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A CONCATENATED CODING SCHEME FOR ERROR CONTROL

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FOR ERROR CONTROL

ABSTRACT

In this paper, a concatenated coding scheme for error control in data communications is presented and analyzed. In this scheme, the inner code is used for both error correction and detection, however the outer code is used only for error detection. A retransmission is requested if either the inner code decoder fails to make a successful decoding or the outer code decoder detects the presence of errors after the inner code decoding. Probability of undetected error (or decoding error) of the proposed scheme is derived. An efficient method for computing this probability is presented. Throughput efficiency of the proposed error control scheme incorporated with a selective-repeat ARQ retransmission strategy is also analyzed. Three specific examples are presented. One of the examples has been adopted for error control in NASA telecommand system.

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1. Introduction

Consider a concatenated coding scheme [1] for error control for a binary symmetric channel with bit-error-rate $e \leq 1/2$ as shown in Figure 1. Two linear block codes, $C_1$ and $C_2$, are used. The inner code $C_1$ is an $(n_1, k_1)$ code with minimum distance $d_1$. The inner code is designed to correct $t$ or fewer errors and simultaneously detect $\lambda (\lambda \geq t)$ or fewer errors where $t + \lambda + 1 \leq d_1$. The outer code $C_2$ is an $(n_2, k_2)$ code with minimum distance $d_2$ and

$$n_2 = mk_1$$

where $m$ is a positive integer. The outer code is designed for error detection only.

The encoding is done in two stages. A message of $k_2$ bits is first encoded into a codeword of $n_2$ bits in the outer code $C_2$. Then the $n_2$-bit word is divided into $m$ $k_1$-bit segments. Each $k_1$-bit segment is then encoded into an $n_1$-bit codeword in the inner code $C_1$. This $n_1$-bit word is called a frame. Thus, corresponding to each $k_2$-bit message at the input of the outer code encoder, the output of the inner code encoder is a sequence of $m$ frames. This sequence of $m$ frames is called a block. A two dimensional block format is depicted in Figure 2.

The decoding consists of error correction in frames and error detection in $m$ decoded $k_1$-bit segments. When a frame in a block is received, it is decoded based on the inner code $C_1$. If the decoding is successful, the $n_1 - k_1$ parity bits are then removed from the decoded frame, and the $k_1$-bit decoded segment is stored in a buffer. If there are $t$ or fewer transmission errors in a received frame, the errors will be corrected and the decoded segment is error free. If $t+1$ or more transmission errors are detected in a received frame, then the entire block which contains the
erroneous frame is discarded, and the receiver requests a retransmission of the block. If there are more than $\lambda$ errors in a received frame, the errors may result in a syndrome which corresponds to a correctable error pattern with $t$ or fewer errors. In this case, the decoding will be successful, but the decoded frame (or segment) contains undetected errors. If $m$ frames of a received block have been successfully decoded, the receiver buffer contains $m$ $k_1$-bit decoded segments. Then error detection is performed on these $m$ decoded segments based on the outer code $C_2$. If no error is detected, the $m$ decoded segments are assumed to be error free and are accepted (with $n_2-k_2$ parity bits removed) by the receiver. If the presence of errors is detected, then the $m$ decoded segments are discarded and the receiver requests a retransmission of the rejected block. Retransmission and decoding process continue until the block is successfully received. Note that a successfully received block may be either error free or contains undetectable errors.

The error control scheme described above is actually a combination of forward-error-correction (FEC) and automatic-repeat-request (ARQ), called a hybrid ARQ scheme [2]. The retransmission strategy determines the system throughput, it may be one of the three basic modes namely, stop-and-wait, go-back-N or selective-repeat. In this paper, we analyze the performance of the proposed error control scheme in terms of the reliability and throughput efficiency. The reliability is measured in terms of the probability of undetected error after decoding. The probability of undetected error is derived, and an efficient method for computing this probability is presented. The throughput efficiency depends on the mode of retransmission. In this paper, we analyze the throughput efficiency of the proposed error control scheme incorporated with a selective-repeat ARQ with a finite receiver buffer.
Three specific example schemes are considered. The first two example schemes use the same inner code which is a distance-4 shortened Hamming code with generator polynomial \[ g_1^{(2)}(X) = g_1^{(1)}(X) = (X+1)(X^6+X+1) = X^7 + X^6 + X^2 + 1 \, . \] (1)

In the first scheme, the outer code is a distance-4 shortened Hamming code with generator polynomial,

\[ g_2^{(1)}(X) = (X+1)(X^{15} + X^{14} + X^{13} + X^{12} + X^4 + X^3 + X^2 + 1) \]
\[ = X^{16} + X^{12} + X^5 + 1 \, . \] (2)

which is the X.25 standard for packet-switched data network \([3]\). This example scheme is proposed and adopted for error control on NASA telecommand links.

In the second example scheme, the outer code is a shortened Reed-Solomon (RS) code \([2,4,5]\) with symbols from the Galois field \(\text{GF}(2^8)\) and generator polynomial,

\[ g_2^{(2)}(X) = (X+1)(X+\alpha) \, , \] (3)

where \(\alpha\) is a primitive element in \(\text{GF}(2^8)\). In the third example scheme, the inner code is a shortened version of the extended double-error-correcting \((63,51)\) BCH code with generator polynomial \([2]\),

\[ g_1^{(3)}(X) = X^{12} + X^{10} + X^8 + X^5 + X^4 + X^3 + 1 \, , \] (4)

The outer code is the same as that of the first example scheme.

