Compressive Buckling Analysis of Hat-Stiffened Panel

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ABSTRACT

Buckling analysis was performed on a hat-stiffened panel subjected to uniaxial compression. Both local buckling and global buckling were analyzed. It was found that the global buckling load was several times higher than the local buckling load. The predicted local buckling loads compared favorably with both experimental data and finite-element analysis.

INTRODUCTION

Various advanced hot-structural panel concepts have been investigated for applications to hypersonic aircraft wing panels (ref. 1). Among those panels investigated, the beaded panels and the tubular panels were found to be highly efficient (that is, high stiffness to weight density ratio). The buckling behavior of these two types of hot-structural panels were studied extensively, both theoretically and experimentally (refs. 2 and 3).

One of the recently developed wing panels with potential application to hypersonic aircraft is a hat-stiffened panel, as shown in figure 1. This panel is equivalent to a corrugated core sandwich panel with one face sheet removed.

This report presents a buckling analysis of the hat-stiffened panel under uniaxial compression. The predicted buckling loads are compared with the experimental data and finite-element solutions.

NOMENCLATURE

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>cross-sectional area of reinforcing edge beam</td>
</tr>
<tr>
<td>A̅</td>
<td>cross-sectional area of global panel segment</td>
</tr>
<tr>
<td>a</td>
<td>length of global panel</td>
</tr>
<tr>
<td>b</td>
<td>width of rectangular flat plate segment</td>
</tr>
<tr>
<td>c</td>
<td>width of global panel</td>
</tr>
<tr>
<td>D</td>
<td>flexural rigidity of flat plate</td>
</tr>
<tr>
<td>d</td>
<td>one-half of diagonal region of corrugation leg</td>
</tr>
<tr>
<td>Ec</td>
<td>modulus of elasticity of hat material</td>
</tr>
<tr>
<td>Es</td>
<td>modulus of elasticity of face sheet material</td>
</tr>
<tr>
<td>f₁</td>
<td>lower flat region of hat stiffener</td>
</tr>
<tr>
<td>f₂</td>
<td>upper flat region of hat stiffener</td>
</tr>
<tr>
<td>Gc</td>
<td>shear modulus of hat material</td>
</tr>
<tr>
<td>Gs</td>
<td>shear modulus of face sheet material</td>
</tr>
<tr>
<td>h</td>
<td>distance between middle surfaces of hat</td>
</tr>
<tr>
<td>h₀</td>
<td>distance between middle surfaces of hat</td>
</tr>
<tr>
<td>I_c</td>
<td>polar moment of inertia of hat stiffener</td>
</tr>
</tbody>
</table>

NOMENCLATURE:

- \( A \): cross-sectional area of reinforcing edge beam that is the cross-sectional area of one corrugation leg, \( A = \ell \ell_e \), in²
- \( A̅ \): cross-sectional area of global panel segment bounded by \( p, A + pt_s + \frac{1}{2}(f_1 - f_2)tc \), in²
- \( a \): length of global panel, in.
- \( b \): width of rectangular flat plate segment, or horizontal distance between centers of corrugation and curved region, \( \frac{1}{2} [p - \frac{1}{2}(f_1 + f_2)] \), in.
- \( c \): width of global panel, in.
- \( D \): flexural rigidity of flat plate, \( \frac{E_c \ell_e^3}{12(1 - \nu^2)} \), lb-in²/in.
- \( d \): one-half of diagonal region of corrugation leg, in.
- \( E_c \): modulus of elasticity of hat material, lb/in²
- \( E_s \): modulus of elasticity of face sheet material, lb/in²
- \( f_1 \): lower flat region of hat stiffener, in.
- \( f_2 \): upper flat region of hat stiffener, in.
- \( G_c \): shear modulus of hat material, lb/in²
- \( G_s \): shear modulus of face sheet material, lb/in²
- \( h \): distance between middle surfaces of hat top flat region and face sheet, \( h_c + \frac{1}{2}(tc + ts) \), in.
- \( h_c \): distance between middle surfaces of hat top and bottom flat regions, in.
- \( h_o \): distance between middle surface of face sheet and centroid of global panel segment, in.
- \( I_c \): polar moment of inertia of hat stiffener, \( \frac{1}{12} \ell_e^3 \), in⁴/in.
\( I_c \) \quad \text{moment of inertia of corrugation leg of length } \ell \text{ (reinforcing edge beam) taken with respect to its neutral axis } \eta, \text{ in}^4

