, 0.
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS=
INPUT A 1 IN THE COLUMN SPECIFIED BELOW IF YOU WISH
THE CORRESPONDING PLOT OPTION, OTHERWISE INPUT 0.
NOTE: WHEN PERFORMING PRODUCT OF RELIABILITIES, NO OTHER
PLOT OPTION BESIDES PRODUCT OF RELIABILITIES
COLUMN 1 = PLOTS PRODUCT OF RELIABILITIES
COLUMN 2 = PLOTS RELIABILITY
COLUMN 3 = PLOTS DIFF, RIF, AND GAIN
COLUMN 4 = PLOTS MTF AND RELIABILITY AT MTF
COLUMN 5 = PLOTS UNRELIABILITY
10000
FOR ABSCISSA, INPUT 1 IN COLUMN 1 IF ABSCISSA IS T,
1 IN COLUMN 2 IF ABSCISSA IS LOG(T) - BASE 10,
1 IN COLUMN 3 IF ABSCISSA IS LAHT,
1 IN COLUMN 4 IF ABSCISSA IS LOG(LAHT) - BASE 10,
1 IN COLUMN 5 IF ABSCISSA IS EXP(-LAMBDA(T)),
1 IN COLUMN 6 IF ABSCISSA IS LOG(EXP(-LAHT)) - BASE 10.
10000
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
AND GAIN RESULTS =
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS =
                                OUTPUT1= T
                                OUTPUT2= F
                                OUTPUT4= F
                                OUTPUT5= F

                                LPLDT=  T

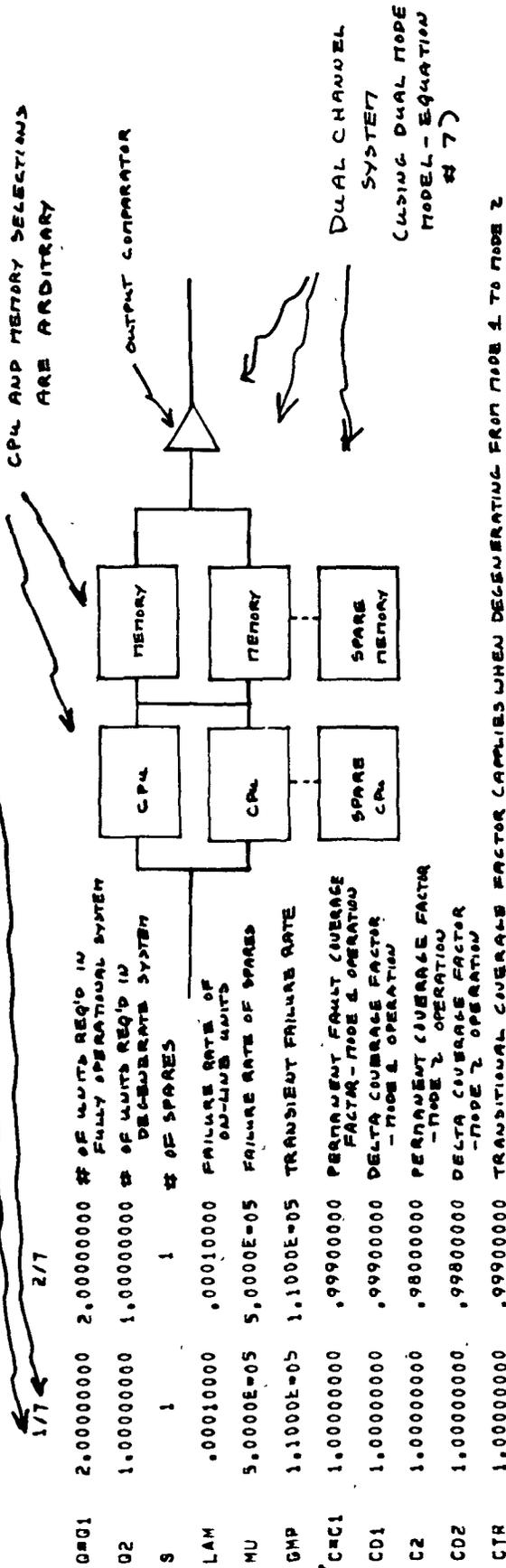
```

FIGURE 6-3 (Cont.-3)

DATA BASE FOR RUN-SET

PARAMETER

STAGE/EQUATION NUMBER



0M01	2.0000000	2.0000000	# OF UNITS REQ'D IN FULLY OPERATIONAL SYSTEM
02	1.0000000	1.0000000	# OF UNITS REQ'D IN DEGENERATE SYSTEM
S	1	1	# OF SPARES
LAM	.0001000	.0001000	FAILURE RATE OF ON-LINE UNITS
MU	5.000E+05	5.000E+05	FAILURE RATE OF SPARES
GMP	1.1000E+05	1.1000E+05	TRANSIENT FAILURE RATE
CRC1	1.0000000	.9990000	PERMANENT FAULT COVERAGE FACTOR - MODE 1 OPERATION
CD1	1.0000000	.9990000	DELTA COVERAGE FACTOR - MODE 1 OPERATION
C2	1.0000000	.9800000	PERMANENT COVERAGE FACTOR - MODE 2 OPERATION
CD2	1.0000000	.9980000	DELTA COVERAGE FACTOR - MODE 2 OPERATION
CTR	1.0000000	.9990000	TRANSITIONAL COVERAGE FACTOR APPLIES WHEN DEGENERATING FROM MODE 1 TO MODE 2
CDTH	1.0000000	.9990000	DELTA TRANSITIONAL COVERAGE FACTOR (U)
PRC1	1.0000000	.9900000	TRANSIENT COVERAGE FACTOR - MODE 1 OPERATION
PRC2	1.0000000	.9500000	" " " " " " " "

DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES	2	FAILURE RATE OF HARDWARE (E.G. SWITCHES) WHICH WOULD TAKE OUT ENTIRE CHANNEL
CHANNEL FAILURE RATE	.00000010	"SINGLE POINT" FAILURE RATE (E.G. COMPARTOR) COVERAGE VALUE TO BE APPLIED IN EVENT OF CHANNEL LOSS DUE TO "SWITCH" FAILURE
SYSTEM FAILURE RATE	.00000002	F (FALSE) SPECIFIED THAT, GIVEN THE LOSS OF A SINGLE CHANNEL, ITS UNITS WHICH ARE STILL FUNCTIONAL CANNOT BE USED AS SPARES FOR THE REMAINING CHANNEL
CHANNEL FAILURE COV.	1.00000000	T (TRUE) = F
REASSIGNMENT SWITCH	F	

ALL COVERAGE VALUES ARE PRE-ASSIGNED, NOT COMPUTED

COMPUTED BY 2ND EQUATION IN SECTION 3.1.7
 COMPUTED BY 3RD EQUATION IN SECTION 3.1.7
 DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.9569892	.9784506	.9781833
2000.000	.8558788	.9254776	.9250189
3000.000	.7295625	.8545920	.8540043
4000.000	.6000171	.7751271	.7744604
5000.000	.4799951	.6933780	.6926714
6000.000	.3756112	.6134504	.6127336
7000.000	.2887028	.5378990	.5371840
8000.000	.2186291	.4681415	.4674637
9000.000	.1635062	.4048975	.4042575
10000.000	.1209855	.3483364	.3477407

SYSTEM AND COMPONENT STAGE RELIABILITIES, AT TIME T, IF DEGENERATE SYSTEM OPERATION NOT ALLOWED. USEFUL INFORMATION ONLY FOR SYSTEM ANALYSIS WORK.

COMPUTED BY 1ST EQUATION IN SECTION 3.1.7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9980114	.0019886	.8187308	1.2189739E+00	9.1153913E+01
2000.000	.9870321	.0129679	.6703200	1.4724788E+00	2.5422673E+01
3000.000	.9616920	.0383080	.5488116	1.7523171E+00	1.1779244E+01
4000.000	.9208261	.0791739	.4493290	2.0493361E+00	6.9552050E+00
5000.000	.8662972	.1337028	.3678794	2.3548400E+00	4.7278046E+00
6000.000	.8015662	.1984338	.3011942	2.6612936E+00	3.5216072E+00
7000.000	.7305658	.2694342	.2465970	2.9625905E+00	2.7962415E+00
8000.000	.6569852	.3430148	.2018965	3.2540691E+00	2.3267320E+00
9000.000	.5839004	.4160996	.1652989	3.5323914E+00	2.0060127E+00
10000.000	.5136460	.4863540	.1353353	3.7953991E+00	1.7778505E+00

IDENTIFIES LAST STAGE IN THE SYSTEM, IN THE CASE OF DUAL CHANNEL IF IT READ STAGES 1-2 IN THIS CASE.

DATE: DUAL CHANNEL SYSTEMS MUST START IN STAGE POSITION "1" ALWAYS. THEY MAY "EXTEND" FROM THERE THRU STAGE POSITION 8, WHERE DESIRED

REL PRODUCT

T	REL PRODUCT
0.000	1.000000
1000.000	.9980114
2000.000	.9870321
3000.000	.9616920
4000.000	.9208261
5000.000	.8662972
6000.000	.8015662
7000.000	.7305658
8000.000	.6569852
9000.000	.5839004
10000.000	.5136460

THIS IS THE DUAL CHANNEL SYSTEM RELIABILITY WITH ALL COVERAGES, PERMANENT STRANDED FAILURE RATES, OPERATING MODES, WITH FAILURES, ET AL. TAKEN INTO ACCOUNT

SAME AS REL COLUMN DIRECTLY ABOVE UNLESS ADDITIONAL "SYSTEMS" ARE IN SERIES

FIGURE 6-4

JOB #4 INPUT/OUTPUT LISTINGS

\$OPTSON OUTPT1=T, OUTPT3=T, PRODT=T, LSTCH=T, STGOUT=TS

\$VAR1 PRUD(1)=7,7\$

\$VAR T=1.0E4, STEP=1.0E3, OPTION=1\$

IB

\$PARVEC Q1(1)=2,2, Q2(1)=1,1, S(1)=0,1,

LAM(1)=2*1.0E-4, MU(1)=2*5.0E-5, GMP(1)=2*1.1E-5,

C1(1)=1.0,0.999,CD1(1)=1.0,0.999,C2(1)=1.0,0.98,CD2(1)=1.0,0.998,

CTR(1)=1.0,0.999,CDTR(1)=1.0,0.999,PRC1(1)=1.0,0.99,PRC2(1)=1.0,0.95\$

ID

\$DATA SLH2=1.0E-7, SLH3=2.0E-8, RSGN=TS

IV 4

\$VARY PARAM(1,1)=0,1,2\$

G

S

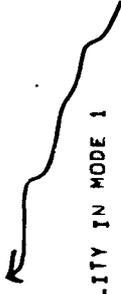
FIGURE 6-4 (Cont.-2)

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.
SVARI
PROD = 7, 7, 0, 0, 0, 0, 0, 0, 0, 0,
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS =
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
AND GAIN RESULTS =
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS =
OUTPUT3= T
PRODT= T
LPLOT= F
OUTPUT1= T
OUTPUT2= F
OUTPUT4= F
OUTPUT5= F

FIGURE 6-4 (Cont.-4)

RUN 1 RELIABILITY RESULTS



DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.8007727	.8187308	.9781833
2000.000	.6199099	.6703200	.9250189
3000.000	.4685188	.5488116	.8540043
4000.000	.3478205	.4493290	.7744604
5000.000	.2546667	.3678794	.6926714
6000.000	.1844190	.3011942	.6127336
7000.000	.1323567	.2465970	.5371840
8000.000	.0942887	.2018965	.4674637
9000.000	.0667512	.1652989	.4042575
10000.000	.0470051	.1353353	.3477407

0 SPARES IN
STAGE 1

STAGE 2 EQUATION NUMBER 7

T	HEL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9897248	.0102752	.8187308	1.2088526E+00	1.7641424E+01
2000.000	.9612376	.0387624	.6703200	1.4339981E+00	8.5051571E+00
3000.000	.9178250	.0821750	.5488116	1.6723862E+00	5.4903791E+00
4000.000	.8632186	.1367814	.4493290	1.9211283E+00	4.0259207E+00
5000.000	.8010786	.1989214	.3678794	2.1775575E+00	3.1777408E+00
6000.000	.7346907	.2653093	.3011942	2.4392590E+00	2.6339288E+00
7000.000	.6668183	.3331817	.2465970	2.7040817E+00	2.2612380E+00
8000.000	.5996600	.4003400	.2018965	2.9701352E+00	1.9935640E+00
9000.000	.5348707	.4651293	.1652989	3.2357790E+00	1.7945570E+00
10000.000	.4736201	.5263799	.1353353	3.4996058E+00	1.6426630E+00

HEL PRODUCT

T	HEL PRODUCT
0.000	1.000000
1000.000	.8097248
2000.000	.6612376
3000.000	.5178250
4000.000	.4032186
5000.000	.3010786
6000.000	.2346907
7000.000	.1868183
8000.000	.1596600
9000.000	.1348707
10000.000	.11736201

RUN 2 RELIABILITY RESULTS

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.9569892	.9784906	.9781833
2000.000	.8558788	.9254776	.9250189
3000.000	.7295625	.8545920	.8540043
4000.000	.6000171	.7751271	.7744604
5000.000	.4799951	.6933780	.6926714
6000.000	.3756112	.6134504	.6127336
7000.000	.2887028	.5378890	.5371840
8000.000	.2186291	.4681415	.4674637
9000.000	.1635062	.4048975	.4042575
10000.000	.1209855	.3483364	.3477407

2 SPARE IN
STAGE 1

STAGE 2 EQUATION NUMBER 7

T	REL PRODUCT	HEL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9982021	.9982021	.0017979	.8167308	1.2192068E+00	1.0082331E+02
2000.000	.9891514	.9891514	.0108486	.6703200	1.4756405E+00	5.0389128E+01
3000.000	.9692395	.9692395	.0307605	.5488116	1.7660696E+00	1.4667793E+01
4000.000	.9376641	.9376641	.0623359	.4493290	2.0868098E+00	8.8339292E+00
5000.000	.8953913	.8953913	.1046087	.3678794	2.4339259E+00	6.0427147E+00
6000.000	.8443679	.8443679	.1556321	.3011942	2.8034000E+00	4.4901123E+00
7000.000	.7869564	.7869564	.2130436	.2465970	3.1912657E+00	3.5363800E+00
8000.000	.7255572	.7255572	.2744428	.2018965	3.5937081E+00	2.9080864E+00
9000.000	.6623751	.6623751	.3376249	.1652989	4.0071360E+00	2.4722737E+00
10000.000	.5992955	.5992955	.4007045	.1353353	4.4282277E+00	2.1578610E+00

NOTE THE IMPROVEMENT IN RELIABILITY DUE TO THE ENABLING OF SPARES CANDIDATING (OR RE-ASSIGNMENT). COMPARE THIS COLUMN WITH THAT OF JOB # 3.

FOR EXAMPLE, AT T = 10,000, SYSTEM RELIABILITY HAS GONE FROM 0.514 TO 0.599

NOTE ALSO THAT THE EFFECT IS MUCH LESS PROMINENT FOR THIS SYSTEM, AT A MORE REASONABLE VALUE OF T. FOR EXAMPLE, AT T = 1000, SYSTEM RELIABILITY HAS GONE FROM 0.99801 TO 0.99820

FIGURE 6-4 (Cont.-6)

RUN 3 RELIABILITY RESULTS



DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.9760362	.9979247	.9761833
2000.000	.9120174	.9861812	.9250189
3000.000	.8204658	.9610739	.8540043
4000.000	.7143059	.9227700	.7744604
5000.000	.6046012	.8733781	.6926714
6000.000	.4994950	.8157782	.6127336
7000.000	.4041299	.7529441	.5371840
8000.000	.3211105	.6875805	.4674637
9000.000	.2511594	.6219571	.4042575
10000.000	.1937580	.5578600	.3477407

2 SPARES IN
STAGE 1

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	STMRIFF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.0000000E+39
1000.000	.9988644	.0011156	.8187308	1.2200401E+00	1.6248047E+02
2000.000	.9935286	.0064714	.6703200	1.4821705E+00	5.0944188E+01
3000.000	.9809743	.0190257	.5486116	1.7874516E+00	2.3714626E+01
4000.000	.9596347	.0403653	.4493290	2.1357064E+00	1.3642205E+01
5000.000	.9291321	.0708679	.3678794	2.5256429E+00	8.9197040E+00
6000.000	.8900379	.1099621	.3011942	2.9550299E+00	6.3549688E+00
7000.000	.8435820	.1564180	.2465970	3.4208936E+00	4.8165995E+00
8000.000	.7913770	.2086230	.2018965	3.9197160E+00	3.6255779E+00
9000.000	.7351865	.2648135	.1652989	4.4476193E+00	3.1520341E+00
10000.000	.6767479	.3232521	.1353353	5.0005282E+00	2.6748928E+00

REL PRODUCT

T	REL PRODUCT
0.000	1.000000
1000.000	.9988844
2000.000	.9935286
3000.000	.9809743
4000.000	.9596347
5000.000	.9291321
6000.000	.8900379
7000.000	.8435820
8000.000	.7913770
9000.000	.7351865
10000.000	.6767479

FIGURE 6-5
JOB #5 INPUT/OUTPUT LISTINGS

\$OVRTON OUTPT1=T, OUTPT3=T, PRODT=T, LSTCH=T, COVPRC=T, STGOUT=TS

\$VAR1 PROD(1)=7,7\$

\$VAR T=1.0E4, STEP=1.0F3, OPTION=1\$

\$COVCAL COVINT=T, IGENC(2)=1, IGENP(2)=1, IFSC(2)=2, FRAC(2)=1.0\$

IB

\$PARVEC Q1(1)=2,2, Q2(1)=1,1, S(1)=1,1,

LAM(1)=2*1.0E-4, MU(1)=2*5.0E-5, GMP(1)=2*1.1E-5\$

ID

\$DATA SLH2=1.0E-7, SLH3=2.0E-8, RSGN=F, TMINOR=1000.0\$

IV 8

\$VARY PARAM(1,1)=5.0E-5,1.0E-4\$

F	D	9	310	1.0	0.0	.091011	.09	0.0	50.0
F	D	10	311	1	.95	.721796	.7	0.0	5.0
F	I	1	01	1.0	0.5				
F	I	2	11	.99	0.0	.04			25.0
F	I	3	01	0.8	0.0				

FIGURE 6-5 (Cont.-2)

F E	1	11	1.0	1.0			10000.0
F E	2	31	1.0	1.0	.00625	0.0	200.0
F T	1	11	.9999	1.0			10000.0
F T	2	31	.9999	1.0	.023	0.0	200.0

M

2	2	9	2	1	2	9	3	1	2	9	2	1	2
2	4	10	1	1	1	10	1	2	2	10	1	1	1

W

PC

N

PF

G

IB

SPARVEC LAM(1)=1.0E-3S

IV 8

SVARY PARAM(1,1)=5.0E-4,1.0E-3S

G

S

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
 QUESTIONS PRINTED BACK FOR VERIFICATION,
 DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
 THE PRODUCT OF THE PRIMARY EQUATIONS.

SVAR1 = 7, 7, 0, 0, 0, 0, 0, 0, 0,
 PROD SEND

DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS=
 DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
 DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
 AND GAIN RESULTS =
 DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
 DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
 TIME CALCULATIONS =

OUTPT1= T

PRODT= T

LPLDT= F

OUTPT1= T

OUTPT2= F

OUTPT4= F

OUTPT5= F

COVERAGE DATA BASE

- FAULT SUBCLASS LINKAGE AND PARAMETERS -

NAME	SYSTEM CONFIGURATION	FAULT SUBCLASS	LINKED TO STAGE	FRACTION OF FAULT RATE	PROB. OF FAULT DET. IN SPARES	TIME FOR FAULT DET. IN SPARES
AS JOB # 3, Out with		1	0	0.000000	1.000000	0.000000
CALCULATED, RATHER THAN		2	2	1.000000	1.000000	0.000000
PRESET, COVERAGE FOR		3	0	0.000000	1.000000	0.000000
STAGE 2		4	0	0.000000	1.000000	0.000000
		5	0	0.000000	1.000000	0.000000
		6	0	0.000000	1.000000	0.000000
		7	0	0.000000	1.000000	0.000000
		8	0	0.000000	1.000000	0.000000

MINOR CYCLE DURATION (FOR SCHEDULED DETECTORS) = 1000.000000

(X MEANS FUNCTION UNDEFINED)

- D/I/R MECHANISM DEFINITIONS -

SUBCLASS	MECHANISM	FAULT TYPE/MODE		TRANS/1		TRANS/2		PERM/0	
		PERM/1	PERM/2	D I E T	D I E T	D I E T	D I E T	D I E T	D I E T
2	2	9 2 1 2	0 0 0 0	9 3 1 2	0 0 0 0	9 2 1 2	0 0 0 0	9 2 1 2	0 0 0 0
2	4	10 1 1 1	10 1 2 2	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	10 1 1 1	10 1 1 1

NORMALIZATION COMPLETE FOR DETECTION FUNCTIONS
 NORMALIZATION COMPLETE FOR ISOLATION FUNCTIONS
 NORMALIZATION COMPLETE FOR E. P. REC. FUNCTIONS
 NORMALIZATION COMPLETE FOR T. L. REC. FUNCTIONS

SIMILAR TO JOB #2 EXCEPT THAT THE DUAL MODE
 MODEL ACCEPTS ADDITIONAL FORMS OF COVERAGE

FIGURE 6-5 (Cont.-4)

COVERAGE FUNCTION SPECIFICATIONS

- DETECTION -

FUNCTION NUMBER	IGPT	INTF	ISCH	IREP	COEF	TDEL	P1	P2	P3	TDUR
9	3	1	0	0	1.00000	0.	9.1011E-02	9.0000E-02	0.	5.0000E+01
10	3	1	1	1	.95000	0.	7.2180E-01	7.0000E-01	0.	5.0000E+00

- ISOLATION -

FUNCTION NUMBER	IGPT	INTF	COEF	TDEL	P1	P2	P3	TDUR
1	0	1	1.00000	5.0000E-01	0.	0.	0.	0.
2	1	1	.99000	0.	4.0000E-02	0.	0.	2.5000E+01
3	0	1	.80000	0.	0.	0.	0.	0.

- FAULT PROPAGATION RECOVERY -

FUNCTION NUMBER	IGPT	INTF	COEF	P1	P2	P3	TDUR
1	1	1	1.00000	1.0000E+00	0.	0.	1.0000E+04
2	3	1	1.00000	1.0000E+00	6.2500E-03	0.	2.0000E+02

- TIME LOST RECOVERY -

FUNCTION NUMBER	IGPT	INTF	COEF	P1	P2	P3	TDUR
1	1	1	.99990	1.0000E+00	0.	0.	1.0000E+04
2	3	1	.99990	1.0000E+00	2.3000E-02	0.	2.0000E+02

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 1 IET = 1 JS = 1
MECHANISM CONTRIBUTION
4 .01583
2 .59925

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 1 IET = 1 JS = 2
MECHANISM CONTRIBUTION
4 .01583
2 .59925

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 2 IET = 1 JS = 1
MECHANISM CONTRIBUTION
4 .03200

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 2 IET = 1 JS = 2
MECHANISM CONTRIBUTION
4 .03200

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 0 IET = 1 JS = 0
MECHANISM CONTRIBUTION
4 .01583
2 .59925

UNLIKE JTD AT 2, ISOLATION AND RECOVERY FUNCTIONS ARE NOW DEFINED TO BE LESS THAN PERFECT

"CONTRIBUTION" TELLS NET WORTH OF EACH DETECTION/ISOLATION/RECOVERY MECHANISM (WITH RESPECT TO ITS CONTRIBUTION TO THE WHOLE OF COVERAGE). LOW VALUES INDICATE (OBVIOUSLY ENOUGH) THAT THE PARTICULAR MECHANISM CONTRIBUTES LITTLE TO SYSTEM RELIABILITY, AND IS PERHAPS A CANDIDATE FOR REMOVAL FROM THE SYSTEM

FIGURE 6-5 (Cont.-5)

ISU = 2 MD = 0 IET = 1 JS = 1

COVERAGE CONTRIBUTIONS

MECHANISM CONTRIBUTION

.01583

.59925

2

ISU = 2 MD = 1 IET = 2 JS = 0

COVERAGE CONTRIBUTIONS

MECHANISM CONTRIBUTION

.64202

2

ISU = 2 MD = 2 IET = 2 JS = 0

COVERAGE CONTRIBUTIONS

MECHANISM CONTRIBUTION

RUN 1 RELIABILITY RESULTS

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.893577	.9784506	.9133674
2000.000	.7594244	.9254776	.8207726
3000.000	.6221214	.8545920	.7282369
4000.000	.4955078	.7751271	.6395670
5000.000	.3859877	.6933780	.5570113
6000.000	.2953104	.6134504	.4817391
7000.000	.2226007	.5378890	.4141890
8000.000	.1657121	.4681415	.3543188
9000.000	.1220597	.4048975	.3017840
10000.000	.0890893	.3483364	.2560635

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9212702	.0787298	.8187308	1.1252419E+00	2.3024215E+00
2000.000	.8440753	.1559247	.6703200	1.2592124E+00	2.1143341E+00
3000.000	.7665343	.2334657	.5488116	1.3967165E+00	1.9325680E+00
4000.000	.6889366	.3110634	.4493290	1.5332565E+00	1.7702853E+00
5000.000	.6126042	.3873958	.3678794	1.6652309E+00	1.6317177E+00
6000.000	.5391237	.4608763	.3011942	1.7899337E+00	1.5162546E+00
7000.000	.4699096	.5300904	.2465970	1.9055772E+00	1.4212726E+00
8000.000	.4060078	.5939922	.2018965	2.0109698E+00	1.3436262E+00
9000.000	.3480503	.6519497	.1652989	2.1055816E+00	1.2803153E+00
10000.000	.2962916	.7037084	.1353353	2.1893149E+00	1.2287258E+00

REL PRODUCT

T	REL PRODUCT
0.000	1.000000
1000.000	.9212702
2000.000	.8440753
3000.000	.7665343
4000.000	.6889366
5000.000	.6126042
6000.000	.5391237
7000.000	.4699096
8000.000	.4060078
9000.000	.3480503
10000.000	.2962916

RUN 2 RELIABILITY RESULTS

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.893207	.9745558	.9133674
2000.000	.749664	.833369	.8207726
3000.000	.650182	.8332956	.7282369
4000.000	.574313	.7455985	.6395670
5000.000	.559473	.6573780	.5570113
6000.000	.275106	.5729849	.4817391
7000.000	.205800	.4948780	.4141890
8000.000	.1501768	.4242536	.3543188
9000.000	.1099728	.3614854	.3017840
10000.000	.0783710	.3064317	.2560635

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.921150	.0788950	.8187308	1.1250402E+00	2.2976025E+00
2000.000	.843030	.1569370	.6703200	1.2577022E+00	2.1007149E+00
3000.000	.769538	.2360442	.5488114	1.3920146E+00	1.9114410E+00
4000.000	.6882440	.3156360	.4493290	1.5230800E+00	1.7446393E+00
5000.000	.6059776	.3940224	.3678794	1.6472178E+00	1.6042756E+00
6000.000	.5355737	.4693263	.3011042	1.7618986E+00	1.4889550E+00
7000.000	.4655449	.5399531	.2465070	1.8655821E+00	1.3953120E+00
8000.000	.3952172	.6047828	.2018965	1.9575237E+00	1.3196531E+00
9000.000	.3358106	.6631894	.1682989	2.0375856E+00	1.2586166E+00
10000.000	.2850254	.7149746	.1353353	2.1060686E+00	1.2093602E+00

REL PRODUCT

T	REL PRODUCT
0.000	1.000000
1000.000	.921150
2000.000	.843030
3000.000	.769538
4000.000	.6882440
5000.000	.6059776
6000.000	.5355737
7000.000	.4655449
8000.000	.3952172
9000.000	.3358106
10000.000	.2850254

RUN 1 RELIABILITY RESULTS

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.3181210	.3483364	.9133674
2000.000	.0530309	.0646264	.8207726
3000.000	.0074118	.0101814	.7282369
4000.000	.0009561	.0014997	.6395670
5000.000	.0001181	.0002121	.5570113
6000.000	.0000142	.0000295	.4817391
7000.000	.0000017	.0000041	.4141890
8000.000	.0000002	.0000006	.3543188
9000.000	.0000000	.0000001	.3017840
10000.000	.0000000	.0000000	.2560635

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+33
1000.000	.7017676	.2982324	.3328711	2.1982263E+00	2.2369430E+00
2000.000	.3119092	.6880908	.1108032	2.8149850E+00	1.2922668E+00
3000.000	.1152445	.8847555	.0348832	3.1245830E+00	1.0885684E+00
4000.000	.0396967	.9603033	.0122773	3.2333315E+00	1.0285528E+00
5000.000	.0133108	.9866892	.0040868	3.2570340E+00	1.0093484E+00
6000.000	.0044177	.9955823	.0013604	3.2474126E+00	1.0030709E+00
7000.000	.0014605	.9985395	.0004528	3.2252197E+00	1.0010091E+00
8000.000	.0004821	.9995179	.0001507	3.1983624E+00	1.0003315E+00
9000.000	.0001590	.9998410	.0000502	3.1697815E+00	1.0001089E+00
10000.000	.0000525	.9999475	.0000167	3.1405665E+00	1.0000358E+00

REL PRODUCT

T	REL PRODUCT
0.000	1.000000
1000.000	.7017676
2000.000	.3119092
3000.000	.1152445
4000.000	.0396967
5000.000	.0133108
6000.000	.0044177
7000.000	.0014605
8000.000	.0004821
9000.000	.0001590
10000.000	.0000525

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	1.0000000	1.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.2796512	.3064317	.9133674	.3328711	2.0436378E+00	2.0865249E+00
2000.000	.0410201	.0499894	.6207726	.1108032	2.6252877E+00	1.2539621E+00
3000.000	.0052337	.0071894	.7282369	.0368832	2.8488615E+00	1.0761984E+00
4000.000	.0006355	.0009941	.6395670	.0122773	2.9162318E+00	1.0243998E+00
5000.000	.0000755	.0001356	.5570113	.0040868	2.9237834E+00	1.0079571E+00
6000.000	.0000089	.0000184	.4817391	.0013604	2.9094679E+00	1.0026079E+00
7000.000	.0000010	.0000025	.4141890	.0004928	2.8873117E+00	1.0008557E+00
8000.000	.0000001	.0000003	.3543188	.0001507	2.8923702E+00	1.0002808E+00
9000.000	.0000000	.0000000	.3017840	.0000502	2.8364462E+00	1.0000922E+00
10000.000	.0000000	.0000000	.2560635	.0000167	2.8101848E+00	1.0000302E+00

REL. PRODUCT

T	REL. PRODUCT
0.000	1.0000000
1000.000	.6802679
2000.000	.2908902
3000.000	.1090750
4000.000	.0358036
5000.000	.0119488
6000.000	.0039579
7000.000	.0013075
8000.000	.0004315
9000.000	.0001423
10000.000	.0000469

FIGURE 6-6

JOB #6 INPUT/OUTPUT LISTINGS

\$OPTSON OUTPT1=T, OUTPT3=T, PRODT=T, COVPRC=T, STGOUT=TS

\$VAR1 PROD(1)=7,7,7S

\$VAR T=1.6E4, STEP=2.0E3, OPTION=1S

\$COVVAL COVINT=T, IGENC(2)=-1,1, IGENP(2)=1,1,

IFSC(2)=2,3,3, FRAC(2)=1.0,0.63,0.37S

IB

\$PARVEC Q1(1)=3,1,2, Q2(1)=2,1,1, S(1)=1,2,1, LAM(1)=1.0E-5,2.0E-4,5.0E-5,

MU(1)=5.0E-6,1.25E-4,2.5E-5, C1(1)=.998, C2(1)=.99, CD1(1)=.995,

CD2(1)=.99, CTR(1)=.996, CDTR(1)=.995, PRC1(1)=.99, PRC2(1)=.97S

ID

\$DATA SLH2=0.0, SLH3=0.0, RSGN=T, TFDS(4)=100., TMINOR=1000.0S

F	D	1	010	1.0	0.0					
F	D	2	010	.25	0.0					
F	D	5	010	.075	0.0					
F	D	10	311	1	.95	0.0	.721796	0.7	0.0	5.0
F	D	20	01		.9996	0.0				
F	I	1	01		1.0	0.5				
F	I	3	01		0.8	20.0				
F	I	4	11		.99985	0.0	.005			200.0



FIGURE 6-6 (Cont.-2)

F E	1	11	1.0		1.0			10000.0
F E	2	31	1.0		1.0	.00625	0.0	200.0
F E	3	11	.96		1.0			10000.0
F T	1	11	.9999		1.0			10000.0
F T	2	31	.9999		1.0	.023	0.0	200.0

M

2	4	10	1	1	1	10	1	2	2										10	1	1	1
2	7	2	1	1	1	2	1	1	2	2	1	1	1	2	1	1	2	2	1	1	1	1
2	9	5	1	1	1	5	1	1	2	5	3	1	1	5	3	1	2	5	1	1	1	1
3	1	1	1	1	1	1	1	1	2	1	1	1	1	1	1	1	2	1	1	1	1	1
4	11	20	4	1	1	20	4	3	2	20	4	1	1	20	4	3	2	20	4	1	1	1

W

PC

N

PF

G

ID

\$DATA TMINOR=400.0\$

G

S

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION) FIGURE 6-6 (Cont. -3)

```

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.
                                OUTPUT3= I
                                PRODT= I

