NASA Computational Fluid Dynamics Conference
Volume 1: Sessions I - VI

Proceedings of a conference held at
Ames Research Center
Moffett Field, California
March 7-9, 1989
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This publication is a collection of the presentations given at the NASA Computational Fluid Dynamics (CFD) Conference held at NASA Ames Research Center, Moffett Field, California, March 7-9, 1989. The objectives of the conference were to disseminate CFD research results to industry and university CFD researchers, to promote synergy among NASA CFD researchers, and to permit feedback from researchers outside NASA on issues pacing the discipline of CFD. The focus of the conference was on the application of CFD technology but also included fundamental activities. The conference was sponsored by the Aerodynamics Division, Office of Aeronautics and Space Technology (OAST), NASA Headquarters, Washington, DC 20546.

The conference consisted of twelve sessions of papers representative of CFD research conducted within NASA and three non-NASA panel sessions. For each panel session, the panel membership consisted of industry and university CFD researchers. A summary of the comments made during the panel sessions have been included in this publication.

The conference proceedings are published in two volumes. Volume 1 contains the papers presented in Sessions I-VI; Volume 2 contains those given in Sessions VII-XII. Each volume contains the same front matter, and each contains a list of attendees as an appendix.
Panel Sessions Summary

The NASA CFD Conference was held at Ames Research Center on March 7-9, 1989. To conclude each day's presentations, a panel session with participation from the audience furnished a great deal of excellent feedback from the industry and academic communities. During the conference it was evident that the panel members proffered comments only after having spent considerable time in preparing them.

The members of the panel sessions are listed below:

March 7  P. Rubbert - Boeing Commercial Airplanes  
           R. Melnik - Grumman Aerospace Corporation  
           D. Whitfield - Mississippi State University

March 8  I. Bhateley - General Dynamics - Fort Worth Division  
           R. Agarwal - McDonnell Douglas Research Laboratories  
           R. MacCormack - Stanford University

March 9  V. Shankar - Rockwell International Science Center  
           J. Carter - United Technologies Research Center  
           A. Jameson - Princeton University

The crucial comments from the three panel sessions have been combined and are summarized as follows:

- NASA's CFD program is now too heavily focused on applications: program balance has swung from fundamentals (1970's) to applications (1980's)

- Three critical "needs" emerged:

  (1) More algorithm research is needed; especially for Navier-Stokes solvers with unstructured grids

  (2) More research is required on geometric modelling; need rapid, accurate, and effective surface definition techniques

  (3) More research is needed on grid generation methods with the focus on speed, efficiency, and grid quality to reduce set up time and complexity

- Developers of CFD need to understand the needs of the users; designers of aerospace vehicles have requirements that are different than the CFD researchers perceptions

- Industry needs more reliable and cost effective CFD tools
Additional detail comments from the three panel sessions are listed below:

- CFD has matured during the last decade and is being used to solve real problems; however, industry lacks confidence in Navier-Stokes solutions

- Industry needs codes that have been validated to increase confidence in CFD technology

- Improved communality between codes would increase usability; standards are needed

- Improved data storage, networking, data transfer, and graphics required to assimilate information provided by CFD

- Improved turbulence modeling for separated flows

- Accurate prediction of drag for complete powered aerospace vehicles

- Develop multidisciplinary CFD technology with optimization capability

- NASA must maintain focus on technology development and high risk research

- Technology transfer is not complete until design engineers are using CFD codes successfully

- Industry needs NASA to improve CFD technology for codes simpler than Navier-Stokes solvers

- NASP program has been extremely helpful to industry in transferring CFD technology

- Industry needs to be more aggressive in their use of CFD

- Improved understanding of CFD by design engineers required; cooperative programs or workshops were suggested to bring CFD researchers and designers together

- Design cycle time needs to be reduced with CFD; codes must be cost effective, reliable, and useable, and robust to work at flight Reynolds Numbers

- Improved coordination/reduced overlap of CFD applications between NASA centers
Organizing Committee

General Chairman ................................................................. Dale Satran
Administrative Chairman .................................................... Paul Kutler
Deputy Administrative Chairman ..................................... Anthony R. Gross
Conference Coordinator ..................................................... Lyz Dunham
Administrative Associate .................................................... Linda Callison
Publications ............................................................................ Betty Rogers
Budget .................................................................................. Karl Talarico
Secretary & Consultant ........................................................... Aggie Ernst

Center Focal Points

Ames Research Center ............................................................ Terry Holst
Langley Research Center ........................................................ Jerry South
Lewis Research Center ........................................................... Robert Stubbs
Marshall Space Flight Center ................................................. Luke Schutzenhofer
Johnson Space Center ............................................................. C. P. Li
PROGRAM

NASA CFD Conference
NASA Ames Research Center
March 7-9, 1989

Tuesday, March 7
7:30 am   Registration

8:00 am   Welcome
D. Satran - Conference Chairman
K. Szalai - Ames Acting Associate Director
R. Graves - OAST Aerodynamics Division Director

Session I (Center Overviews) Chairman: R. Graves
8:30 am   Ames Research Center CFD Overview
by T. Holst

9:10 am   Langley Research Center CFD Overview
by J. South, Jr.

9:50 am   Lewis Research Center CFD Overview
by R. Stubbs

10:30 am  Break

Session II (Center Overviews Continued) Chairman: P. Kutler
10:50 am  Marshall Space Flight Center CFD Overview
by L. Schutzenhofer

11:20 am  Johnson Space Center CFD Overview
by C. Li

11:50 am  CFD Validation Program Overview
by D. Satran

12:10 pm  Lunch
NASA CFD CONFERENCE PROGRAM

Session III (Transition and Turbulence) Chairman: T. Pulliam
1:10 pm  Understanding Transition and Turbulence Through Direct Simulations
         by P. Spalart and J. Kim
1:30 pm  Direct Simulation of Compressible Turbulence
         by T. Zang, G. Erlebacher, and M. Hussaini
1:50 pm  Nonlinear Evolution of a Second Mode Wave in Supersonic Boundary Layers
         by G. Erlebacher and M. Hussaini
2:10 pm  Numerical Simulation of Nonlinear Development of Instability Waves
         by R. Mankbadi
2:30 pm  More Accurate Predictions with Transonic Navier-Stokes Methods Through
         Improved Turbulence Modeling
         by D. Johnson
2:50 pm  Break

Session IV (CFD Codes) Chairman: J. South
3:10 pm  Recent Advances in Runge-Kutta Schemes for Solving 3-D Navier-Stokes Equations
         by V. Vatsa, B. Wedan, and R. Abid
3:30 pm  Computations of Three-Dimensional Steady and Unsteady Viscous Incompressible
         Flows
         by D. Kwak, S. Rogers, S. Yoon, M. Rosenfeld, and L. Chang
3:50 pm  SAGE - A Self-Adaptive Grid Evolution Code and Its Application in Computational
         Fluid Dynamics
         by C. Davies, E. Venkatapathy, and G. Deiwert
4:10 pm  Time Dependent Viscous Incompressible Navier-Stokes Equations
         by J. Goodrich
4:30 pm  CFD for Applications to Aircraft Aeroelasticity
         by G. Guruswamy
4:50 pm  Application of Unstructured Grid Methods to Steady and Unsteady Aerodynamic
         Problems
         by J. Batina
5:10 pm  Break
5:20 pm  Panel Session  Chairman: P. Rubbert - Boeing Commercial
         R. Melnick - Grumman Aerospace
         D. Whitfield - Mississippi State
6:20 pm  Adjourn to Officer's Club
6:30 pm  Cocktail Party at Moffet Field Officer's Club
NASA CFD CONFERENCE PROGRAM

Wednesday, March 8

7:50 am  Administrative Announcements

Session V (Fighter Aircraft) Chairman: T. Holst
8:00 am  Grid Generation and Inviscid Flow Computation about Fighter Airplanes
          by R. Smith
8:20 am  A Zonal Navier-Stokes Methodology for Flow Simulation about a Complete Aircraft
          by J. Flores
8:40 am  Numerical Simulation of F-18 Fuselage Forebody Flows at High Angles of Attack
          by L. Schiff, R. Cummings, R. Sorenson, and Y. Rizk
9:00 am  Navier-Stokes Solutions about the F-18 Forebody-Strake Configuration
          by F. Ghaffari, J. Luckring, and J. Thomas
9:20 am  Navier-Stokes Solutions for Store Separation and Related Problems
          by O. Baysal, R. Stallings, Jr., and E. Plentovich
9:40 am  TRANAIR: Recent Advances and Applications
          by M. Madison
10:00 am Break

Session VI (Rotorcraft) Chairman: W. McCroskey
10:20 am Computations of Airloads and Acoustics of Rotorcraft
        by W. McCroskey, J. Baeder, C. Chen, E. Duque, and G. Srinivasan
10:40 am Calculation of Rotor Induced Download on Airfoils
        by C. Lee
11:00 am Three-Dimensional Viscous Drag Prediction for Rotor Blades
        by C. Chen
11:20 am Progress Toward the Development of an Airfoil Icing Analysis Capability
        by M. Potapczuk, C. Bidwell, B. Berkowitz
11:40 am The Breakup of Trailing-Line Vortices
        by D. Jacqmin
12:00 pm Lunch
NASA CFD CONFERENCE PROGRAM

Session VII (Hypersonics/NASP) Chairman: D. Dwyer
1:00 pm  A Comparative Study of Navier-Stokes Codes for High-Speed Flows
by D. Rudy, J. Thomas, A. Kumar, P. Gnoffo, and S. Chakravarthy

1:20 pm  Modeling of High Speed Chemically Reacting Flow Fields
by J. Drummond, M. Carpenter, and H. Kamath

1:40 pm  Three-Dimensional Simulation of Supersonic Reacting Flows with Finite Rate
Chemistry
by S. Yu, J. Shuen, and P. Tsai

2:00 pm  Progress in Computing Nozzle/Plume Flowfields
by S. Ruffin, E. Venkatapathy, W. Feiereisen, and S. Lee

2:20 pm  Application of CFD Codes for the Simulation of Scramjet Combustor Flow Fields
by T. Chitsomboon and G. Northam

2:40 pm  Hypersonic CFD Applications at NASA Langley Using CFL3D and CFL3DE
by P. Richardson

3:00 pm  Break

Session VIII (Space Shuttle) Chairman: L. Schutzenhofer
3:20 pm  Comparison of the ARC Shuttle Ascent Simulations with Wind Tunnel and Flight Data
by J. Slotnick and F. Martin, Jr.

3:40 pm  Computational Fluid Dynamics Analysis of Space Shuttle Main Propulsion Feed
Line 17-Inch Disconnect Valves
by M. Kandula and D. Pearce

4:00 pm  Analysis of SSME HPOTP Bearing Inlet Cavity
by P. McConnaughey

4:20 pm  A Combined Eulerian-Lagrangian Two-Phase Analysis of the SSME HPOTP
Nozzle Plug Trajectories
by R. Garcia, P. McConnaughey, F. de Jong, J. Sabnis, and D. Pribik

4:40 pm  Conjugate (Solid/Fluid) Computational Fluid Dynamics Analysis of the Space
Shuttle Solid Rocket Motor Nozzle-to-Case and Case-to-Field Joints
by D. Doran, L. Keeton, P. Dionne, and A. Singhal

5:00 pm  Break

5:10 pm  Panel Session Chairman: L. Bhide - General Dynamics
R. Agarwal - McDonnell Douglas
R. MacCormack - Stanford University

6:10 pm  Adjourn to Banquet at Santa Clara Marriott Hotel

7:00 pm  Banquet at Marriott Hotel
Thursday, March 9

7:50 am  Administrative Announcements

Session IX (Turbomachinery) Chairman: R. Stubbs

8:00 am  Simulation of Turbomachinery Flows
by J. Adamczyk

8:20 am  Prediction of Turbine Rotor-Stator Interaction Using Navier-Stokes Methods
by N. Madavan, M. Rai, and S. Gavali

8:40 am  Turbine Stage Aerodynamics and Heat Transfer Prediction
by L. Griffin and H. McConnaughey

9:00 am  Automated Design of Controlled Diffusion Blades
by J. Sanz

9:20 am  Numerical Analysis of Flow Through Oscillating Cascade Sections
by D. Huff

9:40 am  Numerical Analysis of Three-Dimensional Viscous Internal Flows
by R. Chima and J. Yokota

10:00 am  Break

Session X (STOVL) Chairman: M. Liou

10:20 am  Simulators of PoweredLift Flows
by W. Van Dalsem, K. Chawla, M. Smith, K. Rao, and T. Blum

10:40 am  A Numerical Study of the Hot Gas Environment Around a STOVL Aircraft in
Ground Proximity
by T. Van Overbeke and J. Holdeman

11:00 am  CFD Analysis for High Speed Inlets
by T. Benson

11:20 am  The Use of a Navier-Stokes Code in the Wing Design Process
by S. McMillin

11:40 am  Application of a Transonic Wing Design Method
by R. Campbell and L. Smith

12:00 pm  Lunch
NASA CFD CONFERENCE PROGRAM

Session XI (Algorithms and Tools) Chairman: J. Steger

1:00 pm  An Embedded Grid Formulation Applied to Delta Wings
  by J. Thomas and S. Taylor

1:20 pm  Unstructured Mesh Solution of the Euler and Navier-Stokes Equations
  by T. Barth

1:40 pm  3-D Unstructured Grids for the Solution of the Euler Equations
  by C. Gumbert, P. Parikh, S. Pirzadeh, and R. Lohner

2:00 pm  Flux Splitting Algorithms for Two-Dimensional Real Gas Flows
  by J. Shuen and M. Liou

2:20 pm  Visualization of Fluid Dynamics at NASA Ames
  by V. Watson

2:40 pm  Computational Fluid Dynamics on a Massively Parallel Computer
  by D. Jespersen and C. Levit

3:00 pm  Break

Session XII (Hypersonics/AFE) Chairman: C. Li

3:20 pm  Conservation Equations and Physical Models for Hypersonic Air Flows Over the
  Aeroassist Flight Experiment Vehicle
  by P. Gnoffo

3:40 pm  The Computation of Thermo-Chemical Nonequilibrium Hypersonic Flows
  by G. Candler

4:00 pm  Aerodynamic Heating and Stability Analyses for Aeroassist Flight Experiment
  Vehicle
  by J. McGary and C. Li

4:20 pm  Aeroassist Flight Experiment Aerodynamics and Aerothermodynamics
  by E. Brewer

4:40 pm  Direct Simulation of Rarefied Hypersonic Flows
  by J. Moss

5:00 pm  Break

5:10 pm  Panel Session Chairman: V. Shankar - Rockwell
  J. Carter - United Technology
  A. Jameson - Princeton University

6:10 pm  Conference Adjourned
SESSION I

CENTER OVERVIEWS

Chairman:
Randolph A. Graves, Jr.
Director, Aerodynamics Division
NASA Headquarters
COMPUTATIONAL FLUID DYNAMICS PROGRAM
AT NASA AMES RESEARCH CENTER

Terry L. Holst
Chief, Applied Computational Fluids Branch
NASA Ames Research Center, Moffett Field, California

ABSTRACT

The Computational Fluid Dynamics (CFD) Program at NASA Ames Research Center is reviewed and discussed. The presentation is broken into several sections as follows: First, the technical elements of the CFD Program are generally listed and briefly discussed. These elements include algorithm research, research and pilot code development, scientific visualization, advanced surface representation, volume grid generation, and numerical optimization. Next, the discipline of CFD is briefly discussed and related to other areas of research at NASA Ames including Experimental Fluid Dynamics, Computer Science Research, Computational Chemistry, and Numerical Aerodynamic Simulation. These areas combine with CFD to form a larger area of research, which might collectively be called computational technology. The ultimate goal of computational technology research at NASA Ames is to increase the physical understanding of the world in which we live, solve problems of national importance, and increase the technical capabilities of the aerospace community.

Next, the major programs at NASA Ames that either use CFD technology or perform research in CFD are listed and discussed. Briefly, this list includes turbulent/transition physics and modeling, high-speed real gas flows, interdisciplinary research, turbomachinery demonstration computations, complete aircraft aerodynamics, rotorcraft applications, powered lift flows, high alpha flows, multiple body aerodynamics, and incompressible flow applications. Some of the individual problems actively being worked in each of these areas is listed to help define the breadth or extent of CFD involvement in each of these major programs.

State-of-the-art examples of various CFD applications are presented to highlight most of these areas. The main emphasis of this portion of the presentation is on examples which will not otherwise be treated at this conference by the individual presentations. Thus, a good survey of CFD applications research at NASA Ames can be obtained by looking at this presentation in conjunction with the individual NASA Ames presentations made at this conference.

Finally, this overview is concluded with a list of principal current limitations and expected future directions. Some of the future directions include algorithm research, turbulence/transition research, multidisciplinary research, graphics and workstation research and applications which will address more realistic simulations in the engineering world.
COMPUTATIONAL FLUID DYNAMICS
TECHNICAL ELEMENTS

ALGORITHM IMPROVEMENTS

ADVANCED SURFACE REPRESENTATION AND GRID GENERATION (EXPERT SYSTEMS)

RESEARCH CODES FOR INTEGRATING EMERGING TECHNOLOGIES

NUMERICAL OPTIMIZATION (DESIGN CONCEPTS)

PILOT CODES FOR DEMONSTRATING NEW CAPABILITIES

ADVANCED PARALLEL ALGORITHMS

SCIENTIFIC VISUALIZATION
COMPUTATIONAL TECHNOLOGIES
THRUSTS

COMPUTATIONAL FLUID DYNAMICS
- TURBULENCE/TRANSITION MODELS
- CODE VALIDATION DATA

COMPUTATIONAL CHEMISTRY
- CHEMISTRY MODELS
- SURFACE PHYSICS MODELS

EXPERIMENTAL FLUID DYNAMICS
- INCREASED UNDERSTANDING OF GOVERNING PHYSICS
- SOLUTION OF PROBLEMS OF NATIONAL IMPORTANCE
- INCREASED TECHNICAL CAPABILITY OF AEROSPACE COMMUNITY

COMPUTATIONAL TECHNOLOGIES

NUMERICAL AERODYNAMIC SIMULATION
- PATHFINDING FOR ADVANCED COMPUTATIONAL SYSTEMS
- LEADING-EDGE COMPUTATIONAL CAPABILITY FOR AEROSPACE COMMUNITY

COMPUTER SCIENCE RESEARCH
- ADVANCED ARCHITECTURES
- NETWORKING
- GRAPHICS/WORKSTATIONS
MAJOR PROGRAMS USING CFD  
NASA Ames Research Center

TURBULENT/TRANSITION PHYSICS AND PHYSICAL MODELING

HIGH-SPEED REAL GAS FLOWS
  • THERMO- AND CHEMICAL-NONEQUILIBRIUM
  • RADIATION
  • COMBUSTION
  • RAREFIED FLOW EFFECTS

INTERDISCIPLINARY RESEARCH
  • CFD + COMPUTATIONAL ELECTROMAGNETICS
  • CFD + COMPUTATIONAL STRUCTURAL MECHANICS
  • CFD + ACTIVE CONTROLS
  • CFD + HEAT CONDUCTION

TURBOMACHINERY DEMONSTRATION COMPUTATIONS
  • 3D TURBINE ROTOR-STATOR
  • MULTI-STAGE COMPRESSOR ROTOR-STATOR

COMPLETE AIRCRAFT AERODYNAMICS
  • NASP
  • F-16 (TNS, TRANAIR)
MAJOR PROGRAMS USING CFD (CONTINUED)
NASA Ames Research Center

ROTORCRAFT APPLICATIONS
- AEROACOUSTICS
- ROTOR/FUSELAGE INTERACTION
- HELICOPTER/TILTROTOR PERFORMANCE PREDICTIONS
- DYNAMIC STALL COMPUTATIONS

POWERED LIFT
- STOVL AIRCRAFT (HARRIER, E-7)
- UPPER SURFACE BLOWING APPLICATIONS
- JET FREESTREAM MIXING
- THRUST AUGMENTOR EJECTORS
- STOVL DELTA WING IN GROUND EFFECT

HIGH ALPHA
- HARV APPLICATIONS (F-18)
- OGIVE CYLINDER COMPUTATIONS
- UNSTEADY FLOWS
MAJOR PROGRAMS USING CFD (CONCLUDED)
NASA Ames Research Center

MULTIPLE BODY AERODYNAMICS
- SPACE SHUTTLE (LAUNCH CONFIGURATION)
- SRB/ET-ORBITER SEPARATION
- AIRCRAFT STORE SEPARATION
- SPACE SHUTTLE C/ SPACE SHUTTLE II

INCOMPRESSIBLE NAVIER-STOKES
- SSME APPLICATIONS
- HYDRODYNAMICS
- HIGH LIFT CONFIGURATIONS
- ARTIFICIAL HEART BLOOD FLOW SIMULATION
ADVANCED SIMULATION AND ANALYSIS PROJECT (ASAP)

VAN DALSEM, VOGEL, LUH, SORENSON, ATWOOD

OBJECTIVE

- REDUCE THE "CLOCK TIME" REQUIRED TO OBTAIN THE SURFACE DEFINITION AND GRID ABOUT A COMPLEX CONFIGURATION BY AT LEAST AN ORDER OF MAGNITUDE

APPROACH

- DEVELOP AN INTEGRATED, INTERACTIVE SURFACE DEFINITION AND GRID GENERATION CAPABILITY TAILORED TO THE CFD ENVIRONMENT

FUTURE DIRECTIONS

- EXPLORE APPLICATION OF AI TO ENHANCE NONEXPERT USER PERFORMANCE
- INVESTIGATE:
  - GRID QUALITY MEASURES
  - SOLUTION-ADAPTIVE TECHNIQUES
  - NEW GRID GENERATION APPROACHES (STRUCTURED AND UNSTRUCTURED)

PAYOFF

- A POWERFUL, EASY-TO-USE TOOL THAT SIGNIFICANTLY REDUCES THE TURNAROUND TIME FOR CURRENT AND FUTURE CFD ANALYSES
ADVANCED SIMULATION AND ANALYSIS PROJECT (ASAP)

VOGEL, LUH, SORENSON, ATWOOD

F-18 FOREBODY GRID BY 3DGRAPE: SELECTED AXIS-NORMAL SURFACES

SURFACE GRID FOR GENERIC HYPERSOONIC AIRPLANE

2D ZONING COMPARISON: HUMAN EXPERT vs EXPERT SYSTEM (EZGRID)
OBJECTIVES
- Develop capability to analyze complex geometries very quickly
  - Includes leading-edge separation, jet plumes, and unsteady effects (time stepping)

APPROACH
- Low-order panel method with time-stepped wakes

FUTURE DIRECTIONS
- Couple with boundary layer code to include viscous effects
- Use for design and analysis of wind tunnel models and to determine wind tunnel wall interference

PAYOFF
- Efficient, reliable tool for use in low speed applications
PANEL METHOD APPLICATIONS
ASHBY, IGUCHI, BROWN

80-BY 120-FOOT WIND TUNNEL INLET

E-7 STOVL MODEL

VELOCITY VARIATION ACROSS INLET

CHORDWISE PRESSURE DISTRIBUTION ON E-7 WING PMARC COMPUTATION; 2y/b = 0.6, $\alpha = 8^\circ$
TWO-DIMENSIONAL COMPUTATIONS OF MULTI-STAGE COMPRESSOR FLOWS

GUNDY-BURLET, RAI

OBJECTIVE
• DEVELOP CAPABILITY TO CALCULATE UNSTEADY VISCOUS FLOWS WITHIN MULTI-STAGE TURBOMACHINES

FUTURE DIRECTIONS
• EXTEND TO THREE-DIMENSIONS

CURRENT APPROACH
• SOLVE THE TWO-DIMENSIONAL NAVIER-STOKES EQUATIONS USING A ZONAL METHOD TO SIMULATE ROTOR-STATOR INTERACTION

PAYOFF
• BETTER UNDERSTANDING OF UNSTEADY FLUID DYNAMICS IN TURBOMACHINES
• INCREASED RELIABILITY AND EFFICIENCY OF TURBOMACHINES

INSTANTANEOUS TEMPERATURE CONTOURS
\( M_{\infty} = 0.07, \ Re = 100,000/\text{in.} \)
TIME-AVERAGED PRESSURES IN THE SECOND STAGE OF A 2.5 STAGE COMPRESSOR

GUNDY-BURLET, RAI

\[ M_\infty = 0.07, \text{ } Re = 100,000/\text{in.} \]

GRID 1

GRID 2

GRID 3

GRID 4

GRID 5

GRID 6

GRID 7

GRID 8

GRID 9

GRID 10

GRID 11

GRID 12

ROTOR RESULTS

STATOR RESULTS

**NUMERICAL**
- SUCTION SURFACE
- PRESSURE SURFACE

**EXPERIMENTAL**
EFFECT OF TANGENTIAL LEADING EDGE BLOWING ON VORTICAL FLOW
YEH, TAVELLA, ROBERTS

OBJECTIVE
- TO INVESTIGATE THE ABILITY OF TANGENTIAL LEADING EDGE BLOWING TO CONTROL VORTICAL FLOW AT HIGH ALPHA

APPROACH
- UTILIZE DELTA WING GEOMETRY
- SOLVE THIN-LAYER NAVIER-STOKES EQUATIONS USING MULTIPLE-ZONE GRID APPROACH TO ACCOMODATE JET-SLOT GEOMETRY
- UTILIZE ALGEBRAIC TURBULENCE MODEL FOR SURFACE BL AND WALL JET

FUTURE DIRECTIONS
- EXTEND TO FULL AIRCRAFT CONFIGURATIONS
- INVESTIGATE BLOWING CONTROL CONCEPTS

PAYOFF
- INCREASED UNDERSTANDING OF VORTICAL FLOW PHYSICS
- NEW TOOL FOR STUDYING BLOWING CONTROL CONCEPTS

COMPUTED "OIL FLOW"
ON DELTA WING SURFACE
\( M_\infty = 0.3, \quad Re = 1.3 \times 10^6, \quad \alpha = 40^\circ \)

BLOWING

NO BLOWING
EFFECT OF TANGENTIAL LEADING EDGE BLOWING ON VORTICAL FLOW

YEH, TAVELLA, ROBERTS

\( M_\infty = 0.3, \alpha = 40^\circ, \text{Re} = 1.3 \times 10^6, X/C = 0.36 \)
EULER VALIDATION/PRESSURE INTEGRATION
MELTON, ROBERTSON, MOYER

OBJECTIVES
• CFD VALIDATION FOR FLO57 EULER CODE
• ENHANCE WIND TUNNEL PRESSURE INTEGRATION FOR PREDICTING FORCES AND MOMENTS

APPROACH
• FLO57 FINITE VOLUME 3D EULER CODE
• COMPUTE DISCRETIZATION ERROR BY COMPARING CFD FORCE AND MOMENT INTEGRATION WITH CFD PRESSURES INTERPOLATED AND INTEGRATED AT MODEL TAP LOCATIONS

FUTURE DIRECTIONS
• INVESTIGATE NEW METHODS FOR INTEGRATING CFD AND EXPERIMENTAL RESULTS

PAYOFF
• VALIDATION OF FLO 57 FOR DELTA CONFIGURATIONS
• REDUCE INSTRUMENTATION CONSTRAINTS ON COMPLEX WIND TUNNEL MODELS
• INCREASE ACCURACY OF FORCE AND MOMENT PREDICTIONS FROM WIND TUNNEL PRESSURE INTEGRATIONS
EULER VALIDATION/PRESSURE INTEGRATION

MELTON, ROBERTSON, MOYER

M = 0.8 DRAG POLAR

UPPER SURFACE Cp's

M = 0.8 \( \alpha = 9.0^\circ \) \( C_L = 0.45 \)

EXPERIMENTAL DATA

CFD-FLO57

EXPERIMENTAL BALANCE DATA

EXPERIMENTAL PRESSURE INTEGRATION

EXP PRESSURE INTEGRATION CORRECTED FOR DISCRETIZATION ERROR

FINAL EXP PRESSURE INTEGRATION CORRECTED FOR DISCRET ERROR AND SKIN FRICTION

SKIN FRICTION CORRECTION

DISCRETIZATION CORRECTION

\( C_D \)

\( C_L \)
SPACE SHUTTLE LAUNCH CONFIGURATION

STEGER, RIZK, OBAYASHI, MARTIN, CHIU, BUNING

OBJECTIVE
• DEVELOP CAPABILITY TO COMPUTE FLOW OVER INTEGRATED SPACE SHUTTLE IN ASCENT

APPROACH
• SOLVE 3D REYNOLDS-AVERAGED NAVIER-STOKES EQUATIONS
• USE CHIMERA GRID APPROACH

FUTURE DIRECTIONS
• IMPROVE PLUME SIMULATION CAPABILITY AND CODE EFFICIENCY
• VALIDATE UNSTEADY MODE AND STUDY FAST SEPARATION SIMULATIONS

PAYOFF
• PREDICTIVE TOOL FOR UNDERSTANDING AND REFINING AERODYNAMIC PERFORMANCE OF MULTIPLE BODY VEHICLES

\[ M_\infty = 1.05 \]
\[ \alpha = -3^\circ \]
\[ Re = 2.5 \times 10^6/\text{ft} \]
(3% MODEL)
SPACE SHUTTLE ASCENT-MODE RESULTS

\[ M_\infty = 1.05, \alpha = -3^\circ \]

\[ M_\infty = 0.9, \alpha = -3^\circ \]

Cp COMPARISONS ALONG ORBITER FUSELAGE DURING ASCENT

COMPUTATION

\[ M_\infty = 1.05 \]

\[ \alpha = -3 \]

WIND TUNNEL COMPARISON OF SURFACE PRESSURES
UNSTEADY MULTIPLE BODY AERODYNAMICS

OBJECTIVE

- TO DEVELOP A GENERAL CAPABILITY FOR TIME-ACCURATE SIMULATION OF 3-D MULTIPLE BODY VISCOUS FLOWS GIVEN ARBITRARY GRID COMBINATIONS, BODY SHAPES, AND RELATIVE MOTION BETWEEN GRID SYSTEMS

CURRENT APPROACH

- UNSTEADY CHIMERA COMPOSITE GRID TECHNIQUES
- IMPLICIT TIME-ACCURATE SOLVER FOR THE THIN-LAYER NAVIER-STOKES EQUATIONS

FUTURE DIRECTIONS

- DEVELOP TRAJECTORY PREDICTION ROUTINES
- IMPROVE EFFICIENCY AND ACCURACY OF BASIC ALGORITHMS
- CODE VALIDATION STUDIES

PAYOFF

- A VALIDATED COMPUTATIONAL TOOL FOR ANALYZING COMPLEX AERODYNAMIC PROBLEMS INVOLVING MULTIPLE BODIES IN RELATIVE MOTION
TIME-ACCURATE SIMULATION OF THE SPACE SHUTTLE SRB SEPARATION SEQUENCE

PRESSURE CONTOURS

\[ M_\infty = 4.5 \]
\[ \alpha = +2^\circ \]
\[ R_e = 6.95 \times 10^6 \]

ASSUMPTIONS:
- SIMPLIFIED GEOMETRY
- NO PLUMES
- PRESCRIBED SRB TRAJECTORY

DISCRETIZATION

GRIDS:
- ET 73X39X45
- SRB 53X37X21
- ORB 74X77X33

TIME-STEP = 1.36 \times 10^3 \text{sec}
500 STEPS THROUGH BSM BURN
BOOSTER SEPARATION MOTOR (BSM)
BURN-TIME = 0.68 \text{sec}

(MEAKIN, SUHS)
AIRCRAFT STORE SEPARATION
MEAKIN, SUHS

FREESTREAM CONDITIONS: \( M_\infty = 1.05, \ \alpha = +2^\circ, \ \text{Re} = 2.4 \times 10^6 \)

