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A Theoretical Investigation of Noise Reduction Through the Cylindrical Fuselage of a Twin-Engine, Propeller-Driven Aircraft

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SUMMARY

Interior noise in the fuselage of a twin-engine, propeller-driven aircraft with two propellers rotating in opposite directions is studied analytically. The fuselage is modeled as a stiffened cylindrical shell with simply supported ends, and the effect of stringers and frames is averaged over the shell surface. An approximate mathematical model of the propeller noise excitation is formulated which includes some of the propeller noise characteristics such as sweeping pressure waves around the sidewalls due to propeller rotation and the localized nature of the excitation with the highest levels near the propeller plane. Results are presented in the form of noise reduction, which is the difference between the levels of external and interior noise. The influence of propeller noise characteristics on the noise reduction is studied. The results indicate that the sweep velocity of the excitation around the fuselage sidewalls is critical to noise reduction.

INTRODUCTION

One of the main sources of interior noise in propeller-driven aircraft is the propeller noise excitation. A main path by which noise is transmitted to the interior is through the fuselage structure. The present paper is devoted to the study of the noise reduction provided by the fuselage structure when subjected to propeller noise excitation and the influence of propeller noise characteristics on the noise reduction.

Some information is available on the nature of the propeller noise and its near field behavior (refs. 1 to 7) which reveals a few characteristics of propeller noise such as (1) the pressure field rotating with the blades causing a sweeping action around the sidewalls of the fuselage, (2) the localized nature of the noise field on the fuselage surface with highest levels near the propeller plane, and (3) the noise spectrum dominated by propeller harmonics. References 8, 9, and 10 analyze interior noise in fuselages using statistical energy analysis and deterministic analyses for exterior noise pressure inputs such as turbulent boundary layers, jet noise, or plain acoustic waves. Interior noise in propeller-driven light aircraft with flat fuselage sidewalls has been studied experimentally (ref. 11), and analytically considering uniform pressure to represent propeller noise input on the sidewalls (ref. 12).

The present investigation extends previous analyses by employing a more realistic representation of propeller excitation pressures and complements the studies discussed in reference 12 with regard to fuselage geometry by considering cylindrical fuselages. An approximate mathematical model has been developed, using information available in the references, for the propeller noise excitation which includes some of the propeller noise characteristics. Twin-engine aircraft with propellers rotating in opposite directions are considered. The noise fields from the propellers on either side of the fuselage are assumed to be symmetrical about the central vertical plane of the fuselage. The objective
of the present investigation is to study the quantitative influence of the propeller noise characteristics on the noise reduction through the fuselage sidewalls. Two sizes of fuselage structure are studied, one representative of a large passenger aircraft fuselage and the other corresponding to that of a light aircraft fuselage.

The overall development of the analysis in this study closely follows that in reference 10. The fuselage is modeled as a cylindrical shell stiffened by stringers and ring frames and having simply supported ends. The effects of stiffeners are averaged over the fuselage surface. The analysis for the interior noise in the fuselage is carried out using the approximate model of propeller noise input on the fuselage structure and the normal mode approach to determine the response of the fuselage and the resulting pressure fluctuations in the interior acoustic field. The frequency range considered is from 0 to 500 Hz and includes the blade passage frequency and the first few harmonics, which are the dominant sources of propeller noise. The noise reduction through the fuselage sidewalls is the difference between the excitation noise level on the fuselage surface and the space-averaged interior noise level within the fuselage. Results showing the influence of propeller noise characteristics on noise reduction are presented.

SYMBOLS

The units used for physical quantities defined in this paper are given in the International System (SI) of units.

\( A_r, A_s \) cross-sectional areas of ring frame and stringer, respectively, \( \text{m}^2 \)

\( a_1, a_2, b_1, b_2 \) distances defining the fuselage surface area subjected to propeller noise excitation, shown in figure 1, \( \text{m} \)

\( C_1, C_2, C_3, C_4 \) constants appearing in equation (B2)

\( C_{\text{mni}} \) modal constant defined in equation (B11)

\( c \) speed of sound in air, \( \text{m/sec} \)

\( E \) modulus of elasticity of fuselage material, \( \text{Pa} \)

\( E_r, E_s \) moduli of elasticity of ring frame and stringer materials, respectively, \( \text{Pa} \)

\( F_{\text{mni}} \) generalized force for (mni) mode

\( f \) frequency, \( \text{Hz} \)

\( f_r \) reference frequency, \( \text{Hz} \)

\( G_r, G_s \) shear moduli of ring frame and stringer materials, respectively, \( \text{Pa} \)

\( H \) frequency response defined in equation (6)
h \text{ thickness of fuselage material, m}