BYANS
PRDD = 7, 7, 0, 0, 0, 0, 0, 0, 0, 0,
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS=
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
AND GAIN RESULTS =
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS =
                                LPLOTS F
                                OUTPUT1= T
                                OUTPUT2= F
                                OUTPUT4= F
                                OUTPUT5= F

```

FAULT SUBCLASS LINKAGE AND PARAMETERS =

FAULT SUBCLASS	LINKED TO STAGE	FRACTION OF FAULT RATE	PROB. OF FAULT DET. IN SPARES	TIME FOR FAULT DET. IN SPARES
1	0	0.00000	1.00000	0.00000
2	2	1.00000	1.00000	0.00000
3	3	.63000	1.00000	0.00000
4	3	.37000	1.00000	100.00000
5	0	0.00000	1.00000	0.00000
6	0	0.00000	1.00000	0.00000
7	0	0.00000	1.00000	0.00000
8	0	0.00000	1.00000	0.00000

STAGE 2 HAS A SINGLE FAULT SUBCLASS 2
 STAGE 3 HAS 2 FAULT SUBCLASSES, IT MIGHT REPRESENT, FOR EXAMPLE, A MEMORY UNIT CONSISTING OF:

- FIRST SUBCLASSES - BIT PLANES - MINOR CYCLE DURATION (FOR SCHEDULED DETECTORS) = 1000.000000
- ACCOUNTS FOR 63% OF MEMORY FAILURES
- SECOND SUBCLASSES - WORD ELECTRONICS - ACCOUNTS FOR 37% OF MEMORY FAILURES

(X MEANS FUNCTION UNDEFINED)

D/I/R MECHANISM DEFINITIONS =

FAULT SUBCLASS	MECHANISM	PERM/1			PERM/2			TRANS/1			TRANS/2			PERM/0			
		D	I	R	D	I	R	D	I	R	D	I	R	D	I	R	
2	4	10	1	1	10	1	2	2	0	0	0	0	0	0	10	1	1
2	7	2	1	1	2	1	1	2	2	1	1	1	2	1	1	1	1
4	9	5	1	1	5	1	1	2	5	3	1	1	5	3	1	2	1
3	1	1	1	1	1	1	1	2	1	1	1	1	1	1	1	1	1
4	11	20	4	1	1	20	4	3	2	20	4	1	1	20	4	3	2

PARTITIONING INTO SUBCLASSES ENABLES

THE APPLICATION OF

DIFFERENT D/I/R

MECHANISMS TO THE

COMPONENTS OF A

SINGLE STAGE

- NORMALIZATION COMPLETE FOR DETECTION FUNCTIONS
- NORMALIZATION COMPLETE FOR ISOLATION FUNCTIONS
- NORMALIZATION COMPLETE FOR E. P. REC. FUNCTIONS
- NORMALIZATION COMPLETE FOR T. L. REC. FUNCTIONS

FIGURE 6-6 (Cont. -5)

COVERAGE FUNCTION SPECIFICATIONS

- DETECTION -

FUNCTION NUMBER	IGPT	INTF	ISCH	IREP	COEF	TDEL	P1	P2	P3	TDIR
1	0	1	0	0	1.00000	0.	-0.	-0.	-0.	-0.
2	0	1	0	0	.25000	0.	-0.	-0.	-0.	-0.
5	0	1	0	0	.02500	0.	-0.	-0.	-0.	-0.
10	3	1	1	1	.95000	0.	7.2180E-01	7.0000E+01	0.	5.0000E+00
20	0	1	0	0	.99960	0.	-0.	-0.	-0.	-0.

- ISOLATION -

FUNCTION NUMBER	IGPT	INTF	COEF	TDEL	P1	P2	P3	TDIR
1	0	1	1.00000	5.0000E-01	-0.	-0.	-0.	-0.
3	0	1	.80000	2.0000E+01	-0.	-0.	-0.	-0.
4	1	1	.99950	0.	5.0000E-03	-0.	-0.	2.0000E+02

- FAULT PROPAGATION RECOVERY -

FUNCTION NUMBER	IGPT	INTF	COEF	P1	P2	P3	TDIR
1	1	1	1.00000	1.0000E+00	-0.	-0.	1.0000E+04
2	3	1	1.00000	1.0000E+00	6.2500E-03	0.	2.0000E+02
3	1	1	.99990	1.0000E+00	-0.	-0.	1.0000E+04

- TIME LOST RECOVERY -

FUNCTION NUMBER	IGPT	INTF	COEF	P1	P2	P3	TDIR
1	1	1	.99990	1.0000E+00	-0.	-0.	1.0000E+04
2	3	1	.99990	1.0000E+00	2.3000E-02	0.	2.0000E+02

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 1 IET = 1 JS = 1
 MECHANISM CONTRIBUTION
 4 .69462
 7 .24685
 9 .02167

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 1 IET = 1 JS = 2
 MECHANISM CONTRIBUTION
 4 .69462
 7 .24685
 9 .02167

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 2 IET = 1 JS = 1
 MECHANISM CONTRIBUTION
 4 .02340
 7 .24403
 9 .02162

COVERAGE CONTRIBUTIONS - ISU = 2 MD = 2 IET = 1 JS = 2

FIGURE 6-6 (Cont. -6)

MECHANISM CONTRIBUTION									
4	.02340								
7	.24403								
9	.02162								
COVERAGE CONTRIBUTIONS - ISU = 2 MD = 0 IET = 1 JS = 0									
MECHANISM CONTRIBUTION									
4	.69462								
7	.24685								
9	.02167								
COVERAGE CONTRIBUTIONS - ISU = 2 MD = 0 IET = 1 JS = 1									
MECHANISM CONTRIBUTION									
4	.69462								
7	.24685								
9	.02167								
COVERAGE CONTRIBUTIONS - ISU = 2 MD = 1 IET = 2 JS = 0									
MECHANISM CONTRIBUTION									
7	.24685								
9	.01750								
COVERAGE CONTRIBUTIONS - ISU = 2 MD = 2 IET = 2 JS = 0									
MECHANISM CONTRIBUTION									
7	.24403								
9	.01105								
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 1 IET = 1 JS = 1									
MECHANISM CONTRIBUTION									
1	.99990								
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 1 IET = 1 JS = 1									
MECHANISM CONTRIBUTION									
11	.99935								
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 1 IET = 1 JS = 2									
MECHANISM CONTRIBUTION									
1	.99990								
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 1 IET = 1 JS = 2									
MECHANISM CONTRIBUTION									
11	.99935								
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 2 IET = 1 JS = 1									
MECHANISM CONTRIBUTION									
1	.98847								
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 2 IET = 1 JS = 1									
MECHANISM CONTRIBUTION									
11	.01881								
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 2 IET = 1 JS = 2									
MECHANISM CONTRIBUTION									
1	.98847								
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 2 IET = 1 JS = 2									
MECHANISM CONTRIBUTION									
11	.98847								
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 2 IET = 1 JS = 2									
MECHANISM CONTRIBUTION									
11	0.00000								
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 0 IET = 1 JS = 0									
MECHANISM CONTRIBUTION									
1	.99990								
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 0 IET = 1 JS = 0									
MECHANISM CONTRIBUTION									
11	.99995								

FIGURE 6-6 (Cont. -7)

COVERAGE CONTRIBUTIONS - ISU = 3 MD = 0 IET = 1 JS = 1
MECHANISM CONTRIBUTION
1
.99990

COVERAGE CONTRIBUTIONS - ISU = 4 MD = 0 IET = 1 JS = 1
MECHANISM CONTRIBUTION
11
.99935

COVERAGE CONTRIBUTIONS - ISU = 3 MD = 1 IET = 2 JS = 0
MECHANISM CONTRIBUTION
1
.99990

COVERAGE CONTRIBUTIONS - ISU = 4 MD = 1 IET = 2 JS = 0
MECHANISM CONTRIBUTION
11
.99935

COVERAGE CONTRIBUTIONS - ISU = 3 MD = 2 IET = 2 JS = 0
MECHANISM CONTRIBUTION
1
.98847

COVERAGE CONTRIBUTIONS - ISU = 4 MD = 2 IET = 2 JS = 0
MECHANISM CONTRIBUTION
11
.20647

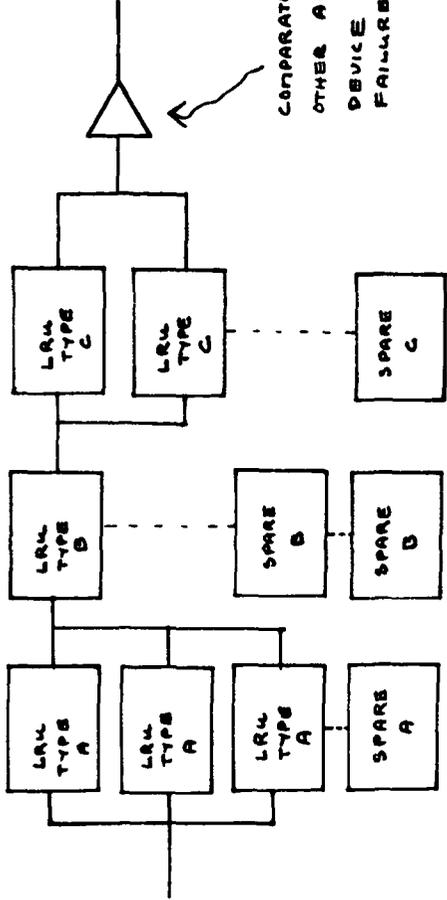
PARAMETER

STAGE/EQUATION NUMBER

HYBRID CONFIGURATION

1/7 2/7 3/7

Q01	3.0000000	1.0000000	2.0000000
Q2	2.0000000	1.0000000	1.0000000
S	1	2	1
LAM	1.000E=05	2.000E=04	5.000E=05
MU	5.000E=06	1.250E=04	2.500E=05
GMP	1.000E=06	1.000E=06	1.000E=06
CBC1	.99800000	.96334470	.99969654
CD1	.99500000	1.0000000	1.0000000
C2	.99000000	.28905341	.62969325
CD2	.99000000	1.0000000	.96894540
CTR	.99600000	.96334470	.99969654
CDTR	.99500000	1.0000000	1.0000000
PRC1	.99000000	.26434856	.99969654
PRC2	.97000000	.25507415	.69912694



3 REQ'D FOR MODE 1 OPERATION 2
 1 REQ'D FOR MODE 2 OPERATION
 2 REQ'D FOR MODE 1 OPERATION, 1 REQ'D FOR MODE 2 OPERATION

DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES 3
 CHANNEL FAILURE RATE 0.00000000
 SYSTEM FAILURE RATE 0.00000000
 CHANNEL FAILURE COV. 1.00000000
 REASSIGNMENT SWITCH 1

VALUES FROM Q=91 a-1 q2

RUN 1 RELIABILITY RESULTS

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2	STAGE 3	3IMREL	3IMGAIN	3IMRIE
0.000	1.000000	1.000000	1.000000	1.000000	1.000000E+00	1.000000E+00	1.000000E+35
2000.000	.9388961	.9978564	.9616839	.9784016	1.6131510E+00	1.6131510E+00	9.9021593E+00
4000.000	.7854347	.9920432	.8555599	.9253990	.3534547	2.3536785E+00	4.1056319E+00
6000.000	.5940845	.9830308	.7072456	.8544976	.2101361	3.2378422E+00	2.4713170E+00
8000.000	.4152251	.9712447	.5533451	.7750263	.1249302	4.1249306E+00	1.6054903E+00
10000.000	.2160450	.9570697	.4160345	.6932771	.0742736	5.0123490E+00	1.4747562E+00
12000.000	.1733641	.9408529	.3038642	.6133534	.0441572	5.8603708E+00	1.2910872E+00
14000.000	.1078572	.9229071	.2173059	.5377984	.0262523	6.7178292E+00	1.1822473E+00
16000.000	.0646886	.9035139	.1529654	.4680984	.0156076	7.5189753E+00	1.1152729E+00

STAGE 3 EQUATION NUMBER 7

T	REL	UNREL	3IMREL	3IMGAIN	3IMRIE
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
2000.000	.9590514	.0409486	.5945205	1.6131510E+00	9.9021593E+00
4000.000	.6425223	.1574777	.3534547	2.3536785E+00	4.1056319E+00
6000.000	.6803874	.3196126	.2101361	3.2378422E+00	2.4713170E+00
8000.000	.513285	.4846715	.1249302	4.1249306E+00	1.6054903E+00
10000.000	.3722851	.6277149	.0742736	5.0123490E+00	1.4747562E+00
12000.000	.2566605	.7403395	.0441572	5.8603708E+00	1.2910872E+00
14000.000	.1733588	.8236412	.0262523	6.7178292E+00	1.1822473E+00
16000.000	.1173528	.8826472	.0156076	7.5189753E+00	1.1152729E+00

COVERAGE CONTRIBUTIONS = ISU # 2 MD # 1 IET # 1 JS # 1

MECHANISM	CONTRIBUTION