WING LOWER SURFACE \( C_p \) DISTRIBUTION          MACH CONTOURS ABOUT STORE

STEADY-STATE

WING ALONE              WING ALONE

WING AND STORE          WING, PYLON AND STORE

TIME-ACCURATE
STORE-SEPARATION SIMULATION

\( t = 0 \text{ sec} \)

\( t = 0.15 \text{ sec} \)

\( t = 0.30 \text{ sec} \)
TURBULENCE MODELING FOR HYPERSONIC FLOWS
COAKLEY, HORSTMANN, KUSSOY, MARVIN

OBJECTIVE

• IMPROVE AND DEVELOP MODELS FOR HYPERSONIC FLOWS

CURRENT APPROACH

• PERFORM COMBINED COMPUTATIONAL AND EXPERIMENTAL STUDIES

FUTURE DIRECTIONS

• IMPROVE COMPUTATIONAL EFFICIENCY
• DEVELOP SECOND ORDER CLOSURE MODELS
• PERFORM EXPERIMENTS USING NEWLY DEVELOPED NON INTRUSIVE INSTRUMENTATION

PAYOFF

• ACCURATE COMPUTATIONS OF HEAT TRANSFER, SKIN FRICTION, AND COMPLEX FLOW STRUCTURES
PRESSURE CONTOURS FOR AN IMPINGING SHOCK WAVE FLOW

\[ M_\infty = 7.2 \quad \theta = 15^\circ \]

**Baldwin-Lomax Model**

NORMALIZED PRESSURE CONTOURS

- \( \text{Re} = 2.26 \times 10^6 \)
- \( \text{GRID}\ 80 \times 1 \times 80 \)

**q-\( \omega \) Model c**

PRESSURE CONTOURS
PRESSURE CONTOURS FOR AN IMPINGING SHOCK WAVE FLOW

\[ M_\infty = 7.2 \quad \theta = 15^\circ \]

COMPUTATION \( q_{\omega} \) MODEL \( c \)

EXPERIMENT
HYPERSONIC APPLICATIONS

OBJECTIVE

- Develop capability to compute real-gas aerothermodynamic characteristics of hypersonic vehicles
- Use capability to guide vehicle designs

APPROACH

- Solve 3D Reynolds-averaged Navier-Stokes and parabolized Navier-Stokes equations using various transition/turbulence models with perfect gas, equilibrium real gas and nonequilibrium real gas models

FUTURE DIRECTIONS

- Improve transition/turbulence models, real gas models, and computational efficiency
- Extend applications to more complex geometries

PAYOFF

- Provide design information not possible to measure in ground-based test facilities
- Enable development of aeroassisted vehicles and airbreathing hypersonic aircraft
GENERIC HYPersonic
AEROTHERMODYNAMIC RESULTS

LAWRENCE

\( M_\infty = 11.4, \alpha = 0^\circ, Re_L = 29 \times 10^6 \)

SYMMETRY PLANE
PRESSURE CONTOURS

WINDWARD SYMMETRY PLANE PRESSURES

WINDWARD SYMMETRY PLANE HEAT TRANSFER

<table>
<thead>
<tr>
<th>NORMALIZED PRESSURE</th>
<th>&quot;UPS - SHARP&quot;</th>
<th>&quot;UPS - BLUNT&quot;</th>
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<tr>
<th>NORMALIZED HEATING RATE</th>
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HYPERSO NIC EXHAUST PLUME/AFT ERBODY INTERACTION

EDWARDS

NOZZLE/AFT ERBODY MODEL

EXHAUST GAS CONCENTRATION
CONTOURS

$M_{\infty} = 6, \text{ NPR } = 4, \alpha = 0^\circ$

EXHAUST GAS CONCENTRATION
CONTOURS

$M_{\infty} = 6, \text{ NPR } = 3, \alpha = 5^\circ$

• EXPERIMENT
  • COMPUTATION

AFTERBODY PRESSURE COMPARISON
BETWEEN 2ND AND 3RD NOZZLES

PRESSURE CONTOURS

$M_{\infty} = 6, \text{ NPR } = 100, \alpha = 0^\circ$

$M_{\infty} = 1.46, \text{ NPR } = 6.27, \alpha = 0^\circ$

• EXPERIMENT
  • COMPUTATION

PRESSURE COMPARISON
WINDWARD PLANE OF SYMMETRY
DOWNSTREAM OF NOZZLE
BLUNT 5° CONE WITH SHOCK GENERATORS

Molvik, Strawa

Conditions: \( M_\infty = 14.4 \)
\( Re_L = 10^6 \)
\( P_\infty = 0.0932 \text{ atm} \)
\( T_\infty = 298^\circ \text{K} \)
\( \alpha = 6.35^\circ \)

Experimental Facility: Ames Ballistic Range

Flow Solvers: Three-Dimensional Navier-Stokes with Finite Rate Chemistry (TUFF and STUFF)

REAL GAS COMPUTATION
O Concentration Contours

REAL GAS COMPUTATION
Pressure Contours
DIRECT PARTICLE SIMULATION OF HYPersonic FLows

OBJECTIVE:
• DEVELOP THE CAPABILITIES OF A NEW DISCRETE PARTICLE SIMULATION METHOD FOR RAREFIED HYPersonic FLOWS IN 3D WITH NON-EQUILIBRIUM CHEMISTRY.

APPROACH:
• FLUID IS MODELED AS A LARGE COLLECTION OF DISCRETE PARTICLES THAT INTERACT WITH EACH OTHER THROUGH COLLISIONS.
• SIMPLIFIED PHYSICAL MODELS ARE USED ALLOWING ORDERS OF MAGNITUDE INCREASE IN COMPUTATIONAL EFFICIENCY WHILE ENHANCING STATISTICAL ACCURACY.

FUTURE DIRECTIONS:
• REALISTIC 3D GEOMETRIES WITH MORE GENERAL BOUNDARY CONDITIONS.
• EXTENDED MOLECULAR MODELS TO ACCOUNT FOR ADDITIONAL INTERNAL DEGREES OF FREEDOM, CHEMISTRY AND WALL-PARTICLE INTERACTIONS.

PAYOFF:
• DIRECT PARTICLE SIMULATION IS APPLICABLE AT LOW DENSITIES AND HIGH MACH NUMBERS BEYOND THE REACH OF CONTINUUM METHODS.
• ENABLES PARTICLE SIMULATIONS ON A MUCH LARGER SCALE THAN PREVIOUSLY POSSIBLE.
• PROVIDES NEEDED INSIGHT IN THE DESIGN OF PROPOSED HYPersonic VEHICLES.
PRINCIPAL CURRENT LIMITATIONS

PHYSICAL MODELS/ALGORITHMS
- BOUNDARY LAYER TRANSITION MODELS
- TURBULENCE MODELS FOR SEPARATING AND REATTACHING FLOWS
- TRANSITION/TURBULENCE MODELS FOR REAL GAS FLOWS AND FLOWS WITH COMBUSTION
- REAL GAS FLOW VALIDATION DATA
- FAST, USER FRIENDLY GEOMETRY DEFINITION/GRID GENERATION SOFTWARE
- FAST, ACCURATE ALGORITHMS FOR COMPLETE SIMULATIONS
- SCIENTIFIC VISUALIZATION SOFTWARE

COMPUTER SYSTEMS
- COMPUTATIONAL SPEED
- NETWORK BANDWIDTHS
- HIGH-SPEED LARGE-VOLUME MASS STORAGE
- TOOLS FOR ANALYZING MASSIVE RESULT FILES
FUTURE DIRECTIONS

ALGORITHM RESEARCH
- IMPROVED ALGORITHMS FOR COMPUTING REAL-GAS TURBULENT FLOWS
- NEW ALGORITHMS TO EXPLOIT ADVANCED MULTIPLE PROCESSOR COMPUTER ARCHITECTURES
- NEW GRID-GENERATION CONCEPTS FOR COMPLEX CONFIGURATIONS, MULTIPLE MOVING BODIES AND UNSTeadY FLOWS

TURBULENCE RESEARCH
- IMPROVED TURBULENCE MODELS FOR PERFECT-GAS SEPARATING AND REATTACHING FLOWS
- NEW TURBULENCE MODELS FOR REAL-GAS FLOWS
- METHODS FOR MANAGING TURBULENCE TO REDUCE DRAG, IMPROVE COMPONENT PERFORMANCE, MINIMIZE HEAT TRANSFER, AND CONTROL COMBUSTION PROCESSES

MULTIDISCIPLINARY RESEARCH
- NUMERICAL METHODS FOR SOLVING FULLY COUPLED COMBINATIONS OF EQUATIONS FOR AERODYNAMICS, GAS CHEMISTRY, STRUCTURES, CONTROLS, PROPULSION AND ELECTROMAGNETICS
FUTURE DIRECTIONS
(CONCLUDED)

GRAPHICS AND WORKSTATION RESEARCH
• IMPROVED USER EFFICIENCY THROUGH ADVANCES IN GRAPHICS AND WORKSTATION TECHNOLOGY

APPLICATIONS CODES
• AIRCRAFT MANEUVERING NEAR PERFORMANCE BOUNDARIES
• POWERED LIFT AIRCRAFT OPERATING IN AND OUT OF GROUND EFFECT
• HYPersonic VEHICLES INCLUDING INLET, ENGINE AND EXHAUST FLOWS
• ROTORCRAFT IN HOVER, TRANSITION AND FORWARD FLIGHT
• TURBOMACHINERY INCLUDING PUMPS, COMPRESSORS AND TURBINES
• METHODS FOR NUMERICALLY OPTIMIZING DESIGNS
• DESIGNER-FRIENDLY CODES WITH 'EXPERT SYSTEMS' ELEMENTS
COMPUTATIONAL FLUID DYNAMICS RESEARCH AND APPLICATIONS
AT NASA LANGLEY RESEARCH CENTER

Jerry C. South, Jr.
Head, Analytical Methods Branch
Fluid Mechanics Division

Research at Langley includes all aeronautics disciplines and selected space disciplines. Nearly all the
aeronautics disciplines have a significant component of CFD research which complements wind-tunnel and flight
experimental research; in space research, aerothermodynamics of planetary entry vehicles is heavily dependent
on CFD as a research tool. Langley's CFD strategy contains four major thrusts: Focus efforts on critical CFD
barriers; focus efforts on critical aerodynamics barriers; validate CFD codes; and transfer technology to United
States users. The Langley presentations in this conference are representative of our strategy. They are grouped
in six broad areas:

1. Direct Simulation of Transition and Turbulence
2. Hypervelocity Aerothermodynamics and Rarified Flows
3. Hypersonic External and Internal (scramjet) Flows
4. Unsteady Aerodynamics and Aeroelasticity Applications
5. Grid Generation and Applications for Complex Configurations
6. Supersonic and Transonic Wing Design Applications

Three examples of important work not shown in this conference are described in the conclusion of the
presentation.
LANGLEY CFD STRATEGY

- FOCUS EFFORT ON CRITICAL CFD BARRIERS
- GRIDS & ALGORITHMS FOR COMPLEX CONFIGURATIONS
- TRANSITION & TURBULENCE MODELS FOR RANS CODES
- NEW ALGORITHMS FOR MASSIVELY-PARALLEL PROCESSORS
- ENABLE ROUTINE APPLICATIONS

- FOCUS EFFORT ON CRITICAL AERODYNAMICS BARRIERS
- DIRECT SIMULATION OF TRANSITION AND TURBULENCE
- SIMULATION/PREDICTION OF HIGH-ALPHA FLOWS
- SIMULATION/PREDICTION OF HYPERSONIC PROPULSION
LANGLEY CFD STRATEGY
(Concluded)

- VALIDATE CFD CODES
  - CODE-ON-CODE
  - CODE-ON-EXPERIMENT (GROUND & FLIGHT)

- TRANSFER TECHNOLOGY
  - RESEARCHER EXCHANGES (ARC → LaRC → LeRC)
  - NAS NETWORK DATA/CODE EXCHANGES
  - TRAINING APPLICATIONS RESEARCHERS
# CFD Five-Year Plan

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<th>Thrust</th>
<th>Year</th>
<th>Goal</th>
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<td><strong>CFD Development</strong></td>
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<td>IMPROVE SPEED/ACCURACY N-S STOKES</td>
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<td>HIGH-SPEED REACTING FLOWS</td>
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<td><strong>Flow Physics</strong></td>
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<td>PREDICTIVE CAPABILITY FOR COMPLEX 3D VICOUS FLOWS FOR ADVANCED A/C MISSILES, &amp; PROP. SYS.</td>
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<td>HIGHLY DETAILED DATA BASE TO EXTRACT UNDERSTANDING OF PHYSICS OF 2D &amp; 3D FLOWS</td>
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3-BLOCK GRID TOPOLOGY

Nearfield view F-18; 300,000 points total
EFFECT OF PATCHING ALGORITHM

\[ M_\infty = 0.60 \quad \alpha = 20^\circ \quad R_c = 0.8 \times 10^6 \]

Spatial-flux conservation

Time-flux conservation
F-18 SURFACE FLOW

\[ \alpha = 30^\circ \quad R_c = 2.7 \times 10^6 \]

WIND-TUNNEL (BART)

NAVIER-STOKES (CFL3D)
ENTROPY AND VORTICITY EFFECTS IMPROVE ACCURACY OF UNSTEADY TRANSONIC SMALL-DISTURBANCE (TSD) THEORY

- **UNMODIFIED THEORY GIVES INACCURATE SHOCK PREDICTION**

  - CAP-TSD
  - Euler

- **ENTROPY AND VORTICITY CORRECTIONS YIELD EULER-LIKE RESULTS**

  - M = 0.92
  - M6 wing

- $C_p$ vs $x/c$ for different $\eta$ values:
  - $\eta = 0.82$
  - $\eta = 0.47$
  - $\eta = 0.08$
EFFECTS OF REDUCED FREQUENCY ON FIRST HARMONIC COMPONENTS OF UNSTEADY PRESSURES DUE TO AIRFOIL PITCHING

• NACA 0012 airfoil at $M_\infty = 0.755$, $\alpha_0 = 0.016^\circ$, $\alpha_1 = 2.51^\circ$

k = 0.163

Real

Imaginary

k = 0.651

Real

Imaginary

k = 0.326

Euler (CFL3D)

Potential (CAP-TSD)

Experiment

k = 1.302

Real

Imaginary

x/c
UNSTRUCTURED ADAPTIVE GRID FOR INVISCID SOLUTION
FOR 3-ELEMENT AIRFOIL (MAVRIPLIS, ICASE)
FINITE-VOLUME EULER SOLUTION FOR 3-ELEMENT AIRFOIL (MAVRIPLIS, ICASE)
UNSTRUCTURED GRID FOR AIRFOIL WITH SLAT. HIGHLY-STRETCHED TRIANGLES TO RESOLVE LAMINAR BOUNDARY LAYER.
(MAVRIPLIS, ICASE)
LAMINAR NAVIER-STOKES CALCULATIONS ON UNSTRUCTURED MESH IN SLAT REGION (MAVRIPIS, ICASE)
Computational Fluid Dynamics at the Lewis Research Center
An Overview

By
Robert M. Stubbs
NASA-Lewis Research Center
Cleveland, Ohio 44135

Lewis is a multidisciplinary Center with strong research and development programs in aeronautical and space propulsion, power, space communications, space experiments and materials. Computational fluid dynamics (CFD) is playing an important and growing role in most of these areas. This presentation describes how CFD is integrated into these programs and highlights elements of the CFD activities. Examples are presented of codes developed to predict flow fields in advanced propulsion systems and several of the code validation experiments are described. As will be evident in the several Lewis authored papers to be presented at this conference, the CFD effort at Lewis ranges from basic research on new and improved algorithms through code development to the application of these codes to specific engineering problems. Because of the substantial improvement in CFD's predictive capability its use at Lewis is on a steep growth path, spreading rapidly into new areas which had not traditionally taken advantage of the techniques of numerical simulation. The presentation concludes with a discussion of multidisciplinary codes and the future direction of CFD at Lewis.
LEWIS COMPUTER RESOURCES

- CRAY X-MP/24
- SCIENTIFIC VAX CLUSTER
- 2 AMDAHLs (VM/CMS AND MVS/XA)
- ALLIANT FX/8 PARALLEL PROCESSOR
- ADVANCED WORK STATIONS (SILICON GRAPHICS, SUN, APOLL0)
- T1 LINK TO NAS
OBJECTIVE

0 TO DEVELOP ADVANCED COMPUTATIONAL METHODS REQUIRED FOR THE SOLUTION OF INTERNAL FLUID MECHANICS AND STRUCTURAL PROBLEMS

ROLE

0 GENERATE NEW IDEAS/APPROACHES TO PROPULSION RESEARCH THROUGH INTERACTION WITH LeRC STAFF

0 PROVIDE OPPORTUNITY TO ICOMP PERSONNEL TO DO ORIGINAL RESEARCH UTILIZING WORLD-CLASS COMPUTERS
CFD'S ROLE IN THE PROBLEM SOLVING PROCESS

**EXPERIMENTS**
- COMPONENT
  - FUNDAMENTAL
    - VALIDATION DATA
      - CALIBRATION DATA
      - IMPROVED PREDICTIVE CAPABILITY
      - IDENTIFICATION OF NEW CONCEPTS

**COMPUTATIONS**
- GOVERNING EQUATIONS
  - SIMPLIFYING ASSUMPTIONS
    - SOLVABLE EQUATION SET
      - ANALYTICAL SOLUTION
      - NUMERICAL SOLUTION
      - ALGORITHMS
      - GRIDS
      - COMPUTERS
COMPUTATIONAL FLUID DYNAMICS AT LEWIS

WHERE DOES CFD PLAY A ROLE?

- AERO PROPULSION
- SPACE PROPULSION
- OTHER
  - SPACE POWER
  - MATERIALS PROCESSING
  - FLUIDS IN MICROGRAVITY
CONCEPTUAL ADVANCED TURBOFAN ENGINE
PHYSICAL PHENOMENA REQUIRING ANALYSES

3D VISCOUS FLOWS
SECONDARY FLOWS
LOSSES
FLOW SEPARATION
SHOCK/Boundary Layer

3D INVISCID FLOWS
SHOCKS

UNSTEADY LOADING
WAKE EFFECTS
MULTISTAGE EFFECTS

SPRAY SIZE/DISTRIBUTION
IGNITION/EXTINCTION
TURBULENT BURNING
CHEMISTRY
JET INTERACTIONS
RADIATION

HEAT TRANSFER
FILM COOLING
RVC3D (ROTOR VISCOUS CODE 3-D)
BY DR. R. V. CHIMA

- NAVIER-STOKES ANALYSIS FOR 3D FLOWS IN TURBOMACHINERY
- STACKED C-TYPE GRIDS FOR AXIAL OR CENTRIFUGAL MACHINES
- THIN-LAYER NAVIER-STOKES FORMULATION RETAINS HUB-TO-TIP AND BLADE-TO-BLADE VISCOUS TERMS
- BALDWIN-LOMAX TURBULENCE MODEL
- EXPLICIT 4-STAGE RUNGE-KUTTA TIME-MARCHING SCHEME WITH VARIABLE TIME STEP AND IMPlicit RESidual SMOOTHING
- HIGHLY VECTORIZED FOR CRAY X-MP
RPLUS 3D

BY DR. S.T. YU, J. S. SHUEN & P. TSAI

- 3D NAVIER-STOKES CODE FOR CHEMICALLY REACTING FLOWS
- FINITE RATE CHEMISTRY MODEL
  O 9 SPECIES INVOLVING O, H, AND N
  O 18 REACTION STEPS
- TIME-MARCHING LU SCHEME
- FAST AND ROBUST
PROTEUS

- IMPPLICIT 2D AND 3D NAVIER-STOKES CODE
- READILY MODIFIED, WELL DOCUMENTED GENERAL SOLVER
- FULL, COMPRESSIBLE NAVIER-STOKES WITH ENERGY EQUATION
- EULER AND THIN-LAYER OPTIONS
- LINEARIZED BLOCK IMPPLICIT (LBI) SOLVER
- IMPPLICIT BOUNDARY CONDITIONS
- FIRST OR SECOND ORDER IN TIME
- ALGEBRAIC (BALDWIN-LOMAX) AND 2-EQUATION TURBULENCE MODELS CURRENTLY BEING IMPLEMENTED
MULTISTAGE AVERAGE PASSAGE CODE

BY DR. JOHN ADAMCZYK

- MULTISTAGE SIMULATIONS FOR ARBITRARY GEOMETRIES
- 3D VISCOUS
- EXPLOITS MACROTASKING
- FIRST SIMULATION OF A 3D MULTISTAGE TURBINE
- COMPATIBLE WITH THE DESIGN ENVIRONMENT
- CODE/METHODOLOGY CURRENTLY BEING USED IN DESIGN OF TURBOMACHINERY
PUTTING IT ALL TOGETHER

INLETS, DUCTS, AND NOZZLES

TURBOMACHINERY

CHEMICAL REACTING FLOWS

COMPUTATIONAL AND EXPERIMENTAL TECHNOLOGY

INTEGRATED MULTIDISCIPLINARY ANALYSIS AND TEST

NUMERICAL PROPULSION SYSTEM SIMULATION
LEWIS RESEARCH CENTER

NUMERICAL SIMULATION OF NONLINEAR DEVELOPMENT OF INSTABILITY WAVES  
R. MANKBADI

TIME DEPENDENT VISCOUS INCOMPRESSIBLE NAVIER-STOKES EQUATIONS  
J. GOODRICH

PROGRESS TOWARD THE DEVELOPMENT OF AN AIRFOIL ICING ANALYSIS CAPABILITY  
M. POTAPCZUK  
C. BIDWELL  
B. BERKOWITZ

THE BREAKUP OF TRAILING-LINE VORTICES  
D. JACQMIN

THREE DIMENSIONAL SIMULATION OF SUPersonic REACTING FLOWS WITH FINITE RATE CHEMISTRY  
S. YU  
J. SHUEN  
P. TSAI

SIMULATION OF TURBOMACHINERY FLOWS  
J. ADAMCZYK

AUTOMATED DESIGN OF CONTROLLED DIFFUSION BLADES  
J. SANZ

NUMERICAL ANALYSIS OF FLOW THROUGH OSCILLATING CASCADE SECTIONS  
D. HUFF

NUMERICAL ANALYSIS OF THREE-DIMENSIONAL VISCOUS INTERNAL FLOWS  
R. CHIMA  
J. YOKOTA

A NUMERICAL STUDY OF THE HOT GAS ENVIRONMENT AROUND A STOVL AIRCRAFT IN GROUND PROXIMITY  
T. VAN OVERBEKE  
J. HOLDEMAN

CFD ANALYSIS FOR HIGH SPEED INLETS  
T. BENSON

FLUX SPLITTING ALGORITHMS FOR TWO-DIMENSIONAL REAL GAS FLOWS  
J. SHUEN  
M. LIOU
FUTURE DIRECTIONS

- SEVERAL FACTORS CONTRIBUTING TO A CFD EXPLOSION AT LEWIS
  - IMPROVED PREDICTIVE CAPABILITY
  - INCREASE IN MACHINE CAPACITY AND AVAILABILITY

- CFD NO LONGER LOCALIZED, NOW IN WIDE USE IN SEVERAL DISCIPLINE AREAS

- GROWING EMPHASIS ON MULTIDISCIPLINARY SYSTEM SIMULATIONS
SESSION II

CENTER OVERVIEWS

(Continued)

Chairman:
Paul Kutler
Chief, Fluid Dynamics Division
NASA Ames Research Center
Marshall Space Flight Center CFD Overview

L. A. Schutzenhofer, NASA/MSFC

Computational Fluid Dynamics (CFD) activities at Marshall Space Flight Center (MSFC) have been focused on hardware specific and research applications with strong emphasis upon benchmark validation. The purpose of this overview is to provide insight into the MSFC CFD related goals, objectives, current hardware related CFD activities, propulsion CFD research efforts and validation program, future near-term CFD hardware related programs, and CFD expectations. The current hardware programs where CFD has been successfully applied are the Space Shuttle Main Engines (SSME), Alternate Turbopump Development (ATD), and Aeroassist Flight Experiment (AFE). For the future near-term CFD hardware related activities, plans are being developed that address the implementation of CFD into the early design stages of the Space Transportation Main Engine (STME), Space Transportation Booster Engine (STBE), and the Environmental Control And Life Support System (ECLSS) for the Space Station. Finally, CFD expectations in the design environment will be delineated.
MARSHALL SPACE FLIGHT CENTER CFD OVERVIEW

- COMPUTATIONAL FLUID DYNAMICS BRANCH ACTIVITIES
  - OBJECTIVES
  - INTERACTION
  - APPROACH TOWARD SOLUTIONS OF COMPLEX FLOWS

- MSFC HARDWARE RELATED ACTIVITIES
  - INHOUSE
  - ROCKETDYNE - SSME
  - PRATT AND WHITNEY - ATD

- NASA EARTH-TO-ORBIT PROPULSION R&T PROGRAM
  - PROGRAM DEFINITION
  - WORK ELEMENT SUMMARY; CFD EMPHASIS
  - EXPERIMENTAL APPARATUS
  - CONSORTIUM

- NEW NEAR TERM CFD ACTIVITIES
  - ADVANCED LAUNCH SYSTEM, ALS
  - ENVIRONMENTAL CONTROL AND LIFE SUPPORT SYSTEM, ECLSS

- CFD EXPECTATIONS
COMPUTATIONAL FLUID DYNAMICS BRANCH ACTIVITIES

OBJECTIVES

• SUPPORT PROGRAM OFFICES
  — "QUICK TURNAROUND" APPLICATIONS
  — INTERACT WITH HARDWARE CONTRACTORS IN DEVELOPMENT OF DESIGN ENVIRONMENTS
  — PROVIDE "SMART BUYER" CAPABILITY FOR LONG-TERM APPLICATIONS
  — DEVELOP SUBSYSTEMS CFD MODELS
  — FOCUS MSFC CFD ACTIVITIES/PROVIDE CENTERWIDE CFD SUPPORT

• FOCUS DEVELOPMENT OF CFD METHODOLOGY
  — INTERACT WITH ARC, LeRC, LaRC, AND OTHER RESEARCH ORGANIZATIONS TO FOCUS TECHNOLOGY DEVELOPMENT TOWARDS MSFC HARDWARE RELATED PROBLEMS
  — DEVELOP REQUIREMENTS FOR CFD CODE VERIFICATION
  — VERIFY CODES THROUGH BENCHMARK COMPARISONS
  — ADVANCE CFD TECHNOLOGY FOR APPLICATIONS

• DEVELOP ADVANCED HARDWARE TECHNOLOGY CONCEPTS
  — TURBINE STAGE
  — IMPELLER STAGE
  — NOZZLES, PREBURNERS, ETC.
COMPUTATIONAL FLUID DYNAMICS BRANCH ACTIVITIES

ORGANIZATIONAL INTERACTIONS AND UNIQUE CFD RESOURCES CAPABILITY

- SUBSYSTEMS MODELS FOR APPLICATIONS
  - "QUICK TURNAROUND" APPLICATIONS
  - "SMART BUYER" CAPABILITY
  - INTERACT WITH HARDWARE CONTRACTORS

- BENCHMARKED CODES AND SUPPORT
  - FOCUS NATIONAL CFD ACTIVITIES
  - FOCUS MSFC CFD ACTIVITIES
  - REQUIREMENTS FOR CODE VERIFICATION
  - BENCHMARK COMPARISONS
  - TECHNOLOGY TRANSFER IN MSFC
  - ADVANCED CFD TECHNOLOGY

- ADVANCED DESIGN TOOLS
  - AFE
  - TURBINE/IMPELLER STAGES
  - BORE/JOINT FLOW MODELS
COMPUTATIONAL FLUID DYNAMICS BRANCH ACTIVITIES

CFD CROSS FERTILIZATION

**BASIC RESEARCH**
- ALGORITHM DEVELOPMENT
- NUMERICAL METHODS
- GRID GENERATION
- ADAPTIVE GRIDS
- CODE DEVELOPMENT
- FLOW PROCESS MODELING
- ADVANCED COMPUTER SYSTEMS

**APPLIED CFD**
- LIBRARY OF CODES
- BENCHMARK VALIDATION
- DESIGN CODES FROM VARIOUS SOURCES
- DEVELOP DESIGN CODES
- DEVELOP CRITERIA TO ASSESS CODES
- EVALUATE ADVANCED HARDWARE TECHNOLOGY CONCEPTS

**ENGINEERING ANALYSIS**
- PARAMETRIC STUDIES
- HARDWARE OPTIMIZATION
- PERFORMANCE OPTIMIZATION
- ANOMALY INVESTIGATION
- SYSTEM DESIGN
- DESIGN ASSESSMENT

ARC, LeRC, LaRC  MSFC  MSFC
COMPUTATIONAL FLUID DYNAMICS BRANCH ACTIVITIES

APPROACH TOWARD SOLUTIONS OF COMPLEX FLOWS

- DEVELOP DATA BASE
  - LITERATURE SEARCH
  - COLLATE RELEVANT EXPERIMENTAL RESULTS
  - IDENTIFY SIGNIFICANT PARAMETERS, SCALING LAWS
  - DEFINE REQUIREMENTS FOR BENCHMARK EXPERIMENTS

- PERFORM FUNDAMENTAL ENGINEERING ANALYSIS
  - SIMPLIFIED 1-D OR 2-D ANALYSES
  - ELEMENTARY SENSITIVITY ANALYSIS

- PERFORM CFD CALCULATIONS
  - EXERCISE BENCHMARKED STATE-OF-THE-ART CODES
  - IMPLEMENT STATE-OF-THE-ART FLOW PROCESS MODELS
PREDICTION OF SECONDARY FLOW IN CURVED DUCTS OF SQUARE CROSS-SECTION

OBJECTIVE: TO VERIFY NAVIER-STOKES CODES FOR THE ACCURATE PREDICTION OF SECONDARY FLOW IN CURVED DUCTS

APPROACH: APPLICATIONS OF A 3-D INCOMPRESSIBLE NAVIER-STOKES CODE (INS3D) TO FLOW IN A 90° AND 180° BEND AND A 22.5° S-DUCT OF SQUARE CROSS-SECTION (25000, 50000, 100000, AND 175000 GRID POINTS); COMPARE PREDICTIONS TO LDV MEASUREMENTS

COMPUTER RESOURCES REQUIRED: 2 TO 6 MW STORAGE ON A CRAY X-MP; 3/4 HOUR RUN TIME ON CRAY X-MP FOR THE 10^5 GRID POINT CASES

IMPACT: VERIFICATION OF INCOMPRESSIBLE NAVIER-STOKES CODE FOR THE PREDICTION OF SECONDARY FLOWS IN COMPLEX INTERNAL FLOW FIELDS
Prediction of Secondary Flow in Curved Ducts of Square Cross-Section

Re = 790
M = 0.0

Outer Wall

Experiment

Inner Wall

Axial Flow at 90 Degree Bend Exit

Radial Flow at 90 Degree Bend Exit

Computation
TURBOPUMP DESIGN EQUATIONS

\[ P_{02} - P_{01} = \eta_T \eta_p \frac{\dot{m}}{m_p} p_p (T_{01} - T_{02}) C_p \]
# MSFC HARDWARE RELATED ACTIVITIES
## INHOUSE PROGRAM SUPPORTING ACTIVITIES