I_{mni} \text{ integrals defined in equations (11), (12), and (13)}

I_n \text{ modified Bessel function of first kind and of nth order}

I_r, I_s \text{ moments of inertia for ring frame and stringer, respectively}

J_n \text{ Bessel function of first kind and nth order}

J_r, J_s \text{ torsional constants for ring frame and stringer, respectively}

k \text{ wave number } \omega/c \text{ defined in equation (B3)}

L \text{ length of fuselage, m}

L_{rs} \text{ differential operators in equation (A1), } r, s = 1, 2, 3

l_r, l_s \text{ ring frame and stringer spacings, respectively, m}

M_{mni} \text{ generalized mass of (mni) mode}

M_x \text{ moment resultant in x-direction}

m, \xi \text{ number of half waves along cylinder axis}

N_x \text{ stress resultant in x-direction}

n, \eta \text{ number of full waves around cylinder circumference}

P \text{ pressure amplitude of excitation pressure, Pa}

p \text{ interior noise pressure, Pa}

P_e \text{ excitation pressure, Pa}

Q_{ac} \text{ dynamic magnification factor for acoustic modes}

Q_{mni} \text{ dynamic magnification factor for (mni) structural mode}

q_{mni} \text{ generalized coordinate of (mni) structural mode}

R \text{ radius of fuselage, m}

r \text{ radial coordinate of fuselage, m}

\hat{r} \text{ dimensionless radial coordinate } r/R

s \text{ number of radial acoustic waves}

t \text{ time, sec}
\[ U_{\text{mni}} \] mode functions for fuselage displacements in x-direction
\[ u \] fuselage displacement in x-direction, m
\[ u_1, u_2 \] fuselage displacement amplitudes in x-direction, m
\[ V \] sweep velocity of exciting pressure waves, m/sec
\[ V_{\text{mni}} \] mode functions for fuselage displacements in y-direction
\[ v \] fuselage displacement in y-direction, m
\[ v_1, v_2 \] fuselage displacement amplitudes in y-direction, m
\[ W_{\text{mni}} \] mode functions for fuselage displacements in z-direction
\[ w \] radial displacement of fuselage, m
\[ w_{\text{a}} \] radial displacement of air particle in fuselage interior, m
\[ x \] coordinate in longitudinal direction of fuselage, m
\[ y \] coordinate in circumferential direction of fuselage, m
\[ z \] coordinate in radial direction of fuselage, m
\[ z_{r, s} \] eccentricities of ring frame and stringer centroids from fuselage skin middle plane, m
\[ \alpha \] parameter defined in equation (B3)
\[ \gamma_{\text{mni}} \] quantity defined in equation (B17)
\[ \theta \] phase angle of frequency response of fuselage displacement, rad
\[ \mu \] Poisson's ratio for material of fuselage
\[ \rho \] density of fuselage skin material, kg/m\(^3\)
\[ \rho_a \] average density of skin-stringer fuselage structure, kg/m\(^3\)
\[ \rho_0 \] density of air, kg/m\(^3\)
\[ \rho_r, \rho_s \] densities of ring frame and stringer materials, respectively, kg/m\(^3\)
\[ \phi_{\text{mni}} \] mode functions of (mni) acoustic modes
\[ \phi \] coordinate in circumferential direction for interior acoustic space y/R
\[ \psi \] quantity defined in equations (B4)
\[ \omega \quad \text{frequency, rad/sec} \]
\[ \omega_{mn} \quad \text{structural modal frequencies, rad/sec} \]
\[ \omega_{mns} \quad \text{acoustic modal frequencies, rad/sec} \]

Subscripts:
\[ i,j,m,n,r,s,\eta,\xi \quad \text{integers} \]

Dots over symbols denote time derivatives.

Primes over symbols denote derivatives with respect to spatial coordinates.

Bars over symbols denote amplitudes.

ANALYSIS

Since propeller noise is predominant near the blade passage frequency and the first few harmonics, which lie in the low-frequency range, a fuselage model that is simple but suitable in the low-frequency range is required. Such a model is available in reference 13 in which the effect of stringers and ring frames are averaged over the fuselage surface. Shown in figure 1(a) is a fuselage structure idealized as a simple cylindrical shell with reinforcing stringers and ring frames. The fuselage is excited by propeller noise excitation, and the resulting vibrations of the fuselage structure excite the interior air space causing interior noise. The displacement response of the fuselage walls is calculated using a normal mode approach. The interior noise in the fuselage is obtained by equating the displacement of the fuselage wall to that of the air particle near the wall. This plan of development follows reference 10 closely.

The following discussion gives the main features of the analysis. Details of the derivation of the forced-response equations for the fuselage structure are given in appendix A, and details of the interior noise derivations are given in appendix B.

Displacement Response of Fuselage Structure

The equation of motion for the \((mni)\) mode of the fuselage structure is (see eq. (A13))

\[ \ddot{q}_{mni}(t) + \frac{\omega_{mn}}{Q_{mni}} \dot{q}_{mni}(t) + \omega_{mn}^2 q_{mni}(t) = \frac{F_{mni}(t)}{M_{mni}} \]  \(1\)

where \(q_{mni}\) represents the generalized coordinates and \(\omega_{mn}\) represents the natural frequencies of the fuselage structure. The subscripts \((mni)\) specify
the resonant deflection shapes of the cylindrical shell where \( m = 1, 2, 3, \ldots \) is the number of elastic half waves along the cylinder axis, \( n = 1, 2, 3, \ldots \) is the number of elastic full waves around the cylinder circumference, and \( i = 1, 2 \) indicates the orthogonal solutions for mode shapes to specify the complete response since there is no preferred location of the origin of the \( y \)-axis. The first few modes are illustrated in figure 2. The dynamic magnification factors at resonance are denoted by \( Q_{mni} \). The term \( M_{mni} \) is the generalized mass of the \((mni)\) structural mode. (See eq. (All).) The term \( F_{mni} \) is the generalized force of the \((mni)\) structural mode given as

\[
F_{mni}(t) = \iint p_e(x,y,t) W_{mni}(x,y) dx \, dy
\] (2)

where \( p_e(x,y,t) \) is the external pressure loading on the fuselage surface and \( W_{mni}(x,y) \) denotes the \((mni)\) structural mode function. The complete radial displacement response of the shell is obtained by summing up the response of all the normal modes of the shell (eq. (A7c)) as

\[
w(x,y,t) = \sum_{mni} W_{mni}(x,y) q_{mni}(t)
\] (3)

Assuming that the generalized force is harmonic at frequency \( \omega \); that is

\[
F_{mni}(t) = F_{mni} e^{i\omega t}
\] (4)

the solution of equation (1) can be written as

\[
q_{mni}(t) = \frac{H(\omega/\omega_{mni})}{\omega_{mni}^2 M_{mni}} \exp\left[-\theta(\omega/\omega_{mni})\right] F_{mni} e^{i\omega t}
\] (5)

where

\[
H(\omega/\omega_{mni}) = \left\{ \left[ 1 - (\omega/\omega_{mni})^2 \right]^2 + \frac{1}{Q_{mni}^2} (\omega/\omega_{mni})^2 \right\}^{-1/2}
\] (6)

and

\[
\theta(\omega/\omega_{mni}) = \tan^{-1}\left\{ \frac{\omega/\omega_{mni}}{Q_{mni} \left[ 1 - (\omega/\omega_{mni})^2 \right]} \right\}
\] (7)
Subsequently, the radial displacement of the shell is obtained by combining equation (5) and equation (3) as

\[
w(x, y, t) = \sum_{mni} \frac{H(\omega/\omega_{mn})}{\omega_{mn}^2} \exp\left[-\theta(\omega/\omega_{mn})\right] F_{mni} M_{mni}(x, y) e^{i\omega t}
\]

**Propeller Noise Excitation**

Previous studies on the nature of the propeller noise (refs. 1 to 7) indicate that:

1. The noise field generated by the propeller blades rotates with the propeller.
2. The propeller noise exciting the fuselage surface has the highest levels near the propeller plane.
3. The spectrum of the propeller noise is dominated by propeller harmonics.

By employing these characteristics of propeller noise excitation an approximate mathematical model is formulated.

In figure 1(b) the location of the propellers is shown relative to the fuselage. The propeller noise on the fuselage is illustrated by the hatched area around the fuselage. It is assumed that the propellers on either side of the fuselage are rotating in opposite directions and also that their noise fields incident on the fuselage sidewalls are symmetrical with respect to the fuselage vertical plane of symmetry. It is also assumed that the noise field is traveling around the fuselage with constant velocity \( V \), as shown in figure 1(b), by the arc around the fuselage. This approximate representation of the propeller noise field is mathematically expressed, for a particular propeller harmonic, as

\[
\begin{align*}
p_e(x, y, t) &= P \exp\left[i\omega\left(t - \frac{y - b_1}{V}\right)\right] \\
p_e(x, y, t) &= P \exp\left[i\omega\left(t + \frac{y + b_1}{V}\right)\right] \\
p_e(x, y, t) &= 0
\end{align*}
\]

\[
\begin{cases}
a_1 \leq x \leq a_2 \\
-\frac{b_2}{V} \leq y \leq -\frac{b_1}{V}
\end{cases}
\]
where $\omega$ is the frequency of the harmonic, $P$ is the amplitude of the exciting pressure, $V$ is the velocity of the pressure waves traveling around the fuselage due to the propeller rotation, and $a_1, a_2, b_1, b_2$ specify the fuselage surface area subjected to propeller noise excitation. (See figs. 1(a) and 1(b).) The sweep velocity $V$ and the frequency $\omega$ can be related to the propeller parameters. In equations (9), $V = \infty$ corresponds to the case of uniform pressure loading on the fuselage surface.