4	.69462
7	.24685
9	.02187

COVERAGE CONTRIBUTIONS = ISU # 2 MD # 1 IET # 1 JS # 2

MECHANISM	CONTRIBUTION
4	.69462
7	.24685
9	.02187

COVERAGE CONTRIBUTIONS = ISU # 2 MD # 2 IET # 1 JS # 1

MECHANISM	CONTRIBUTION
4	.05851
7	.24003
9	.02162

COVERAGE CONTRIBUTIONS = ISU # 2 MD # 2 IET # 1 JS # 2

MECHANISM	CONTRIBUTION
4	.05851
7	.24003
9	.02162

FIGURE 6-6 (Cont. -10)

MECHANISM	CONTRIBUTION
4	.05851
7	.24403
9	.02162

COVERAGE CONTRIBUTIONS = ISU = 2 MD = 0 JET = 1 JS = 0

MECHANISM	CONTRIBUTION
4	.69462
7	.24685
9	.02167

COVERAGE CONTRIBUTIONS = ISU = 2 MD = 0 JET = 1 JS = 1

MECHANISM	CONTRIBUTION
4	.69462
7	.24685
9	.02167

STAGE/EQUATION NUMBER

PARAMETER

	1/7	2/7	3/7
Q01	3.0000000	1.0000000	2.0000000
Q2	2.0000000	1.0000000	1.0000000
S	1	2	1
LAM	1.000E-05	2.000E-04	5.000E-05
MU	5.000E-06	1.250E-04	2.500E-05
GMP	1.000E-06	1.000E-06	1.000E-06
C=C1	.9980000	.96334470	.99969654
CD1	.9990000	1.0000000	1.0000000
C2	.9900000	.32415782	.62969525
CD2	.9900000	1.0000000	.98894540
CTR	.9960000	.96334470	.99969654
CDTR	.9950000	1.0000000	1.0000000
PRC1	.9900000	.26434856	.99969654
PRC2	.9700000	.25507415	.69912694

DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES 3
 CHANNEL FAILURE RATE 0.0000000
 SYSTEM FAILURE RATE 0.0000000
 CHANNEL FAILURE COV. 1.0000000
 REASSIGNMENT SWITCH T

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2	STAGE 3
0.000	1.000000	1.000000	1.000000	1.000000
2000.000	.938891	.9978364	.9616839	.9784016
4000.000	.7854347	.9920432	.8535999	.9253990
6000.000	.5940845	.9830308	.7072456	.8544976
8000.000	.4165251	.9712447	.5533451	.7750263
10000.000	.2760450	.9570697	.4160345	.6932771
12000.000	.1753641	.9408529	.3038842	.6133534
14000.000	.1078972	.9229071	.2171059	.5377984
16000.000	.0646886	.9035139	.1529654	.4680584

STAGE 3 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SINGAIN	SYMTRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
2000.000	.9591357	.0408643	.5942205	1.6132928E+00	9.9225865E+00
4000.000	.8429157	.1570843	.3534847	2.3847913E+00	4.1159116E+00
6000.000	.6811161	.3188839	.210361	3.2413099E+00	2.4769662E+00
8000.000	.5162436	.4837564	.1249302	4.1322558E+00	1.8089058E+00
10000.000	.3732119	.6267881	.0742736	5.0248278E+00	1.4769369E+00
12000.000	.2604801	.7395199	.0441572	5.8989316E+00	1.2925181E+00
14000.000	.1770195	.8229805	.0282523	6.7429980E+00	1.1831965E+00
16000.000	.1178514	.8821486	.0156076	7.5509169E+00	1.1159032E+00

REL PRODUCT

T	REL PRODUCT
0.000	1.000000
2000.000	.9591357
4000.000	.8429157
6000.000	.6811161
8000.000	.5162436
10000.000	.3732119
12000.000	.2604801
14000.000	.1770195
16000.000	.1178514

FIGURE 6-7

JOB #7 INPUT/OUTPUT LISTINGS

\$OPTSON OUTPT1=T,OUTPT3=T,LPLOT=T,PRODT=T,LSTCH=T,DEFCHNG=T,STGOUT=TS

\$VAR1 PROD(1)=7,7,4,2\$

\$VAR T=1.0E4, STEP=1.0E3, OPTION=1\$

\$DEFAULT LAMDEF=1.0E-4\$

10000

100000

IB

\$PARVEC Q1(1)=2,2,0,1, Q2(1)=1,1, S(1)=4*1, Z(2)=2,

MU(1)=2*5.0E-5,1.0E-4,0,0, GMP(1)=2*1.1E-5,

C1(2)=.999, CD1(2)=.999, C2(2)=.98, CD2(2)=.998, CTR(2)=.999, CDTR(2)=.999,

PRC1(2)=.99, PRC2(2)=.95\$

ID

\$DATA SLH2=1.0E-7,SLH3=2.0E-8, RSGN=FS

IV 8

\$VARY PARAM(1,3)=1.0E-4,5.0E-5,0,0, PARAM(1,4)=0,0\$

G

S

CAREZ (COMPUTER-AIDED RELIABILITY ESTIMATION)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY QUESTIONS PRINTED BACK FOR VERIFICATION.
 DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS THE PRODUCT OF THE PRIMARY EQUATIONS.

SVARI = 7, 7, 4, 2, 0, 0, 0, 0, 0, 0, 0.
 PRODU = 7, 7, 4, 2, 0, 0, 0, 0, 0, 0.
 SEND

DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS=
 INPUT A 1 IN THE COLUMN SPECIFIED BELOW IF YOU WISH THE CORRESPONDING PLOT OPTION, OTHERWISE INPUT 0.
 NOTE: WHEN PERFORMING PRODUCT OF RELIABILITIES, NO OTHER PLOT OPTION BESIDES PRODUCT OF RELIABILITIES
 COLUMN 1 - PLOTS PRODUCT OF RELIABILITIES
 COLUMN 2 - PLOTS RELIABILITY
 COLUMN 3 - PLOTS DIFF, RIF, AND GAIN
 COLUMN 4 - PLOTS MTF AND RELIABILITY AT MTF
 COLUMN 5 - PLOTS UNRELIABILITY
 10000

FOR ABSCISSA, INPUT 1 IN COLUMN 1 IF ABSCISSA IS T,
 1 IN COLUMN 2 IF ABSCISSA IS LOG(T) - BASE 10,
 1 IN COLUMN 3 IF ABSCISSA IS LAMT,
 1 IN COLUMN 4 IF ABSCISSA IS LOG(LAMT) - BASE 10,
 1 IN COLUMN 5 IF ABSCISSA IS EXP(-LAMBDA(T)),
 1 IN COLUMN 6 IF ABSCISSA IS LOG(EXP(-LAMT)) - BASE 10.
 100000

DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
 DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
 AND GAIN RESULTS =
 DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
 DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION TIME CALCULATIONS =

OUTPT3= T
 PRODT= T
 LPLOT= T
 OUTPT1= T
 OUTPT2= P
 OUTPT4= P
 OUTPT5= P

FIGURE 6-7 (Cont.-3)

DATA BASE FOR RUN=SET

*****1*****

PARAMETER STAGE/EQUATION NUMBER

PARAMETER	1/7	2/7	3/4	4/2
Q=Q1	2.00000000	2.00000000		1.00000000
Q2	1.00000000	1.00000000		
S	1	1	1	1
W			1	1
Z			1	1
LAM	.00010000	.00010000	.00010000	.00010000
MU	5.0000E=05	5.0000E=05	1.0000E=04	0.
GMP	1.1000E=05	1.1000E=05		
C=C1	1.00000000	.99900000		1.00000000
CD1	1.00000000	.99900000		
C2	1.00000000	.98000000		
CD2	1.00000000	.99800000		
CTR	1.00000000	.99900000		
CDTR	1.00000000	.99900000		
PRC1	1.00000000	.99000000		
PRC2	1.00000000	.95000000		
RV			1.00000000	1.00000000

ITERATION PARAMETER TO BE VARIED = MU

1	5.0000E=05	5.0000E=05	1.0000E=04	0.
2	5.0000E=05	5.0000E=05	5.0000E=05	0.
3	5.0000E=05	5.0000E=05	0.	0.

DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES	2
CHANNEL FAILURE RATE	.00000010
SYSTEM FAILURE RATE	.00000000
CHANNEL FAILURE COV.	1.00000000
REASSIGNMENT SWITCH	F

CONFIGURATION IS THAT OF JOD'S # 3 and # 1 WIRED IN SERIES (I.E. BOTH MUST SUCCEED) WITH EXCEPTION THAT THE STANDBY REPLACEMENT SYSTEM (EQ. # 2) HAD ONLY 1 REPLICATION (#) INSTEAD OF 2

FIGURE 6-7 (Cont.--4)

RUN 1 RELIABILITY RESULTS

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.9569892	.9784506	.9781833
2000.000	.8558788	.9250189	.9250189
3000.000	.7295625	.8545920	.8540043
4000.000	.6000171	.7751271	.7744604
5000.000	.4799951	.6933780	.6926714
6000.000	.3756112	.6134504	.6127336
7000.000	.2887028	.5378890	.5371840
8000.000	.2186291	.4681415	.4674437
9000.000	.1635062	.4048975	.4042575
10000.000	.1209855	.3483364	.3477407

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9980114	.0019886	.8187308	1.2189739E+00	9.1153913E+01
2000.000	.9870321	.0129679	.6703200	1.4724788E+00	2.5422267E+01
3000.000	.9616920	.0383080	.5488116	1.7523171E+00	1.1777924E+01
4000.000	.9208261	.0791739	.4493290	2.0493316E+00	6.9952050E+00
5000.000	.8622972	.1337028	.3678794	2.3548400E+00	4.7278046E+00
6000.000	.8015662	.1984338	.3011942	2.6612936E+00	3.5216072E+00
7000.000	.7305658	.2694742	.2465970	2.9259050E+00	2.7962415E+00
8000.000	.6569852	.3430148	.2018965	3.2540691E+00	2.3267380E+00
9000.000	.5839004	.4160996	.1652289	3.5321914E+00	2.0060127E+00
10000.000	.5136460	.4863340	.1353353	3.7953991E+00	1.7778050E+00

SAME VALUES AS
JOB #3

STAGE 3 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9983584	.0016416	.9048374	1.1033567E+00	5.7970848E+01
2000.000	.9891672	.0108328	.8187308	1.2081715E+00	1.6733367E+01
3000.000	.9696913	.0303087	.7408182	1.3089464E+00	8.5514083E+00
4000.000	.9401482	.0598518	.6703200	1.4025363E+00	5.5082701E+00
5000.000	.9021363	.0978637	.6065307	1.4873713E+00	4.0205844E+00
6000.000	.8577434	.1422566	.5488116	1.5629105E+00	3.1716586E+00
7000.000	.8080674	.1909322	.4965853	1.6292625E+00	2.6366152E+00
8000.000	.7579482	.2420158	.4493290	1.6869249E+00	2.2753518E+00
9000.000	.7060520	.2939480	.4069697	1.7366077E+00	2.0188277E+00
10000.000	.6545004	.3454996	.3678794	1.7791165E+00	1.8295840E+00

SAME VALUES AS
JOB #4

STAGE 4 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9953212	.0046788	.9048374	1.1000000E+00	2.0338926E+01
2000.000	.9824769	.0175231	.8187308	1.2000000E+00	1.0344580E+01
3000.000	.9630637	.0369363	.7408182	1.3000000E+00	7.0169911E+00
4000.000	.9384481	.0615519	.6703200	1.4000000E+00	5.3561268E+00
5000.000	.9097960	.0902040	.6065307	1.5000000E+00	4.3619939E+00
6000.000	.8740986	.1219014	.5488116	1.6000000E+00	3.7012572E+00

DIFFERENT VALUES
THAN JOB #1 DUE
TO A CHANGE IN 2

FIGURE 6-7 (Cont.-5)

7000.000	.8441950	.1558050	.4965853	1.7000000E+00	3.7310564E+00
8000.000	.8087921	.1912079	.4493290	1.0000000E+00	2.8799602E+00
9000.000	.7124824	.2275176	.4065697	1.9000000E+00	2.6082827E+00
10000.000	.7357589	.2642411	.3678794	2.0000000E+00	2.1922112E+00

