Local Strain Redistribution
Corrections for a Simplified
Inelastic Analysis Procedure
Based on an Elastic
Finite-Element Analysis

Albert Kaufman
and Shoi Y. Hwang

TECHNICAL REPORTS
FILE COPY
Local Strain Redistribution Corrections for a Simplified Inelastic Analysis Procedure Based on an Elastic Finite-Element Analysis

Albert Kaufman  
_Lewis Research Center_  
_Cleveland, Ohio_

Shoi Y. Hwang  
_South Carolina State College_  
_Orangeburg, South Carolina_
Summary

Nonlinear finite-element computer programs are too costly to use in the early design stages for hot-section components of aircraft gas-turbine engines. To improve the durability of these components, it is necessary to develop simpler and more economical methods for representing the structural response of materials under cyclic loading. Programs have been under way at the NASA Lewis Research Center to develop simplified procedures for performing nonlinear structural analysis using only an elastic finite-element solution or strain-gauge data as input.

Development of the simplified method was based on the assumption that the inelastic regions in the structure are constrained by the surrounding elastic material. This implies that the total strain history can be defined by an elastic analysis. Initial development of the method did not account for any strain redistribution. A computer program (ANSYMP) was created to predict the stress-strain history at the critical fatigue location of a thermomechanically cycled structure from elastic input data. Appropriate material, stress-strain and creep properties, and plasticity hardening models were incorporated into the program. Effective stresses and equivalent plastic strains are approximated by an iterative and incremental solution procedure. Creep effects can be obtained on the basis of stress relaxation at constant strain, cumulative creep at constant stress, or a combination of stress relaxation and creep accumulation.

The simplified procedure predicts the critical location of stress-strain response with reasonable accuracy relative to nonlinear finite-element analyses for thermally cycled problems. However, the limitation of no strain redistribution is most likely to be violated in the case of mechanically loaded structures, especially in the vicinity of stress concentrations. Nonlinear finite-element analyses of notched-plate specimens subjected to cyclic mechanical loading have shown that the total strain range at the critical location can be significantly larger than would be predicted from elastic solutions.

This study derived and incorporated corrections in the simplified procedure to account for local total strain redistribution and residual stresses due to mechanical load cycling. These corrections would remove some of the limitations and extend the applicability of the procedure. The corrections were based on the Neuber rule relating the theoretical stress concentration factor to the actual stress and strain concentration factors.

Two variations of a benchmark notched-plate problem were analytically examined to verify the accuracy of the improved simplified method. Verification was made through comparison with three-dimensional nonlinear, finite-element analyses. Cyclic stress-strain and creep properties for Inconel 718 alloy, a kinematic hardening model, and the von Mises yield criterion were used for the benchmark notched-specimen problems. Elastic and elastic-plastic finite-element analyses were performed by using the MARC nonlinear finite-element computer code. The elastic solutions for the critical locations were used as input data for the simplified analysis computer code. The stress-strain histories at the critical locations from the simplified and nonlinear finite-element analyses were compared.

The comparisons demonstrated that the improved simplified method can duplicate the cyclic stress-strain hysteresis loops from the MARC elastic-plastic analyses to a high degree of accuracy. For the benchmark problem, ANSYMP used 0.3 percent of the central processor unit time required by MARC to compute the inelastic solution.

Introduction

The severe operating conditions in advanced aircraft gas-turbine engines have subjected hot-section components such as turbine blades and combustor liners to thermomechanical load cycles that induce repeated inelastic strains and eventual fatigue cracking. Life prediction and improvements in the durability of these components require accurate knowledge of the temperature stress-strain history at the critical crack initiation location of the structure.