The probabilities of a decoding error and throughput efficiencies for the three example schemes are computed. We show that they all provide very high reliability even for a very high bit-error rate. All three example schemes also provide high throughput efficiency.

2. Probabilities of Incorrect Decoding and Retransmission

Let \(V_\ell\) denote the set of all binary vectors of length \(\ell\). Let \(n\) be a positive integer defined as follows:

\[ -4 - \]
\[ n = mn_1 \]  

where \( n_1 \) is the length of the inner code and \( m \) is the number of frames per block. Let \( \tilde{u} = (u_1, u_2, \ldots, u_n) \) be a vector in \( V_n \). The \( n_1 \)-tuple

\[ \tilde{u}_h = (u_{(h-1)n_1+1}, u_{(h-1)n_1+2}, \ldots, u_{hn_1}) \]

is called the \( h \)-th frame of \( \tilde{u} \) for \( 1 \leq h \leq m \). Hence, we can represent the vector \( \tilde{u} \) by its frames as follows:

\[ \tilde{u} = (\tilde{u}_1, \tilde{u}_2, \ldots, \tilde{u}_m) \cdot \]

The first \( k_1 \) components of the \( h \)-th frame of \( \tilde{u} \) are said to form the \( h \)-th segment of \( \tilde{u} \). The \( mk_1 \)-tuple obtained by concatenating the \( m \) segments of \( \tilde{u} \) in order is called the projection of \( \tilde{u} \), denoted \( \rho(\tilde{u}) \).

Let \( C \) denote the overall code obtained by concatenating the inner code \( C_1 \) and the outer code \( C_2 \). Then \( C \) is a binary \((n, k_2)\) linear code where \( n = mn_1 \). A binary vector \( \tilde{u} \) in \( V_n \) is a codeword in \( C \) if and only if

1. each frame of \( \tilde{u} \) is a codeword in the inner code \( C_1 \); and
2. the projection \( \rho(\tilde{u}) \) of \( \tilde{u} \) is a codeword in the outer code \( C_2 \).

Let \( P_c \) be the probability of a correct decoding using the concatenated coding scheme described in Section 1. For a binary symmetric channel with bit-error-rate \( \epsilon \leq 1/2 \), \( P_c \) is equal to the probability that there are \( t \) or fewer errors in each frame of the received block, and is given by

\[ P_c = \sum_{i=0}^{t} \binom{n_1}{i} \epsilon^i (1-\epsilon)^{n_1-i} \]

Let \( P_d \) be the probability of a successful decoding (either correct or incorrect) of a received block. Then \( P_d \) is the probability that, for a channel-error pattern \( \bar{e} \), there is a codeword \( \bar{v} \) in the overall code \( C \) such that, for \( 1 \leq h \leq m \), the Hamming distance between the \( h \)-th frame of \( \bar{e} \) and the \( h \)-th
frame of \( \vec{v} \) is \( t \) or less. If \( P_d \) can be computed, then the probability of an incorrect decoding (or a decoding error), \( P_e \), is given by

\[
P_e = P_d - P_c \quad (10)
\]

and the probability of a decoding failure, \( P_r \), is given by

\[
P_r = 1 - P_d \quad (11)
\]

Note that \( P_r \) is also the probability of a retransmission.

In the following we will derive an expression for \( P_d \). Let \( W_{i,j,s} \) denote the number of binary vectors of weight \( j \) in \( V_{n_1} \) which are at a (Hamming) distance \( s \) from a given binary vector of weight \( i \) in \( V_{n_1} \). Let \( \vec{a} = (a_1, a_2, \ldots, a_{n_1}) \) and \( \vec{b} = (b_1, b_2, \ldots, b_{n_1}) \) be two binary vectors in \( V_{n_1} \) with weights \( i \) and \( j \) respectively. Let \( q \) be the number of suffixes \( 2 \)'s such that \( a^Q = 0 \) and \( b < 2 \)'s. Then \( \vec{b} \) is at a distance \( s \) from \( \vec{a} \) if and only if

\[
q = (j + s - i)/2 \quad (12)
\]

Therefore we have that

\[
W_{i,j,s} = \binom{n_1}{i-q} \binom{i}{j-q} = \binom{n_1-i}{(j+s-i)/2} \binom{i}{(j+i-s)/2} \quad (13)
\]

The generating function for \( W_{i,j,s} \) is

\[
\sum_{j=0}^{n_1} \sum_{s=0}^{n_1} W_{i,j,s} x^j y^s = (1 + x y)^{n_1-i} (1 + y)^{i} \quad (14)
\]

which was derived by MacWilliams in 1963 [6].

Let \( \vec{e} = (e_1, e_2, \ldots, e_m) \) be a channel error pattern, and let \( j_h \) be the weight of the \( h \)-th frame \( e_h \) for \( 1 \leq h \leq m \). The occurrence probability of \( \vec{e} \) is

\[
P(\vec{e}) = \prod_{h=1}^{m} \binom{n_1-j_h}{(1-e_h) \cdot i \cdot (1-e_h)} \quad (15)
\]