T	REL PRODUCT
0.000	1.0000000
1000.000	.9917112
2000.000	.9592312
3000.000	.8980997
4000.000	.8124266
5000.000	.7110221
6000.000	.6037263
7000.000	.4989445
8000.000	.4027659
9000.000	.3184667
10000.000	.2473485

RELIABILITY OF THE TOTAL SYSTEM

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.9569892	.9784506	.9781833
2000.000	.8558788	.9254776	.9250189
3000.000	.7295625	.8545920	.8540043
4000.000	.6000171	.7751271	.7744604
5000.000	.4799951	.6933780	.6926714
6000.000	.3756112	.6134504	.6127336
7000.000	.2817028	.5378890	.5371640
8000.000	.2186291	.4681419	.4674437
9000.000	.1635062	.4048979	.4042575
10000.000	.1209855	.3483364	.3477407

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9980114	.0019886	.8187308	1.2189739E+00	9.1153913E+01
2000.000	.9870321	.0129679	.6703200	1.4724768E+00	2.5422673E+01
3000.000	.9616920	.0383080	.5488116	1.7523171E+00	1.1777924E+01
4000.000	.9208261	.0791739	.4493290	2.0493361E+00	6.9552050E+00
5000.000	.8662972	.1337028	.3678794	2.3508400E+00	4.7278046E+00
6000.000	.8015662	.1984338	.3011942	2.6612936E+00	3.5216072E+00
7000.000	.7305658	.2694342	.2485970	2.9625905E+00	2.7962415E+00
8000.000	.6569852	.3430148	.2018965	3.2540691E+00	2.3267320E+00
9000.000	.5839004	.4160996	.1652989	3.5323914E+00	2.0060127E+00
10000.000	.5136460	.4863340	.1353353	3.7953591E+00	1.7778505E+00

STAGE 3 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9985462	.0014538	.9048374	1.1038642E+00	6.5458759E+01
2000.000	.9902986	.0097014	.8187308	1.2095334E+00	1.8684824E+01
3000.000	.9725751	.0274249	.7408182	1.3128390E+00	9.4905842E+00
4000.000	.9453251	.0546749	.6703200	1.4102593E+00	6.0298192E+00
5000.000	.9098163	.0901837	.6053307	1.5000335E+00	4.3629757E+00
6000.000	.8678538	.1321462	.5488116	1.5813326E+00	3.4143310E+00
7000.000	.8213362	.1786638	.4958533	1.6539681E+00	2.8176655E+00
8000.000	.7720221	.2279779	.4493290	1.7181669E+00	2.4154584E+00
9000.000	.7214221	.2785779	.4045697	1.7744120E+00	2.1302132E+00
10000.000	.6707658	.3292342	.3678794	1.8233305E+00	1.9199724E+00

STAGE 4 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9953212	.0046788	.9048374	1.1000000E+00	2.0338928E+01
2000.000	.9824769	.0175231	.8187308	1.2000000E+00	1.0344590E+01
3000.000	.9630637	.0369363	.7408182	1.3000000E+00	7.0169911E+00
4000.000	.9384481	.0615519	.6703200	1.4000000E+00	5.3561265E+00
5000.000	.9097960	.0902040	.6065307	1.5000000E+00	4.3619939E+00

FIGURE 6-7 (Cont.-7)

6000.000	.8780986	.1219014	.5488116	1.6000000E+00	3.7012572E+00
7000.000	.8441950	.1558050	.4965853	1.7000000E+00	3.2310564E+00
8000.000	.8087921	.1912079	.4493290	1.8000000E+00	2.8799602E+00
9000.000	.7724824	.2275174	.4065697	1.9000000E+00	2.6082827E+00
10000.000	.7357589	.2642411	.3678794	2.0000000E+00	2.3922112E+00

REL PRODUCT

T	0.000
1000.000	1.0000000
2000.000	.9918978
3000.000	.9603284
4000.000	.9007705
5000.000	.8169002
6000.000	.7170751
7000.000	.6108425
8000.000	.5065509
9000.000	.4102251
10000.000	.3253994
	.2534956

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.000000	1.000000	1.000000
1000.000	.9569892	.9784506	.9781833
2000.000	.8558788	.9254776	.9250189
3000.000	.7295625	.8545920	.8540043
4000.000	.6000171	.7751271	.7744604
5000.000	.4799951	.6933780	.6926714
6000.000	.3756112	.6134504	.6127336
7000.000	.2887028	.5378890	.5371840
8000.000	.2186291	.4681415	.4674637
9000.000	.1635062	.4048975	.4042575
10000.000	.1209855	.3483364	.3477407

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9980114	.0019886	.8187308	1.2189739E+00	9.1153913E+01
2000.000	.9870321	.0129679	.6703200	1.4724788E+00	2.5422673E+01
3000.000	.9616920	.0383080	.5488116	1.7523171E+00	1.1777924E+01
4000.000	.9208261	.0791739	.4493290	2.0093361E+00	6.9552030E+00
5000.000	.8662972	.1337028	.3678794	2.3548400E+00	4.7278046E+00
6000.000	.8015662	.1984338	.3011942	2.6612936E+00	3.5716072E+00
7000.000	.7305658	.2694342	.2465970	2.9625905E+00	2.7962415E+00
8000.000	.6589852	.3430148	.2018965	3.2540691E+00	2.3267320E+00
9000.000	.5839004	.4160996	.1652989	3.5323914E+00	2.0060127E+00
10000.000	.5136460	.4863440	.1353353	3.7953591E+00	1.7778505E+00

STAGE 3 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9987387	.0012613	.9048374	1.1037769E+00	7.5446916E+01
2000.000	.9914862	.0085138	.8187308	1.2110039E+00	2.1291123E+01
3000.000	.9756726	.0243274	.7408182	1.3170202E+00	1.0653893E+01
4000.000	.9310108	.0489892	.6703200	1.4167414E+00	6.7296472E+00
5000.000	.8784337	.0815663	.6065307	1.5142411E+00	4.8239183E+00
6000.000	.8174336	.1205664	.5488116	1.6024324E+00	3.7422398E+00
7000.000	.7435671	.1643329	.4965853	1.6828270E+00	3.0633844E+00
8000.000	.67887312	.2112688	.4493290	1.7553355E+00	2.6064946E+00
9000.000	.61400474	.2599526	.4048975	1.8202229E+00	2.2028046E+00
10000.000	.5608143	.3091857	.3678794	1.8778280E+00	2.0444690E+00

STAGE 4 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.000000	0.000000	1.000000	1.000000E+00	1.000000E+35
1000.000	.9953212	.0046788	.9048374	1.1000000E+00	2.0338926E+01
2000.000	.9824769	.0175231	.8187308	1.2000000E+00	1.0344590E+01
3000.000	.9630637	.0369363	.7408182	1.3000000E+00	7.0169911E+00
4000.000	.9384481	.0615519	.6703200	1.4000000E+00	5.3561265E+00
5000.000	.9097960	.0902040	.6065307	1.5000000E+00	4.3619939E+00

FIGURE 6-7 (Cont.-9)

6000.000	.8780986	.1219014	.5488116	1.60000000E+00	3.7012572E+00
7000.000	.8441950	.1558050	.4965853	1.70000000E+00	3.7310564E+00
8000.000	.8087921	.1912079	.4493290	1.80000000E+00	2.8799602E+00
9000.000	.7724824	.2275176	.4065697	1.90000000E+00	2.6082827E+00
10000.000	.7357589	.2642411	.3678794	2.00000000E+00	2.3922112E+00

Y	REL PRODUCT
0.000	1.00000000
1000.000	.9920889
2000.000	.9614800
3000.000	.9036393
4000.000	.8218135
5000.000	.7238669
6000.000	.6189930
7000.000	.5153894
8000.000	.4191037
9000.000	.3338004
10000.000	.2610723

SECTION 7

SUMMARY AND CONCLUSIONS

The mathematical models and computer program described in this report are viewed by the authors as but an early step in the development of adequate, fault tolerant computer, design evaluation aids.

The tool provided is by no means a panacea. For example, the requirement for user determination of individual fault detection, isolation and recovery process characteristics, is viewed as a rather significant drawback. There are others as well.

Nevertheless, we also view it as a major improvement over other available reliability evaluation aids. For example, the provision for two distinct operating modes contrasts favorably with the single mode approximations typically encountered. Similarly, the inclusion of a means for calculating multiple coverage factors, conditioned on failure type and location, operating mode, and spares status, goes far beyond the more usual mathematical reliability model.

In addition, the generality of the model enables its use on a wide variety of system configurations, and variations therein. These include TMR, TMR with spares switching, hybrid, and a majority of others as well.

There remains much to be done, however, prior to the transformation of fault tolerant computer design from that of a rather mystical art, to that of a science. Most noteworthy, perhaps, is the task of gathering adequate failure rate statistics within integrated circuit chips, and also the task of establishing and implementing measurement criteria for individual fault detection, isolation and recovery processes. Hopefully, these will prove to be forthcoming from other endeavors.

Page Intentionally Left Blank

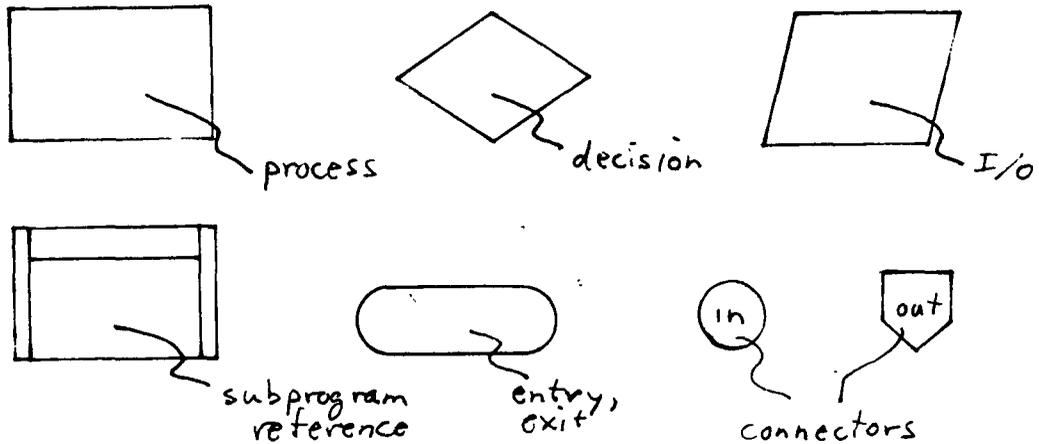


APPENDIX A
FLOW DIAGRAMS

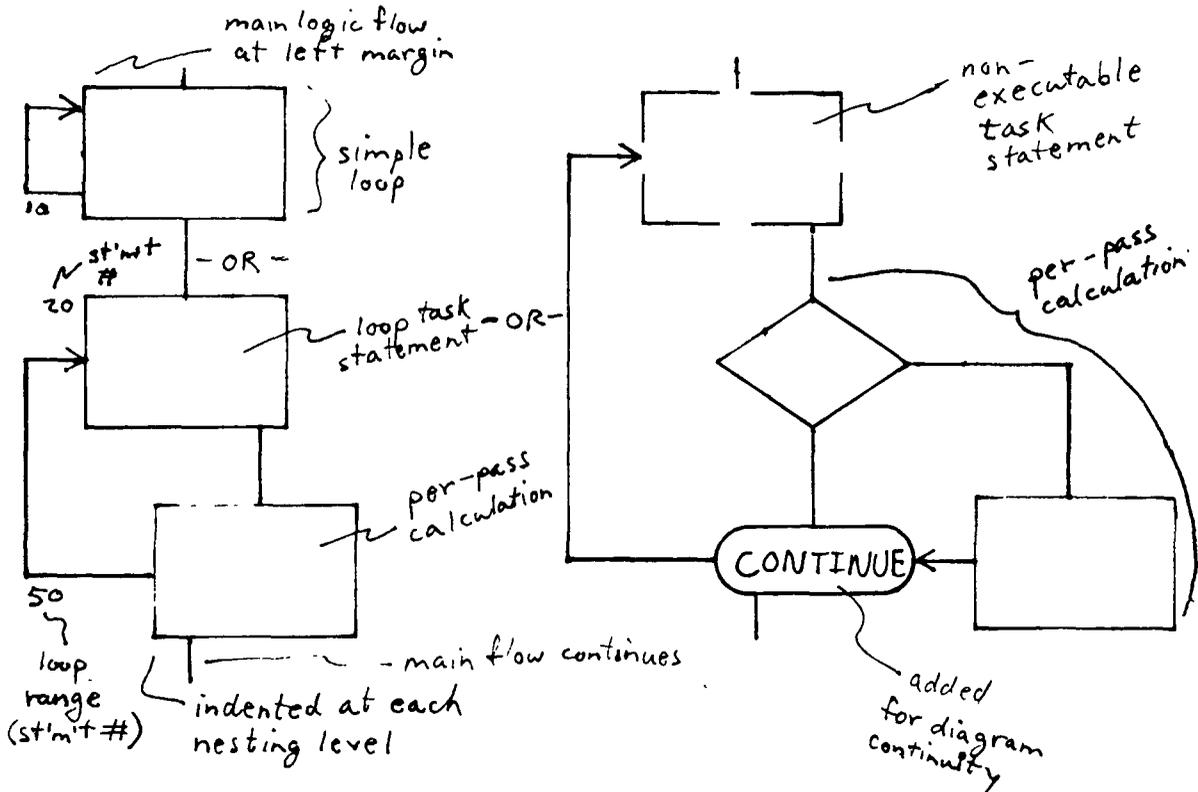
FLOW DIAGRAM

A-0

FLOW DIAGRAM CONVENTIONS

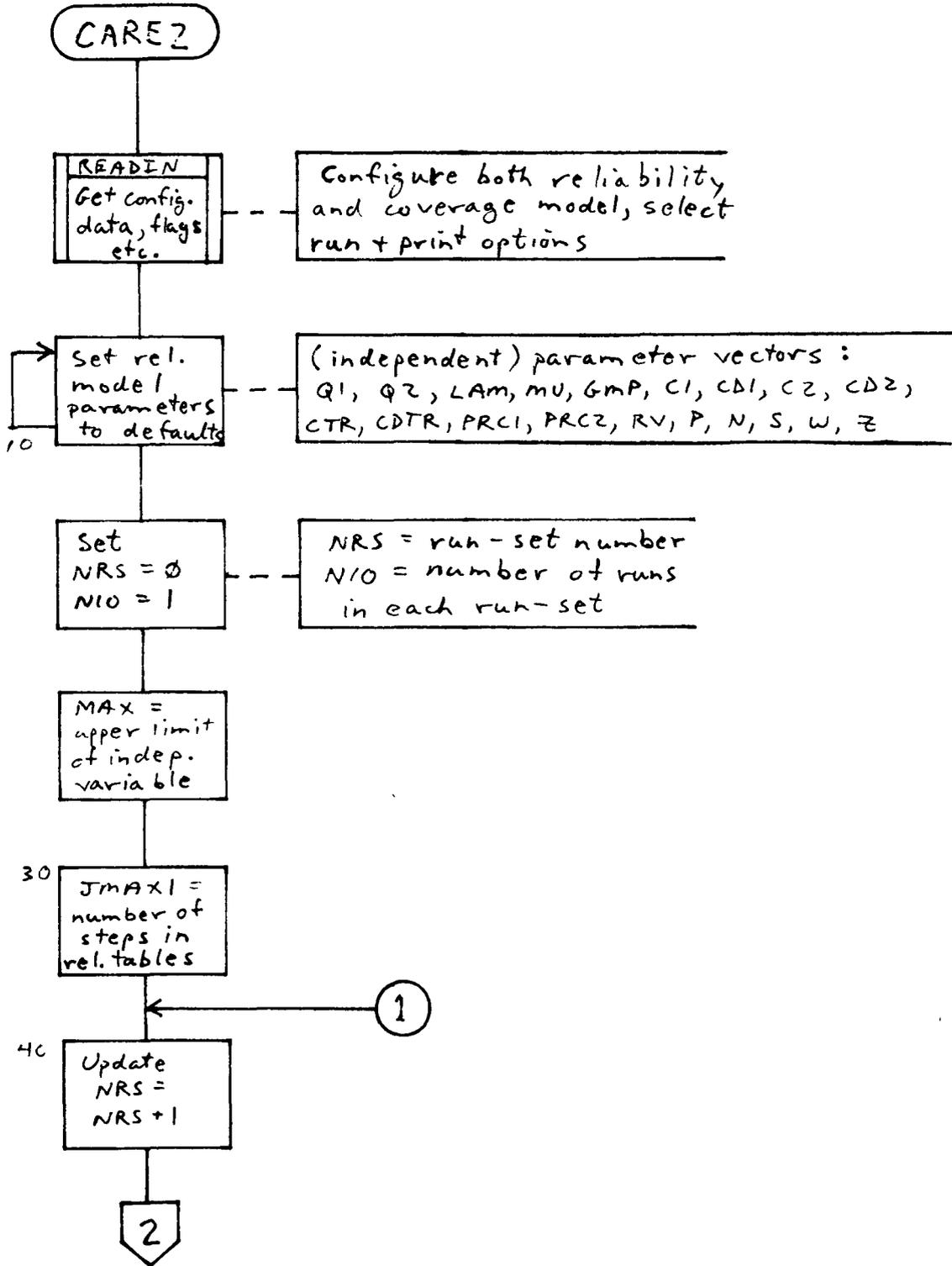


iterative procedures

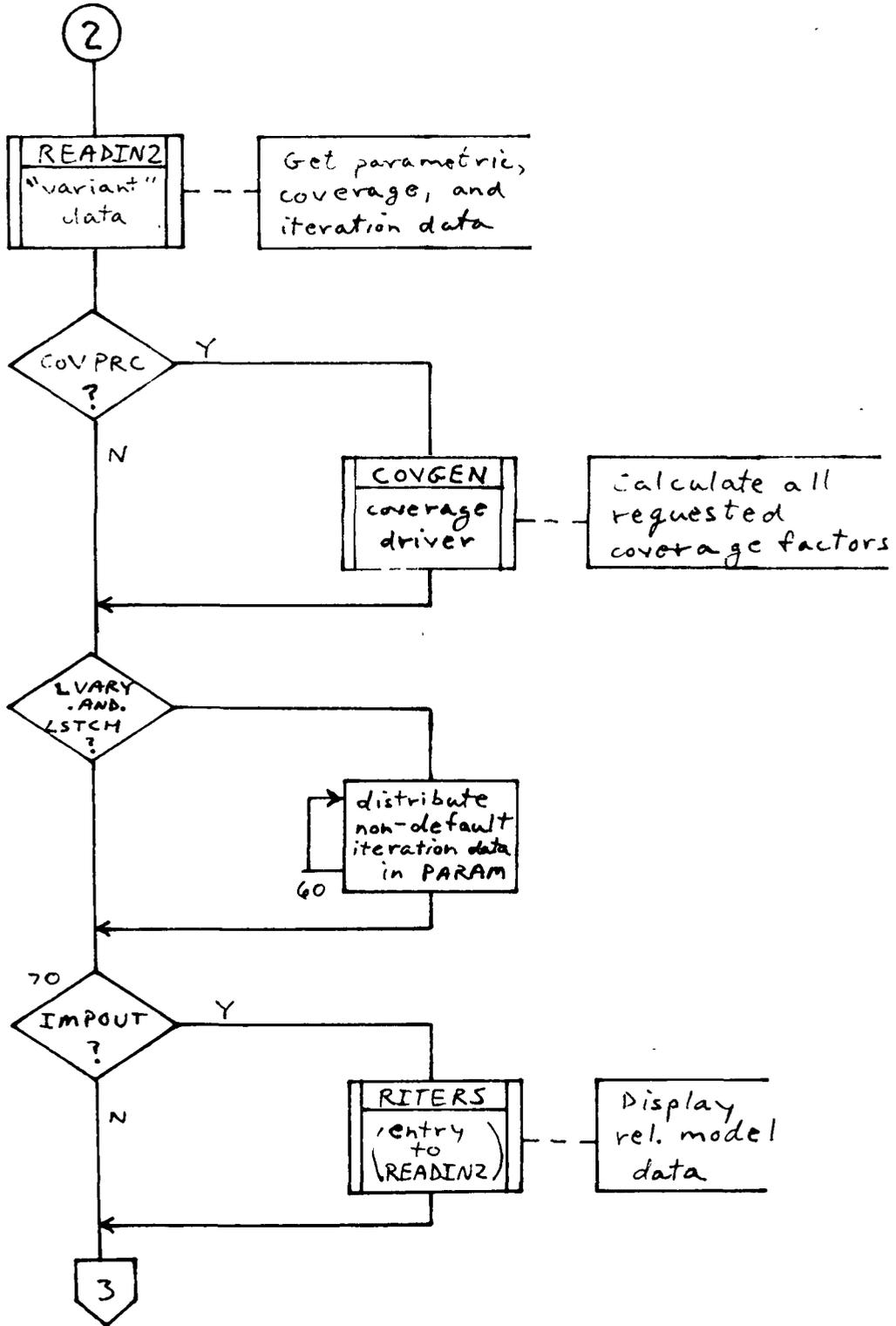


FLOW DIAGRAM

A-1

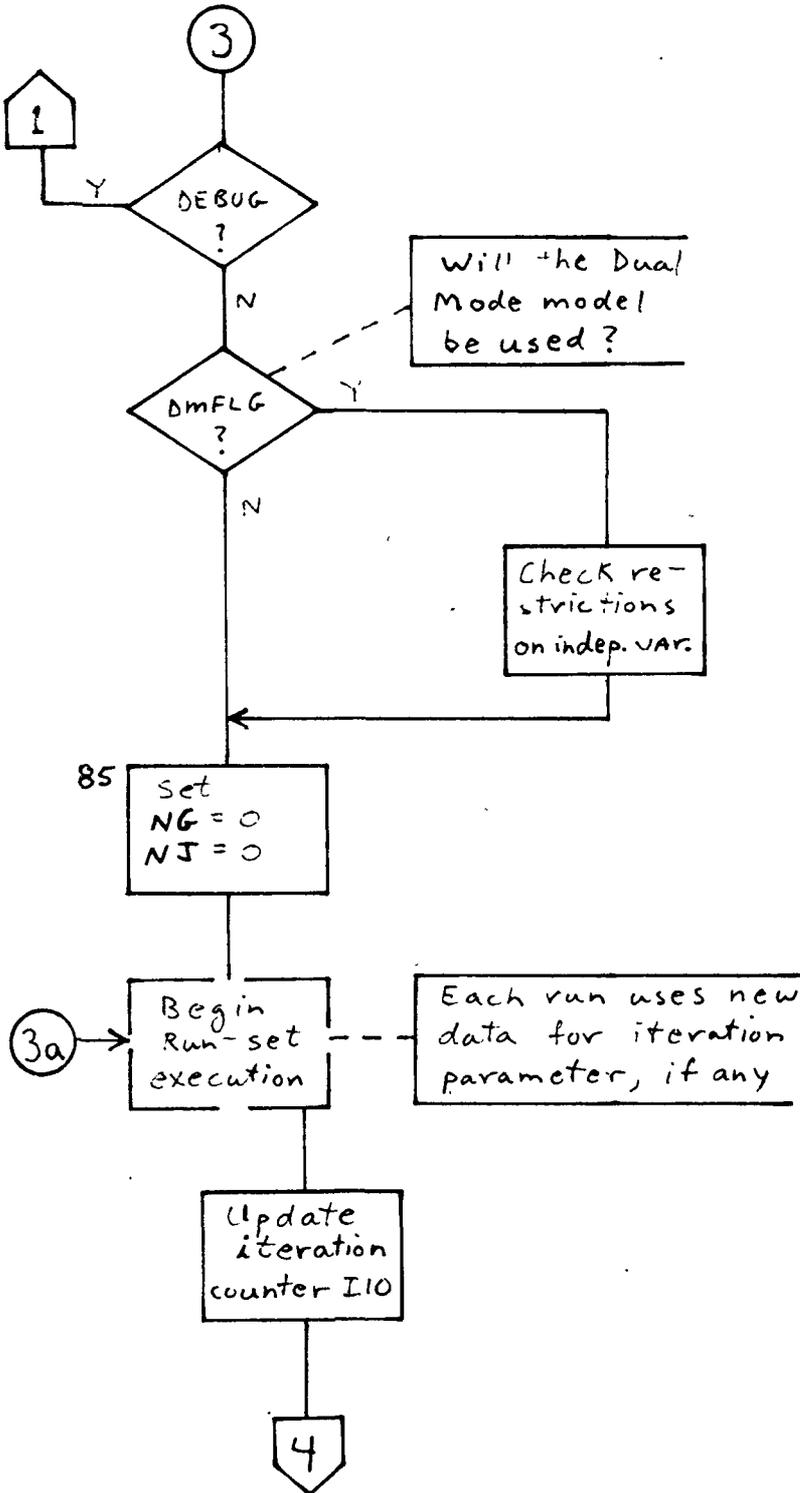


FLOW DIAGRAM
A-1



FLOW DIAGRAM

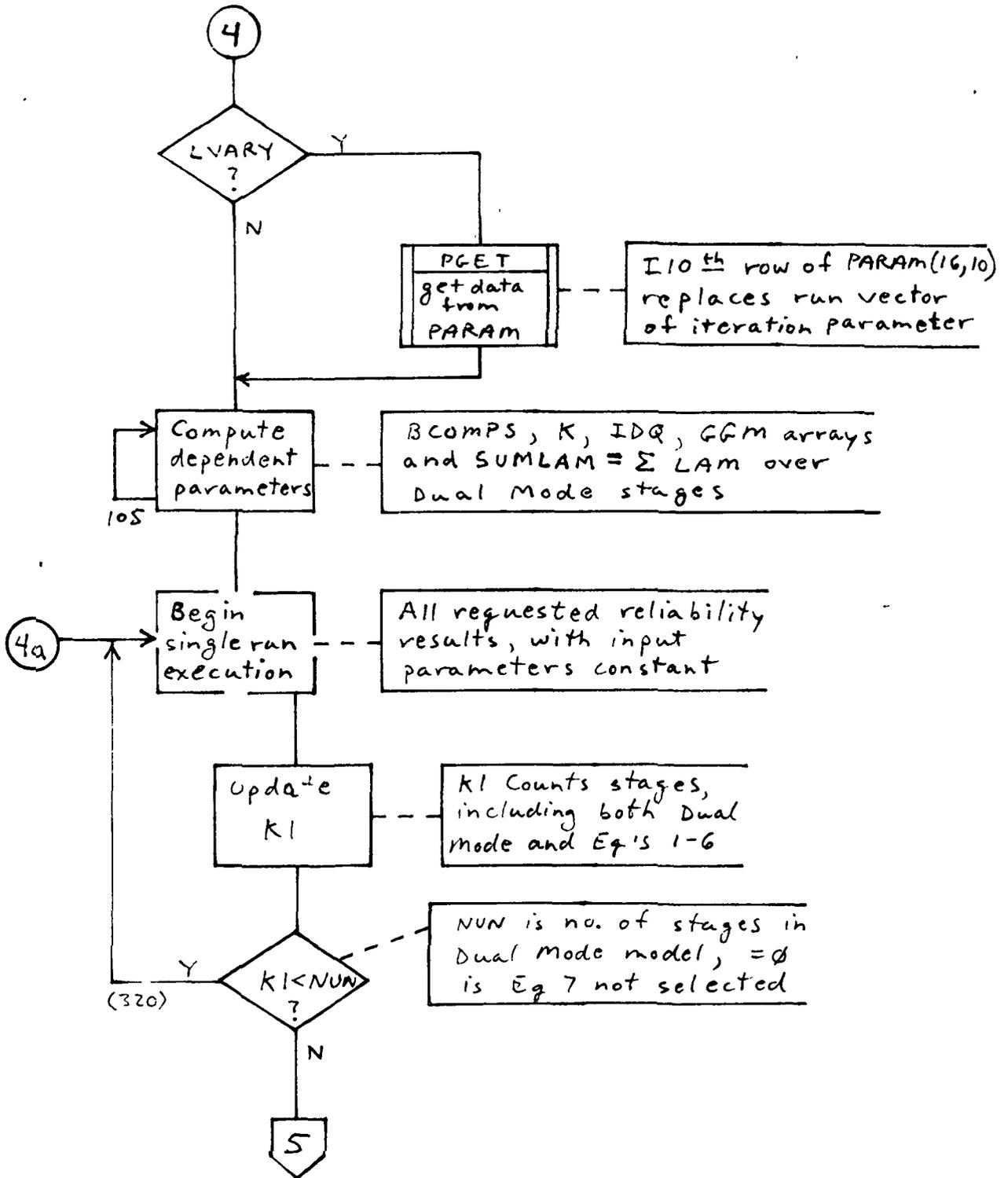
A-1





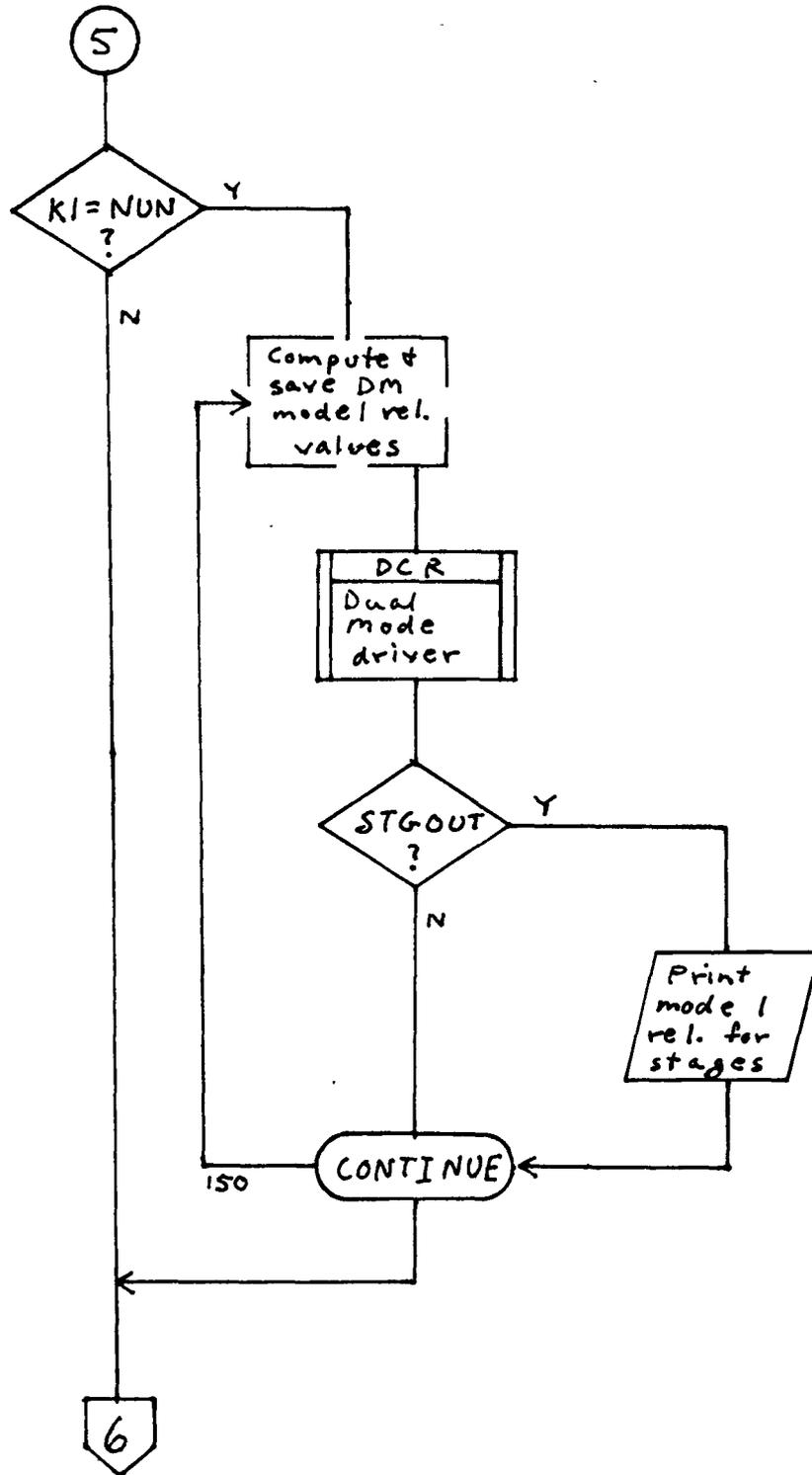
FLOW DIAGRAM

A-1



FLOW DIAGRAM

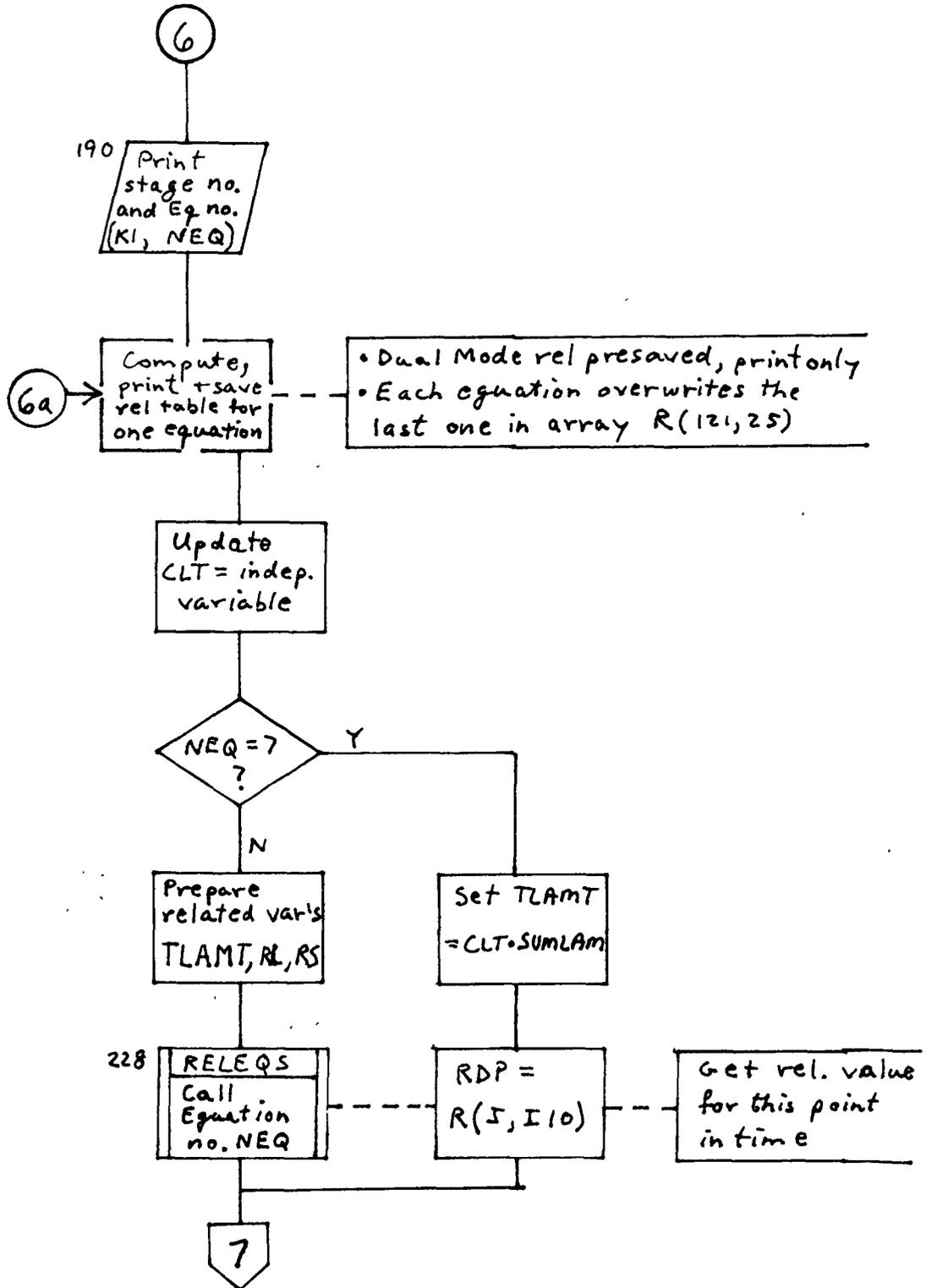
A-1



A-7

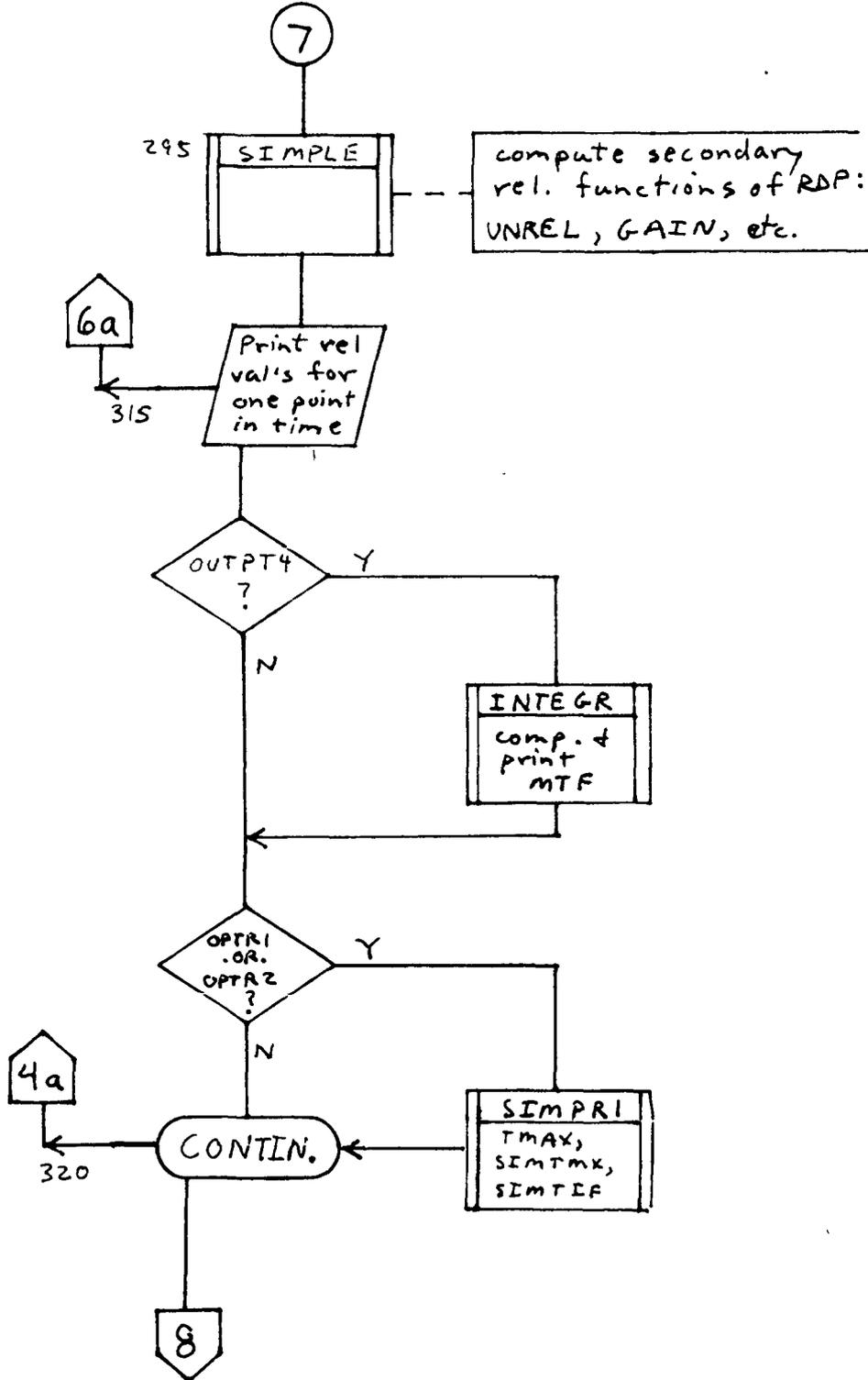
FLOW DIAGRAM

A-1



FLOW DIAGRAM

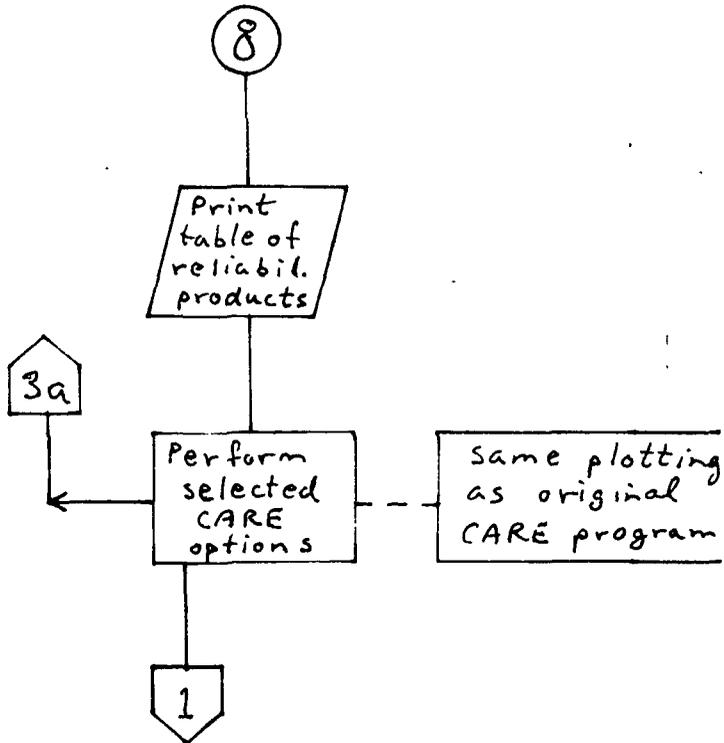
A-1





FLOW DIAGRAM

A-1





FLOW DIAGRAM

A-2

NEQ1A

The original subroutine was corrected
as follows:

original lines	modified lines
DO 70 LX=1, II	SUM1 = 0.0