Nonlinear finite-element computer codes are increasingly being used for calculating inelastic structural response. However, nonlinear finite-element analysis is not generally feasible for use as a component design tool because of the high computing costs associated with the iterative and incremental nature of the inelastic solutions. Computing costs are further increased by the presence of high thermal gradients and geometric irregularities, such
as cooling holes. Most hot-section components are of such geometric complexity as to necessitate three-dimensional analyses, frequently with substructuring. Three-dimensional, nonlinear finite-element analyses are prohibitively time consuming and expensive to conduct in the early design stages for combustor and turbine structures. To improve the design of hot-section components, it is necessary to develop simpler and more economical methods for representing structural behavior under cyclic loading.

The initial development of a simplified analytical procedure for estimating the stress-strain history of a thermomechanically loaded structure subject to cyclic inelasticity was implemented in a computer program (ANSYMP) (refs. 1 to 3). This procedure predicts the stress-strain history at the critical location for crack initiation by using as input the total strain history calculated from elastic finite-element analyses. An incremental and iterative procedure estimates the plastic strains from the material stress-strain properties and a plasticity hardening model. Creep is incorporated in the program through options which permit the calculation of stress relaxation at constant strain, creep at constant stress, or a combination of stress relaxation and creep accumulation.

Analytical predictions from the simplified method for a number of problems were compared in references 1 to 3 with nonlinear finite-element solutions from the MARC computer program (ref. 4). These problems involved uniaxial- and multiaxial-stress states, isothermal and nonisothermal conditions, and various materials and plasticity hardening models. The problems included an Inconel 718 benchmark notched specimen that was mechanically load cycled in an experiment to verify structural analysis methods (ref. 5). In these analyses the predicted stress-strain response from the simplified procedure was in good agreement with the MARC solution for the thermally cycled problems but was truncated for the benchmark notch problem. This disparity in the latter case was due to strain redistribution under mechanical load cycling which resulted in a much larger total strain range than was predicted from the elastic finite-element analysis.

In the present study, the simplified method was further developed to consider strain redistribution effects from plastic strain reversal under mechanical load cycling. Corrections were derived to account for the redistribution of local total strains due to plastic yielding and residual strains during load reversal. These corrections were incorporated into a version of the ANSYMP elastic-plastic-creep program. The improved procedure was applied to the benchmark notch problem. Cyclic stress-strain properties for Inconel 718 alloy, a kinematic hardening model, and the von Mises yield criterion were used for these analyses. Elastic and elastic-plastic finite-element analyses were performed by using the MARC nonlinear finite-element computer code. The elastic solution at the critical location was used as the total strain history input for the simplified analysis computer code. The improved simplified procedure was verified on the basis of how well it was able to duplicate the stress-strain hysteresis loops from the MARC elastic-plastic analyses of the benchmark notch problem.

