TECHNOLOGY FOR THE FUTURE:
In-Space Technology Experiments Program

Compiled by
Roger A. Breckenridge
Lenwood G. Clark
Kelli F. Willshire
and Sherwin M. Beck
NASA Langley Research Center
Hampton, Virginia

Lisa D. Collier
CTA, Inc.
Hampton, Virginia

Proceedings of OAST IN-STEP 88 workshop
sponsored by the National Aeronautics and
Space Administration and held in
Atlanta, Georgia
December 6–9, 1988

JUNE 1991

NASA
National Aeronautics and
Space Administration
Langley Research Center
Hampton, Virginia 23665-5225
Preface

The major space goal of the National Aeronautics and Space Administration's Office of Aeronautics and Space Technology (OAST) is to provide enabling technologies—validated at a level suitable for user-readiness—for future space missions, in order to ensure continued U.S. leadership in space. An important element in accomplishing this goal is the In-Space Technology Experiments Program (IN-STEP), whose purpose it is to explore and validate, in space, advanced technologies that will improve the effectiveness and efficiency of current and future space systems.

On December 6 through 9, 1988, almost 400 researchers, technologists and managers from U.S. companies, universities and the government participated in the OAST IN-STEP 88 Workshop. The participants reviewed the current in-space technology flight experiments, identified and prioritized the technologies that are critical for future national space programs and that require verification or validation in space, and provided constructive feedback on the future plans for the In-Space Technology Experiments Program. The attendees actively participated in the identification and prioritization of future critical space technologies in eight major discipline theme areas. The content presented in the two parts of this NASA Conference Publication (CP), each under separate cover, reflect an overview of the workshop participants' efforts to review IN-STEP planning for the future of the program. These critical space technologies will help focus future solicitations for in-space flight experiments.

At the workshop, Dr. Harrison H. Schmitt emphasized that the nations which effectively exploit the advantages of space will lead human activities on Earth. OAST has worked closely with the aerospace community over the last few years to utilize the Space Shuttle, expendable launch vehicles, and, in the future, Space Station Freedom, for experimentation in space in the same way that we utilize wind tunnels to develop aeronautical technologies. This close cooperation with the user community is an important, integral part of the evolution of the In-Space Technology Experiments Program which was originated to provide access to space for technology research and for experimentation by the entire U.S. aerospace community.

The PREFACE edited for this NASA Conference Publication is based on the IN-STEP 88 WORKSHOP handout foreword written by Dr. Leonard Harris, Chief Engineer, Office of Aeronautics and Space Technology.

1 The Office of Aeronautics and Space Technology has since been renamed the Office of Aeronautics, Exploration and Technology (OAET). In conjunction with this change, the scope of the Human Exploration Initiative (HEI) has been broadened and renamed the Space Exploration Initiative (SEI).

* The IN-STEP 88 Workshop was conducted by the Space Station Freedom Office of the Langley Research Center. Questions regarding this workshop should be directed to Dr. Roger A. Breckenridge, Deputy Manager, Space Station Freedom Office, M.S. 288, NASA Langley Research Center, Hampton, Virginia, 23665.
This Page Intentionally Blank
Introduction

NASA's Office of Aeronautics and Space Technology (OAST) conducted a workshop December 6-9, 1988, on the In-Space Technology Experiments Program (IN-STEP) in Atlanta, Georgia. The purpose of this workshop, IN-STEP 88, was to identify and prioritize space technologies that are critical for future national space programs and which require validation in the space environment. A secondary objective was to review the current NASA (In-Reach) and industry/university (Out-Reach) experiments.

Finally, the aerospace community was asked to review and comment on the proposed plans for continuation of the In-Space Technology Experiments Program itself. In particular, this review included the proposed process for focusing the next experiment selection on specific, critical technologies as well as the process for implementing associated hardware development and integration on the Space Shuttle vehicle.

The product of the workshop was a prioritized listing of the critical space technology needs in each of eight technology disciplines. These listings were the cumulative recommendations of nearly 400 participants—including researchers, technologists and managers—from aerospace industries, universities and government organizations. The identification and prioritization of the critical space technology needs were initiated by assigning NASA chairpersons (theme leaders) to the eight major technology discipline themes requiring consideration. These themes were as follows:

1. Space Structures
2. Space Environmental Effects
3. Power Systems and Thermal Management
4. Fluid Management and Propulsion Systems
5. Automation and Robotics
6. Sensors and Information Systems
7. In-Space Systems
8. Humans in Space

In order to afford further structure within each theme, the chairpersons divided their themes into three theme elements each. The theme element concept allowed focused technical discussions to occur within the broad discipline themes. For each theme element, the theme leader selected government, industry and university experts to present the critical space technology needs of their respective organizations. The presentations were reviewed and discussed by the theme audiences (other members of the aerospace community), and prioritized lists of the critical technologies in need of verification and validation in space were established for each theme element. The comments and conclusions for each theme were incorporated into a summary listing of the critical space technology needs as well as associated flight experiments representing the combined inputs of the speakers, the audience, and the theme leader.

The critical space technology needs and associated space flight experiments identified by the participants provide an important part of the strategic planning process for space technology development and provide the basis for the next solicitation for space technology flight experiments. The results of the workshop will be presented in the IN-STEP Selection Advisory Committee in early 1989. This committee will review the critical technology needs, the funding available for the program, and the space flight opportunities available to determine the specific technologies for which space flight experiments will be requested in the next solicitation.
Conference Publication Content Description, Parts 1 and 2

The proceedings handbooks were organized as three presentation categories in four volumes: (1) Overview (Executive Summary volume), (2) In-Reach/Out-Reach experiments and the experiment integration process (Volume I), and (3) critical technology presentations (Volumes II and III). For presentation in this NASA Conference Publication (CP), a two-part set (under separate covers), the Executive Summary and Volume I are combined in Part 1 and Volumes II and III are combined in Part 2.

Part 1

Keynote Address — Part 1 of the IN-STEP 88 CP set opens with the keynote address presented at the workshop banquet by Dr. Harrison Schmitt, a former U.S. Senator and Apollo astronaut, on the 16th anniversary of his lunar launch (Apollo 17). In his presentation, Dr. Schmitt outlined his vision for the future of the U.S. space program by describing a Millennium Project which would combine space ventures to the Moon, to Mars, and to planet Earth.

Executive Summary — The Executive Summary (first half of Part 1) contains the welcome and workshop instructions, strategic planning for the in-space technology experiments, an overview of the space technology experiments being conducted in OAST as well as the solicitation process for IN-STEP, the proposed accommodation process for Space Station Freedom, and the critical-technology-needs summaries for each theme. These summaries are presented in a standardized format version of the lists prepared in "real-time" at the workshop.

The Welcome and Workshop Instructions describes the purpose, the process, and the product intended for the workshop. The Space Strategic Planning process describes the OAST space research and technology base programs which generate new technology concepts in the major discipline areas, the new focused programs of the Civil Space Technology Initiative (CSTI) as well as the Pathfinder, and provides funding for the industry, university and NASA space technology experiments. Overview charts of current OAST sponsored space flight experiments and specific information regarding the IN-STEP solicitation process are provided to establish an understanding of space technologies currently validated and the proposed approach for initiating new experiments.

Brief overviews of the objectives, technology needs/backgrounds, descriptions, and development schedules for current industry, university and NASA space technology experiments are presented in the second half of Part 1 (Volume I of the original workshop handbook set). This was a very important part of the workshop, providing an opportunity for the aerospace community to interact with experimenters and provide feedback on the flight experiments. An overview of the user/payload integration and accommodation process being established for use on Space Station Freedom is included in the content of Part 1 Experiment Descriptions to promote better understanding within the space experiment community, and presentations describing the experiment integration process are presented at the end of Part 1.

Part 2

Critical Technologies — Part 2 of the IN-STEP 88 CP set combines the contents of Volumes II and III of the original handbook set. This book contains a theme introduction by each chairperson, critical technology presentations for each of the theme's three elements of technical focus, and summary listings of critical space technology needs for each theme. The introduction for each theme includes the chairperson's overview and instructions for the participants. The critical technology presentations, along with summaries listing the critical space technology needs and associated flight experiments, are presented as previously described.
### Contents

**By Presentation Title & Speaker**

#### Part 1: IN-STEP 88 Executive Summary

IN-STEP 88 Keynote Address: *Mission to Earth, Moon, and Mars* ........................................ 1
Dr. Harrison H. Schmitt

**Workshop Opening:**

- Workshop Purpose and Agenda ................................................................. 12
  Dr. Leonard Harris, Chief Engineer, OAST, NASA Headquarters
- In-Space Technology Experiments in NASA’s Strategic Planning† ............................. 14
  Dr. Judith H. Ambrus, Assistant Director for Space, NASA Headquarters
- In-Space Technology Experiment Program .................................................. 34
  Jack Levine, Director, Flight Projects Division, OAST, NASA Headquarters
  Jon S. Pyle, Manager, In-Reach/Out-Reach Programs, NASA Headquarters
- Space Station *Freedom* User/Payload Integration & Accommodations ....................... 43
  Alan C. Holt, Dep. Dir. (Acting), User Integration Division,
  Utilization & Operations Group, Space Station Freedom Program Office

**Critical In-Space Technology Needs:**

<table>
<thead>
<tr>
<th>Category</th>
<th>Author(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Space Structures</td>
<td>Martin Mikulas, Jr., NASA Langley Research Center</td>
</tr>
<tr>
<td>Space Environmental Effects</td>
<td>Lubert J. Leger, NASA Johnson Space Center</td>
</tr>
<tr>
<td>Power Systems and Thermal Management</td>
<td>Roy McIntosh, NASA Goddard Space Flight Center</td>
</tr>
<tr>
<td>Fluid Management and Propulsion Systems</td>
<td>Lynn M. Anderson, NASA Lewis Research Center</td>
</tr>
<tr>
<td>Automation and Robotics</td>
<td>Antal K. Bejczy, Jet Propulsion Laboratory</td>
</tr>
</tbody>
</table>
| Sensors and Information Systems  | Martin M. Sokoloski, NASA Headquarters
  John Dalton, NASA Goddard Space Flight Center                                      |
| In-Space Systems                 | Jon B. Haussler, NASA Marshall Space Flight Center                         |
| Humans in Space                  | Remus Bretoi, NASA Ames Research Center                                     |

*Part 1 Contents Continued on Next Page*

† Dr. Ambrus’ presentation for the IN-STEP 88 Workshop was given by Dr. Harris.
Part 1: IN-STEP 88 Experiment Descriptions

In-Reach / Out-Reach Experiments and Experiment Integration Process

In-Reach / Out-Reach Experiments (by Theme):

1 SPACE STRUCTURES
- In-Space Structural Dynamics Evaluation of a Skewed-Scale Truss
  James H. Peebles, McDonnell Douglas Astronautics
  ................................................................. 78
- Middeck 0-Gravity Dynamics Experiment (MODE)
  Prof. Edward F. Crawley and Dr. David W. Miller, Massachusetts Institute of Technology
  ............................................................................... 81
- Measurement and Modeling of Joint Damping in Space Structures
  Steven L. Folkman and Frank J. Redd, Utah State University
  ............................................................................... 84
- Payload Vibration Isolation in Microgravity Environment
  Carl H. Gerhold and Richard M. Alexander, Texas A&M University
  ................................................................. 87
- Generic Pointing Mount
  Robert W. Bosley, Allied/Signal Aerospace Company
  ............................................................................... 90
- Space Station Structural Characterization Experiment
  James W. Johnson and Paul A. Cooper, NASA Langley Research Center
  ............................................................................... 96
- Inflatable Solar Concentrator Experiment
  Costa Cassapakis and Geoff Williams, L'Garde, Inc.
  ............................................................................... 99

2 SPACE ENVIRONMENTAL EFFECTS
- Measurement of Surface Reactions in the Space Environment
  L.R. Megili, Globesat, Inc.
  ............................................................................... 103
- Optical Properties Monitor (OPM) Experiment
  Donald R. Wilkes, John M. Cockerham & Associates
  ............................................................................... 106
- Experimental Investigation of Spacecraft Glow
  Gary Swenson, Lockheed Missiles & Space Company
  ............................................................................... 109
- Return Flux Experiment (REFLEX)
  Jack J. Triolo and Roy McIntosh, NASA Goddard Space Flight Center
  ............................................................................... 112
- Debris Collision Warning Sensors
  Faith Vilas and David Thompson, NASA Johnson Space Center
  ............................................................................... 115
- Thin Foil X-Ray Optics Space Environment Contamination Experiment
  Robert Petre, P.J. Seriemitsos, C.A. Glasser, NASA Goddard Space Flight Center
  ............................................................................... 118

3 POWER SYSTEMS AND THERMAL MANAGEMENT
- Sodium-Sulfur Battery Flight Experiment Definition
  Becky Chang, Ford Aerospace Corporation
  ............................................................................... 122
- Unitized Regenerative Fuel Cell
  Timothy A. Nalette, United Technologies Corporation
  ............................................................................... 125
  David Namkoong, Jerri Ling, Steve Johnson, Barbara Heizer, Tom Foster; NASA LeRC/Boeing
  ............................................................................... 128
- Investigation of Microgravity Effects on Heat Pipe Thermal Performance and Working Fluid Behavior
  George L. Fleischman, Hughes Aircraft Company
  ............................................................................... 131

Part 1 Contents Continued on Next Page

vi
Part 1: Experiment Descriptions (continued)

- A High-Efficiency Thermal Interface (using condensation heat transfer)
  Between a Two-Phase Fluid Loop and a Heat Pipe Radiator ........................................... 135
  John A. Pohner, TRW Space & Technology Group
- Moving Belt Radiator Dynamics ........................................................................................... 139
  W. Peter Teagan, Arthur D. Little, Inc.
- Liquid Droplet Radiator ........................................................................................................ 144
  Shlomo L. Pfeiffer, Grumman Space Systems

FLUID MANAGEMENT AND PROPULSION SYSTEMS

- Tank Pressure Control Experiment ....................................................................................... 148
  Michael D. Bentz, Boeing Aerospace
- Integrated Cryogenic Experiment (ICE) Microsphere Insulation Investigation ...................... 151
  Dean C. Read, Lockheed Missiles & Space Company
- Liquid Motion in a Rotating Tank ........................................................................................... 157
  Franklin T. Dodge, Southwest Research Institute
- Thermoacoustic Convection Heat Transfer .............................................................................. 160
  Prof. Masood Parang, University of Tennessee

AUTOMATION AND ROBOTICS

- Research and Design of Manipulator Flight Testbeds .......................................................... 162
  T.M. Depkovich, Martin Marietta Corporation
- Control of Flexible Robot Manipulators in Zero Gravity .................................................... 164
  Warren F. Phillips, Utah State University
- Jitter Suppression for Precision Space Structures .................................................................... 169
  Robert M. Laurensen, McDonnell Douglas
- Passive Damping Augmentation for Space Applications ....................................................... 173
  Dr. Thomas E. Alberts, Old Dominion University (Supported by 3M Corporation)

SENSORS AND INFORMATION SYSTEMS

- Development of Emulsion Chamber Technology .................................................................. 177
  John Gregory, University of Alabama in Huntsville
- Infrared Focal Plane Performance in the South Atlantic Anomaly ........................................ 181
  Frank Junga, Lockheed Missiles & Space Company
- Construction and In-Space Performance Evaluation of High Stability
  Hydrogen Maser Clocks .............................................................................................................. 184
  Robert F.C. Vessot, Smithsonian Astrophysical Observatory
- Acceleration Measurement and Management Experiment Definition .................................... 188
  Jan A. Bijvoet, University of Alabama in Huntsville
- Dynamic Spacecraft Attitude Determination with GPS ....................................................... 192
  Dr. Duncan B. Cox, Jr., Mayflower Communications Company, Inc.
- Stanford University / NASA Laser In-Space Technology Experiment (SUNLITE) ................. 196
  Robert L. Byer, Stanford University
Part 1: Experiment Descriptions (concluded)

**IN-SPACE SYSTEMS**
- Definition of Experiments to Investigate Fire Suppressants in Microgravity ........................................ 199
  Dr. James J. Reuther, Battelle Columbus Division
- Risk-Based Fire Safety Experiment Definition ........................................ 202
  George Apostolakis, University of California at Los Angeles
- Plasma Arc Welding in Space ................................................................. 204
  Boris Rubinsky, University of California at Berkeley
- Extra-Vehicular Activity Welding Experiment ........................................... 207
  Gary Schnittgrund, Rockwell International Corporation
- On-Orbit Electron Beam Welding Experiment ........................................... 213
  William Hooper, Martin Marietta Corporation
- Laser Welding in Space ................................................................. 216
  Dr. Gary L. Workman and Dr. William F. Kaukler, University of Alabama
- Liquid Encapsulated Float Zone Refining of Gallium Arsenide ......................... 219
  Edward Barocela, McDonnell Douglas Astronautics Company
- Vapor Crystal Growth Technology .................................................. 223
  Franz E. Rosenberger and Francis C. Wessling, University of Alabama (Supported by Boeing)

**HUMANS IN SPACE**
- Enhancement of In-Space Operations Using Spatial Perception Auditory Referencing (SPAR) ......................... 226
  Dr. Robert H.I. Blanks, Dr. Joie P. Jones, and Dr. Yasuhiro Torigoe; U. of California at Irvine
  Dr. William Douglas and Herb Helly, McDonnell Douglas Astronautics
- Definition of a Microbiological Monitor for Application in Space Vehicles ......................... 229
  Melvin V. Kilgore, Jr., and Dr. Robert J. Zahorchak; U. of Alabama in Huntsville
- Design of a Closed-Loop Nutrient Solution Delivery System for CELSS (Controlled Ecological Life Support Systems) Application ........................................... 232
  Dr. Steven H. Schwartzkopf, Lockheed Missiles & Space Company
  Mr. Mel W. Oleson, Boeing Aerospace Company
- Impact of Low Gravity on Water Electrolysis Operation ........................................... 234
  Franz H. Schubert, Life Systems, Inc.
- Experiment Integration Process Presentations ........................................... 237
  Clarke R. Prouty, NASA Goddard Space Flight Center

**Payload Integration Overview:**
- NSTS Integration and Operations .................................................. 244
  John C. O’Laughlin, NASA Johnson Space Center
- Complex Autonomous Payload Carriers ........................................... 253
  Clarke R. Routy, NASA Goddard Space Flight Center
- Hitchhiker Project Overview .................................................. 257
  T.C. Goldsmith, NASA Goddard Space Flight Center
- Middeck Payload Integration ........................................... 265
  John C. O’Laughlin, NASA Johnson Space Center
- KSC Payload Integration .................................................. 274
  Dean C. Zimmerman, NASA Kennedy Space Center
Part 2: Critical Technologies†
IN-STEP 88 Technology Themes

By Theme:

1 SPACE STRUCTURES
Background and Objectives:

- Theme Orientation and Recap of In-Space RE&E Workshop (Williamsburg, '85) ................. 291
  Martin Mikulas, Jr., NASA Langley Research Center

1.1 Structures:
- Air Force Structural Dynamics and CSI Technology Needs ........................................ 297
  Jerome Pearson, USAF Wright Aeronautical Laboratories
- Industry Perspective on Technology Needs for Space Structures ................................ 299
  Donald E. Skoumal and Richard M. Gates, Boeing Aerospace Company
- University Participation in In-Space Technology Experiments ..................................... 302
  K.C. Park, University of Colorado

1.2 Control/Structure Interaction (CSI):
- An Overview of the NASA Controls-Structures-Interaction Program .......................... 305
  J. Newsom, NASA Langley Research Center
  H. Waites, NASA Marshall Space Flight Center
  W. Layman, Jet Propulsion Laboratory
- Technology Development Needs: Industry Perspective ............................................. 308
  Carolyn S. Major, TRW Space & Technology Group
- The Need for Space Flight Experimentation in Control/Structure Interaction .................. 310
  Edward F. Crawley, Massachusetts Institute of Technology

1.3 Controls:
- Space Structures: Controls (Validation — Ground and In Space) .................................. 314
  Henry B. Waites, NASA Marshall Space Flight Center
- Industry Perspective on Control Technology Needs for Space Flight Verification ............ 316
  Irving Hirsch, Boeing Aerospace
- Experiments in Dynamics and Controls ........................................................................ 319
  Robert E. Skelton, Purdue University
- Space Structures Critical Technology Requirements .................................................... 323
  Martin Mikulas, Jr., NASA Langley Research Center

2 SPACE ENVIRONMENTAL EFFECTS
Background and Objectives:

- Theme General Content and Sub-Theme Definition .................................................... 330
  Lubert J. Leger, NASA Johnson Space Center

2.1 Atmospheric Effects and Contamination:
- Atmospheric Effects & Contamination: Government Perspective .................................. 333
  Bruce A. Banks, NASA Lewis Research Center

Part 2 Contents Continued on Next Page

† Part 2 of the IN-STEP 88 Workshop Conference Publication two-part set is under separate cover.
Part 2: Critical Technologies (continued)

2.1 Atmospheric Effects and Contamination (continued):
- Atmospheric Effects & Contamination Technology Development Needs .......................................................... 336
  Lyle E. Barciss, Martin Marietta Corporation
- Hyperthermal Interactions of Atmospheric Species with Spacecraft .............................................................. 338
  John Gregory, University of Alabama at Huntsville

2.2 Micrometeoroids and Debris:
- Detection and Measurement of the Orbital Debris Environment .............................................................. 341
  Faith Vilas, NASA Johnson Space Center
- Design Considerations for Space Debris: An Industry Viewpoint .............................................................. 343
  Dr. H.W. Babel, McDonnel Douglas Astronautics Company
- Space Debris Environment Definition ........................................................................................................ 346
  Dr. Robert D. Culp

2.3 Charged Particles and Electromagnetic Radiation Effects:
- Effects of Charged Particles and Electromagnetic Radiation on Structural Materials and Coatings ............... 349
  W.S. Slemp and S.S. Tompkins, NASA Langley Research Center
- Effects on Space Systems: Technology Requirements for the Future ......................................................... 352
  H. Garrett, Jet Propulsion Laboratory
- Electromagnetic and Plasma Environment Interactions: Technology Needs for the Future ..................... 354
  G. Murphy, Jet Propulsion Laboratory
- Space Environmental Effects Critical Technology Requirements .............................................................. 357
  Lubert J. Leger, NASA Johnson Space Center

3 POWER SYSTEMS & THERMAL MANAGEMENT

Background and Objectives:
- Review of Previous Workshops (Williamsburg '85, Ocean City '88) .......................................................... 362
  Roy McIntosh, NASA Goddard Space Flight Center

3.1 Dynamic and Nuclear Power Systems:
- Dynamic and Nuclear Systems .................................................................................................................. 370
  John M. Smith, NASA Lewis Research Center
- Dynamic & Nuclear Power Systems ........................................................................................................ 374
  Dr. J.S. Armijo, General Electric Astro Space Division
- Dynamic & Nuclear Systems .................................................................................................................. 377
  Prof. Mohamed S. El-Genk, University of New Mexico

3.2 Conventional Power Systems:
- Conventional Power Systems .................................................................................................................. 381
  Dr. Karl A. Faymon, NASA Lewis Research Center
- Conventional Power Systems .................................................................................................................. 384
  Stephen R. Peck, GE Astro Space Division
- Conventional Power Systems .................................................................................................................. 387
  R.F. Askew, Auburn University

Part 2 Contents Continued on Next Page

X
Part 2: Critical Technologies (continued)

3.3 Thermal Management:
- Government View: Spacecraft Thermal Management Requirements & Technology Needs .............................................................................................................. 390
  Dr. Tom Mahefkey, Air Force Wright Aeronautical Labs
- Thermal Management: An Industry Viewpoint .............................................................................................................. 393
  Ted J. Kramer, Boeing Aerospace Company
- Thermal Management Issues in Advanced Space Missions: University Viewpoint .............................................................................................................. 395
  Prof. Larry C. White, University of Houston
- Power Systems & Thermal Management Critical Technology Requirements .............................................................................................................. 398
  Roy McIntosh, NASA Goddard Space Flight Center

4 FLUID MANAGEMENT & PROPULSION SYSTEMS

Background and Objectives:
- Theme Organization and Purpose .............................................................................................................. 402
  Lynn M. Anderson, NASA Lewis Research Center
4.1 On-Orbit Fluid Management:
- Fluid Management Technology .............................................................................................................. 403
  John C. Aydelott, NASA Lewis Research Center
- Cryogenic Fluid Management Technology: An Industry Perspective .............................................................................................................. 405
  John R. Schuster, General Dynamics
4.2 Propulsion:
- Low Thrust Propulsion Space Experiments .............................................................................................................. 408
  J.R. Stone, NASA Headquarters, OAST
- Key Propulsion Technologies for In-Space Experiments .............................................................................................................. 411
  James H. Kelley, Jet Propulsion Laboratory
- In-Space Technology Experiments in Propulsion: The Role of Universities .............................................................................................................. 414
  Charles L. Merkle, Pennsylvania State University
4.3 Fluid Physics:
- Fluid Physics ................................................................................................................................. 416
  Jack A. Salzman, NASA Lewis Research Center
- Low-G Interface Configurations, Stability and Dynamics .............................................................................................................. 419
  Franklin T. Dodge, Southwest Research Institute
- The Case for Two-Phase Gas-Liquid Flow Experiments in Space .............................................................................................................. 423
  A.E. Dukler, University of Houston
- Fluid Management & Propulsion Systems Critical Technology Requirements .............................................................................................................. 424
  Lynn M. Anderson, NASA Lewis Research Center

5 AUTOMATION AND ROBOTICS

Background and Objectives:
- Subthemes: Robotics, Teleoperation, and Artificial Intelligence;
  Summary of Williamsburg Workshop ('85) .............................................................................................................. 433
  Antal K. Bejczy, Jet Propulsion Laboratory
Part 2: Critical Technologies (continued)

5.1 Robotic Systems:
- Robotics ................................................................. 443
  Al Meintel, NASA Langley Research Center
- Robotics ................................................................. 446
  T.M. Depkovich and J.R. Spofford, Martin Marietta Corporation
- Robots in Space ..................................................... 448
  Prof. Delbert Tesar, University of Texas at Austin

5.2 Teleoperations:
- Space Operations, Now and Future ................................ 451
  Charles R. Price, NASA Johnson Space Center
- Teleoperation .......................................................... 454
  Paul B. Pierson, General Electric Aerospace
- Multimode Operator Interfaces, Intelligent Displays,
  Hierarchical-Control Communication Time Delay Visual Perception Systems .......... 457
  Thomas B. Sheridan, Massachusetts Institute of Technology

5.3 Artificial Intelligence:
- In-Space Experiments in Artificial Intelligence .................. 459
  Dr. Peter Friedland, NASA Ames Research Center
  Nancy Sliwa, NASA Langley Research Center
- Artificial Intelligence: An Industry View ......................... 462
  David A. Rosenberg, ISX Corporation
- Artificial Intelligence .................................................. 465
  Dr. Robert Cannon, Stanford University
- Automation and Robotics Critical Technology Requirements .......... 467
  Antal K. Bejczy, Jet Propulsion Laboratory

6 SENSORS AND INFORMATION SYSTEMS

Background and Objectives:
- Themes and Criteria for Prioritization .............................. 472
  Martin M. Sokoloski, NASA Headquarters
  John T. Dalton, NASA Goddard Space Flight Center

6.1 Sensors:
- In-Space Experiments in Remote Sensing Systems ................ 474
  Martin M. Sokoloski, NASA Headquarters
- In-Space Sensor Technology Experiments .......................... 478
  E. David Hinkley, Hughes Aircraft Company
- LIDAR/Laser Sensors .................................................. 482
  Dr. Denis Killinger, University of South Florida

6.2 Communications:
- In-Space Experiments in Communication Systems ................ 485
  Martin M. Sokoloski, NASA Headquarters
- Space Laser Communication Experiments .......................... 488
  M. Ross, Laser Data Technology, Inc.
Part 2: Critical Technologies (continued)

6.2 Communications (continued):
- Coherent Optical Intersatellite Crosslink Systems ........................................... Vinay W.S. Chan, Massachusetts Institute of Technology
- ................................................................. 491

6.3 Information Systems:
- In-Space Experiments in Information Systems .................................................. John T. Dalton, NASA Goddard Space Flight Center
- ................................................................. 495
- Information System Panel DMS Perspectives — December '88 ......................... George Nossaman, IBM Federal Systems Division
- ................................................................. 499
- In-Space Experiments in Information Systems .................................................. Neil R. White, University of Colorado
- ................................................................. 503
- Sensors and Information Systems Critical Technology Requirements ............ Martin M. Sokoloski, NASA Headquarters
- John T. Dalton, NASA Goddard Space Flight Center
- ............. 506

IN-SPACE SYSTEMS

Background and Objectives:
- Theme Session Objectives and Prioritization Criteria ........................................... Jon B. Haussler, NASA Marshall Space Flight Center
- ................................................................. 512

7.1 Materials Processing:
- Materials Processing ......................................................................................... Larry Spencer, NASA Headquarters (MSAD)
- ................................................................. 516
- Floating-Point Crystal Growth in Space .............................................................. John T. Viola, Rockwell International
- ................................................................. 520
- Materials Processing — Cells and Cellular Products ............................................ David W. Sammons, University of Arizona
- ................................................................. 523

7.2 Maintenance, Repair and Fire Safety:
- Maintenance, Servicing and Repair in Space ..................................................... Ed Falkenhayn, NASA Goddard Space Flight Center
- ................................................................. 525
- Spacecraft Fire Safety for Advanced Spacecraft ................................................... Wallace W. Youngblood, Wyle Laboratories
- ................................................................. 528
- Maintenance, Servicing and Repair in Space ..................................................... Bob Dellacamera, McDonnell Douglas Space Systems Company
- ................................................................. 531

7.3 In-Space Systems:
- Payload Operations from the Perspective of Manned Space Flight .................. Dr. Jeffrey A. Hoffman, NASA Johnson Space Center
- ................................................................. 535
- Orbit Assembly Node ......................................................................................... Tom Styczynski and Lee R. Lunsford, Lockheed Missiles & Space Company
- ................................................................. 537
- In-Space Systems: Space Construction and Payload Operations ...................... Dr. George W. Morgenthaler, University of Colorado
- ................................................................. 540
- In-Space Systems Critical Technology Requirements .......................................... Jon B. Haussler, NASA Marshall Space Flight Center
- ................................................................. 543

Part 2 Contents Continued on Next Page
Part 2: Critical Technologies (concluded)

HUMANS IN SPACE

Background and Objectives:

- Overview: EVA, Performance, Life Support Systems ........................................ 546
  Remus N. Bretoi, NASA Ames Research Center

8.1 EVA / Suit:
- EVA Technology ........................................................................................................ 553
  Dr. Bruce W. Webbon and Bernadette Squire, NASA Ames Research Center

- Extra-Vehicular Activity / Suit ................................................................................. 556
  H.T. Fisher, Lockheed Missiles & Space Company

- EVA and Pressure Suit Technology .......................................................................... 560
  Prof. David L. Akin, Massachusetts Institute of Technology

8.2 Human Performance:
- Crew and Environmental Factors ........................................................................... 562
  Dr. Barbara G. Kanki, NASA Ames Research Center

- Artificial Gravity ........................................................................................................ 565
  Larry G. Lemki, NASA Ames Research Center

- Human Performance .................................................................................................. 568
  William R. Ferrell, University of Arizona

8.3 Closed-Loop Life Support Systems:
- Physical/Chemical Closed-Loop Life Support .......................................................... 571
  R.D. MacElroy, NASA Ames Research Center

- Closed-Loop Life Support: Industry Presentation .................................................... 573
  Thomas J. Slavin, Boeing Aerospace

- Physical/Chemical Closed-Loop Life Support .......................................................... 575
  Marvin W. Luttges and Louis Stodieck, University of Colorado

- Humans in Space Critical Technology Requirements ............................................. 578
  Remus N. Bretoi, NASA Ames Research Center

xiv
This Page Intentionally Blank
Mission to Earth, Moon, and Mars

Dr. Harrison H. Schmitt
Scientist, Administrator, Educator, Consultant on Space Initiatives
Former U.S. Senator and Lunar Module Pilot for Apollo 17

Harrison "Jack" Schmitt has the varied experience of a
geologist, scientist, astronaut, pilot, administrator, educator,
writer, and United States Senator.

He trained as a geologist and scientist at the California
Institute of Technology, as a Fulbright Scholar at the University
of Oslo, and at Harvard University, receiving his Ph.D. in
geology from Harvard in 1964 based on earlier field studies
conducted in Norway.

He was selected for the Apollo Scientist-Astronaut program
in 1965 and served as the Lunar Module Pilot for Apollo 17—the
last Apollo mission to the Moon.

Schmitt’s studies of the Valley of Taurus-Littrow on the
Moon in 1972, as well as his earlier scientific work, made
Schmitt one of the leading experts on the history of the
terrestrial planets. As the only scientist to go to the Moon, he
was also the last of twelve men to step on the Moon.

After organizing and directing the activities of the
Scientist-Astronaut Office and of the Energy Program Office for
NASA in 1973-1975, Schmitt fulfilled a long-standing commitment
by entering politics. He was elected to the U.S. Senate from his
home state of New Mexico in 1976.

In his last two years in the Senate, Senator Schmitt was
Chairman of the Senate Commerce Committee’s Subcommittee on
Science, Technology, and Space and of the Senate Appropriations
Committee’s Subcommittee on Labor, Health and Human Services, and
Education. He currently serves as a member of the Army Science
Board and as consultant to the National Strategic Materials and
Minerals Program Advisory Committee.

Harrison Schmitt is consulting, speaking, and writing on a
wide range of business, foundation, and government initiatives.
His principle activities are in the fields of technology, space,
defense, biomedicine, geology, and policy issues of the future.
He brings to the consideration of complex public and corporate
concerns a unique breadth of experience ranging from the
scientific to the practical and from the administrative to the
political.
Let us jump ahead to late January, 1990, and try to anticipate what should be the concluding paragraphs of the President's State of the Union Address to the Congress.

"Now, my fellow Americans, as your representatives assembled in these historic chambers know so well, there has been a rising tide of domestic and international political pressure in support of initiatives for the future. You have made us all increasingly aware that both vulnerabilities and opportunities in America's future and in the future of humankind require our urgent attention. The unfair inequities of the present still do and will always demand our concern and our compassion, however, many issues essential to the future well-being of our children and our country have been too long neglected.

"Therefore, over the next 60 days, I will send to the Congress a number of proposals that address long term structural changes in our approaches to education, the environment, retirement and health security, basic research, and other critical areas.

"Tonight, because of the central roles played by environment and space in the future of our children, I am calling on the Congress to provide the long term commitments necessary to undertake a specific project focused on the turn of the Third Millennium. Although this rare milestone is only 10 years away, the challenge has grown to for a Millennium Project that will match the times and the opportunities.

"Our Millennium Project, in which we invite the family of nations to join, will be the establishment of a permanent human outpost on Mars by 2010 and, by so doing, provide the technology base necessary to preserve the Earth's global environment.

"The creation of a permanent outpost on Mars will have as its primary purposes the eventual settlement of the planet Mars by free human beings and the provision of abundant and environmentally benign electrical power on Earth. The bridge between these two essential achievements is the development of helium-3 fusion
power plants on Earth fueled by the helium resources of the moon. This bridge of energy also provides, as by-products from the energy resources of the moon, the oxygen, hydrogen, and other consumable materials critical to sustaining the early settlers of Mars.

"Thus, our Millennium Project combines space ventures to the Earth, moon, and Mars into a single great human mission -- a mission to save the atmosphere, waters, and rainforests of Earth, a mission to settle the moon and utilize it resources for the benefit of all, and a mission to establish human civilization and freedom permanently on Mars.

"A draft treaty for international participation in The Millennium Project is being circulated among the nations of Earth. This treaty, tentatively called the INTERNARS Charter, proposes a participant based relationship between nations, users, and investors, modeled after the successful International Telecommunications Satellite or INTELSAT Agreements. It is the intention of the United States Government that an international conference to finalize the INTERNARS Charter will be convened by interested nations before the end of the year.

"Ladies and gentlemen and my fellow Americans, our commitment to the success of The Millennium Project must be unequivocal. It must include an equally unequivocal commitment to carry the sacred institutions of freedom with us as humankind expands into its larger home among the planets and the stars."

The recent return of American astronauts to space, as satisfying as it must be to those of you responsible, constitutes but a very small step in the repair of what can only be called a space policy disaster.

Challenger and the tragedy of its loss did not cause this policy disaster nor was it caused by the dedicated people of NASA and its contractors whatever errors in judgment may have been made. The now so obvious loss of momentum in the United States space program has been the result of a loss of will on the part of national leadership spanning almost two decades.

Humankind's first explorations of the moon and of space near the Earth between 1968 and 1972 were also the species first clear steps of evolution into the solar system and eventually into the galaxy. As the Pueblo Indians tell the lesson of their ancestors, "We walk on the Earth, but we live in the sky."
Early explorers of the sky not only took their eyes and minds into space and became the eyes and minds of billions of other explorers on the starship Earth, but they began the long process of transplanting civilization into space. This fundamental change in the course of history has occurred as humans also have gained new insight into themselves and their first planetary home.

Limitless seas in space exist not only as new frontiers but as new challenges for humankind. The nations on Earth which effectively utilize technology to exploit the economic and military advantages of the new ocean of space will dominate human activities on this planet well into the next century, if not indefinitely. Those nations also will provide the irreversible templates for the social and political evolution of civilization beyond the next century far into the Third Millennium.

The first response to this challenge in space by the United States under President John F. Kennedy's leadership appeared to recognize the historic proportions of the contest. The leading involvement of the United States in space initially insured that the traditions of free institutions would be represented. As a consequence, at the high point of the Apollo Program, the United States verged on the establishment of bases on the moon, research stations in earth orbit, and the statement of a realistic goal of a foothold on Mars by the end of the Century. In the motto of the last Apollo mission to the moon in December 1972, the conclusion of the Apollo Program truly could have been "The End of the Beginning."

The opportunity given to humankind by the Apollo Program and its generation passed by. Consequently, the responsibility to re-ignite Kennedy's torch for space falls to others. The emotional energy to light that torch could be supplied to generations now alive by the vision of the human settlement of Mars and by the necessity of providing vast amounts of environmentally compatible energy for the billions of humans left at home.

The return of Americans and their partners to space must be viewed in the context of the free world's over all perception of the future of humankind. In the United States, unfortunately, little political thought normally is given to that future or to our role with in it. However, in space, we have little choice. The United States will be the free world's principal agent and advocate in space, because there are no other likely alternatives.

One body of opinion in the U.S. today would argue that there is no hurry. "Space will always be there, and meanwhile we have more pressing near term interests here on Earth. What is interesting to do scientifically can be done with robots at
much lower cost." Unfortunately for those who hold this opinion, times are changing rapidly, and there is history being made without us. The challenge in space can no longer be viewed as merely a scientific challenge as valuable as the science to be done will be. The challenge now is to both lead the human settlement of space and the environmental preservation of our home planet.

Why the hurry? Why stretch human technological and psychological reach to the limit? First and foremost, the answers are in the minds of young people who will carry us into the Third Millennium. The answers are in the generations now in school, now playing around our homes, now driving us to distraction as they struggle toward adulthood. They will settle the moon and then Mars. They will do this simply because they want to do this. They want to "be there." "Being there" remains the essential human ingredient in life's meaningful experiences.

The desire to "be there" will drive our young people away from the established paths of history on a now too confining Earth. It will take them and their progeny to an infinity of opportunity among the planets and the stars. Video pictures and data streams from robots on Mars, no matter how good or how complete, will never be enough for the parents of the first Martians. Somewhere, those parents are alive today. Whether they now play on the steppes of Russia, on the river banks of China, or on the mountains, plains, and shores of America, or on a combination of all three, constitutes the most critical question of national will we face today.

Thus, an answer to "why the hurry" also lies in the clear determination of the Soviet Union to establish its sovereignty in deep space and on Mars before the forces of freedom do so. The permanently occupied MIR space station, very long duration earth orbital flights by the cosmonauts, heavy lift launch vehicle testing, and their public emphasis of Mars exploration, leading to human visits early in the 21st Century, all tell us what the Soviets expect to do. In spite of all the real and perceived difficulties faced by the Soviet Union in the future, there is now reason to count on their failure in space.

Perhaps the most important answer from the perspective of the physical welfare of the human species lies in the absolute moral and political requirement to provide the ever expanding population of Earth with an ever improving quality of life. We do not currently have the technical means to do this. We do not know how we are going to provide the ten billion human beings expected before the end of the 21st Century with both the hope and the reality that they will have defeated the four horsemen of worldwide disaster: poverty, hunger, disease, and ignorance. The essential ingredient for victory in this very human battle is environmentally
compatible energy. Fossil fuels, the rainforests, and conventional nuclear power cannot provide the answer without either unacceptable political conflict or potentially devastating consequences to the biosphere of the Earth.

Fusion power plants fueled by helium-3 from the moon (Wittenberg, 1986) could supply the electrical energy human civilization will require to maintain and expand human quality of life as we enter the Third Millennium. Inherently safe and potentially low cost fusion reactors fueled by lunar helium-3 also could become the basis for producing large quantities of continuously available electrical power in space, for highly efficient space propulsion to and from Mars, and for life giving by-products that insure the self sufficiency of settlements on the moon and Mars (Kulcinski, 1987).

Furthermore, establishment of a permanent settlement on the moon, based on the production of helium-3 for use as an energy source on Earth fully supports the desire to live on Mars as soon as possible.

First of all, most of the technology needed for the creation of a permanent lunar settlement with a resources production economy will support the technological requirements for establishing a Martian settlement. The compatible technologies include heavy lift launch vehicles, long duration surface habitats and mobility systems, resource production facilities, regular and routine capability to work in a hostile and dusty environment, and new concepts in equipment automation, reliability, longevity, and maintainability.

Second, the direct and indirect by-products of helium-3 production from the lunar surface materials will provide a ready source of necessary consumables for Martian inhabitants prior to and possibly even after the creation of their own consumables industry. These lunar produced consumables include hydrogen, oxygen, nitrogen, carbon, and food.

A preliminary estimate of the energy equivalent value of helium-3 today is about two billion dollars per metric tonne if matched against the cost of coal currently used to produce electricity in the United States. This is roughly equivalent to $14 per barrel oil at today’s prices. Two billion dollars worth of fuel currently supplies the electrical power needs of the United States for about two weeks or of a city of 10 million for about one year. The foregoing estimates of value do not take into account the additional value of by-products from lunar helium-3 production or the spin-off value of related technologies.

The principle advantages of the helium-3 fusion power cycle on Earth over other nuclear cycles include:
1. About 99 percent of the energy released is in charged particles (protons) that induce no radioactivity in other materials.

2. High efficiency (70-80 percent) in energy conversion due to the potential for direct conversion of protons to electricity.

3. Less waste heat to be rejected due to high efficiency.

4. The energy of each of the few neutrons released (1 percent of total energy) is only one-fourth that released in other fusion cycles and such neutrons create no significant quantities of long lived radioactive waste.