Combining equations (9) and equation (2) and making use of equations (A8) and (A9), the generalized force for the $(mni)$ mode is obtained as

$$F_{mni}(t) = \bar{F}_{mni} e^{i\omega t} = Pe^{i\omega t} (I_{mni})$$  \hspace{1cm} (10)

The integrals $I_{mni}$ in equation (10) are evaluated to obtain

$$I_{mni} = 0$$  \hspace{1cm} (11)

due to the symmetry of the forcing pressure field about the vertical plane of symmetry of the fuselage, and

$$I_{mn2} = \frac{L}{mn} \left[ \cos (mn_1 / L) - \cos (mn_2 / L) \right]$$

$$\times \left\{ \frac{\sin \left[ \frac{nb_2}{R} + \frac{\omega (b_2 - b_1)}{V} \right]}{\frac{n}{R} + \frac{\omega}{V}} - \frac{\sin \left[ \frac{nb_1}{R} \right]}{\frac{n}{R}} + \frac{\sin \left[ \frac{nb_2}{R} - \frac{\omega (b_2 - b_1)}{V} \right]}{\frac{n}{R} - \frac{\omega}{V}} - \frac{\sin \left[ \frac{nb_1}{R} \right]}{\frac{n}{R} - \frac{\omega}{V}} \right\}$$

$$+ i \left\{ \frac{\cos \left[ \frac{nb_2}{R} + \frac{\omega (b_2 - b_1)}{V} \right]}{\frac{n}{R} + \frac{\omega}{V}} - \frac{\cos \left[ \frac{nb_1}{R} \right]}{\frac{n}{R}} + \frac{\cos \left[ \frac{nb_2}{R} - \frac{\omega (b_2 - b_1)}{V} \right]}{\frac{n}{R} - \frac{\omega}{V}} - \frac{\cos \left[ \frac{nb_1}{R} \right]}{\frac{n}{R} - \frac{\omega}{V}} \right\}$$  \hspace{1cm} (12)
when \( n/R \neq \omega/V \) and

\[
I_{mn2} = \frac{L}{m\pi} \left[ \cos \left( m\pi a_1/L \right) - \cos \left( m\pi a_2/L \right) \right]
\]

\[
x \left\{ \sin \left[ \frac{nb_2}{R} + \frac{\omega V (b_2 - b_1)}{R} \right] - \sin \frac{nb_1}{R} \frac{V}{R + \omega V} + (b_2 - b_1) \cos \frac{\omega b_1}{V} \right\}
\]

\[
+ i \left\{ \cos \left[ \frac{nb_2}{R} + \frac{\omega V (b_2 - b_1)}{R} \right] - \cos \frac{nb_1}{R} \frac{V}{R + \omega V} + (b_2 - b_1) \sin \frac{\omega b_1}{V} \right\}
\]

when \( n/R = \omega/V \). In equation (13) when \( n/R = \omega/V \), the sweep velocity \( V \) matches with the bending wave velocity around the fuselage \( \omega R/n \) and hence corresponds to the case of coincidence. Substitution of the generalized force given in equation (10) into equation (8) yields the displacement response of the fuselage structure.

**Interior Noise Analysis**

The internal acoustic field, which is excited by the fuselage vibrations, is defined by the wave equation

\[
\nabla^2 P = \frac{1}{c^2} \frac{\partial^2 P}{\partial t^2}
\]

and the boundary conditions chosen for the ends and wall of the cylindrical section. To permit simplified analysis, open-end conditions are assumed; that is, the acoustic impedance, which is defined as the ratio of acoustic pressure to particle velocity, is taken as zero. While it is recognized that in an actual fuselage the ends have finite impedance, the use of the open-end conditions should have little effect on the calculated modal density of the sound field in the frequency range considered.

An expression for the interior noise pressure is obtained by assuming the boundary conditions at the wall to be such that the acoustic and the structural
analyses are coupled. The radial deflections of the shell are equated to the radial displacements of the air particles adjacent to the shell walls in the interior space. (See appendix B for detailed analysis.) The expressions for the space-averaged mean-square interior noise is given by (see eqs. (B16), (B18), and (B25))

\[
\bar{p}^2(\omega) = \bar{p}_0^2 \rho R^2 \omega^4 \sum_{mni} \left| \frac{H(\omega/\omega_{mn})}{M_{mn}^2} \right|^2 \left\{ \frac{I_{mni}}{\alpha^2 J_n^2(\alpha)} \right\} \times \left\{ J_n^2(\alpha) - J_{n-1}(\alpha) \right\} \left\{ J_{n+1}(\alpha) \right\}
\]

In equation (15), \( J_n^1(\alpha) \rightarrow 0 \) is the condition of acoustic resonance. The acoustic resonance frequencies are given by \( \omega_{mns} \) (see eq. (B14)) where \( m = 1, 2, 3, \ldots \) is the number of longitudinal half waves, \( n = 1, 2, 3, \ldots \) is the number of circumferential full waves, and \( s = 1, 2, 3, \ldots \) is the number of radial waves. Nodal patterns for a few acoustic modes are shown in figure 3. At resonance the interior noise is given by

\[
\bar{p}^2(\omega) = \bar{p}_0^2 \rho R^2 \omega^4 \sum_{mni} \left| \frac{H(\omega/\omega_{mn})}{M_{mn}^2} \right|^2 \left\{ \frac{I_{mni}}{\alpha^2 J_n^2(\alpha)} \right\} \times \left\{ J_n^2(\alpha) - J_{n-1}(\alpha) \right\} \left\{ J_{n+1}(\alpha) \right\}
\]

RESULTS

Results are presented for two fuselage structures whose dimensions are shown in table I. Fuselage 1 is representative of a large passenger-aircraft fuselage and fuselage 2 corresponds to a light-aircraft fuselage. The properties of the fuselage material and air in the fuselage interior are given in table II. The magnification factor for structural modes \( Q_{mni} \) is chosen as 50, which corresponds to 1 percent of the critical damping. This is the nominal value of damping for many actual structures. The magnification factor for acoustic modes \( Q_{ac} \) is chosen as 25, which corresponds to 2 percent of the critical damping. Reference 14 suggests this value of the magnification factor for acoustically treated enclosed spaces in the low-frequency range.