L = LX - 1	DO 70 LX=1, II
SUM1 = 0.0	L = LX - 1
SUM2 = 0.0	SUM2 = 0.0
60 SUM2 = ~	60 SUM2 = ~
70 SUM1 = ~	70 SUM1 = ~

FLOW DIAGRAM

A-3

NEQ7

2nd order interpolation
of saved Dual Mode
reliability values

Compute
time
 $T = \ln RL / \Sigma \lambda$

Determine
optimum
sample
points

$x_1 = \text{STEP} * (I-1), y_1 = R(I, I10)$
 $x_2 = \text{STEP} * (J-1), y_2 = R(J, I10)$
 $x_3 = \text{STEP} * (K-1), y_3 = R(K, I10)$

Compute
 $A = a$
 $B = b$
 $C = c$

Compute
 $\text{DCR} = v(T)$

RETURN

Let: $r(x) = ax^2 + bx + c,$

$x_2 = x_1 + \Delta x,$

$x_3 = x_1 + 2\Delta x,$

$y_1 = r(x_1),$

$y_2 = r(x_2),$ and

$y_3 = r(x_3)$

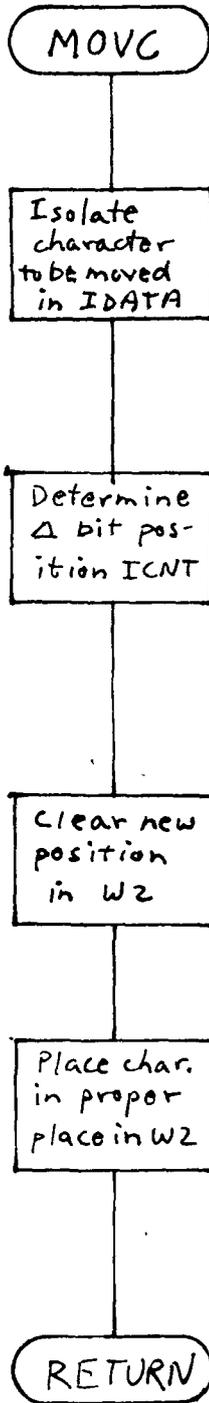
Then:
 $a = \frac{(y_1 - 2y_2 + y_3)}{2(\Delta x)^2}$

$b = \frac{y_3 - y_1 - 2ax_2}{2\Delta x}$

$c = y_2 - ax_2^2 - bx_2$

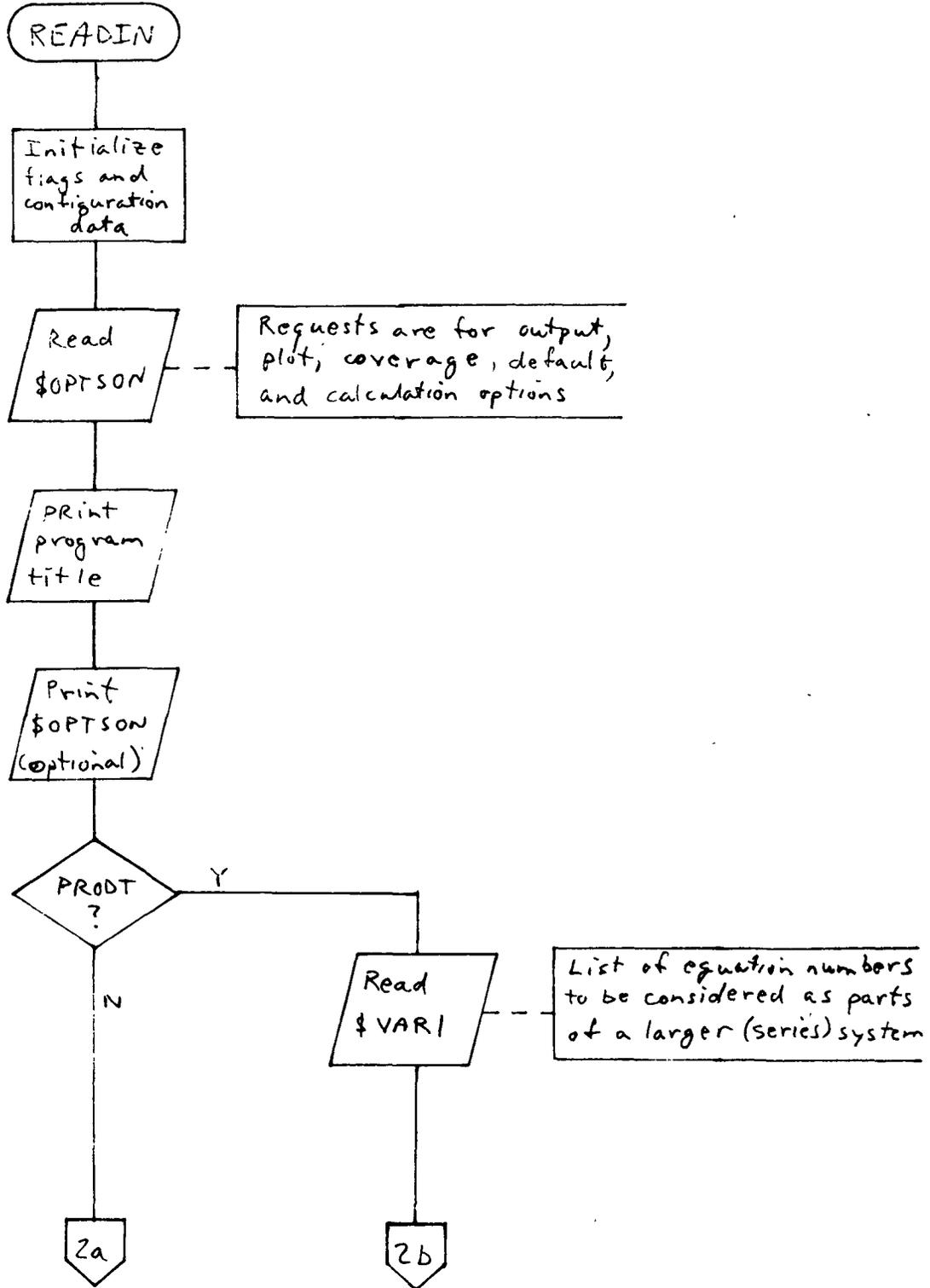
FLOW DIAGRAM

A-4



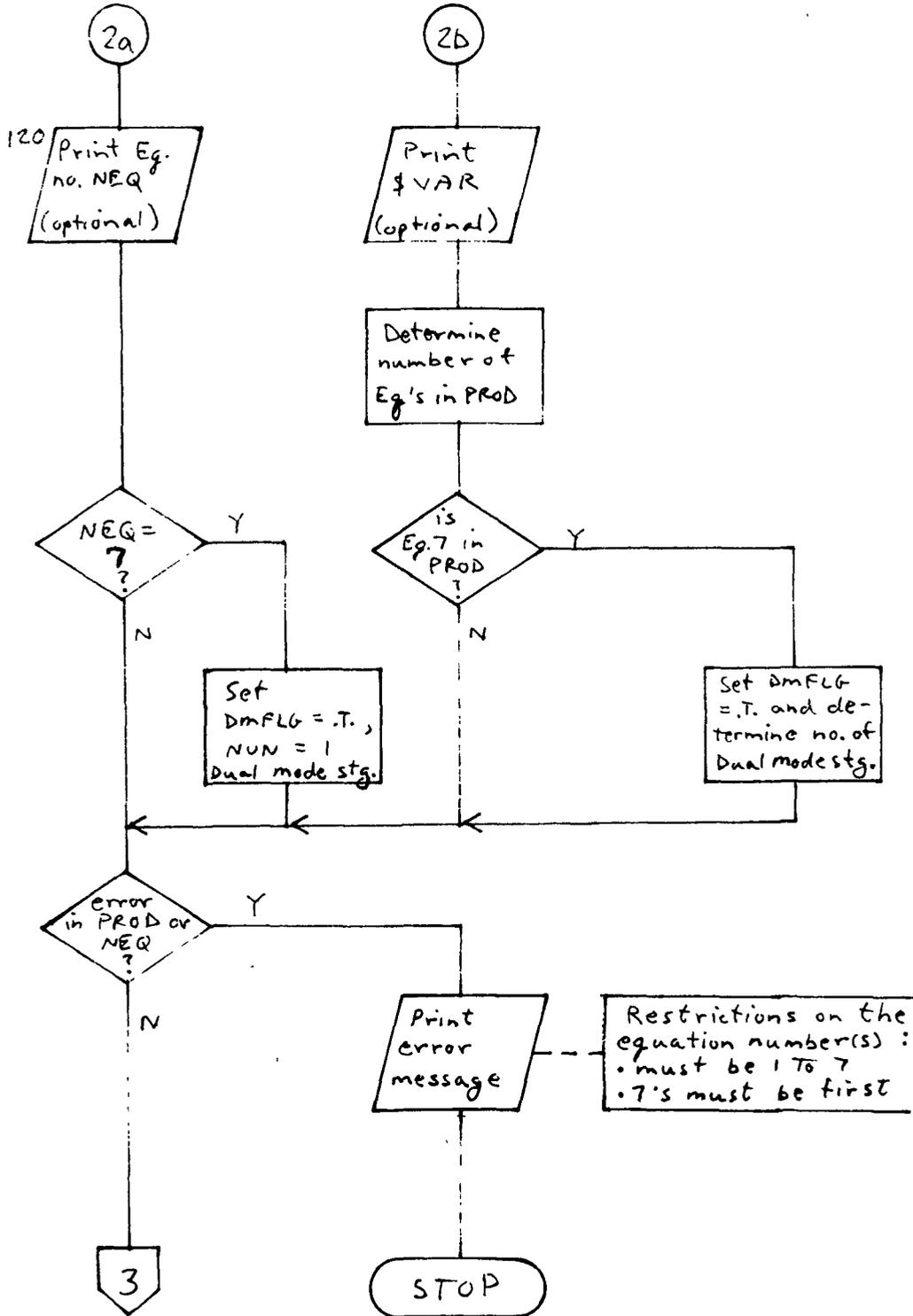
FLOW DIAGRAM

A-5



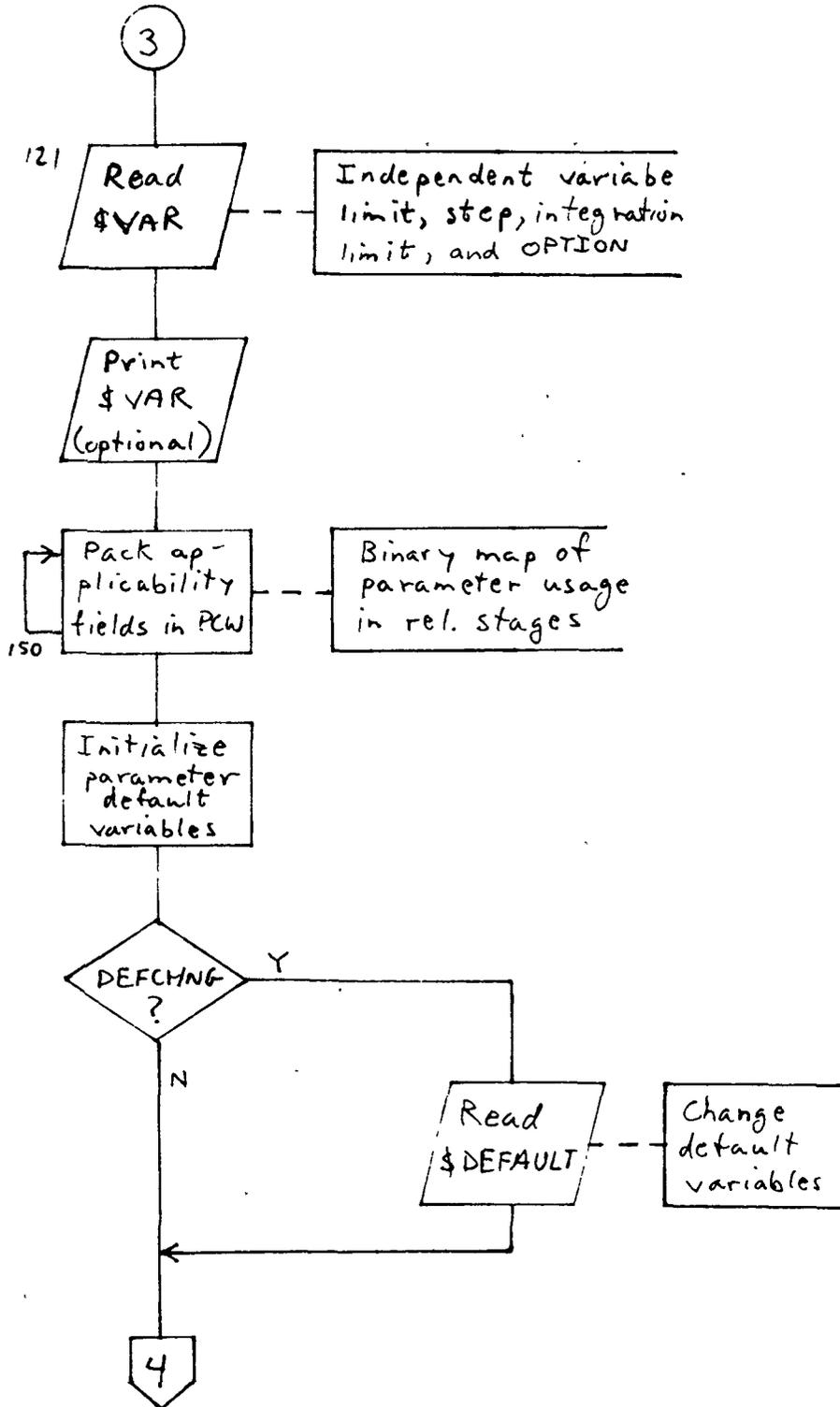
FLOW DIAGRAM

A-5



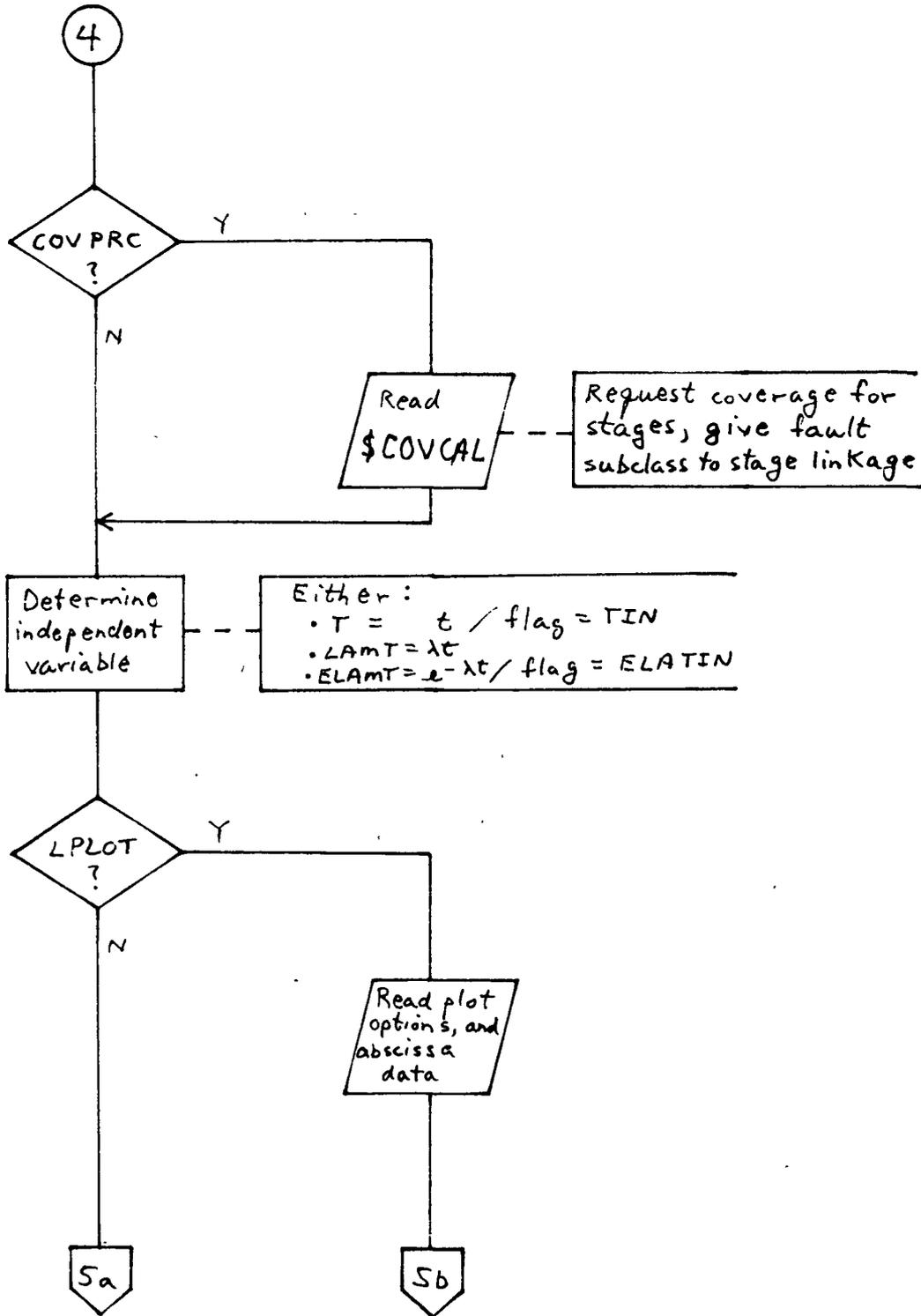
FLOW DIAGRAM

A-5



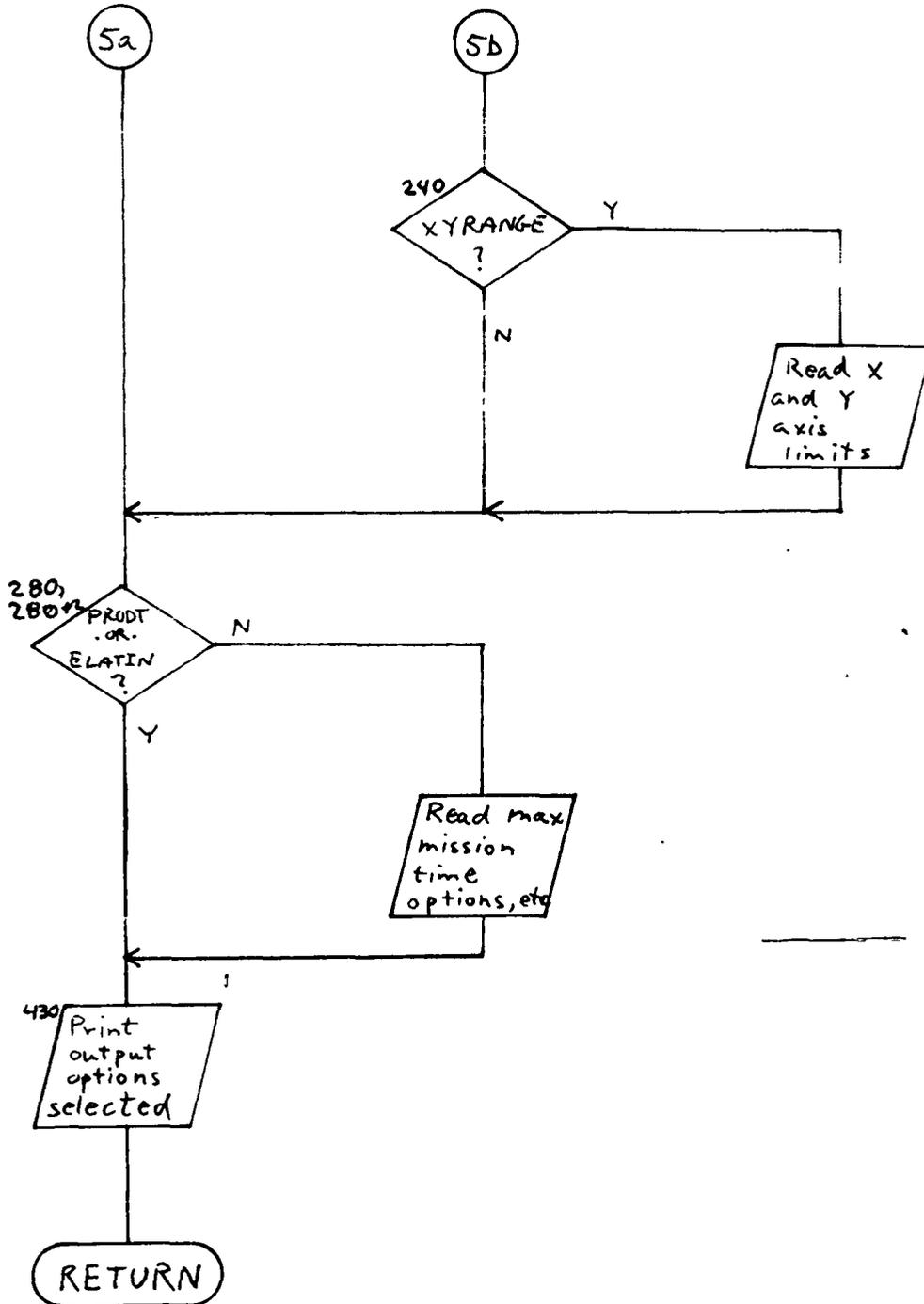
FLOW DIAGRAM

A-5



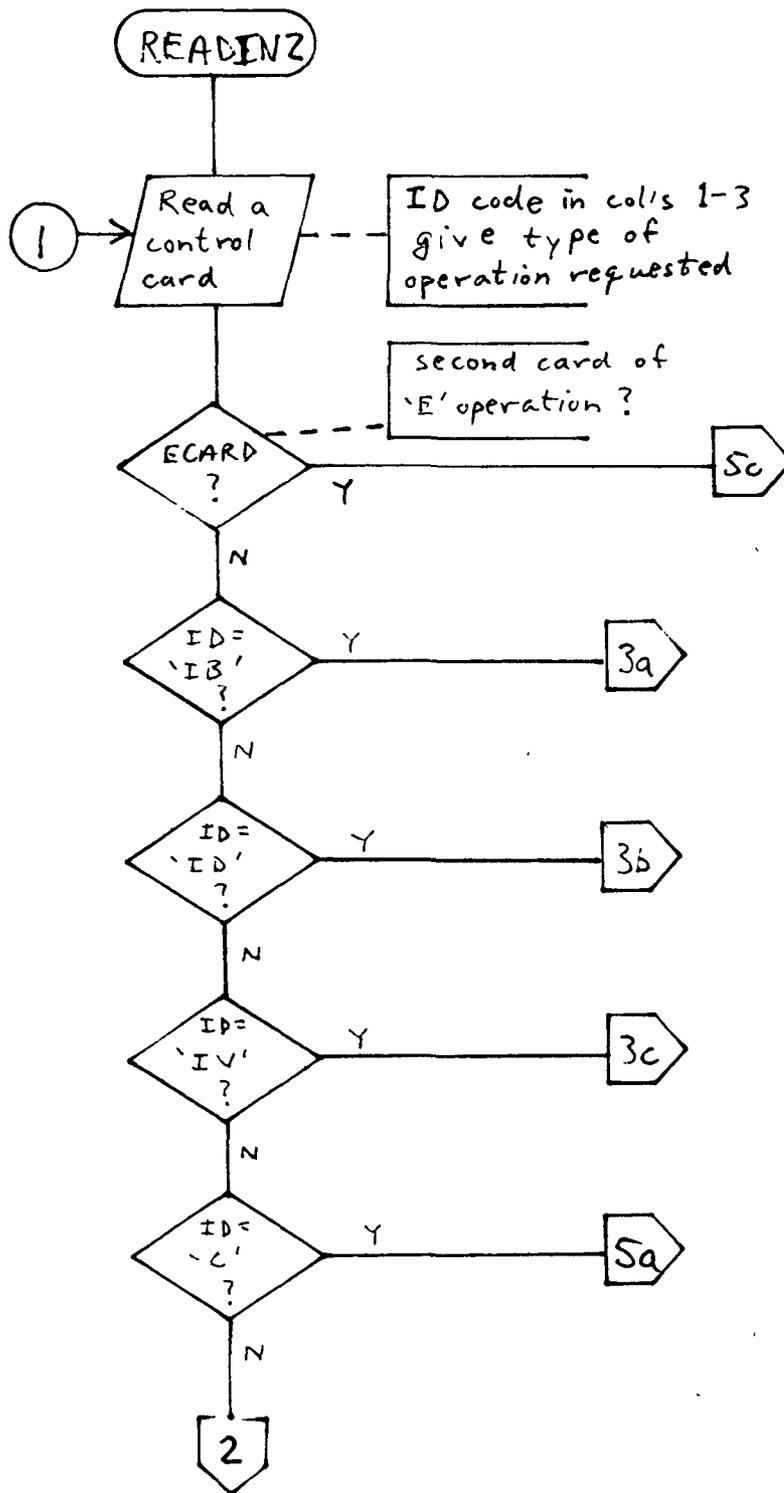
FLOW DIAGRAM

A-5



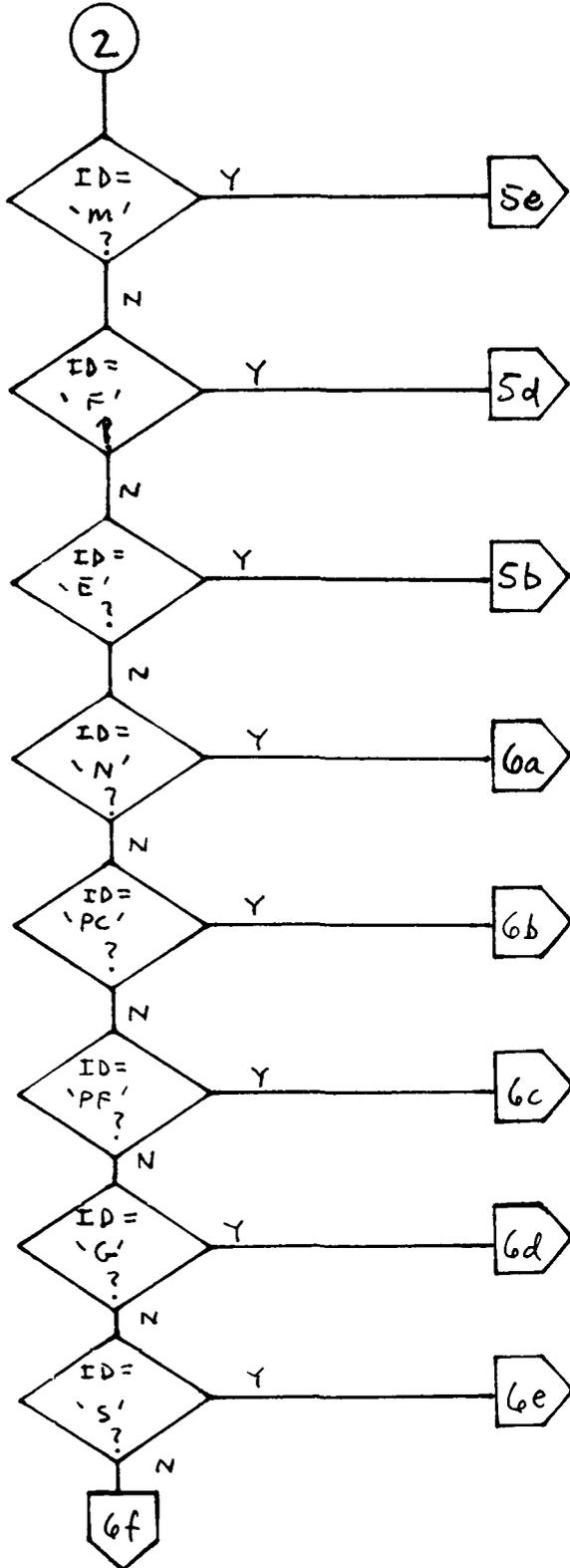
FLOW DIAGRAM

A-6

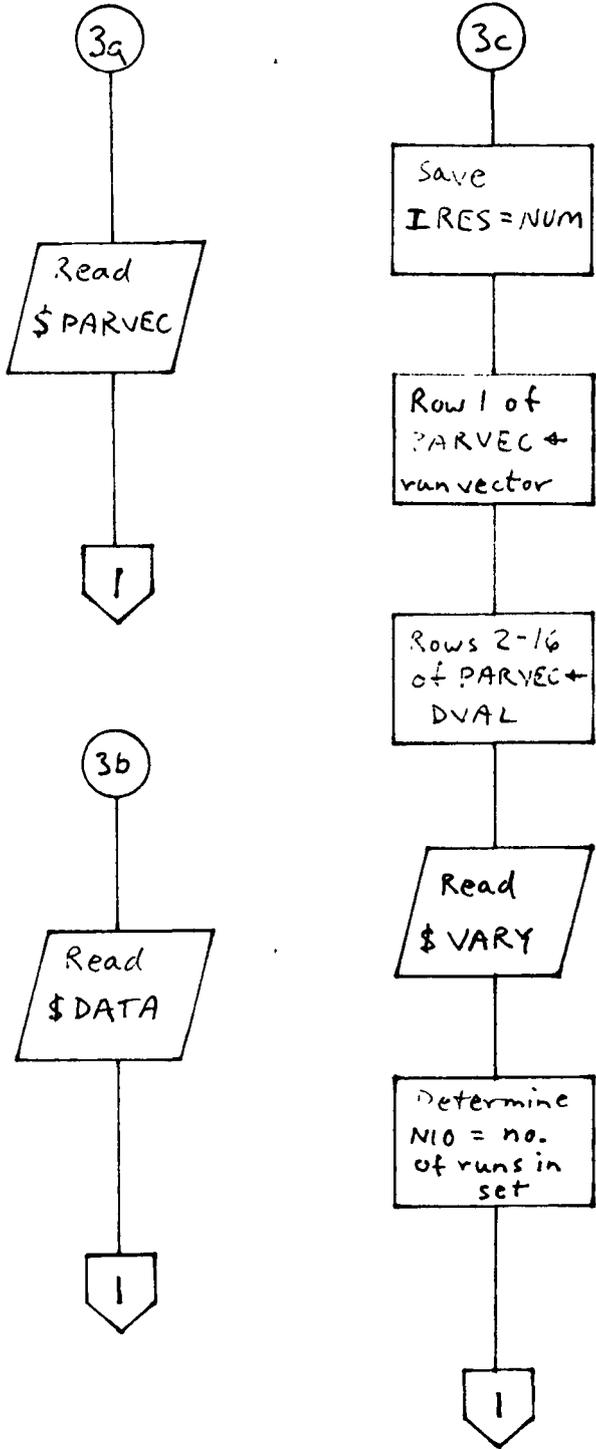


FLOW DIAGRAM

A-6

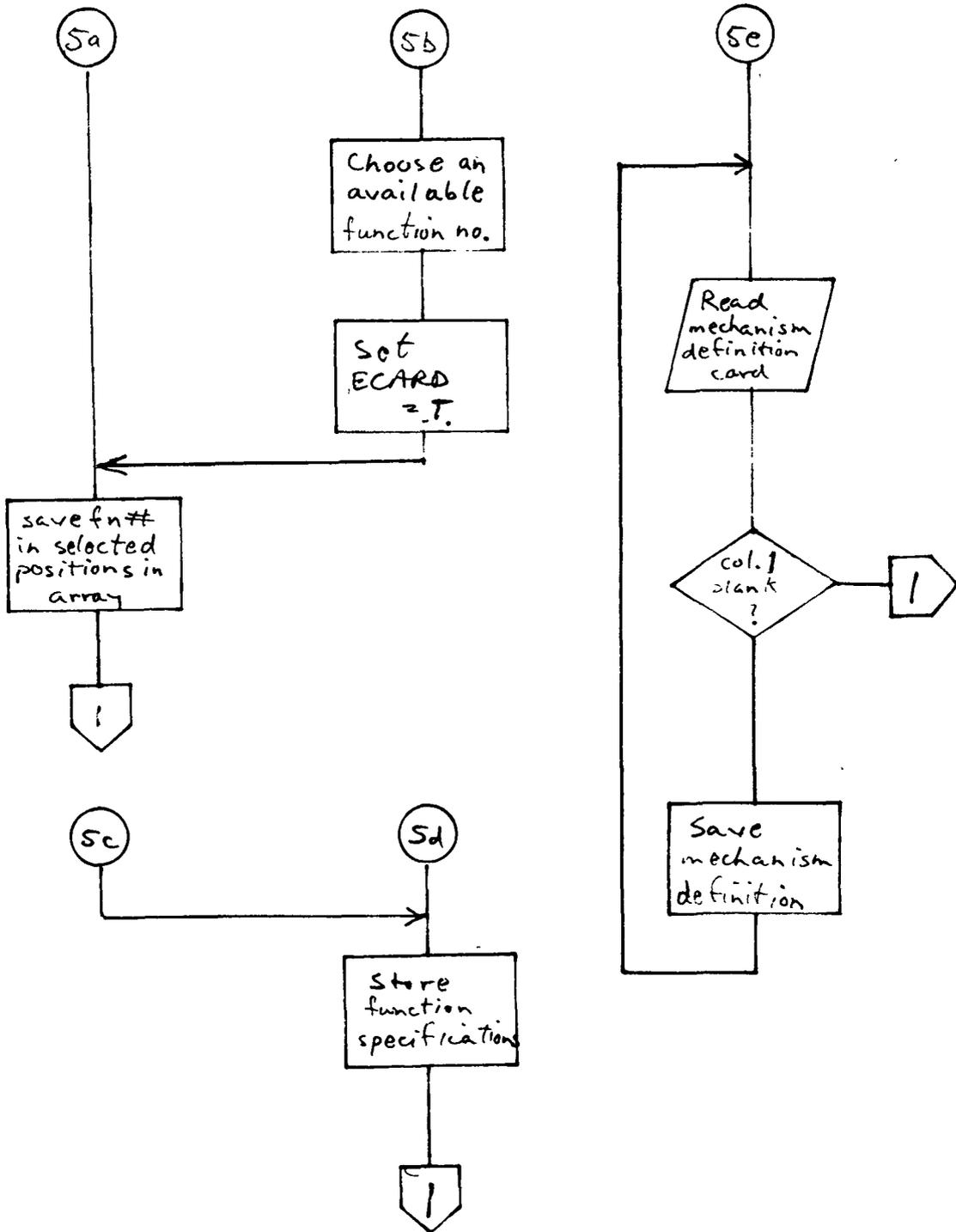


FLOW DIAGRAM
A-6



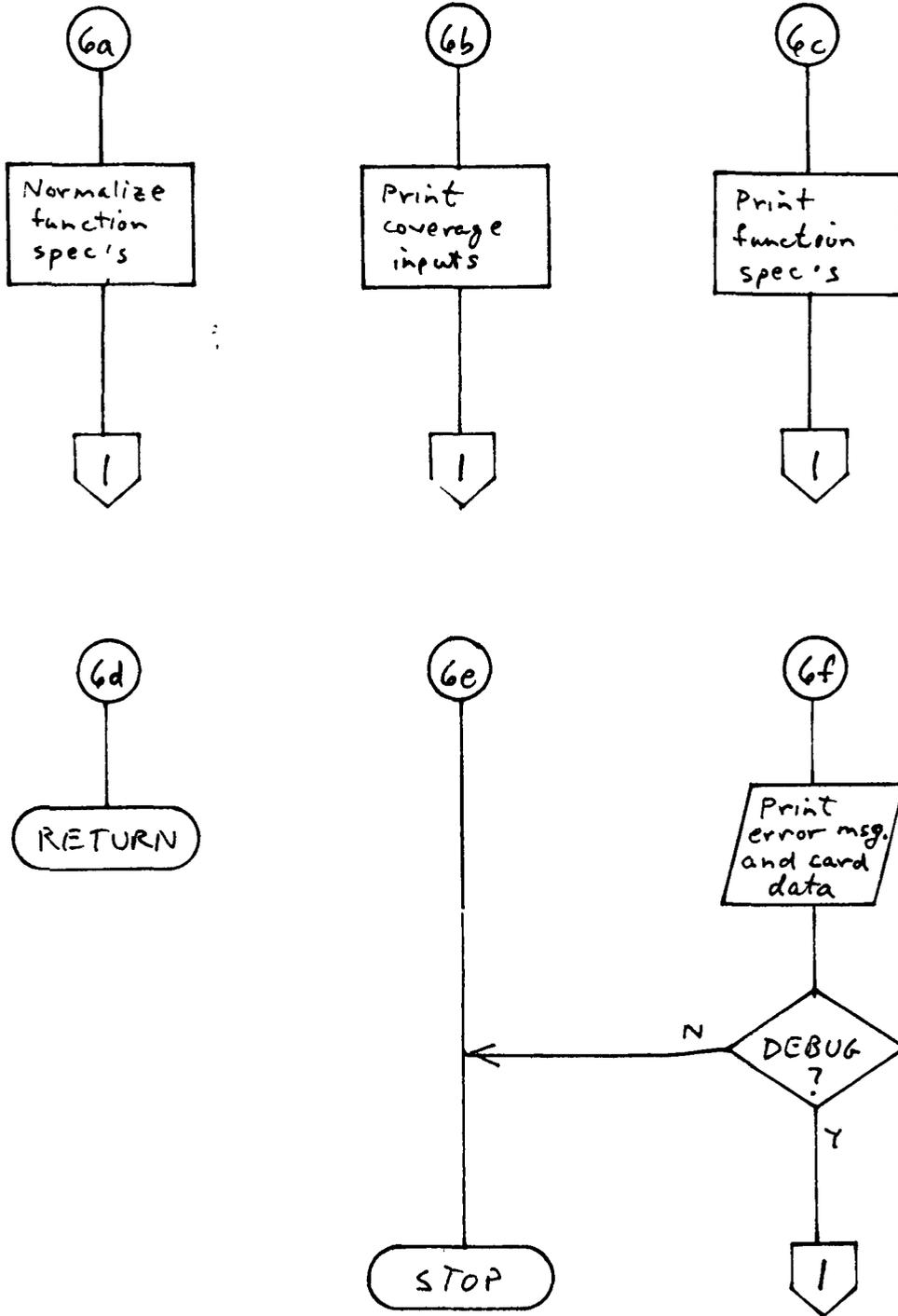
FLOW DIAGRAM

A-6



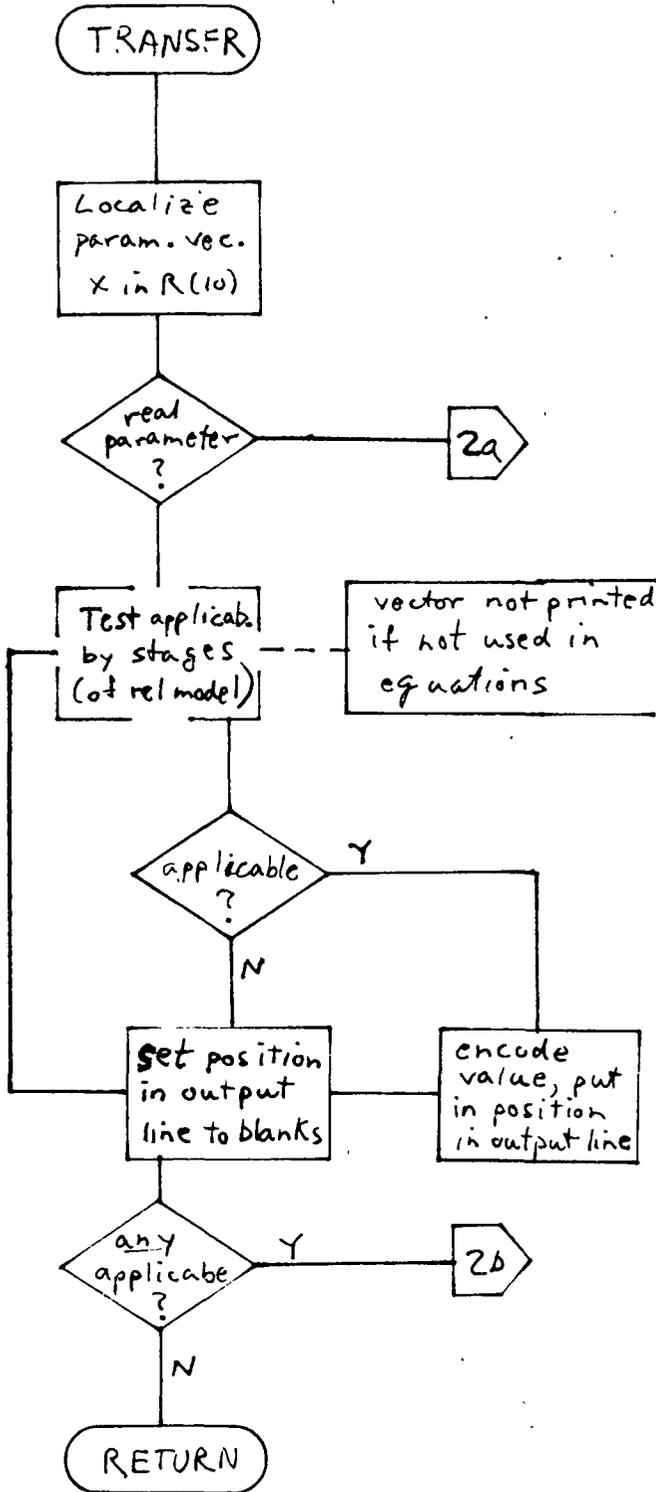
FLOW DIAGRAM

A-6



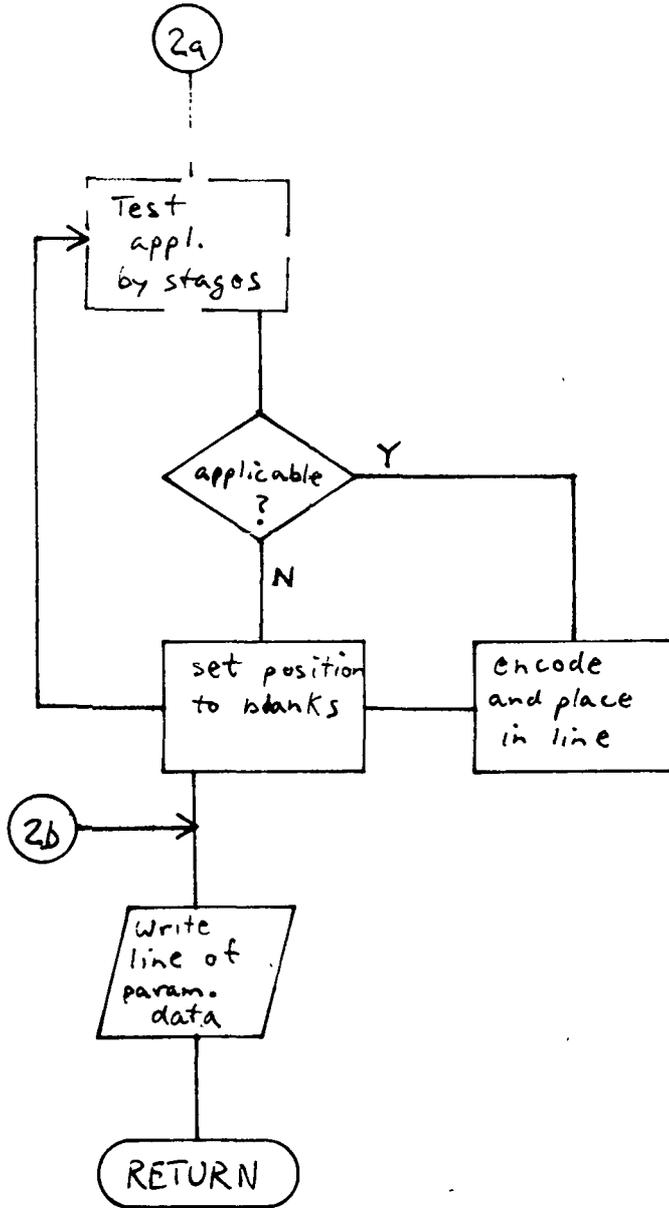
FLOW DIAGRAM

A-7



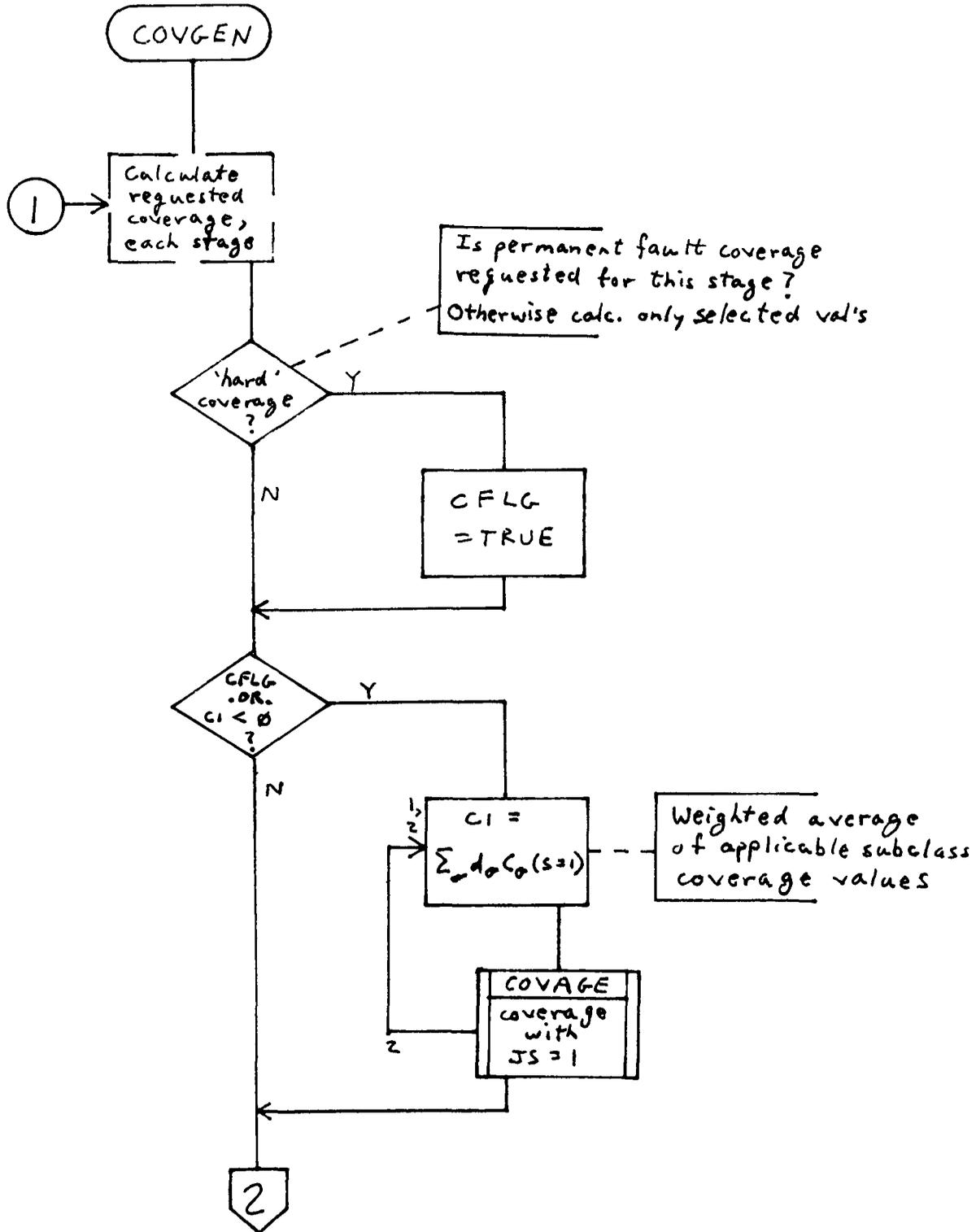
FLOW DIAGRAM

A-7



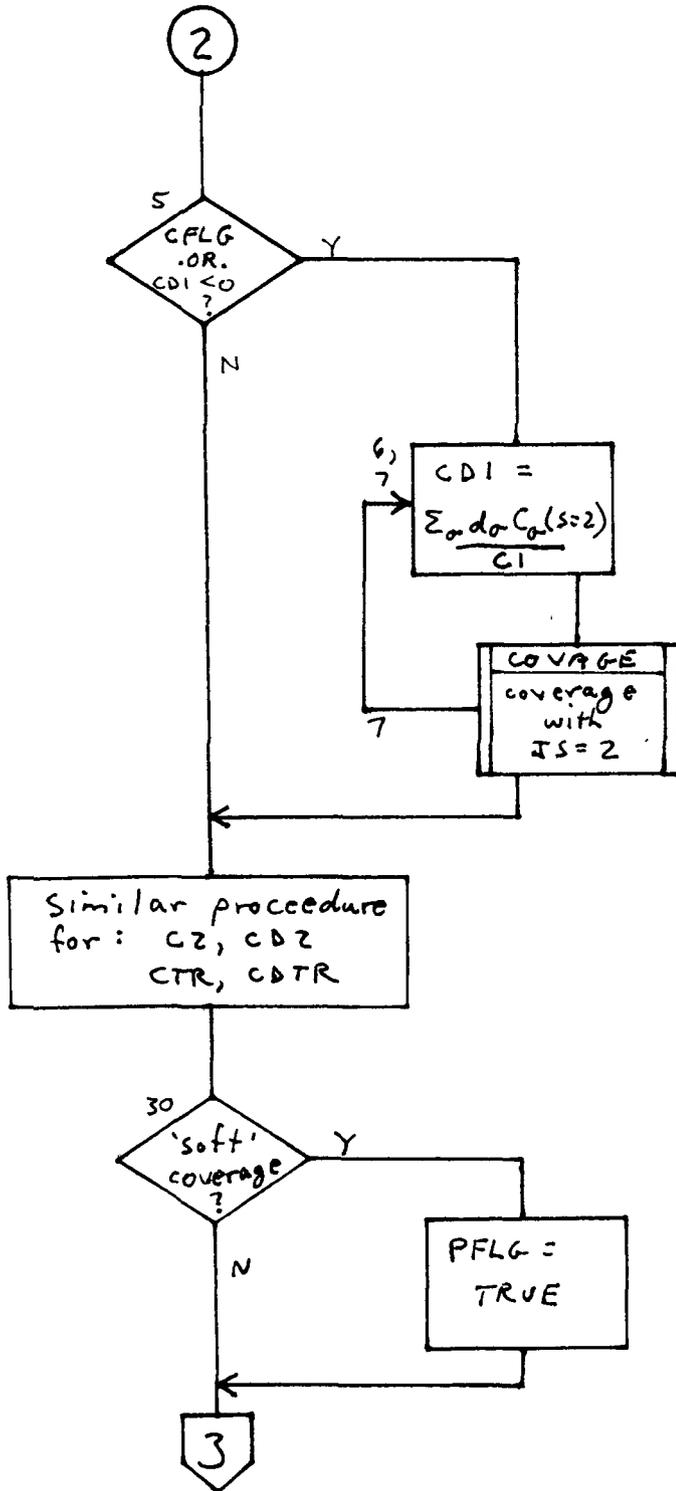
FLOW DIAGRAM

A-8



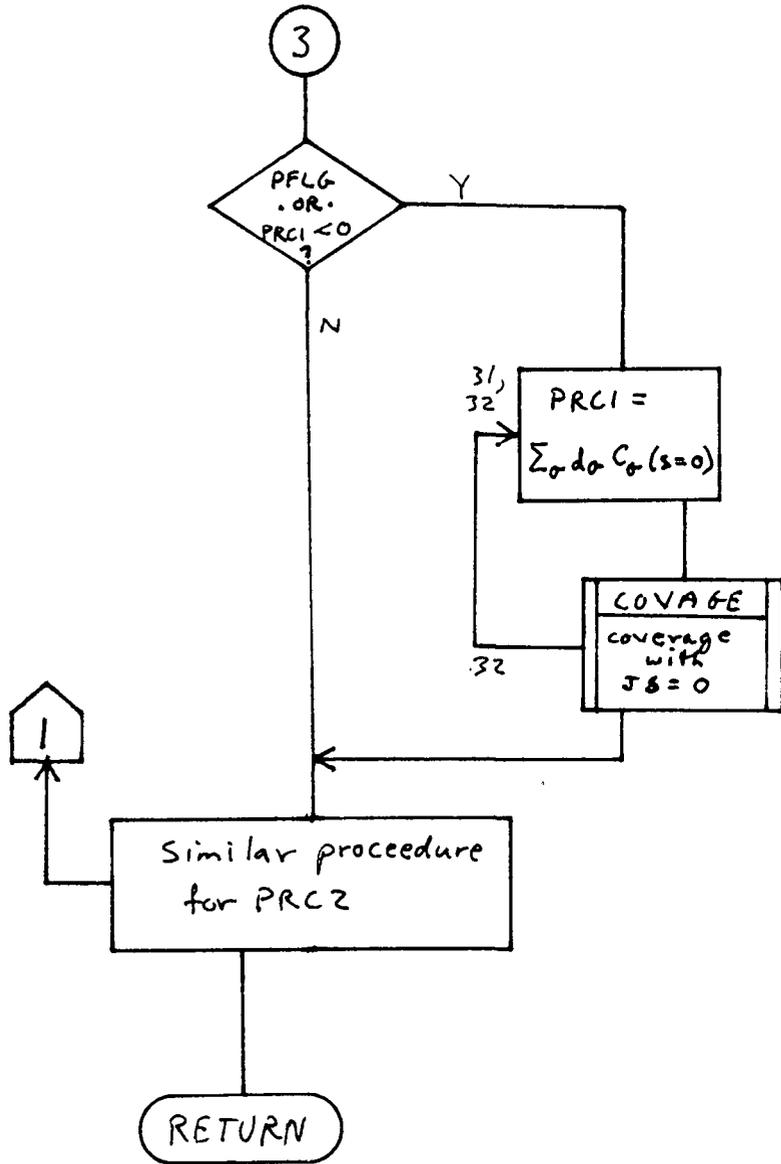
FLOW DIAGRAM

A-8



FLOW DIAGRAM

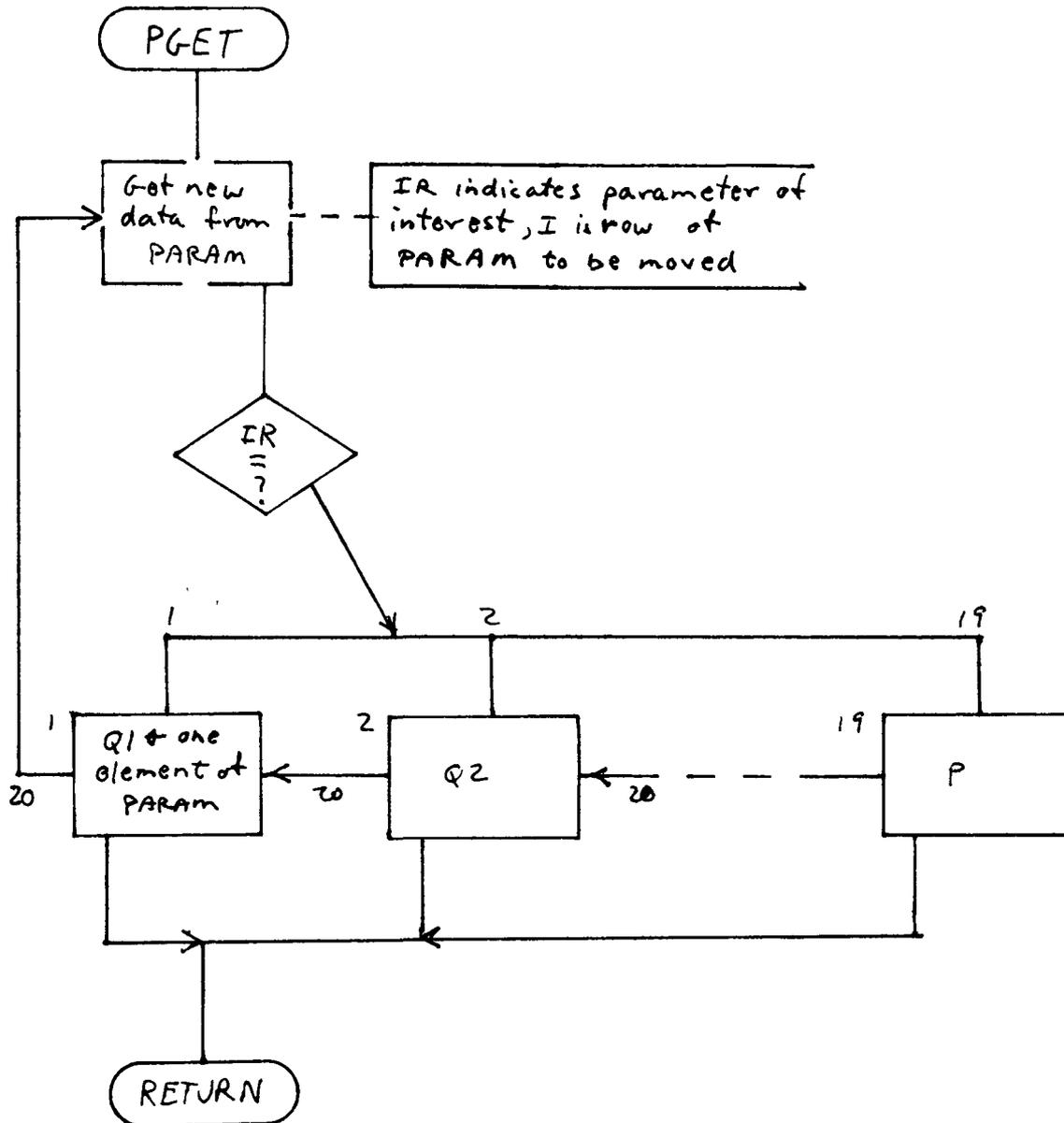
A-8





FLOW DIAGRAM

A-9



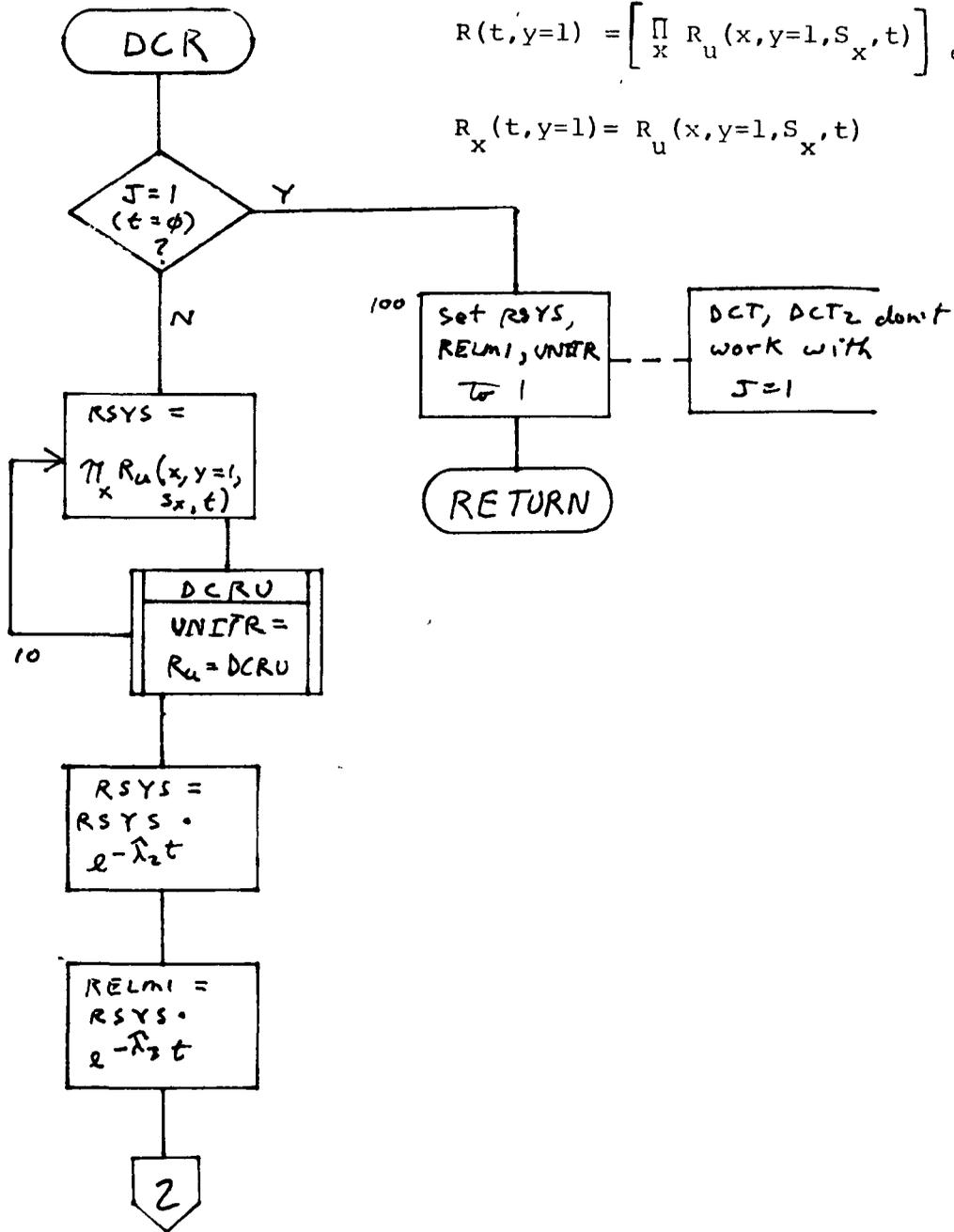
FLOW DIAGRAM

A-10

$$R(t) = \left[\prod_x \left\{ R_u(x, y=1, S_x, t) \right\} * e^{-(\hat{\lambda}_2)t} + \tau_2(t) + \sum_x \left\{ \tau(x, t) \right\} \right] e^{-(\hat{\lambda}_3)t}$$

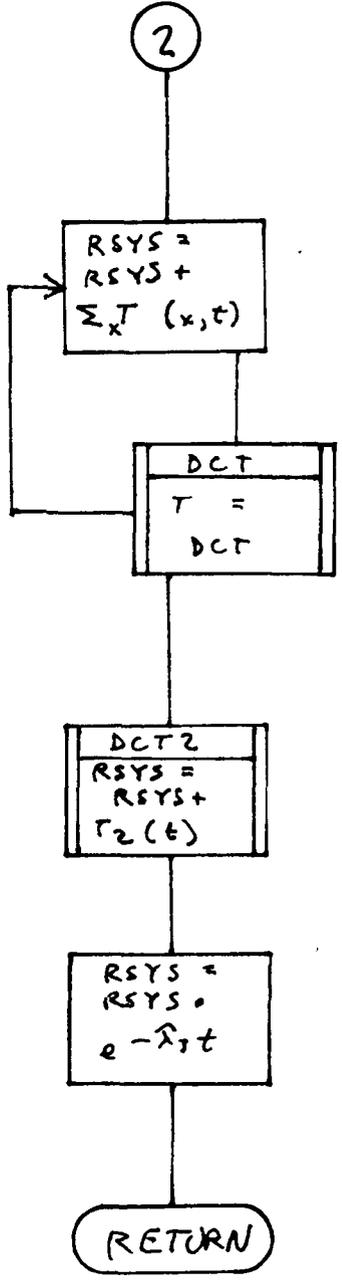
$$R(t, y=1) = \left[\prod_x R_u(x, y=1, S_x, t) \right] e^{-(\hat{\lambda}_2 + \hat{\lambda}_3)t}$$

$$R_x(t, y=1) = R_u(x, y=1, S_x, t)$$



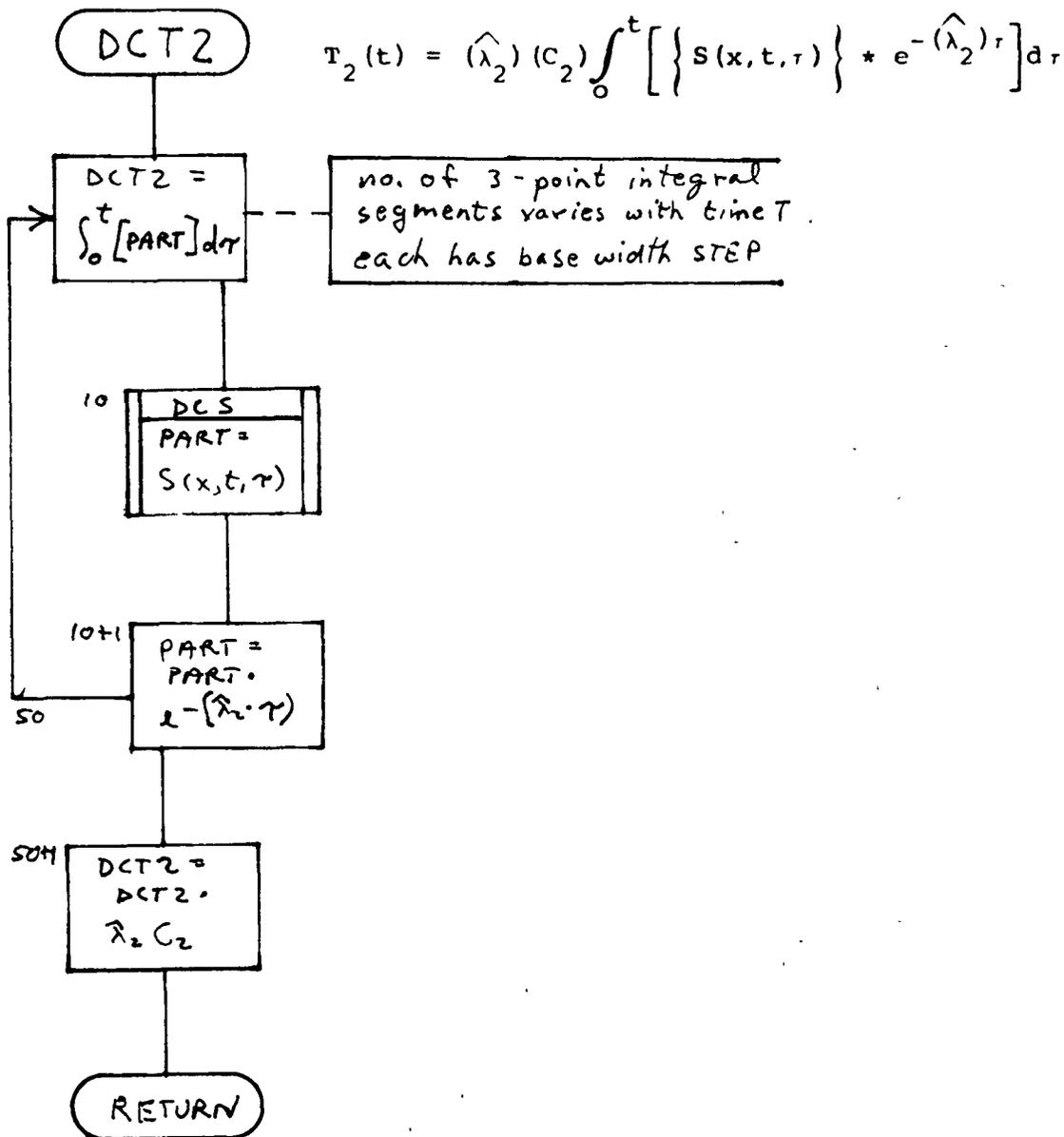
FLOW DIAGRAM

A-10



FLOW DIAGRAM

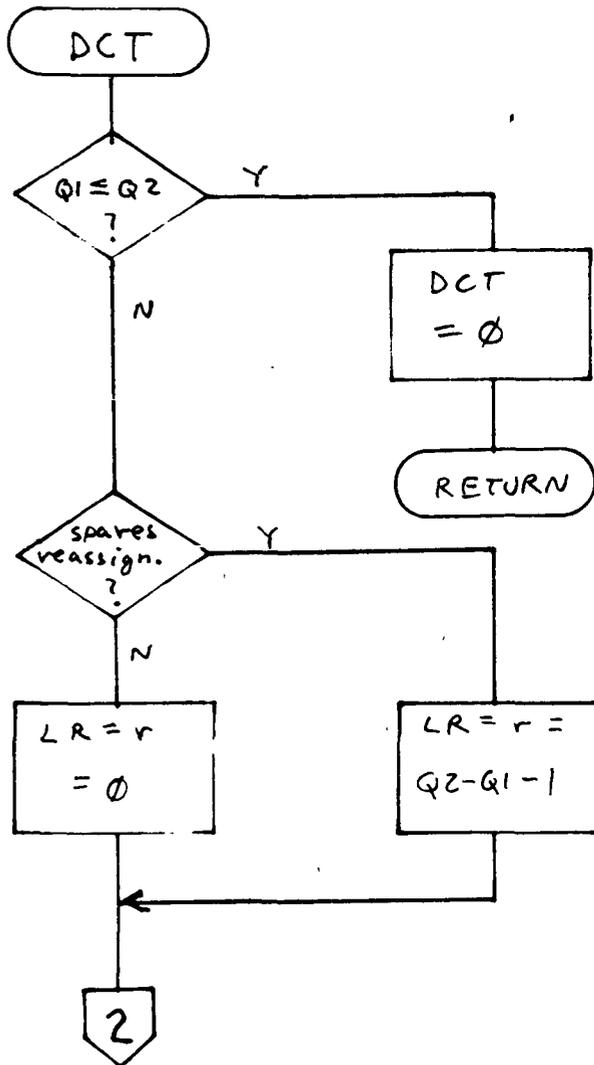
A-11



FLOW DIAGRAM

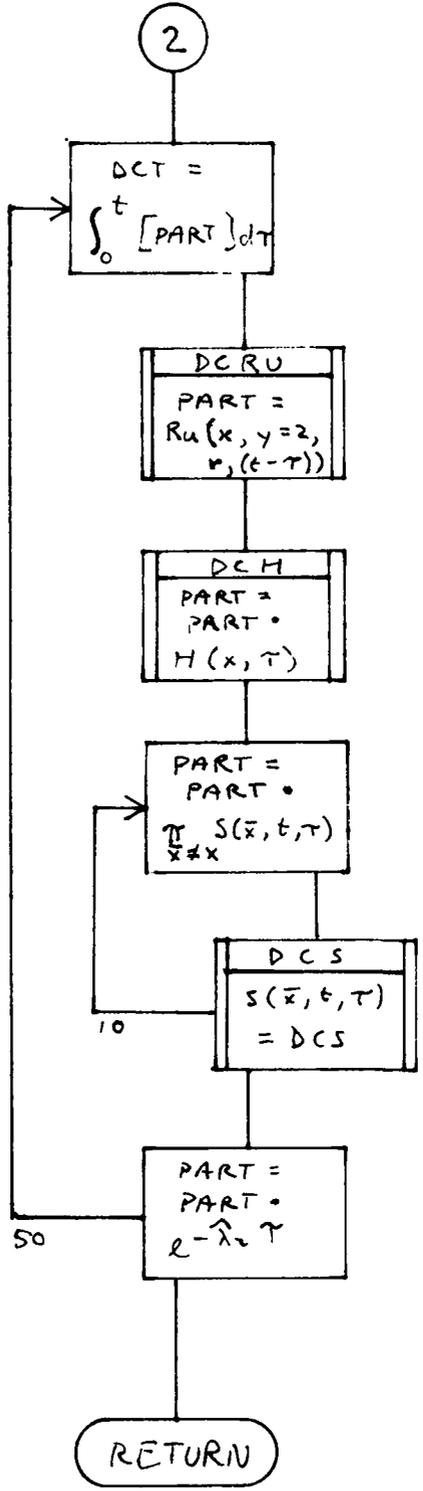
A-12

$$T(x,t) = \begin{cases} \int_0^t \left[\frac{\pi}{x \neq x} \right] S(\bar{x}, t, \tau) \star R_u(x, y=2, r, (t-\tau)) \star H(x, \tau) \star e^{-(\hat{\lambda}_2)\tau} d\tau, & \text{for } Q(x,1) > Q(x,2) \\ 0, & \\ \int_0^t \left[\frac{\pi}{x \neq x} \right] S(\bar{x}, t, \tau) \star R_u(x, y=2, r, (t-\tau)) \star H(x, \tau) \star e^{-(\hat{\lambda}_2)\tau} d\tau, & \text{for } Q(x,1) \leq Q(x,2) \end{cases}$$



FLOW DIAGRAM

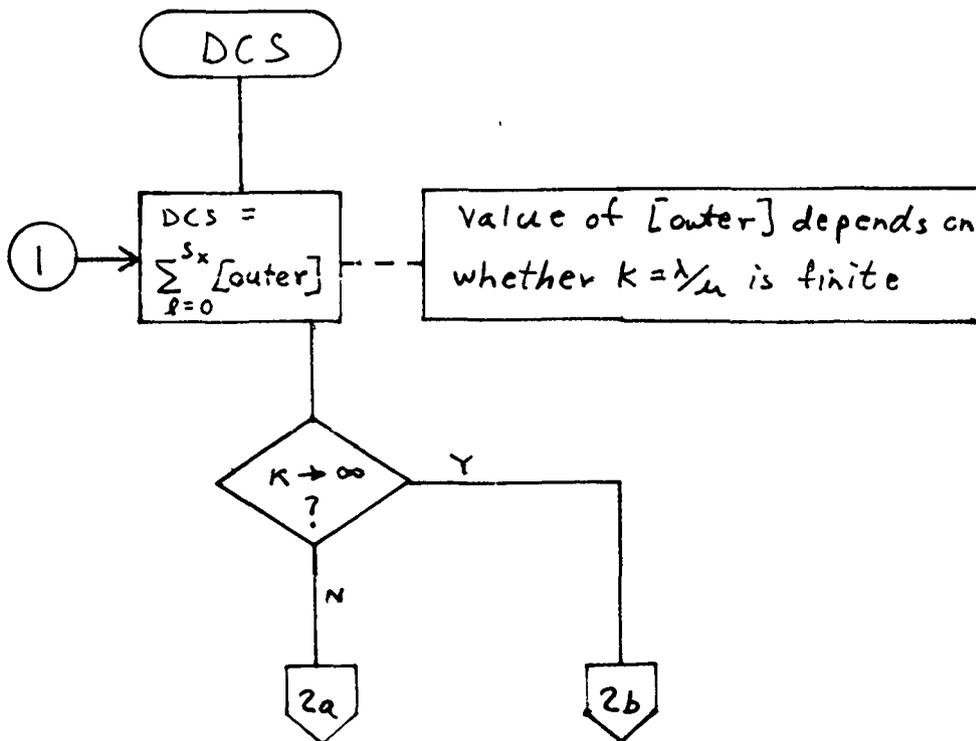
A-12



FLOW DIAGRAM

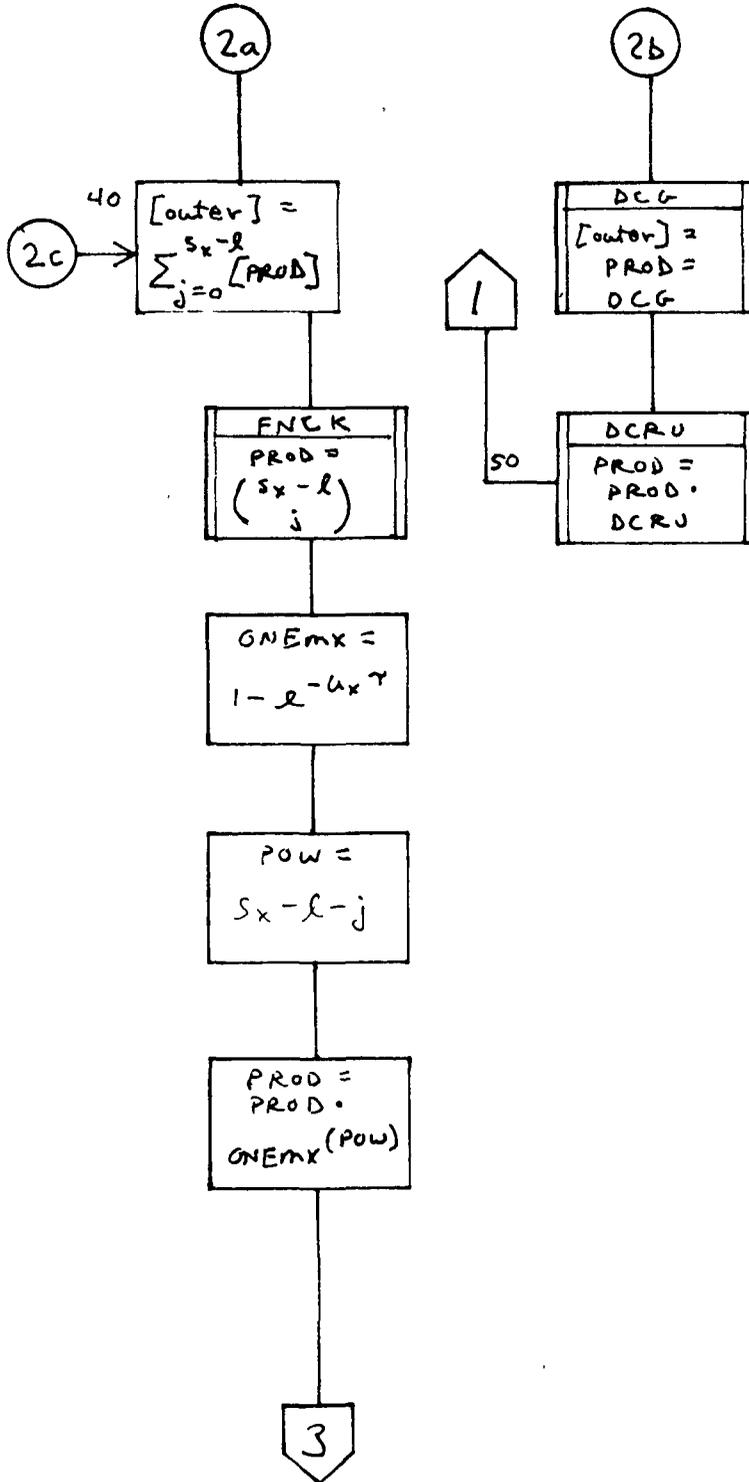
A-13

$$S(x, t, \tau) = \left\{ \begin{array}{l} \sum_{l=0}^{(S_x)} \left[\sum_{j=0}^{(S_x-l)} \binom{(S_x-l)}{j} * (1 - e^{-(\mu_x)\tau}) * ((S_x-l-j) * e^{-j(\mu_x)\tau} * G(x, y=1, l, \tau) * R_u(x, y=2, j', (t-\tau))) \right] \\ \text{for } K < \infty \\ \sum_{l=0}^{(S_x)} \left[G(x, y=1, l, \tau) * R_u(x, y=2, [(S_x-l)', (t-\tau)]) \right] \\ \text{for } K = \infty \end{array} \right.$$



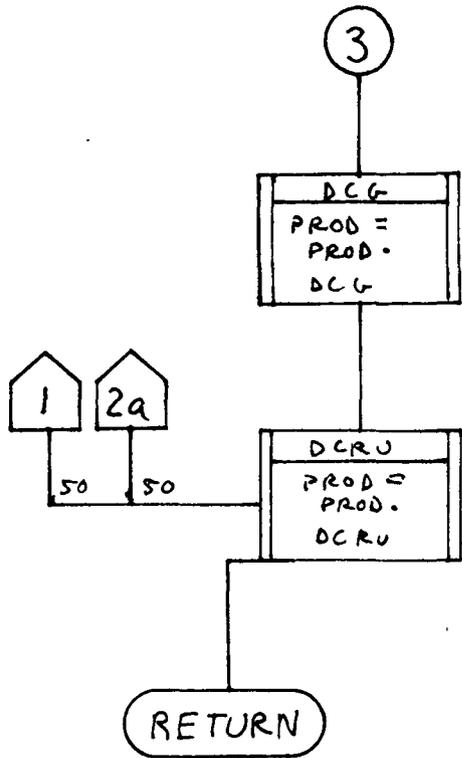
FLOW DIAGRAM

A-13



FLOW DIAGRAM

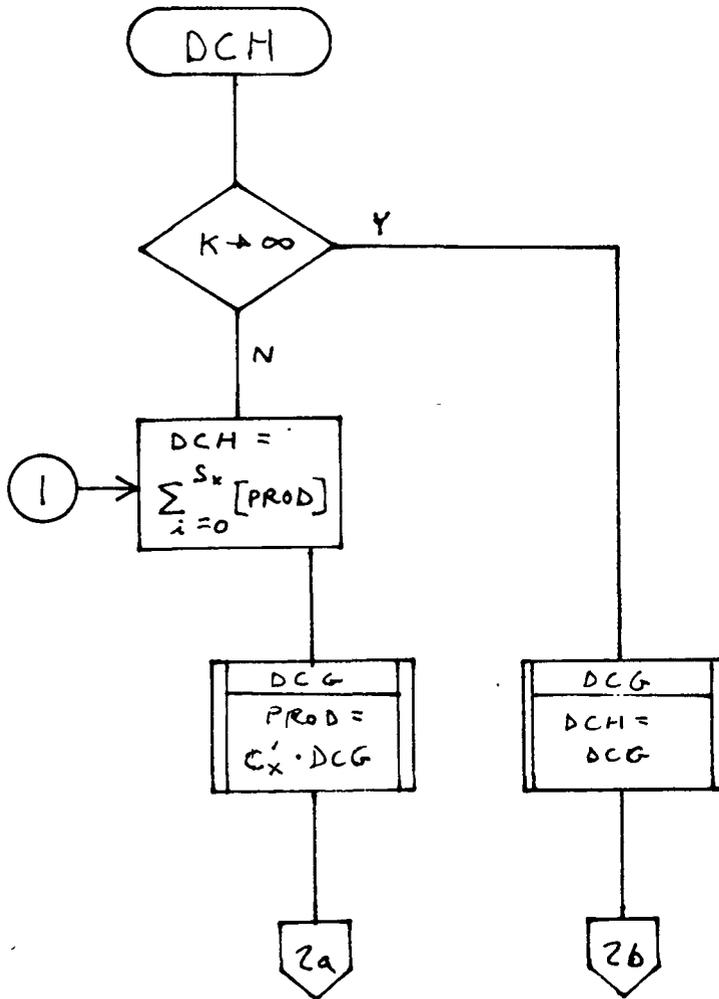
A-13



FLOW DIAGRAM

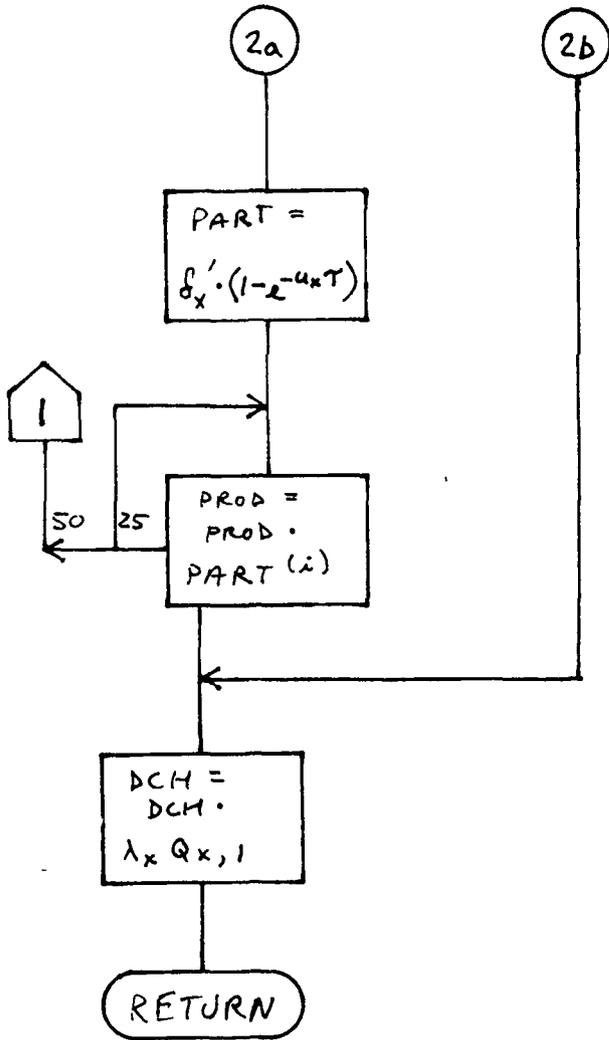
A-14

$$H(x, \tau) = \begin{cases} Q_{x,1} \lambda_x \sum_{i=0}^{(S_x)} \left\{ G(x, y=1, [(S_x)-i], \tau) * (C'_x) (\delta'_x)^i * (1-e^{-(\mu_x)\tau})^i \right\}, & \text{for } Y < \infty \\ \lambda_x Q_{x,1} (C'_x) * G(x, y=1, (S_x), \tau), & \text{for } K = \infty \end{cases}$$



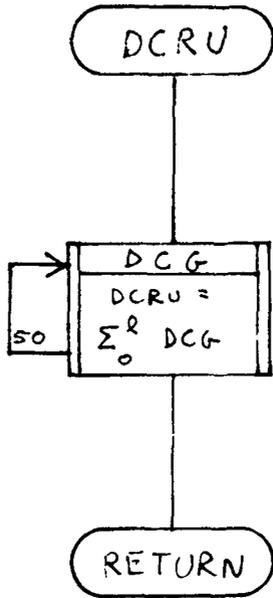
FLOW DIAGRAM

A-14



FLOW DIAGRAM

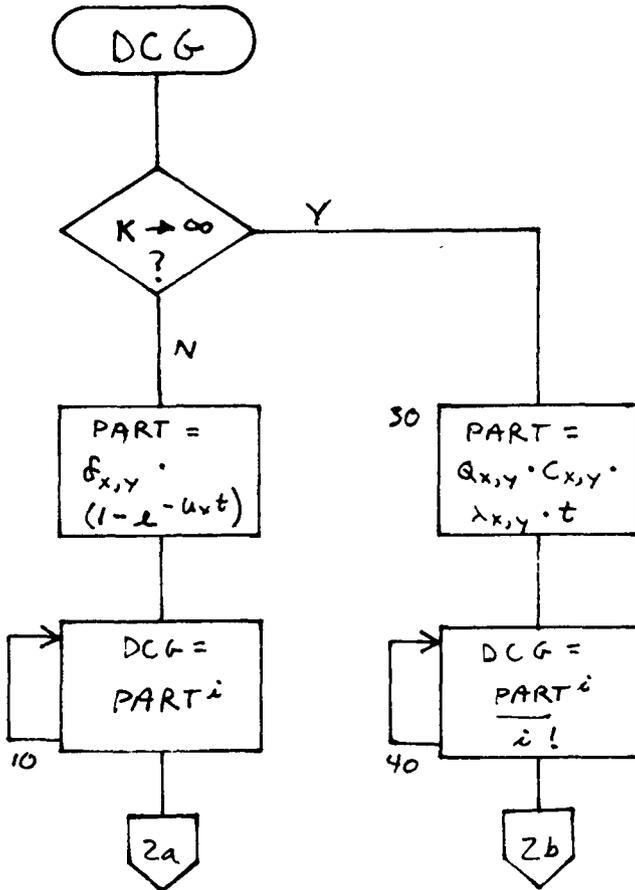
A-15



$$R_u(x, y, l, r) = \sum_{i=0}^l G(x, y, i, r)$$

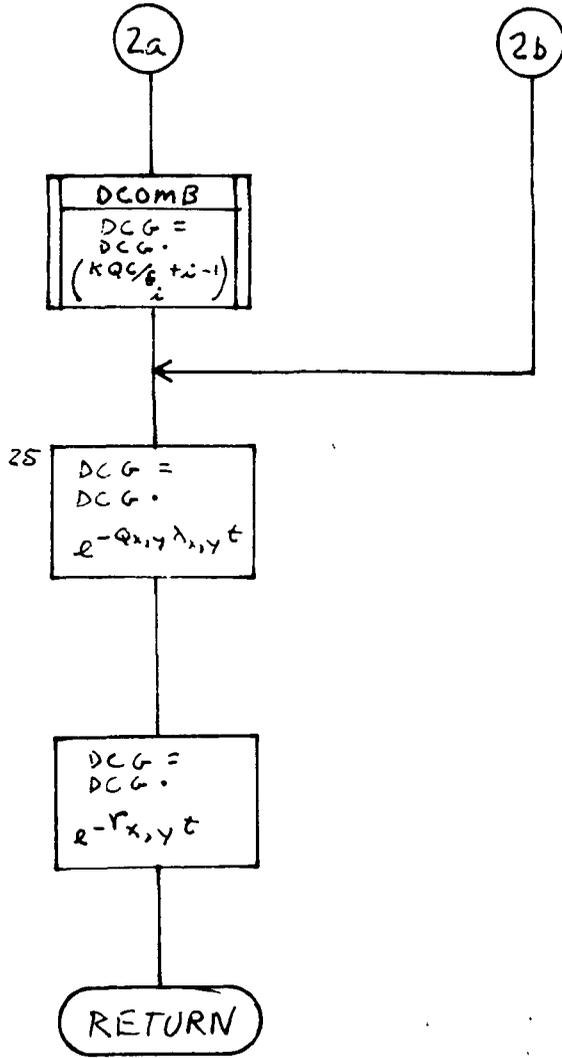
FLOW DIAGRAM
A-16

$$G(x,y,i,t) = \begin{cases} e^{-(\gamma_{x,y})t} * (\delta_{x,y})^i * \binom{(K_x) (Q_{x,y}) (C_{x,y}) (\delta_{x,y})^{-1+i-1}}{i} * \\ (1-e^{-(\mu_x)t})^i * e^{-(Q_{x,y}) (\lambda_x)t} & \text{for } K < \infty \\ e^{-(\gamma_{x,y})t} * \frac{\binom{(Q_{x,y}) (C_{x,y}) (\lambda_x)t}{i!}}{i!} * e^{-(Q_{x,y}) (\lambda_x)t}, & \text{for } K = \infty \end{cases}$$



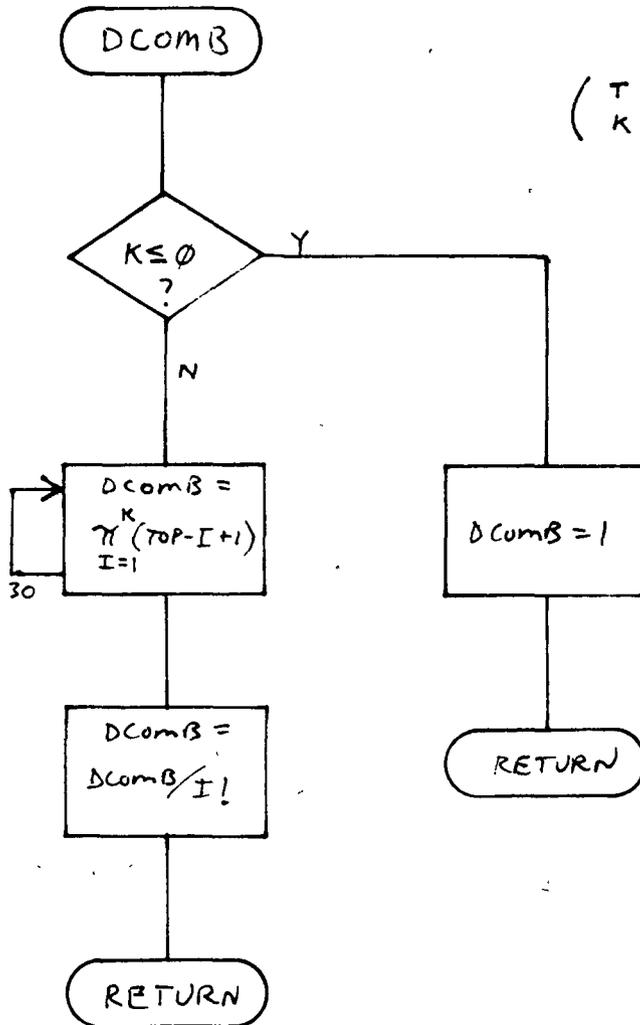
FLOW DIAGRAM

A-16



FLOW DIAGRAM

A-17

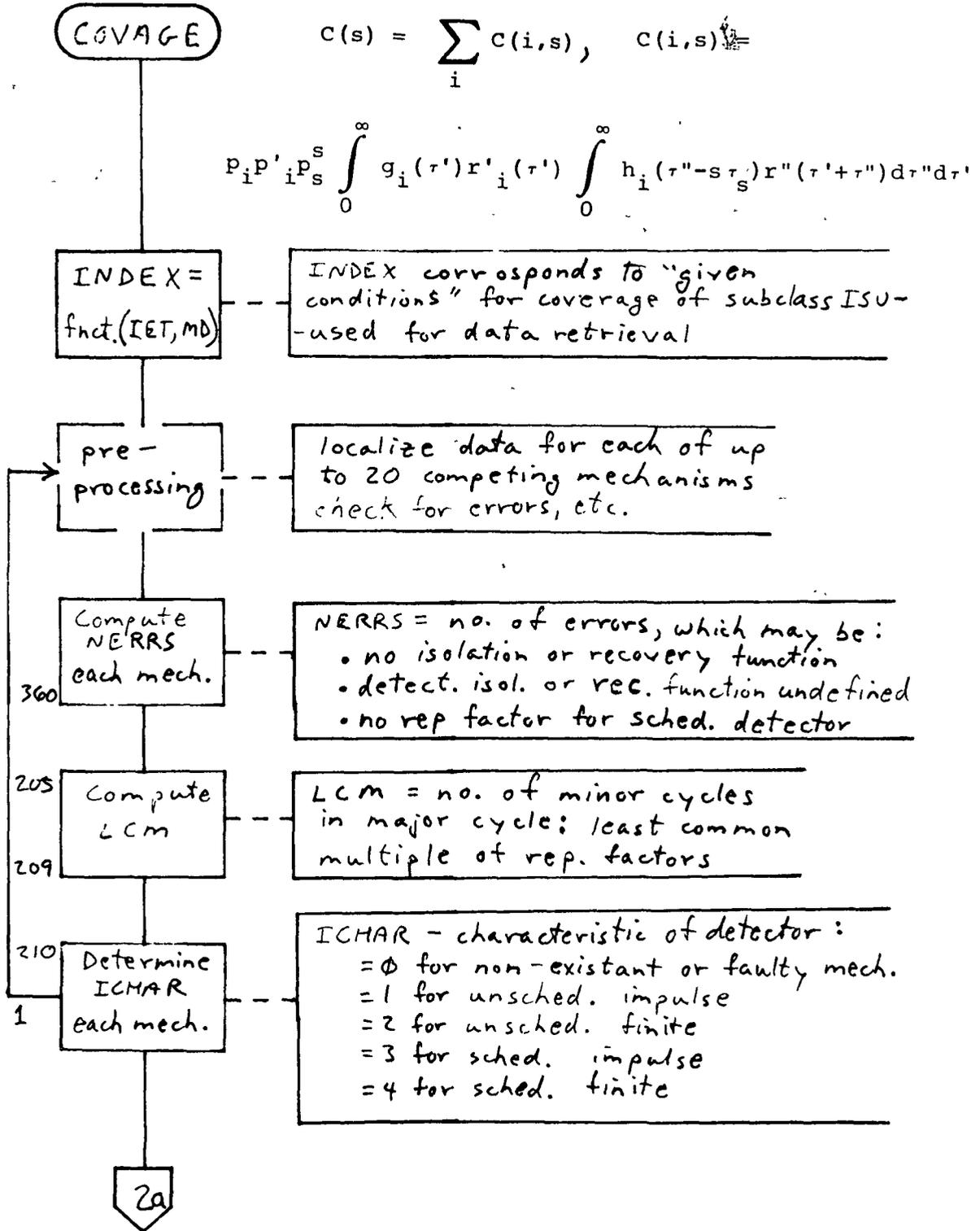


$$\binom{T}{K} = \begin{cases} \frac{1}{K!} \prod_{z=1}^K (T-K+1), & \text{for } K > 0 \\ 1, & \text{for } K \leq 0 \end{cases}$$



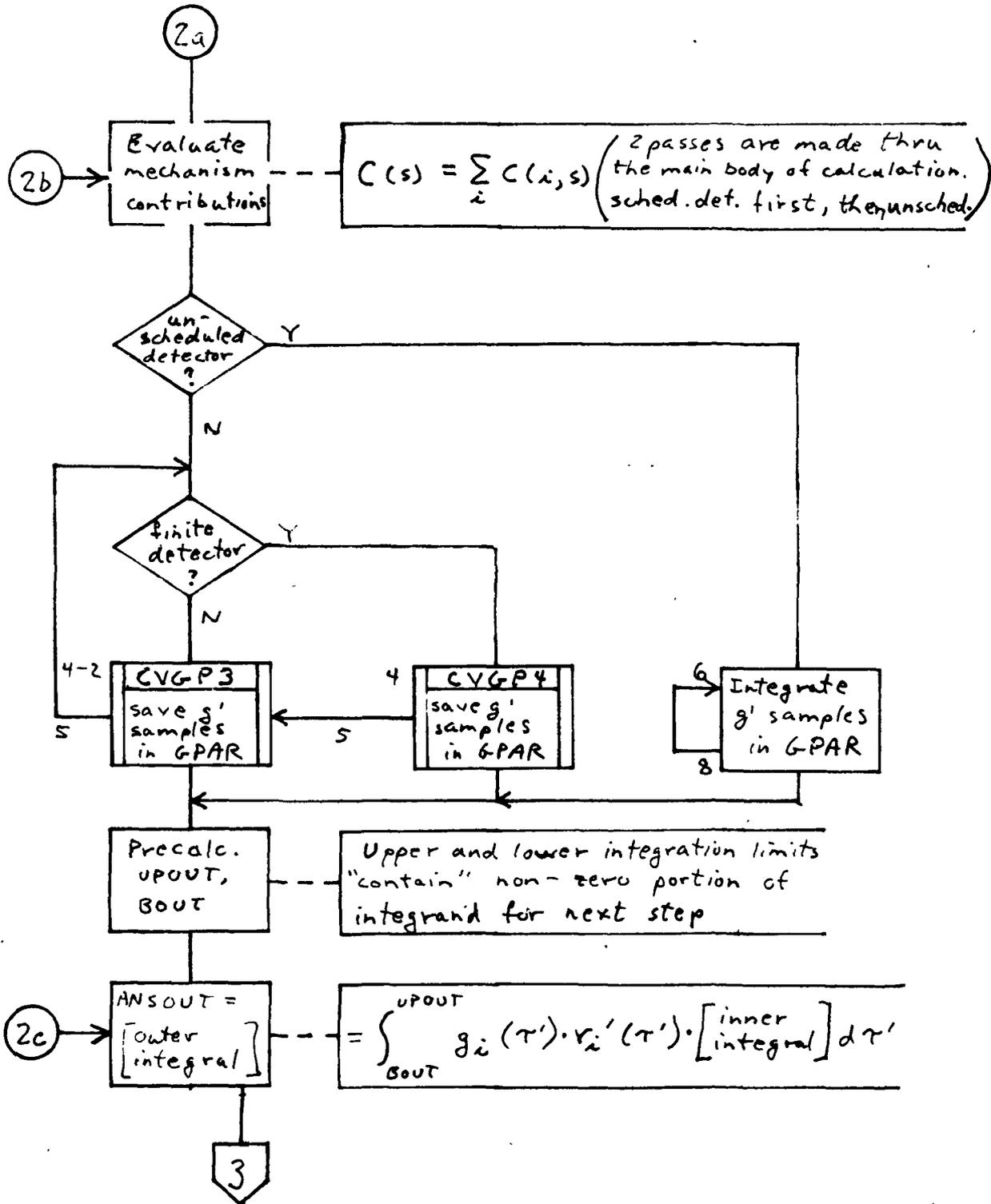
FLOW DIAGRAM

A-18



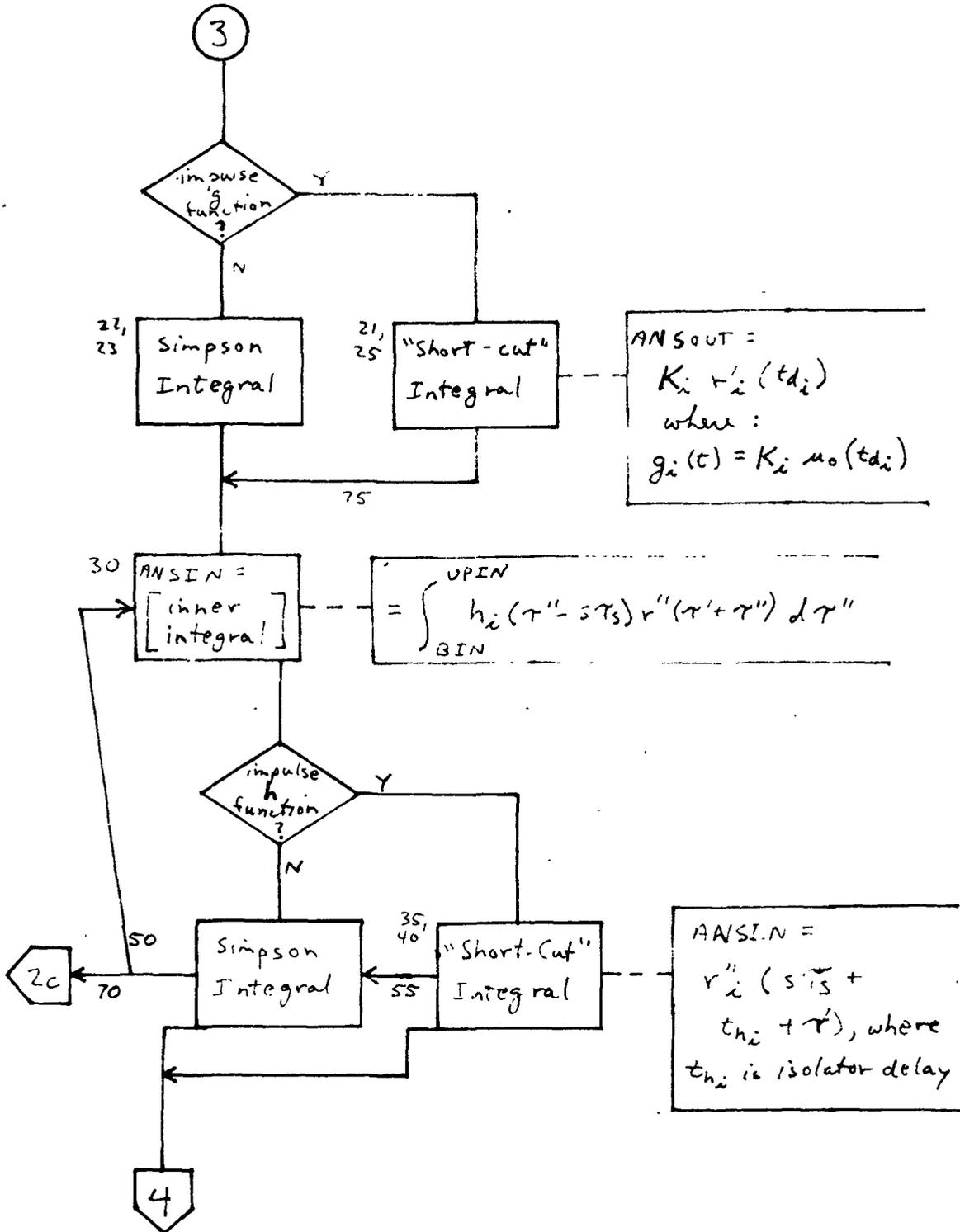
FLOW DIAGRAM

A-18



FLOW DIAGRAM

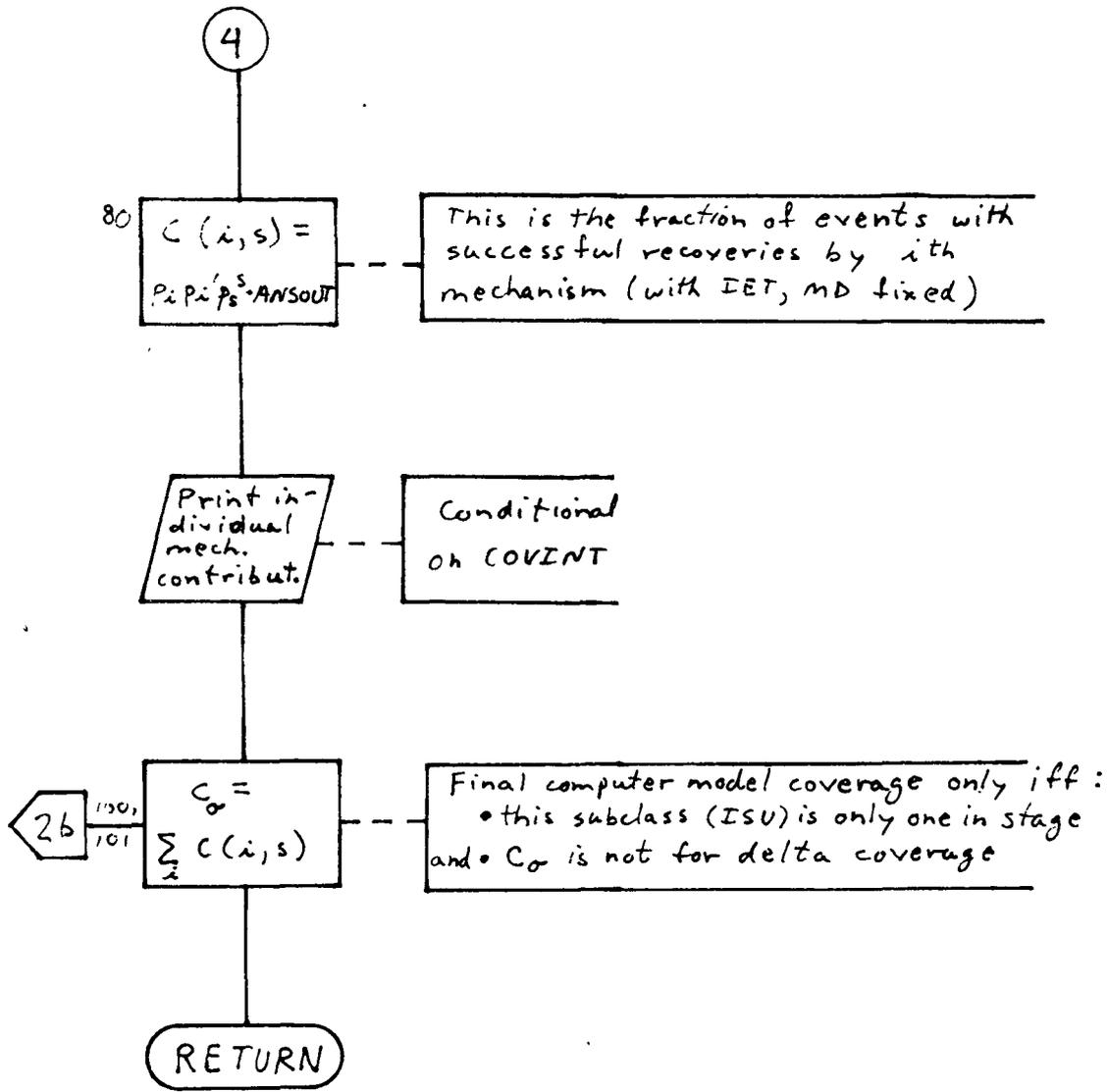
A-18





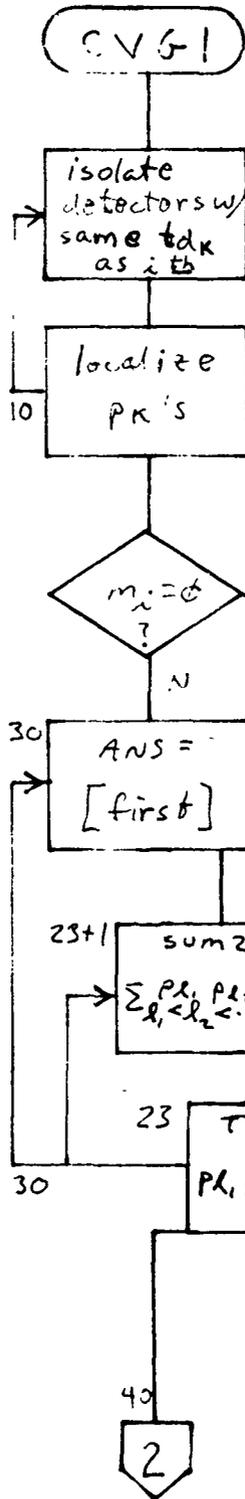
FLOW DIAGRAM

A-18



FLOW DIAGRAM

A-19



$$g_i(\tau) = \left[1 - \sum_{v=1}^{m_i} \frac{(-1)^{v+1}}{v+1} \sum_{l_1 < l_2 < \dots < l_v} p_{l_1} p_{l_2} \dots p_{l_v} \right] *$$

$$\prod_{\substack{k \neq i \\ k \neq l_1, l_2, \dots, l_{m_i}}} \left[1 - p_k F_k(t_{d_i} - t_{d_k}) \right] * \left[1 - \sum_j p_j \int_0^{t_{d_i}} g_j'(\eta) d\eta \right] *$$

$$\mu_0(\tau - \tau_{d_i}), \quad \text{for } f_i(\tau) = \mu_0(\tau - \tau_{d_i})$$

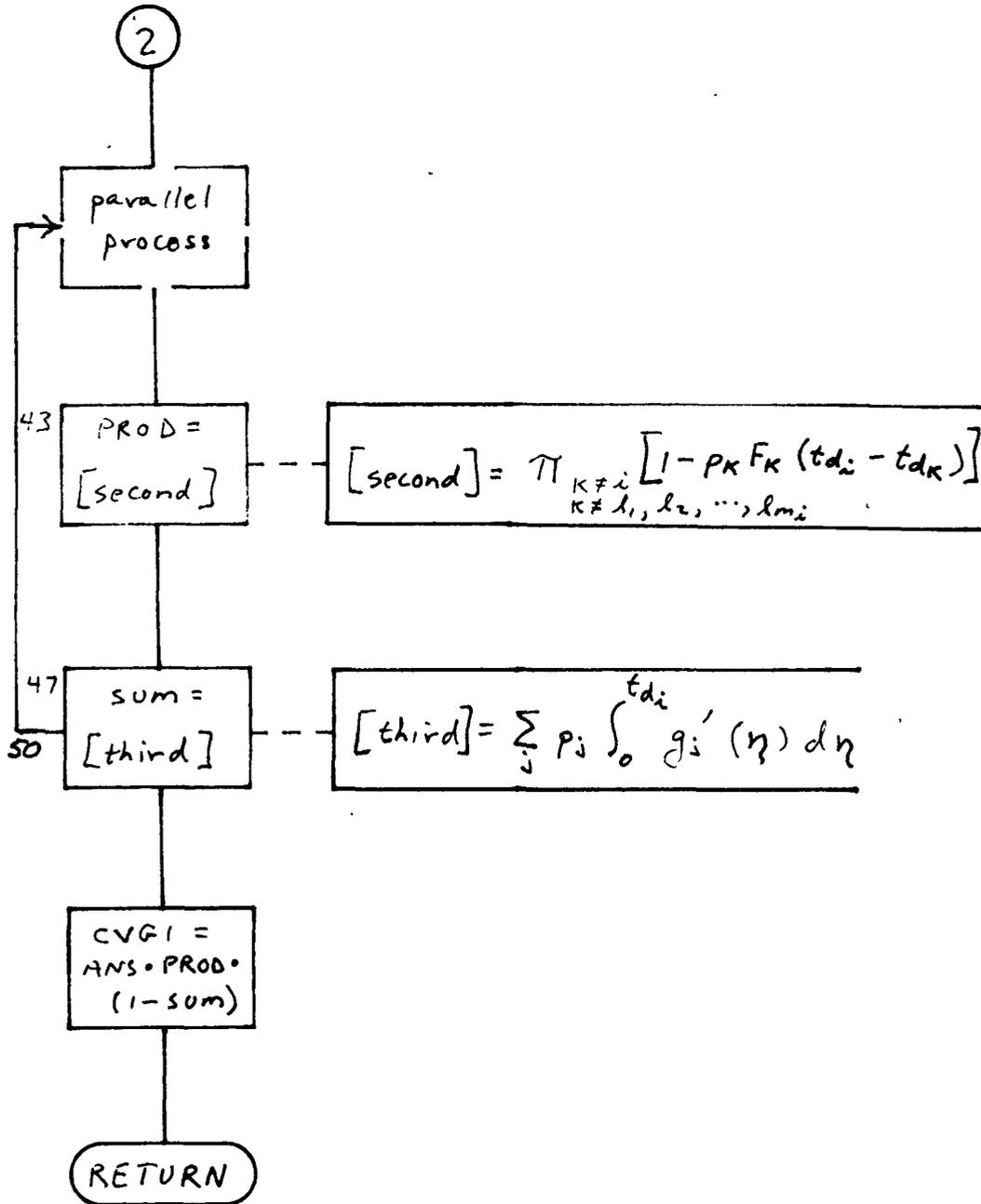
where $\mu_0(x)$ is a unit impulse at $x = 0$

$$[first] = \left[1 - \sum_{v=1}^{m_i} \frac{(-1)^{v+1}}{v+1} \sum_{l_1 < l_2 < \dots < l_v} p_{l_1} p_{l_2} \dots p_{l_v} \right]$$

mechanics of determining l_{μ} 's in statements 23+2 thru 26+2

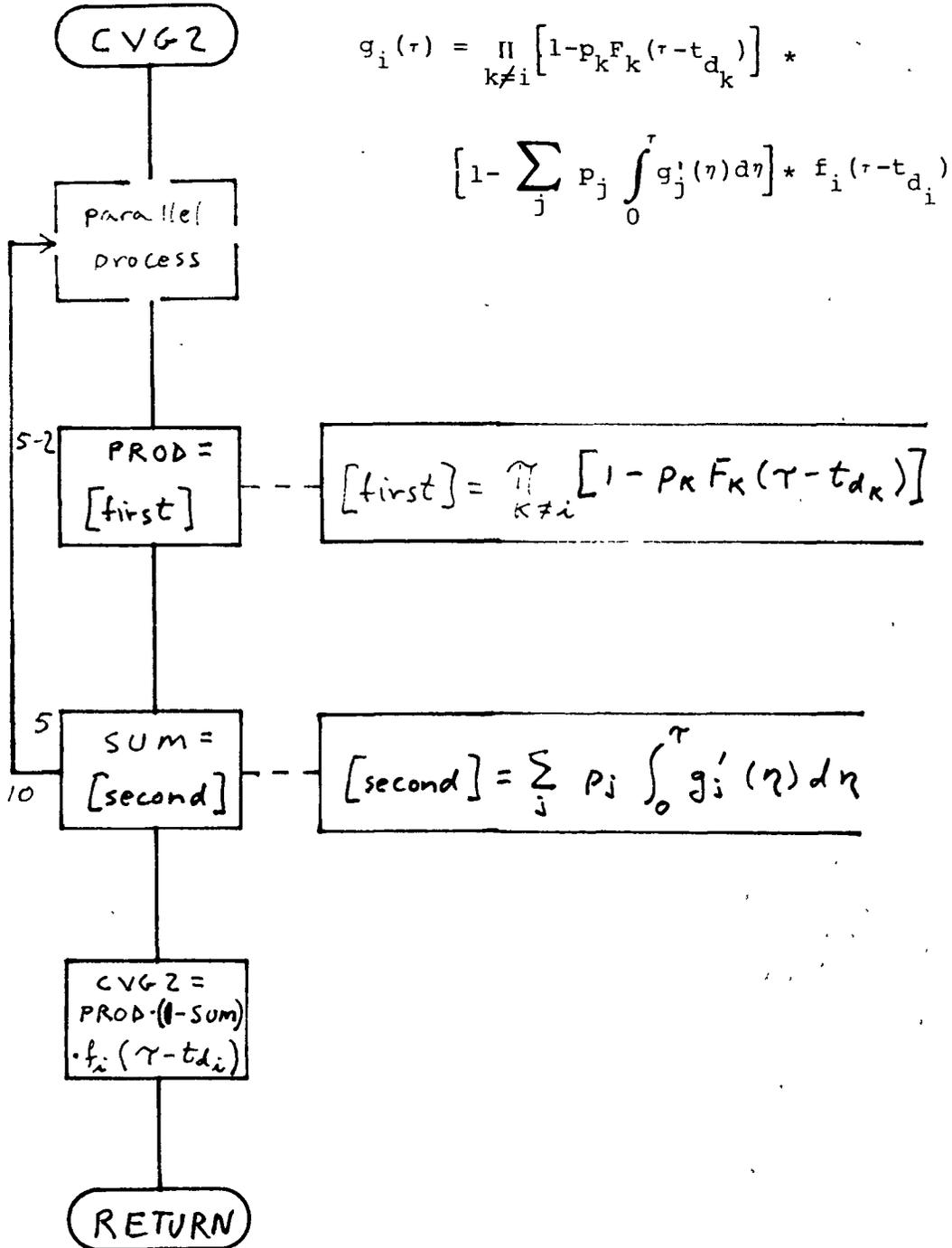
FLOW DIAGRAM

A-19



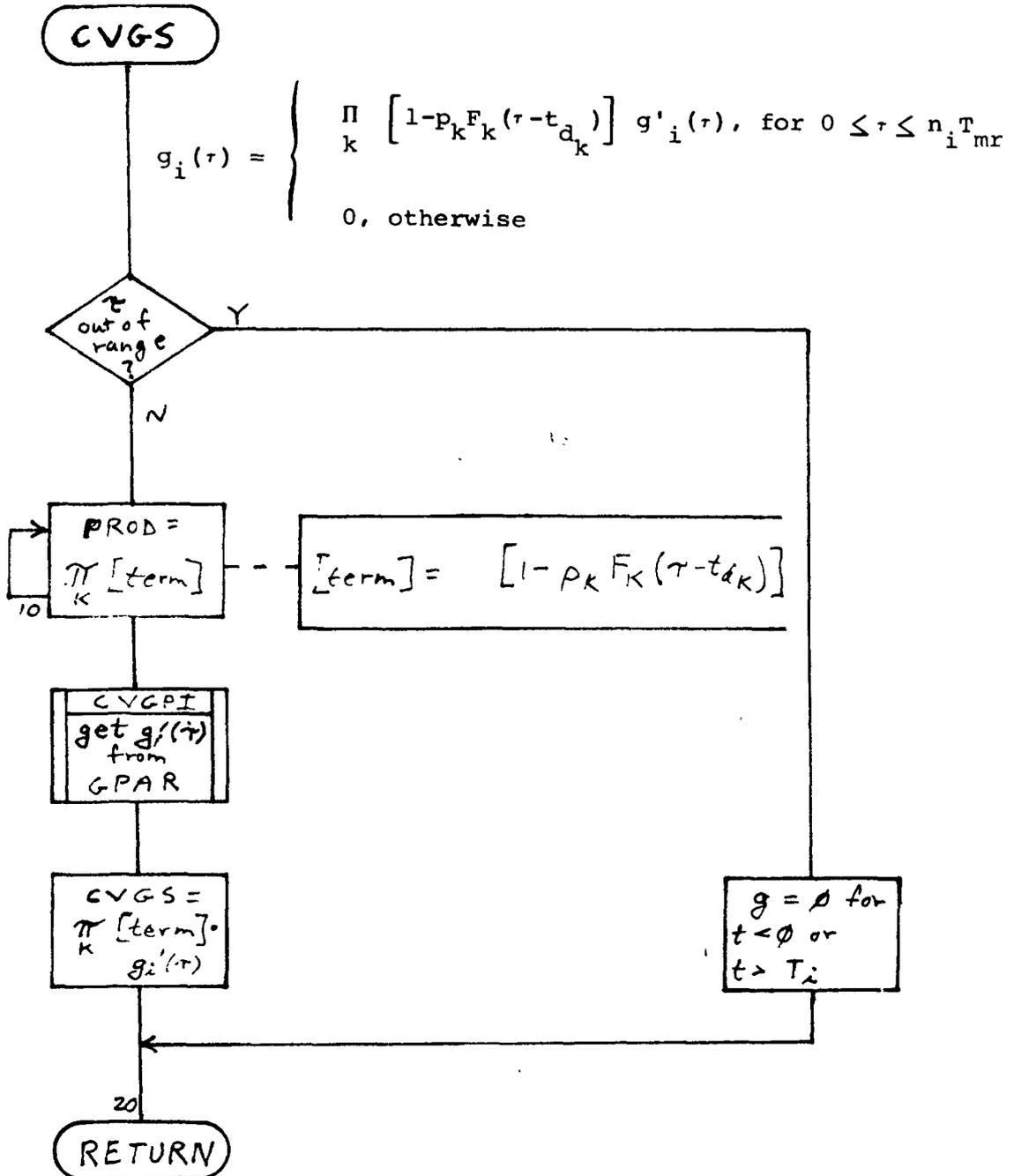
FLOW DIAGRAM

A-20



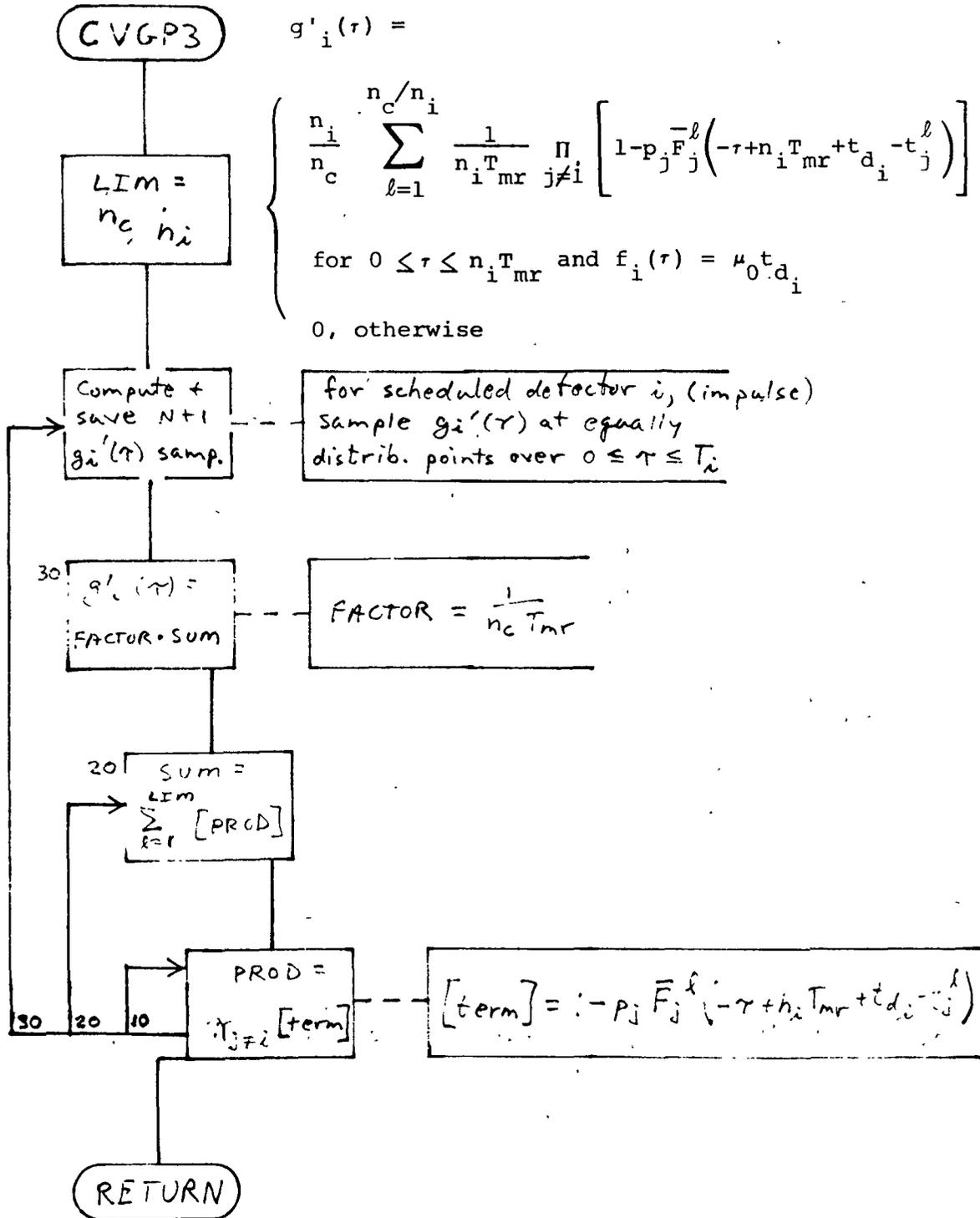
FLOW DIAGRAM

A-21



FLOW DIAGRAM

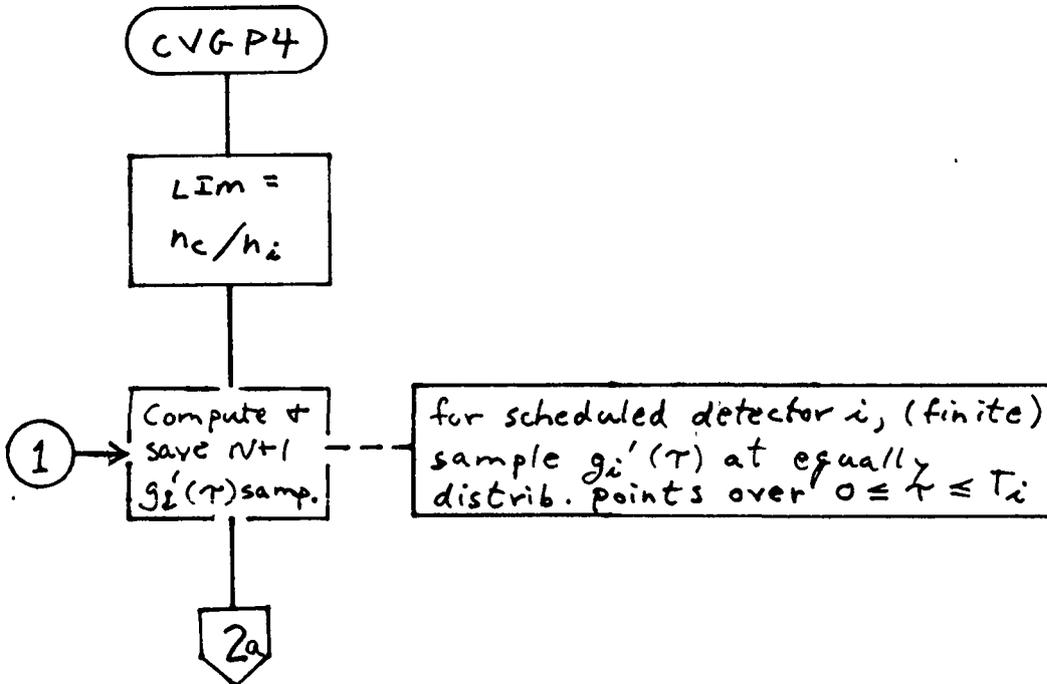
A-22



FLOW DIAGRAM

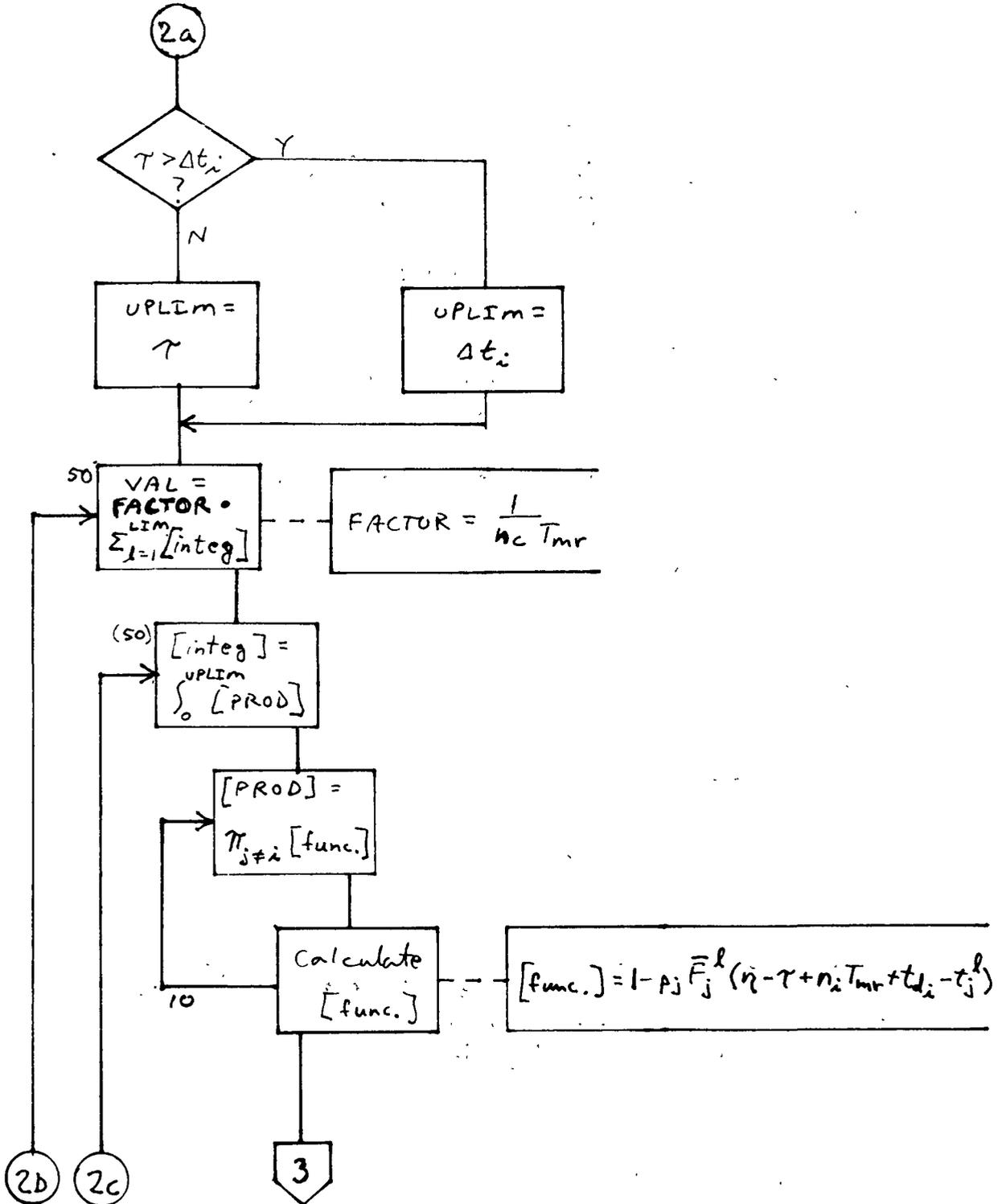
A-23

$$g'_i(\tau) = \begin{cases} \frac{1-F_i(\tau)}{n_i T_{mr}} + \frac{n_i}{n_c} \sum_{l=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \int_0^{\tau} \prod_{j \neq i} [1-p_j \bar{F}_j^l(\eta - \tau + n_i T_{mr} + t_{d_i} - t_j^l)] \\ \quad * f_i(\eta) d\eta & \text{for } 0 \leq \tau \leq \Delta t_i \\ \frac{n_i}{n_c} \sum_{l=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \int_0^{\Delta t_i} \prod_{j \neq i} [1-p_j \bar{F}_j^l(\eta - \tau + n_i T_{mr} + t_{d_i} - t_j^l)] \\ \quad * f_i(\eta) d\eta & \text{for } \Delta t_i < \tau \leq n_i T_{mr} \\ 0, & \text{otherwise} \end{cases}$$



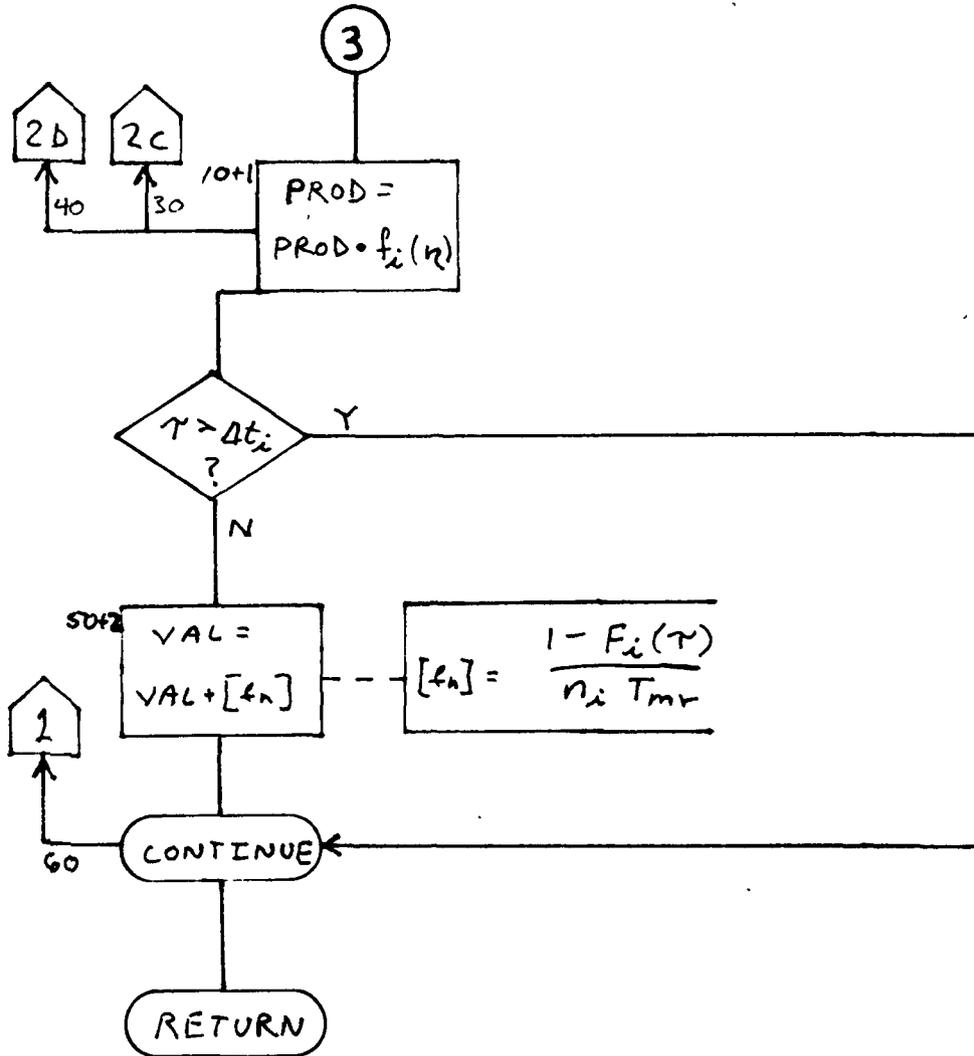
FLOW DIAGRAM

A-23



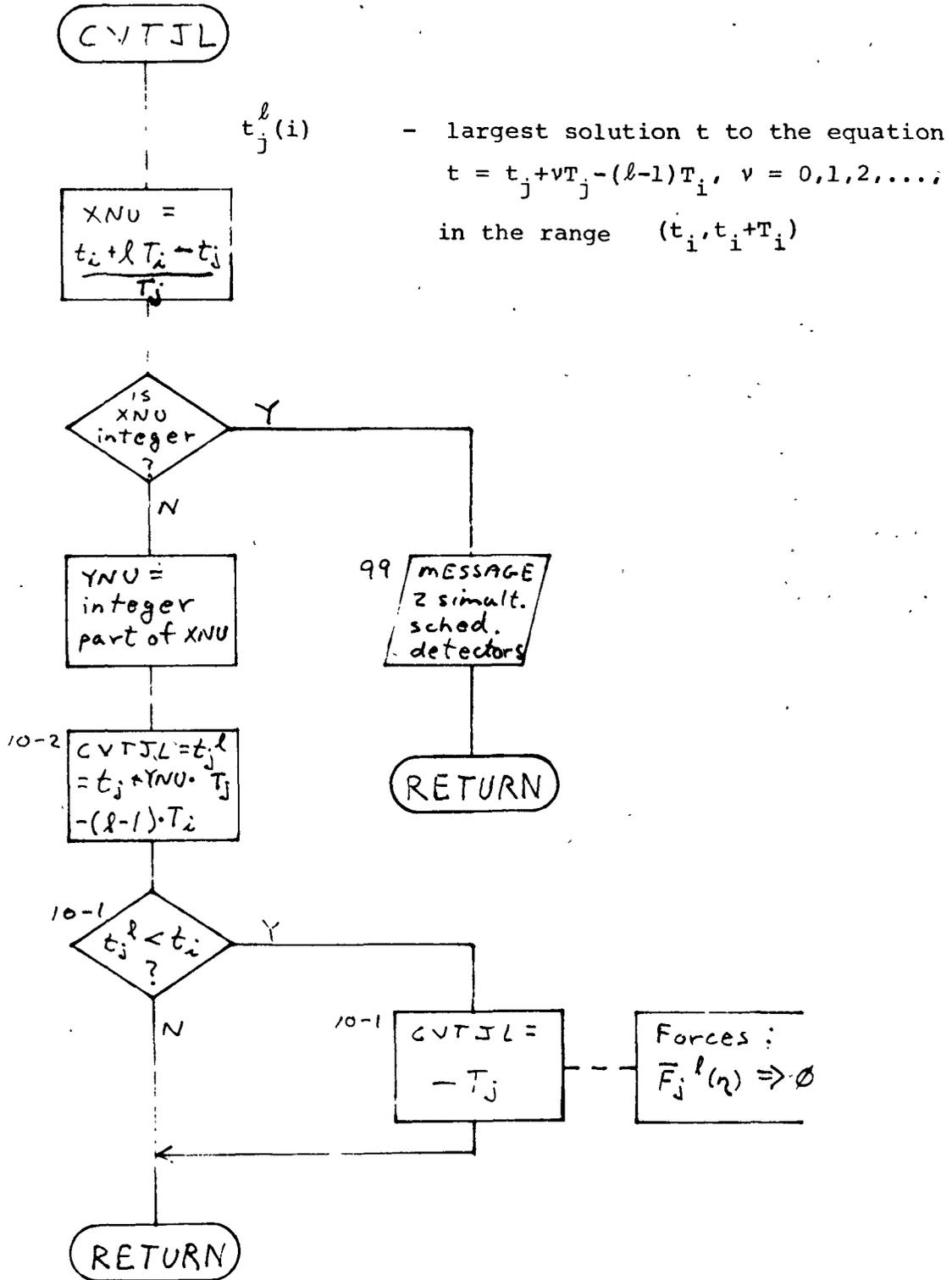
FLOW DIAGRAM

A-23



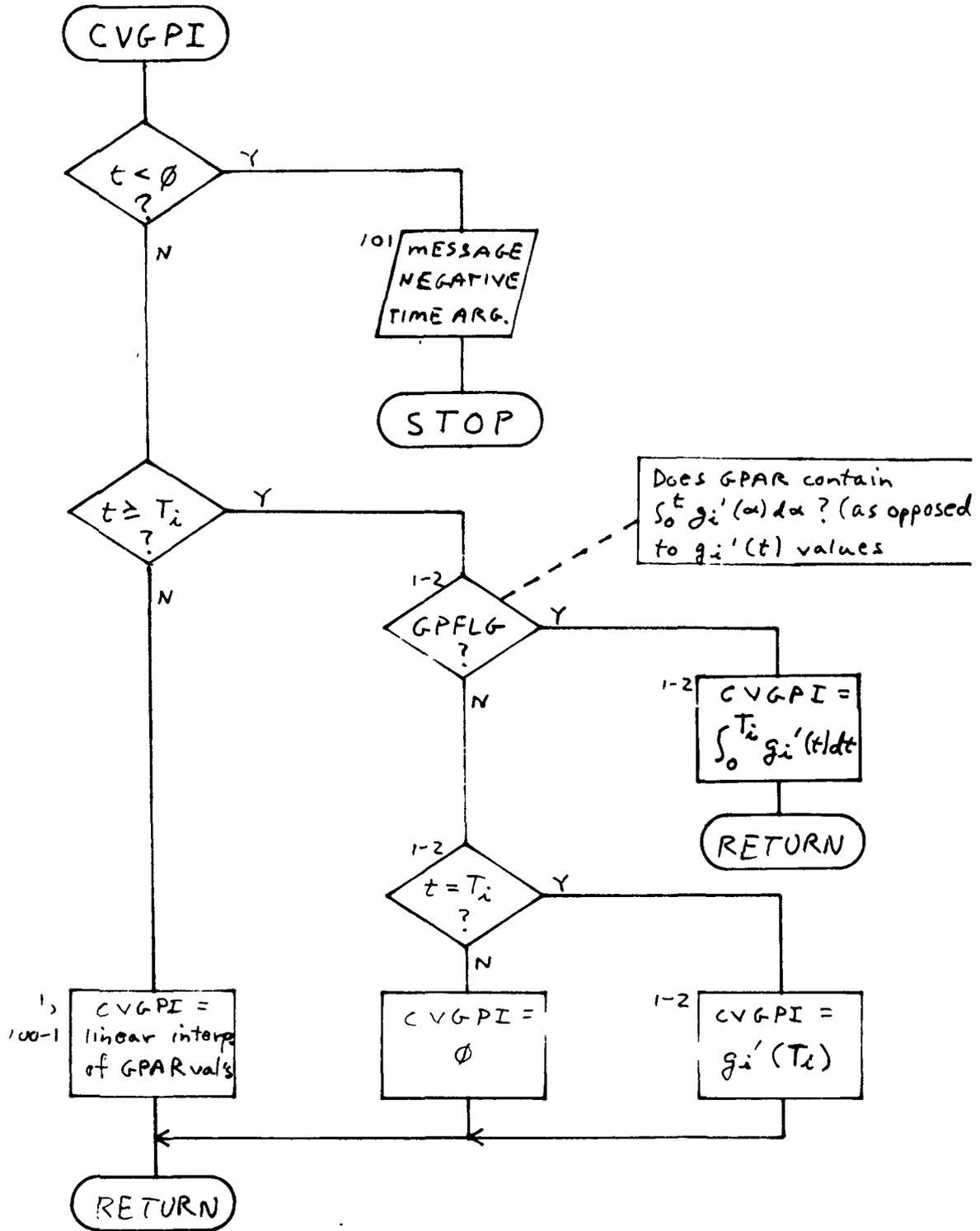
FLOW DIAGRAM

A-24



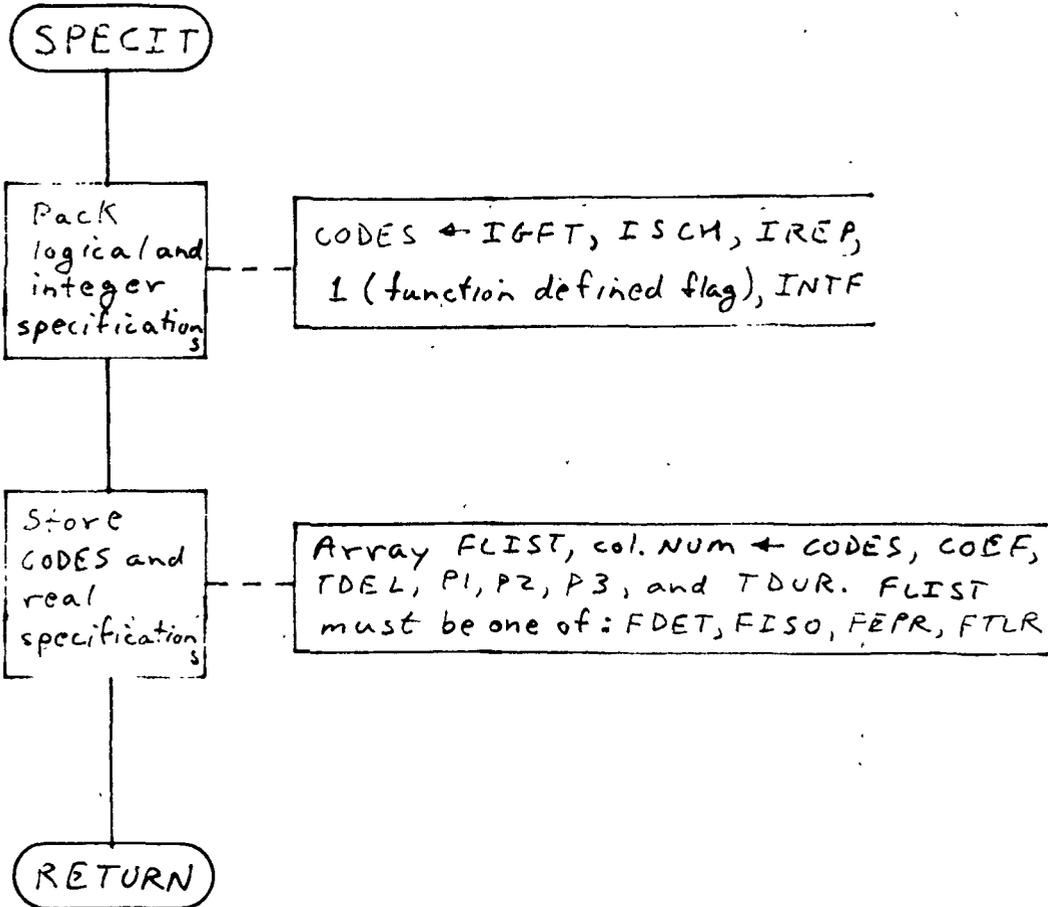
FLOW DIAGRAM

A-25



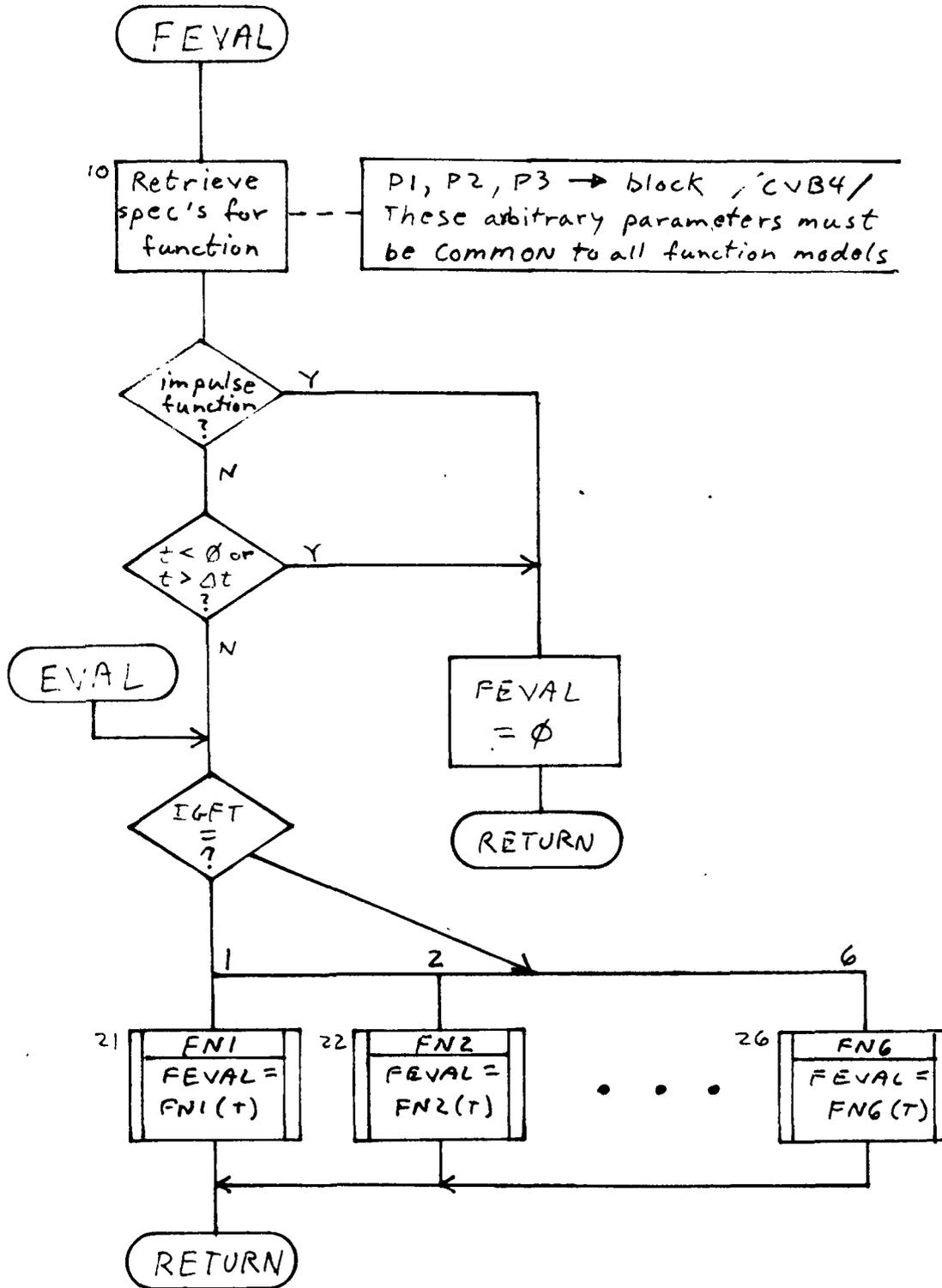
FLOW DIAGRAM

A-26



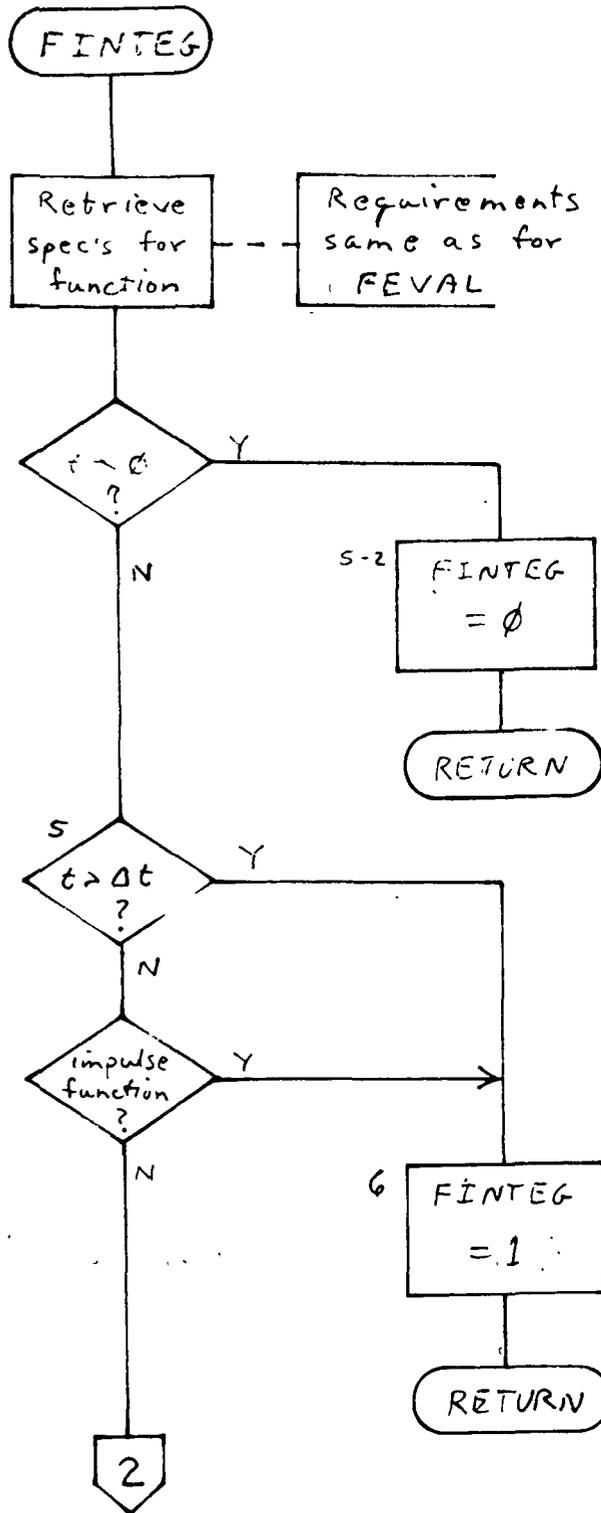
FLOW DIAGRAM

A-27



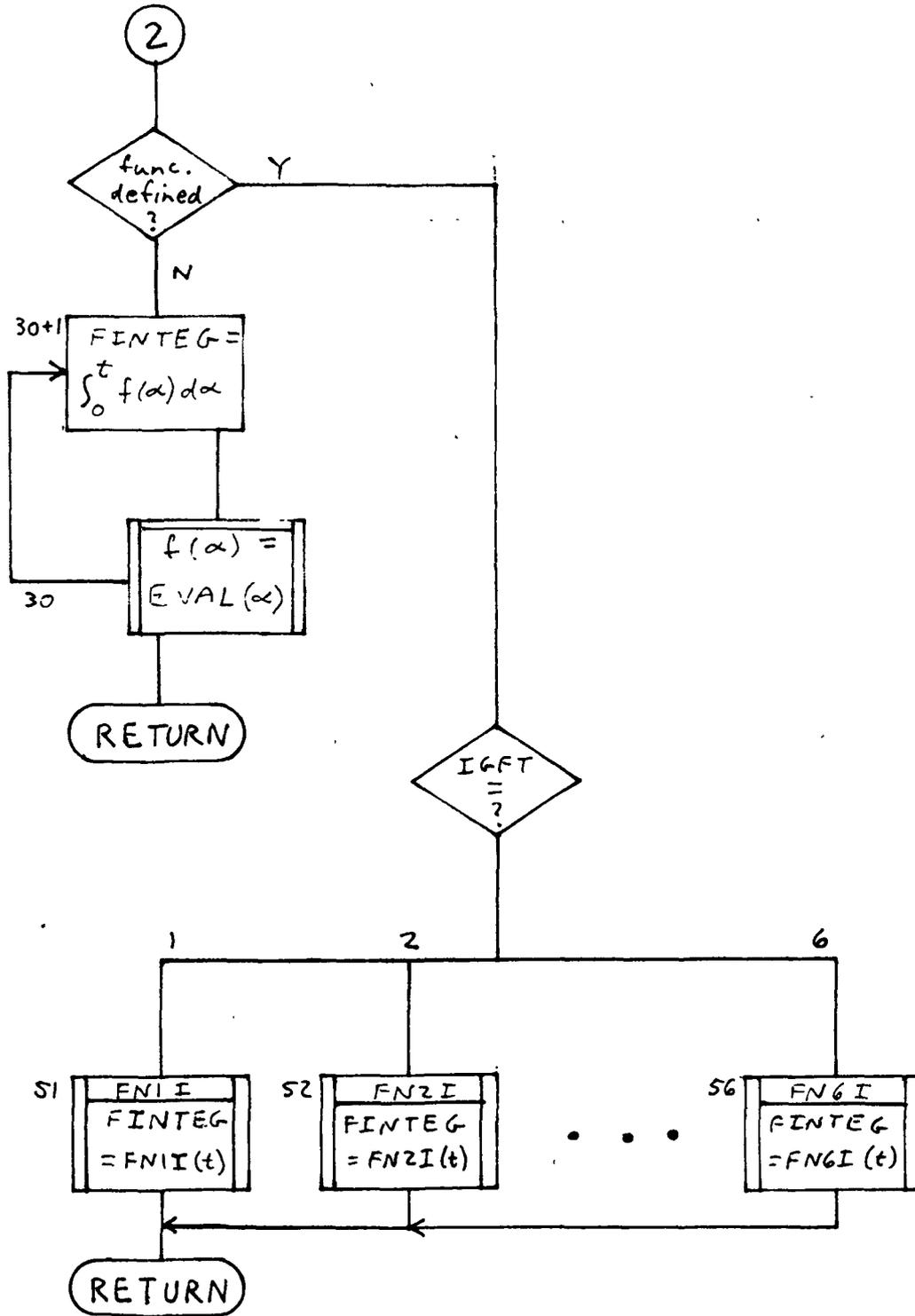
FLOW DIAGRAM

A-28



FLOW DIAGRAM

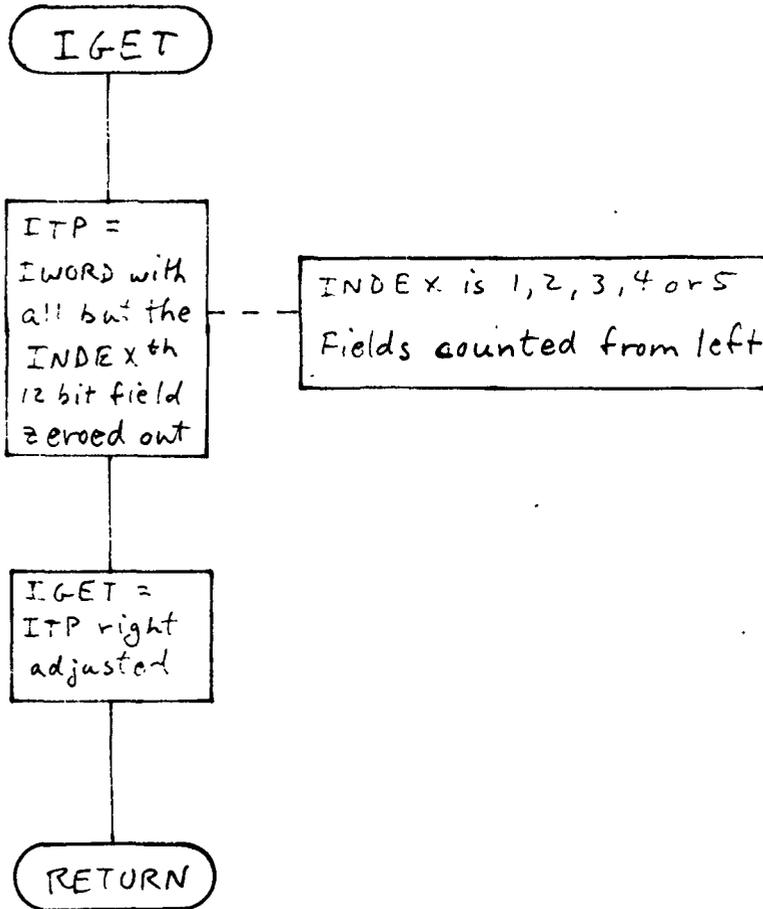
A-28



A-61

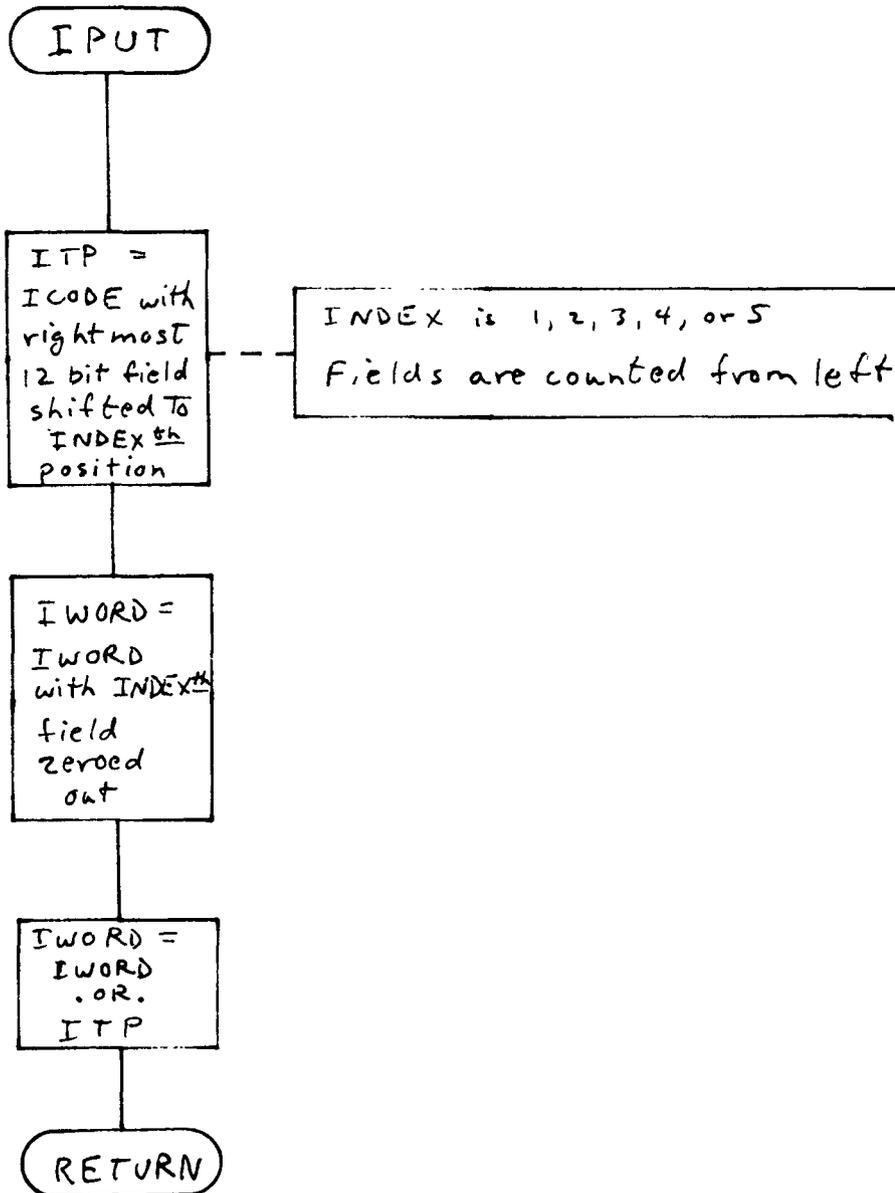
FLOW DIAGRAM

A-29



FLOW DIAGRAM

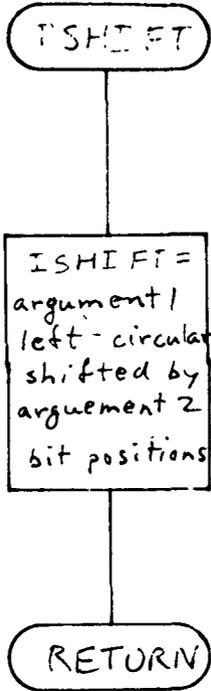
A-30





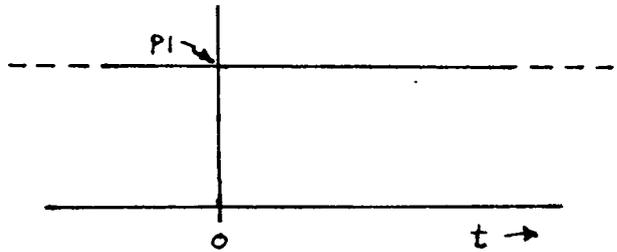
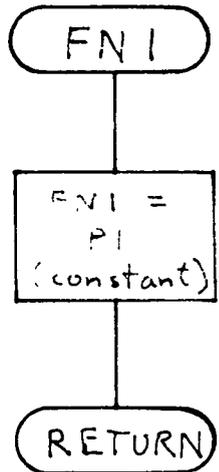
FLOW DIAGRAM

A-31



FLOW DIAGRAM

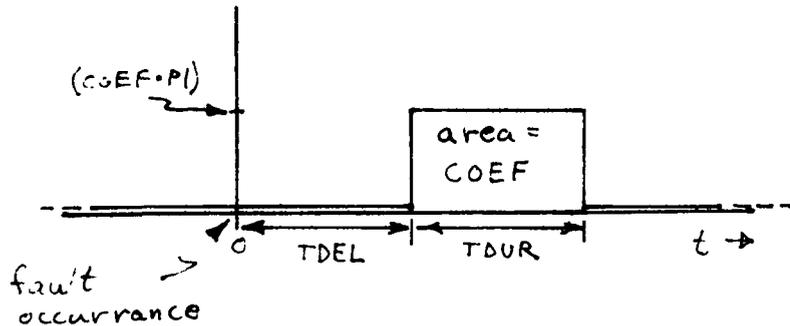
A-32



GRAPH OF FNI(t)
(SINGLE PULSE)

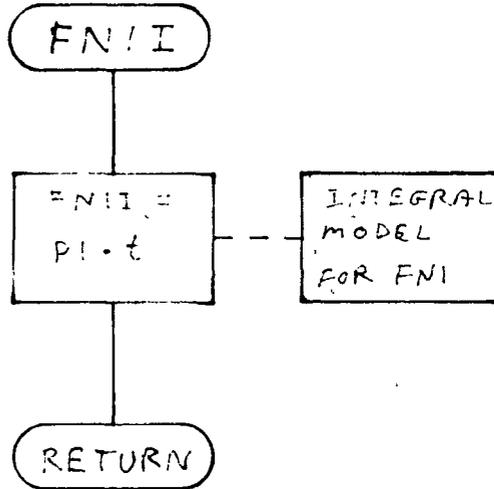
Note:

Function and integral models should be defined for all t as above. Evaluation functions FEVAL and FINTEG and their calling programs provide the additional constraints required by the coverage model. Thus an unscheduled detection function using FNI is effectively like the figure below -



FLOW DIAGRAM

A-33

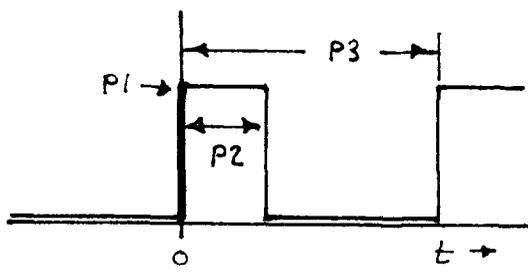




FLOW DIAGRAM

A-34

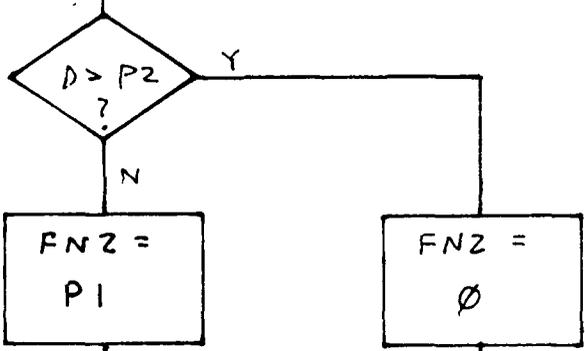
FN2



GRAPH OF FN2(t)
(PULSE TRAIN)

$k = \text{integer part of } t / P3$ — number of full cycles by time t

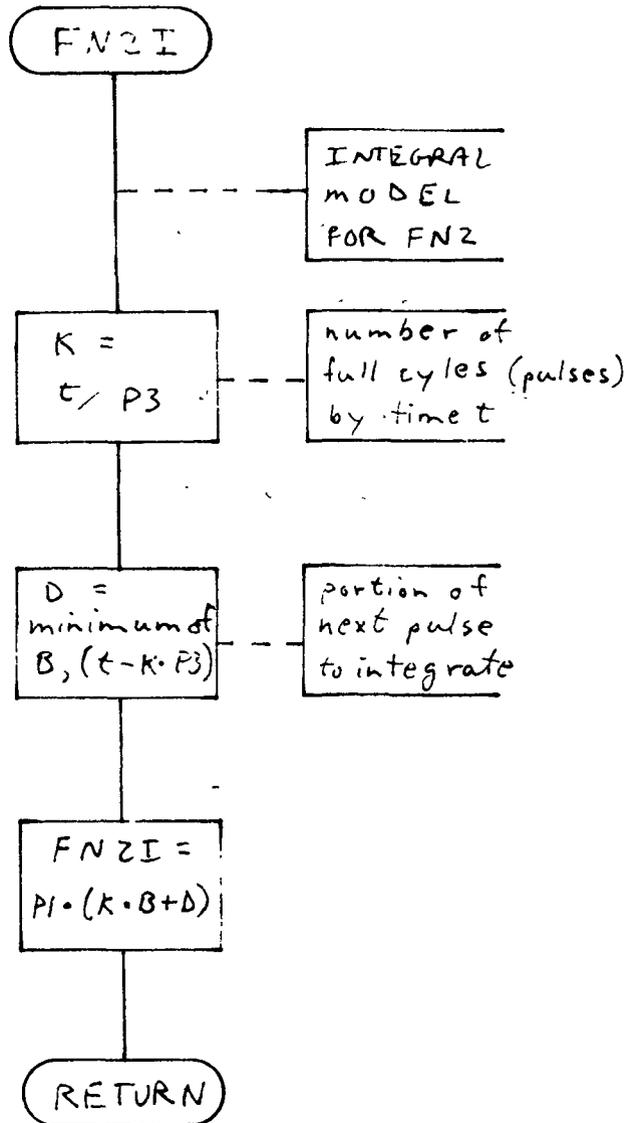
$D = t - k \cdot P3$ — time into next cycle



RETURN

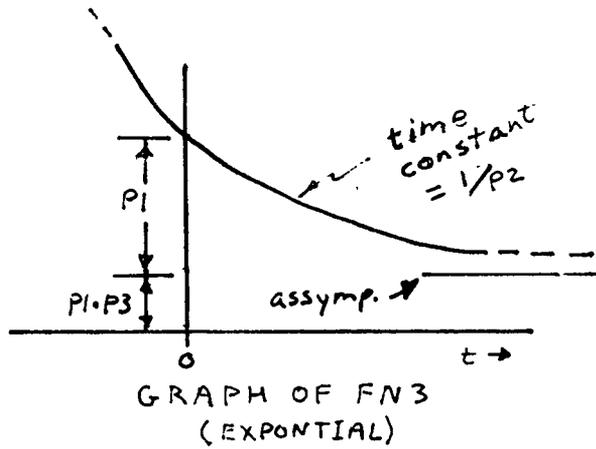
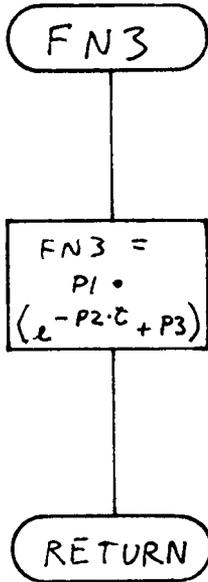
FLOW DIAGRAM

A-35



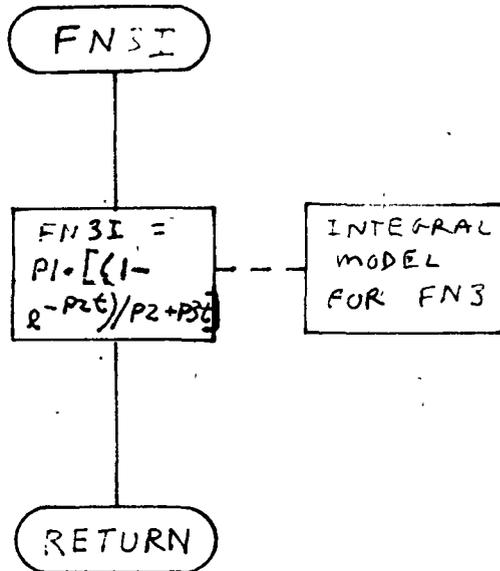
FLOW DIAGRAM

A-36



FLOW DIAGRAM

A-37





APPENDIX B
PROGRAM SOURCE LISTING