Suppose that there is a codeword \( \vec{v} = (\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_m) \) in \( C \) such that \( \vec{e}_h \) is at a distance \( s_h = t \) from \( \vec{v}_h \) for \( 1 \leq h \leq m \). Since \( \vec{v}_h \) is a codeword in the inner code \( C_1 \) for \( 1 \leq h \leq m \) and the minimum distance of \( C_1 \) is assumed to be greater than \( 2t \), such a codeword \( \vec{v} \) in \( C \) is uniquely determined. Conversely, for a codeword
\[ \bar{v} = (\bar{v}_1, \bar{v}_2, \ldots, \bar{v}_m) \] in C whose weight in the h-th frame is \( i_h \) for \( 1 < h < m \), there are

\[ \prod_{h=1}^{m} \frac{(i_h)}{j_h}, s_h \]  \hspace{1cm} (16)

error patterns \((\bar{e}_1, \bar{e}_2, \ldots, \bar{e}_m)\)'s such that the weight of \( \bar{e}_h \) is \( j_h \) and \( \bar{v}_h \) is at a distance \( s_h \) from \( \bar{v}_h \) for \( 1 < h < m \). Let \( A_{i_1, i_2, \ldots, i_m} \) denote the number of codewords in C whose weight in the h-th frame is \( i_h \) for \( 1 < h < m \). Then, the probability of a successful decoding is given below:

\[ P_d = \frac{\sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_2} \ldots \sum_{i_m=0}^{n_m} A_{i_1, i_2, \ldots, i_m}}{\prod_{h=1}^{m} \left( \frac{(i_h)}{j_h}, s_h \right) (1-E)^{n-1}} \]  \hspace{1cm} (17)

Hence, if we know the detail weight distribution \( \{A_{i_1, i_2, \ldots, i_m} : 0 < i_h < n \} \) for \( 1 < h < m \) of C, we can compute the probability \( P_d \) of a successful decoding from (17). Then, from (9) and (10) we can compute error probability \( P_e \). From (11), we can compute the retransmission probability \( P_r \), from which we can determine the system throughput for a given retransmission strategy (ARQ scheme).

The dimension of C is \( k_2 \). In general, \( k_2 \) is large and it is not feasible to compute the detail weight distribution \( A_{i_1, i_2, \ldots, i_m} \) directly from C by generating all the codewords of C. In the next section, we will express \( P_d \) in terms of the detail weight distribution of the dual code of C by using the generalized MacWilliams's identity [7, p. 147].

3. **Evaluation of the Probability of Decoding**

In this section, we will derive a number of results which will facilitate the computation of the probability \( P_d \) of a successful decoding. Let \( C^\perp \) denote the dual code of the overall code C. Let \( B_{i_1, i_2, \ldots, i_m} \) be the number
of codewords in $C^\perp$ for which the weight of $h$-th frame is $i_h$ for $0<i_h<n_1$ and $1<h<m$. Then
\[ \{ B_{i_1,i_2,...,i_m} : 0<i_h<n_1 \text{ with } 1<h<m \} \tag{18} \]
represents the detail weight distribution of $C^\perp$. In the following, the first lemma gives the decoding probability $P_d$ in terms of the detail weight structure of $C^\perp$.

**Lemma 1:** Let $P_s(\cdot,\cdot)$ be a Krawtchouk polynomial [7, p. 129]. Then
\[ P_d = 2^{-(n-k_2)} \sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \sum_{i_3=0}^{n_1} \sum_{i_m=0}^{n_1} \prod_{h=1}^{m} \left[ (1-2\varepsilon)^{i_h} \sum_{s=0}^{n_1} P_s(i_h,n_1) \right]. \tag{19} \]

**Proof:** See Appendix A.

It follows from (19) that, for the worst channel condition $\varepsilon=1/2$,\[ P_d = 2^{-(n-k_2)}(n_1+1)^m. \tag{20} \]

Let $r_1$ and $r_2$ denote the numbers of parity check bits of the inner and outer codes respectively. Then $r_1 = n_1-k_1$ and $r_2 = n_2-k_2$. The dimension of $C^\perp$ is thus $m r_1 + r_2$. In general, $m r_1 + r_2$ is also large, and it is still not feasible to compute $B_{i_1,i_2,...,i_m}$ by generating all the codewords of $C^\perp$. However, the computing time can be reduced considerably by using Lemma 2 given below.

For a vector $\tilde{v} = (v_1,v_2,...,v_{mk_1})$ in $V_{mk_1}$, the $k_1$-tuple $(v_{(h-1)k_1+1},v_{(h-1)k_1+2},...,v_{hk_1})$ is called the $h$-th segment of $\tilde{v}$ for $1<h<m$. Let $\tilde{v}(0)$ (all-zero vector), $\tilde{v}(1),...,\tilde{v}(2^k-1)$ denote all the codewords of $C_2^\perp$, the dual code of the outer code $C_2$. For $0<j<2^k$ and $1<h<m$, let $\tilde{v}_h^{(j)}$ denote the $h$-th segment of $\tilde{v}(j)$. Let $C_1^\perp$ be the dual code of the inner code $C_1$. Let $\tilde{u} = (u_1,u_2,...,u_{k_1})$ be a binary vector in $V_{k_1}$. Let $\tilde{u}_0 = (u_1,u_2,...,u_{k_1},0,0,...,0)$.
be a vector obtained by appending \( n_1 - k_1 \) zeros to \( \bar{u} \). Hence \( \bar{u}_0 \) is a vector in \( V_{n_1} \). For \( 0 \leq i \leq n_1 \), let \( B^{(1)}_i(\bar{u}) \) denote the number of vectors of weight \( i \) in the coset of \( C_1^t \) which contains the vector \( \bar{u}_0 \). Lemma 2 gives \( B_{i_1, i_2, \ldots, i_m} \) in terms of \( B^{(1)}_i(\bar{u}) \).

