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Spectral Feature Design In High Dimensional Multispectral Data

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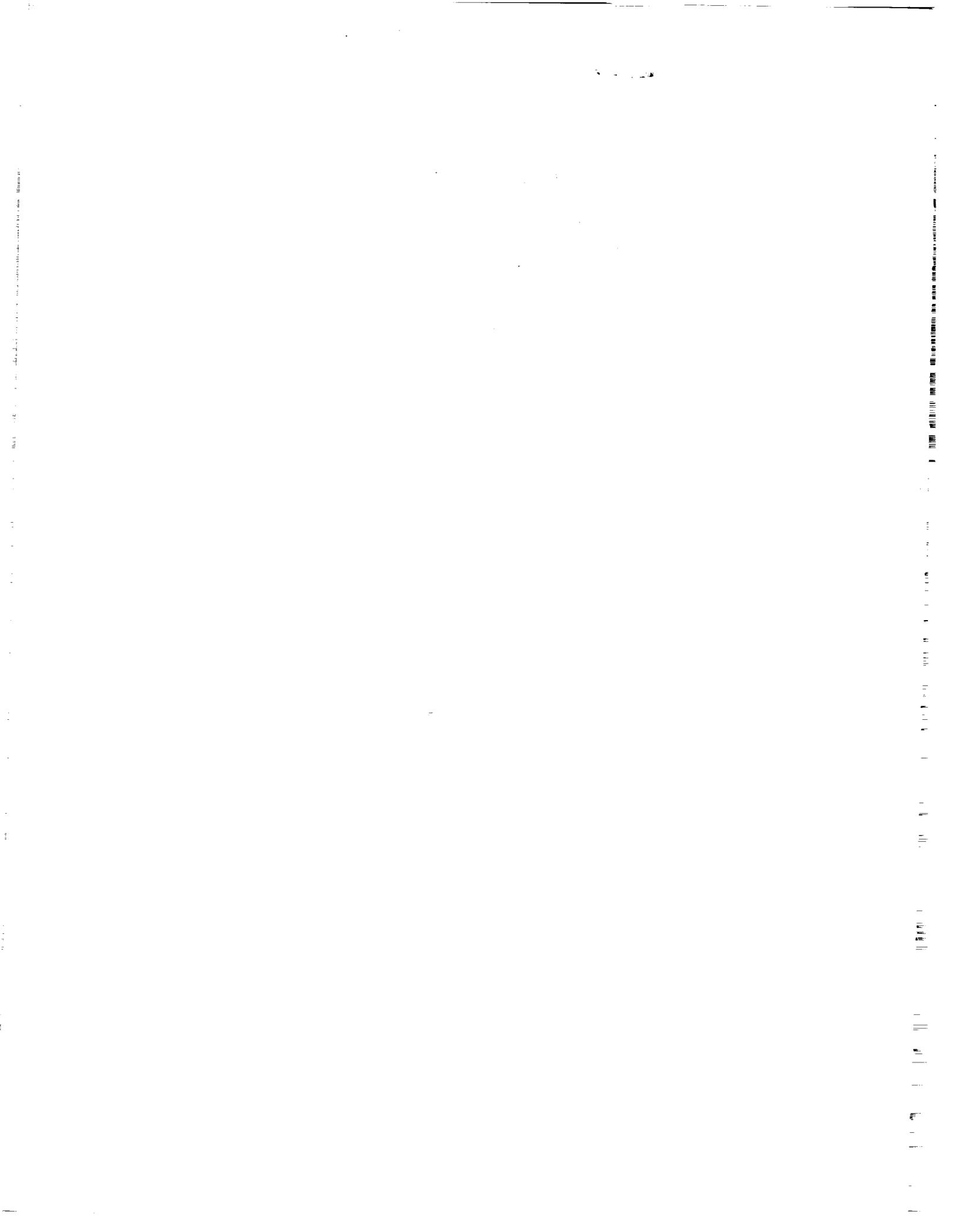
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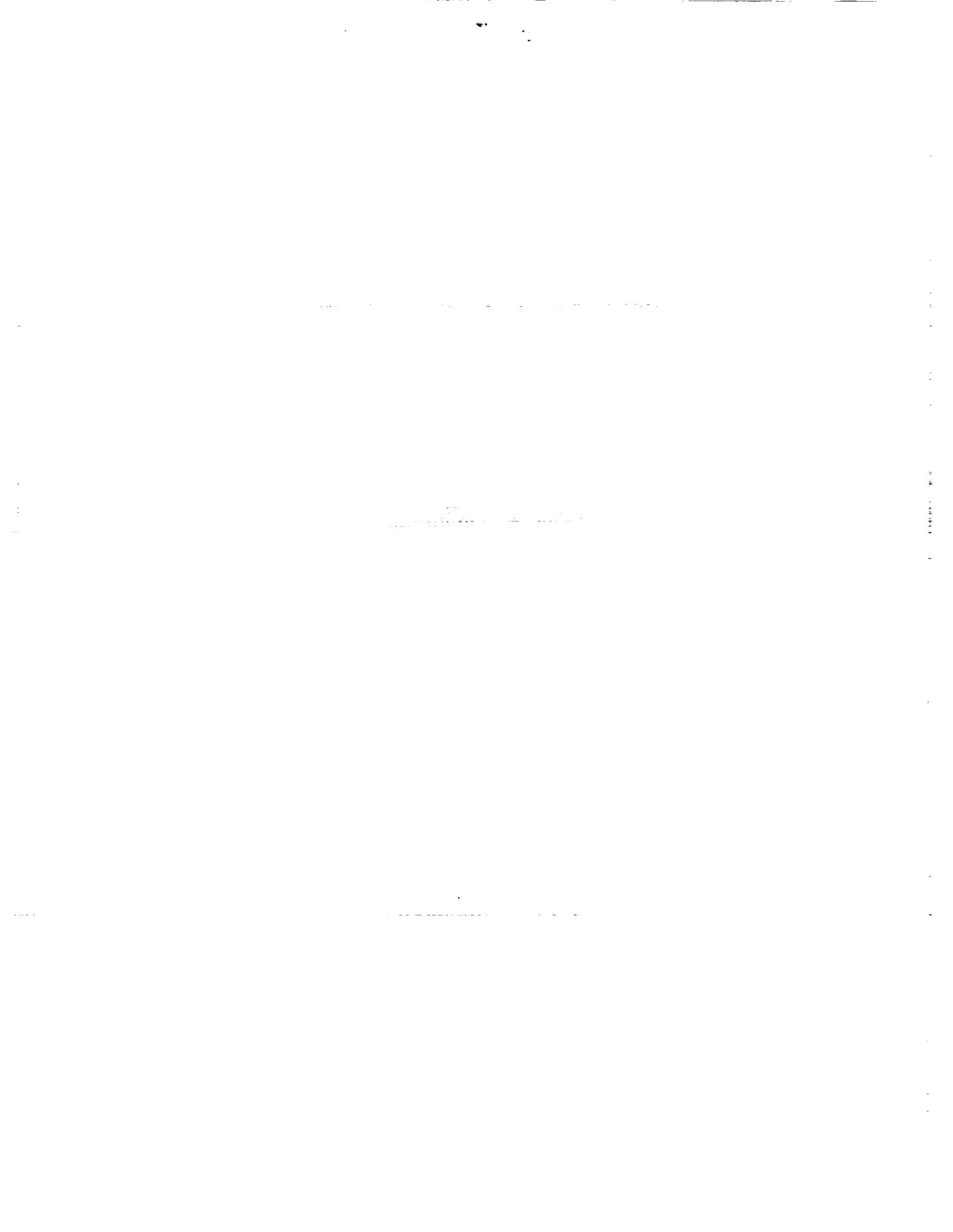


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ABSTRACT

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Professor: David A. Landgrebe. School of Electrical Engineering.

The High resolution Imaging Spectrometer (HIRIS) is designed to acquire images simultaneously in 192 spectral bands in the 0.4-2.5 μm wavelength region. It will make possible the collection of essentially continuous reflectance spectra at a spectral resolution sufficient to extract significantly enhanced amounts of information from return signals as compared to existing systems. By effectively utilizing these signals, direct identification of the parameters of species can be achieved and their subtle changes can also be observed and measured.

The advantages of such high dimensional data come at a cost of increased system and data complexity. For example, since the finer the spectral resolution, the higher the data rate, it becomes impractical to design the sensor to be operated continuously. Even operating HIRIS in a request only mode, its 512 Mbps raw data rate still constitutes a serious communication challenge. In order to solve this problem, it is essential to find new ways to preprocess the data which reduce the data rate while at the same time maintaining the information content of the high dimensional signal produced.

In this thesis, four spectral feature design techniques are developed from the Weighted Karhunen-Loeve Transforms. They are non-overlapping band feature selection algorithm, overlapping band feature selection algorithm, Walsh function approach, and infinite clipped optimal function approach. From a simplicity and effectiveness point of view, the infinite clipped optimal function approach is chosen since the features are easiest to find and their classification performance is the best. This technique approximates the spectral structure of the optimal features via infinite clipping and results in transform coefficients which are either +1, -1 or 0. Therefore the necessary processing can be easily implemented on-board the spacecraft by using a set of programmable adders that operate on the grouping instructions received from the ground station.

After the preprocessed data has been received at the ground station, canonical analysis is further used to find the best set of features under the criterion that maximal class separability is achieved.

In this research, both 100 dimensional vegetation data and 200 dimensional soil data are used to test the spectral feature design system. It will be shown that the infinite clipped versions of the first 16 optimal features derived from the Weighted Karhunen-Loeve Transform have excellent classification performance. Further signal processing by canonical analysis increases the compression ratio and retains the classification accuracy. The overall probability of correct classification is over 90% while providing for a reduced downlink data rate by a factor of 10.

CHAPTER I

INTRODUCTION

1.1 Research Objective

Due to the recent advance in optics and solid state technology, it is now possible to build sensors with much finer spectral resolution. This will provide the opportunity for collecting data for a much enriched information source. For example, the future High resolution Imaging Spectrometer (HIRIS) is planned to have as many as 192 spectral bands [1]. Since the signal dimensionality is tremendously increased, current techniques for analyzing multispectral data would not be adequate. In order to effectively utilize the information collected and achieve these benefits from the high dimensional measurements, it is essential to find new ways to process the data which reduce the data rate while at the same time maintaining the information content of the signals produced.

The fundamental objective of this research is to develop an objective and practical spectral feature design technique for high dimensional multispectral data.

One possible approach that might be used to accomplish the design objective is to tailor the spectral features to the particular analysis problem at hand. Features might be made up by grouping (i.e. summing) the narrow band response functions in particular spectral regions on board the spacecraft, based

upon the particular classes of ground cover parameters that are to be identified. The main advantage of this approach is the possibility of local optimality. Instead of finding optimal features with respect to all possible scenes (global optimal), a more practical and adaptive approach is introduced for each individual situation. The maximal attainable performance of local optimal features is indeed better and at least not worse, than that of global optimal ones. The problem then reduces to finding a means for deciding how to choose these band groupings effectively for each different analysis situation such that the data rate is greatly reduced while the classification performance is preserved or increased.

1.2 Previous Approaches

There have been basically four approaches to this feature design problem. They are (1) in-depth studies of physical considerations, (2) empirical methods, (3) simulation methods, and (4) analytical approaches.

Important physical considerations which have been investigated are atmospheric effects and the interaction of light with various cover types. By evaluating the transmittance of the atmosphere over the spectral interval of interest [2,3] , one can eliminate certain portions of the interval, since little or no information content is contained in those regions.

The interaction of electromagnetic radiation with plant leaves [4] , soils [5] and waters [6] has been studied in the past to find the most effective spectral features for discrimination. A typical procedure for these studies is to take

measurements with a spectroradiometer on restricted information classes over the entire spectrum. Then the average of the spectral responses is found and the subsequent conclusion is drawn from the average. The basic disadvantage of this approach is that only the mean value is considered. The potential information in the variance and covariance is neglected and lost.

The second method is empirical in that a scanner with many spectral bands is constructed, and the selection of the bands is done experimentally. The studies have been done with agriculture cover types [7], forest covers [8], and geological applications [9]. The main advantage of the empirical method is the retaining of the information in the variations about the mean. The correlation is considered in the feature design process. However, the spectral sampling is crude and incomplete for representing the whole spectrum.

Simulation methods have been developed [10] to generate typical spectra according to a scene model. These artificial spectral response functions are then used to choose the best set of features. However, due to the complexity of the scene and the interrelations of various parameters [11], an accurate enough model of the scene is not available yet up to present.

The recent advances in optical and solid state technologies make it possible to build high dimensional multispectral sensors such as HIRIS, with a spectral resolution of 10 nm and a spatial resolution of 30m [1]. In order to effectively utilize, including acquire, archive, retrieve, transmit and analyze the data collected, analytical feature design approaches are sought because of their objective and machine-oriented natures. Early works of this approach are found in Wiswell's and Wiersma's Ph.D dissertations. Wiswell [12] studied the

feasibility of using the maximal average mutual information [13] as a criterion to evaluate the spectral features. The best set of features are chosen so as to obtain the minimal reduction in uncertainty about the scene after the observation is made. The research showed that average mutual information is a useful concept to construct the feature sets. However the relationship between average mutual information and global performance criterion such as classification accuracy was not demonstrated. Moreover, the technique was only applied to much lower dimensional signals (about 10); the feasibility for high dimensional signals in the range of one or two hundred spectral bands was not shown.

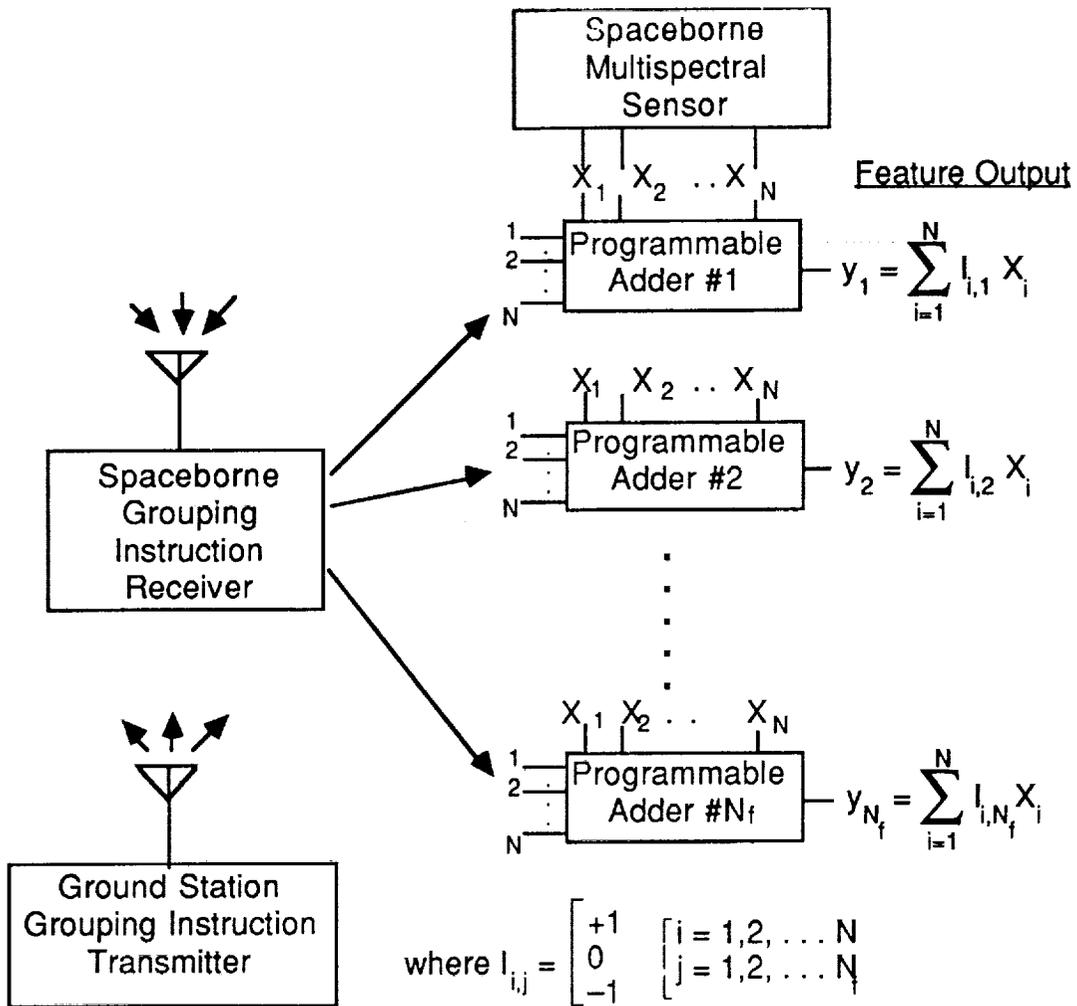
Wiersma and Landgrebe [14,15] proposed the use of minimum mean square representation error criterion for feature design. It was shown that an analytical feature design procedure can be established by applying a weighted Karhunen-Loeve Transform [16,17,18] to the observation space in which the eigenvectors of the transform are the optimal (though impractically complex) spectral features. The dimensionality in this research was 100 which was much higher than that in Wiswell's work. A manual band feature selection was suggested according to the relative importance of spectral regions as indicated by the eigenfunctions. The concept of spectral dominancy was introduced although the final stages of the feature design process were manually implemented. This appears to be tedious and impractical when the number of cover types is greatly increased. Another drawback in Wiersma's work lies basically in the subjective nature of the manual feature design process.

1.3 Current Investigation

The research results presented here will adopt some procedures to extend Wiersma's work in such a way that objective, machine implemented spectral feature design schemes become feasible. The idea of local optimality is introduced in this thesis. Instead of finding the features that are optimal with respect to all possible scenes (global optimal), it is now proposed to tailor the spectral features to the specific user problem at hand. The maximally attainable performance can then be increased. The new concept of structure similarity and its realization are discussed in this dissertation. This makes the feature design problem more general in the sense that overlapping features become practical and easily implemented.

In this research four methods are developed which in effect lead to suboptimal but now practical versions of the optimal features. These derived spectral features were obtained by combining groups of adjacent spectral samples into bands, usually one or more hundred nanometers wide, that are specially tailored to the analysis task at hand. These features could be implemented by utilizing simple programmable adders at the sensor output as shown in Figure 1.1

ON-BOARD FEATURE FORMATION SYSTEM SCHEMATIC DIAGRAM



N = no. of Spectral Samples collected
 N_f = no. of Spectral Features desired

Figure 1.1 Realization of Spectral Feature Design

In Figure 1.1, N is the signal dimensionality from the sensor output, and N_f is the number of spectral features used. The programmable adders on board the spacecraft act according to the received grouping instruction from the ground station, either adding (+1), subtracting (-1) or omitting (0) bands for each spectral function. The resulting features are then transmitted down to the ground station for further processing.

The first method is based on the dominance property of the spectral bands. A manually subjective selection process was used previously in Wiersma's work [14,15]. In this research, an objective and machine oriented process is developed. The spectral band edges are found by applying infinite clipping [21] to the average of the first few eigenvectors associated with the largest eigenvalues. This technique is referred to as a non-overlapping (N.O.L.) band feature selection algorithm due to the fact that designed features are not overlapping.

The second approach utilizes a transformation from the optimal feature space to a new space based upon Walsh Functions (W.F.) [19,20]. These functions have the attractive features of being everywhere equal to either +1 or -1, and being ordered by the number of axis crossings. Thus the transformation can be implemented by either adding or subtracting bands, and the various functions will correspond to spectral ranges of a variety of widths.

The third scheme applies infinite clipping (I.C.) [21] to the original optimal functions derived from the weighted K-L transform. The resulting features are the infinite clipped optimal functions. In this thesis, the experiment concludes

that this scheme is the most promising technique in the sense of best classification performance under the same compression requirement.

The fourth approach extracts the zero crossing information from each optimal function and chooses those spectrum intervals that are in between two zero crossings as band features. Since the band features derived from each optimal function in this way might be linearly dependent [22], special precaution must be taken to get rid of linearly dependent bands. This method is called overlapping (O.L.) band feature selection algorithm because the bands derived by this scheme are overlapping.

1.4 Preliminary Test of the On-Board Preprocessing System

From a simplicity and effectiveness point of view, not all the four developed approaches are ideal for data preprocessing. Six preliminary test data sets are used to select the best technique. The goal is to find the most effective scheme under the simplicity requirement. Of the six sets of high spectral resolution field measurement data, three were taken over Williams County, North Dakota, each with 3 information classes: spring wheat, summer fallow and natural pasture. The other three were taken over Finney County, Kansas, again with 3 information classes each: winter wheat, summer fallow, and grain sorghum or other crops. For convenience, these data sets are referred to with a letter/number designator as shown in Table 1.1.

These data were taken by the Field Spectrometer System (FSS) [23] mounted in a helicopter. The spectral resolution was $0.02 \mu\text{m}$ for the interval from $0.4 \mu\text{m}$ to $2.4 \mu\text{m}$.

Table 1.1 Data Set Designation for Preliminary Test

Location	Date	Designation	#of Observ.
Kansas	9/28/76	K1	832
Kansas	5/03/77	K2	1551
Kansas	6/06/77	K3	1477
N. Dakota	5/08/77	N1	1265
N. Dakota	6/29/77	N2	1239
N. Dakota	8/04/77	N3	1444

For each of the six data sets, the collection of the spectral sample functions forms the ensemble of a random process. The mean vector and the covariance matrix of this ensemble are first estimated. The estimate of the covariance matrix is used to solve the generalized Karhunen-Loeve equation which results in the eigenvalues and the eigenvectors of the transform. Figure 1.2 shows the magnitude of the first 12 eigenvectors associated with the largest eigenvalues for the data set K2 [15]. They will be used to explain the feature design schemes in chapter III. The spectral interval is $0.02 \mu\text{m}$ as stated previously. Therefore the dimensionality used in these preliminary tests is 100.

From this preliminary test, it is concluded that the infinite clipped optimal transform is the simplest and most effective method for on-board data preprocessing.

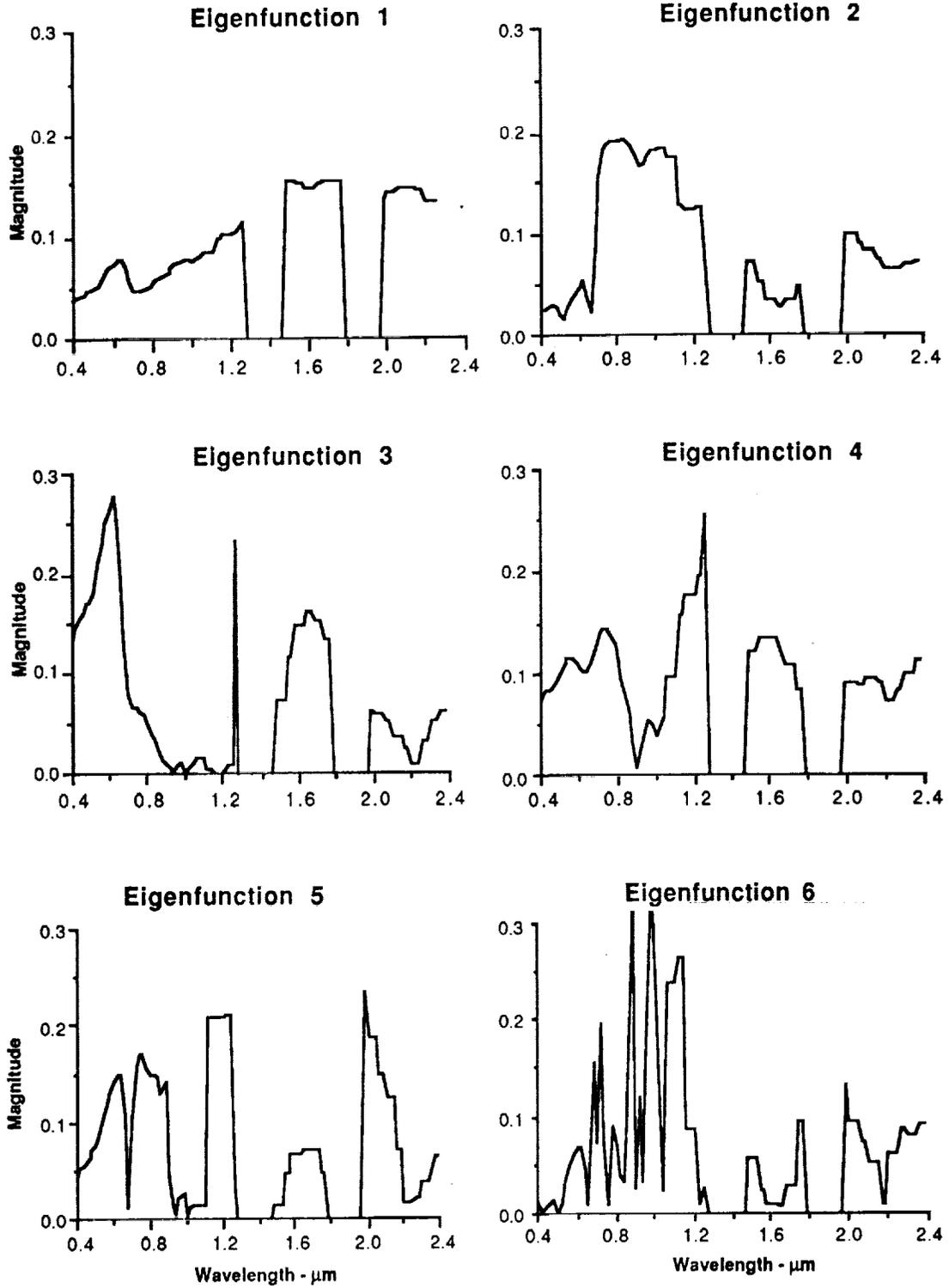


Figure 1.2 First 12 Eigenvectors of Data Set K2

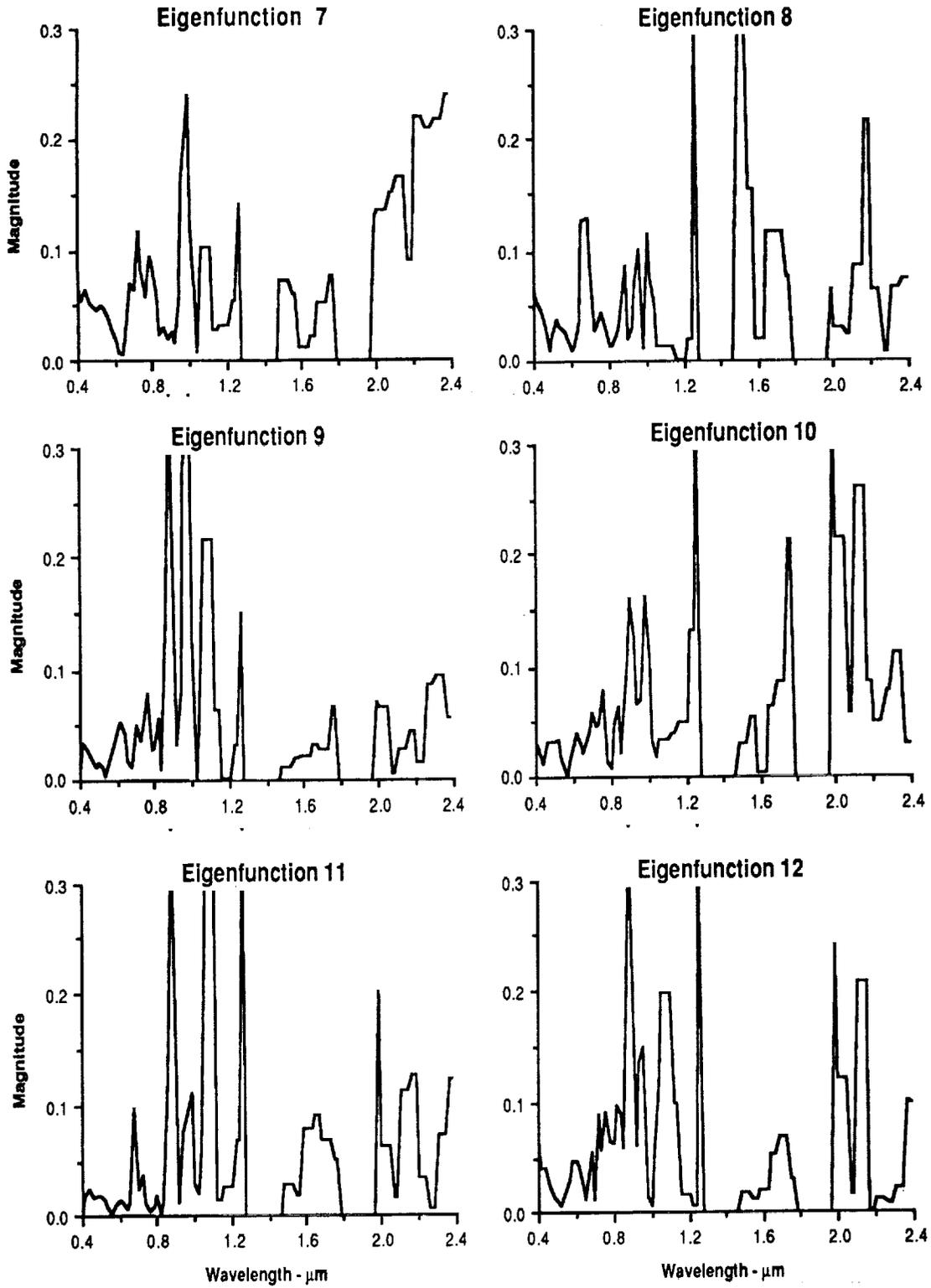


Figure 1.2, continued

1.5 Outline of the Thesis

In chapter 2, a theoretical review of the weighted K-L transform is given. Two important properties, minimum mean square truncation error and uncorrelated transformed coefficients are proved for this generalized transform.

Chapter 3 discusses in detail the four schemes developed to design the spectral features in high dimensional multispectral data. Two of them, non-overlapping band feature selection algorithm and overlapping band feature selection algorithm, are developed from the dominance concept in eigenfunctions; and the other two, Walsh function approach and infinite clipped optimal function approach are derived from the idea of structure similarity between two sets of functions. Furthermore, a comparison among these data preprocessing schemes is included in this chapter. From the simplicity and effectiveness point of view, it is found that the infinite clipped optimal function approach is the best technique. After the preprocessed data would be received at the ground station, canonical analysis would be applied to the infinite clipped optimal transformed data to obtain maximal class separability.

Chapter 4 shows the final results of this research. Both the vegetation data and the soil data are included in this chapter. The Hughes phenomenon is also discussed.

Chapter 5 summarizes the final conclusions and gives recommendations for the future work.

An IBM 3083 Macro file used to run the spectral feature design system and the source code of the system are given in the appendices.

CHAPTER II

KARHUNEN-LOEVE TRANSFORM

The Karhunen-Loeve (KL) expansion [44] was developed to represent random processes. It maps the continuous parameter random process into a sequence of random variables [24]. The expansion generates a set of deterministic orthonormal basis functions. This set has a unique error-minimizing property and uncorrelated transformed coefficients. These properties make it the optimal coordinate system for many feature design problems.

This transform can be generalized [25,26] to include a weighting function to account for certain types of a priori knowledge of the parameter set, and its proper use may have an important impact on the extraction of useful information [15]. Thus using the weighted form of K-L transform may result in more practical and realizable feature design.

In the following we will show that minimum mean square truncation error (MMSE) and uncorrelated coefficients properties, which are directly related to this research, also hold for the generalized K-L transform. The MMSE property ensures that the eigenfunctions associated with the largest eigenvalues derived from the weighted K-L transform are the optimal basis functions in the sense of signal representation. Uncorrelated coefficients property guarantees that the transformed coordinates are independent under Gaussian assumption.

2.1 Minimum Mean Square Truncation Error

Let $X(\lambda)$ be a sample function of a random process. Assume that the random process is continuous in probability and almost every sample function of the random process has finite norm in $L_2(\Lambda)$ space [27]. Then $X(\lambda)$ can be represented by an expansion of the form [24]

$$X(\lambda) = \sum_{i=1}^{\infty} y_i \Phi_i(\lambda) \quad (2.1)$$

where the functions $\{\Phi_i(\lambda)\}$ are deterministic and the expansion coefficients $\{y_i\}$ are random variables.

Define a weighting function $W(\lambda)$ with real finite positive values. Without loss of generality, the set $\{\Phi_i(\lambda)\}$ will be taken to be orthonormal with respect to $W(\lambda)$. From the generalized inner product [27] which defines the metric in $L_2(\Lambda)$ space, we have

$$(\Phi_i, \Phi_j)_W = \int_{\Lambda} \Phi_i(\lambda) W(\lambda) \Phi_j(\lambda) d\lambda = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases} \quad (2.2)$$

and

$$y_i = (\Phi_i, X)_W = \int_{\Lambda} \Phi_i(\lambda) W(\lambda) X(\lambda) d\lambda \quad (2.3)$$

If the set $\{\Phi_i(\lambda)\}$ is not orthonormal to begin with, it can be orthonormalized by the Gram-Schmidt procedure [57]. That such sets exist in $L_2(\Lambda)$ space has been demonstrated by the construction of sets such as

complex sinusoids, Legendre polynomials, Chebyshev polynomials, Laguerre functions, Walsh functions and others.

Therefore $\mathbf{Y} = \{ y_1, y_2, \dots \}$ is simply an orthonormal transformation of the random function $X(\lambda)$, and is itself a random vector. Each component of \mathbf{Y} is a feature which contributes to representing the observed sample function $X(\lambda)$.

Furthermore, we are going to choose a set $\{\Phi_i(\lambda)\}$ which is complete in $L_2(\Lambda)$ space. That is, if we define the sequence

$$c_n(\lambda) = \sum_{i=1}^n y_i \Phi_i(\lambda) \quad (2.4)$$

then,

$$\lim_{n \rightarrow \infty} \left\{ \int_{\Lambda} [X(\lambda) - \sum_{i=1}^n y_i \Phi_i(\lambda)]^2 W(\lambda) d\lambda \right\} = 0 \quad (2.5)$$

That the sequence $c_n(\lambda)$ converges to $X(\lambda)$ in the mean square sense, is denoted by

$$X(\lambda) = \text{l.i.m.}_{n \rightarrow \infty} c_n(\lambda) \quad (2.6)$$

This convergence guarantees that the series can be made arbitrarily close to $X(\lambda)$ by increasing n in the expansion.

The problem of designing the optimal sensor then becomes that of selecting the set of complete orthonormal (CON) basis functions $\{ \Phi_i(\lambda) \}$ such that the series representation will be optimal with respect to the minimum mean square error criterion. In the stochastic environment, this representation error is taken over the ensemble of the random process. Hence, we need :

$$E \left\{ \int_{\Lambda} [X(\lambda) - \sum_{i=1}^{\infty} y_i \Phi_i(\lambda)]^2 W(\lambda) d\lambda \right\} = 0 \quad (2.7)$$

Another desirable property is that the convergence be rapid in the first few terms, that is, each additional term used in the series expansion decreases the representation error by a maximum amount . This property is called energy packing.

In the real applications, however, it is impractical to transmit an infinite or even a very large number of channels to the ground. Therefore only a finite number of terms in the expansion would be used. Let n be a finite number such that the representation error by using the first n terms in the expansion is less than T , the maximal acceptable error. Then we require the selected orthonormal basis functions $\{ \Phi_i(\lambda) \}$ to be complete in a finite n dimensional subspace of $L_2(\Lambda)$. That is, for any $T > 0$, there is an n_0 such that

$$E \left\{ \int_{\Lambda} [X(\lambda) - \sum_{i=1}^n y_i \Phi_i(\lambda)]^2 W(\lambda) d\lambda \right\} < T ; n > n_0 \quad (2.8)$$

for any $X(\lambda)$ defined in the $L_2(\Lambda)$ space.

This completeness property in finite dimensional space can guarantee that if we use the n dimensional subspace of $L_2(\Lambda)$, spanned by the first n elements of a complete orthonormal set $\{\Phi_i(\lambda)\}$, for the representation of an arbitrary signal, then the norm of the error can be made arbitrarily small by choosing n sufficiently large.

The objective then is to find the a finite set of orthonormal basis functions that have the above minimum representation error and energy packing properties. In the following, we are going to show that the eigenfunctions derived from the Weighted Karhunen-Loeve transform are just the desired optimal basis functions.

In the above finite n dimensional subspace of $L_2(\Lambda)$, suppose only m terms in the expansion will be used to estimate the observed $X(\lambda)$, then the estimate $\hat{X}(\lambda)$ can be expressed in the following form

$$\hat{X}(\lambda) = \sum_{i=1}^m y_i \Phi_i(\lambda) + \sum_{i=m+1}^n b_i \Phi_i(\lambda) \quad (2.9)$$

The constants $\{b_i\}$ are preselected. The objective is to find the basis functions and the constants $\{b_i\}$ in such a way that the minimum mean square error can be obtained.

Since we do not use all of the basis functions, the representation error due to truncation is then equal to

$$\Delta X(\lambda) = X(\lambda) - \hat{X}(\lambda) = \sum_{i=m+1}^n (y_i - b_i) \Phi_i(\lambda) \quad (2.10)$$

We define the weighted mean square error to be

$$\mathbf{WMSE} = E((\Delta X, \Delta X)_W) = E\left(\sum_{i=m+1}^n (y_i - b_i) \sum_{j=m+1}^n (y_j - b_j) \int_{\Lambda} \Phi_i(\lambda) \mathbf{W}(\lambda) \Phi_j(\lambda) d\lambda\right) \quad (2.11)$$

Since the basis functions are orthonormal, Eq (2.11) reduces to

$$\mathbf{WMSE} = \sum_{i=m+1}^n E(y_i - b_i)^2 \quad (2.12)$$

The mean square error is minimized when

$$\frac{\partial E(y_i - b_i)^2}{\partial b_i} = -2E(y_i - b_i) = 0 \quad (2.13)$$

That is, the preselected constant b_i must be equal to the expected value of the transform component $E(y_i)$.

We are left to show that when $\Phi_i(\lambda)$ is a weighted K-L basis, then the weighted mean square error is minimized. We need to minimize

$$\mathbf{WMSE} = \sum_{i=m+1}^n E(y_i - E(y_i))^2 = \sum_{i=m+1}^n \iint_{\Lambda \Lambda} \Phi_i(\lambda) \mathbf{W}(\lambda) \mathbf{K}_x(\lambda, u) \mathbf{W}(u) \Phi_i(u) du d\lambda \quad (2.14)$$

where $\mathbf{K}_x(\lambda, u)$ is the covariance function of the random process.