Symbols

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$E$</td>
<td>modulus of elasticity</td>
</tr>
<tr>
<td>$E_e$</td>
<td>modified modulus of elasticity</td>
</tr>
<tr>
<td>$E_p$</td>
<td>work hardening slope (fig. 1)</td>
</tr>
<tr>
<td>$e$</td>
<td>nominal total strain at net section</td>
</tr>
<tr>
<td>$K, n$</td>
<td>temperature-dependent constants in cyclic stress-strain equation</td>
</tr>
<tr>
<td>$K_i$</td>
<td>theoretical elastic stress or strain concentration factor</td>
</tr>
<tr>
<td>$K_s$</td>
<td>actual strain concentration factor</td>
</tr>
<tr>
<td>$K_o$</td>
<td>actual stress concentration factor</td>
</tr>
<tr>
<td>$S$</td>
<td>effective nominal elastic stress at nth increment</td>
</tr>
<tr>
<td>$S_m$</td>
<td>maximum effective local elastic stress</td>
</tr>
<tr>
<td>$S^*$</td>
<td>effective local elastic stress (real or imaginary)</td>
</tr>
<tr>
<td>$\epsilon$</td>
<td>equivalent total strain, unmodified</td>
</tr>
<tr>
<td>$\epsilon_e$</td>
<td>uncorrected equivalent elastic strain</td>
</tr>
<tr>
<td>$\epsilon_p$</td>
<td>equivalent plastic strain</td>
</tr>
<tr>
<td>$\epsilon_p$</td>
<td>maximum equivalent plastic strain in cycle (fig. 1)</td>
</tr>
<tr>
<td>$\epsilon_R$</td>
<td>equivalent local residual strain</td>
</tr>
<tr>
<td>$\epsilon^*$</td>
<td>equivalent total strain, modified</td>
</tr>
<tr>
<td>$\mu$</td>
<td>Poisson's ratio</td>
</tr>
<tr>
<td>$\sigma$</td>
<td>effective stress (loading), unmodified</td>
</tr>
<tr>
<td>$\sigma'$</td>
<td>maximum effective stress in cycle (fig. 1)</td>
</tr>
<tr>
<td>$\sigma_m$</td>
<td>maximum effective stress, unmodified</td>
</tr>
<tr>
<td>$\sigma_m$</td>
<td>maximum effective stress, modified</td>
</tr>
<tr>
<td>$\sigma_R$</td>
<td>local residual stress</td>
</tr>
<tr>
<td>$\sigma_i$</td>
<td>initial yield stress in loading part of cycle</td>
</tr>
<tr>
<td>$\sigma_{ji}$</td>
<td>initial yield stress in unloading part of cycle</td>
</tr>
<tr>
<td>$\sigma_2$</td>
<td>effective stress (unloading), unmodified</td>
</tr>
<tr>
<td>$\sigma_2$</td>
<td>effective stress (unloading), modified</td>
</tr>
<tr>
<td>$\sigma^*$</td>
<td>effective stress (loading), modified</td>
</tr>
</tbody>
</table>
Analytical Procedure

Improvements were made to a simplified inelastic procedure for calculating the stress-strain history at the critical fatigue location of a structure subjected to cyclic thermomechanical loading. Details of the simplified analysis procedure, including a computer program flow chart, are presented in reference 2. The basic assumption in the initial development of the procedure was that the inelastic region is local and constrained from redistribution by the surrounding elastic material. It follows from this assumption that the total strain history at the critical location can be defined by an elastic solution. Justification for the assumption of elastic constraint of local inelasticity can be found in references 6 to 12, which present finite-element analyses of thermally cycled structures, such as combustor liners, air-cooled turbine blades, and wedge-fatigue specimens, where the total strain ranges from elastic and nonlinear solutions are in close agreement. However, this assumption is invalid for structures subjected mainly to mechanical load cycling such as the benchmark notch problem (ref. 1).

In this study, a strain redistribution factor (SRF) was derived to account for local total strain redistribution under applied cyclic loads. This correction also accounted for residual strains induced by plastic yielding. The strain redistribution factor is applied to the ideal local total strain obtained from the elastic solution. These corrections were incorporated in a version of the ANSYSMP program by using a kinematic hardening model to characterize the yield surface under cycling. A representation of a cyclic stress-strain curve by a bilinear kinematic hardening model is illustrated in figure 1. The loci of the tips of the cyclic curves are described by the relation

\[
\sigma = K(\epsilon_p)^n
\]

The work hardening slope \(E_p\) for the kinematic hardening model was determined from energy considerations to give the same strain energy, as indicated by the enclosed area in figure 1, as the actual stress-strain curve. This work hardening slope is defined by

\[
E_p = \frac{\sigma' \cdot 2n}{\epsilon_p \cdot 1 + n}
\]

The von Mises criterion was used to convert the total strain from a uniaxial stress-strain curve into a modified equivalent total strain curve as discussed in reference 13. This modified elastic part of the equivalent total strain corresponds to the measured elastic strain multiplied by \(2(1+\mu)/3\). This relationship must be taken into account in a multiaxial stress-strain field when applying results from elastic finite-element analyses. As a result, all stresses and strains from the elastic solution are expressed in terms of von Mises effective stress and modified equivalent total strain with signs assigned based on the dominant principal stress or strain direction. For computational convenience, the factor \(2(1+\mu)/3\) is included in the elastic modulus, and the modified elastic modulus is designated by \(E_e\), where

\[
E_e = \frac{3}{2(1+\mu)}E
\]