5. A potentially shorter time to licensed commercialization than for other fusion cycles due to the absence of significant radioactivity and waste heat.

Estimates of the ultimate steady-state costs of delivering helium-3 to deuterium/helium-3 power plants on Earth run about one billion dollars per metric tonne. If such cost prove to be correct, such power plants will provide much lower cost electricity as well as much less environmental impact than other competing power sources proposed for the 21st Century.

The only major technical disadvantage of the deuterium/helium-3 fusion cycle is that the ignition temperature and confinement pressure required to initiate fusion is about four times higher that for the competing deuterium/tritium cycle. This disadvantage appears to be becoming less and less significant as new fusion confinement technologies are developed. In fact, a recent test in Great Britain produced a record 60 kilowatts of fusion energy using deuterium and helium-3 (G.L. Kulcinski, personal communication).

Sufficient helium-3 is available on Earth (largely from tritium decay and natural gas) for development and prototype testing of deuterium/helium-3 power plants. Therefore, the primary issues that must be addressed to determine the feasibility of a commercial helium-3 industry are, first, the technical and economic feasibility of deuterium/helium-3 commercial reactors and, second, the technical and economic feasibility of providing lunar helium-3 to fuel such reactors.

Historically, major extensions of the benefits of civilization have built on extensions of the existing
Mission to Earth, Moon, and Mars

Dr. Harrison H. Schmitt
Scientist, Administrator, Educator, Consultant on Space Initiatives
Former U.S. Senator and Lunar Module Pilot for Apollo 17

foundation of scientific and technical understanding. The creation of the pyramids, the aqueducts and roads of the Roman Empire, the Gothic Cathedrals, the industrial revolution, the airplane, the construction of the Panama Canal, the green revolution in agriculture, and controlled nuclear energy have followed this pattern. No less than these examples, Apollo exploration of the moon and the technological revolution brought about by space flight matched the experience and technology of the past with the imagination and research of the moment.

New explorations at the frontiers of space, that is, in places and for times that are significantly beyond the technical capabilities of Apollo, Skylab, the Space Shuttle, and the space station also will require new technologies to augment those necessary to live and work in near Earth space. New and more rapid interplanetary rockets and new concepts of life support, mobility, and transportation will obviously be necessary. Foresight will be required to invest a reasonable proportion of available resources in these essential new technologies.

In the political climate of the last two decades, however, it is probably appropriate to ask, "do the discussions of future large scale space activities have any actual relevance in the United States today?" This question is particularly topical in view of the very limited commitment to major space activities put forth in the recent congressional and presidential campaigns.

Positive indications of the relevance of discussions related to space are found in the interest and motivation of a core of a few tens of thousands of technical, scientific, and philosophical advocates, in the extraordinary qualitative support of the American people for the space program, and in the historical imperative space imposes on free men and women.

Pools and surveys indicate that 75% or more of the American people support a strong space program. 75% support for anything is almost beyond rational explanation. Space has the potential to excite and motivate almost anyone.

Even if this overwhelming qualitative support did not exist, the question would still have to be asked, "if the Americans do not insure that free institutions are established elsewhere in the solar system, who else will guarantee that they will be?" Further, "if the Americans do not insure the ultimate survival of the Earth's biosphere, who else will guarantee that survival?" These fundamental points have been missed in almost all political and technical debates on the future course of the U.S. space effort.

Unfortunately, the indications of a lack of current political relevance of any discussion about advanced space
technology are staggering as any regular reader of Aviation Week and the Wall Street Journal will soon discover.

First, few candidates for political office feel any need to address civilian space activities as a significant philosophical, political, or environmental issue. Nor do they feel the need to address any of the broad spectrum of other critical issues of the future. The short term vested interests dominate their view because that is where elections and re-elections are won or lost.

Second, in spite of tentative commitments to it, the space station may lose its battle for domestic and international legitimacy -- on the one hand, the Administration has failed to make an unequivocal domestic political case for a U.S. managed space infrastructure and, on the other hand, the Soviets have a ten year lead in space station capability with the permanently occupied MIR station already in orbit.

Third, a U.S. heavy lift launch capability, critical to so many aspects of the future in space, does not exist. Again, the Soviets have a ten year lead in such capability which now includes an apparently competitive space shuttle.

Fourth, no significant resources are being allocated to recasting the free world’s space agenda toward the settlement of Mars while, once again, the Soviets have at least a ten year lead in planning and developing such a capability.

Fifth, many national leaders are committed to severe limitation on the development of strategic defenses while the Soviets appear to be nearing a strategic defense breakout in ground based systems.

Sixth, our national leaders as well as the armed services have been unable to recognize the values of integrated manned and automated space based systems in tactical and strategic defense doctrines while the Soviets continue to develop and exercise their decades old commitment to an integrated Earth and space military doctrine. As the CINCSPACE, General Piotrowski, has said recently, the Soviets can rapidly and effectively exercise control of space -- the U.S. cannot do so.

Seventh, no workable policy exists that would insure that the U.S. and its allies would have an assured supply of critical energy and materials and the related industrial base necessary to sustain either long term space activities or near term defense and economic activities (Mott Committee, 1988). Indeed, no national leader appears to recognize that this is even an issue, witness the limited factual basis for proposals related to southern Africa.
**Keynote Address**

**Mission to Earth, Moon, and Mars**

Dr. Harrison H. Schmitt  
Scientist, Administrator, Educator, Consultant on Space Initiatives  
Former U.S. Senator and Lunar Module Pilot for Apollo 17

---

Even this list does not tell the whole terribly sad story as many of you know better than I.

How did we fall so far from the dizzy heights of Apollo? 1970 was the fateful year history must mark as the year the nation’s political leadership began to let our space momentum and maybe our national destiny slip away.

Ironically, the people of Apollo, in spite of their spectacular success in meeting President John Kennedy’s challenge, "to put men on the moon and return them safely to Earth," had lost the media and political support necessary to build on their accomplishments.

Once Apollo missions began to be canceled and the industrial base to utilize the Apollo technology base started to be dismantled, the opportunity to lead humankind into space began to slip away. Even the reluctant decision by the Nixon Administration to build the Space Shuttle, and the equally reluctant decision by the Carter Administration to continue, were made out of context relative to any grand design for our future in space. The underfunding of the Shuttle development program, by at least a factor of three less than prudent estimates of the time, was the direct consequence of this hesitant and uncomprehending political environment. The seeds of the Challenger accident were sown by these events. Their tragic harvest sixteen years later is a stark indictment of all who let this drift in space policy begin and continue.

America, like Ebenezer Scrooge, still has time to change this specter of history yet to come. So, rather than conclude on the preceding pessimistic recital of history and current reality, let me return to the areas of technological challenge before America and the possibilities for progress before the humankind by referring back to the hypothetical State of the Union Address.

"Our Millennium Project combines space ventures to the Earth, moon, and Mars into a single great human mission -- a mission to save the atmosphere, waters, and rainforests of Earth, a mission to settle the moon and utilize its resources for the benefit of all, and a mission to establish human civilization and freedom permanently on Mars.

"Our commitment to the success of The Millennium Project must be unequivocal. It must include an equally unequivocal commitment to carry the sacred institutions of freedom with us as humankind expands into its larger home among the planets and the stars."
Keynote Address

Mission to Earth, Moon, and Mars

Dr. Harrison H. Schmitt
Scientist, Administrator, Educator, Consultant on Space Initiatives
Former U.S. Senator and Lunar Module Pilot for Apollo 17

References


See also:


INSTEP88 Workshop
OAST Technology For the Future
Part 1: Executive Summary & Experiment Descriptions

Executive Summary

Workshop Purpose & Agenda

Dr. Leonard Harris
Chief Engineer
Office of Aeronautics & Space Technology, NASA Hq

IN-STEP 88

- PURPOSE
  - IDENTIFY & PRIORITIZE IN-SPACE TECHNOLOGIES WHICH:
    - ARE CRITICAL FOR FUTURE NATIONAL SPACE PROGRAMS
    - REQUIRE DEVELOPMENT & IN-SPACE VALIDATION
  - REVIEW CURRENT NASA (IN-REACH) & INDUSTRY/UNIVERSITY (OUT-REACH) EXPERIMENTS WITH THE AEROSPACE COMMUNITY
  - OBTAIN AEROSPACE COMMUNITY COMMENTS & SUGGESTIONS ON OAST IN-STEP PLANS

- PRODUCT
  - AEROSPACE COMMUNITY RECOMMENDED PRIORITY LISTING OF CRITICAL SPACE TECHNOLOGY NEEDS & ASSOCIATED SPACE FLIGHT EXPERIMENTS

TECHNOLOGY THEMES

IN-STEP 85 WORKSHOP
SPACE STRUCTURES
SPACE ENVIRONMENT EFFECTS
ENERGY SYSTEMS & THERMAL MANAGEMENT
FLUID MANAGEMENT
AUTOMATION & ROBOTICS
INFORMATION SYSTEMS
IN-SPACE OPERATIONS

IN-STEP 88 WORKSHOP
SPACE STRUCTURES
SPACE ENVIRONMENT EFFECTS
POWER SYSTEMS & THERMAL MGMT.
FLUID MANAGEMENT & PROPULSION SYSTEMS
AUTOMATION & ROBOTICS
SENSORS & INFORMATION SYSTEMS
IN-SPACE SYSTEMS
HUMANS-IN-SPACE
RESULTS OF THE WORKSHOP

- STRENGTHEN COMMUNICATION WITH THE AEROSPACE COMMUNITY ON THE IN-SPACE TECHNOLOGY EXPERIMENTS PROGRAM

- IDENTIFY CRITICAL IN-SPACE TECHNOLOGY NEEDS FOR FUTURE RESEARCH & DEVELOPMENT

- PRIORITIZE SPACE TECHNOLOGY NEEDS & ASSOCIATION IN-SPACE TECHNOLOGY EXPERIMENTS

WORKSHOP AGENDA

Dec 6 (Tuesday Morning) - PROGRAM OVERVIEW
Dec 6 (Tuesday Afternoon) - REVIEW OF CURRENT IN-REACH & OUT-REACH EXPERIMENTS
Dec 7 (Wednesday & Thursday Morning) - THEME REVIEWS & DISCUSSIONS
Dec 8 (Thursday Afternoon) - EXPERIMENT INTEGRATION PROCESS
Dec 9 (Friday Morning) - CRITICAL TECHNOLOGY REQUIREMENTS
INSTEP88 Workshop
OAST Technology For the Future
Part 1: Executive Summary & Experiment Descriptions

Executive Summary

In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq's

SPACE R&T PROGRAM

GOAL

• RECOGNIZED LEADERSHIP IN SPACE R&T TO ENABLE AND ENHANCE FUTURE CIVIL SPACE MISSIONS

AND

• PROVIDE A SOLID BASE OF CAPABILITIES AND TALENT TO SERVE ALL NATIONAL SPACE SECTORS

STRATEGY

• ENSURE INNOVATIVE R&T BASE

LONG RANGE PLAN

• PURSUE NEW DIRECTIONS THROUGH ROLLOVER

• NURTURE NEW FOCUSED PROGRAMS
  - ULTRA-RELIABLE SYSTEMS
  - TECHNOLOGIES FOR MISSION TO PLANT EARTH

• ADVOCATE BUDGET GROWTH
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hqs

R&T BASE CHARACTERISTICS

- LABORATORY RESEARCH
- GENERIC, FUNDAMENTAL
- ANALYTICAL MODELING
- ENGINEERING DATA BASE
- HIGH RISK, HIGH PAYOFF
- TECHNOLOGY OPPORTUNITIES
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq's
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq

INSTEP88 Workshop
OAST Technology For the Future
Part 1: Executive Summary & Experiment Descriptions

Executive Summary

SPACE ENERGY CONVERSION

- PRIMARY SECONDARY BATTERIES
- SOLAR DYNAMICS
- FUEL CELLS
- SP 100

- LIGHTWEIGHT ARRAYS
- CONCENTRATORS
- ADVANCED CELLS

NASA

PROPELION

LOX HYDROGEN
AIRBREATHING
LOX HYDROCARBON

REUSABLE EARTH TO ORBIT

ELECTRIC PROPULSION

OTV PROPULSION

NASA
INSTEP88 Workshop
OAST Technology For the Future
Part 1: Executive Summary & Experiment Descriptions

Executive Summary

In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq's

MATERIALS AND STRUCTURES

STRUCTURAL CONCEPTS
AEROTHERMAL STRUCTURES

DYNAMICS OF FLEXIBLE STRUCTURES
SPACE DURABLE MATERIALS

NASA

SPACE DATA AND COMMUNICATIONS

LARGE APERTURE ANTENNA
LASER COMMUNICATIONS
ON BOARD PROCESSING COMPONENTS

ADVANCED TRAVELING WAVE TUBE

NASA

ORIGINAL PAGE IS OF POOR QUALITY
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hqs

INFORMATION SCIENCES

REMOTE SENSING

COMPUTER SCIENCES

EXPERT SYSTEMS

CONTROLS AND GUIDANCE

BEAM DYNAMICS

ADAPTIVE CONTROL (APS)

SPACECRAFT CONTROL LABORATORY EXPERIMENT

LASER GUIDANCE RESEARCH

NASA

NASA
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA HqS

HUMAN FACTORS

SPACE SUIT

EVA AIDS

CREW STATION DESIGN

DISPLAY MODELING

NASA

SPACE FLIGHT SYSTEMS R&T

SPACE

ORBITER EXPERIMENTS (OEX)

SOLAR ELECTRIC PROPLUSION (SEP)

CRYOGENIC FLUID MANAGEMENT

NASA
In-Space Technology Experiments in NASA’s Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq

SPACE RESEARCH & TECHNOLOGY BASE

CANDIDATE EXAMPLES FOR FUTURE EMPHASIS

- SOFTWARE ENGINEERING
- HIGH TEMPERATURE SUPERCONDUCTORS
- OPTICS
- COMPUTATIONAL CONTROLS
- NDE/NDI
- TECHNOLOGY FOR SELF REPAIR
- BASIC RESEARCH IN "INHERENT RELIABILITY"
- MICROSAT TECHNOLOGY
- WORLD MODELING DATA SYSTEMS
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hqs

BACKGROUND

- THE FIRST STEP IN REVITALIZING THE NATION'S CIVIL TECHNOLOGY BASE
- WILL FILL IN GAPS IN MANY TECHNOLOGY AREAS
- FOCUSED TECHNOLOGY EFFORT, WILL RESULT IN DEMONSTRATED / VALIDATED TECHNOLOGIES
MISSION NEEDS

- TRANSPORTATION TO LOW EARTH ORBIT
  - PROPULSION
  - AEROBRACING

- OPERATIONS IN LOW EARTH ORBIT
  - AUTONOMOUS SYSTEMS
  - TELEROBOTICS
  - POWER

- SCIENCE
  - STRUCTURES
  - SENSORS
  - DATA SYSTEMS
### In-Space Technology Experiments in NASA’s Strategic Planning

Dr. Judith H. Ambrus  
Assistant Director for Space  
Office of Aeronautics & Space Technology, NASA Hq

#### PATHFINDER
- Develops high leverage technologies for piloted and robotic solar system exploration
- Critical element of the President's space policy
- Long-term program, providing both research and demonstrations
- Necessary to maintain U.S. leadership in space

#### STRATEGY
- Validate technology focused on enabling and enhancing new missions

**LONG RANGE PLAN**
- Emphasize healthy and complete CSTI and PATHFINDER programs
- Respond to evolving new mission concepts
- Refine and accelerate technology development and validation in response to agency decision on bold new initiatives
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hqs

UNIVERSITY SPACE ENGINEERING RESEARCH PROGRAM

- INTEGRAL PART OF STRATEGY TO REBUILD R&T BASE
  - INCREASE NUMBER OF ENGINEERING GRADUATES
  - INCREASE INVOLVEMENT OF UNIVERSITIES IN CIVIL SPACE PROGRAM

- LONG TERM FUNDING ENCOURAGES UNIVERSITY COMMITMENT

- UNIVERSITY INVOLVEMENT ADDS VALUE
  - SPACE R&T
    - INNOVATIVE/CREATIVE APPROACHES
    - PARTICIPATION FROM WIDE RANGE OF ENGINEERING AND SCIENTIFIC FIELDS
  - UNIVERSITY
    - IMPROVES CURRICULA
    - GREATER RELEVANCE OF RESEARCH TO CIVIL SPACE NEEDS

UNIVERSITY SPACE ENGINEERING RESEARCH PROGRAM

NINE CENTERS SELECTED FOR FY 1988

UNIVERSITY OF ARIZONA
CENTER FOR UTILIZATION OF LOCAL PLANETARY RESOURCES

UNIVERSITY OF CINCINNATI
HEALTH MONITORING TECHNOLOGY CENTER FOR SPACE PROPULSION SYSTEMS

UNIVERSITY OF COLORADO, BOULDER
CENTER FOR SPACE CONSTRUCTION

UNIVERSITY OF IDAHO
VERY LARGE SCALE INTEGRATED HARDWARE ACCELERATION CENTER FOR SPACE RESEARCH

MASSACHUSETTS INSTITUTE OF TECHNOLOGY
CENTER FOR SPACE ENGINEERING RESEARCH FOCUSED ON CONTROLLED STRUCTURES TECHNOLOGY

UNIVERSITY OF MICHIGAN
CENTER FOR NEAR MILLIMETER WAVE COMMUNICATION

NORTH CAROLINA STATE AT RALEIGH
& NORTH CAROLINA AGRICULTURAL & TECHNICAL STATE UNIVERSITY
MARS MISSION RESEARCH CENTER

PENNSYLVANIA STATE UNIVERSITY
CENTER FOR SPACE PROPULSION ENGINEERING

RENSSELAER POLYTECHNIC INSTITUTE
INTELLIGENT ROBOTIC SYSTEMS FOR SPACE EXPLORATION
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq

**STRATEGY**

- EXPAND UNIVERSITY PROGRAMS

**LONG RANGE PLAN**

- GROWTH FOR NINE INCUMBENT UNIVERSITY ENGINEERING RESEARCH CENTERS AWARDED IN APRIL, 1988
- ADD NEW AREAS OF PROGRAMMATIC INTEREST
- BROADEN UNIVERSITY SUPPORT TO INCLUDE INDIVIDUAL INNOVATION IN RESEARCH

**IN-SPACE EXPERIMENTS IN OAST**

- IN-SPACE EXPERIMENTS HAVE ALWAYS BEEN PART OF OAST'S PROGRAM
  - TO OBTAIN DATA THAT CAN NOT BE ACQUIRED ON THE GROUND
  - TO DEMONSTRATE FEASIBILITY OF CERTAIN ADVANCED TECHNOLOGIES
- CONDUCTING TECHNOLOGY EXPERIMENTS IN SPACE IS A VALUABLE AND COST EFFECTIVE WAY TO INTRODUCE ADVANCED TECHNOLOGY INTO FLIGHT PROGRAMS
- THE SHUTTLE HAS DEMONSTRATED THE FEASIBILITY AND TIMELY BENEFITS OF CONDUCTING HANDS-ON EXPERIMENTS IN SPACE
- SPACE STATION WILL BE A PERMANENT LABORATORY IN SPACE AND WILL PROVIDE LOGICAL AND EVOLUTIONARY EXTENSION OF GROUND BASED R&T IN SPACE
### IN-SPACE EXPERIMENTS PLANNING

<table>
<thead>
<tr>
<th>Event</th>
<th>Date</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASEB PANEL ON NASA'S R&amp;T PROGRAM</td>
<td>JUNE 1983</td>
</tr>
<tr>
<td>INDUSTRY/DOD WORKSHOP</td>
<td>FEB 1984</td>
</tr>
<tr>
<td>ADMINISTRATOR'S POLICY STATEMENT</td>
<td>APRIL 1984</td>
</tr>
<tr>
<td>ASEB PANEL ON IN-SPACE ENGINEERING AND TECHNOLOGY DEVELOPMENT</td>
<td>MAY 1985</td>
</tr>
<tr>
<td>OAST IN-SPACE TECHNOLOGY WORKSHOP</td>
<td>OCT 1985</td>
</tr>
<tr>
<td>INITIATION OF IN-REACH/OUT-REACH PROGRAMS</td>
<td>OCT 1985</td>
</tr>
<tr>
<td>SSTAC AD HOC COMMITTEE ON THE USE OF SPACE STATION FOR IN-SPACE ENGINEERING R&amp;T</td>
<td>AUG 1987</td>
</tr>
<tr>
<td>SPACE STATION OPERATIONS TASK FORCE</td>
<td>OCT 1987</td>
</tr>
<tr>
<td>NASA MANAGEMENT STUDY GROUP (NMSG - 24)</td>
<td>DEC 1987</td>
</tr>
<tr>
<td>NASA CENTER SCIENCE ASSESSMENT TEAM</td>
<td>MAY 1988</td>
</tr>
</tbody>
</table>

### ADVISORY GROUP RECOMMENDATIONS

..."NASA SHOULD PROVIDE ACCESS TO SPACE FOR EXPERIMENTAL PURPOSES AS A NATURAL EXTENSION OF AEROSPACE FACILITIES... AN EVOLUTIONARY PROGRAM OF ON-ORBIT RESOURCE EQUIVALENT TO .... THE WIND TUNNELS"...

ASEB, 1983

..."NASA SHOULD BETTER EXPLOIT THOSE SPACE FACILITIES THAT ARE UNIQUE ...... THE SHUTTLE AND THE SPACE STATION FOR THE DEVELOPMENT OF TECHNOLOGY FOR NASA, DOD, AND THE INDUSTRY"...

DOD/INDUSTRY (HEARTH) WORKSHOP, 1984

..."OAST SHOULD PROVIDE THE LEADERSHIP....TO SUPPORT THE ENGINEERING TECHNOLOGY NEEDS OF THE USER INDUSTRY, OTHER GOVERNMENT AGENCIES, AS WELL AS ITS OWN FOR ALL IN-SPACE ENGINEERING R&T"...

ASEB, 1985
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq's

NASA POLICY ON ROLE OF SPACE TECHNOLOGY

... "IT WILL BE NASA'S POLICY TO SUPPORT THE DOD AND SPACE INDUSTRY THROUGH COMPETITIVE R&T PROGRAMS JUST AS WE DO IN AERONAUTICS"...

..."WE CAN BE PARTICULARLY EFFECTIVE IN ESTABLISHING CLOSER TIES WITH INDUSTRY AND THAT IS THE USE OF THE SHUTTLE FOR IN-SPACE EXPERIMENTS... WHICH WILL LEAD QUITE NATURALLY TO USING THE SPACE STATION FOR TECHNOLOGY AND ENGINEERING EXPERIMENTS"...

..."TO BEGIN IMPLEMENTING THIS POLICY, I HAVE ASKED ...(OAST)... TO INCREASE OUR EMPHASIS ON IN-FLIGHT EXPERIMENTS"...

MEMORANDUM FROM THE ADMINISTRATOR
APRIL 3, 1984

USING SPACE FOR TECHNOLOGY DEVELOPMENT

- Space structures
- Space environmental effects
- Power systems and thermal management
- Fluid management and propulsion systems
- Automation and robotics
- Sensor and information systems
- In-space systems
- Humans in space
IN-SPACE TECHNOLOGY EXPERIMENTS INITIATIVE - PHASE I

- FLIGHT OPPORTUNITY RESTORED

- INITIATE MORE VIGOROUS PROGRAM ON SHUTTLE AND ELVs
  - OBTAIN DATA THAT CAN NOT BE OBTAINED ON THE GROUND
  - VALIDATE ADVANCED TECHNOLOGIES FOR EARLY USE IN FLIGHT PROJECTS

- GET A RUNNING START ON SPACE STATION
  - GEAR UP NASA, INDUSTRY, UNIVERSITY ACTIVITY
  - CONDUCT SPACE STATION PRECURSOR EXPERIMENTS

IN-SPACE TECHNOLOGY EXPERIMENTS PROGRAM

- NASA EXPERIMENTS
  - ARISE FROM THE R&T BASE OR FOCUSED PROGRAMS
  - INCLUDE PRESENTLY ONGOING EXPERIMENTS

- INDUSTRY/UNIVERSITY EXPERIMENTS
  - FOLLOWING THROUGH ON OUR COMMITMENTS IN THE OUT-REACH PROGRAM

- INTERNATIONAL EXPERIMENTS
  - COOPERATIVE ACTIVITIES WITH OUR ALLIES
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq

Executive Summary

NASA IN-SPACE TECHNOLOGY EXPERIMENTS

- INCORPORATES PRESENTLY ON-GOING IN-SPACE R&T PROGRAM
  - ORBITER EXPERIMENTS PROGRAM (OEX)
  - LONG DURATION EXPOSURE FACILITY (LDEF)
  - LIDAR IN-SPACE TECHNOLOGY EXPERIMENT (LITE)
  - ARCJET AUXILIARY PROPULSION SYSTEM
  - EXPERIMENTS SELECTED FROM IN-REACH SOLICITATION

- FUTURE EXPERIMENTS WILL CONTINUE TO ARISE AS A NATURAL EXTENSION OF R&T BASE AND FOCUSED PROGRAMS
  - CIVIL SPACE TECHNOLOGY INITIATIVE (CSTI)
  - PATHFINDER

INDUSTRY/UNIVERSITY IN-SPACE EXPERIMENTS

- PROVIDE ACCESS TO SPACE FOR INDUSTRY AND UNIVERSITIES TO DEVELOP SPACE TECHNOLOGY
  - ENTHUSIASTIC RESPONSE OF AEROSPACE COMMUNITY TO OUT-REACH SOLICITATION

- OAST HAS COMMITTED TO AEROSPACE COMMUNITY TO SERVE AS CONDUIT FOR TECHNOLOGY DEVELOPMENT IN SPACE
  - PERIODIC RESOLICITATIONS TO INDUSTRY/UNIVERSITY COMMUNITY FOR EXPERIMENT DEFINITION, DEVELOPMENT, AND FLIGHT
In-Space Technology Experiments in NASA’s Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq's

INTERNATIONAL IN-SPACE EXPERIMENTS

- PROMOTES COOPERATION WITH ALLIES
- LEVERAGES TECHNOLOGY DEVELOPMENT BY OTHERS IN KEY AREAS
- LEVERAGES AND HUSBANDS SCARCE FLIGHT OPPORTUNITIES

IN-SPACE EXPERIMENTS INITIATIVE - PHASE II

- ROUTINE OPERATIONS IN LOW EARTH ORBIT WILL INITIATE ERA OF BOLD NEW INITIATIVES
  - NEED FOR TECHNOLOGY DEMONSTRATIONS FOR ENABLING TECHNOLOGIES WILL INCREASE
  - THE RANGE OF TECHNOLOGIES TO BE DEMONSTRATED IN SPACE WILL INCREASE
  - SPACE STATION WILL PROVIDE THE FACILITY FOR SIMPLER, FASTER ACCESS TO SPACE
  - SPACE STATION WILL ENABLE EXPERIMENTS NEEDING LONG-TERM HUMAN INTERACTION
- EXPERIMENTS PLANNED AND DEFINED FOR SPACE STATION DURING PHASE I WILL ENTER HARDWARE DEVELOPMENT STAGE
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq's

**SUMMARY**

- TECHNICAL NEED IDENTIFIED 1983
- PLANNING COMPLETE 1983-86
- COMMITMENTS MADE 1986-88
  - INDUSTRY / UNIVERSITIES (VIA OUT-REACH)
  - CENTERS (VIA IN-REACH)
  - INTERNATIONAL COMMUNITY
- OPPORTUNITY FOR SPACE FLIGHT RESTORED
  - SHUTTLE, ELV MANIFESTING
  - SPACE STATION PLANNING

**STRATEGY**

- ENSURE INNOVATIVE R&T BASE
- VALIDATE TECHNOLOGY FOCUSED ON ENABLING NEW MISSIONS
- BUILD STRONGER LINKAGES TO EFFECTIVELY TRANSFER NEW TECHNOLOGIES TO USERS
- EXPAND UNIVERSITY PROGRAMS
- STEP UP TO COMMITMENT AS LEADER FOR TECHNOLOGY DEVELOPMENT ON SPACE STATION
In-Space Technology Experiments in NASA's Strategic Planning

Dr. Judith H. Ambrus
Assistant Director for Space
Office of Aeronautics & Space Technology, NASA Hq

SUMMARY

SPACE R&T: A FIVE YEAR OUTLOOK

- EQUITABLE AGENCY TECHNOLOGY INVESTMENT ESTABLISHED
- OAST IN TECHNOLOGY LEADERSHIP ROLE FOR AGENCY
- COOPERATIVE TECHNOLOGY HAND-OFF AGREEMENTS ESTABLISHED WITH USERS
- COORDINATION WITH NATIONAL SPACE SECTORS WELL ESTABLISHED
- OAST RECOGNIZED AS NATIONAL FOCAL POINT FOR IN-SPACE TECHNOLOGY DEVELOPMENT

IN-SPACE RESEARCH AND TECHNOLOGY PROGRAM UTILIZING SPACE STATION AND OTHER SPACE FACILITIES AS A LOGICAL EVOLUTIONARY EXTENSION OF GROUND-BASED RESEARCH AND TECHNOLOGY
# CURRENT SPACE FLIGHT EXPERIMENTS

<table>
<thead>
<tr>
<th>FLIGHT EXPERIMENTS</th>
<th>HQ</th>
<th>LEAD CENTER</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>LONG DURATION EXPOSURE FACILITY</td>
<td>JOHN LORIA</td>
<td>LANGLEY</td>
<td></td>
</tr>
<tr>
<td>ORBITER EXPERIMENTS</td>
<td>RICHARD GUALDONI</td>
<td>JOHNSON</td>
<td></td>
</tr>
<tr>
<td>LIDAR IN-SPACE TECHNOLOGY EXPERIMENT</td>
<td>RICHARD GUALDONI</td>
<td>LANGLEY</td>
<td></td>
</tr>
<tr>
<td>AEROGUIDE FLIGHT EXPERIMENT</td>
<td>JOHN SMITH</td>
<td>MARSHALL</td>
<td></td>
</tr>
<tr>
<td>ARCJET FLIGHT EXPERIMENT</td>
<td>JOHN LORIA</td>
<td>LEWIS</td>
<td></td>
</tr>
<tr>
<td>TELEROBOT INTELLIGENT INTERFACE FLIGHT EXPERIMENT</td>
<td>RICHARD GUALDONI</td>
<td>JPL</td>
<td></td>
</tr>
<tr>
<td>CRYOGENIC FLUID MANAGEMENT FLIGHT EXPERIMENT</td>
<td>JOHN LORIA</td>
<td>LEWIS</td>
<td></td>
</tr>
<tr>
<td>IN-REACH (NASA TECHNOLOGY EXPERIMENTS)</td>
<td>JON PYLE</td>
<td>LEWIS</td>
<td></td>
</tr>
<tr>
<td>OUT-REACH (INDUSTRY/UNIVERSITY TECHNOLOGY EXPERIMENTS)</td>
<td>JON PYLE</td>
<td>LEWIS</td>
<td></td>
</tr>
</tbody>
</table>

# LDEF

**LONG DURATION EXPOSURE FACILITY**

**OBJECTIVES:**

- DETERMINE LONG-TERM SPACE EXPOSURE EFFECTS ON MATERIALS, COATINGS, & OPTICS
- MEASURE SPACE ENVIRONMENTAL PHENOMENA OVER EXTENDED TIME

**STATUS:**

- 34 EXPERIMENTS ADVERSELY AFFECTED BY LDEF RECOVERY DELAY
- 23 EXPERIMENTS EITHER IMPROVED OR NOT AFFECTED
- LDEF STRUCTURE AVAILABLE FOR STUDY OF ENVIRONMENTAL EROSION & DEBRIS IMPACT
- SCHEDULED FOR RETRIEVAL - NOVEMBER 1989

**LEAD CENTER CONTACT:**

- ROBERT L. JAMES, JR.
  - LANGLEY RESEARCH CENTER
  - PHONE NO. (804) 865-4987
### In-Space Technology Experiment Program

**Jack Levine, Director, Flight Projects Division**  
**Jon S. Pyle, Manager, In-Reach & Out-Reach Programs**  
**Office of Aeronautics & Space Technology, NASA Hq's**

#### OEX ORBITER EXPERIMENT PROGRAM

**OBJECTIVES:**
- Obtain basic aerothermodynamic & entry environment data from R&D instrumentation installed in Space Shuttle Orbiter
- Flight-validate ground test results to improve basis for design of advanced spacecraft

**STATUS:**
- Data collection on-going since 1985 - will continue into 1990's
- Some experiments still to be designed & developed

**LEAD CENTER CONTACT:**
- Robert Spann  
  Johnson Space Center  
  Phone # (713) 483-3022

### LIDAR IN-SPACE TECHNOLOGY EXPERIMENT

**OBJECTIVE:**
- Evaluate critical atmospheric parameters & validate operation of a solid-state lidar system from a spaceborne platform, measuring:
  - Cloud deck altitudes
  - Planetary boundary-layer heights
  - Stratospheric & tropospheric aerosols
  - Atmospheric temperature & density (10km to 40km)

**STATUS:**
- Laser transmitter module, Cassegrain telescope, & environmental monitoring system in development
- Flight manifested for 1993

**LEAD CENTER CONTACT:**
- Richard R. Nelms  
  Langley Research Center  
  Phone No. (804) 865-4947
In-Space Technology Experiment Program

Jack Levine, Director, Flight Projects Division
Jon S. Pyle, Manager, In-Reach & Out-Reach Programs
Office of Aeronautics & Space Technology, NASA Hq's

AFE
AEROASSIST FLIGHT EXPERIMENT

OBJECTIVE:
- INVESTIGATE CRITICAL VEHICLE DESIGN & ENVIRONMENTAL TECHNOLOGIES APPLICABLE TO THE DESIGN OF AEROASSISTED SPACE TRANSFER VEHICLES

STATUS:
- PHASE B DEFINITION COMPLETE
- EXPERIMENT/INSTRUMENT COMPLEMENT ESTABLISHED
- PRELIMINARY DESIGN INITIATED

LEAD CENTER CONTACT:
- LEON B. ALLEN
  MARSHALL SPACE FLIGHT CENTER
  PHONE NO. (205) 544-1917

ARCJET FLIGHT EXPERIMENT

OBJECTIVES:
- ASSESS ARCJET AUXILIARY PROPULSION SYSTEM OPERATION IN SPACE ENVIRONMENT
  - HY DRAZINE PROPellant
  - 1.4 KW, 50 mLb THRUST, Isp 450
- EVALUATE PLUME EFFECTS & THRUSTER/HERMAL INTERACTIONS ON A COMMERCIAL COMMUNICATIONS SATELLITE

STATUS:
- PRELIMINARY DESIGN & ARCJET COMPONENT DEVELOPMENT COMPLETED
- FLIGHT HARDWARE DESIGN, DEVELOPMENT & TESTING SCHEDULED TO START IN 1989
- FLIGHT TEST TENTATIVELY PLANNED FOR 1991

LEAD CENTER CONTACT:
- JERRI S. LING
  LEWIS RESEARCH CENTER
  PHONE NO. (216) 433-2841
In-Space Technology Experiment Program

Jack Levine, Director, Flight Projects Division
Jon S. Pyle, Manager, In-Reach & Out-Reach Programs
Office of Aeronautics & Space Technology, NASA Hq's

TRIIFEX
TELEROBOTIC INTELLIGENT INTERFACE
FLIGHT EXPERIMENT

OBJECTIVES:
- EVALUATE & VALIDATE TELEOPERATION OF A ROBOTIC MANIPULATOR UNDER CONDITIONS OF MICRO-G & COMMUNICATION TIME DELAYS
- VALIDATE ADVANCED SPACE TELEROBOT CONTROLS INCLUDING HIGH-FIDELITY HYBRID POSITION & FORCE CONTROL TECHNIQUES

STATUS:
- CONCEPTUAL DESIGN IN PROGRESS AT JPL
- DEVELOPMENT & INTEGRATION SCHEDULED TO START IN LATE 1988
- FLIGHT TEST PLANNED IN COMBINATION WITH GERMAN ROTEX EXPERIMENT ON SPACELAB D-2 MISSION (1991)

LEAD CENTER CONTACT:
- DANIEL KERRISK
  JET PROPULSION LABORATORY
  PHONE NO. (818) 354-2566

CFMFE
CRYOGENIC FLUID MGMT FLIGHT EXP.

OBJECTIVES:
- DEVELOP TECHNOLOGY REQUIRED FOR EFFICIENT STORAGE, SUPPLY & TRANSFER OF SUBCRITICAL CRYOGENIC LIQUIDS IN LOW-GRAVITY SPACE ENVIRONMENT
- FLIGHT VALIDATE NUMERICAL MODELS OF THE PHYSICS INVOLVED

STATUS:
- CONTRACTOR FEASIBILITY STUDIES CURRENTLY UNDER WAY
- 1992 NEW START PROPOSED

LEAD CENTER CONTACT:
- E. PAT SYMONS
  LEWIS RESEARCH CENTER
  PHONE NO. (216) 433-2853
# In-Space Technology Experiment Program

**Jack Levine, Director, Flight Projects Division**  
**Jon S. Pyle, Manager, In-Reach & Out-Reach Programs**  
Office of Aeronautics & Space Technology, NASA Hq's

## PROGRAM OBJECTIVES

- PROVIDE FOR IN-SPACE FLIGHT RESEARCH  
  EVALUATION & VALIDATION OF ADVANCED  
  SPACE TECHNOLOGIES

### OUT-REACH PROGRAM
- INDUSTRY/UNIVERSITY FLIGHT  
  TECHNOLOGY EXPERIMENTS

### IN-REACH PROGRAM
- NASA FLIGHT TECHNOLOGY  
  EXPERIMENTS

## IN-REACH EXPERIMENTS

<table>
<thead>
<tr>
<th>Date</th>
<th>Event</th>
</tr>
</thead>
<tbody>
<tr>
<td>June 1986</td>
<td>LETTER TO CENTERS REQUESTING PROPOSED IN-SPACE TECHNOLOGY FLIGHT EXPERIMENTS</td>
</tr>
<tr>
<td>Aug. 1986</td>
<td>58 FLIGHT EXPERIMENT PROPOSALS FROM NASA CENTERS</td>
</tr>
<tr>
<td>Jan. 1987</td>
<td>COMPLETED EVALUATION OF PROPOSALS</td>
</tr>
<tr>
<td>Apr. 1987</td>
<td>ADVISORY COMMITTEE REVIEW &amp; PRIORITIZATION OF PROPOSALS</td>
</tr>
<tr>
<td>Jul. 1987</td>
<td>SELECTION OF 6 DEFINITION &amp; 1 DEVELOPMENT EXP.</td>
</tr>
</tbody>
</table>

- SPACE STATION STRUCTURAL CHARACTERIZATION  
- LASER COMMUNICATION FLIGHT EXPERIMENT  
- DEBRIS COLLISION SENSOR  
- LASER IN-SPACE SENSOR EXPERIMENT  
- CONTAMINATION FLIGHT EXPERIMENT  
- EFFECT OF SPACE ENVIRONMENT ON THIN-FOIL MIRRORS  
- THERMAL ENERGY STORAGE TEST EXPERIMENT
In-Space Technology Experiment Program

Jack Levine, Director, Flight Projects Division
Jon S. Pyle, Manager, In-Reach & Out-Reach Programs
Office of Aeronautics & Space Technology, NASA Hqrs

OUT-REACH EXPERIMENTS

Dec. 1985 IN-STEP 85 WORKSHOP
Oct. 1986 REQUEST FOR INDUSTRY/UNIVERSITY PROPOSALS
Jan. 1987 231 PROPOSALS FOR IN-SPACE EXPERIMENTS
(140 FROM INDUSTRY & 91 FROM UNIVERSITIES)
Sept. 1987 SELECTED 5 PROPOSALS FOR DEVELOPMENT OF
FLIGHT EXPERIMENT HARDWARE
- TANK PRESSURE CONTROL EXPERIMENT
  BOEING AEROSPACE COMPANY/LARC
- MID-DECK 0-G DYNAMICS EXPERIMENT
  MASSACHUSETTS INSTITUTE OF TECHNOLOGY/LARC
- INVESTIGATION OF SPACECRAFT GLOW
  LOCKHEED MISSILE & SPACE COMPANY/JSC
- HEAT PIPE THERMAL PERFORMANCE
  HUGHES AIRCRAFT COMPANY/GSFC
- EMULSION CHAMBER TECHNOLOGY EXPERIMENT
  UNIVERSITY OF ALABAMA IN HUNTSVILLE/MSFC

Sept. 1987 SELECTED 36 PROPOSALS FOR DEFINITION OF
FLIGHT TECHNOLOGY EXPERIMENTS
- STUDIES TO BE COMPLETED IN SEPT. 1989
- SOLICITATION FOR DEVELOPMENT OF FLIGHT
  HARDWARE OPEN TO ENTIRE COMMUNITY

FIRST SOLICITATION REVIEW

OBSERVATIONS

- SIGNIFICANT EXPENDITURE BY INDUSTRY
  & UNIVERSITIES (231 PROPOSALS)
- APPROX. 250 NASA SCIENTISTS & TECHNOLOGISTS
  INVOLVED IN TECHNICAL EVALUATIONS
- NEW SOLICITATION BETWEEN DEFINITION &
  DEVELOPMENT ADDS MORE PROPOSAL COSTS
- GENERAL TECHNOLOGY SOLICITATION TOO BROAD
  (SHOTGUN APPROACH TO TECHNOLOGY DEVELOPMENT)
**In-Space Technology Experiment Program**

Jack Levine, Director, Flight Projects Division  
Jon S. Pyle, Manager, In-Reach & Out-Reach Programs  
Office of Aeronautics & Space Technology, NASA Hq's

---

## REVISED APPROACH

- Define & Prioritize critical space technology development requirements for future space missions.
- Use prioritized listing to focus future technology development & in-space flight technology experiments.
- Future solicitations for definition of focused in-space flight technology experiments.
- Down-select between competing experiments for conceptual design phase & flight hardware development phase.