Using the orthonormality constraint, we can write the mean square error as the quadratic functional [19] of $\Phi_i(\lambda)$

$$\begin{aligned} \text{WMSE} &= \sum_{i=m+1}^n \int_{\Lambda} \int_{\Lambda} \Phi_i(\lambda) \mathbf{W}(\lambda) \mathbf{K}_x(\lambda, u) \mathbf{W}(u) \Phi_i(u) du d\lambda \\ &\quad - \sum_{i=m+1}^n \lambda_i \left\{ \int_{\Lambda} \Phi_i(\lambda) \mathbf{W}(\lambda) \Phi_i(\lambda) d\lambda - 1 \right\} \end{aligned} \quad (2.15)$$

Minimizing with respect to Φ_i yields [19]

$$\nabla_{\Phi_i} (\text{WMSE}) = 2 \int_{\Lambda} \mathbf{W}(\lambda) \mathbf{K}_x(\lambda, u) \mathbf{W}(u) \Phi_i(u) du - 2\lambda_i \mathbf{W}(\lambda) \Phi_i(\lambda) = 0 \quad (2.16)$$

The set $\{\lambda_i\}$ thus turns out to be the eigenvalues of the covariance function of the observed $X(\lambda)$, and the basis functions satisfy the weighted K-L equation

$$\int_{\Lambda} \mathbf{K}_x(\lambda, u) \mathbf{W}(u) \Phi_i(u) du = \lambda_i \Phi_i(\lambda) \quad i = 1, 2, \dots, n \quad (2.17)$$

From equations 2.14 and 2.17, we have

$$\text{WMSE} = \sum_{i=m+1}^n \int_{\Lambda} \Phi_i(\lambda) \mathbf{W}(\lambda) [\lambda_i \Phi_i(\lambda)] d\lambda \quad (2.18)$$

or

$$\text{WMSE} = \sum_{i=m+1}^n \lambda_i \quad (2.19)$$

If we rank the optimal functions according to the magnitudes of their associated eigenvalues from the largest to the smallest, then using the first few optimal functions in the series representation will result in the desired weighted minimum mean square error. Furthermore, the energy packing property will also be satisfied since the mean square error reduction for using each additional term in the expansion will be maximized.

2.2 Uncorrelated Transformed Coefficients

The generalized K-L transform results in uncorrelated coefficients. This property can be derived as follows. Since

$$\mathbf{Y} = \{ y_1, y_2, \dots, y_n \} \quad (2.20)$$

where

$$y_i = \int_{\Lambda} \Phi_i(\lambda) \mathbf{W}(\lambda) X(\lambda) d\lambda \quad (2.21)$$

and the covariance between y_i and y_j is defined as

$$\sigma_{i,j} = E(y_i - E(y_i))(y_j - E(y_j)) \quad (2.22)$$

Using Eq.(2.21), Eq.(2.22) becomes

$$\sigma_{i,j} = \iint_{\Lambda\Lambda} \Phi_i(\lambda) \mathbf{W}(\lambda) \mathbf{K}_x(\lambda, u) \mathbf{W}(u) \Phi_j(u) du d\lambda \quad (2.23)$$

From the Weighted Karhunen-Loeve Equation derived in Eq.(2.17), we get

$$\sigma_{i,j} = \int_{\Lambda} \Phi_i(\lambda) \mathbf{W}(\lambda) [\lambda_j \Phi_i(\lambda)] d\lambda = \begin{cases} \lambda_i & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases} \quad (2.24)$$

Therefore the transformed coefficients are uncorrelated. If the underlying distribution of the random process is Gaussian, the coefficients are then independent.

CHAPTER III

SPECTRAL FEATURE DESIGN

From the discussion in chapter 2, we know the weighted K-L transform preserves the minimum weighted mean square error (MWMSE) and ordered uncorrelated coefficients properties. In fact, the K-L transform is a special case of its generalized form with unity weight matrix. The fundamentals in remote sensing indicate [14,15] that the eigenfunctions derived in the K-L transform with unity weight matrix can not be used satisfactorily for feature design. The reason for this is basically the fact that the reflectance around the two water absorption bands has high variance and thus tends to dominate the formation of the basis functions. Therefore the spectral response in these two regions is not information-bearing. Indeed, the spectral radiance emanates mostly from the atmosphere and must be considered as noise. Understanding this important a priori knowledge about the scene, we can incorporate a weighting function into the calculation process to eliminate the effect of noise. The generalized K-L transform is then the solution. The resulting optimal functions can be used to transform the original observation space into a new feature space.

In this chapter, four spectral feature design techniques will be presented first. Using simplicity and effectiveness as criteria, the most promising technique is then selected from these four schemes for our final feature design system. The four techniques developed in the course of this research are

1. Non-overlapping band feature selection algorithm,
2. Walsh function approach,
3. Infinite clipped optimal function approach, and
4. Overlapping band feature selection algorithm.

The non-overlapping and overlapping band feature selection algorithms are derived from the shape of the optimal features. The Walsh function approach and the infinite clipped optimal function approach are developed from the structure of the optimal features.

After performing the generalized K-L transformation to the data [15], where a weight function is incorporated into the transform to avoid portions of the spectrum where the atmosphere is known to be opaque, the eigenfunctions can be found. These eigenfunctions serve as optimal features that linearly transform the original measurement space to the new space in a minimum mean square error sense [18]. However, because of the inherently complex nature of the optimal functions, an easy and fast implementation directly using them to process the tremendous amount of information collected must be found. Therefore, more realistic features are sought in order to achieve this requirement. More realistic features can be found by carefully studying the shapes of the first few eigenfunctions. The importance of a wavelength region for the purpose of accurately representing the ensemble of functions is indicated by the magnitude of the eigenfunctions in that region. It is hypothesized that the importance of a region in an ensemble-representational sense is positively correlated with (though not identical to) its importance with respect to classification accuracy. Referring to Figure 1.2, it is observed that each eigenfunction thus points to the more important regions.

For instance, the magnitude of the first eigenfunction indicates that there are 3 important regions over the entire spectrum: 0.4-1.28 μm , 1.48-1.78 μm and 1.98-2.4 μm , the magnitude of the second eigenfunction indicates that important regions are approximately 0.4-0.66 μm , 0.66-1.28 μm , 1.48-1.78 μm and 1.98-2.4 μm , etc. From the fact that the magnitude of the first eigenfunction is very similar to the soil response function, and the magnitude of the second eigenfunction is similar to the vegetation curve, it is observed that the dominant portion of the ensemble, i.e. summer fallow, winter wheat and unknown crops for this data set K2, can be shown in the first few eigenfunctions derived from the weighted K-L transform. Therefore, it is desired to choose the regions with larger magnitude in the eigenfunctions, especially from those with largest eigenvalues, as sensor bands since these regions contribute most to reduction of representation error as well as increasing of classification performance.

However, such a subjective process is difficult to carry out objectively due to the spectral detail in the eigenfunctions and the number of eigenfunctions to be examined. A machine implemented band selection algorithm based on this dominance concept in the eigenfunctions is thus sought.

3.1 Non-Overlapping Band Feature Selection Algorithm

Infinite clipping is a procedure used to transform the signal into its signed form [21]. There is evidence in various circumstances that the axis crossings of a signal carry a substantial portion of the information that the signal carries. For example, in the field of speech recognition [28-33], the infinite clipping procedure can be used to extract zero crossing information and perform

speech recovery very successfully. For example, Ewing and Taylor [29] showed that zero-crossing information from a speech signal is a feasible way for computer speech recognition; and Niederjohn, et al [30] showed that the set of zero-crossings of a speech waveform represents a nearly minimal set of informational attributes in the sense that any reordering or averaging of the zero-crossing intervals has a detrimental effect upon speech intelligibility.

Some other examples of using zero-crossing information of a signal can also be found in the fields of radar target detection [51-52], biomedical engineering [53], communications [54-55] and image processing [56]. Rainal [52] described a zero-crossing principle for detecting weak narrow-band signals immersed in Gaussian noise. An application of the zero-crossing principle to the detection problem of a stationary radar target in clutter was discussed. Masuda, et al [53] demonstrated in a biomedical context that the muscle fiber conduction velocity, which is known to be an index of the degree of muscle fatigue or muscle disease, can be accurately measured by using zero-crossing information from a surface electromyogram signal. In conventional communications, Voelcker [54] showed that an angle-modulated signal can be demodulated given only its zero-crossings; Wiley, et al [55] proposed an iterative demodulation procedure for very wide-band FM by use of a zero-crossing discriminator. Haralick [56] showed that the zero-crossing of second directional derivatives within the pixel's area can be used to detect the step edges in the image.

Thus, one possible approach to finding the desired procedure would be to apply infinite clipping to extract the zero crossing information. The input to this algorithm will be the average of the first few eigenfunctions. The output of

this algorithm is to be the band edges showing how the bands should be chosen. We will refer to this procedure as the non-overlapping (N.O.L.) band feature selection algorithm. Figure 3.1 shows the average of the first 12 eigenfunctions. After thresholding, the data of Figure 3.1 become as in Figure 3.2 where +1 represents the positive portions of Figure 3.1, -1 represents the negative portions, and 0 represents the water absorption bands centered at 1.4 and 1.9 μm respectively. It should be noted that there is no response over the above water absorption bands due to the use of the weight function in the K-L transform, which has been set 1.0 over the entire spectrum and a very small positive value in the water bands.

The band edges are found as follows: whenever a transition in sign or magnitude occurs in Figure 3.2, the wavelength of the associated band is recorded. Table 3.1 shows the results after transition operation. The band edges in Table 3.1 can be used to set up the suboptimal basis functions for data compression [refer to the 2nd column in Table 3.6].

Table 3.1. Band Edges Obtained by Infinite Clipping of the Average of the First 12 Eigenvectors for Data Set K2

Band	wavelength (μm)
1	0.40 - 0.68
2	0.68 - 0.90
3	0.90 - 0.92
4	0.92 - 0.94
5	0.94 - 1.00
6	1.00 - 1.06
7	1.06 - 1.12
8	1.12 - 1.26
9	1.26 - 1.28
10	1.48 - 1.78
11	1.98 - 2.40

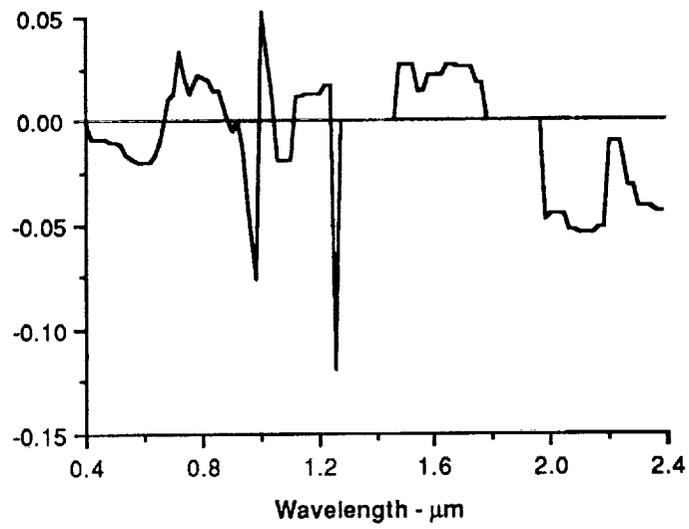


Figure 3.1 Average of the First 12 Eigenvectors of Data Set K2

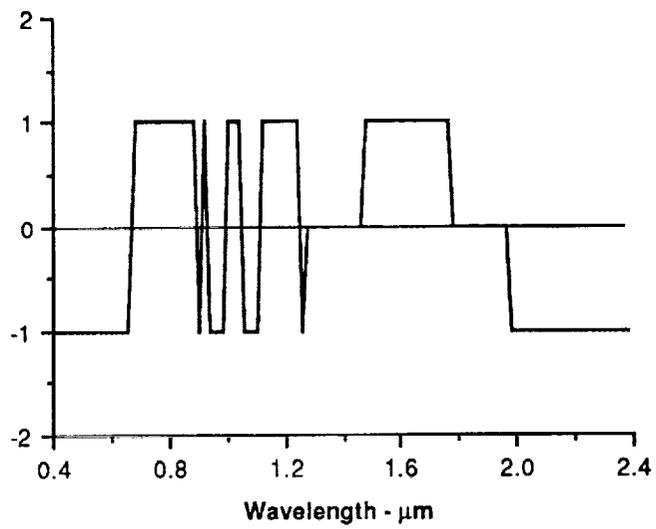


Figure 3.2 Thresholded Version of Figure 3.1

3.2 Walsh Function Approach

By carefully viewing the structure of the eigenfunctions in Figures 1.2, one may also observed that the eigenfunctions corresponding to the larger eigenvalues tend to have coarser structure than those with smaller eigenvalues. A similar effect exists in the Walsh functions indexed by the number of zero-crossings. The higher the index of the Walsh function, the finer the structure of the function [19,20]. The first 10 Walsh functions indexed by the number of axis crossings are shown in Figure 3.3, where curve 0 is the first Walsh function with no axis crossing, curve 1 is the second Walsh function with one axis crossing, etc.

The inner product of the two functions may be thought of as a mathematical measure of similarity of the two functions. The absolute values of the inner products of the first 16 eigenfunctions with the first 64 Walsh functions are calculated. Table 3.2 shows part of the results. Absolute values of the inner product are used since the polarity is not significant here. Table 3.3 shows the similarity relation between these two sets of functions. For example, the number "1" in the (1,1) matrix position indicates that the first eigenfunction is more similar to the first Walsh function than to any other 63 Walsh functions since the value 0.84 in Table 3.2 is the largest in the " first " column. The numbers "2", "3" and "4" in the (1,2), (1,3) and (1,4) matrix positions indicate that the 2nd, 3rd and 4th eigenfunctions mostly look like the 2nd, 3rd and 4th Walsh functions respectively in the sense of signal structure similarity. Therefore, the structure of the first 4 eigenfunctions can be approximated by that of the first 4 Walsh functions. By observing the first two rows of Table 3.3, it can be concluded that the first 16 eigenfunctions and the first 16 Walsh functions have approximately

the same structure. The structure in the eigenfunctions is related to the axis crossings in the signals. The coarser the structure, the less the number of axis crossings; and vice versa. These axis crossings are hypothesized to contain important information that can be used for classification. Therefore, it is feasible to use the first few Walsh functions as spectral features in high dimensional multispectral data.

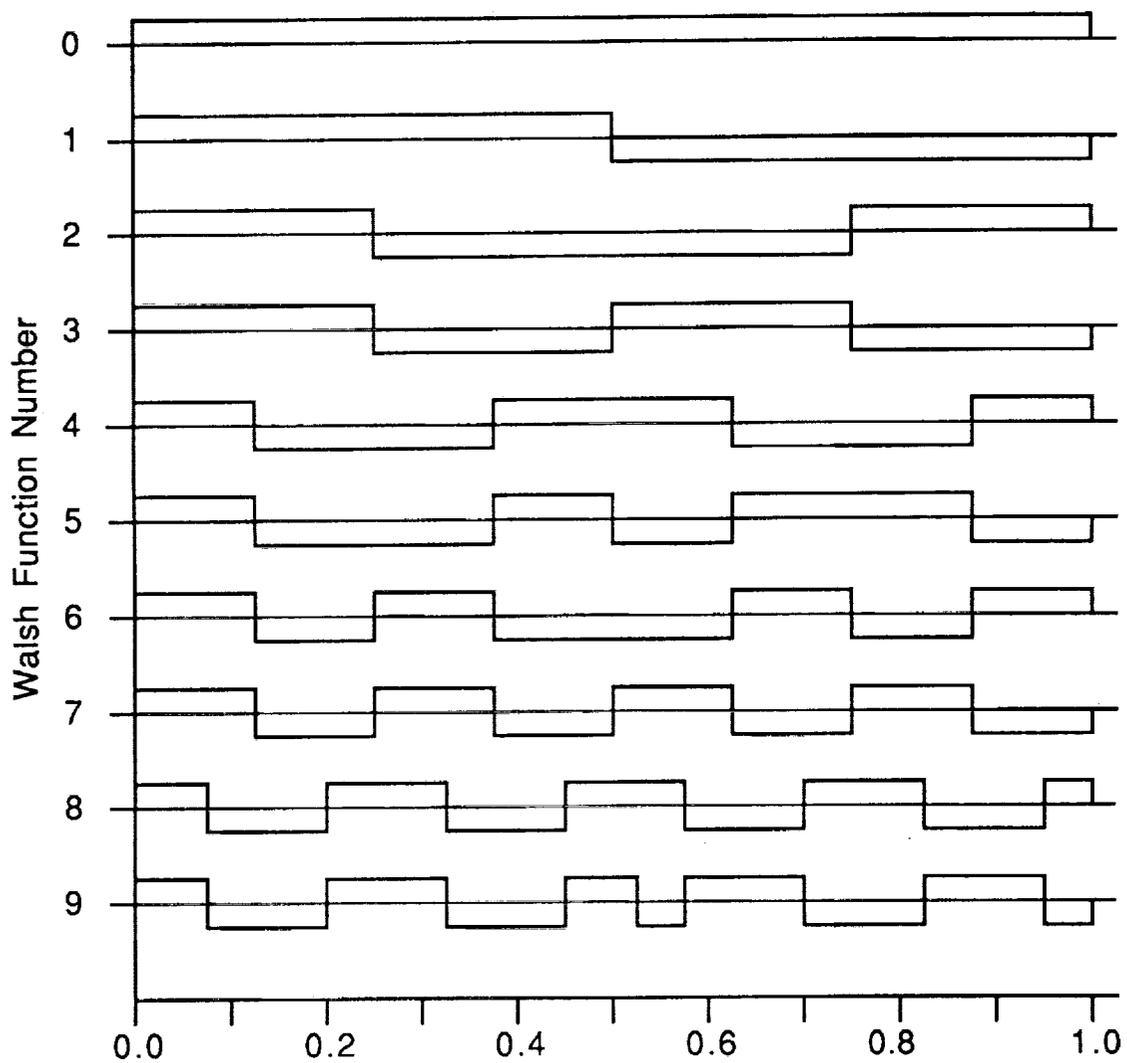


Figure 3.3 First 10 Walsh Functions Indexed By Number of Axis Crossings

Table 3.2 Absolute Values of Inner Products Between Optimal Functions and Walsh Functions

Optimal#	1	2	3	4	5	6	7	8
Walsh#								
1	0.84	0.21	0.21	0.09	0.01	0.01	0.00	0.00
2	0.21	0.68	0.42	0.12	0.24	0.01	0.13	0.03
3	0.04	0.23	0.66	0.05	0.43	0.02	0.17	0.17
4	0.09	0.03	0.09	0.78	0.12	0.01	0.03	0.09
5	0.04	0.39	0.13	0.05	0.40	0.03	0.13	0.17
6	0.11	0.32	0.09	0.01	0.28	0.14	0.33	0.25
7	0.06	0.11	0.13	0.09	0.20	0.35	0.23	0.10
8	0.03	0.10	0.15	0.06	0.03	0.03	0.52	0.36
9	0.25	0.07	0.03	0.05	0.29	0.14	0.16	0.28
10	0.12	0.05	0.26	0.24	0.27	0.02	0.20	0.14
11	0.13	0.15	0.21	0.06	0.15	0.08	0.18	0.15
12	0.03	0.15	0.05	0.32	0.09	0.07	0.21	0.02
13	0.02	0.18	0.00	0.04	0.08	0.00	0.09	0.03
14	0.15	0.10	0.04	0.15	0.00	0.07	0.09	0.10
15	0.08	0.03	0.09	0.16	0.09	0.15	0.01	0.14
16	0.03	0.04	0.03	0.04	0.20	0.18	0.05	0.10

Optimal#	9	10	11	12	13	14	15	16
Walsh#								
1	0.01	0.00	0.01	0.01	0.03	0.04	0.01	0.05
2	0.00	0.03	0.08	0.08	0.07	0.04	0.02	0.06
3	0.00	0.04	0.06	0.00	0.07	0.02	0.06	0.09
4	0.12	0.18	0.18	0.14	0.06	0.04	0.02	0.00
5	0.13	0.21	0.02	0.09	0.04	0.14	0.14	0.19
6	0.09	0.24	0.03	0.07	0.29	0.02	0.16	0.16
7	0.07	0.09	0.05	0.10	0.02	0.39	0.23	0.03
8	0.03	0.05	0.10	0.03	0.06	0.15	0.15	0.13
9	0.22	0.06	0.08	0.29	0.21	0.19	0.13	0.07
10	0.07	0.10	0.32	0.00	0.06	0.27	0.12	0.17
11	0.14	0.16	0.08	0.10	0.14	0.07	0.01	0.40
12	0.21	0.00	0.05	0.23	0.08	0.14	0.11	0.16
13	0.01	0.11	0.33	0.19	0.13	0.08	0.00	0.09
14	0.11	0.00	0.24	0.12	0.08	0.10	0.07	0.08
15	0.27	0.06	0.06	0.05	0.18	0.07	0.05	0.04
16	0.12	0.24	0.19	0.01	0.01	0.07	0.02	0.05

Table 3.3 Similarity Relation Between Optimal Functions and Walsh Functions

Optimal#	1	2	3	4	5	6	7	8
Rank	Walsh#							
1	1	2	3	4	3	7	8	8
2	57	5	2	12	5	36	6	9
3	9	6	59	60	9	16	7	6
4	2	3	10	10	6	40	28	22
5	14	1	11	15	10	35	12	18
6	11	58	1	14	2	19	10	24
7	10	13	58	2	7	23	25	64
8	33	11	8	52	16	15	11	3
9	6	12	27	29	21	63	3	5
10	58	59	7	7	59	9	24	50
11	47	7	5	35	58	32	9	11
12	4	42	50	1	11	6	64	19
13	25	8	35	50	26	20	30	25
14	15	14	4	17	28	54	2	36
15	42	25	15	43	45	47	19	10
16	18	18	26	57	49	57	5	17

Optimal#	9	10	11	12	13	14	15	16
Rank	Walsh#							
1	15	17	13	9	6	7	20	11
2	22	16	10	22	23	10	24	19
3	9	6	14	12	19	21	18	20
4	12	21	26	62	9	9	7	5
5	18	5	58	54	28	33	19	36
6	50	19	16	52	15	8	52	27
7	17	53	49	13	34	5	6	50
8	49	20	38	47	29	12	8	51
9	54	4	4	43	38	49	33	10
10	26	51	55	20	11	42	5	6
11	11	43	23	34	13	31	9	12
12	36	42	44	18	25	29	30	22
13	5	11	17	50	55	28	10	34
14	29	18	31	61	52	18	50	52
15	16	61	37	30	62	14	12	8
16	35	49	63	33	44	46	44	18

3.3 Infinite Clipped Optimal Function Approach

If one studies the Walsh functions more carefully, it is found that although the Walsh functions approximate the optimal functions in the sense of structure similarity, they do distort some of the spectral spacing information in the optimal functions. The axis crossing separation in the optimal functions is a relatively irregular pattern, while it is quite regular in the Walsh functions.

One way that can be applied to avoid this information loss is to use the infinite clipped optimal functions as spectral features. The infinite clipped optimal function approach preserves the zero-crossing information in the optimal functions which is hypothesized to contain important spectral information that can be used for classification.

Furthermore, the Walsh function approach is less flexible than the infinite clipped optimal function approach since the spectral features using the Walsh functions tend to be fixed for all analysis situations; while, on the other hand, the infinite clipped optimal function approach does give some degree of adaptability. Figure 3.4 shows the infinite clipping versions of the first 6 eigenfunctions for data set K2.

The infinite clipped optimal functions, derived from the signs of the optimal functions, are then used as spectral features (i.e., basis functions) to linearly transform the high dimensional multispectral data to the ground station for further processing.

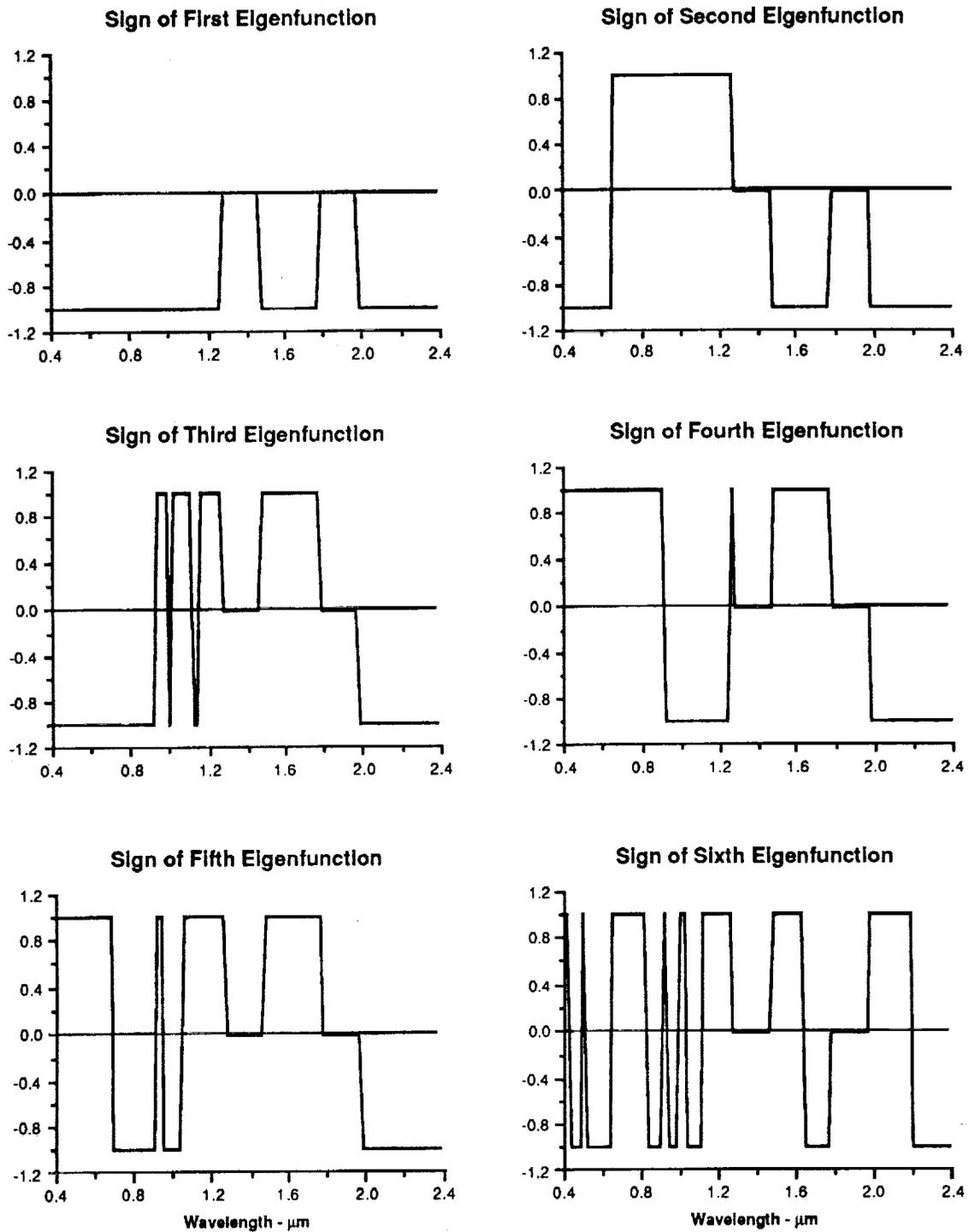


Figure 3.4 Infinite Clipping Versions of the First 6 Eigenfunctions for K2

3.4 Overlapping Band Feature Selection Algorithm

The overlapping band feature selection algorithm originates from the inherent overlapping property of the optimal functions. This property suggests that overlapping bands might be even more powerful for spectral feature design. The idea of this algorithm is to find the locations of the important spectral bands without imposing the additional restriction that the bands be non-overlapping. The basic procedures used are very similar to those in the non-overlapping band feature selection algorithm. In the non-overlapping band feature selection algorithm, the infinite clipping procedure is applied to the average of the first few eigenfunctions in order to extract the information of the important spectral bands; while in this overlapping case, the infinite clipping procedure is applied to each individual eigenfunction.

The first step is to find the band edges of each individual eigenfunction. Table 3.4 shows part of the results for data set K2. In Table 3.4, comparing to Figure 1.2, it is found that there are 3 important bands for the first eigenfunction, 4 for the 2nd one, 8 for the 3rd one, etc.

It should be noted that the band features derived in this way are not all linearly independent. For example, the first and second band feature from the second eigenfunction, that is, 0.40-0.66 μm and 0.66-1.28 μm , are linearly dependent on the first band feature from the first eigenfunction (0.40-1.28 μm). Another example is the identical band features (1.48-1.78 and 1.98-2.40 μm) derived from the first 5 eigenfunctions. Indeed, these repeated bands and the bands which are linearly dependent on the previously selected bands can not

be used as spectral features since linearly dependent features will result in singular class covariance matrix.

Table 3.4 Linearly Dependent Bands Found by Overlapping Band Feature Selection Algorithm for Data Set K2

EigenVector#	1	2	3
BAND			
1	0.40 - 1.28	0.40 - 0.66	0.40 - 0.94
2	1.48 - 1.78	0.66 - 1.28	0.94 - 1.00
3	1.98 - 2.40	1.48 - 1.78	1.00 - 1.02
4		1.98 - 2.40	1.02 - 1.12
5			1.12 - 1.16
6			1.16 - 1.28
7			1.48 - 1.78
8			1.98 - 2.40

EigenVector#	4	5	6
BAND			
1	0.40 - 0.92	0.40 - 0.70	0.40 - 0.44
2	0.92 - 1.26	0.70 - 0.92	0.44 - 0.50
3	1.26 - 1.28	0.92 - 0.96	0.50 - 0.52
4	1.48 - 1.78	0.96 - 1.06	0.52 - 0.66
5	1.98 - 2.40	1.06 - 1.28	0.66 - 0.84
6		1.48 - 1.78	0.84 - 0.92
7		1.98 - 2.40	0.92 - 0.94
8			0.94 - 1.00
9			1.00 - 1.04
10			1.04 - 1.12
11			1.12 - 1.28
12			1.48 - 1.64
13			1.64 - 1.78
14			1.98 - 2.20
15			2.20 - 2.40

An algorithm is developed to automatically choose the linearly independent bands from the first 6 eigenfunctions. Table 3.5 shows the result. Basically, this algorithm checks the rank of the matrix consisting of the bands

derived in Table 3.4. First, the linearly dependent bands in Table 3.4 are ranked from the widest to the narrowest. Then, starting from the widest band, this algorithm checks the matrix rank. If the rank is less than the total number of the band features, the band features in the matrix are linearly dependent, the widest linearly dependent band in the matrix is then eliminated from the set. On the other hand, if the rank is equal to the total number of the band features, increase the matrix rank by one and test the next widest band.

The procedure used in the above overlapping band feature selection algorithm can find the largest set of smallest bands that are linearly independent. This procedure can be summarized as follows :

- (1) Find the band edges of each individual eigenfunction
- (2) Rank these linearly dependent bands from the widest to the narrowest, then set rank $n = 1$
- (3) Starting from the widest band, check the rank of the feature matrix
- (4) If the rank is less than the total number of the bands, eliminate the widest linearly dependent band in the matrix, then go to step (3) to test the next widest band;
- (5) If the rank is equal to the total number of the bands, increase n by 1, then go to step (3) to test the next widest band
- (6) Set up the final feature set

Table 3.5 Linearly Independent Bands Found by Overlapping Band Feature Selection Algorithm for Data Set K2

Band	wavelength (μm)
1	0.70 - 0.92
2	1.98 - 2.20
3	2.20 - 2.40
4	0.66 - 0.84
5	1.48 - 1.64
6	0.52 - 0.66
7	1.64 - 1.78
8	1.16 - 1.28
9	0.96 - 1.06
10	1.04 - 1.12
11	0.94 - 1.00
12	0.44 - 0.50
13	1.12 - 1.16
14	0.92 - 0.96
15	0.40 - 0.44
16	1.00 - 1.04
17	1.00 - 1.02
18	1.26 - 1.28
19	0.50 - 0.52
20	0.92 - 0.94

3.5 Experimental System

In order to process the data in a digital computer, the spectral reflectance function $X(\lambda)$, the weight function $W(\lambda)$, the optimal basis function $\Phi_i(\lambda)$ and the sequence of the optimal basis functions $\Phi(\lambda)$ are represented by their discrete approximations, vector \mathbf{X} , diagonal matrix \mathbf{W} , basis vector Φ_i and the matrix Φ respectively.

An experimental software system has been set up to test the four approaches developed in the previous sections. This system has been

implemented on IBM 3083 computer. A collection of field data consisting of spectral sample functions on three dates from Williams County, ND, and three dates from Finney County, KS, was available from the field measurement library at Purdue/LARS. The spectral functions were sampled at $0.02 \mu\text{m}$ over the range 0.4 to $2.4 \mu\text{m}$, therefore, the dimensionality is 100.

The optimal features are found numerically by estimating the covariance matrix from the sample functions. Maximum likelihood estimates of the mean and covariance matrix are given [34] by

$$\mathbf{M}_x = E(\mathbf{X}) \approx \bar{\mathbf{X}} = \frac{1}{N_s} \sum_{i=1}^{N_s} \mathbf{X}_i \quad (3.1)$$

and

$$\mathbf{K}_x = \frac{1}{N_s - 1} \sum_{i=1}^{N_s} (\mathbf{X}_i - \bar{\mathbf{X}}) (\mathbf{X}_i - \bar{\mathbf{X}})^T \quad (3.2)$$

where N_s is the number of the sample functions and \mathbf{X}_i is the i^{th} sample vector. The covariance matrix is then used to solve the discrete form of the generalized Karhunen Loeve Equation [14,15] :

$$\mathbf{K}_x \mathbf{W} \Phi = \Phi \Gamma \quad (3.3)$$

where the Φ , Γ and \mathbf{W} are the eigenvectors, eigenvalues and the weight matrix, respectively. The solutions of the equation are the optimal features.

In order to find appropriate non-overlapping bands used in feature design, the non-overlapping band feature selection algorithm is applied to the

average of the first few eigenvectors. Three cases were studied, tests using the first 6, 12 or 24 eigenvectors in the algorithm. For the illustrative example shown in section 3.1, the second case is considered.

For overlapping band features, the infinite clipping procedure is applied to each individual eigenfunction. In this preliminary test the first 6 eigenfunctions from each of the 6 data sets are used. The locations of the important spectral bands are then extracted. After applying the overlapping band feature selection algorithm to the spectral bands derived above, the desired linearly independent (L.I.) band features are found.

The bands found by the above two algorithms, the Walsh functions or the infinite clipped optimal features developed from the structure similarity property are then used as spectral features to perform the linear transformation on the data sets.

$$y_i = \Phi_i^T W X \quad (3.4)$$

In order to test the spectral features thus determined, the probability of correct classification is estimated using them. To do so, the class-conditional statistics are first computed using the transformed data. An algorithm based on the maximum likelihood estimator [34] is then applied, where the class conditional statistics are assumed to be multivariate Gaussian.

3.6 Preliminary Results

After applying the N.O.L. band feature selection algorithm to the average of the first 6, 12 or 24 eigenvectors of the six test data sets, the band edges are found. Table 3.6 shows the results for the data set K2 for three different number of eigenvectors. These three feature sets are named as proposed sensor C1, C2 and C3 respectively. For brevity, they are denoted PC1, PC2 and PC3. On the other hand, the O.L. band feature selection algorithm is applied to the first 6 eigenfunctions, the result of the first 16 linearly independent bands is shown in Table 3.7 for data set K2.

Furthermore, the probabilities of correct classification using Landsat (LS) MSS bands, Thematic Mapper (TM) bands and the two sensors proposed in Wiersma's work (PA and PB) [14,15] are also computed here. Table 3.8 shows the band edges associated with each sensor [15].

Table 3.6 Bands Found by Non-Overlapping Band Feature Selection Algorithm for Data Set K2

Band	PC1	PC2	PC3
1	0.40 - 0.68	0.40 - 0.68	0.40 - 0.66
2	0.68 - 0.84	0.68 - 0.90	0.66 - 0.80
3	0.84 - 0.90	0.90 - 0.92	0.80 - 0.88
4	0.90 - 0.96	0.92 - 0.94	0.88 - 0.94
5	0.96 - 1.00	0.94 - 1.00	0.94 - 1.00
6	1.00 - 1.06	1.00 - 1.06	1.00 - 1.04
7	1.06 - 1.12	1.06 - 1.12	1.04 - 1.16
8	1.12 - 1.28	1.12 - 1.26	1.16 - 1.26
9	1.48 - 1.74	1.26 - 1.28	1.26 - 1.28
10	1.74 - 1.78	1.48 - 1.78	1.48 - 1.54
11	1.98 - 2.40	1.98 - 2.40	1.54 - 1.64
12			1.64 - 1.74
13			1.74 - 1.78
14			1.98 - 2.20
15			2.20 - 2.26
16			2.26 - 2.40

Table 3.7 Bands Found by Overlapping Band Feature Selection Algorithm for Data Set K2

Band	wavelength (μm)
1	0.70 - 0.92
2	1.98 - 2.20
3	2.20 - 2.40
4	0.66 - 0.84
5	1.48 - 1.64
6	0.52 - 0.66
7	1.64 - 1.78
8	1.16 - 1.28
9	0.96 - 1.06
10	1.04 - 1.12
11	0.94 - 1.00
12	0.44 - 0.50
13	1.12 - 1.16
14	0.92 - 0.96
15	0.40 - 0.44
16	1.00 - 1.04

Figures 3.5 to 3.10 are the classification performance comparisons of the optimal functions (Optimal), Walsh functions (Walsh) and the infinite clipped optimal functions (Clipped) for the 6 data sets. Figure 3.11 to 16 are the comparisons of the LS, TM, Wiersma's proposed sensor PA, non-overlapping band features (NOL) derived from the first 24 eigenfunctions (i.e., PC3), overlapping band features (OL), Walsh functions, infinite clipped optimal functions and optimal functions for the 6 preliminary test data sets. From the implementation point of view, since there are only two values (+1, -1) for the Walsh functions and three values (+1, -1, 0) for the infinite clipped optimal functions, it can be concluded from Figures 3.5 to 3.16 that representing the optimal features using their infinite clipping versions or using the first 16 Walsh functions produces the more practical features used for classification which

provide a classification accuracy quite near that of optimal features. The classification performances estimated for the above sensors are shown in Table 3.9, where PC1, PC2 and PC3 represent the sensors derived from N.O.L. band feature selection algorithm using the first 6, 12 and 24 eigenvectors as their input respectively; Optimal, Walsh and Clipped stand for the sensors using the first 16 optimal functions, the first 16 Walsh functions and the first 16 infinite clipped optimal functions as spectral features respectively.