The elastic input data are subdivided into a sufficient number of increments to define the stress-strain cycle. Dwell times are specified for increments which require creep analysis. The increments are analyzed sequentially to obtain the cumulative plastic and creep strains and to track the yield surface. An iterative process is used to calculate the yield stresses for increments undergoing plastic straining. First, an estimated plastic strain is assumed for calculating an initial yield stress from the stress-strain properties and the simulated hardening model. Second, a new plastic strain is calculated as the difference between the total strain and the elastic- and creep-strain components. The yield stress is then recalculated by using the new plastic strain. This iterative process is repeated until the new and previous plastic strains agree within a tolerance of 1 percent.

Neuber's rule (ref. 14), which has been widely used to approximate local stresses and strains in the plastic
region, was selected as the basis for the development of the strain redistribution corrections. With minor modifications, this rule provides acceptable predictions of local stresses and strains in the loading part of a stable cycle and less accurate predictions in the unloading part of the cycle. The relative failure of Neuber’s rule for the unloading part of the cycle has been mainly due to neglect of the local residual stresses. Regardless of the part of the cycle being studied, an adjustment must be made to the stresses to account for the work hardening slope of the cyclic stress-plastic-strain curve.

The strain redistribution analysis for the stable cycle is divided into the following three stages: elastic-plastic loading, elastic unloading, and inelastic unloading. Figure 2 is presented to further define the symbols used in the governing equations for each of these stages.

**Elastic-Plastic Loading**

Neuber’s rule specifies a relationship among the theoretical stress concentration factor $K_\alpha$, the actual stress concentration factor $K_\sigma$, and the actual strain concentration factor $K_\epsilon$ of the form

$$K_\sigma^2 = K_\alpha K_\epsilon$$

(3)

Substituting local and net section stresses and strains into equation (3) gives

$$K_\sigma^2 = \frac{\sigma}{S} \frac{\epsilon}{e}$$

(4)

where $K_\sigma$ also equals $S^*/S$ or $\frac{S^* \sigma}{\epsilon E_p}$.

The cyclic stress-strain relation is assumed to take the form

$$\sigma = E_p \epsilon \quad \text{when} \quad \epsilon \leq \frac{\sigma}{E_p}$$

(5)

or

$$\sigma = \left(1 - \frac{E_p}{E_c}\right) \sigma + E_p \epsilon \quad \text{when} \quad \epsilon \geq \frac{\sigma}{E_p}$$

(6)

Combining equations (4) to (6) gives the local strain as

$$\epsilon = -\frac{B + \sqrt{B^2 + 4AC}}{A}$$

(7)

where

$$A = 2E_p \epsilon$$

$$B = \left(1 - \frac{E_p}{E_c}\right) \sigma$$

$$C = 4 \frac{E_p S^*}{E_c}$$

The local stresses and strains calculated by using the work hardening slope (eqs. (6) and (7)) have to be modified to account for the elastic-strain change between $\sigma$ and $\sigma_\epsilon$. The modified local stress $\sigma^*$ corresponding to the local strain $\epsilon^*$ can be expressed as

$$\sigma^* = \frac{E_p}{E_c} \sigma + \left(1 - \frac{E_p}{E_c}\right) \sigma$$

(8)

and the modified local strain $\epsilon^*$ as

$$\epsilon^* = \epsilon - \frac{\sigma - \sigma^*}{E_c}$$

(9)

The plastic strain $\epsilon_p$ at the stress level $\sigma^*$ is

$$\epsilon_p = \epsilon^* - \frac{\sigma^*}{E_c}$$

(10)