**Lemma 2:**

\[
B_{i_1, i_2, \ldots, i_m} = \sum_{j=0}^{2^{r_2} - 1} \prod_{h=1}^{m} B^{(1)}_{i_h}(\bar{v}_h^{(j)}). 
\]  

(21)

**Proof:** See Appendix B.

Since the dimensions \( r_1 \) and \( r_2 \) of \( C_1^t \) and \( C_2^t \) are much smaller than the dimension \( m r_1 + r_2 \) of \( C^t \), it is much easier to compute \( B_{i_1, i_2, \ldots, i_m} \) from (21) than from \( C^t \) directly by generating all the codewords of \( C^t \). This will be shown in the next section.

It follows from Lemmas 1 and 2 that we have Theorem 1.

**Theorem 1:**

\[
P_d = 2^{-(n-k_2)} \sum_{j=0}^{2^{r_2} - 1} \prod_{h=1}^{m} B^{(1)}_{i_h}(\bar{v}_h^{(j)})(1-2\varepsilon)^i \prod_{s=0}^{i} p_e(i, n_1). 
\]  

(22)

**Proof:** (See Appendix C).

It follows from (9), (10), and (22) that we can obtain the probability \( p_e \) of a decoding error for the concatenated coding scheme proposed in Section 1.

4. **Time Complexity for Computing the Probability of Decoding**

In this section, we will evaluate the time complexity for computing the decoding probability \( p_d \) given by (22). The number of different \( \bar{v}_h^{(j)} \)'s with \( 1 \leq h \leq m \) and \( 0 \leq j \leq 2^{r_2} \) is at most \( m 2^{r_2} \). Hence the computing time for finding \( \{ B^{(1)}_i(\bar{v}_h^{(j)}); 0 \leq i \leq n_1, \ 0 \leq j \leq 2^{r_2} \text{ and } 1 \leq h \leq m \} \) is roughly proportional to \( m n_1 2^{r_1 + r_2} \). Furthermore, we need multiplications and additions of order \( (n_1 + m) 2^{r_2} \) for computing \( p_d \). The dominant order of computation for \( p_d \) is \( m n_1 2^{r_1 + r_2} \).
Next we assume that the outer code $C_2$ is a shortened (or the full) code of a quasi-cyclic code $C_{2,f}$ of length $n_f$ [5] which is invariant under every cyclic shift by $s$ places, where $s$ divides $k_1$ (note that, if $s=1$, $C_{2,f}$ is a cyclic code). Then the dual code of $C_{2,f}$ denoted $C_{2,f}^\perp$ is also quasi-cyclic for every $s$-place shift. The codewords in $C_{2,f}$ can be partitioned into equivalent classes, each equivalent class consists of a codeword $\tilde{v}$ and the codewords obtained by cyclically shifting $\tilde{v}$ $s$ places at a time. We may choose a codeword in each equivalent class as its representative. A vector $(\epsilon_1, \epsilon_2, \ldots, \epsilon_{n_2})$ in $V_{n_2}$ is a codeword in $C_{2}^\perp$ if and only if there is a representative codeword $(v_1, v_2, \ldots, v_{n_f})$ for an equivalent class of $C_{2,f}^\perp$, for which there exists a positive integer $j$ such that $\epsilon_i = v_{j+i}$ for $1 \leq i \leq n_2$ where $j+i$ is taken modulo $n_f$. Hence the number of different $\tilde{v}(j)$'s with $1 \leq h \leq m$ and $0 \leq j < 2$ is at most $2^{r_2}$. Since $n_1 < 2^{r_1}$, the dominate order of computation for $P_d$ is

$$\max\{n_1^{r_1+r_2}, m2^{r_2}\}.$$  

However, if we compute

$$\{B_{i_1, i_2, \ldots, i_m}: 0 \leq i_k < n_1 \text{ and } 1 \leq h \leq m\}$$

directly from $C_{1}^\perp$, the computation time is proportional to $mn_1 2^{mr_1+r_2}$ which is much greater than $n_1^{2^{r_1+r_2}}$ and $m2^{r_2}$. Hence, using expression (22) for computing $P_d$ reduces the computing time considerably.

Suppose that $C_{1}^\perp$ contains the all-one vector, $(1,1,\ldots,1)$. Let $C_{1,0}$ denote the $(n_1, r_1-1)$ linear subcode of $C_{1}^\perp$ which does not contain the all-one vector. For a vector $\bar{u} = (u_1, u_2, \ldots, u_{k_1})$ in $V_{k_1}$, let $B_{i}^{(1),0}(\bar{u})$ be the number of vectors of weight $i$ in the coset of $C_{1,0}$ which contains the vector $\bar{u}_0 = (u_1, u_2, \ldots, u_{k_1}, 0, 0, \ldots, 0)$ in $V_{n_1}$. Then

$$B_{i}^{(1)}(\bar{u}) = B_{i}^{(1),0}(\bar{u}) + B_{n_1-i}^{(1),0}(\bar{u}).$$  

(23)

The above relation reduces the computing time for $B_{i}^{(1)}(\bar{u})$. 