In order to provide a partial check of the structural part of the present analysis, natural frequencies of a simply supported, externally stiffened shell were calculated and compared with experimental results from reference 15. The experimental model had longitudinal stiffeners integrally built into the shell. As shown in figure 4, the agreement between analytical and experimental frequencies for this check case is good.
Natural Frequencies of Structure and Acoustic Field

Analytical natural frequencies of both fuselages are shown in figure 5. In calculating the results, all the modes in the frequency range studied are included (0 to 500 Hz); however, to simplify figure 5, not all of the modal frequencies are included. Figure 5 shows that the structural modal spectrum is significantly different for the two aircraft. For example, the lowest natural frequency is about 28 Hz for fuselage 1 and about 108 Hz for fuselage 2, and fuselage 1 has more modes (approximately 250) than does fuselage 2 (13) in the frequency range.

The acoustic mode frequencies of the fuselage interior space are shown in figure 6. As in the case of structural modes, all the acoustic modes in the frequency range studied were included in the calculations (0 to 500 Hz); however, not all modes are shown in figure 6. Fuselage 1 had more acoustic modes in the frequency range studied (1200) than fuselage 2 (47). The fuselage interior space receives acoustic energy in its acoustic modes, which are excited by the fuselage structural modes. For the particular end conditions assumed, the mth acoustic mode will respond only to a structural mode having the same m and n numbers. (For other end conditions, the coupling between structural and acoustic modes is more complicated, as discussed in ref. 10.) In addition, when the natural frequencies of such mode pairs are close together, noise transmission into the fuselage interior takes place very efficiently. From the complicated nature of the modal frequency curves shown in figures 5 and 6, it can be seen that many such frequency matchings may occur. A search of the tabulated values of the modal frequencies revealed that approximate frequency matchings occurred for fuselage 1 at the following values:

<table>
<thead>
<tr>
<th>m</th>
<th>n</th>
<th>s</th>
<th>$\omega_{mn}$</th>
<th>$\omega_{mns}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
<td>46.3</td>
<td>51.3</td>
</tr>
<tr>
<td>1</td>
<td>6</td>
<td>0</td>
<td>218.7</td>
<td>204.1</td>
</tr>
<tr>
<td>2</td>
<td>6</td>
<td>0</td>
<td>218.0</td>
<td>205.0</td>
</tr>
<tr>
<td>2</td>
<td>8</td>
<td>1</td>
<td>388.6</td>
<td>384.0</td>
</tr>
<tr>
<td>3</td>
<td>2</td>
<td>0</td>
<td>88.0</td>
<td>89.7</td>
</tr>
<tr>
<td>3</td>
<td>8</td>
<td>1</td>
<td>388.0</td>
<td>385.0</td>
</tr>
<tr>
<td>4</td>
<td>8</td>
<td>1</td>
<td>387.5</td>
<td>386.2</td>
</tr>
<tr>
<td>5</td>
<td>8</td>
<td>1</td>
<td>387.5</td>
<td>387.7</td>
</tr>
</tbody>
</table>

For fuselage 2, such frequency matchings occurred only at

<table>
<thead>
<tr>
<th>m</th>
<th>n</th>
<th>s</th>
<th>$\omega_{mn}$</th>
<th>$\omega_{mns}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>2</td>
<td>0</td>
<td>269.7</td>
<td>270.2</td>
</tr>
</tbody>
</table>

The relation of these frequency matchings to the noise reduction will be discussed later.
Numerical results for the interior noise are calculated from equations (15) and (16) and are presented in the form of noise reduction, which is defined as

\[
\text{Noise reduction} = 10 \log_{10} \left( \frac{\overline{p_e^2}}{\overline{p^2}} \right) \tag{17}
\]

where \( \overline{p_e^2} \) is the mean-square excitation pressure and \( \overline{p^2} \) is the space-averaged mean-square interior noise pressure. The frequency range considered in the present study is from 0 to 500 Hz, since this range covers the blade passage frequency and the first few harmonics which are the predominant frequencies exciting the structure. In the results shown in figures 7 to 12, noise reduction is studied as a continuous function of excitation frequency, for a number of sweep velocities. It is noted that an interior noise spectrum actually consists of tones at the blade passage frequency and its harmonics. The noise reduction at those corresponding frequencies can be obtained from the continuous noise reduction plot. Sweep velocity is a function of the propeller rotational speed and the distance from the propeller center to the fuselage side-wall. Hence, when the propeller rotation or the propeller center relative to the fuselage sidewalls are altered, the sweep velocity is affected and a different noise reduction plot must be computed.

To illustrate the effect of blade passage frequency on noise reduction, a plot of noise reduction against frequency is shown in figure 7. The blade passage frequency is denoted as \( f_1 \) Hz. The noise reductions at \( f_1 \) and its higher harmonics are marked with circular symbols. If the blade passage frequency is changed to \( f_1^\star \) (either by changing the number of blades in the propeller or the speed of rotation of the propeller) but the sweep velocity \( V \) is kept constant, the resulting discrete frequency spectrum of noise reduction associated with \( f_1^\star \) and its harmonics changes as indicated by the square symbols in figure 7. Sweep velocity can be held constant by adjusting the distance between the propeller center and the fuselage sidewalls. It is seen from figure 7 that, by changing the blade passage frequency, the noise reduction changes significantly, depending on whether it and its harmonics lie near resonances or away from resonances. Hence, noise reduction is very sensitive to blade passage frequency and structural and acoustic resonances.

The effect of sweep velocity on the noise reduction is shown in figures 8(a) and 8(b) for fuselage 1 and fuselage 2, respectively. The entire surface area of the fuselages is exposed to noise excitation as shown in figure 8. Noise reduction is plotted against nondimensional frequency, with the reference frequency \( f_r \) as the nondimensionalizing frequency. The reference frequency is the frequency of \( m = 1, n = 0 \), shell mode obtained as described in appendix A. This reference frequency is approximately equal to the ring frequency discussed in reference 14. It is seen from figure 8(a) that, when the excitation is uniform (sweep velocity \( V = \infty \) in eqs. (9)), noise reduction is a minimum at the reference frequency, whereas when the exciting pressures are sweeping around the fuselage sidewalls the noise reduction at this frequency is considerably higher. At frequencies below \( f/f_r = 0.5 \), however, noise
reduction is higher for uniform excitation than for the case of excitation with sweep velocity. For the case of uniform excitation, covering the full circumference of the fuselage (that is, \( b_2 = \pi R \) and \( b_1 = 0 \)), the integrals \( I_{mn} \) are zero except when \( n = 0 \), and hence, for uniform excitation, only \( n = 0 \) structural modes are excited and transmit noise to the fuselage interior. The dip in the noise-reduction curve at the reference frequency for the case of uniform excitation in figure 8(a) may be explained by the large number of structural modes near this frequency as compared to other frequencies, as shown in figure 5. The dips in this curve below the reference frequency are due to the presence of acoustic modes only. In figure 8(b), for the frequency range shown, the noise reduction for uniform excitation is always higher than it is when sweep velocity is present. A comparison with figure 8(a) shows that this behavior is similar to that of fuselage 1 in the frequency range where \( (f/f_\tau) < 0.5 \). From figures 8(a) and 8(b), it is seen that the effect of sweep velocity on noise reduction is quite significant, often making a difference of 25 dB in comparison with uniform excitation.