---

## SOLICITATION PROCESS

```
IN-STEP 88

CRITICAL IN-SPACE TECHNOLOGY NEEDS

SELECTION ADVISORY COMMITTEE

TECHNOLOGIES FOR NEXT SOLICITATION

REQUEST FOR PROPOSALS

REVIEW & EVALUATION

SELECTION & DISTRIBUTION TO NASA FIELD CENTERS FOR CONTRACTING & MANAGEMENT
```
In-Space Technology Experiment Program

Jack Levine, Director, Flight Projects Division
Jon S. Pyle, Manager, In-Reach & Out-Reach Programs
Office of Aeronautics & Space Technology, NASA Hq's

SUMMARY

- LONG & SUCCESSFUL HISTORY IN THE CONDUCT OF SPACE FLIGHT TECHNOLOGY EXPERIMENTS
- PROGRAM IS BEING EXPANDED TO EMPHASIZE THE DEVELOPMENT OF ADVANCED SPACE FLIGHT TECHNOLOGIES
- OAST PLANS TO PROVIDE ACCESS TO SPACE FOR THE AEROSPACE TECHNOLOGY COMMUNITY (NASA, DOD, INDUSTRY & UNIVERSITIES)

USER ROLE -- STRATEGIC PLANNING

Diagram showing the relationships between NASA Administrator, NASA Space Station User Board, Multilateral Control Board, Utilization Operations Panel, Systems Operations Panel, and other government agencies.
In-Space Technology Experiment Program

Jack Levine, Director, Flight Projects Division
Jon S. Pyle, Manager, In-Reach & Out-Reach Programs
Office of Aeronautics & Space Technology, NASA Hq's

OAST IN-SPACE TECHNOLOGY PROGRAM PHASES

PROGRAM DEVELOPMENT

- AO's
- FOCUSED PLANNING
- TECHNOLOGY THEME WORKING GROUPS
- CRITICAL FLIGHT EXPERIMENT ROADMAPS
- AO PREPARATION

- TECHNICAL REQUIREMENTS
- HARDWARE IDEAS
- PRELIMINARY PROJECT PLAN

PROJECT MANAGEMENT

- TECHNOLOGY CONCEPT REVIEW
- ENGINEERING DEVELOPMENT
- FLIGHT EXPERIMENT REVIEW
- FLIGHT DEVELOPMENT

- ENGINEERING REQUIREMENTS DEFINED
- FEASIBILITY ESTABLISHED
- HARDWARE CONCEPTUAL DESIGN
- DATA ANALYSIS & REPORT

- FLIGHT HARDWARE DESIGN, FABRICATE, INTEGRATION, & TEST OPERATIONS
- PHASE 0 SAFETY PACKAGE
- PROJECT PLAN

OAST TECHNOLOGY CONTRIBUTIONS

APOLLO
SHUTTLE
VIKING
GROWTH SPACE STATION

ACCESS SAFE IN REACH OUT REACH
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

Space Station Freedom Technology Payloads

- Critical to the success of the Space Station growth or development and future space projects and missions.

- Effective way of augmenting Space Station payload accommodation capabilities - test and conversion to operational use.

- Promote the development of technological applications which support other government and private projects and products.

- Provides new educational opportunities for new generations of scientists, engineers, and other professions.

Revised Baseline Configuration
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

SPACE STATION FREEDOM TECHNOLOGY PAYLOAD ACCOMMODATION

- MATERIALS R&D
- ADVANCED RADIATOR AND POWER SYSTEM
- ADVANCED PROPULSION SYSTEMS
- TECHNOLOGY PAYLOADS WITH STRONG MAGNETIC FIELDS
- LASER SYSTEMS - OPTICAL COMMUNICATION
- ELECTRON BEAMS, WAVE GENERATION, ETC.
- INTERNAL TECHNOLOGY PAYLOADS - RADIATION, SEU
- ADVANCED ECLS SUBSYSTEMS

Potential Attached Payload Locations

A = possible attached payload locations

NOTE: Could utilize more than one trace cube surface but utility port provided
resources would have to be shared
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

MANNED BASE ATTACHED PAYLOAD ACCOMMODATIONS

<table>
<thead>
<tr>
<th>PAYLOAD CLASSIFICATION</th>
<th>PAYLOAD FEATURES</th>
</tr>
</thead>
<tbody>
<tr>
<td>MAJOR</td>
<td>LARGE</td>
</tr>
<tr>
<td></td>
<td>REQUIRES MAJOR APAE RESOURCES</td>
</tr>
<tr>
<td></td>
<td>ACTIVE THERMAL COOLING</td>
</tr>
<tr>
<td></td>
<td>SOME NEED PPS FOR POINTING</td>
</tr>
<tr>
<td></td>
<td>LONG STAY</td>
</tr>
<tr>
<td>SMALL AND/OR RAPID RESPONSE</td>
<td>SMALL</td>
</tr>
<tr>
<td></td>
<td>NO ACTIVE THERMAL COOLING</td>
</tr>
<tr>
<td></td>
<td>MODEST POWER/DATA RESOURCES</td>
</tr>
<tr>
<td></td>
<td>VARIETY OF FIELDS OF VIEW</td>
</tr>
<tr>
<td></td>
<td>SET ASIDE RESOURCES</td>
</tr>
<tr>
<td>DISTRIBUTED SENSOR</td>
<td>CAN BE VERY SMALL IN SIZE (LIKE ACCELEROMETER)</td>
</tr>
<tr>
<td></td>
<td>NON-STANDARD LOCATIONS</td>
</tr>
<tr>
<td></td>
<td>MODEST POWER/DATA RESOURCES</td>
</tr>
<tr>
<td></td>
<td>CAN BE ANALYTICALLY INTENSIVE</td>
</tr>
<tr>
<td></td>
<td>CAN HAVE UNIQUE PACKAGING</td>
</tr>
</tbody>
</table>

APAE TYPICAL CONFIGURATIONS

- Multiple Payloads
- Pallet Mounted Payload
- Payload and Payload Pointing System
- Single Payload
- Large Payload
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

MANNED BASE ATTACHED PAYLOAD ACCOMMODATIONS

APAE DESIGN CAPABILITY

DESIGNED FOR:

MULTIPLE PAYLOADS | MAJOR | POINTING PAYLOADS

- APAE DESIGNED TO SUPPORT UP TO 25,000 LB PAYLOAD
- PROVIDES: 10kW POWER
  50 MBPS DATA RATE
  10 kW ACTIVE COOLING
- STRUCTURAL SUPPORT FOR POINTING CAPABILITY (60 ARC SEC ACCURACY) FOR 6000 kg PAYLOAD

MULTIPLE PAYLOAD/DECK CARRIER CONFIGURATION

CONTAMINATION MONITORING UNIT (CMU)
(PAYLOAD DEPENDENT)

MULTIPLE PAYLOAD ADAPTER (MPA)
SS PROVIDED INCLUDES SIC AND
OPTIONAL COLD PLATE

PAYLOAD INTERFACE ADAPTER (PIA)

SYSTEM SUPPORT MODULE
ELECTRICAL POWER/DATA ORU

SYSTEM SUPPORT MODULE
THERMAL ORU

STATION INTERFACE ADAPTER (SIA)
(INSTALLED ON SSFMb VIA EVA)
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

PAYLOAD POINTING SYSTEM (PPS)

PPS PAYLOAD ACCOMMODATION CAPABILITIES

- 1 ARC MINUTE POINTING ACCURACY
- 30 ARC SECOND POINTING STABILITY (OVER 1800 SECS)
- 15 ARC SECOND/SECOND JITTER
- 3 AXES
- 5 kW OF POWER/ACTIVE COOLING
- 50 MEGABITS HIGH RATE DATA/IMAGERY
- 6000 KG PAYLOAD - 3 METERS WIDE, C.G. TO BASE 2.5 METERS
- ACCEPTS PAYLOAD SENSOR INPUT FOR POINTING

CAPABILITY TO ADD TRUSS STRUCTURE TO ENHANCE ATTACHED PAYLOAD VIEWING AND CLEARANCE
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division Utilization & Operations Group NASA Space Station Freedom Program Office, Reston, Virginia

JAPANESE EXPERIMENT MODULE

SMALL AND RAPID RESPONSE PAYLOADS

EXTERNAL SARR PAYLOAD ENVELOPE & PROPOSED CONSTRAINTS

- TRUNNION/KEEL (T/K) SARR PAYLOAD:
  FIT INTO 4M X 1.25M X 2M ENVELOPE (MAX VOL <10M³)
  ≤ 900 KG
  ≤ 900 WATTS
  ≤ 0.3 MBPS UPLINK/2.0 MBPS DOWNLINK
  ≤ 100 MBYTES DATA STORAGE/ORBIT
  CAN ACCOMMODATE MORE THAN ONE PAYLOAD
  RMS GRAPPLE FIXTURE (ON T/K CARRIER)

- GENERIC (GEN) SARR PAYLOAD:
  FIT INTO 1.25 M X 1.25 M X 1.25 M ENVELOPE (MAX VOL ≤ 2 M³)
  ≤ 300 KG
  ≤ 300 WATTS
  ≤ 0.3 MBPS UPLINK/2.0 MBPS DOWNLINK
  ≤ 100 MBYTES DATA STORAGE/ORBIT
  ORU COMPATIBLE I/F (ORU TOOL)
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

SMALL AND RAPID RESPONSE PAYLOADS

INTERFACE COMPARISON CHART FOR RELATIVELY SMALL ATTACHED PAYLOADS* ON TRUSS AND JEM EF (PROPOSED)

<table>
<thead>
<tr>
<th>Interface or Physical Constraint</th>
<th>PAYLOAD</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>SARR Trunnion Keel</td>
</tr>
<tr>
<td>Weight</td>
<td>≤ 1980 lbs (890 kg)</td>
</tr>
<tr>
<td>Volume Limitations</td>
<td>- 10m³</td>
</tr>
<tr>
<td>Physical Dimensions</td>
<td>1.25m x 2.0m x 4.0m</td>
</tr>
<tr>
<td>Thermal Cooling</td>
<td>only passive</td>
</tr>
<tr>
<td>Power Constraint</td>
<td>≤ 1.5kW</td>
</tr>
<tr>
<td>Data Rates Downlink</td>
<td>2.0 Mbps</td>
</tr>
<tr>
<td></td>
<td>0.3 Mbps</td>
</tr>
<tr>
<td>Access to Pressurized Module</td>
<td>None</td>
</tr>
<tr>
<td>Pointing Capability Provided</td>
<td>None</td>
</tr>
</tbody>
</table>

U.S. SPACE STATION PRESSURIZED MODULES

* These do not require an APAE
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

TRIAL PAYLOAD MANIFEST, U.S. LABORATORY MODULE: AFTER OUTFITTING FLIGHT OF-1

COMMAND/CONTROL WORKSTATION DESIGN CONCEPT

DMS Fixed MPAC Components
- Three 15" color CRTs
- QWERTY keyboard
- Trackball
- Hand controllers
- Processor
- Safety-critical D&C
- Hard-copy printer/plotter

Other Components
- Video recorders
- Audio recorders
- Lighting
- Crew restraints

Functions
- Subsystem management, customer support, proximity operations, telerobotic (MSC, FTS) control, external operations support
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

COMMAND/CONTROL WORKSTATION DESIGN CONCEPT

Key MPAC Requirements
- Alphanumeric
- Graphics
- Animation
- Integrated Video, Graphics, Text
- Color Displays
- Windowing
- Voice Input
- Voice Output
- 3D Graphics
- Run the DMS USE Software
INTERNAL SARR PAYLOAD REQUIREMENTS

- LOCATION REQUIREMENTS:
  DEDICATED STANDARD DOUBLE RACK FOR UP TO 10 INTERNAL SARR PAYLOADS. RACK SHALL BE CAPABLE OF BEING RECONFIGURED ON ORBIT TO SUPPORT STANDARD SARR PAYLOADS.

- RESOURCE PROVISIONS FOR DEDICATED STANDARD DOUBLE RACK:

  MAXIMUM RESOURCES ARE WITHIN BASELINE VALUES

NO ACTIVE COOLING (STANDARD RACK AIR COOLING ONLY)

CUPOLA WORKSTATION CONCEPT

Key Cupola MPAC Reqs
- Alphanumeric
- Graphics
- Animation
- Video
- Telerobotics Control
- OMV Piloting
- MSC Control
- Run the DMS USE Software

DMS Cupola MPAC Component
- Two 15" TFEL Displays
- Two QWERTY keyboards
- Two Trackballs
- Hand controllers
- Processor

Other Components
- Lighting
- Crew restraints
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

MOBILE SERVICING CENTER
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

Microgravity Quasi-Static Isogravity Contours ($x10^4$ G)
(June, 1999, Altitude 230 n. miles)
Front View

Microgravity Quasi-Static Isogravity Contours ($x10^4$ G)
(June, 1999, Altitude 230 n. miles)
Side View
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

Microgravity Quasi-Static Isogravity Contours (x10^4 G)
(June, 1999, Altitude 230 n. miles)
Close-up of U.S. Laboratory

SPACE STATION ELECTROMAGNETIC COMPATIBILITY
AND ENVIRONMENTAL INTERACTIONS STUDY

NATURAL ENVIRONMENTS
- NEUTRAL
- PARTICULATE
- RADIATION
- MAGNETIC FIELD
- PLASMA
- EM RADIATION

ENVIRONMENT PERTURBATIONS
- THRUSTER FIRINGS
- VENTS AND OUTGASSING
- INDUCED CURRENTS
- COUPLING OF EM WAVES
- PLASMA BEAMS
- PARTICULATES
- RAM/WAKE

ENVIRONMENT INDUCED PHENOMENA
- CHARGING
- ESD
- EMI
- HIGH VOLTAGE SURFACES
- SURFACE CONTAMINATION
- LONG TERM DEGRADATION
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

INDUCED ENVIRONMENT NEAR LARGE SURFACES (ANDERSON [1984])

<table>
<thead>
<tr>
<th>PARAMETERS</th>
<th>RAM</th>
<th>WAKE</th>
<th>COMMENT</th>
<th>EFFECT</th>
</tr>
</thead>
<tbody>
<tr>
<td>NEUTRAL DENSITY, Torr</td>
<td>$10^{-5}$</td>
<td>$10^{-7}$</td>
<td>MEASURED</td>
<td>HIGH VOLTAGE SHORTS, CONTAMINATION</td>
</tr>
<tr>
<td>PLASMA DENSITY, cm$^3$/m$^3$</td>
<td>AS HIGH AS $5 \times 10^5$</td>
<td>AS LOW AS 10</td>
<td>MEASURED</td>
<td>POWER LOSS, ARcing</td>
</tr>
<tr>
<td>PLASMA WAVES</td>
<td>20 Hz - 300 kHz (220nV)/m at peak</td>
<td>LOW</td>
<td>MEASURED ELECTROSTATIC WAVES</td>
<td>EM BACKGROUND NOISE</td>
</tr>
<tr>
<td>ENERGETIC PARTICLES</td>
<td>MEAN ENERGY OF ELECTRONS 10 - 100 eV FLUX $10^9$/cm$^2$ sec ster ev MEAN ENERGY OF IONS 10 - 30 eV</td>
<td>LOW</td>
<td>HIGHER FLUXES PREDICTED; LITTLE NUMERICAL DATA PUBLISHED</td>
<td>PLASMA WAKE, DIFFERENTIAL CHARGING</td>
</tr>
<tr>
<td>GLOW, PHOTONS (cm$^3$/s)$^{-1}$</td>
<td>$10^7$ - $10^8$</td>
<td>LOW</td>
<td>GLOWING LAYER IN RAM 10 - 20 cm THICK</td>
<td>OPTICAL (IR) CONTAMINATION</td>
</tr>
</tbody>
</table>

ORIGINAL PAGE IS OF POOR QUALITY
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division Utilization & Operations Group NASA Space Station Freedom Program Office, Reston, Virginia

POTENTIAL ENVIRONMENTALLY ACTIVE PAYLOADS

ASTROMAG (EARLY ATTACHED PAYLOAD CANDIDATE)
- ENERGY STORED BY MAGNETIC FIELD: 10 MEGA JOULES
- MAXIMUM MAGNETIC FIELD INTENSITY: 70,000 GAUSS
- FIELD CONFIGURATION: QUADRUPOLE, DECREASES TO EARTH'S MAGNETIC FIELD INTENSITY AT 15 METER DISTANCE

SOLAR TERRESTRIAL OBSERVATORY: PLASMA PHYSICS GROUP (LATER ATTACHED PAYLOAD CANDIDATE)
- ELECTRON BEAMS
- WAVE GENERATORS - GROWTH VERSION UP TO 50 KW POWER REQUIREMENT

HIGH TEMPERATURE SUPERCONDUCTING MAGNETIC FIELD ENERGY STORAGE SYSTEM (CANDIDATE PAYLOAD ANTICIPATED)
- HIGH MAGNETIC FIELD INTENSITIES

ADVANCED ELECTRIC AND ELECTROMAGNETIC PROPULSION SUBSYSTEM TECHNOLOGY TESTS (CANDIDATE PAYLOAD ANTICIPATED)
- HIGH MAGNETIC FIELD AND ELECTRIC FIELD INTENSITIES
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

INDUCED ENVIRONMENTAL EFFECTS OF ACTIVE TECHNOLOGY PAYLOADS - TOP VIEW

---

Space Station Freedom User/Payload Integration & Accommodations

---

SERVICING FACILITY

- Repair and conduct resupply and refueling operations for free flyers and co-orbiting platforms
- Extensive repair work for attached payloads
- Assembly of upper stages and payloads

LARGE SPACE CONSTRUCTION FACILITY

- Large crane for positioning
- Additional mobile robotics
- Capability to assemble large antennas, phased-array optical systems

CO-ORBITING PLATFORM, ADVANCED TECHNOLOGY TEST FACILITY

- User-supplied or station-supplied platform to conduct partial or full-up tests of advanced propulsion and power systems
- Testing of technology involving hazardous materials or operations or requiring orbital dynamics not supported by the station
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

| SPACE STATION FREEDOM POLAR PLATFORM |
| SKP TRUSS DERIVATIVE CONFIGURATION |
| WITH HRSO |
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

Assembly of Large Deployable Reflector - I

Assembly of Large Deployable Reflector - II
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

SPACE STATION WITH CANDIDATE MANNED MARS CONFIGURATION

Manned Mars Accommodation Study
PROPELLANT TANK FARM

CO-ORBITING PROPELLANT TANK FARM RECOMMENDED TO STORE AND TRANSFER PROPELLANTS FOR MANNED MARS MISSION

CAPACITY
1.9 M LB H₂, O₂
12 TANKS 16' X 60'
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

<table>
<thead>
<tr>
<th>Space Station User Integration Process</th>
<th>SPACE STATION FREEDOM UTILIZATION &amp; OPERATIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Process Description</strong></td>
<td></td>
</tr>
<tr>
<td>◊ SCOPE</td>
<td></td>
</tr>
<tr>
<td>▶ End to End User Integration Is the Process Which:</td>
<td></td>
</tr>
<tr>
<td>▶ Enables a User to Conduct Research, Development or Commercial Activities on the Station.</td>
<td></td>
</tr>
<tr>
<td>▶ Includes All Interactions Between the SSP and the User/User Sponsors</td>
<td></td>
</tr>
<tr>
<td>▶ External Activities Beginning with the User's Initial Contact With the SSP and Continuing Until Exit from the Program.</td>
<td></td>
</tr>
<tr>
<td>◊ The Integration Process Shall Provide a &quot;Level Playing Field&quot;, with Payloads having similar Physical and Operational Requirements following the Same Path.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Space Station User Integration Process</th>
<th>SPACE STATION FREEDOM UTILIZATION &amp; OPERATIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Process Description</strong></td>
<td></td>
</tr>
<tr>
<td>◊ PROCESS DEVELOPMENT GOAL:</td>
<td></td>
</tr>
<tr>
<td>▶ Provide a Process for User Integration Which:</td>
<td></td>
</tr>
<tr>
<td>▶ Supports a Diverse User Community, Including Rapid Response Research (RIB)</td>
<td></td>
</tr>
<tr>
<td>▶ Enables high priority research and development supporting national objectives and future missions.</td>
<td></td>
</tr>
<tr>
<td>▶ Minimizes the Burden on the Users (Data, Meetings, etc.)</td>
<td></td>
</tr>
<tr>
<td>▶ Provides single point of contact for Shuttle and Station Integration</td>
<td></td>
</tr>
<tr>
<td>▶ Does Not Compromise Safety</td>
<td></td>
</tr>
<tr>
<td>▶ Incorporates Lessons Learned from Past Programs</td>
<td></td>
</tr>
<tr>
<td>▶ Recognizes Constraints Imposed by the Physical Requirements of Payload Integration</td>
<td></td>
</tr>
</tbody>
</table>
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

Space Station User Integration Process

Integration Process Overview

- Consider as Multiple Processes:
  ◇ Payload Accommodation Assessment
    - Verify station or platform capabilities can accommodate payload requirements
    - Identify deficiencies and potential station enhancements or potential reduction in payload requirements required
  ◇ Payload Development
    - Payload DDT&E Conducted by Developer, PI
    - Driven by Experiment Goals, Development Resources
  ◇ Analytical Integration
    - Engineering Analysis (Loads, Thermal, EMI, Contam., etc.)
    - Verify S/W Design
    - Analytical Support of Certification/Verification
  ◇ Payload Integration, Test & Verification
    - Safety Certification
    - Verify P/L Design for Transportation, On-orbit Ops
    - Ensure that P/L Ops, Failures Will Not Endanger Crew, Station, Other Payloads (FMEA's, Failure Propagation, Debris Impacts, Etc.)
  ◇ Physical Integration
    - Perform Required P/L to Rack, Carrier Integration
  ◇ Payload Operations
    - On-orbit Payload Installation & C/O
    - Conduct Experiment Runs, Gather Data
    - Telescience & On-orbit Control
    - Safing, Deintegration & Return to Developer
  ◇ Post Flight Debriefing, Lessons Learned, and Data Analysis
### Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

#### User Support Features

- **Standardized Flows for Payload Classes**
  - Payloads Integration Flows Optimized for Level of P/L Complexity
  - Streamlined Flows for Rapid Response Research Payloads
    - Payloads Meet Pre-defined Constraints
    - Users of Existing Facilities

- **Payload Accommodations Manager**
  - Single Point of Contact Between User/Sponsor & SSP
  - Assists User During All Phases After Selection

- **Science & Technology Centers**
  - Conduct Tests, Modelling, Physical Integration for User
  - Both Gov't and Commercial (NASA Approved) Entities

- **Payload Operations**
  - Payload Operations Conducted by User (Telescience)
  - Overall Coordination, Safety Monitoring Provided by POIC
  - Distributed User Locations

- **Computer Supported Document Preparation, Reviews**
  - Use of Expert Systems as Appropriate ("Smart Documents")

#### "Beat The System"

- **TWO PATHS TO SIMPLE INTEGRATION, RAPID FLIGHTS**
  - **Use an Existing "Facility Class Payload"**
    - Freedom is a Long Duration "Orbital International Research and Development Lab"
      - Analogous to: Argonne National Laboratory, LaRC, Kitt Peak, LeRC, etc.
    - Major Facilities and Lab Support Equipment Available:
      - Truss Payload Accommodation Equipment, Payload System, Mobile Servicing Center, Flight Telerobotic Servicer, SS Furnace Facility, EVA Servicing, Glovebox, etc.
    - Use of Existing Facilities Requires Integration of Sample, Procedures: No DDT&E, Certification of Unique Hardware

  - **Design/Build an "R" Payload**
    - "R" = Rapid Response Research: Payloads Defined to Established Guidelines (extension of GAS, STS Mid deck):
      - Simple, Standard Interfaces
      - Modest Resource Requirements
      - Standard Req'ts for Safety, Physical Integration, Crew Support
      - Both Internal and External
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

Space Station User Integration Process

User/Payload Integration Complexity

Longest Duration (2 - 5 Years)

- User Designs/Supplies Facility Class (Multiple User) Payload for Station
- User Designs/Supplies Standard (Single User) Payload for Station
- User Modifies Facility P/L Hardware, Software and Operations and Provides Samples, Specimens
- User Designs/Supplies R Payload
- User Modifies Existing Facility Payload Software and Operations; Provides Samples

Shortest Duration

- User Modifies Facility Operations and Provides Samples, Consumables

Most Complex

Least Complex

Space Station User Integration Process

Existing Facilities Use Dominates Mature Operations

Attached & Pressurized Facility Installation (Station Outfitting)

Mature User/Facility Operations

Early User Operations

SARRs, Press. & Attach. P.A. Changeout

Time Period

Traditional "Payload/Mission Integration" for hardware being shipped to/from Orbit

"Reconfiguration" of on-Orbit Facilities/Payloads to support Multiple User Operations (includes shipment/changeout/use of technology units, specimens, samples and consumables)
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

Space Station User Integration Process

Examples of Station-to-User Interface:
U.S. Commercial Cooperative vs. U.S. Technology User

Commercial Cooperative (JEA Type)
- OCP Level-I (Code C)
- OCP Commercial Development Division
- Private Corporation
- Corporate Principal Investigator
- OCP LV-III Organizations
- Payload Accommodations Manager

Government Technology (NASA OAST Type)
- OAST Level-I (Code E)
- Program Office Level II
- Utilization & Operations
- User Integration Division
- OAST Flight Systems Division
- Payload Sponsoring Division
- OAST Space Station Utilization
- OAST LV-III Organization: PI Developer
- Principal Investigator Team

Space Station User Integration Process

User Operations Architecture

NSTS/Spacelab
- Mission Control Center (MCC) NASA/USC
- Payload Operations Control Center (POCC) NASA/MSFC

S. S. Freedom
- Space Station Control Center (SSCC) NASA/USC
- Payload Operations Integration Center (POIC) NASA/MSFC

Distributed, User Owned Command & Control (Telescience) Facilities
- Single User
- Multiuser, Multidiscipline
- Multiuser, Single Discipline
- User Operations Facilities (UOFs)
- Regional Operations Centers (ROCs)
- Discipline Operations Centers (DOCs)
Space Station Freedom User/Payload Integration & Accommodations

Alan C. Holt, Deputy Director (Acting), User Integration Division
Utilization & Operations Group
NASA Space Station Freedom Program Office, Reston, Virginia

**SPACE STATION FREEDOM TECHNOLOGY PAYLOAD ACCOMMODATION**

- **PROVIDES FOR MULTIPLE TYPES AND SIZES OF TECHNOLOGY R.&D. OPPORTUNITIES**
  - Quiet and active environmental condition periods can be scheduled

- **SPACE STATION FREEDOM, TOGETHER WITH CO-ORBITING PLATFORM TEST FACILITIES, CAN FUNCTION AS A MAJOR TEST BED FACILITY**
  - To support interplanetary spacecraft R.&D.
  - To support lunar/mars base technology and systems R.&D.

- **SPACE STATION FREEDOM USER INTEGRATION AND PAYLOAD ACCOMMODATION PROCESSES WILL BE ESTABLISHED**
  - To insure rapid and successful integration of technology payloads
  - Will enable "Skunk Works" R.&D. in space.
### CRITICAL IN-SPACE TECHNOLOGY NEEDS

**Space Structures**

Martin Mikulas, Jr.  
Langley Research Center  
Hampton, Virginia

#### THEME ELEMENT #1: STRUCTURES

1. SYSTEM IDENTIFICATION  
   - QUASI-STATIC  
   - DYNAMIC
2. VERIFICATION OF PREDICTION METHODS
3. ERECTABLE STRUCTURES CONSTRUCTION
4. PRECISION SENSOR DEVELOPMENT
5. STRUCTURAL INTEGRITY

#### THEME ELEMENTS #2 & 3: CONTROL/STRUCTURE INTERACTION & CONTROLS (COMBINED)*

1. FLEXIBLE MULTIBODY/ARTICULATED CONTROL
2. PRECISION POINTING AND SHAPE DIMENSIONAL CONTROL
3. MULTIPLE INTERACTING CONTROL SYSTEM
4. DAMPING AND VIBRATION SUPPRESSION
5. VIBRATION ISOLATION

*RECOMMENDATIONS: EXPERIMENTS SHOULD BE MULTIDICIPLINARY IN NATURE AND PREFERABLY IN THE FORM OF REUSABLE TEST BEDS.

**NOTE:** Lists are in priority order, starting with 1 for each Theme Element
CRITICAL IN-SPACE TECHNOLOGY NEEDS
Space Environmental Effects

Lubert J. Leger
Johnson Space Center
Houston, Texas

THEME ELEMENT #1: ATMOSPHERIC EFFECTS AND CONTAMINATION

1. ACTIVE MEASUREMENT OF ATMOSPHERIC CONSTITUENTS SUCH AS ATOMIC OXYGEN, TO SUPPORT STUDIES OF ALL ATMOSPHERIC INTERACTION PHENOMENA
2. GLOW PHENOMENA INFORMATION TO SUPPORT SENSOR DESIGN
3. CONTAMINATION EFFECTS AND ATOMIC OXYGEN EROSION DATA FOR MATERIAL DURABILITY ASSESSMENT FUNCTIONAL PERFORMANCE PREDICTION AND MODEL DEVELOPMENT AND VERIFICATION

THEME ELEMENT #2: MICROMETEOROID AND DEBRIS

1. CHARACTERIZATION OF THE LOW EARTH ORBIT DEBRIS ENVIRONMENT
   - PARTICLE SIZE DISTRIBUTION
   - MORE INFORMATION ON DEBRIS CHARACTERISTICS - SPECTRAL PROPERTIES, SHAPE, COMPOSITION
2. LONG TERM SURFACE DEGRADATION FROM DEBRIS
3. DEVELOP AND VERIFY COLLISION WARNING SYSTEMS TECHNOLOGY
4. EVALUATE AND VERIFY MITIGATION TECHNIQUES

THEME ELEMENT #3: CHARGED PARTICLES & ELECTROMAGNETIC RADIATION EFFECTS

1. BETTER CHARACTERIZATION OF RADIATION ENVIRONMENT IN POLAR REGION AND VAN ALLEN RADIATION BELTS & ASSOCIATED WITH SOLAR FLARE ACTIVITY
2. LONG TERM, CONTINUOUS MEASUREMENTS OF MATERIAL PHYSICAL AND ELECTRICAL PROPERTIES IN CRITICAL ORBITS FOR UNDERSTANDING OF INTERACTION MECHANISM AND VALIDATION OF GROUND BASED TESTING
3. DETERMINE THE EFFECTS OF GAS RELEASES IN LEO ON ELECTROMAGNETIC INTERACTIONS
4. DEVELOPMENT OF SIMPLE SMALL AUTONOMOUS SENSORS FOR MEASUREMENT OF SURFACE CHARGING, RADIATION EXPOSURE AND ELECTRIC FIELDS

NOTE: Lists are in priority order, starting with 1 for each Theme Element
CRITICAL IN-SPACE TECHNOLOGY NEEDS
Power Systems and Thermal Management

Roy McIntosh
Goddard Space Flight Center
Greenbelt, Maryland

THEME ELEMENT #1: DYNAMIC AND NUCLEAR POWER SYSTEMS
1. GAS COLLECTION AND RETENTION IN LIQ COOLANTS
2. FREEZE/THAW IN LIQ METAL SYSTEMS
3. GAS BUBBLE NUCLEATION/GROWTH IN LIQ METALS
4. TWO COMPONENT (SOLID/LIQUID) PUMPING/SEPARATION
5. TWO PHASE LIQ/GAS SEPARATION IN COOLANTS

THEME ELEMENT #2: CONVENTIONAL POWER SYSTEMS
1. ADVANCED ENERGY STORAGE
2. ADVANCED P.V. CELL TECHNOLOGY
3. PRIMARY & REGENERATIVE FUEL CELLS
4. THERMAL ENERGY STORAGE
5. CONTAMINATION, UV & CHARGED PARTICLE PV EFFECTS

THEME ELEMENT #3: THERMAL MANAGEMENT
1. TWO-PHASE HEAT TRANSFER
2. HEAT PIPES (LIQUID METAL & CRYO)
3. CAPILLARY LOOPS
4. TWO PHASE FLOW & STABILITY
5. VOID BEHAVIOR FLIGHT TEST

NOTE: Lists are in priority order, starting with 1 for each Theme Element
CRITICAL IN-SPACE TECHNOLOGY NEEDS  
Fluid Management and Propulsion Systems

Lynn Anderson  
Lewis Research Center  
Cleveland, Ohio

<table>
<thead>
<tr>
<th>THEME ELEMENT #1: ON-ORBIT FLUID MANAGEMENT</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. FLUID TRANSFER</td>
</tr>
<tr>
<td>2. MASS GAUGING</td>
</tr>
<tr>
<td>3. THERMODYNAMIC VENT SYSTEM/MIXING</td>
</tr>
<tr>
<td>3. LIQUID ACQUISITION DEVICES</td>
</tr>
<tr>
<td>3. FLUID DUMPING/TANK INERTING</td>
</tr>
<tr>
<td>4. LIQUID DYNAMICS/SLOSH</td>
</tr>
<tr>
<td>5. AUTOGENOUS PRESSURIZATION</td>
</tr>
<tr>
<td>5. LONG TERM STORAGE</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>THEME ELEMENT #2: PROPULSION</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. PLUME IMPACTS &amp; CHARACTERISTICS</td>
</tr>
<tr>
<td>2. ELECTRIC PROPULSION SPACE TEST</td>
</tr>
<tr>
<td>3. MULTIDISCIPLINE SPACE TEST BED</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>THEME ELEMENT #3: FLUID PHYSICS</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. LIQUID-VAPOR INTERFACES</td>
</tr>
<tr>
<td>2. POOL/FLOW BOILING</td>
</tr>
<tr>
<td>2. CONDENSATION/EVAPORATION</td>
</tr>
<tr>
<td>3. ADVANCING LIQUID FRONTS</td>
</tr>
<tr>
<td>3. BUBBLE/DROPLET DYNAMICS</td>
</tr>
</tbody>
</table>

NOTE: Lists are in priority order, starting with 1 for each Theme Element
CRITICAL IN-SPACE TECHNOLOGY NEEDS
Automation and Robotics

Antal K. Bejczy
Jet Propulsion Laboratory
Pasadena, California

THEME ELEMENT #1: ROBOTIC SYSTEMS

1. Active/Passive Compliance Control and Precision Control in Smart End Effector-Tool-Object Interaction
2. Disturbance Rejection and Stabilization in Robot/Platform Coupling Dynamics
3. Sensor-Corrected Planned Motion Execution, Including Collision Detection and Avoidance
4. Adaptive Control Coordination of Multiple Arm/End Effector Systems
5. Fast, High Bandwidth and Small-Volume Control and Data Processing Electronics

THEME ELEMENT #2: TELEOPERATIONS

1. Operator Interaction in Micro-G with Force-Reflecting Control
2. Control Techniques for Communication Time Delay Conditions
3. Operator Multi-Mode Manual and Supervisory Control Interaction with Remote Manipulators
4. Intelligent Information Fusion Display Systems
5. Operator Perceptive/Command Interaction with High Degree of Freedom Arm/End Effector Systems

THEME ELEMENT #3: ARTIFICIAL INTELLIGENCE

1. Fault Detection and Processing Systems
2. Large Input/Output Sensor and Sensor Fusion Systems
3. Integrated Model and Data Sensing Information Systems
4. Contingency Management Systems
5. Parallel, Integrated Symbolic and Numeric Data Processing and Intelligent Operating Systems

NOTE: Lists are in priority order, starting with 1 for each Theme Element
THEME ELEMENT #1 : SENSORS

1. SPACE QUALIFIED COOLER AND COOLER SYSTEMS
2. IN-SPACE POINTING AND CONTROL

THEME ELEMENT #2 : COMMUNICATIONS

1. IN-SPACE LASER COMMUNICATIONS TECHNOLOGY DEMO.

THEME ELEMENT #3 : INFORMATION SYSTEMS

1. IN SPACE TESTING/DEMONSTRATION OF HIGHER PERFORMANCE COMPUTERS FOR AUTOMATED OPERATIONS AND ROBOTICS APPLICATIONS
2. IN SPACE TESTING/DEMONSTRATION OF SPECIAL PURPOSE PROCESSORS (e.g., FROM THE CSTI HIGH RATE DATA SYSTEMS PROGRAM) FOR IMAGE COMPRESSION/PROCESSING FOR SCIENCE EXPERIMENTS AND ROBOTICS APPLICATIONS
3. IN SPACE TESTING OF HIGH RATE/VOLUME STORAGE DEVICES FOR IMAGE DATA PROCESSING AND COMMUNICATION LINK BUFFERING
4. IN SPACE TESTING AND CHARACTERIZATION OF RADIATION EFFECTS OF NEXT GENERATION COMMERCIAL AND RADIATION HARDENED DEVICES IN VARIOUS ORBITS FOR GENERAL SPACECRAFT AND INSTRUMENT APPLICATIONS

NOTE: Lists are in priority order, starting with 1 for each Theme Element
CRITICAL IN-SPACE TECHNOLOGY NEEDS
In-Space Systems

Jon B. Haussler
Marshall Space Flight Center
Huntsville, Alabama

THEME ELEMENT #1: MATERIALS PROCESSING

1. UNDERSTANDING OF MATERIALS BEHAVIOR IN SPACE ENVIRONMENT
2. DEMONSTRATION OF INNOVATIVE IN-SPACE SAMPLE ANALYSIS TECHNIQUES
3. CHARACTERIZATION AND MANAGEMENT OF THE MICRO-G ENVIRONMENT
4. DEMONSTRATION OF IMPROVED SENSING AND IMAGING TECHNIQUES IN EXPERIMENTAL SYSTEMS
5. DEMONSTRATION OF AUTOMATION AND ROBOTICS APPLICATIONS TO MATERIAL PROCESSING SYSTEMS

THEME ELEMENT #2: MAINTENANCE, REPAIR, AND FIRE SAFETY

1. DEMONSTRATION AND VALIDATION OF CAPABILITY TO REPAIR UNEXPECTED EVENTS
2. INVESTIGATION OF LOW-G IGNITION, FLAMMABILITY/FLAME SPREAD AND FLAME CHARACTERISTICS
3. DEMONSTRATION AND VALIDATION OF FLUID REPLENISHMENT TECHNIQUES
4. UNDERSTAND BEHAVIOR OF FLAME EXTINGUISHANTS IN SPACE ENVIRONMENT
5. DEMONSTRATE ROBOTIC MAINTENANCE AND REPAIR CAPABILITY

THEME ELEMENT #3: PAYLOAD OPERATIONS

1. DEMONSTRATION AND VALIDATION OF TELESCIENCE TECHNIQUES
2. DEMONSTRATION OF AUTONOMOUS CHECKOUT, PLACEMENT AND SPACE CONSTRUCTION

NOTE: Lists are in priority order, starting with 1 for each Theme Element
CRITICAL IN-SPACE TECHNOLOGY NEEDS
Humans In Space

Remus Bretol
Ames Research Center
San Jose, California

THEME ELEMENT #1 : EVA / SUIT

1. TECHNOLOGY FOR MEASUREMENT OF EVA FORCES, MOMENTS, DYNAMICS, PHYSIOLOGICAL WORKLOAD, THERMAL LOADS, AND MUSCULAR FATIGUE
2. EVALUATION OF COOPERATIVE ROLES BETWEEN EVA AND TELEROBOTS AND FOR IVA AND ROBOTICS
3. SUIT CONTAMINANTS DETECTION, IDENTIFICATION AND REMOVAL

THEME ELEMENT #2 : HUMAN PERFORMANCE

1. TECHNOLOGY AND MEASUREMENT OF GRAVITY-RELATED ADAPTATION AND RE-ADAPTATION BEHAVIOR
2. TECHNOLOGY FOR IN-SPACE ANTHROPOMETRIC AND PERFORMANCE MEASUREMENT
3. VARIABLE GRAVITY FACILITY AND APPLICATION TECHNOLOGY

THEME ELEMENT #3 : CLOSED-LOOP LIFE SUPPORT

1. IMPROVED PHASE SEPARATION SYSTEMS
2. GRAVITY-INDEPENDENT SENSOR SYSTEMS
3. WASTE-CONVERSION PROCESSES

NOTE: Lists are in priority order, starting with 1 for each Theme Element
This Page Intentionally Blank
In-Reach / Out-Reach Program

In-Reach / Out-Reach Experiments and Experiment Integration Process
EXPERIMENT OBJECTIVE

Define a flight experiment for a hybrid scaled truss in the Orbiter’s cargo bay. This experiment may be used to:

- Validate analytical techniques for predicting nonlinear dynamic behavior in truss structures
- Validate Hybrid Scale theory
- Validate 1g ground test techniques
- Address other technology issues

BACKGROUND/TECHNOLOGY NEED

- Many space truss structures envisioned for the future will be too large to dynamically test in full-scale on the ground
- Truss joints can dominate dynamic behavior and are not easily scaled due to their complexity
- Nonlinear characteristics in joints, such as free play, nonlinear stiffness, damping, and friction can only reasonably be simulated in a 0g space environment
- Analytical methods for predicting nonlinear behavior and damping need to be validated

- A hybrid scaled truss with full-size joints and subscale struts offers a smaller, more manageable structure for dynamic testing on the ground and in space. The truss will be used to validate analytic predictive methods, ground test techniques, the hybrid scale concept, and investigate other important technology issues.
EXPERIMENT DESCRIPTION

- 1g ground test multi-bay erectable truss with short struts and full-size joints (Hybrid Scaled)
- 0g flight test truss and correlate with ground test results
- Validate analytical predictive techniques for nonlinear response and damping
- Investigate other technology issues
  - Instrumentation performance
  - Disturbance propagation
  - Damaged or damped members
  - Utilities/payload integration
  - EVA time lines
  - Long-term exposure test bed
In-Space Structural Dynamics: Evaluation of a Skewed Scale Truss

James H. Peebles
McDonnell Douglas Astronautics, Space Station Division
Contract: NAS1-18688, NASA Langley Research Center, Stanley E. Woodard

1. Participate in OAST workshop.
2. Develop the specific objectives.
3. Perform preliminary analyses.
4. Examine methods to erect truss.
5. Propose support structure concepts:
   - Launch, On-Orbit Test, Ground Test.
6. Examine potential test parameters.
   - (a) Wind out
   - (b) Nonlinear joint
   - (c) Damping
   - (d) Utility tray installation
   - (e) On-orbit test bed
7. Develop test plans for in-space and lab tests.
8. Develop an instrumentation plan.
9. Identify requirements for excitation sources.
10. Develop an analytical modeling plan.
11. Establish an implementation plan.
12. Prepare quarterly progress reports.
13. Prepare and publish final report.
OBJECTIVES OF MODE

INVESTIGATE DYNAMICS OF TWO ASPECTS OF NONLINEAR SPACECRAFT DYNAMIC SYSTEMS WHICH ARE GRAVITY DEPENDENT

- **MODE I**
  Dynamics of a partially filled fluid tank as it interacts with flexible vehicle motions. Needed to verify modeling of large mass fraction fluid storage system.

- **MODE II**
  Nonlinear contribution of joints of statically indeterminate truss structure to damping and modal structure. Needed to verify structural modeling techniques for use with precision/active structure.

BACKGROUND TO MODE

**MODE I - FLUID/STRUCTURE INTERACTION**
- Linearized and nonlinear fluid models already developed consider large motion of highly curved free surface.
- Extensive 1-g testing at M.I.T.
- Extensive short term 0-g testing on KC-135.
- Twenty seconds of +/- 0.02 g environment not sufficient.