\( \bar{I}_c \) \quad \text{moment of inertia, per unit width, of one-half of reinforcing hat taken with respect to the neutral axis } \eta_0 \text{ of the hat-stiffened panel, in}^4/\text{in}

\( I_f \) \quad \frac{1}{12} t_s^3, \text{ in}^4/\text{in}

\( I_s \) \quad \text{moment of inertia, per unit width, of face sheet with respect to } \eta_0 \text{ axis passing through the centroid of the global panel segment, } t_s h_s^2 + \frac{1}{12} t_s^3, \text{ in}^4/\text{in}

\( k_z \) \quad \text{compressive buckling load factor, no dimension}

\( \ell \) \quad \text{length of corrugation leg}, f_z + 2 d + 2 R \theta, \text{ in.}

\( m \) \quad \text{number of buckle half-waves in } x\text{-direction}

\( (N_x)_{cr} \) \quad \text{panel compressive buckling load, lb/\text{in}}

\( n \) \quad \text{number of buckle half-waves in } y\text{-direction}

\( P \) \quad \text{compressive load, lb}

\( P_{cr} \) \quad \text{compressive buckling load, lb}

\( p \) \quad \text{one-half of reinforcing hat pitch, in.}

\( R \) \quad \text{radius of circular arc segments of corrugation leg, in.}

\( t_c \) \quad \text{thickness of reinforcing hat, in.}

\( t_s \) \quad \text{thickness of face sheet, in.}

\( x, y, z \) \quad \text{rectangular Cartesian coordinates, in.}

\( \beta \) \quad \text{panel aspect ratio, } a/c

\( \eta \) \quad \text{neutral axis of corrugation leg}

\( \eta_0 \) \quad \text{neutral axis of corrugation leg and face sheet combined}

\( \theta \) \quad \text{corrugation angle (angle between the face sheet and the straight diagonal segment of corrugation leg), rad}

\( \nu_c \) \quad \text{Poisson ratio of hat material}

\( \nu_s \) \quad \text{Poisson ratio of face sheet material}

\( \sigma_x \) \quad \text{compressive stress, lb/\text{in}^2}

\( (\sigma_x)_{cr} \) \quad \text{critical compressive stress, lb/\text{in}^2}

**APPROACH**

For analyzing the buckling behavior of the complex structure as shown in figure 1, two approaches will be taken: (1) local buckling analysis and (2) global buckling analysis (general panel instability).

**Local Buckling Analysis**

The local buckling analysis studies the buckling behavior of a local weak region of the panel. This weak region is identified as a rectangular flat plate region bounded by two legs of the reinforcing hat located at the center of the global panel, shown in the left diagram of figure 2. The local buckling analysis studies the buckling behavior of this rectangular flat plate (slender strip). Two types of edge conditions are considered: (1) elastically supported and (2) simply supported.
Elastically Supported

For this case, the two horizontal edges are assumed to be simply supported. The two vertical edges are supported by two elastic beams. Each of the beams has the same flexural rigidity as that of a semihat (one leg of corrugation), shown in the center diagram of figure 2.

Simply Supported

Because the reinforcing hat has high flexural rigidity, the two vertical edges of the rectangular plate are assumed simply supported, as shown in the right diagram of figure 2. Also, the two horizontal edges are assumed simply supported.

Global Buckling Analysis

In the global buckling analysis (general panel instability), the complex panel is represented by a homogeneous panel having effective elastic constants. These effective elastic constants must be calculated first. The analysis is similar to the conventional buckling analysis of sandwich panels (ref. 4).