<table>
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<tr>
<th>SSME</th>
<th>INHOUSE</th>
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<td>• HPFTP TURBINE BLADES</td>
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<td>• SINGLE CRYSTAL HOLLOW CORE TURBINE BLADES</td>
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<td>• LOX PUMP BEARINGS</td>
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<td>• FUEL PREBURNER</td>
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<td>• LOX PREBURNER</td>
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<td>• LOX MANIFOLD TEE (4000 Hz)</td>
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<td>• HOT GAS MANIFOLD/MANIFOLD STRUTS</td>
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<td>• PUMP COOLANT FLOW PATHS</td>
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<td>• NOZZLE/MCC MISMATCH</td>
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<td>• HPOTP NOZZLE PLUG TRAJECTORIES</td>
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<td>• TRANSIENT BEHAVIOR OF FUEL PREBURNER MANIFOLD</td>
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<td>• UTRC HPFTP COOLANT FLOW EXPERIMENT</td>
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<td>• BEARING DEFLECTOMETER (TTBE)</td>
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<td>• ROTOR-STATOR INTERACTION</td>
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<td>• TURNAROUND DUCT AND HOT GAS MANIFOLD</td>
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<td>• BEARING ANALYSIS</td>
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<td>• LOX PUMP INLET SCROLL</td>
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<td>• FUEL PUMP INTERSTAGE CROSSOVER DUCTS</td>
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<td>• FUEL PUMP INLET SCROLL</td>
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<td>• LOX PUMP DISCHARGE VOLUTE</td>
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<td>— CANTED NOZZLE</td>
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<td>— BROKEN INHIBITOR</td>
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<td>• FIELD JOINT</td>
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MSFC HARDWARE RELATED ACTIVITIES

INHOUSE PROGRAM SUPPORTING ACTIVITIES (CONTINUED)

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<td><strong>ADVANCED PROGRAM DEVELOPMENT</strong></td>
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<td>• EXTERNAL TANK GAMMA RAY IMAGING TELESCOPE</td>
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# MSFC Hardware Related Activities

## Rocketdyne Application of CFD to SSME

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<th>Code</th>
<th>Nonturbomachinery</th>
<th>Code</th>
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<td>HPFTP Impeller Cavity</td>
<td>STEP</td>
<td>HOT GAS MANIFOLD</td>
<td>INS3D</td>
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<tr>
<td>HPOTP P/B Bearing Disch Cavity</td>
<td>STEP</td>
<td>FUEL-SIDE</td>
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<tr>
<td>HPOTP Turbine End BRG Disch Cavity</td>
<td>STEP</td>
<td>2-DUCT TURBULENT</td>
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<td>HPOTP 2ND STG Turbine Nozzle</td>
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<td>3-DUCT TURBULENT</td>
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<td>HPFTP 1ST STG Turbine Disk Cavity</td>
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<td>OXIDIZER-SIDE</td>
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<td>HPOTP Turbine End BRG Flood Cool</td>
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<td>AXISYMMETRIC</td>
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<td>HPOTP R/S Interaction</td>
<td>ROTOR</td>
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<td>HPFTP Turbine Disk Cavities</td>
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<td>COMBINED HGM</td>
<td>INS3D</td>
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<td>HPFTP 2ND STG Turbine Disk Cavity/Diverter</td>
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<td>SC/HC 2ND STG Turbine Disk Cavity Diverter</td>
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<td>FLUCTUATING PRESSURE &amp; DYNAMIC LOADING</td>
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<td>Rough Surface Seal Flow</td>
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<td>NOZZLE</td>
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<td>REACT 3D</td>
<td>NOZZLE TRANSIENT AND OPERATION</td>
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<td>LPOTP 4TH STG Turbine R/S</td>
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<td>HPOTP Impeller-Diffuser Unsteady</td>
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<td>REACT 3D</td>
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<tr>
<td>HPOTP P/B Diffuser</td>
<td>REACT 2D/3D</td>
<td>TEST BED LOX FLOWMETER</td>
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<td>T/P Hardware Deviation Sensitivities</td>
<td>REACT 2D/3D</td>
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<td>To Reduce MR'S</td>
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</table>
MSFC HARDWARE RELATED ACTIVITIES
PRATT AND WHITNEY APPLICATION OF CFD TO ATD

• MOTIVATION

  — DESIGN VERIFICATION

    • CFD ANALYSIS OF CRITICAL FLOWPATHS IN SSME TURBOPUMPS
    • IDENTIFY POTENTIAL FLOWFIELD NONUNIFORMITIES, REGIONS OF SEPARATED FLOWS
    • PROVIDE DETAILED FLOW DATA TO MECHANICAL DESIGN GROUPS FOR ADDITIONAL STRUCTURAL, THERMAL ANALYSES

  — ANALYTICAL SUPPORT

    • WHERE NECESSARY, PERFORM FUNDAMENTAL CFD RESEARCH TO SUPPORT THE DESIGN VERIFICATION PROCESS
    • INCORPORATE THESE IMPROVEMENTS INTO THE DESIGN DECKS
MSFC HARDWARE RELATED ACTIVITIES
PRATT AND WHITNEY APPLICATION OF CFD TO ATD

• ACCOMPLISHMENTS
  - ANALYZED COMPLETE HOT GAS FLOW PATH
  - PROVIDED TURBINE INLET CONDITIONS
  - PROVIDED STRUT PRESSURE LOADS FOR MECH DESIGN
  - TAD CALCULATIONS RESULTED IN SUBSTANTIAL REDUCTION IN INSTRUMENTATION
  - CFD MODELS OF TAD-HGM, LOX PUMP INLET, PREBURNER AND FUEL PUMP CROSSOVER DUCTS READY FOR HOT TEST SUPPORT
  - TURBULENCE MODEL SELECTED FOR COMPLEX DUCT FLOWS
  - ARICC SUBSTANTIALLY UPGRADED
  - CAD TO CFD CAPABILITY IMPLEMENTED
  - 2D INVISCID ROTOR-STATOR INTERACTION CAPABILITY DEVELOPED AND DEMONSTRATED
NASA EARTH-TO-ORBIT PROPULSION R&T PROGRAM

PROGRAM DEFINITION

• TECHNOLOGY ACQUISITION PHASE

  – SEeks Improved understanding of the basic chemical and physical processes of propulsion

  – DEVELOPS ANALYSIS METHODS, DESIGN MODELS, AND CODES USING ANALYTICAL
    TECHNIQUES SUPPORTED BY EMPIRICAL LABORATORY DATA AS REQUIRED

  – RESULTS ARE OBTAINED THROUGH TEN DISCIPLINE WORKING GROUPS

  • BEARINGS
  • STRUCTURAL DYNAMICS
  • TURBOMACHINERY √
  • FATIGUE/FRACTURE/LIFE
  • IGNITION/COMBUSTION √

  • FLUID & GAS DYNAMICS √
  • INSTRUMENTATION
  • CONTROLS
  • MANUFACTURING/PRODUCIBILITY/INSPECTION
  • MATERIALS
NASA EARTH-TO-ORBIT PROPULSION R&T PROGRAM
PROGRAM DEFINITION

• LARGE SCALE SUBSYSTEM TECHNOLOGY VALIDATION
  — VALIDATES TECHNOLOGY EMANATING FROM THE ACQUISITION
    PHASE AT THE LARGE SCALE COMPONENT OR SUBSYSTEM LEVEL
  — THREE CATEGORIES OF EFFORT
    • LARGE SCALE COMBUSTORS ✓
    • LARGE SCALE TURBOMACHINERY ✓
    • CONTROLS AND HEALTH MONITORING

• TECHNOLOGY TEST BED VALIDATION
  — VALIDATES TECHNOLOGY EMANATING FROM THE ACQUISITION
    PHASE AT THE ENGINE SYSTEM LEVEL
  — THREE CATEGORIES OF EFFORT
    • COMBUSTORS ✓
    • TURBOMACHINERY ✓
    • CONTROLS AND HEALTH MONITORING

5-1540-9-105
NASA EARTH-TO-ORBIT PROPULSION R&T PROGRAM
WORK ELEMENT SUMMARY

• TECHNOLOGY ACQUISITION

  G2        TURBINE DRIVE COMBUSTOR DESIGN
  G29       TTB COMBUSTION MODELS
  G31       COMBUSTION CODE ENHANCEMENTS
  G32       COMBUSTION STABILITY CODE
  G33       TURBULENCE MODELS FOR COMB. ANALYSIS
  G39       ERE PREDICTION METHODS
  H6        FLUID STRUCTURE INTERACTION
  H16       VERIFICATION OF INTERNAL FLOW ANALYSIS IN 3D GEOMETRIES
  H19       EVALUATION CRITERIA FOR INTERNAL FLOW CFD NUMERICAL MODELING
  H22       ADAPTIVE COMPUTATIONAL METHOD FOR HIGH REYNOLDS NUMBER INTERNAL
            FLOWS IN ADVANCED PROPULSION SYSTEMS
  H23       DEVELOPMENT OF CONVERGENCE ACCELERATION TECHNIQUES FOR
            ALGORITHMS APPLIED TO COMPLEX 3D INTERNAL FLOWS
  H35       ADVANCED INS3D CFD CODE
  H36       CFD CONSORTIUM

• LARGE SCALE SUBSYSTEM TECHNOLOGY VALIDATION

  LSVT1     EXP. VER. OF CFD TURB. STAGE DESIGN
  LSVT4     HI PRESS TURBOMACHINERY SYS. VALIDATION
  LSVT5     3D TURBOPUMP FLOWFIELD
  LSVT6     EXP. VER. OF IMPELLER STAGE DESIGN
  LSVT10    MEASUREMENTS IN MULTI ELEMENT INJECTOR
  LSVT12    CFD TURNAROUND DUCT DESIGN VALIDATION
TECHNOLOGY TEST BED VALIDATION

- TBVC4  INJECTOR DIAGNOSTICS
- TBVC1  IMPROVED HPOTP PREBURNER PUMP
- TBVT2  ENHANCED ROTOR CODES
- TBVT3  IMPROVED BEARING COOLANT PATH
- TBVT5  WATER FLOW MODELS
- TBVT8  HGM FUEL SIDE ANALYSIS
- TBVT9  CFD DATA REDUCTION HARDWARE
- TBVT10 HPOTP JET COOLANT RING
- TBVT13 PREBURNER DOME FILLING FLOW ANALYSIS
- TBVT24 TURBINE STAGE CFD ANALYSIS AND DATA BASE FOR
          UNSTEADY AERO/HEAT TRANSFER
- TBVT25 DEV. OF UNSTEADY AERO HEAT/TRANSFER EXPERIMENTS
          DATA BASE FOR AXIAL TURBINE STAGES
- TBVT26 ADVANCED AXIAL TURBINE STAGE DESIGN METHODS
- TBVT27 ADVANCED IMPELLER DESIGN METHODS
- TBVT28 CFD ANALYSIS OF BSMT
- TBVT29 UTRC ROTOR/STATOR HEAT/TRANSFER
NASA EARTH-TO-ORBIT PROPULSION
R&T PROGRAM

CONSORTIUM OBJECTIVES

• FOCUS CFD APPLICATIONS IN PROPULSION
  • TECHNOLOGY ACQUISITION PHASE
    • DIRECT BASELINE PROGRAM TOWARDS IMPROVED ACCURACY,
      STABILITY, AND EFFICIENCY
  • LARGE SCALE SUBSYSTEM TECHNOLOGY VALIDATION
    • STIMULATE CFD VALIDATION TOWARDS PROPULSION FLOWS
    • DIRECT APPLICATIONS CODES TOWARD DESIGN TOOLS AND
      ADVANCED HARDWARE TECHNOLOGY CONCEPTS
• IDENTIFY NATIONAL CFD PROPULSION REQUIREMENTS
• STIMULATE A FORUM FOR GOVERNMENT, INDUSTRY, AND UNIVERSITY
  INTERACTIONS
• ENCOURAGE INDUSTRY TO PARTICIPATE IN CFD DEVELOPMENT WITH IRAD FUNDS
• PROVIDE SYNERGISM IN THE CFD COMMUNITY
• PROVIDE PEER REVIEW OF CFD PROGRAMS
NASA EARTH-TO-ORBIT PROPULSION
R&T PROGRAM

CONSORTIUM TASKS

- DEVELOP A PLAN TO APPLY CFD TO CURRENT AND FUTURE PROPULSION SYSTEMS
  - IDENTIFY AND RANK CRITICAL FLOW PROBLEMS RELATED TO PROPULSION SYSTEMS
  - IDENTIFY NATIONAL CFD RELATED RESOURCES
  - DEFINE HIGH PERFORMANCE COMPUTING REQUIREMENTS TO ACCOMPLISH CFD FOR PROPULSION APPLICATIONS

- DIRECT CFD TECHNOLOGY DEVELOPMENT TO PROPULSION APPLICATIONS

- ASSESS AND VALIDATE CFD APPLICATIONS IN PROPULSION SYSTEMS
  - DEVELOP EVALUATION CRITERIA
  - DEFINE AND IMPLEMENT BENCHMARK VALIDATION
  - DEFINE AND IMPLEMENT VALIDATION TESTS

- DIRECT THE APPLICATION OF CFD DESIGN TOOLS TOWARDS ADVANCED HARDWARE TECHNOLOGY CONCEPTS

- ACCELERATE THE TRANSFER OF CFD TECHNOLOGY FROM UNIVERSITIES AND RESEARCH CENTERS TO INDUSTRY AND HARDWARE DEVELOPMENT CENTERS
NASA EARTH-TO-ORBIT PROPULSION R&T PROGRAM

CONSORTIUM TEAMING

FOCUS DEVELOPMENT OF CFD METHODOLOGY
AND
DEVELOP ADVANCED HARDWARE TECHNOLOGY CONCEPTS

* TURBOMACHINERY

* DUCTS, COOLANT FLOWS, DRIVEN CAVITIES

RARIFIED GAS FLOWS

* COMBUSTION DRIVEN FLOWS

SOLID ROCKET MOTORS

* ACTIVITIES SUPPORTED BY ETO RESOURCES
VALIDATION OF TURBINE STAGE DESIGN TOOLS

RESEARCH CODE TECHNOLOGY DEVELOPMENT

H35 ADVANCED ROTOR 1 & ROTOR 2 CODES
DEVELOP CODE AT ARC

E10 MULTISTAGE TURB. FLOW SIM
3D VISCOUS CODE

H4m TURB. MODELING FOR PROTEUS TURBO. APP.
ANALYTICAL MODELING

H4a&b
SPECIAL TURBINE STAGE CFD ANALYSIS

APPLICATIONS & CODE VALIDATION

MSFC INHOUSE TURBINE STAGE BENCHMARK CFD ANALYSES

LSVT 5 3D TURBOPUMP FLOW FIELD ANALYSIS
ANALYSIS CODE ENHANCEMENT
TBVT 24, 25 TURBINE STAGES CFD UNSTEADY FLOW D.B.
AIRFLOW AT TBD CONTRACTOR

TBVT 2 ENHANCED ROTOR STATOR CODE
CODE MODIFICATION

ADVANCED CONCEPTS & DEMONSTRATION OF DESIGN TOOLS

TBVT 26 ADVANCED AXIAL TURB. DES. METHODOLOGY

H4E
3D STATOR/ROTOR BLADE FLOW EXP.

H36 (SUPPORT FROM H19, TBVT 7 & 9)
CFD CONSORTIUM-VALIDATION OF CFD ACTIVITIES-NATION WIDE

LSVTI EXP. VER OF CFD TURB. STAGE DES. METHOD
TEST RIG DESIGN & FAB
TESTING AT MSFC EATTE

LSVT23 IMP AERO H/T PREDICTION
DEV. D.B. VIA EXP. AT CALSPAN

FAB ACCEPT. TEST TEST

CONSORTIUM INTEGRATION

PERFORMANCE
NASA EARTH-TO-ORBIT PROPULSION R&T PROGRAMS
DELIVERABLE PRODUCTS/MILESTONES
TURBINE STAGES

- THREE-DIMENSIONAL MULTISTAGE CFD CODES
  - RESEARCH CODE
    - 3-D MULTISTAGE CFD CODE TO PREDICT STEADY AND
      UNSTEADY FLOW FIELD CHARACTERISTICS, PERFORMANCE,
      LOADS AND HEAT TRANSFER
  - PRODUCTION CODE
    - MODIFICATION TO RESEARCH CODE TO ENHANCE ENGINEERING
      APPLICATION
      - IMPROVED EFFICIENCIES
      - STREAMLINE PRE/POST PROCESSING ETC.

- UNSTEADY THREE-DIMENSIONAL DATA BASE FOR MULTISTAGE TURBINE
  - INITIAL UNSTEADY AERO DATA BASE
  - ENHANCED UNSTEADY AERO DATA BASE
  - HEAT TRANSFER DATA BASE

- IMPROVED FLOW PROCESS MODELING
  - TURBULENCE MODEL FOR PROTEUS
  - TURBULENCE MODEL FOR AXIAL TURBOMACHINERY

- ADVANCED CONCEPTS AND DEMONSTRATION OF DESIGN TOOLS
  - PRELIMINARY CONCEPT DEFINITION
  - TESTS
  - ADVANCED CONCEPT DEFINITION
  - FINAL RIG TEST VERIFICATION
  - HOT FIRE TEST (TTVF)

8/89

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NEW NEAR TERM CFD ACTIVITIES

STBE/STME DESIGN APPROACH FOR LOW COST

THE ALS FAMILY

![Diagram of ALS families showing Core & Booster Diameter - 30 Ft, with PAYLOAD (net MARGIN) values for ALS-L and ALS-L2.]

- DESIGN PRIORITIES
  - RELIABILITY
  - COST
  - PERFORMANCE/WEIGHT
  - COMMONALITY

- DESIGN BENEFITS
  - REDUCED INTERNAL ENVIRONMENTS
  - ROBUSTNESS
  - REDUCED DEVELOPMENT TIME
  - REDUCED INVENTORIES/INTERCHANGEABILITY
NEW NEAR TERM CFD ACTIVITIES

STME BASELINE DESIGN REQUIREMENTS

- GAS GENERATOR CYCLE, SERIES TURBINE DRIVE,
- LOX/LH2 PROPELLANTS
  CHAMBER PRESSURE = 2250 psi
- FIXED THRUST OF 580K (VAC)
- DUAL THRUST: 580K AND 435K (VAC)
- RELIABILITY = .99, 90% CONFIDENCE LEVEL (DEMONSTRATED)
- EXPENDABLE OR REUSABLE (15 CYCLES)
- GIMBAL CAPABILITY FOR TVC, +/-6 DEGREES
- FIXED NOZZLE, AR = 62:1
- USABLE IN SINGLE OR MULTI-ENGINE ARRANGEMENT
- HIGH RELIABILITY, LOW COST
NEW NEAR TERM CFD ACTIVITIES

CFD ACTIVITIES TO SUPPORT STBE/STME DESIGN

● THRUST CHAMBER
  — INJECTOR
  — MAIN COMBUSTION CHAMBER
  — NOZZLE
  — COOLING CHANNELS

● GAS GENERATOR
  — INJECTOR
  — COMBUSTION CHAMBER

● PUMPS
  — INLET FLANGE
  — VOLUTE/INDUCER/IMPELLER
  — DIFFUSER/CROSSOVER DUCTS
  — DISCHARGE COLLETOR/DUCTS
  — BEARINGS
  — SEALS

● TURBINE
  — INLET FLANGE
  — INLET MANIFOLD
  — ROTOR-STATOR INTERACTION
  — MULTISTAGE ANALYSIS
  — AIRFAILS/GUIDE VANES
  — TURBINE EXHAUST — TURN AROUND DUCT

● SYSTEM ANALYSIS
  — DUCTS
  — MANIFOLDS
  — VALVES
  — CAVITIES

● ENGINE AIRFRAME INTERACTION
  — PLUME
  — AEROHEATING/LOADS
NEW NEAR TERM CFD ACTIVITIES

ENVIRONMENTAL CONTROL AND LIFE SUPPORT SYSTEM (ECLSS)

SPACE STATION CONFIGURATION

RESPIRABLE ATMOSPHERE AND WATER REQUIREMENTS

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>UNITS</th>
<th>OPERATIONAL</th>
<th>DEGRADED</th>
<th>EMERGENCY</th>
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<tr>
<td>CO₂ PARTIAL PRESSURE</td>
<td>N/m²</td>
<td>400 MAX</td>
<td>1013 MAX</td>
<td>1600 MAX</td>
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<tr>
<td></td>
<td>(mmHg)</td>
<td>(3.0 MAX)</td>
<td>(7.6 MAX)</td>
<td>(12 MAX)</td>
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<tr>
<td>O₂ PARTIAL PRESSURE</td>
<td>N/m² x 10³</td>
<td>18.5 - 23.1</td>
<td>16.5 - 23.7</td>
<td>15.8 - 23.7</td>
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<tr>
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<td>(psia)</td>
<td>(2.83 - 3.35)</td>
<td>(2.4 - 3.45)</td>
<td>(2.3 - 3.45)</td>
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<tr>
<td>TOTAL PRESSURE</td>
<td>N/m² x 10³</td>
<td>99.9 - 102.7</td>
<td>99.9 - 102.7</td>
<td>99.9 - 102.7</td>
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<tr>
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<td>(psia)</td>
<td>(14.5 - 14.9)</td>
<td>(14.5 - 14.9)</td>
<td>(14.5 - 14.9)</td>
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<tr>
<td>TEMPERATURE</td>
<td>°K</td>
<td>291.5 - 299.8</td>
<td>291.5 - 299.8</td>
<td>288.8 - 302.6</td>
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<tr>
<td></td>
<td>(°F)</td>
<td>(65 - 80)</td>
<td>(65 - 80)</td>
<td>(60 - 85)</td>
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<td>DEWPOINT</td>
<td>°K</td>
<td>277.6 - 288.6</td>
<td>273.9 - 294.3</td>
<td>273.9 - 294.3</td>
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<td></td>
<td>(°F)</td>
<td>(40 - 60)</td>
<td>(35 - 70)</td>
<td>(35 - 70)</td>
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<td>VENTILATION</td>
<td>m³/sec,</td>
<td>.076 - .203</td>
<td>.051 - .508</td>
<td>.051 - 1.016</td>
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<td>(liters/min)</td>
<td>(15 - 40)</td>
<td>(10 - 100)</td>
<td>(10 - 200)</td>
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<td>TRACE CONTAMINANTS</td>
<td>mg/m³</td>
<td>TBD</td>
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<td>PARTICULATES</td>
<td>PARTICLES/</td>
<td>3,500,000</td>
<td>-</td>
<td>-</td>
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<tr>
<td></td>
<td>m³</td>
<td>0.5 MICROMETERS</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td></td>
<td>TBD x 150 MICROMETERS</td>
<td>-</td>
<td>-</td>
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<tr>
<td>MICRO-ORGANISMS</td>
<td>CFU/m³</td>
<td>1000</td>
<td>1000</td>
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ORIGINAL PAGE IS OF POOR QUALITY
NEW NEAR TERM CFD ACTIVITIES

CFD ACTIVITIES TO SUPPORT ECLSS

- GENERIC BASELINE CFD MODELS
  - PLANAR, ONE MODULE (NS)
  - 3D, ONE MODULE (NS)
  - 3D, INNER LOCK DUCTS (NS)
  - PLANAR INTERMODULE (NS)
  - 3D, INTERMODULE (NS)

- FLOW CONTROL DESIGN PARAMETRIC OPTIMIZATION
  - INTERNAL CONFIGURATION VARIATIONS
  - VENTILATION CONTROL
  - INTRAMODULE VENTILATION (FANS)
  - CONTAMINATION TRANSPORT
  - CO₂/FLOW MANAGEMENT
  - BODY FORCE EFFECTS

- BENCHMARK COMPARISONS
  - PARAMETRIC DESIGN OF EXPERIMENTS
  - CODE VALIDATION
CFD EXPECTATIONS

- DIRECT HARDWARE DESIGN UTILIZING CFD
  - PROVIDE INITIAL IMPACT IN DESIGN
  - PERFORM DESIGN OPTIMIZATION STUDIES
  - DEVELOP ADVANCED HARDWARE TECHNOLOGY CONCEPTS

- ESTABLISH EVALUATION CRITERIA FOR CODES AND CLASSES OF PROBLEMS

- BENCHMARKED/VALLIDATED CODES
  - LAMINAR FLOWS
  - TURBULENT FLOWS $u$, $p$
  - ACOUSTIC PROBLEMS
  - CERTAIN CLASS OF UNSTEADY PROBLEMS

- USER FRIENDLY CODES
  - B.S. LEVEL ENGINEER 2-3 YRS EXPERIENCE
  - GUIDELINES FOR CLASSES OF PROBLEMS
  - CAD/CAM/CAE; GEOMETRY GRID GENERATION
  - GENERALIZED BOUNDARY CONDITIONS
  - ALGORITHM/GRID OPTIMIZATION FOR SOLUTION EFFICIENCY
  - ARTIFICIAL INTELLIGENCE/EXPERT SYSTEMS
  - MODULAR CODES

- FLOW ADAPTIVE GRIDS FOR CURRENT CLASS OF PROBLEMS

- MULTIPLE SCALE AND/OR ZONAL TURBULENCE MODELS, MULTIPHASE, MULTISPECIES, COMBUSTION FLOW PROCESS ENGINEERING MODELS EVOLVED FROM EXPERIMENTS AND CFD ANALYSIS
Johnson Space Center CFD Overview

C. P. Li
Advanced Programs Office
Johnson Space Center, Houston, Tx 77058

Recent applications and development of CFD technology have focused on flow problems that are critically important to the operation and design of space flight vehicles. The main effort is spent on the Space Shuttle in order to provide an understanding of the cryogenic fluid in the duct connecting the External Tank and the Main Engines, the subsonic flow surrounding the Orbiter during crew egress maneuvers, the transonic aerodynamic forces on the the Orbiter fuselage and wing, the high angle-of-attack abort flight, and the aerodynamic heating during entry. To provide in-depth analyses for such diverse problems within a timely schedule, matured panel codes and a state-of-the-art incompressible turbulent flow code were adapted. Collaboration with Ames Research Center has resulted in a Shuttle ascent aerodynamic code; and a viscous chemical nonequilibrium code is being developed for predicting Orbiter real-gas aerodynamics and finite-catalytic heating. The remaining activities are devoted to the prediction of the flow environment around the Aeroassist Flight Experiment vehicle at hypersonic speeds and high altitudes. A thermochemical nonequilibrium Navier-Stokes code has been developed on the basis of two-temperature and 11-species models for solving both the shock layer and near wake. After validating the code against wind-tunnel aerodynamic, pressure and heating data, the code is being used to supplement the ground test facilities in predicting a more realistic flight environment. CFD technology is being relied upon by other programs as well in the consideration of candidate configurations. A biconic cone entering the Martian atmosphere at moderate angles of attack will be analyzed for its stability and heating distribution for the proposed mission. Capabilities of simulating the low and medium lift-to-drag vehicles flowfield, flying back from the Space Station have been demonstrated and will be enhanced to include winglets. The development of hypersonic CFD technology at JSC will continuously emphasize the modeling of radiation and ablation in continuum flow regime, sufficient realism of geometry, and efficiency of computational methods.
CFD SUPPORT FOR VARIOUS PROGRAMS

- Shuttle (MY6.5, OSF)
- Orbiter (MY2.5, OSF)
- Aeroassist Flight Experiment (MY3.5, OAST)
- Mars Rover Sample Return Mission (MY1, SE)
- Crew Rescue Escape Vehicle (MY0.25, SS)
- High-Energy Aerobraking (MY0.5, OAST)
Simulation Codes and Computers

- PANAIR, VSAERO, QUADPLAN (potential flow, panel method)
- INS3D (incompressible Navier-Stokes code)
- F3D (compressible flow NS code)
- EAGLE, SVTGD3D (grid generation codes)
- U3D (upwind finite-volume implicit method)
- NOSIP, AFTB (shock-fitting NS and Parabolized NS codes)
- VRFNS (shock-fitting, chemically reactive NS codes)
- VRFLO (shock-fitting, thermochemical nonequilibrium NS code)
- VAX8650s, SCS40 or CX200 (code development)
- Cray XMP at MSFC and CRAY 2 at NAS (engineering application)
- Class IV computer (CY89)
OUTLINE OF PRESENTATION

• Cryogenic Duct Flow Simulation by Kandula and Pearce
• Subsonic Orbiter Flow Computation by Slotnick
• Shuttle Debris Analyses by Gomez, Labbe, Martin
• Supersonic Orbiter Flow Computation and Comparison by Wey and Ma
• Hypersonic Orbiter Viscous and Reactive Flow Simulation by Li
• Biconic Cone Flow by Stuart
• AFE results by Gomez, McGary, Tam and Li
• CERV results
ANALYSIS OF ET/ORBITER DISCONNECT VALVES

- Objective:
  - to predict and correlate the hydrodynamic stability of the flappers and pressure drop with test data

- Approach:
  - Adapted and modified INS3D, SVTGD3D and INGRID
  - Compared with water test data

[Diagram of ET/ORBITER DISCONNECT VALVES]
GRID IN THE DUCT WITH FLAPPER VALVES

X-Y VIEW OF THE GRID IN THE MIDPLANE OF THE FLAPPERS

A PORTION OF X-Z VIEW OF THE GRID AT THE PLANE OF SYMMETRY
Crew Egress Aerodynamic Analysis

- **Objective:** Numerically simulate the external flowfield surrounding the various flight test vehicles so that an accurate assessment of the astronaut exit trajectories may be determined.

- **Methodology:** Use production panel code methods to compute aero characteristics.
  - Fast, efficient CFD tool
  - Appropriate for subsonic unobstructed external flow

- **Simulations:**
  - Space Shuttle Orbiter (VSAERO/PANAIR)
  - Convair C240 (QUADPAN) - Tractor Rocket Concept
  - Lockheed C-141B (QUADPAN) - Pole Concept
NUMERICAL SIMULATION OF SSLV ASCENT AERO ENVIRONMENT

- RECENT ADVANCES IN CFD ENABLE FRESH LOOK AT SPACE SHUTTLE ASCENT AERODYNAMICS
- JOINT EFFORT BETWEEN ARC TEAM (J.L. STEGER, P.G. BUNING) & JSC TEAM (F. W. MARTIN)

TEAM OBJECTIVES

- ARC: Develop the Technology to Numerically Simulate Complex Launch Vehicle Geometry
- JSC: Employ CFD Technology to Gain Insight & Understanding of the Ascent Aero Loads Environment

CFD ANALYSIS

- Complex SSLV Ascent Configuration Modelled Using "CHIMERA" Composite Grid Discretization Approach
- Overset Body-Conforming Grids Of Major Geometry Components - Communication by PEGASUS Code

CFD ANALYSIS PROGRESS HAS BEEN STEADY & PROMISING

- EFFORTS CONCENTRATED ON FULLY UPDATING SSLV CONFIGURATION GEOMETRY DETAILS
  Highest Priority Given to Attach Hardware & LOX/Fuel Feedlines
  SRB/IEA Attach Ring and SRB Plume Simulations Incorporated -- Check Out Proceeding
- ABILITY TO ACCURATELY DETERMIN WING LOADS ➔ MODEL SSLV GEOMETRY DETAILS
AERO DATABASE COMPARISONS

MID-FUSELAGE

WING UPPER SURFACE

Aero Datasets:
- NASA/Ames CFD Data (M=1.05)
- STS-5 Flight Data (M=1.05)
- IA-308A WT Data (M=1.10)
STS–27 Ascent Debris Trajectory Simulation

Mach No. 2.50
Alpha 3.00°

MSA–1 (SRB ablator) released @ 0° – 90° on nose cone
ORBITER AERODYNAMICS AT HIGH INCIDENCE ANGLES

- Objective:
  - To predict aerodynamics and flight characteristics for angles of attack up to 90 deg

- Approach:
  - Validate the U3D code with wind-tunnel data for angles of attack lower than 50 deg
  - Apply the multi-zonal U3D for higher angles-of-attack flow
ORBITER GRID AND MACH 5.2 COMPARISON
MACH 7.32 FLOW RESULTS AND GRID

MACH NUMBER

| CONTOUR LEVEL | 1  | 0.164 |
|               | 2  | 0.361 |
|               | 3  | 0.558 |
|               | 4  | 0.755 |
|               | 5  | 0.953 |
|               | 6  | 1.150 |
|               | 7  | 1.347 |
|               | 8  | 1.544 |
|               | 9  | 1.742 |
|               | 10 | 1.939 |
|               | 11 | 2.136 |
|               | 12 | 2.333 |
|               | 13 | 2.530 |
|               | 14 | 2.728 |
|               | 15 | 2.925 |
|               | 16 | 3.122 |
|               | 17 | 3.319 |
|               | 18 | 3.517 |
|               | 19 | 3.714 |
|               | 20 | 3.911 |
|               | 21 | 4.108 |
|               | 22 | 4.306 |
|               | 23 | 4.503 |
|               | 24 | 4.700 |
|               | 25 | 4.997 |
|               | 26 | 5.295 |
|               | 27 | 5.592 |
|               | 28 | 5.889 |
|               | 29 | 6.186 |
|               | 30 | 6.484 |
|               | 31 | 6.781 |
|               | 32 | 6.276 |
|               | 33 | 6.475 |
|               | 34 | 6.672 |
|               | 35 | 6.870 |

Orbiter Alone
Surface Mach No.
$M_a = 7.32$

Grid $96 \times 35 \times 51$

WEY 1/13/89
NUMERICAL INVESTIGATION OF CONTINGENCY ABORT

Orbiter Left Wing
Bottom Surface

Orbiter Left Wing
Bottom Surface

Orbiter Fuselage
Top Centerline

Orbiter Fuselage
Bottom Centerline

PRESSURE COEFF.

