AN IMPLEMENTATION OF THE DISTRIBUTED PROGRAMMING STRUCTURAL SYNTHESIS SYSTEM (PROSSS)

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INTRODUCTION

Numerous approaches have been documented for combining optimization
techniques with an analysis capability (e.g., refs. 1-4). The PROgraming
Structural Synthesis System (PROSSS), described in reference 4, was first
implemented entirely on a CDC CYBER computer. This implementation is
described in reference 5. PROSSS was then distributed between a mainframe and
a minicomputer (ref. 6) to provide the user easier access to intermediate
results, more control over the flow of the problem, and an interactive
modeling and data generation capability (ref. 7).

This document describes the implementation of the distributed version of
PROSSS, the second step in a series of implementations. After an overview
which explains PROSSS in general with respect to this implementation, the
remainder of this document is devoted to describing (1) each component of the
system, (2) how to examine the intermediate results, (3) how to restart the
system, and (4) results from a sample problem exercising the options of this
implementation. Appendices contain listings to clarify the descriptions of
the components of the system contained in the body of this paper.

It is not the purpose of this paper to be a self-contained user's guide
for PROSSS. Its purpose is to demonstrate a method for implementing a
flexible software system that combines large complex programs with small,
user-supplied, problem-dependent programs and distributes their execution between a mainframe and a minicomputer.

OVERVIEW OF THIS IMPLEMENTATION

This distributed implementation of the PROgraming Structural Synthesis System (PROSSS) combines a general purpose finite-element computer program for structural analysis (SPAR, ref. 8), a state-of-the-art optimization program (CONMIN, ref. 9), and several user-supplied, problem-dependent computer programs. The results are flexibility of the optimization procedure organization and versatility of the formulation of constraints and design variables.

Figure 1 is a flow chart of the analysis-optimization process for this implementation. The process results in a minimized objective function, typically the mass. Notice that the analysis and optimization programs are executed repeatedly by looping through the system until the process is stopped by a user-defined termination criterion. This is referred to as the repeatable part of PROSSS. However, some of the analysis, such as model definition, need only be done one time and the results are saved for future use. This analysis is performed outside of the loop and referred to as the nonrepeatable part of PROSSS. The user must write some small, simple FORTRAN programs to interface between the analysis and optimization programs. One of these programs, the front processor, converts the design variables output from the optimizer into a suitable format for input into the analyzer. Another, the end processor, retrieves the behavior variables and, optionally, their gradients from the analysis program and evaluates the objective function and constraints and optionally their gradients. These quantities are output in a format suitable for input into the optimizer. These user-supplied programs
are problem-dependent because they depend primarily upon which finite elements are being used in the model.

The analysis is always performed on the mainframe, in this implementation a CDC 6600, because the CPU on the mainframe is much faster than that of the minicomputer. The end processor is also executed on the mainframe to reduce the large amounts of data generated by the analysis program to the small amount of data (e.g., objective function and constraints) required by the optimizer. This limits the amount of data transmitted between the two computers.

The optimization is always performed on the minicomputer, in this implementation a PRIME 750, because the optimizer requires a significant memory allocation and the minicomputer has virtual memory. The front processor is also executed on the minicomputer and, as in the case of the end processor, the amount of data transmitted between the two computers is reduced to the minimum. The data transmitted from the front processor to the analysis program consist of updated design variable information.

Five options exist for organization of optimization procedures comprising nonlinear and piecewise linear programming with analytical and finite-difference gradients. These options are shown in Table I. One of the primary differences between the distributed implementation of PROSSS and the first implementation described in reference 5 is the method of controlling the flow of the options. In the first implementation, each option is controlled by a complex sequence of Control Data Corporation-Cyber Control Language (CDC-CCL (ref. 10)), while the flow of the options in the distributed implementation of PROSSS is controlled by FORTRAN programs using FORTRAN-callable system subroutines (ref. 11). Although presented in the context of structural analysis,
these organizations are independent of the type of analysis. The same system concept could be used for aerodynamic optimization of, for example, a wing, if the analyzer had a capability for computational aerodynamics.

The system is intended to be used in the following three basic ways:

1. as a research tool for development of optimization techniques where it offers an interface to efficient analysis and flexibility of execution and sequencing,
2. as a test bed for trying new structural analysis techniques tailored toward efficient use in optimization loop, and
3. as an application tool that can be adopted to a very wide scope of different types of problems.

Before trying to implement this system, the user should be thoroughly familiar with references 4, 5, 6, 8 and 9.

COMPONENTS OF THE SYSTEM

There are seven primary components for the distributed implementation of PROSSS including (1) the driver program, (2) the front processor, (3) CONMIN-the optimizer, (4) procedures transmitting jobs between the PRIME minicomputer and CDC mainframe computer, (5) SPAR-the analyzer, (6) the end processor, and (7) the plotting program. Each component and the files associated with them are explained in detail in the following subsections. Files generated by the system are not shown. Only those files that must be created by the user are shown.

The Driver Program

As previously mentioned, each option in PROSSS is controlled by a FORTRAN program using FORTRAN-callable procedure files. While each option uses its own main driver program, there is a group of eight subroutines common to each
option. A typical flowchart of an option is shown in figure 2. The listings of the program and subroutines are shown in Appendix A. The driver program performs the following functions: (1) initialization, (2) restarting, (3) controlling the flow of the option, and (4) termination.

The driver program first reads one line from a file named NAMEij where ij is the option number without the decimal. For example, a file named NAME11 contains the input data for option 1.1. This first line in NAMEij contains the following variables:

- **NRSTRT**
  - 0 - not restarting
  - 1 - restarting

- **ICR**
  - 0 - data not created by a data generator
  - 1 - data created by a data generator

- **NR**
  - 0 - no nonrepeatable analysis is to be done
  - 1 - perform nonrepeatable analysis

- **NOPT**
  - the option number (e.g. 11)

- **NAMES**
  - the name of the file to be sent to the CDC 6600 (four characters in length)

- **COUNT**
  - the number of passes made through the analysis program (initially one)

The format is (3(I1,1X),I2,1X,A4,1X,I3).
An example of a NAMEij file is as follows:

<table>
<thead>
<tr>
<th>NAMEij</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STRP3</td>
<td>file containing starting design variables</td>
</tr>
<tr>
<td>CONPI</td>
<td>file containing CONMIN parameters</td>
</tr>
<tr>
<td>CONS</td>
<td>file containing constants for front processors</td>
</tr>
<tr>
<td>RRSNG</td>
<td>file containing repeatable runstream with no analytical gradients</td>
</tr>
<tr>
<td>JIM</td>
<td>UFD name</td>
</tr>
<tr>
<td>DPROSS</td>
<td>SUBUFD name</td>
</tr>
<tr>
<td>SSPROUT</td>
<td>file containing SPAR output</td>
</tr>
<tr>
<td>SCNMINIO</td>
<td>file containing end processor output</td>
</tr>
<tr>
<td>NRLANG</td>
<td>file containing non-repeatable SPAR library</td>
</tr>
<tr>
<td>123456</td>
<td>user number</td>
</tr>
<tr>
<td>XYZ</td>
<td>password</td>
</tr>
<tr>
<td>123456</td>
<td>charge number</td>
</tr>
<tr>
<td>EPFUBIP</td>
<td>file containing end processor</td>
</tr>
<tr>
<td>EPFUIN</td>
<td>file containing input to end processor</td>
</tr>
<tr>
<td>FPFUS</td>
<td>file containing front processor (Ø mean compile)</td>
</tr>
<tr>
<td>CONMS1</td>
<td>file containing CONMIN main program (1 means do not compile)</td>
</tr>
</tbody>
</table>

If NRSTRT is equal to zero, subroutine INIT is called to create a temporary procedure file called INITPRC. INIT reads the remainder of file NAMEij and creates edit procedures on file INITPRC to replace general file names in procedure files executing other components of the system with specific file names depending upon the problem being solved. Files for other components of the system are created depending on the option number. (This is transparent to the user.)
If ICR is not equal to zero, then INIT calls subroutine CRSNPT. This subroutine reads data from a file called NAMECRRS, edits a file created by the data generator, and inserts a file containing problem-dependent data. An example of a NAMECRRS file is as follows:

```
1
SPARIN  number of design variables
TOPSPARIN  file created by a data generator for input to SPAR
```

If NR is not equal to zero, then INIT calls subroutine NONRPT. This subroutine reads data from a file called NAMENR and creates a procedure file (TONOSNR, described below) to be sent to the CYBER to perform the nonrepeatable part of the analysis. An example of a NAMENR file is as follows:

```
TSPARIN  non-repeatable SPAR runstream
70000  field length required on CDC 6600
NON1  non-repeatable job name
```

If NRSTRT equals 1, then subroutine RSTRT is called instead of subroutine INIT. This subroutine sets up a procedure file named RSTRTPRC to reinitialize the files saved for restarting the program.

If the nonrepeatable part of the analysis is required (NR = 0), a job has been sent to the CDC 6600 to perform this analysis. At this point, subroutine STCHEK is called. This subroutine calls subroutine COMSTA which returns the status of a file that has been transmitted to the CDC 6600 computer. If COMSTA determines that the job has not yet completed executing on the CDC 6600 (because no file has been returned to the PRIME), then it returns a status of zero. If the job has completed executing on the CDC 6600 and a file has been returned to the PRIME, the status is returned as one. When the status cannot be determined, an error has occurred and the status is returned as -1.
Subroutine STCHEK checks the status returned from COMSTA. If the status is one, then control is passed back to the driver program. If the status is -1, subroutine ERRMSG is called to print an error message, and the job is terminated. If the status is zero, a system routine is called to put the job on the PRIME to "sleep" for 2 minutes while waiting for the CDC 6600 to finish processing. After 2 minutes, the job "awakens" and again calls subroutine COMSTA to determine if the file has been returned from the CDC 6600. The "sleep" and "awake" process continues until the CDC 6600 has finished processing the analysis and returned the output file to the PRIME. This concept makes efficient use of the PRIME's resources.

Once the nonrepeatable part of the analysis program has been completed, the driver enters the optimization loop shown in figure 1. It will remain in this loop until an error is encountered, a loop limit (default is 999) is met, or the termination criteria are satisfied. In the optimization loop, procedure files executing the optimization program and front processor program (described below) are called. The front processor creates a file containing updated design variable information to be transmitted to the CDC 6600. The file sent to the CDC 6600 to perform the repeatable part of the analysis must have a unique job name to facilitate the return checking done by subroutine COMSTA. Subroutine UPDSF is called to create a temporary procedure file (UPDTE) for assigning this unique job name. The job name is created from the NAMES variable from the first line of the NAMEij file coupled with the loop counter.

Two temporary files containing the names of files pertaining to the specific problem at hand are created during initialization from two permanent files containing general file names. One temporary file, the names coming from the NAMES variable on the NAMEij file, is created from a permanent file
called TONOS. TONOS is a file containing CDC-CCL statements to execute the repeatable analysis (SPAR) and end processor on the CDC 6600. The second temporary file, called TSENDPRC is created from the permanent file SENDPRC. SENDPRC is a PRIME procedure file for appending the data file created by the front processor to the temporary file created from TONOS and then transmitting that file to the CDC 6600. Once the TSENDPRC file has been executed and processing is transferred to the CDC 6600 for the repeatable part of the analysis, then subroutine STCHEK is again called to test for the status of the file to be returned from the CDC 6600. The same checking, "sleeping," and "awakening" pattern described above for the nonrepeatable analysis is also followed here.
A sample listing of a TONOS file is shown below. This listing contains the general names that are replaced by specific, problem dependent names during initialization.

```
JOB,T100,CM70000.
USER,USERNO,PASSWRD.
CHARGE,CHARGENO,LRC.
DELIVER,$UFDSUBUFDTCMNIO
RFL,70000.
REDUCE(-)
MAP,OFF.
COPYCR,INPUT,SPFPOUT.
REWIND,SPFPOUT.
GET,RUNSTREAM,MERGF.
EDIT,RUNSTREAM,,MERGF.
EDIT,RUNSTREAM,,MERGF,EDOUT.
REWIND,RUNSTREAM.
GET,SPAR=SPAR141,DCU=DCU141.
GET,SPARLA=SPAROUT.
SPAR,RUNSTREAM,SPAROUT.
REWIND,SPAROUT.
REWIND,SPARLD.
GET,EPXXXX,ENDINXX.
GET,SPARLIB.
LDSET(LIB=SPARLIB,PRESET=ZERO)
EPXXXX,ENDINXX,CNMNIO.
REPLACE,SPAROUT=DUMOUT,CNMNIO=DUMIO.
REWIND,CNMNIO.
COPYSBF,CNMNIO,OUTPUT.
DAYFILE(L=DISOUT)
REPLACE,DISOUT.
EXIT.
DAYFILE(L=DISOUT)
REPLACE,DISOUT.
```
A sample SENDPRC file is:

```
SAVE TEMP
DELETE UPDTE
APPEND SENDFILE SPFPOUT
DELETE CNMNIO
RJSEND SENDFILE CDC
DELETE SPFPOUT
R TEMP
```

After the analysis output file, TCMNIO, is returned from the CDC 6600, the driver program checks for the existence of a file called GONOGO. GONOGO is created by the CONMIN main program when the termination criteria have been met. If GONOGO exists, then the optimization process stops. If GONOGO does not exist, then the optimization loop continues by calling the EDPRC procedure file. This procedure file edits TCMNIO to remove any extraneous information, such as the dayfile, returned from the CDC 6600. This leaves only the objective function and constraint data required for input into CONMIN. At this point, the optimization loop begins a new iteration. A sample EDPRC file is:

```
SAVE TEMP
ED TCMNIO
L END CNMNIO
DI0000
T
L BEGIN CNMNIO
D
UNLOAD CNMNIO 1000
FIL
DELETE TCMNIO
R TEMP
```
The Optimizer

The procedure file called from the driver program to execute CONMIN, the optimizer, is named CNMNPRC1. Whenever any procedure file is called from the driver program, the first instruction in the procedure file is to save the current address. The final instruction in the procedure file is to return control to the saved address. The CNMNPRC1 procedure file performs four functions: (1) saves restart files, (2) opens and closes files for CONMIN input and output, (3) executes CONMIN, and (4) save cumulative plotting and optimization data. A listing of CNMNPRC1 is below:

```
SAVE TEMP
ED PASS
FIL SPASS
ED CNMNIO
FIL SCNMNIO
ED CONREST
FIL SCONREST
OPEN TPLT 12 2
OPEN PLTDATA 11 3
OPEN PASS 7 3
OPEN CNMNIO 5 3
OPEN CONREST 3 3
OPEN CONOUT 2 2
OPEN CONPAR 1 1
SEG CONMIN
C 1
C 2
C 3
C 5
C 11
C 12
APPEND PLTDATA TPLT
DELETE TPLT
APPEND CONOUTHOLD CONOUT
DELETE CONOUT
R TEMP
```
Three files are required to restart CONMIN. File PASS contains the number of passes made through CONMIN--one initially and two on each subsequent pass. File CNMNIO contains the objective function and constraints found in the repeatable analysis. File CONREST contains all of the remaining data saved from the preceding pass through CONMIN. These files are saved as temporary files named SPASS, SCNMNIO, and SCONREST, respectively.

Other files open for CONMIN input and output include TPLOT, PLTDATA, CONOUT, and CONPAR. TPLOT contains the plotting data created in this (and only this) pass through CONMIN. PLTDATA contains a cumulative history for the objective function, design variables, and constraints for the entire run. CONOUT contains the output listing for only this pass through CONMIN. CONPAR contains the output listing for this pass through CONMIN. CONPAR contains the initialization values for the parameters input to CONMIN. This file must be created by the user and is input via a free-field format. A description of these variables, except for JSC, can be found in reference 9. The variable JSC is used to determine the linear constraint identification vector, JSC. If JSC is -999, then all of the constraints are known to be a linear function of the design variables. If JSC is zero, then all of the constraints are nonlinear. If JSC is other than these two numbers, then a file, ISCFILE, must be created by the user containing the constraint numbers (in I4 format) of the linear constraints if JSC is positive or the constraint numbers of the nonlinear constraints if JSC is negative. JSC in this last case is the number of constraints in ISCFILE. ISCFILE is opened and closed within CONMIN. Another file, STARTX, is also opened and closed within CONMIN and must be created by the user. This file contains the number of design variables in I5.
format followed on succeeding lines by the starting values of the design variables in 6E13.5 format. A sample CONPAR file is:

```
5 3 20 190 0 1 0
4 0 0 0.0 0.0 0.0 0.025 0.0 0.0
0.125 5.0 0.000000001 0 20 200 100 100 2000
0.0 0.0 0.005 0.1 1.0 1.0 1.0 1.0.
```

A sample STARTX file is:

```
3
0.50000E+01 0.10000E+01 0.40000E+01
```

Once the restart files have been saved and the necessary files have been opened, the CNMNPRCI executes CONMIN. CONMIN consists of a group of nine subroutines as defined in reference 9. These routines are never changed by the user. The routines are called by a CONMIN main program written by the user dependent upon the problem to be solved. An example of a main program is listed in Appendix B. In addition to calling the CONMIN subroutines, the CONMIN main program is responsible for reading and writing data from and to the above files. After executing CONMIN, CNMNPRCI closes all files that remain open.