The variation of noise reduction with sweep velocity is shown in figures 9(a) and 9(b) for fuselage 1 and fuselage 2, respectively. Only a portion of the fuselage surface area is exposed to excitation, in the vicinity of the propeller plane, as shown in figures 9(a) and 9(b). It is seen from these figures that, when the sweep velocity is reduced from 341.4 m/sec to 136.6 m/sec, the noise reduction increases by about 10 dB. These velocities are chosen due to the fact that many propellers have tip speeds in this range. The same trend of noise reduction, decreasing with increasing sweep velocities, has been observed to be generally maintained over a broad range of sweep velocities. This trend is shown in figures 10(a) and 10(b), for fuselage 1 and fuselage 2, respectively, where the noise reduction is plotted against sweep velocity at a few representative resonance frequencies.

The effect of changing the axial length exposed to noise excitation on noise reduction is shown in figures 11(a) and 11(b) for fuselage 1 and fuselage 2, respectively. It is seen from both the figures that at most frequencies the noise reduction is greater by as much as 10 dB when a smaller portion of fuselage length is subjected to excitation. An exception is shown in figure 11(b) at about 270 Hz where the noise reduction is substantially less when a smaller length of fuselage is excited. As indicated previously, the structural and acoustic modes with \( m = 2 \) and \( n = 2 \) have nearly the same frequencies, resulting in a matching of their resonances and consequently a low noise reduction. This low noise reduction does not occur when the whole fuselage is excited because the \( m = 2 \) axial modes are orthogonal to the uniform excitation distribution. It is also interesting to note that the dips in the noise-reduction curve in figure 11(a) correspond with the modal frequencies discussed earlier where structural and acoustic modal frequencies match.

The effect of circumferential pressure distribution on noise reduction is shown in figures 12(a) and 12(b) for fuselage 1 and fuselage 2, respectively. In these figures noise reductions are plotted for two different circumferential areas exposed to noise excitation, keeping the axial portion exposed to noise and the sweep velocity constant. A comparison of the two curves in figure 12(a) shows that the noise reduction does not vary substantially with circumferential
area for most frequencies. In figure 12(b) noise reduction is higher by as much as 20 dB when the circumferential area exposed to noise is reduced. These results indicate that, in general, it is important to have a knowledge of the distribution of noise in order to determine properly the noise reduction in a fuselage.

CONCLUDING REMARKS

The effect on noise reduction of propeller noise characteristics has been studied for a twin-engine, propeller-driven aircraft with two propellers rotating in opposite directions. The fuselage is modeled as a cylindrical shell with stringers and ring frames, whose effects are averaged over the fuselage surface. The mathematical model of the propeller noise excitation used in this study includes some of the propeller noise characteristics such as pressure waves sweeping around the fuselage sidewalls due to propeller rotation and the localized nature of excitation with the highest levels near the propeller plane. The influence of the propeller noise characteristics on the noise reduction is studied.

The results of this investigation show that substantial changes in noise reduction occurred when sweep velocity and area of fuselage subjected to noise excitation were changed. Noise reduction generally decreased as the sweep velocity increased. Reducing the area exposed to excitation generally increased noise reduction. For the range of variables studied, differences in noise reduction of the order of 10 to 20 dB were observed.

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APPENDIX A

EQUATION OF MOTION OF THE FUSELAGE STRUCTURE

In the differential equation of dynamic equilibrium for the fuselage structure, Donnell-type strain displacement relations for the cylinder (ref. 13) and beam-type strain displacement relations for the stiffeners are considered. Inplane inertias are neglected since they do not significantly influence the radial modes of the shell, which are of interest in this investigation. The equations of motion for an element of the smeared shell can be written as

\[
L_{11}u + L_{12}v + L_{13}w = 0 \quad (A1a)
\]

\[
L_{21}u + L_{22}v + L_{23}w = 0 \quad (A1b)
\]

\[
L_{31}u + L_{32}v + L_{33}w = \left[-\frac{\rho_a(1-\mu^2)}{E} \frac{\partial^2 w}{\partial t^2} \right] + \frac{p_e(x,y,t)}{Eh}(1-\mu^2) \quad (A1c)
\]

where \(u\), \(v\), and \(w\) are shell displacements in the \(x\)-, \(y\)-, and \(z\)-directions, respectively, \(h\) is the shell thickness, \(E\) is the modulus of elasticity of the shell material, \(\mu\) is Poisson's ratio, \(t\) is the time, and \(p_e(x,y,t)\) is the excitation pressure on the fuselage surface. The term \(\rho_a\) is the average density of the fuselage material given by

\[
\rho_a = \rho + \frac{\rho_s A_s}{h l_s^2} + \frac{\rho_r A_r}{h l_r^2} \quad (A2)
\]

The differential operators \(L_{rs}\) in equations (A1) are as follows (see ref. 13):

\[
L_{11} = \left[1 + \frac{E_s A_s (1-\mu^2)}{E h l_s^2}\right] \frac{\partial^2}{\partial x^2} + \left(\frac{1-\mu}{2}\right) \frac{\partial^2}{\partial y^2} \quad (A3a)
\]

\[
L_{12} = L_{21} = \left(\frac{1+\mu}{2}\right) \frac{\partial^2}{\partial x \partial y} \quad (A3b)
\]

\[
L_{13} = L_{31} = \frac{\mu}{R} \frac{\partial}{\partial x} - \frac{z_s E_s A_s (1-\mu^2)}{E h l_s^2} \frac{\partial^3}{\partial x^3} \quad (A3c)
\]
With simple supports at each end of the shell, the boundary conditions to be satisfied at \( x = 0 \) and \( L \) are

\[
w = M_x = v = N_x = 0
\]  \( (A4) \)

where \( M_x \) is the moment resultant and \( N_x \) is the stress resultant in the \( x \)-direction. The boundary conditions in equation \( (A4) \) are satisfied by

\[
u(x,y,t) = \tilde{u}_1(t) \cos (m \pi x/L) \sin (n \pi y/R)
\]  \( (A5a) \)

\[
v(x,y,t) = \tilde{v}_1(t) \sin (m \pi x/L) \cos (n \pi y/R)
\]  \( (A5b) \)

\[
w(x,y,t) = \tilde{w}_1(t) \sin (m \pi x/L) \sin (n \pi y/R)
\]  \( (A5c) \)

and also by

\[
u(x,y,t) = \tilde{u}_2(t) \cos (m \pi x/L) \cos (n \pi y/R)
\]  \( (A6a) \)

\[
v(x,y,t) = \tilde{v}_2(t) \sin (m \pi x/L) \sin (n \pi y/R)
\]  \( (A6b) \)
APPENDIX A

\[ w(x,y,t) = \ddot{w}_2(t) \sin \left( \frac{m\pi x}{L} \right) \cos \left( \frac{ny}{R} \right) \]  \hspace{1cm} (A6c)

where \( m \) is the number of longitudinal half waves, and \( n \) is the number of circumferential waves, as illustrated in figure 2.