0.0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1.0
LENGTH

PRESSURE COEFF.

0.0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1.0
LENGTH

PRESSURE COEFF.

-1.373242 2497 3752 5008 6263 7518 8774 10029 11284 12540
LENGTH

PRESSURE COEFF.

-1.423342 2898 4054 5111 6167 7223 8279 9335 10391 11447 12503 13559
LENGTH

M_∞ 7.32
α 35.10
Y/L 0.25
t 468.34
△ E3D
○ OH10

M_∞ 7.32
α 35.10
Y/L 0.40
t 468.34
△ E3D
○ OH10

M_∞ 7.32
α 35.10
θ 180.00
△ E3D
○ OH10

M_∞ 7.32
α 35.10
θ 0.00
△ E3D
○ OH10

T. C. Wey/LESC
ORBITER ENTRY FLOW SIMULATION

• Objective:
  - To assess aerodynamic and heating issues for each flight
  - To validate the VRFNS code using flight data

• Approach:
  - Use a chemical nonequilibrium model and shock-fitting technique
  - Use a decouple technique for species
  - Compare the perfect-gas model results with wind-tunnel data
INVISCID CHEMICAL NONEQUILIBRIUM FLOW

Orbiter canopy

(b) Isotherm:

(c) Contours of nitrogen atom mass fraction.
BOW SHOCK SURROUNDING A SWEPT-WING VEHICLE
AT MACH 22 and AOA 40 WITH EQUILIBRIUM CHEMISTRY
PROJECTIONS OF TEMPERATURE CONTOURS
Comparison of shock shape with data

**MRSR aerocapture CFD**

Mach 5.997  
Alpha 27 deg  
Air  
Navier-Stokes Solution  
45 x 19 x 29 grid  
1200 iterations  
CFL 2

Wind tunnel shock locations

Flow

Mach Number Contours
12.84°/7° Biconic
Mach 6.0  Alpha 27°

Grid
Pressure
Temperature
AFE FLOWFIELD SIMULATION

• Objectives:
  – To predict aerodynamic loads and heating distributions for flight conditions
  – To define flowfield environment using appropriate physical models

• Approaches:
  – Developed the VRFLO code for typical aerobraking vehicles
  – Calibrated the code using wind-tunnel data
  – Compared the two-temp and 11-species model results with RAMC data
  – Performed sensitivity studies of different models
PHYSICAL MODELING FOR HYPersonic VEHICLES
Comparison of Shock Shapes and Subsonic Regions for an AFE Configuration

Ideal Air Mach 9.81
Ideal CF₄ Mach 6.29
Equilibrium Air Mach 32.0
COMPARISON OF FLIGHT AND WIND-TUNNEL PRESSURES

(a) Front view

(b) Rear view

Comparison of flight and wind-tunnel wall pressure distributions (the left side corresponds to the flight case).
CONTOUR PLOTS OF AFE FLIGHT FLOWFIELD
inviscid chemical nonequilibrium flow in the pitchplane

(c) z-component velocity $w\sqrt{\rho_\infty/p_\infty}$

(b) Isotherm $T/T_\infty$

(b) $N_e$
WALL PRESSURES COMPARISON AND HEATING
LOW L/D CERV

\[ P_{\text{st}} = 131.793 \]
TECHNOLOGY DEVELOPMENT

- A multi-zonal Navier-Stokes code to predict the Orbiter flow at incidence up to 90 deg
- A thermochemical nonequilibrium PNS code for high L/D configurations
- An Euler code with adaptive, unstructured grid for complex geometry
- Radiation and ablation modeling and code implementation
NASA'S CFD VALIDATION PROGRAM

by

Dale R. Satran
Program Manager
Aerodynamics Division
NASA Headquarters

With computational fluid dynamics (CFD) becoming a productive research and design tool, the requirement to validate CFD codes has grown significantly. NASA has emphasized CFD validation activities since 1986 when a separate work element was formed to fund experimental activities related to validation. NASA's CFD and CFD validation programs are closely coordinated to ensure that experimental data bases are available as soon as possible for validating codes. In response to industry and academic requirements, four levels of experimental research have been defined as part of CFD validation with NASA's Aeronautics Advisory Committee (AAC) support although only the fourth level actually has the detailed information necessary for validating codes.

Critical flow physics especially turbulence modeling are key to improved CFD codes. NASA has focused additional resources on transition and turbulence physics to meet these requirements. With improved turbulence models, CFD codes will be more accurate, robust, and efficient. However, with the level of detailed information available from CFD codes, highly accurate and detailed experiments are required to capture the critical information for validating codes. Advanced instrumentation especially non-intrusive instrumentation is required to acquire this information in validation experiments. The CFD validation program is being coordinated and managed to address these critical activities. A list of experiments which are currently being supported at least partially has been included with this presentation.
CFD CODE VALIDATION DEFINITION

CFD VALIDATION CATEGORIES

CATEGORIES OF CFD-RELATED EXPERIMENTATION

A. EXPERIMENTS DESIGNED TO UNDERSTAND FLOW PHYSICS
B. EXPERIMENTS DESIGNED TO DEVELOP PHYSICAL MODELS FOR CFD CODES
C. EXPERIMENTS DESIGNED TO CALIBRATE CFD CODES
D. EXPERIMENTS DESIGNED TO VALIDATE CFD CODES

ALL FOUR CATEGORIES ARE IMPORTANT AND ARE NECESSARY TO BUILD A MATURE CFD CAPABILITY
IMPLEMENTATION PLAN

- ALL EXPERIMENTS HAVE BEEN CLASSIFIED AND DOCUMENTED
  - GOALS
  - LIMITATIONS
  - MODELING
  - PARTICIPATION
  - LEVEL OF EFFORT

- SEVERAL KEY EXPERIMENTS INVOLVE MULTIPLE RESEARCH CENTERS

- CFD VALIDATION WORKSHOP HELD TO IDENTIFY CRITICAL NEEDS

- COORDINATING BOARD FOR CFD VALIDATION DEVELOPING UPDATED DETAILED IMPLEMENTATION PLAN

- EFFORTS INITIATED TO INVOLVE THE AEROSPACE INDUSTRY AND UNIVERSITIES
CFD VALIDATION PROGRAM

EXPERIMENTS HAVE BEEN CLASSIFIED INTO MULTIPLE CATEGORIES

<table>
<thead>
<tr>
<th>CATEGORY</th>
<th>AMES</th>
<th>LANGLEY</th>
<th>LEWIS</th>
<th>TOTAL</th>
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<td>16</td>
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<td>B. FLOW MODELING</td>
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<td>C. CODE CALIBRATION</td>
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<td>19</td>
<td>12</td>
<td>37</td>
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<tr>
<td>D. CODE VALIDATION</td>
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<td>24</td>
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<tr>
<td>TOTAL NUMBER OF EXPERIMENTS</td>
<td>27</td>
<td>45</td>
<td>29</td>
<td>101</td>
</tr>
</tbody>
</table>
CFD VALIDATION PROGRAM

- EXPERIMENTS COVER LARGE SPEED RANGE
  - SUBSONIC: 33 EXPERIMENTS
  - TRANSONIC: 27 EXPERIMENTS
  - SUPersonic: 23 EXPERIMENTS
  - HYPERSONIC: 18 EXPERIMENTS

- EXPERIMENTS FALL INTO SEVERAL VEHICLE CLASSES
  - GENERIC
  - FIGHTER/ATTACK
  - SUBSONIC TRANSPORT
  - ROTORCRAFT
  - ASTOVL
  - PROPULSION SYSTEMS
CFD VALIDATION EVENTS

- NEW RTOP ELEMENT, FLOW MODELING AND VERIFICATION, CREATED
  FY 1986
- NRC ASEB REVIEW OF CFD ACTIVITIES
  FY 1986
- NASA REVIEW AND DEVELOPMENT OF IMPLEMENTATION PLAN FOR CFD VALIDATION
  FEB., 1986
- AAC AD HOC SUBCOMMITTEE REVIEW OF CFD VALIDATION
  FY 1987
- NASA COORDINATING BOARD FOR CFD VALIDATION FORMED
  JUNE, 1987
- FIRST NASA CFD VALIDATION WORKSHOP AT AMES
  JULY, 1987
- IMPLEMENTATION PLAN REVISED BY COORDINATING BOARD
  AUG., 1987
- AGARD CFD VALIDATION CONFERENCE IN LISBON
  MAY, 1988
- CFD VALIDATION ACTIVITIES AND IMPLEMENTATION PLAN REVIEW
  NOV., 1988
- NASA CFD CONFERENCE AT AMES
  MAR., 1989
- SECOND NASA CFD VALIDATION WORKSHOP
  JULY, 1990
NASA CFD VALIDATION WORKSHOP

- 103 PERSONS ATTENDED FROM NASA, DOD, INDUSTRY, AND UNIVERSITIES

- 31 PRESENTATIONS WERE GIVEN ON CFD VALIDATION STATUS

- 6 WORKING GROUP SESSIONS FOCUSED ON NEAR AND FAR TERM NEEDS

- NUMEROUS RECOMMENDATIONS
  - STANDARDIZED TEST CASES FOR CALIBRATION
  - CLOSE COOPERATION BETWEEN CFD DEVELOPERS AND EXPERIMENTALISTS
  - INCREASE FLIGHT-BASED ACTIVITIES
  - DETAILED MEASUREMENTS OF FLOW FIELD AND BOUNDARY CONDITIONS
  - IMPROVED OR NEW NON-INTRUSIVE MEASUREMENT CAPABILITIES
  - REDUNDANCY IN BOTH MEASUREMENTS AND EXPERIMENTS
SUMMARY

- AAC AD HOC TASK TEAM RECOMMENDATIONS IMPLEMENTED
- NASA PROGRAM EXPANDING TO COVER ADDITIONAL AREAS
- INSTRUMENTATION HAS BEEN ADDED TO SEVERAL FACILITIES BY VALIDATION PROGRAM
- INCREASED EMPHASIS ON COOPERATIVE PROGRAMS WITH UNIVERSITIES AND INDUSTRY
AMES CFD VALIDATION PROGRAM FOR FY 1989

LEX/DELTA VORTICAL FLOW
TRANSONIC LOW ASPECT RATIO WING-BODY
REARWARD FACING STEP
SSME TURNAROUND DUCT
SUPERSONIC SHOCK BOUNDARY LAYER INTERACTION
COMPRESSIBLE PRESSURE-DRIVEN 3-D INTERACTIONS
2-D TRANSONIC CIRCULATION CONTROL
3-D SPIN FLOWS
3-D LOW SPEED WEDGE FLOW WITH SEPARATION
TRANSONIC SUPERCRITICAL AIRFOIL
LOW SPEED HIGH ALPHA INVESTIGATION
CFD VALIDATION FOR WING AERODYNAMICS
3-D HIGH ASPECT RATIO SEPARATED FLOW
STOVL AERO/PROPULSION INTERACTION
THERMO-CHEMICAL NONEQUILIBRIUM FLOWS
PHOTODIAGNOSTIC INSTRUMENTATION
UNSTEADY VISCOUS FLOW
HYPERSONIC SHOCK BOUNDARY INTERACTION
TURBULENT SHEAR LAYERS
TURBULENT BOUNDARY LAYERS
ALL-BODY HYPERSONIC TEST
HIGH SPEED ROTOR FLOWS
HYPERSONIC REAL GAS
SHOCK TUNNEL NOZZLE TESTS
3.5' HWT NOZZLE TESTS
COMBUSTION/DETONATION
FLIGHT/CFD CORRELATION OF F-18 WING PRESSURES AT HIGH ALPHA
HYPERSONIC VORTEX-SHOCK WAVE INTERACTION
LANGLEY CFD VALIDATION PROGRAM FOR FY 1989

TRANSONIC HIGH ASPECT-RATIO WING
TRANSONIC LOW ASPECT RATIO WING
REARWARD FACING STEP IN WATER TUNNEL
REARWARD FACING STEP IN BART
DELTA WING VORTEX FLOWS
SUPersonic COAXIAL JET
TURBULENT MODELING IN SEPARATED FLOWS
45-DEG SWEEP AIRFOIL
BARF LDV TEST
SUPersonic BOUNDARY LAYER TRANSITION
NTF FLAT PLATE TEST
VORTEX BURST EXPERIMENTS
HypersonIC FLIGHT INSTRUMENTATION
HypersonIC INLET TESTS IN HELIUM
HypersonIC SHOCK-ON-LIP
HALIS ORBITER EXPERIMENT
BLUNT BODIES (AOTV/AFE) EXPERIMENT
HypersonIC WINGED SLENDER BODY
OSCILLATING CANARD/WING UNSTEADY PRESSURES
VALIDATION OF JET PLUME MODULES
SUPersonic JET PLUME DYNAMICS
SUPersonic HIGH-ALPHA FLOWFIELD
OFF-AXIS WING-BODY STUDY
STORE/CAVITY SEPARATION EXPERIMENTS
WAVERIDER DESIGN PROCEDURE
5 DEG CONE EXPERIMENT
75/76-DEG DELTA WINGS
NTF FOREBODY/MISSILE MODEL
LEADING EDGE VORTEX FLAP
X-29 EXPERIMENT IN NTF
3-D TRANSONIC CAVITY FLOW
LOW REYNOLDS NUMBER AIRFOIL EXPERIMENTS
CONFLUENT BOUNDARY LAYER
GORTLER INSTABILITY ON AIRFOILS
EXPERIMENTAL INVESTIGATION OF TURBULENCE
RANGE AND ACCURACY OF THIN FILM ARRAYS
JUNCTURE FLOW EXPERIMENT
SWEPT SUPERCRITICAL HLFC AIRFOIL EXPERIMENTS
TWIN ENGINE AFTERBODY EXPERIMENT
LEWIS CFD VALIDATION PROGRAM FOR FY 1989

3-D SHOCK WAVE/TURBULENT BOUNDARY LAYER INTERACTIONS
3-D FLOWS IN HIGH SPEED TURBOMACHINERY
BLADE SURFACE BOUNDARY LAYER
FUNDAMENTAL SEPARATION BUBBLE RESEARCH
AIRFOIL (BLADING) FLOW CONTROL
LEADING EDGE STAGNATION REGION
BOUNDARY LAYERS IN TRANSITION
UNSTEADY HEAT TRANSFER IN ROTOR WAKES
TRANSITION DUCT - AERO & HEAT TRANSFER
VORTEX GENERATORS
SHEAR LAYER EXCITATION - JET MIXING
SHEAR LAYER EXCITATION - SLOT RESONATOR
MULTI-PHASE FLOWS
MULTI-PHASE FLOW AND FLUID SPRAY STUDY
LOW TEMPERATURE HEAT TRANSFER
FUEL SWIRLER CHARACTERIZATION
COMBUSTION CHARACTERISTICS OF HYDROCARBON FLAMES
KINETIC STUDY OF H2/O2 SYSTEM
FLOW INTERACTION EXPERIMENT
HOT GAS INGESTION
COHERENT STRUCTURES IN SUPERSONIC SHEAR LAYER
AERO CHARACTERISTICS OF AIRFOIL WITH ICE ACCRETION
TURBOMACHINERY BLADE ROW INTERACTIONS
SUPERSONIC THROUGH-FLOW CASCADE RESEARCH
CENTRIFUGAL COMPRESSOR FLOW RESEARCH
SUPERSONIC THROUGH-FLOW FAN RESEARCH
HIGH REYNOLDS NUMBER (HEAT TRANSFER)
DETAILED AERO OF ADVANCED TURBOPROPS
FUEL RICH CATALYTIC COMBUSTION
SESSION III

TRANSITION AND TURBULENCE

Chairman:
Thomas A. Pulliam
Chief, Computational Physics Section
Fluid Dynamics Division
NASA Ames Research Center
Direct simulations consist in solving the full Navier-Stokes equations, without any turbulence model, and describing all the detailed features of the flow. Usually the flows are three-dimensional and time-dependent and contain both coarse and fine structures, which makes the numerical task very challenging in terms of both the algorithm and the computational effort. Most of the work until now has involved spectral methods, which are highly accurate but not very flexible in terms of geometry or complex equations. For that reason, future work will also rely on high-order finite-difference or other methods.

Direct simulations complement experimental work, and both contribute to the theory and the empirical knowledge of turbulence. Once such a simulation has been shown to be accurate the flow field is completely known, in three dimensions and time, including the pressure, the vorticity and any other quantity. On the other hand, most simulations to date solved the incompressible equations in rather simple geometries, and direct simulations will always be limited to moderate Reynolds numbers. Extensive simulations have been conducted in homogeneous turbulence, channel flows, boundary layers, and mixing layers. Much effort is devoted to addressing flows with compressibility and chemical reactions, and to new geometries such as a backward-facing step.
UNDERSTANDING TRANSITION AND TURBULENCE
THROUGH DIRECT SIMULATIONS

P. R. Spalart & J. J. Kim

A. R. C., C. F. D. Branch, Turbulence Physics Section

- Secondary instability in channel flow.
- Stability and relaminarization of the swept attachment-line flow.
- Improvement of the pressure term in turbulence models.
- Coherent structures in homogeneous and wall-bounded shear flows.
- Lyapunov exponents of a turbulent channel flow.
- Growth of compressible mixing layers.
Secondary instability in channel flow

- Direct simulation is applied to “natural” transition; only small ($\approx 10^{-10}$) random disturbances are introduced.

- By the primary instability, a 2D TS wave grows (wavenumbers $k_x = 1$, $k_z = 0$) ($x$ streamwise). The final 3D breakdown may start as a “K” type (fundamental, $k_x = 1$, aligned $\Lambda$ vortices) or as an “H” type (subharmonic, $k_x = 1/2$, staggered $\Lambda$’s). Theory and experiments don’t fully agree in a channel.

- We find that spanwise nonuniformities ($k_x = 0$, $k_z \neq 0$) accumulate energy much larger than the initial disturbances (by a factor $Re$) and transfer some to the “K” modes before the Herbert secondary instability.

- This explains the difficulties in observing the “H” type breakdown in experiments.
Evolution of Modal Energy

"Natural" Transition in Channel

REOUT.DAT
O = Kx = 1.0 Ks = 0.0
△ = Kx = 1.0 Ks = 1.0
+ = Kx = 1.0 Ks = 2.0
X = Kx = 0.5 Ks = 1.0
○ = Kx = 0.5 Ks = 2.0

Primary 2D

Fundamental

Sub-harmonic
Stability and relaminarization of the swept attachment-line flow

- Turbulence has been found to propagate from the fuselage along the attachment line and render Laminar Flow Control impossible. This is "leading-edge contamination" (Gregory, 1960).

- Direct simulations are conducted in this region. Curvature, compressibility, and spanwise variations are neglected.

- Previous linear-stability results (Görtler & Hämmerlin, 1955, Hall, Malik & Poll, 1984) are confirmed and generalized.

- The unswept flow is found to be linearly and nonlinearly stable.

- The instability and relaminarization boundaries are computed in $(K, \bar{R})$ space, where $K$ is the suction parameter and $\bar{R}$ the Reynolds number based on strain rate and sweep velocity component. Suction has much less effect on relaminarization than on linear stability.
Critical Re at Leading Edge

- - $R_2$, linear theory
$\times$ $R_2$, direct simulation
$\Box$ $R_1$, experiments
$*$ $R_1$, direct simulation

suction $\leftarrow$ $K$ $\rightarrow$ blowing
Pressure terms in a Reynolds-stress turbulence model

- The complete budgets of the Reynolds-stress tensor and the dissipation tensor have been extracted from a direct simulation of turbulent channel flow.

- This allows one to test a turbulence model term by term, instead of as a whole (e.g., using the $C_f$).

- The published estimates for the terms that are difficult to measure experimentally (pressure, dissipation) were often very inaccurate, especially near a wall.

- As a result, the widespread $k - \epsilon$ and Reynolds-stress models incur large errors near walls.
Pressue-strain term

Figure 27. Pressure strain term, $\overline{p'u_{2.2}}$, in the budget equation for $\overline{u_2'u_2}$ across the channel. $\bigcirc$, term computed from the channel data; model, (equations (46) + (48) + (49)); model, equation (46); model, (equations (48) + (49)).
Coherent structures in shear flows

- Streaks have long been observed near the wall in boundary layers (\(y^+ < 20\)), and horseshoes away from the wall. These observations were confirmed by simulation results.

- Why the difference?

- Near the wall, the nondimensional shear rate \(S^* \equiv Sq^2/\epsilon\) takes values much larger than in the homogeneous flows that had been studied (\(q^2\): turbulent energy; \(\epsilon\): dissipation rate).

- When \(S^*\) is given such values in a homogeneous shear flow, streaks appear, indicating that the presence of a wall is not essential to form them.
Profile of $S^*$ in Boundary Layer

\[ \frac{S^2}{\varepsilon} = S^* \quad (S = \frac{\partial U}{\partial y}) \]

\[ y^+ = yU_r/\nu \quad (U_r = \sqrt{\tau_w/\rho}) \]
Velocity contours in a homogeneous shear flow
The dimension of strange attractors in turbulent shear flows

- Does a turbulent solution live on a “strange attractor”? (i.e., does its state always return to the same region, but never settle down, with almost identical initial conditions rapidly moving apart?)

- If so, chaos (nonlinear dynamics) theory may provide a new framework to unify known turbulent phenomenology and to understand the dynamics rather than the statistics of turbulence.

- Using numerical simulation of low Reynolds number turbulent channel flow we have confirmed the existence of a strange attractor by measuring its Lyapunov exponent spectrum and calculating its dimension.

- At a Reynolds number $R_\tau (\equiv \delta u_\tau /\nu)$ of 80 the dimension of the attractor is $\simeq 360$. This is the first measurement of the intrinsic complexity of a fully developed turbulent flow.

- This result shows that shear flow turbulence cannot be considered to result from the interaction of a “few” degrees of freedom.
Direct simulation of compressible (free shear) flows

• Goal: study compressibility effects on turbulent flows, in particular on their structure, global evolution, and aerodynamic noise.

• Tool: D. N. S. using high-order compact finite differences (close to spectral resolution). Compressible ideal-gas Navier-Stokes equations. No artificial viscosity or filtering.

• Example: Spatially evolving mixing layers. 2D, forced at inflow with 1% amplitude. $R \equiv \rho_1 (U_1 - U_2) \delta \omega / \mu_1 \approx 200 - 400$.

• Experiments have shown that: a) compressibility reduces the growth rate; b) it scales with the convective Mach number $M_c \equiv (U_1 - U_2)/(a_1 + a_2) (\gamma_1 = \gamma_2)$.

• Simulations have: a) reproduced this effect; b) validated $M_c$; c) provided a physical explanation.
Direct Simulation of Compressible Turbulence
T.A. Zang and G. Erlebacher
NASA Langley Research Center

M.Y. Hussaini
Institute for Computer Applications in Science and Engineering
NASA Langley Research Center

The physics of turbulence remains one of the most challenging problems in fluid dynamics. Although more than a century of effort has been devoted to it, a lot of fundamental issues are still unresolved. This is particularly so in the case of turbulence in high speed flows because of the increased number of possible mode interactions due to compressibility effects. For example, the cubic non-linearities in the momentum equations allow the vorticity, acoustic and entropy modes to interact with each other. The dynamics are further complicated by the possible existence of non-stationary shocks and/or eddy shocklets.

In this paper, several direct simulations of 3-D homogeneous, compressible turbulence are presented with emphasis on the differences with incompressible turbulent simulations. A fully spectral collocation algorithm, periodic in all directions coupled with a 3rd order Runga-Kutta time discretization scheme is sufficient to produce well-resolved flows at Taylor Reynolds numbers below 40 on grids of 128x128x128. A Helmholtz decomposition of velocity is useful to differentiate between the purely compressible effects and those effects solely due to vorticity production. In the context of homogeneous flows, this decomposition is unique. Time-dependent energy and dissipation spectra of the compressible and solenoidal velocity components indicate the presence of localized small scale structures. These structures are strongly a function of the initial conditions. We concentrate on a regime characterized by very small fluctuating Mach numbers $Ma$ (on the order of 0.03) and density and temperature fluctuations much greater than $Ma^2$. This leads to a state in which more than 70% of the kinetic energy is contained in the so-called compressible component of the velocity. Furthermore, these conditions lead to the formation of curved weak shocks (or shocklets) which travel at approximately the sound speed across the physical domain. Various terms in the vorticity and divergence of velocity production equations are plotted versus time to gain some understanding of how small scales are actually formed. Possible links with Burger turbulence are examined.

To visualize better the dynamics of the flow, new graphic visualization techniques have been developed. The 3-D structure of the shocks are visualized with the help of volume rendering algorithms developed in house. A combination of stereographic projection and animation greatly increase the number of visual cues necessary to properly interpret the complex flow. The presence or absence of shocks is automatically detected by monitoring of the minimum and maximum divergence of the velocity field over the physical domain.
NAVIER-STOKES EQUATIONS

Non-Dimensionalizations

Velocity, \( U_0\), Temperature \( T_0\), density \( \rho_0\), pressure \( \rho U_0^2\).

Viscosity and Prandl number are constant.

\[
\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0
\]

\[
\rho \frac{D \vec{v}}{Dt} = -\frac{\epsilon_p}{\gamma M_{\infty}^2} \nabla P + \frac{1}{Re} \nabla \cdot \vec{\tau}
\]

\[
\frac{DP}{Dt} = -\gamma P \nabla \cdot \vec{v} + \frac{\gamma}{\epsilon_p Pr Re} \nabla \cdot (\kappa \nabla T) + \frac{\gamma(\gamma - 1)M_{\infty}^2}{\epsilon_p Re} \vec{\tau} : \vec{\varepsilon}.
\]

\[\epsilon_p P = \rho T\]

where the stress tensors and dissipation function are defined by

\[
\vec{\varepsilon} = \frac{1}{2}(\nabla \vec{v} + \nabla \vec{v}^T),
\]

\[
\vec{\tau} = 2\mu \vec{\varepsilon} - \frac{2}{3} \mu (\nabla \cdot \vec{v}) \vec{I},
\]

and

\[
\vec{\tau} : \vec{\varepsilon} = \frac{\mu}{2}(\nabla \vec{v} + \nabla \vec{v}^T) : (\nabla \vec{v} + \nabla \vec{v}^T) - \frac{2}{3} \mu (\nabla \cdot \vec{v})^2.
\]
OBJECTIVE

• Understand if, when, and why shocks occur in homogeneous turbulence, shear layers and mixing layers in the supersonic and hypersonic regimes.

• Develop mixing enhancement strategies in supersonic shear layers (e.g. scramjets)

• The study of initial condition effects on the time-dependent characteristics of supersonic “isotropic” turbulence is the first step toward the aforementioned objectives.
PHYSICS

- Solve time-dependent, 3-D full Navier-Stokes equations
- Code set up for variable viscosity, but set to a constant
  - Pr = 0.7 (air)
- ideal gas
- no chemistry
- initial energy and thermodynamics autocorrelation spectrums identical
INITIAL CONDITIONS (1)

- Generate random $\vec{v}, \delta \rho, \delta T$ subject to
  \[
  \nabla \cdot \vec{v}_s = 0 \\
  \nabla \times \vec{v}_c = 0 
  \]

- Impose autocorrelation spectrum on $\vec{v}, \delta \rho, \delta T$
  \[
  E(k) = k^4 e^{-k^2/2k_0^2} 
  \]

- Specify rms levels for $\delta \rho, \delta T$

- Calculate
  \[
  \rho = 1 + \delta \rho \\
  T = 1 + \delta T
  \]
INITIAL CONDITIONS (2)

- Specify fluctuating Mach number $M_a$, and compute

\[ M_0^2 = \frac{u_0^2}{\gamma RT_0} \]

according to the approximate formula

\[ M_a = M_0 u_{rms} \]

- Specify initial level of compressibility

\[ \chi = \frac{\int u_c^2 dV}{\int (u_s^2 + u_c^2) dV} \]
NUMERICAL METHOD

• Fourier Collocation in both directions (periodic box)
• Conservative scheme in absence of time discretization errors
• Isotropic truncation in Fourier space at every iteration
• Splitting algorithm
  – 3rd order Runge-Kutta method in time on the explicit terms (1st step)
  – Acoustic terms treated implicitly (2nd step)
turb3d/run132

![Graph showing time series of dissipation with time on the x-axis and dissipation on the y-axis, with data points at 0.00, 1.10, 2.20, 3.30, 4.40, and 5.50 time units, and dissipation values at 0.79e-01, 0.11e-01, 0.49, 0.38, 0.27, and 0.14, respectively.]
turb3d/run132

\[ \text{\(\omega^{**2}\)} \]

\begin{tabular}{c c c c c c c c}
0.00 & 1.10 & 2.20 & 3.30 & 4.40 & 5.50 \\
\hline
3.84 & & & & & \\
3.98 & & & & & \\
4.13 & & & & & \\
4.27 & & & & & \\
4.42 & & & & & \\
4.57 & & & & & \\
4.71 & & & & & \\
4.86 & & & & & \\
5.01 & & & & & \\
5.15 & & & & & \\
5.30 & & & & & \\
\end{tabular}

time
DIVERGENCE OF VELOCITY

turb3d/run132, t=3.3, it=600
Re=150, Ma=.028, k0=1.85, urms=.1, chi=.07, rho,T=10%

CONTOUR LEVELS
-3.100000
-3.000000
-2.900000
-2.800000
-2.700000
-2.600000
-2.500000
-2.400000
-2.300000
-2.200000
-2.100000
-2.000000
-1.900000
-1.800000
-1.700000
-1.600000
-1.500000
-1.400000
-1.300000
-1.200000
-1.100000
-1.000000
-0.900000
-0.800000
-0.700000
-0.600000
-0.500000
-0.400000
-0.300000
-0.200000
-0.100000
0.000000
0.100000
0.200000
0.300000

1.000
0.00 DEG
-1.0
5.5
65x65x166

MACH
ALPHA
Re
TIME
GRID
run132, it=725, t=4
CONCLUSIONS

- Weak shocks can be generated by an initially random 2-D velocity and thermodynamic field.
- These shocks propagate at the speed of sound across the domain.
- The presence of these shocks is reflected in the structure of the compressible energy spectrum.
- Although the flow is isotropic at the onset, the compressible component of velocity quickly becomes anisotropic (as evidenced by the shock structure).
- Sophisticated visualization techniques are necessary to capture the essence of the dynamics in 3 dimensions.

Future Work

- Mixing layers with shock interactions
- Three-dimensional isotropic turbulence (in progress)
- Turbulence modeling Testing
Non Linear Evolution of a Second Mode Wave in Supersonic Boundary Layers

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Recent advances in supersonic and hypersonic aerospace technology have led to a renewed interest in the stability and transition to turbulence of high speed flows. The last 30 years have intermittently witnessed some vigorous attempts to understand some of the fundamental routes to transition for incompressible flows. While a fairly comprehensive picture of the initial stages leading to the breakdown of an incompressible laminar boundary layer has emerged (mostly under controlled conditions) the non-linear effects responsible for transition at high speeds are still very much a mystery. However, the current nonlinear incompressible theories, numerical simulations and experiments will, hopefully, serve as a guide in gaining a better understanding of the mechanisms present in the supersonic and hypersonic regimes.