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If $C_2$ is generated by an $(n_2, r_2-1)$ linear subcode $C_{2,0}$ and the all-one vector $(1,1,...,1)$ in $V_{n_2}$, the computing time for $B_i^{(1)}(\bar{u})$ can be further reduced by using the following relation:

$$B_i^{(1)}(\bar{u}+(1,1,...,1)) = \sum_{j=0}^{i} [B_i^{(1)}, 0]_{k_1-j, 1-j}(\bar{u}) + B_i^{(1)}, 0]_{r_1-i+j}(\bar{u})$$

(24)

where $B_i^{(1), 0}(\bar{u})$ denote the number of vectors with weight $i$ in the first $k_1$ bit positions and weight $j$ in the last $r_1$ bit positions, which are in the coset of $C_{1,0}$ containing the vector $(\bar{u}, 0, 0, ..., 0)$ in $V_{n_1}$.

5. Example Schemes

In this section we consider three examples of the concatenated coding scheme described in Section 1. For each of the example schemes, the probability of a decoding error, $P_e$, and the probability of a retransmission, $P_r$, are computed for various bit-error rates.

Example Scheme I

In this example scheme, the inner code $C_1$ is a shortened distance-4 Hamming code with generator polynomial,

$$g_1^{(1)}(X) = (X+1)(X^6+X+1) = X^7+X^6+X^2+1$$

(25)

where $X^6+X+1$ is a primitive polynomial of degree 6. The full length code generated by $g_1(X)$ of (25) is a $(63, 56)$ cyclic Hamming code. The 56 information bits form 7 8-bit information bytes. If $\lambda$ information bits are deleted from the full length code, then the inner code $C_1$ becomes a $(63-\lambda, 56-\lambda)$ shortened cyclic code [2, 4, 5]. In practical applications, $\lambda$ is generally chosen to make $k_1=56-\lambda$ as a multiple of 8-bit byte. The inner code $C_1$ is used for single error correction (i.e., $t=1$). It is also capable of detecting all the error patterns of double and odd number errors [2, 4, 5, 7].

The outer code is also a shortened distance-4 Hamming code with generator polynomial,
where $X_{15} + X_{14} + X_{13} + X_{12} + X_{4} + X_{3} + X_{2} + X + 1$ is a primitive polynomial of degree 15. This code is the X.25 standard for packet-switched data networks [3]. The natural length of this code is $2^{15} - 1 = 32,767$. But the maximum length of $C_2$ being considered is 3,584 bits. We assume that the number $m$ of frames in a block varies from 3 to a maximum 64. We also assume that the number of information bytes contained in a frame varies 1 to 7, i.e., $k_1 = 8 - 56$ bits. Hence the length $n_2$ of the outer code varies from 3 to 448 bytes or from 24 to 3,584 bits. The 16 parity bits of the outer code is used for error detection only. The error detection performance of this outer code for various lengths has been investigated recently by Fujiwara, et al. [8].

Example scheme I has been adopted by NASA for error control on telecommand links. The probability of a decoding error, $P_e$, for this scheme is shown in figures 3, 5, 7 and 9 for various $k_1$, $m$ and bit-error-rate $\varepsilon$. We see from Figure 9 that, as the bit-error-rate $\varepsilon$ increases, $P_e$ increases to a peak value and then decreases to the value $P_{e*} = 1 - P_{d*}$ where $P_{d*}$ is given by (20). We see that the scheme provides very high reliability even for very high bit-error-rate. The probability of a decoding failure (or retransmission), $P_f$ is shown in Figures 4, 6, 8 and 10 for various $k$, $m$ and bit-error-rate $\varepsilon$.

**Example Scheme II**

In this example scheme, the inner code $C_1$ is the same as that of example scheme I. The outer code is a shortened Reed-Solomon (RS) code with symbols from the Galois field $GF(2^8)$ and generator polynomial

$$g^{(2)}(X) = (X+1)(X+\alpha),$$

where $\alpha$ is a primitive element of $GF(2^8)$ and a root of $x^3 + x^4 + x^3 + x^2 + 1$. This code is used as a binary code with each code symbol represented by a 8-bit...
byte. This binary RS is quasi-cyclic and has a minimum distance 4. The
natural length of the code is 255 bytes or 2046 bits.

The probability $P_e$ of a decoding error is shown in Figures 3, 5, 7
and 9. The performance of this example scheme is inferior to example scheme
1, however still provides very high reliability. The probability $P_x$ of a
decoding failure is shown in Figures 4, 6, 8 and 10. Since $P_e$ is very
small, it follows from (10) and (11) that $P_x = 1 - P_e$. Hence example schemes 1
and 2 have almost the same $P_x$.

**Example Scheme III**

In this example scheme, the outer code $C^*$ is the same as that of the
t example scheme 1, the X.25 standard code. However, the inner code is a short-
ened version of the extended (with an overall parity bit appended) double-
error-correcting (63,51) BCH code with generator polynomial [2],

$$g_{1}^{(3)}(X) = x^{12} + x^{10} + x^{8} + x^{5} + x^{4} + x^{3} + 1.$$ (28)

The inner code $C_1$ generated by $g_{1}^{(3)}(X)$ has minimum distance 6 and is used
for correcting all the double and single errors ($t=2$). The code is capable of
detecting all the triple errors and many other errors.

The probability of a decoding error, $P_e$ is shown in Figures 3, 5, 7, and
9. Since the inner code is designed for double error correction, the perfor-
mance of this example scheme is superior to the example schemes 1 and 2. The
probability of a decoding failure is shown in Figures 4, 6, 8 and 10.