To relate the ideal local inelastic strain to the local total strain, a strain redistribution factor (SRF) is introduced. The SRF at the $n$th increment on the stress-strain curve can be written as

$$(\text{SRF})_n = \epsilon_n + \frac{S^*}{E_c} - \frac{S^*}{E_c}$$

(11)

To improve the accuracy of the predicted local stress-strain history, an SRF was generated for each increment during the loading part of the cycle. This SRF is the cumulative total strain correction up to the $n$th point on the stress-strain curve. Therefore, the total strain at that increment is the uncorrected elastic strain $\epsilon_e$ for that increment plus the sum of all the incremental SRF’s up to that increment:

$$\epsilon^*_n = \epsilon_e + \sum_{i=1}^{n} \left[ (\text{SRF})_i - (\text{SRF})_{i-1} \right]$$

(12)

Equation (12) is another way of expressing $\epsilon^*$ given in equation (9).
Figure 2.—Description of symbols.

(a) Overall cyclic stress-strain response.
(b) Loading part of cycle.
(c) Unloading part of cycle.
Elastic Unloading

The local stress at the nth increment in the elastic unloading part of the cycle (fig. 2) is simply

\[ \sigma_n = \sigma_{m} - (S_m - S^*) \]  

(13)

and the corresponding local total strain is

\[ \epsilon_n = \epsilon_{m} - \frac{S_m - S^*}{E_e} \]  

(14)

or expressed in a form similar to equation (12)

\[ \epsilon_n = \epsilon_{m} + \sum_{i=1}^{n} [ (SRF)_i - (SRF)_{i-1} ] \]  

(15)

For an isothermal problem where an incremental approach is not required, equation (15) can be simplified to \( \epsilon_n = \epsilon_{m} + \text{(SRF)}_m \).

Inelastic Unloading

Upon complete removal of the applied load, residual stresses remain across the net section. Denoting the local residual stress as \( \sigma_R \) gives

\[ \sigma_R = \sigma^*_m - S^*_m \]  

(16)

The complimentary local residual strain, \( \epsilon_R \), is then

\[ \epsilon_R = \frac{\sigma_R}{E_e} \]  

(17)

Again the cyclic stress-strain relation in the plastic region is assumed to take a linear form

\[ \sigma = \left(1 - \frac{E_p}{E_e}\right) \sigma_{yi} + E_p \epsilon \]  

(18)

As a kinematic hardening model is used in the analysis, the new initial yield stress is given by

\[ \sigma_{yi} = \sigma_{m}^* - 2\sigma_{yi} \]  

(19)

Considering the zero stress and plastic strain at the new origin \( \sigma_{m}^* \) (fig. 2), the local stress and total strain can be expressed as

\[ \sigma = K_\sigma S + \sigma_R \]  

(20)

and

\[ \epsilon = K_\epsilon \epsilon + \epsilon_R \]  

(21)

Combining equations (3), (18), (20), and (21) leads to the solution for

\[ \epsilon = \frac{-A - \sqrt{A^2 + B}}{2E_p} \]  

(22)

where

\[ A = \left(1 - \frac{E_p}{E_e}\right) \sigma_{yi}^* - E_p \epsilon_R - \sigma_R \]

\[ B = 4E_p \left[ \left(1 - \frac{E_p}{E_e}\right) \sigma_{yi}^* + \frac{S^*_2}{E_e} - \sigma_R \epsilon_R \right] \]

The actual local stresses and strains are obtained by a series of iterations between the modified and unmodified values. As shown here, two iterations are sufficient to give an acceptably convergent solution. Iterations are not necessary for the loading part of the cycle. The modified local stress \( \sigma^*_2 \) corresponding to \( \epsilon^* \) is expressed as

\[ \sigma^*_2 = \frac{E_p}{E_e} \sigma_{yi}^* + \left(1 - \frac{E_p}{E_e}\right) \sigma_2 \]  