**MODE II - NONLINEAR TRUSS STRUCTURE**
- Linearized and nonlinear models already developed include contribution of material damping and joint nonlinearity.
- Extensive 1-g and vacuum testing at M.I.T.
- Short term 0-g testing in M.I.T. ASTROVAC.
- Require zero gravity pre-load/long duration to study lightly damped/on-orbit behavior.
**MIDDECK EXPERIMENT**

**ESM**
Experimental Support Module

- **Experiment Control**
- **Excitation**
- **Data Recorder**
- **Data Measurement**

**Test Articles**

- **MODE I**
- **MODE II**

**TEST ARTICLES**

- **MODE I**
  - Cylindrical tank coupled to a one DOF dynamic system

- **MODE II**
  - Hybrid scale model erectable truss

**EXPERIMENTAL HARDWARE**

- ESM: Experimental support module provides capabilities typical of a dynamic test facility in single middeck locker
- Two test articles, MODE I & II, deployed and tested in Middeck.
TIMELINE

<table>
<thead>
<tr>
<th>JAN</th>
<th>FEB</th>
<th>MAR</th>
<th>APR</th>
<th>MAY</th>
<th>JUN</th>
<th>JUL</th>
<th>AUG</th>
<th>SEP</th>
<th>OCT</th>
<th>NOV</th>
<th>DEC</th>
</tr>
</thead>
<tbody>
<tr>
<td>'88</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>START</td>
</tr>
<tr>
<td>'89</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>PFER</td>
</tr>
<tr>
<td>'90</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>PDR/</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>FER</td>
</tr>
<tr>
<td>'91</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>CREW</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>TRAIN</td>
</tr>
<tr>
<td>'92</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>PMER</td>
</tr>
</tbody>
</table>

PFER: Preliminary Flight Experiment Review
FER: Flight Experiment Review
PPDR: Payload Pre-Delivery Review
PMER: Post Mission Experiment Review

SUMMARY

- Since each of the phenomena under study is fundamentally influenced by gravity, experiments must be done in zero gravity.
- All available Earth based simulations of zero gravity have already been exploited.
- These experiments complement programs of near term interest to NASA.
- Involvement of corporate participants, Boeing Aerospace and McDonnell Douglas, assures relevance of experiment and dissemination of technology.
Experiment Objective

The objective is to build an experiment which will measure the influence of gravity on structural damping of a truss structure.

- A three-bay subscale truss will be constructed.
- The truss and the joints used will be similar to those proposed for the Space Station.
- Ground-based testing will measure damping with 1-g loads.
- Fly as Get Away Special experiment to get micro-gravity damping.
- Results will provide qualitative data on the influence of gravity on damping.

Background/Technology Need

Predicting the amount of damping expected in large space structures is expected to be difficult.

- Joints holding the structure together will produce some damping.
- The amount of damping produced by joints is dependent on several variables.
- Damping can be gravity dependent in a truss with pinned joints.
- On-ground damping measurements may be in error due to gravity loads.
- A data base of in-orbit and on-ground tests is needed to permit better predictions of damping for other structures.
Experiment Description

The experiment consists of a three-bay truss and associated hardware for truss excitation and measurement of oscillations.

- The experiment fits inside a 5 cubic foot Get Away Special Cannister.
- Cantilevered truss with a tip mass to reduce the resonant frequency.
- Cannister vented to space to eliminate air damping.
- Truss excitation will induce bending modes in two directions or a torsional mode.
- Means for tip mass support during launch and reentry will be provided.

Previous Experiments

An experiment has been constructed to measure damping of a tetrahedral truss with pinned joints.

- One of 6 experiments to fly as a GATOS Payload.
- Very small project budget.
- Damping is gravity dependent.
Prototype truss design

As part of the Experiment Definition Phase we are constructing a truss for ground testing.

- 3 Bay truss.
- First bay uses 1/4 scale joints made by StarNet Structures.
- An inexpensive bolted joint is used elsewhere.
- Ground tests will examine the influence of gravity on damping.

1988-89 Schedule

<table>
<thead>
<tr>
<th>Joint Selection</th>
<th>JUN</th>
<th>JUL</th>
<th>AUG</th>
<th>SEP</th>
<th>OCT</th>
<th>NOV</th>
<th>DEC</th>
<th>JAN</th>
<th>FEB</th>
<th>MAR</th>
<th>APR</th>
<th>MAY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Truss Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Excit/Locker Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Prototype Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Fabricate Prototype</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Ground Testing</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Drawing Package</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Report Preparation</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### EXPERIMENT OBJECTIVE:

- Develop both passive and active techniques to isolate sensitive payloads from shock and vibration.
- Demonstrate candidate methodologies in low-gravity simulator.

### BACKGROUND/TECHNOLOGY NEED

Experiments and processes in laboratory module require microgravity. Vibration excited by adjacent experiments or crew activity can contaminate the low-gravity environment and degrade the usefulness of the experiment or process.

- Study will identify vibration isolation techniques for rigid body payload.
- Can verify methodology concept in one-"g" environment.
- Working model design verification requires shuttle flight.
EXPERIMENT DESCRIPTION:

- Low-gravity is simulated in the horizontal plane with a cart supported on air-bearing pads.
  - The cart rides on a film of air above a smooth, flat marble surface.
  - Motion of the test payload is measured using an ultrasonic sensor.

- Candidate isolation techniques are evaluated in terms of transmission ratio for harmonic and impulsive excitations.
  - Passive isolation
    - Utilize existing theory
    - Design for isolation = 99.9975%
  - Active Method
    - Payload floats in enclosure
    - Control system keeps payload centered
Space Structures

Payload Vibration Isolation in Microgravity Environment

Carl H. Gerhold and Richard M. Alexander
Texas A&M University, Mechanical Engineering Department
Contract: NAS9-17972, Johnson Space Center, A.R. Rocha, Loads & Dynamics Branch

Estimated Free Vibration

Estimated Vibration Response

Response Estimated by Analytical Model.
CONCLUSIONS:

- Vibration control demonstrated
  - System has one degree of freedom
  - Passive system can meet impulse criterion
  - Digital controller developed for active system
- Analytical model developed
  - Verified by experiment
  - Will be used to develop control system parameters

SCHEDULE

I. Background
   A. Develop/Refine Isolation Criteria

II. Passive Methods
   A. Select Candidate Techniques
   B. Develop Design Parameters
   C. Fabricate Samples & Evaluate

III. Active Methods
   A. Select Candidate Technique
   B. Develop Design Parameters
   C. Fabricate and Test

IV. Experiment Facility
   A. Fabricate 1 DOF System
   B. Modify for Plane Motion
EXPERIMENTAL OBJECTIVE

CHARACTERIZE THE PERFORMANCE CAPABILITIES OF A GENERIC POINTING MOUNT DESIGNED TO ISOLATE VIBRATION AND AIM INTERCHANGEABLE PAYLOADS OVER LARGE ARTICULATION ANGLES.

THIS EXPERIMENT WILL:

- VERIFY THE ABILITY OF ADVANCED MAGNETIC SUSPENSIONS TO:
  - ELIMINATE THE NEED FOR MECHANICAL GIMBALS
  - OPERATE OVER LARGE ARTICULATION ANGLES
  - IMPLEMENT ADAPTIVE CONTROL LAWS
  - UTILIZE ARTIFICIAL INTELLIGENCE SCHEMES

- ESTABLISH DESIGN/PERFORMANCE DATA BASE FOR THE NEXT GENERATION OF GENERIC POINTING MOUNTS

CURRENT SPACE DEPLOYABLE POINTING TECHNOLOGY

SPERRY/NASA ANNULAR SUSPENSION AND POINTING SYSTEM (ASPS)
TECHNOLOGIES/FEATURES USED BY THE GENERIC POINTING MOUNT:

- UTILIZES ADVANCED MAGNETIC SUSPENSION/BEARING TECHNOLOGY IN LIEU OF MECHANICAL GIMBALS FOR ARTICULATION

- AUTOMATICALLY MEASURES THE MASS, MOMENTS OF INERTIA, RESONANT FREQUENCIES, RESONANT MODE SHAPES, AND VIBRATION DAMPING REQUIREMENTS OF EACH PAYLOAD

- AUTOMATICALLY OPTIMIZES THE MAGNETIC SUSPENSION AND POINTING/TRACKING SERVOSYSTEM CONTROL LAWS TO MATCH EACH PAYLOAD

- OPTIMIZES THE CONTROL LAWS IN REAL TIME FOR SIMULTANEOUS CONVERGENCE OF POSITION, VELOCITY, AND ACCELERATION ERRORS

- TRANSFERS POWER AND DATA ACROSS THE MAGNETIC SUSPENSION GAP WHILE EXPERIENCING LARGE ARTICULATION ANGLES
Robert W. Bosley
Allied/Signal Aerospace Co., Airsearch Los Angeles Division
Contract: NAS1-18685, Langley Research Center, Sharon S. LaFleur

SIX ORDERS OF MAGNITUDE ERROR REDUCTION WITH NO OVERSHOOT/UNDERSHOOT

SIX ORDERS OF MAGNITUDE ERROR REDUCTION WITH NO OVERSHOOT/UNDERSHOOT
EXPERIMENT DESCRIPTION:

- THE SPACE BASED POINTING MOUNT MODULE WILL BE COMPRISED OF:
  - THE MAGNETICALLY SUSPENDED AND CONTROLLED GENERIC POINTING MOUNT
  - A POINTING MIRROR ATTACHED TO AND ARTICULATED BY THE MOUNT
  - THREE OPTICAL AUTOCOLLIMATORS (one articulated)
  - A TELESCOPE WITH STAR PATTERN RECOGNITION CAPABILITIES AND STAR POSITION/POINTING ERROR SENSORS. THIS TELESCOPE WILL BE ALTERNATELY
    - ATTACHED TO AND ARTICULATED BY THE POINTING MOUNT.
    - ATTACHED TO A NON-ARTICULATED SURFACE IN THE MODULE SO AS TO RECEIVE
      OPTICAL SIGNALS/IMAGES REFLECTING OFF THE POINTING MIRROR
  - SIMULATED INSTRUMENTS/DEVICES WITH DIFFERENT MECHANICAL IMPEDANCES
  - AN INERTIAL MEASUREMENT UNIT (IMU) WITHIN THE ARTICULATED POINTING MOUNT
  - AN IMU WITHIN THE NON-ARTICULATED PORTION OF THE MODULE
  - POWER AND DATA LINKS BETWEEN THE MOUNTED TELESCOPE AND THE MODULE
    (across the magnetic suspension gap)
  - DATA LINKS:
    - TO THE SPACECRAFT IMU AND COMPUTERS
    - TO ONE OR MORE GROUND STATIONS
- THE EXPERIMENT WILL BE DIVIDED INTO FIVE SUB-EXPERIMENTS

SUB-EXPERIMENT 1: CHARACTERIZE THE DYNAMIC SYSTEM PERFORMANCE WHEN SHIFTING LOCK FROM ONE AUTOCOLLIMATOR TO ANOTHER

SUB-EXPERIMENT 2: CHARACTERIZE THE ABILITY OF THE SYSTEM TO ADAPT TO CHANGES IN THE MECHANICAL IMPEDANCES OF THE INSTRUMENTS/DEVICES BEING AIMED

SUB-EXPERIMENT 3: CHARACTERIZE THE TRACKING STABILITY WHEN THE TELESCOPE IS ARTICULATED AND LOCKED TO A STAR OR EARTH STATION

SUB-EXPERIMENT 4: CHARACTERIZE THE TRACKING STABILITY WHEN THE MIRROR/TELESCOPE IS LOCKED TO A STAR OR EARTH STATION AND THE UNARTICULATED TELESCOPE IS EXCITED BY EXTERNAL VIBRATIONS

SUB-EXPERIMENT 5: CHARACTERIZE THE TRACKING STABILITY WHEN THE MIRROR IS RELAYING LASER BEAMS GENERATED BY EARTH STATIONS
MASTER SCHEDULE
(3 PHASES)

SUMMARY OF EXPERIMENT FEATURES:

- GENERIC POINTING MOUNT FOR INTERCHANGEABLE PAYLOADS
- SYSTEM AUTOMATICALLY ADAPTS CONTROL LAWS TO EACH PAYLOAD
- POINTING CONTROL IN THREE AXES AROUND A SINGLE PIVOT POINT
- 135° ARTICULATION ANGLES
### OBJECTIVE

THE DEVELOPMENT OF MODELING TECHNIQUES FOR LARGE SPACE STRUCTURES USING ON-ORBIT MEASUREMENTS OF SPACE STATION STRUCTURAL DYNAMICS

### TECHNOLOGY REQUIREMENT

- LARGE SPACE STRUCTURES
  - CANNOT BE INTEGRATED AND TESTED IN 1G
  - REQUIRE ANALYTICAL PREDICTION AND / OR ON-ORBIT MEASUREMENT OF PERFORMANCE

- DYNAMICS: MODELING TO PREDICT PERFORMANCE
- CONTROL: ON-ORBIT CHARACTERIZATION FOR ACTIVE CONTROL
EXPERIMENT DESCRIPTION

0 SPACE STATION FREEDOM
- PRESENTS AN EARLY OPPORTUNITY TO DEVELOP MODELING TECHNOLOGY
- MAGNIFIES THE OPPORTUNITY WITH MULTIPLE ASSEMBLY CONFIGURATIONS

0 FLIGHT EXPERIMENT CONCEPT

PHASE A
- MODAL TESTING OF SELECTED CONFIGURATIONS THRU ASSEMBLY COMPLETE
  - EXCITATION REBOOST TRANSIENTS
  - MEASUREMENTS MODULATED REBOOST
  - MODAL IDENTIFICATION ACCELERATION
  - FREE DECAY REBOOST TRANSIENTS

EXPERIMENT DESCRIPTION (Cont.)

MODAL DENSITY
ASSEMBLY COMPLETE CONFIGURATION

149 MODES / 0 - 4 HZ

<table>
<thead>
<tr>
<th>FREQUENCY, Hz</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
</tr>
<tr>
<td>150</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>MODE NUMBER</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
</tr>
<tr>
<td>150</td>
</tr>
</tbody>
</table>

EXCITATION FUNCTIONS
STARBOARD X RCS JETS

REBOOST TRANSIENTS

MODULATED REBOOST

TIME ←
In-Reach SPACE STRUCTURES
Space Station Structural Characterization Experiment

James W. Johnson and Paul A. Cooper
NASA Langley Research Center

PRIMARY SENSOR LOCATIONS

SCHEDULE

<table>
<thead>
<tr>
<th>CY</th>
<th>88</th>
<th>89</th>
<th>90</th>
<th>91</th>
<th>92</th>
<th>93</th>
<th>94</th>
<th>95</th>
<th>96</th>
<th>97</th>
<th>98</th>
</tr>
</thead>
<tbody>
<tr>
<td>PDR</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDI</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>ASSEMBLY</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

SPACE STATION FREEDOM

SPACE STATION STRUCTURAL CHARACTERIZATION EXPERIMENT

PHASE A STUDY

PHASE B STUDIES

DESIGN, DEVELOPMENT AND INTEGRATION

FLIGHT EXPERIMENTS
## Study Description

1. **Trade Studies will be conducted on the:**
   - Desirable Orbit Type
     - HEO
     - LEO
   - Inflatable Structure
     - Type (e.g. spherical or paraboloid)
     - Materials (e.g. Kapton, Mylar, Teflon, etc.)
     - Response Instrumentation (meteoids, UV, O)
     - Dynamics Instrumentation (accelerometers and/or video for instance)
   - Carrier Vehicle
     - Type:
       - Free Flyer, Non-Retrievable
       - Free Flyer, Retrievable
       - Space Station
     - Telemetry (may not be required for space station measurements)
   - Control
     - Attitude control?
     - On-board Microprocessor Type
     - Inflation Feedback Loop
     - Inflatable Dynamics Induction Type
   - Power
     - Requirements
     - Type

2. **Recommendations will be made for the most cost effective experimental configuration concept**
### STUDY OBJECTIVE

Assess in-space the two most critical issues pertaining to the performance of inflatable structures in space:

* Assess the effects of space environment on the structural integrity and service life:
  - Meteors
  - UV radiation
  - Atomic oxygen

* Demonstrate that inflatable systems can be designed to provide high levels of structural damping.
  - Byproduct: Validation of existing analytical tools that predict structural damping.

### BACKGROUND / TECHNOLOGY NEED

* Inflatable structures in space have been very successful and their advantages have been demonstrated in short missions
  - Small packaged volumes
  - Low weight
  - Less expensive to build and test than competing mechanically erected systems

* For long term space missions, as in the case of antennas and solar concentrators, it is necessary to demonstrate that:
  - Induced damage due to environment (meteors, UV radiation and atomic oxygen at low earth orbits) can be handled by on-board gas supply, and/or other means.
  - Induced dynamics are damped out quickly, so that structural accuracy is maintained.

* This experiment must be conducted in-space, because zero gravity, vacuum, meteors, UV and atomic oxygen are all simultaneously present.
STUDY DESCRIPTION

1. Trade Studies Will Be Conducted on the:

   * Desirable Orbit Type
     Low Earth Orbit (LEO)
     High Earth Orbit (HEO)

   * Inflatable Structure
     Type - (e.g., spherical or paraboloid)
     Materials - (e.g., kapton, mylar, teflon, etc)
     Response Instrumentation (meteoroids, UV, O)
     Dynamics Instrumentation
       (e.g., accelerometers and/or video)

   * Carrier Vehicle
     Type -
     Free Flyer, Nonretrievable
     Free Flyer, Retrievable
     Space Station

     Telemetry -
     May not be required for
     space station measurements

     Control -
     Attitude Control?
     On-board Microprocessor Type
     Inflation Feedback Loop
     Inflatable Dynamics Induction Type

     Power -
     Requirements
     Type

2. Recommendations will be made for the most cost effective
   experimental configuration concept.
Part 1: Executive Summary & Experiment Descriptions

### SPACE STRUCTURES

**Inflatable Solar Concentrator Experiment Definition Program**

Costa Cassapakis and Geoff Williams  
L'Garde, Inc.  
Contract: NAS1-18681, Langley Research Center, Tom Campbell

- **Instrumented Spherical Inflatable**
  - **Video Camera**  
  - **Platform**  
  - **On Board Processor, Electronics, Telemetry & Power System**  
  - **Stressed Inflatable Materials Panel**  
  - **N2 Supply for Inflation, Nozzle Operation and Make Up Gas**

- **Inflatable Solar Concentrator**
  - **Video Camera**  
  - **Platform**  
  - **On Board Processor, Electronics, Telemetry & Power System**  
  - **Stressed Inflatable Materials Panel**  
  - **N2 Supply for Inflation, Nozzle Operation and Make Up Gas**

- **Instrumented Inflatable Antenna**
  - **Video Camera**  
  - **Platform**  
  - **On Board Processor, Electronics, Telemetry & Power System**  
  - **Stressed Inflatable Materials Panel**  
  - **N2 Supply for Inflation, Nozzle Operation and Make Up Gas**
INSTEP'88 Workshop
OAST Technology For the Future
Part 1: Executive Summary & Experiment Descriptions

Out-Reach SPACE STRUCTURES
Inflatable Solar Concentrator Experiment Definition Program

Costa Cassapakis and Geoff Williams
L'Garde, Inc.
Contract: NAS1-18681, Langley Research Center, Tom Campbell

PROJECTED EXPERIMENT SCHEDULE

LEGEND:
- Major Milestone
- Test Duration
- Issue Date 10/24/88

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Preliminary Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2. Detail Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3. Development Tests</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5. Dual Hardware Fab.</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6. Qualification Testing</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7. Flight Hardware Fab.</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8. Flight Test &amp; Analyses</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>9. Management</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
## Experiment objectives

Measure in space effective reaction rates for degradation of materials

- Selected space materials
- In-space analysis
- Inexpensive, small satellite

## Background

- Observations of returned specimens indicate severe degradation
- Future structures will make use of composite materials
- Laboratory sources of 5eV atomic oxygen are difficult to obtain
### SPACE ENVIRONMENTAL EFFECTS

**Atmospheric Effects and Contamination**

**Measurement of Surface Reactions In the Space Environment**

L.R. Megill  
Globesat, Inc.

Contract: NAS1-18684, Langley Research Center / JPL, Lenwood G. Clark / Dr. David A. Brinza

<table>
<thead>
<tr>
<th>Out-Reach</th>
<th>Experiment Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Out-Reach</strong></td>
<td><strong>Space Environmental Effects</strong></td>
</tr>
<tr>
<td><strong>Atmospheric Effects and Contamination</strong></td>
<td></td>
</tr>
<tr>
<td><strong>Measurement of Surface Reactions In the Space Environment</strong></td>
<td></td>
</tr>
<tr>
<td>L.R. Megill</td>
<td>Globesat, Inc.</td>
</tr>
<tr>
<td>Contract: NAS1-18684, Langley Research Center / JPL, Lenwood G. Clark / Dr. David A. Brinza</td>
<td></td>
</tr>
</tbody>
</table>

- **Gravity Gradient/Magnetic Torque**
  - Stabilized satellite

- **Several in-space measurements**
  - to be used

- **Results telemetered to the ground**
## Measurement of Surface Reactions In the Space Environment

L.R. Megill  
Globesat, Inc.  
Contract: NAS1 18684, Langley Research Center / JPL, Lenwood G. Clark / Dr. David A. Brinza

### Measurement Techniques Under Consideration

- Mass Spectrometer
- QCM
- Osmium Detectors
- Surface erosion measurements

**Optical**
- SEM
- Scattering

<table>
<thead>
<tr>
<th>Definition</th>
<th>88</th>
<th>89</th>
<th>90</th>
<th>91</th>
<th>92</th>
<th>93</th>
</tr>
</thead>
<tbody>
<tr>
<td>Satellite</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Fab</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Experiment</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Procurement</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Integration</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Flight</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Analysis</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
SPACE ENVIRONMENTAL EFFECTS
Atmospheric Effects and Contamination

Optical Properties Monitor (OPM) Experiment

Donald R. Wilkes
John M. Cockerham & Associates
Contract: NAS8-37755, Marshall Space Flight Center, Jim Zwiener

EXPERIMENT OBJECTIVE

To study the effects of the space environment, both natural and induced, on optical materials and thermal surfaces.

- Develop a multifunction, reusable flight instrument for in-space optical studies
- Determine the effects and damage mechanisms of the space environment on optical materials and thermal surfaces
- Provide flight testing of critical spacecraft and optical materials
- Validate ground test facilities and techniques

BACKGROUND

- The natural and induced space environment can damage spacecraft materials
- Space environmental effects and damage mechanisms are not well understood
- The space environment cannot be fully simulated
- There have been only limited in-space optical measurements of material properties

TECHNOLOGY NEED

- Longer duration, and more complex missions, such as Space Station, require better materials and better materials performance characterization
- A better understanding of space environmental damage mechanisms will lead to:
  - Better, more stable materials and coatings
  - Better, more accurate ground simulation testing
- Improved materials and better material performance characterization will lead to better, more cost effective, lower weight space systems designs
- A multifunction, reusable flight instrument is needed for in-space optical studies
EXPERIMENT DESCRIPTION

Selected materials will be exposed to the near earth space environment and the effects measured through in-situ and post flight analysis.

- Active sample optical and thermal properties are measured by the in-situ measurement subsystem
  - Spectral total hemispherical reflectance - Integrating Sphere
  - Total integrated scatter - Coblentz Sphere
  - Spectral Transmittance
  - Total emittance/solar absorptance - Calorimetric Method

- Environmental monitors measure the sample exposure environment
  - Solar/earth irradiance - Radiometers
  - Molecular contamination - Temperature controlled quartz crystal microbalance
  - Atomic oxygen

- Passive sample optical and thermal properties, surface degradation, and surface contamination are determined by post-flight analysis.
**Space Environmental Effects**

Atmospheric Effects and Contamination

**Optical Properties Monitor (OPM) Experiment**

Donald R. Willans

John M. Cockerham & Associates

Contract: NAS8-37755, Marshall Space Flight Center, Jim Zwiener

---

**OPM Schedule**

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- Performance & Requirements Definition
- Preliminary Design
- Definition Phase Complete
- Detailed Design
- Critical Design Review
- Procure, Fab & Assemble
- Integrate, Test & Check Out
- Performance Testing
- Flight Qualification Tests
- Payload Integration
- First OPM Mission

---

**OPM Summary**

- Definition phase effort is underway (September 16, 1988)

- Basic flight hardware concept proven on the LDEF Thermal Control Surfaces Experiment (TCSE)

- Total Integrated Scatter (TIS) and transmission measurements are added to the TCSE design

- Environmental monitors for molecular contaminants and atomic oxygen are added to the TCSE design

- The TIS measurement system design will be verified by laboratory breadboard testing

- 1978 TCSE design will be modernized to current technology

- OPM mission opportunities are being researched

- An OPM advisory committee is being formed
Experiment Objective

Develop understanding of the physical processes leading to spacecraft glow phenomena, with emphasis on surface temperature and altitude effects. This development can be used to:

- Characterize optical instrument backgrounds
- Provide guidelines for thermal insulations
- Characterize material selection for flight optics and associated spacecraft
- Affect flight-operation altitude selection for relevant missions

Background/Technology Need

Experimental data from STS missions suggest that cold surfaces result in increased surface catalysis with atmospheric constituents, resulting in brighter glow.

Confirming spectral and intensity data are needed from a temperature monitored surface in ram. Intensities at different altitudes are desired in order to understand the synergistic effect of multiple atmospheric species. Spectral and intensity data from ultraviolet and infrared wavelengths are also required.

Why a space experiment? Glow contamination results from large fluxes (>10^{13} \text{ cm}^{-2}) of fast atmospheric constituents (4-10 \text{ eV}), catalytically reacting on surfaces to form excited-state molecules which emit glow. The combined fluxes and energies are not reproducible in ground facilities.
The experiment hardware will include a 1 x 1 m flat plate with a material sample. The plate will be directed into atmospheric ram direction on orbit. The instrumentation includes a visible imaging spectrometer (400-800 nm), an IR detector (1-3 μm), and a far-ultraviolet imaging spectrometer (110-300 nm). The instrumentation will be mounted on an MPESS structure. An uplink command will activate the experiment, and an onboard recorder will log the data. Operation during four "shadowed" orbit periods is desired, at low altitude. At least two orbits of 175-km perigee are desired (as part of the STS reentry sequence).

Breadboard Tests for Functionality, Response, and Sensitivity

- Breadboard an image detector for the far-ultraviolet imaging spectrometer
  - Gated intensifier, plug coupled to a CCD
  - 110-300-nm response
  - RbTe photocathode
  - 25-mm diameter
  - 388 x 480 CCD array, thermoelectrically cooled to 230 K
  - Digital output

- Breadboard an IR detector
  - Dewar resident, single element
  - 1-5.5 μm response
  - InSb element
  - Joule-Thompson cooled to 77 K
  - High-gain analog output
SPACE ENVIRONMENTAL EFFECTS
Atmospheric Effects and Contamination

Experimental Investigation of Spacecraft Glow

Gary Swenson
Lockheed Missiles & Space Co., Palo Alto Research Laboratory ( teamed with Lockheed Houston)
Contract: NAS9-17969, Johnson Space Center, Jim Visentine - ES5

OUT. REACH SPACE ENVIRONMENTAL EFFECTS
Atmospheric Effects and Contamination

Experimental Investigation of Spacecraft Glow

Gary Swenson
Lockheed Missiles & Space Co., Palo Alto Research Laboratory ( teamed with Lockheed Houston)
Contract: NAS9-17969, Johnson Space Center, Jim Visentine - ES5

OUT-REACH

The experiment may also be flown on the NFFS with the Hitchhiker-N system.

SAMPLE PLATE
IR SPECTROPHOTOMETER
SPECTROMETER
VIS-UV IMAGER
ELECTRONICS

NASA CARRIER

GLOW EXPERIMENT SHOWN ON NFFS CARRIER WITH STANDARD MSL CONFIGURATION

MASTER SCHEDULE

<table>
<thead>
<tr>
<th>YR</th>
<th>88</th>
<th>89</th>
<th>90</th>
<th>91</th>
<th>92</th>
<th>93</th>
<th>94</th>
<th>95</th>
</tr>
</thead>
<tbody>
<tr>
<td>QTR</td>
<td>1 2 3 4</td>
<td>1 2 3 4</td>
<td>1 2 3 4</td>
<td>1 2 3 4</td>
<td>1 2 3 4</td>
<td>1 2 3 4</td>
<td>1 2 3 4</td>
<td></td>
</tr>
</tbody>
</table>

FORMAL REVIEWS
DEFINITION STUDY
SYSTEM DESIGN
FABRICATE AND ASSEMBLY
TESTING
FLIGHT OPERATIONS
DATA ANALYSIS
REFURBISHMENT

POD
CDR
2 SAFETY
SHIP KSC
EXPERIMENT OBJECTIVES

* CONTAMINATION MEASUREMENTS

- Fully characterize the S/C molecular contamination environment
- Total contamination accretion from direct flux and return flux
- Individual species accretion from direct flux and return flux
- Verification of all available mass transfer codes (newly developed and current)
- Velocity/direction of each species
- Chemistry of natural + induced species (gas phase and heterogeneous reactions)

* NATURAL ENVIRONMENT CHARACTERIZATION

- Direct measurement of concentration of species in the natural environment (atomic oxygen, atomic nitrogen, O2, N2, CO, NO, AR, etc.)

BACKGROUND/TECHNOLOGY NEED

- Available data on spacecraft induced environment is very sparse. No systematic effort to measure the contamination environment as a function of mission parameters has been made to date.

- Existing contamination models are not flight verified. The meager amount of flight data seems to indicate gross inaccuracies in some areas (particularly for the return flux component of the molecular environment).

- Flight experiments are urgently needed to gather data in an organized manner.

- Reliable predictions will allow great economical advantage in the sizing of the contamination control activities for a large number of NASA programs.
**SPACE ENVIRONMENTAL EFFECTS**

Atmospheric Effects and Contamination

*Return Flux Experiment (REFLEX)*

J.J. Triolet and R. McIntosh
Goddard Space Flight Center

**EXPERIMENT DESCRIPTION**

- **MAJOR EXPERIMENT COMPONENTS:**
  1) SENSOR: MASS SPECTROMETER
  2) MOLECULAR SOURCE: NOBLE GAS
  3) CARRIER: TBD

- **COMPONENT FUNCTION:**
  1) SENSOR: DETECTION OF ALL MOLECULAR SPECIES OF INTEREST IN BOTH NATURAL AND SPACECRAFT INDUCED ENVIRONMENTS. CHEMICAL NATURE AND VELOCITY ARE OBTAINED AS A FUNCTION OF TIME.
  2) MOLECULAR SOURCE: PROVIDES A KNOWN INPUT TO THE S/C ENVIRONMENT FOR RETURN FLUX MEASUREMENTS.
  3) CARRIER: ALLOWS POSITIONING OF THE EXPERIMENT PACKAGE TO LOW/ZERO BACKGROUND LOCATIONS FOR EXTREMELY ACCURATE MEASUREMENTS OF LOW INTENSITY PHENOMENA (RETURN FLUX).
SPACE ENVIRONMENTAL EFFECTS
Atmospheric Effects and Contamination
_Return Flux Experiment (REFlex)"

J.J. Trilo and R. McIntosh
Goddard Space Flight Center

SCHEDULE

- COMPLETE PHASE A: NOV 88
- PHASE B START: JAN 89
- PHASE C/D START: JAN 90
<table>
<thead>
<tr>
<th>In-Reach</th>
<th>SPACE ENVIRONMENTAL EFFECTS</th>
<th>In-Reach</th>
</tr>
</thead>
<tbody>
<tr>
<td>Meteoroids and Debris</td>
<td><strong>Debris Collision Warning Sensors</strong></td>
<td></td>
</tr>
<tr>
<td>Faith Villas and David Thompson</td>
<td>Johnson Space Center</td>
<td>Solar System Exploration Division</td>
</tr>
</tbody>
</table>

**EXPERIMENT OBJECTIVE:**

CHARACTERIZE STATISTICALLY THE LEO DEBRIS ENVIRONMENT, CONCENTRATING ON OBSERVING DEBRIS OF SIZES DOWN TO 1 mm DIAMETER; OBTAINING BOTH VISIBLE PHOTOMETRY (~0.56μm) AND THERMAL RADIOMETRY (5μm). TEST DETECTOR EFFECTIVENESS FOR SPACECRAFT DEBRIS COLLISION WARNING SYSTEM.

DATA ACQUIRED WILL BE USED TO:

- MODEL EFFECTS (NOISE SOURCES, FALSE SIGNALS) WHICH SMALL DEBRIS PIECES COULD HAVE ON DEBRIS COLLISION WARNING SYSTEM OPERATION.

- OPTIMIZE DETECTOR SELECTION FOR DCW BY UNDERSTANDING ALBEDO VALUES AND THERMAL HEATING PROPERTIES OF LEO DEBRIS.

- CALCULATE DEBRIS FRAGMENT SIZES WITH ACCURATE ALBEDO MEASUREMENT.

**BACKGROUND/TECHNOLOGY NEED**

- LEO DEBRIS POPULATION INCREASING, PRODUCING INCREASED HAZARD TO SPACECRAFT.

- NEW CONCEPTS FOR PROTECTING SPACECRAFT MUST BE DEVELOPED.
  - ON-BOARD DETECTION WILL PROBABLY PLAY A KEY ROLE.
  - REQUIRES SCIENTIFIC TECHNIQUE AND TECHNOLOGY DEVELOPMENT.

- DATA AMOUNT AND QUALITY ARE WORST IN SIZE (1mm-10cm), SPECTRAL RANGES (0.56μm, 5μm) WHERE INFORMATION IS MOST CRITICAL TO DEBRIS COLLISION WARNING SYSTEM DESIGN.
SPACE ENVIRONMENTAL EFFECTS
Meteoroids and Debris

Debris Collision Warning Sensors
Faith Vilas and David Thompson
Johnson Space Center
Solar System Exploration Division

EXPERIMENT DESCRIPTION

THE APPARATUS WILL CONSIST OF ONE 60-IN. F/1.2 TELESCOPE HAVING ALL-REFLECTING OPTICS WITH A 3.7° FIELD OF VIEW. A TEKTRONIX 2048x2048 PIXEL CCD RINGED BY SINGLE-ELEMENT 5-μm DETECTORS, OPERATING AT A READOUT RATE OF ONE FRAME EVERY 1/10 SEC, IS LOCATED IN THE FOCAL PLANE. VISIBLE PHOTOMETRY, THERMAL RADIOMETRY, AND VELOCITY DATA CAN BE ACQUIRED ON DEBRIS PIECES PASSING THROUGH THE TELESCOPE'S FOV. EXPERIMENT MODES INCLUDE A BLIND SEARCH FOR DEBRIS DOWN TO 1mm DIAMETER, OBSERVATIONS OF KNOWN DEBRIS PIECES TRACKED BY USSPACECOM.
### Preliminary Schedule for Proposed Flight Experiment

<table>
<thead>
<tr>
<th>Activity</th>
<th>FY89</th>
<th>FY90</th>
<th>FY91</th>
<th>FY92</th>
<th>FY93</th>
<th>FY94</th>
</tr>
</thead>
<tbody>
<tr>
<td>Design Study</td>
<td></td>
<td></td>
<td>▼</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PRR</td>
<td></td>
<td></td>
<td></td>
<td>▼</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Initial Design</td>
<td></td>
<td></td>
<td></td>
<td>▼</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PDR</td>
<td></td>
<td>▼</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Final Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>▼</td>
<td></td>
</tr>
<tr>
<td>CDR</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>▼</td>
</tr>
<tr>
<td>Fabrication/Verification</td>
<td>▼</td>
<td>▼</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>AR/IRR</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Instrument to KSC</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>▼</td>
</tr>
<tr>
<td>Physical Integration</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>▼</td>
<td></td>
</tr>
<tr>
<td>Flight</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>▼</td>
</tr>
</tbody>
</table>
Experiment Objective:

Expose thin-foil, lacquer-coated, grazing incidence X-ray reflectors to low earth orbit environment in order to:

1. Measure the degradation of X-ray reflection efficiency of candidate mirror surfaces due to interaction with atomic oxygen
2. Determine the effectiveness of protective measures

Background:

- Thin-foil, conical imaging X-ray mirrors represent new technology X-ray astronomy instrumentation
- Mirror technology developed entirely within NASA (GSFC)
- Grazing incidence reflecting surfaces consist of lacquer-coated, high reflectivity aluminum foil, with evaporated 500 Angstrom gold layer
- Initial implementation on Broad Band X-Ray Telescope (STS-35, March 1990)
- Will be used or being studied for use on several long term X-ray astronomy missions: ASTRO-D, 1993 (Japan/USA) Spectrum-X, 1994 (USSR/Denmark/USA) Spektrosat, 1994 (W. Germany/USA)
- Lacquer coating technology has direct applications for other kinds of X-ray mirrors and for far and extreme ultraviolet optics
- Unclear how previous contamination studies relate to grazing incidence or lacquer coated surfaces, or to X-ray reflectivity
**Experiment Description**

Baseline approach: low cost, minimal STS interface

Strategy: use GAS carrier, develop hardware quickly to allow possibility of manifesting with larger experiments with similar mission requirements (e.g., FOIM-3, IFCE)

Key Components:

- Conical mirror quadrant: holds reflector samples at proper incidence angles
- Sample tray: holds thin foil mirror samples at normal incidence
- Shutter mechanism: shuts slowly over duration of experiment to allow determination of degradation vs. exposure time
- Carrier: GAS can with Motorized Door Assembly
Thin Foil Mirror Contamination Experiment

GAS Experiment Mounting Plate

Conical mirror housing

Shutter door mechanism

Battery box

GAS can (less lid)

Space for additional instrumentation

Top View

Side View

Scale

1 foot

Thin-foil conical mirror quadrant to be used for holding samples for contamination experiment
<table>
<thead>
<tr>
<th>Milestones</th>
<th>Dates</th>
</tr>
</thead>
<tbody>
<tr>
<td>In-Reach proposal submitted</td>
<td>July, 1986</td>
</tr>
<tr>
<td>In-Reach proposal accepted; begin Phase A study</td>
<td>August, 1987</td>
</tr>
<tr>
<td>Finish Phase B definition phase</td>
<td>November, 1988</td>
</tr>
<tr>
<td>Begin Phase C/D development (pending funding)</td>
<td>January, 1989</td>
</tr>
<tr>
<td>Submit GAS reservation</td>
<td>January, 1989</td>
</tr>
<tr>
<td>Deliver complete instrument to GAS program</td>
<td>June, 1990</td>
</tr>
</tbody>
</table>
NaS BATTERY TECHNOLOGY BENEFITS -

$\ 1.1-1.7 \text{ MS/KW SAVING IN LAUNCH FOR GEO MISSION OVER NIH2 BATTERY}$

$\ 0.2-0.4 \text{ MS/KW SAVING IN LAUNCH FOR LEO MISSION OVER NIH2 BATTERY}$

EXPERIMENT OBJECTIVE

TO DESIGN AN EXPERIMENT THAT WILL DEMONSTRATE OPERATION OF SODIUM-SULFUR BATTERY/CARDS UNDER SPACE ENVIRONMENTS WITH PARTICULAR EMPHASIS ON EVALUATION ON MICROGRAVITY EFFECTS.

- TO EVALUATE CHARGE AND DISCHARGE CHARACTERISTICS AS AFFECTED BY FLUID REACTANT DISTRIBUTIONS
- TO DETERMINE REACTANT DISTRIBUTIONS UNDER MICROGRAVITY CONDITION
- TO UNDERSTAND CURRENT & THERMAL DISTRIBUTION WITHIN CELLS
- TO EVALUATE FREEZE THAW EFFECTS
- TO EVALUATE COLD VS WARM LAUNCH
- TO EVALUATE MULTICELL OPERATION

BACKGROUND/TECHNOLOGY
EXPERIMENTAL APPROACH

- Select only those tests that are critical and expected to differ under microgravity condition.
- "Spinners" can be duplicated on Earth.
- Correlate cell characteristics before/during/following space flight to eliminate extraneous variables.
- Incorporate additional control cells.

EXPERIMENT DESCRIPTION

I. CELL CHARACTERIZATION TEST
- Rated 40 Ah baseline cells
- 8 cells for space; 4 cells for ground control
- Cold launch
- Two operating temperatures: 275-300; 350-375°C
- Charge rates: C/5, C/2, 3/4C, C plus taper
- Discharge rates C/2, C; 1.5C, 2C plus pulses to ~4C
- Cell impedance & efficiency

II. REACTANT DISTRIBUTION DESTRUCTIVE PHYSICAL ANALYSIS
- 8 cells reused after No. I

III. REACTANT DISTRIBUTION TEST
- Special instrumented 40 Ah cells
- 2 cells in space, 1 cell on ground
- To determine current density vs. axial position during discharge/charge and open circuit

IV. FREEZE/THAW TEST
- Rated 40 Ah baseline cells
- 4 cells for space; 2 cells on ground

V. WARM LAUNCH TEST
- Rated 40 Ah baseline cells
- 4 cells for space
- 200°C prelaunch/launch

VI. CELL CYCLE TEST
- Multi-cell operation
- Early-life LEO characteristics
OUT-REACH
POWER SYSTEMS AND THERMAL MANAGEMENT
Conventional Power Systems
Sodium-Sulfur Battery
Becky Chang
Ford Aerospace Corporation, Space Systems Division
Contract: NAS3-25355, Lewis Research Center, H.F. Leibeck

SUMMARY

- NA-S Battery Technology offers significant payoff for space applications, but operation in space environment is unknown.
- Further enhancement of NA-S excellent performance and cycle life could occur due to more uniform condition within cell due to microgravity conditions.
- Some hypotheses predict performance limitations with impact on cell life in low-gravity environments.
- Flight experiments have been selected to document and correlate critical cell characteristics under space environments with known response on Earth.
- Resulting data base will minimize costs of subsequent larger-scale application-specific experiments.
- Cycle life efforts can not be addressed in simple STS flight would require extended orbit experiment.
Out-Reach POWER SYSTEMS AND THERMAL MANAGEMENT

Conventional Power Systems

Unitized Regenerative SPE® Fuel Cell

Timothy A. Nalette
United Technologies Corporation, Hamilton Standard Division
Contract: NAS9-18001, Lewis Research Center, Rick Baldwin

<table>
<thead>
<tr>
<th>Experiment Objective:</th>
</tr>
</thead>
<tbody>
<tr>
<td>• Evaluate zero gravity operation of a passive Unitized Regenerative SPE Fuel Cell (URFC) electrical energy storage system</td>
</tr>
<tr>
<td>- Cell module</td>
</tr>
<tr>
<td>• Reversible SPE Fuel Cell/electrolyzer operation</td>
</tr>
<tr>
<td>• Passive phase separation</td>
</tr>
<tr>
<td>• Static vapor feed</td>
</tr>
<tr>
<td>- System</td>
</tr>
<tr>
<td>• Passive fluid management</td>
</tr>
<tr>
<td>• Passive thermal control</td>
</tr>
</tbody>
</table>

Background:

• Existing spacecraft energy storage and fluid management systems are heavy and/or complex

• SPE fuel cells and SPE electrolyzers are mature technologies

• Unitized regenerative fuel cells offer potential reductions in system complexity, weight, and volume

Technology need:

• Reliability is enhanced through the use of passive fluid and thermal management technologies

• Applications include electrical energy storage for Space Station, satellites, rechargeable rover vehicles, peak power requirements, and any orbiting system requiring electrical energy storage
Out-Reach

POWER SYSTEMS AND THERMAL MANAGEMENT
Conventional Power Systems

Unitized Regenerative SPE® Fuel Cell

Timothy A. Nalette
United Technologies Corporation, Hamilton Standard Division
Contract: NAS9-18001, Lewis Research Center, Rick Baldwin

Packaging Concept

H₂ storage

Relief valve

Pressure transducers

Solenoid valve

Servo pressure regulators

O₂ sensor

Manifold plate

O₂ storage

URFC assembly

H₂O₂ separator and storage

Out-Reach

<table>
<thead>
<tr>
<th>Months from award</th>
<th>1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36</th>
</tr>
</thead>
<tbody>
<tr>
<td>Finalize concept</td>
<td>PDR</td>
</tr>
<tr>
<td>System design</td>
<td>CDR</td>
</tr>
<tr>
<td>Fabrication/assembly</td>
<td></td>
</tr>
<tr>
<td>Test program</td>
<td></td>
</tr>
<tr>
<td>Refurbish &amp; ship</td>
<td></td>
</tr>
<tr>
<td>Mission support</td>
<td></td>
</tr>
<tr>
<td>Safety review</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Phase 0  Phase 1  Phase 2  Phase 3</td>
</tr>
</tbody>
</table>

As required
Experiment Description:

- URFC system will demonstrate a simple passive means of electrical energy storage for space applications employing passive fluid and thermal management technologies.