Table 3.8 Band Edges of Landsat MSS, TM, PA and PB Sensors

Band	LS	TM	PA	PB
1	0.50-0.60	0.45-0.52	0.42-0.54	0.42-0.66
2	0.60-0.70	0.52-0.60	0.56-0.66	0.68-0.70
3	0.70-0.80	0.63-0.69	0.68-0.70	0.72-0.92
4	0.80-1.10	0.76-0.90	0.72-0.90	0.94-1.04
5		1.55-1.75	0.92-1.00	1.06-1.10
6		2.08-2.35	1.02-1.30	1.12-1.30
7			1.52-1.74	1.52-1.74
8			1.96-2.40	1.96-2.40

Table 3.9 Probability of Correct Classification for 6 Data Sets

SENSOR	K1	K2	K3	N1	N2	N3
LS	0.90	0.78	0.85	0.77	0.83	0.96
TM	0.92	0.79	0.93	0.89	0.95	0.99
PA	0.94	0.86	0.95	0.92	0.96	0.99
PB	0.94	0.85	0.94	0.89	0.96	0.96
PC1	0.94	0.87	0.96	0.92	0.97	0.99
PC2	0.96	0.88	0.97	0.94	0.97	0.99
PC3 (NOL)	0.96	0.94	0.98	0.96	0.98	0.99
OL	0.97	0.94	0.98	0.97	0.99	0.99
Walsh	0.98	0.95	0.98	0.95	0.98	0.99
Clipped	0.98	0.97	0.99	0.97	0.99	0.99
Optimal	0.98	0.97	0.98	0.97	0.99	0.99

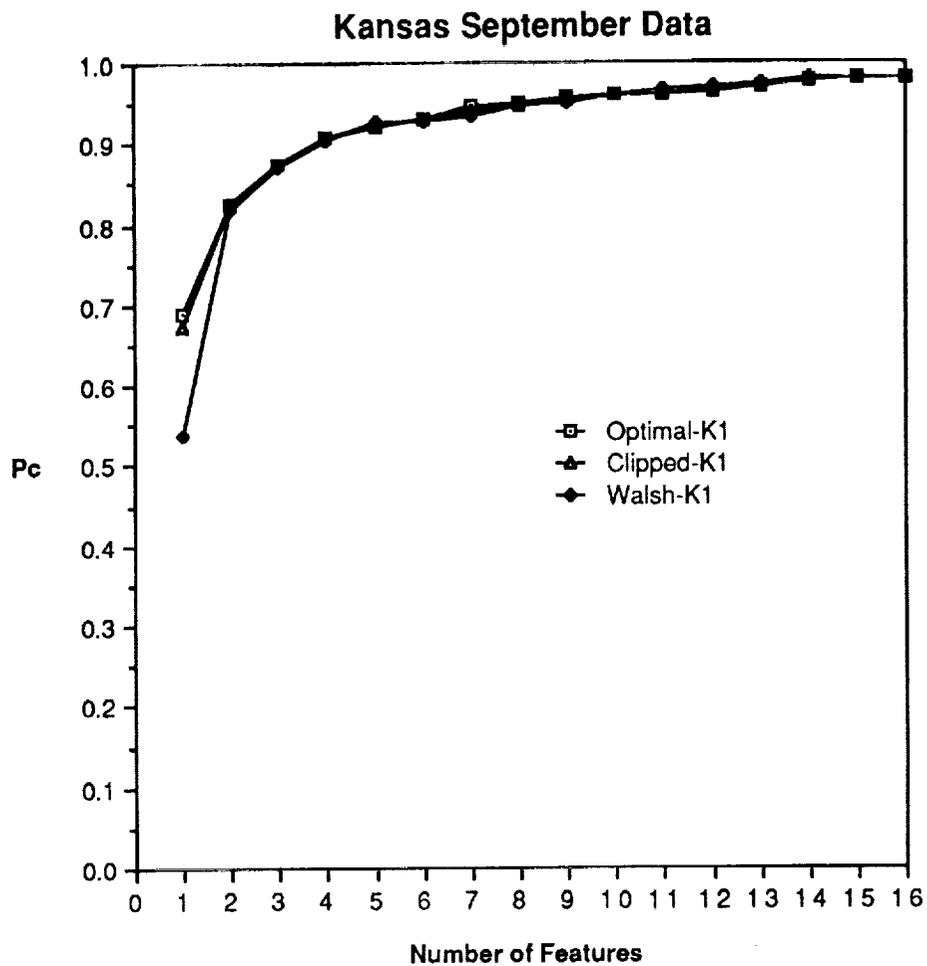


Figure 3.5 Performance Comparison of Optimal, Infinite Clipped Optimal and Walsh Functions for Data Set K1

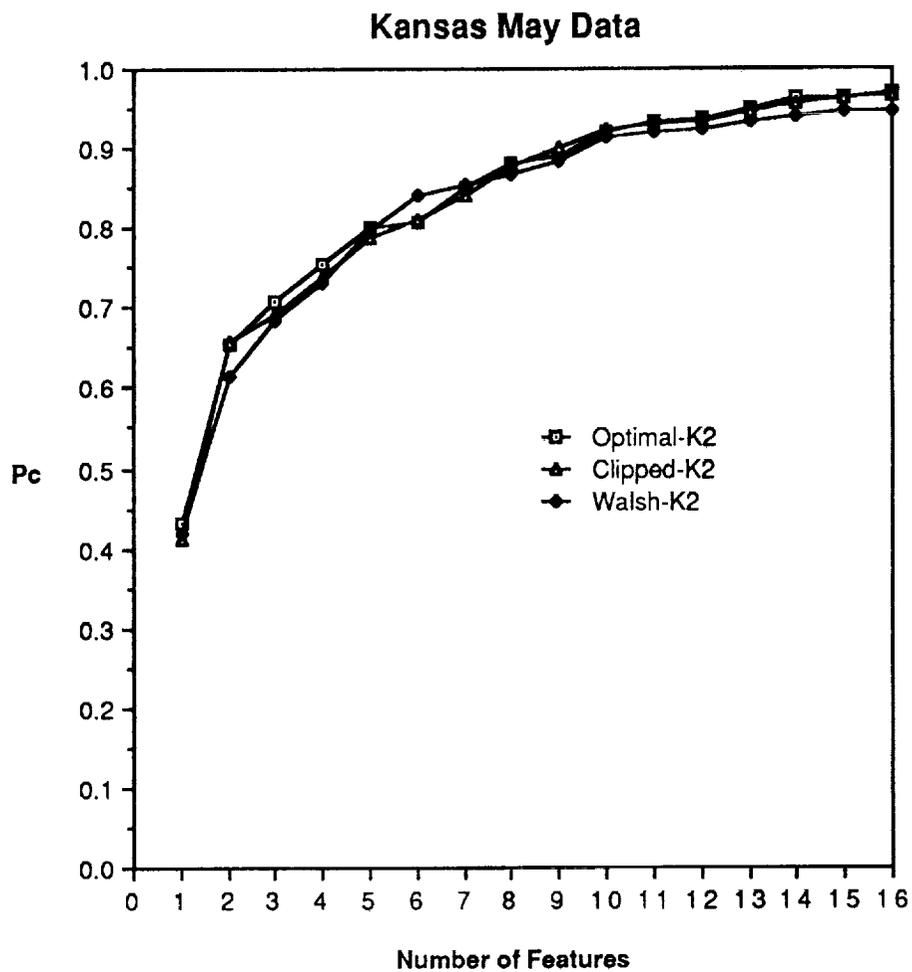


Figure 3.6 Performance Comparison of Optimal, Infinite Clipped Optimal and Walsh Functions for Data Set K2

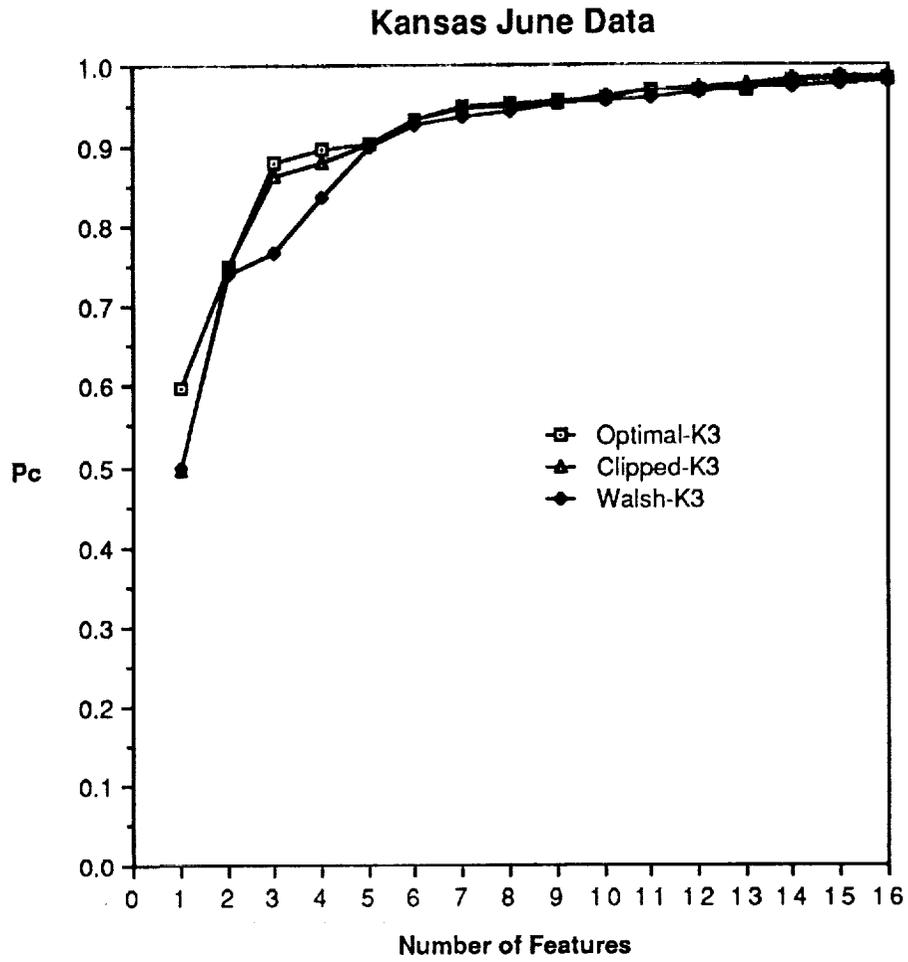


Figure 3.7 Performance Comparison of Optimal, Infinite Clipped Optimal and Walsh Functions for Data Set K3

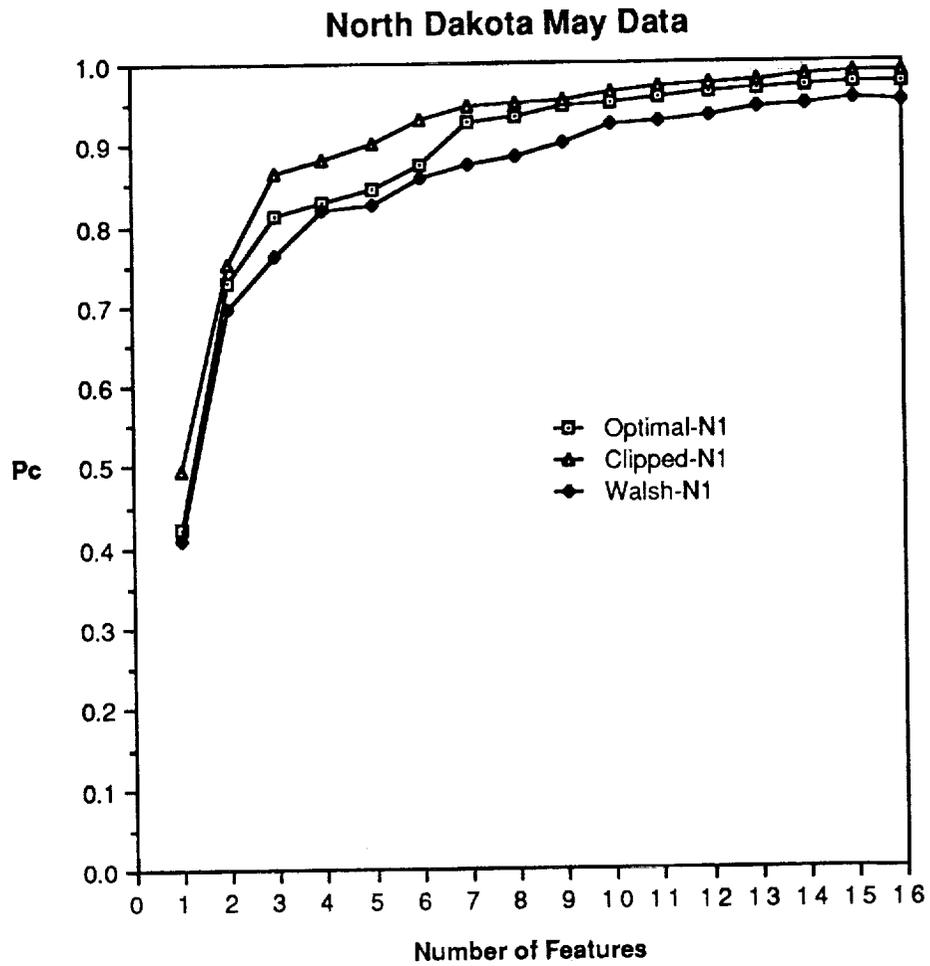


Figure 3.8 Performance Comparison of Optimal, Infinite Clipped Optimal and Walsh Functions for Data Set N1

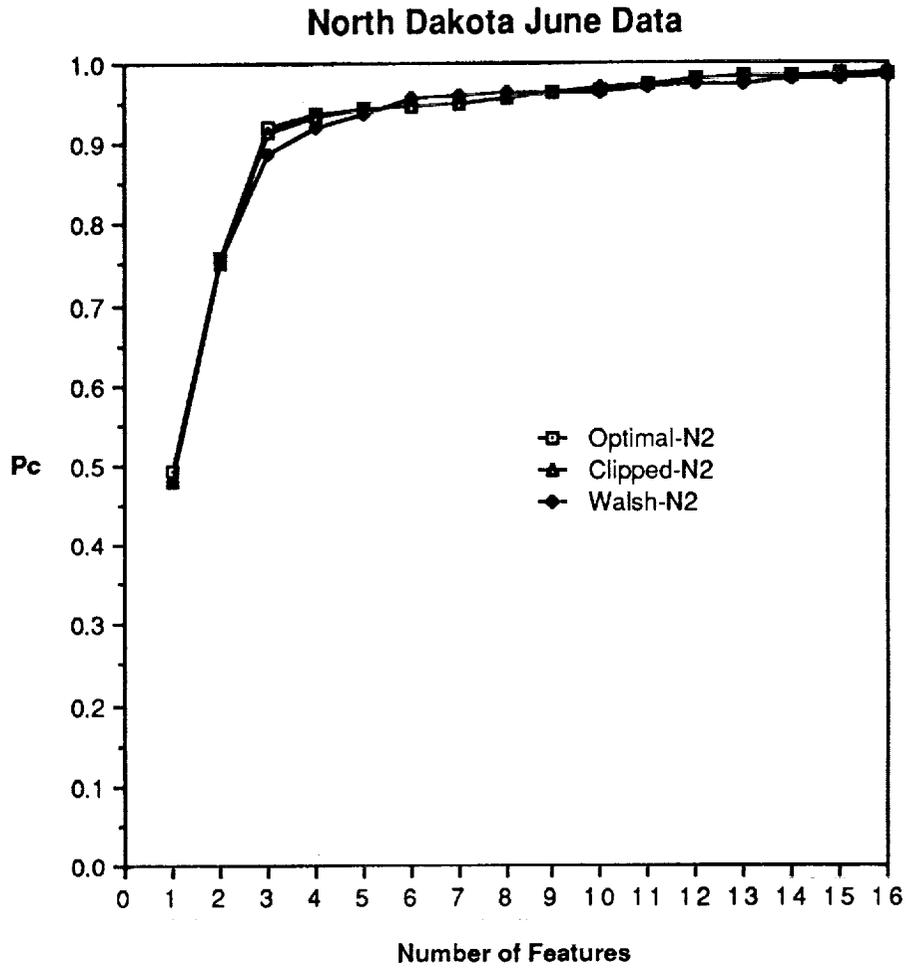


Figure 3.9 Performance Comparison of Optimal, Infinite Clipped Optimal and Walsh Functions for Data Set N2

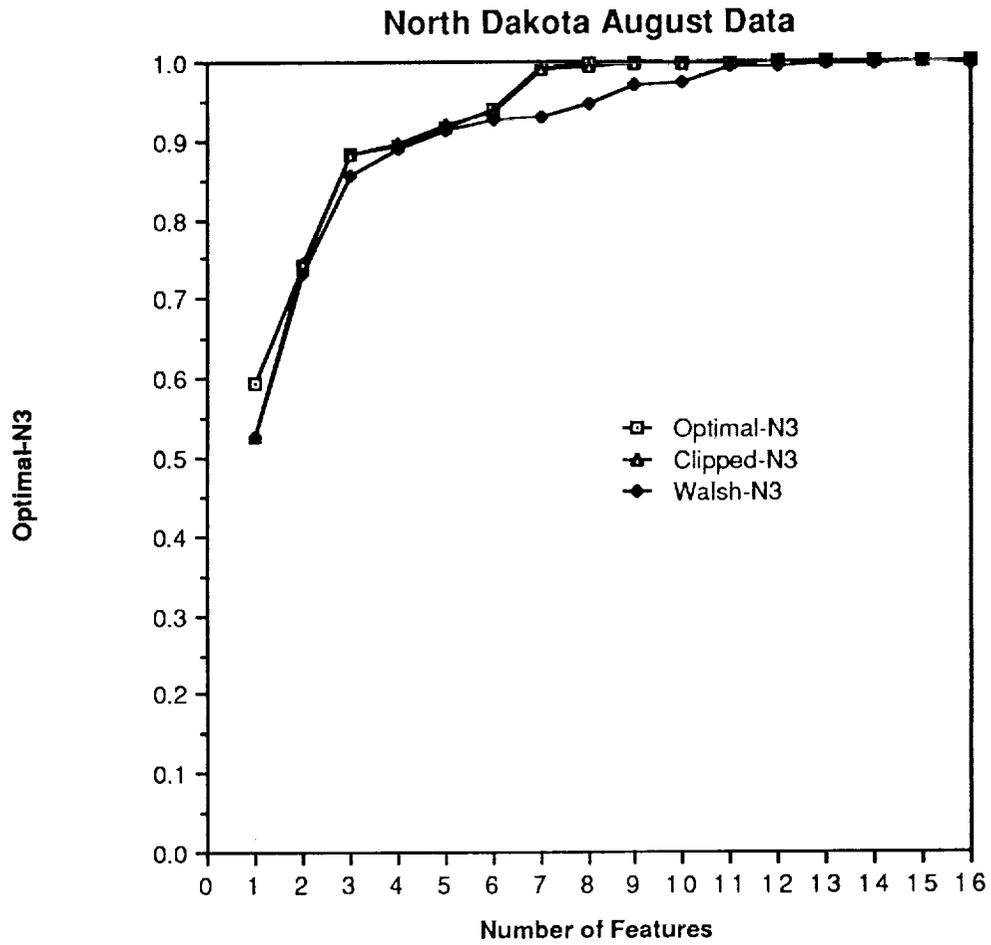


Figure 3.10 Performance Comparison of Optimal, Infinite Clipped Optimal and Walsh Functions for Data Set N3

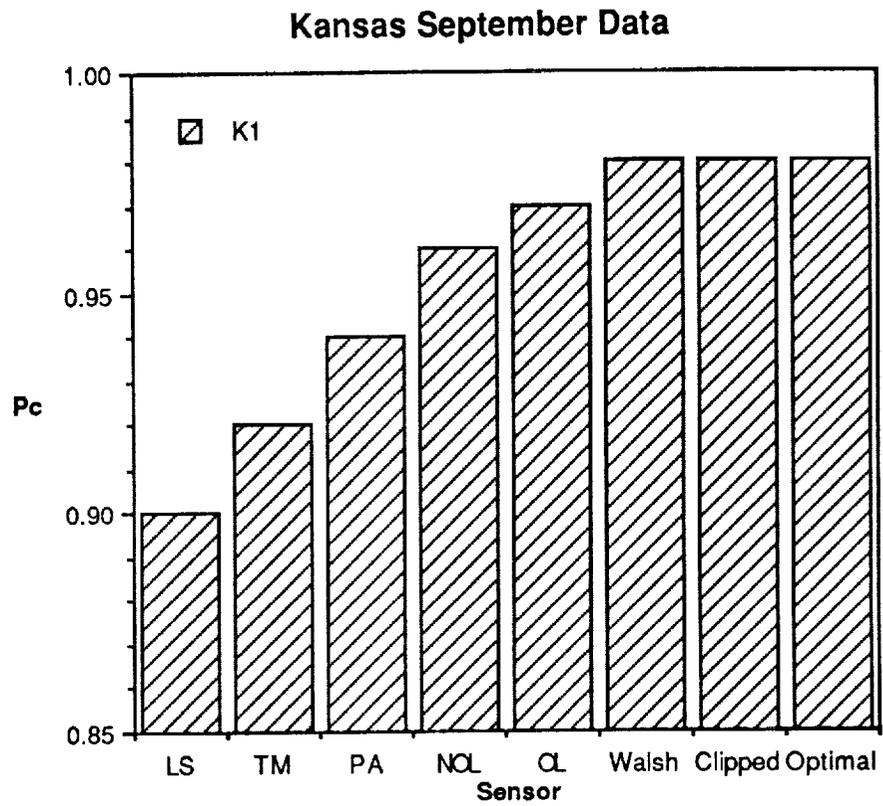


Figure 3.11 Performance Comparison for Data Set K1

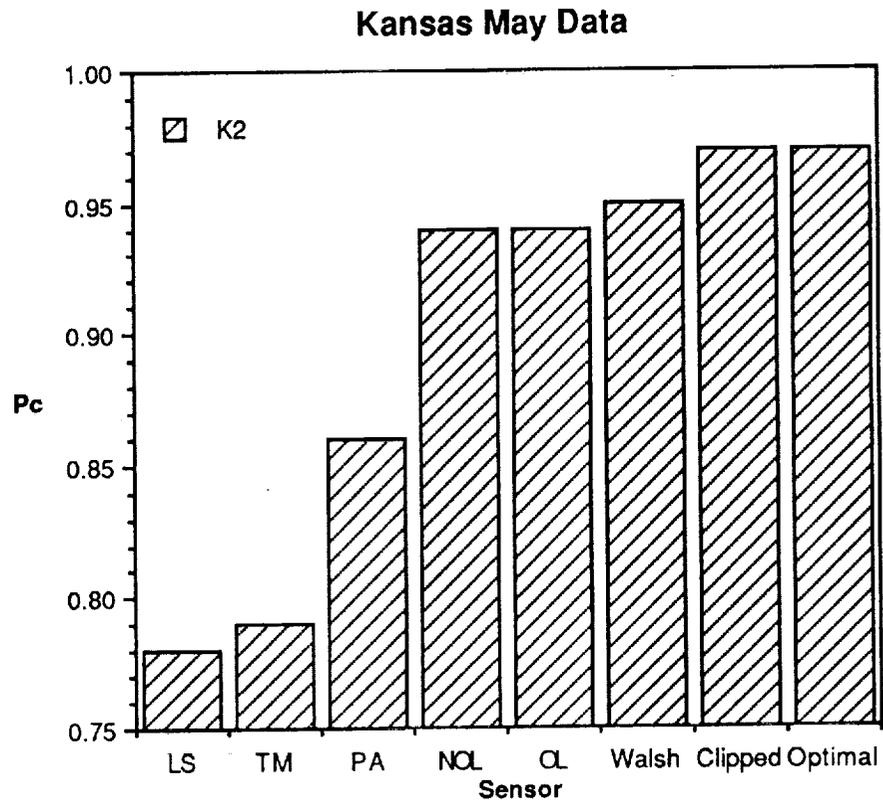


Figure 3.12 Performance Comparison for Data Set K2

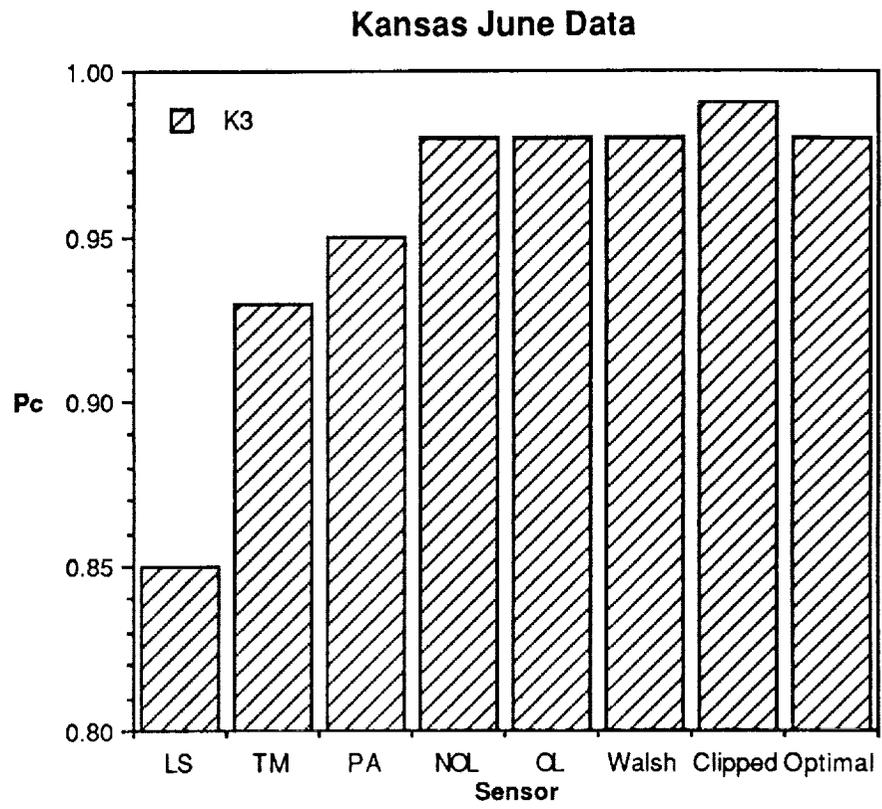


Figure 3.13 Performance Comparison for Data Set K3

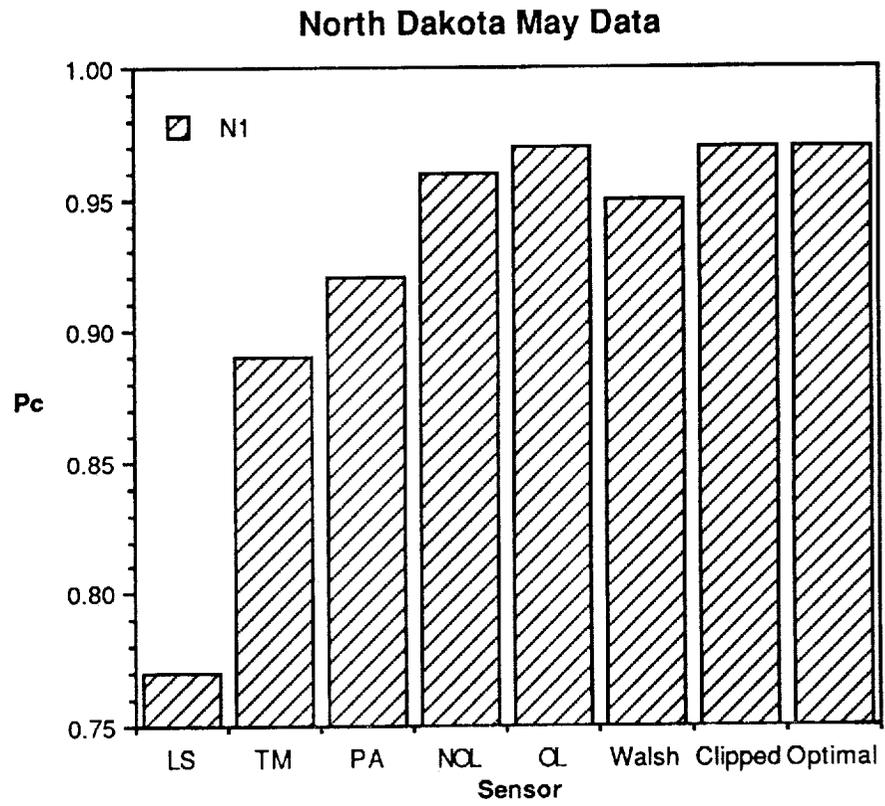


Figure 3.14 Performance Comparison for Data Set N1

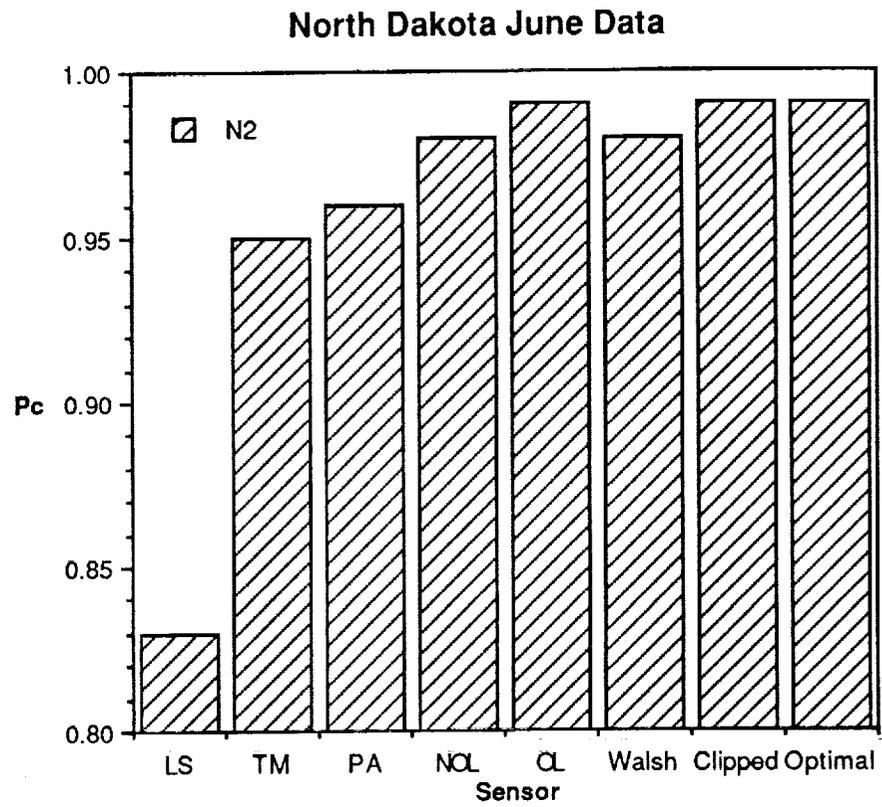


Figure 3.15 Performance Comparison for Data Set N2

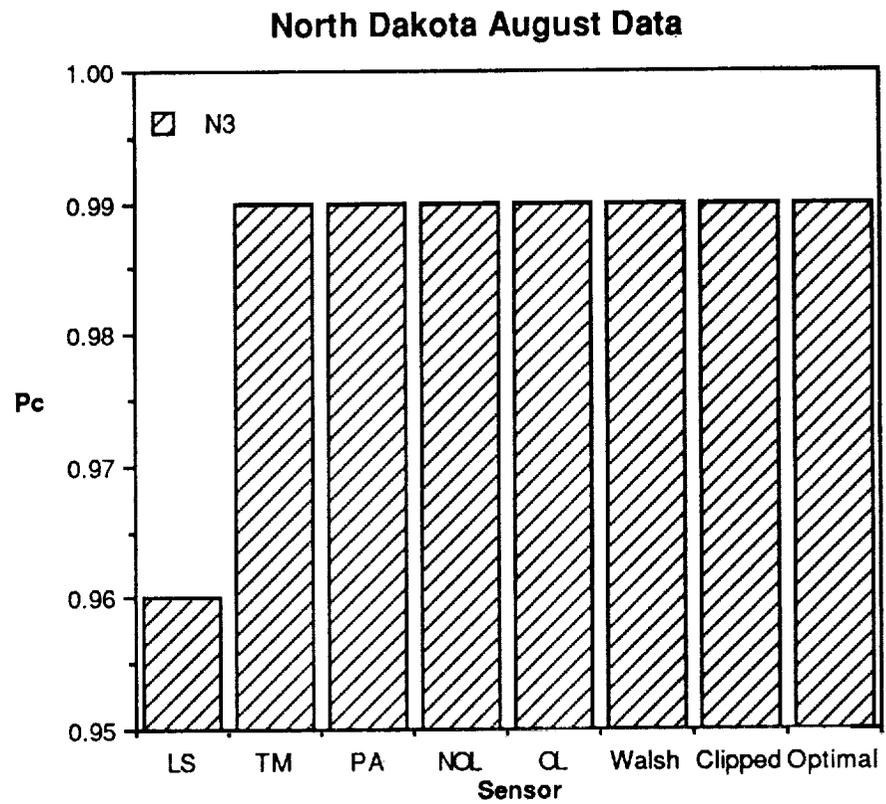


Figure 3.16 Performance Comparison for Data Set N3

3.7 Selection of the Best On-Board Preprocessing Scheme

From Table 3.9 and Figures 3.5 to 3.16, it is seen that the four approaches developed in this research, two based on the "shape" of the optimal features and the other two from their "structure" similarity with the optimal functions, are feasible ways for feature design.

The fundamental objective of this research is to develop an objective and practical spectral feature design technique for high dimensional multispectral data. There are two important factors, simplicity and effectiveness, which must be considered in this respect.

First of all, from simplicity point of view, the overlapping band feature selection algorithm is harder to perform than the other three because of the existence of linear dependence problem. In order to find appropriate overlapping band features, we have to check the rank of the matrix for each newly selected band. This procedure needs more time than the other three approaches. However, its classification performance [referring to Figure 3.11 to 3.16] does not indicate much advantage over the other three, especially the infinite clipped optimal function approach.

For example, Figure 3.11 and 3.12 show that for Kansas September and Kansas May data the performances of the overlapping band feature selection algorithm are the 3rd best among the four techniques. The infinite clipped optimal function approach and the Walsh function approach have better performances than that of the overlapping band feature selection algorithm. Figure 3.13 to 3.16 indicate that the performances of the overlapping band feature selection algorithm are never better than those of the infinite clipped

optimal function approach. Therefore, from simplicity point of view, the overlapping band feature selection algorithm would not be used in this thesis as the best technique for the final data preprocessing system.

On the other hand, from effectiveness point of view, referring to Table 3.9 and Figure 3.5 to 3.16 again, it is shown that the infinite clipped optimal transform has better performance than the Walsh transform and the non-overlapping band feature selection algorithm.

For instance, Figure 3.5 to 3.10 indicate that the infinite clipped optimal features have better classification accuracy than the Walsh features for all the six preliminary test data sets in Kansas and North Dakota. Figure 3.11 to 3.16 show that the infinite clipped optimal features perform better than the non-overlapping band features for all the 6 test data sets except for North Dakota August data (Figure 3.16) where these two techniques have the same performance.

Therefore, from simplicity and effectiveness point of view, the infinite clipped optimal transform is chosen to be the best scheme in the data preprocessing stage of the spectral feature design system.

The processing up to this point, consisting of the optimal features calculation, the infinite clipping, and the data transform is based solely upon the ensemble statistics of the field data. Additional a priori knowledge that might be used to improve the performance is the class statistics of the scene. The objective is then to find the best features under the criterion of maximal class separability.

3.8 Canonical Analysis and Ground Station Data Processing.

Canonical Analysis is a technique that can be used to find the optimal features under a maximal separability criterion [36-41]. Unlike principal component analysis, which is based on the global covariance matrix of the full data set, canonical analysis utilizes the class structure of the data. The advantage of canonical analysis is its ordering property on the separability measure. By using the features derived from canonical analysis to further process the received transformed data, the classification performance should, therefore, be improved.

Let M_i and S_i be the i^{th} class mean vector and covariance matrix of a data set with L classes. In canonical analysis one first finds the within-class scatter and the among-class scatter matrices S_w and S_a respectively :

$$S_w = \sum_{i=1}^L \frac{(N_i - 1)}{N_s} * S_i \quad (3.5)$$

where N_i is the number of samples of the i^{th} class data and N_s is the total number of samples of the ensemble. And,

$$S_a = \frac{1}{L} \sum_{i=1}^L (M_i - M_o)(M_i - M_o)^T \quad (3.6)$$

where M_o is the global mean, given by

$$M_o = \sum_{i=1}^L \frac{N_i}{N_s} * M_i \quad (3.7)$$

The within class scatter matrix, S_w , is an average quantity that describes how closely the samples are distributed around their class means while the among class scatter matrix, S_a , is a quantity measuring the average degree of closeness between the ensemble mean and each class mean. The optimally separable feature is a feature such that S_w is minimized and S_a is maximized after the transformation. Define a quantity r and let the desired feature be vector \mathbf{d} . Then the objective is to find the r and \mathbf{d} that result in maximal class separability. That is,

$$r = \frac{\mathbf{d}^T \mathbf{S}_a \mathbf{d}}{\mathbf{d}^T \mathbf{S}_w \mathbf{d}} \quad (3.8)$$

must be maximized. The ratio of variances in the new space is maximized by the selection of feature \mathbf{d} if,

$$\frac{\partial r}{\partial \mathbf{d}} = \mathbf{0} \quad (3.9)$$

The above equation can be reduced to

$$(\mathbf{S}_a - r * \mathbf{S}_w) * \mathbf{d} = \mathbf{0} \quad (3.10)$$

which is called a generalized eigenvalue equation and must be solved now for the unknown r and \mathbf{d} . The first canonical axis will be in the direction of \mathbf{d} , and r will give the associated ratio of among-class to within-class variance for that axis.

The development to this stage is usually referred to as discriminant analysis. One more step is included in the case of canonical analysis where the derived canonical features are normalized with respect to the within class scatter matrix. That is,

$$\mathbf{D}^T * \mathbf{S}_w * \mathbf{D} = \mathbf{I} \quad (3.11)$$

where \mathbf{D} is the matrix of canonical features \mathbf{d} . This says that the within class scatter matrix after the transformation must be the identity matrix. In other words, after transformation, the classes should appear spherical.