(23)

where \( \sigma_2 \) is obtained from the following steps:

\[ \sigma = \left(1 - \frac{E_p}{E_e}\right) \sigma_{yi}^* + E_p \epsilon \]  

(24)

\[ \sigma^* = \frac{E_p}{E_e} \sigma_{yi}^* + \left(1 - \frac{E_p}{E_e}\right) \sigma \]  

(25)

\[ \epsilon_1 = \epsilon - \frac{\sigma - \sigma^*}{E_p} \]  

(26)

\[ \sigma_1 = \left(1 - \frac{E_p}{E_e}\right) \sigma_{yi}^* + E_p \epsilon_1 \]  

(27)
and the modified local total strain $\varepsilon^*$ is

$$
\varepsilon^* = \varepsilon - \frac{\sigma - \sigma_2}{E_p} - \frac{\sigma_2 - \sigma_p^*}{E_e} + \varepsilon_p
$$

The plastic strain $\varepsilon_p$ at the stress level $\sigma_2$ is

$$
\varepsilon_p = \varepsilon^* - \frac{\sigma_2}{E_e}
$$

The strain redistribution factor at the $n$th increment on the stress-strain curve is

$$
(SRF)_n = \varepsilon_n - \frac{\sigma_n - \sigma_{n-1}}{E_p} - \frac{\sigma_{n-1} - \sigma_{n-2}}{E_e} - \frac{S_m + \sigma_R}{E_e}
$$

or, in terms of the uncorrected elastic strain, the total strain at the $n$th increment can be written as

$$
\varepsilon^*_n = \varepsilon_n + (SRF)_m - \sum_{i=1}^{n} [(SRF)_i - (SRF)_{i-1}]
$$

where

$$
(SRF)_m = \varepsilon_m - \frac{S_m}{E_e} - \frac{\sigma_m - \sigma_{m-1}}{E_e}
$$

Equation (34) is simply another form of expressing the $\varepsilon^*$ previously given in equation (31).

Another version of the ANSYMP computer program was created to implement the improved simplified analytical procedure. The program consists of the main executive routine, ANSYMP, and four subroutines, ELAS, YIELD, CREEP, and SHIFT. The incremental elastic data and temperatures are read into subroutine ELAS. Material stress-strain properties as a function of temperature and a simulated hardening model are incorporated in subroutine YIELD, and the creep characteristics are incorporated in subroutine CREEP. Subroutine SHIFT is required to update the temperature effects on the yield stress shift. SHIFT also serves the function of deciding the future direction of the yield surface under nonisothermal conditions by determining the relation of future to past thermal loading.

The calculation scheme initially follows the effective stress-equivalent-strain input data from subroutine ELAS until the occurrence of initial yielding. The stress-strain solution then proceeds along the yield surface as determined from the stress-strain properties in subroutine YIELD. At each increment during yielding the stress shift (difference between new yield stress and stress predicted from elastic analysis) from the original input data is calculated. Elastic load reversal is signaled when the input stress is less than the yield stress from the previous increment. During elastic unloading the stresses are translated from the original elastic-analysis solution by the amount of the calculated stress shift. Reverse yielding occurs when the stress reaches the reverse yield surface as determined from the hardening model incorporated in subroutine YIELD. Again the solution follows the yield surface until another load reversal is indicated when the stress, based on the shifted elastic solution, is less than the yield stress. The elastic response during load reversal is obtained by translating the original elastic solution according to the new stress shift calculated during reversed yielding. The stress-strain response for subsequent cycles is computed by repeating this procedure of identifying load reversals, tracking reverse yield surfaces, and translating the original elastic solution during elastic loading and unloading. Creep computations are performed for increments involving dwell times by using the creep equation and strain hardening rule incorporated in subroutine CREEP. Depending on the nature of the problem, the creep effects are determined on the basis of one of the three options provided in the subroutine.