The final task performed by CNMNPRCI is to append the temporary files containing the plotting data (TPLT) and CONMIN output listing (CONOUT) to the permanent cumulative files PLTDATA and CONOUTHOLD, respectively. TPLT and CONOUT are deleted and control is returned to the driver program.

The Front Processor

The procedure file called from the driver program to execute the front processor, FPFUS, is named FRONTPRC. The front processor is supplied by the user and converts the design variables output from CONMIN on file CNMNIO to
a file SPFPOUT formatted suitable for input into the SPAR analysis program. A listing of FRONTPRC follows:

```
SAVE TEMP
OPEN CNMNIO 1 1
OPEN SPFPOUT 2 2
OPEN CONSXX 3 1
R *FPROCESSOR
C 1
C 2
C 3
R TEMP
```

The FRONTPRC procedure file opens the CNMNIO and SPFPOUT files. In addition, a file called CONSXX, supplied by the user if necessary and containing certain constants such as the cross section dimensions of a beam, is also opened. The format of the CONSXX file is determined by the user because the user writes the front processor program dependent upon what elements are used in the finite-element model. An example of a front processor is then executed, all open files are closed, and control is returned to the driver program. A sample CONSXX file for the beam parameters B1Ø, B2Ø and TØ follows:

```
12. 30. 2. (beam parameters)
```

The Analyzer--Nonrepeatable Part

The INITPRC procedure file (described above in the section on the driver program) transmits the TONOSNR procedure file to the CDC 6600 to execute the nonrepeatable part of the analysis. The nonrepeatable SPAR runstream (NRRS) is appended to the TONOSNR file for transmittal to the CDC 6600. NRRS is
copied to a local file and SPAR is then executed using NRRS as input. The results are saved on a SPAR library file (NRLA) for later use in the repeatable part of the analysis. A file named TNREPT is returned to the PRIME indicating that the nonrepeatable analysis has completed execution. A listing of TONOSNR follows.

```
JOB,T100,CMFLX.
USER,USERNO,PASSWRD.
CHARGE,CHARGENO,LRC.
DELIVER,$UFD>SUBUFD>TNREPT
MAP,OFF.
COPYCR,INPUT,NRRS.
REPLACE,NRRS.
.*
.* THE PROCEDURE CREATES A SPAR LIBRARY FROM THE NON-REPEATABLE PART
.*
GET,SPAR=SPAR14I,DCU=DCU14I.
GET,NRRS.
RFL,FLX.
REDUCE,-
SPAR,NRRS,NSPROUT.
REPLACE,SPARLA=NRLA.
.*
.* TEST TO SEE IF GRADIENTS ARE REQUIRED
.*
IFE,(NROPT.EQ.13.0R.NROPT.EQ.23),GRADIENTS.
GET,INPT=INPTXX.
GET,EDIT1,EDIT2,BLDELDB.
REWIND,NRRS.
.*
.* EDIT OUT ALL BUT ELD INPUT IN RUNSTREAM
.*
EDIT,NRRS,EDIT1,EDOUT.
REWIND,NRRS.
.*
.* CREATE SPAR RUNSTREAM TO FIND DERIVATIVES
.*
BLDELDB,INPT,NRRS,RSOUT.
REWIND,RSOUT.
EDIT,RSOUT,EDIT2,EDOUT.
REWIND,RSOUT,SPARLA.
.*
.* EXECUTE SPAR AGAIN TO FIND DERIVATIVES OF THE STIFFNESS MATRIX WITH RESPECT TO THE DESIGN VARIABLES
.*
SPAR,RSOUT,NSPROUT.
RETURN,INPT,EDIT1,EDIT2,BLDELDB,EDOUT.
RETURN,RSOUT,TAPE21,TAPE22,NSPROUT.
REPLACE,SPARLB=NRLA.
ENDIF,GRADIENTS.
RETURN,SPARLB=NRLA.
ENDIF,GRADIENTS.
RETURN,SPAR,DCU,SPARLA,NRRS.
DAYFILE(L=DISOUT)
REPLACE,DISOUT.
EXIT.
DAYFILE(L=DISOUT)
REPLACE,DISOUT.
```
An example of a non-repeatable SPAR runstream (NRRS) is as follows:

\texttt{EXQT TAB}
\texttt{START 80, 5$ ROTATIONS ABOUT Y EXCLUDED}
\texttt{TITLE" FUSELAGE MODEL,FSPAR1}
\texttt{TEXT}
\texttt{* MEMBRANE-ROD-BEAM FUSELAGE MODEL}
\texttt{*NONREPEATABLE PART}
\texttt{JLOC$ FUSELAGE DIA. 800. CM., LENGTH=800. CM.}
\texttt{FORMAT=2%CYLINDRICAL COORDINATES}
\texttt{1 400. 0. 0. 400. 337.5 0. 16 1 5}
\texttt{16 400. 0. 800. 400. 337.5 800.}
\texttt{MREF}
\texttt{FORMAT=2}
\texttt{1 -2 0. 0. 10000000.}
\texttt{2 1 0. 0. 10000000.}
\texttt{MATC}
\texttt{1 0.72+6 0.3 0.0028 22.-6$ AL-ALLOY, METRIC UNITS}
\texttt{E23 SECTION PROPERTIES $ROD ELEMENTS}
\texttt{1 4.168$ AREA OF THE RODS}
\texttt{E21 SECTION PROPERTIES $BEAM ELEMENTS}
\texttt{DSY 1 16804. 0. 1262.7 0. 108. 144. 0. 6.0784 0. 0.}
\texttt{0. 0. 0. -8.7778 17. 3.2222 17. 3.2222 -17. -8.7778 -17.}
\texttt{SHELL SECTION PROPERTIES}
\texttt{1 0.1$ SKIN THICKNESS}
\texttt{CONSTRAINT CASE 1}
\texttt{ZERO 1,2,3;1,16$ CANTILEVER THE FUSELAGE}
\texttt{EXQT ELD}
\texttt{$START}
\texttt{E23$ ROD ELEMENTS}
\texttt{NSECT=1$}
\texttt{NREF=2}
\texttt{1 17 1 4 3 1$}
\texttt{4 20$}
\texttt{5 21$}
\texttt{6 22$}
\texttt{52 68$}
\texttt{53 69$}
\texttt{54 70$}
\texttt{7 23 1 4 10 1$}

\texttt{$END}
\texttt{$START}
\texttt{E21$ BEAM ELEMENTS}
\texttt{NSECT=1$}
\texttt{NREF=2}
\texttt{1 17 18 2 2 16 1$}
\texttt{49 65 66 50 2 16 1$}
\texttt{17 33 34 18 1 1 2 2 16$}
\texttt{23 39 40 24 1 1 9 2 16$}
\texttt{32 48 33 17$}
\texttt{48 64 49 33$}

\texttt{$END}
\texttt{EXQT DCU}
\texttt{TOC 1}
\texttt{EXQT EXIT}
The Analyzer--Repeatable Part

The SENDPRC procedure file transmits the TONOS procedure file (both files discussed in the above section on the driver program) to the CDC 6600 to execute the analysis (SPAR) and end processor (EPXXXX) programs. The SPFPOUT file created by the front processor is appended to the TONOS file for transmittal to the CDC 6600. The SPAR library file (SPARNAME) containing data created during the nonrepeatable analysis and the repeatable SPAR runstream file (RUNSTREAM) both reside as permanent files in the CDC 6600 disk storage. SPFPOUT is copied onto a temporary file on the CDC 6600 and merged into RUNSTREAM file using a file named MERGFP consisting of CDC TEXT EDITOR (ref. 12) commands. SPAR is then executed using the RUNSTREAM and SPARNAME files as input. The objective function and stresses are computed in SPAR and saved on a SPAR library file (SPARLD). This file is then used as input to the end processor. A listing of the MERGFP file is as follows:

```
MERGE:/SPFPOUT/,/$ MERGE NEW;/
R
RS:/E+/,/+;*
RS:/E-/,/-;*
END
```
An example of a repeatable SPAR runstream without analytical gradients (RRSNG) is as follows:

```
$ XTQ TAB
TITLE"FUSELAGE MODEL"
TEXT
"MEMBRANE ROD BEAM FUSELAGE MODEL"
"REPEATABLE PART WITHOUT GRADIENTS"
UPDATE=1
$ MERGE NEW PROPERTIES HERE.
UPDATE=0
$ XTQ TOPO
$ XTQ E
$ XTQ EKS
$ XTQ K
$ XTQ INV
$ XTQ M
RESET G=991.
$ XTQ AUS
SYSEVC;APPLIED FORCES 1
I=1; J=65; 69; 77; 10000. -20000. 20000.
SYSEVC;UNIT VEC
I=1; J=1; 80; 1.0
DEFINE WT=DEM DIAG 0 0
DEFINE UN=UNIT VEC
OBJFUN=XTY(UN,WT)
$ XTQ DCU
PRINT 1 OBJFUN
$ XTQ SSOL
$ XTQ GSF
$ XTQ PSF
$ XTQ VPRT
PRINT APPL FORC 1 1
PRINT STAT DISP 1 1
$ XTQ DCU
PRINT 1 STAT DISP 1 1
PRINT 1 STRS E21 1 1
PRINT 1 STRS E23 1 1
PRINT 1 STRS E41 1 1
TOC 1
COPY 1,4 OBJF AUS 1 1
COPY 1,4 STRS E21 1 1
COPY 1,4 STRS E23 1 1
COPY 1,4 STRS E41 1 1
TOC 4
$ XTQ EXIT
```
The End Processor

The end processor, EPFUS, is also executed on the CDC 6600. The objective function and stress data saved on the SPAR library file, SPARLD, are input to the end processor using FORTRAN-callable subroutines from SPAR (ref. 13). Another file, ENDINXX, is stored on the CDC 6600 in NAMELIST form and input to the end processor. This file contains the number of each different type of element used in the model and the limits imposed on the behavior variables in constraint function evaluation. The format of the ENDINXX file is determined by the user because the user writes the end processor program dependent upon what elements are used in the finite-element model. The end processor then computes the constraints and outputs the objective function and constraints in a suitable format for input to the optimizer. The output is placed on file CNMNI0 and transmitted to the PRIME on file TCMNIO. An example of an end processor program is listed in Appendix D. A sample of an ENDINXX file is as follows:

```plaintext
$EPIN
E23AL=2000.,
E21AL=2000.,
E41AL=2000.,
NSE23=58,
NSE21=76,
NSE41=56,
$END
```

Gradients

Options 1.3 and 2.3 have the capability for calculating gradients analytically. There are three problem independent programs used
to compute the analytical gradients. The first, BLDELDS, builds a file for
input into the analysis program to calculate the derivatives for the mass and
stiffness matrices with respect to the design variables in the nonrepeatable
part. A listing of BLDELDS is in Appendix E. The program is stored on the
CDC 6600 and is called by the TONOSNR (described in the section on the
nonrepeatable analysis) sent to the CDC 6600 from the PRIME. The file
containing the nonrepeatable SPAR runstream NRNS, is edited using the CDC Text
Editor (ref. 12) commands from file EDIT1 to remove all but the element
connectivity data. A listing of EDIT1 follows:

```
F:/[XQT ELD/
F:/[XQT/;2
D;*
R
F:/[XQT ELD/
E;*
R
D;*
R
ADD
$
END
```
Another file, INPT, stored on the CDC 6600 and created by the user is input to BLDELDS along with the edited NRRS file. The INPT file contains two card types. The first type (only one card) has the format \((6(1X,I4),1X,A4)\) and contains the following variables:

- **NOLC** - number of load cases
- **NODV** - number of design variables
- **ISNOLC** - new starting number for load cases with derivatives
- **JOINTS** - number of joints in the model
- **NDF** - number of degrees of freedom
- **NOEL** - number of different elements
- **VORB** - a four character word to determine the type of analysis (e.g., STAT, VIBR, BUCK)

The second type has the format \((6(1X,A3,1X,I3,1X,I3))\) consists of one or more cards, and contains the following variables (one set for each element):

- **EL** - element type (e.g., E21, E43)
- **NSECT** - largest section property number used for that element type
- **NODVPE** - number of design variables for that element type

A sample listing of INPT follows.

```
1 3 100 80 5 3 STAT
E23 1 1 E21 1 1 E41 1 1
```

BLDELDS creates a SPAR runstream and outputs it on file RSOUT. File RSOUT is then edited using the CDC Text Editor and commands from file EDIT2 to remove any extraneous blanks or characters before being input to SPAR. SPAR is then executed using RSOUT as input. The results are saved on a SPAR library file (NRLA) for later use in the repeatable part of the analysis.
A listing of the EDIT2 file follows:

```
RS:/ /;/;*
RS: /;/;*
A:/TOP/;*
>RESET MAXSUB=2500
END
```

The other two gradient programs, GRDXXXX and DRVXXXX, are used in the repeatable part of the analysis. Listings of GRDXXXX and DRVXXXX are in Appendices F and G, respectively. Two procedure files SENDPRCG and TONOSG (similar to the SENDPRC and TONOS files previously described) are used to execute these programs in conjunction with the SPAR analysis program on the CDC 6600. The first part of the repeatable analysis with analytical gradients is identical to repeatable analysis described above. The CNMNIO file created by the optimizer is appended to the TONOSG file by SENDPRCG before it is transmitted to the CDC 6600. The GRDXXXX, DRVXXXX, INPTXX, CONSXX, and EDGRDS files are all stored on the CDC 6600. The contents of the INPTXX and CONSXX have already been described. Each of the GRDXXXX, DRVXXXX, INPTXX, and CONSXX general file names are replaced by specific names from the NAMEij file before execution. GRDXXXX uses the repeatable SPAR runstream (RRSG) as with analytical gradients to create a runstream to calculate the derivatives of the stiffness and the mass matrices with respect to the design variables when an element (such as a beam or plate) has more than one contributing factor. The program calls user supplied subroutine(s) with any of the following names DKDVE21, DKDVE22, DKDVE33, and/or DKDVE43. These subroutines compute the derivatives of the stiffness matrix with respect to a design variable for a particular element type in SPAR (ex. E21 or E43). The name(s) used depend
upon the elements used in the finite-element model. If a subroutine is not used, it remains as an unsatisfied external. Two integer parameters used in naming the created data sets are passed to each subroutine. The first is the counter for the design variable and the second is the number of unconstrained degrees of freedom (from 1 to 6). A listing of a sample DKDVE21 subroutine is shown in Appendix H. The subroutine card for DKDVE21 is as follows:

```
SUBROUTINE DKDVE21(NDVJIM,NDF)
```

where

- `NDVJIM` - the number of the design variables (first, second, third, etc.)
- `NDF` - number of degrees of freedom per joint squared