Now we consider the accuracy of computation for probabilities $P_c$, $P_d$, and
$P_e$ of the above example schemes. If the wordlength of the computer under
consideration is at least $r_1 = n_1 - k_1$, then the exact value of $B_{1}^{(1)}(\bar{y}(1))$ can be
computed. Let $w$ be the number of bits in the mantissa of the floating point
number of the computer. Then the number of significant bits of the result
computed for $P_c$ by using (9) is no less than

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\[ w - \log_2(t+1)mn_1 \].

The number of significant bits of the result computed for \( P_d \) by using (22) is no less than

\[ \lambda = \lfloor w - \log_2(2^t mn_1) \rfloor. \]

If the computational result for \( P_e \) by using (10) is greater than

\[ 2^{-(\lambda - \delta)} \]

for a positive integer \( \delta \), then the number of significant bits of the results is greater than \( \delta \). In our computation, we used FORTRAN 77 on ACOS-1000 whose number of bits in the mantissa of the quadruple precision floating point number is 124. For \( m=4 \) and \( n_1=31 \), if the computational result for \( P_e \) is greater than \( 10^{-24} \) or for \( m=64 \) and \( n=63 \), if the computational result for \( P_e \) is greater than \( 10^{-22} \), then the number of significant (decimal) digits is greater than 3.

6. **Throughput Efficiency**

The error control scheme presented in this paper is actually a hybrid ARQ scheme [2], which is a combination of forward-error-correction (FEC) and automatic-repeat-request (ARQ). The throughput efficiency of the scheme depends on the mode of retransmission. There are three basic modes of retransmission: namely stop-and-wait ARQ, go-back-N ARQ and selective-repeat ARQ [2]. In a stop-and-wait ARQ system, the transmitter sends a block to the receiver and waits for an acknowledgment. A positive acknowledgement (ACK) from the receiver signals that the block has been successfully decoded and accepted, and the transmitter then sends the next block. A negative acknowledgement (NAK) (or no acknowledgment) from the receiver indicates that the received block has been detected in error; the transmitter resends the block. Stop-and-wait ARQ is very simple to implement, however it is inherently inefficient because of the idle time spent waiting for an acknowledgment.
In a go-back-N ARQ, the transmitter continuously transmits blocks in order and then stores them pending receipt of an ACK/NAK for each. The acknowledgment of a block arrives after a round-trip (propagation) delay, defined as the time interval between the transmission of a block and the receipt of an acknowledgment for the block. During this interval, N-1 other blocks are also sent. Whenever the transmitter receives a NAK for a particular block, say block i, it stops transmitting new blocks. Then it goes back to block i and proceeds to retransmit block i and the N-1 succeeding blocks which were transmitted during one round-trip delay. At the receiving end, the receiver discards the erroneously received block i and all N-1 subsequently received blocks whether they are error-free or not. Retranmission continues until block i is successfully decoded. In each retransmission for block i, the transmitter resends the same sequence of blocks. As soon as block i is positively acknowledged, the transmitter proceeds to send new blocks.

Clearly, go-back-N ARQ is more efficient than the stop-and-wait ARQ. However, it still has a severe drawback. When the receiver fails to decode a block, it also rejects the next N-1 received blocks, even though many of them may be error free.

In a selective-repeat ARQ system, blocks are also transmitted continuously. However, the transmitter only resends those blocks that are negatively acknowledged (NAK'ed). After resending a NAK'ed block, the transmitter continues sending new blocks. Clearly, selective-repeat ARQ is superior to the other two ARQ schemes. However, with selective-repeat ARQ, a buffer must be provided at the receiver to store the successfully decoded blocks following a decoding failure, because ordinarily, blocks must be delivered to the destination in correct order, e.g. in point-to-point communications. Sufficient buffer (theoretically infinite buffer) must be provided at the receiver, otherwise, buffer overflow may occur and blocks may be lost.
Stop-and-wait and go-back-N ARQ's provide satisfactory throughput efficiency for data communication systems with low or moderate data rate and short round-trip delay. For systems with high data rate and long round-trip delay, e.g. satellite links, the throughput efficiency of stop-and-wait and go-back-N ARQ's becomes unacceptable, and selective-repeat ARQ must be used.

The throughput efficiency \( \eta \) of a data communication system is defined as the ratio of average number of message (or information) bits successfully accepted by the receiver per unit of time to the total number of bits that could be transmitted per unit of time. Suppose that an ideal selective-repeat ARQ (with infinite receiver buffer) is incorporated in the error control scheme proposed in this paper. Then the throughput efficiency of the scheme is

\[ \eta_{SR} = \left( \frac{1}{n} \right) (1 - P_r) \]

where \( k_2/n \) is the rate of the overall concatenated code \( C \) and \( P_r \) is the retransmission probability given by (11). Using the value of \( P_r \) given in Figure 4, 6, 8 and 10, we can compute \( \eta_{SR} \) for various bit-error-rate and \( m \).

In practice, only finite buffer can be provided at the receiver. In this case, buffer overflow may occur in a selective-repeat ARQ scheme, this reduces the throughput efficiency. However, if a sufficiently long buffer is used and if buffer overflow is properly handled, even with a reduction in throughput, selective-repeat ARQ still significantly outperforms the other two ARQ schemes. Practical schemes have been devised for handling buffer overflow [9-12]. One such scheme is the selective-repeat plus go-back-N (SR+GBN) ARQ devised by Miller and Lin [11]. With SR+GBN ARQ scheme, retransmission of an erroneous block, say block \( i \), is first carried out in selective-repeat mode. If block \( i \) fails to be successfully decoded at the \( v \)-th retransmission \( (v>1) \),
the transmitter switches to the go-back-N mode. That is, it sends no more new blocks but backs up to block $i$ and resends that block and the $N-1$ succeeding blocks that were transmitted after the $V$-th retransmission of block $i$.