The code automatically avoids the Neuber-type strain redistribution corrections for thermal loading problems where there are no applied mechanical loads. Without applied loads, the Neuber method would be inapplicable since equation (4) would have zero net stresses and strains in the denominator. Provision is also made for the user to circumvent the corrections for other situations where they should not be taken into account. These situations include locally strain controlled problems and, as shown in the next section, problems where the total strain input is based on strain measurements rather than elastic finite-element analyses.

Since the stable cyclic stress-strain curve is a function of the plastic-strain range, it is necessary to iterate between the maximum plastic strain used to specify the
stress-strain curve and the analytical solution. In both the MARC code and the original ANSYMP code the iteration required rerunning the problem until the assumed and calculated plastic strains were in reasonable agreement. In the improved version of the ANSYMP program, the iteration was automated so that the analysis was repeated with the previously calculated maximum plastic strain used to define the stress-strain curve. This iterative process is continued until the specified and calculated maximum plastic strains agree within 10 percent, usually within three iterations.

The computer program was verified by conducting simplified analyses for the benchmark notch problem and comparing the results to those from MARC nonlinear analyses. The geometry of the benchmark notch specimen is illustrated in figure 3. This specimen was tested under isothermal conditions as part of a program to provide controlled strain data for constitutive model verification (ref. 5). A MARC analysis of this problem using kinematic hardening demonstrated excellent agreement with experimental data in reference 8. Two variations of this problem were analyzed, one with the initial loading carried out to a plastic strain of 0.4 percent and the second with the specimen loaded to a maximum plastic strain of 0.6 percent with a small amount of strain ratcheting. A kinematic hardening model was used with cyclic stress-strain data for Inconel 718 alloy obtained from reference 5. Nonlinear and elastic MARC analyses of this problem were performed by using approximately 600 triangular-plane strain elements to model a quarter segment bounded by planes of symmetry (fig. 4). The MARC solutions shown for the benchmark notch specimen were computed at the closest Gaussian integration point to the root of the notch. Excellent agreement between the MARC solution and the measured strains at the notch root was demonstrated in the work of reference 8.

The results of the improved simplified inelastic analyses of the benchmark notch problems are discussed in this section. Comparisons are made with MARC inelastic solutions. Stress-strain cycles used for comparison purposes are discussed in terms of effective stresses and equivalent total strains by using the von Mises yield criterion with signs computed from the assigned signs in the original elastic solution. The entire discussion is based on the critical location at the notch root.

The benchmark notch test was conducted by mechanical load cycling at a constant temperature of 649 °C. A mechanically loaded structure, especially where the peak strain occurs at a stress raiser, is most likely to violate the basic assumption of the simplified approach that strain redistribution is prevented by containment of the local plastic region by the surrounding elastic material. Reference 1 reports that the total strain range from the MARC elastic-plastic analysis was 20 percent greater than that obtained from the MARC elastic analysis. This foreshortening of the elastic-strain range caused the simplified procedure to truncate the stress-strain hysteresis loop (fig. 5(a)). When the input total strain history was based on optical strain measurements at the notch root, the agreement was good between the simplified and MARC elastic-plastic stress-strain hysteresis loops, as demonstrated in figure 5(b). Both the ANSYMP and MARC elastic-plastic analyses gave stable stress-strain hysteresis loops for the second cycle. Note that when the simplified analysis uses strain measurements rather than elastic finite-element solutions, strain redistribution corrections are unnecessary and should not be applied.

In figure 5(c) similar comparisons are shown by using the simplified procedure corrected for strain redistribution.
redistribution on the loading part of the cycle and the MARC elastic solution as input. Neuber corrections for residual stresses and strain redistribution on the unloading part of the cycle were not implemented for this case. The truncation of the stress-strain hysteresis loop (fig. 5(a)) was eliminated, and the ANSYMP solution agreed well with the MARC solution. This demonstrates the significant improvement in accuracy that can be attained by applying the Neuber correction in the plastic region, even without the residual stress correction during unloading.