CHAPTER IV

RESULTS AND DISCUSSIONS

In the previous chapter, we have introduced the four spectral feature design techniques developed in the course of this research. Six preliminary test data sets in Kansas and North Dakota were used to test the schemes. From a simplicity and effectiveness point of view, the infinite clipped optimal transform is chosen as the better means for data preprocessing. Furthermore, canonical analysis is applied to the above received transformed data on the ground station to achieve the maximal class separability. In this chapter, both the vegetation and the soil data will be used to find the classification performance for the final spectral feature design system. The spectral range for the vegetation data is from $0.4 \mu\text{m}$ to $2.4 \mu\text{m}$ with resolution $0.02 \mu\text{m}$ while the range for the soil data is from $0.45 \mu\text{m}$ to $2.45 \mu\text{m}$ with resolution $0.01 \mu\text{m}$. Therefore the dimensionality for the vegetation data and the soil data is 100 and 200 respectively. The final results of these data will be presented in section 4.1 and 4.2. Moreover, due to the limited sample size of the data set to estimate the covariance matrix, different degree of Hughes phenomenon occurs in some of the one-day Kansas and North Dakota vegetation data sets as well as in all soil data sets. This effect will be discussed in section 4.3.

4.1 Vegetation Data

Four sets of multitemporal multispectral data collected in Kansas, North Dakota, Iowa and South Dakota are acquired to test the proposed spectral feature design system. Table 4.1 show the species, the dates on which the data were collected, and the total numbers of sample functions for each information class. In Table 4.1, the numbers appearing in the parentheses are the total numbers of sample functions collected for that class. Furthermore, W.Wheat and S.Wheat stand for winter wheat and spring wheat respectively.

Figure 4.1 to 4.6 show the probability of correct classification, P_c , using the optimal features, infinite clipped optimal features and features that are derived from infinite clipped optimal transform and canonical analysis for the six preliminary test data sets. These 6 data sets are part of the multitemporal data in Kansas and North Dakota (referring to Table 1.1 and Table 4.1). Each one of them consists of the sample functions collected on one single date and has 3 informational classes. The results indicate that using the first 16 infinite clipped versions of the optimal functions, 95% classification accuracy can be achieved.

Another important point is the occurrence of Hughes phenomenon [42,43] shown in Figure 4.1 to 4.4. It says that for data set K1, K2, K3 and N1, increasing the computational complexity [11] does not always increase the classification performance. For example, Figure 4.1 shows that canonical analysis improves the accuracy for the first 3 features, but it does not help beyond this complexity for data set K1. Figure 4.2 to 4.4 show that canonical analysis can only have better performance for the first 4 features for data sets K2, K3 and N1 respectively.

For data set N2 and N3, it is found in Figure 4.5 and 4.6 that Hughes phenomenon does not occur, and the classification performance using the features derived from infinite clipped optimal transform and canonical analysis is always better than those of the optimal features and the infinite clipped optimal features. It is also shown that only 2 features are needed to have about 94% and 99% classification accuracy for these 2 data sets respectively.

Figure 4.7 and 4.8 show the results for Kansas and North Dakota multi-temporal data. Each one has 9 information classes collected on 3 different dates from 1976 to 1977. The results indicate that canonical analysis improves the accuracy by about 15% to 25% for the first feature and about 1% for the first 16 features. Figure 4.9 is the results of Kansas and North Dakota combined data with 18 information classes. It is used to show the robustness property of this spectral feature design system. The results show that the technique is not overly sensitive for spatially and temporally combined data.

Figure 4.10 and 4.11 are the results for 25-class Iowa and 42-class South Dakota multi-temporal data. They are used to show the capability of this spectral feature design system for complex data sets. It can be seen that the system is very successful in this respect.

Table 4.1 : Vegetation Data Sets.
Numbers in the parenthesis are the total numbers of samples.

Kansas Vegetation Data Set : 9 classes

9/28/76	5/3/77	6/26/77
W.Wheat (141)	W.Wheat (658)	W.Wheat (677)
Summer Fallow (414)	Summer Fallow (211)	Summer Fallow (643)
Sorghum (277)	Unknown Class (682)	Sorghum (157)

North Dakota Vegetation Data Set : 9 classes

5/8/77	6/29/77	8/4/77
S.Wheat (664)	S.Wheat (787)	S.Wheat (931)
Summer Fallow (437)	Summer Fallow (291)	Summer Fallow (330)
Pasture (164)	Pasture (161)	Pasture (183)

Iowa Vegetation Data Set : 25 classes collected on 9 different dates of 1979;

5/15/79	5/23/79	6/11/79	6/29/79	7/16/79	7/17/79	8/30/79	10/25/79	11/2/79
Corn (514)	Corn (517)	Corn (621)	Corn (610)	Corn (437)	Corn (190)	Corn (650)	Corn (435)	Corn (393)
	Soybeans (36)	Soybeans (517)	Soybeans (485)	Soybeans (377)	Soybeans (172)	Soybeans (568)	Soybeans (417)	Soybeans (267)
Oats (41)	Oats (32)	Oats (45)	Oats (21)	Oats (22)	Oats (25)	Oats (42)	Oats (44)	

South Dakota Vegetation Data Set : 42 classes collected on 6 different dates of 1978 and 1979

9/21/78	10/26/78	6/1/79	6/21/79	7/25/79	8/11/79
Pasture (225)	Pasture (217)				
Alfalfa (61)	Alfalfa (51)			Alfalfa (45)	Alfalfa (42)
W.Wheat (292)	W.Wheat (393)				
S.Wheat (469)	S.Wheat (441)	S.Wheat (118)	S.Wheat (121)	S.Wheat (102)	S.Wheat (119)
Barley (82)	Barley (80)	Barley (43)	Barley (44)	Barley (66)	Barley (69)
Oats (182)	Oats (88)			Oats (89)	Oats (76)
IdleLand (63)					
Sorghum (103)	Sorghum (88)			Sorghum (78)	Sorghum (96)
Sunflower (39)	Sunflower (41)			Sunflower (53)	Sunflower (107)
Corn (39)	Corn (32)			Corn (147)	Corn (154)
	Millet (26)			Millet (39)	Millet (28)
				Safflower (24)	Safflower (19)

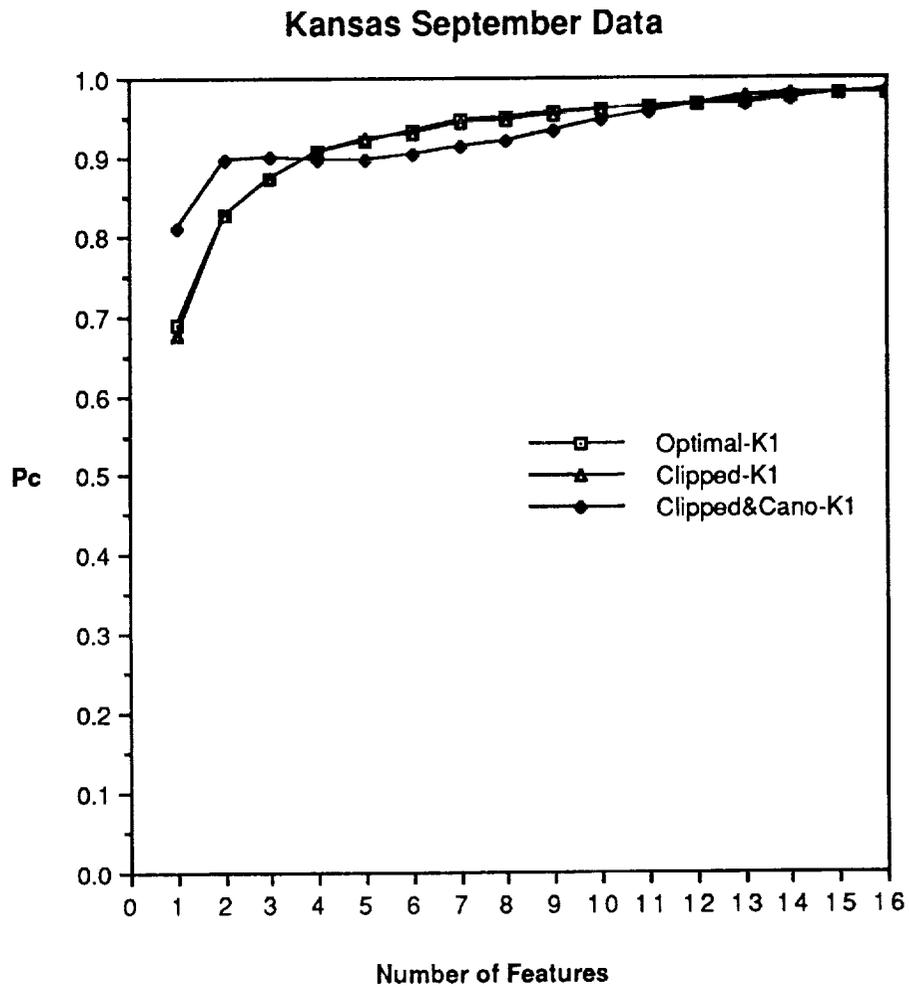


Figure 4.1 Classification Performance for Data Set K1

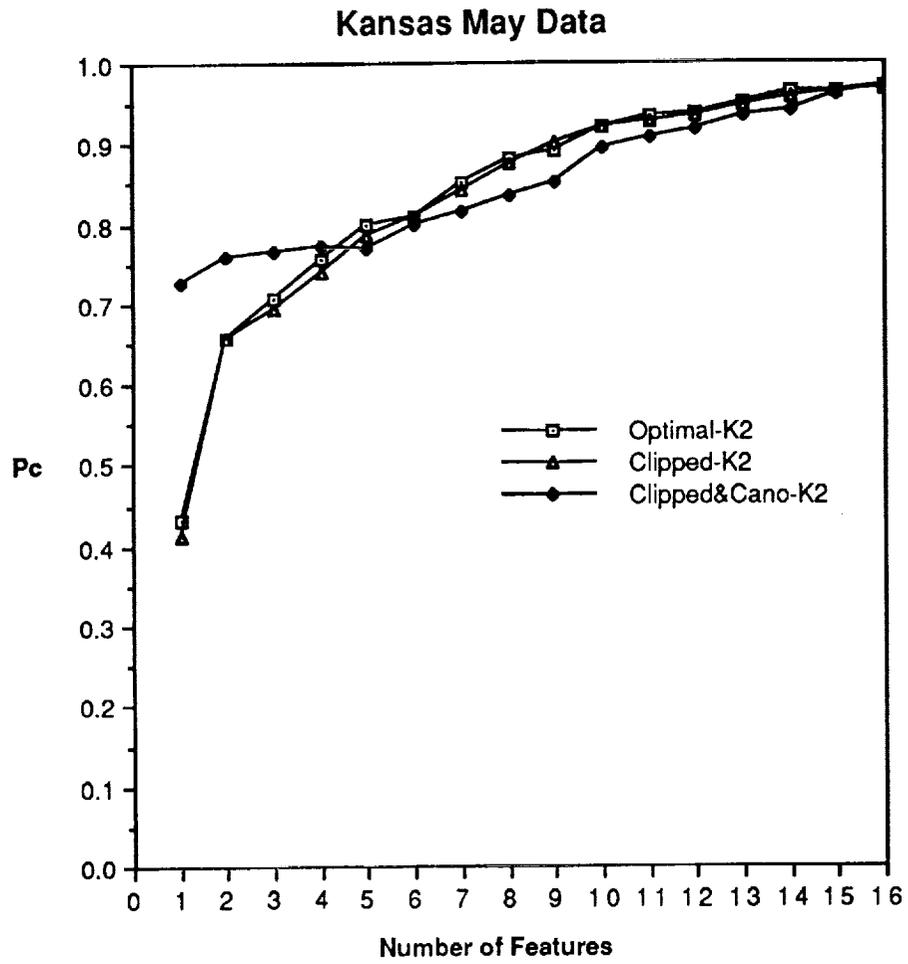


Figure 4.2 Classification Performance for Data Set K2

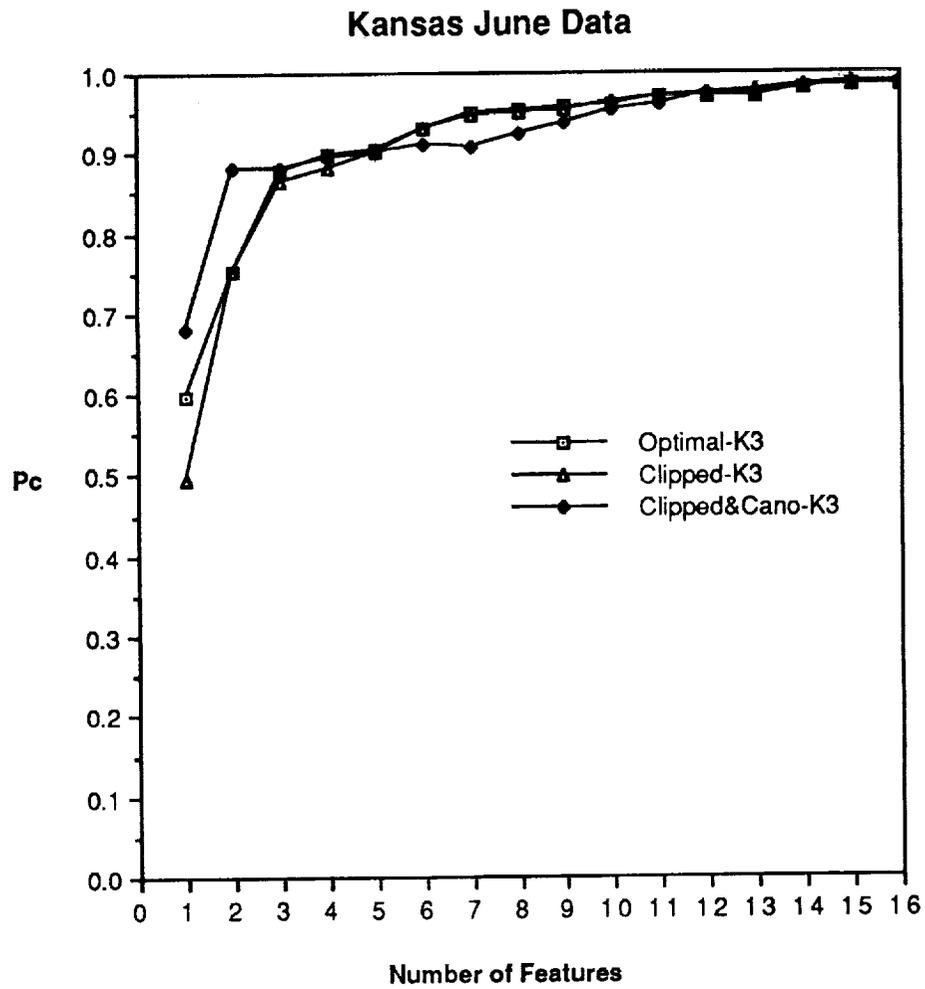


Figure 4.3 Classification Performance for Data Set K3

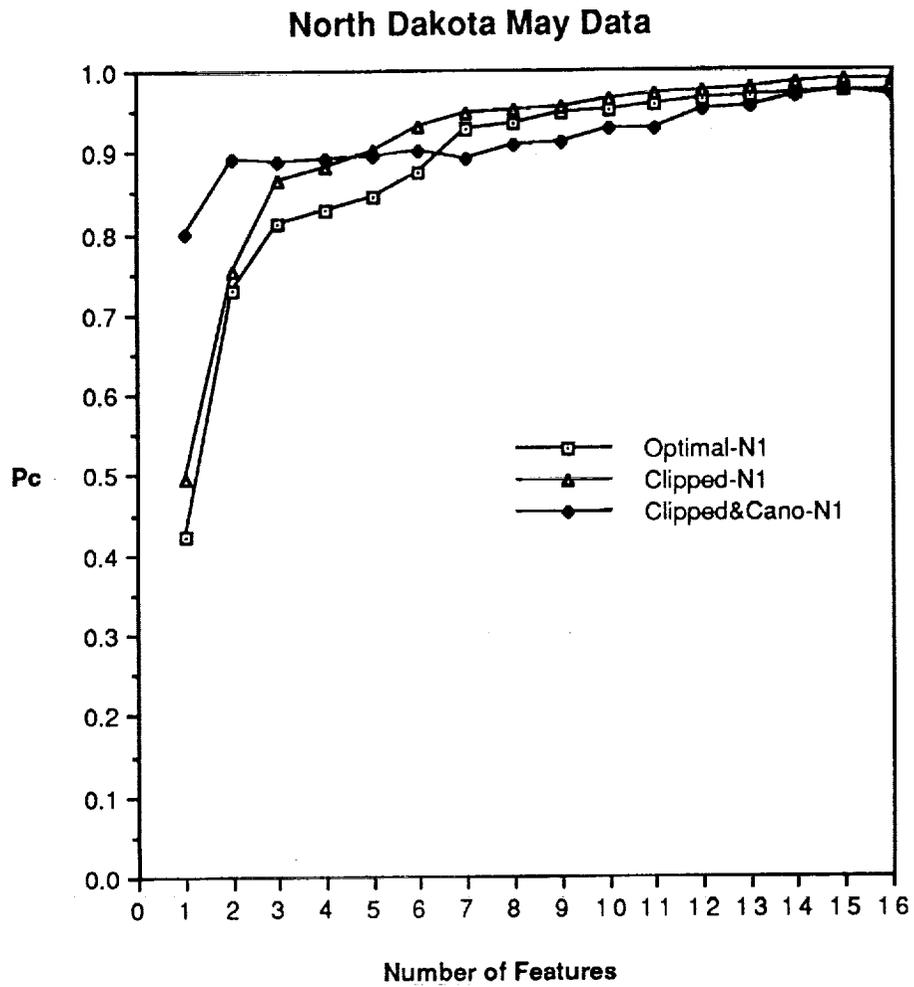


Figure 4.4 Classification Performance for Data Set N1

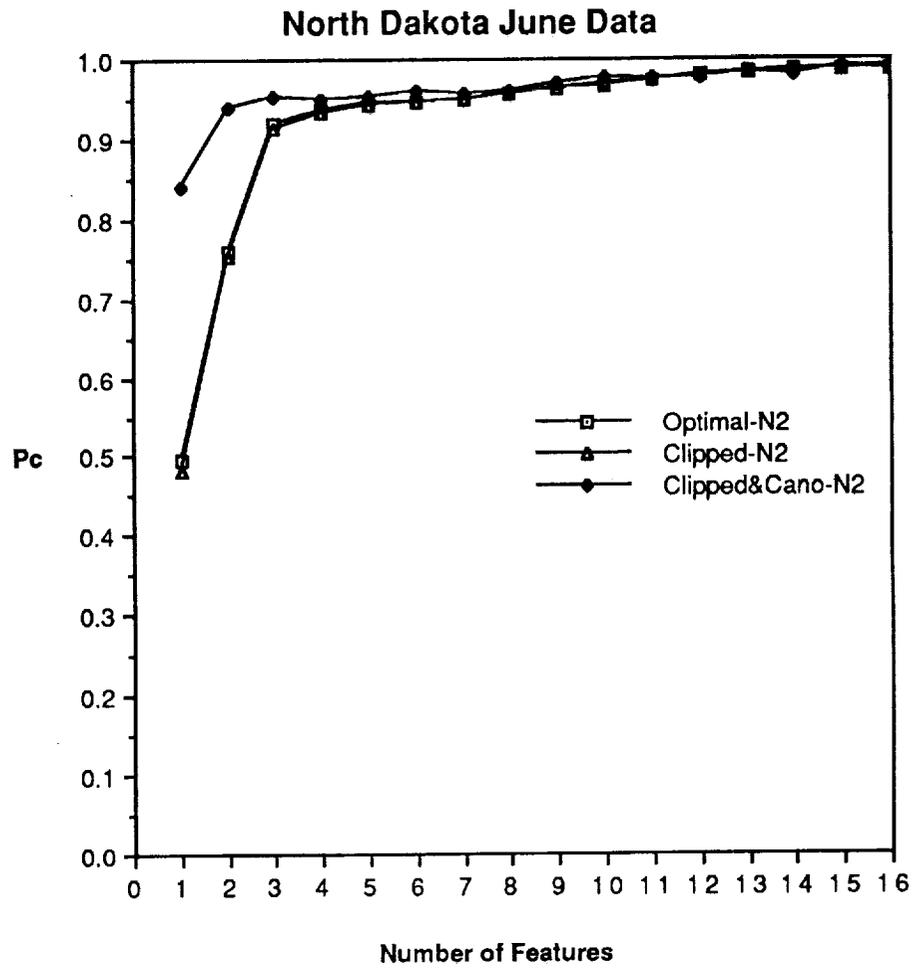


Figure 4.5 Classification Performance for Data Set N2

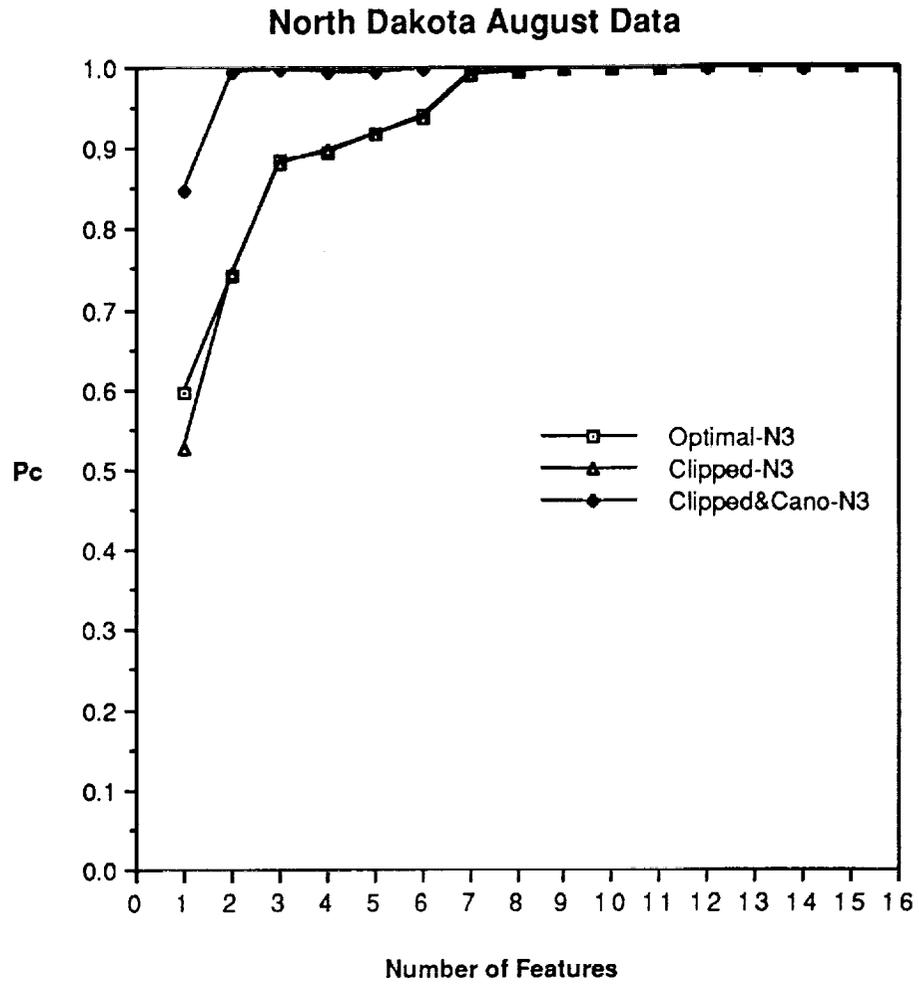


Figure 4.6 Classification Performance for Data Set N3

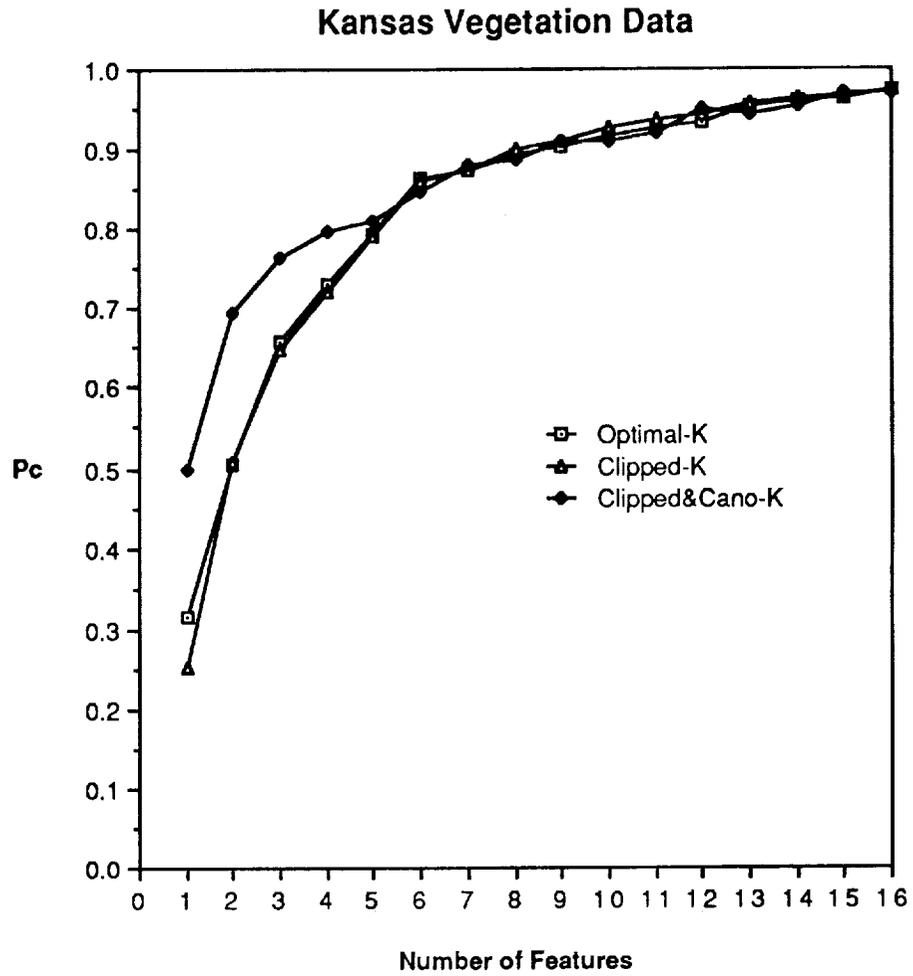


Figure 4.7 Classification Performance for Kansas Multitemporal Data Set

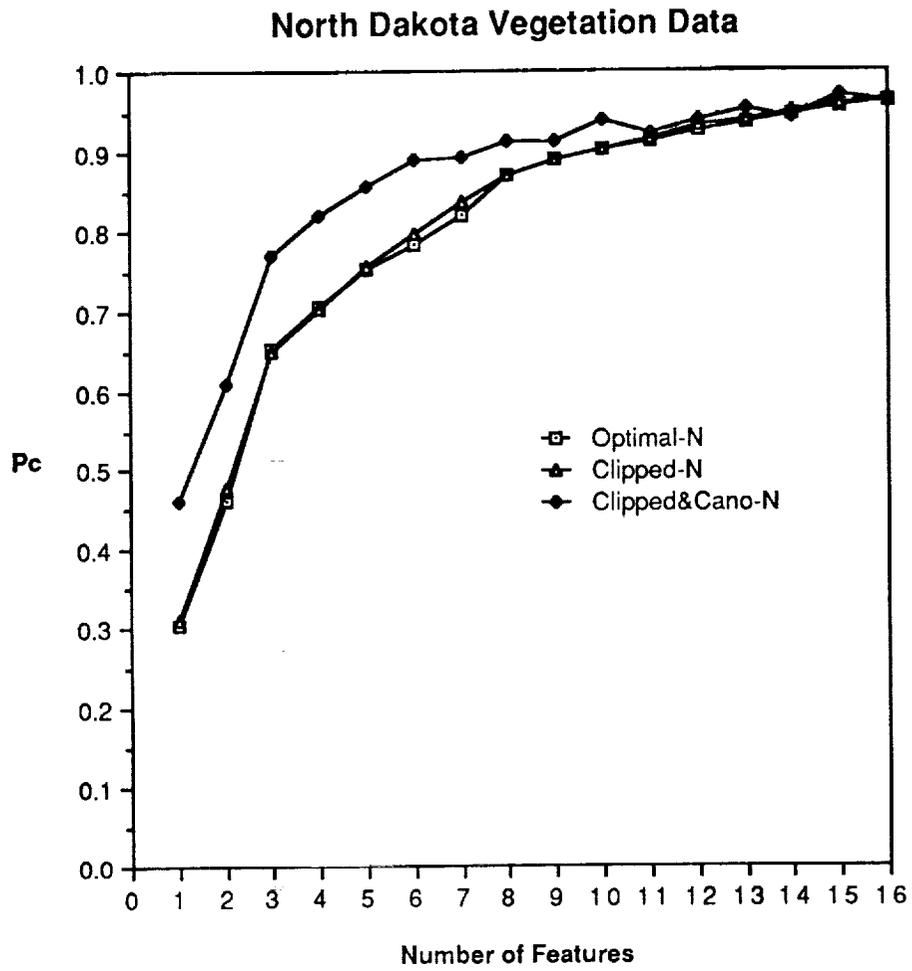


Figure 4.8 Classification Performance for N. Dakota Multitemporal Data Set

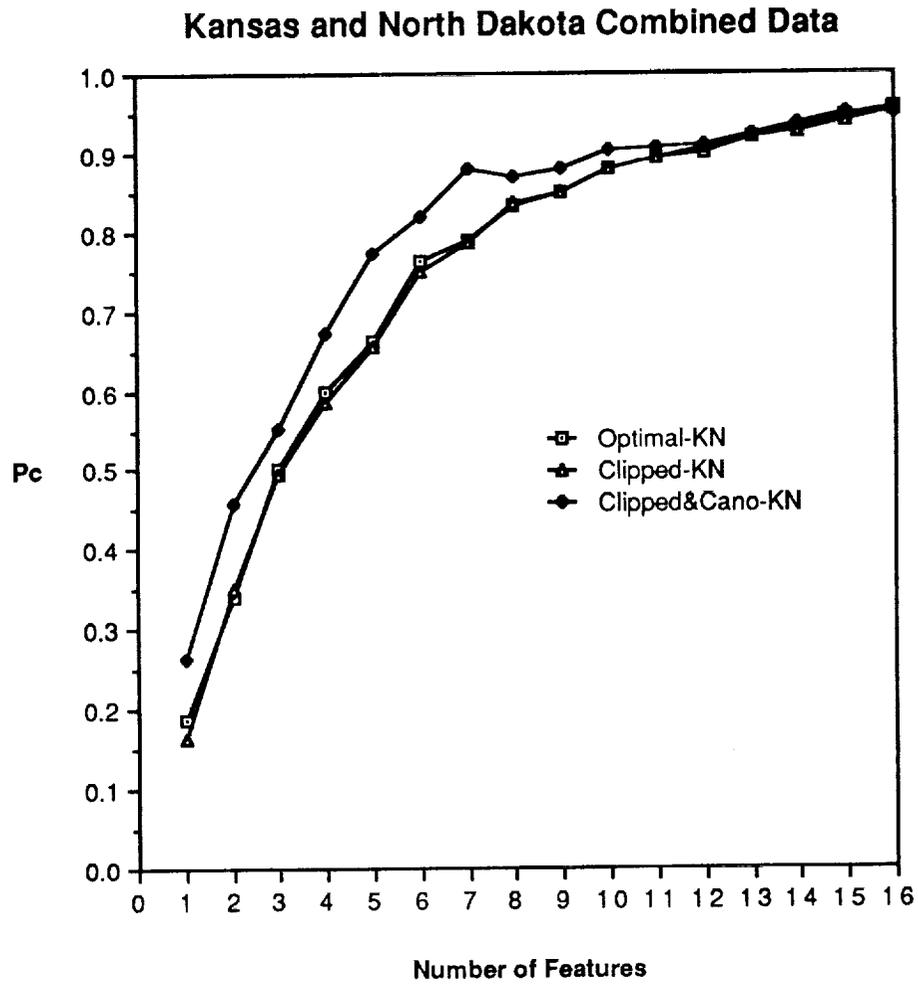


Figure 4.9 Classification Performance for KS/ND Combined Data Set

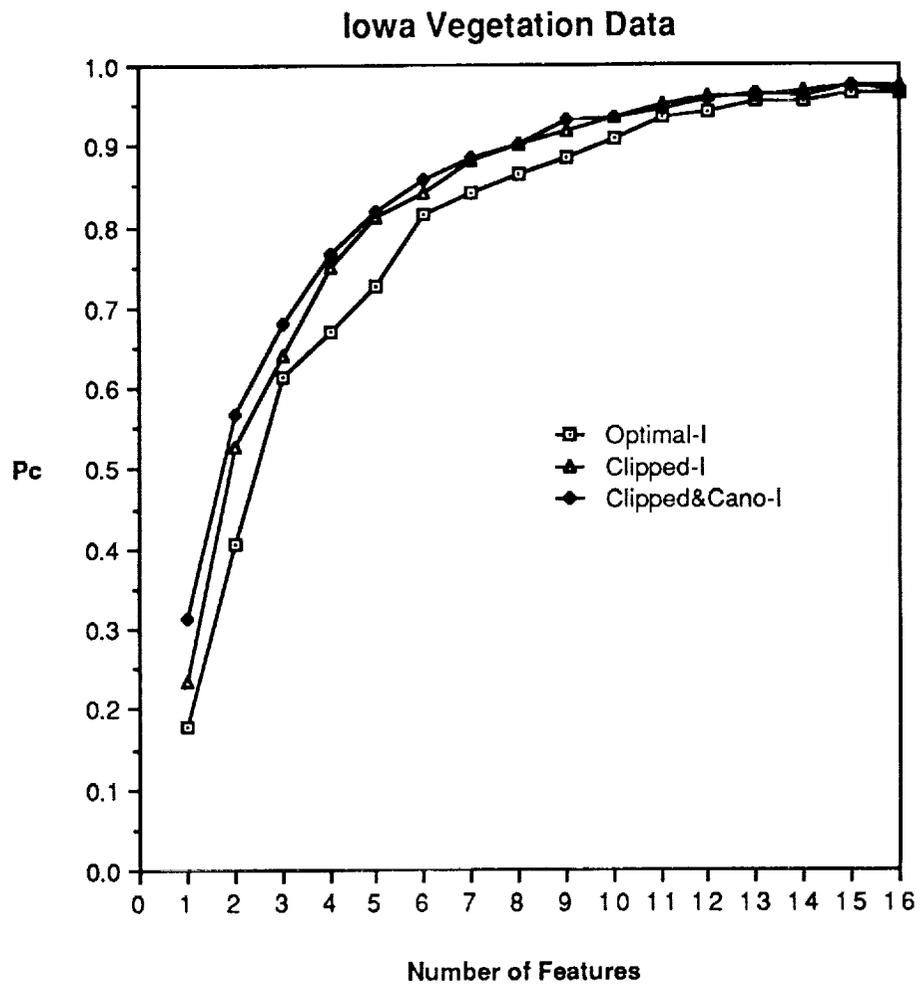


Figure 4.10 Classification Performance for Iowa Multitemporal Data Set

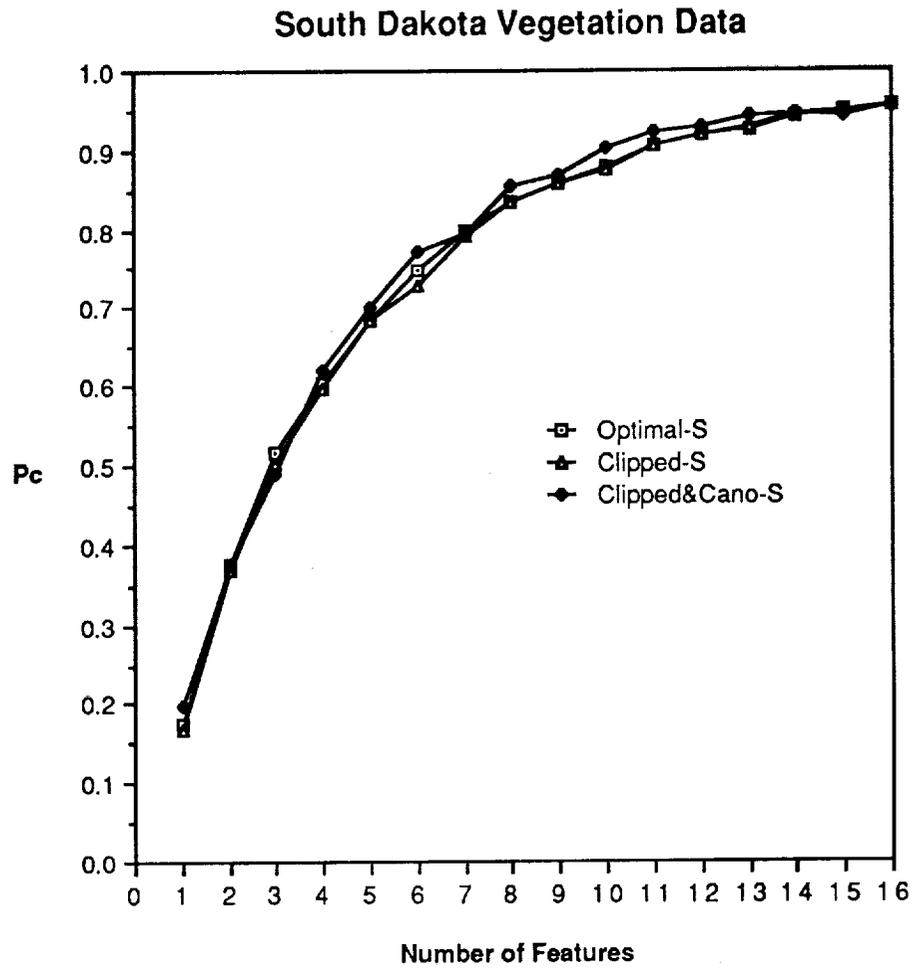


Figure 4.11 Classification Performance for S. Dakota Multitemporal Data Set

4.2 Soil Data

In addition to the above FSS vegetation data, a soil data base with 571 soil samples collected by Eric Stoner [45] in 1979 was acquired to test the system. The soil reflectance functions were measured by an EXOTECH-C spectrometer in the laboratory. In this research, five data sets grouped by soil order, organic matter content #1, organic matter content #2, Iron oxide content and soil texture [46-50] were formed respectively to test the spectral feature design system. They are designated as data sets SO, OM1, OM2, IO and ST respectively. It should be noted that the same soil samples are used in the data sets, but they are only grouped differently into classes. The soil data set designated as organic matter content #1 is from the soil orders Mollisol and Alfisol [48] only, while the soil data set designated as organic matter content #2 is from all soil orders. These 5 soil data sets are shown in Table 4.2

Table 4.2(a) shows the 10 soil orders in American Soil Taxonomy [48]. Since the total numbers of sample functions for Spodosol, Vertisol, Histosol and Oxisol are very limited, in this research, these soils are not used to form the data set SO. Only the data in the first 6 soil orders are included in SO. Table 4.2(b), (c) and (d) indicate the ranges of organic matter content #1, organic matter content #2 and iron oxide content respectively. Six classes are chosen in these 3 data sets: OM1, OM2 and IO. Table 4.2(e) shows the 6 soil texture classes used in data set ST where some of the classes consist of more than one soil texture group. For example, class 1 in data set ST includes clay and silty clay; class 2 includes sandy clay loam, clay loam and silty clay loam; etc.