Retransmission in go-back-N mode continues until block $i$ is successfully decoded, the transmitter is then switched back to selective-repeat mode. With SR+GBN mode, buffer overflow is prevented if the receiver buffer is capable of storing $(N-1)V+1$ decoded blocks. If the SR+GBN ARQ is incorporated in the proposed error control scheme, the throughput efficiency is then

$$\eta_{SR+GBN} = \frac{1 - \sum \frac{k_r}{n}}{1 + \sum \frac{(N-1)\varepsilon_{i-1}^{V+1}}{n}}.$$  \hfill (30)

We see from (30) that, for large $V$, the throughput performance of the SR+GBN ARQ approaches the throughput performance of an ideal selective-repeat ARQ.

For many data communication systems where bit-error-rate $\varepsilon$ is not very high, SR+GBN ARQ with $V=1$ or $2$ would provide very good throughput efficiency. Consider a satellite communications system with a data rate 1.54 Mbps and a round-trip delay of 700 ms. Throughput efficiencies of the three example schemes with SR+GBN ARQ are shown in Figures 11, 12 and 13 for various $m$, $k_1$, $\varepsilon$ and $V$. We see that all three example schemes with SR+GBN ARQ provide good throughput efficiency.

7. Conclusion

In this paper, a concatenated coding scheme for error control is presented. The probability of a decoding error for this scheme is derived for a binary symmetric channel. An efficient method for computing this error probability is presented. Three specific examples are analyzed, and their probabilities of a decoding error for various bit-error-rates are computed. All the example schemes provide very high reliability even for very high
bit-error-rate $\varepsilon$. For bit-error-rate $\varepsilon=10^{-4}$, a probability of decoding error in the order less than $10^{-16}$ is achieved. The first example scheme is proposed and has been adopted by NASA for error control in NASA Telecommand System. The proposed error control scheme also provides high throughput performance if a proper retransmission scheme is used.
APPENDIX A

Proof of Lemma 1

It follow from (14) that
\[
\sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} W_{i_1,i_2',\ldots,i_m} \prod_{h=1}^{m} \left( 1 + X_h^{i_h} Y_h^{i_h} \right) = \sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} \prod_{h=1}^{m} (1+X_h^{i_h} Y_h^{i_h}) n_1^{-i_h} (X_h^{j_h} + Y_h^{j_h})^{i_h}. \tag{A-1}
\]

By generalized MacWilliams' Theorem [7, p. 147] we obtain the following identity,
\[
\sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} A_{i_1,i_2',\ldots,i_m} \prod_{h=1}^{m} X_h^{j_h} Y_h^{j_h} = 2^{-(n-k_2)} \sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} B_{i_1,i_2',\ldots,i_m} \prod_{h=1}^{m} (1+X_h^{i_h} Y_h^{i_h}) n_1^{-i_h} (X_h^{j_h} - Y_h^{j_h})^{i_h}. \tag{A-2}
\]

The right-hand side of (A-2) can be rewritten as
\[
2^{-(n-k_2)} \sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} B_{i_1,i_2',\ldots,i_m} \prod_{h=1}^{m} (1+X_h^{i_h} Y_h^{i_h}) n_1^{-i_h} (1-X_h^{j_h}) (1+Y_h^{j_h})^{n_1-i_h} (1-Y_h^{j_h})^{i_h}. \tag{A-3}
\]

Let \( P_s(i,n_1) \) be the Krawtchouk polynomial [7, p. 129]. Since \((1+Y)^{i_h} (1-X)^{-i_h} = \sum_{s=0}^{n_1} P_s(i,n_1) Y^s \) [7, p. 130], it follows from (A-1) and (A-3) that
\[
\sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} A_{i_1,i_2',\ldots,i_m} \prod_{h=1}^{m} \left( \sum_{s=0}^{n_1} P_s(i_h,n_1) Y_h^{s_h} \right) = 2^{-(n-k_2)} \sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} B_{i_1,i_2',\ldots,i_m} \prod_{h=1}^{m} \left( 1+X_h^{i_h} Y_h^{i_h} \right) \sum_{s=0}^{n_1} P_s(i_h,n_1) Y_h^{s_h}. \tag{A-4}
\]
Taking the terms on both sides of (A-4) for which the degree of $Y_h$ is $t$ or less for $1 < h < m$ and substituting one for $Y_h$ with $1 < h < m$, we have that

$$n_1 \sum_{i_1 = 0}^{n_1} \cdots \sum_{i_m = 0}^{n_1} \sum_{j_h = 0}^{m} w_{i_h} X_h = 1 \sum_{i_1 = 0}^{A_1} \cdots \sum_{i_m = 0}^{A_m} X_{i_1, i_2, \ldots, i_m}.$$ 

Substituting $\epsilon/(1 - \epsilon)$ for $X_h$ on both sides of (A-5) for $1 < h < m$, we obtain

$$n_1 \sum_{i_1 = 0}^{n_1} \cdots \sum_{i_m = 0}^{n_1} \sum_{j_h = 0}^{m} w_{i_h} \epsilon (1 - \epsilon)^{1 - i_h} = 1 \sum_{i_1 = 0}^{A_1} \cdots \sum_{i_m = 0}^{A_m} X_{i_1, i_2, \ldots, i_m}.$$ 