COMPRESSION BUCKLING ANALYSIS

Local Buckling—Elastically Supported

The critical stress equation for a rectangular plate supported by elastic beams at its two vertical edges and subjected to uniaxial compression (ref. 5 and fig. 2) may be written as

\[
\sqrt{\Psi} \phi \left[ \Psi + (1 - \nu_s) \phi \right]^2 \tan \left( \frac{1}{2} \sqrt{\Psi} \phi \right) + \sqrt{\Psi + \phi} \left[ \Psi - (1 - \nu_s) \phi \right]^2 \tanh \left( \frac{1}{2} \sqrt{\Psi} \phi \right) = 2 \phi \Psi \xi
\]  

where

\[
\phi = \frac{m \pi b}{a}
\]  

\[
\Psi = b \sqrt{\frac{t_s \sigma_s}{D}}
\]  

\[
\xi = \frac{E_s I^*_c}{b D} - \frac{A \Psi^2}{b t_s \phi^2}
\]  

where

\[
D = \frac{E_s t_s^3}{12(1 - \nu_s^2)}
\]

\[
A = \ell t_c = (f_s + 2d + 2R \theta)t_c
\]

and \( I^*_c \) is the moment of inertia of a corrugation leg of length \( \ell \), taken with respect to its neutral axis \( \eta \) (fig. 3), and is given by

\[
I^*_c = h_c^3 t_c \left\{ \frac{1}{4} h_c \left( 1 + \frac{1}{3} \frac{t_c^2}{h_c^2} \right) + \frac{2}{3} \frac{d^3}{h_c^2} \left( \sin^2 \theta + \frac{1}{4} \frac{t_c^2}{d^2} \cos^2 \theta \right) \right\}
\]

\[
+ \frac{R}{h_c} \left[ \frac{\theta}{2} - \frac{R^2}{h_c^2} \sin \theta (1 - \cos \theta) - \frac{R}{h_c} \left( 2 - 3 \frac{R}{h_c} \right) (\theta - \sin \theta) \right]
\]
The panel buckling load \((N_x)_{cr}\) may then be obtained from

\[
(N_x)_{cr} = (\sigma_x)_{cr} \frac{\bar{A}}{p} \tag{8}
\]

where \(\bar{A}\) is the cross-sectional area of the panel segment bounded by one-half of the corrugation pitch \(p\) (fig. 3), and is given by

\[
\bar{A} = A + pl_s + \frac{1}{2}(f_1 - f_2)t_c \tag{9}
\]

**Local Buckling—Simply Supported**

The critical stress \((\sigma_x)_{cr}\) for the rectangular plate under uniaxial compression with four edges simply supported (ref. 5) may be written as

\[
(\sigma_x)_{cr} = \frac{\pi^2 D}{l_s a^2} \left(m + \frac{\pi^2 a^2}{m b^2}\right) \tag{10}
\]

The panel buckling load \((N_x)_{cr}\) can then be obtained from equation (8).

**Global Buckling—General Panel Instability**

The current hat-stiffened panel is equivalent to a corrugated-core sandwich panel with one face sheet removed. Thus, the buckling analysis of a corrugated-core sandwich panel (ref. 4) may be applied to the present problem with slight modifications of the effective elastic constants. The compressional panel buckling load \((N_x)_{cr}\) may be obtained from the following buckling equation (ref. 4):

\[
k_z = \frac{c^2 (N_x)_{cr}}{\pi^2 E_s I_s} \tag{11}
\]

\[
= \frac{a_{11}(a_{23}a_{32} - a_{22}a_{33}) + a_{21}(a_{12}a_{33} - a_{13}a_{32})}{a_{12}a_{23} - a_{22}a_{13}} \tag{12}
\]

where the coefficients \(a_{ij}\) (where \(i, j = 1, 2, 3\)) are defined as follows:

\[
a_{11} = \frac{m}{\beta} \left[ \frac{1}{1 - \nu_s^2} \frac{D_x}{E_s I_s} \frac{m^2}{\beta^2} + \left( \frac{\nu_s}{1 - \nu_s^2} \frac{D_x}{E_s I_s} + \frac{D_{xy}}{E_s I_s} \right) \frac{n^2}{\beta^2} \right] \tag{12}
\]

\[
a_{12} = - \left[ 1 + \frac{\pi^2 E_s I_s}{c^2 D_{q_y}} \left( \frac{1}{1 - \nu_s^2} \frac{D_x}{E_s I_s} \frac{m^2}{\beta^2} + \frac{1}{2} \frac{D_{xy}}{E_s I_s} \frac{n^2}{\beta^2} \right) \right] \tag{13}
\]

\[
a_{13} = - \frac{\pi^2 E_s I_s}{c^2 D_{q_y}} \left( \frac{\nu_s}{1 - \nu_s^2} \frac{D_x}{E_s I_s} + \frac{1}{2} \frac{D_{xy}}{E_s I_s} \right) \frac{mn}{\beta} \tag{14}
\]