- System parameters such as temperatures, pressures, voltage, and current will be measured for purposes of control and analysis.

- Packaging concept depicts the "Get Away Special" carrier option but is easily adapted to other options.

- Experiment will be self-contained.

- Component selection and safety consideration based on mature flight designs.

Simplified URFC system schematic:

- \( H_2O \) storage
- \( O_2 \)
- \( H_2 \)
- Power/load interface
- Product \( H_2O \)
- \( O_2 \)
- Membrane & electrode assembly
- \( H_2 \)
- Feed \( H_2O \)
### OBJECTIVE
EVALUATION OF PHASE CHANGE THERMAL ENERGY STORAGE (TES) SYSTEM AND MATERIALS IN MICROGRAVITY.

### ISSUES

#### PROGRAMMATIC
- TES CRITICAL TO EFFICIENT OPERATION OF THE RECEIVER, SYSTEM.
- FLIGHT TESTS ARE REQUIRED TO ASSESS VOID BEHAVIOR OF ADVANCED TES MATERIALS UNDERGOING REPEATING PHASE CHANGE IN MICROGRAVITY.
- COMPREHENSIVE APPROACH REQUIRES ANALYTICAL UNDERSTANDING AND EXPERIMENTAL VERIFICATION — NEEDED FOR ADVANCED HEAT RECEIVER DESIGN PROCESS.

#### TECHNICAL
- VOID SHAPE AND LOCATION
- EFFECT OF VOID ON HEAT TRANSFER MECHANISMS
- COMPARISON BETWEEN 1-g AND MICROGRAVITY PERFORMANCE
- EFFECT OF STORAGE MATERIAL THERMAL/PHYSICAL PROPERTIES ON SYSTEM PERFORMANCE
- LACK OF A VALIDATED COMPUTER MODEL TO PREDICT PERFORMANCE TES SYSTEMS IN MICROGRAVITY

### APPROACH

#### STSE DEFINITION
- DEFINE SPECIFIC EXPERIMENT OBJECTIVES AND REQUIREMENTS
- DEVELOP PRELIMINARY DESIGN OF EXPERIMENT TO ACCOMMODATE MULTIPLE TES CONCEPTS
- CONDUCT TRADE STUDIES, ANALYSES, AND GROUND TESTS
- PREPARE PROGRAM PLAN, SCHEDULE, AND COST

#### TEST
- DEVELOP AN ANALYTICAL AND COMPUTATIONAL BASIS TO PREDICT TRANSIENT BEHAVIOR OF TES MATERIALS, PARTICULARLY VOID SHAPE AND LOCATION, UNDER MICROGRAVITY
- CONDUCT MICROGRAVITY EXPERIMENTS TO ESTABLISH DATA BANK OF TES MATERIALS UNDER 1-g AND MICROGRAVITY
- VERIFY CAPABILITY OF DEVELOPED COMPUTER CODE TO PREDICT VOID LOCATION AND THERMAL HISTORY OF TES SYSTEM UNDERGOING PHASE CHANGE IN MICROGRAVITY
**TEST EXPERIMENT**

- "GAS" CAN EXPERIMENTAL PACKAGE
- FOUR EXPERIMENTS:
  - UF 1121 K
  - CaF50 MgF 1250 K
  - GERMANIUM 1210 K
  - NISI 1285 K
- SUN/SHADE PERIODS OF 60/34 MINUTES PER CYCLE; 5 CYCLES
- RESULTS:
  - TEMPERATURE MEASUREMENTS
  - POST-TEST EXAMINATION OF VOID SHAPE, LOCATION
  - COMPARISON WITH ANALYTICAL PREDICTION

**TES EXPERIMENT NO. 1**

---

**"TEST" FLIGHT EXPERIMENT NO. 1**

<table>
<thead>
<tr>
<th>MILESTONES</th>
<th>CY</th>
</tr>
</thead>
<tbody>
<tr>
<td>IN-REACH APPROVAL</td>
<td></td>
</tr>
<tr>
<td>INITIATE DEFINITION STUDY</td>
<td></td>
</tr>
<tr>
<td>SUGGESTED REVIEWS</td>
<td></td>
</tr>
<tr>
<td>1-1 DEFINITION STUDY</td>
<td></td>
</tr>
<tr>
<td>2-1 DESIGN &amp; ANALYSES</td>
<td></td>
</tr>
<tr>
<td>3-1 COMPONENT FABRICATION &amp; TESTING</td>
<td></td>
</tr>
<tr>
<td>4-1 SYSTEM TEST - FLIGHT QUALIFICATION</td>
<td></td>
</tr>
<tr>
<td>5-1 FLIGHT HARDWARE</td>
<td></td>
</tr>
<tr>
<td>6-1 GROUND SUPPORT EQUIPMENT</td>
<td></td>
</tr>
<tr>
<td>7-1 DOCUMENTATION</td>
<td></td>
</tr>
<tr>
<td>8-1 FIRST LAUNCH OPPORTUNITY</td>
<td></td>
</tr>
<tr>
<td>9-1 POST LAUNCH EVALUATION</td>
<td></td>
</tr>
<tr>
<td>NOTES:</td>
<td></td>
</tr>
<tr>
<td>TCR - TECHNOLOGY CONCEPT REVIEW</td>
<td></td>
</tr>
<tr>
<td>PRR - PRELIMINARY REQUIREMENTS REVIEW</td>
<td></td>
</tr>
<tr>
<td>PDR - PRELIMINARY DESIGN REVIEW</td>
<td></td>
</tr>
<tr>
<td>CDR - CRITICAL DESIGN REVIEW</td>
<td></td>
</tr>
<tr>
<td>PSR - PRE-shipment REVIEW</td>
<td></td>
</tr>
<tr>
<td>FRR - FLIGHT READINESS REVIEW</td>
<td></td>
</tr>
</tbody>
</table>

**NOTES:**
- C - CONCEPTUAL DESIGN
- P - PRELIMINARY DESIGN
- F - FINAL DESIGN
- AB - AS BUILT DRAWINGS
In-Reach

POWER SYSTEMS AND THERMAL MANAGEMENT
Dynamic and Nuclear Power Systems


David Namkoong, Jerri Ling, Steve Johnson, Barbara Helzer, Tom Foster
Lewis Research Center (Boeing, Contract NAS3-25364)

STSE EXPERIMENT

DESCRIPTION

• COMPATIBLE WITH HITCHHIKER
• DESIGNED FOR MODULARITY
• MULTIPLE CONCEPTS TESTED SIMULTANEOUSLY
• TEMPERATURE DISTRIBUTION AND HEAT FLUX MEASURED

OBJECTIVES

• VERIFY THERMAL PERFORMANCE IN MICROGRAVITY
• VERIFY NONDESTRUCTIVE METHODS OF DETERMINING VOID DISTRIBUTION
• COMPARE VOID DISTRIBUTION AND VOID MANAGEMENT FOR 1g AND MICROGRAVITY ENVIRONMENTS
• VALIDATE PERFORMANCE PREDICTION METHODS
EXPERIMENT OBJECTIVE

DEVELOP IN-DEPTH UNDERSTANDING OF THE BEHAVIOR OF HEAT PIPES IN SPACE. BOTH CONSTANT CONDUCTANCE HEAT PIPES WITH AXIAL GROOVES AND VARIABLE CONDUCTANCE HEAT PIPES WITH WICKS WILL BE INVESTIGATED. THIS UNDERSTANDING WILL BE APPLIED TO THE DEVELOPMENT OF:

- IMPROVED PERFORMANCE OF HEAT PIPES SUBJECTED TO VARIOUS ACCELERATIONS IN SPACE.
- MORE EFFICIENT AND RELIABLE SPACECRAFT THERMAL MANAGEMENT SYSTEMS.
- LIGHTER WEIGHT SPACECRAFT THERMAL SYSTEMS.

BACKGROUND/TECHNOLOGY NEED

A PROBLEM THAT OFTEN ARISES IS HOW TO USE HEAT PIPE GROUND TEST DATA TO MAKE MICRO-GRAVITY PERFORMANCE PREDICTIONS. DURING GROUND TESTING, GRAVITY DOMINATES THE CAPILLARY FORCES AND BECOMES A LIMITING FACTOR. MOREOVER, BOTH THERMAL PERFORMANCE AND VEHICLE STABILIZATION ARE AFFECTED BY SPACECRAFT ACCELERATIONS CAUSED BY:

- MOTION IN ORBIT
- CHANGING ORBITS
- THREAT AVOIDANCE
**Investigation of Microgravity Effects on Heat Pipe Thermal Performance and Working Fluid Behavior**

George L. Retschman  
Hughes Aircraft Company, Electron Dynamics Division  
Contract: NAS5-30359, Goddard Space Flight Center, Roy McIntosh

**EXPERIMENT DESCRIPTION**

The apparatus will provide the ability to spin 4 heat pipes, mounted in a hoop assembly, up to several hundred RPM, and to record the nutation acceleration using an infrared telemetry system. The nutation divergence flight test measures the exponential time constant for nutation divergence of a spinning model with circumferential heat pipes.

The apparatus will provide the ability to spin 4 heat pipes, mounted in a radial configuration, up to 100 RPM to force the working fluid to one of the heat pipe. Next, the assembly will be brought to rest, and the evaporator portion of each heat pipe will be heated using battery powered heaters. Repriming rates, effect of excess liquid and fluid distribution will be evaluated using temperature sensitive liquid crystals.
## POWER SYSTEMS AND THERMAL MANAGEMENT

**Thermal Management**

*Investigation of Microgravity Effects on Heat Pipe Thermal Performance and Working Fluid Behavior*

**George L. Fleischman**
Hughes Aircraft Company, Electron Dynamics Division
Contract: NAS5-30359, Goddard Space Flight Center, Roy McIntosh

### Experiment Descriptions

<table>
<thead>
<tr>
<th>In-Reach</th>
<th>Experiment Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>GROOVED CONSTANT CONDUCTANCE HEAT PIPE</strong></td>
<td></td>
</tr>
<tr>
<td><strong>VARIABLE CONDUCTANCE HEAT PIPE WITH CENTRAL CORE WICK</strong></td>
<td></td>
</tr>
</tbody>
</table>
INSTEP88 Workshop
OAST Technology For the Future
Part 1: Executive Summary & Experiment Descriptions

Experiment Descriptions

In-Reach

POWER SYSTEMS AND THERMAL MANAGEMENT

Thermal Management

Investigation of Microgravity Effects on Heat Pipe Thermal Performance and Working Fluid Behavior

George L. Reischman
Hughes Aircraft Company, Electron Dynamics Division
Contract: NAS5-30359, Goddard Space Flight Center, Roy McIntosh

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>PHASE B</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.0 PROGRAM MANAGEMENT</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.0 PRELIMINARY REQUIREMENTS</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3.0 HARDWARE EVALUATION</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4.0 CONCEPTUAL DESIGN</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5.0 PROJECT DEFINITION</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6.0 PROJECT CONTROL</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7.0 KEY DOCUMENTATION</td>
<td>FINAL REPORT</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>SAFETY REPORT</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>INTERIM REVIEW</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>FINAL REVIEW</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

PHASE C/D

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1.0 DESIGN AND FABRICATE</td>
<td>CONSTANT COND. HEAT PIPES</td>
<td>VARIABLE COND. HEAT PIPES</td>
<td>TEST FIXTURES</td>
</tr>
<tr>
<td>2.0 GROUND TESTING</td>
<td>PERFORMANCE TEST</td>
<td>WICKING TEST</td>
<td>MUTATION TEST</td>
</tr>
<tr>
<td>3.0 FLIGHT EXPERIMENT SUPPORT</td>
<td>DEVELOP FLIGHT TEST PROCEDURE</td>
<td>SUPPORT FLIGHT OPERATIONS</td>
<td>DATA ANALYSIS AND CORRELATION</td>
</tr>
<tr>
<td>4.0 KEY DOCUMENTATION</td>
<td>INTERIM REPORT</td>
<td>FINAL REPORT</td>
<td></td>
</tr>
</tbody>
</table>

---

134
EXPERIMENT OBJECTIVE

Characterize the microgravity performance of a High-Efficiency Thermal Interface (HETI) which thermally couples a two-phase fluid loop to a heat pipe radiator.

- For high-power spacecraft which must reject 10 to 100 kW of waste heat, two-phase fluid loops will be required to collect and transport heat, and large deployed radiators will be needed to reject the waste heat to space.
- High efficiency (low $\Delta T$) interface required between fluid loop and radiator to minimize radiator size and weight.
- Vapor from two-phase loop condenses on Gregorig-grooved exterior of heat pipe. Gregorig grooves use capillary forces to drain liquid from crests of grooves.
- Fibrous wick structure transfers liquid from Gregorig groove troughs to liquid return line.
- Quantities of Interest:
  a) Condensation $h$ on Gregorig grooves (predicted value = 50 kW/m²·K)
  b) Evaporation $h$ in heat pipe
  c) Condensation $h$ in heat pipe
### BACKGROUND

- TRW developed the High Efficiency Thermal Interface (HETI) under the Air Force Wright Aeronautical Laboratory-sponsored High Power Spacecraft Thermal Management Study (Contract No. F33615-84-C-2414).

- Prior to development of HETI, no thermal bus-to-radiator heat exchangers suitable to high-power missions (excluding Space Station) were available.

- Ground testing of a single heat pipe version of the HETI resulted in heat transfer coefficients of the order of 10 kW/m²-K. Satisfactory ground testing is difficult since capillary forces and gravitational body forces are of the same order of magnitude.

- Microgravity testing is required to determine:
  - heat transfer coefficients;
  - startup behavior; and
  - response to suddenly increased or decreased heat loads.

### EXPERIMENT DESCRIPTION

- Experiment will be configured for Get Away Special or Hitchhiker-G carrier.

- Key components will include:
  - capillary pumped loop (CPL) including evaporator pump, liquid and vapor transport lines, accumulator (reservoir), and subcooler;
  - two slab wick heat pipes
  - HETI which accommodates two heat pipes
  - radiator panel
  - battery and power control electronics; and
  - data acquisition electronics package.

- Heat pipes and CPL will use ammonia as the working fluid.

- Experiment will be heat sink limited. Increase of radiator mass will alleviate this problem.

- Experiment will be instrumented so that condensation and evaporation heat transfer coefficients in HETI and heat pipes may be calculated.

- Radiator panel must accommodate two heat pipes and liquid subcooler.

- Experiment will be designed to permit preliminary ground testing (heat pipes in reflux mode, evaporator pump of CPL below HETI, gravity-aided drainage of ammonia from Gregorig grooves).
Out-Reach

POWER SYSTEMS AND THERMAL MANAGEMENT

Thermal Management

A High-Efficiency Thermal Interface Between a Two-Phase Fluid Loop and a Heat Pipe Radiator

John A. Pohner

TRW, Space and Technology Group
Contract: NAS5-30375, Goddard Space Flight Center, Roy McIntosh

EXPERIMENT DESIGN

SCHEDULE - EXPERIMENT DEFINITION PHASE

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>N</td>
<td>D</td>
<td>J</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

ANALYSIS AND PRELIMINARY DESIGN
IN-SPACE IMPLEMENTATION PLAN
DEVELOPMENT PHASE COST ESTIMATE
QUARTERLY STATUS REPORTS
ORAL REVIEW
DRAFT FINAL REPORT
NEW TECHNOLOGY REPORT
**POWER SYSTEMS AND THERMAL MANAGEMENT**

**Out-Reach**

**Thermal Management**

*A High-Efficiency Thermal Interface Between a Two-Phase Fluid Loop and a Heat Pipe Radiator*

John A. Pohner

TRW, Space and Technology Group

Contract: NAS5-30375, Goddard Space Flight Center, Roy McIntosh

**SCHEDULE - EXPERIMENT DEVELOPMENT PHASE**

<table>
<thead>
<tr>
<th></th>
<th>1990</th>
<th>1991</th>
</tr>
</thead>
</table>

PDR - Preliminary Design Review
LSA - Launch Services Agreement
FSDP - Final Safety Data Package
FR - Final Report

CDR - Critical Design Review
PSDP - Preliminary Safety Data Package
QR - Quarterly Report
EXPERIMENTAL OBJECTIVE

Develop an improved understanding of the dynamics of a Moving Belt Radiator (MBR) during deployment and operation. In a zero gravity environment the primary forces on the belt will be those due to rotational motion (centrifugal forces) and spacecraft accelerations.

This understanding is needed to:

- Verify analytical methods developed to model the dynamics of flexible moving belt structures.
- Design MBR systems (belt structures, deployment, operation, and control)
BACKGROUND/TECHNOLOGY NEED

- Computerized dynamic models have been developed to describe shape of MBR as influenced by rotational speeds, acceleration fields, and belt structure.

- Ground based testing subject to gravity are not very useful since gravity forces will dominate the centrifugal forces which define belt dynamics in a space environment.

- Ground based zero-G experiments (drop towers, KC135 test plane) provide too short a test period for extensive testing.

- Lack of an experimentally verified dynamic model adds uncertainty to the design of this class of radiator - possibly resulting in overly conservative design criteria.

EXPERIMENTAL DESCRIPTION

- Experimental apparatus is a small scale moving belt structure 2-4 feet in diameter. Means are provided to:
  - vary belt rotational speed
  - subject belt to short term accelerations
  - vary sealing forces in interface heat exchanger structure

- Belt motion visualization (photographic) and measurements of forces on the IHX due to a belt motion, sealing pressure, and imposed acceleration will allow refinement of analytical models.
Moving Belt Radiator Dynamics
W. Peter Teagan
Arthur D. Little, Inc.
Contract: NAS3-25356, Lewis Research Center, Alan White

FIGURE 2 MBR SHAPE DURING DEPLOYMENT PROCESS
### Moving Belt Radiator Dynamics

**W. Peter Teagan**  
Arthur D. Little, Inc.  
Contract: NAS3-25356, Lewis Research Center, Alan White

<table>
<thead>
<tr>
<th>FIGURE 3</th>
<th>TEST APPARATUS DURING OPERATION (no perturbation)</th>
</tr>
</thead>
<tbody>
<tr>
<td>FIGURE 4</td>
<td>EXPERIMENTAL APPARATUS DURING LINEAR PERTURBATION</td>
</tr>
<tr>
<td>Out-Reach</td>
<td>POWER SYSTEMS AND THERMAL MANAGEMENT</td>
</tr>
<tr>
<td>-----------</td>
<td>-------------------------------------</td>
</tr>
<tr>
<td>Thermal Management</td>
<td>Moving Belt Radiator Dynamics</td>
</tr>
<tr>
<td>Arthur D. Little, Inc.</td>
<td></td>
</tr>
</tbody>
</table>

**PROJECT IS IN EXPERIMENTAL DEFINITION PHASE**

<table>
<thead>
<tr>
<th>Year</th>
<th>1988</th>
<th>1989</th>
</tr>
</thead>
<tbody>
<tr>
<td>6 7 8 9 10 11 12</td>
<td>1 2 3 4 5 6 7 8 9 10 11 12</td>
<td></td>
</tr>
<tr>
<td>1. Objectives</td>
<td>![ ]</td>
<td>![ ]</td>
</tr>
<tr>
<td>Requirements</td>
<td>![ ]</td>
<td>![ ]</td>
</tr>
<tr>
<td>1.1 Technical</td>
<td>![ ]</td>
<td>![ ]</td>
</tr>
<tr>
<td>Requirements</td>
<td>![ ]</td>
<td>![ ]</td>
</tr>
<tr>
<td>1.2 Experimental Test</td>
<td>![ ]</td>
<td>![ ]</td>
</tr>
<tr>
<td>Requirements</td>
<td>![ ]</td>
<td>![ ]</td>
</tr>
<tr>
<td>2. Conceptual Designs</td>
<td>![ ]</td>
<td>![ ]</td>
</tr>
<tr>
<td>3. Implementation Plan</td>
<td>![ ]</td>
<td>![ ]</td>
</tr>
</tbody>
</table>
Background

• Power levels for future space applications are increasing

• The heat rejection system can represent the dominant weight penalty of future space platforms

• Studies have shown that the Liquid Droplet Radiator (LDR) is significantly lighter than conventional radiators

• Contracts sponsored by NASA LeRC and AFAL have demonstrated LDR generator and collector operation

Need

• Test subscale LDR system which will provide end-to-end system verification of the LDR concept in zero-g

- Heated fluid is generated into a spray of droplets
- Droplets radiatively cool as they pass through space
- Droplets are collected and recycled back to the heat source
Conceptual Design of Linear Collector

Rectangular and Triangular LDR Conceptual Designs
Heat Rejection System Weight Comparison

- Brayton cycle
- 650 K avg temp
- Transport loop
- Structure
- Thermal storage

Power Level

<table>
<thead>
<tr>
<th>Power Level</th>
<th>System Weight, lb x 1000</th>
</tr>
</thead>
<tbody>
<tr>
<td>30 MW</td>
<td></td>
</tr>
<tr>
<td>3 MW</td>
<td></td>
</tr>
</tbody>
</table>

Liquid Droplet Radiator In-Space Experiment

- Droplet Collector
- Photo Multiplier Detectors
- High Speed Cameras
- Alignment Laser
- Laser Retrorreflector
- Diagnostic Laser (Droplet Loss)
- Dropet Generator
- Leak-Tight Enclosure
- Accumulator (DC 704 Fluid)
- SRAD Beam

The LDR is an advanced heat rejection concept which can be used to radiate large amounts of heat using minimal weight. The heated fluid is generated into a spray of droplets which radiatively cool as they pass through space. The fluid is then collected and recycled back to the heat source.
Zero-g Experimental Objectives

- **Startup**
  - Generator fluid loss
  - Film/stream interaction at the collector
  - Initial film capture and pressurization
- **Steady state running**
  - Droplet stream characteristics
  - Generator/collector operation
- **Shutdown**
  - Effect of fluid decay on pump operation
  - Fluid losses at generator and collector

Program Schedule
### Out-Reach

#### FLUID MANAGEMENT AND PROPULSION SYSTEMS

**On-Orbit Fluid Management**

**Tank Pressure Control Experiment**

M.D. Bentz  
Boeing Aerospace  
Contract: NAS3-25363, Lewis Research Center, R. Knoll

---

**EXPERIMENT OBJECTIVE:**

Improve our understanding of jet mixing and its effect on thermal stratification, develop a better predictive capability, and give confidence in our ability to positively and reliably control cryogenic tank pressures in low gravity.

Our specific objectives are to:

- Measure heat and mass transfer rates and compare with models
- Observe mixing flow patterns to confirm/extend empirical correlations
- Obtain data to validate or improve NASA-ECLIPSE computer code
- Together with COLD-SAT experiment, show effects of tank scale and fluid properties on mixing

---

**BACKGROUND/TECHNOLOGY NEED**

**Justification:**

- Future space systems will require storage and transfer of cryogenic fluids  
  - STV / OTV  
  - manned Mars mission stage  
  - Space Station nitrogen supply  
  - satellite propellants, reactants, coolants
- Lack of natural convection in low-g leads to increased thermal stratification, higher tank pressures, and possibly longer no-vent fill times
- Use of refrigeration or TVS for pressure control depends on distribution of cooling in tank
- Compact forced-convection heat exchanger could save cost and weight
- Mixing energy should be minimized but must provide reliable pressure control

**Previous Work:**

- One-g thermal mixing tests
- Small-scale low-g dye mixing tests in drop tower
- Low-g simulations
- NASA-ECLIPSE code development
- In-space experiment needed to provide low-g data of sufficient duration and scale
**Tank Pressure Control Experiment**

**M.D. Bentz**  
Boeing Aerospace  
Contract: NAS3-25363, Lewis Research Center, R. Knoll

**Experiment Description:**
- Small Self-Contained Payload (GAS)  
- 5.0 cu-ft., approx. 160 lbm  
- autonomous control and data recording  
- 800 W-hr power supply (alkaline cells)

**Proposed Tests**
- Measure effect of low-g on stratification buildup  
- Measure performance of mixer as functions of flow rate and vapor location  
  - Expected flow patterns:  
    - Symmetrical, low flow rate (regime I)  
    - Symmetrical, high flow rate (regime IV)  
    - Unsymmetrical, high flow rate

**Procedure**
- Heat fluid at one of two locations  
- Measure pressure rise rate and temperature gradients  
- Mix contents at a range of flow rates and measure pressure collapse rate, temperature transients  
- Record liquid/vapor orientations and flow patterns on video

**End Results**
- Demonstrate effective pressure control  
- Determine minimum mixing energy  
- Understand effect of g-jitter on self-mixing  
- Provide visual record of fluid behavior  
- Validate or identify needed improvements to NASA-ECLIPSE and other models
Out-Reach

FLUID MANAGEMENT AND PROPULSION SYSTEMS

On-Orbit Fluid Management

Tank Pressure Control Experiment

M.D. Bentz
Boeing Aerospace

Contract: NAS3-25363, Lewis Research Center, R. Knoll

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Definition</td>
<td>Engineering Development</td>
<td>Detailed Design</td>
<td>Ground Test Unit</td>
</tr>
<tr>
<td>start</td>
<td>TCP</td>
<td>PDDR</td>
<td>PDDR</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>components ordered</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>qual. assembly, test</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

TCP: Technical Concept Review
PDDR: Preliminary Design Review
FDRR: Flight Development Readiness Review
CDR: Critical Design Review
FRR: Flight Readiness Review
Out-Reach FLUID MANAGEMENT AND PROPULSION SYSTEMS

On-Orbit Fluid Management

Integrated Cryogenic Experiment (ICE) Microsphere Insulation Investigation

Dean C. Read
Lockheed Missiles & Space Company, Research & Development Division
Contract: NAS2-12897, Ames Research Center, Jeffrey M. Lee

EXPERIMENT OBJECTIVE

- MEASURE THE LOW-G PERFORMANCE OF VARIOUS MICROSPHERE INSULATIONS OVER AN APPROPRIATE RANGE OF BOUNDARY TEMPERATURES. RESULTS OF PARTICULAR INTEREST ARE:
  1) COMPARISON OF ONE-G AND LOW-G PERFORMANCE
  2) PERFORMANCE AT LOW HOT BOUNDARY TEMPERATURES
  3) PERFORMANCE OF DIFFERENT TYPES OF MICROSPHERES
  4) COMPARISON TO MLI PERFORMANCE


- OTHER EXPERIMENTS MAY ALSO BE INCLUDED IN THE HELD.

BACKGROUND

- IMPROVED INSULATION SYSTEMS ARE OF GREAT INTEREST SINCE THEY ARE A MAJOR COMPONENT IN DETERMINING THE LIFETIME AND COST OF A CRYOGENIC SYSTEM.

- THE BENEFITS OF A MICROSPHERE INSULATION SYSTEM ARE:
  1) LOW-G PREDICTIONS SHOW THE POTENTIAL FOR BETTER PERFORMANCE THAN MLI.
  2) INSTALLATION OF MICROSPHERES IS LESS LABOR INTENSIVE THAN MLI, RESULTING IN A SUBSTANTIAL COST SAVINGS.
  3) POTENTIAL FOR BETTER PERFORMANCE WITH GEOMETRIES THAT ARE DIFFICULT TO WRAP WITH MLI.
TECHNOLOGY NEEDED

- Extensive testing at LMSC has verified MLI and microsphere performance predictions. Extrapolating these predictions from one-G to low-G conditions show a substantial improvement in microsphere performance.

- The effective thermal conductivity of microspheres can be approximated by the linear summation of the conduction and radiation components.

- In one-G, the radiation component dominates at high boundary temperatures and the solid conduction term dominates at low values of the hot boundary temperature.

- In low-G, the solid conduction component would be zero and radiation would be the only heat transfer mechanism.

COMPARISON OF CALCULATED AND MEASURED HEAT RATES

![Graph comparing calculated and measured heat rates.]

Legend:
- Prediction
- Data

T cold = 78K
**Integrated Cryogenic Experiment (ICE) Microsphere Insulation Investigation**

Dean C. Read

Lockheed Missiles & Space Company, Research & Development Division

Contract: NAS2-12897, Ames Research Center, Jeffrey M. Lee

**Out-Reach**

**FLUID MANAGEMENT AND PROPULSION SYSTEMS**

On-Orbit Fluid Management

**Out-Reach**

**Comparision of Microsphere and MLI Performance Predictions**

- Microsphere parameters to be tested include diameter, coatings, packing density, mixes of different microspheres, etc.

- If the heat transfer is totally by radiation, changes in the hot boundary temperature will be easy to detect for small changes in heater power since $q = T^4$. 

---

**Out-Reach**

**Part 1: Executive Summary & Experiment Descriptions**

**Out-Reach**
FLUID MANAGEMENT AND PROPULSION SYSTEMS

On-Orbit Fluid Management

Integrated Cryogenic Experiment (ICE) Microsphere Insulation Investigation

Dean C. Read
Lockheed Missiles & Space Company, Research & Development Division
Contract: NAS2-12897, Ames Research Center, Jeffrey M. Lee

EXPERIMENT CONFIGURATION

INSULATION TUBE CONFIGURATION

PREDICTED EXPERIMENTAL RESULTS
Integrated Cryogenic Experiment (ICE) Microsphere Insulation Investigation

Dean C. Read
Lockheed Missiles & Space Company, Research & Development Division
Contract: NAS2-12897, Ames Research Center, Jeffrey M. Lee
### FLUID MANAGEMENT AND PROPULSION SYSTEMS

**Out-Reach**

**On-Orbit Fluid Management**

*Integrated Cryogenic Experiment (ICE) Microsphere Insulation Investigation*

Dean C. Read  
Lockheed Missiles & Space Company, Research & Development Division  
Contract: NAS2-12897, Ames Research Center, Jeffrey M. Lee

---

### MASTER SCHEDULE

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>QUARTER</td>
<td>1</td>
<td>2</td>
<td>3</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>EXPERIMENT REQUIREMENTS &amp; OBJECTIVES</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PRELIMINARY DESIGN</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PROJECT PLAN</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>EXPERIMENT ENGINEERING &amp; DESIGN</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FABRICATION &amp; ASSEMBLY</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TESTING &amp; FLIGHT QUALIFICATION</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PAYLOAD INTEGRATION &amp; CHECKOUT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FIRST FLIGHT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
EXPERIMENT OBJECTIVE

Develop a detailed understanding of liquid motions in a tank spinning about an external axis - primarily "inertial waves." Rotation rate can be so low that surface tension effects are important.

This understanding is needed for:

- general scientific knowledge (many unanswered theoretical questions that cannot be resolved by ground-based testing)
- design of spinning spacecraft (attitude control and stability problems)

BACKGROUND / TECHNOLOGY NEED

- Basic theory still has unresolved questions. CFD codes have not yet proved applicable. Good data is needed to guide theoretical work.

- Ground-based fundamental experiments are practically impossible - spin rate must be large to eliminate gravitational effects. Observation and measurement under such conditions are practically impossible.

- Liquid torques and energy dissipation interfere with attitude control systems and can cause a "flat" spin for a "prolate" spinner.

- Lack of good models and data lead to overly conservative satellite design.
Out-Reach FLUID MANAGEMENT AND PROPULSION SYSTEMS
On-Orbit Fluid Management
*Liquid Motion In a Rotating Tank*
Franklin T. Dodge
Southwest Research Institute
Contract: NAS3-25358, Lewis Research Center, F.P. Chiamonte

**EXPERIMENT DESCRIPTION**
- Basic experimental apparatus is a forced motion spin table to control the motion of the test tanks
  - steady spin = 0 - 10 rpm
  - nutation (wobbling) frequency is less than twice the spin rate
- Flow visualization and measurement of fluid torque used to determine resonant frequencies and flow characteristics
- Two sets of tanks - ellipsoids and cylinders
  - 15 cm diameter

![Diagram of the experimental setup](image)
### FLUID MANAGEMENT AND PROPULSION SYSTEMS

**Out-Reach**

**On-Orbit Fluid Management**

*Liquid Motion in a Rotating Tank*

Franklin T. Dodge  
Southwest Research Institute  
Contract: NAS3-25358, Lewis Research Center, F.P. Chiaramonte

---

<table>
<thead>
<tr>
<th>PROJECT IS IN EXPERIMENT DEFINITION PHASE</th>
</tr>
</thead>
<tbody>
<tr>
<td>1988</td>
</tr>
<tr>
<td>07 08 09 10 11 12 01 02 03 04 05 06 07</td>
</tr>
</tbody>
</table>

- Objectives & Requirements  
- Modeling  
- Conceptual Design  
- Develop Plans, Schedule & Cost
EXPERIMENT OBJECTIVE

THE OBJECTIVE IS TO ENHANCE FUNDAMENTAL UNDERSTANDING OF THERMOACOUSTIC CONVECTION (TAC) HEAT TRANSFER PHENOMENON AND EVALUATE ITS IMPORTANCE IN VARIOUS PROCESSES INVOLVING TRANSIENT HEAT TRANSFER IN LOW GRAVITY ENVIRONMENT. THE EXPERIMENT WILL PROVIDE DATA WHICH WILL BE USED TO VERIFY ANALYTICAL RESULTS AND COMPARE WITH GROUND-BASED EXPERIMENTS. THE UNDERSTANDING OF THIS PHENOMENON WILL BE APPLICABLE TO:

- DEVELOP INNOVATIVE WAYS FOR RAPID HEATING UNDER MICROGRAVITY CONDITIONS
- IMPROVE HEAT TRANSFER CONTROL IN FLUID HANDLING, STORAGE AND TRANSPORT
- UNDERSTAND THE ROLE AND IMPORTANCE OF HEAT TRANSFER IN ACOUSTIC LEVITATORS

BACKGROUND

ANALYTICAL STUDIES INDICATE:

- VERY LARGE HEAT TRANSFER COMPARED TO CONDUCTION
- VERY SMALL TRANSIENT TIME

EXPERIMENTAL STUDIES SHOW:

- CONTRADICTORY AND INCONCLUSIVE RESULTS
- WHEN TAC EFFECTS ARE OBSERVED, THEIR IMPORTANCE IS SEEN TO BE NOT AS SIGNIFICANT
**EXPERIMENT DESCRIPTION**

The apparatus will provide rapid heating of a compressible fluid near a boundary. The system can be modified to provide experimental data for both closed and open-ended vessel geometry. Instrumentation for temperature and pressure measurements are required to detect and record the effects of thermoconvective waves.
EXPERIMENT OBJECTIVES

Advance the state-of-the-art in space robotics through the design and development of manipulator testbeds to be flown on the Space Transportation System (STS) supporting:

- Rigid Link Manipulators
- Large, Flexible Manipulators

BACKGROUND/TECHNOLOGY NEED

- Significant results from ground experimentation have not been validated in space
- Space robotics R & D program has need for long-term testbed capability in support of:
  - Mechanisms
  - Sensors
  - Processing
  - Controls
- On-orbit experimentation is required to provide a database for defining technology directions

EXPERIMENT DESCRIPTION

- Experiment will support rigid and flexible arm experiments
- Processing system will support varied controls research objectives
- Experiment will support both autonomous and teleoperated functions
- Emphasis is on growth capability
SUMMARY

- A need exists for research testbeds, on orbit, to support validation of technology
- Must support both:
  - rigid and flexible structures
  - teleoperation and autonomy
  - operation from ground or space
- Key design feature: ability to integrate new technology

SCHEDULE

<table>
<thead>
<tr>
<th>RESEARCH AND DESIGN</th>
<th>1988</th>
<th>1989</th>
</tr>
</thead>
<tbody>
<tr>
<td>MASTER SCHEDULE</td>
<td>J J A S O N D</td>
<td>J F M A</td>
</tr>
<tr>
<td>FACE/DMACE</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Requirements Definition</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Concept Definition</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Program Definition</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Program Plan</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
EXPERIMENT OBJECTIVE

DEVELOP A MANIPULATOR CONTROL SYSTEM CAPABLE OF ACCURATELY CONTROLLING A ROBOT ARM WITH LIGHTWEIGHT NON-RIGID LINKS IN A ZERO GRAVITY VACUUM. THIS CONTROL SYSTEM MUST MEET THE FOLLOWING REQUIREMENTS:

• POSITION CONTROL OF THE END-EFFECTOR MUST BE AS GOOD AS OR BETTER THAN PRESENT DAY INDUSTRIAL ROBOTS.

• CONTROL ACCURACY MUST NOT BE A FUNCTION OF PAYLOAD MASS OVER THE DESIGN LOAD-RANGE.

• STRUCTURAL STIFFNESS OF THE MANIPULATOR LINKS MUST NOT SIGNIFICANTLY AFFECT THE POSITION CONTROL ACCURACY.

BACKGROUND / TECHNOLOGY NEED

PROBLEMS ASSOCIATED WITH USING A COMPLETE MODEL BASED, DECOUPLING AND LINEARIZING MANIPULATOR CONTROL SYSTEM:

• IT IS COMPUTATIONALLY VERY EXPENSIVE TO USE THE ENTIRE DYNAMIC MODEL INSIDE THE CONTROL LOOP.

• THE VALUES OF THE PARAMETERS IN THE DYNAMIC MODEL ARE OFTEN NOT ACCURATELY KNOWN.

• SOME OF THE PARAMETERS ARE NOT REPEATABLE BECAUSE THEY CHANGE AS THE ROBOT AGES.

• STRUCTURAL VIBRATIONS MAY BE INDUCED BY THE CONTROL SYSTEMS IN MANIPULATORS WITH FINITE STIFFNESS.
BACKGROUND / TECHNOLOGY NEED

SIMPLIFICATIONS MADE IN MOST PRESENT DAY INDUSTRIAL ROBOT CONTROL SYSTEMS:

- THE DYNAMIC MODEL IS NOT USED AT ALL INSIDE THE CONTROL LOOP.
- THE CONTROL SYSTEM GAINS ARE ALL SET TO CONSTANT DIAGONAL MATRICES.
- THE CONSTANT GAINS ARE SET AS HIGH AS POSSIBLE, SO THAT THE ERRORS CAUSED BY THE JOINT COUPLING WILL BE QUICKLY SUPPRESSED BY THE ERROR DRIVEN CONTROL LAW.
- ALL LINKS ARE CONSTRUCTED TO BE VERY STIFF, TO PREVENT THE HIGH GAINS FROM INDUCING STRUCTURAL VIBRATIONS.

BACKGROUND / TECHNOLOGY NEED

PROBLEMS ASSOCIATED WITH USING PRESENT INDUSTRIAL ROBOT CONTROL SYSTEMS FOR IN-SPACE APPLICATIONS:

- IF THE MANIPULATOR IS DESIGNED TO HAVE VERY STIFF LINKS, IT NATURALLY MUST BE VERY HEAVY. A ROBOT TO PAYLOAD WEIGHT RATIO OF 50 IS COMMON.
- IF THE LINK WEIGHT AND STIFFNESS IS REDUCED, THE HIGH CONSTANT GAINS WILL EXCITE THE NATURAL VIBRATION MODES OF THE MANIPULATOR.
- IF THE CONSTANT GAINS ARE REDUCED, ERRORS INDUCED BY THE JOINT COUPLING WILL NOT BE ADEQUATELY SUPPRESSED.
EXPERIMENT DESCRIPTION

THE PRESENT RESEARCH WILL TEST THE FEASIBILITY OF ACCURATELY CONTROLLING A ROBOT ARM WITH LIGHTWEIGHT NON-RIGID LINKS IN A ZERO GRAVITY VACUUM. THE WORK WILL BE CARRIED OUT IN THREE PHASES:

- THE DEVELOPMENT OF A 2-AXIS ROBOT WHICH MINIMIZES THE EFFECTS OF GRAVITY AND CAN BE USED FOR PRELIMINARY GROUND TESTING OF THE CONTROL SYSTEM.
- THE DEVELOPMENT OF A COMPUTER SIMULATION FOR THE TEST ROBOT AND THE CONTROL SYSTEM.
- THE DEVELOPMENT OF A 3-AXIS ROBOT TO BE USED FOR IN-SPACE TESTING OF THE CONTROL SYSTEM.

SCHEMATIC
AUTOMATION AND ROBOTICS

Robotic Systems

Control of Flexible Robot Manipulators in Zero Gravity

Warren F. Phillips
Utah State University, Center for Computer Aided Design and Manufacturing
Contract: NAS8-37754, Marshall Space Flight Center, Pamela Nelson
## Control of Flexible Robot Manipulators in Zero Gravity

**Warren F. Phillips**  
Utah State University, Center for Computer Aided Design and Manufacturing  
Contract: NAS8-37754, Marshall Space Flight Center, Pamela Nelson

### MASTER SCHEDULE

<table>
<thead>
<tr>
<th>Year</th>
<th>Experiment Definition</th>
<th>Experiment Development</th>
<th>Mission 1</th>
<th>Mission 2</th>
</tr>
</thead>
<tbody>
<tr>
<td>1988</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1989</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1990</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1991</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1992</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1993</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1994</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- GROUND EXPERIMENT DESIGN
- GROUND EXPERIMENT FABRICATION
- GROUND TESTING
- SIMULATION DEVELOPMENT
- SIMULATION
- IN-SPACE EXPERIMENT DESIGN
- IN-SPACE EXPERIMENT FABRICATION
- PRE-FLIGHT TESTING
- MISSION & FLIGHT OPERATIONS
- DATA ANALYSIS
- REFURBISHMENT
### Experiment Description

**Jitter Suppression for Precision Space Structures**

Robert M. Laurer
McDonnell Douglas

**Contract:** NAS1-18689, Langley Research Center / JPL, Dean W. Sparks, Jr. / John A. Garba

#### Experiment Objective

- **In-space demonstration of active and passive damping techniques to suppress jitter for precision space structures.**

- Implement a shuttle payload bay experiment to account for in-space conditions.