The free-vibration problem is solved to obtain the natural frequencies \( \omega_{mn} \) by putting \( p_0(x,y,t) \) equal to zero in equation (A1c), combining equations (A1) and (A5), and solving the resulting simultaneous equations in \( \ddot{u}_1, \ddot{v}_1, \) and \( \ddot{w}_1 \). The same frequency equation yielding the same set of natural frequencies \( \omega_{mn} \) is also obtained by combining equations (A1) and (A6).

Since both equations (A5) and (A6) satisfy the equations of motion and boundary condition of the fuselage structure, a complete solution for the response of the shell will involve the summation of both sets of solutions. Accordingly, the solutions for \( u, v, \) and \( w \) are taken as

\[ u(x,y,t) = \sum_{mn} U_{mn1}(x,y) q_{mn1}(t) \]  \hspace{1cm} (A7a)

\[ v(x,y,t) = \sum_{mn} V_{mn1}(x,y) q_{mn1}(t) \]  \hspace{1cm} (A7b)

\[ w(x,y,t) = \sum_{mn} W_{mn1}(x,y) q_{mn1}(t) \]  \hspace{1cm} (A7c)

where \( i = 1, 2 \). In equations (A7), the subscript \( i = 1 \) corresponds to the set of solutions in equations (A5) and \( i = 2 \) corresponds to the set of solutions given in equations (A6) and

\[
\begin{align*}
U_{mn1}(x,y) &= \cos \left( \frac{m\pi x}{L} \right) \sin \left( \frac{ny}{R} \right) \\
V_{mn1}(x,y) &= \sin \left( \frac{m\pi x}{L} \right) \cos \left( \frac{ny}{R} \right) \\
W_{mn1}(x,y) &= \sin \left( \frac{m\pi x}{L} \right) \sin \left( \frac{ny}{R} \right) \\
U_{mn2}(x,y) &= \cos \left( \frac{m\pi x}{L} \right) \cos \left( \frac{ny}{R} \right) \\
V_{mn2}(x,y) &= \sin \left( \frac{m\pi x}{L} \right) \sin \left( \frac{ny}{R} \right) \\
W_{mn2}(x,y) &= \sin \left( \frac{m\pi x}{L} \right) \cos \left( \frac{ny}{R} \right)
\end{align*}
\]  \hspace{1cm} (A8)

\[
\begin{align*}
U_{mn1}(x,y) &= \cos \left( \frac{m\pi x}{L} \right) \sin \left( \frac{ny}{R} \right) \\
V_{mn1}(x,y) &= \sin \left( \frac{m\pi x}{L} \right) \cos \left( \frac{ny}{R} \right) \\
W_{mn1}(x,y) &= \sin \left( \frac{m\pi x}{L} \right) \sin \left( \frac{ny}{R} \right) \\
U_{mn2}(x,y) &= \cos \left( \frac{m\pi x}{L} \right) \cos \left( \frac{ny}{R} \right) \\
V_{mn2}(x,y) &= \sin \left( \frac{m\pi x}{L} \right) \sin \left( \frac{ny}{R} \right) \\
W_{mn2}(x,y) &= \sin \left( \frac{m\pi x}{L} \right) \cos \left( \frac{ny}{R} \right)
\end{align*}
\]  \hspace{1cm} (A9)
After combining equations (A7) and equations (Al), the first two equations (Ala) and (Alb) identically vanish, and equation (Alc), after simplifying and applying the orthogonal property of the normal modes, yields the equation of motion for the (mni) mode as

\[ \dddot{q}_{mni}(t) + \omega_{mn}^2 q_{mni}(t) = \frac{F_{mni}(t)}{M_{mni}} \quad \text{(Al0)} \]

since \( i = 1 \) and \( i = 2 \) yield the same natural frequencies \( \omega_{mn} \). The terms \( M_{mni} \) and \( F_{mni} \) are the generalized mass and force of the (mni) mode, respectively, given by

\[ M_{mni} = \iint \rho_0 h \omega_{mni}^2(x,y) \, dx \, dy \quad \text{(All)} \]

and

\[ F_{mni}(t) = \iint p_e(x,y,t) \omega_{mni}(x,y) \, dx \, dy \quad \text{(Al2)} \]

The presence of light damping in the fuselage structure can be accounted for by adding a damping term in equation (A10) so that the equation of motion of the (mni) mode of the damped structure becomes

\[ \dddot{q}_{mni}(t) + \frac{\omega_{mn}}{Q_{mni}} \ddot{q}_{mni}(t) + \omega_{mn}^2 q_{mni}(t) = \frac{F_{mni}(t)}{M_{mni}} \quad \text{(Al3)} \]

where \( Q_{mni} \) denotes the dynamic magnification factor at resonance for the (mni) mode. Equation (Al3) is the same as equation (1) of the Analysis.
APPENDIX B

INTERIOR NOISE

The internal acoustic field is defined by the wave equation

\[ \nabla^2 p = \frac{1}{c^2} \left( \frac{\partial^2 p}{\partial t^2} \right) \]  \hspace{1cm} (B1)

and the boundary conditions. Assuming the process to be harmonic, the solution to the wave equation for acoustic pressure is

\[ p(x,\phi,r,t) = \left[ C_1 J_\eta(\alpha \hat{r}) + C_2 Y_\eta(\alpha \hat{r}) \right] \]
\[ \times (\cos \eta \phi + C_3 \sin \eta \phi) (\sin \psi x + C_4 \cos \psi x) e^{i\omega t} \]  \hspace{1cm} (B2)

where \( C_1, C_2, C_3, C_4 \) and \( \psi \) are constants of integration, \( J_\eta \) and \( Y_\eta \) are \( \eta \)th order Bessel functions of the first and second kind, respectively, and

\[ \alpha = kR \left[ 1 - \left( \frac{\psi}{k} \right)^2 \right]^{1/2} \]
\[ \hat{r} = \frac{r}{R} \]
\[ k = \frac{\omega}{c} \]  \hspace{1cm} (B3)

and \( r, \phi, \) and \( x \) denote the cylindrical coordinates along radial, circumferential, and axial directions, and \( c \) is the speed of sound in air.