Compressible linear stability theory diverges from incompressible linear stability theory in several ways. Incompressible inviscid instabilities, linked with the existence of an inflection point in the mean streamwise velocity profile are replaced by a correlation between inviscid compressible instabilities and a generalized inflection point, which brings into play the mean density profile. Furthermore, as the Mach number increases, the growth rate of the 3-D modes begin to overtake those of the 2-D modes. Beyond Mach 2.2, multiple unstable modes (at fixed Reynolds number and frequency) can coexist. The higher modes are inviscid in nature and have different behaviors with regard to wall cooling. Not only are they more unstable than their first mode counterparts (viscous in nature) above a certain Mach number, but they are destabilized by wall cooling, which is detrimental for high altitude hypersonic aircraft.

It is of vital importance that the nonlinear nature of these second mode instabilities be understood, and that their role in the context of transition be elucidated. The objective of the work is to understand the possible equilibrium state of a second mode wave, before initiating a study of 3-D wave interactions.

Two years ago, a spectral code was developed to perform direct simulations of subsonic and supersonic flows over flat plates. In this paper, we present several direct simulations of one 2-D second mode perturbation wave, superimposed upon a prescribed mean flow. Periodicity is assumed in the streamwise direction (Fourier) and the variables are expanded in Chebyshev series in the direction normal to the plate. The code is fully explicit and is time advanced with a 3rd order Runge-Kutta scheme. The second mode wave \( (Re^* = 8000) \), interacts with itself to generate higher streamwise harmonics. Physical parameters are chosen to maximize the linear growth rate at the prescribed Reynolds number. Initial results indicate that the nonlinear processes begin in the critical layer region and are the result of the cubic interactions in the momentum equations, rather than due to the higher streamwise harmonics. Analysis of the various terms in the momentum equations combined with numerical experiments in which various modes are artificially suppressed, lead to the conclusion that asymptotic methods will produce the saturated state in one or two orders of magnitude less computer time than that required by the direct numerical simulations.
CURRENT STATUS OF FLAT PLATE STABILITY AND TRANSITION

- Theory
  - Inviscid Stability Theory (Lees and Lin, 1946)
  - Linear Parallel Theory (Mack 1965)
  - Linear Non-Parallel Theory (Nayfeh and El-Hady, 1980)
  - Non-Linear Theories
    * Wave-Interactions: NONE
    * Secondary Instability: (El-Hady 1988, Ng 1988)

- Experiment
  - Stability of Supersonic Boundary Layers (Laufer and Vrebalovich 1960)

- Numerical
  - Linear Stability of real gases (equilibrium air) (Malik 1988, Macaraeg & Streett 1988)
  - Non-Linear Stability of (Erlebacher and Hussaini 1987)
PHYSICAL PARAMETERS

Non-Dimensionalization

length: $\delta^*$
$\bar{u}, \rho, T$: free-stream values
$P$: $\rho U_\infty^2$

- boundary layer flow
- ideal gas (air)
- $Pr = 0.70$, $Re = 8000$
- $M = 4.5$
- $\alpha = 2.25$, $\psi = 0^\circ$
- - linear frequency: $2.05 \implies$ period $= 3.07$
  - linear growth: $0.0215$
  - 20 periods in time gives amplification of 3.76
  - $e^9$ amplification in 136 periods
DISCRETIZATION

- Fully explicit
- $3^{rd}$ order low-storage Runga-Kutta in time
- Fourier collocation in two periodic directions (stream and span)
- Chebyshev collocation in vertical direction
- Zero normal stress boundary-conditions in the free-stream
- Continuity equation is imposed at the wall and in the far-field
- Zero temperature perturbations at the wall
MODAL ANALYSIS

\[ u \propto e^{-\omega t} \]
\[ \frac{\dot{u}}{u} \approx -i\omega \]
\[ \omega_i = \text{Real} \left( \frac{\dot{u}}{u} \right) \]
\[ \omega_r = \text{Imag} \left( \frac{\dot{u}}{u} \right) \]

Let

\[ u(x, y) = \sum_{n=-\infty}^{\infty} u_n(y, t)e^{in\alpha x} \]

After substitution into the x-momentum equation,

\[ \dot{u} = \text{linear + cubic + viscous terms} \]

where

Linear = \( i\alpha u_0 u_1 \rho_0 + \cdot \)

Cubic = \( i\alpha u_1 u_{-1} \rho_1 + \cdot \)
2nd mode run19  M=4.5
2nd mode run19 M=4.5
2nd mode run19 M=4.5

rho ampl (10)

0.00  0.10e+00
0.00  0.90e-01
0.00  0.80e-01
0.00  0.70e-01
0.00  0.60e-01
0.00  0.50e-01
0.00  0.40e-01
0.00  0.30e-01
0.00  0.20e-01
0.00  0.10e-01
0.00  0.00

y

0.00  2.00
0.00  1.60
0.00  1.20
0.00  0.80
0.00  0.40
0.00  0.00

0 periods
5 periods
10 periods
15 periods
20 periods
2nd mode run19 M=4.5
2nd mode run19  M=4.5
2nd mode run19 M=4.5

![Graph showing vorticity and dilatation for different periods.](image-url)
COST OF DIRECT SIMULATION

- The number of operations for a single iteration is approximately twice that of an incompressible direct simulation
- Acoustic effects must be treated implicitly for low Mach number simulations. At high Mach numbers, time step restrictions are a function of the Reynolds number
- Steep gradients of $u'$ and $T'$ in the critical layer increase the initial resolution
- Compressibility effects weaken the secondary instability, further increasing the required computer time to capture the initial stages of breakdown
- Cost can decrease with use of static or dynamics adaptive grids, or multidomain decompositions in the vertical direction

⇒ VERY EXPENSIVE !!!
25 periods on $8 \times 2 \times 65$ grid: 10 CPU hrs on Cray II at 100 Mflops average yields factor 4 amplification
CONCLUSIONS

- Compressible boundary-layer code is suitable for the study of second modes, albeit is still very expensive due to the slow growth and high spatial and temporal frequencies of the instabilities.

- Non-linearities (not due to higher streamwise harmonics) induces strong growth rate departures from the linear values in the critical layer region. The actual cause is still unknown.

- Density perturbations probably play (as expected) a fundamental role in the development of the non-linear saturated state. Further information awaits more detailed considerations of intermodal energy transfers.
NUMERICAL SIMULATION OF NONLINEAR DEVELOPMENT OF INSTABILITY WAVES

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and

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SUMMARY

The present work is concerned with the nonlinear interactions of high amplitude instability waves in turbulent jets. In plane shear layers Riley and Metcalf (1980) and Monkewitz (1987) have shown that these interactions are dependent, among other parameters, on the phase-difference between the two instability waves. Therefore, in the present work we consider the nonlinear development of both the amplitudes and the phase of the instability waves. The development of these waves are also coupled with the development of the mean flow and the background turbulence. In formulating this model it is assumed that each of the flow components can be characterized by conservation equations supplemented by closure models. Results for the interactions between the two instability waves under high-amplitude forcing at fundamental and subharmonic frequencies are presented here. Qualitative agreements are found between the present predictions and available experimental data.

CONSERVATION EQUATIONS

Each flow component is split in the form:

\[ \mathbf{U}_i(x, r, t) = \mathbf{\bar{U}}_i(x, r) + \tilde{\mathbf{U}}_i(x, r, t) + \mathbf{u}_i(x, r, t) \]

\( \mathbf{\bar{U}} \) is the time-averaged mean flow velocity which is taken to be given by the two-stage hyperbolic tangent profile. \( \tilde{\mathbf{U}} \) is the periodic component which is split into two frequency-components in the form:

\[ \tilde{\mathbf{U}}_i = A_1 \mathbf{\hat{u}}_i(x, r, \theta) e^{i \phi_1(x) - i \omega_1 t} + A_2 \mathbf{\hat{u}}_i(x, r, \theta) e^{i \phi_2(x) - i \omega_2 t} + \text{c.c.} \]

\( \mathbf{\hat{u}} \) is the radial shape taken as the eigen-function solution of the locally-parallel linear stability equation for each frequency-component. \( A \) and \( \phi \) are the amplitude and phase to be obtained from the nonlinear interaction equations, and \( \theta \) is the momentum thickness \( u' \) is the turbulence component which is related to the turbulence-energy through an assumed Gaussian profile.

THE NONLINEAR INTERACTION EQUATIONS

Time-averaging and phase-averaging techniques are applied to the full unsteady Navier-Stokes equations to derive the governing equations for each
These equations are manipulated to obtain nonlinear equations for the amplitudes $A_1$, $A_2$, phases $\phi_1$, $\phi_2$, momentum thickness $\theta$ and the turbulence energy $T$:

**Mean flow**

$$\frac{1}{2} \frac{d}{dx} \left[ \frac{d}{d\theta} A_1 - \frac{d}{d\theta} A_2 \right] = -I_{mt} T - I_{om} A_1^2 - I_{2\omega} A_2^2$$

**Turbulence**

$$\frac{d}{dx} \left[ I_{\omega} T \right] = I_{mt} T + I_{\omega} A_1^2 T + I_{2\omega} A_2^2 T - \frac{I}{\varepsilon} T^{3/2}$$

**$\omega$-component**

$$\frac{d}{dx} \left[ I_{\omega} A_1^2 \right] = I_{\omega} A_1^2 - I_{\omega} A_1^2 T + I_{2\omega} A_2^2 \cos(2\phi_1 - \phi_2 - \phi_0 + \sigma)$$

$$I_{\omega} \frac{d\phi_1}{dx} = \pi S_{\omega} + I^*_{\omega} + A_1 I_{2\omega} \sin(2\phi_2 - \phi_2 - \phi_0 + \sigma)$$

**$2\omega$-component**

$$\frac{d}{dx} \left[ I_{2\omega} A_2^2 \right] = I_{2\omega} A_2^2 - I_{2\omega} A_2^2 T - I_{2\omega} A_2^2 A_1^2 \cos(2\phi_2 - \phi_2 - \phi_0 + \sigma)$$

$$I_{2\omega} \frac{d\phi_2}{dx} = \pi S_{2\omega} + I^*_{2\omega} - A_2 A_1^2 I_{2\omega} \sin(2\phi_2 - \phi_2 - \phi_0 + \sigma)$$

The integrals $I$ appearing in the above equations are functions of $\Theta$, frequencies, and the closure assumptions. $S$ is the Strouhal number defined as $\omega d/(2\pi U)$. The solution of the above system of equations is subject to the initial conditions at $x = 0$: $\theta_0$, $T_0$, $A_{10}$, $A_{20}$, and $\phi_0$.

**RESULTS AND DISCUSSIONS**

The calculated fundamental and subharmonic components at Strouhal numbers 0.3 and 0.6 are shown in figure 1 for several initial phase angles. The initial momentum thickness is 0.026 $R$, initial turbulence energy levels is 0.0001 the initial energies of the fundamental and subharmonic are taken such that the initial instability velocity components at the jet centerline are 1.2 and 0.6 percent, respectively. Figure 1 shows that the fundamental is not sensitive to the phase-difference as much as the subharmonic does. Bradley and Ng's (1989) measured integral spectral amplitude shows similar features. The fundamental is less dependent than the subharmonic on the phase angle. Maximum subharmonic amplification occurs at $\phi_2 = 180^\circ$ and minimum subharmonic's amplification occurs at $\phi_0 = 0^\circ$, same as the present results in figure 1(b).

The calculated centerline phase-averaged velocities are shown in figure 2 in comparison with the data of Arbey and Ffowcs-Williams (1984). The Strouhal
numbers are 0.3 and 0.6, the initial turbulence energy level is 0.00001, initial momentum thickness is 0.012. The initial centerline velocity of the S = 0.3 component is taken 1.5 percent and that of the S = 0.6 is 0.38 of the S = 0.3 component as in the experiment. At S = 0.3, figure 2(a) shows that calculate peak occurs further downstream as compared to the measured ones. However, the calculated peak has the same level as the measured one. The peak increases when $\phi_0$ is changed from 0 to $180^\circ$, as the present computations also predict. The calculated phase averaged velocities at S = 0.6 shown in figure 2(b) has the same features as the measured one; same level of amplification and same dependency on $\phi_0$. The measured component increases again after it decays which is probably due to its interaction with other frequency components. This mechanism is not accounted for here.

The dependency of the subharmonic amplification on the initial phase angle is shown in figure 3 for Strouhal numbers 0.2 and 0.4. The initial levels are $\bar{u}_f = 7$ percent, $\bar{u}_0 = 0.5$ percent. The peak of the subharmonic at $\phi_0 = 270^\circ$ is three times higher than its peak at $\phi_0 = 90^\circ$. The corresponding momentum thickness is shown in figure 4, compared to the unexcited momentum thickness. The figure shows that the momentum thickness is only weakly dependent on the phase angle. This indicates that the direct role of the subharmonic in turbulent jets in controlling the mixing is less pronounced as compared to its role in controlling the mixing in laminar jets. However, the subharmonic can still have a strong role in the mixing process through enhancing the background turbulence which in turn increases the mixing.

If both the fundamental and subharmonic's initial levels are high, the dependency on the phase angle is less pronounced as figure 5 indicates. The Strouhal numbers are 0.3 and 0.6 and the initial levels are $\bar{u}_f = \bar{u}_s = 3$ percent. At high initial levels, large energy levels are drained from the mean flow and therefore the fundamental-subharmonic energy exchanges are relatively smaller and consequently less pronounced.

The effect of the forcing level at a fundamental frequency of S = 0.4 on the subharmonic's amplification is shown in figure 6. The figure shows that the peak of the subharmonic increases with increasing the forcing level. However, a saturation condition occurs around a forcing level of 10 percent. Higher forcing levels result in no further increase of the subharmonic's peak over 20 percent.

REFERENCES


DEPENDENCY OF THE STABILITY COMPONENTS ON THE INITIAL PHASE ANGLES

Figure 1

(a) $S = 0.6$

(b) $S = 0.3$

$A^2/A_0^2$

$x/d$
Figure 2

DEPENDENCY OF SUBHARMONIC'S AMPLIFICATION ON THE INITIAL PHASE-ANGLE AT STROUHAL NUMBERS OF 0.4 AND 0.2
DEVELOPMENT OF THE MOMENTUM THICKNESS UNDER TWO-FREQUENCY EXCITATION AND FOR THE UNEXCITED CASE
Figure 5

DEPENDENCY OF THE SUBHARMONIC'S PEAK ON THE PHASE-ANGLE AT HIGH LEVELS BOTH THE FUNDAMENTAL AND THE SUBHARMONIC

\[ \frac{U_{sp}}{U_j} \]

\[ \Phi_0 \]
DEPENDENCY OF THE SUBHARMONIC'S PEAK ON THE FORCING LEVEL AT STROUHAL NUMBERS OF 0.2 AND 0.4
More Accurate Predictions with Transonic Navier-Stokes
Methods Through Improved Turbulence Modeling

by

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Because the aerodynamic characteristics of aircraft in the transonic regime are so sensitive to viscous effects, the selection of the turbulence model for a transonic prediction method is no less important than the selection of the numerical algorithm. Yet, the usual practice in transonic airfoil, Reynolds-Averaged, Navier-Stokes codes has been to employ "equilibrium" algebraic turbulence models. Satisfactory results are obtained with these turbulence models for weak interaction cases (i.e., cases where the upper surface shock wave is too weak to have a major effect on the turbulent boundary layer). Such is not the situation for cases where the shock wave is sufficiently strong to cause separation. The danger in using these "equilibrium" turbulence models for airfoil design is that they can result in unduely optimistic projections of aircraft performance at off-design conditions.

Significant improvements in predictive accuracies for off-design conditions are achievable through better turbulence modeling; and, without necessarily adding any significant complication to the numerics. One well established fact about turbulence is it is slow to respond to changes in the mean strain field. With the "equilibrium" algebraic turbulence models no attempt is made to model this characteristic and as a consequence these turbulence models exaggerate the turbulent boundary layer's ability to produce turbulent Reynolds shear stresses in regions of adverse pressure gradient. As a consequence, too little momentum loss within the boundary layer is predicted in the region of the shock wave and along the aft part of the airfoil where the surface pressure undergoes further increases.

Recently, a "nonequilibrium" algebraic turbulence model was formulated which attempts to capture this important characteristic of turbulence. This "nonequilibrium" algebraic model employs an ordinary differential equation to model the slow response of the turbulence to changes in local flow conditions. In its original form, there was some question as to whether this "nonequilibrium" model performed as well as the "equilibrium" models for weak interaction cases. However, this turbulence model has since been further improved wherein it now appears that this turbulence model performs at least as well as the "equilibrium" models for weak interaction cases and for strong interaction cases represents a very significant improvement.

The performance of this turbulence model relative to popular "equilibrium" models is illustrated for three airfoil test cases of the 1987 AIAA Viscous Transonic Airfoil Workshop, Reno, Nevada. A form of this "nonequilibrium" turbulence model is currently being applied to wing flows for which similar improvements in predictive accuracy are being realized.
TRANSONIC FLOW TURBULENCE MODELING
AIRFOIL AND WING FLOWS

WHY BE CONCERNED ABOUT THE TURBULENCE MODEL?

- NUMERICAL PREDICTIONS CAN BE EXTREMELY SENSITIVE TO TURBULENCE MODEL IN TRANSONIC REGIME

- WIDELY USED EQUILIBRIUM ALGEBRAIC TURBULENCE MODELS OVERPREDICT AIRCRAFT PERFORMANCE
NONEQUILIBRIUM JOHNSON-KING
ALGEBRAIC TURBULENCE MODEL

• SLOW RESPONSE OF TURBULENT SHEAR STRESS TO
  CHANGES IN STRAIN FIELD MODELED

• ORDINARY DIFFERENTIAL EQUATION FOR MAXIMUM
  REYNOLDS SHEAR STRESS ESTABLISHES EDDY VISCOSITY
  (SIMPLIFIED "REYNOLDS STRESS" MODEL?)

• DUE TO RECENT IMPROVEMENTS, MODEL PERFORMS BETTER
  FOR ATTACHED FLOW CASES (SURPRISINGLY, ORIGINAL
  MODEL WORKED BETTER FOR STRONGLY SEPARATED CASES)
SURFACE PRESSURE COEFFICIENT AXISYMMETRIC BUMP

CLOSEUP MODEL
- PRESENT
- JONES-LAUNDER
- CEBECI-SMITH
- EXPERIMENT
  S SEPARATION
  R REATTACHMENT
REYNOLDS SHEAR STRESS PROFILES
AXISYMMETRIC BUMP, $M_\infty = 0.875$

- EXPERIMENT
- PRESENT MODEL

$y$, cm

$x/c = 0.63$, $0.69$, $0.75$, $0.81$, $0.88$

$-\overline{u'v'}/u_\infty^2 \times 10^3$
MAXIMUM REYNOLDS SHEAR STRESS DISTRIBUTIONS

CLOSURE MODEL
- PRESENT
- JONES-LAUNDER
- CEBECI-SMITH

$M_\infty = 0.6$

$\overline{-u'v'}/U_\infty^2 \times 10^3$

$X/C$

$M_\infty = 0.875$
IMPROVEMENTS IN JOHNSON-KING MODEL

NEW INNER EDDY VISCOITY EXPRESSION

- BETTER SATISFIES "LAW OF THE WALL" FOR ATTACHED ADVERSE PRESSURE GRADIENT CONDITIONS (ORIGINAL MODEL OVERPREDICTED $C_f$ DOWNSTREAM OF SHOCK WAVE)

- INCLUDES VELOCITY SCALE WHICH ACCOUNTS FOR COMPRESSIBILITY
IMPROVEMENTS IN JOHNSON - KING TURBULENCE MODEL FOR WEAK SHOCK WAVE/BOUNDARY LAYER INTERACTIONS

RAE 2822, $M_{\text{exp}} = 0.729$, $\alpha_{\text{exp}} = 3.19^\circ$

<table>
<thead>
<tr>
<th></th>
<th>$C_L$</th>
<th>$C_D$</th>
</tr>
</thead>
<tbody>
<tr>
<td>EXP</td>
<td>0.803</td>
<td>0.0168</td>
</tr>
<tr>
<td>OLD J-K</td>
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</tr>
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<td>NEW J-K</td>
<td>0.828</td>
<td>0.0170</td>
</tr>
<tr>
<td>C-S</td>
<td>0.825</td>
<td>0.0170</td>
</tr>
</tbody>
</table>

$M_{\text{comp}} = 0.730$, $\alpha_{\text{comp}} = 2.80^\circ$

![Graph showing drag and lift coefficients for different models.](image-url)
ATTACHED AIRFOIL CASE
RAE 2822, $M_{\text{exp}} = 0.73$, $\alpha_{\text{exp}} = 3.19^\circ$

CEBECI-SMITH "EQUILIBRIUM" MODEL
$M_{\text{comp}} = 0.734$
$C_L = 0.801 \ (0.803)$
$C_D = 0.0169 \ (0.0169)$

JOHNSON-KING "NON-EQUILIBRIUM" MODEL
$\alpha_{\text{comp}} = 2.65^\circ$
$C_L = 0.804 \ (0.803)$
$C_D = 0.0169 \ (0.0169)$
SEPARATED AIRFOIL CASE

RAE 2822, $M_{\text{exp}} = 0.75$, $\alpha_{\text{exp}} = 3.19^\circ$

**Baldwin-Lomax “Equilibrium” Model**

- $M_{\text{comp}} = 0.758$
- $C_L = 0.837$ (0.743)
- $C_D = 0.0312$ (0.0242)

**Johnson-King “Non-Equilibrium” Model**

- $\alpha_{\text{comp}} = 2.70^\circ$
- $C_L = 0.739$ (0.743)
- $C_D = 0.0254$ (0.0242)
SEPARATED AIRFOIL CASE
NACA 0012, $M_{exp} = 0.8$, $\alpha_{exp} = 2.86^\circ$

**Baldwin-Lomax "Equilibrium" Model**
- $M_{comp} = 0.785$
- $C_L = 0.466 (0.390)$
- $C_D = 0.0372 (0.0331)$

**Johnson-King "Nonequilibrium" Model**
- $\alpha_{comp} = 2.26^\circ$
- $C_L = 0.388 (0.390)$
- $C_D = 0.0329 (0.0331)$
SUMMARY

SIGNIFICANT IMPROVEMENTS IN PREDICTIVE ACCURACY WITH NONEQUILIBRIUM ALGEBRAIC TURBULENCE MODEL

PRESENT APPROACH IS TO MODEL MOST RELEVANT PHYSICS WHILE MAINTAINING MATHEMATICAL SIMPLICITY

NEGLIGIBLE INCREASE IN COMPUTATIONAL EFFORT COMPARED TO EQUILIBRIUM ALGEBRAIC TURBULENCE MODELS
SESSION IV

CFD CODES

Chairman:
Jerry C. South, Jr.
Head, Analytical Methods Branch
NASA Langley Research Center
RECENT ADVANCES IN RUNGE-KUTTA SCHEMES FOR SOLVING 3-D NAVIER-STOKES EQUATIONS

By

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NASA Langley Research Center

Bruce W. Wedan, Ridha Abid

Abstract

A thin-layer Navier-Stokes has been developed for solving high Reynolds number, turbulent flows past aircraft components under transonic flow conditions. The computer code has been validated through data comparisons for flow past isolated wings, wing-body configurations, prolate spheroids and wings mounted inside wind-tunnels. The basic code employs an explicit Runge-Kutta time-stepping scheme to obtain steady state solution to the unsteady governing equations. Significant gain in the efficiency of the code has been obtained by implementing a multigrid acceleration technique to achieve steady-state solutions. The improved efficiency of the code has made it feasible to conduct grid-refinement and turbulence model studies in reasonable amount of computer time. The non-equilibrium turbulence model of Johnson and King has been extended to three-dimensional flows and excellent agreement with pressure data has been obtained for transonic separated flow over a transport type of wing.
OBJECTIVES

- Develop an efficient Navier-Stokes code for high Reynolds number, transonic, separated flows
- Assess the effect of grid refinement
  - on solution accuracy
  - on convergence properties
- Improve turbulence model for separated flows by including non-equilibrium effects
- Validate the code via data comparisons
GOVERNING EQUATIONS

- Reynolds-averaged Navier-Stokes equations
- Thin-layer approximation
- Equations are written in conservation law form
- Turbulence models
  - Equilibrium model: Baldwin-Lomax model
  - Non-equilibrium model: Johnson-King model
BOUNDARY CONDITIONS

- Solid surface: viscous
  - no slip and zero injection
  - zero normal pressure gradient
  - specified temperature or adiabatic condition
- Solid surface: inviscid
  - zero flux across surface
  - extrapolate surface pressure
- Inflow/outflow: free-air
  - Riemann invariants for farfield
  - extrapolate all variables at downstream
- Inflow/outflow: in-tunnel simulations
  - Riemann invariants at inflow
  - specify initial profile for viscous sidewall
  - specify pressure and extrapolate other variables at downstream
NUMERICAL ALGORITHM

- Based on Runge-Kutta schemes of Jameson and co-workers: 5-stage scheme with 3 dissipation evaluations
- Finite volume, central-difference scheme
- Non-isotropic artificial dissipation added for stability
- Variable coefficient, grid aspect-ratio dependent, implicit residual smoothing for increasing stability bound
- Multigrid acceleration technique
  - Full multigrid (FMG) strategy
  - V-cycle (saw-tooth)
  - Viscous fluxes evaluated only on fine mesh
Effect of grid refinement on convergence

history for ONERA M6 wing

( \( M_\infty = 0.84, \alpha = 6.06^\circ \) )

Baldwin-Lomax Turbulence Model

193x65x33 grid

289x65x49 grid
Effect of grid refinement on pressure distributions for ONERA M6 wing

\( M_\infty = 0.84, \alpha = 6.06^\circ \)

Baldwin-Lomax Turbulence Model

- Experimental data
- 193x65x33 grid results
- 289x65x49 grid results

\( C_P \) vs \( X/C \) for
- \( 2Y/B = 0.440 \)
- \( 2Y/B = 0.650 \)
Effect of grid refinement on pressure distributions for ONERA M6 wing

( $M_\infty = 0.84$, $\alpha = 6.06^\circ$ )

Baldwin-Lomax Turbulence Model

- Experimental data
- 193x65x33 grid results
- 289x65x49 grid results

![Graphs showing pressure distributions for different grid refinements and aspect ratios](image)
Convergence history for ONERA M6 wing
with Johnson-King model, 289x65x49 grid

\( \text{M}_\infty = 0.84, \alpha = 6.06^\circ \)
Effect of turbulence model on pressure contours for ONERA M6 wing

( $M_\infty = 0.84$, $\alpha = 6.06^\circ$ )

Upper surface, 289x65x49 grid

Johnson-King

Baldwin-Lomax
Effect of Turbulence Model
ONERA M6 Wing

M = 0.84, AOA = 6.06 deg, Re = 11.7 million

Baldwin–Lomax

Johnson–King
Effect of turbulence model on pressure distributions for ONERA M6 wing

\( M_\infty = 0.84, \alpha = 6.06^\circ \)

289x65x49 grid computations

- ○ Experimental data
- ---- Baldwin-Lomax results
- --- Johnson-King results
Effect of turbulence model on pressure distributions for ONERA M6 wing

\( M_\infty = 0.84, \alpha = 6.06^\circ \)

289x65x49 grid computations

- ○ Experimental data
- - - Baldwin-Lomax results
- --- Johnson-King results

\( C_p \)

2Y/B = 0.800

2Y/B = 0.900

X/C
CONCLUDING REMARKS

- Significant gains in efficiency are achieved through multigrid acceleration technique
- Grid-convergence studies feasible due to improved efficiency
- Baldwin-Lomax model gives good solutions for attached flows, but is found inadequate for separated flows
- Johnson-King model results in improved comparison with data for separated flows
- Block-structured grids must be employed for more efficient use of mesh points and for computing more complex configurations
COMPUTATIONS OF THREE-DIMENSIONAL STEADY AND UNSTEADY VISCOUS INCOMPRESSIBLE FLOWS

Dochan Kwak, Stuart E. Rogers
NASA Ames Research Center

Seokkwan Yoon, Moshe Rosenfeld, and Leon Chang
MCAT Institute

The INS3D family of computational fluid dynamics computer codes is presented. These codes are used to as tools in developing and assessing algorithms for solving the incompressible Navier-Stokes equations for steady-state and unsteady flow problems. This work involves applying the codes to real-world problems involving complex three-dimensional geometries. The algorithms utilized include the method of pseudocompressibility and a fractional step method. Several approaches are used with the method of pseudocompressibility including both central and upwind differencing, several types of artificial dissipation schemes, approximate factorization, and an implicit line-relaxation scheme. These codes have been validated using a wide range of problems including flow over a backward-facing step, driven cavity flow, flow through various type of ducts, and steady and unsteady flow over a circular cylinder. Many diverse flow applications have been solved using these codes including parts of the Space Shuttle Main Engine, problems in naval hydrodynamics, low-speed aerodynamics, and biomedical fluid flows. The presentation details several of these including the flow through a Space Shuttle Main Engine inducer, vortex shedding behind a circular cylinder, and flow through an artificial heart.
OUTLINE

- Objective and Approach

- Summary of Flow Codes
  - INS3D Family of codes
  - CENS3D

- Applications and Results
  - Space Shuttle Main Engine (SSME) components
  - Artificial Heart Flow

- Summary and Future Work

- Movie
  - Circular cylinder vortex shedding
  - Artificial heart flow
OBJECTIVE AND APPROACH

Objective
- To develop CFD capability for simulating steady and unsteady viscous incompressible flows (Incompressible Navier-Stokes)

Approach
- Develop and assess algorithms, and implement in codes
- Develop / implement physical models for engineering analysis (turbulence, cavitation, porous medium, etc.)
- Apply the codes to real-world problems
SUMMARY OF INS3D

- Governing equations
  - Incompressible Navier-Stokes equations in generalized 3-D coordinates for steady-state solutions
  - Pseudocompressibility approach

- Numerical scheme
  - Finite difference, central differencing plus artificial dissipation
  - Approximate Factorization
  - Single or multiple zones

- Turbulence Models
  - Algebraic models
  - $k - \varepsilon$ model

- Applications
  - Numerous SSME related simulations

- Status
  - Distributed to numerous users across the nation
  - Available through COSMIC
EXTENSIONS TO INS3D

INS3D family of research codes used to study various approaches to solving the INS equations in generalized 3-D coordinates

Pseudocompressibility Approach

INS3D-UP (Steady-State and Time-accurate calculations)
- Upwind flux-difference splitting of uniformly high order
- Line-relaxation implicit scheme
- Characteristic boundary conditions

INS3D-LU (Steady-State and Rotating reference frame)
- Finite-volume method
- Spectral radius or flux-difference split based dissipation
- LU-SGS Implicit Scheme
- Non-reflecting boundary conditions
- Completely vectorized
EXTENSIONS TO INS3D, continued

Fractional Step Approach

- INS3D-FS (Time-accurate problems)
  - Finite-volume method on a staggered mesh
  - Accurate treatment of geometry
    $\Rightarrow$ Exact discrete mass conservation
  - Two-step fractional step method:
    Solve momentum equations in time (AF scheme)
    Correct for pressure and velocity (Poisson equation)
SUMMARY OF CENS3D CODE

○ Governing Equations
  - Compressible Euler and Navier-Stokes equations and species transport equations in generalized 3-D coordinates

○ Numerical Methods
  - Fully-coupled and implicit thermal-chemical nonequilibrium finite-rate-chemistry
  - Finite volume / flux-limited TVD, optional high-order flux difference split upwind scheme
  - LU-SGS implicit scheme

○ Applications
  - SSME preburner, main combustor and nozzle

○ Status
  - Research code
VALIDATION CASES

○ INS3D
  • Internal flow : Channel, Backward-facing step, Rectangular duct, Turn-around duct
  • External flow : Circular cylinder (steady-state), Ogive cylinder
  • Juncture flow : Cylinder-plate, Wing-plate, Cavity

○ INS3D-UP
  • Internal flow : Driven cavity, Backward-facing step, Square duct with a 90° bend
  • External flow : Oscillating plate, Circular cylinder (steady and vortex-shedding flows)

○ INS3D-FS
  • Internal flow : Driven cavity
  • External flow : Impulsively started circular cylinder, vortex shedding from a circular cylinder
SUMMARY OF APPLICATIONS

○ Space Shuttle Main Engine (SSME)
  (NASA/MSFC, Rocketdyne)
  • Hot Gas Manifold, Main Injector
  • Bearing
  • Impeller/Inducer
  • Preburner

○ Artificial Heart / Biofluid Mechanics
  (NASA Tech Utilization, Penn State Univ and Stanford Univ)

○ Low Speed Aerodynamics
  • High lift device
  • External flow over Automobiles and Trucks

○ Naval Hydrodynamics (Submarine)
  (DARPA, ONR and David Taylor Research Center)
Particle Traces for SSME Inducer (INS3D–LU)
Surface Pressure for SSME Inducer
(INS3D-LU)
FLOW OVER A CIRCULAR CYLINDER AT RE = 105

Computation

Experiment
ARTIFICIAL HEART

- Current artificial devices have problems stemming from fluid dynamic phenomena
  - High shear stress damages the red blood cells and arterial walls
  - Stagnation and secondary flow regions lead to clotting
  - Desire short residence time in artificial environment
  - Large pressure losses cause heart to work harder

- Apply CFD technology to analyzing blood flow through artificial hearts and to suggest improved design
  - Develop moving boundary capability
  - Apply time accurate flow solvers to Penn State Artificial Heart
  - Develop simple non-Newtonian fluid model
Penn State Artificial Heart – INS3D-UP Code

Computation

Experiment

BLACK AND WHITE PHOTOGRAPH

ORIGINIAL PAGE IS OF POOR QUALITY
CONCLUDING REMARKS

☉ Incompressible and low speed flow simulation codes have been developed (INS3D-xx, CENS3D).