- Establish ground/flight database on jitter suppression techniques.

#### Background/Technology Need

**Background**

- Space-based optical applications require low line-of-sight residual jitter levels.

- Laser communications and laser radar are representative systems.

- Jitter suppression places demands on structural subsystem.

- Present systems - microradian pointing budgets.

- Future systems - sub-microradian pointing and/or larger / complex configurations.

**Technology Need**

- Ground test validation is inadequate.

- Data needed for low-G, thermal/vacuum environment of space.

- Provide validation of jitter suppression techniques for space application.
REDUCED JITTER YIELDS SYSTEM PAYOFF

REDUCED JITTER WITH DAMPING

SYSTEM PAYOFF

- REDUCED POWER
- REDUCED WEIGHT
- LOWER COST
- HIGHER RELIABILITY
- INCREASED LIFE

ANALYSES DEMONSTRATE JITTER REDUCTION WITH INTREGAL DAMPING

VISCOELASTIC DAMPING MATERIAL IMPLEMENTATION

JITTER ATTENUATION WITH VISCOELASTIC DAMPING

- ASSESSMENT OF PIEZOELECTRIC DAMPING
- EFFECTIVE MODAL DAMPING
- ORDER OF MAGNITUDE GREATER THAN VISCOELASTIC DAMPING
Out-Reach

AUTOMATION AND ROBOTICS
Robotic Systems (Control/Structure Interaction)

*Jitter Suppression for Precision Space Structures*

Robert M. Laurenson
McDonnell Douglas

Contract: NAS1-18689, Langley Research Center / JPL, Dean W. Sparks, Jr. / John A. Garba

---

**EXPERIMENT DESCRIPTION**

- Based on existing space-based laser communications subsystem design
- Use existing engineering model hardware
  - Mass simulated equipment components
- Integrate damping into graphite/epoxy structure
  - Passive viscoelastic damping
  - Active piezoelectric damping
- Provide excitation sources and instrumentation
- Integrate into shuttle payload bay experiment

---

**ENGINEERING MODEL UNIT STRUCTURE**
GRAPHITE/EPoxy CONSTRUCTION
SUMMARY

- EXPERIMENT DEFINITION PHASE
  - JUNE 88 THROUGH FEBRUARY 89
- BASED ON SPACE-BASED LASER COMMUNICATIONS DESIGN
  - HARDWARE IS AVAILABLE
  - MODIFICATIONS FOR EXPERIMENT BEING DEFINED
- PERFORM PRELIMINARY ANALYSES
  - DISTURBANCE SOURCES
  - DAMPING IMPLEMENTATION
  - SUPPORTING ANALYSES
  - INSTRUMENTATION
- DEVELOP PRELIMINARY PLANS
  - GROUND TEST, SHUTTLE INTEGRATION, IMPLEMENTATION (COST/SCHEDULE)
- INTEGRATION WITH OTHER EXPERIMENTS MAY BE BENEFICIAL
  - REDUCED COST
  - MAXIMUM PAYLOAD BAY UTILIZATION
EXPERIMENT OBJECTIVE

Demonstrate the use of constrained layer viscoelastic damping treatments to reduce vibrations in flexible space manipulators. The target example is the space shuttle RMS. The current phase of the project includes:

- Analysis and design of damping treatment for bending and torsion.
- Design for reduced sensitivity to temperature variations.
- Simulate and evaluate results.
- Experimental verification.
### Out-Reach AUTOMATION AND ROBOTICS

**Passive Damping Augmentation for Space Manipulators**

Dr. Thomas E. Alberts  
Old Dominion University (Support by 3M Corporation)  
Contract: NAS1-18687, Langley Research Center, Jack Pennington

<table>
<thead>
<tr>
<th>Experiment Descriptions</th>
</tr>
</thead>
</table>

Total 52 pieces of steel sheets on both sides

Viscoelastic film on both sides

Aluminum beam

Beam size: 48 x 3/4 x 3/16 in  
(A1 6061)

Steel sheet: 1.72 x 3/4 x 0.01 in  
(steel 1025)

Thickness of viscoelastic film: 0.002 in  
(SI2015X Type J10)

**DAMPING TREATMENT**

Finite Element Analysis of Damped System - Bending
**Passive Damping Augmentation for Space Manipulators**

Dr. Thomas E. Alberts

Old Dominion University (Support by 3M Corporation)

Contract: NAS1-18687, Langley Research Center, Jack Pennington

---

**Finite Element Analysis of Damped System - Torsion**

Two beam elements for both sides steel sheets

Five QU4 elements for aluminum beam

Tri for viscoelastic to connect the gaps

Four TRI elements for viscoelastic material on gaps

Six QU4 elements for viscoelastic material on both sides

**FINITE MESH FOR RECTANGULAR BEAM**
DAMPING ANALYSIS

- Finite element analysis of single layer treatments.
  - Bending
  - Torsion
  - Experiment
- Use validated code to evaluate multi-layer treatments designed to extend effective temperature range.
- Use damping results in full scale simulation.
## OBJECTIVES

- **Design, Fabricate and Fly on the STS an Emulsion Chamber of the General Type** which will be a likely candidate for Cosmic Ray and High Energy Physics Studies on the Space Station.

- **Assess the Radiation Background Encountered in Such Detectors in Orbits up to 400 km.**

- **Assess Pre- and Post-Flight Environmental Effects on Passive Detectors.**

- **Assess the Effects of Large Shielding on Dose in Space Station Orbits.**

- **Provide the Astrophysics Community with an Environmental Assessment of the Performance Capabilities of Emulsion Techniques in Space.**

- **Develop and Modify Emulsion Techniques as Necessary to Allow Optimum Use of the Power of the Method.**

## BACKGROUND

- Nuclear Track Emulsions have been used for 50 years in particle physics and Cosmic Ray Physics and have produced many landmark discoveries or measurements:
  - **First-Demonstration of Existence of I-Meson (1947).**
  - **Discovery of Heavy Elements in Cosmic Rays (1948).**
  - **First Measurement of Helium Spectrum (1957).**
  - **Confirmation of Trans-Iron Nuclei in Cosmic Rays (1967).**
  - **Observation of Evidence of Quark-Gluon Plasma Formation in Heavy Nucleus Collisions above 1 TeV/n.**
  - **First Measurement of Chemical Composition of Cosmic Rays at 10^5 eV.**
## TECHNOLOGY NEEDS

(TO BE ADDRESSED BY ENGINEERING FLIGHT OF EMULSION CHAMBER.)

- Radiation-induced background in orbit. Self-shielding to ambient radiation. Shower production within the chamber from energetic background radiation.
- Radiation-induced background accumulated during storage and ground operations.
- Temperature and humidity effects: impact on mechanical design and ground operations. Temperature gradient effects within the chamber.
- Ability to perform various measurements on interactions observed in the test flight chamber with a known background.

## EXPERIMENT DESCRIPTION

- Detector plates include nuclear track emulsions of different types, X-ray film and CR-39 etchable track detectors. This stack (also including inactive material such as Lucite and lead) must be protected from light, heat, humidity and vibration damage.
- The stack (or Emulsion Chamber) is contained in a hermetic aluminum box which is partially evacuated. The box has a honeycomb lid to reduce nuclear interactions of incoming cosmic rays.
- Dimensions: 50 cm x 60 cm x 40 cm
- Weight: 180 kg
- Temperature: ≤ 20°C, Redline 30°C
- Power: Heaters, thermistors and temperature data recorder
- Orbit: ≤ 57 deg; ≤ 400 km; 5-10 days
Development of Emulsion Chamber Technology

John Gregory
University of Alabama in Huntsville
Contract: NAS8-37751, Marshall Space Flight Center, Jon Haussler
SENSORS AND INFORMATION SYSTEMS

Sensors

Development of Emulsion Chamber Technology

John Gregory
University of Alabama in Huntsville
Contract: NAS8-37751, Marshall Space Flight Center, Jon Haussler

SCHEDULE

<table>
<thead>
<tr>
<th>6 MONTHS</th>
<th>12 MONTHS</th>
<th>15 MONTHS</th>
</tr>
</thead>
<tbody>
<tr>
<td>DESIGN</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MECHANICAL</td>
<td></td>
<td></td>
</tr>
<tr>
<td>THERMAL</td>
<td></td>
<td></td>
</tr>
<tr>
<td>SCIENTIFIC</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MID-TERM REVIEW</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MSFC</td>
<td>Δ</td>
<td></td>
</tr>
<tr>
<td>FABRICATION OF TEST ARTICLE</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PHASE B DESIGN REVIEW</td>
<td>Δ</td>
<td></td>
</tr>
<tr>
<td>BACKGROUND STUDY</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PREPARATION OF DRAWINGS</td>
<td></td>
<td></td>
</tr>
<tr>
<td>DELIVERY OF DRAWINGS, SPECIFICATIONS AND COST PLAN FOR FLIGHT INVESTIGATION</td>
<td>Δ</td>
<td></td>
</tr>
<tr>
<td>Out-Reach SENSORS AND INFORMATION SYSTEMS</td>
<td>Out-Reach</td>
<td></td>
</tr>
<tr>
<td>------------------------------------------</td>
<td>----------</td>
<td></td>
</tr>
</tbody>
</table>

**SENSORS**

*Infrared Focal Plane Performance In the South Atlantic Anomaly*

Frank Junga
Lockheed, Research and Development Division
Contract: NAS2-12898, Ames Research Center, Craig McCreight

---

**PROGRAM OBJECTIVES**

- Construct a model to predict selected focal plane performance parameters in the South Atlantic Anomaly environment. Outputs shall include proton-induced pulse height distribution in detectors and proton induced noise

- Verify pulse height distribution calculations for several proton energies and shielding thicknesses

- Develop a detailed concept for a flight experiment

---

**BACKGROUND**

- NASA and DOD will fly missions employing low background IR detectors. The proton environment can significantly affect detector performance

---

**TECHNOLOGY NEED**

- An accurate model is required to assess noise problems and to develop signal processing algorithms for noise reduction

---

**NEED FOR SPACE EXPERIMENT**

- We can model and verify model for effects of particle energy, geometric factors, and shielding. We cannot model noise contributions due to fluctuations in the instantaneous proton energy distribution.
### SENSORS AND INFORMATION SYSTEMS

#### Sensors

**Infrared Focal Plane Performance In the South Atlantic Anomaly**

Frank Junga  
Lockheed, Research and Development Division  
Contract: NAS2-12898, Ames Research Center, Craig McCreight

---

### PULSE HEIGHT DISTRIBUTIONS, NOISE ANALYSIS, AND VERIFICATION

#### ANALYSIS INCLUDES

- Chord length distribution
- Proton energy distribution
- Proton energy loss, variance in energy distribution (a parameter)
- Secondary sources of ionizing radiation (e.g. soft x-rays)

#### VERIFICATION

- Measure pulse height distributions for various angles of incidence, proton energy (20-60 MeV), and type and thickness of shielding material
- Test for blooming

---

### ACTIVITIES TO DATE

- Background material assembled for pulse height distribution and noise calculations
- Visits to UC Berkeley and Davis cyclotrons to get specifics on experiment configurations
- Designed and fabricated necessary fixtures for proton pulse height distribution experiments*
- Scheduled Davis cyclotron for Dec 7

*NASA Ames completed dewar and software modifications
OUT-REACH

SENSORS AND INFORMATION SYSTEMS

Infrared Focal Plane Performance In the South Atlantic Anomaly

Frank Junga
Lockheed, Research and Development Division
Contract: NAS2-12898, Ames Research Center, Craig McCreight

FLIGHT EXPERIMENT CONCEPT

Lockheed ID
He Extended Life
Dewar (HELD)

A self-contained experiment
• Data collected on tape
Minimum of two focal plane arrays
• One with added shielding
Several experiments to be accommodated in dewar

PROGRAM SCHEDULE (MONTHS AFTER GO-AHEAD)

<table>
<thead>
<tr>
<th></th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
<th>9</th>
<th>10</th>
<th>11</th>
<th>12</th>
</tr>
</thead>
<tbody>
<tr>
<td>EXPERIMENT DEFINITION</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CYCLOTRON TESTS</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>MODEL DEVELOPMENT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CONCEPT DEVELOPMENT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>INTERFACE DEFINITION</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PHASE II PLAN</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>COST ESTIMATE</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FINAL REPORT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Program Start Date: 7 September 1988
EXPERIMENT OBJECTIVE:

- TO DEVELOP TECHNOLOGY FOR ULTRASTABLE ATOMIC HYDROGEN MASER CLOCKS FOR LONG DURATION SPACE-BORNE EXPERIMENTS
- TO DESIGN AND BUILD TWO FLIGHT-QUALIFIED HYDROGEN MASERS
- TO TEST AND EVALUATE THE MASERS' PERFORMANCE IN SPACE

BACKGROUND

- 1976 GP-A (REDSHIFT) H-MASER DEVELOPED FOR SHORT DURATION ROCKET FLIGHT ~2 HOURS, MASER STABILITY 7x10^{-15}
- 1980-84 STUDY OF ORBITING CLOCK EXPERIMENT FOR VERY HIGH PRECISION GLOBAL TIME AND FREQUENCY TRANSFER
- 1988 GROUND BASED MASER FREQUENCY STABILITY APPROACHING 1x10^{-16} AT 10^4 SEC; THIS CAN BE REALIZED IN A SPACEWORTHY H MASER

TECHNOLOGY NEEDS SATISFIED BY SPACEBORNE ULTRA-HIGH STABILITY HYDROGEN MASERS

- HIGH PRECISION SPACE-BORNE GUIDANCE AND NAVIGATION SYSTEMS
- RADIO ASTRONOMY VERY LONG BASELINE INTERFEROMETRY
- REAL-TIME HIGH PRECISION GLOBAL TIME AND FREQUENCY SYNCHRONIZATION
- GRAVITATION AND RELATIVITY PHYSICS
- SPACE-BORNE MULTISTATION TIME-CORRELATED RADAR TRACKING
Construction and In-Space Performance Evaluation of High-Stability Hydrogen Maser Clocks

Robert F.C. Vessot
Smithsonian Astrophysical Observatory
Contract: NAS8-37752, Marshall Space Flight Center, Dr. R. Decher

EXPERIMENT DESCRIPTION

---

PHOTOGRAPH OF SPACE MASER COMPONENTS

ORIGINAL PAGE IS OF POOR QUALITY
Out-Reach SENSORS AND INFORMATION SYSTEMS

Construction and In-Space Performance Evaluation of High-Stability Hydrogen Maser Clocks

Robert F.C. Vessot
Smithsonian Astrophysical Observatory
Contract: NAS8-37752, Marshall Space Flight Center, Dr. R. Decher

SPACE MASER DESIGN CONCEPT

- 4-Layer Magnetic Shields, Ovens, Insulation
- TE 011 Mode Resonator (CER-VIT)
- Vacuum Envelope
- Hydrogen Sorption Cartridges
- Atomic Hydrogen R.F. Dissociator
- Hexapole State Selector Magnet
- Storage Bulb (fused silica)

SIZE: 16.2" (41.1 cm.) Dia.
37.8" (96.3 cm.) Long
WEIGHT: 98.4 lbs. (44.6 kg.)
POWER: 10 Watts

SCHEDULE OF PRESENT PROGRAM AND ITS EXTENSION TO A FLIGHT EXPERIMENT.

<table>
<thead>
<tr>
<th>1988</th>
<th>1989</th>
</tr>
</thead>
<tbody>
<tr>
<td>June</td>
<td>July</td>
</tr>
<tr>
<td>CONTRACT AWARD: August 11, 1988</td>
<td></td>
</tr>
</tbody>
</table>

- Concept Design (Vehicle)
- Locate Existing Hardware and Procure Components
- Model Shop Fabrication
- Assemble and Checkout Physics Package
- Adapting Existing Control Electronics
- Functional Testing with Data
- Refinements and Validation Test
- Life Testing in Vacuum Chamber

- Dec. 1988
- PDR Oct 1989
- PDR Mar 1990
- 1990
- 1991
- 1997
- Detailed Planning For Space Experiment
- Ongoing Survey of Space Clock Requirements
- Engineering Model Design and Test
- Build and Test Flight Maser
- Integration Into Flight and Test

DELIVERY TO M.S.F.C. JUNE 1991

SHIP TO KSC JAN 1992
### CONCLUSIONS AND SUMMARY

Earth-based hydrogen masers have achieved extremely high performance and stability approaching $1 \times 10^{-16}$. This technology should be adapted for space applications of long duration.

- The space station and polar orbiter will require high stability clocks for
  -- VLBI operation of spaceborne radio telescopes
  -- World wide time and frequency coordination
  -- High speed communications synchronization

- High precision, very high stability, clock signals are necessary as an on-board utility for other system applications.

Modern metrology depends on the definition of time interval in terms of the atomic second. Distance is now defined by the velocity of light in terms of atomic time.

Atomic clocks provide the most precise measurements of physical parameters.
SENORS AND INFORMATION SYSTEMS

**Out-Reach**

**Acceleration Measurement and Management Experiment Definition**

Jan A. Blijvoet
University of Alabama in Huntsville (support by Teledyne Brown Engineering)
Contract: NAS1-18683, Langley Research Center, Robert C. Blanchard

**General Experiment Objectives:**

- Enhance the level of Acceleration Measurement and spatial patterning as an essential support to high quality microgravity operations.

- To bring acceleration measurement and management toward the mature status enjoyed by attitude and orbit determination & management.

**Technology Need:**

- Microgravity materials processes require:
  - very low acceleration disturbance levels.
  - knowledge of direction of the residual acceleration vector for experiment accommodation.

- No methodology available to determine on-orbit the center-of-mass.

- Acceleration disturbance level and vector needs to be known at a large number of experiment locations.

- Needs to be known in real time.

- Information needed in real time for control of the center of mass.

**Experiment Definition Objectives:**

- Develop analytical methods for in-orbit calculation of center of mass from a number of separately located 3-D accelerometers.

- Develop analytical methods for in-orbit calculation of acceleration level and acceleration vector at any selectable experiment location.

- Determine data for control of the center of mass.
ACCELEROMETER MEASUREMENT AND MANAGEMENT

SURVEY OF EXISTING ACCELEROMETERS

Other Similar Uses for Accelerometers
- Missile Guidance
- Satellite Sensor Stabilization
- Seismic Motion Detection
- Orbital Experiment Instrumentation

Teledyne Brown Engineering Requested Information from the Following Organizations:
- Applied Technology Associates
- Bell Aerospace Textron
- Bruel & Kjaer
- C.S. Draper Laboratories
- G.E. Space Div.
- Honeywell
- IC Sensors
- KMS Fusion
- Litton
- Payload Systems, Inc.
- Rockwell Defense Electronics
- Singer Kearfott
- Sperry Aerospace
- Stanford University
- Sundstrand Data Control
- Systron Donner
- Teledyne Geotech
- U of MD Physics Dept.

Specifications Requested Were:
- Measure 10^{-7} to 10^{-2} g_b
- Frequency response of 10^+ to 50 Hz
- Accommodate a noise spectrum of up to 10^{-2} g_b from 1 to 50 Hz
- A method of calibrating the sensor

Conclusions:
- Currently existing sensors may be suitable for our needs, pending testing
- Sensor bias and drift characteristics will interfere with the low amplitude, low frequency measurements
- Testing and calibration will be difficult in a one g_b environment
- A new type of sensor may be more appropriate for this application
## POTENTIAL SHUTTLE FLIGHTS FOR PILOT EXPERIMENTATIONS

<table>
<thead>
<tr>
<th>Flight, Orbiter Date</th>
<th>Relevant Payload</th>
<th>Carrier</th>
<th>Low-g Accelerometer Flight?</th>
<th>meters*</th>
</tr>
</thead>
<tbody>
<tr>
<td>32.C Nov 89</td>
<td></td>
<td></td>
<td></td>
<td>H, O</td>
</tr>
<tr>
<td>35.C Mar 90</td>
<td>Astro-1</td>
<td>2SL-PAL</td>
<td>yes</td>
<td>H, O</td>
</tr>
<tr>
<td>40.C Jun 90</td>
<td>SLS-1</td>
<td>SL-LM</td>
<td>?</td>
<td>S7, H, O</td>
</tr>
<tr>
<td>44.C Dec 90</td>
<td>Atlas-1, MSL-32</td>
<td>2SL-PAL</td>
<td>yes</td>
<td>S7, H, O</td>
</tr>
<tr>
<td>45,A Jan 01</td>
<td>TSS-1</td>
<td>SL-PAL,MPESS</td>
<td></td>
<td>TBD</td>
</tr>
<tr>
<td>47,C Apr 91</td>
<td>IML-1</td>
<td>SL-LM</td>
<td>yes</td>
<td>S, H, O</td>
</tr>
<tr>
<td>48,A May 91</td>
<td>EURECA-II</td>
<td></td>
<td>yes</td>
<td>TBD</td>
</tr>
<tr>
<td>49,C Jul 91</td>
<td>S/I-2</td>
<td>SL-LM</td>
<td>yes</td>
<td>S, H, O</td>
</tr>
<tr>
<td>52,C Dec 91</td>
<td>S/L-D2</td>
<td>SL-LM+USS</td>
<td>yes</td>
<td>H, O (TBD)</td>
</tr>
<tr>
<td>55,C Mar 02</td>
<td>USML-1</td>
<td>SL-LM+MPESS</td>
<td>yes</td>
<td>2S, H, O</td>
</tr>
<tr>
<td>56,A Apr 92</td>
<td>ORFEUS</td>
<td>SPAS</td>
<td>yes</td>
<td>TBD</td>
</tr>
<tr>
<td>57,D May 92</td>
<td>USMP-1</td>
<td>MSL-MPESS</td>
<td>yes</td>
<td>TBD</td>
</tr>
<tr>
<td>59,C Jul 92</td>
<td>SLS-2</td>
<td>SL-LM</td>
<td>?</td>
<td>S7, H, O</td>
</tr>
<tr>
<td>60,A Jul 92</td>
<td>ISF-1</td>
<td></td>
<td>yes</td>
<td>TBD</td>
</tr>
<tr>
<td>63,C Oct 92</td>
<td>IML-2</td>
<td>SL-LM</td>
<td>yes</td>
<td>S7, H, O</td>
</tr>
<tr>
<td>65,D Nov 92</td>
<td>MSL-4</td>
<td>MPESS</td>
<td>yes</td>
<td>S?</td>
</tr>
<tr>
<td>68,A Feb 93</td>
<td>ISF-2</td>
<td></td>
<td>yes</td>
<td>TBD</td>
</tr>
<tr>
<td>70, OV 105</td>
<td>EURECA-2L</td>
<td></td>
<td>yes</td>
<td>TBD</td>
</tr>
<tr>
<td>73,C Jul 93</td>
<td>USML-2</td>
<td>SL-LM+MPESS</td>
<td>yes</td>
<td>2S7, H, O</td>
</tr>
<tr>
<td>74, OV 105</td>
<td>AAPE</td>
<td>2SL-PAL</td>
<td>?</td>
<td>S?(Mod.1?</td>
</tr>
<tr>
<td>75,A Sep 93</td>
<td>GP-B1</td>
<td>SL-PAL</td>
<td>yes</td>
<td>TBD</td>
</tr>
<tr>
<td>?</td>
<td></td>
<td>MSL-5</td>
<td>MPESS</td>
<td>yes</td>
</tr>
<tr>
<td>?</td>
<td></td>
<td>MSL-6</td>
<td>MPESS</td>
<td>yes</td>
</tr>
</tbody>
</table>

*S - SAMS - Space Acceleration Measurement System (JSC, R.C.)
H - HIRAP - High Resolution Accelerometer Package (JSC, R.C.)
0 - OARE - Orbital Acceleration Research Experiment (JSC, R.C.)
**Acceleration Measurement and Management Experiment Definition**

Jan A. Bijvoet  
University of Alabama in Huntsville (support by Teledyne Brown Engineering)  
Contract: NAS1-18683, Langley Research Center, Robert C. Blanchard

### M & M Process Flow

**Measurements:**  
- Accelerometers  
- Attitude  
- Orbit  
- Strain Gauges

**Known Quantities:**
- Physical Constants  
- Structural Parameters

**Model:**  
- Gravity gradient  
- Atmospheric drag  
- Radiator Pressure  
- Orbital  
- Dynamics  
- Attitude  
- Structural Dynamics

**Processing:**  
- Data Reduction, Correlation, Error Estimates

**Determining of Parameters and Error Estimates:**  
- CM  
- Local structural response parameters, incl. vibration modes

**Extrapolated Spatial Acceleration Environment:**  
- (incl. Variance, covariance)

**Signal for Control Systems:**  
- CM  
- Attitude  
- TEA  
- Damping
### Dynamic Spacecraft Attitude Determination with GPS

**Dr. Duncan B. Cox, Jr.**
Mayflower Communications Company, Inc.
Contract: NAS5-30358, Goddard Space Flight Center, Dr. Seymour Kant

#### EXPERIMENT OBJECTIVE

Determine the feasibility of using NAVSTAR GPS signals to accurately measure very small differences in antenna locations in multiple antenna arrays.

- **Determine spacecraft orbit, attitude, and flexure.**
  - Consider shading of antennas by spacecraft structures.
  - Utilize optimum estimation filters, including models of spacecraft dynamics and potentially available inertial sensors.

- **Measure very slow ground motions due to geodynamics.**
  - Utilize data obtained by continuously monitoring GPS signals at multiple sites, including stable baselines as well as potentially unstable ones.
  - Estimate ionospheric and tropospheric delays and multipath perturbations.

#### BACKGROUND

**NAVSTAR Global Positioning System (GPS)**

Signals soon available continuously world-wide, to LEO and beyond

Likely to be widely used for spacecraft navigation

Phase information can be used to measure lengths and bearings of short baselines with subcentimeter accuracies.

- Allows determination of attitude and flexure of spacecraft with multiple antennas.
- Allows determination of geodynamic motions of GPS-instrumented ground sites.
TECHNOLOGY NEEDS

GPS-derived attitude data can be used for initial pointing of spacecraft subsystems, such as laser radars and laser communications systems. But technical issues must be resolved before mission applications are undertaken.

Spacecraft structures obscure the views of satellites and cause multipath interference.

A Geodynamic Laser Ranging System (GLRS) demonstration can benefit from having independent GPS measurements of terrestrial baselines with subcentimeter accuracies.

A system design employing low-cost, weather-tolerant, terrestrial equipment and advanced algorithms needs to be developed and demonstrated. The system should be integrated appropriately with the GLRS system.

EXPERIMENT DESCRIPTION

Instrumented space vehicle

Three GPS antennas, one GPS receiver, one high-accuracy clock, one digital controller, one data recorder.

One independent attitude determination subsystem, preferably part of a GLRS experiment. (Note that GPS receivers are likely to be utilized by GLRS for orbit determination.)

Record raw GPS pseudorange and phase data, and independent attitude data for post-flight processing. Include inertial sensor data if available.

Instrumented terrestrial range

A GPS antenna, receiver, and recorder at each of two GLRS sites.

Compare GPS attitude and baseline data with independent results.
Dynamic Spacecraft Attitude Determination with GPS

Dr. Duncan B. Cox, Jr.
Mayflower Communications Company, Inc.
Contract: NAS5-30358, Goddard Space Flight Center, Dr. Seymour Kant

---

SCHEDULE

<table>
<thead>
<tr>
<th>TASK DESCRIPTION</th>
<th>O</th>
<th>N</th>
<th>D</th>
<th>J</th>
<th>F</th>
<th>M</th>
<th>A</th>
<th>M</th>
<th>J</th>
<th>J</th>
<th>S</th>
</tr>
</thead>
<tbody>
<tr>
<td>System Description</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Algorithm development</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Hardware selection</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Performance analysis</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Experiment planning</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Final report</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Out-Reach</td>
<td>SENSORS AND INFORMATION SYSTEMS</td>
<td>Out-Reach</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>-----------</td>
<td>--------------------------------</td>
<td>-----------</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Sensors</td>
<td>Dynamic Spacecraft Attitude Determination with GPS</td>
<td>Sensors</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Dr. Duncan B. Cox, Jr.</td>
<td>Mayflower Communications Company, Inc.</td>
<td>Contract: NAS5-30358, Goddard Space Flight Center, Dr. Seymour Kant</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**SUMMARY**

GPS signals probably can be used simply and at low cost to determine the attitudes of spacecraft, and bending of spacecraft members, to milliradian accuracies.

GPS signals probably can be used with low cost equipment for determination of slow geodynamic motions of terrestrial baselines to subcentimeter accuracies.

An experiment is proposed in which GPS would synergistically support a GLRM experiment.

- Utilizing GLRM-spacecraft attitude data to corroborate GPS attitude data.
- Utilizing GPS data to corroborate GLRM baseline data.
- Using GPS data for satellite orbit estimation, to the benefit of both experiments.
OBJECTIVE:

To provide ultra-stable, solid-state laser oscillators for future applications in space-based systems. The self-powered SUNLITE instrument will use the vibration-free, microgravity environment in or about the orbiting Shuttle to test the stability and Schawlow-Townes linewidth limit of specially configured monolithic Non-Planar Ring Oscillators (NPRO).

BACKGROUND:

The availability of diode lasers, as pump sources, provides the opportunity for development of small, stable, long-life all solid-state laser sources. The monolithic Non-Planar Ring Oscillator (NPRO), developed at Stanford under NASA/OAST sponsorship, promises to satisfy scientific, medical and industrial applications requiring coherent narrow linewidth sources. Immediate benefits are promised for spacecraft operations and remote sensing applications.

Improved techniques in frequency control are used to lock the NPRO to external cavities and have yielded linewidths down to about 150 Hz. Resultant linewidth measurements are limited by noise induced by sources within the lab environment. Reducing these sources to practical limits will leave gravity, mechanical and acoustically coupled vibration as limiting factors in laboratory experiments. The Shuttle experiment will provide the environment needed to further examine linewidth and stability limitations.
The NPRO Module

The Nd:YAG laser is tuned by modulating the voltage across the PZT squeezing or stretching the crystal.

The laser crystal is specially ground containing all the elements of the laser cavity taking advantage of total internal reflection.

The magnet functions as an optical diode to assure a unidirectional light path.

DESCRIPTION

The experiment consists of 3 NPROs in heterodyne pairs using photodetection for examination and recording of difference signals.

The self contained unit will be stored in a Shuttle mid-deck locker. The experiment timeline takes about an hour, a warm-up period followed by short data taking periods. Data is stored in solid state memory for dump after the return flight.
Out-Reach SENSORS AND INFORMATION SYSTEMS

Sensors

Stanford University/NASA Laser In-Space Technology Experiment (SUNLITE)

Robert L. Byer, Stanford University
A. Martin Buoncristiani, Langley Research Center (National Research Council)

SCHEDULE

Calendar Year | 1989 | 1990 | 1991 | 1992
--- | --- | --- | --- | ---
Conceptual Dsg Rev Workshop | | | | 
Breadboard | | | | 
Prelim Dsg Rev Brassboard | | | | 
Critical Dsg Rev | | | | 
KC135 Flight Flight Fabrication | | | | 
Available for Flt | | | | 
EXPERIMENT OBJECTIVE

- Define specific in-space technology experiment(s) to identify, evaluate, and develop effective fire suppressants for the microgravity environment. Fire suppression technology is broadly defined as the technology both to prevent ignition through atmosphere control and to extinguish smoldering and flaming combustion once initiated.

BACKGROUND/TECHNOLOGY NEED

- A preliminary analysis by Battelle of the combustion situation under microgravity conditions revealed that spacecraft fire suppression may be more difficult than that for 1-G fires on Earth. Specifically, fire suppressants that are routinely and rather universally used on Earth may not be as effective, or may even be ineffective, in spacecraft fire situations.

- Because there may not be proven techniques developed to extinguish fires in space, crews and hardware of future manned space missions may be at risk.
<table>
<thead>
<tr>
<th>IN-SPACE SYSTEMS</th>
<th>Out-Reach</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maintenance, Repair, and Fire Safety</td>
<td>Out-Reach</td>
</tr>
<tr>
<td><strong>Definition of Experiments to Investigate Fire Suppressants in Microgravity</strong></td>
<td></td>
</tr>
<tr>
<td>Dr. James J. Reuther</td>
<td></td>
</tr>
<tr>
<td>Battelle Columbus Division</td>
<td></td>
</tr>
<tr>
<td>Contract: NAS3-25362, Lewis Research Center, Mr. Robert Friedman</td>
<td></td>
</tr>
</tbody>
</table>

**EARLY PROGRESS**

- Determination of the extent to which the effectiveness and/or mode of action of terrestrial fire suppressants are altered by the spacecraft environment.

- Formulation of guidelines with which to identify terrestrial agents that have the potential for acting as effective spacecraft fire suppressants.

**EXPERIMENT DESCRIPTION**

- The apparatus will provide a means by which to simulate various flame situations representative of plausible spacecraft fire scenarios after which various means will be used to deliver and evaluate the suppression effectiveness of various agents.

**ZERO GRAVITY COMBUSTION**

- GASES
  - Earth Gravity
  - Zero Gravity

- SOLIDS
  - Earth Gravity
  - Zero Gravity
SUMMARY/CONCLUDING REMARKS

- The mission of the project is to identify those technologies that quickly and permanently extinguish spacecraft fires, with the action taken being no more life or mission threatening than the fire itself.

PROJECT SCHEDULE

1. TASK 1 APPROVAL
2. TASK 2 APPROVAL
3. FINAL REPORT TO NASA REVIEW
**EXPERIMENT OBJECTIVE**

Expand the understanding of processes and phenomena important to the assessment of risks associated with fires in spacecraft.

- Observe the mechanisms of flame propagation between two solid objects and the competing processes of detection and suppression.
- Observe the generation, motion, and adverse impact of combustion products.
- Contribute to the development of probabilistic risk assessment methodology for spacecraft.

**BACKGROUND**

- Quantitative risk assessment is playing an increasingly important role in identifying significant risks and justifying mitigating actions (see also NMI 8070.4)
- PRA methodology quantifying the fire risk in nuclear power plants has been developed at UCLA.

**TECHNOLOGY NEEDS**

- To integrate basic knowledge acquired in previous microgravity research to investigate system level phenomena
- To expand basic fire-safety knowledge

**OUTLINE OF FIRE RISK ASSESSMENT**

1. Identification of "critical" locations and assessment of the frequency of fires.
2. Estimation of fire growth times and competing detection and suppression times.
   
   \[ Q = Fr\{T_G < T_D + T_S | \text{FIRE}\} \]

3. Response of the system.
   
   \[ 1 + 2 + 3 => \lambda_D = \Sigma \lambda_j Q_D | j Q_D | D, J \]
## Preliminary Schematic

![Preliminary Schematic Diagram](image)

## Program Master Schedule

<table>
<thead>
<tr>
<th>MILESTONES</th>
<th>1988</th>
<th>1989</th>
<th>90</th>
<th>91</th>
<th>92</th>
<th>93</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>DEFINITION</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Major Milestones</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Review STS, St. &amp; SS Configs &amp; Interface Reqmts</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Review Microgravity Fire Research</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Mission Science Reqmts</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• System Reqmts</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Detailed Experiment Definition</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>DEVELOPMENT</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Detailed Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Fab, Assy. Test</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Mission &amp; Flight Ops</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Final Report</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

As of 06 Dec 88

**Exhibit**

1. **IN-SPACE SYSTEMS**
   - Out-Reach
   - Maintenance, Repair, and Fire Safety
   - Risk-Based Fire Safety Experiment Definition

2. **Out-Reach**
   - University of California, Los Angeles
   - Contract: NAS8-37750, Marshall Space Flight Center, J. Austin

3. **Program Master Schedule**

<table>
<thead>
<tr>
<th>MILESTONES</th>
<th>1988</th>
<th>1989</th>
<th>90</th>
<th>91</th>
<th>92</th>
<th>93</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>DEFINITION</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Major Milestones</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Review STS, St. &amp; SS Configs &amp; Interface Reqmts</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Review Microgravity Fire Research</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Mission Science Reqmts</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• System Reqmts</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Detailed Experiment Definition</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>DEVELOPMENT</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Detailed Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Fab, Assy. Test</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Mission &amp; Flight Ops</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Final Report</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**As of 06 Dec 88**
EXPERIMENT OBJECTIVE

To develop a fundamental understanding of the heat transfer, mass transfer and fluid flow processes that occur during plasma arc welding in a low-gravity and low pressure environment. To develop correlations with analytical models. This understanding will be applied to:

- The identification of the optimal parameters for plasma arc welding in space.
- The design of low weight task specific plasma arc welding systems.

BACKGROUND/TECHNOLOGY NEEDS

- Computer model of the plasma arc welding process for the identification of welding parameters.
- Analytical and experimental method for the analysis of the experimental data retrieved from the in-space experiment.
- Experimental systems for verification of the above methods in ground-based laboratories.

COMPUTER MODEL

A finite element computer model will provide the ability to determine the shape of the liquid region and the temperature distribution in the solid region as a function of gravity and air pressure.

ASSUMPTIONS USED IN THE STUDY INCLUDE:

- The process is quasi-stationary as viewed in a frame of reference moving with the plasma-torch.
- The molten liquid is Newtonian and incompressible.
- The heat transfer and fluid flow correlations for the flow of plasma are taken from known experimental data for flow of plasmas in tubes.
- Material properties are temperature dependent.
<table>
<thead>
<tr>
<th>Out-Reach</th>
<th>IN-SPACE SYSTEMS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Out-Reach</td>
<td>Materials Processing</td>
</tr>
</tbody>
</table>

**Plasma Arc Welding In Space**  
Boris Rubinsky  
University of California, Berkeley  
Contract: NAS1-18686, Langley Research Center, Dr. John Buckley

**Velocity and temperature distributions in the molten pool, U = 0.5 mm/sec**

![Diagram showing velocity and temperature distributions in the molten pool](image)

**Temperature distribution in the solid**  
U = 0.5 mm/sec

![Diagram showing temperature distribution in the solid](image)
ANALYTICAL/EXPERIMENTAL METHOD FOR DATA ANALYSIS

AN INVERSE FINITE ELEMENT COMPUTER PROGRAM WILL PROVIDE
THE ABILITY TO DETERMINE THE TEMPERATURE FIELD AND THE
POSITION OF THE SOLID-LIQUID INTERFACE DURING WELDING USING
CONTINUOUS TEMPERATURE AND HEAT FLUX MEASUREMENTS TAKEN ON
THE OUTER SURFACE OF THE WORKPIECE, AWAY FROM THE WELD REGION.
THE METHOD COULD ALSO PROVIDE REAL TIME CONTROL OVER THE
QUALITY OF THE WELDING PROCESS.

ON GROUND LABORATORY EXPERIMENTS

THE DIRECT AND INVERSE FINITE ELEMENT COMPUTER CODES
WILL BE VERIFIED USING A COMMERCIAL PLASMA ARC WELDING SYSTEM
THROUGH:

- THERMOCUPTURE TEMPERATURE MEASUREMENTS.
- HIGH POWER FLASH X-RAY PHOTOGRAPHY.
- METALURGICAL CROSS SECTIONS.

<table>
<thead>
<tr>
<th>Development of Direct Finite Element Code</th>
<th>Development of Inverse Finite Element Code</th>
<th>Design of Experiment to Verify Inverse Code and Direct Code</th>
<th>Verification of Inverse and Direct Code</th>
<th>Compatibility Design Constraints with Spacecraft</th>
<th>Design of System for Experiment in Space</th>
</tr>
</thead>
<tbody>
<tr>
<td>JUL 88</td>
<td>OCT 88</td>
<td>MAR 88</td>
<td>JUL 88</td>
<td>OCT 88</td>
<td>MAR 88</td>
</tr>
</tbody>
</table>
**Out-Reach**

**IN-SPACE SYSTEMS**

**Materials Processing**

*Extra-Vehicular Activity Welding Experiment*

Gary Schnittgrund
Rockwell International Corporation, Rocketdyne Division

---

**Experiment Objective**

Generate data to assess flight crew capability to perform on-orbit EVA welding operations

- Investigate equipment requirements
- Investigate crew/equipment & crew/process interaction
- Investigate weld automation
- Evaluate process/material compatibility
- Define critical human factors

---

**Background**

- Soviets welding in space since 1965
- Welding in vacuum demonstrated by Rocketdyne
- "Enabling" for Pathfinder missions

**Technology Needed**

- Welding is a versatile joining technique for diverse materials
- Welding applicable to contingency repair or in-space construction

**Need for space experiment**

- Extended duration of space flight gives environment integrated weld data
- Welding process sensitive to human factors
Out-Reach Experiment Description

**Issues**
- Equipment requirements
- Process interactions
- Materials effects
- Human factors

**On-Orbit Tasks**
- Manual GTA welding
- Semiautomatic in-place GTA tube welding
- Various materials, configurations, orientations, parameters

**Baseline Data**
- KC-135 low-G tube welding
- Gas can (G-169) tube welding experiment
- Pressure-suited manual welding tests
- KC-135 manual welding tests
- Laboratory process development
Extravehicular Activity Welding Experiment

Gary Schnittgrund
Rockwell International Corporation, Rockwell Division
Extra-Vehicular Activity Welding Experiment
Gary Schnittgrund
Rockwell International Corporation, Rocketdyne Division

Rocketdyne Vacuum GTAW Torch

Argon

Hollow Electrode

Argon in

Automatically Pulsed Single Pass
Full Penetration Vacuum GTA Weld
Material 304SS

6.9X Mag. 6.9X Mag. 9X Mag.

Appearance of Top Bead Appearance of Bottom Bead Cross-Section

Top Width = 0.229 in., Bottom Width = 0.090 in.
<table>
<thead>
<tr>
<th>Experiment Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Out-Reach</strong></td>
</tr>
<tr>
<td>IN-SPACE SYSTEMS</td>
</tr>
<tr>
<td>Materials Processing</td>
</tr>
<tr>
<td><strong>Extra-Vehicular Activity Welding Experiment</strong></td>
</tr>
<tr>
<td>Gary Schnittgrund</td>
</tr>
<tr>
<td>Rockwell International Corporation, Rocketdyne Division</td>
</tr>
<tr>
<td>KC-135 Welding Flight Experiments</td>
</tr>
<tr>
<td>Rockwell International/Cal Poly Gas Can Welding Experiment</td>
</tr>
</tbody>
</table>
**Out-Reach**

**IN-SPACE SYSTEMS**

**Material Processing**

*Extra-Vehicular Activity Welding Experiment*

Gary Schnitigund

Rockwell International Corporation, Rocketdyne Division


<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>KC-135 Flight Experiments</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Vacuum Welding</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Gas Can Experiment</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Definition</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Technical Requirements and Objectives</td>
<td>⬜</td>
<td>⬜</td>
<td>⬜</td>
<td>⬜</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Equipment Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Work Station Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Human Factors Evaluation</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Flight Experiment Development</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Detailed Equipment Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Equipment Fabrication and Checkout</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Training and Baseline Data Acquisition</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Payload Integration and Checkout</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>First Flight</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Data Analysis</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Master Schedule

- 1988: Initial planning and concept development
- 1989: Detailed design and preliminary testing
- 1990: Prototype fabrication and testing
- 1991: Flight experiment development
- 1992: Flight experiment integration and checkout
- 1993: Flight experiment integration and launch

**Out-Reach**
OUT-REACH IN-SPACE SYSTEMS
Materials Processing

**On-Orbit Electron Beam Welding Experiment**
William Hooper
Martin Marietta Aerospace, Manned Space Systems

**EXPERIMENT OBJECTIVE**

Design an experiment that will demonstrate that the electron beam process can safely produce high integrity welds in the space environment.