\[
a_{21} = n \left[ \frac{1}{1 - \nu_s^2} \frac{D_y}{E_s I_s} \frac{n^2}{\beta^2} + \left( \frac{\nu_s}{1 - \nu_s^2} \frac{D_y}{E_s I_s} + \frac{D_{xy}}{E_s I_s} \right) \frac{m^2}{\beta^2} \right] \tag{15}
\]

\[
a_{22} = - \frac{\pi^2 E_s I_s}{c^2 D_{q_x}} \left( \frac{\nu_s}{1 - \nu_s^2} \frac{D_y}{E_s I_s} + \frac{1}{2} \frac{D_{xy}}{E_s I_s} \right) \frac{mn}{\beta} \tag{16}
\]
\[ a_{23} = - \left[ 1 + \frac{n^2 E_s I_s}{c^2 D_{Q_y}} \left( \frac{1}{1 - \nu_s^2} \frac{D_y n^2}{E_s I_s} + \frac{1}{2} \frac{D_{sy} m^2}{E_s I_s} \right) \right] \] (17)

\[ a_{32} = -\frac{\beta}{m} \] (18)

\[ a_{33} = -\frac{\beta^2}{m^2 n} \] (19)

where

\[ D_x = E_c I_c + E_s I_s \] (20)

\[ D_y = E_s I_s \frac{1 + \frac{E_s I_c}{E_s I_s}}{1 + (1 - \nu_s^2) \frac{E_s I_c}{E_s I_s}} \] (21)

\[ I_s = t_s h_o^2 + \frac{1}{12} t_s^3 \] (22)

and \( I_c \) is the moment of inertia of the corrugation leg and face sheet combined, taken with respect to neutral axis \( \eta_o \) (fig. 3):

\[ I_c = \frac{I_c}{p} + \frac{A}{p} \left( \frac{1}{2} (h_c + t_c + t_s) - h_o \right)^2 + \frac{1}{24} \left( f_1 - f_2 \right) t_c^2 + \frac{f_1 - f_2}{2p} t_c \left( h_o - \frac{t_c + t_s}{2} \right)^2 \] (23)

where \( h_o \) is the distance between the middle surface of the face sheet and the centroid of the global panel segment:

\[ h_o = \frac{1}{2} A \left[ A(h_c + t_c + t_s) + \frac{1}{2} t_c (f_1 - f_2) (t_c + t_s) \right] \] (24)

and \( D_{xy} \) appearing in \( a_{ij} \) may be obtained from reference 6 with slight modification to fit the present problem in the following form:

\[ D_{xy} = 2 \overline{GJ} \] (25)

where

\[ \overline{GJ} = \left[ G_s I_s k_{GJ}^2 + \frac{2G_c I_c}{A_c} (k_{GJ} - k_c)^2 \right] h^2 \] (26)

where

\[ k_{GJ} = \frac{k_c}{1 + \frac{A_G A_s I_s}{p G_c I_c}} \] (27)

and

\[ k_c = \frac{1}{2} \left[ 1 - \frac{(f_1 - f_2) h_c}{2ph} \right] \] (28)

\[ A_c = \left[ e + \frac{1}{2} (f_1 - f_2) \right] t_c \] (29)

\[ \text{5} \]
and

\[ D_{Qz} = \frac{G_{e} c_{e} \hbar^{2}}{p \ell} \]

\[ D_{Qy} = \frac{\hbar}{\pi} \frac{\varepsilon_{c}}{1 - \varepsilon_{c}^{2}} \left( \frac{t_{c}}{\hbar_{c}} \right)^{3} \]

where

\[ S = \frac{6 \frac{\hbar}{p_{c}} D_{z}^{F} + \left( \frac{p}{h_{c}} \right)^{2}}{12 \left\{ \frac{h}{h_{c}} \frac{p_{c}}{h_{c}} D_{z}^{F} - 2 \left( \frac{p}{h_{c}} \right)^{2} D_{z}^{H} + \frac{h}{h_{c}} \left[ 6 \frac{t_{c}}{h_{c}} \left( D_{z}^{F} D_{y}^{H} - D_{z}^{H} D_{y}^{F} \right) + \left( \frac{p}{h_{c}} \right)^{3} D_{y}^{H} \right] \right\}} \]