☉ Results of computer simulations have made significant impact on analysis and redesign of the SSME power head.

☉ These codes are being extended to analyze other important real world problems.

☉ Future work includes further enhancement of these codes and improvement in physical modeling.
SAGE

A 2-D Self-Adaptive Grid Evolution Code and its Application in Computational Fluid Dynamics

by

Carol B. Davies¹, Ethiraj Venkatapathy² and George S. Deiwerk³

Abstract

SAGE is a user-friendly, highly efficient, 2-dimensional self-adaptive grid code based on Nakahashi & Deiwerk's variational principles method. Grid points are redistributed into regions of high flowfield gradients while maintaining smoothness and orthogonality of the grid. CPU efficiency is obtained by splitting the adaption into 2 directions and applying one-sided torsion control, thus producing a 1-D elliptic system that can be solved as a set of tridiagonal equations.

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² Elorot Institute, Sunnyvale, Ca.
³ Chief, Aerothermodynamics Branch, NASA Ames Research Center, Moffett Field, Ca.
Outline of Presentation

- Brief Description of Self-Adaptive Method (based on Nakahashi & Deiwert's variational principles scheme.)

- SAGE code features, including input parameters.

- Application of SAGE to various flow problems:
  - Hypersonic blunt body
  - Supersonic shock impingement
  - Hypersonic inlet with cowl
  - Supersonic plume flow
  - Supersonic inlet
Self-Adaptive Grid Method of Nakahashi & Deiwert

Objective: to redistribute points into regions of high flow gradients (utilizing minimization principles) while maintaining smoothness and orthogonality between adapted lines. The technique is analogous to connecting each node by tension and torsion springs and locating the equilibrium position of the resulting system.
Adaption Equation

Splitting the adaption into 2 directions and applying one sided torsion control reduces the problem to the following 1-D elliptic system which can be solved as a tridiagonal system of equations:

\[ \omega_i \Delta s_{i+1} + \omega_{i-1} \Delta s_i - C_i \theta_i = 0 \]

where:
- tension spring constants, \( \omega_i = 1 + A f_i^B \)
- \( f_i = f(\text{gradient of } Q_i) \) \{ error measure \}
- self-adaptive mesh size controlled by \( A \) and \( B \):
  - \( A = \Delta s_{max}/\Delta s_{min} - 1 \), \( B \) enforces computed \( \Delta s_{min} = \Delta s_{min} \)
- torsion spring constant, \( C_i = f(\omega_i, \lambda_i, \text{cell aspect ratio}) \)
- and \( \theta_i = f(C_i, \text{smoothness, orthogonality}) \)
SAGE Input Parameters

Control parameters:

\[ \lambda, \ C_t, \ \Delta s_{\text{min}} \text{ and } \Delta s_{\text{max}} \]

Adaption parameters:

Limits of adaption domain.
Stepping direction.
Adaption variable (or combination or user defined).
Boundary spacing controls.
Addition of grid points.
Order of interpolation and smoothing.
SAGE Code Features

- Fast and efficient - ~0.005 secs/grid point on a VMS/VAX e.g. 30x30 grid takes 5 secs
- Small size: 1900 lines of code (40% comments)
- Structured code and detailed user guide available - easy to customise
- Few user input parameters necessary but many options for great flexibility
- Can be applied to zonal, patched and multiple grids
Application 1: Hypersonic Blunt Body

Flow features: Simple 1-directional problem, shock shape aligned with grid.

Initial grid (32x32)  Initial flow solution (density contours)  Adapted grid (i step): $\lambda=.001$
Application 2: Cowl Lip with Shock Impingement

Flow features: blunt body shocks, impinging shock and shear layers
Application 3: Hypersonic Inlet with Cowl

Flow features: Cowl blunt body shock, Mach stem & reflected shocks

Initial Grid (128x32)  Initial density contours
Application 3 continued: Adapted Grid

Example of zonal adaption

i-direction - full domain adaption
j-direction - 3 zonal adoptions: 1) cowl region
                                    2) lower inlet region
                                    3) upper inlet region
Application 4: Plume Flow

Flow features: Outer shear layer, barrel shock, Mach disc, reflected shock, triple-point shear layer

Initial grid and Mach contours

Adapted grid and solution (after 3 iterations)

Comparison with shadowgraph
Application 5: Supersonic Inlet

Flow features: Corner shock, reflected shock and expansion fan

Initial grid (101x81) and density solution contours
Application 5 continued: Adapted grid (marching in j) and Solution

Input parameters: \( \Delta s_{\text{min}} = .25, \Delta s_{\text{max}} = 2.5, \lambda = .0005 \)
Application 5 continued: Adapted Grid (marching in i) and Solution

Input parameters: jstep=false, Δs_{min}=0.25, λ=0.001
Concluding Remarks

- SAGE is a new 2-D self-adaptive grid code that is user-friendly, flexible and efficient.
- Appropriate for a variety of CFD applications.
- Use of the SAGE code will efficiently improve the flowfield solution.
Time Dependent Viscous Incompressible Navier-Stokes Equations

By

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TIME DEPENDENT INCOMPRESSIBLE NAVIER-STOKES EQUATIONS

\[ \frac{\partial u}{\partial t} + \nabla \cdot (uu) - \frac{1}{Re} \Delta u = -\nabla p + F, \quad \text{for } x \in \Omega, \text{ and } t > 0, \]
\[ \nabla \cdot u = 0, \quad \text{for } x \in \Omega, \text{ and } t > 0. \]

* \( \Omega \) is a bounded open region in \( \mathbb{R}^2 \), with boundary \( \partial \Omega \).
* Initial and boundary conditions must be supplied.
* \( F \) is the volume force per unit mass, assumed to be 0.

\( \Rightarrow \) The continuity equation is not given in a time evolution form.
\( \Rightarrow \) The pressure gradient couples the continuity equation to the momentum equations.
STREAMFUNCTION EQUATIONS FOR UNSTEADY INCOMPRESSIBLE FLOW

\[ \frac{\partial \Delta \psi}{\partial t} = \frac{1}{Re} \Delta^2 \psi + \frac{\partial \psi}{\partial x} \frac{\partial^2 \psi}{\partial y^2} - \frac{\partial \psi}{\partial y} \frac{\partial^2 \psi}{\partial x^2}, \quad \text{for } x \in \Omega, \text{ and } t > 0; \]

with

\[ u(x, t) = \frac{\partial \psi}{\partial y}, \quad \text{and } v(x, t) = -\frac{\partial \psi}{\partial x}, \quad \text{for } x \in \Omega, \text{ and } t \geq 0. \]

* For \( \Omega \) in \( \mathbb{R}^2 \).

* Initial and boundary conditions must be supplied.

\[ \Rightarrow \quad \text{Vorticity and pressure do not enter into the streamfunction formulation.} \]

\[ \Rightarrow \quad \text{The velocity solution is always divergence free, and so incompressible.} \]
THE STREAMFUNCTION ALGORITHM FOR UNSTEADY INCOMPRESSIBLE FLOW

\[
\frac{\Delta t}{2Re} \bigg[ \delta_x \left( \frac{\delta (\bar{z}^n) \La (\bar{z}^n)}{2} \right) - \delta_y \left( \frac{\delta (\bar{z}^n) \La (\bar{z}^n)}{2} \right) \bigg]
\]

\[
+ \frac{\Delta t}{2} \left[ \delta_x \left( \frac{\delta (\bar{z}^{n-1}) \La (\bar{z}^{n-1})}{2} \right) - \delta_y \left( \frac{\delta (\bar{z}^{n-1}) \La (\bar{z}^{n-1})}{2} \right) \right],
\]

with

\[
u_{i,j}^n = \frac{1}{2\Delta y}(z_{i,j+1}^n - z_{i,j-1}^n), \quad \text{and} \quad v_{i,j}^n = -\frac{1}{2\Delta x}(z_{i+1,j}^n - z_{i-1,j}^n).
\]

* \( \La \) and \( \Bi \) are central difference approximations to the Laplace and Biharmonic operators.

* \( \delta_x \) and \( \delta_y \) are conventional centered difference operators.

\( \Rightarrow \) In \( \mathbb{R}^2 \) there is one unknown \( \{z_{i,j}^n\} \) per grid cell instead of three.

\( \Rightarrow \) The velocity components and streamfunction are all defined at each grid point.

\( \Rightarrow \) The discrete solution is exactly incompressible, \( \delta_x (u_{i,j}^n) + \delta_y (v_{i,j}^n) = 0 \).

\( \Rightarrow \) Stability limit is Courant number < 1.
A MULTIGRID SOLVER FOR THE LINEAR IMPLICIT EQUATIONS

\[ La(\tilde{z}^n) - \frac{\Delta t}{2Re} Bi(\tilde{z}^n) = \text{Source Term}(\tilde{z}^n, \tilde{z}^{n-1}) \]

\[ \rightarrow \] Use a multigrid solver for the implicit equations at each time step.

* The Biharmonic operator is factored as two Laplacians.

* On a 256 by 256 fine grid, 7 grid levels are used in 6.8 MBytes storage.

* Point Gauss-Seidel smoothing, linear restriction and prolongation.

* A V-cycle with 3 iterations per grid level while coarsening, none while refining.

* 10 to 15 iteration cycles reduce residuals to less than \( 5.0 \times 10^{-11} \).
STREAM FUNCTION CONTOURS
Re=5k, 128*128 grid, t=491.80625

STREAM FUNCTION CONTOURS - NORMALIZED VECTOR PLOTS
Re=5k, 128*128 grid, t=491.80625
0.5<=x<=1.0 and 0.0<=y<=0.5
u at $x=0.5$ as a function of $y$

Re=5000, 128 by 128 grid, $t=491.8$
STREAM FUNCTION CONTOURS

Re = 5k, 96 x 192 grid, i = 4000

PSI

0.00  0.25  0.50  0.75  1.00
-0.090 -0.070 -0.050 -0.030 -0.010
-0.001  0.001  0.010  0.020

262
KINETIC ENERGY SURFACE
Re=5k, 96*192 grid, t=4000
STREAMFUNCTION CHANGE PER TIME STEP
Relative L1 norm for the change
Re=5k, 96*192 grid, 3800<=t<=4100
STREAM FUNCTION CONTOURS - NORMALIZED VECTOR PLOTS
Re=5k, 96*192 grid, t=4100.25
0.0<=x<=1.0 and 0.85<=y<=1.35
STREAM FUNCTION CONTOURS – NORMALIZED VECTOR PLOTS
Re=5k, 96*192 grid, t=4101.25
0.0<=x<=1.0 and 0.85<=y<=1.35
STREAM FUNCTION CONTOURS - NORMALIZED VECTOR PLOTS
Re=5k, 96*192 grid, t=4101.50
0.0<=x<=1.0 and 0.85<=y<=1.35
STREAM FUNCTION CONTOURS – NORMALIZED VECTOR PLOTS
Re=5k, 96*192 grid, t=4102.50
0.0<=x<=1.0 and 0.85<=y<=1.35
SUMMARY: A NEW ALGORITHM

⇒ has one unknown per grid cell in two space dimensions;
⇒ requires storage that increases linearly with the number of grid points;
⇒ CPU time per time step increases linearly with the number of grid points;
⇒ is second order accurate in both time and space;
⇒ stability limit is Courant number < 1;
⇒ is robust with respect to Reynolds number.

SUMMARY: A NEW PERIODIC FLOW SOLUTION

⇒ is exactly periodic;
⇒ does not use a time dependent forcing term;
⇒ has no periodic or artificial throughflow boundary conditions;
⇒ is probably driven by the wall jet descending from the lid;
⇒ is evidence of a Hopf bifurcation;
⇒ may lead to period doubling bifurcations and a chaotic flow.
CFD for Applications to Aircraft Aeroelasticity

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Abstract

Strong interactions of structures and fluids are common in many engineering environments. Such interactions can give rise to physically important phenomena such as those occurring for aircraft due to aeroelasticity. Aeroelasticity can significantly influence the safe performance of aircraft. At present exact methods are available for making aeroelastic computations when flows are in either the linear subsonic or supersonic range. However, for complex flows containing shock waves, vortices and flow separations, computational methods are still under development. Several phenomena that can be dangerous and limit the performance of an aircraft occur due to the interaction of these complex flows with flexible aircraft components such as wings. For example, aircraft with highly swept wings experience vortex-induced aeroelastic oscillations. Correct understanding of these complex aeroelastic phenomena requires direct coupling of fluids and structural equations. This paper provides a summary of the development of such coupled methods and its applications to aeroelasticity since about 1978 to present. A part of the paper discusses the successful use of the transonic small perturbation theory (TSP) coupled with structures. This served as a major stepping stone for the current stage of aeroelasticity using CFD. The need for the use of more exact Euler/Navier-Stokes (ENS) equations for aeroelastic problems is explained. The current development of unsteady aerodynamic and aeroelastic procedures based on the ENS equations are discussed. The paper illustrates aeroelastic results computed using both TSP and ENS equations.
**HISTORY OF CFD APPLICATIONS TO AEROELASTICITY**

*BASED ON UNSTEADY TIME ACCURATE METHODS*

<table>
<thead>
<tr>
<th></th>
<th>TSP</th>
<th>FP</th>
<th>EULER</th>
<th>NAVIER STOKES</th>
</tr>
</thead>
</table>
MAJOR ISSUES FOR ADVANCED CFD METHODS

• Computational speed
  - Aeroelastic computations require two orders more computational time than steady computations

• Time accuracy
  - An essential requirement for accurate aeroelastic computations

• Grid and its unsteady movement
  - Time accuracy between zones

• Validity of turbulence models for unsteady and separated flows

• Robustness of solution methods
  - Other issues like artificial viscosity, upwinding, etc.
APPROACH FOR COMPUTER SIMULATION

- GOVERNING EQUATIONS
  - Aerodynamics: 3-D Euler/Navier-Stokes equations (ENS) and transonic small perturbation equation (TSP)
  - Aeroelastic: Modal equations of motion

- ALGORITHM
  - Aerodynamics: time accurate finite difference methods based on alternate direction implicit schemes
  - Aeroelastic: Simultaneous time integration method

- Note
  - ENS computations are made using aeroelastic adaptive dynamic grids
  - For TSP computations, aerodynamic and structural properties of the fuselage tip stores, and control surfaces are modeled
COUPLED AEROELASTIC EQUATIONS OF MOTION

- Deformed shape is a sum of modal coordinates
- Equations are solved by simultaneous integration technique
- Equations of Motion

Assuming displacement vector \( \{d\} = [\phi]\{q\} \) where \([\phi]\) is the modal matrix and \(\{q\}\) is the generalized displacement vector, the aeroelastic equation of motion is

\[
[M]\ddot{\{q\}} + [G]\{\dot{q}\} + [K]\{q\} = \{F\}
\]

\([M]\), \([G]\), and \([K]\) mass, damping and stiffness matrices
\(\{F\} = \left(\frac{1}{2}\right)\rho U^{2}\infty[\phi]^T[A]\{\Delta C_{p}\}\) is the aerodynamic force vector
\([A]\) is the diagonal area matrix of the aerodynamic control points.
MODES OF A RECTANGULAR WING

16 d.o.f. finite element

displacements
SOME APPLICATIONS OF TSP THEORY

- Transonic flutter boundaries of transport and fighter wings
- Aeroelasticity of a variable sweep wing (B-1 wing)
- Aeroelasticity of wings with tip stores
- Aeroelasticity of wings with active control surfaces
- Aeroelasticity of full span wing-body configurations (Symmetric and Asymmetric modes)
TYPICAL RESULTS FROM TSP CODE ATRAN3S
Full-Span Wing-Body Aeroelasticity

ANTISYMMETRIC MODES

MODE 1, FREQ. = 13.21 Hz

MODE 2, FREQ. = 87.32 Hz

MODE 3, FREQ. = 78.97 Hz

MODE 4, FREQ. = 203.80 Hz

MODE 5, FREQ. = 203.92 Hz

RESPONSES
Symmetric -- Antisymmetric

M = 0.851

M = 0.875

M = 0.905

TIME, sec
DEVELOPMENT OF ENSAERO

• PURPOSE
  - To develop an aeroelastic code to solve Euler/Navier Stokes equations coupled with structural equations of motion for full aircraft

• CHARACTERISTICS
  - Solves either Euler or Navier Stokes equations
  - Models structure by either modal or finite element equations
  - Includes aeroelastic configuration adaptive grid scheme
  - Modular to adopt different finite difference schemes
  - Transportable to different computer configurations

• ENSAERO-version 2.0
  - Solves Euler/Navier Stokes equations with modal structural equations of motion for wings
CONFIGURATION ADAPTIVE DYNAMIC GRID

- Grids are generated by an algebraic method
- Grids conform to the wing surface defined by displacements \( \{d\} \)
- Grids are generated every time-step of integration
- Time metrics are computed every time step

\[
\begin{align*}
\xi_t &= -x_\tau \xi_x - y_\tau \xi_y - z_\tau \xi_z \\
\eta_t &= -x_\tau \eta_x - y_\tau \eta_y - z_\tau \eta_z \\
\zeta_t &= -x_\tau \zeta_x - y_\tau \zeta_y - z_\tau \zeta_z
\end{align*}
\]

\[
J^{-1} = x_\xi y_\eta z_\zeta + x_\zeta y_\xi z_\eta + x_\eta y_\zeta z_\xi - x_\xi y_\zeta z_\eta - x_\eta y_\xi z_\zeta - x_\zeta y_\eta z_\xi
\]

- Note - Present technique can be used for both structured and unstructured grids
VOXET DOMINATED UNSTEADY PRESSURES
Navier-Stokes Computations
Rectangular Wing in ramp motion, AR = 4.0, NACA0015

GRID 151x20x40
$M\infty = 0.50$, $A = 0.30$,
$Re = 60000.0$

$\tau(\alpha)$
--- 0.31,(8.8°)
-.-- 0.47,(13.5°)
........ 0.63,(18.1°)
--- 0.79,(20.0°)
--- 0.94,(20.0°)

\begin{figure}
\centering
\includegraphics[width=\textwidth]{vortex-dominated-unsteady-pressures}
\end{figure}
COMPARISON OF UNSTEADY PRESSURES BETWEEN RIGID AND FLEXIBLE WINGS
(Navier-Stokes Computations)
Rectangular Wing in ramp motion, AR = 4.0, NACA0015

GRID 151x20x40
\( M_\infty = 0.50 \), \( A = 0.30 \),
\( R_e = 60000.0 \)
\( \alpha = 20^\circ \), \( \tau = 0.94 \)

--- Rigid Wing
--- Flexible Wing
CONCLUDING REMARKS

- During last decade TSP applications have progressed from airfoils to almost full aircraft
  - Computational speed has increased by a factor of about 100
  - Robust codes such as ATRAN3S are now available
  - Applied for advanced applications such as active controls

- Euler/Navier Stokes (ENS) equations are currently being used for aeroelastic problems of wings
FUTURE DIRECTIONS

- Improve time accurate Euler/Navier Stokes (ENS) algorithms
- Extend unsteady ENS algorithms for full aircraft configurations
- Couple advanced CFD methods with advanced CSM methods
- Conduct research in unsteady aerodynamics and aeroelasticity of full aircraft at high angles of attack
- Maintain TSP codes for immediate industrial use
FUTURE DIRECTIONS (continued)
Algorithm Development

- Typical results from a new upwind scheme that will be implemented in ENSAERO

Vortical flow on a 75° delta wing
Steady pressures at $M = 2.80, \alpha = 16.0^\circ$
FUTURE DIRECTIONS (continued)

- Typical steady results from Transonic Navier Stokes (TNS) code
- Unsteady algorithm will be implemented in full aircraft TNS code

ZONAL GRIDS IN PHYSICAL SPACE FOR F-16

ZONAL GRIDS IN COMPUTATIONAL SPACE

MACH CONTOURS
M = 0.9, $\alpha = 1.69^\circ$, Re = $4.5 \times 10^6$
APPLICATION OF UNSTRUCTURED GRID METHODS TO STEADY AND UNSTEADY AERODYNAMIC PROBLEMS

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Abstract

The presentation summarizes recent work in the Unsteady Aerodynamics Branch at NASA Langley Research Center on developing unstructured grid methods for application to steady and unsteady aerodynamic problems. The CAP-TSD transonic aeroelasticity code, which is based on the transonic small-disturbance (TSD) theory, is described first to provide background information to put the present work in context. The CAP-TSD code is the most fully-developed code for aeroelastic analysis of complete aircraft configurations at the TSD equation level and has been widely accepted throughout the U.S. aerospace industry. Currently, aeroelastic analysis capabilities are being developed at NASA Langley for the Euler and Navier-Stokes equations based on both structured and unstructured grids. The purpose of the presentation is to describe the development of unstructured grid methods which have several advantages when compared to methods which make use of structured grids. Unstructured grids, for example, easily allow the treatment of complex geometries, allow for general mesh movement for realistic motions and structural deformations of complete aircraft configurations which is important for aeroelastic analysis, and enable adaptive mesh refinement to more accurately resolve the physics of the flow. The presentation is therefore organized in three parts including: (1) steady Euler calculations for a supersonic fighter configuration to demonstrate the complex geometry capability; (2) unsteady Euler calculations for the supersonic fighter undergoing harmonic oscillations in a complete-vehicle bending mode to demonstrate the general mesh movement capability; and (3) vortex-dominated conical-flow calculations for highly-swept delta wings to demonstrate the adaptive mesh refinement capability. The basic solution algorithm is a multi-stage Runge-Kutta time-stepping scheme with a finite-volume spatial discretization based on an unstructured grid of triangles in 2D or tetrahedra in 3D. The moving mesh capability is a general procedure which models each edge of each triangle (2D) or tetrahedra (3D) with a spring. The resulting static equilibrium equations which result from a summation of forces are then used to move the mesh to allow it to continuously conform to the instantaneous position or shape of the aircraft. The adaptive mesh refinement procedure enriches the unstructured mesh locally to more accurately resolve the vortical flow features. These capabilities are described in detail along with representative results which demonstrate several advantages of unstructured grid methods. The presentation further discusses the applicability of the unstructured grid methodology to steady and unsteady aerodynamic problems and suggests directions for future work.
PRESENTATION OVERVIEW

- Background on CAP-TSD transonic aeroelasticity code
- Unstructured grid methods
  - steady and unsteady Euler calculations for a supersonic fighter configuration
  - vortex-dominated conical-flow calculations including adaptive mesh refinement
- Concluding remarks
CAP-TSD: COMPUTATIONAL AEROLELASTICITY PROGRAM - TRANSONIC SMALL DISTURBANCE

- Based on time-accurate approximate factorization algorithm
- Complete aircraft modeling involving arbitrary combinations of lifting surfaces and bodies
- Static and dynamic aeroelastic analysis
- Aircraft trim capability
- Longitudinal short-period response
- Entropy and vorticity effects included to treat cases with strong shock waves
CAP-TSD INSTANTANEOUS PRESSURES ON F-16C AIRCRAFT DUE TO RIGID PITCHING MOTION

- $M_\infty = 0.9$, $\alpha_0 = 2.38^\circ$, $k = 0.1$

Pitch-up

Pitch-down
ADVANTAGES OF UNSTRUCTURED GRID METHODOLOGY

- Allows the treatment of complex geometries
- Allows general mesh movement for realistic motions and structural deformations of complete aircraft
- Enables adaptive mesh refinement to more accurately resolve the physics of the flow
DESCRIPTION OF EULER SOLUTION ALGORITHMS

- Four-stage Runge-Kutta time-stepping scheme
- Finite-volume spatial discretization on unstructured grids of triangles in 2D or tetrahedra in 3D
- Adaptive blend of harmonic and biharmonic operators for artificial dissipation
- Enthalpy damping, local time-stepping, and implicit residual smoothing to accelerate convergence to steady state
- Dynamic mesh algorithm employed for unsteady applications
SURFACE TRIANGULATION FOR LANGLEY FIGHTER

- Total grid has 13,832 nodes and 70,125 tetrahedra
STEADY PRESSURE CONTOURS ON LANGLEY FIGHTER

- $M_\infty = 2.0$ and $\alpha_0 = 0^\circ$
OVERVIEW OF DYNAMIC MESH ALGORITHM

- Each edge of each triangle is modeled using a spring
- Spring stiffness is inversely proportional to the length of the edge

- Points on outer boundary of grid are fixed
- Locations of points on inner boundary of grid are specified
OVERVIEW OF DYNAMIC MESH ALGORITHM

- Displacement of interior nodes determined by solving the static equilibrium equations

- Equations solved using predictor-corrector procedure

  - new locations of nodes predicted by extrapolation

  \[ \tilde{\delta}_x = 2 \delta^n_x - \delta^{n-1}_x \quad \tilde{\delta}_y = 2 \delta^n_y - \delta^{n-1}_y \quad \tilde{\delta}_z = 2 \delta^n_z - \delta^{n-1}_z \]

  - locations corrected by several Jacobi iterations

\[
\begin{align*}
\delta_{x_i}^{n+1} &= \sum k_m \frac{\tilde{\delta}_x}{\sum k_m} \\
\delta_{y_i}^{n+1} &= \sum k_m \frac{\tilde{\delta}_y}{\sum k_m} \\
\delta_{z_i}^{n+1} &= \sum k_m \frac{\tilde{\delta}_z}{\sum k_m}
\end{align*}
\]
ASSUMED BENDING MODE FOR LANGLEY FIGHTER
INSTANTANEOUS PRESSURE CONTOURS ON LANGLEY FIGHTER

- $M_\infty = 2.0$, $\alpha_0 = 0^\circ$, and $k = 0.1$

Bend-up

Bend-down

$C_p$

$-0.15$ to $0.15$
DESCRIPTION OF CONICAL EULER/NAVIER-STOKES ALGORITHM

- Solves the conical Euler/Navier-Stokes equations
- Multi-stage Runge-Kutta time-stepping with finite-volume spatial discretization on unstructured grid of triangles
- Scheme is a zonal method
- Mesh enrichment capability enables automatic refinement in regions of high flow gradients
- Presently limited to laminar flow
EFFECTS OF MESH ENRICHMENT ON CONICAL EULER VORTICAL FLOW SOLUTION

- 75° swept flat plate delta wing at $M_\infty = 1.7$, $\alpha = 12^\circ$, $\beta = 8^\circ$
- Meshes

<table>
<thead>
<tr>
<th>Nodes</th>
<th>Total pressure loss contours</th>
</tr>
</thead>
<tbody>
<tr>
<td>2048</td>
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<tr>
<td>2555</td>
<td></td>
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<tr>
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</tbody>
</table>
CROSS FLOW VELOCITY VECTORS FROM CONICAL NAVIER-STOKES SOLUTION

- 70° swept elliptic cone delta wing; thickness ratio 14:1
- $M_\infty = 2.0$, $\alpha = 10^\circ$, and $Re = 5 \times 10^5$
CONCLUDING REMARKS

- CAP-TSD code developed for transonic aeroelastic analysis at the transonic small-disturbance equation level

- Unstructured grid methods for the Euler and Navier-Stokes equations under development for steady and unsteady aerodynamic applications
  
  - Steady Euler calculations for a supersonic fighter demonstrated ability to treat complex geometries
  
  - Unsteady Euler calculations for a supersonic fighter demonstrated general dynamic mesh capability
  
  - Vortex-dominated conical-flow calculations demonstrated adaptive mesh refinement capability
SESSION V

FIGHTER AIRCRAFT

Chairman:
Terry L. Holst
Chief, Applied Computational Fluids Branch
NASA Ames Research Center
Grid Generation and Inviscid Flow Computation About Aircraft Geometries

Robert E. Smith
Analysis and Computation Division
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Abstract

Grid generation and Euler flow about fighter aircraft are described. A fighter aircraft geometry is specified by an area ruled fuselage with an internal duct, cranked delta wing or strake/wing combinations, canard and/or horizontal tail surfaces, and vertical tail surfaces. The initial step before grid generation and flow computation is the determination of a suitable grid topology. The external grid topology that has been applied is called a dual-block topology which is a patched $C^1$ continuous multiple-block system where, inner blocks cover the highly-swept part of a cranked wing or strake, rearward inner-part of the wing, and tail components. Outer-blocks cover the remainder of the fuselage, outer-part of the wing, canards and extended to the far field boundaries. The grid generation is based on transfinite interpolation with Lagrangian blending functions. This procedure has been applied to the Langley experimental fighter configuration and a modified F-18 configuration. Supersonic flow between Mach 1.3 and 2.5 and angles of attack between 0° and 10° have been computed with associated Euler solvers based on the finite-volume approach. When coupling geometric details such as boundary layer diverter regions, duct regions with inlets and outlets, or slots with the general external grid, imposing $C^1$ continuity can be extremely tedious. The approach taken here is to patch blocks together at common interfaces where there is no grid continuity, but enforce conservation in the finite-volume solution. The key to this technique is how to obtain the information required for a conservative interface. We have used the Ramshaw technique which automates the computation of proportional areas of two overlapping grids on a planar surface and is suitable for coding. We have generated internal duct grids for the Langley experimental fighter configuration independent of the external grid topology, with a conservative interface at the inlet and outlet.
FEATURES

- MULTIPLE-BLOCK STRUCTURED GRIDS
- FINITE-VOLUME EUCLER SOLVERS
- CONSERVATIVE INTERFACE BETWEEN GRID BLOCKS
CONTENTS

- FIGHTER CONFIGURATIONS
- BOUNDARY GRIDS
- VOLUME GRID GENERATION
- CONSERVATIVE INTERFACING
- EULER FLOW SOFTWARE AND SOLUTIONS
- VIDEO DISPLAY
- CONCLUSIONS AND COMMENTS
FIGHTER CONFIGURATIONS

EXPERIMENTAL FIGHTER

MODIFIED F-18
BOUNDARY GRIDS

- CONFIGURATION SURFACE
  1. Component Cross Sections
  2. Interpolation, Fitting and Smoothing
  3. Grid Point Distributions

- INTERMEDIATE BOUNDARY SURFACES
  1. Algebraic Functions
  2. Embedded Grid Point Distributions

- FAR FIELD BOUNDARY SURFACES
BOUNDARY-SURFACE GRIDS

Original Definition

Grid-Surface Definition

Top-Surface Grid

Bottom-Surface Grid

Inlet Region
VOLUME GRID GENERATION

- GRID TOPOLOGY
  * Block Location and Interfaces

- TRANSFINITE INTERPOLATION
  * Various Interpolation Techniques

- GRID SPACING CONTROL
  * Exponential Functions
CONSERVATIVE GRID INTERFACES

- Rai's Approach
- Ramshaw Redistribution

\[ Q_N = \sum_{i=1}^{N_{NO}} Q_{O_i} \frac{A_{NO_i}}{A_{O_i}} = \sum_{i=1}^{N_{NO}} q_{O_i} A_{NO_i} \]
FIGHTER GRID
INVISCID-COMPRESSIBLE FLOW

- FINITE-VOLUME METHODOLOGY
- CUSTOM EULER SOLVER
  * CONTINUITY, MOMENTUM AND ENERGY
  * 3rd ORDER RUNGE-KUTTA
- GENERAL MULTI-BLOCK EULER SOLVER
  * CONTINUITY, MOMENTUM AND CONST. ENTHALPY
  * 4th ORDER RUNGE-KUTTA
SUMMARY OF SOLUTIONS
Mach Number = 2
Coefficient of pressure
EXPERIMENTAL FIGHTER CONFIGURATION
CONTOURS OF PRESSURE COEFFICIENT
Mach number = 2  Angle of attack = 0°
AERODYNAMIC CHARACTERISTICS

MODEL \( \equiv \) BW\(_{ACV} \)
- Experiment LaRC
- Present Computation

MODEL \( \equiv \) BW\(_{AV} \)
- Experiment LaRC
- Present Computation

\( C_L \)
MACH NUMBER = 2

\( \alpha \) Degs.
CONCLUSIONS

- ALGEBRAIC GRID GENERATION FEASIBLE
- CONSERVATIVE BLOCK INTERFACES POSSIBLE
- FINITE-VOLUME EULER SOLVERS USED
- FLOW CHARACTERISTICS IN GOOD AGREEMENT
- VORTEX COMPUTATION NEEDS MORE STUDY
A ZONAL NAVIER-STOKES METHODOLOGY FOR FLOW SIMULATION ABOUT A COMPLETE AIRCRAFT

Jolen Flores

Abstract: The thin-layer, Reynolds-averaged, Navier-Stokes equations are used to simulate the transonic viscous flow about the complete F-16A fighter aircraft. These computations demonstrate how computational fluid dynamics (CFD) can be used to simulate turbulent viscous flow about realistic aircraft geometries. A zonal grid approach is used to provide adequate viscous grid clustering on all aircraft surfaces. Zonal grids extend inside the F-16A inlet and up to the compressor face while power on conditions are modeled by employing a zonal grid extending from the exhaust nozzle to the far field. Computations are compared with existing experimental data and are in fair agreement. Computations for the F-16A in side slip are also presented.