A listing of the SENDPRCG file follows.

```
SAVE TEMP
DELETE UPDATE
APPEND SENDFILE SPFPOUT
APPEND SENDFILE CNMNO
DELETE CNMNO
RJSEND SENDFILE CDC
DELETE SPFPOUT
R TEMP
```
A listing of the TONOSG file follows.

```
JOB, T100, CM100000.
USER, USERN0, PASSWRD.
CHARGE, CHARGENO, LRC.
DELIVER, SUBFD, SUBFD, TCMNO.
RFL, 100000.
REDUCE(-).
MAP, OFF.
COPYCR, INPUT, SPFPOUT.
REWIND, SPFPOUT.
GET, MERGFP, UN=753437N.
GET, RUNSTREAM.
EDIT, RUNSTREAM, MERGFP, EDDUT.
REWIND, RUNSTREAM.
GET, SPAR = SPAR14I, DCU=DCU14I, UN=750756N.
GET, SPARLA=SPARNAME.
SPAR, SPAROUT.
RETURN, RUNSTREAM, SPFPOUT, MERGFP, EDDUT.
REWIND, SPARLA.
GET, SPARLIB, UN=319925N.
GET, GRDXXXX, DRVXXXX, INPTXX, CONXX.
GET, EDGRDS, UN=753437N.
COPYCR, INPUT, CMNMO.
REWIND, CMNMO.
GRDXXXX, INPTXX, CONXX, CMNMO, RSOUT.
REWIND, RSOUT.
EDIT, RSOUT, EDGRDS, EDDUT.
REWIND, RSOUT.
SPAR, RSOUT, SPAROUT.
RETURN, EDGRDS, EDDUT, GRDXXXX.
IFE, (NSUBS.NE.0), DERIV.
REWIND, SPARLA, SPARLD, SPARLC, CMNMO, CONXX, INPTXX.
LDSET (LIB=SPARLIB, PRESET=ZERO)
DRVXXXX, INPTXX, CONXX, CMNMO.
RETURN, DRVXXXX, INPTXX, CONXX, SPARLA, SPARLC.
ENDIF, DERIV.
REWIND, SPARLD, SPARLIB, CMNMO.
GET, EPXXXX, ENDINXX.
LDSET (LIB=SPARLIB, PRESET=ZERO)
EPXXXX, ENDINXX, CMNMO, BLK.
RETURN, SPARLD, EPXXXX, ENDINXX, SPARLIB.
REPLACE, SPAROUT=DUMOUT, CMNMO=DUMIO.
REWIND, BLK, CMNMO.
COPYSBF, BLK, OUTPUT.
COPYSBF, CMNMO, OUTPUT.
DAYFILE (L=DISOUT)
REPLACE, DISOUT.
EXIT.
DAYFILE (L=DISOUT)
REPLACE, DISOUT.
```
An example of a repeatable SPAR runstream with analytical gradients (RRSG) follows.

```plaintext
EXQT TAB
  TITLE "FUSELAGE MODEL"
TEXT
"MEMBRANE ROD BEAM FUSELAGE MODEL"
"REPEATABLE PART WITH GRADIENTS"
UPDATE=1
$ MERGE NEW PROPERTIES HERE.
UPDATE=0
EXQT E
EXQT EKS
EXQT TOPO
EXQT K
EXQT INV
EXQT M
RESET G=981.
EXQT AUS
SYSVEC; APPLIED FORCES 1
  I=1; J=65; 69; 77; 10000, -20000, 20000.
SYSVEC; UNIT VEC
  I=1; J=1; 80; 1.0
DEFINE WT*DEM DIAG 0 0
DEFINE UN*UNIT VEC
OBJF AUS 1 1=XTY(UN,WT)
EXQT DCU
PRINT 1 OBJF AUS 1 1
EXQT SSOL
EXQT GSF
EXQT PSF
EXQT VPRT
PRINT APPL FORC 1 1
PRINT STAT DISP 1 1
EXQT DCU
CHANGE 1, STRS E21 1 1, FAMS E21 1 1
TOC 1
COPY 1, 4 OBJF AUS 1 1
COPY 1, 4 FAMS E21 1 1
COPY 1, 4 STRS E23 1 1
COPY 1, 4 STRS E41 1 1
TOC 4
EXQT EXIT
```
The SPAR runstream is output on file RSOUT. A file, EDGRDS, containing CDC Text Editor commands is used to remove any extraneous blanks or characters from RSOUT. SPAR is executed to compute the derivatives using RSOUT as input. The output data from SPAR, including stresses, stress derivatives, forces and moments, and derivatives of forces and moments are output on a SPAR library file, SPARLD. A listing of EDGRDS follows.

```
RS:/E+/,/+;/*
RS:/ . /*/ . /*;*
RS:/ . /0/ . /0;/*
RS:/ . /-;/ . /-;/*
RS:/ / / ;/*
RS:/E-/ ,/- ;*
RS:/ / , / ;*
RS:/ / , / ;*
RS:/ W ,/ W ;*
RS:/ G ,/ G ;*
RS:/ W ,/ W ;*
RS:/ F ,/ F ;*
RS:/ L ,/ L ;*
END
```

Program DRVXXXX is called if there is a need to convert forces and moments, and derivatives of forces and moments to stresses and stress derivatives. The program computes stresses and stress derivatives using a user supplied subroutine named BMSTRS (for beams) or PLTSTRS (for plates). As before, if a name is not used it remains an unsatisfied external. Four integer parameters are passed to BMSTRS. They are (1) a switch, (2) a counter so
certain computations can be skipped if they are not needed, (3) a block counter for accessing an array, and (4) another switch to determine if the beam is the contributing factor to the stress derivative. The first three parameters are also passed to PLTSTRS. A listing of a sample BMSTRS subroutine is provided in Appendix I. The subroutine for BMSTRS is as follows:

```fortran
SUBROUTINE BMSTRS (ISW,KCNT,JCNT,IBEAM)

where

ISW, KCNT - a switch and a counter used to store certain beam data (ex. moments of inertia) and make certain computations (ex. derivatives of Y with respect to the design variables) only on the first time BMSTRS is called from DRVXXXX
JCNT - a counter to find the location in blank common for various data times, depends on the number of beam elements
IBEAM - 1 if beam is a contributing factor to stress derivatives - 0 otherwise
```

This program also uses FORTRAN-callable SPAR subroutines (ref. 13) to input and output this data to and from the SPAR library, SPARLD. After DRVXXXX completes execution the end processor is executed before control is returned to the PRIME.

EXAMINING THE INTERMEDIATE RESULTS

One of the key features in the distributed PROSSS is the capability for the user to examine the intermediate results. Because of this feature, the user does not have to wait until the end of the complete optimization process to determine whether or not the model, variables, and/or process are behaving as expected. The user, after examining the intermediate results, can let the
process continue; stop the process; or temporarily stop the process, make some changes to the optimization parameters or design variables, and restart the process. This gives the user much more control over the flow of the problem and should significantly reduce the total time required to reach the optimal solution.

All examining of intermediate results is done on the PRIME because of the faster transmission rate (9600 BAUD) to the interactive terminals. Two files, CONOUTHOLD, and PLTDATA, created by the CONMIN driver program are essential for examining these results. The CONOUTHOLD contains a cumulative listing of all information output from CONMIN. This information is originally output on file CONOUT. At the end of the CNMNPRC1 procedure file, CONOUT is appended to CONOUTHOLD to create the cumulative listing. It is best to examine the CONOUTHOLD file with the PRIME editor (ref. 14). The user is usually interested in seeing the progress of the objective function and design variables. Also of interest are the active and violated constraints. It is useful to check for errors and warning messages issued by CONMIN so that the process can be stopped at this point.

If the user desires to see a graphical display of the optimization data, the PLTDATA file should be used in conjunction with program plots. The program plots either the objective function, design variables, or constraints versus the iteration number. The capability of listing these values in tabular form is also available. The user makes a choice from a menu displayed on the screen (figure 3). The user can also decide whether or not the objective function and design variables are to be normalized. Examples of each type of plot are shown in figures 4-6.
RESTARTING PROSSS

The user may wish to restart PROSSS for a particular point in the process because the computers go down, there is an error in the system, or the examination of the intermediate results revealed a change in the system, or the examination of the intermediate results revealed a change is needed in the model or optimization parameters. To restart PROSSS is quite simple. All of the necessary files required for restarting are saved by the procedure file CNMNPRCI. The user edits the first line of the NAMEij file to restart. The NRSTRT variable is set to 1. The NAMES variable is changed to create a unique name. The COUNT variable may or may not be updated depending upon whether or not the user has need of keeping track of the number of iterations through the system. Other names may be changed in the NAMEij file as needed. After these changes have been made, the user restarts PROSSS. After initialization, processing begins at CONMIN.

SAMPLE PROBLEM

Each option was executed to determine the final objective function (minimum mass, kg) of the finite-element model of the fuselage shown in figure 7 using the NAMEij input files. The model is composed of 80 joints, 58 rods, 76 beams, and 56 membranes. There are 352 degrees of freedom. The three design variables are (1) the cross-sectional area of the transverse stringers (beams), (2) the cross-sectional area of the longitudinal stringers (rods), and (3) the thickness of the panels (membranes). The design variables are handled by the optimizer in reciprocal form to improve the convergence. Their initial reciprocal starting values are 0.05 cm², 1.0 cm², 4.0 cm, respectively. The initial objective function is 5460.12 kg. Figure 8 shows the results for each option. All final objective functions are within
reasonable limits, even though some of the design variables differ significantly. The piecewise linear approach is 50 to 75 percent less expensive to execute than the nonlinear approach. Reference 6 describes, in detail, the results of this test compared to the results from an identical model tested on the mainframe-only version of PROSSS. The comparison is done in terms of accuracy, cost, CPU time, and total time.
REFERENCES


<table>
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<th>METHOD</th>
<th>IN OPTIMIZER BY</th>
<th>EXTERNAL TO OPTIMIZER BY</th>
</tr>
</thead>
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<tr>
<td></td>
<td>FINITE DIFFERENCE</td>
<td>FINITE DIFFERENCE</td>
</tr>
<tr>
<td>NONLINEAR PROGRAMMING</td>
<td>1.1</td>
<td>1.2</td>
</tr>
<tr>
<td>PIECEWISE LINEAR PROGRAMMING</td>
<td>N/A</td>
<td>2.2</td>
</tr>
</tbody>
</table>

Table 1.- Options for Optimization.
FIGURE 1.- FLOWCHART OF A DISTRIBUTED OPTIMIZATION SOFTWARE SYSTEM.
FIGURE 2.—FLOWCHART OF A TYPICAL OPTIMIZATION OPTION.
INPUT NUMBER CORRESPONDING TO TYPE OF PLOT DESIRED

1 - PLOT ITERATIONS VS OBJECTIVE FUNCTION
2 - PLOT ITERATIONS VS DESIGN VARIABLES
3 - PLOT ITERATIONS VS CONSTRAINTS
4 - PRINT NUMERICAL RESULTS
5 - END

FIGURE 3.- MENU FOR PLOTTING PROGRAM.
FIGURE 4.- CHANGE IN OBJECTIVE FUNCTION FOR THE FUSELAGE MODEL.
FIGURE 5.—CHANGE IN DESIGN VARIABLES (RECIPROCALS) FOR THE FUSELAGE MODEL.
FIGURE 6.- ACTIVE AND VIOLATED CONSTRAINTS FOR THE FUSELAGE MODEL.
LOADING DISTRIBUTED ON ALL JOINTS

CLAMPED EDGE

352 DOF

EDGE SUBJECT TO LOAD

MEMBRANES
RODS
BEAMS

FIGURE 7.- 352 DOF FUSELAGE MODEL USED FOR TESTING.
### TABLE 1: COMPARISON OF DESIGN VARIABLES

<table>
<thead>
<tr>
<th>OPTION</th>
<th>CROSS SECTIONAL AREA BEAM (CM²)</th>
<th>CROSS SECTIONAL AREA ROD (CM²)</th>
<th>THICKNESS MEMBRANE (CM)</th>
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<tr>
<td></td>
<td>M/O</td>
<td>D</td>
<td>M/O</td>
</tr>
<tr>
<td>1.1</td>
<td>1.6332</td>
<td>1.6292</td>
<td>4.7341</td>
</tr>
<tr>
<td>1.2</td>
<td>1.5713</td>
<td>1.5681</td>
<td>8.4175</td>
</tr>
<tr>
<td>1.3</td>
<td>1.5458</td>
<td>1.5175</td>
<td>10.6723</td>
</tr>
<tr>
<td>2.2</td>
<td>1.5659</td>
<td>1.5149</td>
<td>1.1770</td>
</tr>
<tr>
<td>2.3</td>
<td>1.6215</td>
<td>1.6134</td>
<td>1.6722</td>
</tr>
</tbody>
</table>

M/O = MAINFRAME-ONLY SYSTEM    D = DISTRIBUTED SYSTEM

FIGURE 8.— COMPARISON OF DESIGN VARIABLES.
APPENDIX A.- LISTING OF OPTION 1.1 DRIVER PROGRAM AND GENERAL SUBROUTINES.

C DISTRIBUTED PROSSS OPT11
C
INTEGER*4 COUNT,NAMES
INTEGER*2 STAT,SW,ERROR,NRSTRT
SW = 0
C
C SET UP INITIALIZATION PROCEDURE
C
CALL SRCH$$ (1,'NAME11',6,1,0,ICODE)
READ(5,2) NRSTRT,ICR,NR,NOPT,NAMES,COUNT
2 FORMAT(3(I1,I1X),I2,1X,A4,1X,I3)
IF(NRSTRT.EQ.0) CALL INIT(NR,ICR,NAMES,NOPT)
COUNT = COUNT-1
C
C SET UP FOR RESTART IF NRSTRT = 1
C
IF(NRSTRT.EQ.0) GO TO 4
CALL SRCH$$ (4,'NAME11',6,1,0,ICODE)
CALL RSTRT(NOPT,NAMES)
CALL COMI$$ ('RSTRTPRC',8,6,ICODE)
CALL EXIT
CALL SRCH$$ (4,'RSTRTPRC',8,1,0,ICODE)
CALL SRCH$$ (5,'RSTRTPRC',8,1,0,ICODE)
GO TO 6
C
C INITIALIZATION PROCEDURE FILE
C
4 CALL SRCH$$ (4,'NAME11',6,1,0,ICODE)
CALL COMI$$ ('INITPRC',7,5,ICODE)
CALL EXIT
CALL SRCH$$ (4,'INITPRC',7,1,0,ICODE)
CALL SRCH$$ (5,'INITPRC',7,1,0,ICODE)
C
C SKIP IF NONREPEATABLE PART NOT REQUIRED
C
IF(NR.EQ.0) GO TO 5
C
C CHECK STATUS OF RETURNED FILE
C
CALL STCHEK(STAT,1)
CALL SRCH$$ (5,'TNREPT',6,1,0,ICODE)
IF(STAT.EQ.0) GO TO 5
ERROR = 2
GO TO 40
CONMIN PROCEDURE FILE

5  COUNT = COUNT + 1
   IF (COUNT .LT. 999) GO TO 6
   ERROR = 1
   GO TO 40
   6  CALL COMI$$('CNMNPRC1', 8, 6, ICODE)
      CALL EXIT

FRONT PROCESSOR PROCEDURE FILE

CALL COMI$$('TFRTPRC', 7, 6, ICODE)
CALL EXIT

SUBROUTINE TO UPDATE SEND FILE NAME (UNIQUELY)

CALL UPDSF(COUNT, SW, INFO)
   SW = SW + 1

UPDATE NAME PROCEDURE FILE

CALL COMI$$('UPDTE', 5, 6, ICODE)
CALL EXIT

SEND TO NOS PROCEDURE FILE

CALL COMI$$('TSENDPRC', 8, 6, ICODE)
CALL EXIT

CHECK STATUS OF RETURNED FILE

   CALL STCHKEK(STAT, 0)
   IF (STAT .GT. 0) GO TO 35
   ERROR = 2
   GO TO 40

TEST FOR SYSTEM TERMINATION

35  CALL SRCH$$('GONOGO', 6, 1, 0, ICODE)
    IF (ICODE .EQ. 0) GO TO 100

EDIT CNMNIO FILE RETURNED FROM NOS PROCEDURE FILE

CALL COMI$$('EDPRC', 5, 6, ICODE)
CALL EXIT
GO TO 5

PRINT ERROR MESSAGE AND STOP PROGRAM

40  CALL ERRMSG(ERROR)
100  STOP
END
SUBROUTINE INIT(NR, ICR, NAME1, NOPT)
C CREATES A PROCEDURE FILE (INITPRC) FOR
INITIALIZING FILES
C
INTEGER*4 NAME, NAME1, NAME2, STARTX, CONPAR, UFD, SUBUFD
INTEGER*4 SPLA, USERN0, PASSW, CHARGE, INPT, CONS
DIMENSION NAME(Z), STARTX(Z), CONPAR(Z), UFD(Z), SUBUFD(Z), SPLA(Z)
DIMENSION USERN0(Z), CHARGE(Z), INPT(Z), CONS(Z)
C OPEN PROCEDURE FILE
CALL SRCHS$(2, 'INITPRC', 7, 2, 0, ICODE)
WRITE(6, 7)
7 FORMAT('SAVE TEMP'/'OPEN CONOUTHOLD 1 2'/'C 1')
C SET UP TEMPORARY FILES FOR CNMNIO, CONREST, AND BLK
C IF(NOPT.EQ.11 OR NOPT.EQ.12 OR NOPT.EQ.13) WRITE(6, 8)
8 FORMAT('ED'/'X'/'FIL CNMNIO'/'ED'/'X'/'FIL CONREST')
IF(NOPT.EQ.22 OR NOPT.EQ.23) WRITE(6, 9)
9 FORMAT('ED'/'X'/'FIL BLK')
C INITIALIZE PASS, GONOGO, AND CNT
C
45
WRITE(6,10)
10 FORMAT(ED'/10FIL PASS')
   IF(NOPT.EQ.12 .OR. NOPT.EQ.22 .OR. NOPT.EQ.23) WRITE(6,16)
16 FORMAT(ED'/1.0E 00 1.0E 00 1.0E 00 0.5E-01 '
   1 'FIL CNT')
C INITIALIZE SENDPRC
C
   IF(NOPT.EQ.11 .OR. NOPT.EQ.12 .OR. NOPT.EQ.22) WRITE(6,45)
45 FORMAT(ED SENDPRC')
   IF(NOPT.EQ.13 .OR. NOPT.EQ.23) WRITE(6,46)
46 FORMAT(ED SENDPRCG')
   WRITE(6,61) NAME1
61 FORMAT(ED/C/SENDFILE/',A4,'/100'/'FIL TSENDPRC')
C STORE NAMES FOR STARTX AND CONPAR
C
   READ(5,30) STARTX
30 FORMAT(2A4)
   WRITE(6,40) STARTX
40 FORMAT(ED ',2A4,'FIL STARTX')
   READ(5,30) CONPAR
   WRITE(6,43) CONPAR
43 FORMAT(ED ',2A4,'FIL CONPAR')
C INITIALIZE FRONT PROCESSOR
C
   READ(5,30) CONS
30 FORMAT(2A4)
   WRITE(6,44) CONS
44 FORMAT(ED FRONTPRC'/C/CONSXX/',2A4,'/100'/'FIL TFRTPRC')
C INITIALIZE TONOS
C
   READ(5,30) NAME
30 FORMAT(2A4)
   IF(NOPT.EQ.11 .OR. NOPT.EQ.12 .OR. NOPT.EQ.22) WRITE(6,65) NAME
65 FORMAT(ED TONOS'/C/RUNSTREAM/',2A4,'/100'/'T')
   IF(NOPT.EQ.23) WRITE(6,64) NAME
64 FORMAT(ED TONOSG'/C/RUNSTREAM/',2A4,'/100'/'T')
   IF(NOPT.NE.13) GO TO 644
   WRITE(6,640) NAME
640 FORMAT(ED TONOS13'/C/RSGRAD/',2A4,'/100'/'T')
   READ(5,30) NAME
   WRITE(6,641) NAME
641 FORMAT(ED/RSGRAD/',2A4,'/100'/'T')
   READ(5,30) NAME
   WRITE(6,642) NAME
642 FORMAT(ED/EPYYY/',2A4,'/100'/'T')
644 READ(5,30) UFD
   WRITE(6,66) UFD
46
66 FORMAT('C/UFD/','2A4, '/100, '/T')
READ(5,30) SUBUFD
WRITE(6,67) SUBUFD
67 FORMAT('C/SUBUFD/','2A4, '/100, '/T')
READ(5,30) NAME
WRITE(6,68) NAME
68 FORMAT('C/DUMOUT/','2A4, '/100, '/T')
READ(5,30) NAME
WRITE(6,69) NAME
69 FORMAT('C/DUMIO/','2A4, '/100, '/T')
READ(5,30) SPLA
WRITE(6,70) SPLA
70 FORMAT('C/SPARNAME/','2A4, '/100, '/T')
WRITE(6,71) NAME1
71 FORMAT('C/JOB/','4A4, '/100, '/T')
READ(5,30) USERNO
WRITE(6,72) USERNO
72 FORMAT('C/USERNO/','2A4, '/100, '/T')
READ(5,30) PASSW
WRITE(6,720) PASSW
720 FORMAT('C/PASSWRD/','4A4, '/100, '/T')
READ(5,30) Charge
WRITE(6,73) Charge
73 FORMAT('C/CHARGENO/','2A4, '/100, '/T')
READ(5,30) NAME
WRITE(6,75) NAME
75 FORMAT('C/EPXXXX/','2A4, '/100, '/T')
READ(5,30) NAME
WRITE(6,74) NAME
74 FORMAT('C/ENDINXX/','2A4, '/100, '/T')