The results of these 5 soil data sets are shown in Figure 4.12 to 4.16. Taking a general view of these graphs, it is found that the cumulative

performances of these soil data sets are less like a standard error function compared to those found in vegetation data sets (referring to Figure 4.1 to 4.11). The reason for this is that the total numbers of sample functions used to estimate the covariance matrices in the soil data sets are very limited, from a little more than the dimensionality in data set OM1, that is, 255 sample functions with dimensionality 200, to about 2.5 times the dimensionality in SO, OM2, IO and ST, that is about 500 sample functions for each data set; while on the other hand at least 8 times the dimensionality are available in the vegetation data sets. For example, the smallest data set K1 has 832 sample functions with dimensionality 100 and data sets other than K1 have more than 1000 sample functions to estimate the covariance matrix. Therefore, the estimates of the covariance matrices for the vegetation data sets are likely to be much more accurate than those for the soil data sets. The subsequent Gaussian model thus becomes more valid for the vegetation data and the cumulative classification curves are more like a standard error function.

Furthermore, Figure 4.12 to 4.16 show that the infinite clipped optimal functions are very effective to extract the information for soil classification. For instance, Figure 4.12 to 4.13 indicate that using the first 16 infinite clipped optimal functions, over 90% accuracy can be achieved while Figure 4.14 to 4.16 tell that over 85% accuracy is obtained. Due to the limited sample size for each of the soil data sets, different degrees of the Hughes phenomenon occur. Figure 4.12 to 4.14 show that canonical analysis improves the performance for the first 5 features while Figure 4.15 to 4.16 show that improvement is possible up to the first 7 features.

Table 4.2 Soil Data Sets :

(a) SO by Soil Order

Sample size for the first 6 classes : 479

class #	Order Name	# of Sample Functions
1	Mollisol	154
2	Alfisol	113
3	Entisol	78
4	Aridisol	52
5	Ultisol	45
6	Inceptisol	37
7	Spodosol	30
8	Vertisol	11
9	Histosol	8
10	Oxisol	11
11	Unclassified	32

(b) OM1 by Organic #1

Soil from Mollisol and Alfisol only. Sample size : 255

Class #	Organic Matter Range %	# of Sample Functions
1	0.11 ~ 1.5	51
2	1.5 ~ 2.0	54
3	2.0 ~ 2.5	33
4	2.5 ~ 3.5	45
5	3.5 ~ 5.0	39
6	5.0 ~ 10.12	33

(c) OM2 by Organic #2

Soil from all orders. Sample size : 514

Class #	Organic Matter Range %	# of Sample Functions
1	0.08 ~ 1.0	82
2	1.0 ~ 2.0	135
3	2.0 ~ 3.0	120
4	3.0 ~ 4.0	54
5	4.0 ~ 6.0	59
6	6.0 ~ 84.79	64

Table 4.2, continued

(d) IO by Iron Oxide Content
Sample size : 467

Class #	Iron Oxide Range %	# of Sample Functions
1	0.02 ~ 0.4	102
2	0.4 ~ 0.6	73
3	0.6 ~ 0.8	69
4	0.8 ~ 1.2	105
5	1.2 ~ 1.6	52
6	1.6 ~ 25.6	66

(e) ST by Soil Texture
Total sample size : 483 excluding the unclassified

Class #	Soil Texture Group/Groups	# of Sample Function	Class Sample Size
1	Clay	19	40
	Silty Clay	21	
2	Sandy Clay Loam	6	63
	Clay Loam	25	
	Silty Clay Loam	32	
3	Coarse Sand	3	76
	Large Coarse Sand	6	
	Sand	13	
	Large Sand	16	
	Large Fine Sand	18	
	Fine Sand	20	
4	Coarse Sandy Loam	5	93
	Very Fine Sandy Loam	12	
	Sandy Loam	24	
	Fine Sandy Loam	52	
5	Loam	68	68
6	Silt	4	143
	Silt Loam	139	
7	Unclassified	88	88

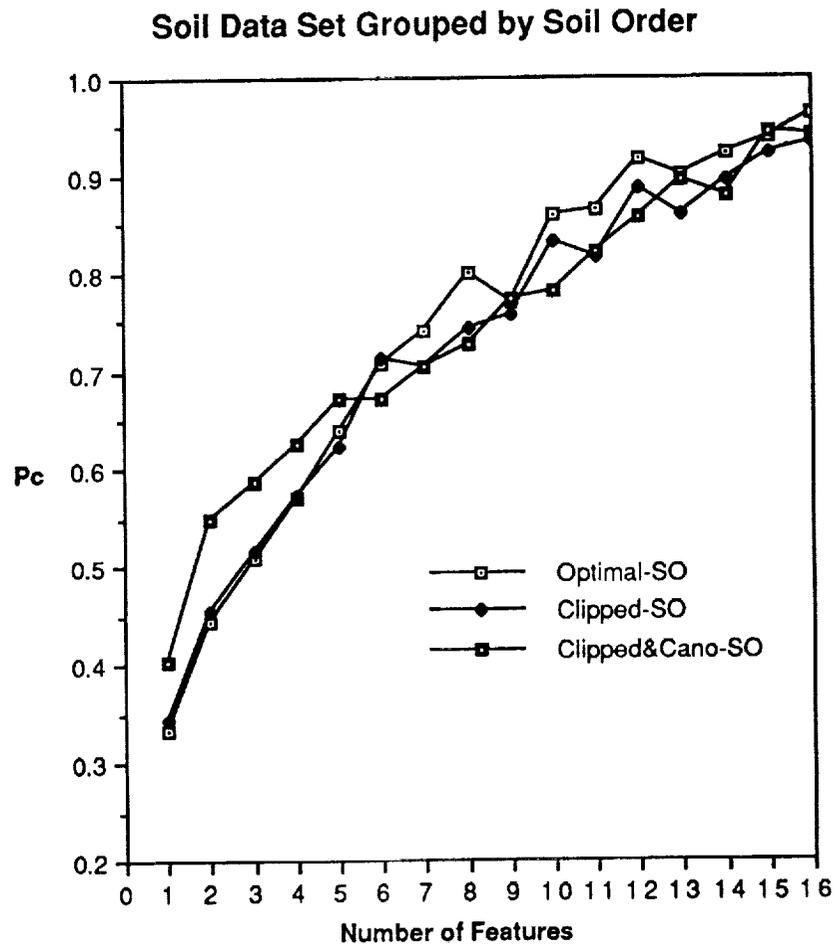


Figure 4.12 Classification Performance for Soil Data Grouped by Soil Order

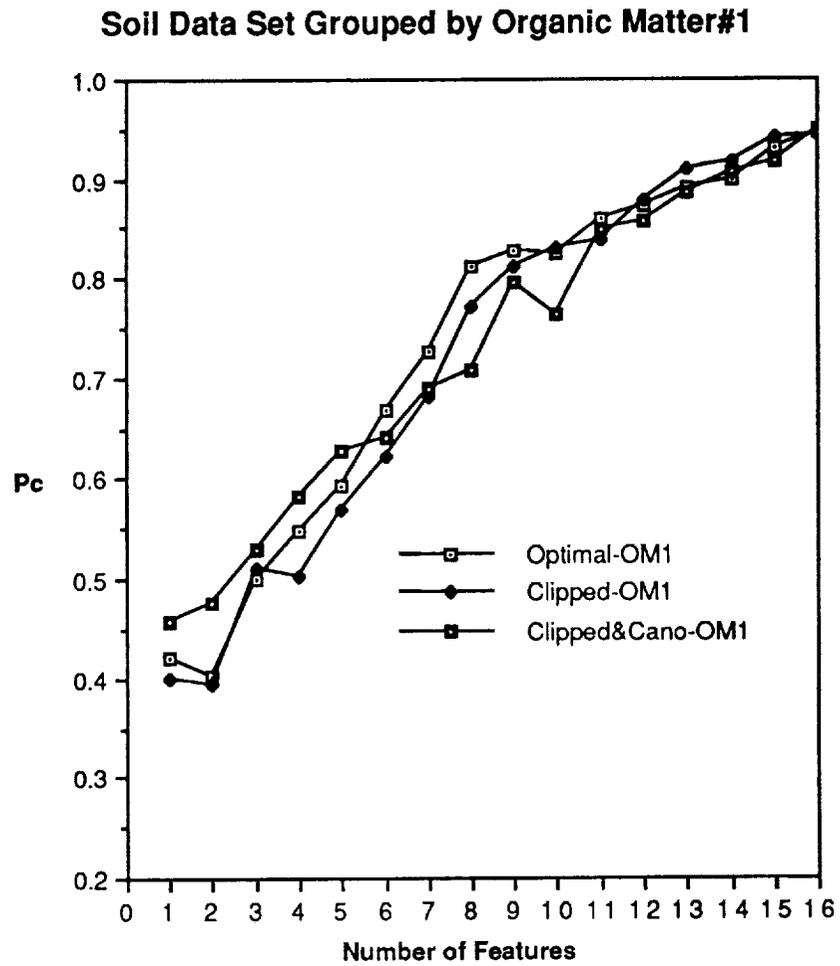
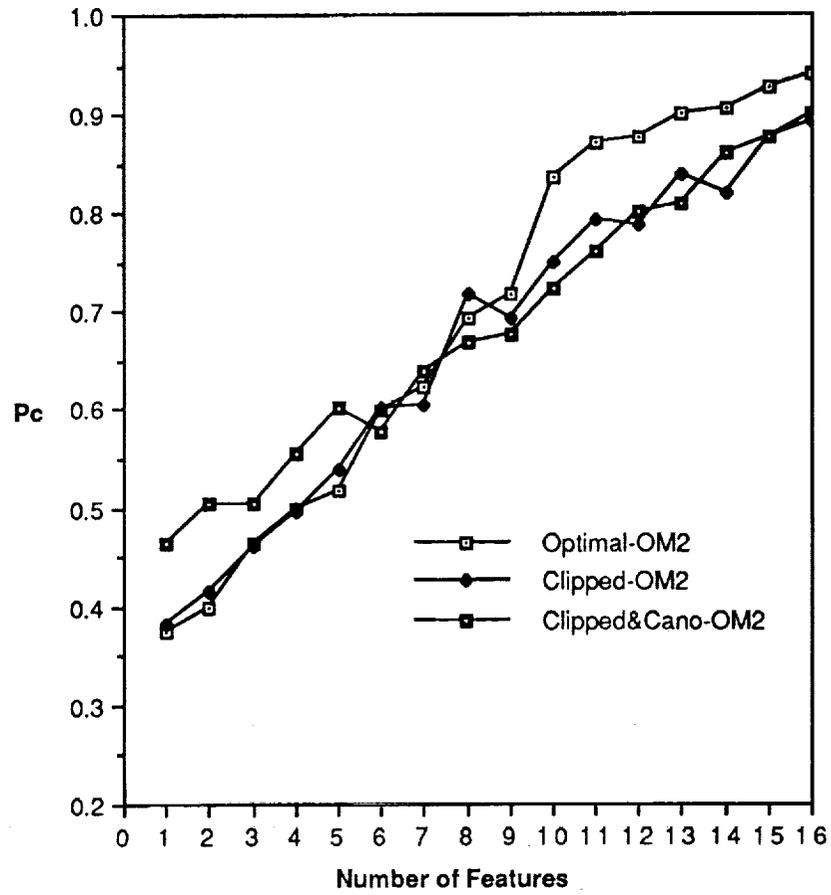


Figure 4.13 Classification Performance for Soil Data Grouped by Organic #1

Soil Data Set Grouped by Organic Matter#2

**Figure 4.14** Classification Performance for Soil Data Grouped by Organic #2

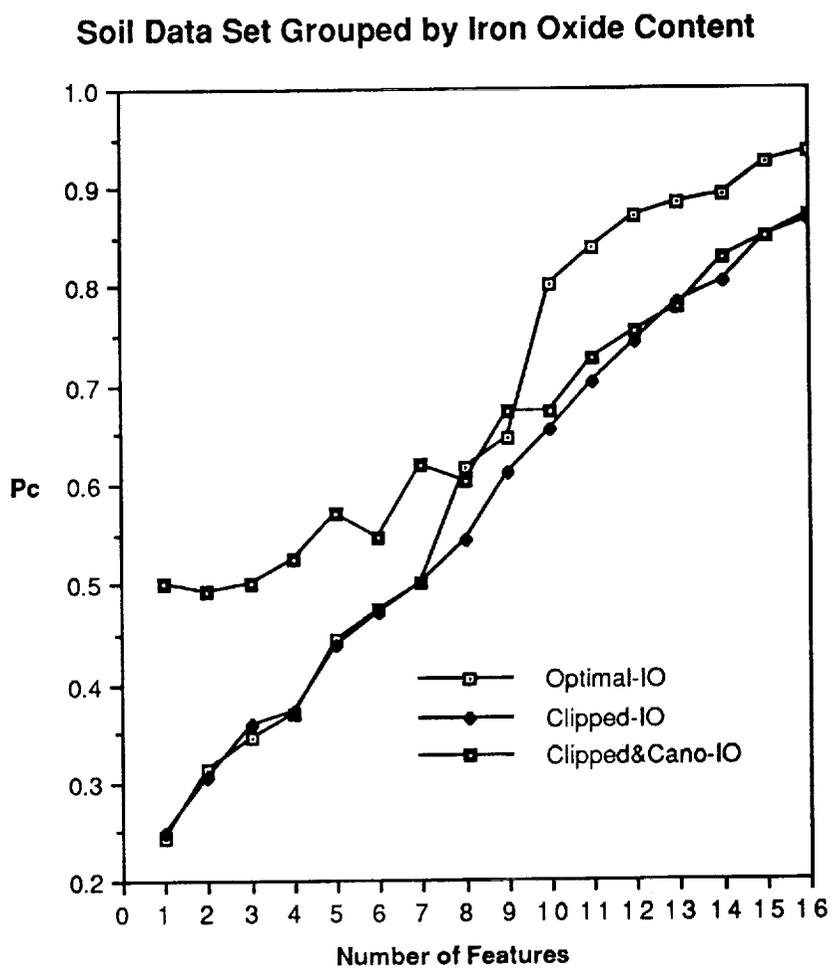


Figure 4.15 Classification Performance for Soil Data Grouped by Iron Oxide

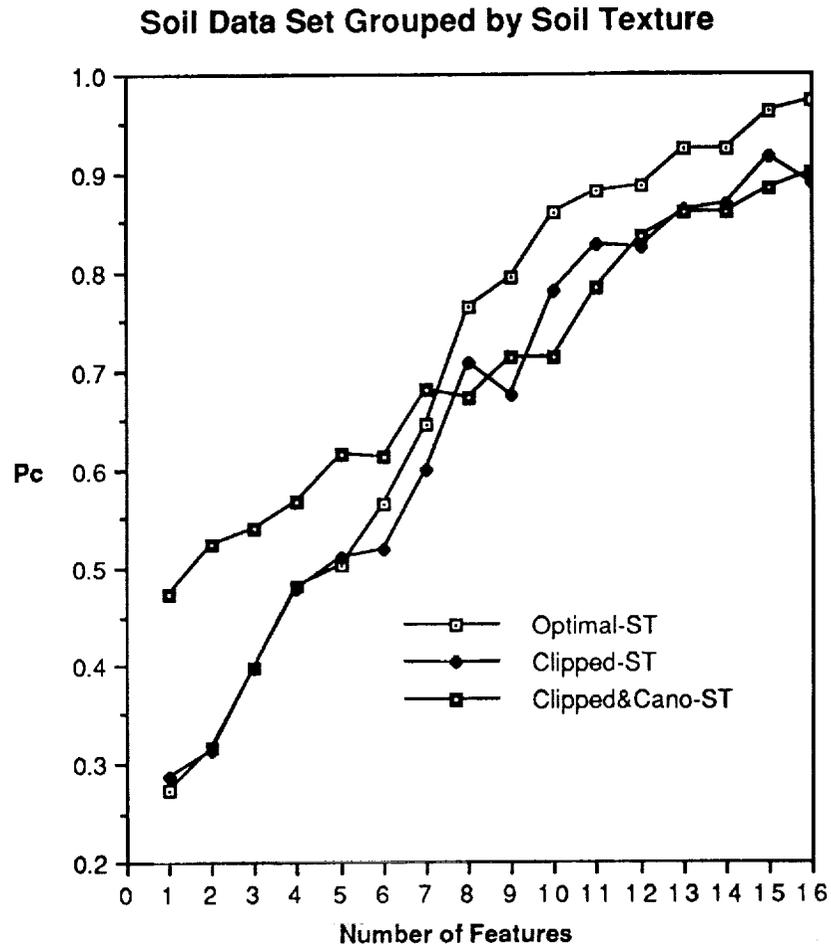


Figure 4.16 Classification Performance for Soil Data Grouped by Soil Texture

4.3 Hughes Phenomenon

In 1968, Hughes [42] showed theoretically that the mean recognition accuracy for the statistical pattern classifiers did not always increase as the measurement complexity increased so long as the number of training samples was fixed and finite. This result was experimentally demonstrated in a remote sensing context by Fu, Landgrebe and Phillips [43] in 1969. The conclusion of these investigations was that for a fixed number of training samples, there is an optimal measurement complexity. More complexity is undesirable from the standpoint of expected classification accuracy.

Kalayeh, Muasher and Landgrebe [51,52] developed a criterion to predict the occurrence of the Hughes phenomenon. They suggested that a number of sample functions equal to about 8 to 10 times the dimensionality must be available for the ensemble in order to avoid the Hughes phenomenon.

In this section, four experiments are described to show that the Hughes phenomenon did occur in the data sets with limited training samples. The data sets K1 and N2 were chosen for this purpose because K1 has the least training samples (referring to Table 1.1) among all vegetation data sets and N2 (referring to Figure 4.5) indicated some possibility for the occurrence of the Hughes phenomenon. Tables 4.3(a) to (d) show the data used for these 4 experiments and Figures 4.17 to 4.20 show the results. In the above tables and figures, K1H and N2H are the data sets with about one half of the original training samples while K1Q and N2Q represent those with approximately one quarter of the training samples.

Figure 4.17 and 4.18 show that for data set K1, the Hughes phenomenon has occurred (referring to Figure 4.1). If the size of the training samples is reduced to half or even to quarter, the effect of this phenomenon becomes more and more serious. On the other hand, for data set N2, there is no Hughes phenomenon (referring to Figure 4.5). If the size of the training samples becomes one half of the original N2, the Hughes phenomenon might or might not occur. Figure 4.19 indicates that for data set N2, reducing the size of the training samples to approximately one half, that is 630 samples with dimensionality 100, the estimate of covariance matrix is still accurate enough, and the Hughes phenomenon does not occur.

However, if the training size of the data set N2 is reduced to one quarter, the Hughes phenomenon does occur. Figure 4.20 says that the optimal number of features in this data set N2Q with 315 training samples is only 2. The maximal classification accuracy that can be achieved is about 85%. Furthermore, more than 2 features used for classification would not help the performance and in some cases even reduce the accuracy.

The four experiments in this section indicate that for data set K1, more than 832 samples are needed in order to avoid the effect of Hughes phenomenon; on the other hand, for data set N2, 1239 samples are enough to accurately estimate the covariance matrix. From the classification performances of data sets K1, K2, K3 and N1, shown in Figure 4.1 to 4.4, it is suggested that more than 15 times dimensionality sample functions may be required to avoid the effect of the Hughes phenomenon.

Table 4.3 Data Sets Used to Test the Occurrence of the Hughes Phenomenon :

**(a) Kansas September Data With Half Training Samples :
Data Set K1H**

K1H	Winter Wheat	Summer Fallow	Grain Sorghum	Total Samples
Training	70	200	140	410
Testing	71	214	137	412
Total	141	414	277	832

**(b) Kansas September Data With Quarter Training Samples :
Data Set K1Q**

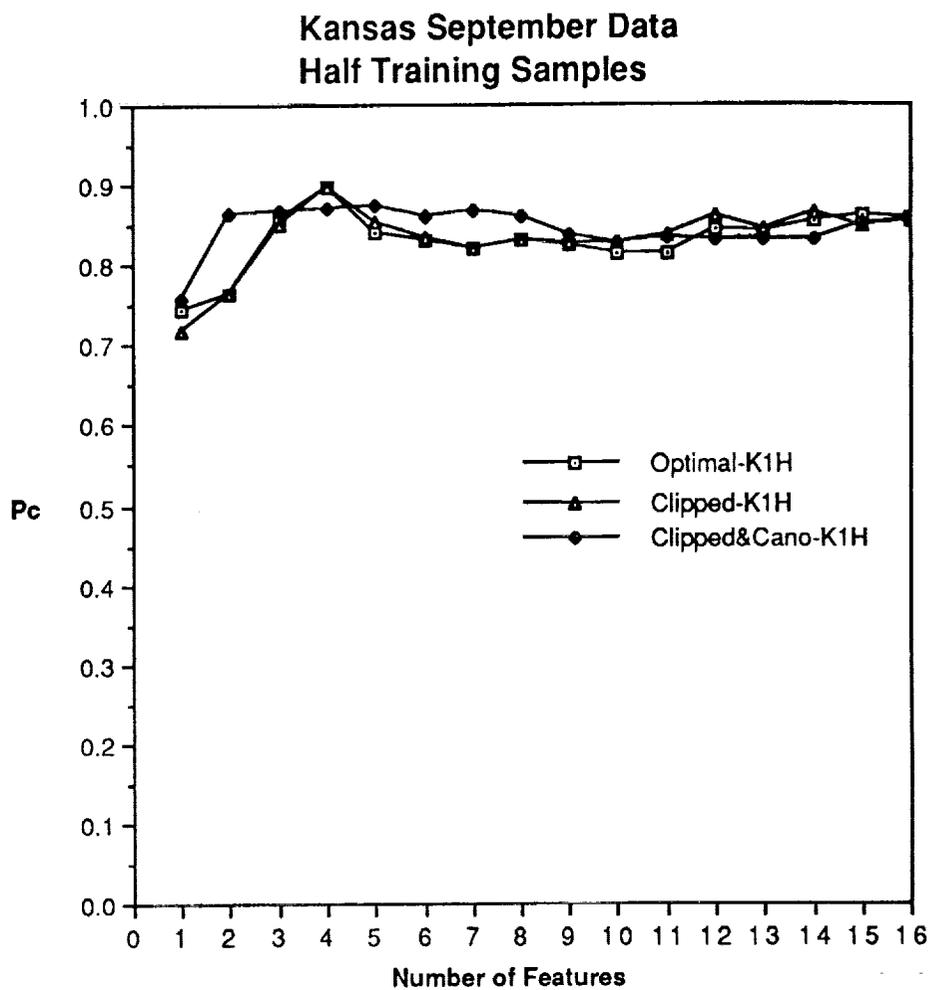
K1Q	Winter Wheat	Summer Fallow	Grain Sorghum	Total Samples
Training	35	100	70	205
Testing	106	314	207	627
Total	141	414	277	832

**(c) North Dakota June Data With Half Training Samples :
Data Set N2H**

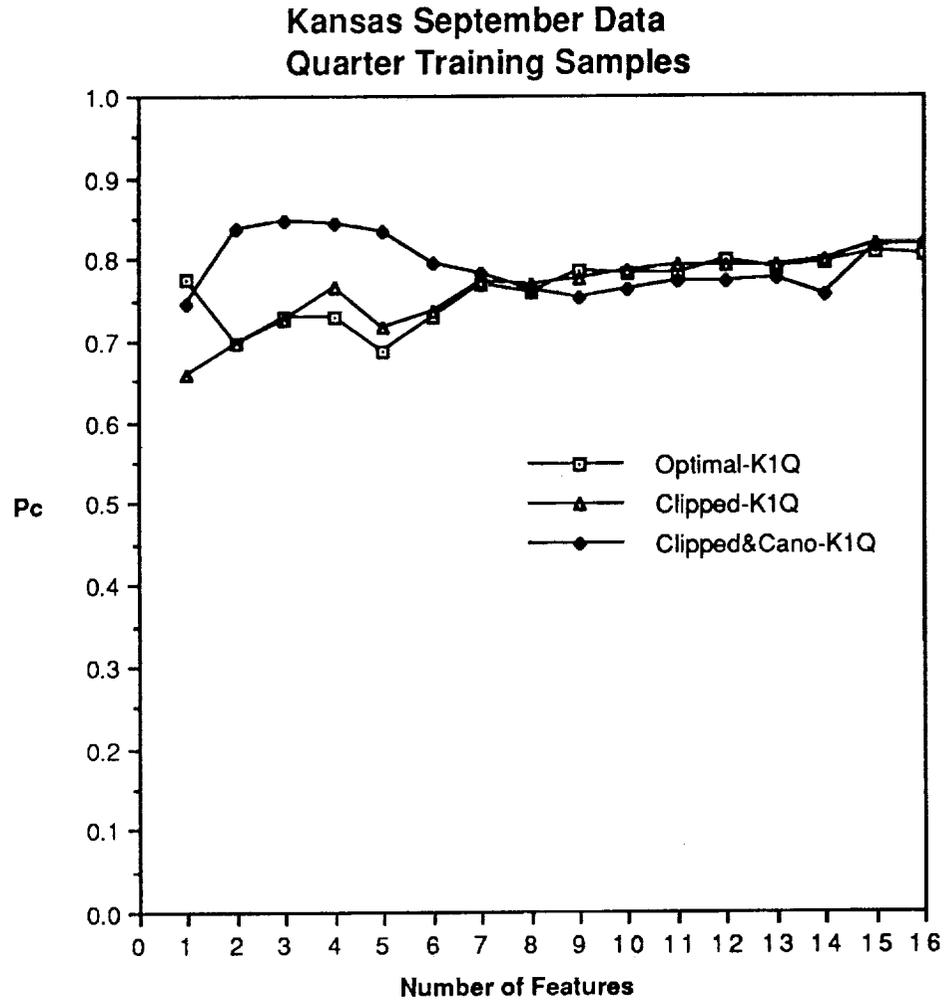
N2H	Spring Wheat	Summer Fallow	Natural Pasture	Total Samples
Training	400	150	80	630
Testing	387	141	81	609
Total	787	291	161	1239

**(d) North Dakota June Data With Quarter Training Samples :
Data Set N2Q**

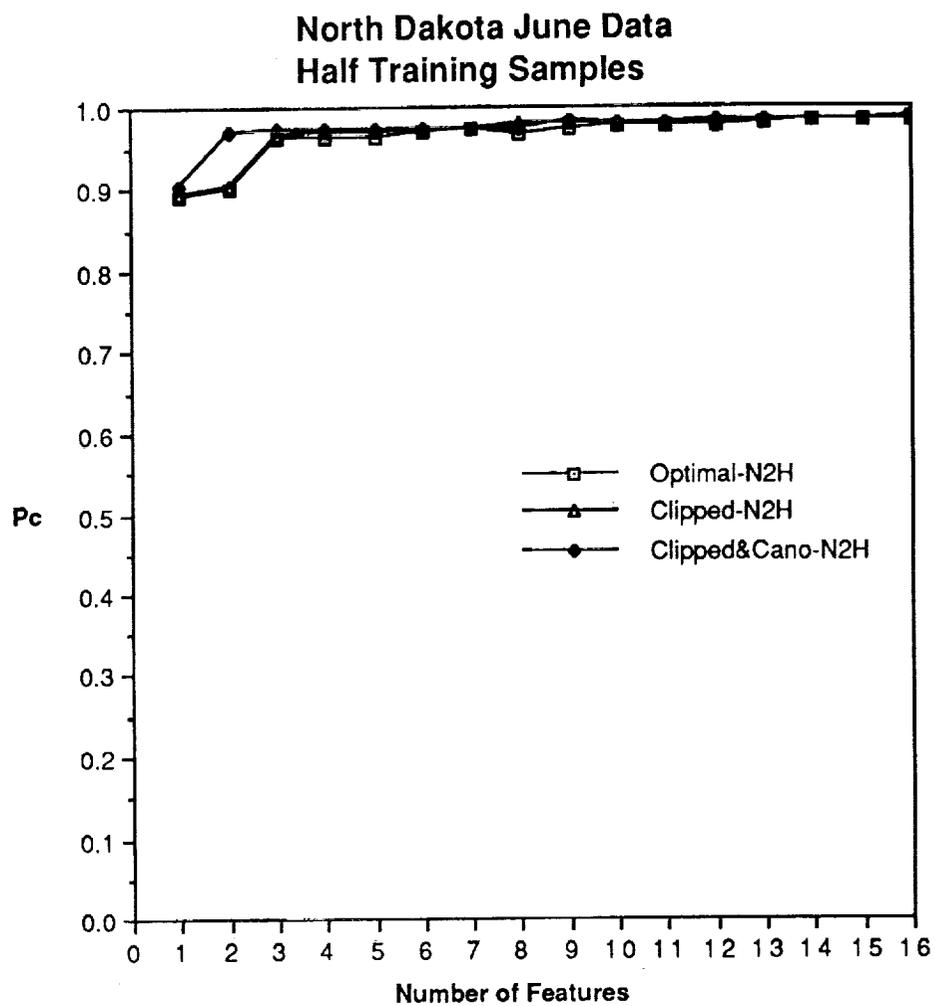
N2Q	Spring Wheat	Summer Fallow	Natural Pasture	Total Samples
Training	200	75	40	315
Testing	587	216	121	924
Total	787	291	161	1239



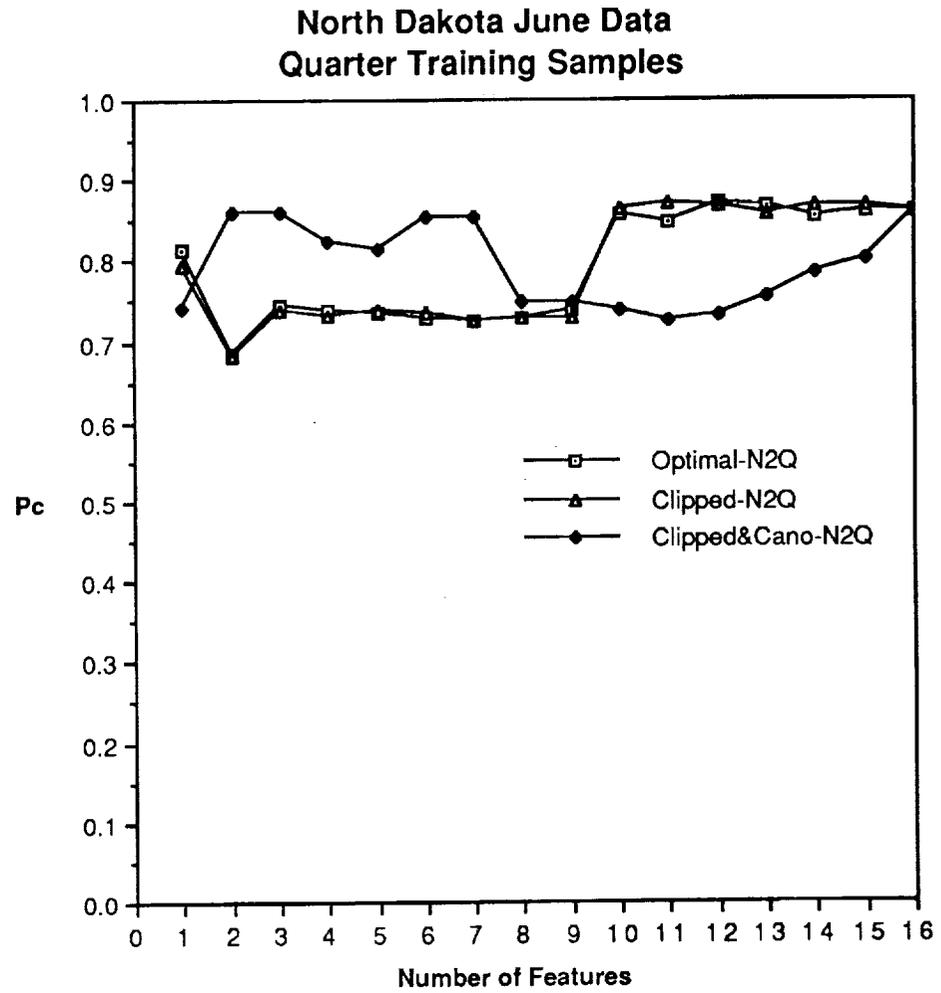
**Figure 4.17 First Experiment of the Hughes Phenomenon :
Data Set K1H**



**Figure 4.18 Second Experiment of the Hughes Phenomenon :
Data Set K1Q**



**Figure 4.19 Third Experiment of the Hughes Phenomenon :
Data Set N2H**



**Figure 4.20 Fourth Experiment of the Hughes Phenomenon :
Data Set N2Q**

4.4 Signal to Noise Ratio Considerations

In the previous sections, the classification results obtained by using the spectral features developed in this research are presented for 100 dimensional FSS vegetation data and 200 dimensional Exotech-C soil data. It is found (referring to Figure 4.1 to 4.16) that about 10 to 1 compression ratio can be achieved while maintaining satisfactory classification accuracy. One question an Earth scientist user of the algorithm may have is that the 10 to 1 downlink data rate reduction is not at a severe cost to the usefulness of the data. Thus, in this section, we will discuss the data volume reduction issue from the Earth scientist point of view, that is, from signal-to-noise ratio considerations.

Weighted Karhunen-Loeve transform rotates the original N-dimensional signal space to a more favorable orientation. This orientation is one in which the source energy is redistributed such that a larger percentage of the energy is distributed over fewer coordinates. Table 4.4 and Figure 4.21 show how the source energy is redistributed over the first 25 transformed coordinates for 100 dimensional vegetation data set K2.

In Table 4.4, the first row shows that the magnitude of the total source energy is 3497, which is the sum of all eigenvalues; Further, the mean square representation error (MSE) and percent mean square representation error (%MSE) are 3497 and 100% respectively if 'none' of the optimal feature is used to transform the data. The second row indicates that the magnitude of the first eigenvalue is 2779.8; If the first optimal feature is used to transform the data, the representation error and percent representation error will be 717 and 20.5% respectively, that is, the first transformed coordinate contains about 79.5%

source energy in it. Similarly, it can be found that using the first 2 optimal features, about 97.5% of the total source energy can be preserved, and using the first 10 optimal features to transform the data in the measurement space, the percent mean square representation error, that is 0.17%, is indeed negligible. Figure 4.21 shows graphically how fast the representation error can be reduced by using the first few optimal features. It should be noticed that the representation error (MSE) is plotted in logarithmic scale.

The practical values of the signal to noise ratio in a typical remote sensing system are from 50 to 200 in most of the 0.4 to 2.5 μm spectrum range [1]. This indicates that the maximal noise level in the system is only 1/50, that is, 2%. Since using the first 10 optimal features derived from the Weighted K-L transform preserves almost all the signal energy in the original measurement space; Further, the representation error level is 0.17% which is much lower than the noise level in the system. Hence, the effect on the signal to noise ratio due to compression is quite limited even as the signal to noise ratio is down to 20. Therefore, a data volume reduction by a factor of 10 is achieved with essentially no loss of information.

Table 4.4 Mean Square Representation Error for Data Set K2

Eigenvalue	Magnitude of Eigenvalue	Mean Square Error	% Mean Square Error
0	3497.0691	3497.0691	100.0000
1	2779.8821	717.1870	20.5082
2	627.0327	90.1543	2.5780
3	39.0218	51.1325	1.4622
4	18.4108	32.7217	0.9357
5	14.0425	18.6792	0.5341
6	4.9193	13.7599	0.3935
7	2.5450	11.2149	0.3207
8	1.8422	9.3727	0.2680
9	1.7561	7.6166	0.2178
10	1.3731	6.2435	0.1785
11	0.8927	5.3508	0.1530
12	0.8225	4.5283	0.1295
13	0.6291	3.8993	0.1115
14	0.4818	3.4175	0.0977
15	0.4498	2.9676	0.0849
16	0.3778	2.5898	0.0741
17	0.3469	2.2429	0.0641
18	0.3266	1.9163	0.0548
19	0.2328	1.6835	0.0481
20	0.2192	1.4643	0.0419
21	0.1696	1.2947	0.0370
22	0.1499	1.1448	0.0327
23	0.1268	1.0181	0.0291
24	0.1174	0.9006	0.0258
25	0.0904	0.8103	0.0232

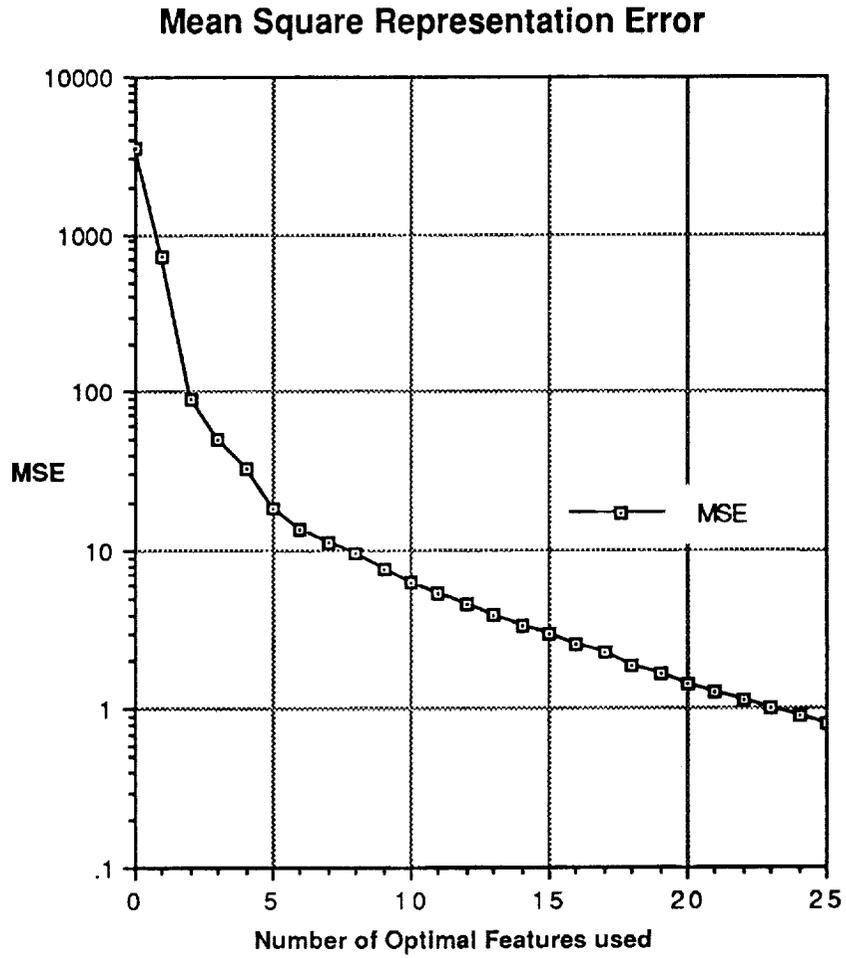


Figure 4.21 Mean Square Representation Error for Data Set K2

CHAPTER V

CONCLUSIONS AND RECOMMENDATIONS

5.1 Conclusions

The fundamental objective of this research is to develop an objective and practical spectral feature design technique for high dimensional multispectral data. In this thesis, four spectral feature design techniques have been developed. Two of them, non-overlapping band feature selection algorithm and overlapping band feature selection algorithm, are derived from the spectral dominance concept of the optimal functions; the other two, Walsh function approach and infinite clipped optimal function approach, are derived from the spectral similarity concept of the optimal functions. These four approaches have been proved effective for data compression and classification purposes in high dimensional multispectral data.