For this problem open-end conditions are assumed for the fuselage, and hence the acoustic pressures are zero at \( x = 0 \) and \( x = L \). Using these values in equation (B2)

\[ C_4 = 0 \]
\[ \psi = \left( \xi \pi / L \right) \]  \hspace{1cm} (B4)

For finite pressures at the center of the cylindrical section, \( C_2 \) must be zero. Hence, by summing up the contributions of all the modes, the interior pressure is obtained as
APPENDIX B

\[ p(x, \phi, r, t) = \sum_{\xi \eta} C_{1j} J_{n}(\alpha r) \left( \sin \left( \frac{\xi \pi x}{L} \cos \eta \phi + C_3 \sin \eta \phi \right) e^{i\omega t} \right) \]  

(B5)

where \( \xi = 1, 2, \ldots, \infty \) and \( \eta = 0, 1, 2, \ldots, \infty \). With the circumferential coordinate \( \phi = (y/R) \) in equation (B5), the total pressure in the interior of the fuselage can be expressed as

\[ p(x, y, r, t) = \sum_{\xi \eta j} C_{\xi \eta j} J_{n}(\alpha r) \left( \phi_{\xi \eta j}(x, y) e^{i\omega t} \right) \]  

(B6)

where \( j = 1, 2 \) and

\[
\begin{align*}
\phi_{\xi \eta 1}(x, y) &= \sin \left( \frac{\xi \pi x}{L} \right) \sin \left( \frac{\eta y}{R} \right) \\
\phi_{\xi \eta 2}(x, y) &= \sin \left( \frac{\xi \pi x}{L} \right) \cos \left( \frac{\eta y}{R} \right)
\end{align*}
\]

(B7)

When the process is harmonic, the pressure \( p \) is related to the particle displacement in the radial direction \( w_a \) by the relation

\[ w_a = \left( \frac{1}{\rho_o \omega^2} \right) \left( \frac{\partial p}{\partial r} \right) \]  

(B8)

where \( \rho_o \) is the air density within the fuselage. This relation couples the structural and acoustic analyses. By equating the radial deflections of the shell and the particle displacement in the radial direction at \( r = R \), it is possible to arrive at an expression for the interior noise pressure. Combining equation (B6) and equation (B8) the particle displacement in the radial direction at \( r = R \) is

\[ w_a(x, y, R, t) = \sum_{\xi \eta j} \frac{C_{\xi \eta j}}{\rho_o \omega^2 R^3} \left[ J_{\eta}^{(1)}(\alpha) \right] \left[ \phi_{\xi \eta j}(x, y) e^{i\omega t} \right] \]  

(B9)

where \( \left( \frac{d}{dr} \right)^{\prime} = \frac{d}{dr} \). Equating \( w_a(x, y, R, t) \) given in equation (B9) to \( w(x, y, t) \) in equation (8), the values of the constants \( C_{\xi \eta j} \) can be obtained by using the orthogonal property of the normal modes. It can be seen from equations (A7c), (A8), and (A9) and equations (B6) and (B7) that the space functions describing the shell radial deflections and the space functions describing the interior noise pressures at \( r = R \) are similar, that is,

\[ w_{\text{mni}}(x, y) = \phi_{\text{mni}}(x, y) \]  

(B10)
APPENDIX B

where \( m = c u_j \). Using this result and the orthogonality property of the space functions, the modal constants \( C_{mn} \) are obtained as

\[
C_{mn} = \frac{\rho_o \omega^2 R P m_{mn}^2 H(\omega/\omega_{mn}) e^{-\theta(\omega/\omega_{mn})}}{M_{mn}^2 \omega_{mn}^2 J_n'(\alpha)} \quad (B11)
\]

Substituting for \( C_{mn} \) from equation (B11) in equation (B6) the noise pressure in the fuselage interior is obtained as

\[
p(x,y,r,t) = \rho_o \omega^2 R P \sum_{mn} \left[ \frac{H(\omega/\omega_{mn}) e^{-\theta(\omega/\omega_{mn})} I_{mn}}{M_{mn}^2 \omega_{mn}^2 J_n'(\alpha)} \right] \left[ J_n(\alpha) \right] \left[ \phi_{mn}(x,y) e^{i\omega t} \right] \quad (B12)
\]

In equation (B12) when \( J_n'(\alpha) = 0 \), the noise pressure goes to infinity. In an undamped acoustic field, subjected to finite excitations, pressure will go to infinity only at its natural frequencies. Hence, the roots of the equation

\[
J_n'(\alpha) = 0 \quad (B13)
\]

correspond to the natural frequencies of acoustic modes. If \( \alpha_{ns} \) represents roots of equation (B13), then the natural frequencies of acoustic modes are obtained using equations (B3)

\[
\omega_{mn} = \omega_m \left[ 1 + L^2 \left( \frac{\alpha_{ns}^2}{\pi^2} \right) m^2 R^2 \right]^{1/2} \quad (B14)
\]

and

\[
\omega_m = (m \pi c/L)
\]

From equation (B12) the mean-square pressure is obtained as

\[
\overline{p^2}(x,y,r,\omega) = \overline{p^2} \rho_o R^2 \omega^4 \sum_{mn} \left[ \frac{H(\omega/\omega_{mn})}{M_{mn}^2 \omega_{mn}} \right]^2 \left[ \frac{J_n^2(\alpha) e^{-\theta(\omega/\omega_{mn})}}{\omega_{mn}^2} \right] \left[ \phi_{mn}^2(x,y) I_{mn} \right] + \sum (cross \ terms) \quad (B15)
\]

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Space averaging the mean-square interior noise pressure, the cross terms in equation (B15) vanish due to the orthogonality of the modes, and hence the space-averaged mean-square pressure in the fuselage interior is obtained as

\[
\overline{p^2}(\omega) = \overline{p_o^2} \rho_o R^2 \omega^4 \sum_{\text{mni}} \frac{|H(\omega/\omega_m)|^2}{M_{mni}^2 \omega_m^2} \left\{ \frac{|I_{mni}|^2 \gamma_{mni}}{\alpha^2 \left[ J_n(\alpha)^2 \right]} \right\} \left[ J_n^2(\alpha) - J_{n-1}(\alpha)J_{n+1}(\alpha) \right]
\]  

(B16)

for \( \omega_m < \omega \) where

\[
\gamma_{mni} = \frac{1}{2\pi RL} \int \int \Phi_{mni}^2(x,y) \, dx \, dy
\]

(B17)

Since \( \alpha = kr\left[1 - (\omega_m/\omega)\right]^{1/2} \), \( \alpha \) becomes imaginary when \( \omega_m > \omega \), in which case the equation (B16) becomes

\[
\overline{p^2}(\omega) = \overline{p_o^2} \rho_o R^2 \omega^4 \sum_{\text{mni}} \frac{|H(\omega/\omega_m)|^2}{M_{mni}^2 \omega_m^2 |\alpha|^2} \left[ I_n^2(|\alpha|) - I_{n-1}(|\alpha|)I_{n+1}(|\alpha|) \right]
\]

(B18)

for \( \omega_m > \omega \) where \( I_n \) represents modified Bessel functions of the first kind.