C SKIP IF NO GRADIENTS ARE REQUIRED
C
IF(NOPT.EQ.11. OR. NOPT.EQ.12. OR. NOPT.EQ.22) GO TO 755
READ(5,30) NAME
WRITE(6,750) NAME
750 FORMAT('C/DRVXXXX/','2A4, '/100, '/T')
READ(5,30) NAME
WRITE(6,751) NAME
751 FORMAT('C/GRDXXXX/','2A4, '/100, '/T')
READ(5,79) NSUBS
79 FORMAT(I1)
 WRITE(6,752) NSUBS
752 FORMAT('C/NSUBS/','I1, '/100, '/T')
READ(5,30) INPT
WRITE(6,753) INPT
753 FORMAT('C/INPTXX/','2A4, '/100, '/T')
WRITE(6,754) CONS
754 FORMAT('C/CONSXX/','2A4, '/100, '/T')

REMOVE EXTRANEOUS BLANKS

WRITE(6,76)
76 FORMAT(('/C//100''/T'/''C//100''/T'/''C//100')
WRITE(6,77) NAME1
77 FORMAT(('/T'/''C//100''/T'/''C//100''/FIL',A4)

INITIALIZE STATIN

WRITE(6,78) NAME1
78 FORMAT(('/ED'/A4//'FIL STATIN')

IF NOCR EQ 0 JUST CHANGE NAMES FOR PROGRAMS
IF NOCR NE 0 EDIT FILES TO COMPILE PROGRAMS

FRONT PROCESSOR

READ(5,115) NAME,NOCR
115 FORMAT(2A4,1X,1I)
IF(NOCR.NE.0) WRITE(6,80) NAME
80 FORMAT('/ED CRFPROC/C/FPXXX/2A4,'/1234/'FIL TCRFPROC')
IF(NOCR.NE.0) WRITE(6,120)
120 FORMAT('/CO TCRFPROC 6/'C 6//'DELETE TCRFPROC')
IF(NOCR.EQ.0) WRITE(6,800) NAME
800 FORMAT('/CN *',2A4,'FPROCESSOR')

EVAL

IF(NOPT.EQ.11.OR.NOPT.EQ.13) GO TO 860
READ(5,115) NAME,NOCR
IF(NOCR.NE.0) WRITE(6,85) NAME
85 FORMAT('/ED CREVAL/C/EVALXX/2A4,'/1234/'FIL TCREVAL')
IF((NOPT.EQ.12.OR.NOPT.EQ.22).OR.NOPT.EQ.23).AND.NOCR.NE.0)
1 WRITE(6,140)
140 FORMAT('/C 6//'CO TCREVAL/C 6//'DELETE TCREVAL')
IF(NOCR.EQ.0) WRITE(6,850) NAME
850 FORMAT('/CN *',2A4,'EVAL')

CONMIN

860 READ(5,115) NAME,NOCR
IF(NOCR.NE.0) WRITE(6,90) NAME
IF(NOCR.NE.0) WRITE(6,130)
130 FORMAT('/C 6//'CO TCRCONMIN/C 6//'DELETE TCRCONMIN')
IF(NOCR.EQ.0) WRITE(6,900) NAME
900 FORMAT('/CN *',2A4,'CONMIN')
IF(NOPT.NE.12) GO TO 960

READ(5,115) NAME,NOCR
IF(NOCR.NE.0) WRITE(6,950)
950 FORMAT('CO CRRESET 6/'C 6')
GO TO 145

TEST TO DETERMINE IF MODEL CREATED WITH DATA GENERATOR
145 IF(ICR.NE.0) CALL CRSNPT

TEST TO DETERMINE IF NONREPEATABLE PART IS TO BE DONE
IF(NR.NE.0) CALL NONRPT(NR,SPLA,INPT,USERNO,PASSW,CHARGE,
1 UFD,SUBUD,NOPT)
WRITE(6,150)
150 FORMAT('R TEMP')
CALL SRCH$(4,'INITPRC',7,2,0,ICODE)
RETURN
END

SUBROUTINE RSTRTCNOPT,NAMES)

THIS SUBROUTINE SETS UP A PROCEDURE FILE FOR RESTARTING THE PROGRAM
INTEGER*4 NAMES,NAMERS,NAMOLD
DIMENSION NAMERS(2)
CALL SRCH$(2,'RSTRTPRC',8,2,0,ICODE)
WRITE(6,10)
10 FORMAT('SAVE TEMP')
IF(NOPT.EQ.11.OR.NOPT.EQ.12.OR.NOPT.EQ.13) GO TO 20
IF(NOPT.EQ.22.OR.NOPT.EQ.23) GO TO 60

SET UP FILES FOR OPTIONS 1.1, 1.2, AND 1.3
20 WRITE(6,30)
30 FORMAT('DELETE PASS'/CN SPASS PASS')
WRITE(6,40)
40 FORMAT('DELETE CNMNIO'/CN SCNMINO CNMNIO')
WRITE(6,50)
50 FORMAT('DELETE CONREST'/CN SCONREST CONREST')
GO TO 100

C SET UP FILES FOR OPTIONS 2.2 AND 2.3

60 WRITE(6,70)
70 FORMAT('DELETE CNT'/'CN SCNT CNT')
WRITE(6,80)
80 FORMAT('DELETE BLK'/'CN SBLK BLK')
WRITE(6,90)
90 FORMAT('DELETE STARTX'/'CN SSTARTX STARTX')

C REINITIALIZE SENDPRC

100 WRITE(6,101)
101 FORMAT('DELETE TSENDPRC')
   IF(NOPT.EQ.11.OR.NOPT.EQ.12.OR.NOPT.EQ.22) WRITE(6,102)
102 FORMAT('ED SENDPRC')
   IF(NOPT.EQ.13.OR.NOPT.EQ.23) WRITE(6,103)
103 FORMAT('ED SENDPRCC')
   WRITE(6,107) NAMES
107 FORMAT('CISENDFILE/'A4,'/100'/'FIL TSENDPRC')

C REINITIALIZE STATIN

   CALL SRCH$$(1,'STATIN',6,1,0,ICODE)
   READ(5,110) NAMOLD
110 FORMAT(A4)
   CALL SRCH$$(4,'STATIN',6,1,0,ICODE)
   WRITE(6,115) NAMOLD,NAMES
115 FORMAT('CN ',A4,1X,A4)
   WRITE(6,120) NAMES
120 FORMAT('DELETE STATIN'/'ED'/A4/'FIL STATIN')
130 FORMAT('R TEMP')
   CALL SRCH$$(4,'RSTRTPRC',8,2,0,ICODE)
RETURN
END

SUBROUTINE NONRPT(NR,SPLA,INPT,USERNO,PASSW,CHARGE,UFD,SUBUFD,1 NOPT)

C CREATES PROCEDURE FILE TO SEND TO CYBER FOR NONREPEATABLE PART
C OF ANALYSIS

   INTEGER*4 NAME,INPT,SPLA,NROPT,NRRS,USERNO,CHARGE,UFD,SUBUFD,PASSW
   1 ,TNREPT
   DIMENSION NRRS(2),SPLA(2),INPT(2),NAME(2),USERNO(2),CHARGE(2)
   1 ,UFD(2),SUBUFD(2)
   CALL SRCH$$(1,'NAMENR',6,3,0,ICODE)
   WRITE(6,10)
C EDITS FILE CREATED BY DATA GENERATOR AND LOADS IN FILE CONTAINING
C PROBLEM DEPENDENT DATA
C
DIMENSION FNAME(2), LNAME(2)
INTEGER*4 NDV, LNAME, FNAME
CALL SRCH%(1, 'NAMECRRS', 6, 3, 0, ICODE)
READ IN NUMBER OF DESIGN VARIABLES

READ(5,1) NDV
1 FORMAT(I3)

READ IN NAME OF FILE CREATED BY DATA GENERATOR

READ(5,2) FNAME
2 FORMAT(2A4)
WRITE(6,3) FNAME
3 FORMAT(\'LD\'2A4/\'L JLOC\'/\'N\'/\'D\'/\'L CMD\')
WRITE(6,4)
4 FORMAT(\'D\'/\'L CMD\'/\'C/CMD/\'XQT/\'/C>5/13>\'/\'$START\'//)
NDV1 = NDV-1
IF(NDV1.EQ.0) GO TO 8
DO 7 I = 1,NDV1
WRITE(6,6)
6 FORMAT(\'L E\'/\'N-1\'/\'$END\'/\'$START\'//)
7 CONTINUE
8 WRITE(6,9)
9 FORMAT(\'L CMD\'/\'D\'/\'N-1\'/\'$END\'/\'XQT EXIT\'//\'T\')

READ IN FILE NAME CONTAINING PROBLEM DEPENDENT DATA TO BE LOADED IN AT THE TOP OF THE FILE

READ(5,2) LNAME
WRITE(6,10) LNAME
10 FORMAT(2A4)
CALL SRCH$$\'(\'NAMECRRS\',8,3,0,ICODE)
RETURN
END
SUBROUTINE UPDSF(CNT,SW,INFO)

THIS SUBROUTINE CREATES A PROCEDURE FILE (UPDTE) TO CREATE UNIQUE JOB NAMES TO SEND TO NOS

INTEGER*2 NME(2),SW
INTEGER*4 CNT,CNTM1

MODIFY STATIN

CALL SRCH$$\'(\'STATIN\',6,1,0,ICODE)
READ(5,10) NME
10 FORMAT(2A2)
CALL SRCH$$\'(\'STATIN\',6,1,0,ICODE)
CALL SRCH$$\'(\'UPDTE\',5,2,0,ICODE)
WRITE(6,20) NME,NME,CNT
20 FORMAT('SAVE TEMP\'/\'ED STATIN\'/\'N\'/\'C\'/\'2A2\'/\'2A2,13)
WRITE(6,30)
CNTM1 = CNT-1

C CHECK FOR FIRST TIME THROUGH

IF(SW.EQ.0) GO TO 41

C MODIFY SENOPRC DEPENDING UPON PASS COUNTER

IF(CNT.LT.10) WRITE(6,35) NME,CNTM1,NME,CNT
  FORMAT('ED TSENDPRC'/'C/',2A2,I1,'/',2A2,I1,'/100'/'T')
IF(CNT.EQ.10) WRITE(6,360) NME,CNTM1,NME,CNT
  FORMAT('ED TSENDPRC'/'C/',2A2,I2,'/',2A2,I2,'/100'/'T')
IF(CNT.GT.10.AND.CNT.LT.100) WRITE(6,36) NME,CNTM1,NME,CNT
  FORMAT('ED TSENDPRC'/'C/',2A2,I3,'/',2A2,I3,'/100'/'T')
IF(CNT.GE.100.AND.CNT.LT.1000) WRITE(6,37) NME,CNTM1,NME,CNT
  FORMAT('ED TSENDPRC'/'C/',2A2,I3,'/',2A2,I3,'/100'/'T')
WRITE(6,38) NME,CNTM1

IF(SW.NE.1) WRITE(6,39)
  FORMAT('N'/'O'/'T')
IF(SW.EQ.1) WRITE(6,40)
  FORMAT('T')
GO TO 49

WRITE(6,45) NME,NME,CNT
45 FORMAT('ED TSENDPRC'/'C/',2A2,'/',2A2,I3,'/100'/'T')
WRITE(6,50) NME,NME,NME
50 FORMAT('C/'2A2,'/99'/'FIL TSENDPRC')

C MODIFY FILE TO BE SENT TO NOS

IF(CNT.LT.10) WRITE(6,70) NME,NME,NME,CNT,INFO,NME,CNT
  FORMAT('ED '2A2,'/N'/'C/'2A2,'/2A2,I1,'/100'/'T'/
1 'C/INFO/'2A2,'/100'/'FIL ',2A2,I1)
IF(CNT.GE.10.AND.CNT.LT.100) WRITE(6,80) NME,NME,NME,CNT,INFO,NME,CNT
  FORMAT('ED '2A2,'/N'/'C/'2A2,'/2A2,I3,'/100'/'T'/
1 'C/INFO/'2A2,'/100'/'FIL ',2A2,I3)
IF(CNT.GE.100.AND.CNT.LT.1000) WRITE(6,90) NME,NME,NME,CNT,INFO,NME,CNT
  FORMAT('ED '2A2,'/N'/'C/'2A2,'/2A2,I3,'/100'/'T'/
1 'C/INFO/'2A2,'/100'/'FIL ',2A2,I3)
WRITE(6,100)
100 FORMAT('R TEMP*)

CALL SRCH$$('UPDATE',5,2,0,ICODE)
RETURN
SUBROUTINE ERRMSG(ERROR)
CALL SRCH$$ (2,'ERRFILE',72,0,ICODE)
IF (ERROR.NE.1) GO TO 15
WRITE (6,10)
10 FORMAT ('MORE THAN 999 ITERATIONS. STOP PROGRAM.')
GO TO 100
15 IF (ERROR.NE.2) GO TO 100
WRITE (6,20)
20 FORMAT ('CANNOT FIND COMET. STOP PROGRAM.')
GO TO 100
100 CALL SRCH$$ (4,'ERRFILE',72,0,ICODE)
RETURN
END

SUBROUTINE STCHEK(STAT,ICHK)
C
C THIS SUBROUTINE CHECKS STATUS UNTIL FILE IS RETURNED
FROM NOS
C
INTEGER*2 SNAME(3),RNAME(3),UFD(3),STAT
INTEGER*4 TIMER,CNTR
TIMER = 120000
CNTR = 0
C
PUT JOB TO SLEEP FOR TWO MINUTES
C
CALL SLEEP$(TIMER)
C
DETERMINE FILE NAME FOR NONREPEATABLE PART
C
IF(ICHK.EQ.0) GO TO 5
CALL SRCH$$ (1,'NRSTAT',61,0,ICODE)
READ (5,10) SNAME
CALL SRCH$$ (4,'NRSTAT',61,0,ICODE)
CALL SRCH$$ (5,'NRSTAT',61,0,ICODE)
GO TO 20
C
DETERMINE FILE NAME FOR REPEATABLE PART
C
5 CALL SRCH$$ (1,'TSTATIN',71,0,ICODE)
READ (5,10) SNAME
10 FORMAT (3A2)
CALL SRCH$$ (4,'TSTATIN',71,0,ICODE)
C
CHECK STATUS UNTIL STAT NE 0
C
20 CALL COMSTA(SNAME,RNAME,UFD,STAT)
IF (STAT.NE.0) GO TO 30
CALL SLEEP$(TIMER)
**INCREASE SLEEP PERIOD EVERY 5 ITERATIONS**

```plaintext
CNTR = CNTR+1
IF(CNTR.LT.5) GO TO 20
CNTR = 0
TIMER = TIMER*2
GO TO 20
30 RETURN
END
```

**SUBROUTINE COMSTAT(SNAME,RNAME,UFD,STAT)**

**COMSTAT -COMET STATUS. RETURNS STATUS OF FILE TRANSMITTED TO THE HOST CDC COMPUTER.**

**CALLING SEQUENCE:**

C - THREE WORD ARRAY IN CALLING PROGRAM CONTAINING NAME OF FILE SENT TO HOST. LEFT JUSTIFIED, BLANK FILL.
C - THREE WORD ARRAY IN CALLING PROGRAM WHERE NAME OF FILE RETURNED FROM HOST IS STORED. LEFT JUSTIFIED, BLANK FILL.
C - THREE WORD ARRAY IN CALLING PROGRAM WHERE UFO OF RETURNED FILE IS STORED. THE CALLER'S LOGIN UFD, OTHERWISE, COMET.