```

PROGRAM CARE2(INPUT=201,OUTPUT=201,TAPES=INPUT,TAPE6=OUTPUT)
*****
* THIS VERSION OF CARE IS ENTITLED CARE2, AND
* WAS PREPARED FOR THE LANGLEY RESEARCH CENTER BY
* THE EQUIPMENT DIVISION OF KAYTHEON COMPANY.
* S.J. BAVUSO OF THE CENTER SERVED AS CONTRACT MONITOR.
*
* CARE2 WAS ORIGINALLY DEVELOPED BY F.P. MATMUR
* OF THE JET PROPULSION LABORATORY, AND MORE RECENTLY
* WAS UPDATED AND MODIFIED FOR USE AT THE CENTER BY
* S.J. BAVUSO.
*
* CARE2 EXTENDS THE ORIGINAL PROGRAM'S CAPABILITIES
* IN TWO PRIMARY AREAS
*
* = ADDITION OF A COVERAGE CALCULATION CAPABILITY
*
* = ADDITION OF A DUAL MODE MODEL (EQUATION 7)
*
* THE PROGRAM IS IMPLEMENTED IN CDC FORTRAN 2.1
* FOR EXECUTION UNDER SCOPE 3.0
*****
REAL LAMT,MIN,MAX
REAL MUT(10),MTF(16),FOFX(16)
REAL R(121,10),PDT(121),SIMPX(121),DJ,SIMRF
REAL DIFF(1,1),RIF(1,1),GAIN(1,1),ABSC(1,1)
REAL G(1,1),XY(1,4),HLRV(1,2),FDUM(1),ENC(20)
REAL TMAX(101,15)
DIMENSION QRC(8),PCM(22),NAMES(22),RLDPS(10),INTDPS(4),UNITR(8)
DIMENSION GO(10,2),G(10),G1(10),G2(10),N(10)
REAL LAM(10),MU(10),K(10),RV(10),P(10)
DIMENSION CC(10,2),C(10),C1(10),C2(10),CTR(10)
DIMENSION CCD(10,2),CD(10),CD1(10),CD2(10),CDTR(10)
DIMENSION GGM(10,2),GM(10),GM1(10),GM2(10),GMP(10)
DIMENSION PPRC(10,2),PRC(10),PRC1(10),PRC2(10),PARAM(16,10)
INTEGER S(10),M(10),Z(10),ANSWER(3)
INTEGER IDUM(11),PROD(10),PAR(6),OPTIUN,RZUPT
INTEGER IGENC(10),IGENP(10),IFSC(6),IDG(10)
LOGICAL PRODT,IN,MUTIN,XYRANGE,LPLUT,GPLOT,NOPDT
LOGICAL LVARY,DEBUG,INPDT,STGOUT,COVINT,LSTCH,CVPRC,DMFLG
LOGICAL BCOMP,RELATIN,RVPLOT,TRUNC,OPTR1,OPTR2,PLOT1,PLOT2
LOGICAL BCOMPS(10),RSUN
LOGICAL UUTPT1,UUTPT2,UUTPT3,UUTPT4,UUTPT5,RVLOC5
EQUIVALENCE (XY(1,1),ABSC(1,1)), (XY(1,4),G(1,1))
EQUIVALENCE (GO(1,1),G(1),G1(1)),(GO(1,2),G2(1))
EQUIVALENCE (C(1,1),C(1),C1(1)),(C(1,2),C2(1))
EQUIVALENCE (CCD(1,1),CD(1),CD1(1)),(CCD(1,2),CD2(1))
EQUIVALENCE (GGM(1,1),GM(1),GM1(1)),(GGM(1,2),GM2(1))
EQUIVALENCE (PPRC(1,1),PRC(1),PRC1(1)),(PPRC(1,2),PRC2(1))
COMMON /PLUTIN/ IN,MIN,MAX,STXP,DIFF,RIF,GAIN,MTF,FOFX,
* PDT,SIMPX,XMIN,XMAX,YMIN,YMAX,XYRANGE,IA,IAA,IB,IBB,
* IC,ICC,IPLT1,IPLT2,IPLT3,IPLT4,IPLT5
COMMON/GRAPH/ NEQ,PROD,NPROD,PAR,ENC,AB,PRODT
COMMON /PAR1/GO,IDD,N,S
COMMON /PAR2/LAM,MU,K,BCOMPS,SLM2,SLM3
COMMON /PAR3/RV,Z,M,P
COMMON /PAR4/CC,CCD,CTR,CUTN,CCSF
COMMON /PAR5/GGM,GMP,PPRC
COMMON/GHAFF/HLRV,PSYHBL(16)
COMMON /PARM/ PARAM,N(10,K)
COMMON /UUTPT/ UUTPT1,UUTPT2,UUTPT3,UUTPT4,UUTPTS

```

```

1 1 MAINLOG
1 1 TITLE
2 2 TITLE
3 3 TITLE
4 4 TITLE
5 5 TITLE
6 6 TITLE
7 7 TITLE
8 8 TITLE
9 9 TITLE
10 10 TITLE
11 11 TITLE
12 12 TITLE
13 13 TITLE
14 14 TITLE
15 15 TITLE
16 16 TITLE
17 17 TITLE
18 18 TITLE
19 19 TITLE
20 20 TITLE
21 21 TITLE
22 22 TITLE
23 23 TITLE
30 30 CARE
32 32 CARE
1 1 CRUSH
2 2 CRUSH
3 3 CRUSH
36 36 CARE
2 2 MAINLOG
1 1 PARMOD
2 2 PARMOD
3 3 PARMOD
4 4 PARMOD
5 5 PARMOD
6 6 PARMOD
7 7 PARMOD
38 38 CARE
3 3 MAINLOG
39 39 CARE
4 4 MAINLOG
40 40 CARE
8 8 PARMOD
41 41 CARE
42 42 CARE
9 9 PARMOD
10 10 PARMOD
11 11 PARMOD
12 12 PARMOD
13 13 PARMOD
43 43 CARE
44 44 CARE
45 45 CARE
46 46 CARE
14 14 PARMOD
1 1 FINAL
16 16 PARMOD
17 17 PARMOD
18 18 PARMOD
48 48 CARE
49 49 CARE
50 50 CARE

```



```

C      *  WZUPT,I10,THAX)
364 IF (OPTION,EG,1,AND,I10,LT,N10) GO TO 370
    IF (PROUT) GO TO 370
C
C      *** COMPUTE DIFF, RIF, AND GAIN ***
    IF (OPTION,NE,2) NG=0
    CALL RIFUIF (I10,OPTION,IRES,N10,FIN,MIN,MAX,STEP,JOIM,R,
    *  DIFF,RIF,GAIN,NG,LPLT,GPLOT)
    IF (IPLT3,NE,1,OR,OPTION,EG,2) GO TO 370
    IF (GPLOT) CALL PLOTG (NG,ABSC,XY,G,3,PARAM,K1,2)
370 IF (IPLT1,EG,1) CALL PLOTG(1,ABSC,XY,G,1,PARAM,K1,3)
380 CONTINUE
C
C      END OF DO LOOP FOR FAMILY OF PARAMETER
C
    IF (LVARY) CALL PGET(IRES,1,NPROD)
    IF (PROUT) GO TO 390
    IF (IPLT2,EG,1,OR,IPLT5,EG,1) CALL PLOTG (N10,ABSC,XY,G,3,PARAM,
    *  K1,1)
    IF (IPLT3,EG,1,AND,OPTION,EG,2) CALL PLOTG (NG,ABSC,XY,G,3,PARAM,
    *  K1,2)
    IF (IPLT4,EG,1) CALL PLOTG (N10,ABSC,XY,G,3,PARAM,K1,3)
390 IF (XVPLOT) CALL PLOTG(I10,DELRL)
    GO TO 40
9999 STOP
C
C      FORMAT STATEMENTS
C
1001 FORMAT (6A1)
1002 FORMAT (80A1)
1003 FORMAT(* T OR LAMT MUST BE GIVEN FOR THE EQUATION YOU SPECIFIED*,
    /, *  ENTIRE DATA CASE IS TERMINATED*)
1004 FORMAT(* THE VARIABLE THAT IS TO BE USED*,//)
1005 FORMAT(* RV VERSUS R PLOT NOT TO BE PERFORMED FOR THIS CASE*,//)
1006 FORMAT(* INCORRECT PARAMETER FOR EQUATION *,I2,* TRY ANOTHER*)
1007 FORMAT(1M ,F10.3,F12.7,2E18.7)
1008 FORMAT(( 1M ,F7.5,2X,E14.5,2(2X,F10.7),2(2X,E16.7))
1009 FORMAT(* DO YOU WISH TO SPECIFY ANOTHER PARAMETER*,//)
    ** ANSWER YES OR NO**
1029 FORMAT(* TYPE IN NEW PARAMETER OR PARAMETERS (FOR PRODUCT OF*,//)
    ** RELIABILITIES) AS BEFORE**
1030 FORMAT(* IMPROPER VALUE FOR K = K = *,E14.6,//)
    ** K MUST SATISFY 0.LE.K.LE.INFINITY**//
    ** CALCULATIONS ARE NOT PERFORMED FOR THIS K VALUE**
1032 FORMAT (1M ,80A1)
2006 FORMAT(/76X,*LANT*,3X,*REL PRODUCT*)
2007 FORMAT(/76X,*T*,4X,*REL PRODUCT*)
2008 FORMAT(1X,F10.3,F12.7)
3000 FORMAT(10X,*FOR DUAL MODE MODEL, INDEP. VARIABLE MUST BE TIME*/
    25X,*JOB ABORTED*)
3001 FORMAT(10X,*FOR DUAL MODE MODEL, TIME MUST START AT 0.0*/
    25X,*JOB ABORTED*)
3002 FORMAT(/743X,*DUAL MODE SYSTEM RELIABILITY IN MODE 1*/74X,
    *TIME*,6X,*SYSTEM REL. *,8(A5,I3,4X))
3003 FORMAT(1X,F10.3,F12.7)
3004 FORMAT(/25X,*= WARNING --/10X,*G2 GREATER THAN G1 *,
    *FOR STAGE*,I3,* = MSGN FORCED TO TRUE*)
3005 FORMAT(1M1,49X,*RUN*,I5,* RELIABILITY RESULTS*/
    50X,*-----*)
3006 FORMAT(/749X,*STAGE*,I3,* EQUATION NUMBER*,I2/)
3007 FURMAT(6X,*LANT*,7X,*REL*,8X,*UNREL*,7X,*SIMREL*,9X,
    *SIMGAIN*,9X,*SINHIF*)
3008 FORMAT(8X,*T*,8X,*REL*,8X,*UNREL*,7X,*SIMREL*,9X,

```

```

308 CARE
309 CARE
310 CARE
311 CARE
312 CARE
313 CARE
314 CARE
315 CARE
316 CARE
317 CARE
318 CARE
319 CARE
320 CARE
321 CARE
322 CARE
323 CARE
324 MAINLOG
325 CARE
326 CARE
327 CARE
328 CARE
329 CARE
330 CARE
342 CARE
343 CARE
344 CARE
345 CARE
346 CARE
347 CARE
348 CARE
349 CARE
350 CARE
351 CARE
352 CARE
353 CARE
354 CARE
355 CARE
356 MAINLOG
357 CARE
358 CARE
359 CARE
360 CARE
361 CARE
362 CARE
363 CARE
364 CARE
365 CARE
2 POSTPCH
3 POSTPCH
4 POSTPCH
131 MAINLOG
132 MAINLOG
133 MAINLOG
134 MAINLOG
135 MAINLOG
136 MAINLOG
137 MAINLOG
138 MAINLOG
139 MAINLOG
140 MAINLOG
141 MAINLOG
142 MAINLOG
143 MAINLOG
144 MAINLOG
145 MAINLOG

```



```

61 BISECT
62 BISECT
63 BISECT
64 BISECT
65 BISECT
66 BISECT
67 BISECT
68 BISECT
69 BISECT
70 BISECT
71 BISECT
72 BISECT
73 BISECT
74 BISECT
75 BISECT
76 BISECT
77 BISECT
78 BISECT
79 BISECT
80 BISECT
81 BISECT
82 BISECT
83 BISECT
84 BISECT
85 BISECT
86 BISECT
87 BISECT
88 BISECT
89 BISECT
90 BISECT
91 BISECT
92 BISECT
93 BISECT
94 BISECT
95 BISECT
96 BISECT
97 BISECT
98 BISECT
99 BISECT
1  EQUAL
2  EQUAL
3  EQUAL
4  EQUAL
5  EQUAL
6  EQUAL
7  EQUAL
8  EQUAL
9  EQUAL
10 CRUSH
11 EQUAL
12 EQUAL
13 EQUAL
14 EQUAL
15 EQUAL
16 EQUAL
17 EQUAL
18 EQUAL
19 EQUAL
20 EQUAL
21 EQUAL
22 EQUAL
23 EQUAL
24 EQUAL
25 EQUAL
26 EQUAL
27 EQUAL

YI=REL-R
C INTERPOLATE FOR NEW VALUE OF LAMT BY REGULA FALSI METHOD
C 110 LAMT=(X1*Y2-X2*Y1)/(Y2-Y1)
RL= EXP(-LAMT)
IF (.NOT.BCOMP) RS=RL*(1.0E0/K)
C OBTAIN RELIABILITY FOR NEW LAMT
C CALL RELEUS (NEG,BCOMP,RL,RS,S,N,K,Q,C,RV,Z,W,P,LAMT,REL)
DIF=REL-R
C CONVERGENCE TEST
C IF ( ABS(DIF).LE.TOL) RETURN
ITEM=ITER+1
C TEST FOR MAX NUMBER OF ITERATIONS EXCEEDED
IF (ITER.LE.ITMAX) GO TO 120
WRITE(6,1003)
RETURN
C 140 IF (DIF*Y2) 130,130,140
130 X1=X2
Y1=Y2
X2=LAMT
Y2=DIF
GO TO 110
140 X2=LAMT
Y2=DIF
GO TO 110
C 1001 FORMAT(* REFERENCE POINT/R2 MUST BE GREATER THAN 0.0*)
1002 FORMAT(* R1 OR R2 MUST BE LESS THAN OR EQUAL TO 1.0*)
1003 FORMAT (* CONVERGENCE PROBLEM WHEN CALCULATING MAXIMUM MISSION*,
* TIME*)
1004 FORMAT (* MAXIMUM MISSION TIME IS NOT CALCULATED FOR THIS CASE*)
1005 FORMAT (* R1 OR R2 CAN NOT BE NEGATIVE*)
C END
SUBROUTINE EQUAL (HCOMP,MU,S,N,K,Q,C,Z,W,P,NEG,I10,RLRV,DELRL)
*****
* THIS SUBROUTINE CALCULATES THE *
* LOCUS OF RV SUCH THAT THE SYSTEM *
* RELIABILITY EQUALS THE UNIT *
* RELIABILITY, R. *
*****
REAL RLRV(1,2)
REAL K,MU
INTEGER S,N,M,Z
LOGICAL BCOMP
DATA HVLAMT/1.0E0/
DELML=5.0E-5
RVT=1.0
RL=1.0E-10
JM=1
JTM=1
WRITE (6,1001)
20 IF (K.NE.0.0 ) HS=RL*(1.0 /K)
CALL RELEUS (NEG,BCOMP,RL,RS,S,N,K,Q,C,RV,T,1,1,P,RVLAMT,EXPR)
RLRV(J,1)=RL
RLRV(J,10+1)=RL*(1.0/(M*Z))/EXPR
IF (JT.LE.20) GO TO 110
WRITE (6,1002) RLRV(J,1),RLRV(J,10+1)
JT=1

```



```

45 FNCK
26 FNCK
27 FNCK
28 FNCK
29 FNCK
1 INTEGR
2 INTEGR
3 INTEGR
4 INTEGR
5 INTEGR
6 INTEGR
7 INTEGR
8 INTEGR
9 INTEGR
10 INTEGR
11 INTEGR
12 INTEGR
13 INTEGR
14 INTEGR
15 INTEGR
16 INTEGR
17 INTEGR
18 INTEGR
19 INTEGR
20 INTEGR
21 INTEGR
22 INTEGR
23 INTEGR
24 INTEGR
25 INTEGR
26 INTEGR
27 INTEGR
28 INTEGR
29 INTEGR
30 INTEGR
31 INTEGR
32 INTEGR
33 INTEGR
34 INTEGR
35 INTEGR
36 INTEGR
37 INTEGR
38 INTEGR
39 INTEGR
40 INTEGR
41 INTEGR
42 INTEGR
43 INTEGR
44 INTEGR
45 INTEGR
46 INTEGR
47 INTEGR
48 INTEGR
49 INTEGR
50 INTEGR
51 INTEGR
52 INTEGR
53 INTEGR
54 INTEGR
55 INTEGR
56 INTEGR
57 INTEGR
58 INTEGR
59 INTEGR
60 INTEGR
61 INTEGR

Z1=Z1+1.
10 CONTINUE
50 CONTINUE
RETURN
END
SUBROUTINE INTEGR (TIN,BCOMP,LAMBDA,MU,S,N,K,Q,C,RV,Z,W,P,NEG,B,
* MTF,FOFX)
*****
* THIS SUBROUTINE COMPUTES THE *
* MEAN TIME TO FAILURE = MTF *
* AND THE RELIABILITY AT MTF *
*****
REAL K ,MTF
REAL LAMBDA,MU
INTEGER N,S,Z,W
LOGICAL TIN,BCOMP,TESTG
COMMON /OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS
TESTG=.FALSE.
A=0.0
HSTAR=0.01
HMIN=0.0001
HMAX=10.0
ERMAX=1.0E-6
KEY=0
PMTF=0.0
D=8
IF (D.NE.0.0 ) GO TO 3
*** INPUT UPPER LIMIT OF INTEGRATION ***
*** IF IT WAS NOT INPUTED IN SVAR ***
WRITE (6,1000) B1
1 READ(5,1001) B1
2 IF (OUTPT3) WRITE (6,1005) B1
D=8
*** CALL ROMBERG INTEGRATOR ***
3 CALL RUMBD (A,D,X1,FOFX,HSTAR,HMIN,HMAX,ERMAX,MTF,K1,KEY)
5 X=X1
IF (TIN) X=LAMBDA*X1
HL= EXP(-X)
IF (K.NE.0.0 ) RS= EXP(-X/K)
CALL RELEGS (NEG,BCOMP,RL,RS,S,N,K,Q,C,RV,Z,W,P,X,FOFX)
IF (TESTG) GO TO 90
CALL ROMZD(A,D,X1,FOFX,HSTAR,HMIN,HMAX,ERMAX,MTF,K1,KEY)
MTF=MTF+PMTF
REL=ABS(MTF-PMTF)/ MAX1(ABS(MTF),1.0)
IF (REL.LT.1.0E-8) GO TO 80
IF (D.GT.1.0E24) GO TO 80
PMTF=MTF
A=D
D=D*1.5E0=D
GO TO 3
80 IF (OUTPT4) WRITE (6,1002) MTF,D
X1=MTF
TESTG=.TRUE.
GO TO 5
90 IF (OUTPT4) WRITE (6,1004) FOFX
RETURN
9999 STOP
1000 FORMAT( * THE INTEGRATION UPPER LIMIT =8= WAS NOT INPUTTED IN=,/

```

```

** NAMELIST VAR, THE VALUE OF -B- IS EXPECTED AND MUST BE **
** .LE. 1.0E24 AND .GT. 0.0**
1001 FORMAT(/,F20.0)
1002 FORMAT(/,MEAN TIME TO FAILURE = MTF = ,E15.8,/,
** UPPER LIMIT FOR INTEGRATION = B = ,E15.8)
1004 FORMAT(* RELIABILITY AT MTF = ,E15.8)
1005 FORMAT (1H ,F20.5)
END
SUBROUTINE NEG2A (RL,RS,S,K,Q,RV,Z,M,P,LAMT,R,C)
C
C *****
C *
C * THIS SUBROUTINE COMPUTES THE *
C * RELIABILITY FOR EQUATION 2A *
C *
C *****
REAL K,LAMT
INTEGER I,S,L,M
SUM=0.0
IF (LAMT.NE.0.0 ) GO TO 5
R=RV**(*Z)
RETURN
5 IF (S.NE.0) GO TO 7
R=((RL**(*Z))*RV)**(*Z)
RETURN
7 DO 10 I=1,8
10 SUM=SUM+(C*(1.0-MS**(*Z)))**I/FFAC(I)*PROD(J,I-1,Q,M)
R=RV**(*Z)
RETURN
END
SUBROUTINE NEG2B (RL,LAMT,S,RV,Z,M,P,R,C,Q)
C
C *****
C *
C * THIS SUBROUTINE COMPUTES THE *
C * RELIABILITY FOR EQUATION 2B *
C *
C *****
REAL LAMT
INTEGER S,L,M
SUM=0.0
IF (LAMT.NE.0.0 ) GO TO 5
R=RV**(*Z)
RETURN
5 IF (S.NE.0) GO TO 7
R=((RL**(*Z))*RV)**(*Z)
RETURN
7 DO 10 I=1,8
10 SUM=SUM+(((LAMT*C*Q)/M)**I)/FFAC(I)
R=(RV* EXP((-LAMT*Q)/M))*(1.0+SUM)**(*Z)
RETURN
END
SUBROUTINE NEG1A (RL,RS,S,N,K,RV,Z,M,P,LAMT,R)
C
C *****
C *
C * THIS SUBROUTINE COMPUTES THE *
C * RELIABILITY FOR EQUATION 1A *
C *
C *****
REAL LAMT,K,KLS
INTEGER S,S2,ETA,I,N,M,Z ,S22
SUM=0.0

```

62 INTEGR
 63 INTEGR
 64 INTEGR
 65 INTEGR
 66 INTEGR
 67 INTEGR
 68 INTEGR
 69 INTEGR
 NEG2A 1
 NEG2A 2
 NEG2A 3
 NEG2A 4
 NEG2A 5
 NEG2A 6
 NEG2A 7
 NEG2A 8
 NEG2A 9
 NEG2A 10
 NEG2A 11
 NEG2A 12
 NEG2A 13
 NEG2A 14
 NEG2A 15
 NEG2A 16
 NEG2A 17
 NEG2A 18
 NEG2A 19
 NEG2A 20
 NEG2A 21
 NEG2A 22
 NEG2A 23
 NEG2B 1
 NEG2B 2
 NEG2B 3
 NEG2B 4
 NEG2B 5
 NEG2B 6
 NEG2B 7
 NEG2B 8
 NEG2B 9
 NEG2B 10
 NEG2B 11
 NEG2B 12
 NEG2B 13
 NEG2B 14
 NEG2B 15
 NEG2B 16
 NEG2B 17
 NEG2B 18
 NEG2B 19
 NEG2B 20
 NEG2B 21
 NEG2B 22
 NEG2B 23
 NEG1A 1
 NEG1A 2
 NEG1A 3
 NEG1A 4
 NEG1A 5
 NEG1A 6
 NEG1A 7
 NEG1A 8
 NEG1A 9
 NEG1A 10
 NEG1A 11
 NEG1A 12

```

13  NEG1A
14  NEG1A
15  NEG1A
16  NEG1A
17  NEG1A
18  NEG1A
19  NEG1A
20  NEG1A
21  NEG1A
22  NEG1A
23  NEG1A
24  NEG1A
25  NEG1A
26  NEG1A
27  NEG1A
28  NEG1A
29  NEG1A
30  NEG1A
31  NEG1A
32  NEG1A
33  NEG1A
34  NEG1A
35  NEG1A
36  NEG1A
37  NEG1A
38  NEG1A
39  NEG1A
40  NEG1A
41  NEG1A
42  NEG1A
43  NEG1A
44  NEG1A
45  NEG1A
46  NEG1A
47  NEG1A
48  CAREFIX
49  NEG1A
50  NEG1A
51  NEG1A
52  NEG1A
53  NEG1A
54  NEG1A
55  NEG1A
56  NEG1A
57  NEG1A
58  NEG1A
59  NEG1A
60  NEG1A
61  NEG1A
62  NEG1A
63  NEG1A
64  NEG1A
65  NEG1A
66  NEG1A
67  NEG1A
1  NEG1B
2  NEG1B
3  NEG1B
4  NEG1B
5  NEG1B
6  NEG1B
7  NEG1B
8  NEG1B
9  NEG1B
10 NEG1B
11 NEG1B

SUM1=0.
SUM2=0.0
SUM3=0.0
S2=S-2
IF (LAMT.NE.0.0 ) GO TO 3
RERV**=(WZ)
RETURN
3  ETA=2*N+1
  ETAKS=ETA*K+S
  KLAMRL=(1.0/W)
  RMURS=(1.0/W)
  IF (S=1) S=20.50
5  R=0.0
  NN=N+1
  DO 10 IX=1,NN
    I=IX-1
    10 R=R+FNCK(ETA,I)*(1.0-KLAM)**I*RLAM**(ETA-I)
  RETURN
20  NN=N+1
  DO 40 IX=1,NN
    I=IX-1
    SUM=0.0
    II=I+1
    DO 30 LX=1,II
      L=LX-1
      30 SUM=SUM+FNCK(I,L)*(=1)**(I=L)*(1.0/(RMUR*KLAM**L))-1.0)/(K*L+1.0)
      40 SUM1=SUM1+FNCK(ETA,I)*SUM
      R=RLAM**ETA*HM*(1.0*(ETA*K+1.0)*SUM1)
      R=(R*RV)**(WZ)
    RETURN
50  NN=N+1
  DO 60 JX=1,S22
    I=IX-1
    II=I+1
    SUM1=0.0
    DO 70 LX=1,II
      L=LX-1
      SUM2=0.0
      KL8=K*L+S
      S2=S2+1
      DO 60 JX=1,S22
        J=JX-1
        60 SUM2=SUM2+RCOMB(KL8,J+1)*(1.0/RMU=1.0)**(J+1)
        70 SUM1=SUM1+FNCK(I,L)*(=1)**(I=L)*(1.0/(RMUR**8*RLAM**L))-1.0*SUM2)/
          * RCOMB(KL8,S)
      80 SUM=SUM+FNCK(ETA,I)*RCOMB(ETAKS,S)*SUM1
      S2=S2+1
    DO 90 JX=1,S22
      J=JX-1
      90 SUM3=SUM3+RCOMB(ETAKS,J+1)*(1.0/RMU=1.0)**(J+1)
      R=RLAM**ETA*RMU**S*(1.0+SUM3*SUM)
      R=(R*RV)**(WZ)
    RETURN
  END
SUBROUTINE NEG1B (RL,8,N,RV,Z,W,P,LAMT,H)
*****
*
* THIS SUBROUTINE COMPUTES THE *
* RELIABILITY FOR EQUATION 1B *
*
*****
C
C
C
C
C
C
C
C
REAL LAMT
INTEGER 8,N,Z,W,ETA,N2,81 ,88

```

```

12 NEG18
13 NEG18
14 NEG18
15 NEG18
16 NEG18
17 NEG18
18 NEG18
19 NEG18
20 NEG18
21 NEG18
22 NEG18
23 NEG18
24 NEG18
25 NEG18
26 NEG18
27 NEG18
28 NEG18
29 NEG18
30 NEG18
31 NEG18
32 NEG18
33 NEG18
34 NEG18
35 NEG18
36 NEG18
37 NEG18
38 NEG18
39 NEG18
40 NEG18
41 NEG18
42 NEG18
43 NEG18
44 NEG18
45 NEG18
46 NEG18
47 NEG18
48 NEG18
49 NEG18
50 NEG18
51 NEG18
52 NEG18
53 NEG18
54 NEG18
55 NEG18
1  NEG3
2  NEG3
3  NEG3
4  NEG3
5  NEG3
6  NEG3
7  NEG3
8  NEG3
9  NEG3
10 NEG3
11 NEG3
12 NEG3
13 NEG3
14 NEG3
15 NEG3
16 NEG3
17 NEG3
18 NEG3
19 NEG3
20 NEG3
21 NEG3
22 NEG3

```

```

IF (LAMT.NE.0.0 ) GO TO 10
R=RV**(*M*Z)
RETURN
10 N2=2*N
ETA=N2+1
RLAM=RL**((1.0/M)
81=8-1
SUM1=0.0
SUM2=0.0
SUM3=0.0
SUM4=0.0
IF (81) 20,30,60
20 SUM1 = RLAM**ETA
DO 25 I=1,N
SUM1=SUM1+((1.0 -RLAM)**I)*(RLAM**ETA=I))*FNCK(ETA,I)
25 CONTINUE
R=(RV*SUM1)**(*M*Z)
RETURN
30 DO 50 I=1,N
SUM2=0.0
DO 40 J=1,I
40 SUM2=SUM2+FNCK(I,J)*((-1)**(I=J))*((1.0 / (RLAM**J))-1.0 )/J
50 SUM1=SUM1+FNCK(ETA,I)*SUM2
R=(RV*RLAM**ETA*(1.0 +ETA*LAMT*(-1)**N*FNCK(N2,N)
+ETA*SUM1))**(*M*Z)
RETURN
60 DO 90 I=1,N
SUM2=0.0
DO 80 J=1,I
SUM1=0.0
DO 70 L=1,S1
70 SUM1=SUM1+LAMT**L/(FFAC(L)*J**S*L)
80 SUM2=SUM2+FNCK(I,J)*((-1)**(I=J))*((1.0 / (RLAM**J))-1.0 )/(J**S)
+SUM1)
90 SUM3=SUM3+FNCK(ETA,I)*SUM2
SS=S1+1
DO 100 IX=1,SS
IX=1
100 SUM4=SUM4+(ETA*LAMT)**I/FFAC(I)
R=(RV*RLAM**ETA*(SUM4*(ETA=LAMT)**S*(-1)**N*FNCK(N2,N)/FFAC(S)+
*ETA**S*SUM3))**(*M*Z)
RETURN
1001 FORMAT (* IMPROPER INPUT FOR 8 - 8 CANNOT BE LESS THAN 1*)
END
SUBROUTINE NEG3 (RL,RS,S,K,G,C,RV,Z,W,P,BCOMP,LAMT,R)
C *****
C * THIS SUBROUTINE COMPUTES THE *
C * RELIABILITY FOR EQUATION 3 *
C * *
C *****
REAL K,LAMT
INTEGER I,S,Z,W ,SS
LOGICAL BCOMP
IF (C.LT.1.0 .AND.C.GT.0.0 ) GO TO 5
WRITE (6,1000) C
GO TO 40
5 IF (LAMT.NE.0.0 ) GO TO 7
R=RV**(*M*Z)
RETURN
7 SUM=0.0
SS=S+1
DO 10 IX=1,SS
IX=1

```

```

23 NEG3
24 NEG3
25 NEG3
26 NEG3
27 NEG3
28 NEG3
29 NEG3
30 NEG3
31 NEG3
32 NEG3
1  NEG4
2  NEG4
3  NEG4
4  NEG4
5  NEG4
6  NEG4
7  NEG4
8  NEG4
9  NEG4
10 NEG4
11 NEG4
12 NEG4
13 NEG4
14 NEG4
15 NEG4
16 NEG4
17 NEG4
18 NEG4
19 NEG4
20 NEG4
21 NEG4
22 NEG4
23 NEG4
24 NEG4
25 NEG4
26 NEG4
27 NEG4
28 NEG4
29 NEG4
30 NEG4
31 NEG4
32 NEG4
33 NEG4
34 NEG4
35 NEG4
36 NEG4
37 NEG4
38 NEG4
1  NEG4B
2  NEG4B
3  NEG4B
4  NEG4B
5  NEG4B
6  NEG4B
7  NEG4B
8  NEG4B
9  NEG4B
10 NEG4B
11 NEG4B
12 NEG4B
13 NEG4B
14 NEG4B
15 NEG4B
16 NEG4B
17 NEG4B
18 NEG4B

10 SUM=SUM*FNCK(S,I)*C**I*(1.0-C)**(S-I)
   IF (BCOMP) GO TO 20
   CALL NEG2A (RL,RS,S,K,Q,RV,Z,W,P,LA,MT,R)
   GO TO 30
20 CALL NEG2B (LA,MT,S,RV,Z,W,P,R)
30 R=(SUMR)**Z
40 RETURN
1000 FORMAT (* IMPROPER INPUT FOR C - C = *E15.6,/,
** MUST HAVE 0.LT.C.LT.1*)
END
SUBROUTINE NEG4A (RL,RS,S,K,RV,Z,W,P,LA,MT,R)
C *****
C *
C * THIS SUBROUTINE COMPUTES THE *
C * RELIABILITY FOR EQUATION 4A *
C *
C *****
REAL K,LA,MT
INTEGER S,Z,W,S1
IF (S) 30,40,60
30 WRITE (6,1001)
1001 FORMAT (* ILLEGAL VALUE FOR S - S CANNOT BE NEGATIVE*)
40 IF (LA,MT,NE.0.0 ) GO TO 50
   R=RV**(W*Z)
   RETURN
50 R=((1.5 *RL**((1.0/W)-0.5*RL**((3.0/W)))**RV)**(W*Z))
   RETURN
60 IF (LA,MT,NE.0.0 ) GO TO 10
   R=RV**(W*Z)
   RETURN
10 SUM=0.0
   HES=5
   S1=9-1
   HES1=51
   NS1=51+1
   DO 20 IX=1,NS1
     I=IX-1
     20 SUM=SUM+FNCK(S,I)*((=1)**I)**((1.0 / (RS**((RES-I)/W))=1.0 ))**((NEG4A
     *3.0 *K**2)/(2.0 *K+I)**(3.0 *K+I))
     PROD2=PROD1*(1.5/3.0 *K,0.0 )
     PROD3=PROD1*(1.5/3.0 *K,2.0 *K)
     R=((RL**((3.0/W)))*(RS**((RES/W))**((1.0 )+1.5 *((1.0 / ((RL**((2.0/NEG4A
     **))*(RS**((RES/W))))-1.0 )-PROD3=PROD2*SUM))**RV)**(W*Z)
     RETURN
   END
SUBROUTINE NEG4B (RL,S,RV,Z,W,P,LA,MT,R)
C *****
C *
C * THIS SUBROUTINE COMPUTES THE *
C * RELIABILITY FOR EQUATION 4B *
C *
C *****
REAL LA,MT
INTEGER S,Z,W,S1
IF (S) 10,20,40
10 WRITE (6,1001)
20 IF (LA,MT,NE.0.0 ) GO TO 30
   R=RV**(W*Z)
   RETURN
30 R=((1.5 *RL**((1.0/W)-0.5*RL**((3.0/W)))**RV)**(W*Z))
   RETURN
40 IF (LA,MT,NE.0.0 ) GO TO 50

```

```

19 NEG4B
20 NEG4B
21 NEG4B
22 NEG4B
23 NEG4B
24 NEG4B
25 NEG4B
26 NEG4B
27 NEG4B
28 NEG4B
29 NEG4B
30 NEG4B
1 NEG5
2 NEG5
3 NEG5
4 NEG5
5 NEG5
6 NEG5
7 NEG5
8 NEG5
9 NEG5
10 NEG5
11 NEG5
12 NEG5
13 NEG5
14 NEG5
15 NEG5
16 NEG5
17 NEG5
18 NEG6
19 NEG6
20 NEG6
21 NEG6
22 NEG6
23 NEG6
24 NEG6
25 NEG6
26 NEG6
27 NEG6
28 NEG6
29 NEG6
30 NEG6
1 INTERP
2 INTERP
3 FINAL
4 FINAL
5 FINAL
6 FINAL
7 FINAL
8 CRUSH
9 INTERP
10 INTERP
11 INTERP
12 INTERP
13 INTERP
14 INTERP
15 NEG6
16 NEG6
17 NEG6
18 INTERP
19 INTERP
20 FINAL
21 FINAL
22 FINAL
23 FINAL
24 FINAL
25 INTERP
26 FINAL
27 FINAL
28 CRUSH
29 INTERP
30 INTERP
1 INTERP
2 INTERP
3 INTERP
4 INTERP
5 INTERP
6 INTERP
7 INTERP
8 INTERP
9 INTERP
10 INTERP
11 INTERP
12 INTERP
13 INTERP
14 INTERP

```

```

M=RV** (M*Z)
RETURN
50 SUM=0.0
SI=S+1
NS=S+1
DO 60 IX=1,N3
I=IX-1
60 SUM=SUM+((1.0 *LMT)**I)*((1.50 )** (SI-I))-1.0 )/FPAC(I)
R=(((1.50 )*(SI))*(HL** (1.0/M)))-((RL** (3.0/M))*SUM)**(M*Z)
RETURN
1001 FORMAT (* ILLEGAL VALUE FOR S = S CANNOT BE NEGATIVE*)
END
SUBROUTINE NEG5 (RL,RV,Z,M,P,LAMT,R)
C *****
C * THIS SUBROUTINE COMPUTES THE *
C * RELIABILITY FOR EQUATION 5 *
C * *
C *****
REAL LAMT
INTEGER M,Z
RLAM=RL** (1.0/M)
R=3.0 *RLAM**2-2.0 *RLAM**3+6.0 *P** (1.0 -P)*RLAM
R=(R*RV)**(M*Z)
RETURN
END
SUBROUTINE NEG6 (RL,Z,M,P,LAMT,R)
C *****
C * THIS SUBROUTINE COMPUTES THE *
C * RELIABILITY FOR EQUATION 6 *
C * *
C *****
REAL LAMT
INTEGER Z,M
IF (M.EQ. 0.0) WRITE (6,20 )
20 FORMAT (// 'EEEEEEEEEEEEEEHRROR, THE PARAMETER = M = IS ZERO *')
R=RL** (Z/R*M)
RETURN
END
SUBROUTINE NEG7 (RL,RS,NS,N,XK,0,CX,RV,NZ,NM,P,
* BCOMP,XLAMT,DCR)
C LOGICAL BCOMP,MSGN
COMMON /DRIVE/TX,STEP,HSTEP,NUN,RSGN,JMAX,I10,SUMLAM
T=ALOG(RL)/SUMLAM
COMMON //IDUM(I1),FDUM(I1),R(121,10)
J1/STEP+1
J=MAX0(2,J)
J=MIN0(J,JMAX)
I=J-1
K=J+1
X1=STEP*(I-1)
X2=X1+STEP
X3=X2+STEP

```

```

9 FINAL
10 FINAL
11 FINAL
12 INTERP7
13 INTERP7
14 INTERP7
15 INTERP7
16 INTERP7
17 INTERP7
18 INTERP7
19 INTERP7
20 INTERP7
21 INTERP7
22 INTERP7
23 INTERP7
24 INTERP7
25 INTERP7
26 INTERP7
27 INTERP7
28 INTERP7
29 INTERP7
30 INTERP7
31 PARARI
32 PARARI
33 PARARI
34 PARARI
35 PARARI
36 PARARI
37 PARARI
38 PARARI
39 PARARI
40 PARARI
41 PARARI
42 PARARI
43 PARARI
44 PARARI
45 PARARI
46 PARARI
47 PARARI
48 PARARI
49 PARARI
50 PARARI

Y1=K(1,110)
Y2=K(2,110)
Y3=K(3,110)
Z1=Y1-2*Y2+Y3
Z2=2.0*STEP**2
A=Z1/Z2
Z3=(Y3-Y1)/(2.0*STEP)
H=Z3-2.0*A*X2
C=Y2-A*X2**2-B*X2
D=C*A*ST**2+B*ST+C
IF (DCR.LT.0.0.UR,DCR,GT.1.0) GO TO 100
RETURN
100 WRITE(6,11)
11 FORMAT(/25X,'*KRRUR IN EQUATION 7 INTERPOLATION*')
END.
SUBROUTINE PARAH1 (R2,R1MIN,H1MAX,R1STEP,PLOTX2,K2OPT,I10,TMAX)
*****
*
* THIS SUBROUTINE COMPUTES THE *
* RATIO OF MAX. MISSION TIMES *
* (RATIF) FOR THE VARIOUS SYSTEM *
* PARAMETERS SPECIFIED. *
*
*****
DIMENSION PARAM(16,10)
REAL COMR1(101,4),TMAX1(101),TMAX2(101),RATIF(101)
REAL TMAX(101,15),XAXIS(101)
REAL ENC(20),A3
INTEGER PROD(10),PAR(6),NPHOD,NEG,N10,K1,I10,R2OPT
LOGICAL OUTP1,OUTP2,OUTP3,OUTP4,OUTP5
COMMON/GRAPH/ NEG,PROD,NPHOD,PAR,ENC,AB,PRODT
COMMON /PARAM/ PARAM,N10,K1
COMMON /OUTPT/ OUTP1,OUTP2,OUTP3,OUTP4,OUTP5
COMMON/CPLT/CUMRI
EQUIVALENCE (COMR1(1,1),XAXIS(1)), (COMR1(1,2),TMAX1(1)),
(COMR1(1,3),TMAX2(1)), (COMR1(1,4),RATIF(1))
*
DATA INFI/4HINFI,NITY/4HNITY/
DATA ITEST1/1/
DATA NPT/10/
NPLT=0
NOPLOT=.TRUE.
IF (R2OPT.EQ.1) GO TO 30
IF (R2OPT.EQ.3) GO TO 10
IR2=I10
IR1=I10-1
GO TO 60
10 WRITE (6,1001) PAR
20 READ(5,1002) IR1,IR2
21 IF (OUTP3) WRITE (6,1003) IR1,IR2
IF (IR1.LE.I10.AND.IR2.LE.I10) GO TO 60
WRITE (6,1004)
STOP
30 IR1=0
40 IR1=IR1+1
IF (IR1.EQ.N10) GO TO 130
IR2=IR1
IR2=IR2+1
IF (IR2.GT.N10) GO TO 40
60 IF (OUTP5) WRITE (6,1005) PAR,PARAM(IR1,K1),PAR,PARAM(IR2,K1),
NEG,AB,R2
R1=R1MIN
J=0
90 J=J+1

```



```

1 CRUSH
2 CRUSH
3 CRUSH
4 CRUSH
17 PLOTR
18 PLOTR
19 PLOTR
20 PLOTR
21 PLOTR
22 PLOTR
5 CRUSH
24 PLOTR
25 PLOTR
26 PLOTR
1 CAREPIX
28 PLOTR
29 PLOTR
30 PLOTR
31 PLOTR
32 PLOTR
33 PLOTR
34 PLOTR
35 PLOTR
36 PLOTR
37 PLOTR
38 PLOTR
39 PLOTR
40 PLOTR
41 PLOTR
42 PLOTR
43 PLOTR
44 PLOTR
45 PLOTR
46 PLOTR
47 PLOTR
48 PLOTR
49 PLOTR
50 PLOTR
51 PLOTR
52 PLOTR
53 PLOTR
54 PLOTR
55 PLOTR
56 PLOTR
57 PLOTR
58 PLOTR
59 PLOTR
60 PLOTR
61 PLOTR
62 PLOTR
63 PLOTR
64 PLOTR
65 PLOTR
66 PLOTR
67 PLOTR
68 PLOTR
69 PLOTR
70 PLOTR
71 PLOTR
72 PLOTR
73 PLOTR
74 PLOTR
75 PLOTR
76 PLOTR
77 PLOTR
78 PLOTR

DIMENSION XY(1,4),XNAME1(2),XNAME5(2),XNAME4(2),
* XNAME(2),YNAME(2)
REAL DIFF(1,1),RIF(1,1),GAIN(1,1),ABSC(1,1),
* G(1,1),FDUM(1),R(121,10)
INTEGER IDUM(11),PLOT
LOGICAL TIN,XYRANGE,LUG
COMMON /PLOTIN/ TIN,MIN,MAX,STEP,DIFF,RIF,GAIN,MTF,FOPX,
* PDT,SIMPX,XMIN,XMAX,YMIN,YMAX,XYRANGE,IA,IAA,IB,IBB,
* IC,ICC,IPLT1,IPLT2,IPLT3,IPLT4,IPLT5
COMMON IDUM,FDUM,R
COMMON /GRAFF/DUM(2),PSYMBL(16)
DATA JDIM/121/
DATA XNAME(1),XNAME(2),XNAME3(1),XNAME3(2),XNAME4(1),
*XNAME4(2),XNAME5,XNAME6,XNAME7,YNAME3,YNAME4,YNAME5,YNAME6,
*XNAME7,YNAME8/8MISSION,7M TIME T,10NORMALIZED,8MSIMPLEX,
*10RELIABILITY,5HLOG10,3H(T),6H(LAMT),10HEXP(-LAMT),9HPARAMETER,
*10H UN,4HDIFF,3HRIF,4HGAIN,10HPRODUCT OP,3HMTF,6HAT MTF/
DD 10 I=1,2
10 XNAME(I)=YNAME(I)=1H
NPLT=0
NPT=INT((MAX=MIN)/STEP)+1
IPLT=1
IAAT=IAA
IBBT=IBB
ICCT=ICC
IF (IPLT2.NE.1) IPLT=2
20 GO TO (30,40,50),IPLT
C
C *** SET UP INFORMATION FOR RELIABILITY PLOT ***
30 DD 35 I=1,KC
DD 35 J=1,JDIM
35 G(J,I)=R(J,I)
C
C SET UP SIMREL CURVE FOR REL. PLOTS WHEN X-AXIS IS EXP(-LAMT)
KCEXP=KC+1
DD 38 J=1,JDIM
38 G(J,KCEXP)=SIMPX(J)
YNAME(1)=XNAME3(2)
YNAME(2)=10H(EJA,EGB,,
GO TO 170
40 IF (IPLT5.NE.1) GO TO 310
C
C *** SET UP INFORMATION FOR UNRELIABILITY PLOT ***
DD 45 I=1,KC
DD 45 J=1,JDIM
45 G(J,I)=1.0-H(J,I)
YNAME(1)=YNAME2
YNAME(2)=XNAME3(2)
GO TO 170
50 WRITE (6,1016) NPLT
RETURN
C
C *****
C *
C * ENTRY FOR DIFF, RIF, *
C * AND GAIN PLOTS *
C *
C *****
C
C ENTRY PLOTG
KCEXP=KC+1
NPT=INT((MAX=MIN)/STEP)+1
IAAT=IAA
IBBT=IBB
ICCT=ICC
NPLT=0

```



```

145 PLOTR
146 PLOTR
147 PLOTR
148 PLOTR
149 PLOTR
150 PLOTR
151 PLOTR
152 PLOTR
153 PLOTR
154 PLOTR
155 PLOTR
156 PLOTR
157 PLOTR
158 PLOTR
159 PLOTR
160 PLOTR
161 PLOTR
162 PLOTR
163 PLOTR
164 PLOTR
165 PLOTR
166 PLOTR
167 PLOTR
168 PLOTR
169 PLOTR
170 PLOTR
171 PLOTR
172 PLOTR
173 PLOTR
174 PLOTR
175 PLOTR
176 PLOTR
177 PLOTR
178 PLOTR
179 PLOTR
180 PLOTR
181 PLOTR
182 PLOTR
183 PLOTR
184 PLOTR
185 PLOTR
186 PLOTR
187 PLOTR
188 PLOTR
189 PLOTR
190 PLOTR
191 PLOTR
192 PLOTR
193 PLOTR
194 PLOTR
195 PLOTR
196 PLOTR
197 PLOTR
198 PLOTR
199 PLOTR
200 PLOTR
201 PLOTR
202 PLOTR
203 PLOTR
204 PLOTR
205 PLOTR
206 PLOTR
207 PLOTR
208 PLOTR
209 PLOTR
210 PLOTR