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Presentation at NASA OAST CFD CONFERENCE
March 7-9, 1989
NASA Ames Research Center
• **OBJECTIVE**
  > To numerically simulate viscous transonic flow about realistic aircraft configurations.

• **MOTIVATION**
  > Technical demonstration of state-of-the-art CFD research
  > To provide bench-mark calculations (validated by measurements)
  > Reveal areas requiring future research emphasis
  > Catalyst for future cooperative efforts between NAS, aerospace industry and academia
  > Industrial use for prediction of integrated aircraft performance

• **APPROACH**
  > Thin-layer Navier-Stokes equations
  > Zonal grid approach
  > Modular program
GRID INTERFACING AT WING SPANWISE STATION
WING–FUSELAGE–INLET SURFACE GRIDS
CROSS-SECTIONAL VIEW OF THE GRID THROUGH THE DIVERTER REGION
F-16A WING PRESSURE COEFFICIENT COMPARISONS

$M_\infty = 0.9$, $\alpha = 6.0^\circ$, $Re_c = 4.5 \times 10^6$

\begin{align*}
\Delta \nabla & \quad \text{EXPERIMENT} \\
- \Delta & \quad \text{TNS}
\end{align*}

\begin{align*}
\eta & = 0.59 \\
\eta & = 0.71
\end{align*}
VERTICAL TAIL PRESSURE COEFFICIENT COMPARISONS

\[ M_\infty = 0.9, \alpha = 6.0^\circ, Re_c = 4.5 \times 10^6 \]
INLET/DIVERTER PRESSURE COEFFICIENT COMPARISONS

\[ M_\infty = 0.9, \alpha = 6.0^\circ, Re_c = 4.5 \times 10^6 \]
PRESSURE CONTOURS ON UPPER SURFACE OF F-16A
(Mach=0.9, Alpha=6.0°, Beta=0.0°, Re_c=4.5x10^6)
PRESSURE CONTOURS ON UPPER SURFACE OF F-16A
(Mach=0.9, Alpha=6.0°, Beta=5.0°, Re=4.5x10^6)
CROSS-FLOW INFLUENCE ON UNRESTRICTED PARTICLE TRACES
(Mach=0.9, Alpha=6.0°, Beta=5.0°, Re_c=4.5x10^6)
SUMMARY

- Benchmark Navier-Stokes simulation of a complete aircraft including sideslip

\[ \beta = 0.0^\circ \]

- Good comparison with \( C_P \), \( C_L \), and \( C_D \)
- Successful implementation of internal inlet grids
- Successful simulation of power-on conditions
- Convergence in 5000 iterations/ 25 hours of cpu

\[ \beta = 5.0^\circ \]

- Pressure contours/particle traces indicate proper physical trends
NUMERICAL SIMULATION OF F-18 FUSELAGE FOREBODY FLOWS AT HIGH ANGLES OF ATTACK

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Abstract

As part of the NASA High Alpha Technology Program, fine-grid Navier-Stokes solutions have been obtained for flow over the fuselage forebody and wing leading edge extension of the F/A-18 High Alpha Research Vehicle at large incidence. The resulting flows are complex, and exhibit crossflow separation from the sides of the forebody and from the leading edge extension. A well-defined vortex pattern is observed in the leeward-side flow. Results obtained for laminar flow show good agreement with flow visualizations obtained in ground-based experiments. Further, turbulent flows computed at high-Reynolds-number flight-test conditions \( (M_\infty = 0.2, \alpha = 30^\circ, \text{ and } Re = 11.52 \times 10^6) \) show good agreement with surface and off-surface visualizations obtained in flight.

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† National Research Council Research Associate. Associate Professor, on leave from California Polytechnic State University, Aeronautical Engineering Department.
‡ Member of the Professional Staff, Sterling Federal Systems, Inc., Palo Alto, CA.
OBJECTIVE

• DEVELOP FLIGHT-VALIDATED DESIGN METHODS THAT ACCURATELY PREDICT THE AERODYNAMICS OF AIRCRAFT MANEUVERING AT LARGE ANGLES OF ATTACK

APPROACH

• UTILIZE A THREE-DIMENSIONAL NAVIER-STOKES CODE, WITH SUITABLE GRIDS AND AN EDDY-VISCOSITY TURBULENCE MODEL, TO COMPUTE HIGH-ALPHA FLOWS OVER THE F-18 FUSELAGE FOREBODY AND LEX

• VALIDATE THE NUMERICAL RESULTS BY COMPARISON WITH FLIGHT-TEST DATA OBTAINED ON THE NASA F-18 HIGH ALPHA RESEARCH VEHICLE (HARV)
GOVERNING EQUATIONS

\[
\frac{\partial \hat{Q}}{\partial \tau} + \frac{\partial \hat{F}}{\partial \xi} + \frac{\partial \hat{G}}{\partial \eta} + \frac{\partial \hat{H}}{\partial \zeta} = \frac{1}{Re} \frac{\partial \hat{S}}{\partial \zeta}
\]

- THIN-LAYER NAVIER-STOKES EQUATIONS
- CURVILINEAR, BODY-CONFORMING COORDINATES
- HIGH REYNOLDS NUMBER FLOWS
- LAMINAR VISCOSITY FROM SUTHERLAND'S LAW
- ALGEBRAIC EDDY-VISCOSITY MODEL CORRECTED FOR CROSSFLOW SEPARATION
NUMERICAL METHOD

\[ \left\{ I + h \left[ \delta_{\xi}^b (\hat{A}^+) + \delta_{\xi} \hat{C} - \frac{1}{Re} \delta_{\xi} \hat{M} \right] \right\} \left\{ I + h \left[ \delta_{\xi}^f (\hat{A}^-) + \delta_{\eta} \hat{B} \right] \right\} \Delta \hat{Q}^n = R.H.S. \]

- TWO-FACTORED ALGORITHM (F3D)
- FIRST OR SECOND-ORDER ACCURACY IN TIME
- SECOND-ORDER SPATIAL ACCURACY
  - FLUX-VECTOR SPLITTING AND UPWIND DIFFERENCING IN \( \xi \) (STREAMWISE) DIRECTION
  - CENTRAL DIFFERENCING IN THE \( \eta \) (CIRCUMFERENTIAL) AND \( \zeta \) (RADIAL) DIRECTIONS
- COMBINATION OF SECOND AND FOURTH-ORDER SMOOTHING USED IN THE \( \eta \) AND \( \zeta \) DIRECTIONS
  - SMOOTHING TERMS SCALED BY \( q/q_\infty \)
- SINGLE-BLOCK AND TWO-BLOCK GRIDS USED
F-18 FOREBODY TWO-BLOCK GRID

FRONT GRID
36 x 53 x 50 POINTS

BACK GRID
35 x 85 x 50 POINTS

NASA-AMES
HIGH ALPHA GROUP
ONE-BLOCK GRID: F-18 FOREBODY CLOSE-UP
TWO-BLOCK GRID: F-18 FOREBODY CLOSE-UP
TANGENT OGIVE–CYLINDER SINGLE–BLOCK GRID

59 x 63 x 50 POINTS

NASA–AMES
HIGH ALPHA GROUP
COMPUTED SURFACE OIL FLOW

\[ M_{\infty} = 0.2, \quad \alpha = 20^\circ \]
\[ Re_D = 5.0 \times 10^6 \quad \text{(TURBULENT)} \]
HELICITY

$M_\infty = 0.2, \alpha = 20^\circ$

$Re_D = 5.0 \times 10^6$ (TURBULENT)
SURFACE FLOW PATTERN

$M_\infty = 0.2, \quad \alpha = 30^\circ$

$Re_c = 11,540,000$ (TURBULENT)
FLIGHT SURFACE FLOW VISUALIZATION

QUARTER VIEW, $\alpha = 30^\circ$
HELICITY DENSITY

$M_\infty = 0.2, \alpha = 30^\circ$

$Re_C = 11,540,000$ (TURBULENT)
Wingtip Photograph of F-18

$\alpha = 20.8^\circ$ and $\beta = +1.15^\circ$

- LEX vortices visualized using smoke
SUMMARY REMARKS

- NAVIER-STOKES COMPUTATIONS FOR HIGH-ALPHA SEPARATED TURBULENT FLOW ABOUT THE F-18 (HARV) FUSELAGE FOREBODY AND LEX SHOW GOOD AGREEMENT WITH FLIGHT-TEST DATA
  - ONLY MINOR DIFFERENCES BETWEEN SINGLE-BLOCK AND TWO-BLOCK RESULTS
  - EFFECTS OF INCREASING INCIDENCE CONSISTENT WITH EXPERIMENT
  - CFD RESULTS HAVE GIVEN NEW INSIGHT INTO HIGH-ALPHA FLOW STRUCTURE

- COMPUTATION-TO-FLIGHT PREDICTIONS OF FULL F-18 CONFIGURATIONS ARE NEXT STEP

- USE OF CFD AS A DESIGN TOOL FOR VORTEX CONTROL CONCEPTS IS AT HAND
NAVIER-STOKES SOLUTIONS ABOUT THE F/A-18 FOREBODY-LEX CONFIGURATION

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Brent L. Bates  
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Abstract

Three-dimensional viscous flow computations are presented for the F/A-18 forebody-LEX geometry. Solutions are obtained from an algorithm for the compressible Navier-Stokes equations which incorporates an upwind-biased, flux-difference-splitting approach along with longitudinally-patched grids. Results are presented for both laminar and fully turbulent flow assumptions and include correlations with wind tunnel as well as flight-test results. A good quantitative agreement for the forebody surface pressure distribution is achieved between the turbulent computations and wind tunnel measurements at $M_{\infty} = 0.6$. The computed turbulent surface flow patterns on the forebody qualitatively agree well with in-flight surface flow patterns obtained on an F/A-18 aircraft at $M_{\infty} = 0.34$. 
Overview

- Navier-Stokes Formulation
  - CFL-3D

- Grid Generation
  - Transfinite interpolation

- Results
  - Laminar, turbulent flow
  - Comparisons with wind-tunnel experiment
  - Comparisons with flight test

- Summary
Grid Generation - Transfinite interpolation

- H-O topology

- Far field
  - Inflow, outflow $\approx 1 \bar{c}$
  - Radial $\approx 1.5 \bar{c}$

- Baseline grid
  - Block 1: $31 \times 65 \times 27$
  - Block 2: $65 \times 65 \times 31$
  - Approximately 185,000 points
  - $y^+ \approx 2$ for wind-tunnel conditions
  - $y^+ \approx 8$ for flight conditions

- Refined grid
  - Doubled number of radial points
  - Normal surface spacing $\approx 0.25 \times$ baseline
  - $y^+ \approx 3$ for flight conditions
F-18 Forebody–LEX Grid
Computed Results

- Wind tunnel conditions
  - $M_\infty = 0.6$, $R_\infty = 0.8 \times 10^6$, $\alpha = 20^\circ$
  - Laminar, turbulent flow
  - Comparison with experiment

- Flight conditions
  - $M_\infty = 0.34$, $R_\infty = 13.5 \times 10^6$, $\alpha = 19^\circ$
  - Turbulent flow
  - Comparison with experiment
Total Pressure - Laminar Flow

\( M_\infty = 0.6, \quad R_C = 0.8 \times 10^6, \quad \text{Alpha} = 20^\circ \)

Grid1: 27x31x65
Grid2: 31x65x65
Total Pressure – Turbulent Flow

$M_{\infty} = 0.6$, $Re_C = 0.8 \times 10^6$, $\alpha = 20^\circ$

Grid1: 11x31x65
Grid2: 17x31x65
Grid3: 31x65x65
LEX Upper Surface Flow – Laminar

\[ M_\infty = 0.6, \quad R_c = 0.8 \times 10^6, \quad \text{Alpha} = 20^\circ \]

Grid1: 27x31x65
Grid2: 31x65x65
LEX Upper Surface Flow – Turbulent

$M_\infty = 0.6, \quad R_\infty = 0.8 \times 10^6, \quad \text{Alpha} = 20^\circ$

Grid1: 11x31x65
Grid2: 17x31x65
Grid3: 31x65x65
Surface Pressure Coefficient – Laminar Flow

\( M_\infty = 0.6, \quad R_\infty = 0.8 \times 10^6, \quad \text{Alpha} = 20^\circ \)

Grid1: 27x31x65
Grid2: 31x65x65
Surface Pressure Coefficient - Turbulent Flow

$M_{\infty}=0.6$, $R_c=0.8 \times 10^6$, $\text{Alpha}=20^\circ$

Grid1: 11x31x65
Grid2: 17x31x65
Grid3: 31x65x65
Forebody Surface Pressure

\[ M_a = 0.6, \quad R_e = 0.8 \times 10^6, \quad \alpha = 20^\circ \]

LEX Surface Pressure
Turbulent Surface Flow – Side View

\[ M_\infty = 0.34, \quad R_c = 13.5 \times 10^6, \quad \text{Alpha} = 19^\circ \]

Grid1: 11x31x65
Grid2: 17x31x65
Grid3: 31x65x65
Summary of Results

- Significant differences between laminar and turbulent solutions
  - Forebody
  - LEX upper surface
  - Body-LEX juncture on lower surface

- Turbulent solutions provide good correlation with experiment
  - Surface $C_p$ comparison with wind tunnel data
  - Surface flow comparison with flight test data

- Convergence achieved with practical resource utilization
  - $\approx 185,000$ points
  - $\approx 2400$ cycles
  - $\approx 2$ hours of Cray-2 time
The objective is developing CFD capabilities to obtain solutions for viscous flows about generic configurations of internally and externally carried stores. Wind tunnel experiments are also being conducted to accomplish this goal. Current work on the VUMX3 code is oriented towards the supersonic flow regime with extensions being made to the transonic regime. Three dimensional unsteady cavity flows solutions are obtained by an explicit, MacCormack algorithm, EMCAV3, for open, close, and transitional cavities. High angle of attack flows are solved by an implicit, upwind algorithm, EMCAV3, for open, close, and transitional cavities. High angle of attack flows about a body inside or in the proximity of a cavity. These configurations are solved by an implicit, upwind algorithm, FEMCAV3. For flows about multiple body configurations, the Chimera embedding scheme is modeled for finite-volume and multi-grid algorithms. For flows about multiple body configurations, the Chimera embedding scheme is modeled for finite-volume and multi-grid algorithms. The results compare favorably with the experimental data. For flows about multiple body configurations, the Chimera embedding scheme is modeled for finite-volume and multi-grid algorithms. The results compare favorably with the experimental data.

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RELATED TO STORE SEPARATION
NAVIER-STOKES SOLUTIONS FOR FLOWS

COLOR ILLUSTRATIONS
ORIGINIAL CONTENTS
ATTRIBUTES OF MagGie CODE

- Subdomain grids generated separately and independently.
- Distance between cell centers used for interpolations.
- Regions of a fine level grid common to others removed (holes).
- Regions of a coarse level grid overlapping solid surfaces removed (illegal zones).
- Edges of holes or illegal zones are intergrid boundaries.
- 3-D vector operations to locate cells in a hole or an illegal zone.
- Cells of outer boundary of overlap regions (fringe cell).
- Immediate-neighbor cells of a hole or an illegal-zone cell (fringe cell).
- Information hexahedrons around fringe cells formed.
- Cells in a hole but not in an illegal zone updated from fine level equal coarse level of other grids
- Coefficients for trilinear interpolations.
- Vectorized data structures as preprocessor for VUMXZ3
- Developed from Chimera.
- Characteristic intergrid boundary conditions.
ATTRIBUTES OF VUMXZ3 CODE

- DEVELOPED FROM CFL3D CODE, HENCE INCLUDES ALL CFL3D ATTRIBUTES.
- ALL BUT CROSS-DERIVATIVE VISCIOUS TERMS.
- BALDWIN-LOMAX TURBULENCE MODEL MODIFIED FOR VORTICAL FLOWS, MULTIPLE-WALLS, AND TURBULENT MEMORY RELAXATION FOR WAKES AND SHEAR LAYERS.
- BLOCK OR DIAGONAL INVERSIONS ACCOMODATE HOLES AND ILLEGAL ZONES FOR OVERLAPPED GRIDS.
- AVOIDS INFORMATION POLLUTION NEAR HOLES OR ILLEGAL ZONES FOR HIGHER ORDER SCHEMES.
- NULLIFIES WEIGHT OF CONTRIBUTIONS FROM ILLEGAL ZONES DURING 3-D MULTIGRID PROLONGATION.
- INTERGRID INFORMATION EXCHANGED BY TRILINEAR INTERPOLATIONS COUPLED WITH CHARACTERISTIC BOUNDARY CONDITIONS.
- COMBINED ZONAL AND OVERLAPPED EMBEDDING.
- DEMONSTRATIVE CASES:

  SUPERSONIC FLOW PAST A BLUNT-NOSE CYLINDER (L/D=6.7) AT 32° ANGLE OF ATTACK ON
  SINGLE C-O GRID.
  C-O GRID EMBEDDED IN CARTESIAN GRID.
  C-O GRID PATCHED TO H-O GRID.

  SUPERSONIC FLOW PAST AN OGLIVE-NOSE CYLINDER (L/D=18) NEAR FLAT PLATE.
EFFECTS OF SHAPE AND INCIDENCE ON FLOW PAST A CYLINDRICAL SECTION

Mx = 1.6, Re = 2x10^6 / ft

DENSITY

HEMISPHERICAL-NOSE-CYLINDER

SECANT-OGIVE-NOSE-BOAT-TAIL CYLINDER

BLUNT-NOSE-CYLINDER

α = 8°

α = 12°

α = 20°

Cp

upper surface

α = 10°

α = 5°

α = 20°

lower surface

α = 10°

α = 5°

α = 20°

PRESSURE

α = 12°
EMBEDDED GRIDS FOR BLUNT-NOSE-CYLINDER WITH STING

C-O GRID : 73x65x57

CARTESIAN GRID : 81x73x73

cartesian grid with hole

hole boundary cells

overlap of c-o with cartesian
MACH CONTOURS OF FLOW (M=1.6, RE=2E6/FT) PAST OGIVE-NOSE CYLINDER (L/D=6.7, alpha=32)
CROSSFLOW DENSITY CONTOURS OF FLOW PAST A BLUNT-NOSE-CYLINDER

$M_x = 1.6 \quad Re_x = 2 \times 10^6 / \text{ft}$

$\alpha = 1.2^\circ$

$\alpha = 3.2^\circ$

$\alpha = 4.4^\circ$

LAMINAR

$\alpha = 20^\circ$

TURBULENT
FLOW PAST A BLUNT-NOSE CYLINDER (L/D=6.7, M=1.6, Re=2E6/FT) \( \eta = 0 \) LEESIDE, \( \eta = 180 \) WINDSIDE
PRESSURE CONTOURS ON THE SYMMETRY PLANES OF BLUNT-NOSE-CYLINDER

\[ M_\infty = 1.6 \quad Re_\infty = 2 \times 10^6 / \text{ft} \quad \alpha = 32^\circ \]

(a) composite grid

(b) single C-O grid

(c) \( C_p \) on leeside
DENSITY CONTOURS OF FLOW (M=2.86, RE=2E6/FT) PAST OGIVE-NOSE CYLINDER (L/D=18) NEAR A FLAT PLATE
FLOW OVER OGIVE-NOSE-CYLINDER NEAR FLAT PLATE

\[ M_\infty = 2.86 \quad Re_\infty = 2 \times 10^6 / ft \quad \alpha = 0^\circ \]

Pressure Contours on the Symmetry Plane of ONC

Pressure Coefficient Contours on the surface of the flat plate

Skin Friction Patterns near the flat plate surface

(a) two cells above the surface

(b) one cell above the surface
OVERLAPPED/EMBEDDED AND ZONAL GRIDS FOR OGIVE-NOSE CYLINDER (L/D=20)

WITH L-STING NEAR A CAVITY (L/H=6.7)
ATTRIBUTES OF EMCAV3

- 3-D REYNOLDS-AVERAGED NAVIER-STOKES EQUATIONS FOR UNSTEADY COMPRESSIBLE FLOW.
- EXPLICIT, UNSPLIT, PREDICTOR-CORRECTOR TIME INTEGRATION (MACCORMACK).
- FINITE DIFFERENCE SPATIAL DISCRETIZATION.
- SECOND ORDER ACCURATE IN TIME AND SPACE.
- VECTORIZED DATA STRUCTURE.
- DEVELOPED FROM SCRM32.
- ALGEBRAIC GRID GENERATOR.

- BALDWIN-LOMAX TURBULENCE MODEL MODIFIED FOR
  VORTICAL FLOWS.
  MULTIPLE WALLS.
  TURBULENT MEMORY RELAXATION FOR SHEAR LAYER.

- IMPLICIT MARCHING SOLUTION FOR 2-D COMPRESSIBLE BOUNDARY LAYER PROFILE.

- FOURIER TIME SERIES ANALYSIS FOR CAVITY ACOUSTICS.

- DEMONSTRATIVE CASES

\[
\begin{array}{c}
2\text{-D} \\
3\text{-D}
\end{array}
\begin{array}{c}
\text{SUBSONIC} \\
\text{TRANSonic} \\
\text{SUPERSONIC}
\end{array}
\begin{array}{c}
\text{FLOWS AT} \\
\begin{array}{c}
0^\circ \\
45^\circ
\end{array}
\end{array}
\begin{array}{c}
\text{YAW PAST} \\
\text{DEEP TRANSITIONAL} \\
\text{SHALLOW}
\end{array}
\begin{array}{c}
\text{CAVITIES}
\end{array}
\]
INSTANTANEOUS STREAMLINES OF FLOW PAST RECTANGULAR CAVITIES

\[ M_x = 1.5 \quad L/D = 6 \quad Re = 6.56 \times 10^6 / m \]

\[ M_x = 0.9 \quad L/D = 4.4 \quad Re = 5.35 \times 10^6 / m \]

\[ M_x = 0.58 \quad L/D = 11.7 \quad Re = 5.02 \times 10^6 / m \]

\[ Z/W = 0.4706 \]

\[ Z/W = 0.3529 \]

\[ Z/W = 0.0 \]
CONCLUSIONS

- 3-D CFD CAPABILITIES FOR UNSTEADY CAVITY FLOWS.

- TIME-AVERAGED AND TIME SERIES ANALYSES OF CAVITY FLOWS:
  EFFECTS OF LENGTH-TO DEPTH, FLOW REGIMES, YAW ANGLES.

- 2-D ANALYSES OF FLOWS PAST VARIOUS CYLINDRICAL SECTIONS AT VARIOUS ANGLES OF ATTACK.

- 3-D ANALYSES OF LAMINAR AND TURBULENT FLOWS PAST A BODY OF REVOLUTION
  AT VARIOUS ANGLES OF ATTACK.

- 3-D CFD CAPABILITIES DEVELOPED FOR VISCOUS FLOWS ABOUT
  COMPLEX AND/OR MULTICOMPONENT CONFIGURATIONS.

- COMBINED ADVANTAGES: GEOMETRICALLY CONSERVATIVE, MINIMALLY DISSIPATIVE
  : NUMERICALLY AND COMPUTATIONALLY EFFICIENT.
  : FLEXIBILITY IN BODY GEOMETRIES AND GRID TOPOLOGIES.

- FLUX CONSERVATION ACROSS INTERGRID BOUNDARIES NEED FURTHER STUDY.

- ANALYSES OF AERODYNAMIC INTERERENCE OF A STORE NEAR A FLAT PLATE (EXTERNAL CARRIAGE).

- WORK-IN-PROGRESS: CFD SOLUTIONS FOR FLOWS PAST AN OGIVE-NOSE-CYLINDER WITH L-SHAPE
  STING NEAR A CAVITY AND CODE VALIDATION WIND TUNNEL EXPERIMENTS.
TranAir: Recent Advances and Applications

Michael D. Madson

NASA Ames Research Center, Moffett Field, CA

March 8, 1989

Abstract

TranAir is a computer code which solves the full-potential equation for transonic flow about very general and complex configurations. Piecewise flat surface panels are used to describe the surface geometry. This paneled definition is then embedded in an unstructured cartesian flow field grid. Finite elements are used in the discretization of the flow field grid in a manner which is fully conservative and 2nd-order accurate. Since geometries may be defined with relative ease, and since the user is not involved in the generation of the flow field grid, computational results may be generated rather quickly for a wide range of geometries. For transonic cases in the cruise angle-of-attack range, TranAir has generated results which are in generally good agreement with both Euler results and wind tunnel data. A typical transonic case runs in 1-2 CPU hours on a Cray X-MP. For subcritical cases, the code runs in 15-30 CPU minutes, even for geometries in which several thousand surface panels are used in the definition. This ability to rapidly and accurately provide both subsonic and transonic predictions about very complex aircraft configurations gives TranAir the potential of being a very powerful and widely used design tool.

Acknowledgements

TranAir is being developed by Boeing Advanced Systems, Seattle, WA, under contract to NASA. The author wishes to thank Forrester Johnson, Satish Samant, David Young, Robin Melvin and John Bussoletti for their dedicated work in the development of the code, and for providing many of the results presented in the charts which follow.
TRANAIR: RECENT ADVANCES AND APPLICATIONS
MICHAEL D. MADSON
NASA Ames Research Center

ACKNOWLEDGEMENTS
Forrester T. Johnson, Satish S. Samant, David P. Young,
Robin G. Melvin, and John E. Bussoletti

OUTLINE
• OBJECTIVE
• APPROACH
• RECENT ADVANCES
• APPLICATIONS
• OBSERVATIONS
• POSSIBLE FUTURE DIRECTIONS
OBJECTIVE

TO DEVELOP AND VALIDATE A COMPUTATIONAL METHOD WHICH ELIMINATES THE USE OF SURFACE-CONFORMING GRIDS IN THE ANALYSIS OF COMPLEX AIRCRAFT CONFIGURATIONS IN THE TRANSONIC FLOW REGIME.
APPROACH

- GEOMETRY DEFINED BY SURFACE PANELS
- EMBEDDED IN UNIFORM CARTESIAN GRID
- LOCAL GRID REFINEMENT CAPABILITY BASED ON
  - LOCAL PANEL SIZE
  - USER INPUT

- SOLUTION PROCESS
  - GRID DISCRETIZED W/FIXED ELEMENTS, CONSERVATIVE, 2ND ORDER
  - SET OF NONLINEAR ALGEBRAIC EQNS SIMULATE FULL-POTENTIAL
  - 1ST ORDER DISSIPATION FOR SHOCK CAPTURING
  - SET OF EQNS SOLVED BY ITERATIVE PROCESS
RECENT ADVANCES

• LOCAL GRID REFINEMENT
  • CURRENTLY REQUIRES SUBSTANTIAL USER INPUT
  • SOLUTION ADAPTIVE REFINEMENT NEARLY COMPLETE

• IMPROVEMENTS IN SOLUTION PROCESS
  • DYNAMIC DROP TOLERANCE IN SPARSE MATRIX SOLVER
  • "SHOCK SMEARING" FOR CONVERGENCE IMPROVEMENTS
  • REGIONS OF DIFFERING $T_T$, $P_T$
  • MORE GENERAL BOUNDARY CONDITION OPTIONS
  • SUPersonic FREESTREAM \{ CURRENT EFFORTS
  • HIERARCHICAL MULTIGRID \}
APPLICATIONS

- F-16A W/TIP MISSILES, FUEL TANKS
- BOEING 747-200
- OBLIQUE WING RESEARCH AIRCRAFT
- GENERIC FIGHTER
- ONERA M6
  - AXISYMMETRIC NACELLE
  - ADVANCED TURBOPROP MODEL
F-16A W/TIP MISSILES, FUEL TANKS
F-16A W/TIP MISSILES, FUEL TANKS

$M_{\infty} = 0.9, \alpha = 4^\circ$

![Graphs showing pressure distribution for different wetted fractions ($\eta$) with $M_{\infty} = 0.9$ and $\alpha = 4^\circ$.](image)

- (a) $\eta = 0.32$
- (b) $\eta = 0.59$
- (c) $\eta = 0.71$
- (d) $\eta = 0.84$
F-16A, TIP MISSILE EFFECT

$M_\infty = 0.6, \alpha = 4^\circ, \eta = 0.95^\circ$

- **WIND TUNNEL**
  - • UPPER SURFACE
  - □ LOWER SURFACE
- **TRANAIR**
  - —— Refined, W/MISSILE
  - —— Uniform, No MISSILE

![Graph](image-url)
BOEING 747-200
BOEING 747–200

$M_\infty = 0.8, \alpha = 2.7^\circ$

![Diagram](image_url)

$\eta = 0.26$

$\eta = 0.60$

$\eta = 0.69$

$\eta = 0.81$

MDM–9/15
GENERIC FIGHTER
GENERIC FIGHTER

$M_\infty = 0.8, \alpha = 5^\circ, \text{WING/BODY}$

- $X/C_{\text{ROOT}} = 0.40$
- $X/C_{\text{ROOT}} = 0.50$
- $X/C_{\text{ROOT}} = 0.625$
- $X/C_{\text{ROOT}} = 0.75$

MDM-11/15
ONERA M6

REFINED GRID AT ROOT SECTION
ONERA M6 WING

$M_\infty = 0.84, \alpha = 3.06^\circ$

(a) FLO28
   - FIRST ORDER VISCOSITY
   - SECOND ORDER VISCOSITY
   - TRANAIR

PLANE OF SYMMETRY

$\eta = 0.44$

$\eta = 0.70$

$\eta = 0.91$
OBSERVATIONS

- SHOWS PROMISE OF BEING EXCELLENT DESIGN TOOL
  - EXPECTED TO REPLACE PANAIR FOR ANALYSIS OF COMPLEX CONFIGURATIONS
  - LINEAR CASES TAKE 15-30 CPU MINUTES ON CRAY X-MP
  - NONLINEAR CASES TAKE 1-2 CPU HOURS ON X-MP
  - FOR CASES W/LIMITED VORTICAL FLOW, GOOD AGREEMENT W/FLO57
  - INITIAL Y-MP RUNS INDICATE 25-40% IMPROVEMENT IN CPU TIME

- AREAS FOR IMPROVEMENT
  - FURTHER MODS COULD REDUCE CPU TIME BY A FACTOR OF 2
  - BOUNDARY LAYER COUPLING FOR MORE ACCURATE SHOCK LOCATION
  - ADDITION OF “WAKE CAPTURING” TERM FOR VORTICAL FLOW TRACKING
POSSIBLE FUTURE DIRECTIONS

- MODIFIED FULL-POTENTIAL
  - SOURCE TERM ADDED TO FULL-POTENTIAL EQN FOR WAKE TRACKING
  - VISCIOUS COUPLING

- EULER EQUATIONS
  - MAINTAIN CURRENT GEOMETRY, GRID FORMAT
  - SOLUTION ADAPTIVE REFINEMENT FOR ACCURATE VORTEX CAPTURING

- NAVIER-STOKES??
  - PROBABLY REQUIRES "PSEUDO-GRID" FOR BOUNDARY LAYER SOLUTION
SESSION VI

ROTORCRAFT

Chairman:
W. J. McCroskey
U.S. Army Aeroflightdynamics Directorate
NASA Ames Research Center
NUMERICAL SIMULATION OF ROTORCRAFT*

W. J. McCroskey

U. S. Army Aeroflightdynamics Directorate-AVSCOM

and

NASA Ames Research Center, Moffett Field, California

The objective of this research is to develop and validate accurate, user-oriented viscous CFD codes (with inviscid options) for three-dimensional, unsteady aerodynamic flows about arbitrary rotorcraft configurations. This effort draws heavily from the supercomputer capabilities of the National Aerodynamic Simulation project, and it will provide significantly better design and analysis tools to the rotorcraft industry. Better vehicles can be designed at lower cost, with less expensive testing, and with less risk.