where

\[ D_{z}^{F} = \frac{2}{3} \left( \frac{d}{h_{c}} \right)^{3} \cos^{2} \theta + \frac{2 I_{e}}{3 I_{f}} \left[ \frac{1}{8} \left( \frac{p}{h_{c}} \right)^{3} - \left( \frac{b}{h_{c}} \right)^{3} \right] \]

\[ + \frac{R}{h_{c}} \left[ 2 \left( \frac{b}{h_{c}} \right)^{3} \theta - 4 \frac{Rb}{h_{c}^{2}} (1 - \cos \theta) + \left( \frac{R}{h_{c}} \right)^{2} (\theta - \sin \theta \cos \theta) \right] \]

\[ + \frac{I_{c}}{h_{c}^{2} t_{c}} \left[ 2 \frac{d}{h_{c}} \sin^{2} \theta + \frac{R}{h_{c}} (\theta - \sin \theta \cos \theta) \right] \]

\[ D_{z}^{H} = \frac{2}{3} \left( \frac{d}{h_{c}} \right)^{3} \sin \theta \cos \theta + \frac{1}{2} I_{f} \left[ \frac{1}{4} \left( \frac{p}{h_{c}} \right)^{2} - \left( \frac{b}{h_{c}} \right)^{2} \right] \]

\[ + \frac{R}{h_{c}} \left\{ \frac{b}{h_{c}} \theta - 2 \frac{Rb}{h_{c}^{2}} (\theta - \sin \theta) - \frac{R}{h_{c}} (1 - \cos \theta) \left[ 1 - \frac{R}{h_{c}} (1 - \cos \theta) \right] \right\} \]

\[ - \frac{I_{c}}{h_{c}^{2} t_{c}} \left( 2 \frac{d}{h_{c}} \sin \theta \cos \theta + \frac{R}{h_{c}} \sin^{2} \theta \right) \]

\[ D_{y}^{F} = \frac{2}{3} \left( \frac{d}{h_{c}} \right)^{3} \sin^{2} \theta + \frac{1}{2} \left( \frac{R}{h_{c}} \theta + \frac{1}{2} \frac{f}{h_{c} I_{f}} \right) \]

\[ - \left( \frac{R}{h_{c}} \right)^{2} \left[ \left( 2 - 3 \frac{R}{h_{c}} \right) (\theta - \sin \theta) + \frac{R}{h_{c}} \sin \theta (1 - \cos \theta) \right] \]

\[ + \frac{I_{c}}{h_{c}^{2} t_{c}} \left[ \frac{f}{h_{c} t_{f}} + 2 \frac{d}{h_{c}} \cos^{2} \theta + \frac{R}{h_{c}} (\theta + \sin \theta \cos \theta) \right] \]

where

\[ f = \frac{1}{2} (f_{1} + f_{2}) \]

\[ I_{e} = \frac{1}{12} t_{e}^{3} \]

\[ I_{f} = \frac{1}{12} t_{f}^{3} \]

\[ b = \frac{1}{2} \left[ p - \frac{1}{2} (f_{1} + f_{2}) \right] \]
NUMERICAL RESULTS

The titanium hat-stiffened panel has the following material properties and geometries:

\[ E_s = E_c = 16 \times 10^6 \text{ lb/in}^2 \]
\[ G_s = G_c = 6.2 \times 10^6 \text{ lb/in}^2 \]
\[ \nu_s = \nu_c = 0.31 \]
\[ a = 24 \text{ in.} \]
\[ b = 1.77 \text{ in.} \text{ (width of rectangular flat strip)} \]
\[ c = 24 \text{ in.} \]
\[ d = 0.3505 \text{ in.} \]
\[ f_1 = 1.12 \text{ in.} \]
\[ f_2 = 0.26 \text{ in.} \]
\[ h = h_c + \frac{t_s}{2} = 1.202 \text{ in.} \]
\[ h_c = 1.1860 \text{ in.} \]
\[ p = 1.49 \text{ in.} \]
\[ R = 0.346 \text{ in.} \]
\[ t_s = t_c = 0.032 \text{ in.} \]
\[ \theta = 79.13^\circ = 1.3811 \text{ rad} \]