NPTP= INT((MAX=MIN)/STEP)+1
YNAME(1)=YNAME6
YNAME(2)=XNAME3(2)
GO TO 170
160 WRITE (6,1016) NPLT
RETURN
170 CONTINUE
IF (IA.NE.1) GO TO 210
C
C *** SET UP INFORMATION FOR PLOTS WITH ***
C *** ABSCISSA T OR LOG(T) = BASE 10 ***
XNAME(1)=XNAME1(1)
XNAME(2)=XNAME1(2)
LOG=.FALSE.
GO TO 200
190 XNAME(1)=XNAME4(1)
XNAME(2)=XNAME4(2)
C
200 CALL PLOTN(KC,NPTP,50,XY,G,PSYMBL,16,121,LOG)
C
C *** PRINT DATA BELOW PLOT ***
WRITE(6,205) (YNAME(KL),KL=1,2), (XNAME(KL),KL=1,2)
205 FORMAT(/,40X,2A10,2X,*VS*,2X,2A10)
CALL ROMPLT
NPLT=NPLT+1
210 IF (IA.NE.1) GO TO 220
IAA=0
LOG=.TRUE.
GO TO 190
220 CONTINUE
IF (IB.NE.1) GO TO 250
C
C *** SET UP INFORMATION FOR PLOTS WITH ***
C *** ABSCISSA LAMT OR LOG(LAMT) = BASE 10 ***
XNAME(1)=XNAME2
XNAME(2)=XNAME1(2)
LOG=.FALSE.
GO TO 240
230 XNAME(1)=XNAME4(1)
XNAME(2)=XNAME5
C
240 CALL PLOTN(KC,NPTP,50,XY(1,2),G,PSYMBL,16,121,LOG)
C
C *** PRINT DATA BELOW PLOT ***
WRITE(6,205) (YNAME(KL),KL=1,2), (XNAME(KL),KL=1,2)
CALL ROMPLT
NPLT=NPLT+1
250 IF (IB.NE.1) GO TO 260
IRB=0
LOG=.TRUE.
GO TO 230
260 CONTINUE
IF (IC.NE.1) GO TO 290
C
C *** SET UP INFORMATION FOR PLOTS WITH ***
C *** ABSCISSA EXP(-LAMBDA*T) OR ***
C *** LOG(EXP(-LAMBDA*T)) = BASE 10 ***
XNAME(1)=XNAME3(1)
XNAME(2)=XNAME3(2)
LOG=.FALSE.
GO TO 280
270 XNAME(1)=XNAME4(1)
XNAME(2)=XNAME6
280 CALL PLOTN(KC,NPTP,50,XY(1,3),G,PSYMBL,16,121,LOG)
C
C *** PRINT DATA BELOW PLOT ***

```

```

WRITE(6,205) (YNAME(KL),KL=1,2), (XNAME(KL),KL=1,2)
CALL ROMPLT
NPLT=NPLT+1
LUG=.TRUE.
290 IF (ICC.NE.1) GO TO 310
ICC=0
GO TO 270
300 XNAME(2)=XNAME7
XNAME(1)=1H
DU 305 I=1,KC
305 ABSC(I,1)=PANAM(I,K1)
CALL PLOTN(1,KC,50,XY,6,PSYMBL,16,121,L06)
WRITE(6,205) (YNAME(KL),KL=1,2), (XNAME(KL),KL=1,2)
CALL ROMPLT
NPLT=NPLT+1
310 IPLOT=IPLOT+1
IAA=IAAT
IBB=IBBT
ICC=ICCT
GO TO (20,70,120), IPLT
1016 FORMAT(/,40X,I3,*, PLOT(S) COMPLETED*)
END
SUBROUTINE PLOT(NPP,IBIRTH)
*****
C *
C * THIS SUBROUTINE PLOTS THE *
C * MAX. MISSION TIME FUNCTIONS*
C * TMAX, SIMTMAX, SIMTIF AND *
C * MATIF. *
C * *
C *****
DIMENSION PSYMBL(3)
COMMON/PLOT/AXIS(101),YAXIS(101,J)
COMMON/PLOT/AXISC(101),YAXISC(101,3)
COMMON/SWAFF/DUM(2),PSYMBL
IF(IBIRTH.EQ.1)
1CALL PLOTN(3,NPP,50,AXIS,YAXIS,PSYMBL,3,101,*,F.)
IF(IBIRTH.EQ.2) CALL PLOTN(3,NPP,50,AXISC,YAXISC,PSYMBL,3,101,
2F.)
CALL ROMPLT
RETURN
END
SUBROUTINE PLOTN(NPLT,NBIN,NLIN,AXIS,YAXIS,PSYMBL,MAXPLT,MAXPT,
1LUG)
DIMENSION AXIS(MAXPT),PSYMBL(MAXPLT),YAXIS(MAXPT,MAXPLT)
COMMON/PLTWR/NUM,PS(10),ZLINE,BLANK,DUM(3),NHI,JMB,RESTY
LOGICAL LUGN
COMMON /PUN/LOGN
DATA ZLINE/10H-----/
LOGN=LOG
IF(.NOT.LUGN) GO TO 91
DO 90 KIP=1,NPLT
DO 90 LIP=1,NBIN
YAXIS(LIP,KIP)=ALOG10(YAXIS(LIP,KIP))
90 CONTINUE
91 CONTINUE
NHI=(NBIN+9)/10
IF (NPLT.GT.0) GO TO 8
NPLT=NPLT
GO TO 18
8 CONTINUE
YMAX=YAXIS(1,1)
YMIN=YMAX
DO 2 J=1,NPLT
DO 2 I=1,NBIN
YMAX=MAX1(YMAX,YAXIS(I,J))

```

211 PLOTN
212 PLOTN
213 PLOTN
214 PLOTN
215 PLOTN
216 PLOTN
217 PLOTN
218 PLOTN
219 PLOTN
220 PLOTN
221 PLOTN
222 PLOTN
223 PLOTN
224 PLOTN
225 PLOTN
226 PLOTN
227 PLOTN
228 PLOTN
229 PLOTN
230 PLOTN
231 PLOTN
232 PLOTN
1 PLOTN
2 PLOTN
3 PLOTN
4 PLOTN
5 PLOTN
6 PLOTN
7 PLOTN
8 PLOTN
9 PLOTN
10 PLOTN
11 PLOTN
12 PLOTN
13 CRUSH
14 PLOTN
15 PLOTN
16 PLOTN
17 PLOTN
18 PLOTN
19 PLOTN
20 PLOTN
1 PLOTN
2 PLOTN
3 PLOTN
4 PLOTN
5 PLOTN
6 PLOTN
7 PLOTN
8 PLOTN
9 PLOTN
10 PLOTN
11 PLOTN
12 PLOTN
13 PLOTN
14 PLOTN
15 PLOTN
16 PLOTN
17 PLOTN
18 PLOTN
19 PLOTN
20 PLOTN
21 PLOTN
22 PLOTN
23 PLOTN
24 PLOTN

```

2  YMIN=AMINI(YMIN,YAXIS(I,J))
   YSPAN=MAX-YMIN
   AMX=MAX
   HYMX=MAX
   IF (YMIN.GE.0.0) GO TO 10
   IF ((YMAX.GT.0.0).AND.(YMIN.LT.0.0)) GO TO 11
   HYMX=MIN
   AMX=MIN
   YMIN=MAX
   YMAX=HYMX
10  IF (YSPAN.GT.(HYMX/2.)) GO TO 11
   HYMX=HYMX/2.
   DO 12 J=1,NPLT
   DO 12 I=1,NBIN
12  YAXIS(I,J)=YAXIS(I,J)+HYMX
   GO TO 10
11  CONTINUE
   NLINES=IABS(NLIN)
   DV=AMAXI(YSPAN,AYMX)/FLOAT(NLINES)
   RESTY=MAX-HYMX
   HYMX=DIM(HYMX,0.0)
   XHYM=HYMX
18  CONTINUE
   NBIN=NBIN
   NGROS=(NBIN-1)/100
   IGRUS=NGROS
19  CONTINUE
   HYMX=XHYM
   PRINT 105
   IF (IGROS.EQ.0) GO TO 60
   NBIN=100
   GO TO 61
60  NBIN=NBIN-NGROS+100
61  NHI=(NBIN+9)/10
   ICOR=100*(NGROS-IGROS)
   DO 62 J=1,NPLT
   DO 62 I=1,NBIN
62  YAXIS(I,J)=YAXIS(I+ICOR,J)
   DO 63 I=1,NBIN
63  XAXIS(I)=XAXIS(I+ICOR)
   LFLG=0
   DO 20 K=1,NLINES
   IF ((HYMX.GT.0.0).OR.(LFLG.NE.0)) GO TO 23
   LFLG=1
   DO 25 I=1,NHI
25  PS(I)=ZLINE
   PRINT 101,(PS(I),I=1,NHI)
23  DO 21 I=1,NHI
21  PS(I)=BLANK
   DO 22 J=1,NPLT
   DO 22 I=1,NBIN
   YI=YAXIS(I,J)
   IF ((HYMX.LT.YI).OR.((HYMX=YI).GT.DY)) GO TO 22
   I2=I+9)/10
   I2=I-(I1-1)=10
   CALL MOVCI(PSYHBL(J),I2,PS(I))
22  CONTINUE
   CONT=REDUC(HYMX+RESTY)
   PRINT 102,CONT,(PS(I),I=1,NHI)
   PRINT 107
20  HYMX=HYMX-DY
   CONT=REDUC(HYMX+RESTY)
   DO 30 I=1,NHI
30  PS(I)=ZLINE
   PRINT 102,CONT,(PS(I),I=1,NHI)

```

```

65  PLOTN
66  PLOTN
67  PLOTN
68  PLOTN
69  PLOTN
70  PLOTN
71  PLOTN
72  PLOTN
73  PLOTN
74  PLOTN
75  PLOTN
76  PLOTN
77  PLOTN
78  PLOTN
79  PLOTN
80  PLOTN
81  PLOTN
82  PLOTN
83  PLOTN
84  PLOTN
85  PLOTN
86  PLOTN
87  PLOTN
88  PLOTN
89  PLOTN
90  PLOTN

```

```

PRINT 107
DO 40 I=1,NBIN
  I1=(I+9)/10
  I2=I-(I1-1)*10
40 CALL MOVG(I1,NUM,I2,PS(I1))
PRINT 107
CONTINUE(J)
PRINT 106,CONT,(PS(I),I=1,NHI)
DO 45 I=1,NBIN
  I1=(I+9)/10
  I2=I-(I1-1)*10
45 CALL MOVG(I2,NUM,I2,PS(I1))
CONTINUE
PRINT 106,CONT,(PS(I),I=1,NHI)
IF (NLINE.LT.0) GO TO 70
PRINT 104
CALL WRNR(XAXIS(1),NBIN)
DO 50 J=1,NPLT
  PRINT 103, PBYMBL(J)
DO 55 I=1,NBIN
55 YAXIS(I,J)=REDUC(YAXIS(I,J)+RESTY)
50 CALL WRNR(YAXIS(1,J),NBIN)
70 IF (IGRUS.EQ.0) GO TO 100
  IGRUS=IGRUS+1
  GO TO 19
100 RETURN
101 FORMAT(1H+,19X,10A10)
102 FORMAT(1H+,F12.3,7X,10A10)
103 FORMAT(1H0,*CONTENTS OF CHANNELS FOR HISTOGRAM=3X,A1,3X,
  A *FOLLOW=/)
104 FORMAT(=CHANNEL VALUES FOR X AXIS=/)
105 FORMAT(1H1)
106 FORMAT(10X,45,5X,10A10)
107 FORMAT(1H )
END
SUBROUTINE WRNR(X,N)
  DIMENSION X(1)
  DIMENSION IX(100)
  COMMON/PLTWR/NUM ,KX(10),MINUS,MESAG(4),NHI,NUMB,RESTY
  DATA NUM/10H0123456789/,NUMB/4HNUMB/,
  DATA MESAG/1H ,4HCONT,3H OF,4HCHAN/,1DOT/1H,/,
  DATA INF/10HRRRRRRRRR/,IZERO/10HZZZZZZZZZ/
  XMAX=ABS(X(1))
  DO 10 I=2,N
    XMAX=MAX1(XMAX,ABS(X(I)))
  IF (XMAX.LT.1.E-6) GO TO 150
  IF (XMAX.GE.1.E6) GO TO 160
  XI=ALOG10(XMAX)
  NLINE=6
  IPNT=(XI+ABS(XI))/2. +1.
  NPWR=NLINE-IPNT
  DO 5 I=1,NHI
    KX(I)=MESAG(I)
    DO 11 I=1,N
      IF (X(I).GE.0.0) GO TO 11
      I1=(I+9)/10
      I2=I-(I1-1)*10
      CALL MOVG(I1,MINUS,I2,KX(I1))
11 CONTINUE
    MES1=MESAG(1)
    MES2=MES1
    PRINT 1010,MES1,MES2,(KX(I),I=1,NHI)
    DO 20 I=1,N
      I1=(I+9)/10
      I2=I-(I1-1)*10
      CALL MOVG(I1,NUM,I2,PS(I1))
20 IX(I)=ABS(X(I))*10.**NPWR+.5
21 K9=0
22 DO 22 I=1,N

```

PLOTN 91
PLOTN 92
PLOTN 93
PLOTN 94
PLOTN 95
PLOTN 96
PLOTN 97
PLOTN 98
PLOTN 99
PLOTN 100
PLOTN 101
PLOTN 102
PLOTN 103
PLOTN 104
PLOTN 105
PLOTN 106
PLOTN 107
PLOTN 108
PLOTN 109
PLOTN 110
PLOTN 111
PLOTN 112
PLOTN 113
PLOTN 114
PLOTN 115
PLOTN 116
PLOTN 117
PLOTN 118
PLOTN 119
PLOTN 120
PLOTN 121
PLOTN 122
PLOTN 123
PLOTN 124
PLOTN 125
WRNR 1
WRNR 2
WRNR 3
WRNR 4
WRNR 5
WRNR 6
WRNR 7
WRNR 8
WRNR 9
WRNR 10
WRNR 11
WRNR 12
WRNR 13
WRNR 14
WRNR 15
WRNR 16
WRNR 17
WRNR 18
WRNR 19
WRNR 20
WRNR 21
WRNR 22
WRNR 23
WRNR 24
WRNR 25
WRNR 26
WRNR 27
WRNR 28
WRNR 29
WRNR 30
WRNR 31


```

0  MOVL
1  MOVC
2  REDUC
3  REDUC
4  REDUC
5  REDUC
6  REDUC
7  REDUC
8  ROMBD
9  ROMBD
10 ROMBD
11 ROMBD
12 ROMBD
13 ROMBD
14 ROMBD
15 ROMBD
16 ROMBD
17 ROMBD
18 ROMBD
19 ROMBD
20 ROMBD
21 ROMBD
22 ROMBD
23 ROMBD
24 ROMBD
25 ROMBD
26 ROMBD
27 ROMBD
28 ROMBD
29 ROMBD
30 ROMBD
31 ROMBD
32 ROMBD
33 ROMBD
34 ROMBD
35 ROMBD
36 ROMBD
37 ROMBD
38 ROMBD
39 ROMBD
40 ROMBD
41 ROMBD
42 ROMBD
43 ROMBD
44 ROMBD
45 ROMBD
46 ROMBD
47 ROMBD
48 ROMBD
49 ROMBD
50 ROMBD
51 ROMBD
52 ROMBD
53 ROMBD
54 ROMBD
55 ROMBD
56 ROMBD
57 ROMBD

RETURN
END
FUNCTION REDUC(X)
LOGICAL LOGN
COMMON /FUN/LOGN
REDUC=X
IF (LOGN) REDUC=(10.)*X
RETURN
END
SUBROUTINE ROMBD(A,B,X2,POFX,HSTAR,HMIN,HMAX,ERMAX,ANS,K,KEY)
C
C THE DOCUMENTATION OF THIS SUBROUTINE IS ENTITLED
C ROMBERG QUADRATURE SUBROUTINES FOR SINGLE AND MULTIPLE INTEGRALS
C SECTION 314 TECH. MEMO NO. 221, JET PROPULSION LAB.
C 1 JULY, 1969
C BY W. BUNTON, M. DIETHELM, K. HAIGLER
C
H = CURRENT STEP SIZE
NAB= 0, H .GT. HMIN, S1, THEN H =LE. HMIN
NFG= 0 MAY DOUBLE STEP, S=1 CANT DOUBLE AFTER PREVIOUS CUT
K=1, INTEGRATE FROM A TO B, S2, FINISHED INTEGRATION
I = COUNTER ON I TH FUNCTIONAL EVALUATION
X2= INDEPENDENT VARIABLE
LL=1, TAKE 16 OR 17 FUNCTIONAL EVALUATIONS
LL=2, TAKE ONLY 6 FUNCTIONAL EVALUATIONS
X1 = FIRST X VALUE OF EACH SUBINTERVAL
KEY= FLAG ON THE DIAGNOSTIC PRINT
C
C DIMENSION Y(17),T(5,5)
C POFX HAS BEEN DIMENSIONED TO OBTAIN PROPER EXECUTION ON THE UNIVACROMBD
C 1108. IT IS NOT NECESSARY FOR THE USER TO DIMENSION POFX IN HIS
C CALLING PROGRAM
C INTEGER FINISH
C IF(A.GE.B.OR.HMIN.GT.HSTAR.OR.HMIN.LE.0..OR.HMAX.LT.HMIN.OR.ERMAX.
C *LE.0..OR.HSTAR.GT.HMAX)GO TO 200
C
C INITIALIZE STARTING VALUES
ANS = 0.
NAB = 0.
NFG = 0
X1 = A
H = HSTAR
K = 1
I = 0
X2 = X1
LL=1
FINISH = 0
IF(X1+16.*H.LT.B)GO TO 10
H=(B-A)/16.
FINISH=1
10 RETURN
ENTRY ROM2D
C
C STORE FUNCTIONAL EVALUATIONS IN Y ARRAY
IF( LL.GT.1 ) GO TO 140
I = I + 1
Y(I)=POFX
IF(I.EQ.17) GO TO 20
X2 = X2 +H
IF(I.EQ.16.AND.FINISH.EQ.1)X2=B
RETURN
C
C CALCULATE T VALUES

```



```

124 ROMBD
125 ROMBD
126 ROMBD
127 ROMBD
128 ROMBD
129 ROMBD
130 ROMBD
131 ROMBD
132 ROMBD
133 ROMBD
134 ROMBD
135 ROMBD
136 ROMBD
137 ROMBD
138 ROMBD
139 ROMBD
140 ROMBD
141 ROMBD
142 ROMBD
143 ROMBD
144 ROMBD
145 ROMBD
146 ROMBD
147 ROMBD
148 ROMBD
149 ROMBD
150 ROMBD
151 ROMBD
152 ROMBD
153 ROMBD
154 ROMBD
155 ROMBD
156 ROMBD
157 ROMBD
158 ROMBD
159 ROMBD
160 ROMBD
161 ROMBD
162 ROMBD
163 ROMBD
164 ROMBD
165 ROMBD
166 ROMBD
167 ROMBD
168 ROMBD
169 ROMBD
170 ROMBD
171 ROMBD
172 ROMBD
173 ROMBD
174 ROMBD
175 ROMBD
176 ROMBD
177 ROMBD
1 RIFDIF
2 RIFDIF
3 RIFDIF
4 RIFDIF
5 RIFDIF
6 RIFDIF
7 RIFDIF
8 RIFDIF
9 RIFDIF
10 RIFDIF
11 RIFDIF
12 RIFDIF

NFG=1
IF(H.GT.HMIN) GO TO 130
IF(NAB.EQ.1) GO TO 160
C
C
C
MMIN HAS BEEN REACHED
NAB=1
HMIN
X2 = X1 + H
I = 1
GO TO 10
C
C
C
IN H CUT, SAVE VALUABLE INFO
130 Y(17)= Y(9)
Y(15)= Y(8)
Y(13)= Y(7)
Y(11)= Y(6)
Y(9)= Y(5)
Y(7)= Y(4)
Y(5)= Y(3)
Y(3)= Y(2)
I=0
LL = 2
X2 = X1 + H
FINISH=0
RETURN
C
C
C
NOW PICK UP ONLY THOSE FUNCTIONAL EVALUATIONS NECESSARY
140 I= I+2
Y(I)=F(X)
IF( I .GE. 16) GO TO 150
X2= X2 +2.*H
RETURN
150 LL=1
GO TO 20
C
C
C
BOTH TEST D.1 AND D.2 HAVE FAILED, ACCEPT ANSWER
AND PROCEED WITH INTEGRATION
160 H= HMIN
IF(KEY.NE.7) WRITE (6,170) X1,X2
170 FORMAT(16H IN INTERVAL X= E18.8,7H TO X= F18.8,56H RELATIVE ERROR
SCANNOT BE REACHED WITH MINIMUM STEP SIZE )
GO TO 50
180 K = 2
RETURN
200 WRITE(6,201)A,B,HSTAR,HMIN,HMAX,ERMAX
201 FORMAT(10X,36HERROR ROMBD,CHECK CALLING PARAMETERS//10X,3HA =,
*E15.8,5X,3HB =,E15.8,5X,8HMHSTAR =,E15.8,5X,6HMHMIN =,E15.8//10X
*6HMAX =,E15.8,5X,7HERMAX =,E15.8)
STOP
END
SUBROUTINE RIFDIF (I7,OPTION,IPRES,N7,TIN,MIN,MAX,STEP,JDIM,R,
* PDIFF,PRIF,PGAIN,NG,LPL0T,GPLOT)
C
C
C
*****
* THIS SUBROUTINE COMPUTES THE
* DIFFERENCE = DIFF, RELATIVE
* IMPROVEMENT = RIF, AND
* GAIN BETWEEN TWO VALUES OF
* THE FAMILY OF PARAMETERS
*****

```

```

13 RIFUIF
14 RIFDIF
1 CRUSH
16 RIFDIF
17 RIFDIF
18 RIFUIF
19 RIFDIF
20 RIFUIF
21 RIFDIF
22 RIFDIF
23 RIFDIF
24 RIFDIF
25 RIFDIF
26 RIFDIF
27 RIFDIF
28 RIFDIF
29 RIFDIF
30 RIFDIF
31 RIFDIF
32 RIFDIF
33 RIFDIF
34 RIFDIF
35 RIFDIF
36 RIFDIF
37 RIFDIF
38 RIFDIF
39 RIFDIF
40 RIFDIF
41 RIFDIF
42 RIFDIF
43 RIFDIF
44 RIFDIF
45 RIFDIF
46 RIFDIF
47 RIFDIF
48 RIFDIF
49 RIFDIF
50 RIFDIF
51 RIFDIF
52 RIFDIF
53 RIFDIF
54 RIFDIF
55 RIFDIF
56 RIFDIF
57 RIFDIF
58 RIFDIF
59 RIFDIF
60 RIFDIF
61 RIFDIF
62 RIFDIF
63 RIFDIF
64 RIFDIF
65 RIFDIF
66 RIFDIF
67 RIFDIF
68 RIFDIF
69 RIFDIF
70 RIFDIF
71 RIFDIF
72 RIFDIF
73 RIFUIF
74 RIFDIF
75 RIFDIF
76 RIFDIF
77 RIFDIF
78 RIFDIF

DIMENSION PARAM(16,10 )
REAL PDIFF(1,1),PRIF(1,1),PGAIN(1,1),R(121,1),RF(2)
REAL ENC(20),AB,DIFF,RIF,GAIN,INFINITY
REAL MIN,MAX
INTEGER PHOD(10),PAR(6),OPTION,NPROD
LOGICAL TIN,LPLOT,GPLUT,LRIF
LOGICAL PRODT
LOGICAL OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS
COMMON/CHARM/ NEG,PROD,NPROD,PAR,ENC,AB,PRODT
COMMON /PARAM/ PARAM,N10,K1
COMMON /OUTPT/ OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS
DATA ITES1,1/
DATA INFI,4MINFI,NITY,4MNITY/
GPLOT=.FALSE.
IF (OPTION.EQ.1) GO TO 30
IF (OPTION.NE.2) GO TO 10
IR2=I7
IR1=I7-1
NGENG+1
GO TO 60
10 WRITE (6,1000) PAR
20 HEAD (5,1001)
21 IF (OUTPT3) WRITE (6,1009) IR1,IR2
NGENG+1
IF (IR1.LE.I7.AND.IR2.LE.I7) GO TO 60
NGENG+1
WRITE (6,1003)
GO TO 20
30 IR1=0
40 IR1=IR1+1
IF (IR1.EQ.N7) GO TO 130
NGENG+1
IR2=IR1
50 IR2=IR2+1
IF (IR2.GT.N7) GO TO 40
60 IF (TIN) GO TO 70
IF (OUTPT2) WRITE (6,1004) PAR,PARAM(IR1,K1),PAR,PARAM(IR2,K1),
* NEG,AB
GO TO 80
70 IF (OUTPT2) WRITE (6,1005) PAR,PARAM(IR1,K1),PAR,PARAM(IR2,K1),
* NEG,AB
80 CT=MIN
J=1
LRIF=.TRUE.
DIFF=R(J,IR2)-R(J,IR1)
RIF=(1.0 -R(J,IR1))/(1.0 -R(J,IR2))
IF (R(J,IR2).NE.1.0 ) GO TO 91
ENCODE(8,1012,RF(1)) INFI,NITY
RIF=1.0E35
GO TO 910
91 ENCODE(14,1013,RF(1)) RIF
910 GAIN=R(J,IR2)/R(J,IR1)
IF (OUTPT2) WRITE (6,1006) CT,DIFF,(RF(I),I=1,2),GAIN
IF (OPTION.EQ.0.AND.LPLOT) GO TO 92
IF (IR2.NE.(IR1+1).OR.NOT.LPLOT) GO TO 96
C
C *** SET UP ARRAYS FOR DIFF, RIF, AND GAIN PLOTS ***
92 PDIFF(J,NG)=DIFF
PRIF(J,NG)=RIF
IF (LRIF) GO TO 94
C
C INSTEAD OF PLOTTING POINT WITH VALUE OF 1.0E35
C FOR RIF, PLOT 3.0TIMES THE VALUE OF THE NEXT POINT
C TO THE RIGHT FOR THAT VALUE
C PRIF(J-1,NG)= 3.0*PRIF(J,NG)

```



```

C      GO TO 110
C      60 IF (BCOMP) GO TO 70
C      COMPUTE RELIABILITY FOR EQUATION 4A
CALL NEG4A (RL,RS,S,K,RV,Z,W,P,LAMT,RDP)
GO TO 110
C      COMPUTE RELIABILITY FOR EQUATION 4B
70 CALL NEG4B (RL,S,RV,Z,W,P,LAMT,RDP)
GO TO 110
C      COMPUTE RELIABILITY FOR EQUATION 5
80 CALL NEG5 (RL,HV,Z,W,P,LAMT,RDP)
GO TO 110
C      COMPUTE RELIABILITY FOR EQUATION 6
90 CALL NEG6 (RL,Z,W,P,LAMT,RDP)
GO TO 110
C      COMPUTE RELIABILITY FOR EQUATION 7
100 CALL NEG7 (RL,RS,S,N,K,G,C,RV,Z,W,P,BCOMP,LAMT,RDP)
110 RETURN
END
SUBROUTINE HOPMLT
*****
* * THIS SUBROUTINE LABELS *
* * THE PLOTS GENERATED. *
* *
*****
REAL ENC(20)
INTEGER NEG,PRUD(10),NPROD,PAR(6)
LOGICAL PRODT
COMMON /GRAPH/NEG,PROD,NPROD,PAR,ENC,AB,PRODT
COMMON /PARAM/ PARAM,N10,K1
DIMENSION PARAM(10,10)
IF (PHODT) GO TO 10
WRITE(6,1001) NEG
WRITE(6,1002) PAR,(PARAM(I,K1),I=1,N10)
GO TO 20
10 WRITE(6,1006) (PROD(I),I=1,NPROD)
20 WRITE(6,1003)
WRITE(6,1004)
WRITE(6,1005) (ENC(I),I=1,20)
RETURN
C      FORMAT STATEMENTS
C      1001 FORMAT(/,60X,' PLOT FOR EQUATION ',I2)
C      1002 FORMAT (20X,'FAMILY OF PARAMETERS IS *6A1,* = *5(G13,6,2X),/,
C      * (40X,6(G13,8,2X)))
C      1003 FORMAT(20X,'(N1 MEANS NOT INPUTED OR DEFAULT VALUE USED)*')
C      1004 FORMAT(3X,'+LAMBDA*,9X,*MU*,11X,*S*,5X,*N*,6X,*K*,12X,*G*,
C      * 12X,*C*,11X,*RV*,12X,*Z*,5X,*W*,6X,*P*,11X,*MUTE*)
C      1005 FORMAT (1H ,10(2A6,1X))
C      1006 FORMAT (67X,*PLOT FOR EQUATIONS *,10(I2,2X))
C
C      END
SUBROUTINE SIMPRI (TIN,RCOMP,LAMBDA,S,N,K,G,C,RV,Z,W,P,NEG,
C      * R2,RLMIN,R1MAX,R1STEP,PLOTR1,OPTRI,I10,TMAX)
*****
* * THIS SUBROUTINE COMPUTES THE MAX. MISSION *
* * TIME (TMAX) AND THE SIMPLEX MISSION TIME *

```

```

36 RELEGS
37 RELEGS
38 RELEGS
39 RELEGS
40 RELEGS
41 RELEGS
42 RELEGS
43 RELEGS
44 RELEGS
45 RELEGS
46 RELEGS
47 RELEGS
48 RELEGS
49 RELEGS
50 RELEGS
51 RELEGS
52 RELEGS
53 RELEGS
54 RELEGS
55 RELEGS
56 RELEGS
57 RELEGS
58 RELEGS
59 RELEGS
1  ROMPLT
2  ROMPLT
3  ROMPLT
4  ROMPLT
5  ROMPLT
6  ROMPLT
7  ROMPLT
8  ROMPLT
9  ROMPLT
10 ROMPLT
11 ROMPLT
12 ROMPLT
13 ROMPLT
14 ROMPLT
15 ROMPLT
16 ROMPLT
17 ROMPLT
18 ROMPLT
19 ROMPLT
20 ROMPLT
21 ROMPLT
22 ROMPLT
23 ROMPLT
24 ROMPLT
25 ROMPLT
26 ROMPLT
27 ROMPLT
28 ROMPLT
29 ROMPLT
30 ROMPLT
31 ROMPLT
32 ROMPLT
33 ROMPLT
34 ROMPLT
35 ROMPLT
36 ROMPLT
1  SIMPRI
2  SIMPRI
3  SIMPRI
4  SIMPRI
5  SIMPRI
6  SIMPRI

```

```

7 SIMPRI
8 SIMPRI
9 SIMPRI
10 SIMPRI
11 SIMPRI
12 SIMPRI
13 SIMPRI
14 SIMPRI
15 SIMPRI
16 SIMPRI
17 SIMPRI
18 SIMPRI
19 SIMPRI
20 SIMPRI
21 SIMPRI
22 SIMPRI
23 SIMPRI
24 SIMPRI
25 SIMPRI
26 SIMPRI
27 SIMPRI
28 SIMPRI
29 SIMPRI
30 SIMPRI
31 SIMPRI
32 SIMPRI
33 SIMPRI
34 SIMPRI
35 SIMPRI
36 SIMPRI
37 SIMPRI
38 SIMPRI
39 SIMPRI
40 SIMPRI
41 SIMPRI
42 SIMPRI
43 SIMPRI
44 SIMPRI
45 SIMPRI
46 SIMPRI
47 SIMPRI
48 SIMPRI
49 SIMPRI
50 SIMPRI
51 SIMPRI
52 SIMPRI
53 SIMPRI
54 SIMPRI
55 SIMPRI
56 SIMPRI
57 SIMPRI
58 SIMPRI
59 SIMPRI
60 SIMPRI
61 SIMPRI
62 SIMPRI
63 SIMPRI
64 SIMPRI
65 SIMPRI
66 SIMPRI
67 SIMPRI
68 SIMPRI
69 SIMPRI
70 SIMPRI
71 SIMPRI
72 SIMPRI

C * (SIMTMAX) AND THE RATIO OF THESE (SIMTIF) *
C *
C *****
REAL SIMR1(101,4),XAXIS(101),SIMTMAX(101),SIMTIF(101),TH(101)
REAL TMAX(101,15),TX(4),INFINITY
REAL LAMBDA,K,LAMTR2,LAMTR1,INF
INTEGER S,N,Z,W,NEG
LOGICAL IIN,BCOMP,PLUTH1,FIRST,SEC,ZERO,OPTR1
LOGICAL OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPT5
EQUIVALENCE (SIMR1(1,1),XAXIS(1)), (SIMR1(1,2),SIMTMAX(1)),
* EQUIVALENCE (SIMR1(1,3),SIMTIF(1)), (SIMR1(1,4),TH(1))
COMMON /OUTPT/ OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPT5
COMMON/PLOT/SIMR1
DATA FIRST,.TRUE./, SEC,.FALSE./, INF/1.0E35/
DATA INFI/4*INFI/,NITY/4*INFI/
ZERO=.FALSE.
IF (.NOT.(OPTR1.AND.OUTPT5)) GO TO 20
IF (.NOT.(IN)) GO TO 10
WRITE (6,1001) R2
GO TO 20
10 WRITE (6,1002) R2
20 CALL BISECT(NEG,BCOMP,S,N,K,Q,C,RV,Z,W,P,FIRST,LAMTR2,R2)
R1=R1MIN
J=0
40 J=J+1
XAXIS(J)=R1
CALL BISECT(NEG,BCOMP,S,N,K,Q,C,RV,Z,W,P,SEC,LAMTR1,R1)
IF (LAMTR1.NE.INF) GO TO 50
ENCODE(8,1005,TX(1)) INFI,NITY
ENCODE(8,1005,TX(3)) INFI,NITY
SIMTIF(J)=1.0
ZEROS=THUE.
JJB=J
GO TO 84
50 SIMTMAX(J)=ALOG(R1)
IF (SIMTMAX(J).GT.1.0E=8) GO TO 60
SIMTMAX(J)=0.0
TMAX(J,I10)=0.0
SIMTIF(J)=1.0
GO TO 80
60 TMAX(J,I10)=LAMTR1-LAMTR2
IF (.NOT.TIN) GO TO 70
TMAX(J,I10)=TMAX(J,I10)/LAMBDA
SIMTMAX(J)=SIMTMAX(J)/LAMBDA
70 SIMTIF(J)=TMAX(J,I10)/SIMTMAX(J)
80 TH(J)=TMAX(J,I10)
ENCODE( 14,1006,TX(1)) SIMTMAX(J)
ENCODE( 14,1006,TX(3)) TMAX(J,I10)
84 IF (OPTR1.AND.OUTPT5) WRITE (6,1003) R1,(TX(I),I=1,4),SIMTIF(J)
R1=R1R1STEP
IF (R1.LE.R1MAX) GO TO 40
IF (.NOT.ZERO) GO TO 88
TMAX(J,I10)=2.0*TMAX(J,I10)
SIMTMAX(J)=2.0*SIMTMAX(J,I10)
88 IF (.NOT.PLOTR1) GO TO 90
CALL PLOTT(J,I)
WRITE (6,1004)
90 RETURN
1001 FORMAT (//,6X,MAXIMUM MISSION TIME=4X,REFERENCE R2 = *,F7.5//,
* 4X,R1=,9X,SIMLAMTMAX=,16X,LAMTMAX=,16X,*SIMTIF=)
1002 FORMAT (//,6X,MAXIMUM MISSION TIME=4X,REFERENCE R2 = *,F7.5//,
* 4X,R1=,8X,SIMTMAX=,17X,*TMAX=,17X,*SIMTIF=)
1003 FORMAT(1H ,F7.5(4X,2A10),3X,E14.7)
1004 FORMAT(//36X,* SIMLAMTMAX(A),SIMTIF(B),LAMTMAX(C) V8 R1(XAXIS) PLOTT(SIMPRI
* 3T COMPLETED *)

```



```

1  POSTPCH
2  POSTPCH
3  PARMOD
4  READIN
5  READIN
6  MAINLOG
7  MAINLOG
8  MAINLOG
9  MAINLOG
10 MAINLOG
11 READIN
12 READIN
13 READIN
14 READIN
15 READIN
16 MAINLOG
17 MAINLOG
18 MAINLOG
19 READIN
20 READIN
21 READIN
22 READIN
23 READIN
24 READIN
25 POSTPCH
26 MAINLOG
27 MAINLOG
28 READIN
29 READIN
30 READIN
31 READIN
32 READIN
33 READIN
34 READIN
35 READIN
36 READIN
37 READIN
38 READIN
39 READIN
40 READIN
41 READIN
42 READIN
43 MAINLOG
44 MAINLOG
45 MAINLOG
46 MAINLOG
47 MAINLOG
48 MAINLOG
49 MAINLOG
50 MAINLOG
51 MAINLOG
52 MAINLOG
53 MAINLOG
54 MAINLOG
55 MAINLOG
56 MAINLOG
57 MAINLOG
58 MAINLOG
59 MAINLOG
60 MAINLOG
61 MAINLOG
62 MAINLOG
63 MAINLOG
64 MAINLOG
65 MAINLOG
66 MAINLOG
67 MAINLOG
68 MAINLOG
69 MAINLOG
70 MAINLOG
71 MAINLOG
72 MAINLOG
73 MAINLOG
74 MAINLOG
75 MAINLOG
76 MAINLOG
77 MAINLOG
78 MAINLOG
79 MAINLOG
80 MAINLOG
81 MAINLOG
82 MAINLOG
83 MAINLOG
84 MAINLOG
85 MAINLOG
86 MAINLOG
87 MAINLOG
88 MAINLOG
89 MAINLOG
90 MAINLOG
91 MAINLOG
92 MAINLOG
93 MAINLOG
94 MAINLOG
95 MAINLOG
96 MAINLOG

DATA (IGENC(I),I=1,10)/10*0/, (IGENP(I),I=1,10)/10*0/
DATA (IFSC(I),I=1,8)/8*0/, (FRAC(I),I=1,8)/8*0.0/
NAMELIST /VAR/T,LAMT,ELAMT,MUT,MIN,STEP,B,OPTION
NAMELIST /VARI/ PROD
NAMELIST /OPTSON/OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS, PROOT,NEQ,
*   DEBUG,INPUT,STGOUT,COVINT,LSICH,CVPRC,DEFCHNG,
*   LPLOT,RVPLT,OPTR1,OPTR2,PLOTR1,PLOTR2,INO,XYRANGE,
NAMELIST /DEFAULT/GDEF,GDEF,LANDEF,LANDEF,GMDEF,CDEF,
*   CTRDEF,PRCDEF,RVDEF,POEF,NDEF,SDEF,HDEF,ZDEF
NAMELIST /COVCA/COVINT,IGENC,IGENP,IFSC,PRAC
INO=0
NPTS=10
T=0.0
LAMT=0.0
ELAMT=0.0
MIN=0.0
NPRODS=1
NUNS=0
DMFLG=.F.
DEBUG=.F.
INPUT=.T.
STGOUT=.F.
COVINT=.F.
LSICH=.F.
CVPRC=.F.
DEFCHNG=.F.
STEP=1.0
B=0.0
OPTION=0
TINS=.FALSE.
MUTINS=.FALSE.
ELATINS=.FALSE.
PRDINS=.FALSE.
XYRANGE=.FALSE.
LPLOT=.FALSE.
RVPLT=.FALSE.
OPTR1=.FALSE.
OPTR2=.FALSE.
PLOTR1=.FALSE.
PLOTR2=.FALSE.
OUTPT1=.FALSE.
OUTPT2=.FALSE.
OUTPT3=.FALSE.
OUTPT4=.FALSE.
OUTPTS=.FALSE.
IA=0
IAA=0
IB=0
IBB=0
IC=0
ICC=0
IPLT1=0
IPLT2=0
IPLT3=0
IPLT4=0
IPLT5=0
DO 20 I=1,10
MUT(I)=0.0
20 PROD(I)=0
C
C READ THE REQUESTED OPTIONS
HEAD(5,OPTSON)
PRINTED ANSWERS TO QUESTIONS OPTION
IF(OUTPTS) WRITE(6,1037) OUTPTS
IF(INO.GT. 0) WRITE(6,OPTSON )
PRODUCT OF RELIABILITY OPTION

```



```

105  GO TO 26
112 VAL=C2(J)
106  GO TO 26
113 VAL=C02(J)
107  GO TO 26
114 VAL=CTR(J)
108  GO TO 26
115 VAL=C0TR(J)
109  GO TO 26
116 VAL=PRC1(J)
110  GO TO 26
117 VAL=PRC2(J)
111  GO TO 26
118 VAL=RV(J)
112  GO TO 26
119 VAL=P(J)
120  GO TO 26
121 PARAM(1,J)=VAL
122  HEAD(S,VARY)
123  DO 28 I=1,16
124  DO 28 J=1,NPR0D
125  IF(PARAM(1,J).EQ.DVAL) GO TO 28
126  N10=1
127  CONTINUE
128  GO TO 1
129  GO TO 1
130  CONTROL CARD CONTAINS FUNCTION NUMBER SELECTION
131  DATA (C CARD)
132  GO TO 1
133  IPR=0
134  IF(IP.EQ.1MD) IPR=1
135  IF(IP.EQ.1MI) IPR=2
136  IF(IP.EQ.1ME) IPR=3
137  IF(IP.EQ.1HT) IPR=4
138  IF(IPR.EQ.0) GO TO 999
139  IF(ECARD) GO TO 52
140  IF(NUM.CT.NEXT(IPR)) GO TO 999
141  NUMSAV=NUM
142  IF(FCARD) GO TO 62
143  MD=MD.GT.2
144  IF(IET.EQ.0.AND.MD.NE.0) GO TO 999
145  IET=IET.GT.2
146  IF(ISU.EQ.0) GO TO 999
147  IF(ISU.GT.8) GO TO 32
148  ISU1=ISU
149  ISU2=ISU
150  GO TO 34
151  ISU1=1
152  ISU2=8
153  IF(MKN.EQ.0) GO TO 999
154  IF(MKN.GT.20) GO TO 36
155  MKN1=MKN
156  MKN2=MKN
157  GO TO 38
158  MKN1=1
159  MKN2=20
160  DO 49 MDT=1,3
161  IF(MDF.UR.(MDT.EQ.(MD+1))) GO TO 40
162  GO TO 49
163  DO 48 IETT=1,2
164  IF(IETF.QM.(IETT.EQ.IET)) GO TO 41
165  GO TO 48
166  IF(MDT.EQ.1.AND.IETT.GT.1) GO TO 48
167  INDEX=2*IETT+MDT-3
168  IF(MDT.EQ.1) INDEX=5
169  DO 47 ISU=ISU1,ISU2
170  DO 47 MKN=MKN1,MKN2

```

```

C      60 TU(43,44,45,46),IPK
43 CALL INPUT(NDET(MKN,ISU),INDEX,NUMSAV)
GO TO 47
C      44 CALL INPUT(NISO(MKN,ISU),INDEX,NUMSAV)
GO TO 47
C      45 CALL INPUT(NPR(MKN,ISU),INDEX,NUMSAV)
GO TO 47
C      46 CALL INPUT(NTLR(MKN,ISU),INDEX,NUMSAV)
47 CONTINUE
48 CONTINUE
49 CONTINUE
GO TO 1

C      CONTROL CARD IS FIRST OF TWO E CARDS, DATA,
C      EXCEPT FOR FUNCTION NUMBER, IS SAME AS ON
C      C AND F CARDS.
C

50 ECARD=T.
GO TO 30
52 NUMSAV=NEXT(IPK)
NEXT(IPR)=NUMSAV-1
GO TO 31

C      ENTER THE MECHANISM DEFINITION LOOP, WHICH
C      USES THE SPECIAL INPUT FORMAT BELOW. (M CARD ONLY)
C
55 READ(9,15)ID,ISU,MKN,((LINE(I,J),J=1,4),I=1,5)
15 FORMAT(A1,9X,2I5,20I3)
IF(ID,NE,1M) GO TO 1
IF(ISU,LT,1,OR,ISU,GT,0) GO TO 999
IF(MKN,LT,1,OR,MKN,GT,20) GO TO 999
DO 57 I=1,5
DO 56 J=1,4
IF(LINE(I,J),LE,0) LINE(I,J)=0
56 CONTINUE
CALL INPUT(NDET(MKN,ISU),I,LINE(I,1))
CALL INPUT(NISO(MKN,ISU),I,LINE(I,2))
CALL INPUT(NPR(MKN,ISU),I,LINE(I,3))
57 CALL INPUT(NTLR(MKN,ISU),I,LINE(I,4))
GO TO 55

C      CONTROL CARD CONTAINS FUNCTION SPECIFICATION DATA
C      (F CARD)
C
60 FCARD=T.
GO TO 30
62 FCARD=F.
65 ECARD=F.
GO TO (66,67,68,69),IPR
* TOEL,P1,P2,P3,TDUR)
66 CALL SPECIT(FDET,NUMSAV,IGFT,ISCH,I,REP,INTF,COEF,
GO TO 1
67 CALL SPECIT(FISO,NUMSAV,IGFT,0,0,INTF,COEF,
* TOEL,P1,P2,P3,TDUR)
GO TO 1
68 CALL SPECIT(FEPR,NUMSAV,IGFT,0,0,INTF,COEF,
* 0,0,P1,P2,P3,TDUR)
GO TO 1
69 CALL SPECIT(FTLR,NUMSAV,IGFT,0,0,INTF,COEF,
* 0,0,P1,P2,P3,TDUR)
GO TO 1

C      NORMALIZE RATE FUNCTIONS AND CHECK ALL DEFINED
C      FUNCTIONS FOR REASONABLENESS
C
70 DO 270 IPR=1,4

```

```

167 READING
168 READING
17 POSTPCH
170 READING
18 POSTPCH
172 READING
19 POSTPCH
174 READING
20 POSTPCH
175 READING
21 POSTPCH
176 READING
28 FINAL
29 FINAL
30 FINAL
31 FINAL
32 FINAL
177 READING
178 READING
179 READING
180 READING
181 READING
33 FINAL
34 FINAL
35 FINAL
36 FINAL
182 READING
183 READING
184 READING
185 READING
186 READING
187 READING
188 READING
189 READING
190 READING
191 READING
192 READING
193 READING
198 READING
199 READING
200 READING
201 READING
202 READING
203 READING
204 READING
205 READING
206 READING
207 READING
208 READING
209 READING
210 READING
211 READING
212 READING
41 FINAL
42 FINAL
43 FINAL
44 FINAL
213 READING

```

```

214 HEADIN2
215 READING2
216 READING2
217 READING2
218 PINAL
219 READING2
220 READING2
221 READING2
222 READING2
223 READING2
224 READING2
225 READING2
226 READING2
227 READING2
228 READING2
229 READING2
230 READING2
231 READING2
232 READING2
233 READING2
234 READING2
235 READING2
236 READING2
237 READING2
238 READING2
239 READING2
240 READING2
241 READING2
242 READING2
243 READING2
244 READING2
245 READING2
246 READING2
247 READING2
248 READING2
249 READING2
250 READING2
251 READING2
252 READING2
253 READING2
254 READING2
255 READING2
256 POSTPCH
257 POSTPCH
258 READING2
259 READING2
260 READING2
261 READING2
262 READING2
263 READING2
264 READING2
265 READING2
266 READING2
267 READING2
268 READING2
269 READING2
270 READING2
271 READING2
272 READING2
273 READING2
274 POSTPCH
275 POSTPCH
276 READING2
277 READING2

NAMEN#MUL(1,PH)
NMAX#NEXT(1,PH)
200 DO 260 NUM#1,NMAX
GO TO (210,220,230,240),IPR
210 COEF#FDET(2,NUM)
CODES#FDET(1,NUM)
IF(IGET(CODES,4).EQ.0) GO TO 250
IF(IGET(CODES,1).EQ.0) GO TO 250
TDUR#FDET(7,NUM)
TEST#FINTEG(FDET,NUM,TDUR)
IF(TEST.GT.0.0) GO TO 212
WRITE(6,71)NAM,NUM
71 FORMAT(/10X, #RANGE ERROR IN *,A10, # FUNCTION NUMBER*,14,
$ * = FUNCTION DISABLED*)
CALL INPUT(CODES,4,0)
FDET(1,NUM)=CODES
GO TO 250
212 FDET(4,NUM)=FDET(4,NUM)/TEST
GO TO 250
220 COEF#FISU(2,NUM)
CODES#FISU(1,NUM)
IF(IGET(CODES,4).EQ.0) GO TO 250
IF(IGET(CODES,1).EQ.0) GO TO 250
TDUR#FISU(7,NUM)
TEST#FINTEG(FISU,NUM,TDUR)
IF(TEST.GT.0.0) GO TO 222
WRITE(6,71)NAM,NUM
CALL INPUT(CODES,4,0)
FISU(1,NUM)=CODES
GO TO 250
222 FISU(4,NUM)=FISU(4,NUM)/TEST
GO TO 250
230 COEF#FEPR(2,NUM)
CODES#FEPR(1,NUM)
IF(IGET(CODES,4).EQ.0) GO TO 250
IF(IGET(CODES,1).GT.0) GO TO 232
WRITE(6,73)NAM,NUM
73 FORMAT(/10X, #IMPULSE NOT ALLOWED FOR REC. FUNCTIONS = *,
$ A10, # FUNCTION NUMBER*,14, # DISABLED*)
232 TDUR#FEPR(7,NUM)
DT#TDUR/10.0
TFLG#.T.
DO 235 ITP1=1,11
ITP1=1
ITP1=DT
TEST#FEVAL(FEPR,NUM,T)
IF(TEST.LT.0.0.OR.TEST.GT.1.0001) TFLG#.F.
235 CONTINUE
IF(TFLG) GO TO 250
WRITE(6,71)NAM,NUM
237 CALL INPUT(CODES,4,0)
FEPR(1,NUM)=CODES
GO TO 250
240 COEF#FTLR(2,NUM)
CODES#FTLR(1,NUM)
IF(IGET(CODES,4).EQ.0) GO TO 250
IF(IGET(CODES,1).GT.0) GO TO 242
WRITE(6,73)NAM,NUM
GO TO 247
242 TDUR#FTLR(7,NUM)
DT#TDUR/10.0
TFLG#.T.
DO 245 ITP1=1,11
ITP1=1
ITP1=DT
TEST#FEVAL(FTLR,NUM,T)

```



```

CODES=DET(I,NUM)
GO TO 325
322 NUM=IGET(NISO(MEC,ISU),INDEX)
IF(NUM.EQ.0) GO TO 325
CODES=PI80(I,NUM)
GO TO 325
323 NUM=IGET(MEPR(MEC,ISU),INDEX)
IF(NUM.EQ.0) GO TO 325
CODES=FEPR(1,NUM)
GO TO 325
324 NUM=IGET(NTLR(MEC,ISU),INDEX)
IF(NUM.EQ.0) GO TO 325
CODES=FTLR(1,NUM)
325 LINE(INDEX,IPR)NUM
IF(LINE(INDEX,1).EQ.0) GO TO 330
IF(NUM.EQ.0) GO TO 327
326 IF(IGET(CODES,4).GT.0) GO TO 330
327 FUNBAD(INDEX,IPR)X
BFLG=.T.
330 CONTINUE
WRITE(6,504)ISU,MEC,((LINE(I,J),J=1,4),I=1,5)
304 FORMAT(/10X,2I12,5X,5(3X,4I3))
IF(BFLG) WRITE(6,305)((FUNBAD(I,J),J=1,4),I=1,5)
305 FORMAT(39X,5(3X,4A3))
350 CONTINUE
GO TO 1
C
C DISPLAY RELEVANT SPECIFICATIONS FOR ALL DEFINED
C FUNCTIONS IN THE COVERAGE DATA BASE
C
90 WRITE(6,400)(STAR,I=1,34)
400 FORMAT(1H,48X,*COVERAGE FUNCTION SPECIFICATIONS*/48X,34A1/)
WRITE(6,401)
401 FORMAT(/59X,*- DETECTION **//14X,*FUNCTION IGFT INTF ISCH *,
* IREP COEF*,7X,*TDEL*,9X,*P1*,10X,*P2*,10X,*P3*,9X,
* TDUR*/15X,*NUMBER*/)
DO 420 NUM=1,200
CODES=DET(1,NUM)
IF(IGET(CODES,4).EQ.0) GO TO 420
IGFT=IGET(CODES,1)
ISCH=IGET(CODES,2)
IREP=IGET(CODES,3)
INTF=IGET(CODES,5)
WRITE(6,406)NUM,IGFT,INTF,ISCH,IREP,(PDET(I,NUM),I=2,7)
406 FORMAT(11X,2I8,3I6,7F11.6,5E12.4)
420 CONTINUE
WRITE(6,402)
402 FORMAT(/59X,*- ISOLATION **//14X,*FUNCTION IGFT INTF *,
* COEF*,7X,*TDEL*,9X,*P1*,10X,*P2*,10X,*P3*,9X,*TDUR*/
* 15X,*NUMBER*/)
DO 430 NUM=1,50
CODES=PI80(1,NUM)
IF(IGET(CODES,4).EQ.0) GO TO 430
IGFT=IGET(CODES,1)
INTF=IGET(CODES,5)
WRITE(6,407)NUM,IGFT,INTF,(FI80(I,NUM),I=2,7)
407 FORMAT(11X,2I8,16F11.6,5E12.4)
430 CONTINUE
WRITE(6,403)
403 FORMAT(/51X,*- FAULT PROPAGATION RECOVERY **/)
WRITE(6,405)
405 FORMAT(14X,*FUNCTION IGFT INTF COEF*,8X,*P1*,10X,*P2*,10X,
* P3*,9X,*TDUR*/15X,*NUMBER*/)
DO 440 NUM=1,25
CODES=FEPR(1,NUM)
IF(IGET(CODES,4).EQ.0) GO TO 440

```

```

340 READING
341 READING
342 READING
343 READING
344 READING
345 READING
346 READING
347 READING
348 READING
349 READING
350 READING
351 READING
352 READING
353 READING
354 READING
355 READING
356 READING
357 READING
358 READING
359 READING
360 READING
361 READING
362 READING
363 READING
364 READING
365 READING
50 FINAL
51 FINAL
52 FINAL
53 FINAL
366 READING
367 READING
368 READING
369 READING
370 READING
371 READING
372 READING
373 READING
374 READING
375 READING
376 READING
377 READING
378 READING
379 READING
380 READING
381 READING
382 READING
383 READING
384 READING
385 READING
386 READING
387 READING
388 READING
389 READING
390 READING
391 READING
392 READING
393 READING
394 READING
395 READING
396 READING
397 READING
398 READING
399 READING
400 READING
401 READING

```