So far in the analysis, damping has not been considered for the acoustic modes, and hence the interior pressure will tend to infinity when \( J_n'(\alpha) = 0 \). Damping in the acoustic modes is introduced as explained in reference 10. The term \( J_n'(\alpha) \) is expanded in a series around those points where \( J_n'(\alpha) = 0 \); that is,

\[
J_n'(\alpha) = J_n'(\alpha_{ns}) + (\alpha - \alpha_{ns})[J_n''(\alpha_{ns})] + \ldots
\]

(B19)

Since \( J_n'(\alpha_{ns}) = 0 \), equation (B19) can be written as

\[
J_n'(\alpha) \approx (\alpha - \alpha_{ns})J_n''(\alpha_{ns})
\]

(B20)
where the series in equation (B19) is truncated after the second term. For small values of \((\alpha - \alpha_{ns})\),

\[
\alpha^2 - \alpha_{ns}^2 \approx 2\alpha_{ns}(\alpha - \alpha_{ns}) \tag{B21}
\]

Substituting \(\alpha^2 = \frac{\omega^2 R^2}{c^2} \left[1 - \left(\frac{\omega_m}{\omega}\right)^2\right]\) and \(\alpha_{ns}^2 = \frac{\omega_{mns}^2 R^2}{c^2} \left[1 - \left(\frac{\omega_{mns}}{\omega}\right)^2\right]\) in equation (B21) it is seen that

\[
\frac{k^2 R^2 \left[1 - \left(\frac{\omega_{mns}}{\omega}\right)^2\right]}{2\alpha_{ns}} \approx \alpha - \alpha_{ns} \tag{B22}
\]

Using the relationships in equations (B20) and (B22),

\[
\frac{1}{\alpha^2 \left[J_n'(\alpha)\right]^2} \approx \frac{4}{k^4 R^4 \left[J_n''(\alpha_{ns})\right]^2 \left[1 - \left(\frac{\omega}{\omega_{mns}}\right)^2\right]} \tag{B23}
\]

where \(\alpha \rightarrow \alpha_{ns}\). Inserting the acoustic dynamic magnification factor \(Q_{ac}\) and allowing \(\omega \rightarrow \omega_{mns}\), equation (B23) can be written as

\[
\frac{1}{\alpha^2 \left[J_n'(\alpha)\right]^2} \approx \frac{4Q_{ac}^2}{k^4 R^4 \left[J_n''(\alpha_{ns})\right]^2} \tag{B24}
\]

Substituting the value of \((1/\alpha^2) \left[J_n'(\alpha)\right]^2\) given in equation (B24) into equation (B16), the space-averaged mean-square interior noise pressure in the vicinity of acoustic resonances is obtained as

\[
\overline{p^2(\omega)} = \overline{\rho_0^2 R^2 \omega^4} \sum_{mni} \frac{\left|H(\omega/\omega_{mn})\right|^2 \left|I_{mn} \gamma_{mn} (4Q_{ac}^2) \right| \left[J_n^2(\alpha) - J_{n-1}(\alpha)J_{n+1}(\alpha)\right]}{k^4 R^4 \left[J_n''(\alpha_{ns})\right]^2} \tag{B25}
\]

for \(\omega \rightarrow \omega_{mns}\).
REFERENCES


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### TABLE I.- STRUCTURAL DETAILS OF THE FUSELAGES

<table>
<thead>
<tr>
<th>Dimension</th>
<th>Fuselage 1</th>
<th>Fuselage 2</th>
<th>Stiffener cross sections</th>
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<tr>
<td>Modulus of elasticity of skin, stringer, and frame, $E$, $E_s$, $E_f$, Pa</td>
<td>$0.71 \times 10^{11}$</td>
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<tr>
<td>Poisson's ratio, $\mu$</td>
<td>0.33</td>
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<tr>
<td>Density of skin, stringer, and frame material, $\rho$, $\rho_s$, $\rho_f$, kg/m$^3$</td>
<td>$0.27 \times 10^{4}$</td>
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</tr>
<tr>
<td>Density of air, $\rho_o$, kg/m$^3$</td>
<td>1.25</td>
<td></td>
<td></td>
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<tr>
<td>Velocity of sound in air, $c$, m/sec</td>
<td>341.4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Magnification factor for structure, $Q_{mni}$</td>
<td>50</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Magnification factor for air, $Q_{ac}$</td>
<td>25</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Figure 1.- Models showing fuselage and propeller noise distribution. All dimensions are in meters.
Figure 2.- Structural mode shapes of a cylindrical shell. 

m indicates number of elastic half waves along cylinder axis; n, number of elastic full waves around cylinder circumference.
Figure 3.- Typical circumferential and radial acoustic node patterns. $n$ indicates number of circumferential full waves; $s$, number of radial waves.

Figure 4.- Comparison of predicted and measured natural frequencies.
Figure 5. - Modal frequencies of fuselage structure.

(a) Fuselage 1.

(b) Fuselage 2.
Figure 6.- Acoustic modal frequencies of fuselage interior space. $m$ indicates number of longitudinal half waves; $n$, number of circumferential full waves; $s$, number of radial waves.
Figure 6.- Concluded.

(b) Fuselage 2.
Figure 7.- Effect on noise reduction of changing blade passage frequency.
Fuselage 2; sweep velocity, \( V = 68.4 \) m/sec.
Figure 8.- Variation of noise reduction with excitation frequency with and without sweep velocity.

(a) Fuselage 1; exterior pressure distributed uniformly over the whole fuselage; $f_r = 347$ Hz.
Figure 8.- Concluded.

(b) Fuselage 2; exterior pressure distributed uniformly over the whole fuselage; \( f_r = 1056 \) Hz.

\[
\begin{align*}
\text{Noise reduction, dB} \\
\text{Frequency, } f/f_r
\end{align*}
\]
(a) Fuselage 1; exterior pressure on part of fuselage.

Figure 9.— Variation of noise reduction with excitation frequency for two sweep velocities.
Figure 9.- Concluded.

(b) Fuselage 2; exterior pressure on part of fuselage.
Figure 10.- Variation of noise reduction with sweep velocity at structural resonances.
Noise reduction, dB

Sweep velocity, \( V \), m/sec

(b) Fuselage 2.

Figure 10.- Concluded.
Figure 11.- Effect on noise reduction of reducing axial length exposed to noise excitation.
Figure 11.— Concluded.
Figure 12.- Effect on noise reduction of reducing circumferential area exposed to noise excitation.

(a) Fuselage 1.
Figure 12.— Concluded.
**Title and Subtitle**

A THEORETICAL INVESTIGATION OF NOISE REDUCTION THROUGH THE CYLINDRICAL FUSELAGE OF A TWIN-ENGINE, PROPELLER-DRIVEN AIRCRAFT

**Abstract**

Interior noise in the fuselage of a twin-engine, propeller-driven aircraft with two propellers rotating in opposite directions is studied analytically. The fuselage is modeled as a stiffened cylindrical shell with simply supported ends, and the effect of stringers and frames is averaged over the shell surface. An approximate mathematical model of the propeller noise excitation is formulated which includes some of the propeller noise characteristics such as sweeping pressure waves around the sidewalls due to propeller rotation and the localized nature of the excitation with the highest levels near the propeller plane. Results are presented in the form of noise reduction, which is the difference between the levels of external and interior noise. The influence of propeller noise characteristics on the noise reduction is studied. The results indicate that the sweep velocity of the excitation around the fuselage sidewalls is critical to noise reduction.

**Subject Category**

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