Unsteady, three-dimensional Euler and Navier-Stokes codes are being developed, adapted, and extended to rotor-body combinations. Flow solvers are being coupled with zonal grid topologies, including rotating and nonrotating blocks. Special grid clustering and wave-fitting techniques have been developed to capture low-level radiating acoustic waves.

Significant progress has been made in computing the propagation of acoustic waves due to the interaction of a concentrated vortex and a helicopter airfoil. In this study, the need for higher-order schemes was firmly established in relatively inexpensive two-dimensional calculations. In three dimensions, the number of grid points required to capture the low-level acoustic waves becomes very large, so that large supercomputer memory becomes essential.

Good agreement was obtained between the numerical results obtained with a thin-layer Navier-Stokes code and experimental data from a model rotor. In addition, several nonrotating configurations that are sometimes proposed to simulate rotor blade tips in conventional wind tunnels were examined, and the complex flow around the radical tip shape of the world's fastest helicopter is under investigation. These studies demonstrate the flexibility and power of CFD to gain physical insight, study novel ideas, and examine various possibilities that might be difficult or impossible to set up in physical experiments.

As a prelude to studies of rotor-body aerodynamic interactions, a preliminary grid topology and moving-interface strategy has been developed. A new Euler / Navier-Stokes code using these techniques computes the vortical wake directly, rather than modeling it, as in most previous rotorcraft studies. Several hover cases were run for conventional and advanced-geometry blades. Numerical schemes using multi-zones and/or adaptive grids appear to be necessary to simulate the complex vortical flows in rotor wakes.

Although major improvements both in supercomputers and in codes will be required, the present trends and rate of progress indicate that practical computations of rotor-body combinations will be feasible in the mid-1990's.

*This research is performed by the Rotorcraft CFD Group, consisting of James Baeder, Ryan Border, Earl Duque, G.R. Srinivasan, and Sharon Stanaway, whose contributions are gratefully acknowledged.
NUMERICAL SIMULATION OF ROTORCRAFT

OBJECTIVE:
- DEVELOP AND VALIDATE CFD CODES FOR 3-D VISCOUS FLOWS ABOUT ARBITRARY ELASTIC ROTORCRAFT CONFIGURATIONS

APPROACH:
- DEVELOP AND VALIDATE EULER AND NAVIER-STOKES CODES FOR FUTURE NAS SUPERCOMPUTERS

BACKGROUND:
- PRESENT DESIGN AND ANALYSIS TOOLS FOR ROTORCRAFT ARE INADEQUATE
- TRIAL-AND-ERROR TESTING IS EXPENSIVE AND TIME-CONSUMING
- FOREIGN COMPETITION IS GROWING RAPIDLY
- CFD TECHNOLOGY FOR ROTORCRAFT LAGS FIXED-WING DEVELOPMENTS BY YEARS,
  BUT FUTURE SUPERCOMPUTERS WILL PERMIT REALISTIC ROTORCRAFT APPLICATIONS
NUMERICAL SIMULATION OF ROTORCRAFT

I. Very Difficult Problems

II. We’re Doing Great Work
    Specific Examples

III. We Have Great Plans
    Complete Aeroelastic Rotor–Body Combinations, etc.

IV. BUT...
    Hardware
    Software
    Algorithms
    Grids
    Turbulence Model

V. Summary and Conclusions
    Supercode RC222
ARMY/NASA ROTORCRAFT CFD PROGRAMS

- **INDIVIDUAL COMPONENTS**
  1. TRANSONIC AIRFOIL CHARACTERISTICS
  2. BLADE-VORTEX INTERACTIONS
  3. ROTOR TIP-VORTEX FORMATION
  4. 3-D ACOUSTIC PROPAGATION

- **COUPLED FINITE-DIFFERENCE CODES AND WAKE MODELS**

- **ISOLATED ROTOR** (*NAVIER STOKES*)

- **ROTOR-BODY COMBINATIONS**
UNSTEADY VORTEX INTERACTIONS

3-D ROTOR BLADE

2-D AIRFOIL, Λ₁ = 0

VORTEX PATH

HELICOPTER ROTOR BLADE

TRAILING TIP VORTEX
BERP ROTOR

$\alpha = 20^\circ, \quad Re = 1.5 \times 10^6, \quad M = 0.2$

E.P.N. DUQUE, U.S. ARMY AEROFIGHTDYNAMICS DIRECTORATE, AVSCOM
THE BRITISH EXPERIMENTAL ROTOR PROGRAM BLADE

\[ M = 0.2, \ \alpha = 13^\circ, \ \text{Re} = 1.5 \times 10^6, \ \text{NONROTATING} \]
TIP SHAPE COMPARISON

M = 0.6, alpha = 6 degrees, Inviscid
EULER HOVERING ROTOR CALCULATIONS
WITH AND WITHOUT COMPUTED VORTEX WAKE

$M_T = 0.794, \theta_c = 8^\circ$

INBOARD WAKE

---

WITH

W/O

EXP.

$Y/R = 0.80$

$Y/R = 0.89$

$Y/R = 0.96$
COMPUTATIONAL GRIDS FOR ROTORCRAFT

ROTATING OUTER GRID

ROTATING INNER GRID

FIXED GRID

ROTATING BLADE

ROTATING INNER GRID
COMPUTER SPEED AND MEMORY REQUIREMENTS
FOR 1 HOUR RUNS

MEMORY MWords

CRAY 2

ADV. TIP

AIRFOIL

AIRFOIL POLAR

ACOUSTICS

TIP

VORTEX

RETR. BL. STALL

ROTOR-BODY

2 BLADE ROTOR

SPEED, MFLOPS

1000

100

10

1

.1

1

10

100

1000

10^4

10^5

TODAY'S CAPABILITY

NAVIER-STOKES

FULL POTENTIAL
What Can We Do?

1. Accept Longer Run Times
2. Speed Up the Hardware
3. Change the Hardware and Software
   Different Architectures,
   Different Operating Systems,
   Different Languages,
   New / Improved Coding
4. Improve the Algorithms
   Increase Stability $\rightarrow$ *increase* $\Delta t$
   Reduce Numerical Dissipation
5. Use Dynamic, Solution – Adaptive Grids
6. Simplify the Turbulence Model
SUPERCODE  R C 2 2 2

- Two Blades + Body:
  $10^6$ grid pts/blade + $0.5 \times 10^6$ for body
  200 Mwords, 2 Gflops (4 μsec/grid pt/time step)

- Major Improvements Are Required
  20 Times Faster than Today's Unsteady Navier–Stokes Codes

  $\Rightarrow$ $\Delta t$ 10 times larger (1° azimuth per time step)
  $\Rightarrow$ Flow solver 2 times faster

Rotating and Nonrotating Grid Zones
Solution – Adaptive Grids, Minimum Artificial Dissipation
Near – Wake Vortex Capturing, Far – Wake Modeling
Improved Transition Modeling and Separation Prediction

- Flow Solver Coupled with Finite – Element Structural Model
ROTORCRAFT CFD PROJECTIONS
FOR 1 HOUR RUNS

- ADVERTISED
- REALISTIC

1988 ALGORITHMS, OPTIMISTIC HARDWARE TRENDS
IMPROVED ALGORITHMS, CURRENT HARDWARE TRENDS

SPEED, MFLOPS

SUMMARY AND CONCLUSIONS

• CFD IS VIABLE AND USEFUL FOR ROTORCRAFT

• FUTURE DIRECTIONS
  - Detailed Study of BERP and Other Advanced Tips
  - Rotor – Body Interactions
  - Improved Wake Computations
  - Increased Collaboration with Industry
  - New Tilt – Rotor Initiatives

• CONCERNS AND LIMITATIONS
  - Manpower – Trained in Both CFD and Rotorcraft
  - Far – Field Aeroacoustics and Structural Coupling
  - Wake Capturing vs. Wake Modeling
  - Turbulence Models
  - Grids for Complex Bodies in Relative Motion
  - Code Validation, Accuracy, and Reliability
  - Computer Power -- CPU and Clock Time
  - Mass Storage, Post – Processing, and Graphical Display
    of 3 – D Time – Dependent Results

• PRACTICAL ROTOR – BODY COMBINATIONS BY MID – 1990’s
CALCULATION OF THE ROTOR INDUCED DOWNLOAD ON AIRFOILS

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ABSTRACT

Interactions between the rotors and wing of a rotary wing aircraft in hover have a significant detrimental effect on its payload performance. The reduction of payload results from the wake of lifting rotors impinging on the wing, which is at -90 degrees angle of attack in hover. This vertical drag, often referred as download, can be as large as 15% of the total rotor thrust in hover.

The rotor wake is a three-dimensional, unsteady flow with concentrated tip vortices. With the rotor tip vortices impinging on the upper surface of the wing, the flow over the wing is not only three-dimensional and unsteady, but also separated from the leading and trailing edges.

A simplified two-dimensional model was developed to demonstrate the stability of the methodology. The flow model combines a panel method to represent the rotor and the wing, and a vortex method to track the wing wake. A parametric study of the download on a 20% thick elliptical airfoil below a rotor disk of uniform inflow was performed. Comparisons with experimental data are made where the data are available. This approach is now being extended to three-dimensional flows. Preliminary results on a wing at -90 degrees angle of attack in free stream is presented.
SCHEMATIC OF ROTOR/WING FLOW FIELD

- Recirculation
- Fountain
- Separated flow under wing
- Chordwise flow at wing tip
- Spanwise flow at wing root
TWO-DIMENSIONAL ANALYSIS FORMULATION

• DOUBLET PANELS ON ROTOR, VORTICITY PANELS ON AIRFOIL, AND POINT VORTICES IN WAKE

• UNSTEADY CALCULATION
  --- IMPULSIVELY STARTED FLOW
  --- TIME STEPPING FOR FOLLOWING SOLUTIONS

• BOUNDARY CONDITION
  --- KNOWN NORMAL VELOCITY DISTRIBUTION ON ACTUATOR DISK
  --- CONSTANT STREAM FUNCTION ALONG AIRFOIL
  --- ZERO TOTAL VORTICITY IN FLOW FIELD

[Diagram showing rotor, airfoil, known velocity distribution, rotor wake, wing wake, and ground]
TWO-DIMENSIONAL ANALYSIS FORMULATION
CONTINUED

• KUTTA CONDITION

--- ROTOR WAKE STRENGTH
determined by total
pressure difference across
slipstream: \( \Gamma_r = \gamma_r \ V_r \Delta t \)

--- AIRFOIL WAKE STRENGTH
related to strength of
bound vorticity at
separation point: \( \Gamma_a = \gamma_s \ V_s \Delta t \)

• TOTAL PRESSURE VARIATION
across rotor slipstream
and airfoil wake

\( \Delta P_r = \rho \ V_r \ \gamma_r \)

\( \Delta P_a = \rho \ V_s \ \gamma_s \)
NACA 64A223 AIRFOIL (XV-15 WING) IN FREE STREAM

-90 DEGREE ANGLE OF ATTACK
25% CHORD FLAP DEFLECTED AT 45 DEGREE
NACA 64A223 AIRFOIL (XV-15 WING) IN FREE STREAM

-90 DEGREE ANGLE OF ATTACK
25% CHORD FLAP DEFLECTED AT 45 DEGREE

SURFACE PRESSURE DISTRIBUTION
AIRFOIL/ROTOR INTERACTION: EFFECT OF ROTOR/AIRFOIL SPACING
ELLIPTICAL AIRFOIL

\[ R \]

\[ z \]

\[ \frac{\text{DOWNLOAD/THRUST}}{\text{ROTOR AREA/WING AREA}} \]

- 2-D CALCULATION
- 3-D EXPERIMENTAL DATA (Felker)
AIRFOIL/ROTOR INTERACTION: EFFECT OF ROTOR HEIGHT ABOVE GROUND
ELLiptical AIRFOIL

\( h \)

\( R \)

\( \frac{h}{R} \)

\( \text{CALCULATION} \)

\( \text{EXPERIMENTAL DATA (Fradenburg)} \)

\( \text{EXPERIMENTAL DATA (Marr)} \)
THREE-DIMENSIONAL ANALYSIS FORMULATION

- CONSTANT SOURCE AND DOUBLET PANELS ON WING, DOUBLET PANELS IN WAKE

- UNSTEADY CALCULATION
  --- IMPULSIVELY STARTED FLOW
  --- TIME STEPPING FOR FOLLOWING SOLUTIONS

- WAKE CORE SIZE GROWS WITH AGE
  \[ r_0 \sim \sqrt{t} \]

- BOUNDARY CONDITIONS
  --- FLOW TANGENCY
  --- VELOCITY POTENTIAL JUMP ACROSS BODY PANEL = \( \Phi/2 \)

- KUTTA CONDITION
  WAKE STRENGTH, \( \mu_w = \mu_u - \mu_L \)
ELLiptical Wing in free stream

-90 Degree angle of attack
Aspect ratio = 4.0

Perspective view

View from wing tip
ELLiptical Wing in Free Stream (continued)

SIDE VIEW

View FROM Beneath
FUTURE WORK

• ROTOR MODEL

--- ACTUATOR DISK MODEL
LINEAR DOUBLET PANELS IN STREAMWISE DIRECTION FOR ROTOR WAKE

--- ROTOR BLADE MODEL
DOUBLET PANELS ON ROTOR BLADE TO INCLUDE THE EFFECT OF BLADE TWIST, AND SENSE OF ROTOR ROTATION

• WAKE MODEL

--- AMALGAMATE AND REDISTRIBUTE WAKE PANELS TO REDUCE COMPUTATIONAL TIME

--- DISCRETIZE FAR WAKE PANELS TO MODEL OSCILLATING WAKE
THREE-DIMENSIONAL VISCOUS DRAG PREDICTION
FOR ROTOR BLADES

CHING S. CHEN
NATIONAL RESEARCH COUNCIL
NASA AMES RESEARCH CENTER

SUMMARY

The state-of-the-art in rotor blade drag prediction involves the use of two-dimensional airfoil tables to calculate the drag force on the blade. One of the most serious problems with the current methods is that they cannot be used for airfoils that have yet to be tested. Most of the drag prediction methods also do not take the Reynolds number or the rotational effects of the blade into account, raising doubts about the accuracy of the results. This project addresses these problems with the development of an analytical method which includes the shape of airfoil, the effects of Reynolds number, and the rotational motion of the blade.
OBJECTIVES

• PROVIDE AN EFFICIENT ANALYSIS FOR ROTOR BLADE DRAG PREDICTION

• ENABLE ACCURATE DESIGN OF NEW, ADVANCED ROTOR SYSTEMS WITH IMPROVED PERFORMANCE
MOTIVATIONS

ROTOR BLADE DRAG PREDICTION CURRENTLY USES TWO-DIMENSIONAL AIRFOIL TABLES

MAJOR SHORTCOMINGS:
- CANNOT BE USED FOR AIRFOILS NOT YET TESTED
- NO REYNOLDS NUMBER OR ROTATIONAL EFFECTS INCLUDED

CURRENT APPROACH INCLUDES:
- AIRFOIL SHAPE
- REYNOLDS NUMBER EFFECTS
- ROTATIONAL MOTION OF BLADE
RELATION OF COMPUTATIONAL DOMAIN OF INVISCID ANALYSIS
AND ROTOR WAKE

The computational domain of the inviscid analysis
THE COUPLING SCHEME OF VISCOUS, INVISCID, AND FREE-WAKE METHODS
DIRECT APPROACH

FREE-WAKE

INDUCED ANGLE OF
ATTACK $\alpha_i$

DIRECT

$V_\delta = \frac{1}{\rho_\theta} \frac{d(p_\theta u_\theta \delta^*)}{ds}$

$\tan \alpha_{BL} = \pm \left(\frac{V_\delta}{U_c}\right)$

INVISCID

$\alpha_{BL}$

VISCOUS

$\delta^*$
UNSTEADY, COMPRESSIBLE, THREE-DIMENSIONAL BOUNDARY-LAYER EQUATIONS

ROTATING REFERENCE FRAME

X-MOMENTUM EQUATION

\[ \rho (u_t + uu_x + vu_y + wu_z - 2w\Omega - x\Omega^2) = -p_x + (\mu u_y)_y \]

Z-MOMENTUM EQUATION

\[ \rho (w_t + uw_x + vw_y + ww_z + 2u\Omega - z\Omega^2) = -p_z + (\mu w_y)_y \]

PERFECT GAS RELATION

\[ p = \rho RT \]

ENERGY EQUATION

\[ C_pT + \frac{1}{2}(u^2 + v^2 + w^2) = \text{CONST} \]

CONTINUITY EQUATION

\[ \rho_t + (\rho u)_x + (\rho v)_y + (\rho w)_z = 0 \]
THE COUPLING SCHEME OF VISCOUS, INVISCID, AND FREE-WAKE METHODS
INVERSE APPROACH

FREE-WAKE

INDUCED ANGLE OF ATTACK $\alpha_1$

INVISCID

$\alpha_{BL}$

VISCOUS

TRANSPERSION ANGLE $\delta^*$

$\tan \alpha_{BL} = \pm \left(\frac{V_\delta}{U_e}\right)$

$BINARY LAYER$ $\tau_{w_i}^{n+1} = \tau_{w_i}^n + \omega (p_{v_i}^n - p_{i_i}^{n+1})$ $\omega = 5$

$WAKE$ $u_{wc_i}^{n+1} = u_{wc_i}^n + \omega (p_{i_i}^n - p_{i_i}^{n+1})$ $\omega = 1$
COMPARISON OF PREDICTED AND MEASURED DRAG COEFFICIENT FOR NACA 0012 TWO-DIMENSIONAL AIRFOIL FLOWS

- **NUMERICAL, \( RE=9 \times 10^5 \)**
- **NUMERICAL, \( RE=9 \times 10^6 \)**
- **TEST, \( RE=10^6 \text{ to } 10^7 \)**

![Graph showing comparison of predicted and measured drag coefficients for NACA 0012 airfoil flows.](image-url)
COMPARISON OF Cp DISTRIBUTION WITH AND WITHOUT BOUNDARY-LAYER INTERACTION
TIP MACH NUMBER = 0.9, r/R = 0.8453
COMPARISON OF $C_p$ DISTRIBUTION WITH AND WITHOUT
BOUNDARY-LAYER INTERACTION
TIP MACH NUMBER = 0.9, $r/R = 0.9759$
VELOCITY VECTOR PLOT SHOWING SEPARATION BUBBLE
AT ROOT OF SHOCK

TIP MACH NUMBER = 0.925, r/R = 0.9759, AR = 13.71
VELOCITY VECTOR PLOT SHOWING SEPARATION REGION
AT TRAILING EDGE
TIP MACH NUMBER = 0.925, r/R = 0.9759, AR = 13.71
COMPARISON OF PREDICTED AND MEASURED TORQUE  
FOR A NONLIFTING, HOVERING ROTOR  
TWO BLADES, RECTANGULAR NACA 0012 BLADE,  
RADIUS = 3.428 FT, AR = 13.71

![Graph showing comparison of predicted and measured torque versus tip Mach number. The graph includes data points and a numerical results line.](image-url)
FUTURE WORK

- SIMULATE NONLIFTING ROTOR FLOWS WITH ADVANCED BLADE PLANFORMS, AIRFOILS, AND TWIST DISTRIBUTIONS

- INCORPORATE FREE-WAKE ANALYSIS INTO VISCOUS-INVIScid APPROACH TO SIMULATE LIFTING ROTOR FLOWS

- INVESTIGATE EFFECTS OF ROTATIONAL MOTION ON DEVELOPMENT OF BOUNDARY-LAYER
Progress Toward the Development of an Airfoil Icing Analysis Capability

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The NASA-Lewis aircraft icing analysis program is composed of three major sub-programs. These sub-programs are ice accretion simulation, performance degradation evaluation, and ice protection system evaluation. These topics cover all areas of concern related to the simulation of aircraft icing and its consequences. The motivation for these activities is twofold, reduction of time and effort required in experimental programs and the ability to provide reliable information for aircraft certification in icing, over the complete range of environmental conditions. In addition to the analytical activities associated with development of these codes, several experimental programs are underway to provide verification information for existing codes. These experimental programs are also used to investigate the physical processes associated with ice accretion and removal for improvement of present analytical models. The NASA-Lewis icing analysis program is thus striving to provide a full range of analytical tools necessary for evaluation of the consequences of icing and of ice protection systems.

Recently, two of these tools were used to produce a computational evaluation of the ice accretion process and resulting performance changes for a NACA0012 airfoil. The ice accretion code, LEWICE, provided the ice shape geometry at several points in time during the simulated icing encounter. The predicted shapes are a function of several environmental input parameters, including airspeed, temperature, water droplet size and distribution, liquid water content, and duration of the encounter. These ice shape geometries are then used as input for a Navier-Stokes analysis code, ARC2D, which calculates the flowfield and determines changes in performance characteristics of the airfoil. Presently, there is no direct link between the two codes and all interfacing is done by the user. One of the objectives of the icing analysis program is to combine codes such as these into a comprehensive icing analysis method. Work in this area is currently underway via a number of grant supported activities.
STEPS IN AIRFOIL ICING ANALYSIS METHODOLOGY

INVISCID, INCOMPRESSIBLE FLOWFIELD

DROPLET TRAJECTORIES

VISCOUS FLOWFIELD

ICE ACCRETION

LEWICE
KEY ASPECTS OF AIRFOIL ICING

THICK, DISTORTED BOUNDARY LAYER
FLOW RE-ATTACHMENT

SEPARATED FLOW ZONE

SURFACE ROUGHNESS
AERODYNAMIC PERFORMANCE DEGRADATION DUE TO ICING
MULTIZONE MODEL OF ICE ACCRETION PROCESS

ZONE B
LARGE SURFACE ROUGHNESS
NO WATER FLOW

ZONE A
NO SURFACE ROUGHNESS
WATER FLOW

TRANSITION REGION
ZONE C
VARYING ROUGHNESS

CD-88-38184
CONTROL VOLUME ANALYSIS OF ICE ACCRETION PROCESS

- Convection
- Water flow out of CV
- Evaporation
- Impinging water
- Conduction
- Water flow into CV
- Ice layer

CD-88-38180
COLLECTION EFFICIENCY COMPARISONS

LOCAL IMPINGEMENT EFFICIENCY, $\beta$

SURFACE DISTANCE, $s$

EXPERIMENTAL
NAVIER-STOKES FLOWFIELD
POTENTIAL FLOW PREDICTION

CLEAN CYLINDER

"ICED" CYLINDER

CD-88-38179
COMPARISON OF CALCULATED AND MEASURED HEAT TRANSFER COEFFICIENTS ON SMOOTH SURFACE "ICED" CYLINDER MODEL

![Graph showing comparison of experimental and predicted Nusselt numbers against cylinder angle.](chart.png)
COMPARISON OF ICE SHAPE PREDICTIONS WITH AIRFOIL ICING DATA

CALCULATED
LWC = 1.02 g/m$^3$

MVD = 12 μm

$V_\infty = 52$ m/sec

T$\infty = -26$ °C

CALCULATED
LWC = 1.20 g/m$^3$

MVD = 20 μm

$V_\infty = 89$ m/sec

T$\infty = -11$ °C

CD-88-38181
EFFECT OF TURBULENCE MODEL ON NAVIER-STOKES PREDICTIONS
OF LEADING EDGE PRESSURE DISTRIBUTIONS, $\alpha = 0^\circ$
EFFECT OF BOUNDARY LAYER TRANSITION SPECIFICATION ON NAVIER-STOKES PREDICTED VELOCITY PROFILES IN SEPARATION-REATTACHMENT ZONE, $\alpha = 0^\circ$
RESULTS OF GRID GENERATION STUDY

GRID SPACING

<table>
<thead>
<tr>
<th>ALONG SURFACE</th>
<th>DENSE L.E.</th>
<th>EVEN</th>
</tr>
</thead>
<tbody>
<tr>
<td>TO SURFACE</td>
<td>NORMAL</td>
<td>NORMAL</td>
</tr>
</tbody>
</table>

GRID CODE

- DENSE L.E.: NORMAL
- EVEN: NORMAL
- HYPGRID
- GRAPE

Graphs showing the variation of $C_l$ and $C_d$ with $\alpha$.
COMPARISON OF ICED AIRFOIL CODE PREDICTIONS WITH EXPERIMENTAL MEASUREMENTS

- Interactive Boundary Layer (IBL)
- Navier-Stokes (NS)
- Experiment

Lift coefficient, $C_{l}$ vs. Angle of Attack, deg $\alpha$

Drag coefficient, $C_{d}$ vs. Angle of Attack, deg $\alpha$
CONCLUDING REMARKS

- First generation airfoil icing capability exists

- Code validation activities are ongoing
  Droplet trajectories / impingement
  Ice accretion
  Aerodynamic performance

- Supporting analytical/experimental efforts underway to improve physical modeling in codes
  Movies/photographs of ice accretion
  Ice surface roughness

- Extension to 3D icing analysis has been initiated
The Breakup of Trailing-Line Vortices

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It is now known that Batchelor's trailing-line vortex is extremely unstable to small amplitude disturbances for swirl numbers in the neighborhood of .83. We present results of numerical calculations that show the response of the vortex in this range of swirl numbers to finite amplitude, temporal, helical disturbances. Phenomena observed include: 1) ejection of axial vorticity and momentum from the core resulting in the creation of secondary, separate vortices; 2) a great intensification of core axial vorticity and a weakening of core momentum; 3) the production of azimuthal vorticity in the form of a tightly wrapped spiral wave. The second phenomenon eventually stabilizes the vortex, which then smooths and gradually returns to an axisymmetric state. The calculations are mixed spectral-finite-difference, fourth-order accurate, and have been carried out at Reynolds numbers of 1000-2000. Some linearized results will also be discussed in an attempt to explain the process of vortex intensification.
Applications

- Axisymmetric evolution of vortices, jets, and wakes.
- 3D instability of axisymmetric flows (weakly nonlinear).
- Spiral and axisymmetric vortex breakdown - strongly nonlinear instabilities.
- Acoustic excitation of swirling jets.
- Mixing caused by vortices - effects on combustion.
Numerical Methods

- 3D direct numerical simulation using primitive variables.
- Unbounded cylindrical coordinates - use of mapping $r = \tan \lambda$.
- Mixed spectral and finite difference methods
  - Azimuthal: spectral ($\exp in\theta$).
  - Axial: spectral ($\exp i\alpha x$) or 2nd order FD.
  - Radial: spectral ($\sin^n 2\lambda \cos 2j\lambda$) or 4th order FD.
- Fourth order accurate (Runge-Kutta) in time.
Batchelor's Trailing-Line Vortices

- Defined by axial velocity $= \exp(-r^2)$, axial vorticity $= q \exp(-r^2)$.
- Model for aircraft trailing line vortices, created in laboratory.
- Very unstable in some ranges of $q$. \( q \approx 0.85 \) most unstable.
- From inviscid theory, all azimuthal wavenumbers unstable.
  
  As $n \to \infty$ \( c_i \to 0.4 \).

  As $n \to \infty$ most unstable axial wavenumber $\to 0.52n$

- From viscous theory, $c_i$ modified by $O(R^{-1})$. \# unstable waves $O(R^{3/5})$. 
Numerical Solution

- Quasi-3D calculation can capture all the most unstable modes.
- Navier Stokes equations have helical solutions:

\[ \sum_{n=-\infty}^{n=+\infty} f_n(r,t) \exp in(\beta x - \theta) \]

- Calculations have \( q = .82, \beta = .52, R = 1600. \)
- Calculations spectral in \( x \) and \( \theta \), fourth order in \( \lambda \).
Features of Solution

- Initially, elliptical deformation of vortex. Helical displacement from center line.
- Kinematic deformation of vortex then produces spiral structure.
- Axial divergence intensifies axial vorticity, is associated with azimuthal vorticity.
- "Turbulent" patches form at vortex outer edges.
- In later stages, viscous diffusion weakens spiral structure. Turbulent patches separate from vortex. Vortex core remains intense.
- Intensified vortex returns to axisymmetric state.

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This publication is a collection of the presentations given at the NASA Computational Fluid Dynamics (CFD) Conference held at NASA Ames Research Center, Moffett Field, California, March 7-9, 1989. The objectives of the conference were to disseminate CFD research results to industry and university CFD researchers, to promote synergy among NASA CFD researchers, and to permit feedback from researchers outside of NASA on issues pacing the discipline of CFD. The focus of the conference was on the application of CFD technology but also included fundamental activities. The conference was sponsored by the Aerodynamics Division, Office of Aeronautics and Space Technology (OAST), NASA Headquarters, Washington, D.C. 20546.

The conference consisted of twelve sessions of papers representative of CFD research conducted within NASA and three non-NASA panel sessions. For each panel session, the panel membership consisted of industry and university CFD researchers. A summary of the comments made during the panel sessions has been included in this publication.

Volume 1 contains the papers given in Sessions I-VI. Volume 2 covers Sessions VII-XII.