```

C C COVGEN IS THE DRIVER FOR COVAGE, IT CONTAINS THE
C C ALGORITHMS NEEDED TO DETERMINE REQUESTS FOR CALCULATION,
C C APPLICABILITY OF EACH COVERAGE FACTOR, AND TO
C C IMPLIMENT THE SUBCLASS TO STAGE LINKAGE.
C C
C C THE ORDER OF PROCESSING ALLOWS ANY SET OF FACTORS TO
C C BE CALCULATED AT ONE TIME, (EACH MAY BE SELECTED
C C BY PRESETTING IT TO =1.0.)
C C
C C * COVERAGE FACTORS ARE COMPUTED BY STAGE, WITH
C C * #HARD# COVERAGE (PERMANENT FAILURES) PRECEEDING
C C * #SOFT# COVERAGE (TRANSIENT ERRORS). THE COMPUTATIONS
C C * ARE MADE ONLY IF REQUESTED AND APPLICABLE TO THE
C C * APPROPRIATE RELIABILITY EQUATION.
C C DIMENSION C1(10),C2(10),C3(10),C4(10),C5(10),C6(10),C7(10),C8(10)
C C COMMON /PARA5/CC(10,2),CCD(10,2),CTR(10),CDTR(10)
C C COMMON /DEFS/PCW(22)
C C COMMON /CVB0/COVINT,IGENC(10),IGENP(10),IFSC(8),FRAC(8)
C C EQUIVALENCE (CC(1,1),C1(1)), (CC(1,2),C2(1))
C C EQUIVALENCE (CCD(1,1),C3(1)), (CCD(1,2),C4(1))
C C EQUIVALENCE (PPRC(1,1),PRC1(1)), (PPRC(1,2),PRC2(1))
C C LOGICAL CFLG,PFLG
C C DO 40 I=1,NPROD
C C I19=I+19
C C CFLG=(IGENC(I).LT.0).OR.(IGENC(I).GT.0.AND.NRS.E9.1)
C C IF(.NOT.(CFLG.OR.C1(I).LT.0.0)) GO TO 5
C C IF(I8HIFT(PCW(I0),I19))1,200,5
C C 1 C1(I)=0.0
C C DO 2 J=1,8
C C IF(IFSC(J).NE.I) GO TO 2
C C C1(I)=C1(I)+FRAC(J)*COVAGE(J,1,1,1)
C C 2 CONTINUE
C C 5 IF(.NOT.(CFLG.UR.C2(I).LT.0.0)) GO TO 10
C C IF(I8HIFT(PCW(I1),I19))6,200,10
C C 6 CTMP=0.0
C C DO 7 J=1,8
C C IF(IFSC(J).NE.I) GO TO 7
C C CTMP=CTMP+FRAC(J)*COVAGE(J,1,1,2)
C C 7 CONTINUE
C C IF(C1(I).GT.0.0) C2(I)=CTMP/C1(I)
C C 10 IF(.NOT.(CFLG.UR.C2(I).LT.0.0)) GO TO 15
C C IF(I8HIFT(PCW(I2),I19))11,200,15
C C 11 C2(I)=0.0
C C DO 12 J=1,8
C C IF(IFSC(J).NE.I) GO TO 12
C C C2(I)=C2(I)+FRAC(J)*COVAGE(J,2,1,1)
C C 12 CONTINUE
C C 15 IF(.NOT.(CFLG.UR.C2(I).LT.0.0)) GO TO 20
C C IF(I8HIFT(PCW(I3),I19))16,200,20
C C 16 CTMP=0.0
C C DO 17 J=1,8
C C IF(IFSC(J).NE.I) GO TO 17
C C CTMP=CTMP+FRAC(J)*COVAGE(J,2,1,2)
C C 17 CONTINUE
C C IF(C2(I).GT.0.0) C3(I)=CTMP/C2(I)
C C 20 IF(.NOT.(CFLG.UR.CTR(I).LT.0.0)) GO TO 25
C C IF(I8HIFT(PCW(I4),I19))21,200,25
C C 21 CTR(I)=0.0
C C DO 22 J=1,8
C C IF(IFSC(J).NE.I) GO TO 22
C C CTR(I)=CTR(I)+FRAC(J)*COVAGE(J,0,1,0)
C C 22 CONTINUE
C C 25 IF(.NOT.(CFLG.UR.CDTR(I).LT.0.0)) GO TO 30
C C IF(I8HIFT(PCW(I5),I19))26,200,30

```

```

FINAL 1
FINAL 2
FINAL 3
FINAL 4
FINAL 5
FINAL 6
FINAL 7
FINAL 8
FINAL 9
FINAL 10
COVGEN 11
COVGEN 12
COVGEN 13
COVGEN 14
COVGEN 15
COVGEN 16
COVGEN 17
COVGEN 18
COVGEN 19
COVGEN 20
COVGEN 21
COVGEN 22
COVGEN 23
COVGEN 24
COVGEN 25
POSTPCH 1
COVGEN 27
COVGEN 28
COVGEN 29
COVGEN 30
COVGEN 31
COVGEN 32
POSTPCH 2
COVGEN 34
COVGEN 35
COVGEN 37
COVGEN 38
COVGEN 39
COVGEN 41
COVGEN 42
POSTPCH 3
COVGEN 44
COVGEN 45
COVGEN 46
COVGEN 47
COVGEN 48
COVGEN 49
POSTPCH 4
COVGEN 51
COVGEN 52
COVGEN 54
COVGEN 55
COVGEN 56
COVGEN 58
COVGEN 59
POSTPCH 5
COVGEN 61
COVGEN 62
COVGEN 63

```

```

64 COVGEN
65 COVGEN
66 COVGEN
67 POSTPCH
68 COVGEN
69 COVGEN
70 COVGEN
71 COVGEN
72 COVGEN
73 COVGEN
74 COVGEN
75 COVGEN
76 POSTPCH
77 COVGEN
78 COVGEN
79 COVGEN
80 COVGEN
81 COVGEN
82 COVGEN
83 POSTPCH
84 COVGEN
85 COVGEN
86 COVGEN
87 COVGEN
88 COVGEN
89 COVGEN
90 COVGEN
91 PGET
92 FINAL
93 FINAL
94 FINAL
95 PGET
96 PGET
97 PGET
98 PGET
99 PGET
100 PGET
101 PGET
102 PGET
103 PGET
104 PGET
105 PGET
106 PGET
107 PGET
108 PGET
109 PGET
110 PGET
111 PGET
112 PGET
113 PGET
114 PGET
115 PGET
116 PGET
117 PGET
118 PGET
119 PGET
120 PGET
121 PGET
122 PGET
123 PGET
124 PGET
125 PGET
126 PGET
127 PGET
128 PGET
129 PGET
130 PGET
131 PGET
132 PGET
133 PGET
134 PGET
135 PGET

```

```

60 LTEMP=0
61 DO 27 J=1,8
62 IF (IFSC(J).NE.1) GO TO 27
63 CTMP=CTMP+FRAC(J)*(COVAGE(J),0,1,1)
64 CONTINUE
65 IF (CTR(I).GT.0.0) CTR(I)=CTMP/CTR(I)
66 PFLG=(IGENP(I).LT.0).OR.(IGENP(I).GT.0.AND.NRS.EQ.1)
67 IF (.NOT.(PFLG.OR.PRC1(I).LT.0.0)) GO TO 35
68 IF (ISHIFT(PCW(16),I19))31,200,35
69 PRC1(I)=0
70 DO 32 J=1,8
71 IF (IFSC(J).NE.1) GO TO 32
72 PRC1(I)=PRC1(I)+FRAC(J)*COVAGE(J,1,2,0)
73 CONTINUE
74 IF (.NOT.(PFLG.OR.PRC2(I).LT.0.0)) GO TO 40
75 IF (ISHIFT(PCW(17),I19))36,200,40
76 PRC2(I)=0
77 DO 37 J=1,8
78 IF (IFSC(J).NE.1) GO TO 37
79 PRC2(I)=PRC2(I)+FRAC(J)*COVAGE(J,2,2,0)
80 CONTINUE
81 RETURN
82 200 WRITE(6,201)
83 201 FORMAT(/10X,*ERROR IN COVGEN*)
84 STOP
85 END
86 SUBROUTINE PGET(IR,I,NPROD)
87 C
88 C TRANSFER A ROW OF ARRAY PARAM TO THE BASE-RUN
89 C VECTOR OF THE PARAMETER OF INTEREST
90 C
91 COMMON /PAR1/GO(10,2),IJK(10),N(10),KS(10)
92 COMMON /PAR2/XLAM(10),XMU(10)
93 COMMON /PAR3/RV(10),KZ(10),KW(10),P(10)
94 COMMON /PAR4/SC(10,2),CCD(10,2),CTR(10),CDTR(10)
95 COMMON /PAR5/XYZ(10,2),GMP(10),PPRC(10,2)
96 COMMON /PARM/PARAM(16,10)
97 DO 20 J=1,NPROD
98 VAL=PARAM(I,J)
99 GO TO (1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19),IK
100 1 GO(J,1)=VAL
101 GO TO 20
102 2 GO(J,2)=VAL
103 GO TO 20
104 3 N(J)=VAL
105 GO TO 20
106 4 KS(J)=VAL
107 GO TO 20
108 5 KW(J)=VAL
109 GO TO 20
110 6 KZ(J)=VAL
111 GO TO 20
112 7 XLAM(J)=VAL
113 GO TO 20
114 8 XMU(J)=VAL
115 GO TO 20
116 9 GMP(J)=VAL
117 GO TO 20
118 10 CC(J,1)=VAL
119 GO TO 20
120 11 CC(J,1)=VAL
121 GO TO 20
122 12 CC(J,2)=VAL
123 GO TO 20
124 13 CC(J,2)=VAL

```

36 PGET
 37 PGET
 38 PGET
 39 PGET
 40 PGET
 41 PGET
 42 PGET
 43 PGET
 44 PGET
 45 PGET
 46 PGET
 47 PGET
 48 PGET
 49 PGET
 50 PGET
 DCR 1
 FINAL 1
 FINAL 2
 FINAL 3
 FINAL 4
 FINAL 5
 FINAL 6
 FINAL 7
 FINAL 8
 FINAL 9
 FINAL 10
 DCR 2
 DCR 3
 DCR 4
 DCR 5
 DCR 6
 DCR 10
 DCR 11
 DCR 12
 DCR 13
 DCR 14
 DCR 15
 DCR 16
 DCR 17
 DCR 18
 DCR 19
 DCR 20
 DCR 21
 DCR 22
 DCR 23
 DCR 24
 DCR 25
 DCR 26
 DCT2 1
 DCT2 1
 FINAL 2
 FINAL 3
 FINAL 4
 FINAL 5
 DCT2 2
 DCT2 3
 DCT2 4
 DCT2 5
 DCT2 6
 DCT2 7
 DCT2 8
 DCT2 9
 DCT2 10
 DCT2 11
 DCT2 12
 DCT2 13

```

GO TO 20
14 CTR(J)=VAL
GO TO 20
15 CDTR(J)=VAL
GO TO 20
16 PPRC(J,1)=VAL
GO TO 20
17 PPRC(J,2)=VAL
GO TO 20
18 RV(J)=VAL
GO TO 20
19 P(J)=VAL
20 CONTINUE
RETURN
END
SUBROUTINE DCR(J,UNITR,RELM1,RSYS)
C
C COMPUTE THE DUAL-MODE SYSTEM RELIABILITY, RSYS,
C FOR THE JTH TIME STEP. ALSO RETURN VALUES FOR
C SYSTEM AND INDIVIDUAL STAGE RELIABILITIES
C ASSUMING MODE 1 OPERATION
C
C NOTE THAT DUE TO THE USE OF STRUCTURED NUMERICAL
C INTEGRATIONS IN SUBPROGRAMS DCT2 AND DCT, DCR MAY
C NOT BE CALLED FOR AN ARBITRARY VALUE OF CLTIME.
C
C DIMENSION UNITR(8)
COMMON /DRIVE/T,XYZ(2),NUN
COMMON /PAR1/YXZ(20),IJK(20),NS(10)
COMMON /PAR2/ZYX(40),SLM2,SLM3
RSYS =1.0
IF(J.EQ.1) GO TO 100
DO 10 IX=1,NUN
UNITR(IX)=DCRU(IX,1,NS(IX),T)
10 RSYS=RSYS*UNITR(IX)
ESLM3=EXP(-SLM3*T)
RELM1=RSYS*ESLM3
DO 20 IX=1,NUN
20 RSYS=RSYS*DCT(IX,J)
RSYS=RSYS*DCT2(J)
RSYS=RSYS*ESLM3
99 RETURN
100 RELM1=RSYS
DO 110 IX=1,NUN
110 UNITR(IX)=RSYS
GO TO 99
END
FUNCTION DCT2(J)
C
C FOR THE JTH TIME STEP, COMPUTE THE PROBABILITY
C THAT THE DUAL-MODE SYSTEM WILL HAVE SURVIVED
C AND HAVE DEGRADED DUE TO A CATEGORY 2 SWITCH FAILURE
C
COMMON /DRIVE/T,STEP,STEP,NUN
COMMON /PAR2/YXZ(40),SLM2
COMMON /PAR4/ZYX(60),CCSF
JN=2-J-1
DCT2=0.0
DO 50 IT=1,JN
TAU=HSTEP*(IT-1)
PART =1.0
DO 10 IX=1,NUN
10 PART=PART*DCS(IX,T,TAU)
PART=PART*EXP(-SLM2*TAU)
IF(IT.GT.1) GO TO 30

```



```

13 DCS
14 DCS
15 DCS
16 DCS
17 POSTPCH
18 POSTPCH
19 POSTPCH
20 DCS
21 OCS
22 OCS
23 OCS
24 OCS
25 OCS
26 OCS
27 OCS
28 OCS
29 OCS
30 OCS
31 OCS
1 DCH
1 FINAL
2 FINAL
3 FINAL
4 FINAL
5 FINAL
6 DCH
7 DCH
8 DCH
9 DCH
10 DCH
11 POSTPCH
12 POSTPCH
13 POSTPCH
14 DCH
15 DCH
16 DCH
17 DCH
18 DCH
19 DCH
20 DCH
21 DCH
22 DCH
1 DCRU
2 FINAL
3 FINAL
4 FINAL
5 FINAL
6 DCRU
7 DCRU
8 DCRU
9 POSTPCH
10 POSTPCH
11 POSTPCH
12 DCRU
13 DCRU
14 DCRU
15 DCG
16 FINAL
17
18
19
20
21
22
23
24
25
26
27
28
29
30
31
32
33
34
35
36
37
38
39
40
41
42
43
44
45
46
47
48
49
50
51
52
53
54
55
56
57
58
59
60
61
62
63
64
65
66
67
68
69
70
71
72
73
74
75
76
77
78
79
80
81
82
83
84
85
86
87
88
89
90
91
92
93
94
95
96
97
98
99

```

```

JP=NSL
IF(RSGN) JP=JP+IDG(IUN)
PROD=DCG(IUN,1,LO,TAU)*DCRU(IUN,2,JP,T=TAU)
GO TO 50
40 NSLP1=NSL+1
DO 50 JDP1=1,NSLP1
JD=JDP1-1
PROD=FNCK(NSL,JD)
MUTY=TAU*HU(IUN)
PROD=PROD*EXP(-JD*MUTY)
ONEHX=1.0-EXP(-MUTY)
PUM=NSL-JD
IF(ONEHX.LE.0.0.AND.POM.LE.0) GO TO 45
PROD=PROD*ONEHX*POM
45 PROD=PROD*DCG(IUN,1,LD,TAU)
JP=JD
IF(RSGN) JP=JP+IDG(IUN)
PROD=PROD*DCRU(IUN,2,JP,T=TAU)
50 DCS=DCS+PROD
RETURN
END
FUNCTION DCG(IUN,TAU)
C
C COMPUTE THE PROBABILITY DENSITY OF A DEGENERATIVE
C FAILURE IN STAGE IUN OF THE DUAL MODE SYSTEM BY
C TIME T
C
COMMON /PARA1/QG(10,2),IJK(20),S(10)
COMMON /PARA2/LAM(10),MU(10),K(10),BCOMPS(10)
COMMON /PARA4/XYZ(40),CTR(10),CDTR(10)
INTEGER S
REAL LAM,K,MU
LOGICAL BCOMPS
NSB(IUN)
IF(BCOMPS(IUN)) GO TO 60
DCH=0.0
NSPI=NS+1
DO 50 IDP1=1,NSPI
ID=IDP1-1
PROD=DCG(IUN,1,NS-ID,TAU)*CTR(IUN)
IF(ID.EQ.0) GO TO 50
PART=CDTR(IUN)*(1.0-EXP(-MU(IUN)*TAU))
DU 25 I1=1,ID
25 PRD=PROD*PART
50 DCH=DCH+PROD
55 DCH=LAM(IUN)*QG(IUN,1)*DCH
RETURN
60 DCH=DCG(IUN,1,NS,TAU)*CTR(IUN)
GO TO 55
END
FUNCTION DCRU(IUN,MD,L,TAU)
C
C COMPUTE THE PROBABILITY OF USING AT MOST L SPARE
C LRU'S IN STAGE IUN OF THE DUAL MODE SYSTEM
C (OPERATING IN MODE MD) BY TIME TAU
C
DCRU=0.0
IF(L.LT.0) RETURN
LP1=L+1
DO 50 IDP1=1,LP1
ID=IDP1-1
50 DCRU=DCRU+DCG(IUN,MD,ID,TAU)
RETURN
END
FUNCTION DCG(IUN,MD,I,T)
C

```



```

IF(IMPG) GO TO 10
IF(ICH,LE,2) TGFIN=TOELAR(I)+FDET(7,NH)
IF(ICH,GE,3) TGFIN=PERIAR(I)
TRIFIN=FEPR(7,NY)
UPUT=AMINI(TGFIN,TRIFIN)
ROUT=0.0
IF(ICH,LE,2) ROUT=TOELAR(I)
DOUT=(UPUT-ROUT)/N
POUT=.P
      8OUT=0.0
10 HDL=FI(3,NX)
   THFIN=HDL+FI(7,NX)
   TR2FIN=FLR(7,NZ)
      BEGIN OUTER INTEGRAL
C
C
      DO 70 IOUTPI=1,NPI
      IOUT=IOUTPI-1
      TAU=DOUT+IOUT*ROUT
      GO TO (21,22,23,23),ICH
21 TAU=TOELAR(I)
   VOUT=CVG(I,TAU)
   GO TO 25
22 VOUT=CVG2(I,TAU)
   GO TO 25
23 VOUT=CVG5(I,TAU)
25 VOUT=VOUT*FEVAL(FEPR,NY,TAU)
   UPIN=AMINI((THFIN+SDEL),(TR2FIN+TAU))
   BIN=HDL+SDEL
   DIN=(UPIN-BIN)/N
   FIN=.P
   BIN=0.0
      BEGIN INNER INTEGRAL
C
C
      DO 50 IINPI=1,NPI
      IIN=IINPI-1
      IF(IMPH) GO TO 35
      TAUP=DIN+IIN*BIN
      VIN=FEVAL(FISO,NX,TAUP-BIN)
      GO TO 40
35 TAUP=FI(3,NX)+SDEL
   VIN=1.0
40 VIN=VIN*FEVAL(FLR,NZ,TAUP+TAUP)
   IF(IMPH) GO TO 55
   IF(IIN,EG,0.OR,IIN,EG,N) GO TO 45
   IF(FIN) GO TO 42
   SIN=SIN+.0*VIN
   GO TO 50
42 SIN=SIN+.4*VIN
   GO TO 50
45 SIN=SIN+VIN
50 FIN=.NOT.FIN
   ANSIN=DIN*SIN/.5,0
   GO TO 60
55 ANSIN=VIN
60 VOUT=VOUT*ANSIN
   IF(IMPG) GO TO 75
   IF(IOUT,EG,0.OR,IOUT,EG,N) GO TO 65
   IF(FOUT) GO TO 62
   ROUT=ROUT+.2*VOUT
   GO TO 70
62 ROUT=ROUT+.4*VOUT
   GO TO 70
65 ROUT=ROUT+VOUT

```

```

COVAGE 129
COVAGE 130
COVAGE 131
COVAGE 132
COVAGE 133
COVAGE 134
COVAGE 135
COVAGE 136
COVAGE 137
COVAGE 138
COVAGE 139
COVAGE 140
COVAGE 141
COVAGE 32
FINAL 33
FINAL 34
FINAL 35
POSTPCH 5
POSTPCH 6
COVAGE 143
COVAGE 144
COVAGE 145
COVAGE 146
COVAGE 147
COVAGE 148
COVAGE 149
COVAGE 150
COVAGE 151
COVAGE 152
COVAGE 153
COVAGE 154
COVAGE 155
COVAGE 156
COVAGE 157
FINAL 35
FINAL 36
FINAL 37
POSTPCH 7
POSTPCH 8
COVAGE 159
COVAGE 160
COVAGE 161
COVAGE 162
COVAGE 163
COVAGE 164
COVAGE 165
COVAGE 166
COVAGE 167
COVAGE 168
COVAGE 169
COVAGE 170
COVAGE 171
COVAGE 172
COVAGE 173
COVAGE 174
COVAGE 175
COVAGE 176
COVAGE 177
COVAGE 178
COVAGE 179
COVAGE 180
COVAGE 181
COVAGE 182
COVAGE 183
COVAGE 184
COVAGE 185
COVAGE 186

```

187 COVAGE
 188 COVAGE
 189 COVAGE
 190 COVAGE
 191 FINAL
 192 COVAGE
 193 COVAGE
 194 COVAGE
 195 COVAGE
 196 COVAGE
 197 COVAGE
 198 COVAGE
 199 COVAGE
 200 COVAGE
 201 COVAGE
 202 COVAGE
 203 COVAGE
 204 COVAGE
 205 COVAGE
 206 COVAGE
 207 COVAGE
 208 COVAGE
 209 COVAGE
 210 COVAGE
 211 COVAGE
 212 COVAGE
 213 COVAGE
 214 COVAGE
 215 COVAGE
 216 COVAGE
 217 COVAGE
 218 COVAGE
 219 COVAGE
 220 COVAGE
 221 COVAGE
 222 COVAGE
 223 COVAGE
 224 COVAGE
 225 COVAGE
 226 COVAGE
 227 COVAGE
 228 COVAGE
 229 COVAGE
 230 COVAGE
 231 COVAGE
 232 COVAGE
 233 COVAGE
 234 COVAGE
 235 COVAGE
 236 COVAGE
 237 COVAGE
 238 COVAGE
 239 COVAGE
 240 COVAGE
 241 COVAGE
 242 COVAGE
 243 COVAGE
 244 COVAGE
 245 COVAGE
 246 COVAGE
 247 COVAGE
 248 COVAGE
 249 COVAGE

```

70 POUT=NU1*POUT
   ANSOUT=DUUT*SDUT/3.0
   GO TO 80
75 ANSUUTEVOUT
   CONTRIB=ANSOUT*PDIRAR(I)*FAILFAC
   IF(COVIANT) WRITE(6,13)I,CONTRIB
13  FORMAT(15X,I5,F15.5)
   COVAGE=COVAGE+CONTRIB
100 CONTINUE
101 GPFLE=T.
   RETURN
   END
   FUNCTION CVG1(I,T)
   C
   C      COMPUTE THE COEFFICIENT OF THE G FUNCTION FOR
   C      UNSCHEDULED IMPULSE DETECTOR I, TIME T.
   C      (THE COMPETITIVE RATE OF DETECTION)
   C
   DIMENSION LL(20),PP(20)
   COMMON /CVB3/NDSAV(20) /CVB7/ICAR(20),PDETAR(20),XYZ(40),
1   TDELAR(20) /CVB2/FDET(7,1)
   ANS=1.0
   NS=0
   DO 10 NU=1,20
   IF(NU.EQ.1) GO TO 10
   IF(ICAR(NU).NE.1) GO TO 10
   IF(TDELAR(NU).NE.T) GO TO 10
   NS=NS+1
   PP(NS)=PDETAR(NU)
10  CONTINUE
   IF(NS.EQ.0) GO TO 40
   ONE=1.0
   DO 30 NU=1,NS
   ONE=ONE
   SUM2=0.0
   DO 21 M=1,NU
   LL(M)=M
   LL(NU+1)=NS+1
22  TERM=1.0
   DO 23 L=1,NU
   LLL=LL(LP)
23  TERM=TERM*PP(LLL)
   SUM2=SUM2+TERM
   LP=NU
24  LT=LL(LP)+1
   IF(LT.GE.LL(LP+1)) GO TO 26
   LLL=LT
   IF(LP.EQ.NU) GO TO 22
   LP=LP+1
   DO 25 M=LP,NU
   GO TO 22
25  LL(M)=LL(M-1)+1
26  IF(LP.LE.1) GO TO 30
   LP=LP-1
   GO TO 24
30  ANS=ANS+ONE*SUM2/(NU+1)
40  PROD=1.0
   SUM=0.0
   DO 50 K=1,20
   IF(K.EQ.1) GO TO 50
   ICM=ICAR(K)
   IF(ICM.EQ.0) GO TO 50
   IF(ICM.GE.3) GO TO 47
   IF(ICM.GE.2) GO TO 43
   IF(TDELAR(K).EQ.T) GO TO 50
43  PROD=PROD*(1.0-PDETAR(K)*FINTEG(FDET,NDSAV(K),T-TDELAR(K)))

```



```

00*20 LEI,LIM
PRDD=1.0
DO 10 J=1,20
IF(J.EQ.1) GO TO 10
IF(ICHAR(J),LT,3) GO TO 10
IF(IT.EQ.1) TJFLG=.F.
TJL=CVTJL(J,L,I)
PRODPRD=(1.0-PDETAR(J))*(1.0-FINTEG(FDET,NDSAV(J),PERIAR(I)+
1 TDELAR(I)-TAU-TJL))
10 CONTINUE
20 SUM=SUM+PRD
30 GPAR(I,IT+1)=FACTOR*SUM
RETURN
END
SUBROUTINE CVGP4(I)
C
C COMPUTE AND SAVE N+1 SAMPLES OF THE G-PRIME FUNCTION
C FOR SCHEDULED FINITE DETECTOR I, OVER ITS PERIOD.
C (RATE OF DETECTION IN COMPETITION WITH OTHER
C SCHEDULED DETECTORS)
C
COMMON /CVB3/NDSAV(20) /CVB6/LCM,TMINOK,FACTOR /CVB7/ICHAR(20),
1 PDETAR(20),IREPAR(20),PERIAR(20),TDELAR(20) /CVB8/GPFLS,
2 GPAR(20,101) /CVB9/N /CVB2/FDET(7,1)
3 /CVB10/TJLFLG
LOGICAL FLOP,TJLFLG,TPLG
NPI=N+1
NUMNDSAV(I)
TDUR=FDDET(7,NUM)
TFLG=.F.
LIMLCH/IREPAR(I)
DT=PERIAR(I)/N
DO 60 ITPI=1,NPI
IT=ITPI-1
SUM=0.0
DE=0.0
TAU=DT*IT
IF(IT.EQ.0) GO TO 50
UPLIM=TAU
TFLG=TAU.GT.TDUR
IF(TFLG) UPLIM=TDUR
DE=UPLIM/N
DO 40 LEI,LIM
FLOP=.F.
EUM=0.0
DO 30 IEPI=1,NPI
IE=IEPI-1
ETA=DE*IE
PROD=1.0
DO 10 J=1,20
IF(ICHAR(J),LT,3) GO TO 10
IF(J.EQ.1) GO TO 10
IF(IT+IE.EQ.1) TJLFLG=.F.
TJL=CVTJL(J,L,I)
PRODPRD=(1.0-PDETAR(J))*(1.0-FINTEG(FDET,NDSAV(J),PERIAR(I)+
1 TDELAR(I)+ETA-TAU-TJL))
10 CONTINUE
PRODPRD*FEVAL(FDET,NDSAV(I),ETA)
IF(IE.EQ.0.OR.IE.EQ.N) GO TO 20
IF(FLOP) GO TO 15
EUM=EUM+2.0*PRD
GO TO 30
15 EUM=EUM+4.0*PRD
GO TO 30
20 EUM=EUM+PRD
30 FLOP=.NOT.FLOP

```

```

CVG 98
CVG 99
CVG 100
CVG 101
CVG 102
CVG 103
CVG 104
CVG 105
CVG 106
CVG 107
CVG 108
CVG 109
CVG 110
CVG 111
CVG 112
CVG 113
CVG 114
CVG 115
CVG 116
CVG 117
CVG 118
CVG 119
CVG 120
CVG 121
CVG 122
CVG 123
CVG 124
CVG 125
CVG 126
CVG 127
CVG 128
CVG 129
CVG 130
CVG 131
CVG 132
CVG 133
CVG 134
CVG 135
CVG 136
CVG 137
CVG 138
CVG 139
CVG 140
CVG 141
CVG 142
CVG 143
CVG 144
CVG 145
CVG 146
CVG 147
CVG 148
CVG 149
CVG 150
CVG 151
CVG 152
CVG 153

```

```

C
C
C
C
C
C

```

```

154 CVG
155 CVG
156 CVG
157 CVG
158 CVG
159 CVG
160 CVG
161 CVG
162 FINAL
163 FINAL
164 FINAL
165 CVG
166 CVG
167 CVG
168 CVG
169 CVG
170 CVG
171 CVG
172 CVG
173 CVG
174 CVG
175 CVG
176 CVG
177 CVG
178 CVG
179 CVG
180 FINAL
181 FINAL
182 FINAL
183 FINAL
184 CVG
185 CVG
186 CVG
187 CVG
188 CVG
189 CVG
190 CVG
191 CVG
192 CVG
193 CVG
194 CVG
195 CVG
196 CVG
197 CVG
198 CVG
199 CVG
200 8SPECIT
201 1
202 1
203 2
204 3
205 4
206 2
207 3
208 4
209 5
210 6
211 7
212 8
213 9
214 9
215 8
216 7
217 6
218 5
219 4
220 3
221 2
222 1
223 1
224 1
225 2
226 3
227 4
228 5
229 6
230 7
231 8
232 9
233 9
234 8
235 7
236 6
237 5
238 4
239 3
240 2
241 1
242 1
243 1
244 2
245 3
246 4
247 5
248 6
249 7
250 8
251 9
252 9
253 8
254 7
255 6
256 5
257 4
258 3
259 2
260 1
261 1
262 1
263 2
264 3
265 4
266 5
267 6
268 7
269 8
270 9
271 9
272 8
273 7
274 6
275 5
276 4
277 3
278 2
279 1
280 1
281 1
282 2
283 3
284 4
285 5
286 6
287 7
288 8
289 9
290 9
291 8
292 7
293 6
294 5
295 4
296 3
297 2
298 1
299 1
300 1
301 2
302 3
303 4
304 5
305 6
306 7
307 8
308 9
309 9
310 8
311 7
312 6
313 5
314 4
315 3
316 2
317 1
318 1
319 1
320 2
321 3
322 4
323 5
324 6
325 7
326 8
327 9
328 9
329 8
330 7
331 6
332 5
333 4
334 3
335 2
336 1
337 1
338 1
339 2
340 3
341 4
342 5
343 6
344 7
345 8
346 9
347 9
348 8
349 7
350 6
351 5
352 4
353 3
354 2
355 1
356 1
357 1
358 2
359 3
360 4
361 5
362 6
363 7
364 8
365 9
366 9
367 8
368 7
369 6
370 5
371 4
372 3
373 2
374 1
375 1
376 1
377 2
378 3
379 4
380 5
381 6
382 7
383 8
384 9
385 9
386 8
387 7
388 6
389 5
390 4
391 3
392 2
393 1
394 1
395 1
396 2
397 3
398 4
399 5
400 6
401 7
402 8
403 9
404 9
405 8
406 7
407 6
408 5
409 4
410 3
411 2
412 1
413 1
414 1
415 2
416 3
417 4
418 5
419 6
420 7
421 8
422 9
423 9
424 8
425 7
426 6
427 5
428 4
429 3
430 2
431 1
432 1
433 1
434 2
435 3
436 4
437 5
438 6
439 7
440 8
441 9
442 9
443 8
444 7
445 6
446 5
447 4
448 3
449 2
450 1
451 1
452 1
453 2
454 3
455 4
456 5
457 6
458 7
459 8
460 9
461 9
462 8
463 7
464 6
465 5
466 4
467 3
468 2
469 1
470 1
471 1
472 2
473 3
474 4
475 5
476 6
477 7
478 8
479 9
480 9
481 8
482 7
483 6
484 5
485 4
486 3
487 2
488 1
489 1
490 1
491 2
492 3
493 4
494 5
495 6
496 7
497 8
498 9
499 9
500 8
501 7
502 6
503 5
504 4
505 3
506 2
507 1
508 1
509 1
510 2
511 3
512 4
513 5
514 6
515 7
516 8
517 9
518 9
519 8
520 7
521 6
522 5
523 4
524 3
525 2
526 1
527 1
528 1
529 2
530 3
531 4
532 5
533 6
534 7
535 8
536 9
537 9
538 8
539 7
540 6
541 5
542 4
543 3
544 2
545 1
546 1
547 1
548 2
549 3
550 4
551 5
552 6
553 7
554 8
555 9
556 9
557 8
558 7
559 6
560 5
561 4
562 3
563 2
564 1
565 1
566 1
567 2
568 3
569 4
570 5
571 6
572 7
573 8
574 9
575 9
576 8
577 7
578 6
579 5
580 4
581 3
582 2
583 1
584 1
585 1
586 2
587 3
588 4
589 5
590 6
591 7
592 8
593 9
594 9
595 8
596 7
597 6
598 5
599 4
600 3
601 2
602 1
603 1
604 1
605 2
606 3
607 4
608 5
609 6
610 7
611 8
612 9
613 9
614 8
615 7
616 6
617 5
618 4
619 3
620 2
621 1
622 1
623 1
624 2
625 3
626 4
627 5
628 6
629 7
630 8
631 9
632 9
633 8
634 7
635 6
636 5
637 4
638 3
639 2
640 1
641 1
642 1
643 2
644 3
645 4
646 5
647 6
648 7
649 8
650 9
651 9
652 8
653 7
654 6
655 5
656 4
657 3
658 2
659 1
660 1
661 1
662 2
663 3
664 4
665 5
666 6
667 7
668 8
669 9
670 9
671 8
672 7
673 6
674 5
675 4
676 3
677 2
678 1
679 1
680 1
681 2
682 3
683 4
684 5
685 6
686 7
687 8
688 9
689 9
690 8
691 7
692 6
693 5
694 4
695 3
696 2
697 1
698 1
699 1
700 2
701 3
702 4
703 5
704 6
705 7
706 8
707 9
708 9
709 8
710 7
711 6
712 5
713 4
714 3
715 2
716 1
717 1
718 1
719 2
720 3
721 4
722 5
723 6
724 7
725 8
726 9
727 9
728 8
729 7
730 6
731 5
732 4
733 3
734 2
735 1
736 1
737 1
738 2
739 3
740 4
741 5
742 6
743 7
744 8
745 9
746 9
747 8
748 7
749 6
750 5
751 4
752 3
753 2
754 1
755 1
756 1
757 2
758 3
759 4
760 5
761 6
762 7
763 8
764 9
765 9
766 8
767 7
768 6
769 5
770 4
771 3
772 2
773 1
774 1
775 1
776 2
777 3
778 4
779 5
780 6
781 7
782 8
783 9
784 9
785 8
786 7
787 6
788 5
789 4
790 3
791 2
792 1
793 1
794 1
795 2
796 3
797 4
798 5
799 6
800 7
801 8
802 9
803 9
804 8
805 7
806 6
807 5
808 4
809 3
810 2
811 1
812 1
813 1
814 2
815 3
816 4
817 5
818 6
819 7
820 8
821 9
822 9
823 8
824 7
825 6
826 5
827 4
828 3
829 2
830 1
831 1
832 1
833 2
834 3
835 4
836 5
837 6
838 7
839 8
840 9
841 9
842 8
843 7
844 6
845 5
846 4
847 3
848 2
849 1
850 1
851 1
852 2
853 3
854 4
855 5
856 6
857 7
858 8
859 9
860 9
861 8
862 7
863 6
864 5
865 4
866 3
867 2
868 1
869 1
870 1
871 2
872 3
873 4
874 5
875 6
876 7
877 8
878 9
879 9
880 8
881 7
882 6
883 5
884 4
885 3
886 2
887 1
888 1
889 1
890 2
891 3
892 4
893 5
894 6
895 7
896 8
897 9
898 9
899 8
900 7
901 6
902 5
903 4
904 3
905 2
906 1
907 1
908 1
909 2
910 3
911 4
912 5
913 6
914 7
915 8
916 9
917 9
918 8
919 7
920 6
921 5
922 4
923 3
924 2
925 1
926 1
927 1
928 2
929 3
930 4
931 5
932 6
933 7
934 8
935 9
936 9
937 8
938 7
939 6
940 5
941 4
942 3
943 2
944 1
945 1
946 1
947 2
948 3
949 4
950 5
951 6
952 7
953 8
954 9
955 9
956 8
957 7
958 6
959 5
960 4
961 3
962 2
963 1
964 1
965 1
966 2
967 3
968 4
969 5
970 6
971 7
972 8
973 9
974 9
975 8
976 7
977 6
978 5
979 4
980 3
981 2
982 1
983 1
984 1
985 2
986 3
987 4
988 5
989 6
990 7
991 8
992 9
993 9
994 8
995 7
996 6
997 5
998 4
999 3
1000 2
1001 1
1002 1
1003 1
1004 2
1005 3
1006 4
1007 5
1008 6
1009 7
1010 8
1011 9
1012 9
1013 8
1014 7
1015 6
1016 5
1017 4
1018 3
1019 2
1020 1
1021 1
1022 1
1023 2
1024 3
1025 4
1026 5
1027 6
1028 7
1029 8
1030 9
1031 9
1032 8
1033 7
1034 6
1035 5
1036 4
1037 3
1038 2
1039 1
1040 1
1041 1
1042 2
1043 3
1044 4
1045 5
1046 6
1047 7
1048 8
1049 9
1050 9
1051 8
1052 7
1053 6
1054 5
1055 4
1056 3
1057 2
1058 1
1059 1
1060 1
1061 2
1062 3
1063 4
1064 5
1065 6
1066 7
1067 8
1068 9
1069 9
1070 8
1071 7
1072 6
1073 5
1074 4
1075 3
1076 2
1077 1
1078 1
1079 1
1080 2
1081 3
1082 4
1083 5
1084 6
1085 7
1086 8
1087 9
1088 9
1089 8
1090 7
1091 6
1092 5
1093 4
1094 3
1095 2
1096 1
1097 1
1098 1
1099 2
1100 3
1101 4
1102 5
1103 6
1104 7
1105 8
1106 9
1107 9
1108 8
1109 7
1110 6
1111 5
1112 4
1113 3
1114 2
1115 1
1116 1
1117 1
1118 2
1119 3
1120 4
1121 5
1122 6
1123 7
1124 8
1125 9
1126 9
1127 8
1128 7
1129 6
1130 5
1131 4
1132 3
1133 2
1134 1
1135 1
1136 1
1137 2
1138 3
1139 4
1140 5
1141 6
1142 7
1143 8
1144 9
1145 9
1146 8
1147 7
1148 6
1149 5
1150 4
1151 3
1152 2
1153 1
1154 1
1155 1
1156 2
1157 3
1158 4
1159 5
1160 6
1161 7
1162 8
1163 9
1164 9
1165 8
1166 7
1167 6
1168 5
1169 4
1170 3
1171 2
1172 1
1173 1
1174 1
1175 2
1176 3
1177 4
1178 5
1179 6
1180 7
1181 8
1182 9
1183 9
1184 8
1185 7
1186 6
1187 5
1188 4
1189 3
1190 2
1191 1
1192 1
1193 1
1194 2
1195 3
1196 4
1197 5
1198 6
1199 7
1200 8
1201 9
1202 9
1203 8
1204 7
1205 6
1206 5
1207 4
1208 3
1209 2
1210 1
1211 1
1212 1
1213 2
1214 3
1215 4
1216 5
1217 6
1218 7
1219 8
1220 9
1221 9
1222 8
1223 7
1224 6
1225 5
1226 4
1227 3
1228 2
1229 1
1230 1
1231 1
1232 2
1233 3
1234 4
1235 5
1236 6
1237 7
1238 8
1239 9
1240 9
1241 8
1242 7
1243 6
1244 5
1245 4
1246 3
1247 2
1248 1
1249 1
1250 1
1251 2
1252 3
1253 4
1254 5
1255 6
1256 7
1257 8
1258 9
1259 9
1260 8
1261 7
1262 6
1263 5
1264 4
1265 3
1266 2
1267 1
1268 1
1269 1
1270 2
1271 3
1272 4
1273 5
1274 6
1275 7
1276 8
1277 9
1278 9
1279 8
1280 7
1281 6
1282 5
1283 4
1284 3
1285 2
1286 1
1287 1
1288 1
1289 2
1290 3
1291 4
1292 5
1293 6
1294 7
1295 8
1296 9
1297 9
1298 8
1299 7
1300 6
1301 5
1302 4
1303 3
1304 2
1305 1
1306 1
1307 1
1308 2
1309 3
1310 4
1311 5
1312 6
1313 7
1314 8
1315 9
1316 9
1317 8
1318 7
1319 6
1320 5
1321 4
1322 3
1323 2
1324 1
1325 1
1326 1
1327 2
1328 3
1329 4
1330 5
1331 6
1332 7
1333 8
1334 9
1335 9
1336 8
1337 7
1338 6
1339 5
1340 4
1341 3
1342 2
1343 1
1344 1
1345 1
1346 2
1347 3
1348 4
1349 5
1350 6
1351 7
1352 8
1353 9
1354 9
1355 8
1356 7
1357 6
1358 5
1359 4
1360 3
1361 2
1362 1
1363 1
1364 1
1365 2
1366 3
1367 4
1368 5
1369 6
1370 7
1371 8
1372 9
1373 9
1374 8
1375 7
1376 6
1377 5
1378 4
1379 3
1380 2
1381 1
1382 1
1383 1
1384 2
1385 3
1386 4
1387 5
1388 6
1389 7
1390 8
1391 9
1392 9
1393 8
1394 7
1395 6
1396 5
1397 4
1398 3
1399 2
1400 1
1401 1
1402 1
1403 2
1404 3
1405 4
1406 5
1407 6
1408 7
1409 8
1410 9
1411 9
1412 8
1413 7
1414 6
1415 5
1416 4
1417 3
1418 2
1419 1
1420 1
1421 1
1422 2
1423 3
1424 4
1425 5
1426 6
1427 7
1428 8
1429 9
1430 9
1431 8
1432 7
1433 6
1434 5
1435 4
1436 3
1437 2
1438 1
1439 1
1440 1
1441 2
1442 3
1443 4
1444 5
1445 6
1446 7
1447 8
1448 9
1449 9
1450 8
1451 7
1452 6
1453 5
1454 4
1455 3
1456 2
1457 1
1458 1
1459 1
1460 2
1461 3
1462 4
1463 5
1464 6
1465 7
1466 8
1467 9
1468 9
1469 8
1470 7
1471 6
1472 5
1473 4
1474 3
1475 2
1476 1
1477 1
1478 1
1479 2
1480 3
1481 4
1482 5
1483 6
1484 7
1485 8
1486 9
1487 9
1488 8
1489 7
1490 6
1491 5
1492 4
1493 3
1494 2
1495 1
1496 1
1497 1
1498 2
1499 3
1500 4
1501 5
1502 6
1503 7
1504 8
1505 9
1506 9
1507 8
1508 7
1509 6
1510 5
1511 4
1512 3
1513 2
1514 1
1515 1
1516 1
1517 2
1518 3
1519 4
1520 5
1521 6
1522 7
1523 8
1524 9
1525 9
1526 8
1527 7
1528 6
1529 5
1530 4
1531 3
1532 2
1533 1
1534 1
1535 1
1536 2
1537 3
1538 4
1539 5
1540 6
1541 7
1542 8
1543 9
1544 9
1545 8
1546 7
1547 6
1548 5
1549 4
1550 3
1551 2
1552 1
1553 1
1554 1
1555 2
1556 3
1557 4
1558 5
1559 6
1560 7
1561 8
1562 9
1563 9
1564 8
1565 7
1566 6
1567 5
1568 4
1569 3
1570 2
1571 1
1572 1
1573 1
1574 2
1575 3
1576 4
1577 5
1578 6
1579 7
1580 8
1581 9
1582 9
1583 8
1584 7
1585 6
1586 5
1587 4
1588 3
1589 2
1590 1
1591 1
1592 1
1593 2
1594 3
1595 4
1596 5
1597 6
1598 7
1599 8
1600 9
1601 9
1602 8
1603 7
1604 6
1605 5
1606 4
1607 3
1608 2
1609 1
1610 1
1611 1
1612 2
1613 3
1614 4
1615 5
1616 6
1617 7
1618 8
1619 9
1620 9
1621 8
1622 7
1623 6
1624 5
1625 4
1626 3
1627 2
1628 1
1629 1
1630 1
1631 2
1632 3
1633 4
1634 5
1635 6
1636 7
1637 8
1638 9
1639 9
1640 8
1641 7
1642 6
1643 5
1644 4
1645 3
1646 2
1647 1
1648 1
1649 1
1650 2
1651 3
1652 4
1653 5
1654 6
1655 7
1656 8
1657 9
1658 9
1659 8
1660 7
1661 6
1662 5
1663 4
1664 3
1665 2
1666 1
1667 1
1668 1
1669 2
1670 3
1671 4
1672 5
1673 6
1674 7
1675 8
1676 9
1677 9
1678 8
1679 7
1680 6
1681 5
1682 4
1683 3
1684 2
1685 1
1686 1
1687 1
1688 2
1689 3
1690 4
1691 5
1692 6
1693 7
1694 8
1695 9
1696 9
1697 8
1698 7
1699 6
1700 5
1701 4
1702 3
1703 2
1704 1
1705 1
1706 1
1707 2
1708 3
1709 4
1710 5
1711 6
1712 7
1713 8
1714 9
1715 9
1716 8
1717 7
1718 6
1719 5
1720 4
1721 3
1722 2
1723 1
1724 1
1725 1
1726 2
1727 3
1728 4
1729 5
1730 6
1731 7
1732 8
1733 9
1734 9
1735 8
1736 7
1737 6
1738 5
1739 4
1740 3
1741 2
1742 1
1743 1
1744 1
1745 2
1746 3
1747 4
1748 5
1749 6
1750 7
1751 8
1752 9
1753 9
1754 8
1755 7
1756 6
1757 5
1758 4
1759 3
1760 2
1761 1
1762 1
1763 1
1764 2
1765 3
1766 4
1767 5
1768 6
1769 7
1770 8
1771 9
1772 9
1773 8
1774 7
1775 6
1776 5
1777 4
1778 3
1779 2
1780 1
1781 1
1782 1
1783 2
1784 3
1785 4
1786 5
1787 6
1788 7
1789 8
1790 9
1791 9
1792 8
1793 7
1794 6
1795 5
1796 4
1797 3
1798 2
1799 1
1800 1
1801 1
1802 2
1803 3
1804 4
1805 5
1806 6
1807 7
1808 8
1809 9
1810 9
1811 8
1812 7
1813 6
1814 5
1815 4
1816 3
1817 2
1818 1
1819 1
1820 1
1821 2
1822 3
1823 4
1824 5
1825 6
1826 7
1827 8
1828 9
1829 9
1830 8
1831 7
1832 6
1833 5
1834 4
1835 3
1836 2
1837 1
1838 1
1839 1
1840 2
1841 3
1842 4
1843 5
1844 6
1845 7
1846 8
1847 9
1848 9
1849 8
1850 7
1851 6
1852 5
1853 4
1854 3
1855 2
1856 1
1857 1
1858 1
1859 2
1860 3
1861 4
1862 5
1863 6
1864 7
1865 8
1866 9
1867 9
1868 8
1869 7
1870 6
1871 5
1872 4
1873 3
1874 2
1875 1
1876 1
1877 1
1878 2
1879 3
1880 4
1881 5
1882 6
1883 7
1884 8
1885 9
1886 9
1887 8
1888 7
1889 6
1890 5
1891 4
1892 3
1893 2
1894 1
1895 1
1896 1
1897 2
1898 3
1899 4
1900 5
1901 6
1902 7
1903 8
1904 9
1905 9
1906 8
1907 7
1908 6
1909 5
1910 4
1911 3
1912 2
1913 1
1914 1
1915 1
1916 2
1917 3
1918 4
1919 5
1920 6
1921 7
1922 8
1923 9
1924 9
1925 8
1926 7
1927 6
1928 5
1929 4
1930 3
1931 2
1932 1
1933 1
1934 1
1935 2
1936 3
1937 4
1938 5
1939 6
1940 7
1941 8
1942 9
1943 9
1944 8
1945 7
1946 6
1947 5
1948 4
1949 3
1950 2
1951 1
1952 1
1953 1
1954 2
1955 3
1956 4
1957 5
1958 6
1959 7
1960 8
1961 9
1962 9
1963 8
1964 7
1965 6
1966 5
1967 4
1968 3
1969 2
1970 1
1971 1
1972 1
1973 2
1974 3
1975 4
1976 5
1977 6
1978 7
1979 8
1980 9
1981 9
1982 8
1983 7
1984 6
1985 5
1986 4
1987 3
1988 2
1989 1
1990 1
1991 1
1992 2
1993 3
1994 4
1995 5
1996 6
1997 7
1998 8
1999 9
2000 9

```



```

19 FINTEG
20 FINTEG
21 FINTEG
22 FINTEG
23 FINTEG
24 FINTEG
25 FINTEG
26 FINTEG
2 POSTPCH
3 POSTPCH
28 FINTEG
29 FINTEG
30 FINTEG
31 FINTEG
32 FINTEG
33 FINTEG
34 FINTEG
35 FINTEG
36 FINTEG
37 FINTEG
38 FINTEG
39 FINTEG
40 FINTEG
41 FINTEG
42 FINTEG
43 FINTEG
44 FINTEG
45 FINTEG
46 FINTEG
47 FINTEG
48 FINTEG
49 FINTEG
50 FINTEG
51 FINTEG
52 FINTEG
53 FINTEG
54 FINTEG
1 GETPUT
1 FINAL
2 FINAL
3 FINAL
4 FINAL
2 GETPUT
3 GETPUT
4 GETPUT
5 GETPUT
6 GETPUT
7 GETPUT
8 GETPUT
9 GETPUT
5 FINAL
6 FINAL
7 FINAL
8 FINAL
10 GETPUT
11 GETPUT
12 GETPUT
13 GETPUT
14 GETPUT
15 GETPUT
16 GETPUT
17 GETPUT
1 POSTPCH
2 POSTPCH
3 POSTPCH
4 POSTPCH

INTP=IGET(ICODES,5)
IF(INTF.GT.0) GO TO 50

C
C
C
START OF SIMPSON INTEGRAL

DELT/N
IFLOR=F.
SUMS=0.0
DO 30 IPI=1,NPI
I=IPI-1
TAUDEL=I
VALSEVAL(0.0,TAU)
IF(I.EQ.0.OR.I.EQ.N) GO TO 20
IF(IFLOR) GO TO 15
SUMS=SUM+2.0*VAL
GO TO 30
15 SUMS=SUM+4.0*VAL
GO TO 30
20 SUMS=SUM+VAL
30 IFLOR=.NOT.IFLOR
ANSDEL=SUM/3.0
GO TO 100
50 GO TO (51,52,53,54,55,56),IGFT
51 ANS=FN1I(T)
GO TO 100
52 ANS=FN2I(T)
GO TO 100
53 ANS=FN3I(T)
GO TO 100
54 ANS=FN4I(T)
GO TO 100
55 ANS=FN5I(T)
GO TO 100
56 ANS=FN6I(T)
100 RETURN
END
FUNCTION IGET(IWORD,INDEX)
C
C
C
RETURN THE VALUE OF THE INDEX=TH 12 BIT FIELD
OF IWORD, AS A RIGHT JUSTIFIED INTEGER

C
C
C
DIMENSION MASK(5)
DATA MASK/777700000000000000B,00007777000000000000B,
1000000077770000000000B,0000000000000077770000B,00000000000000007777B/
ITP=AND(IWORD,MASK(INDEX))
IGET=ISHIFT(ITP,12*INDEX)
RETURN
END
SUBROUTINE IPUT(IWORD,INDEX,ICODE)
C
C
C
PACK THE RIGHTMOST 12 BITS OF ICODE INTO THE
INDEX=TH 12 BIT FIELD OF IWORD

C
C
C
DIMENSION MASK(5)
DATA MASK/00007777777777777777B,77770000777777777777B,
17777777000077777777B,77777777777700007777B,77777777777777777777B/
ITP=ISHIFT(ICODE,12*(5-INDEX))
IWORD=AND(IWORD,MASK(INDEX))
IWORD=OR(IWORD,ITP)
RETURN
END
IDENT ISHIFT
ENTRY ISHIFT
P8
ISHIFT 8A1 81

```