Specifically address the experiment design to the repair of micrometeoroid strike damage to structural panels and the type of alloy specified for the space station structures.

Provide for correlation between space-derived and ground-based data.

**BACKGROUND**

Prior Work
- D-56R: On-Orbit Welding and Cutting
- M-42R: Long Term Space Exposure of Metals
- M-01S: Space Debris and Meteoroid Protection
- M-05S: Manned Spacecraft EVA Repair

Demonstrates
- Long term risk of penetration damage
- Type of damage
- Compatibility of EB welding process with EVA repair

**TECHNOLOGY NEED**
- Cannot predict EB weld bead push-through capacity in absence of gravity effects
- Solidification characteristics of weld bead metal in microgravity and effect on weld properties
INSPACE SYSTEMS
Materials Processing

On-Orbit Electron Beam Welding Experiment

William Hooper
Martin Marietta Aerospace, Manned Space Systems

EXPERIMENT DESCRIPTION

- SIX WELD PANEL CONFIGURATIONS AND WELD SCHEDULES ARE DEVELOPED
- ONE SET OF SIX PANELS IS WELDED IN GROUND-BASED EXPERIMENT
- AN IDENTICAL SET IS MOUNTED FOR ONORBIT EXPERIMENT
- ONORBIT ENCLOSURE IS PORTED TO SPACE: THE AUTOMATED CYCLE OF WELDS IS REPEATED
- THE OPTIONAL HAND-HELD WELDING EXPERIMENT IS COMPLETED
- PROPERTIES OF ONORBIT WELDED AND GROUND-LEVEL WELDED PANELS ARE COMPARED

CAROUSEL FOR 6 WELD PANELS, INDEXES TO 6 FIXED STATIONS
INSPACE SYSTEMS
Materials Processing

On-Orbit Electron Beam Welding Experiment
William Hooper
Martin Marietta Aerospace, Manned Space Systems

EXPERIMENT ENCLOSURE

ELECTRONICS AND CONTROLS ENCLOSURE

ED WELDING GUN
- 60 LBS.
- 8 FT. CABLE (2)

EXPERIMENT ENCLOSURE (150 LBS.)
MANUAL WELD PANEL (30 LBS.)
ELECTRONICS AND CONTROLS ENCLOSURE (150 LBS.)
- POWER SUPPLY/TRANSFORMER
- CONTROL COMPUTER

EXPERIMENT IMPLEMENTATION PLAN

STUDY TASKS
7) FUNCTIONAL DIAGRAM
8) IMPLEMENTATION PLAN & COSTS

CONCEPTUAL DESIGN STUDY TASKS
- MONTHLY REPORTS
- PROGRESS REVIEWS

MASTER SCHEDULE

<table>
<thead>
<tr>
<th>1988</th>
<th>1989</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>0 11</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
</tbody>
</table>
OUT-REACH IN-SPACE SYSTEMS
Laser Welding in Space
Dr. Gary L. Workman and Dr. William F. Kauker
University of Alabama in Huntsville
Contract: NAS9-17962, Johnson Space Center, Jay Bennett

EXPERIMENT OBJECTIVES

To develop a conceptual understanding of the significant characteristics of laser welding for space applications, including the following:

Operational characteristics of a laser welder in a micro gravity environment.

Correlations between ground-based welds and those performed in low-gravity.

This understanding will be used to develop an optimal design for a space based laser welding facility which can be used for assembly or repair of space structures.

BACKGROUND/TECHNOLOGY NEEDS

Need for In-flight Experiment
To develop experience in welding operations in Space where processes and materials can behave differently
To evaluate suitability of laser power and beam delivery systems for Space Systems operation.
To determine overall man-process interactions and required level of automation for operations aboard a space structure.

Essential Technology Advancements
High efficiency solid-state lasers.
Alternate sources of pumping. (solar)
Robotized fiber-optic beam coupling system.
Demonstrations of materials joining capability other than metals.

EXPERIMENT DESCRIPTION

The space based laser welding facility will be used to weld tubular components using a solid-state laser with a fiber-optic beam delivery system. Variable weld parameters will include weld material, laser energy, and weld speed. Temperature measurements adjacent to the weld seam will be used to correlate processing parameters of each sample. Ground based metallurgical and weld strength analysis will be used to determine consistency in the overall weld process and the reliability of the space based welds.
Out-Reach

IN-SPACE SYSTEMS
Materials Processing

Laser Welding in Space
Dr. Gary L. Workman and Dr. William F. Kaukler
University of Alabama in Huntsville
Contract: NAS9-17962, Johnson Space Center, Jay Bennett

Current version of the KC-135 laser welding experimental apparatus.

Sample chamber under vacuum

Laser welding experiments as performed here on the NASA KC-135 are used to obtain information about weld solidification and heat transfer in a microgravity environment.
SUMMARY

Laser welding experiments have been performed on the KC-135 aircraft resulting in a preliminary definition for a space-based welding facility using a solid-state laser with fiber-optic delivery system and solar pumping for an alternate source of energy.

SCHEDULE

<table>
<thead>
<tr>
<th>TASK</th>
<th>88</th>
<th>89</th>
<th>90</th>
<th>91</th>
<th>92</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ground Based Experiment Definition</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Laser Sources Evaluation</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Determine Weld Parameters</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Metallurgical Analysis</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>KC-135 Experimentation</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Space Experiment Definition</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Space System Design</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Fabrication</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Flight Test and Qualification</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Space Based Experiments</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Current Contract</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Future Efforts</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
**EXPERIMENT OBJECTIVE**

DEMONSTRATE THE FEASIBILITY OF A NEW FLOAT ZONE REFINING PROCESS THAT TAKES ADVANTAGE OF MICROGRAVITY TO PRODUCE DEFECT-FREE SEMICONDUCTORS.

- INVESTIGATE THE BENEFITS OF CONTAINERLESS PROCESSING ON GALLIUM ARSENIDE CRYSTAL QUALITY.

- DEMONSTRATE THE FEASIBILITY OF USING A FREE SURFACE ENCAPSULANT IN MICROGRAVITY.

- TEST THE STABILITY OF AN ENCAPSULATED GALLIUM ARSENIDE FLOATING ZONE.

**BACKGROUND**

COMPOUND SEMICONDUCTORS PLAY AN INCREASINGLY IMPORTANT ROLE IN AEROSPACE TECHNOLOGY.

- HIGH SPEED COMPUTERS
- SOLID STATE LASERS
- RADIATION HARDENED ELECTRONICS
- OPTICAL DETECTORS

**TECHNOLOGY NEED**

- GROWING CRYSTALS OF COMPOUND SEMICONDUCTORS IS DIFFICULT IN THE PRESENCE OF GRAVITATIONAL EFFECTS.

- CONTAINER WALLS INTRODUCE CRYSTAL STRAIN AND CHEMICAL CONTAMINANTS.

- HIGH DENSITY IC'S REQUIRE LOW DOPANT CONCENTRATIONS: LIQUID ENCAPSULATION PREVENTS CONTAMINATION FROM FURNACE COMPONENTS.

**NEED FOR SPACE EXPERIMENT**

- GALLIUM ARSENIDE CANNOT BE FLOAT ZONE PROCESSED IN GRAVITY.

- FREE SURFACE ENCAPSULANT WOULD FLOW IN GRAVITY.
**IN-SPACE SYSTEMS**

**Materials Processing**

**Liquid Encapsulated Float Zone Refining of Gallium Arsenide**

Edward Barocela

McDonnell Douglas Astronautics Company

Contract: NAS3-25360, Lewis Research Center, Arnon Chait

---

**EXPERIMENT DESCRIPTION**

- A rod of gallium arsenide is coated with a thin layer of boron trioxide encapsulant.

- The sample rod is sealed into a quartz ampoule, which is filled with dry nitrogen or argon.

- The sample is float zone processed in microgravity.

- Thermal and optical observations are made on orbit to document the process. These observations will be analyzed to assess the behavior of the combined liquid encapsulant-molten semiconductor system and the solid-liquid interface.

- The sample will be compared on the ground with terrestrially grown material.
IN-SPACE SYSTEMS
Materials Processing

Liquid Encapsulated Float Zone Refining of Gallium Arsenide
Edward Barocela
McDonnell Douglas Astronautics Company
Contract: NAS3-25360, Lewis Research Center, Amon Chait

THERMAL MODELING - NEAR TERM TASKS

• Refine baseline operating parameters to optimize:
  - Electrical power consumption
  - Peak temperature
  - Thermal gradients

• Establish requirements for coating process by investigating the effects of:
  - Different encapsulant thicknesses
  - Encapsulant thickness nonuniformities
  - Pinholes in the encapsulant

GALLIUM ARSENIDE CRYSTAL GROWTH:
1.07 μM BORON TRIOXIDE COATING
HEAT FLUX = 25 W/CM²
TIME = 1800 SEC.
EMISSIVITY = 100%
HEATER BEGINS TO MOVE AT T = 298.63 SEC
INSTEP88 Workshop
OAST Technology For the Future
Part 1: Executive Summary & Experiment Descriptions

Out-Reach
IN-SPACE SYSTEMS
Materials Processing

**Liquid Encapsulated Float Zone Refining of Gallium Arsenide**
Edward Barocela
McDonnell Douglas Astronautics Company
Contract: NAS3-25360, Lewis Research Center, Amon Chait

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>QTR</td>
<td>1</td>
<td>2</td>
<td>3</td>
<td>4</td>
<td>1</td>
</tr>
<tr>
<td>TECHNICAL REQUIREMENTS AND OBJECTIVES</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>HARDWARE CONCEPT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PROJECT PLAN</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>SYSTEM DESIGN</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FABRICATION AND ASSEMBLY</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TEST AND FLIGHT QUALIFICATION</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PAYLOAD INTEGRATION AND CHECK OUT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FIRST FLIGHT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

222
**Experiment Descriptions**

<table>
<thead>
<tr>
<th>Out-Reach</th>
<th>IN-SPACE SYSTEMS</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Workshop</strong></td>
<td><strong>Materials Processing</strong></td>
</tr>
<tr>
<td><strong>OAST Technology</strong></td>
<td><strong>Vapor Crystal Growth Technology</strong></td>
</tr>
<tr>
<td><strong>For the Future</strong></td>
<td><strong>Franz E. Rosenberger and Francis C. Wessling</strong></td>
</tr>
<tr>
<td><strong>Part 1: Executive Summary &amp; Experiment Descriptions</strong></td>
<td><strong>University of Alabama Center for Microgravity and Materials Research (support by Boeing)</strong></td>
</tr>
<tr>
<td><strong>Contract: NAS3-25361, Lewis Research Center, Walter Duval</strong></td>
<td></td>
</tr>
</tbody>
</table>

### EXPERIMENT OBJECTIVE

Develop a novel vapor growth technology that results in increased flexibility in the control of the process parameters for high quality crystal growth in space and on earth.

Emphasis on:

- Advantageous crystal nucleation and growth location
- Growth of a controlled number (preferably one) of single crystals
- Reduced mechanical interaction between ampoule and crystal, in particular during cooldown
  
  ➡️ higher structural quality
- Continuous removal of volatile impurities
  
  ➡️ higher purity
- Increased growth rates

### BACKGROUND/TECHNOLOGY NEED

NASA and ESA-sponsored researchers, and workers in the USSR have been conducting vapor growth experiments in space.

Crystal growth from vapors has many advantages over other techniques.

All low gravity vapor growth experiments have been carried out in closed ampoules and traditional heating geometries, thus resulting in

- little control of number of size of crystals grown,
- relatively low growth rates

  ➡️ particularly important in view of limited experiment time in space

Despite these shortcomings, vapor growth in space has yielded very promising results.

To take full advantage of microgravity conditions for vapor crystal growth a novel technology is needed.
### Experiment Description

**Essential Elements of Congruent (Diffusionless) Growth Technique:**

- **Traveling Furnace**
- **Compacted Source**
- **Vacuum**
- **Heat Elements**
- **Capillary**
- **Initial Fill**
- **Leak**
- **Viewing Port**
- **Seed**

#### Experiment Details:

- **Semi-closed (leaky) ampoule**
- **Predetermined (viscous) transport rates and minimization of rate fluctuations**
- **No sealing of ampoule required**
- **Initial purification of source material**
- **Continuous purification, but possible stoichiometry shifts**
- **Predetermined crystal location, size, and orientation**
- **Observability and, hence, controllability of seeding**
- **Temperature profile readily adjustable and, hence, expedient determination of optimum growth conditions**
### IN-SPACE SYSTEMS
#### Materials Processing

**Vapor Crystal Growth Technology**

Franz E. Rosenberger and Francis C. Wessling

University of Alabama Center for Microgravity and Materials Research (support by Boeing)

Contract: NAS3-25361, Lewis Research Center, Walter Duval

---

#### TASK SCHEDULE/PRODUCTS

<table>
<thead>
<tr>
<th>Experiment Technical Requirements</th>
<th>'88</th>
<th>'89</th>
<th>'90</th>
</tr>
</thead>
<tbody>
<tr>
<td>Definition of Experiment Requirements</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Choice of Specific Crystal Material</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Supporting Research</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Modelling of heat transfer, thermometry</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Modelling of vapor transport conditions</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Prototype System and Experiments</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Component design, building and/or procurement</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>System assembly and testing</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Development of (semi-automated) growth procedure</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Technical Requirements Report</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

#### EXPERIMENT CONCEPTUAL DESIGN (For Phase II)

- Definition of Specific In-Space Technology Experiment
- Identification of Support Equipment Requirements
- Hardware Accomodation Study
- Engineering Trade Study
- Functional Diagram

---

#### IMPLEMENTATION PLAN AND COST ESTIMATE (For Phase II)

---

#### REVIEWS AND REPORT

- Quarterly Technical Status Reports
- Semiannual Progress Report
- Final Report (principal deliverable)

- Δ  Δ  Δ

#### MEETINGS

- OAST IN-STEP (Atlanta)
- Review Technical Requirements (UAH)
- Review Hardware Concept (LeRC)
- Final Review (LeRC)

- O  O  O
HUMANS IN SPACE
Human Performance

Enhancement of In-Space Operations Using Spatial Perception Auditory Referencing (SPAR)
Dr. Robert H.I. Blanks, Dr. Job P. Jones, and Dr. Yasuhiro Torigoe
University of California, Irvine
Contract: NAS2-12834, Ames Research Center, Elizabeth M. Wenzel

OBJECTIVES:

DETERMINE THE FEASIBILITY OF USING DIRECTIONALLY CODED AUDITORY TRANSMISSION FOR THE ENHANCEMENT OF IN-SPACE OPERATIONS BY PROVIDING DIRECTIONALLY CODED SOUND FOR:

1) ADVANCED LIFE SUPPORT
   * DIRECTIONALLY CODED PROXIMITY / THREAT ALERT
   * AUDITORY DISPLAY OF AIR LOCKS, CO-WORKERS EVA, ROBOTICS AND PARTS
   * IMPROVED ASTRONAUT VIGILANCE, JUDGEMENT AND WORK EFFICIENCY EVA

2) DIAGNOSTIC AND DATA SYSTEM (ALGORITHMS)
   * KINEMATIC REFERENCING OF EVA ASTRONAUTS, ROBOTS AND MATERIALS
   * PROVIDE DIRECTIONAL INFORMATION TO SAFETY OFFICERS
     - ON BOARD
     - SPACE STATION CONTROL FACILITY

3) LIFE SUPPORT AND SAFETY
   * TREATMENT STRATEGY FOR SPACE ADAPTATION SYNDROME

4) OTHER BENEFITS
   * IMPROVED QUALITY OF AUDITORY COMMUNICATIONS
   * CUSTOMIZED ENTERTAINMENT FOR ASTRONAUTS

BACKGROUND:

* NATURAL SOUND CONVEYS THE DIRECTION, DISTANCE AND *SIZE* OF THE SOURCE

* DIRECTIONAL CUES ARE LOST WHEN SOUND IS HEARD OVER EARPHONES

* SOUND CAN BE ELECTRONICALLY PROCESSED, FOR TRANSMISSION OVER EARPHONES, TO REINSTATE DIRECTIONAL CUES

* SOUND PROCESSING CAN BE:
  VIRTUAL (E.G., VOICES HEARD AS COMING FROM THE DIRECTION OF PERSON SPEAKING)
  CODED (E.G., TONES INDICATING LOCATION OF AIRLOCKS, ROBOTS, PARTS OR GEOCENTRIC REFERENCE)

* MINIMUM TRAINING IS REQUIRED TO EXTRACT DIRECTIONAL CUES FROM PROCESSED SOUND TRANSMISSIONS
HUMANS IN SPACE

Human Performance

Enhancement of In-Space Operations Using Spatial Perception Auditory Referencing (SPAR)

Dr. Robert H.L Blanks, Dr. Jole P. Jones, and Dr. Yasuhiro Torigoe
University of California, Irvine
Contract: NAS2-12834, Ames Research Center, Elizabeth M. Wenzel

TECHNOLOGY REQUIRED FOR SOUND LOCALIZATION:

- KINEMATIC REFERENCING (SENSOR SYSTEMS) ASTRONAUT BODY AND HEAD POSITION, ROBOTS AND PARTS
- OPTIMUM SOUND SYSTEM, HELMET AND HEADPHONE DESIGN
- INTERFACE TO COMPUTER SYSTEMS/COMMUNICATIONS

NEED FOR SPACE EXPERIMENT:

- CONSTRUCTION AND MAINTENANCE OF SPACE STATION requires unprecedented amounts of EVA activity
- THE BENEFITS OF DIRECTIONALLY CODED SOUND ON ASTRONAUT PERFORMANCE EVA (IMPROVED SAFETY, WORK EFFICIENCY, VIGILANCE) are best assessed operationally and under microgravity conditions
- SPACE ADAPTATION SYNDROME (SAS) will be a problem given frequent crew changes for construction and servicing of the station
- TREATMENT STRATEGIES FOR SAS must ultimately be tested in microgravity of space

THREE DIMENSIONAL REFERENCING OF ASTRONAUT HEAD POSITION & ORIENTATION RELATIVE TO SPACECRAFT
Achieved by:
1) ON-BOARD INERTIAL NAVIGATION SYSTEMS
2) UPGRADE OF "COMMON TRACKING SYSTEM" TO INCLUDE ASTRONAUT POSITION & ORIENTATION
3) NEW APPLICATION FOR LOCAL NAVIGATION SYSTEMS
   - LASER DOCKING SYSTEM
   - FIBER OPTIC INERTIAL GYROSOPES

STAND ALONE HARDWARE/FIRMWARE SYSTEM
SINGLE BOARD - MULTIPROCESSOR

EVA: SMALL CONTROLLER BOARD ON EMU

IVA/GROUND CONTROL: INTERFACE/ADD ON TO ON-BOARD COMPUTER SYSTEM
FULL COMPATIBILITY WITH ON-BOARD/GROUND CONTROL SYSTEMS

DISPLAY MODES 1 & 2 could be achieved with fixed speaker in EMU helmet or via ear inserts.
3-D SOUND (3 ABOVE) requires fixed multiple speakers or head phones

1) WARNING SIGNALS
   (O₂ LEVELS, PROXIMITY ALERT)
2) ACOUSTICAL POINTING
   (AIRLOCKS, PARTS, ETC.)
3) 3-D SOUND
   (CODED TRANSMISSIONS BETWEEN ASTRONAUTS AND SAFETY OFFICER)

SIMULTANEOUS VISUAL DISPLAY FOR BENEFIT OF ON-BOARD SAFETY OFFICER

AUDITORY DISPLAY OF:
## HUMANS IN SPACE
### Human Performance

**Enhancement of In-Space Operations Using Spatial Perception Auditory Referencing (SPAR)**

Dr. Robert H. Blanks, Dr. Joe P. Jones, and Dr. Yasuhiro Torigoe  
University of California, Irvine  
Contract: NAS2-12834, Ames Research Center, Elizabeth M. Wenzel

### SCHEDULE

<table>
<thead>
<tr>
<th>MONTHS</th>
<th>1988</th>
<th>1989</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. EVALUATE COMMERCIAL SOUND SYSTEM</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2. EVALUATE SPAR TECHNOLOGY</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3. EVALUATE EXISTING SENSOR TECHNOLOGY</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4. BUILD AND ASSEMBLE PROTOTYPE</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5. SOFTWARE DEVELOPMENT</td>
<td></td>
<td></td>
</tr>
<tr>
<td>6. BENCH TEST 4 &amp; 5 ABOVE FOR EXPERIMENTS</td>
<td></td>
<td></td>
</tr>
<tr>
<td>7. PSYCHOACOUSTIC EXPERIMENTS</td>
<td></td>
<td></td>
</tr>
<tr>
<td>8. UNDERWATER ORIENTATION EXPERIMENTS</td>
<td></td>
<td></td>
</tr>
<tr>
<td>9. MODIFY PROTOTYPE (UNDERWATER EXP.)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>10. PREPARE DOCUMENTATION TO NASA</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

228
HUMANS IN SPACE
Closed-Loop Life Support

Definition Of a Microbiological Monitor for Application in Space Vehicles
Melvin V. Kilgore, Jr., and Dr. Robert J. Zahorchak
University of Alabama in Huntsville, Consortium For the Space Life Sciences
Contract: NAS9-17963, Johnson Space Center, Dr. Duane Pierson

EXPERIMENT OBJECTIVES:

PHASE I

- Identify and Evaluate current methodologies for microbial monitoring
- Determine the Feasibility of Developing the Hardware for Space Applications
- Develop a Method for the Application of Microbiological Monitoring in Space
- Develop a Conceptual Design and Functional Diagram
- Prepare a Cost Estimate Regarding the Development Phase
- Define the Experimental Parameters to be Evaluated on Future STS Missions

PHASE II

- Thorough Evaluation of the Candidate Methodologies
- Development of Prototype Hardware
- Extensive Ground Based Evaluation of Hardware and Methodology
- In Flight Experiments

BACKGROUND

- Necessity for Microbiology Monitoring
  Closed System Environment
  Increased Duration Missions
  Increased Distances
  Potential for Immuno Compromised Crew Experiments and Hardware

- Unique Requirements
  Microgravity Conditions
  Multiple Sample Handling
  Power, Weight, Volume
  Analysis Time

- Specifications
  Water
  Air
  Surfaces

TECHNOLOGY NEED

- No Commonly used Near Real Time Monitor Currently Available

JUSTIFICATION

- Assurance of Performance
- Bacterial Physiology Significantly Different in Space
# HUMANS IN SPACE

**Closed-Loop Life Support**

**Definition Of a Microbiological Monitor for Application in Space Vehicles**

Melvin V. Kilgore, Jr., and Dr. Robert J. Zahorchak  
University of Alabama in Huntsville, Consortium For the Space Life Sciences  
Contract: NAS9-17963, Johnson Space Center, Dr. Duane Pierson

## Experiment Descriptions

### EXPERIMENT DESCRIPTION:

**PHASE I**
- Definition and Design of a Near Real-Time Microbiological Monitor for Space Applications

**PHASE II**
- Development and Evaluation of Performance of a Microbiological Monitor Under Microgravity and Other Conditions Imposed by Space

### CRITERIA FOR FLIGHT EXPERIMENT

- Should Provide Information Required for the Development of a RTMM  
- Should Demonstrate Proof of Concept Under Microgravity Conditions  
- Should be Self Contained and Require Little Crew Support  
- Experimental Design Should be such that Results/Products can be Analyzed/Retrieved on the Ground

## Technical Approach

**METHOD EVALUATION AND TRADE STUDIES**

- Technical  
  - Primary
  - Sensitivity
  - Time
  - Maturity
  - Applications
- Secondary  
  - Engineering
  - Power
  - Weight
  - Volume
  - Expendables
- Feasibility  
  - Precision
  - Compatibility
  - Complexity
  - Development
- Cost

### Extensive Ground Based Evaluation of Methodology

**Development of Prototype and Ground Based Studies**

**Proof of Concept (In Flight)**

**Evaluation of Hardware (In Flight)**
CHARACTERISTICS OF A NEAR REAL TIME MICROBIOLOGICAL MONITOR

- It Should be Adaptable to Water, Air and Surfaces
- It Should be Reliable and Require Little Maintenance
- It Should be Rapid
- It Should be Self-Contained and Require Minimum Crew Support
- It Should provide for Crew and Ground Support Interactions
- It Should Lend itself to Improvements and Modifications toward both Quantitative and Qualitative Monitor
- It Should be ready for Incorporation Aboard SS Freedom

SUMMARY OF RESULTS

- Identified Approximately 30 Methodologies having Potential Application to Microbiological Monitoring
- Approximately One-third of these met the Primary Requirements
- Five Highest Candidates from Secondary Screening chosen for Further Evaluation
- Engineering Trade Studies Currently Underway
- Feasability Studies Currently Underway
- Conceptual Design and Functional Diagrams

SCHEDULE

<table>
<thead>
<tr>
<th>PHASE I</th>
<th>PHASE II</th>
</tr>
</thead>
<tbody>
<tr>
<td>J</td>
<td>A</td>
</tr>
<tr>
<td>A</td>
<td>C</td>
</tr>
<tr>
<td>S</td>
<td>C</td>
</tr>
<tr>
<td>C</td>
<td>S</td>
</tr>
<tr>
<td>D</td>
<td>A</td>
</tr>
</tbody>
</table>

- REVIEW
- DESIGN
- EVALUATION
- DEFINITION
- DEVELOPMENT
- FLIGHT EXPERIMENT
### EXPERIMENT OBJECTIVE (PHASE I)

The protocol of this experiment is designed to:

1) Measure solution monitoring capabilities under micro-gravity conditions

2) Measure solution composition control capabilities under micro-gravity conditions

3) Measure the capability of three different nutrient solution delivery/recovery systems to provide water and nutrients to higher plants under micro-gravity conditions

4) Measure the capability to condense, collect and recycle water vapor

**CELSS**: Controlled Ecological Life Support Systems
Design Of a Closed-Loop Nutrient Solution Delivery System for CELSS Application

Dr. Steven H. Schwartzkopf and Mr. Mel W. Oleson
Lockheed Missiles & Space Co., Boeing Aerospace Co.
Contract: NAS9-17981, Johnson Space Center, Dr. Halice S. Cullingford

CONCEPT DRAWING

PROJECT SCHEDULE
EXPERIMENT OBJECTIVE

Investigate ways a low-G environment may improve static feed water electrolysis (SFE) performance based on the hydrophobic/philic cell components, and fluid and thermal flows within the cell. The results will be used to improve static feed electrolysis process efficiency for:

- Life Support
- Propulsion
- EMU O₂ Bottle Recharge
- Energy Storage
- Industry

BACKGROUND/TECHNOLOGY NEED

- Hydrogen and Oxygen (H/O) are key to survival for humans in deep space
- Static Feed Electrolysis (SFE) is a key technology for H/O based economy
- Electrochemical processes are key to industrialization of space

![Diagram of water electrolysis process]

- Solar Power → SFE → H₂ & O₂ Storage → ECLSS → EVA → Propulsion → Electric Power → Users
- Recovered Water
**EXPERIMENT DESCRIPTION**

The experiment apparatus will provide the ability to study the two major processes which occur within an SFE. The first is the electrochemical process of water electrolysis in an alkaline electrolyte. The second process is the static addition of water to the cell and diffusion to the electrolysis site. The experiment will be self-contained except for a power supply requirement. Conventional instrumentation including pressure and temperature sensors will be required.

---

**Characteristics:**
- **Dimensions, in:** 9 x 16 x 20
- **Weight, lb:** 30
**HUMANS IN SPACE**

Closed-Loop Life Support

*Impact of Low Gravity on Water Electrolysis Operation*

Franz H. Schubert
Life Systems, Inc.

Contract: NAS9-17966, Johnson Space Center, Albert Behrend

---

**MASTER SCHEDULE**

<table>
<thead>
<tr>
<th>Year</th>
<th>00</th>
<th>01</th>
<th>02</th>
<th>03</th>
<th>04</th>
<th>05</th>
<th>06</th>
<th>07</th>
</tr>
</thead>
<tbody>
<tr>
<td>PDR</td>
<td>△</td>
<td></td>
<td></td>
<td></td>
<td>△</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDR</td>
<td>△</td>
<td></td>
<td></td>
<td></td>
<td>△</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Ship</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>△</td>
<td></td>
<td></td>
</tr>
<tr>
<td>KSC</td>
<td>△</td>
<td></td>
<td></td>
<td></td>
<td>△</td>
<td>△</td>
<td>△</td>
<td>△</td>
</tr>
</tbody>
</table>

(a) Experiment equipment can be refurbished (and modified, if necessary) and flown again to investigate other areas of electrochemical phenomena in low gravity.
HUMANS IN SPACE
Experiment Integration Process

Payload Integration Overview

Clarke R. Prouty
Goddard Space Flight Center, Special Payloads Division

In-Step Payload Milestones

Payload Requirements

Payload Requirements

- Experiment Description
- Hardware Description
- Operational Scenario

Support

- Mission Manager
- Safety Officer
- Integration
- Pre and Post Flight
HUMANS IN SPACE
Experiment Integration Process
Payload Integration Overview

Clarke R. Prouty
Goddard Space Flight Center, Special Payloads Division

Safety Review
And Certification

- Phase 0
  Informal - Identify Hazards

- Phase I
  Formal - Assess Preliminary Design
  Evaluate preliminary hazard controls,
  Verification methods

- Phase II
  Assess Final Design
  Concur on hazard controls,
  Safety verification Methods

- Phase III
  Formal - Approve Safety Assessment Report
  Review Safety Compliance Data Package
  Identify Open Safety Items

NASA Documents

- PIP
- PIP Annexes
- ICD
HUMANS IN SPACE
Experiment Integration Process

Payload Integration Overview

Clarke R. Prouty
Goddard Space Flight Center, Special Payloads Division

Payload Integration
Carrier

• Fit Checks and Assembly
Loading consumables

• Final testing

• System Checkout

Payload Integration
Carrier

• Mid-Deck Payloads
JSC

• CAP Payloads
GSFC, KSC

• Hitchhiker Payloads
GSFC, KSC

Payload Integration
Orbiter

• Mid-Deck Payloads
KSC

• CAP Payloads
KSC
Adapter Beam, MPRESS

• Hitchhiker Payloads
KSC
Adapter Beam, MPRESS
HUMANS IN SPACE
Experiment Integration Process
Payload Integration Overview

Clarke R. Prouty
Goddard Space Flight Center, Special Payloads Division
HUMANS IN SPACE
Experiment Integration Process

Payload Integration Overview

Clarke R. Prouty
Goddard Space Flight Center, Special Payloads Division
### Mission

- Launch
- On Orbit Operations
- POCC
- Landing
- Post Landing
### In-Step Payload Review and Integration Schedule

<table>
<thead>
<tr>
<th>Months</th>
<th>24</th>
<th>12</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Requirements</td>
<td>■</td>
<td>■</td>
<td></td>
</tr>
<tr>
<td>Safety Reviews</td>
<td>●</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Integration and Environmental Test</td>
<td>■</td>
<td>■</td>
<td></td>
</tr>
<tr>
<td>Post Flight Data Analysis</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Launch</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### In-Step Payloads The Future

- Current Flight Opportunities on Shuttle
- Will expand to Expendable Launch Vehicles
- Begin with available Shared Flights
- May Fund Dedicated OAST ELV
- Eventual Space Station Experiments
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
NSTS Integration and Operations

John C. O'Laughlin
Johnson Space Center, Spacelab & Middeck Integration Office

THE SPACE SHUTTLE SYSTEM PAYLOAD INTEGRATION PROCESS OVERVIEW

• NATIONAL SPACE TRANSPORTATION SYSTEM (NSTS) ORGANIZATION

• SPACE SHUTTLE SYSTEM DESCRIPTION

• PAYLOAD INTEGRATION PROCESS

• SCHEDULES/MANIFESTING

NSTS ORGANIZATION

• NASA HEADQUARTERS
  • OVERALL MANAGEMENT OF THE NSTS
  • MANAGES TRANSPORTATION SERVICES
    - FLIGHT SCHEDULING
    - REQUEST FOR FLIGHT ASSIGNMENT (NASA FORM 1628)
    - NEGOTIATION AND IMPLEMENTATION (POLICY, LEGAL, BUSINESS AND FINANCIAL ASPECTS)

• JSC
  • MANAGES THE DEVELOPMENT AND OPERATIONS OF THE SPACE SHUTTLE
  • MANAGES TECHNICAL INTEGRATION OF PAYLOAD INTO THE STS SHUTTLE
    - WORKING GROUPS FOR ENGINEERING AND OPERATIONS PLANNING
    - DEFINE INTERFACE AND OPERATIONAL REQUIREMENTS
    - IDENTIFY, DEFINE, AND INTEGRATE ENGINEERING TASKS
<table>
<thead>
<tr>
<th>HUMANS IN SPACE</th>
<th>Space Shuttle System Payload Integration Process</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>NSTS Integration and Operations</strong></td>
<td></td>
</tr>
<tr>
<td>John C. O'Laughlin</td>
<td>Johnson Space Center, Spacelab &amp; Middeck Integration Office</td>
</tr>
</tbody>
</table>

- **KSC**
  - Launch and Landing support for the Shuttle
  - Implements activities associated with preparing the Space Shuttle and its payloads
    - Payload processing
    - Launch support
    - Landing
    - Post-flight services

- **MSFC**
  - Responsible for managing the development of:
    - Solid Rocket Boosters
    - Space Shuttle Main Engines
    - External Tank
    - Spacelab Modules and P/II.1EIS

- **GSFC**
  - Responsible for managing:
    - Communications Network
    - Space Flight Tracking Data Network
    - Get Away Special (GAS) Program
    - Other small payload carrier programs
HUMANS IN SPACE
Space Shuttle System Payload Integration Process

NSTS Integration and Operations

John C. O’Laughlin
Johnson Space Center, Spacelab & Middeck Integration Office

SPACE SHUTTLE SYSTEM

- ORBITER
  - PAYLOAD BAY
  - HABITAT
- SOLID ROCKET BOOSTERS
- EXTERNAL TANK
- FLIGHT CREW
  - COMMANDER
  - PILOT
  - MISSION SPECIALIST (2 OR MORE)
PAYLOAD INTEGRATION PROCESS OVERVIEW

- FORMAL REQUEST FOR FLIGHT ASSIGNMENT (FORM 1628)
- DEVELOPMENT OF FORMAL AGREEMENTS
- IMPLEMENTATION OF AGREEMENTS
- PHASED SAFETY REVIEWS - FLIGHT AND GROUND EQUIPMENT
- LAUNCH
- POSTFLIGHT ACTIVITIES
PAYLOAD INTEGRATION PROCESS OVERVIEW

JOINT AGREEMENTS

CUSTOMER REQUIREMENTS

ANNEXES
1. PAYLOAD DATA
2. FLIGHT PLANNING
3. FLIGHT OPERATIONS SUPPORT
4. COMMAND & DATA
5. PAYLOAD OPER CONTROL CNTR
6. ORBITER CREW COMPARTMENT
7. TRAINING
8. LAUNCH SITE SUPPORT PLAN
9. INTERFACE VERIFICATION
10. INTRAVEHICULAR ACTIVITY
11. EXTRAVEHICULAR ACTIVITY
INSTEP88 Workshop
OAST Technology For the Future
Part 1: Executive Summary & Experiment Descriptions

**HUMANS IN SPACE**
Space Shuttle System Payload Integration Process
*
NSTS Integration and Operations
*

John C. O'Laughlin
Johnson Space Center, Spacelab & Middeck Integration Office

---

**NASA PAYLOAD INTEGRATION TEAM**

- **HQ** - CUSTOMER SERVICE MANAGER
  - FLIGHT SCHEDULE
  - POLICY

- **JSC** - PAYLOAD INTEGRATION MANAGER (PIM)
  - CUSTOMER PRIMARY POINT OF CONTACT
  - ENSURE PAYLOAD REQ. ACCURATELY DEFINED/DOCUMENTED
  - COORDINATES ENGINEERING TECHNICAL SUPPORT

- **KSC** - LAUNCH SITE SUPPORT MANAGER (LSSM)
  - CUSTOMER POINT OF CONTACT AT KSC
  - ENSURES PAYLOAD PROCESSING SUPPORT AT LAUNCH SITE

---

**PAYLOAD INTEGRATION SCHEDULE**

- FINAL MANIFESTING IS DEPENDENT ON COMPLETION OF JOINT AGREEMENTS (PIP, ICD, ANNEXES)

- COMPLETION DATES OF JOINT AGREEMENTS ARE DEPENDENT UPON CATEGORY OF PAYLOAD

- PAYLOAD INTEGRATION PROCESS FOR ALL PAYLOADS SHOULD START AS SOON AS POSSIBLE AFTER AGREEMENT TO PROCEED (ACCEPTANCE OF FORM 1628 BY NASA HEADQUARTERS)

- QUARTER SECTION TYPICAL SCHEDULE
  - PAYLOAD INTEGRATION PLAN ............... DRAFT COMPLETE 2-3 MONTHS AFTER FORM 1628
  - ICD ........................................ COMPLETE 1 MONTH AFTER PIP
  - ANNEXES.................................. CONSISTENT WITH START OF CIR ASSESSMENT ACTIVITY
  - SAFETY REVIEWS ......................... PAYLOAD DEVELOPMENT

- MISSION CAN BE DEFINED IN THE FDRO WHEN JOINT AGREEMENTS ARE BASELINED PRIOR TO THE "NO LATER THAN" DATES SHOWN ON THE FOLLOWING MATRIX
PAYLOAD CATEGORIES

- PRIMARY PAYLOAD
  - DRIVES THE OVERALL FLIGHT DESIGN
  - GENERALLY WEIGHS MORE THAN 6000 POUNDS
  - REQUIRES AT LEAST ONE-FOURTH OF PAYLOAD BAY SERVICES
- COMPLEX SECONDARY PAYLOAD
  - EXCEEDS NSTS ACCOMMODATIONS AS DEFINED IN APPLICABLE DOCUMENTATION
  - HAS ONE OR MORE OF THESE CHARACTERISTICS:
    - UTILIZES QUARTER-BAY PAYLOAD SERVICES
    - HAS OPTIONAL PAYLOAD BAY INTERFACES
    - HAS REQUIREMENTS WHICH DRIVE THE FLIGHT DESIGN
    - HAS UNIQUE INSTALLATION REQUIREMENTS IN THE ORBITER MIDDECK
HUMANS IN SPACE
Space Shuttle System Payload Integration Process

NSTS Integration and Operations

John C. O'Laughlin
Johnson Space Center, Spacelab & Middeck Integration Office

- NONSTANDARD SECONDARY/SMALL PAYLOAD ACCOMMODATION (SPA)
  - REQUIRES MINOR DEVIATIONS FROM GAS OR MIDDECK SIP AND/OR IDD
  - SPA MEETS THE SIP AND IDD REQUIREMENTS, BUT ITS COMPLEXITY REQUIRES THAT IT BE TREATED AS A NONSTANDARD SECONDARY PAYLOAD FROM A SCHEDULE PERSPECTIVE
  - DEVIATION FROM SPA STANDARDS REQUIRES THAT A PAYLOAD BE TREATED AS A COMPLEX SECONDARY

- STANDARD SECONDARY
  - DOES NOT EXCEED NSTS ACCOMMODATIONS AS DEFINED IN THE GAS OR MIDDECK SIP AND/OR IDD

FLIGHT ASSIGNMENT

<table>
<thead>
<tr>
<th>PAYLOAD CATEGORY</th>
<th>LATEST FLIGHT ASSIGNMENT</th>
<th>PREREQUISITES</th>
</tr>
</thead>
<tbody>
<tr>
<td>PRIMARY</td>
<td>FDRD L-19 MONTHS</td>
<td>BASELINED*</td>
</tr>
<tr>
<td></td>
<td></td>
<td>PIP AND ICD</td>
</tr>
<tr>
<td>COMPLEX SECONDARY</td>
<td>FDRD L-19 MONTHS</td>
<td>BASELINED</td>
</tr>
<tr>
<td></td>
<td></td>
<td>PIP AND ICD</td>
</tr>
<tr>
<td>NONSTANDARD SECONDARY OR SPA</td>
<td>CARGO INTEGRATION REVIEW (CIR) L-11.5 MONTHS</td>
<td>BASELINED PIP AND ICD. ALL ANNEXES BASELINED EXCEPT 4 AND 9; HOWEVER, CUSTOMER SUBMITTAL OF ANNEXES 4 AND 9 IS REQUIRED.</td>
</tr>
<tr>
<td>STANDARD SECONDARY</td>
<td>FLIGHT PLANNING AND STOWAGE REVIEW (FPSR) L-7 MONTHS</td>
<td>BASELINED PIP, ICD, AND ALL ANNEXES. PHASE II SAFETY REVIEW IS REQUIRED.</td>
</tr>
</tbody>
</table>

*BASELINED = SIGNED BY BOTH NSTS AND THE CUSTOMER
**HUMANS IN SPACE**

Space Shuttle System Payload Integration Process

**NSTS Integration and Operations**

John C. O'Laughlin
Johnson Space Center, Spacelab & Middeck Integration Office

**Timeline Required for Flight Readiness**

<table>
<thead>
<tr>
<th>FORM</th>
<th>PAYLOAD TYPE</th>
<th>PRIMARY</th>
<th>COMPLEX</th>
<th>NON-STANDARD SECONDARY, OR NON-STANDARD SPA</th>
</tr>
</thead>
<tbody>
<tr>
<td>1628</td>
<td>11 MONTHS</td>
<td>PIP B/L</td>
<td>23 MONTHS</td>
<td>LAUNCH</td>
</tr>
</tbody>
</table>

- **FLIGHT ASSIGNMENT: FDRO**
  *(L-19 MONTHS)*

- **16 1/2 MONTHS**
  **LAUNCH**
  **FLIGHT ASSIGNMENT: CIR**
  *(L-11.5 MONTHS)*

- **12 MONTHS**
  **LAUNCH**
  **FLIGHT ASSIGNMENT: FPSR**
  *(L-7 MONTHS)*
**GAS / CAP**

**Similarities**
- Hardware
- Facilities
- Personnel

**GAS / CAP**

**Differences**

<table>
<thead>
<tr>
<th>GAS</th>
<th>CAP</th>
</tr>
</thead>
<tbody>
<tr>
<td>Existing Customers</td>
<td>Secondaries Policy</td>
</tr>
<tr>
<td>Subject to Queue</td>
<td>Manifested</td>
</tr>
<tr>
<td>Restrictive Interfaces</td>
<td>More Commands Possible</td>
</tr>
<tr>
<td></td>
<td>Some Pointing Possible</td>
</tr>
<tr>
<td></td>
<td>Payload Integration Plan (PIP)</td>
</tr>
<tr>
<td></td>
<td>Longer Processing</td>
</tr>
</tbody>
</table>
Get Away Special Concept

- Encourage the use of Space by all Researchers: Private Individuals and Organizations
- Foster Enthusiasm in Younger Generation
- Increase Knowledge of Space
- Be Alert to Possible growth of GAS Investigation into a Prime Experiment
- Generate New Activities Unique to Space
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
*Complex Autonomous Payload Carriers*

Clarke R. Prouty
Goddard Space Flight Center, Special Payloads Division

**GET AWAY SPECIAL**
**SMALL SELF-CONTAINED PAYLOADS**

**CONTAINER CONCEPT**

**GET AWAY SPECIAL**
**GAS**
CONTAINER/ADAPTER BEAM ASSEMBLY
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
Complex Autonomous Payload Carriers

Clarke R. Prouty
Goddard Space Flight Center, Special Payloads Division

GET AWAY SPECIAL
SMALL SELF-CONTAINED PAYLOADS
CONTROL CONCEPT

Dedicated Twisted Shielded Pair

AFT Flight Deck

ORBITER BAY

BULKHEAD (576)

BLACK AND WHITE PHOTOGRAPH

ORIGINAL PAGE IS OF POOR QUALITY
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
Hitchhiker Project Overview

T.C. Goldsmith
Goddard Space Flight Center, Shuttle Small Payloads Project

SHUTTLE SMALL PAYLOADS PROJECT

- THE SHUTTLE SMALL PAYLOADS PROJECT CONTAINS THE HITCHHIKER, GET-AWAY-SPECIAL (GAS), AND COMPLEX AUTONOMOUS PAYLOADS (CAP) PROJECTS.
- HITCHHIKER INCLUDES HH-G SIDE MOUNT CARRIERS AND HH-M CROSS-BAY CARRIERS WHICH CONNECT TO ORBITER ELECTRICAL SERVICES AND ARE FLOWN UNDER THE SECONDARY PAYLOAD MANIFEST.
- GAS PAYLOADS ARE MOUNTED IN CANISTERS, DO NOT CONNECT TO ORBITER ELECTRICAL SERVICES, AND DO NOT REQUIRE SIGNIFICANT STS SUPPORT. GAS PAYLOADS ARE IN AN EXISTING TERTIARY PAYLOAD QUEUE. NO NEW RESERVATIONS ARE BEING ACCEPTED BUT EXISTING LAUNCH SLOTS MAY BE SOLD BY EXISTING RESERVATION HOLDERS.
- COMPLEX AUTONOMOUS PAYLOADS USE GAS PROJECT CARRIER EQUIPMENT, DO NOT CONNECT TO ORBITER ELECTRICAL SERVICES, BUT MAY REQUIRE STS SERVICES SUCH AS POINTING, CREW ACTIVITY, LATE ACCESS, ETC., IN EXCESS OF THOSE ALLOWED FOR GAS. CAP PAYLOADS ARE MANIFESTED UNDER THE SECONDARY PAYLOAD SYSTEM.