It follows from (17) and (A-6) that we obtain (19).
APPENDIX B

Proof of Lemma 2

Consider a parity-check matrix $H$ of the overall concatenated code $C$. $H$ has the following form:

$$
H = \begin{bmatrix}
H_{0,1} & O_0 & H_{0,2} & O_0 & \cdots & H_{0,n} & O_0 \\
H_{1} & O_1 & \cdots & O_1 \\
O_1 & H_1 & \cdots & O_1 \\
\vdots & \vdots & \ddots & \vdots \\
O_1 & O_1 & \cdots & H_1 \\
\end{bmatrix}
$$

where

1. $[H_{0,1} H_{0,2} \ldots H_{0,m}]$ is a parity-check matrix of the outer code $C_2$;
2. $H_1$ is a parity-check matrix of the inner code $C_1$;
3. $O_0$ is a $r_2 \times r_1$ zero matrix;
4. $O_1$ is a $r_1 \times n_1$ zero matrix.

Let $C_{2,ex}^\perp$ be the code generated by the first $r_2$ rows of the matrix $H$. For a codeword $\overline{v}$ in $C_{2,ex}^\perp$, its projection $\rho(\overline{v})$ is a codeword in $C_2^\perp$, and the components in $\overline{v}$ but not in $\rho(\overline{v})$ are zeros. $C^\perp$ is the direct sum of $C_{2,ex}^\perp$ and $C_1^\perp \times C_1^\perp \times \ldots \times C_1^\perp$, the $m$-th direct-product of $C_1^\perp$. Then, (21) follows directly from the definition of $B_{1}^{(1)}(\overline{u})$. 

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APPENDIX C

Proof of Theorem 1

It follows from (19) and (21) that

\[ P_d = 2^{-(n-k_2)} \sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} \prod_{h=1}^{m} B_{i_1}^{(1)} (v_h) \prod_{h=1}^{m} (1-2\epsilon) \sum_{s=0}^{i_h} P_s(i_h, n_1) \]

\[ = 2^{-(n-k_2)} \sum_{j=0}^{r_2-1} \sum_{i_1=0}^{n_1} \sum_{i_2=0}^{n_1} \cdots \sum_{i_m=0}^{n_1} \prod_{h=1}^{m} B_{i_1}^{(1)} (v_h) (1-2\epsilon) \sum_{s=0}^{i_h} P_s(i_h, n_1) \]

\[ = 2^{-(n-k_2)} \sum_{j=0}^{r_2-1} \prod_{h=1}^{m} \left[ \sum_{i=1}^{n_1} B_i^{(1)} (v_h) (1-2\epsilon) \sum_{s=0}^{i_h} P_s(i_h, n_1) \right] \]
REFERENCES


Figure 1 A concatenated coding system
Figure 2 Block format
Figure 3 The probability of undetected error $P_e$ for bit error rate $e = 10^{-2}$ and the number of information bits in a frame $k_1 = 32$ or $48$.

- ---: Example scheme 1
- - - - -: Example scheme 2
- - - - - - - -: Example scheme 3
Figure 4 The probability of retransmission $P_r$ for bit error rate $e = 10^{-2}$ and the number of information bits in a frame $k_1 = 32$ or 48.

- : Example schemes 1 and 2
- : Example scheme 3
Figure 5 The probability of undetected error $P_e$ for bit error rate $e = 10^{-3}$ and the number of information bits in a frame $k_1=32$ or 48.

--- Example schemes 1 and 2
--- Example scheme 3
Figure 6 The probability of retransmission $P_r$ for bit error rate $\epsilon = 10^{-3}$ and the number of information bits in a frame $k_1 = 32$ or 48.

- : Example schemes 1 and 2
- : Example scheme 3
Figure 7 The probability of undetected error $P_e$ for bit error rate $\epsilon = 10^{-4}$ and the number of information bits in a frame $k_1 = 32$ or 48.

- : Example scheme 1
- : Example scheme 2
- : Example scheme 3
Probability of retransmission $P_r$ for bit error rate $\varepsilon = 10^{-4}$ and the number of information bits in a frame $k_1 = 32$ or 48.

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Example schemes 1 and 2

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Example scheme 3
Figure 9  The probability of undetected error $P_e$ for the number of information bits in a frame $k_1=32$ and number of frames in a block $m=63$, and $k_1=48$ and $m=42$.

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Example scheme 1
Example scheme 2
Example scheme 3
Figure 10 The probability of retransmission $P_r$ for the number of information bits in a frame $k_1=32$ and the number of frames in a block $m=63$, and $k_1=48$ and $m=42$.

---: Example schemes 1 and 2

---: Example scheme 3
Figure 11 Throughput efficiencies of the SR+GBN ARQ with an infinite receiver buffer \((v=\infty)\) for the number of information bits in a frame \(k_1=32\) and the number of frames in a block \(m=63\), and \(k_1=48\) and \(m=42\).

--- Example schemes 1 and 2
--- Example scheme 3
Figure 12 Throughput efficiencies of SR+GBN ARQ with \( \nu = 1 \) for the number of information bits in a frame \( k_1 = 32 \) and the number of frames in a block \( m = 63 \), and \( k_1 = 48 \) and \( m = 42 \).

---

Example schemes 1 and 2

Example scheme 3
Figure 13 Throughput efficiencies of SR+GBN ARQ with $v=2$ for the number of information bits in a frame $k_1=32$ and the number of frames in a block $m=63$, and $k_1=48$ and $m=42$.

- : Example schemes 1 and 2
- : Example scheme 3