C - ONE WORD INTEGER IN CALLING PROGRAM.
- 1 = ERROR HAS OCCURRED, STATUS CANNOT BE DETERMINED.
- 0 = FILE HAS NOT BEEN RETURNED.
- 1 = FILE HAS BEEN RETURNED.

```plaintext
$INSERT SYSCOM>KEYS.F
LOGICAL NAMEQV,FOUND
DATA FOUND/.FALSE./
DATA COMUFD/'COMET'/'
DATA BLANKS/' '/
C ATTACH TO UFD COMET
CALL ATTACH(COMUFD,INTS(:100000),BLANKS,0,$900)
CALL TDOU('ATT TO COM',10)
C WRITE(1,777)STAT
```
TRY TO OPEN STATUS FILE ON UNIT 12
CALL OPRDW('STATUS',12,CODE)
IF(CODE.NE.0) GO TO 950
OPRDWT CYCLES UNTIL 'STATUS' IS UPDATED DURING RE-WRITE
CALL TNOU('OPEN STATUS',11)
SET POS TO EOF AND THEN
REWIND SO WE CAN HAVE
A VALID EOF POSITION
CALL PRWF$$K$POSN,12,LOC(0),0,10000000,RNW,CODE)
CALL PRWF$$K$RPOS,12,LOC(0),0,POS,RNW,CODE)
EOFPOS=POS
CALL PRWF$$K$POSN,12,LOC(0),0,-10000000,RNW,CODE)
CALL PRWF$$K$RPOS,12,LOC(0),0,POS,RNW,CODE)
READ A STATUS ENTRY AND LOOK FOR MATCH WITH SNAME
CALL PRWF$$K$RPOS,12,LOC(0),0,POS,RNW,CODE)
IF(CODE.NE.0) GO TO 100
IF(POS.GE.EOFPOS) GO TO 100
CALL ISAD07(12,RJDATA,30)
IF(.NOT.((NAMEQV(SNAME(1),RJDATA(1)))) GO TO 10
NAME FOUND, CHECK STATUS
CALL TNOU('FOUND NAME',10)
FOUND=.TRUE.
WRITE(1,444) RJDATA(30)
IF(RJDATA(30).LE.0)GO TO 800
444 FORMAT('RJDATA 30 = ',15)
CHECK FILE NAME FOR T$ PREFIX, IF PREFIX NOT PRESENT, AN ERROR HAS OCCURRED.
IF(RJDATA(17).NE.'T$')GO TO 800
CHECK FOR REPEATABLE NAME TCMNIO
IF(RJDATA(17).EQ.'TC'.AND.RJDATA(18).EQ.'MN'.AND.
1 RJDATA(19).EQ.'10') GO TO 19
CHECK FOR NONREPEATABLE NAME TNREPT
IF(RJDATA(17).EQ.'TN'.AND.RJDATA(18).EQ.'RE'.AND.
1 RJDATA(19).EQ.'PT') GO TO 19
GO TO 800
FILE HAS BEEN RETURNED, COPY NAME TO RNAME.
DO 20 I=1,3
RNAME(I)=RJDATA(I+16)
20 CONTINUE
C GET UFO STATUS
IF(RJDATA(30).EQ.1)GO TO 50
DO 25 I=1,3
    UFD(I)=CMUFD(I)
25 CONTINUE
GO TO 60
50 DO 55 I=1,3
    UFD(I)=RJDATA(I+6)
55 CONTINUE
60 CONTINUE
C SET RETURN STATUS TO FOUND
STAT = 1
GO TO 10
100 CONTINUE
IF(FOUND) STAT=1
CALL ATTACH(0,0,0,0,0)
CALL SEARCH(4,0,12)
RETURN
800 CONTINUE
C NAME NOT FOUND, SET STATUS AND RETURN
STAT = 0
DO 810 I=1,3
    RNAME(I)=BLANKS(I)
    UFD(I)=BLANKS(I)
810 CONTINUE
CALL TNOU('NAME NOT FOUND',14)
FOUND=.FALSE.
GO TO 100
900 CONTINUE
C CANNOT FIND COMET, SET ERROR STATUS AND RETURN
STAT = -1
GO TO 100
950 CONTINUE
C CANNOT OPEN STATUS, IF BUSY, TRY AGAIN.
CALL GETERR(ERR,1)
IF(ERR.EQ.'SI')GO TO 5
C FILE NOT FOUND MEANS NOT RETURNED YET.
CALL TNOU('CANT OPEN STATUS',17)
GO TO 900
END
C OPRDWT->OPEN READ AND WAIT
SUBROUTINE OPRDWT(NAME,UNIT,RCODE)
C
C INTEGER*2 NAME(3),UNIT,TYPE,CODE,RCODE
C
$INSERT SYS.COM>KEYS.F
DATA I/O/
RCODE=0
CALL SRCH$(K$EXIST,'T$0001',6,1,0,CODE)

IF T$0001 DOES EXIST THEN STATUS IS BEING RE-WRITTEN
SO LOOP UNTIL THRU WITH UPDATE FUNCTION

IF(CDDE.EQ.0) GO TO 999

DO 200 I=1,25 /*KEEP TRYING*/
CALL SRCH$(K$READ,NAME,6,UNIT,TYPE,CODE)
IF(CODE.EQ.0) RETURN /*SUCCESSFUL*/
IF(CODE.EQ.4.OR.CODE.EQ.5) GO TO 100
RCODE=1
RETURN

CALL SLEEP$(INTL(5000))

SLEEP FOR 5 SECONDS

CONTINUE
RCODE=1
RETURN

CALL SLEEP$(INTL(5000))
GO TO 10
END
APPENDIX B.- LISTING OF MAIN PROGRAM FOR CONMIN.

C PROGRAM CONMS1(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,
C TAPE7,TAPE8,TAPE9,TAPE10,TAPE11)
C NEW CONMIN SUBROUTINE
COMMON/CNMN1/DELFUN,DABFUN,FDCH,FDCHM,CT,CTMIN,CTL,CTLMIN,
1ALPHAX,ABOBJ1,THETA,OBJ,NDV,NCON,NSIDE,IPRINT,NFDG,NSCAL,
2LINOBJ,ITMAX,ITRM,ICNDIR,IGOTO,NAC,INFO,INFOG,ITER
COMMON/CNMN2/RDUM(50),IDUM(25)
COMMON X(20),VLB(20),VUB(20),G(200),SCAL(20),DF(20),
1A(20,100),S(20),G1(200),G2(200),B(100,100),C(100),ISC(200),
2IC(100),MS1(200)
COMMON/CONSAV/RSAV(50),ISAV(25)
DIMENSION KSC(200),SAVX(20),SAVG(200)
INTEGER*2 ICODE
C REAOC, PASSAGE)
REAOC,*) IPRINT,NDV,ITMAX,NCON,NFDG,NSIDE,ICNDIR,
1NSCAL,LINOBJ,ITRM,FDCH,FDCHM,CT,CTMIN,CTL,CTLMIN,
2THETA,PHI,DELFUN,DABFUN,JSC,N1,N2,N3,N4,N5,
3ALPHAX,ABOBJ1,IGOTO,(VLB(I),I=1,NDV),(VUB(I),I=1,NDV)
JITER = 0
MSC = 0
IF(JSC.LT.0)MSC = 1
DO 15 I = 1,NCON
ISC(I) = MSC
15 CONTINUE
IF(JSC.EQ.0.OR.JSC.EQ.-999) GO TO 13
MSC = 1
IF(JSC.LT.0)MSC = 0
IF(JSC.LT.0)JSC = JSC+1
CALL SRCH$(INTS(1), 'ISCFILE', INTS(7), INTS(4), INTS(0), ICODE)
READ(9,12) (KSC(I),I=1,JSC)
12 FORMAT(10I4)
CALL SRCH$(INTS(4), 'ISCFILE', INTS(7), INTS(4), INTS(0), ICODE)
DO 11 I = 1,JSC
ITEMP = KSC(I)
ISC(ITEMP) = MSC
11 CONTINUE
REWRITE(13,14) JITER,NDV,NCON,(ISC(I),I=1,NCON)
14 FORMAT(20I5)
READ(8,STARTX)
CALL SRCH$(INTS(1), 'STARTX', INTS(6), INTS(4), INTS(0), ICODE)
READ(8,30) NDV,(X(I),I=1,NDV)
30 FORMAT(15/(6E13.5))
CALL SRCH$(INTS(4), 'STARTX', INTS(6), INTS(4), INTS(0), ICODE)
GO TO 201
200 CONTINUE
READ(7,SAVE)
READ(7) IPRT,NDV,ITMAX,NCON,NSIDE,ICNDIR,NSCAL,NFDG,
FDCH,FDCHM,CT,CTMIN,CTL,CTMLN,THETA,PHI,NAC,DELFUN,DABFUN,
2LINOBJ,ITRM,ITER,INFOG,IGOTO,INFO,OBJ,
3RDUM,4X,DF,G,IISC,IC,A,S,G1,G2,C,MS1,B,VLB,VUB,SCAL,RSAV,ISAV,NCOUNT
5,N1,N2,N3,N4,N5,ALPHAX,ABOBJ1
REWIND 7
READ(9,LINKE)
READ(9,40) OBJ,G
40 FORMAT(E13.5/(6E13.5))
ITERSV = ITER
DO 41 I = 1,NCON
SAGV(I) = G(I)
41 CONTINUE
DO 42 I = 1,NDV
SAVX(I) = X(I)
42 CONTINUE
SAVOBJ = OBJ
SAVC = CT
SAVCTL = CTL
REWRIND 13
READ(13,14) JITER, NDV, NCON, (ISC(I), I=1, NCON)
JITER = JITER + 1
201 CONTINUE
NPASS = 2
REWRIND 11
C WRITE (10, PASSAGE)
WRITE(11, 10) NPASS
C SOLVE OPTIMIZATION
CALL CONMINC(X, VLB, VUB, G, SCAL, DF, A, S, G1, G2, B, C,
* ISC, IC, MS1, N1, N2, N3, N4, N5)
IF(JITER.EQ.0) GO TO 48
IF(JITER.EQ.1) GO TO 47
IF(JITER.EQ.ITERSV) GO TO 48
47 ITERSV = ITER
REWRIND 13
WRITE(13, 14) JITER, NDV, NCON, (ISC(I), I=1, NCON)
REWRIND 14
WRITE(14, 45) SAVOBJ, (SAVX(I), I=1, NDV), SAVCT, SAVCTL
1, (SAVG(I), I=1, NCON)
45 FORMAT(6E13.5)
C FUNCTION AND CONSTRAINT VALUES
C WRITE (7, SAVE)
48 WRITE(7) IPRINT, NDV, ITMAX, NCON, NSIDE, ICNDIR, NSCAL, NFDF,
1FDCH, FDCHM, CT, CTMIN, CTL, CTLMIN, THETA, PHI, NAC, DELFUN, DABFUN,
2LINOBJ, ITRM, ITER, INFOG, IGOTO, INFO, OBJ,
3RDU, IDUM,
4X DF, G, ISC, IC, A, S, G1, G2, C, MS1, B, VLB, VUB, SCAL, RSAV, ISAV, NCOUNT
5, N1, N2, N3, N4, N5, ALPHAX, ABOBJ1
C WRITE (9, LINKF)
REWRIND 9
WRITE(9, 50) NDV, (X(I), I=1, NDV)
50 FORMAT(15/(6E13.5))
C WRITE CONTROL CARD STORED IN PROCFII E GONOGO.
101 FORMAT(1')
IF (IGOTO.NE.0) GO TO 301
CALL SRCH$(INTS(2), 'GONOGO', INTS(6), INTS(8), INTS(0), ICODE)
WRITE(12, 101)
CALL SRCH$(INTS(4), 'GONOGO', INTS(6), INTS(8), INTS(0), ICODE)
C WRITE ON TAPE8 IF GRADIENTS ARE REQUIRED
REWIND 13
JITER = JITER + 1
WRITE(13, 14) JITER, NDV, NCON, (ISC(I), I=1, NCON)
WRITE(14, 45) OBJ, (X(I), I=1, NDV), CT, CTL, (G(I), I=1, NCON)
301 IF (INFO.NE.2) GO TO 303
CALL SRCH$(INTS(2), 'STARTX', INTS(6), INTS(8), INTS(0), ICODE)
WRITE(8, 30) NDV, (X(I), I=1, NDV)
CALL SRCH$(INTS(4), 'STARTX', INTS(6), INTS(8), INTS(0), ICODE)
303 CALL SRCH$(INTS(2), 'INFO', INTS(4), INTS(8), INTS(0), ICODE)
WRITE(8, 304) INFO
304 FORMAT(1')
CALL SRCH$(INTS(4), 'INFO', INTS(4), INTS(8), INTS(0), ICODE)
STOP
END
APPENDIX C.- LISTING OF FRONT PROCESSOR.

C PROGRAM FPFGS1(INPUT,OUTPUT,TAPE7,TAPE5=INPUT,TAPE6=OUTPUT)
C SPAR FRONT PROCESSOR READS DESIGN VARIABLES AND
C PRINTS THEM IN SPAR SECTION PROPERTY FORMAT
C FUSELAGE MADE OF ROD BEAM MEMBRANE ELEMENTS
C DIMENSION X(50)
C NAMELIST/LINKF/NDV,X
C NDV=NUMBER OF DESIGN VARIABLES
C X(NDV)=DESIGN VARIABLES
C DV'S ARE X(1)=SECTIONAL AREA OF STRINGER RODS
C X(2)=NONDIMENSIONAL AREA OF BEAM
C X(3)=THICKNESS OF MEMBRANE PANEL
READ(7,10) B10,B20,T0
10 FORMAT(3F10.3)
C READ(5,LINKF)
READ(5,15) NDV,(X(I),I=1,NDV)
15 FORMAT(I5/(6E13.5))
XIN1=1./X(1)
XIN2=1./X(2)
XIN3=1./X(3)
C WRITE E23 ELEMENTS
WRITE(6,200)
200 FORMAT(' E23 SECTION PROPERTIES')
WRITE(6,201) XIN1
201 FORMAT(' 1 ',F8.3)
C COMPUTE VALUES FOR DSY CARDS
C WRITE E21 ELEMENTS
WRITE(6,202)
202 FORMAT(' E21 SECTION PROPERTIES')
AREA0=(2.*B10+B20)*T0
AREA=AREA0*XIN2
SCALE=SQRT(AREA/AREA0)
B1=B10*SCALE
B2=B20*SCALE
T=T0*SCALE
ALPHA1=0.
C=C/AREA
EI2=2.*T*B1**3/12.+2.*T*B1*(B1/2.-C)**2
ALPHA2=0
F1=0.
Z2=0.
THETA=0.
Q1=0.
Q2=0.
Q3=0.
Y11=-(B1-C)
Y12=5*B2+T
Y21=C
Y22=5*B2+T
Y31=C
Y32=-(5*B2+T)
Y41=-(B1-C)
Y42=-(5*B2+T)
J=1
WRITE(6,103) J,EI1,ALPHA1,EI2,ALPHA2,AREA
WRITE(6,1003) F,F1,Z1,Z2,THETA
103 FORMAT(9DSY',Y2,5F12.4,' THETA')
1003 FORMAT(1X,5F13.5)
WRITE(6,104) Q1,Q2,Q3,Y11,Y12,Y21
104 FORMAT(1X,6F12.4,'')
WRITE(6,1004) Y22,Y31,Y32,Y41,Y42
1004 FORMAT(1X,5F12.4)
C WRITE E41 ELEMENTS
WRITE(6,300) XIN3
300 FORMAT('& SHELL SECTION PROPERTIES*/ 1',F8.3)
WRITE(6,301)
301 FORMAT('&')
STOP
END
APPENDIX D.- LISTING OF END PROCESSOR.