HITCHHIKER PROGRAM DESCRIPTION

- THE HITCHHIKER PROGRAM WAS INITIATED BY THE NASA OFFICE OF SPACE FLIGHT IN 1984 TO PROVIDE A QUICK REACTION SHUTTLE CARRIER SERVICE FOR SMALL PAYLOADS. GSFC DEVELOPED THE SHUTTLE PAYLOAD OF OPPORTUNITY CARRIER (SPOC) SYSTEM TO SUPPORT THE HITCHHIKER-G PROGRAM. SPOC WAS SPECIFICALLY DESIGNED TO HAVE SIMPLE, STANDARD CARRIER TO ORBITER INTERFACES AND STANDARD, USER-FRIENDLY, CARRIER TO CUSTOMER INTERFACES TO REDUCE PAYLOAD UNIQUE INTEGRATION EFFORT REQUIRED AND THEREBY REDUCE LEAD TIME AND RECURRING COST. HITCHHIKER-G IS A FAMILY OF COMPONENTS DESIGNED TO MOUNT SMALL PAYLOADS TO THE SIDE OF THE ORBITER WITH MINIMUM TOTAL PAYLOAD WEIGHT.
- HITCHHIKER-M IS A SECOND CARRIER SYSTEM DEVELOPED BY MSFC AND CONSISTING OF A CROSS-BAY (BRIDGE) TYPE CARRIER INTENDED FOR SOMEWHAT HEAVIER PAYLOADS. IN 1987 THE HITCHHIKER-M CARRIER SYSTEM WAS COMBINED WITH THE HITCHHIKER-G PROJECT AT GSFC AND WILL FLY WITH THE SAME ELECTRICAL CUSTOMER AND ORBITER INTERFACES AS THE HITCHHIKER-G.
- HITCHHIKER IS BASICALLY AN EXTENSION OF THE STS AND IS PROVIDED AND OPERATED BY THE OFFICE OF SPACE FLIGHT AT NO COST TO A NASA USER PROVIDED ONLY STANDARD SERVICES ARE REQUIRED. EXCESS SERVICES ARE FUNDED BY THE CUSTOMER.
- HITCHHIKERS ARE FLOWN AS SECONDARY PAYLOADS UNDER THE 7/87 NASA SECONDARY PAYLOAD POLICY AND CAN FLY AS EITHER "SMALL" PAYLOADS OR STANDARD ATTACHED MIXED CARGO PAYLOADS.
HUMANS IN SPACE
Space Shuttle System Payload Integration Process

Hitchhiker Project Overview

T.C. Goldsmith
Goddard Space Flight Center, Shuttle Small Payloads Project

HITCHHIKER MANIFESTING SITUATION

- A NEW POLICY FOR SECONDARY PAYLOADS ON NASA SHUTTLE FLIGHTS WAS ANNOUNCED 7/29/87 AS FOLLOWS:
- ALLOCATIONS OF SECONDARY PAYLOAD SPACE BY WEIGHT (PERCENTAGE OF AVAILABLE SPACE) HAVE BEEN ESTABLISHED FOR THE VARIOUS DISCIPLINES AS FOLLOWS: THE CORRESPONDING TOTAL PAYLOAD WEIGHT FOR EACH DISCIPLINE IS SHOWN FOR THE 4/30/88 MANIFEST.

<table>
<thead>
<tr>
<th>CODE</th>
<th>WEIGHT</th>
</tr>
</thead>
<tbody>
<tr>
<td>E</td>
<td>36</td>
</tr>
<tr>
<td>C</td>
<td>39</td>
</tr>
<tr>
<td>S</td>
<td>26</td>
</tr>
<tr>
<td>M</td>
<td>5</td>
</tr>
<tr>
<td>A</td>
<td>3</td>
</tr>
<tr>
<td>X</td>
<td>3</td>
</tr>
<tr>
<td>DOD</td>
<td>0</td>
</tr>
<tr>
<td>TOTAL</td>
<td>100</td>
</tr>
</tbody>
</table>

- GET-AWAY-SPECIAL (GAS) PAYLOADS WILL FLY IN SPACE AVAILABLE AFTER ACCOMMODATING PRIMARY AND SECONDARY PAYLOADS AND WILL CONTINUE TO USE THE EXISTING QUEUE AND POLICY. NO NEW GAS PAYLOADS ARE BEING ACCEPTED.
- EMPHASIS TO BE PLACED ON MICROGRAVITY PAYLOADS OR SPACE STATION SUPPORT.

MANIFESTED IN-BAY SECONDARY PAYLOADS AS OF 10/1/88

<table>
<thead>
<tr>
<th>FLIGHT</th>
<th>PAYLOAD</th>
<th>ORG</th>
<th>WEIGHT</th>
</tr>
</thead>
<tbody>
<tr>
<td>89-2/16</td>
<td>SHARE</td>
<td>COS</td>
<td>830</td>
</tr>
<tr>
<td>89-2/18</td>
<td>SSBUV-1</td>
<td>CDE</td>
<td>1219</td>
</tr>
<tr>
<td>90-11/08</td>
<td>SSBUV-2</td>
<td>CDE</td>
<td>1219</td>
</tr>
<tr>
<td>90-TBD</td>
<td>TPC</td>
<td>CDR</td>
<td>495</td>
</tr>
<tr>
<td>91-1/31</td>
<td>PMG-1</td>
<td>CDM</td>
<td>750</td>
</tr>
<tr>
<td>91-1/31</td>
<td>ASP</td>
<td>CDX</td>
<td>540</td>
</tr>
<tr>
<td>91-8/15</td>
<td>PTS-DTF-1</td>
<td>CDS</td>
<td>1500</td>
</tr>
<tr>
<td>91-12/23</td>
<td>CXH-1</td>
<td>CDC</td>
<td>4000</td>
</tr>
<tr>
<td>92-2/27</td>
<td>DEE</td>
<td>CDM</td>
<td>300</td>
</tr>
<tr>
<td>92-2/27</td>
<td>SEDS-1</td>
<td>CDE</td>
<td>930</td>
</tr>
<tr>
<td>92-6/11</td>
<td>EOIM/TEMP2A2</td>
<td>CDS</td>
<td>2345</td>
</tr>
<tr>
<td>92-6/11</td>
<td>SSBUV-3</td>
<td>CDE</td>
<td>1219</td>
</tr>
<tr>
<td>92-7/30</td>
<td>CTM</td>
<td>CDX</td>
<td>830</td>
</tr>
<tr>
<td>92-7/30</td>
<td>HPE</td>
<td>CDX</td>
<td>930</td>
</tr>
<tr>
<td>92-10/29</td>
<td>SPARTAN-2</td>
<td>CDE</td>
<td>5700</td>
</tr>
<tr>
<td>92-11/19</td>
<td>SEDS</td>
<td>CDM</td>
<td>350</td>
</tr>
<tr>
<td>92-TBD</td>
<td>CGAS-1</td>
<td>CDC</td>
<td>500</td>
</tr>
<tr>
<td>93-1/14</td>
<td>MAST-1 CSI</td>
<td>CDR</td>
<td>7000</td>
</tr>
<tr>
<td>93-2/11</td>
<td>LTE-1</td>
<td>CDR</td>
<td>4900</td>
</tr>
<tr>
<td>93-2/11</td>
<td>CXH-2</td>
<td>CDC</td>
<td>3000</td>
</tr>
<tr>
<td>93-3/18</td>
<td>SDS-2</td>
<td>CDE</td>
<td>740</td>
</tr>
<tr>
<td>93-4/08</td>
<td>SPH</td>
<td>CDM</td>
<td>3200</td>
</tr>
<tr>
<td>93-4/15</td>
<td>MSL-3</td>
<td>CDE</td>
<td>5700</td>
</tr>
<tr>
<td>93-6/10</td>
<td>SSBUV-4</td>
<td>CDE</td>
<td>980</td>
</tr>
<tr>
<td>93-6/17</td>
<td>PTS-DTF-2</td>
<td>CDS</td>
<td>5500</td>
</tr>
<tr>
<td>93-6/17</td>
<td>CXM-1</td>
<td>CDC</td>
<td>6000</td>
</tr>
<tr>
<td>93-8/05</td>
<td>CXH-3</td>
<td>CDC</td>
<td>3000</td>
</tr>
<tr>
<td>93-8/09</td>
<td>SRAD</td>
<td>CDS</td>
<td>5700</td>
</tr>
<tr>
<td>93-TBD</td>
<td>CGAS-2</td>
<td>CDC</td>
<td>500</td>
</tr>
<tr>
<td>93-TBD</td>
<td>CGAS-3</td>
<td>CDC</td>
<td>500</td>
</tr>
</tbody>
</table>

*HITCHHIKER / CSCP PAYLOADS
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
*Hitchhiker Project Overview*

T.C. Goldsmith
Goddard Space Flight Center, Shuttle Small Payloads Project

**HITCHHIKER-G MISSION ONE**

**USAF PARTICLE ANALYSIS CAMERAS FOR SHUTTLE (PACS) INSTRUMENT**

**PERKIN-ELMER SHUTTLE ENVIRONMENTAL EFFECT ON COATED MIRROR (SEECM) INSTRUMENT**

**GSFC CAPILLARY PUMPED LOOP (CPL) INSTRUMENT**

**SUPERFLUID HELIUM ON ORBIT TRANSFER FLIGHT DEMONSTRATION**
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
Hitchhiker Project Overview

T.C. Goldsmith
Goddard Space Flight Center, Shuttle Small Payloads Project

SPOC FEATURES FOR REDUCTION OF CUSTOMER COSTS

- Standard pre-defined interfaces reduce engineering effort, design iteration, and lead time.
- Transparent data system allows use of customer's own ground support equipment, software, and personnel during payload integration and flight operations minimizing retraining and retesting efforts and allowing the customer maximum autonomy.
- Simple mounting scheme.
- Canister option provides containment and reduces safety analysis.
- Short hands-on integration period - instruments delivered as late as L-5 months.
- Reduced requirements for conferences, travel, etc.

TYPICAL HITCHHIKER SCHEDULE MILESTONES (MONTHS)

-24
-23
-18
-8
-3
0
1
1

PRELIMINARY
# HUMANS IN SPACE

Space Shuttle System Payload Integration Process  

*Hitchhiker Project Overview*

T.C. Goldsmith  
Goddard Space Flight Center, Shuttle Small Payloads Project

## Hitchhiker Mechanical Accommodations

- **Plate**  
  - The large plate is 50 x 60 inches and can accommodate up to 250 lbs of customer hardware in addition to the SPOC avionics.  
  - The small plate is 25 x 39 inches and can accommodate 100 lbs.  
  - Plates have a grid of 3/8 bolt holes on 70 mm centers.

- **Canister**  
  - Canisters can accommodate a payload 19.25 inches (dia) x 28 inches (height).  
  - Canisters with opening doors can accommodate 170 lb payloads.  
  - Sealed canisters (1 atm air or nitrogen) can accommodate 200 lb.

- **Bridge (HH-M)**  
  - The bridge has three attachment locations each on the top, front, and rear of the truss. The top locations can accommodate up to 380 lbs each and the side locations can accommodate up to at least 170 lbs. The side mounting areas are 27 x 28 inches and the top mounts are 28 x 36 inches. Standard mounting holes are provided.

- **THERMAL**  
  - Thermal control surfaces, heaters, thermostats, etc. on plate mounted customer equipment are provided by the customer.  
  - GSFC provides external thermal blanket or white paint surface for canisters.  
  - No fluid loop cooling is provided but several hundred watts (continuous) or several kW (short periods) of heat dissipation can usually be accommodated by radiation and temporary storage of heat in the thermal mass of the equipment.

- **ATTITUDE CONTROL**  
  - Orbiter can point at a target within 9 arc minutes (5 arc min for short periods).  
  - User supplied pointing system can be used to improve pointing accuracy.  
  - Nominal shuttle attitude is bay down.
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
Hitchhiker Project Overview

T.C. Goldsmith
Goddard Space Flight Center, Shuttle Small Payloads Project

SPOC STRUCTURAL ASSEMBLY
(EXPLDED VIEW)

Hitchhiker-G Canister
Mechanical and Electrical Interfaces
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
Hitchhiker Project Overview

T.C. Goldsmith
Goddard Space Flight Center, Shuttle Small Payloads Project

CUSTOMER ELECTRICAL INTERFACES

The standard electrical interface or "port", consists of a signal cable and a separate power cable which provide the following:

- Two 28 V (± 4 V) 10 Amp. power lines which can be turned on (together) by ground command. Customer power and energy are monitored by the carrier system. The maximum simultaneous total customer power for a Hitchhiker is 1300 W and the nominal maximum total customer energy is 6 KWH/day with additional energy negotiable. Non-Hitchhiker payloads may use up to 1650 W (2350 W for 15 minutes) and 10 KWH/day.
- Four 28V bi-level or pulse commands (10 ms max) which can be used with relay drivers and relays to control additional power switching within a payload. (For canister payloads one command is reserved for control of the door.)
- An asynchronous 1200 baud uplink command channel.
- An asynchronous 1200 baud low-rate downlink data channel. This data is available over Ku-band service or C-band service and can also be recorded on the orbiter's tape recorder.
- A medium-rate downlink channel 1-1600 Kbps for use with the real-time-only Ku-band TDRS service. The total simultaneous customer data rate for the carrier cannot exceed 1400 Kbps.
- IRIG-B serial time code and a one pulse per minute square wave signal which can be complemented by a time command via the above asynchronous uplink channel.
- Three channels for temperature sensors to allow measurement of payload temperatures even when the payload power is off (for canister payloads these channels are reserved for door position, canister pressure, and temperature).
- An analog channel, 0-5V, 8 bit quantizing, 10 hertz sample rate. An index pulse is also supplied which can be used to advance a user supplied analog multiplexer to allow measuring a large number of parameters.

SPOC TRANSPARENT DATA SYSTEM COMMUNICATIONS

AT CUSTOMER'S FACILITY

AT CUSTOMER/CARRIER INTEGRATION

AT FLIGHT OPERATIONS
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
Hitchhiker Project Overview

T.C. Goldsmith
Goddard Space Flight Center, Shuttle Small Payloads Project
HUMANS IN SPACE
Space Shuttle System Payload Integration Process

Middeck Payload Integration: Orbiter Crew Module Description

John C. O’Laughlin
Johnson Space Center, Spacelab Middeck Integration Office

Middeck Payload Integration

- Orbiter Crew Module Description
- Middeck Payload Accommodations
- Payload Design Guidelines/Considerations
- Schedules/Manifesting

Orbiter Crew Module

[Diagram of the Orbiter Crew Module]
HUMANS IN SPACE

Space Shuttle System Payload Integration Process

Middeck Payload Integration: Orbiter Crew Module Description

John C. O'Laughlin
Johnson Space Center, Spacelab Middeck Integration Office

MIDDECK - RIGHT SIDE VIEW LOOKING FORWARD AND OUTBOARD

MIDDECK - LEFT SIDE VIEW LOOKING AFT AND OUTBOARD
**HUMANS IN SPACE**

Space Shuttle System Payload Integration Process

*Middeck Payload Integration: Middeck Payload Accommodations*

John C. O'Laughlin
Johnson Space Center, Spacelab Middeck Integration Office

<table>
<thead>
<tr>
<th>PHYSICAL ACCOMMODATIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td>• LOCKER STOWED PAYLOAD</td>
</tr>
<tr>
<td>• 54 POUND MAX PAYLOAD WEIGHT</td>
</tr>
<tr>
<td>• CENTER-OF-GRAVITY (CG) OF LOCKER CAN BE NO MORE THAN 14 INCHES FROM FACE OF ORBITER WIRE TRAY</td>
</tr>
<tr>
<td>• LOCKER PROVIDES 2 CUBIC FEET OF STOWAGE VOLUME</td>
</tr>
<tr>
<td>• NONLOCKER PAYLOAD</td>
</tr>
<tr>
<td>• 69 POUND MAX PAYLOAD WEIGHT - ONE LOCKER REPLACEMENT</td>
</tr>
<tr>
<td>• 120 POUND MAX PAYLOAD WEIGHT - TWO LOCKER REPLACEMENT</td>
</tr>
<tr>
<td>• CG OF PAYLOAD CAN BE NO MORE THAN 14 INCHES FROM FACE OF ORBITER WIRE TRAY</td>
</tr>
<tr>
<td>• MAX PAYLOAD WEIGHT CG DEPENDENT</td>
</tr>
<tr>
<td>• PAYLOAD SHALL NOT PROTRUDE BEYOND FACE OF LOCKERS</td>
</tr>
</tbody>
</table>

---

[Diagram of Space Shuttle System Payload Integration Process]
HUMANS IN SPACE

Space Shuttle System Payload Integration Process

Middeck Payload Integration: Middeck Payload Accommodations

John C. O'Laughlin
Johnson Space Center, Spacelab Middeck Integration Office

STANDARD MIDDECK MODULAR LOCKER

MIDDECK LOCKER STANDARD STOWAGE TRAYS

LARGE STOWAGE TRAY

SMALL STOWAGE TRAY
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
Middeck Payload Integration: Middeck Payload Accommodations

John C. O’Laughlin
Johnson Space Center, Spacelab Middeck Integration Office

MIDDECK MODULAR STOWAGE LOCKER CONFIGURATIONS

EXAMPLE NONLOCKER MIDDECK PAYLOAD
<table>
<thead>
<tr>
<th>HUMANS IN SPACE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Space Shuttle System Payload Integration Process</td>
</tr>
<tr>
<td>Middeck Payload Integration: Middeck Payload Accommodations</td>
</tr>
</tbody>
</table>

John C. O'Laughlin  
Johnson Space Center, Spacelab Middeck Integration Office

### ELECTRICAL POWER

- Nominal 28 volt DC, limited to 115 watts max continuous
- Power generally not available during ascent/descent
- Standard power cables provided by NSTS

### THERMAL

- Cooling
  - Heat dissipated into crew compartment by passive or forced air cooling
  - Passive air cooling - heat load limited to 60 watts max continuous for locker stowed payload
  - Forced air cooling - heat load limited to 115 watts max continuous
  - Payload provides air circulation fan
  - Air outlet temperature limited to 120°F max

- External surface temperatures
  - Payload surfaces accessible to crew limited to 113°F max
  - Payload surfaces inaccessible to crew limited to 120°F max
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
Middeck Payload Integration: Payload Design Guidelines/Considerations

John C. O’Laughlin
Johnson Space Center, Spacelab Middeck Integration Office

- Payload operations limited to middeck except for “out-the-window” photographic activities
- No payload operations on launch and landing days except for simple activation/deactivation activities
- Payload operations requiring crew involvement allowed only during crew awake periods
- Normal shuttle flight has one-shift on-orbit workday of 10 hours with 8 hours available for payload operations. An additional 1 hour may be available just before and just after the normal workday for simple payload operations
- Typical shuttle flight has a crew of 5 and a duration of 4-5 days
- No ground commanding or data downlink available for middeck payloads
**HUMANS IN SPACE**

Space Shuttle System Payload Integration Process

*Middeck Payload Integration: Payload Design Guidelines/Considerations*

John C. O'Laughlin
Johnson Space Center, Spacelab Middeck Integration Office

- **Documentation for Payloads**
  - Payload provided systems for data storage
  - Crew comments - audio/log books
  - Video
  - Photography

- **Payload Installation/Removal**
  - Middeck payloads normally installed in shuttle orbiter 3-8 days prior to launch and removed one day after landing
  - If absolutely required (subject to NSTS approval) installation of middeck payloads may be provided as late as 18 hours prior to launch and removal as early as 2 hours after landing

- **Payload Installed Orientation**
  - Should be considered during design - will be different during launch and landing phases

- **Shuttle does not provide absolute zero-gravity environment** - crew movements, crew treadmill exercise, thruster firings, and other payload operations will induce disturbances

- **Materials selection very important** for middeck payloads to protect the crew and orbiter
  - Toxicity
  - Flammability
  - Nuclear radiation

- **Working in low gravity** generally requires more time than same task on ground

- If payload assembly is required on-orbit, avoid use of small parts that can get loose in cabin

- Velcro (NSTS approved type) can be used to restrain payload components during on-orbit activities

- **Redundant/spare parts should be considered for critical payload components**

- **Simple in-flight maintenance can be designed into payload, but must not violate safety requirements and must be approved by NSTS**
### Payload Integration Process

**Middeck Payload Integration: Schedules/Manifesting**

**John C. O'Laughlin**
Johnson Space Center, Spacelab Middeck Integration Office

### Flight Assignment

<table>
<thead>
<tr>
<th>Payload Category</th>
<th>Latest Flight Assignment</th>
<th>Prerequisites</th>
</tr>
</thead>
<tbody>
<tr>
<td>Primary</td>
<td>FDRD L-19 MONTHS</td>
<td>Baseline* PIP and ICD</td>
</tr>
<tr>
<td>Complex Secondary</td>
<td>FDRD L-19 MONTHS</td>
<td>Baseline PIP and ICD</td>
</tr>
<tr>
<td>Nonstandard Secondary OR SPA</td>
<td>Cargo Integration Review (CIR) L-11.5 MONTHS</td>
<td>Baseline PIP and ICD. All Annexes baselined except 4 and 9; however, customer submittal of Annexes 4 and 9 is required.</td>
</tr>
<tr>
<td>Standard Secondary</td>
<td>Flight Planning and Stowage Review (FPSR) L-7 MONTHS</td>
<td>Baseline PIP, ICD, and all Annexes. Phase II Safety Review is required.</td>
</tr>
</tbody>
</table>

*Baseline = Signed by both NSTS and the customer*

### Timeline Required for Flight Readiness

<table>
<thead>
<tr>
<th>Form 1628</th>
<th>11 MONTHS</th>
<th>PIP B/L</th>
<th>23 MONTHS</th>
<th>Launch</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- Flight Assignment: FDRD (L-19 MONTHS)
- 16 1/2 MONTHS Launch
- Flight Assignment: CIR (L-11.5 MONTHS)
- 12 MONTHS Launch
- Flight Assignment: FPSR (L-7 MONTHS)

- Primary, Complex
- Non-Standard Secondary, or Non-Standard SPA
- Non-Standard Secondary or SPA
- Standard Secondary
PAYLOAD MANAGEMENT RESPONSIBILITIES

- Kennedy Space Center (KSC) is the primary NASA launch site
  - Responsible for the management and direction of:
    - Assembly and verification of the Shuttle
    - Assembly and processing of Spacelab and similar type payloads
    - Support of payload processing and final preparation for launch
    - Final test and integration of payloads in the Orbiter bay before launch
    - Final test and integration of payloads with expendable vehicles
    - Countdown and launch
    - Facilities, communications, and data support to early phase of orbital activity when required
    - Primary and contingency landing site operations
    - Deintegration of payloads from the SIS upon their return from space
    - Performing the host role as the customer's agent
HUMANS IN SPACE
Space Shuttle System Payload Integration Process

**KSC Payload Integration**

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

---

**Example of Payload Flow for **

**O&C Integration**

---

**Example of Payload Flow for **

**VPF Integration**

---

275
**KSC GET-AWAY SPECIAL PAYLOAD PROCESSING**

- **Customer's plant** → **Receipt at KSC** → **Install in orbiter at OPF** → **Launch** → **Land at DFRC**

  - GSFC
  - 5 days
  - 60 to 80 days
  - 5 to 7 days
  - 6 to 7 days

- **Shuttle carrier aircraft** land at KSC → **Remove GAS payload in OPF** → **Return GAS payload to customer at GAS facility**

  - 3 days
  - 2 days

**CINEMA 360° INSTALLATION**

---

*ORIGINAL PAGE IS OF POOR QUALITY*
**HUMANS IN SPACE**
Space Shuttle System Payload Integration Process

*KSC Payload Integration*

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

### GENERIC EXPERIMENT PHYSICAL AND FUNCTIONAL FAMILIARIZATION

- Personnel assigned after the payload experiment complement is defined
  - Assignment continues through experiment deintegration

- Personnel participate in
  - Experiment and payload design reviews at design facility
  - Technical exchange meetings
  - Payload ground operations working group meetings at KSC
  - Integration and testing activities at the experiment developer's facility

- Personnel utilize knowledge about experiments to
  - Develop inputs for KSC processing schedules
  - Develop procedures for experiment activities at KSC
  - Evaluate requirement validity and impact

### GENERIC EXPERIMENT PRE-TURNOVER SUPPORT

- Evaluate pre-turnover activities and provide task direction for hazardous operations

- Participate in post delivery tests conducted by experiment developer
  - KSC engineers gain additional experience with experiment
  - KSC engineers keep abreast of experiment status

- Provide generic test equipment and facilities

- Provide servicing support as required
**HUMANS IN SPACE**

Space Shuttle System Payload Integration Process

**KSC Payload Integration**

Dean C. Zimmerman  
Kennedy Space Center, Payload Support Office

## EXPERIMENT INTEGRATION

### INTRODUCTION

1. **KSC PERFORMS EXPERIMENT INTEGRATION AS DEFINED BY THE PAYLOAD MISSION MANAGER REQUIREMENTS.**
2. **THE EXPERIMENTER IS AN INTEGRAL PART OF THE EXPERIMENT INTEGRATION TEAM**
   - Sets up and verifies experiment ground support equipment
   - Monitors and operates GSE during testing
   - Provides details on how experiments are operated
   - Provides experiment expertise for problem resolution/unique experiment operations
   - Inputs to reviews/sign-off procedures
3. **INTERFACE VERIFICATION POLICY**
   - Interfaces are verified at earliest opportunity by functional test(s)
   - Experiment compatibility is verified using MST/Major Integrated Testing
   - No "failure" mode/unique software validation (except safety related)

## EXPERIMENT INTEGRATION

### REQUIREMENTS

1. **PAYLOAD MISSION MANAGER PROVIDES REQUIREMENTS DOCUMENT WITH ALL KSC PROCESSING REQUIREMENTS TO LSSM INCLUDING:**
   - Off-line facility support
   - Experiment installation
   - Interface verification
   - Servicing, alignment, and calibration
   - Launch delay contingencies
   - Deintegration
   - Experimenter post flight support
   - contingency landing site processing
2. **KSC RESPONDS TO REQUIREMENTS WITH THE KSC LAUNCH SITE SUPPORT PLAN (LSSP), ANNEX 8 OF THE PAYLOAD INTEGRATION PLAN (PIP)**
3. **LSSP COMPLEMENTS KSC RESOURCES:**
   - Identifies integration phase of requirement
   - Identifies those requirements which are non-standard (optional services)
   - Identifies requirements which cannot be met or need further resolution (preliminary only)
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
KSC Payload Integration

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

EXPERIMENT INTEGRATION

PMW/PI/ED PARTICIPATION

- Works with KSC to satisfactorily implement requirements
- Provides procedure inputs relative to proper experiment operation to ensure accurate testing and health, review/sign resultant procedures
- Perform experiment unique functions which require special expertise or training
- Checkout GSE in User Room
- Operate GSE during KSC operations (passive activity)
- Provide experiment expertise when problems occur
- Evaluate experiment GSE data
- Evaluate test results to ensure objectives are met

EXPERIMENT INTEGRATION

OFF-LINE PREPARATIONS

- "Off-line" refers to those functions which occur outside the normal serial flow of payload hardware integration
  - Normally performed by experimenter personnel
  - Normally performed in off-line areas (lab, etc.)
  - KSC personnel only involved to provide support or control hazardous operations

- "On-line" refers to those functions which occur as a part of the integration flow after experiment turnover
  - Normally performed by KSC
  - Normally occurring in the integration stand/orbiter
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
*KSC Payload Integration*

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

**EXPERIMENT INTEGRATION**

**OFF-LINE ACTIVITIES**

- **EXPERIMENT TURNOVER**
  - The PHM will provide KSC with a data package defining:
    1. Experiment Configuration
    2. Open Work Items (Scheduled)
    3. Non-Flight Items (Red Tag)
    4. Open Problems/Verifications/Waivers
    5. Flight Spares
    6. Bonded Storage Needs
    7. Hazards (Lasers, Cryogens, etc.)
  - The PHM/PI/ED will certify that all ground safety reviews are completed (identify any open items) and experiment is qualified for STS flight

---

*O&C BUILDING ASSEMBLY AND TEST AREA*
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
KSC Payload Integration

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

GENERIC EXPERIMENT INTEGRATION WITH CARRIER

- MECHANICAL INTEGRATION ACTIVITIES, SUCH AS
  - MISSION PECULIAR EQUIPMENT (MPE) INSTALLATION (E.G., FLUID LINES, CABLES, SUPPORT STRUCTURES)
  - EXPERIMENT INSTALLATION
  - MPE AND EXPERIMENT HARDWARE MODIFICATIONS

- MECHANICAL MISSION DEPENDENT ACTIVITIES, SUCH AS
  - EXPERIMENT ALIGNMENT
  - EXPERIMENT SERVICING
  - MPE FLUID SYSTEM LEAK CHECKS AND SERVICING
  - EXPERIMENT HARDWARE STORAGE (MODULE MISSIONS)

- ELECTRICAL PRE-TEST ACTIVITIES, SUCH AS
  - CONTINUITY AND MEGGER CHECKS
  - VOLTAGE AND POLARITY CHECKS
  - ISOLATION CHECKS

GENERIC EXPERIMENT TESTING

- LEVEL IV EXPERIMENT FUNCTIONAL TESTS
  - VERIFY EXPERIMENT TO SUBSYSTEM AND TO ORBITER INTERFACES
  - VERIFY EXPERIMENT FUNCTIONAL OPERATIONS TO EXTENT PRACTICAL

- INTEGRATED TESTS
  - MOST SYSTEMS/EXPERIMENTS ARE ACTIVE
  - SYSTEMS/CREW ARE UTILIZED IN MAXIMUM RESOURCE MODE
  - COMPATIBILITY BETWEEN EXPERIMENTS/SUBSYSTEMS IS VERIFIED

- CREW EQUIPMENT INTERFACE TESTS
  - VERIFY CREW/CREW EQUIPMENT COMPATIBILITY
  - VERIFY EXPERIMENT/CREW EQUIPMENT INTERFACES AND COMPATIBILITY

- CITE TESTS (MISSION DEPENDENT)
  - UTILIZED FOR FIRST TIME CONFIGURATIONS
  - PROVIDE HIGH FIDELITY SIMULATION OF ORBITER

- ORBITER INTERFACE TESTS
  - PERFORMED AT EITHER THE OPF OR THE PAD
  - VERIFY PAYLOAD TO ORBITER INTERFACES

NOTE: EXTENSIVE INVOLVEMENT BY FLIGHT CREW MEMBERS DURING EXPERIMENT TESTING FOR CERTAIN PAYLOADS, SUCH AS SPACELABS.
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
KSC Payload Integration

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

GENERIC EXPERIMENT SERVICING AND CLOSEOUT

- Servicing and closeout operations are mission dependent and may be performed in the O&C test stands, in the OPF, and/or at the pad.

- Servicing and periodic maintenance, such as
  - Experiment purges
  - Fluids fill/topoff
  - Experiment calibration
  - Battery installation/charge

- Closeout activities, such as
  - Payload envelope clearance checks
  - Payload weight and CG measurements
  - Pyrotechnics installation and verification
  - Experiment unique operations (e.g., remove before flight items)
  - OPF time constrained stowage and crew walkdown (module missions)
  - Pad late access final stowage (e.g., biological samples, SL-3 primates and rodents)

CANISTER/TRANSPORTER CONFIGURATIONS
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
KSC Payload Integration

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office
VERTICAL PROCESSING FACILITY ACTIVITIES

- Payload integration with orbiter systems and other payloads also takes place in the Vertical Processing Facility (VPF).

- Delivery configuration varies depending on the Upper Stage:
  - PM already mated with payload
  - IUS/TDRS and payload arrive separately
  - Syncom class and its PKN arrive separately

- Payload elements stacking and tests involve:
  - Mating with Upper Stage as necessary and installation into workstand in payload bay sequence
  - Standalone Health and Status tests
  - Integration tests
    - Orbiter-to-payload interface verification with payload integration test equipment (CITE)
    - Mission sequence test
    - End-to-end test
    - Ordnance systems test

CANISTER/TRANSPORTER BEING READIED TO LEAVE VPF
## HUMANS IN SPACE

Space Shuttle System Payload Integration Process

**KSC Payload Integration**

Dean C. Zimmerman  
Kennedy Space Center, Payload Support Office

<table>
<thead>
<tr>
<th>CANISTER/TRANSPORTER ON PAD</th>
<th>CANISTER BEING RAISED TO PCR</th>
</tr>
</thead>
</table>

*ORIGINAL PAGE IS OF POOR QUALITY*
HUMANS IN SPACE
Space Shuttle System Payload Integration Process
KSC Payload Integration

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

PAYLOAD ELEMENTS BEING TRANSFERRED FROM THE PCR INTO THE SHUTTLE PAYLOAD BAY

ORBITER INTEGRATION

- AFTER PAYLOAD INSTALLATION IN ORBITER PAYLOAD BAY IN THE OPF OR THE PCR:
  - OPF
    - PAYLOAD CABLES TO ORBITER ARE CONNECTED AND THE INTERFACE IS VERIFIED FROM FIRING ROOM AT LAUNCH CONTROL CENTER (LCC)
    - END-TO-END AND MISSION SEQUENCE TESTS WILL BE PERFORMED (IF REQUIRED)
  - PCR
    - FINAL ORDNANCE CONNECTIONS ARE MADE AND SAFING IS COMPLETED
    - ALL CLOSEOUT PREPARATIONS FOR FLIGHT ARE PERFORMED AND VERIFIED
    - PAYLOAD BAY DOORS ARE CLOSED AT L-10 DAYS
    - LATE SERVICING OR COMMANDS WILL BE ACCOMPLISHED THROUGH THE ORBITER UMBILICALS AS PART OF THE SHUTTLE COUNTDOWN PRIOR TO T-9 MINUTES
    - ACCESS IS EXTREMELY LIMITED AFTER INSTALLATION OF THE PAYLOAD AT THE VPF AND PCR
HUMANS IN SPACE
Space Shuttle System Payload Integration Process

KSC Payload Integration

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

PAYLOAD LAUNCH OPERATIONS CONTROL LOCATIONS

- LAUNCH CONTROL CENTER (LCC)
  - SHUTTLE COUNTDOWN AND LAUNCH CONTROL
  - KSC PAYLOAD MANAGEMENT AND TEST CONTROL
  - CUSTOMER ENGINEERING SUPPORT AREA (LPS DATA MONITORING)

- MISSION DIRECTOR'S CENTER (VERTICAL PAYLOADS)
  - CUSTOMER MANAGEMENT LAUNCH DIRECTION
  - COMMUNICATIONS TO ALL LOCATIONS

- D&C CONTROL ROOM (HORIZONTAL PAYLOADS)
  - CUSTOMER MANAGEMENT LAUNCH DIRECTION
  - COMMUNICATIONS TO ALL LOCATIONS

- CUSTOMER’S KSC PAYLOAD CONTROL STATION (VERTICAL PAYLOADS)
  - PAYLOAD COMMAND AND DATA EVALUATION
  - VOICE AND DATA COMMUNICATIONS TO LCC AND PAD

- OFF-SITE CONTROL
  - MISSION CONTROL AT JSC
  - PAYLOAD OPERATIONS CONTROL CENTER AT JSC
  - CUSTOMER'S MISSION CONTROL CENTER

POSTLANDING OPERATIONS

- AFTER KSC OR DFRF LANDING AND CREW EGRESS:
  - PAYLOAD BAY ENVIRONMENTAL LIMITS ARE MAINTAINED BY EXTERIOR UNITS
  - ORBITER IS TOWED TO A PROCESSING FACILITY FOR SAFING
  - REMOVAL OF RETURNING PAYLOADS AND AIRBORNE SUPPORT EQUIPMENT - APPROXIMATELY 3 DAYS AFTER LANDING AT KSC (EITHER DIRECT LANDING OR SHUTTLE CARRIER AIRCRAFT LANDING AT KSC)
  - PAYLOADS CAN BE TURNED OVER TO PAYLOAD OWNERS AS FOLLOWS:
    - SOME MIDDECKS CAN BE REMOVED PRIOR TO ORBITER TOW (LANDING + 2 HOURS)
    - REMAINING MIDDECK LOCKERS CAN BE REMOVED WITHIN 24 HOURS
    - OTHER PAYLOADS/AIE ARE REMOVED AFTER THE PAYLOAD BAY DOORS ARE OPENED (LAND AT KSC + 3 DAYS)

- NON-KSC/DFRF LANDINGS ARE COVERED BY KVT-PL-0014 AND APPROPRIATE ANNEX, KSC OFF-SITE OPERATIONS PLAN AND KCS-PL-0012.0, PAYLOAD OPERATIONAL LOGISTICS PLAN.
KSC Payload Integration

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

Kennedy Space Center Integration Activities

- Customer support required during all phases of integration activities for ground operations and related payload testing.

- Reviews requiring customer support are:
  - Ground Operations Review (GOR)
  - Payload Readiness Review (PRR)
  - Launch Readiness Review (LRR)
  - Flight Readiness Review (FRR)
  - Payload Management Countdown Review (PMCR)
HUMANS IN SPACE
Space Shuttle System Payload Integration Process

KSC Payload Integration

Dean C. Zimmerman
Kennedy Space Center, Payload Support Office

GENERIC PAYLOAD PROCESSING REVIEWS

SUMMARY OF AVAILABLE PPF'S

• BUILDING AE
  - HIGH BAY WORK AREA: 43 FT. 10 IN. BY 51 FT. 6 IN.
  - CRANE: 6-TON, 36 FT. 10 IN. LIFT
  - CLEANLINESS: CLASS 10,000, CMA LEVEL 2
  - ENTRY DOOR: 14 FT. 9 IN. WIDE BY 36 FT. 1 IN. HIGH

• HANGARS
  - HIGH BAY WORK AREAS
    • NORTH: 42 FT. 1 IN. BY 29 FT. 11 IN.
    • SOUTH: 45 FT. BY 55 FT.
  - CRANES: 2-TON, 19 FT. 1 IN. LIFT
  - CLEANLINESS: CLASS 100,000, CMA LEVEL 4
    (CAN MAINTAIN CLASS 10,000, CMA LEVEL 2)
  - ENTRY DOOR: 14 FT. 9 IN. WIDE BY 19 FT. 8 IN. HIGH

ORIGINAL PAGE IS OF POOR QUALITY.
This Page Intentionally Blank
**Title and Subtitle**

Technology for the Future: In-Space Technology Experiments Program

**Author(s)**

Roger A. Breckenridge, Lenwood G. Clark, Kelli F. Willshire, Sherwin M. Beck, and Lisa D. Collier (Compilers)

**Performing Organization Name and Address**

Space Station Freedom Office
NASA, Langley Research Center
Hampton, Virginia 23665-5225

**Sponsoring Agency Name and Address**

National Aeronautics and Space Administration
Washington, DC 20546-0001

**Abstract**

The purpose of the OAST In-STEP 88 Workshop was to identify and prioritize technologies that are critical for future national space programs and require validation in the space environment, and review current NASA (In-Reach) and Industry/University (Out-Reach) experiments. A prioritized list of the critical technology needs was developed for the following 8 disciplines: Structures; Environmental Effects; Power Systems and Thermal Management; Fluid Management and Propulsion Systems; Automation and Robotics; Sensors and Information Systems; In-Space Systems; and Humans in Space.

Part I is the Executive Summary and Experiment Description. The Executive Summary portion contains keynote addresses, strategic planning information, and the critical technology needs summaries for each theme. The Experiment Descriptions portion contains brief overviews of the objectives, technology needs and backgrounds, descriptions, and development schedules for current industry, university, and NASA space flight technology experiments.

**Key Words**

- Space Systems
- Space Technology
- Man/Systems Technology

**Distribution Statement**

Unclassified - Unlimited

**No. of pages**

307

**Price**

A14