A comparison among these four techniques indicates that the infinite clipped optimal function approach is the best scheme since the features are easiest to find and their classification performance is the best under the same compression requirement. This technique approximates the spectral structure of the optimal features via infinite clipping and results in transform coefficients which are either +1, -1 or 0. Therefore the necessary processing can be easily implemented on-board the spacecraft by using a set of programmable adders that operate on the grouping instructions received from the ground station.

After the preprocessed data has been received, canonical analysis is further used to find the best set of features under the criterion that maximal class separability is achieved

Both vegetation and soil data have been tested in this research. For vegetation data, four sets of multitemporal multispectral vegetation data collected in Kansas, North Dakota, Iowa and South Dakota respectively with 9 to 42 information classes in 1976 to 1979 are used to test the spectral feature design system. One spatially and temporally combined data set is also formed by combining the Kansas and North Dakota Data sets to test the robustness property of the scheme. The results indicate that the system is not overly sensitive to spatial and temporal variation.

Furthermore, a soil data base collected by Eric Stoner in 1979 was also acquired and used to test the system. In this research, five different soil data sets grouped by the soil order, organic content #1, organic content #2, iron oxide content and soil texture are formed. The classification performances are then found. It is shown that soil order, organic content percentage, iron oxide content percentage and soil texture can be delineated and predicted by the proposed technique.

It is concluded that the infinite clipped versions of the first 16 optimal functions derived from the Weighted Karhunen-Loeve Transform have excellent classification performance. Further signal processing by canonical analysis increases the compression ratio while retains the classification accuracy. The overall probability of correct classification of the proposed system is over 90% while providing for a reduced downlink data rate by a factor of 10.

5.2 Recommendations

The spectral feature design system developed in this research has been demonstrated for the FSS vegetation data and the Exotech-C soil data. In the future, it is proposed to test AVIRIS and HIRIS data. The following procedure is recommended :

(A) Pre-Flight Stage :

- (1) Collect enough representable samples from all reference sources available, for example, the field data base collected in the past, to form the ensemble of a specific problem (Ground Truth Gathering)
- (2) Calculate the mean vector and covariance matrix of this ensemble
- (3) Find the eigenvectors of the covariance matrix
- (4) Run the spectral feature design system on the ground to find the grouping coefficients (either +1, -1, or 0)

(B) On-Board Preprocessing Stage :

- (5) Send up these grouping coefficients (instructions) to the spacecraft for on-board data preprocessing

(C) Post-Flight Stage :

- (6) Receive the preprocessed low dimensional data
- (7) Run the spectral feature design system on the ground to find the canonical features
- (8) Use these canonical features to further transform the received data into the final signal space where the data classification is performed

In this procedure, there are basically 3 processing stages involved : pre-flight stage, on-board preprocessing stage and post-flight stage. The pre-flight stage, which consists of step 1 to step 4, is used to gather ground truth information, estimate ensemble statistics and find appropriate grouping coefficients from one of the four developed schemes. This stage would be done before the data take by the aids of aerial photography, topographical maps, historical information, field data base collected in the past or other reference sources available. One more comment about this stage is the problem of the sample size, it is suggested from the experience in this research that the total number of samples used to estimate the ensemble statistics needs to be at least 15 times their signal dimensionality in order to accurately estimate the covariance matrix.

The second stage, on-board preprocessing stage, which contains step 5, performs band groupings on board the spacecraft, either summing (+1), subtracting (-1) or omitting (0) bands for each spectral function according to the grouping instructions sent by the ground user. Since this data preprocessing stage would be done on board the spacecraft, from implementation point of view, the algorithm simplicity is then required and important. The spectral feature design system developed in this research makes this simplicity possible. Figure 1.1 shows how the data preprocessing can be implemented on board the spacecraft by a set of programmable adders.

Finally, the post-flight stage, which includes step 6 to step 8, is applied to further process the received transformed data such that the maximal class

separability is achieved. Since this stage and the pre-flight stage would be done at the ground station, the algorithm simplicity is therefore less important than that in the on-board preprocessing stage. Hence, it might be more effective to use the overlapping band feature selection algorithm to design the features in some future situations although it's the most complex among the four techniques developed in this research.

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Appendix A IBM 3083 Macro File

```
/* RUN A FORTRAN PROGRAM USING IMSLSP OR IMSLDP SUBROUTINES */  
ARG FN FN1 FN2 FN3 FN4 FN5 FN6 FN7 FN8 FN9 FN10 FN11  
LINKTO IMSL  
GLOBAL TXTLIB IMSLSP IMSLDP PFORTLIB VSF2FORT CMSLIB  
GLOBAL LOADLIB VSF2LOAD  
FORTVS2 FN  
LOAD FN  
FILEDEF 11 DISK FN1 DATA C1  
FILEDEF 12 DISK FN2 DATA C1  
FILEDEF 13 DISK FN3 DATA C1  
FILEDEF 14 DISK FN4 DATA C1  
FILEDEF 15 DISK FN5 DATA C1  
FILEDEF 16 DISK FN6 DATA C1  
FILEDEF 17 DISK FN7 DATA C1  
FILEDEF 18 DISK FN8 DATA C1  
FILEDEF 19 DISK FN9 DATA C1  
FILEDEF 20 DISK FN10 DATA C1  
FILEDEF 21 DISK FN11 DATA C1  
START
```

Appendix B Spectral Feature Design System - Program Listing

```

PROGRAM MV
PARAMETER(NP2=1551,NP1=100,NP3=NP1*(NP1+1)/2,NF2=10,NF3=5)
REAL X(NP2,NP1),XM(NP1),VCV(NP3)
DATA IFLAG1,XM,VCV/0,NP1*0.0,NP3*0.0/
C
C NP1 : DIMENSIONALITY OF SAMPLE FUNCTIONS
C NP2 : TOTAL NUMBER OF SAMPLE FUNCTIONS
C NP3 : TOTAL NUMBER OF ELEMENTS IN COVARIANCE MATRIX VCV
C NF2 : RAW DATA INPUT FILE STORED IN FORMAT 10F8.3
C NF3 : XM & VCV OUTPUT DATA FILE STORED IN FORMAT 5E15.7
C
C X : RAW DATA ( INPUT )
C XM : MEAN VECTOR ( OUTPUT )
C VCV : COVARIANCE MATRIX STORED IN SYMMETRIC MODE ( OUTPUT )
C IFLAG1 ----- INTERNAL CHECKING PARAMETER
C
C 11 = DATA FILE ; 12 = MV FILE
C
C OPEN(11)
C OPEN(12)
C REWIND 11
C REWIND 12
C
C READ IN RAW DATA AND PRINT THE PROGRESS FOR EVERY 100 SAMPLES
C
C DO 20 ISAMP=1,NP2
C K=MOD(ISAMP,100)
C IF(K.EQ.0)PRINT*,' NP2 = ',NP2,' ; ISAMP = ',ISAMP
C DO 20 I=1,NP1/NF2
20 READ(11,1)(X(ISAMP,J),J=1+(I-1)*NF2,I*NF2)
PRINT*,' DATA READ IN FINISHED '
1 FORMAT(10F8.3)
C
C FIND THE ENSEMBLE MEAN VECTOR
C
C DO 30 J=1,NP1
C DO 30 I=1,NP2
30 XM(J)=XM(J)+X(I,J)
C DO 40 I=1,NP1
40 XM(I)=XM(I)/FLOAT(NP2)
PRINT*,' MEAN VECTOR FOUND '
C
C FIND THE ENSEMBLE COVARIANCE MATRIX AND PRINT THE PROGRESS FOR
C EVERY 10 DIMENSIONS
C
C DO 50 I=1,NP1
C KX=MOD(I,10)
C IF(KX.EQ.0)PRINT*,' I
C DO 50 J=1,I
C IND=(I-1)*I/2+J

```

```

MV 00010
MV 00020
MV 00030
MV 00040
MV 00050
MV 00060
MV 00070
MV 00080
MV 00090
MV 00100
MV 00110
MV 00120
MV 00130
MV 00140
MV 00150
MV 00160
MV 00170
MV 00180
MV 00190
MV 00200
MV 00210
MV 00220
MV 00230
MV 00240
MV 00250
MV 00260
MV 00270
MV 00280
MV 00290
MV 00300
MV 00310
MV 00320
MV 00330
MV 00340
MV 00350
MV 00360
MV 00370
MV 00380
MV 00390
MV 00400
MV 00410
MV 00420
MV 00430
MV 00440
MV 00450
MV 00460
MV 00470
MV 00480
MV 00490
MV 00500

```

```

DO 50 K=1,NP2
50 VCV(IND)=VCV(IND)+(X(K,I)*X(K,J)-XM(I)*XM(J))
DO 60 I=1,NP3
60 VCV(I)=VCV(I)/FLOAT(NP2-1)
PRINT*, ' COV. MATRIX FOUND '
C
INTERNAL CHECKING FOR ALGORITHM ACCURACY
C
DO 80 I=1,NP1
IND=I*(I+1)/2
IF (VCV(IND).LT.0.0)GO TO 70
GO TO 80
70 WRITE(*,2)I,VCV(IND)
2 FORMAT('ACCURACY OF ALGORITHM IS POOR AT I =',I5,
+' WHERE VCV(I,I) = ',E15.7)
VCV(I)=-VCV(I)
IFLAG1=IFLAG1+1
80 CONTINUE
C
PRINT THE COMMENTS FOR ACCURACY
C
IF (IFLAG1.GT.0)GO TO 90
PRINT*, ' POSITIVE VARIANCES CHECK DONE '
WRITE(*,4)
GO TO 100
90 WRITE(*,3)IFLAG1
3 FORMAT(' THERE ARE ',I5,' VARIANCES LESS THAN 0.0 ')
4 FORMAT(' ALL VARIANCES ARE ">= 0.0", ACCURACY IS GOOD')
C
SEND THE RESULTS TO OUTPUT DATA FILE
C
100 DO 110 I=1,NP1/NF3
110 WRITE(12,5)(XM(J),J=1+(I-1)*NF3,I*NF3)
5 FORMAT(5E15.7)
DO 120 I=1,NP3/NF3
120 WRITE(12,5)(VCV(J),J=1+(I-1)*NF3,I*NF3)
STOP
END
C
PROGRAM EV
PARAMETER(NP1=100,NP3=NP1*(NP1+1)/2,NP5=NP3+NP1,
+NF2=10,NF3=5)
REAL XM(NP1),VCV(NP3),VCVF(NP1,NP1),D(NP1),
+Z(NP1,NP1),WK2(NP5)
REAL TRACE,SUM
DATA JOB2,IFLAG1,SUM,TRACE/2,0,2*0.0/
C
NP1 : RAW DATA DIMENSIONALITY
C
NP3 : TOTAL NUMBER OF ELEMENTS FOR VCV
C
NP5 : DIMENSION FOR PERFORMANCE INDEX MATRIX WK2
C
XM : MEAN VECTOR
C
VCV : COVARIANCE MATRIX ( SYMMETRIC STORAGE MODE )
C
VCVF : COVARIANCE MATRIX ( FULL STORAGE MODE )
C
D : EIGENVALUE

```

```

MV 00510
MV 00520
MV 00530
MV 00540
MV 00550
MV 00560
MV 00570
MV 00580
MV 00590
MV 00600
MV 00610
MV 00620
MV 00630
MV 00640
MV 00650
MV 00660
MV 00670
MV 00680
MV 00690
MV 00700
MV 00710
MV 00720
MV 00730
MV 00740
MV 00750
MV 00760
MV 00770
MV 00780
MV 00790
MV 00800
MV 00810
MV 00820
MV 00830
MV 00840
MV 00850
MV 00860
MV 00870
MV 00880
EV 00010
EV 00020
EV 00030
EV 00040
EV 00050
EV 00060
EV 00070
EV 00080
EV 00090
EV 00100
EV 00110
EV 00120
EV 00130
EV 00140
EV 00150
EV 00160

```

C	Z	:	EIGENVECTOR	EV	00170
C	WK2	:	PERFORMANCE INDEX MATRIX	EV	00180
C				EV	00190
C	11	:	INPUT MV FILE ; 12 : OUTPUT EV FILE	EV	00200
C				EV	00210
	OPEN(11)			EV	00220
	OPEN(12)			EV	00230
	REWIND 11			EV	00240
	REWIND 12			EV	00250
C				EV	00260
C	READ	IN	MEAN VECTOR AND COVARIANCE MATRIX	EV	00270
C				EV	00280
	DO	10	I=1,NP1/NF3	EV	00290
	10	READ	(11,*) (XM(J), J=1+(I-1)*NF3, I*NF3)	EV	00300
	1	FORMAT	(5E15.7)	EV	00310
	DO	20	I=1,NP3/NF3	EV	00320
	20	READ	(11,*) (VCV(J), J=1+(I-1)*NF3, I*NF3)	EV	00330
		CALL	VCVTSF (VCV, NP1, VCVF, NP1)	EV	00340
				EV	00350
C				EV	00360
C	FIND	TRACE,	EIGENVALUES AND EIGENVECTORS OF THE COVARIANCE MATRIX	EV	00370
C				EV	00380
	DO	30	I=1,NP1	EV	00390
	30	TRACE=TRACE+VCVF	(I, I)	EV	00400
		CALL	EIGRS (VCV, NP1, JOB2, D, Z, NP1, WK2, IER)	EV	00410
C				EV	00420
C	PRINT	THE	PERFORMANCE INDEX AND ACCURACY COMMENTS	EV	00430
C				EV	00440
	IF	(IER.NE.0.OR.WK2(1).GE.1.0)GO	TO 40	EV	00440
	WRITE	(*, 3)IER, WK2(1)		EV	00450
	GO	TO 50		EV	00460
	40	WRITE	(*, 2)IER, WK2(1)	EV	00470
	2	FORMAT	(' PERFORMANCE OF "EIGRS" IS POOR, IER =', I5,	EV	00480
		+' WK2(1) =', E15.7)		EV	00490
	3	FORMAT	(' PERFORMANCE OF "EIGRS" IS GOOD, IER =', I5,	EV	00500
		+' WK2(1) =', E15.7)		EV	00510
				EV	00520
C				EV	00530
C	INTERNAL	CHECKING	FOR ACCURACY	EV	00540
C				EV	00550
	50	DO	70 I=1,NP1	EV	00560
		IF	(D(I).LE.0.0)GO TO 60	EV	00560
		GO	TO 70	EV	00570
	60	WRITE	(*, 4)I, D(I)	EV	00580
	4	FORMAT	(' EIGEN VALUE IS "< = 0.0" AT I =', I5,	EV	00590
		+' WHERE D(I) =', E15.7)		EV	00600
		IFLAG1=IFLAG1+1		EV	00610
	70	CONTINUE		EV	00620
		IF	(IFLAG1.GT.0)GO TO 80	EV	00630
		WRITE	(*, 6)	EV	00640
		GO	TO 90	EV	00650
	80	WRITE	(*, 5)IFLAG1	EV	00660
	5	FORMAT	(' THERE ARE', I5, ' NEGATIVE OR ZERO EIGEN VALUES ')	EV	00670
	6	FORMAT	(' ALL EIGEN VALUES ARE GREATER THAN ZERO ')	EV	00680
				EV	00690
C				EV	00700
C	FIND	THE	SUM OF THE EIGENVALUES AND PRINT THE ACCURACY COMMENTS	EV	00710
C				EV	00710
	90	CALL	VABSMF (D, NP1, 1, SUM)	EV	00720
		IF	(ABS (TRACE-SUM) .GT.1.0E-1)GO TO 100	EV	00730


```

PROGRAM WALSH
C
C THIS PROGRAM IS USED TO GENERATE THE FIRST 64 100-DIM. WALSH FUN.
C IN THIS PROGRAM WE SET W1=0.1 AND W2=-0.1 SUCH THAT NORM(W)=1.0
C NP1 = 100, M = 6 , NF4 = 5 USED FOR 64 100-DIM WALSH FUNCTIONS
C
C PARAMETER (NP1=100,M=6,NTVEC=2**M,NMAX=2** (M-1) ,
+W1=0.1,W2=-0.1,NF4=5,NP5=NP1/2,NP6=NP1/4)
C REAL Z (NP1,NTVEC) , ZW1 (NP1,NMAX) , ZW2 (NP1,NMAX)
C INTEGER NZERO (NTVEC)
C
C NP1 : DIMENSIONALITY OF WALSH FUNCTION
C M : TOTAL NUMBER OF WALSH FUNCTIONS IS 2**M
C NTVEC : TOTAL NUMBER OF WALSH FUNCTIONS
C W1 : THE NORMALIZED LENGTH OF 100-DIM. WALSH FUNCTION
C W2 : THE NEGATIVE OF W1
C NF4 : OUTPUT FORMAT USE
C Z : RESULTS OF WALSH FUNCTIONS ( OUTPUT )
C ZW1 : INTERMEDIATE MATRIX FOR WALSH FUNCTION GENERATION
C ZW2 : INTERMEDIATE MATRIX FOR WALSH FUNCTION GENERATION
C NZERO : CHECKING VECTOR FOR AXIS CROSSINGS OF WALSH FUNCTIONS
C
C SET UP THE FIRST 4 WALSH FUNCTIONS
C
C DATA ((Z (I, J), I=1, NP1), J=1, 4) / NP1 * W1, NP5 * W1, NP5 * W2,
+NP6 * W1, NP5 * W2, NP6 * W1, NP6 * W1, NP6 * W2, NP6 * W1, NP6 * W2 /
C
C OPEN (11)
C REWIND 11
C
C STORE THE THIRD AND FOURTH WALSH FUNCTIONS
C
C DO 10 J=1,2
C DO 10 I=1, NP1
10 ZW1 (I, J) = Z (I, 2+J)
PRINT *, 'IM = 0, 1, 2, SEQ : Z (I, 1), Z (I, 2), ZW1 (I, 1), ZW1 (I, 2) '
DO 20 I=1, NP1
20 WRITE (*, *) I, Z (I, 1), Z (I, 2), ZW1 (I, 1), ZW1 (I, 2)
C
C GENERATE THE FIRST 2**M WALSH FUNCTIONS
C
C DO 70 IM=3,M
C K=2** (IM-1)
C DO 30 IK=1,K-1,2
C IKM=(IK+1) / 2
C DO 30 I=1, NP5
C ZW2 (I, IK) = ZW1 (2*I, IKM)
30 ZW2 (NP5+I, IK) = ((-1.) ** (IKM+1)) * ZW1 (2*I, IKM)
DO 40 IK=2,K,2
IKM=IK/2
DO 40 I=1, NP5
ZW2 (I, IK) = ZW1 (2*I, IKM)
40 ZW2 (NP5+I, IK) = ((-1.) ** (IKM)) * ZW1 (2*I, IKM)
DO 50 IK=1,K
DO 50 I=1, NP1
Z (I, K+IK) = ZW2 (I, IK)
50 ZW1 (I, IK) = ZW2 (I, IK)

```

```

WAL00010
WAL00020
WAL00030
WAL00040
WAL00050
WAL00060
WAL00070
WAL00080
WAL00090
WAL00100
WAL00110
WAL00120
WAL00130
WAL00140
WAL00150
WAL00160
WAL00170
WAL00180
WAL00190
WAL00200
WAL00210
WAL00220
WAL00230
WAL00240
WAL00250
WAL00260
WAL00270
WAL00280
WAL00290
WAL00300
WAL00310
WAL00320
WAL00330
WAL00340
WAL00350
WAL00360
WAL00370
WAL00380
WAL00390
WAL00400
WAL00410
WAL00420
WAL00430
WAL00440
WAL00450
WAL00460
WAL00470
WAL00480
WAL00490
WAL00500
WAL00510
WAL00520
WAL00530
WAL00540
WAL00550
WAL00560
WAL00570