PROGRAM EPFSUS(INPUT, OUTPUT, TAPE8, TAPE5=INPUT, TAPE6=OUTPUT)
DIMENSION A(4500), B(1400)
DIMENSION A1(400), B1(400), C1(400)
DIMENSION G(400)
NAMELIST/EPIN/E23AL, E21AL, E41AL, NSE23, NSE21, NSE41
NAMELIST/LINKE/OBJ, G
READ(5, EPIN)
CALL DAL(4, 1, A(1), 0, IEA, KADR, IERR, NWDS, NE, LB, ITYPE,
14HOBJF, 3HAUS, 1, 1)
OBJ = A(1)
CALL DAL(4, 1, A(1), 0, IEA, KADR, IERR, NWDS, NE, LB, ITYPE,
14HSTRS, 3HE23, 1, 1)
I1 = 1
INL = 6 * NSE23
DO 2 IN = 6, INL, 6
I = I1
A1(IN) = A(IN)
G(IN) = ABS(A(IN)) / E23AL - 1.
I1 = I1 + 1
2 CONTINUE
CALL DAL(4, 1, A(1), 0, IEA, KADR, IERR, NWDS, NE, LB, ITYPE,
14HSTRS, 3HE21, 1, 1)
J1 = 1
KNL1 = (NSE21 - 1) * 52 + 6
DO 4 IM = 5, KNL1, 52
B1(J1) = ABS(A(IM))
A1(J1) = ABS(A(IM + 1))
I = I1 + J1 - 1
GNUM = B1(J1)
IF (A1(J1) > B1(J1)) GNUM = A1(J1)
G(IN) = GNUM / E21AL - 1.
J1 = J1 + 1
4 CONTINUE
CALL DAL(4, 1, A(1), 0, IEA, KADR, IERR, NWDS, NE, LB, ITYPE,
14HSTRS, 3HE41, 1, 1)
K1 = 1
LNLI = (NSE41 + 23)
DO 10 NP = 21, LNL1, 23
C1(K1) = A(NP)
B1(K1) = A(NP + 1)
A1(K1) = A(NP + 2)
I = I1 + J1 + K1 - 2
GNUM = SQRT(C1(K1)**2 + B1(K1)**2 - C1(K1)*B1(K1) + 3. * A1(K1)**2)
G(IN) = GNUM / E41AL - 1.
K1 = K1 + 1
10 CONTINUE
CALL FIN(0, 0)
REWIND 6
WRITE(6, LINKE)
WRITE(6, 232) OBJ, G
232 FORMAT(*BEGIN CNMNO*, *E13.5*/(6E13.5))
WRITE(6, 233)
233 FORMAT(*END CNMNO*)
STOP
END
APPENDIX E.- LISTING OF BLDELDs.

PROGRAM BLDELDs(TAPE5, TAPE23, TAPE20, TAPE21, TAPE22, OUTPUT)

C THIS PROGRAM CREATES A RUNSTREAM THAT WILL CREATE
C DMDV AND DKDV FOR PARTICULAR ELEMENTS USED DESIGN VARIABLES
C
DIMENSION EL(999), NSECT(999), TNAME1(8), TNAME2(8), FOR(9)
DIMENSION NODVPE(999)
DATA E21, E22, E23, E41, E43, E44 /3HE21, 3HE22, 3HE23, 3HE41, 3HE43, 3HE44/
DATA E31, E33 /3HE31, 3HE33/
DATA TNAME1/4HDEF, 4HGD, 4HGTIT, 4HDIR, 4HNS, 3*4HELTS/
DATA TNAME2/5*4H, 4HNAME, 4HNNOD, 4HISCT/
DATA START, END, XNSECT/4H$STA, 4H$END, 4HNSEC/
DATA YNSECT/3HNSE/

C CALL SUBROUTINE TO REMOVE BEGINNING BLANKS
C CALL REMOVE
C
READ INPUT
C NOEL=NUMBER OF ELEMENTS
C NODV=NUMBER OF DESIGN VARIABLE ELEMENTS
C VORB=TYPE OF ANALYSIS (EX. BUCKLING)
C NDF=NUMBER OF DEGREES OF FREEDOM PER JOINT
C EL=ELEMENT NAMES CONTAINING DESIGN VARIABLES
   (EX. E21)
C NSECT - LAST SECTION NUMBER USED FOR EACH DESIGN VARIABLE
C NODVPE - NUMBER OF DESIGN VARIABLES PER ELEMENT

READ(5,5) NOLC, NODV, ISNOLC, JOINTS, NDF, NOEL, VORB
5 FORMAT(6(I1X, I4), 1X, A4)
READ(5,6) (EL(I), NSECT(I), NODVPE(I), I=1, NOEL)
6 FORMAT(6(I1X, A3, 1X, I3, 1X, I3))
NDF = NDF * NDF
WRITE(20,2)
2 FORMAT(*XQT TAB/** UPDATE=1*)

C LOOP ON NUMBER OF ELEMENTS
DO 30 I = 1, NOEL

C CALL SUBROUTINE TO UPDATE TAB BY SETTING DESIGN VARIABLES TO UNITY.
KCNT RETURNS THE NUMBER OF POSSIBLE DESIGN VARIABLES FOR A PARTICULAR ELEMENT.
KCNT=99 MEANS THE ELEMENT NAME IS BAD

CALL TABNPUT(EL(I), NSECT(I), KCNT)
IF(KCNT.NE.99) GO TO 30
PRINT 29, EL(I)
29 FORMAT(* ELEMENT NAME *, A3, * DOES NOT EXIST*)
GO TO 190
30 CONTINUE

C CONCLUDE UPDATE AND SET UP DISABLES
WRITE(20,31)
31 FORMAT(* UPDATE=0*)
WRITE(20,32)
32 FORMAT(*XQT DCU/** COPY 1,2*)
DO 35 I = 1, 8
IF(I.GT.4) GO TO 33
DO 37 J = 1, NOEL
TNAME2(I) = EL(J)
WRITE(20,34) TNAME1(I), TNAME2(I)
37 CONTINUE
GO TO 35
33 WRITE(20,34) TNAME1(I), TNAME2(I)
34 FORMAT(* DISABLE 1*, A4, 1X, A4)
35 CONTINUE

C SET COUNTER FOR TOTAL NUMBER OF DESIGN VARIABLES
IELCNT = 0
ICNTDV = 1
ISW=0
ISAVCNT = 0

READ IN RUNSTREAM AND CHECK FOR START OF A DESIGN VARIABLE

39   JCNT = 0
40   READ(21,50) (FOR(J), J=1,9)
50   FORMAT(A4,A6,7A10)
     IF(EOF(21)) 170,60
60   IF(FOR(1).EQ.START) GO TO 70
    WRITE(20,50) (FOR(J), J=1,9)
    GO TO 40
70   IF(ISW.EQ.1) WRITE(20,75)
75   FORMAT(*[XQT ELD]*)
     ISW=1
     READ(21,80) (FOR(J), J=1,9)
80   FORMAT(A3,A7,7A10)

SET ICNT = NUMBER OF POSSIBLE DESIGN VARIABLES FOR AN ELEMENT

ICNT=99

DETERMINE POSSIBLE NUMBER OF DESIGN VARIABLES PER ELEMENT

IF(FOR(1).EQ.E23.OR.FOR(1).EQ.E41.OR.FOR(1).EQ.E44) ICNT=1
IF(FOR(1).EQ.E31) ICNT=1
IF(FOR(1).EQ.E21) ICNT=4
IF(FOR(1).EQ.E43.OR.FOR(1).EQ.E33) ICNT=12
IF(FOR(1).EQ.E22) ICNT=21
TNAME=FOR(1)
IF(ICNT.EQ.99) TNAME=SAVNAM
JCNT = JCNT+1
IF(ICNT.NE.99) IELCNT=IELCNT+1

SET UNIT = 20 IF ONLY ONE DESIGN VARIABLE PER ELEMENT
OTHERWISE SET UNIT = 22 (SCRATCH UNIT)

IUNIT=22
REWIND 22
IF(ICNT.EQ.1) IUNIT=20
IF(ICNT.EQ.99.AND.ISAVCNT.EQ.1) IUNIT=20

CHECK FOR REPEAT OF ELEMENT NAME

IF(ICNT.NE.99) GO TO 86
WRITE(IUNIT,85) SAVNAM
85   FORMAT(A3,77X)
    GO TO 860
C READ DATA FROM UNIT 21 AND WRITE DATA ON UNIT 20 OR 22
C DEPENDING UPON VALUE OF ICNT
C
86 WRITE(IUNIT,50) (FOR(J),J=1,9)
SAVNAME=FOR(1)
ISAVCNT=ICNT
GO TO 87
860 ICNT=ISAVCNT
GO TO 870
87 READ(21,50) (FOR(J),J=1,9)
870 IF(FOR(1).EQ.XNSECT.OR.FOR(1).EQ.YNSECT) GO TO 88
IF(FOR(1).EQ.END) GO TO 110
WRITE(IUNIT,50) (FOR(J),J=1,9)
GO TO 87
88 IP1=NSECT(IELCNT)+JCNT
WRITE(IUNIT,90) IP1
90 FORMAT(*NSECT=*,I3,71X)
100 READ(21,50) (FOR(J),J=1,9)
IF(FOR(1).EQ.END) GO TO 110
WRITE(IUNIT,50) (FOR(J),J=1,9)
GO TO 100
C
C SKIP THIS IF MORE THAN ONE DESIGN VARIABLE PER ELEMENT
C
110 IF(ICNT.NE.1) GO TO 120
C
C CALL SUBROUTINE TO CREATE REMAINDER OF RUNSTREAM
C
CALL CRRS(ICNTDV,O,O,TNAME,NDF,NODVPE(IELCNT))
ICNTDV=ICNTDV+NODVPE(IELCNT)
GO TO 39
C
C LOOP ON POSSIBLE NUMBER OF DESIGN VARIABLES PER ELEMENT
C READ FROM UNIT 22
C
WRITE ON UNIT 20
C
120 DO 160 I = 1,ICNT
IF(I.NE.1) WRITE(20,75)
REWIND 22
130 READ(22,50) (FOR(J),J=1,9)
IF(EOF(22)) 150,140
140 IF(FOR(1).EQ.XNSECT.OR.FOR(1).EQ.YNSECT) GO TO 141
WRITE(20,50) (FOR(J),J=1,9)
GO TO 130
141 WRITE(20,90) IP1
GO TO 130
C
C CALL SUBROUTINE TO CREATE REMAINDER OF RUNSTREAM
CALL CRRS(ICNTDV, ICNT, I, TNAME, NDF, NODVPE(IELCNT))
IP1 = IP1 + 1
CONTINUE
ICNTDV = ICNTDV + NODVPE(IELCNT)
GO TO 39
WRITE(20, 180)
FORMAT(* TOC 2**[XQT EXIT*)
STOP
END

SUBROUTINE TABNPUT(ELNAME, NSCT, ICNT)

THIS SUBROUTINE CREATES TAB PROCESSOR INPUT FOR A RUNSTREAM
DEPENDING UPON ELEMENTS USED.
ALL DESIGN VARIABLES ARE SET TO UNITY.
ICNT = NUMBER OF DESIGN VARIABLES FOR A PARTICULAR ELEMENT
ICNT = 99 MEANS THE ELEMENT NAME IS BAD

DIMENSION ELEMENT(21)
DATA E21, E22, E23, E41, E43, E44 / 3HE21, 3HE22, 3HE23, 3HE41, 3HE43, 3HE44 /
DATA E31, E33 / 3HE31, 3HE33 /
DATA BA, BB, BC, SA, SB / 2HBA, 2HBB, 2HBC, 2HSA, 2HSB /
IF(ELNAME.EQ.E21) ElID = BA
IF(ELNAME.EQ.E22) ElID = BB
IF(ELNAME.EQ.E23) ElID = BC
IF(ELNAME.EQ.E41 .OR. ELNAME.EQ.E43 .OR. ELNAME.EQ.E31 .OR.
1 ELNAME.EQ.E33) ElID = SA
IF(ELNAME.EQ.E44) ElID = SB
WRITE(20, 10) ElID
FORMAT(2X, A2)
ICNT = 99
IF(ELNAME.EQ.E23 .OR. ELNAME.EQ.E41 .OR. ELNAME.EQ.E44) GO TO 30
IF(ELNAME.EQ.E31) GO TO 30
IF(ELNAME.EQ.E21) GO TO 50
IF(ELNAME.EQ.E43 .OR. ELNAME.EQ.E33) GO TO 100
IF(ELNAME.EQ.E44) GO TO 150
PRINT 20, ELNAME
FORMAT(* ELEMENT NAME *, A3, * DOES NOT EXIST*)
GO TO 210

ELEMENT NAMES E23, E31, E41, E44
ICNT = 1

K = NSCT + 1
WRITE(20, 40) K
FORMAT(1X, I3, * 1.0*)
ICNT = 1
GO TO 210
C ELEMENT NAME E21
C ICNT = 4
C
50 DO 90 I = 1,4
DO 60 J = 1,10
ELEMENT(J)=0.0
60 CONTINUE
IF(I.EQ.1) ELEMENT(1)=1.0
IF(I.EQ.2) ELEMENT(3)=1.0
IF(I.EQ.3) ELEMENT(5)=1.0
IF(I.EQ.4) ELEMENT(6)=1.0
K=I+NSCT
WRITE(20,70) K,(ELEMENT(J),J=1,10)
70 FORMAT(* DSY *,I1,10(I1X,F3.1))
WRITE(20,80)
80 FORMAT(2X,11(*0.0 *))
90 CONTINUE
ICNT=4
GO TO 210
C
C ELEMENT NAMES E33 , E43
C ICNT = 12
C
100 DO 140 I = 1,12
DO 110 J = 1,12
ELEMENT(J)=0.0
110 CONTINUE
ELEMENT(1)=1.E-06
ELEMENT(3)=1.E-06
ELEMENT(4)=1.E-06
ELEMENT(6)=1.E-06
ELEMENT(7)=1.E-06
ELEMENT(9)=1.E-06
ELEMENT(12)=1.E-06
ELEMENT(I)=1.
K=I+NSCT
IF(I.EQ.1) WRITE(20,115)
115 FORMAT(* FORMAT=UNCOPLED*)
WRITE(20,120) K
120 FORMAT(2X,12,1X,9(*1.0 *))
WRITE(20,130) (ELEMENT(J),J=1,6)
130 FORMAT(1X,6(1X,E10.2))
WRITE(20,130) (ELEMENT(J),J=7,12)
140 CONTINUE
ICNT=12
GO TO 210
C
C ELEMENT NAME E22
C ICNT = 21
C
150 DO 200 I = 1,21
   DO 160 J = 1,21
      ELEMENT(J) = 0.0
   160 CONTINUE
   K = I + NSCT
   ELEMENT(I) = 1.
   WRITE (20,170) K,ELEMENT(I)
   170 FORMAT(2X,12,1X,E10.2)
   KK = 2
   DO 190 J = 2,6
      L = KK + J - 1
      WRITE (20,180) (ELEMENT(N),N=KK,L)
   180 FORMAT(ZX,6(F3.1,1X))
   KK = KK + J
   190 CONTINUE
   CONTINUE
   200 CONTINUE
   ICNT = 21
   210 RETURN
END

SUBROUTINE CRRS(ICNTDV,ICNT,J,TNAME,NOF,NODVE1)

C
C THIS SUBROUTINE CREATES REMAINDER OF RUNSTREAM TO FIND DMDV AND DKDV.
C USE NAMES
DMDV DIAG 0 I AND
DKDV SPAR 25 I
WHERE I = 1 TO NUMBER OF POSSIBLE DESIGN VARIABLES

DIMENSION BA(4), BB(21), SAE1(12), TNAME1(9), TNAME2(9)
DATA DK, DM, CK, CM, SK, SM/2HDK,2HDK,2HDK,2HDK,2HDK,2HDK,2HDK,2HDK,2HDK/  
DATA DV/2HDK/
DATA BB/2H11,2H21,2H31,2H41,2H42,2H43,2H44,2H51,2H52,2H53,2H54,2H55,2H56,2H61,2H62,2H63,2H64,2H65,2H66/
DATA SAE1/2H11,2H12,2H13,2H22,2H23,2H24,2H25,2H26,2H31,2H32,2H33,2H34,2H35,2H41,2H42,2H43,2H44,2H45,2H46,2H51,2H52,2H53,2H54,2H55,2H56,2H61,2H62,2H63,2H64,2H65,2H66/
DATA DEM/10HDEM DIAG 0/
DATA KSP/7HK SPAR /
DATA CHA/9HCHANGE 2/  
DATA COP/9HCOPY 1,2/  
DATA BA/2HIX,2HIY,2HDH,2HJO/  
DATA TNAME1/4HDEF,4HGD,4HGTIT,4HELTS,4HNS,4HKMAP,4HMAP,4HMASK,4HDIR/  
DATA TNAME2/3*4H,4HMASK,3*4H,4HEFIL,4H/  
DATA DMDV,DKDV,SPAR/4HMDV,4HDKDV,6HSPAR/  
DATA DIAG/6H DIAG/
JCNTDV = ICNTDV

C
C XQT E, EKS, TOPO, K, DCU

71
WRITE(20,10)
10 FORMAT(*\XQT E**\XQT EKS**\XQT TOPO**\XQT K**\XQT DCU*)
C
C DISABLE DATA SETS
C
DO 30 I = 1,9
IF(I.EQ.8) TNAME1(I)=TNAME
IF(I.EQ.1.OR.I.EQ.2.OR.I.EQ.3.OR.I.EQ.9) TNAME2(I)=TNAME
WRITE(20,20) TNAME1(I),TNAME2(I)
20 FORMAT(* DISABLE 1,*A4,2X,A4)
30 CONTINUE
C
C SET UP ELEMENT NAMES FOR CHANGE AND COPY STATEMENTS
C
DDV=DV
DDK=DK
DDM=DM
IF(ICNT.NE.4) GO TO 31
DDV=BA(J)
GO TO 39
31 IF(ICNT.NE.12) GO TO 32
DDK=CK
DDM=CM
DDV=SAEL(J)
GO TO 39
32 IF(ICNT.NE.21) GO TO 39
DDK=SK
DDM=SM
DDV=BB(J)
39 DO 80 IJK = 1,NODVEL
WRITE(20,40) COP,DEM
40 FORMAT(A9,A10,* O*)
WRITE(20,50) CHA,DEM,DOM,DDV,DIAG,JCNTDV
50 FORMAT(A9,A10,* O,*2A2,A6,*0 *,I3)
WRITE(20,60) COP,KSP,NDF
60 FORMAT(A9,A7,I2,* O*)
WRITE(20,70) CHA,KSP,NDF,DDK,DDV,SPAR,NDF,JCNTDV
70 FORMAT(A9,A7,I2,* O,*2A2,A6,I2,I4)
JCNTDV = JCNTDV+1
80 CONTINUE
RETURN
END
SUBROUTINE REMOVE
C
C THIS SUBROUTINE REMOVES THE LEADING BLANKS FROM EACH
C LINE IN THE RUNSTREAM.
C
DIMENSION DATIN(80)
DATA BLANK/I H/
REWIND 23
1 READ(23,2) (DATIN(I),I=1,80)
2 FORMAT(80A1)
   IF(EOF(23)) 7,3
3 IF(DATIN(1).NE.BLANK) GO TO 50
   DO 6 I = 2,80
      IF(DATIN(I).NE.BLANK) GO TO 60
   6 CONTINUE
60 L = I - 1
   K = 80 - I
   DO 4 J = 1,K
      DATIN(J) = DATIN(J+L)
   4 CONTINUE
   K = K + 1
   DO 5 J = K,80
      DATIN(J) = BLANK
   5 CONTINUE
50 WRITE(21,2) (DATIN(J),J=1,80)
   GO TO 1
7 REWIND 21
RETURN
END
APPENDIX F.- LISTING OF GRDXXXX.