Local Buckling—Elastically Supported

The experimental observations by R. Fields (ref. 7) and the finite-element buckling analysis (carried out by W. Percy of McDonnell Douglas, ref. 7) showed that the flat rectangular plate strip (fig. 2) would buckle with 13 buckle half-waves \((m = 13)\) in the \(x\)-direction and 1 buckle half-wave \((n = 1)\) in the \(y\)-direction (fig. 4). Thus, by taking \(m = 13, n = 1\), equation (1) gives the buckling stress \((\sigma_x)_{cr}\) of the rectangular plate

\[ (\sigma_x)_{cr} = 19,060 \text{ lb/in}^2 \]

from which the panel buckling load \((N_x)_{cr}\) is calculated from equation (8) as

\[ (N_x)_{cr} = 1600 \text{ lb/in} \]

which gives the buckling load of \(P_{cr} = 38,400 \text{ lb}\).

Local Buckling—Simply Supported

For \(m = 13, n = 1\), equation (10) gives

\[ (\sigma_x)_{cr} = 19,068 \text{ lb/in}^2 \]
which gives the value of the panel buckling load \((N_x)_{cr}\) (eq. (8)) as
\[
(N_x)_{cr} = 1601 \text{ lb/in}^2
\]
The compressive buckling load will then be \(P_{cr} = 38,424\) lb, which is slightly larger than the previous case.

Both of the previous two predictions are slightly lower than the buckling load of 39,700 lb calculated from finite-element buckling analysis and the measured value of 41,403 lb by Fields (ref. 7).

### Global Buckling

The lowest buckling load for the global buckling will occur at \(m = 1\) and \(n = 1\). Thus, the panel buckling load calculated from equation (11) has the value of \(k_x = 5.61\), which gives
\[
(N_x)_{cr} = 4917 \text{ lb/in}
\]
which gives the compressive buckling load of \(P_{cr} = 108,008\) lb. This load is approximately three times larger than the value predicted from local buckling analysis. Thus, the global buckling is unlikely to occur before the local buckling.

The following table summarizes the present results of the compressive buckling study.

<table>
<thead>
<tr>
<th>Case</th>
<th>((N_x)_{cr}), lb/in</th>
<th>(P_{cr}), lb</th>
</tr>
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<tbody>
<tr>
<td>Local buckling:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Elastically supported</td>
<td>1,600</td>
<td>38,400</td>
</tr>
<tr>
<td>Simply supported</td>
<td>1,601</td>
<td>38,424</td>
</tr>
<tr>
<td>Global buckling</td>
<td>4,500</td>
<td>108,008</td>
</tr>
<tr>
<td>W. Percy's finite element</td>
<td>1,654</td>
<td>39,700</td>
</tr>
<tr>
<td>Fields' experiment (ref. 7)</td>
<td>1,725</td>
<td>41,403</td>
</tr>
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</table>

The predicted local compressive buckling loads are slightly lower than the value predicted from Percy’s finite-element buckling analysis, and are also lower than Field’s experimental value. The reason may be the existence of the reinforcements at the test panel edges (fig. 4), which were neglected in the compressive buckling analysis.

### CONCLUSION

Compressive buckling behavior of a hat-stiffened panel was analyzed in the light of local bucklings and global buckling. The predicted compressive local buckling loads were slightly lower than the value predicted from finite-element buckling analysis and were also lower than the experimental value. The reason may be the existence of the reinforcements at the panel edges, which were ignored in the analysis.

The global buckling theory predicted the compressive buckling load approximately three times more than the values predicted from local buckling theories. Therefore, the hat-stiffened panel will buckle locally instead of globally.

*Dryden Flight Research Facility*

*National Aeronautics and Space Administration*

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REFERENCES


Figure 1. Hat-stiffened panel under uniaxial compression.
Figure 2. Compressive buckling of hat-stiffened panel analyzed by using two simplified local models.
Figure 3. Segment of hat-stiffened flat panel.
Figure 4. Buckled shape of hat-stiffened panel under uniaxial compression. (Finite-element buckling analysis by W. Percy, McDonnell Douglas, ref. 7.)
Buckling analysis was performed on a hat-stiffened panel subjected to uniaxial compression. Both local buckling and global buckling were analyzed. It was found that the global buckling load was several times higher than the local buckling load. The predicted local buckling loads compared favorably with both experimental data and finite-element analysis.