```

```

IF (IM.GE.6)GO TO 70
WRITE(*,1)IM,K
1 FORMAT(' IM = ',I2,' , THE SEQ IS ZW2(I,J) , J=1,K=',I3)
DO 60 I=1,NP1
60 WRITE(*,3)I, (ZW2(I,J),J=1,K)
3 FORMAT(I4,2X,16F4.1)
70 CONTINUE
C
C CHECK TOTAL NUMBER OF AXIS CROSSINGS FOR EACH WALSH FUNCTIONS
C
DO 80 J=1,NTVEC
DO 80 I=1,NP1-1
IF (Z(I,J).NE.Z(I+1,J))NZERO(J)=NZERO(J)+1
80 CONTINUE
C
C THE FOLLOWING 2 STATEMENTS CAN BE USED FOR INTERNAL CHECKING
C
DO 85 I1=1,NTVEC/8
85 WRITE(I1,86) (NZERO(J),J=1+(I1-1)*8,I1*8)
86 FORMAT(8I8)
C WRITE(*,*) (NZERO(J),J=1,NTVEC)
DO 90 J=1,NTVEC
IF (NZERO(J).NE.(J-1))GO TO 200
90 CONTINUE
C
C SEND THE RESULTS TO OUTPUT FILE
C
DO 140 J=1,NTVEC
DO 140 K=1,NP1/NF4
140 WRITE(I1,4) (Z(I,J),I=1+(K-1)*NF4,K*NF4)
C
C CHOOSE FORMAT(10F8.1) IF NF4=10 INSTEAD OF 5
C
4 FORMAT(10F8.1)
4 FORMAT(5E15.7)
200 STOP
END
WAL00580
WAL00590
WAL00600
WAL00610
WAL00620
WAL00630
WAL00640
WAL00650
WAL00660
WAL00670
WAL00680
WAL00690
WAL00700
WAL00710
WAL00720
WAL00730
WAL00740
WAL00750
WAL00760
WAL00770
WAL00780
WAL00790
WAL00800
WAL00810
WAL00820
WAL00830
WAL00840
WAL00850
WAL00860
WAL00870
WAL00880
WAL00890
WAL00900
WAL00910
WAL00920
WAL00930
WAL00940

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```

PROGRAM INFCLIP
PARAMETER (NP1=100, NTERM=16, IEV=1)
REAL X(NP1)
C
C NP1 : RAW DATA DIMENSIONALITY
C NTERMS : TOTAL NUMBER OF OPTIMAL FUNCTIONS USED IN THE ALGORITHM
C X : INPUT AND OUTPUT VARIABLE
C
C IEV : INPUT FILE READING INDEX ( CHOOSE EITHER 1 OR 0 )
C IEV = 1 IF INPUT FILE CONTAINS TRACE, EIGENVALUES AND THEIR SUM
C IEV = 0 IF INPUT FILE CONTAINS ONLY EIGENVECTORS
C
C 11 : INPUT EV FILE; 12 : OUTPUT INF. CLIPPED OPT. FEATURE FILE
C
INF00010
INF00020
INF00030
INF00040
INF00050
INF00060
INF00070
INF00080
INF00090
INF00100
INF00110
INF00120
INF00130
INF00140
INF00150

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C      NTERM : TOTAL NUMBER OF OPTIMAL FUNCTIONS USED IN THE ALGORITHM OLB00120
C      NV    : PRESET TOTAL NUMBER OF L.D. BANDS, INCREASE IT IF NEEDED OLB00130
C      N1    : STARTING WAVELENGTH POINT OLB00140
C      N2    : ENDING WAVELENGTH POINT OLB00150
C      W1    : STARTING WAVELENGTH IN MICRO METER ( UM ) OLB00160
C      DW    : SPECTRAL RESOLUTION ( UM ) OLB00170
C      NVX   : PRESET TOTAL NUMBER OF L.I. BANDS, INCREASE IT IF NEEDED OLB00180
C      X     : INPUT EIGENVECTOR MATRIX OLB00200
C      S1    : SIGNED VERSION OF THE EIGENVECTOR OLB00210
C      Z     : L.D. BAND FEATURES OLB00220
C      T1    : TEMPORARY STORAGE VECTOR OLB00230
C      TEST  : OUTPUT O.L. BAND FEATURES ( L.I. FEATURES ) OLB00240
C      A     : INTERMEDIATE MATRIX FOR RANK TEST OLB00250
C      NX(K) : TOTAL NO. OF L.D. BANDS FOR THE FIRST K EIGENVECTOR(S) OLB00260
C      NEDGE : BAND EDGES FOR EACH L.D. BANDS OLB00270
C      NWID  : BAND WIDTH FOR EACH L.D. BANDS OLB00280
C      NRANK : POSITIONS OF THE RANKED FEATURES BY THE WIDTHS OLB00290
C      NREP  : INDEX SHOWS IF THE L.D. BANDS ARE REPEATED OLB00300
C      MREP  : INDEX SHOWS IF THE BANDS ARE L.I. BANDS OLB00310
C      NREP = 1 IF NON-REPEATED BAND ; NREP = 0 IF REPEATED OLB00330
C      MREP = 1 IF L.I. BAND ; MREP = 0 IF L.D. OLB00340
C      11 : INPUT EIGENVECTOR FILE OLB00360
C      12 : FIRST OUTPUT FILE ---- L.D. AND L.I. BAND INFORMATION OLB00370
C      13 : SECOND OUTPUT FILE ---- DESIRED O.L. BAND FEATURE OLB00380
C      OPEN(11) OLB00400
C      OPEN(12) OLB00410
C      OPEN(13) OLB00420
C      REWIND 11 OLB00430
C      REWIND 12 OLB00440
C      REWIND 13 OLB00450
C      READ IN EIGENVECTORS OLB00470
C      READ(11,*)X1,X2 OLB00490
C      DO 10 I=1,NP1/5 OLB00500
10    READ(11,*)X1,X2,X3,X4,X5 OLB00510
C      DO 20 J=1,NTERM OLB00520
C      DO 20 I=1,NP1/5 OLB00530
20    READ(11,*) (X(K,J),K=1+(I-1)*5,I*5) OLB00540
C      FIND THE L.D. BAND FEATURES FROM FIRST 'NTERM' OPTIMAL FUNCTIONS OLB00560
C      IVEC=1 OLB00580
C      DO 70 J=1,NTERM OLB00590
C      DO 40 I=1,NP1 OLB00600
C      IF(X(I,J).LT.0.0)S1(I)=-1.0 OLB00610
C      IF(X(I,J).GT.0.0)S1(I)=+1.0 OLB00620
C      IF(X(I,J).EQ.0.0)S1(I)=0.0 OLB00630
C      IF(NP1.NE.100)GO TO 40 OLB00640
C      IF(I.GE.45.AND.I.LE.54)S1(I)=0.0 OLB00650
C      IF(I.GE.70.AND.I.LE.79)S1(I)=0.0 OLB00660
40    CONTINUE OLB00670
C      Z(N1,IVEC)=ABS(S1(N1)) OLB00680

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DO 60 I=N1+1,N2                                OLB00690
IF(NP1.NE.100)GO TO 50                          OLB00700
IF(I.GE.45.AND.I.LE.54)GO TO 60                OLB00710
IF(I.GE.70.AND.I.LE.79)GO TO 60                OLB00720
50 IF(S1(I-1).NE.S1(I))IVEC=IVEC+1             OLB00730
IF(IVEC.GT.NV)GO TO 350                         OLB00740
Z(I,IVEC)=ABS(S1(I))                            OLB00750
60 CONTINUE                                     OLB00760
NX(J)=IVEC                                       OLB00770
IVEC=IVEC+1                                      OLB00780
70 CONTINUE                                     OLB00790
C                                                OLB00800
C FIND THE BAND EDGES AND BAND WIDTH FOR EACH L.D. BAND FEATURES OLB00810
C                                                OLB00820
NVTOT=NX(NTERM)                                  OLB00830
DO 90 J=1,NVTOT                                  OLB00840
I1=0                                              OLB00850
I2=0                                              OLB00860
DO 80 I=1,NP1                                    OLB00870
CK1=Z(I,J)                                       OLB00880
IF(CK1.EQ.0.0)GO TO 80                           OLB00890
IF(CK1.NE.0.0.AND.I1.EQ.0)I1=I                  OLB00900
IF(CK1.NE.0.0.AND.I1.NE.0)I2=I                  OLB00910
80 CONTINUE                                     OLB00920
IF(I2.EQ.0)I2=I1                                  OLB00930
NEDGE(1,J)=I1                                     OLB00940
NEDGE(2,J)=I2                                     OLB00950
NWID(J)=I2-I1+1                                  OLB00960
90 CONTINUE                                     OLB00970
C                                                OLB00980
C FIND THE WAVELENGTH EDGES AND SEND THEM TO THE FIRST OUTPUT FILE OLB00990
C                                                OLB01000
DO 100 J=1,NTERM                                  OLB01010
WRITE(12,*)J                                       OLB01020
IF(J.EQ.1)NS1=NX(J)                               OLB01030
IF(J.NE.1)NS1=NX(J)-NX(J-1)                     OLB01040
DO 100 I=1,NS1                                    OLB01050
IF(J.EQ.1)NS2=I                                    OLB01060
IF(J.NE.1)NS2=I+NX(J-1)                          OLB01070
I1=NEDGE(1,NS2)                                   OLB01080
I2=NEDGE(2,NS2)                                   OLB01090
XW1=W1+FLOAT(I1-1)*DW                             OLB01100
XW2=W1+FLOAT(I2)*DW                               OLB01110
WRITE(12,101)NS2,I,NEDGE(1,NS2),NEDGE(2,NS2),XW1,XW2,NWID(NS2) OLB01120
100 CONTINUE                                     OLB01130
101 FORMAT(2I5,2X,I3,1X,'-',I3,2X,';',',F5.2,1X,'-',F5.2,I5) OLB01140
PRINT*, 'TOTAL NUMBER OF BANDS IS = ',NVTOT      OLB01150
C                                                OLB01160
C RANK THE L.D. BAND ACCORDING TO THEIR WIDTHS IN DESCENDING ORDER OLB01170
C AND SEND THE RESULTS TO THE FIRST OUTPUT FILE OLB01180
C                                                OLB01190
DO 110 I=1,NV                                     OLB01200
110 T1(I)=FLOAT(NWID(I))                          OLB01210
DO 120 I=1,NVTOT                                  OLB01220
CALL VABMXF(T1(1),NV,1,IMAX,BIG)                 OLB01230
NRANK(I)=IMAX                                     OLB01240
WRITE(12,*)I,NRANK(I),NEDGE(1,IMAX),NEDGE(2,IMAX),NWID(IMAX) OLB01250

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120	T1(IMAX)=0.0	OLB01260
C		OLB01270
C	CHECK IF THE L.D. BAND IS REPEATED. IF IT IS, SET NREP(I) = 0	OLB01280
C		OLB01290
	DO 140 I=1,NVTOT	OLB01300
	DO 130 J=1,NVTOT	OLB01310
	IF(I.EQ.J)GO TO 130	OLB01320
	I1=NRANK(I)	OLB01330
	I2=NRANK(J)	OLB01340
	I3=NWID(I1)	OLB01350
	I4=NWID(I2)	OLB01360
	IF(I3.NE.I4)GO TO 130	OLB01370
	ISTART=NEDGE(1,I1)	OLB01380
	JSTART=NEDGE(1,I2)	OLB01390
	IEND=NEDGE(2,I1)	OLB01400
	JEND=NEDGE(2,I2)	OLB01410
	IF(ISTART.EQ.JSTART.AND.IEND.EQ.JEND.AND.I.GT.J)NREP(I)=0	OLB01420
130	CONTINUE	OLB01430
	IF(NREP(I).EQ.0)GO TO 140	OLB01440
	IX=NRANK(I)	OLB01450
		OLB01460
C		OLB01470
C	THE FOLLOWING WRITE STATEMENT CAN BE USED FOR INTERNAL CHECKING	OLB01480
C		OLB01490
C	WRITE(12,131)I,NREP(I),NRANK(I),NEDGE(1,IX),NEDGE(2,IX),NWID(IX)	OLB01490
131	FORMAT(3I4,5X,I4,'-',I4,5X,I4)	OLB01500
140	CONTINUE	OLB01510
		OLB01520
C		OLB01530
C	FIND TOTAL NUMBER OF NON-REPEATED L.D. BAND	OLB01530
C		OLB01540
	NDIFF=0	OLB01550
	DO 150 I=1,NVTOT	OLB01560
	IF(NREP(I).EQ.1)NDIFF=NDIFF+1	OLB01570
150	MREP(I)=NREP(I)	OLB01580
	PRINT*,'TOTAL NUMBER OF NON-IDENTICAL BANDS IS =',NDIFF	OLB01590
		OLB01600
C		OLB01610
C	FIND L.I. BAND BY CHECKING THE MATRIX RANK	OLB01610
C		OLB01620
	ILI=1	OLB01630
	JWID=1	OLB01640
	DO 300 J=1,NVTOT	OLB01650
	IF(NREP(J).EQ.0)GO TO 300	OLB01660
	JR=NRANK(J)	OLB01670
	DO 160 I=1,NP1	OLB01680
160	TEST(I,ILI)=Z(I,JR)	OLB01690
	DO 170 KI=1,NP1	OLB01700
	DO 170 KJ=1,ILI	OLB01710
170	A(KI,KJ)=TEST(KI,KJ)	OLB01720
		OLB01730
C		OLB01740
C	REDUCE THE MATRIX A TO ITS ECHELON FORM	OLB01740
C		OLB01750
	CALL ECHEL(A,NP1,NVX,NP1,ILI)	OLB01760
	IEV=0	OLB01770
	DO 190 KI=1,NP1	OLB01780
	DO 180 KJ=1,ILI	OLB01790
	IF(A(KI,KJ).NE.0.0)IEV=IEV+1	OLB01800
	IF(A(KI,KJ).NE.0.0)GO TO 190	OLB01810
180	CONTINUE	OLB01820

190	CONTINUE	OLB01830
C		OLB01840
C	SEND THE RANK INFORMATION TO THE FIRST OUTPUT FILE	OLB01850
C	WHERE 'IEV' IS THE RANK AND 'ILI' IS TOTAL NUMBER OF BANDS TESTED	OLB01860
C		OLB01870
	WRITE (12,*) 'IEV=', IEV, '; ILI=', ILI, 'AT J=', J	OLB01880
	IF (IEV.LT.ILI) WRITE (12,*) 'IEV.LT.ILI AT J=', J	OLB01890
	IF (IEV.LT.ILI) GO TO 200	OLB01900
C		OLB01910
C	IF RANK IS EQUAL TO TOTAL NO. OF BANDS, TEST THE NEXT WIDEST BAND	OLB01920
C		OLB01930
	IF (IEV.EQ.ILI) ILI=ILI+1	OLB01940
	GO TO 300	OLB01950
C		OLB01960
C	IF RANK IS LESS THEN TOTAL NO. OF BANDS,	OLB01970
C	ELIMINATE THE WIDEST L.D. BAND	OLB01980
C		OLB01990
200	DO 250 JXLD=1, ILI	OLB02000
	DO 210 KJ=1, ILI	OLB02010
	DO 210 KI=1, NP1	OLB02020
210	A (KI, KJ)=TEST (KI, KJ)	OLB02030
	DO 220 KI=1, NP1	OLB02040
220	A (KI, JXLD)=TEST (KI, ILI)	OLB02050
	JLI=ILI-1	OLB02060
	CALL ECHEL (A, NP1, NVX, NP1, JLI)	OLB02070
	IEV=0	OLB02080
	DO 240 KI=1, NP1	OLB02090
	DO 230 KJ=1, JLI	OLB02100
	IF (A (KI, KJ) .NE. 0.0) IEV=IEV+1	OLB02110
	IF (A (KI, KJ) .NE. 0.0) GO TO 240	OLB02120
230	CONTINUE	OLB02130
240	CONTINUE	OLB02140
C	PRINT*, 'IEV=', IEV, '; ILI=', ILI, 'AT J=', J	OLB02150
C	IF (IEV.LT.ILI) PRINT*, 'IEV.LT.ILI AT J=', J	OLB02160
	IF (IEV.EQ.JLI) J2LD=JXLD	OLB02170
	IF (IEV.EQ.JLI) GO TO 260	OLB02180
250	CONTINUE	OLB02190
260	I1=0	OLB02200
	I2=0	OLB02210
	DO 270 KI=1, NP1	OLB02220
	CK1=TEST (KI, J2LD)	OLB02230
	IF (CK1.EQ.0.0) GO TO 270	OLB02240
	IF (CK1.NE.0.0.AND.I1.EQ.0) I1=KI	OLB02250
	IF (CK1.NE.0.0.AND.I1.NE.0) I2=KI	OLB02260
270	CONTINUE	OLB02270
	IF (I2.EQ.0) I2=I1	OLB02280
	DO 275 KI=1, NVTOT	OLB02290
	IF (MREP (KI) .EQ.0) GO TO 275	OLB02300
	MAX=NRANK (KI)	OLB02310
	MEDGE1=NEDGE (1, MAX)	OLB02320
	MEDGE2=NEDGE (2, MAX)	OLB02330
	IF (I1.EQ.MEDGE1.AND.I2.EQ.MEDGE2) J1LD=KI	OLB02340
	IF (I1.EQ.MEDGE1.AND.I2.EQ.MEDGE2) GO TO 280	OLB02350
275	CONTINUE	OLB02360
280	MREP (J1LD)=0	OLB02370
C		OLB02380
C	SEND THE POSITION OF THE WIDEST L.D. BAND FEATURE	OLB02390

C	TO THE FIRST OUTPUT FILE WHERE :	OLB02400
C		OLB02410
C	J1LD IS THE POSITION ON THE VARIABLES NREP AND MREP	OLB02420
C	J2LD IS THE POSITION ON THE RANK CHECKING MATRIX	OLB02430
C		OLB02440
	WRITE (12,*) 'J =', J, ','; J1LD =', J1LD, ','; J2LD =', J2LD	OLB02450
	DO 290 J1=J2LD, I1I-1	OLB02460
	DO 290 I1=1, NP1	OLB02470
	290 TEST (I1, J1)=TEST (I1, J1+1)	OLB02480
	300 CONTINUE	OLB02490
C		OLB02500
C	SEND THE L.I. INDEX TO THE FIRST OUTPUT FILE	OLB02510
C		OLB02520
	PRINT*, 'TOTAL NUMBER OF L.I. BANDS IS =', IEV	OLB02530
	DO 310 I=1, NVTOT	OLB02540
	310 WRITE (12,*) I, NREP (I), MREP (I)	OLB02550
C		OLB02560
C	NORMALIZE THE O.L. BANDS AND SEND THEM TO THE SECOND OUTPUT FILE	OLB02570
C		OLB02580
	DO 330 J=1, IEV	OLB02590
	XN1=0.0	OLB02600
	DO 320 I=1, NP1	OLB02610
	IF (TEST (I, J) .EQ. 1) XN1=XN1+1	OLB02620
	320 CONTINUE	OLB02630
	DO 330 I=1, NP1	OLB02640
	330 TEST (I, J)=TEST (I, J) /SQRT (XN1)	OLB02650
	DO 340 J=1, IEV	OLB02660
	DO 340 K=1, NP1/5	OLB02670
C	J1=IEV-J+1	OLB02680
	340 WRITE (13, 341) (TEST (I, J), I=1+(K-1)*5, K*5)	OLB02690
	341 FORMAT (5E15.7)	OLB02700
	GO TO 360	OLB02710
	350 PRINT*, 'TOTAL NUMBER OF BANDS IS OUT OF PRESET LIMIT'	OLB02720
	360 STOP	OLB02730
	END	OLB02740
	SUBROUTINE ECHEL (A, NP1, NVX, NROW, NCOL)	OLB02750
	REAL A (NP1, NVX)	OLB02760
C		OLB02770
C	THIS SUBROUTINE REDUCES MATRIX A INTO ITS ECHELON FORM	OLB02780
C		OLB02790
	JCOL=1	OLB02800
	IROW=1	OLB02810
	5 DO 100 I=IROW, NROW	OLB02820
	IF (A (I, JCOL) .EQ. 0.0) GO TO 100	OLB02830
C	INTERCHANGE I AND IROW TO GET NONZERO PIVOT	OLB02840
	IF (I .EQ. IROW) GO TO 20	OLB02850
	DO 10 J=JCOL, NCOL	OLB02860
	X1=A (I, J)	OLB02870
	A (I, J)=A (IROW, J)	OLB02880
	10 A (IROW, J)=X1	OLB02890
C	NORMALIZE ROW TO GET POSITIVE NUMBER FOR PIVOT	OLB02900
	20 IF (A (IROW, JCOL) .GT. 0.0) GO TO 40	OLB02910
	DO 30 J=JCOL, NCOL	OLB02920
	30 A (IROW, J)=-A (IROW, J)	OLB02930
	40 IF (IROW .GE. NROW) RETURN	OLB02940
C	ZERO COLUMN BELOW PIVOT	OLB02950
	IROWX=IROW+1	OLB02960

C X = TRANSFORMED DATA CLS00390
 C Z = FEATURES CLS00400
 C RX = TEMPORARY STORAGE FOR FEATURES CLS00410
 C XT = INPUT DATA CLS00420
 C XM = MEAN VECTOR CLS00430
 C D = EIGENVALUES CLS00440
 C XMCT = MEAN VECTOR FOR ALL CLASSES CLS00450
 C XMC = MEAN VECTOR FOR ONE CLASS CLS00460
 C VCT = COVARIANCE MATRIX FOR ALL CLASSES CLS00470
 C VC = COVARIANCE MATRIX FOR ONE CLASS CLS00480
 C VCIT = INVERSE MATRIX OF ALL CLASS COVARIANCE MATRICES CLS00490
 C VCI = INVERSE MATRIX OF ONE CLASS COVARIANCE MATRIX CLS00500
 C TEST = INTERNAL MATRIX INVERSION CHECKING MATRIX CLS00510
 C VCTLI = COV. MATRIX FOR ALL CLASSES BY USING ALL L.I. FEATURES CLS00520
 C XMTLI = MEAN VECTOR FOR ALL CLASSES BY USING L.I. FEATURES CLS00530
 C WK = WORKING SPACE FOR IMSL ROUTINES CLS00540
 C VCV = COV. MATRIX USED TO TEST ITS POSITIVE DEFINITENESS CLS00550
 C VEC = GENERATED SAMPLES USED TO TEST POSITIVE DEFINITENESS CLS00560
 C
 C --->>CHOOSE OR TYPE IN THE CORRECT NUMBERS OF SAMPLES IN THE DATA SETS CLS00580
 C
 C ----- CLS00590
 C
 C NSET F1 NP2 A B C DACO EXNU RUSE CLS00600
 C 1 M2611K1 832 WW:141 SF:414 GS:277 760928 76102207 1-1622 CLS00620
 C 2 M2611K2 1551 WW:658 SF:211 UC:682 770503 77102207 6515-8096 CLS00630
 C 3 M2611K3 1477 WW:677 SF:643 GS:157 770626 77102207 8097-9691 CLS00640
 C 4 M2614N1 1265 SW:664 SF:437 NP:164 770508 77102217 1-1396 CLS00650
 C 5 M2614N2 1239 SW:787 SF:291 NP:161 770629 77102217 2777-4141 CLS00660
 C 6 M2614N3 1444 SW:931 SF:330 NP:183 770804 77102217 5426-6993 CLS00670
 C
 C DATA NST/141, 414, 277, 658, 211, 682, 677, 643, 157/ CLS00680
 C DATA NST/141, 414, 277, 658, 211, 682, 677, 643, 157, CLS00690
 C +664, 437, 164, 787, 291, 161, 931, 330, 183/ CLS00710
 C DATA NST/664, 437, 164, 787, 291, 161, 931, 330, 183/ CLS00720
 C DATA NST/141, 414, 277, 658, 211, 682, 677/ CLS00730
 C DATA NST/587, 216, 121/ CLS00740
 C DATA NST/658, 211, 682/ CLS00750
 C
 C ----- CLS00760
 C
 C THE FOLLOWING DATA 'NST' ARE USED FOR SOIL ORDER DATA SET. 'SO' CLS00770
 C
 C NP2=479; MOL ALF EN AR UL IN SP VE H OX UNCLASSIFIED CLS00780
 C DATA NST/154, 113, 78, 52, 45, 37, 30, 11, 8, 11, 32/ CLS00790
 C DATA NST/154, 113, 78, 52, 45, 97/ CLS00800
 C DATA NST/154, 113, 78, 52, 45, 37/ CLS00810
 C
 C ----- CLS00820
 C
 C THE FOLLOWING DATA 'NST' IS USED FOR SOIL 'OM1' DATA SET CLS00830
 C I.E. (1) MOLLISOL, OR (2) ALFISOL, AND GROUP SAMPLES CLS00840
 C ACCORDING TO THEIR ORGANIC MATERIAL: % WEIGHT CLS00850
 C CLASS 1 TO 6 : NP2 = 255 CLS00860
 C CLS1 : .11% .GE. OM .LE. 1.5% : # 1 -> # 51 CLS00870
 C CLS2 : 1.5% .GT. OM .LE. 2.0% : # 52 -> # 104 CLS00880
 C CLS3 : 2.0% .GT. OM .LE. 2.5% : # 105 -> # 138 CLS00890
 C CLS4 : 2.5% .GT. OM .LE. 3.5% : # 139 -> # 183 CLS00900
 C CLS5 : 3.5% .GT. OM .LE. 5.0% : # 184 -> # 222 CLS00910
 C CLS00920
 C CLS00930
 C CLS00940
 C CLS00950

C CLS6 : 5.0% .GT. OM .LE. 10.12% : # 223 -> # 255 CLS00960
 C DATA NST/51,54,33,45,39,33/ CLS00970
 C CLS00980
 C CLS00990
 C DATA 'S2A' : ANOTHER TEST GROUPED BY THE SAME OM RANGES AS 'OM2' CLS01000
 C OM PERCENTAGE : 0,1; 1,2; 2,3; 3,4; 4,6; 6 AND ABOVE CLS01010
 C CLS01020
 C DATA NST/26,78,64,32,55/ CLS01030
 C CLS01040
 C CLS01050
 C ----- CLS01060
 C THE FOLLOWING DATA 'NST' IS USED FOR 'OM2' DATA SET CLS01070
 C ACCORDING TO THEIR ORGANIC MATERIAL: % WEIGHT CLS01080
 C CLASS 1 TO 6 : NP2 = 514 CLS01090
 C CLS1 : .08% .GE. OM .LE. 1.0% : # 1 -> # 82 CLS01100
 C CLS2 : 1.0% .GT. OM .LE. 2.0% : # 83 -> # 217 CLS01110
 C CLS3 : 2.0% .GT. OM .LE. 3.0% : # 218 -> # 337 CLS01120
 C CLS4 : 3.0% .GT. OM .LE. 4.0% : # 338 -> # 391 CLS01130
 C CLS5 : 4.0% .GT. OM .LE. 6.0% : # 392 -> # 450 CLS01140
 C CLS6 : 6.0% .GT. OM .LE. 84.79% : # 451 -> # 514 CLS01150
 C CLS01160
 C DATA NST/82,135,120,54,59,64/ CLS01170
 C CLS01180
 C DATA NST/82,135,120,54,123/ CLS01190
 C DATA NST/44,31,18,23,24,51,37,27/ CLS01200
 C DATA NST/83,57,94,31,37,59,103,26,24/ CLS01210
 C DATA NST/103,26,24/ CLS01220
 C ----- CLS01230
 C THE FOLLOWING DATA 'NST' IS USED FOR SOIL IRON OXIDE 'IO' DATA SET CLS01240
 C ACCORDING TO THEIR FE2O3 % WEIGHT CLS01250
 C CLASS 1 TO 6 : NP2 = 467 CLS01260
 C CLS1 : .02% .GE. FE2O3 .LE. 0.4% : # 1 -> # 102 CLS01270
 C CLS2 : 0.4% .GT. FE2O3 .LE. 0.6% : # 103 -> # 175 CLS01280
 C CLS3 : 0.6% .GT. FE2O3 .LE. 0.8% : # 176 -> # 244 CLS01290
 C CLS4 : 0.8% .GT. FE2O3 .LE. 1.2% : # 245 -> # 349 CLS01300
 C CLS5 : 1.2% .GT. FE2O3 .LE. 1.6% : # 350 -> # 401 CLS01310
 C CLS6 : 1.6% .GT. FE2O3 .LE. 25.60% : # 402 -> # 467 CLS01320
 C CLS01330
 C DATA NST/102,73,69,105,52,66/ CLS01340
 C CLS01350
 C ----- CLS01360
 C THE FOLLOWING DATA 'NST' IS USED FOR SOIL TEXTURE 'ST' DATA SET CLS01370
 C ACCORDING TO THEIR SAND-SILT-CLAY % CONTENT CLS01380
 C CLASS 1 TO 6 : NP2 = 483; DETAILS : SEE FILE (S5L.DATA.C1) CLS01390
 C CLS01400
 C DATA NST/40,63,76,93,68,143/ CLS01410
 C CLS01420
 C ----- CLS01430
 C THE FOLLOWING DATA 'NST' IS USED FOR S.D. VEGETATION DATA CLS01440
 C CLS01450
 C DATA NST/225,61,292,469, 82,182,63,103, 39,39,217,51, CLS01460
 C +393,441,80,88, 88,41,32,26, 118,43,121,44, 45,102,66,89, CLS01470
 C +78,53,147,39, 24,42,119,69, 76,96,107,154, 28,19/ CLS01480
 C CLS01490
 C ----- CLS01500
 C THE FOLLOWING DATA 'NST' IS USED FOR IOWA VEGETATION DATA CLS01510
 C CLS01520

C	DATA NST/514,41, 517,36,32, 621,517,45, 610,485,21,	CLS01530
C	+437,377,22, 190,172,25, 650,568,42, 435,417,44, 393,267/	CLS01540
C		CLS01550
C	-----	CLS01560
C		CLS01570
C	11 = DATA; 12 = FEATURES; 13 = CLASS STATISTICS;	CLS01580
C	14 = TRANSFORMED DATA ; 15 = LDBAND ; 16 = RANDOM	CLS01590
C		CLS01600
C	OPEN(11)	CLS01610
C	OPEN(12)	CLS01620
C	OPEN(13)	CLS01630
C	OPEN(14)	CLS01640
C	OPEN(15)	CLS01650
C	REWIND 11	CLS01660
C	REWIND 12	CLS01670
C	REWIND 13	CLS01680
C	REWIND 14	CLS01690
C	REWIND 15	CLS01700
C		CLS01710
C	SET UP DATA INPUT&OUTPUT DO LOOP PARAMETERS	CLS01720
C		CLS01730
C	IK1=MOD (NCLS, 6)	CLS01740
C	IM1=6* (NCLS/6)+1	CLS01750
C	ILP1=NCLS/6	CLS01760
C	IF (ILP1.EQ.0) ILP1=1	CLS01770
C	IK2=MOD (NTERM, 5)	CLS01780
C	IM2=5* (NTERM/5)+1	CLS01790
C	ILP2=NTERM/5	CLS01800
C	IF (ILP2.EQ.0) ILP2=1	CLS01810
C	DO 650 ISET=NSET,MSET,NDSET	CLS01820
C		CLS01830
C	READ FEATURE FILE IN TWO CASES (IEV = 0 OR 1)	CLS01840
C		CLS01850
C	IF (IEV.EQ.0) GO TO 10	CLS01860
C	READ (12,*) TRACE, SUM	CLS01870
C	CALL SRI (12,NP1,NF3,D)	CLS01880
C	10 DO 30 JTERM=1,NTERM	CLS01890
C	CALL SRI (12,NP1,NF3,RX)	CLS01900
C	DO 20 I=1,NP1	CLS01910
C	20 Z (I,JTERM)=RX (I)	CLS01920
C	30 CONTINUE	CLS01930
C		CLS01940
C	FIND MEAN VECTOR AND COVARIANCE MATRIX FOR EACH CLASS	CLS01950
C	IN THE FEATURE TRANSFORMED DATA	CLS01960
C		CLS01970
C	DO 150 LTERM=NTERM,NTERM	CLS01980
C	KTERM=LTERM*(LTERM+1)/2	CLS01990
C	DO 150 ICLS=1,NCLS	CLS02000
C	NS=NST (ICLS, ISET)	CLS02010
C	PRINT*, ' ISET =', ISET, '; ', LTERM, ICLS, NS	CLS02020
C	DO 40 I=1, NSMAX	CLS02030
C	DO 40 J=1, NTERM	CLS02040
C	40 X (I, J)=0.0	CLS02050
C	DO 100 ISAMP=1, NS	CLS02060
C	CALL SRI (11, NP1, NF, XT)	CLS02070
C	DO 70 JTERM=1, LTERM	CLS02080
C	DO 60 I=1, NP1	CLS02090

	T1(I)=XT(I)	CLS02100
	T2(I)=W(I)*T1(I)	CLS02110
60	T3(I)=Z(I,JTERM)	CLS02120
	CALL VIPREF(T3,T2,NP1,1,1,XIP)	CLS02130
70	X(ISAMP,JTERM)=XIP	CLS02140
C		CLS02150
C	SEND THE RESULTS TO THE TRANSFORMED DATA FILE	CLS02160
C		CLS02170
	IF(NTERM.LT.5)GO TO 90	CLS02180
	DO 80 I1=1,ILP2	CLS02190
80	WRITE(14,91)(X(ISAMP,J1),J1=1+(I1-1)*5,I1*5)	CLS02200
	IF(IK2.EQ.0)GO TO 100	CLS02210
90	WRITE(14,91)(X(ISAMP,J1),J1=IM2,NTERM)	CLS02220
91	FORMAT(5E15.7)	CLS02230
100	CONTINUE	CLS02240
C		CLS02250
C	FIND THE CLASS STATISTICS IF NKLT = 0	CLS02260
C		CLS02270
	IF(NKLT.EQ.1)GO TO 150	CLS02280
	NBR(1)=LTERM	CLS02290
	NBR(2)=NS	CLS02300
	NBR(3)=NS	CLS02310
	DO 110 I=1,NP1	CLS02320
110	T(I)=0.0	CLS02330
	CALL BECOVM(X,NSMAX,NBR,T,XMC,VC,IER)	CLS02340
C		CLS02350
C	STORE THE CLASS STATISTICS FOR POSITIVE DEFINITENESS CHECKING	CLS02360
C		CLS02370
	DO 120 I=1,LTERM	CLS02380
C	WRITE(*,*)LTERM,I,XMC(I)	CLS02390
120	XMCT(I,ICLS)=XMC(I)	CLS02400
	DO 130 I=1,KTERM	CLS02410
C	WRITE(*,*)LTERM,I,VC(I)	CLS02420
130	VCT(I,ICLS)=VC(I)	CLS02430
	PRINT*, ' THE IER MUST BE "0" FOR BECOVM '	CLS02440
	PRINT*, IER	CLS02450
150	CONTINUE	CLS02460
C		CLS02470
C	STOP THE PROGRAM IF ONLY WANT TO FIND TRANSFORMED DATA (NKLT=1)	CLS02480
C		CLS02490
	IF(NKLT.EQ.1)GO TO 650	CLS02500
C		CLS02510
C	STORE THE CLASS STATISTICS INTO FULL STORAGE MODE FOR CHECKING	CLS02520
C		CLS02530
	DO 170 ICLS=1,NCLS	CLS02540
	DO 170 I=1,NTERM	CLS02550
	DO 160 J=1,I	CLS02560
	IND=I*(I-1)/2+J	CLS02570
	VCTF(I,J,ICLS)=VCT(IND,ICLS)	CLS02580
	VCTF(J,I,ICLS)=VCTF(I,J,ICLS)	CLS02590
C	WRITE(*,*)I,J,IND,VCTF(I,J,ICLS),VCTF(J,I,ICLS)	CLS02600
160	CONTINUE	CLS02610
	XMCTF(I,ICLS)=XMCT(I,ICLS)	CLS02620
170	CONTINUE	CLS02630
C		CLS02640
C	START CHECKING THE POSITIVE DEFINITENESS OF THE COV. MATRICES	CLS02650
C	IF 'LTERM'TH FEATURE IS L.D. ON THE OTHER FEATURES, THE RELATED	CLS02660

C	ELEMENTS IN THE MEAN VECTORS AND COVARIANCES WILL BE REMOVED	CLS02670
C		CLS02680
	ILI=1	CLS02690
	JLI=ILI*(ILI+1)/2	CLS02700
	DO 600 LTERM=1, NTERM	CLS02710
	KTERM=LTERM*(LTERM+1)/2	CLS02720
	DO 400 ICLS=1, NCLS	CLS02730
	IX=0	CLS02740
	DO 200 IROW=1, LTERM	CLS02750
	V1=0.0	CLS02760
	DO 180 JCK=1, LTERM	CLS02770
180	V1=V1+VCTF(IROW, JCK, ICLS)	CLS02780
	VCK=VLD*LTERM	CLS02790
	IF(V1.EQ.VCK)GO TO 200	CLS02800
	IX=IX+1	CLS02810
	IY=0	CLS02820
	DO 190 JCOL=1, LTERM	CLS02830
	V2=VCTF(IROW, JCOL, ICLS)	CLS02840
	IF(V2.EQ.VLD)GO TO 190	CLS02850
	IY=IY+1	CLS02860
	VCF(IX, IY)=V2	CLS02870
190	CONTINUE	CLS02880
200	CONTINUE	CLS02890
C	WRITE(15,*)IX,IY,ILI	CLS02900
C	PRINT*, 'IX,IY,ILI MUST BE THE SAME', IX,IY,ILI	CLS02910
	CALL VCVTF(VCF, ICLS, NTERM, VC)	CLS02920
C	WRITE(*,*)ICLS,VC(1)	CLS02930
	OPEN(16)	CLS02940
	REWIND 16	CLS02950
	DO 210 I=1, JLI	CLS02960
	WRITE(16,211)VC(I)	CLS02970
C	VCV(I)=VC(I)	CLS02980
210	VCTLI(I, ICLS)=VC(I)	CLS02990
211	FORMAT(E13.5)	CLS03000
	OPEN(16)	CLS03010
	REWIND 16	CLS03020
	DO 220 I=1, JLI	CLS03030
220	READ(16,211)VCV(I)	CLS03040
	DO 230 I=1, NTERM	CLS03050
230	WK(I)=0.0	CLS03060
	DSEED=5.D0	CLS03070
C		CLS03080
C	SECOND TEST ON NUMERICAL POSITIVE DEFINITENESS OF THE MATRICES	CLS03090
C		CLS03100
	CALL GGNSM(DSEED, NSAMP, ILI, VCV, NSAMP, VEC, WK, IER)	CLS03110
	IF(IER.NE.0)GO TO 440	CLS03120
C	WRITE(*,*)ICLS,VCTLI(1, ICLS), VC(1)	CLS03130
C		CLS03140
C	CHECK IF ALL CLASS COVARIANCES HAVE INVERSE MATRICES	CLS03150
C	VC WILL BE CHANGED AFTER LINV1P	CLS03160
C		CLS03170
	CALL LINV1P(VC, ILI, VCI, IDGT, D1, D2, IER)	CLS03180
C	WRITE(*,*)ICLS,VCI(1)	CLS03190
C	PRINT*, ' THE FOLLOWING IER MUST BE 0 FOR LINV1P'	CLS03200
C	PRINT*, ISET, LTERM, ICLS, '; IER =', IER	CLS03210
C	IF(IER.NE.0)GO TO 450	CLS03220
	DO 240 I=1, JLI	CLS03230

240	VCIT(I, ICLS)=VCI(I)	CLS03240
C		CLS03250
C	STORE BACK THE VALUES OF VCVC FROM VCVCF	CLS03260
C		CLS03270
	CALL VCVTFS(VCF, ILI, NTERM, VC)	CLS03280
	CALL VCVTSF(VCI, ILI, VCIF, NTERM)	CLS03290
	DET=D1*2.**D2	CLS03300
	CX=(2.*3.14159)**(FLOAT(ILI)/2.)	CLS03310
	C=1./(CX*SQRT(DET))	CLS03320
	CT(ICLS)=C	CLS03330
	IF(ICLS.NE.NCLS)GO TO 400	CLS03340
C		CLS03350
C	SEND THE FINAL RESULTS TO THE CLASS STATISTICS FILE	CLS03360
C		CLS03370
	DO 250 KCLS=1, NCLS	CLS03380
	IX=0	CLS03390
	DO 250 I=1, LTERM	CLS03400
	V3=XMCTF(I, KCLS)	CLS03410
	IF(V3.EQ.VLD)GO TO 250	CLS03420
	IX=IX+1	CLS03430
	XMTLI(IX, KCLS)=V3	CLS03440
250	CONTINUE	CLS03450
	DO 280 I=1, ILI	CLS03460
	IF(NCLS.LT.6)GO TO 270	CLS03470
	DO 260 IL=1, ILP1	CLS03480
260	WRITE(13, 321)(XMTLI(I, LCLS), LCLS=1+(IL-1)*6, IL*6)	CLS03490
	IF(IK1.EQ.0)GO TO 280	CLS03500
270	WRITE(13, 321)(XMTLI(I, LCLS), LCLS=IM1, NCLS)	CLS03510
280	CONTINUE	CLS03520
	DO 310 I=1, JLI	CLS03530
	IF(NCLS.LT.6)GO TO 300	CLS03540
	DO 290 IL=1, ILP1	CLS03550
290	WRITE(13, 321)(VCTLI(I, LCLS), LCLS=1+(IL-1)*6, IL*6)	CLS03560
	IF(IK1.EQ.0)GO TO 310	CLS03570
300	WRITE(13, 321)(VCTLI(I, LCLS), LCLS=IM1, NCLS)	CLS03580
310	CONTINUE	CLS03590
	IF(NCLS.LT.6)GO TO 330	CLS03600
	DO 320 IL=1, ILP1	CLS03610
320	WRITE(13, 321)(CT(LCLS), LCLS=1+(IL-1)*6, IL*6)	CLS03620
321	FORMAT(6E13.5)	CLS03630
	IF(IK1.EQ.0)GO TO 340	CLS03640
330	WRITE(13, 321)(CT(LCLS), LCLS=IM1, NCLS)	CLS03650
340	DO 370 I=1, JLI	CLS03660
	IF(NCLS.LT.6)GO TO 360	CLS03670
	DO 350 IL=1, ILP1	CLS03680
350	WRITE(13, 321)(VCIT(I, LCLS), LCLS=1+(IL-1)*6, IL*6)	CLS03690
	IF(IK1.EQ.0)GO TO 370	CLS03700
360	WRITE(13, 321)(VCIT(I, LCLS), LCLS=IM1, NCLS)	CLS03710
370	CONTINUE	CLS03720
400	CONTINUE	CLS03730
C		CLS03740
C	INTERNAL CHECKING FOR ACCURACY OF MATRIX INVERSION	CLS03750
C		CLS03760
	DO 430 ICLS=1, NCLS	CLS03770
	DO 410 I=1, JLI	CLS03780
	VC(I)=VCTLI(I, ICLS)	CLS03790
410	VCI(I)=VCIT(I, ICLS)	CLS03800

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C          DO 420 I=1,JLI                                CLS03810
C 420 WRITE(*,*)VC(I),VCI(I)                            CLS03820
C          CALL VMULSS(VC,VCI,ILI,TEST,NTERM)           CLS03830
C                                                     CLS03840
C          THE FOLLOWING 3 STATEMENTS CAN BE USED FOR MATRIX INVERSION CHECK CLS03850
C                                                     CLS03860
C          PRINT*, ' THE FOLLOWING MATRIX MUST BE AN IDENTITY MATRIX ' CLS03870
C          DO 430 I=1,ILI                                CLS03880
C          WRITE(*,421) (TEST(I,J),J=1,ILI)            CLS03890
C 421 FORMAT(16F5.2)                                    CLS03900
C 430 CONTINUE                                          CLS03910
C          PRINT*, ' ILI =',ILI                        CLS03920
C          ILI=ILI+1                                    CLS03930
C          JLI=ILI*(ILI+1)/2                            CLS03940
C          IF(ILI.GT.NLI)GO TO 650                     CLS03950
C          GO TO 600                                    CLS03960
C                                                     CLS03970
C          SEND THE INFORMATION OF L.D. FEATURES & REASONS FOR CLS03980
C          NON-POSITIVE-DEFINITENESS OF COV. MATRICES TO THE FILE 'LDBAND' CLS03990
C                                                     CLS04000
C 440 WRITE(15,*)'GGNSM HAS IER.NE.0'                 CLS04010
C 450 WRITE(15,*)'ISET =',ISET,';LTERM =',LTERM,';ICLS =',ICLS CLS04020
C          PRINT*, 'ISET =',ISET,';LTERM =',LTERM,';ICLS =',ICLS CLS04030
C          DO 500 JCLS=1,NCLS                            CLS04040
C                                                     CLS04050
C          THE FOLLOWING 5 STATEMENTS ARE USED FOR INTERNAL CHECKING CLS04060
C                                                     CLS04070
C          WRITE(15,*)'JCLS =',JCLS                    CLS04080
C          DO 460 I=1,NTERM                              CLS04090
C 460 WRITE(15,*)I,XMCTF(I,JCLS)                       CLS04100
C          DO 470 I=1,NTERM                              CLS04110
C 470 WRITE(15,471)I,(VCTF(I,J,JCLS),J=1,NTERM)       CLS04120
C 471 FORMAT(I4,8F9.2)                                  CLS04130
C                                                     CLS04140
C          RESET THE VARIABLES TO '0.0' FOR FUTURE USE CLS04150
C                                                     CLS04160
C          XMCTF(LTERM,JCLS)=VLD                         CLS04170
C          DO 480 I=1,NTERM                              CLS04180
C 480 VCTF(I,LTERM,JCLS)=VLD                            CLS04190
C          DO 490 J=1,NTERM                              CLS04200
C 490 VCTF(LTERM,J,JCLS)=VLD                           CLS04210
C 500 CONTINUE                                          CLS04220
C                                                     CLS04230
C          THE FOLLOWING 7 STATEMENTS ARE USED FOR INTERNAL CHECKING CLS04240
C                                                     CLS04250
C          DO 550 JCLS=1,NCLS                            CLS04260
C          WRITE(15,*)'JCLS =',JCLS                    CLS04270
C          DO 530 I=1,NTERM                              CLS04280
C 530 WRITE(15,*)I,XMCTF(I,JCLS)                       CLS04290
C          DO 540 I=1,NTERM                              CLS04300
C 540 WRITE(15,421)I,(VCTF(I,J,JCLS),J=1,NTERM)       CLS04310
C 550 CONTINUE                                          CLS04320
C 600 CONTINUE                                          CLS04330
C 650 CONTINUE                                          CLS04340
C          STOP                                          CLS04350
C          END                                          CLS04360
C          SUBROUTINE SR1(IFILE,NP1,NFX,RX)              CLS04370

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C
C THIS SUBROUTINE IS USED TO READ THE INPUT DATA
C
REAL RX(NP1)
IKX=MOD(NP1,NFX)
IMX=NFX*(NP1/NFX)+1
ILPX=NP1/NFX
IF(ILPX.EQ.0)ILPR1=1
IF(NP1.LT.NFX)GO TO 20
DO 10 I=1,ILPX
10 READ(IFILE,*)(RX(J),J=1+(I-1)*NFX,I*NFX)
IF(IKX.EQ.0)GO TO 30
20 READ(IFILE,*)(RX(J),J=IMX,NP1)
30 RETURN
END

```

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CLS04380
CLS04390
CLS04400
CLS04410
CLS04420
CLS04430
CLS04440
CLS04450
CLS04460
CLS04470
CLS04480
CLS04490
CLS04500
CLS04510
CLS04520

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PROGRAM CANONIC
PARAMETER(NTERM=18,MTERM=NTERM*(NTERM+1)/2,NCLS=3,
+NWK=NTERM*(NTERM+2))
REAL XMT(NTERM,NCLS),VCVT(MTERM,NCLS),CT(NCLS),
+VCVIT(MTERM,NCLS),D(NTERM),Z(NTERM,NTERM),WK(NWK),
+WCS(MTERM),ACS(MTERM),WCS1(MTERM),TEST(NTERM,NTERM),
+T(NTERM,NTERM),WCSI(MTERM),XMO(NTERM)
INTEGER NST(NCLS)
DATA IJOB,IFLAG1,IOPT,NIN,NOUT/2,0,3,0,6/

```

```

CAN00010
CAN00020
CAN00030
CAN00040
CAN00050
CAN00060
CAN00070
CAN00080
CAN00090
CAN00100
CAN00110
CAN00120
CAN00130
CAN00140
CAN00150
CAN00160
CAN00170
CAN00180
CAN00190
CAN00200
CAN00210
CAN00220
CAN00230
CAN00240
CAN00250
CAN00260

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```

C
C NTERM = DIMENSIONALITY IN THE CLASS STATISTICS
C NCLS = TOTAL NUMBER OF INFORMATION CLASSES
C
C XMT = MEAN VECTORS FOR ALL CLASSES
C VCVT = COV. MATRICES FOR ALL CLASSES
C CT = VARIABLE USED TO STORE M.L. THRESHOLD PARAMETER
C VCVIT = INVERSE COV. MATRICES FOR ALL CLASSES
C D = EIGENVALUES
C Z = CANONICAL FEATURES
C WK = WORKING SPACE FOR IMSL ROUTINES
C WCS = WITHIN CLASS SCATTER MATRIX
C ACS = AMONG CLASS SCATTER MATRIX
C WCS1 = TEMPORARY STORAGE FOR WCS
C WCSI = INVERSE MATRIX OF WCS
C XMO = GLOBAL MEAN VECTOR
C TEST = INTERNAL CHECKING FOR MATRIX INVERSION ACCURACY

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CAN00270
CAN00280
CAN00290

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C--->>CHOOSE OR TYPE IN THE CORRECT NUMBERS OF SAMPLES IN THE DATA SETS
C
C-----
C NSET F1 NP2 A B C DACO EXNU RUSE
C 1 M2611K1 832 WW:141 SF:414 GS:277 760928 76102207 1-1622
C 2 M2611K2 1551 WW:658 SF:211 UC:682 770503 77102207 6515-8096
C 3 M2611K3 1477 WW:677 SF:643 GS:157 770626 77102207 8097-9691
C 4 M2614N1 1265 SW:664 SF:437 NP:164 770508 77102217 1-1396