PROGRAM GNGRDRS (INPUT, TAPE30, TAPE31, TAPE10, TAPE5=INPUT, OUTPUT)
C
C THIS PROGRAM CREATES A REPEATABLE SPAR RUNSTREAM
C FOR CALCULATING DERIVATIVES WITH RESPECT TO
C DESIGN VARIABLES. THE SIZE OF THE RUNSTREAM VARIES
C WITH THE NUMBER OF LOAD CASES (NOLC) AND THE
C NUMBER OF DESIGN VARIABLES (NODV).
C
C THE RUNSTREAM IS OUTPUT ON UNIT 10
C
DIMENSION EL(999), NSECT(999), NUM(8), MFORM(5), NODVPE(999)
DATA NUM/I1H1,1H2,1H3,1H4,1H5,1H6,1H7,1H8/
DATA BUCK,VIBR/4HBUCK,4HVIBR/
DATA E21,E22,E33,E43/3HE21,3HE22,3HE33,3HE43/
DATA MFORM(1)/10H(*Z11=UNIO/
DATA MFORM(4)/10H(I1,IX,Z*)/
DATA MFORM(5)/9H,I1,*)*/
DATA MFORM7/9HN(Z10,Z*)/
DATA MFORM8/5HN(Z*)/
C
C READ INPUT
C
C NOEL = NUMBER OF DIFFERENT ELEMENTS

74
C NOC = NUMBER OF LOAD CASES  
C NODV = TOTAL NUMBER OF DESIGN VARIABLES  
C ISNOLC = STARTING NUMBER FOR DERIVATIVE LOAD CASES  
C NDF = NUMBER OF DEGREES OF FREEDOM PER JOINT  
C NRB = TYPE OF ANALYSIS (EX. BUCKLING)  
C JOINTS = NUMBER OF JOINTS IN THE MODEL  
C NODVPE = NUMBER OF DESIGN VARIABLES PER ELEMENT  
C EL = NAMES OF ELEMENTS CONTAINING DESIGN VARIABLES  
(Ex. E21)  
C
READ(5,60) NOC,NODV,ISNOLC,JOINTS,NDF,NOEL,VRB  
60 FORMAT(6(I4),1X,A4)  
READ(5,61) (EL(I),NSECT(I),NODVPE(I),I=1,NOEL)  
61 FORMAT(6(I4,A3,1X,I3,1X,I3))  
ISNOLC=ISNOLC-1  
NDF=NDF*NDF  
C
Determine if there is an E21, E22, E33, or E43 element  
C
ICNTDV = 1  
DO 168 I = 1,NOEL  
JJ = NODVPE(I)  
DO 160 J = 1,JJ  
IF(EL(I).EQ.E21) GO TO 161  
IF(EL(I).EQ.E22) GO TO 163  
IF(EL(I).EQ.E43) GO TO 164  
IF(EL(I).EQ.E33) GO TO 165  
GO TO 166  
C
CALL subroutine to find DK/DV for E21 elements  
C
161 CALL DKDVE21(ICNTDV,NDF)  
GO TO 166  
C
CALL subroutine to find DK/DV for E22 elements  
C
163 CALL DKDVE22(ICNTDV,NDF)  
GO TO 166  
C
CALL subroutine to find DK/DV for E43 elements  
C
164 CALL DKDVE43(ICNTDV,NDF)  
GO TO 166  
C
CALL subroutine to find DK/DV for E33 elements  
C
165 CALL DKDVE33(ICNTDV,NDF)  
166 ICNTDV = ICNTDV+1  
160 CONTINUE
CONTINUE
IF(VORB.EQ.VIBR) GO TO 320
WRITE(10,172)
172 FORMAT(1XQT Aus*)
C
C FIND OBJECTIVE FUNCTIONS
C
162 WRITE(10,175) JOINTS
175 FORMAT(* SYSVEC;UNIT VEC/* I=1; J=1,*,I8,>; 1.0*/
1 * DEFINE UN=UNIT VEC*)
DO 200 I = 1,NODV
WRITE(10,180) I,I
180 FORMAT(* DEFINE W*,I3,=*DMV DIAG 0 *,I3)
200 CONTINUE
DO 250 I = 1,NODV
WRITE(10,220) I,I
220 FORMAT(* OBJF G*,I3,=* 1 1=XTY(Un,W*,I3,*))
250 CONTINUE
WRITE(10,260)
260 FORMAT(* IQT DCU*)
DO 300 I = 1,NODV
WRITE(10,270) I
270 FORMAT(* PRINT 1 OBJF G*,I3)
300 CONTINUE
C
C CALL SUBROUTINE TO CREATE RUNSTREAM FOR DERIVATIVE
C CALCULATION
C
C FIND APPLIED FORCES AND MOMENTS
C
WRITE(10,2)
2 FORMAT(* IQT Aus*/ OUTLIB=3*)
DO 4 I = 1,NOLC
WRITE(10,3) I,I
3 FORMAT(* DEFINE F*,I2,=*STAT DISP *,I2,1*)
4 CONTINUE
DO 6 I = 1,NODV
WRITE(10,5) I,NDF,I
5 FORMAT(* DEFINE L*,I3,=*DKV SPAR *,I2,I4)
6 CONTINUE
DO 10 I = 1,NOLC
NWNOLC=I+ISNOLC
WRITE(10,7) NWNOLC
7 FORMAT(* ALPHA; CASE TITLE *,I3)
DO 9 J = 1,NODV
WRITE(10,8) J,I,J
9 FORMAT(1X,I3,* "LOAD CASE *,I2,* DERIVATIVE 1 DESIGN VARIABLE *,
1 I3)
CONTINUE
10 CONTINUE
IF(NODV.NE.1) WRITE(10,2003)
2003 FORMAT(* OUTLIB=4*)
IF(NODV.EQ.1) WRITE(10,6006)
6006 FORMAT(* OUTLIB=3*)
DO 1010 I = 1,NOLC
NWNOLC=I+ISNOLC
DO 1005 J = 1,NODV
WRITE(10,1003) NWNOLC,J,J,I
1003 FORMAT(* APPL FORC *,I3,I3,** PRODUCT(-1.0 L*,I3,**1.0 F*,I2,**))
1005 CONTINUE
1010 CONTINUE
DO 15 I = 1,NOLC
NWNOLC=I+ISNOLC
IF(NODV.EQ.1) GO TO 50
IF(I.EQ.1) WRITE(10,2009)
2009 FORMAT(* INLIB=4**, OUTLIB=3*)
DO 13 J = 1,NODV,9
ITOP=9
ICHK=NODV-J+1
IF(ICHK.LT.9) ITOP=ICHK
DO 40 K = 1,ITOP
L=K+J-1
WRITE(10,12) K,NWNOLC,L
12 FORMAT(* DEFINE Z*,I1,**=APPL FORC *,I3,1X,I3)
40 CONTINUE
IF(ITOP.EQ.1) GO TO 41
MFORM(2)=MFORM7
IF(J.EQ.1) MFORM(2)=MFORM8
MFORM(3)=NUM(ITOP-1)
WRITE(10,MFORM) (K,K=1,ITOP)
41 IF(ITOP.EQ.1) WRITE(10,42)
42 FORMAT(*Z11=UNION(Z10 Z1)**)
WRITE(10,45)
45 FORMAT(* INLIB=3**Z12=UNION(Z11)** DEFINE Z10=Z12*/
1 * INLIB=4*)
13 CONTINUE
WRITE(10,46) NWNOLC
46 FORMAT(* APPL FORC *,I3,**=UNION(Z10)**)
15 CONTINUE
C FIND STRESS AND DISPLACEMENT DERIVATIVES
C
50 DO 32 I = 1,NOLC
WRITE(10,16) NODV
16 FORMAT(*EXQT SSOL** RESET L1=1,L2=*,I3)
NWNOLC=I+ISNOLC
WRITE(10,17) NWNOLC
SET UP RUNSTREAM FOR BUCKLING ANALYSIS

17  FORMAT(* RESET QLIB=3*,* RESET SET=*,I3)
    WRITE(10,18)
18  FORMAT(*[XQT VPRT=*/ LIB=3*)
    WRITE(10,19) NWNOLC
19  FORMAT(* PRINT APPL FORC *,I3)
    WRITE(10,20) NWNOLC
20  FORMAT(* PRINT STAT DISP *,I3)
    IF(VORB.EQ.BUCK) GO TO 400
    WRITE(10,21) NODE
21  FORMAT(*[XQT GSF=*/ RESET L1=1,L2=*,I3/* RESET QLIB=3*)
    WRITE(10,22) NWNOLC
22  FORMAT(* RESET SET=*,I3)
    WRITE(10,23) NODE
23  FORMAT(*[XQT PSF=*/ RESET L1=1,L2=*,I3/* RESET QLIB=3*)
    WRITE(10,24) NWNOLC
24  FORMAT(* RESET SET=*,I3)
    GO TO 25

C
C SET UP RUNSTREAM FOR BUCKLING ANALYSIS
C
400  IDV = 0
    DO 470 J = 1,NOEL
      NODEV = NODEV(J)
    DO 460 K = 1,NODEV
      IDV = IDV+1
      WRITE(10,425)
425  FORMAT(*[XQT GSF=*/ RESET EMBED=1*)
      WRITE(10,430) IDV, IDV, NWNOLC
430  FORMAT(* RESET L1=*,I3,* L2=*,I3,* SET=*,I3,* QLIB=3*)
      WRITE(10,435)
435  FORMAT(*[XQT PSF=*)
      WRITE(10,430) IDV, IDV, NWNOLC
      WRITE(10,440)
440  FORMAT(*[XQT KG*]
      WRITE(10,445)
445  FORMAT(*[XQT DCU*]
      WRITE(10,450) NDF, NDF, IDV
450  FORMAT(* CHANGE 1,KG SPAR *,I3,* 0,DKG SPAR *,I3,I4)
      WRITE(10,455) NDF, IDV
455  FORMAT(* COPY 1,3 DKG SPAR *,I3,I4)
460  CONTINUE
470  CONTINUE
25  WRITE(10,251)
251  FORMAT(*[XQT DCU*]
      WRITE(10,26) NWNOLC, NWNOLC
26  FORMAT(* CHANGE 3,STAT DISP *,I3,* 1,ODIS DISP *,I3,* 1*)

C
C CHANGE DATA SET NAMES
C
IDV=0
DO 31 J=1,NOEL
NOSECT = NSECT(J)
NODVEL = NODVPE(J)
DO 30 K=1,NODVEL
DO 271 LL = 1,NOSECT
   IDV=IDV+1
   DO 27 KK = 1,NOEL
       IF(EL(KK).EQ.E21) GO TO 29
       IF(EL(KK).EQ.E22) GO TO 29
       IF(EL(KK).EQ.E43) GO TO 29
       IF(EL(KK).EQ.E33) GO TO 29
       WRITE(10,28) EL(KK),NWNOLC,IDV,EL(KK),NWNOLC,IDV
   28 FORMAT(* CHANGE 3,STRS *,A3,2I4,*,DSTR *,A3,2I4)
   WRITE(10,285) EL(KK),NWNOLC,IDV
   285 FORMAT(* COPY 3,4 DSTR *,A3,2I4)
   GO TO 27
C
C STORE BEAM CROSS DERIVATIVES
C
   29 WRITE(10,290) EL(KK),NWNOLC,IDV,EL(KK),NWNOLC,IDV
   290 FORMAT(* CHANGE 3,STRS *,A3,2I4,*,DFAM *,A3,2I4)
   WRITE(10,292) EL(KK),NWNOLC,IDV
   292 FORMAT(* COPY 3,4 DFAM *,A3,2I4)
   27 CONTINUE
   271 CONTINUE
   30 CONTINUE
   31 CONTINUE
   32 CONTINUE
   320 IF(VORB.EQ.WIBR) WRITE(10,260)
   DO 333 I = 1,NODV
   WRITE(10,332) I
   332 FORMAT(* COPY 1,4 OBJF G*,I3)
   333 CONTINUE
   WRITE(10,33)
   33 FORMAT(* TOC 3** TOC 1** TOC 4**[XQT EXIT]*)
STOP
END
APPENDIX G.- LISTING OF DRVXXXX.

PROGRAM DRVSTRS(INPUT=65,TAPE30,TAPE31,TAPE5=INPUT 1 ,TAPE15,TAPE16,OUTPUT=65,TAPE6=OUTPUT)
C
C THIS PROGRAM COMPUTES THE STRESSES AND STRESS DERIVATIVES
FOR SPAR BEAM ELEMENTS USING SPAR LIBRARIES AS INPUT.
C
THE STRESSES ARE COMPUTED FROM SPARLA USING DATA SET
FAMS MASK I 1 WHERE I = 1 TO NOLC
THE STRESSES ARE WRITTEN BACK ONTO SPARLA USING DATA SET
STRS MASK I 1 WHERE I = 1 TO NOLC
C
THE STRESS DERIVATIVES ARE COMPUTED FROM SPARLC USING DATA SET
OFAM MASK I J WHERE I = ISTRTLc TO ISTRTLc+NOLC AND J = 1 TO NODV
THE STRESS DERIVATIVES ARE WRITTEN BACK ONTO SPARLC USING DATA SET
DSTR MASK I J WHERE I = ISTRTLc TO ISTRTLc+NOLC AND J = 1 TO NODV
C
COMMON KORE,KEVEN,Z(1)
DIMENSION NAME1(2),NAME2(2),EL(999),NODVPE(999)
DATA E21,E22,E33,E43/3HE21,3HE22,3HE33,3HE43/
DATA NAME1/4HFAMS,4HDFAM/
DATA NAME2/4HSTRS,4HDSTR/
C
READ INPUT VALUES
C
NOEL IS THE NUMBER OF DIFFERENT ELEMENTS
NDF IS THE DEGREES OF FREEDOM PER JOINT
VORB IS THE TYPE OF ANALYSIS (EX. BUCKLING)
JOINTS IS THE NUMBER OF JOINTS IN THE MODEL
NOLC IS THE NUMBER OF LOAD CASES
NODV IS THE NUMBER OF DESIGN VARIABLES
ISTRTLc IS THE STARTING NUMBER FOR THE DERIVATIVE LOAD CASES
EL = NAMES OF ELEMENTS USED AS DESIGN VARIABLES
(EX. E21)

READ(5,1) NOLC, NODV, ISNOLC, JOINTS, NDF, NOEL, VORB
1 FORMAT(6(X,I4),1X,A4)
READ(5,2) (EL(I), NSECT, NODVPE(I), I=1, NOEL)
2 FORMAT(6(X,A3,1X,I3,1X,I3))
ISTRLC=ISNOLC-1
CALL RSET(IL,0,0)