When both the loading and unloading strain redistribution corrections were applied, the agreement between the predicted and MARC elastic-plastic results was even better (fig. 5(d)).

The original benchmark problem analyzed in figure 5 was a completely closed cycle and the maximum plastic strain was about 0.4 percent. To exercise the improved simplified procedure on an even more severe case, the mechanical loading was increased so that the plastic strain reached approximately 0.6 percent, and strain ratcheting was induced. Again the agreement between the
ANSYMP and MARC inelastic solutions was excellent (fig. 6). Note that the simplified procedure was able to capture the strain ratcheting on the second cycle.

The slight discrepancies between the the ANSYMP and MARC hysteresis loops in figures 5(d) and 6 were due primarily to the iteration process built into ANSYMP, which resulted in the use of a cyclic stress-strain curve slightly different from that used in the MARC elastic-plastic analysis. The ANSYMP analyses of the benchmark notch problem used 0.3 percent of the central processor unit time required by the MARC nonlinear analyses; this is without considering that the latter had to be run several times to obtain a cyclic stress-strain curve compatible with the calculated maximum plastic strain.

**Summary of Results**

An improved simplified analysis procedure was developed for calculating the stress-strain history at the critical location of a thermomechanically cycled structure. This improved procedure incorporated Neuber-type corrections to account for strain redistribution and residual stresses due to plastic-strain reversals. The following results were obtained from the evaluation of the method:

1. The predicted stress-strain response based on elastic finite-element solutions with the Neuber-type corrections showed excellent agreement with elastic-plastic finite-element solutions using the MARC program.

2. The predicted stress-strain response using only the corrections for plastic yielding on the loading part of the cycle showed good agreement with the MARC elastic-plastic solution. The corrections for the unloading part of the cycle were of secondary importance.

3. The strain redistribution corrections should not be applied when the input total strain history is based on local strain measurements rather than elastic finite-element analyses. It is also known from previous evaluations of the simplified procedure that these corrections should not be applied in thermal loading problems. For cases where a structure is subjected to a combination of thermal and mechanical loads, a method will have to be developed to partition the thermal and mechanical stresses so that the strain redistribution corrections are applied only to the mechanical stresses.
4. Stress-strain hysteresis loops were computed at the critical location of the structure using 0.3 percent of the central processor unit time required for elastic-plastic finite-element analyses.

Lewis Research Center
National Aeronautics and Space Administration
Cleveland, Ohio, January 8, 1985

References

Local Strain Redistribution Corrections for a Simplified Inelastic Analysis Procedure Based on an Elastic Finite-Element Analysis

Abstract

Strain redistribution corrections were developed for a simplified inelastic analysis procedure to economically calculate material cyclic response at the critical location of a structure for life prediction purposes. The method was based on the assumption that the plastic region in the structure is local and the total strain history required for input can be defined from elastic finite-element analyses. Cyclic stress-strain behavior was represented by a bilinear kinematic hardening model. The simplified procedure predicts stress-strain response with reasonable accuracy for thermally cycled problems but needs improvement for mechanically load-cycled problems. This study derived and incorporated Neuber-type corrections in the simplified procedure to account for local total strain redistribution under cyclic mechanical loading. The corrected simplified method was used on a mechanically load-cycled benchmark notched-plate problem. The predicted material response agreed well with the nonlinear finite-element solutions for the problem. The simplified analysis computer program was 0.3 percent of the central processor unit time required for a nonlinear finite-element analysis.
6 21U,D, 850311 500161DS
DEPT OF THE AIR FORCE
ARNOLD ENG DEVELOPMENT CENTER (AFSC)
ATTN: LIBRARY/DOCUMENTS
ARNOLD AF STA TN 37389