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CAN00300
CAN00310
CAN00320
CAN00330
CAN00340
CAN00350
CAN00360
CAN00370

```

C 5 M2614N2 1239 SW:787 SF:291 NP:161 770629 77102217 2777-4141 CAN00380
 C 6 M2614N3 1444 SW:931 SF:330 NP:183 770804 77102217 5426-6993 CAN00390
 C
 C DATA NST/141,414,277,658,211,682,677,643,157/ CAN00410
 C DATA NST/141,414,277,658,211,682,677,643,157, CAN00420
 C +664,437,164,787,291,161,931,330,183/ CAN00430
 C DATA NST/664,437,164,787,291,161,931,330,183/ CAN00440
 C DATA NST/141,414,277,658,211,682,677/ CAN00450
 C DATA NST/587,216,121/ CAN00460
 C DATA NST/658,211,682/ CAN00470
 C
 C ----- CAN00480
 C
 C THE FOLLOWING DATA 'NST' ARE USED FOR SOIL ORDER DATA SET. 'SO' CAN00490
 C
 C NP2=479; MOL ALF EN AR UL IN SP VE H OX UNCLASSIFIED CAN00510
 C DATA NST/154,113,78,52,45,37,30,11,8,11,32/ CAN00520
 C DATA NST/154,113,78,52,45,97/ CAN00530
 C DATA NST/154,113,78,52,45,37/ CAN00540
 C
 C ----- CAN00550
 C
 C THE FOLLOWING DATA 'NST' IS USED FOR SOIL 'OM1' DATA SET CAN00560
 C I.E. (1) MOLLISOL, OR (2) ALFISOL, AND GROUP SAMPLES CAN00570
 C ACCORDING TO THEIR ORGANIC MATERIAL: % WEIGHT CAN00580
 C CLASS 1 TO 6 : NP2 = 255 CAN00590
 C CLS1 : .11% .GE. OM .LE. 1.5% : # 1 -> # 51 CAN00600
 C CLS2 : 1.5% .GT. OM .LE. 2.0% : # 52 -> # 104 CAN00610
 C CLS3 : 2.0% .GT. OM .LE. 2.5% : # 105 -> # 138 CAN00620
 C CLS4 : 2.5% .GT. OM .LE. 3.5% : # 139 -> # 183 CAN00630
 C CLS5 : 3.5% .GT. OM .LE. 5.0% : # 184 -> # 222 CAN00640
 C CLS6 : 5.0% .GT. OM .LE. 10.12% : # 223 -> # 255 CAN00650
 C
 C DATA NST/51,54,33,45,39,33/ CAN00660
 C
 C DATA 'S2A' : ANOTHER TEST GROUPED BY THE SAME OM RANGES AS 'OM2' CAN00670
 C OM PERCENTAGE : 0,1; 1,2; 2,3; 3,4; 4,6; 6 AND ABOVE CAN00680
 C
 C DATA NST/26,78,64,32,55/ CAN00690
 C
 C ----- CAN00700
 C
 C THE FOLLOWING DATA 'NST' IS USED FOR 'OM2' DATA SET CAN00710
 C ACCORDING TO THEIR ORGANIC MATERIAL: % WEIGHT CAN00720
 C CLASS 1 TO 6 : NP2 = 514 CAN00730
 C CLS1 : .08% .GE. OM .LE. 1.0% : # 1 -> # 82 CAN00740
 C CLS2 : 1.0% .GT. OM .LE. 2.0% : # 83 -> # 217 CAN00750
 C CLS3 : 2.0% .GT. OM .LE. 3.0% : # 218 -> # 337 CAN00760
 C CLS4 : 3.0% .GT. OM .LE. 4.0% : # 338 -> # 391 CAN00770
 C CLS5 : 4.0% .GT. OM .LE. 6.0% : # 392 -> # 450 CAN00780
 C CLS6 : 6.0% .GT. OM .LE. 84.79% : # 451 -> # 514 CAN00790
 C
 C DATA NST/82,135,120,54,59,64/ CAN00800
 C
 C DATA NST/82,135,120,54,123/ CAN00810
 C DATA NST/44,31,18,23,24,51,37,27/ CAN00820
 C DATA NST/83,57,94,31,37,59,103,26,24/ CAN00830
 C DATA NST/103,26,24/ CAN00840
 C
 C ----- CAN00850
 C
 C THE FOLLOWING DATA 'NST' IS USED FOR 'OM2' DATA SET CAN00860
 C ACCORDING TO THEIR ORGANIC MATERIAL: % WEIGHT CAN00870
 C CLASS 1 TO 6 : NP2 = 514 CAN00880
 C CLS1 : .08% .GE. OM .LE. 1.0% : # 1 -> # 82 CAN00890
 C CLS2 : 1.0% .GT. OM .LE. 2.0% : # 83 -> # 217 CAN00900
 C CLS3 : 2.0% .GT. OM .LE. 3.0% : # 218 -> # 337 CAN00910
 C CLS4 : 3.0% .GT. OM .LE. 4.0% : # 338 -> # 391 CAN00920
 C CLS5 : 4.0% .GT. OM .LE. 6.0% : # 392 -> # 450 CAN00930
 C CLS6 : 6.0% .GT. OM .LE. 84.79% : # 451 -> # 514 CAN00940
 C
 C DATA NST/82,135,120,54,59,64/ CAN00950
 C
 C DATA NST/82,135,120,54,123/ CAN00960
 C DATA NST/44,31,18,23,24,51,37,27/ CAN00970
 C DATA NST/83,57,94,31,37,59,103,26,24/ CAN00980
 C DATA NST/103,26,24/ CAN00990

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C ----- CAN00950
C THE FOLLOWING DATA 'NST' IS USED FOR SOIL IRON OXIDE 'IO' DATA SET CAN00960
C ACCORDING TO THEIR FE2O3 % WEIGHT CAN00970
C CLASS 1 TO 6 : NP2 = 467 CAN00980
C CLS1 : .02% .GE. FE2O3 .LE. 0.4% : # 1 -> # 102 CAN00990
C CLS2 : 0.4% .GT. FE2O3 .LE. 0.6% : # 103 -> # 175 CAN01000
C CLS3 : 0.6% .GT. FE2O3 .LE. 0.8% : # 176 -> # 244 CAN01010
C CLS4 : 0.8% .GT. FE2O3 .LE. 1.2% : # 245 -> # 349 CAN01020
C CLS5 : 1.2% .GT. FE2O3 .LE. 1.6% : # 350 -> # 401 CAN01030
C CLS6 : 1.6% .GT. FE2O3 .LE. 25.60% : # 402 -> # 467 CAN01040
C CAN01050
C DATA NST/102,73,69,105,52,66/ CAN01060
C ----- CAN01070
C THE FOLLOWING DATA 'NST' IS USED FOR SOIL TEXTURE 'ST' DATA SET CAN01080
C ACCORDING TO THEIR SAND-SILT-CLAY % CONTENT CAN01090
C CLASS 1 TO 6 : NP2 = 483; DETAILS : SEE FILE ( S5L.DATA.C1) CAN01100
C CAN01110
C DATA NST/40,63,76,93,68,143/ CAN01120
C ----- CAN01130
C THE FOLLOWING DATA 'NST' IS USED FOR S.D. VEGETATION DATA CAN01140
C CAN01150
C DATA NST/225,61,292,469,82,182,63,103,39,39,217,51, CAN01160
C +393,441,80,88,88,41,32,26,118,43,121,44,45,102,66,89, CAN01170
C +78,53,147,39,24,42,119,69,76,96,107,154,28,19/ CAN01180
C ----- CAN01190
C THE FOLLOWING DATA 'NST' IS USED FOR IOWA VEGETATION DATA CAN01200
C CAN01210
C DATA NST/514,41,517,36,32,621,517,45,610,485,21, CAN01220
C +437,377,22,190,172,25,650,568,42,435,417,44,393,267/ CAN01230
C ----- CAN01240
C 11 = CLASS STATISTICS; 12 = CANONICAL FEATURES CAN01250
C CAN01260
C OPEN(11) CAN01270
C OPEN(12) CAN01280
C REWIND 11 CAN01290
C REWIND 12 CAN01300
C ----- CAN01310
C SET THE INPUT&OUTPUT DO LOOP PARAMETERS CAN01320
C CAN01330
C IK1=MOD(NCLS,6) CAN01340
C IM1=6*(NCLS/6)+1 CAN01350
C IK2=MOD(NTERM,5) CAN01360
C IM2=5*(NTERM/5)+1 CAN01370
C IK3=MOD(NTERM,16) CAN01380
C IM3=16*(NTERM/16)+1 CAN01390
C ILP1=NCLS/6 CAN01400
C IF(ILP1.EQ.0) ILP1=1 CAN01410
C ILP2=NTERM/5 CAN01420
C IF(ILP2.EQ.0) ILP2=1 CAN01430
C ILP3=NTERM/16 CAN01440
C IF(ILP3.EQ.0) ILP3=1 CAN01450
C ----- CAN01460
C SET THE IMSL INPUT&OUTPUT TO THE FEATURE DESIGNER ( SCREEN ) CAN01470
C CAN01480
C CAN01490
C CAN01500
C CAN01510

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C	CALL UGETIO(IOPT,NIN,NOUT)	CAN01520
	DO 130 LTERM=1,NTERM	CAN01530
	KTERM=LTERM*(LTERM+1)/2	CAN01540
C		CAN01550
C	READ IN CLASS STATISTICS	CAN01560
C		CAN01570
	DO 30 ITERM=1,LTERM	CAN01580
	IF(NCLS.LT.6)GO TO 20	CAN01590
	DO 10 IL=1,ILP1	CAN01600
10	READ(11,*) (XMT(ITERM,JCLS),JCLS=1+(IL-1)*6,IL*6)	CAN01610
	IF(IK1.EQ.0)GO TO 30	CAN01620
20	READ(11,*) (XMT(ITERM,JCLS),JCLS=IM1,NCLS)	CAN01630
30	CONTINUE	CAN01640
	DO 60 ITERM=1,KTERM	CAN01650
	IF(NCLS.LT.6)GO TO 50	CAN01660
	DO 40 IL=1,ILP1	CAN01670
40	READ(11,*) (VCVT(ITERM,JCLS),JCLS=1+(IL-1)*6,IL*6)	CAN01680
	IF(IK1.EQ.0)GO TO 60	CAN01690
50	READ(11,*) (VCVT(ITERM,JCLS),JCLS=IM1,NCLS)	CAN01700
60	CONTINUE	CAN01710
	IF(NCLS.LT.6)GO TO 80	CAN01720
	DO 70 IL=1,ILP1	CAN01730
70	READ(11,*) (CT(ICLS),ICLS=1+(IL-1)*6,IL*6)	CAN01740
	IF(IK1.EQ.0)GO TO 90	CAN01750
80	READ(11,*) (CT(ICLS),ICLS=IM1,NCLS)	CAN01760
90	DO 120 ITERM=1,KTERM	CAN01770
	IF(NCLS.LT.6)GO TO 110	CAN01780
	DO 100 IL=1,ILP1	CAN01790
100	READ(11,*) (VCVIT(ITERM,JCLS),JCLS=1+(IL-1)*6,IL*6)	CAN01800
	IF(IK1.EQ.0)GO TO 120	CAN01810
110	READ(11,*) (VCVIT(ITERM,JCLS),JCLS=IM1,NCLS)	CAN01820
120	CONTINUE	CAN01830
130	CONTINUE	CAN01840
		CAN01850
C		CAN01860
C	FIND WITHIN CLASS SCATTER MATRIX	CAN01870
C		CAN01880
	CALL FWCS(VCVT,MTERM,NST,NCLS,WCS)	CAN01890
C	CALL USWSM('WCS MATRIX IS ',15,WCS,NTERM,1)	CAN01900
C		CAN01910
C	FIND AMONG CLASS SCATTER MATRIX	CAN01920
C		CAN01930
	CALL FACS(XMT,NTERM,MTERM,NST,NCLS,ACS,XMO)	CAN01940
C	CALL USWSM('ACS MATRIX IS ',15,ACS,NTERM,1)	CAN01950
C		CAN01960
C	FIND CANONICAL FEATURES	CAN01970
C		CAN01980
	CALL EIGZS(ACS,WCS,NTERM,IJOB,D,Z,NTERM,WK,IER)	CAN01990
C	CALL USWFV('CANONIC EVALUES',15,D,NTERM,1,1)	CAN02000
C	CALL USWSM('CANONIC EVECTOR',15,Z,NTERM,1)	CAN02010
C		CAN02020
C	INTERNAL CHECKING FOR MATRIX INVERSION ACCURACY	CAN02030
C		CAN02040
	CALL SCOPY(MTERM,WCS,1,WCS1,1)	CAN02050
	CALL LINVIP(WCS1,NTERM,WCSI,IDGT,D1,D2,IER1)	CAN02060
	CALL VMULSS(WCSI,ACS,NTERM,TEST,NTERM)	CAN02070
	CALL FTRACE(TEST,NTERM,TRACE)	CAN02080

C		CAN02090
C	SEND THE ACCURACY COMMENTS TO THE SCREEN	CAN02100
C		CAN02110
	IF (IER.NE.0.OR.WK(1).GE.1.0)GO TO 140	CAN02120
	WRITE (*, 3) IER, WK(1)	CAN02130
	GO TO 150	CAN02140
140	WRITE (*, 2) IER, WK(1)	CAN02150
	1 FORMAT (5E15.7)	CAN02160
	2 FORMAT (' PERFORMANCE OF "EIGZS" IS POOR, IER =', I5,	CAN02170
	+'; WK(1) =', E15.7)	CAN02180
	3 FORMAT (' PERFORMANCE OF "EIGZS" IS GOOD, IER =', I5,	CAN02190
	+'; WK(1) =', E15.7)	CAN02200
150	DO 170 I=1, NTERM	CAN02210
	IF (D(I).LE.0.0)GO TO 160	CAN02220
	GO TO 170	CAN02230
160	WRITE (*, 4) I, D(I)	CAN02240
	4 FORMAT (' EIGEN VALUE IS "< = 0.0" AT I =', I5,	CAN02250
	+' WHERE D(I) =', E15.7)	CAN02260
	IFLAG1=IFLAG1+1	CAN02270
170	CONTINUE	CAN02280
	IF (IFLAG1.GT.0)GO TO 180	CAN02290
	WRITE (*, 6)	CAN02300
	GO TO 190	CAN02310
180	WRITE (*, 5) IFLAG1	CAN02320
	5 FORMAT (' THERE ARE', I5, ' NEGATIVE OR ZERO EIGEN VALUES '	CAN02330
	6 FORMAT (' ALL EIGEN VALUES ARE GREATER THAN ZERO '	CAN02340
190	CALL VABSMF (D, NTERM, 1, SUM)	CAN02350
	IF (ABS (TRACE-SUM) .GT.1.0E-1)GO TO 200	CAN02360
	WRITE (*, 8) TRACE, SUM	CAN02370
	GO TO 210	CAN02380
200	WRITE (*, 7) TRACE, SUM	CAN02390
	7 FORMAT (' ACCURACY OF "EIGZS" IS POOR, TRACE =', E15.7,	CAN02400
	+'; SUM =', E15.7)	CAN02410
	8 FORMAT (' ACCURACY OF "EIGZS" IS GOOD, TRACE =', E15.7,	CAN02420
	+'; SUM =', E15.7)	CAN02430
C		CAN02440
C	SEND THE FINAL RESULTS TO THE CANONICAL FEATURE FILE	CAN02450
C		CAN02460
210	WRITE (12, 9) TRACE, SUM	CAN02470
	9 FORMAT (2E15.7)	CAN02480
	IF (NTERM.LT.5)GO TO 230	CAN02490
	DO 220 I=1, ILP2	CAN02500
220	WRITE (12, 1) (D (NTERM+1-J), J=1+(I-1)*5, I*5)	CAN02510
	IF (IK2.EQ.0)GO TO 240	CAN02520
230	WRITE (12, 1) (D (NTERM+1-J), J=IM2, NTERM)	CAN02530
240	DO 270 J=1, NTERM	CAN02540
	IF (NTERM.LT.5)GO TO 260	CAN02550
	DO 250 I=1, ILP2	CAN02560
250	WRITE (12, 1) (Z (K, NTERM+1-J), K=1+(I-1)*5, I*5)	CAN02570
	IF (IK2.EQ.0)GO TO 270	CAN02580
260	WRITE (12, 1) (Z (K, NTERM+1-J), K=IM2, NTERM)	CAN02590
270	CONTINUE	CAN02600
	CALL VMULSF (WCS, NTERM, Z, NTERM, NTERM, TEST, NTERM)	CAN02610
	NTM=NTERM	CAN02620
	CALL VMULFM (Z, TEST, NTM, NTM, NTM, NTM, NTM, T, NTM, IER)	CAN02630
C		CAN02640
C	SEND THE ACCURACY COMMENTS TO THE SCREEN	CAN02650

C	PRINT*, ' THE FOLLOWING MATRIX MUST BE AN IDENTITY MATRIX'	CAN02660
	IF (NTERM.LT.16) GO TO 290	CAN02670
	DO 280 IL=1, ILP3	CAN02680
	DO 280 I=1, NTERM	CAN02690
280	WRITE (*, 281) (T (I, J), J=1+(IL-1)*16, IL*16)	CAN02700
281	FORMAT (16F5.2)	CAN02710
	IF (IK3.EQ.0) GO TO 310	CAN02720
290	DO 300 I=1, NTERM	CAN02730
300	WRITE (*, 281) (T (I, J), J=IM3, NTERM)	CAN02740
310	STOP	CAN02750
	END	CAN02760
	SUBROUTINE FWCS (VCVT, MTERM, NST, NCLS, WCS)	CAN02770
C		CAN02780
C	THIS SUBROUTINE FINDS WITHIN CLASS SCATTER MATRIX	CAN02790
C		CAN02800
	REAL VCVT (MTERM, NCLS), WCS (MTERM)	CAN02810
	INTEGER NST (NCLS)	CAN02820
	NX1=0	CAN02830
	DO 10 I=1, NCLS	CAN02840
10	NX1=NX1+NST (I)	CAN02850
	DO 30 I=1, MTERM	CAN02860
	X1=0.0	CAN02870
	DO 20 J=1, NCLS	CAN02880
	X2=FLOAT (NST (J)) -1.0	CAN02890
20	X1=X1+X2*VCVT (I, J) /FLOAT (NX1)	CAN02900
30	WCS (I)=X1	CAN02910
	RETURN	CAN02920
	END	CAN02930
	SUBROUTINE FACS (XMT, NTERM, MTERM, NST, NCLS, ACS, XMO)	CAN02940
C		CAN02950
C	THIS SUBROUTINE FINDS AMONG CLASS SCATTER MATRIX	CAN02960
C		CAN02970
	REAL XMT (NTERM, NCLS), ACS (MTERM), XMO (NTERM)	CAN02980
	INTEGER NST (NCLS)	CAN02990
	NX1=0	CAN03000
	DO 10 I=1, NCLS	CAN03010
10	NX1=NX1+NST (I)	CAN03020
	DO 30 I=1, NTERM	CAN03030
	X1=0.0	CAN03040
	DO 20 J=1, NCLS	CAN03050
	X2=FLOAT (NST (J))	CAN03060
20	X1=X1+X2*XMT (I, J) /FLOAT (NX1)	CAN03070
30	XMO (I)=X1	CAN03080
	DO 50 I=1, NTERM	CAN03090
	DO 50 J=1, I	CAN03100
	IND=(I-1)*I/2+J	CAN03110
	X1=0.0	CAN03120
	DO 40 ICLS=1, NCLS	CAN03130
	X2=FLOAT (NST (ICLS)) /FLOAT (NX1)	CAN03140
40	X1=X1+X2*(XMT (I, ICLS)-XMO (I))* (XMT (J, ICLS)-XMO (J))	CAN03150
50	ACS (IND)=X1	CAN03160
	RETURN	CAN03170
	END	CAN03180
	SUBROUTINE FTRACE (TEST, NTERM, TRACE)	CAN03190
	REAL TEST (NTERM, NTERM)	CAN03200
	TRACE=0.0	CAN03210
		CAN03220

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DO 10 I=1,NTERM
10 TRACE=TRACE+TEST(I,I)
RETURN
END
CAN03230
CAN03240
CAN03250
CAN03260

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PROGRAM PCFIND
PARAMETER (NTSET=4,NTERM=16,MTERM=NTERM*(NTERM+1)/2,NCLS=3,
+NSET=1,MSET=1,NDSET=1,NSMAX=100,NZ1=NCLS*NCLS*NTERM,
+IRES=0,IFIND=1,ICKMV=0,NDTRM=1,NZ2=NCLS*NTERM,NTERMC=15)
C
C IFIND = 1 ----> NDTRM CONTROL : LTERM=1,NTERM,NDTRM
C IFIND = 0 ----> NDTRM DISABLE : LTERM = NTERM ONLY
C-->> IRES = 1 ----> NSMAX MUST EXCEED MAX(NST(I)) <<----- NOTES!!!
C IRES = 0 ----> NSMAX CONTROL : SUBROUTINE GGNSM
C
C NTERMC > OR = NTERM , WHERE NTERMC IS USED TO READ ENTIRE
C TRANSFORMED DATA; WHILE NTERM IS USED TO DECIDE
C HOW MANY OF THEM WILL BE CONTRIBUTED TO PC
C
C NTERM = TOTAL NUMBER OF FEATURES USED
C NCLS = TOTAL NUMBER OF INFORMATION CLASSES
C NSMAX = PRESET MAX. NO. OF SAMPLES FOR ONE CLASS
C
C REAL XMT(NTERM,NCLS),VCVT(MTERM,NCLS),CT(NCLS),
+VCVIT(MTERM,NCLS),TVEC(NSMAX,NTERM,NCLS),
+VCVIF(NTERM,NTERM),VCV(MTERM),VCVI(MTERM),XM(NTERM),
+PC(NTERM),QP(NCLS,NTERM),PR(NCLS,NTERM),PX(NCLS),
+VEC(NSMAX,NTERM),WK(NTERM),X(NTERM),T1(NTERM)
C REAL XMCK(NTERM),VCVCK(MTERM),TX(NTERM),Y(NTERM)
C REAL RVEC(NSMAX,NTERMC,NCLS),AP(NCLS)
C INTEGER NBR(6),NPC(NCLS,NCLS,NTERM),NST(NCLS)
C CHARACTER*2 XC1
C DOUBLE PRECISION DSEED
C DATA XC1/' '/
C DATA PC/NTERM*0.0/
C DATA QP,PR,PX/NZ2*0.0,NZ2*0.0,NCLS*0.0/
C DATA DSEED,NPC/5.D0,NZ1*0/
C DATA (NBR(I),I=4,6),IOPT,NIN,NOUT/1,0,0,3,0,6/
C
C XMT = MEAN VECTORS FOR ALL CLASSES
C VCVT = COV. MATRICES FOR ALL CLASSES
C CT = M.L. DECISION RULE PARAMETER
C VCVIT = INVERSE COV. MATRICES FOR ALL CLASSES
C TVEC = GENERATED SAMPLE VECTORS
C VCVIF = INVERSE COV. MATRIX IN FULL STORAGE MODE
C VCV = COV. MATRIX
C VCVI = INVERSE COV. MATRIX IN SYMMETRIC STORAGE MODE
C XM = MEAN VECTOR
C PC = PROBABILITY OF CORRECT CLASSIFICATION
C XMCK = CHECKING VECTOR FOR MEAN
C VCVCK = CHECKING MATRIX FOR COVARIANCES
C NBR = IMSL ROUTINE-USED PARAMETER VECTOR
C NPC = CLASSIFICATION RESULT MATRIX
PCF00010
PCF00020
PCF00030
PCF00040
PCF00050
PCF00060
PCF00070
PCF00080
PCF00090
PCF00100
PCF00110
PCF00120
PCF00130
PCF00140
PCF00150
PCF00160
PCF00170
PCF00180
PCF00190
PCF00200
PCF00210
PCF00220
PCF00230
PCF00240
PCF00250
PCF00260
PCF00270
PCF00280
PCF00290
PCF00300
PCF00310
PCF00320
PCF00330
PCF00340
PCF00350
PCF00360
PCF00370
PCF00380
PCF00390
PCF00400
PCF00410
PCF00420
PCF00430
PCF00440
PCF00450
PCF00460
PCF00470
PCF00480

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C      NST      = STORE THE TOTAL NO. OF SAMPLES FOR EACH CLASS      PCF00490
C      PCF00500
C      -----PCF00510
C      PCF00520
C      -->>CHOOSE OR TYPE IN THE CORRECT NUMBERS OF SAMPLES IN THE DATA SETS PCF00530
C      PCF00540
C      -----PCF00550
C      NSET      F1      NP2      A      B      C      DACO      EXNU      RUSE      PCF00560
C      1 M2611K1  832  WW:141 SF:414 GS:277 760928 76102207 1-1622 PCF00570
C      2 M2611K2 1551  WW:658 SF:211 UC:682 770503 77102207 6515-8096 PCF00580
C      3 M2611K3 1477  WW:677 SF:643 GS:157 770626 77102207 8097-9691 PCF00590
C      4 M2614N1 1265  SW:664 SF:437 NP:164 770508 77102217 1-1396 PCF00600
C      5 M2614N2 1239  SW:787 SF:291 NP:161 770629 77102217 2777-4141 PCF00610
C      6 M2614N3 1444  SW:931 SF:330 NP:183 770804 77102217 5426-6993 PCF00620
C      PCF00630
C      DATA NST/141,414,277,658,211,682,677,643,157/ PCF00640
C      DATA NST/141,414,277,658,211,682,677,643,157, PCF00650
C      +664,437,164,787,291,161,931,330,183/ PCF00660
C      DATA NST/664,437,164,787,291,161,931,330,183/ PCF00670
C      DATA NST/141,414,277,658,211,682,677/ PCF00680
C      DATA NST/587,216,121/ PCF00690
C      DATA NST/658,211,682/ PCF00700
C      PCF00710
C      -----PCF00720
C      THE FOLLOWING DATA 'NST' ARE USED FOR SOIL ORDER DATA SET. 'SO' PCF00730
C      PCF00740
C      NP2=479; MOL ALF EN AR UL IN SP VE H OX UNCLASSIFIED PCF00750
C      DATA NST/154,113,78,52,45,37,30,11,8,11,32/ PCF00760
C      DATA NST/154,113,78,52,45,97/ PCF00770
C      DATA NST/154,113,78,52,45,37/ PCF00780
C      PCF00790
C      -----PCF00800
C      THE FOLLOWING DATA 'NST' IS USED FOR SOIL 'OM1' DATA SET PCF00810
C      I.E. (1) MOLLISOL, OR (2) ALFISOL, AND GROUP SAMPLES PCF00820
C      ACCORDING TO THEIR ORGANIC MATERIAL: % WEIGHT PCF00830
C      CLASS 1 TO 6 : NP2 = 255 PCF00840
C      CLS1 : .11% .GE. OM .LE. 1.5% : # 1 -> # 51 PCF00860
C      CLS2 : 1.5% .GT. OM .LE. 2.0% : # 52 -> # 104 PCF00870
C      CLS3 : 2.0% .GT. OM .LE. 2.5% : # 105 -> # 138 PCF00880
C      CLS4 : 2.5% .GT. OM .LE. 3.5% : # 139 -> # 183 PCF00890
C      CLS5 : 3.5% .GT. OM .LE. 5.0% : # 184 -> # 222 PCF00900
C      CLS6 : 5.0% .GT. OM .LE. 10.12% : # 223 -> # 255 PCF00910
C      PCF00920
C      DATA NST/51,54,33,45,39,33/ PCF00930
C      PCF00940
C      DATA 'S2A' : ANOTHER TEST GROUPED BY THE SAME OM RANGES AS 'OM2' PCF00950
C      OM PERCENTAGE : 0,1; 1,2; 2,3; 3,4; 4,6; 6 AND ABOVE PCF00960
C      PCF00970
C      DATA NST/26,78,64,32,55/ PCF00980
C      PCF00990
C      PCF01000
C      -----PCF01010
C      THE FOLLOWING DATA 'NST' IS USED FOR 'OM2' DATA SET PCF01020
C      ACCORDING TO THEIR ORGANIC MATERIAL: % WEIGHT PCF01030
C      CLASS 1 TO 6 : NP2 = 514 PCF01040
C      CLS1 : .08% .GE. OM .LE. 1.0% : # 1 -> # 82 PCF01050

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1	NX2=NX2+NST(I)	PCF01630
	IF(IRES.EQ.0)GO TO 3	PCF01640
	DO 2 I=1,NCLS	PCF01650
	NX1=NST(I)	PCF01660
2	AP(I)=FLOAT(NX1)/FLOAT(NX2)	PCF01670
	GO TO 5	PCF01680
3	DO 4 I=1,NCLS	PCF01690
4	AP(I)=1.0/FLOAT(NCLS)	PCF01700
5	IK=MOD(NCLS,6)	PCF01710
		PCF01720
		PCF01730
	SET THE INPUT&OUTPUT DO LOOP PARAMETERS	PCF01740
		PCF01750
	IM=6*(NCLS/6)+1	PCF01760
	IK1=MOD(NCLS,3)	PCF01770
	IM1=3*(NCLS/3)+1	PCF01780
	IK2=MOD(NCLS,15)	PCF01790
	IM2=15*(NCLS/15)+1	PCF01800
	ILP1=NCLS/6	PCF01810
	IF(ILP1.EQ.0)ILP1=1	PCF01820
	ILP2=NCLS/3	PCF01830
	IF(ILP2.EQ.0)ILP2=1	PCF01840
	ILP3=NCLS/15	PCF01850
	IF(ILP3.EQ.0)ILP3=1	PCF01860
	IF(IRES.EQ.0)NSAMP=NSMAX	PCF01870
	DO 550 ISET=NSET,MSET,NDSET	PCF01880
	IF(IRES.EQ.1)CALL RDATA(ISET,RVEC,NSMAX,NTERM,NCLS,NST)	PCF01890
		PCF01900
	READ IN CLASS STATISTICS	PCF01910
		PCF01920
	DO 500 LTERM=1,NTERM	PCF01930
	KTERM=LTERM*(LTERM+1)/2	PCF01940
	DO 30 ITERM=1,LTERM	PCF01950
	IF(NCLS.LT.6)GO TO 20	PCF01960
	DO 10 IL=1,ILP1	PCF01970
10	READ(12,*)(XMT(ITERM,JCLS),JCLS=1+(IL-1)*6,IL*6)	PCF01980
	IF(IK.EQ.0)GO TO 30	PCF01990
20	READ(12,*)(XMT(ITERM,JCLS),JCLS=IM,NCLS)	PCF02000
30	CONTINUE	PCF02010
	DO 60 ITERM=1,KTERM	PCF02020
	IF(NCLS.LT.6)GO TO 50	PCF02030
	DO 40 IL=1,ILP1	PCF02040
40	READ(12,*)(VCVT(ITERM,JCLS),JCLS=1+(IL-1)*6,IL*6)	PCF02050
	IF(IK.EQ.0)GO TO 60	PCF02060
50	READ(12,*)(VCVT(ITERM,JCLS),JCLS=IM,NCLS)	PCF02070
60	CONTINUE	PCF02080
	IF(NCLS.LT.6)GO TO 80	PCF02090
	DO 70 IL=1,ILP1	PCF02100
70	READ(12,*)(CT(ICLS),ICLS=1+(IL-1)*6,IL*6)	PCF02110
	IF(IK.EQ.0)GO TO 90	PCF02120
80	READ(12,*)(CT(ICLS),ICLS=IM,NCLS)	PCF02130
90	DO 120 ITERM=1,KTERM	PCF02140
	IF(NCLS.LT.6)GO TO 110	PCF02150
	DO 100 IL=1,ILP1	PCF02160
100	READ(12,*)(VCVIT(ITERM,JCLS),JCLS=1+(IL-1)*6,IL*6)	PCF02170
	IF(IK.EQ.0)GO TO 120	PCF02180
110	READ(12,*)(VCVIT(ITERM,JCLS),JCLS=IM,NCLS)	PCF02190
120	CONTINUE	

```

IF (IFIND.EQ.1)GO TO 125
IF (LTERM.NE.NTERM)GO TO 500
IF (IFIND.EQ.0)GO TO 128
C
C FIND THE PC RESULTS FOR EVERY DTERM INCREMENT
C
125 NX1=LTERM+ (NDTRM-1)
    NX2=MOD (NX1,NDTRM)
C PRINT*,NX1,NX2
    IF (NX2.NE.0)GO TO 500
128 DO 170 JCLS=1,NCLS
    DO 130 I=1,KTERM
130 VCV(I)=VCVT(I,JCLS)
    CALL UGETIO(IOPT,NIN,NOU)
C CALL USWSM(' THE MATRIX IS ',15,VCV,LTERM,1)
C NOTE : WK(1) MUST BE 0.0 EVERY TIME TO INITIALIZE ' GGNSM '
C NOTE : VCV WILL BE CHANGED AFTER ' GGNSM '
    IF (IRES.EQ.1)NSAMP=NST(JCLS)
    IF (IRES.EQ.1)GO TO 145
    DO 140 I=1,NTERM
140 WK(I)=0.0
    DSEED=5.D0
C
C GENERATE GAUSSIAN SAMPLES ACCORDING TO THE CLASS STATISTICS
C
    CALL GGNSM(DSEED,NSAMP,LTERM,VCV,NSMAX,VEC,WK,IER)
145 DO 155 I=1,NSAMP
    DO 155 J=1,LTERM
    IF (IRES.EQ.1)GO TO 150
    VEC(I,J)=VEC(I,J)+XMT(J,JCLS)
C
C STORE THE SAMPLES INTO ARRAY 'TVEC'
C
    TVEC(I,J,JCLS)=VEC(I,J)
    GO TO 155
150 TVEC(I,J,JCLS)=RVEC(I,J,JCLS)
    VEC(I,J)=RVEC(I,J,JCLS)
C PRINT*,JCLS,I,J,TVEC(I,J,JCLS)
155 CONTINUE
    IF (ICKMV.EQ.0)GO TO 170
C
C CHECK THE MEAN VECTOR AND COV. MATRIX OF THE GENERATED SAMPLES
C THE MATRIX 'VEC' WILL BE CHANGED AFTER ' BECOVM '
C
    DO 160 I=1,NTERM
160 TX(I)=0.0
    NBR(1)=LTERM
    NBR(2)=NSAMP
    NBR(3)=NSAMP
C IF (LTERM.GT.1)GO TO 600
    CALL BECOVM(VEC,NSMAX,NBR,TX,XMCK,VCVCK,IER)
C
C SEND THE CHECKING RESULTS TO THE SCREEN IF NEEDED
C
    CALL USWFV(' THE VECTOR IS ',15,XMCK,LTERM,1,1)
C CALL USWSM(' THE MATRIX IS ',15,VCVCK,LTERM,1)
170 CONTINUE

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PCF02200
PCF02210
PCF02220
PCF02230
PCF02240
PCF02250
PCF02260
PCF02270
PCF02280
PCF02290
PCF02300
PCF02310
PCF02320
PCF02330
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PCF02670
PCF02680
PCF02690
PCF02700
PCF02710
PCF02720
PCF02730
PCF02740
PCF02750
PCF02760

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C		PCF02770
C	START CLASSIFICATION JOB FOR EACH CLASS SAMPLES	PCF02780
C		PCF02790
	DO 230 JCLS=1,NCLS	PCF02800
	IF (IRES.EQ.1) NSAMP=NST (JCLS)	PCF02810
	PRINT*, LTERM, JCLS, NSAMP	PCF02820
	DO 230 ISAMP=1, NSAMP	PCF02830
	DO 180 J=1, LTERM	PCF02840
180	Y (J)=TVEC (ISAMP, J, JCLS)	PCF02850
	DO 220 KCLS=1, NCLS	PCF02860
C	THE FOLLOWING IS NEEDED SINCE X HAS BEEN CHANGED FOR EVERY KCLS!	PCF02870
	DO 190 I=1, LTERM	PCF02880
190	X (I)=Y (I)	PCF02890
	DO 200 I=1, KTERM	PCF02900
200	VCVI (I)=VCVIT (I, KCLS)	PCF02910
	CALL VCVTSF (VCVI, LTERM, VCVIF, NTERM)	PCF02920
	DO 210 I=1, LTERM	PCF02930
210	XM (I)=XMT (I, KCLS)	PCF02940
	CALL SAXPY (LTERM, -1., XM, 1, X, 1)	PCF02950
	CALL VMULFM (X, VCVIF, LTERM, 1, LTERM, NTERM, NTERM, T1, 1, IER)	PCF02960
	CALL VMULFF (T1, X, 1, LTERM, 1, 1, NTERM, T2, 1, IER)	PCF02970
	T3=EXP (-0.5*T2)	PCF02980
220	PX (KCLS)=AP (KCLS) *CT (KCLS) *T3	PCF02990
C		PCF03000
C	PERFORM M.L. DECISION RULE	PCF03010
C		PCF03020
	CALL VABMXF (PX (1), NCLS, 1, IMAX, BIG)	PCF03030
	NPC (JCLS, IMAX, LTERM)=NPC (JCLS, IMAX, LTERM) +1	PCF03040
C	CALL VABSMF (PX, NCLS, 1, DEN)	PCF03050
C	Q=BIG/DEN	PCF03060
C	WRITE (13, *) JCLS, ISAMP, IMAX, NPC (JCLS, IMAX, LTERM)	PCF03070
C	WRITE (13, *) (PX (I), I=1, NCLS), IMAX, BIG	PCF03080
230	CONTINUE	PCF03090
C		PCF03100
C	FIND PROBABILITY OF CORRECT CLASSIFICATION PC FROM NPC	PCF03110
C		PCF03120
	NC1=0	PCF03130
	NC2=0	PCF03140
	DO 240 I=1, NCLS	PCF03150
	IF (IRES.EQ.0) NST (I)=NSMAX	PCF03160
	PR (I, LTERM)=(FLOAT (NPC (I, I, LTERM)))/FLOAT (NST (I))	PCF03170
	NC1=NC1+NPC (I, I, LTERM)	PCF03180
240	NC2=NC2+NST (I)	PCF03190
	IF (IRES.EQ.0) NC2=NSMAX*NCLS	PCF03200
	PC (LTERM)=(FLOAT (NC1))/FLOAT (NC2)	PCF03210
	IF (NCLS.LT.3) GO TO 260	PCF03220
		PCF03230
C		PCF03240
C	SEND THE RESULTS TO THE SCREEN	PCF03250
C		PCF03260
	DO 250 IL=1, ILP2	PCF03270
250	WRITE (*, *) ISET, LTERM, (PR (I, LTERM), I=1+(IL-1)*3, IL*3)	PCF03280
	IF (IK1.EQ.0) GO TO 270	PCF03290
260	WRITE (*, *) ISET, LTERM, (PR (I, LTERM), I=IM1, NCLS)	PCF03300
270	PRINT*, ISET, LTERM, PC (LTERM)	PCF03310
C		PCF03320
C	SEND THE RESULTS TO THE PC FILE	PCF03330
C		PCF03330

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WRITE (13,*) ' LTERM = ',LTERM                                PCF03340
IF (NCLS.LT.6) GO TO 290                                       PCF03350
DO 280 IL=1,ILP1                                              PCF03360
280 WRITE (13,301) (PR (I,LTERM),I=1+(IL-1)*6,IL*6)         PCF03370
IF (IK.EQ.0) GO TO 300                                         PCF03380
290 WRITE (13,301) (PR (I,LTERM),I=IM,NCLS)                   PCF03390
300 WRITE (13,301) PC (LTERM)                                   PCF03400
301 FORMAT (6F13.5)                                           PCF03410
C                                                                PCF03420
C----< RESET ALL RELATED VARIABLES >-----                   PCF03430
C THE FOLLOWING ZEROING PROCEDURES ARE 'ABSOLUTELY' NEEDED!!  PCF03440
C THIS IS DONE FOR EVERY " LTERM = 1, NTERM "                PCF03450
C                                                                PCF03460
DO 310 K=1,NCLS                                              PCF03470
DO 310 I=1,NSMAX                                             PCF03480
DO 310 J=1,NTERM                                             PCF03490
310 TVEC (I,J,K)=0.0                                         PCF03500
DO 320 I=1,NCLS                                             PCF03510
DO 320 J=1,NTERM                                             PCF03520
QP (I,J)=0.0                                                PCF03530
320 PR (I,J)=0.0                                             PCF03540
DO 330 I=1,NTERM                                             PCF03550
330 PC (I)=0.0                                               PCF03560
IF (NCLS.LT.15) GO TO 360                                     PCF03570
C                                                                PCF03580
C SEND THE FINAL CLASSIFICATION MATRIX NPC TO THE PC FILE     PCF03590
C                                                                PCF03600
DO 350 J=1,ILP3                                             PCF03610
DO 340 I=1,NCLS                                             PCF03620
340 WRITE (13,341) I, (NPC (I,K,LTERM),K=1+(J-1)*15,J*15)   PCF03630
341 FORMAT (I3,2X,15I5)                                       PCF03640
WRITE (13,342) XCL                                           PCF03650
342 FORMAT (A2)                                               PCF03660
350 CONTINUE                                                 PCF03670
IF (IK2.EQ.0) GO TO 500                                       PCF03680
360 DO 370 I=1,NCLS                                         PCF03690
370 WRITE (13,341) I, (NPC (I,K,LTERM),K=IM2,NCLS)          PCF03700
500 CONTINUE                                                 PCF03710
DO 510 I=1,NCLS                                             PCF03720
DO 510 J=1,NCLS                                             PCF03730
DO 510 K=1,NTERM                                             PCF03740
510 NPC (I,J,K)=0                                           PCF03750
550 CONTINUE                                                 PCF03760
C                                                                PCF03770
C THE FOLLOWING STATEMENT IS USED FOR INTERNAL CHECKING      PCF03780
C                                                                PCF03790
C 600 STOP                                                    PCF03800
STOP                                                         PCF03810
END                                                         PCF03820
SUBROUTINE RDATA (LSET,RVEC,NSMAX,NTERMC,NCLS,NST)          PCF03830
REAL RVEC (NSMAX,NTERMC,NCLS)                               PCF03840
INTEGER NST (NCLS)                                          PCF03850
IKX=MOD (NTERMC,5)                                          PCF03860
IMX=5*(NTERMC/5)+1                                         PCF03870
ILPX=NTERMC/5                                               PCF03880
IF (ILPX.EQ.0) ILPX=1                                       PCF03890
IFILE1=11+(LSET-1)*10                                       PCF03900

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```
DO 40 K=1,NCLS
N1=NST(K)
PRINT*, 'KCLS = ',K,'; NSAMP = ',N1
DO 30 I=1,N1
IF (NTERMC.LT.5)GO TO 20
DO 10 J1=1,ILPX
10 READ (IFILE1,*) (RVEC(I,J,K),J=1+(J1-1)*5,J1*5)
IF (IKX.EQ.0)GO TO 30
20 READ (IFILE1,*) (RVEC(I,J,K),J=IMX,NTERMC)
30 CONTINUE
40 CONTINUE
RETURN
END
```

PCF03910
PCF03920
PCF03930
PCF03940
PCF03950
PCF03960
PCF03970
PCF03980
PCF03990
PCF04000
PCF04010
PCF04020
PCF04030