LOOP ON THE NUMBER OF LOAD CASES
DO 4 NCNTLC = 1, NOLC

LOOP ON NUMBER OF ELEMENTS
DO 10 ISTRS = 1, NOEL

CHECK FOR E21, E22, E33, E43 ELEMENT
IF(EL(ISTR).EQ.E21 .OR. EL(ISTR).EQ.E43 .OR.
1 EL(ISTR).EQ.E22 .OR. EL(ISTR).EQ.E33) GO TO 9
GO TO 10
9 NODVEL = NODVPE(ISTR)

SET NUMBER OF STRESS OR STRESS DERIVATIVES TO BE WRITTEN
IF(EL(ISTR).EQ.E21 .OR. EL(ISTR).EQ.E22) IWRDCNT = 8
IF(EL(ISTR).EQ.E43 .OR. EL(ISTR).EQ.E33) IWRDCNT = 4

LOOP ON NUMBER OF DESIGN VARIABLES PER ELEMENT
DO 90 JK = 1, NODVEL
REWIND 15
REWIND 16

READ FAMS MASK FROM SPARLA AND COMPUTE STRS MASK
CALL RDATSET(4, NAME1(1), NCNTLC, 1, NE1, 1, 0, EL(ISTR))
REWIND 15
REWIND 16

CALL SUBROUTINE TO WRITE STRESSES ON SPAR LIBRARY

WRITE STRS MASK ON SPARLA
CALL WRTDATA(4, NAME2(1), NCNTLC, 1, NE1, EL(ISTR), IWRDCNT)
90 CONTINUE
10 CONTINUE
ICNTDV = 1

C LOOP ON NUMBER OF ELEMENTS
DO 3 ISTRS=1,NOEL
   IF(EL(ISTR).EQ.E21.0R.EL(ISTR).EQ.E43.0R.
      1 EL(ISTR).EQ.E22.0R.EL(ISTR).EQ.E33) GO TO 19
   GO TO 3
19 DO 30 ICNTDV = 1,NODV
   IBEAM = 0
   NODVEL = NODVPE(ICNTDV)

C SET SWITCH FOR BEAM ELEMENT
   IF(EL(ICNTDV).EQ.E21.0R.EL(ICNTDV).EQ.E22) IBEAM = 1
   N3 = NCNTLC + ISTPTLC

C SET NUMBER OF STRESSES AND STRESS DERIVATIVES TO BE WRITTEN
   IF(EL(ICNTDV).EQ.E21) IWRDCNT = 8
   IF(EL(ICNTDV).EQ.E43) IWRDCNT = 4

C LOOP ON NUMBER OF DESIGN VARIABLES PER ELEMENT
DO 20 JK = 1,NODVEL
C READ DFAM MASK FROM SPARLC AND COMPUTE DSTR MASK
   REWIND 15
   CALL RDATSET(4,NAME1(2),N3,ICNTDV,NE1,0,IBEAM,EL(ISTR))
   REWIND 15
C WRITE DSTR MASK ON SPARLC
   CALL WRTDATA(4,NAME2(2),N3,ICNTDV,NE1,EL(ISTR),IWRDCNT)
20 CONTINUE
30 CONTINUE
4 CONTINUE
   CALL FIN(0,0)
STOP
END

SUBROUTINE WRTDATA(NU,N1,N3,ISTR,S,NE1,X2,IWRDCNT)

C SUBROUTINE TO WRITE STRESS AND STRESS DERIVATIVE DATA SETS BACK INTO SPAR LIBRARIES
C COMMON KORE,KEVEN,Z(1)
SET UP BLOCK SIZES
IF NW03 GT OPEN CORE SIZE, USE MORE THAN ONE BLOCK

NW03 = NE1 * IWRDCNT
LB3 = NW03
IF (NW03 .LT. KORE) GO TO 61
LB3 = NW03 / 2

ISW = 0
IF (NW03 .LT. KORE) ISW = 1
CALL DAL (NU, 0, Z(1), KORE, 1, KADR3, IERR, NW03, NE1, LB3, -1,
I N1, X2, N3, ISTRS)

I1 = 1
I2 = I1 + IWRDCNT - 1
IF (I2 .GT. LB3) GO TO 66

READ STRESSES OR STRESS DERIVATIVES OFF UNIT 15

READ (15) (Z(I), I = I1, I2)
IF (EOF (15)) 66, 65

I1 = I1 + IWRDCNT
GO TO 63

WRITE STRESSES OR STRESS DERIVATIVES ONTO SPAR LIBRARY

CALL RIO (NU, 10, 2, KADR3, Z(1), LB3)
IF (ISW .EQ. 1) GO TO 67
ISW = 1
LB3 = NW03 - LB3
GO TO 62

RETURN
END
SUBROUTINE RDATSET (NU, N1, N3, ISTRS, NE1, ISW, I3, IBEAM, X2)

SUBROUTINE TO READ SPAR LIBRARY, STORE DATA, AND COMPUTE STRESSES OR STRESS DERIVATIVES

COMMON KORE, KEVER, Z(1)
DATA E21, E22, E33, E43, H21, H22, H33, H43/

SET UP BLOCK SIZE

CALL DAL (NU, 10, Z(1), KORE, 1, KADR1, IERR, NW01, NE1, LB1, ITYPE, N1,
X2, N3, ISTRS)
N11 = LB1 / NE1
KCNT = 0
NBLK1 = NW01 / LB1
IF (NBLK1 .LE. NE, NW01) NBLK1 = NBLK1 + 1
DO 6 J = 1, NBLK1
NBL1 = LB1
IF (J .EQ. NBLK1) NLB1 = NW01 - (NBLK1 - 1) * LB1

READ DATA FROM SPAR LIBRARY

CALL RIO (NU, 20, 2, KADR1, Z(1), NLB1)
DO 30 JCNT = 1, NLB1, N11
KCNT = KCNT + 1

CALL SUBROUTINE TO COMPUTE STRESSES AND STRESS DERIVATIVES

IF (X2 .EQ. E21 .OR. X2 .EQ. E22) CALL BMSTRS (ISW, KCNT, JCNT, IBEAM)
IF (X2 .EQ. E43 .OR. X2 .EQ. E33) CALL PLTSTRS (ISW, KCNT, JCNT)
30 CONTINUE
6 CONTINUE
RETURN
END
APPENDIX H - LISTING OF DKDVE21.

SUBROUTINE DKDVE21(NDVJIM, NDF)
DIMENSION X(20)
NAMELIST/LINKF/NDV, X

THIS SUBROUTINE CREATES A SPAR RUNSTREAM TO CALCULATE

\[
\begin{align*}
\text{DK} & \quad \text{DK} & \quad \text{DA} & \quad \text{DK} & \quad \text{DI} & \quad \text{DK} & \quad \text{DI} & \quad \text{DK} & \quad \text{DJ} & \quad X & \quad Y & \quad 0 \\
\text{DV} & \quad \text{DA} & \quad \text{DV} & \quad \text{DI} & \quad \text{DV} & \quad \text{DI} & \quad \text{DV} & \quad \text{DJ} & \quad \text{DV} & I & I & X & I & Y & I & O & I \\
\text{DM} & \quad \text{DM} & \quad \text{DA} & \quad \text{DM} & \quad \text{DI} & \quad \text{DM} & \quad \text{DI} & \quad \text{DM} & \quad \text{DJ} & \quad X & \quad Y & \quad 0 \\
\text{DV} & \quad \text{DA} & \quad \text{DV} & \quad \text{DI} & \quad \text{DV} & \quad \text{DI} & \quad \text{DV} & \quad \text{DJ} & \quad \text{DV} & I & I & X & I & Y & I & O & I
\end{align*}
\]

\[\text{WRITE}(10,1)\]
1 FORMAT(*,[XQT AUS*)
WRITE(10,3)NDF, NDVJIM, NDF, NDVJIM
3 FORMAT(* DEFINE A1=DKDA SPAR *, I2, I4 /* DEFINE A2=DKIX*
1 * SPAR *, I2, I4)
WRITE(10,4)NDF, NDVJIM, NDF, NDVJIM
4 FORMAT(* DEFINE A3=DKY SPAR *, I2, I4 /* DEFINE A4=DKJO*
1 * SPAR *, I2, I4)
WRITE(10,203)NDVJIM, NDVJIM
203 FORMAT(* DEFINE B1=DMDA DIAG O *, I3 /* DEFINE B2=DMIX*
1 * DIAG O *, I3)
WRITE(10,204)NDVJIM, NDVJIM
204 FORMAT(* DEFINE B3=DMY DIAG C *, I3 /* DEFINE B4=DMJO*
1 * DIAG O *, I3)

COMPUTE DA/DV
DADV = 1.

READ IN AND SET UP INITIALIZATION VALUES
READ IN CONSTANTS FROM UNIT 30
READ(30,5) B10, B20, TO
5 FORMAT(3F10.3)

READ IN DESIGN VARIABLES FROM UNIT 31
READ(31, LINKF)
AREAO = (2. * B10 + B20) * TO
AREA = AREAO / X(2)
SCALE = SQRT(AREA / AREAO)
B1 = B10 * SCALE
B2 = B20 * SCALE
T = TO * SCALE
FTR = 0.5 / SQRT(AREA * AREAO)
C = C / AREA

C COMPUTE FACTORS FOR DII/DV, DI2/DV, DJ0/DV

DB1DV = B10 * FTR
DB2DV = B20 * FTR
DTDV = TO * FTR
DCDB2 = (B1 ** 2 - 2 / (B1 - T) * (B1 + T) / 2 - C * T) / AREA
DCDT = (B1 ** 2 + 2 * B2 * T - C * (2 * B1 + B2)) / AREA

DI2DB1 = (T * B1) ** 2 / 2. + (2. * T * (B1 - T) * (C - T)) ** 2 +
1 (4 * T * B1 * (B1 / 2 - C) * (1 - B2IB1)) +
2 (2 * B2 * T * (C - T / 2)) * DCDT

DI2DB2 = (-4 * T * B1 * (B1 / 2 - C) * DCDT) * (T ** 3 / 12. +
1 (T * (C - T / 2)) ** 2 + (2 * B2 * T * (C - T / 2)) * DCDT)

DI2DT = (B1 ** 3 / 6.) + (2 * B1 * (B1 / 2 - C) ** 2) -
1 (4 * T * B1 * (B1 / 2 - C) * DCDT) + (2 * T ** 2 / 4) +
2 (B2 * (C - T / 2)) ** 2 + (2 * B2 * T * (C - T / 2)) * (DCDT - 5))

DJ0DB1 = 2 * T ** 3 / 3.
DJ0DB2 = T ** 3 / 3.
DJ0DT = (2 * B1 + B2) * T ** 2

C COMPUTE DII/DV, DI2/DV, DJ0/DV

DII/DV = DII*DB1 * DB1DV + DII*DB2 * DB2DV + DII*DT * DTDV
DI2/DV = DI2DB1 * DB1DV + DI2DB2 * DB2DV + DI2DT * DTDV
DJ0/DV = DJ0DB1 * DB1DV + DJ0DB2 * DB2DV + DJ0DT * DTDV

C CREATE RUNSTREAM TO FIND DK/DV

WRITE(10, 106) OADV, DII/DV
WRITE(10, 107) OADV, DJ0/DV
WRITE(10, 108) NDF, NDVJIM
108 FORMAT(* DKDV SPAR *, I2, I4, *= SUM(S1, S2))

C CREATE RUNSTREAM TO FIND DM/DV

WRITE(10, 206) OADV, DII/DV
WRITE(10, 207) OADV, DJ0/DV
WRITE(10, 208) NDVJIM
208 FORMAT(* DMDV DIAG O*, I3, *= SUM(T1, T2))
WRITE(10, 209)
209 FORMAT(* [XQT DCU/** TOC 1]*)
RETURN
END
APPENDIX 1.- LISTING OF BMSTRS.

SUBROUTINE BMSTRS(ISW,KCNT,JCNT,IBEAM)
COMMON KORE,KEVEN,Z(1)
DIMENSION DY1DV(4),DY2DV(4),Y(4,2),S(8),F3(2),XM1(2),XM2(2)
DIMENSION X(20)
NAMELIST/LINKF/NDV,X
JM1 = JCNT-1
C
C STORE FORCES AND MOMENTS IF ISTRS EQ 1
C STORE DERIVATIVES OF FORCES AND MOMENTS IF ISTRS EQ 2
C
F3(1)=-Z(JM1+13)
XM1(1)=-Z(JM1+14)
XM2(1)=-Z(JM1+15)
F3(2)=Z(JM1+19)
XM1(2)=Z(JM1+20)
XM2(2)=Z(JM1+21)
IF(KCNT.NE.1) GO TO 31
IF(ISW.NE.1) GO TO 31
C
C STORE AREA, MOMENTS OF INERTIA, AND Y VALUES IF FIRST TIME THROUGH
C
XI1=Z(JM1+25)
XI2=Z(JM1+27)
ICNT=38
DO 3 K = 1,4
DO 2 L = 1,2
ICNT=ICNT+1
Y(K,L)=Z(JM1+ICNT)
2 CONTINUE
3 CONTINUE
C
C FIND DERIVATIVE OF Y VALUES IF NEEDED
C
C
C READ IN CONSTANT NUMBERS FROM UNIT 30
C
READ(30,10) B10,B20,TO
10 FORMAT(3F10.3)
C
C READ IN DESIGN VARIABLES FROM UNIT 31
C
READ(31,LINKF)
C
C CALCULATE DY/DV
C
AO=(2.*B10+B20)*TO
A=AO/X(2)
SCALE=SQRT(A/AO)
B1=B10*SCALE
B2=B20*SCALE
T=TO*SCALE
FTR=0.5/SQRT(A/AO)
C=(B2+2.*T)*B1**2/2.-82*(B1-T)*(B1+T)/2.
C=C/A
DB1DV=B10*FTR
DB2DV=B20*FTR
DTDV=TO*FTR
DDB1=(B1*(B2+2.*T)-B2*B1-2.*C*T)/A
DDB2=(B1**2/2.-B1-T)*(B1+T)/2.-C*T)/A
DC2T=(B1**2+B2*T-C*(2.*B1+B2))/A
DCDV=(DDB1*DB1DV)+(DDB2*DB2DV)+(DC2T*DTDV)
DY1DV(1)=DB1DV+DCDV
DY1DV(2)=DCDV
DY1DV(3)=DCDV
DY1DV(4)=DY1DV(1)
DY2DV(1)=.5*DB2DV+DTDV
DY2DV(2)=DY2DV(1)
DY2DV(3)=DY2DV(1)
DY2DV(4)=DY2DV(3)
31 ICNT=0
DO 200 II = 1,2
DO 100 I = 1,4
ICNT=ICNT+1
C
C COMPUTE STRESSES OR STRESS DERIVATIVES
C
S(ICNT)=(F3(II)/A)+((XM1(II)/XI1)*Y(I,2))-(XM2(II)/XI2)
1 *Y(I,1))
C
C IF AREA OF BEAM IS A CONTRIBUTING FACTOR TO STRESS
C DERIVATIVES AND ISTRS EQ 1 THEN CALCULATE THE FACTOR
C AND STORE ON UNIT 16
C
IF(ISW,NE.1) GO TO 95
DFAC=(((XM1(II)/XI1)*DY2DV(I))-((XM2(II)/XI2)*DY1DV(I))
WRITE(16) DFAC
GO TO 100
C
IF AREA OF BEAM IS A CONTRIBUTING FACTOR TO STRESS
C DERIVATIVES AND ISTRS EQ 2 THEN READ FACTOR OFF UNIT 16
C AND ADD IT TO STRESS DERIVATIVE
C
95 IF(IBEAM.EQ.0) GO TO 100
READ(16) DFAC
S(ICNT)=S(ICNT)+DFAC
100 CONTINUE
200 CONTINUE
C
WRITE STRESSES ON UNIT 15
C
WRITE(15) S
RETURN
END
An Implementation of the Distributed Programing Structural Synthesis System (PROSSS)

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This distributed implementation of the PROgraming Structural Synthesis System (PROSSS) combines a general purpose finite-element computer program for structural analysis, a state-of-the-art optimization program, and several user-supplied, problem-dependent computer programs. The results are flexibility of the optimization procedure organization and versatility of the formulation of constraints and design variables. The analysis-optimization process results in a minimized objective function, typically the mass. The analysis and optimization programs are executed repeatedly by looping through the system until the process is stopped by a user-defined termination criterion. However, some of the analysis, such as model definition, need only be one time and the results are saved for future use. The user must write some small, simple FORTRAN programs to interface between the analysis and optimization programs. One of these programs, the front processor, converts the design variables output from the optimizer into a suitable format for input into the analyzer. Another, the end processor, retrieves the behavior variables and, optionally, their gradients from the analysis program and evaluates the objective function and constraints and optionally their gradients. These quantities are output in a format suitable for input into the optimizer. These user-supplied programs are problem-dependent because they depend primarily upon which finite elements are being used in the model. The analysis and end processor programs are always executed on the mainframe computer because the CPU on the mainframe is much faster than that of the minicomputer. The optimization and front processor programs are always executed on the minicomputer because the optimizer requires a significant memory allocation and the minicomputer has virtual memory.

Optimization, Distributed Processing, Finite-Element Analysis, Minicomputer

Available: NASA's Industrial Applications Centers