ELECTRONIC NEURAL NETWORKS

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ELECTRONIC NEURAL NETWORKS
JET PROPULSION LABORATORY

BACKGROUND

• NEURAL NETWORKS OFFER A TOTALLY NEW APPROACH TO INFORMATION PROCESSING THAT IS ROBUST, FAULT- TOLERANT, AND FAST.

• MODELS OF NEURAL NETWORKS ARE BASED ON HIGHLY PARALLEL AND DISTRIBUTIVE ARCHITECTURES.

• JPL IS DEVELOPING ELECTRONIC IMPLEMENTATIONS OF ARTIFICIAL NEURAL NETWORKS TO EXPLOIT THEIR EMERGENT PROPERTIES FOR "INTELLIGENT" KNOWLEDGE ENGINEERING APPLICATIONS.

• IN AN ELECTRONIC EMBODIMENT, "NEURONS" ARE REPRESENTED BY THRESHOLD AMPLIFIERS, AND "SYNAPSES" BY RESISTORS. INFORMATION IS STORED IN THE VARYING STRENGTHS OF SYNAPTIC CONNECTIONS.

• ELECTRONIC IMPLEMENTATIONS OF APPLICATION - SPECIFIC HIGH SPEED NEUROPROCESSORS FOR:
  • ASSOCIATIVE RECONSTRUCTION
  • CARTOGRAPHIC ANALYSIS
  • RESOURCE ALLOCATION
  • GLOBAL OPTIMIZATION
  • AUTONOMOUS CONTROL
INTRODUCTION

- ARTIFICIAL NEURAL NETWORKS:

- MASSIVELY PARALLEL ARCHITECTURES INSPIRED BY THE NATURE'S APPROACH TO INTELLIGENT INFORMATION PROCESSING

- KEY QUESTIONS:

- WHAT GOOD ARE THEY?

- CAN THEY DO SOMETHING UNIQUE FOR SPACE STATION?

- WHEN WILL THEY DELIVER?
A HUMAN BRAIN HAS OVER $10^{14}$ NEURONS AND $10^{10}$ SYNAPSES.

HARDWARE IMPLEMENTATIONS TODAY ARE AT ABOUT $10^3$ NEURONS AND $10^5$ SYNAPSES.

THE BRAIN IS NOT FULLY CONNECTED!

THE CURRENT ARTIFICIAL NEURAL NETWORKS ARE ALREADY PROVING THEMSELVES EXTREMELY USEFUL.

NEURAL NETWORKS ARE NOT GENERAL PURPOSE COMPUTERS. THEY ARE SPECIAL-PURPOSE HIGH PERFORMANCE CO-PROCESSORS.
NEURAL NETWORK

BASIC COMPONENTS:
- NEURONS
- SYNAPSES

ELECTRONIC IMPLEMENTATION:

INPUT NEURON OUTPUT
ELECTRONIC NEURAL NETWORKS
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NEURAL NETWORK ARCHITECTURES

\[
\dot{C}_i \frac{du_i}{dt} = \sum T_{ij} V_j - \frac{u_i}{R_i} + I_i
\]

FEEDBACK NETWORK

FEEDFORWARD, LAYERED
ELECTRONIC IMPLEMENTATIONS

- JPL'S APPROACH HAS BEEN:
  - TO DEVELOP NEURAL NET "BUILDING BLOCKS" FOR MODULAR HARDWARE
  - TO VERIFY DESIGN OF NEUROCIRCUITS IN SIMULATION
  - TO TAILOR "NEUROPROCESSORS" FOR SELECTED APPLICATIONS

- TECHNOLOGIES:
  - VLSI: CMOS, BIPOLAR, AND EEPROM (FLOATING GATE)
  - THIN FILM: AMORPHOUS SEMICONDUCTORS, ELECTROCHROMIC MATERIALS, AND CHEMICAL MICROSWITCHES
  - HYBRID: VLSI/THIN FILM, SINGLE/MULTI-CHIP, WAFER-LEVEL INTEGRATION
VLSI/THIN FILM HYBRID HARDWARE FOR NEUROCOMPUTING

1024 CAPACITOR-REFRESH, ANALOG SYNAPSE CHIP

32 x 32 BINARY SYNAPSE CHIP

A NEURAL-DIGITAL HYBRID COMPUTER SYSTEM

A NEURO-PROCESSOR

17-NEURON ARRAY CHIP

HIGH DENSITY, THIN FILM SYNAPTIC ARRAY
ELECTRONIC NEURAL NETWORKS

JET PROPULSION LABORATORY
CASCADABLE, PROGRAMMABLE, 32 x 32 SYNAPTIC CMOS CHIP

- A BUILDING BLOCK FOR VLSI NEURAL NET HARDWARE
- PROVIDES OVER $10^9$ ANALOG OPERATIONS/SEC
- POTENTIAL APPLICATIONS:
  - MULTI SENSOR DATA FUSION
  - ASSOCIATIVE RECONSTRUCTION
  - PATTERN RECOGNITION
COMPUTATION WITH ANALOG PARALLEL PROCESSING

- NEURAL NETWORK ARCHITECTURES
- CELLULAR ARRAY PROCESSORS
- CUSTOM THIN FILM MICRODEVICES

- ASSOCIATIVE MEMORY
- AUTONOMOUS CONTROL
- GLOBAL OPTIMIZATION
- CARTOGRAPHIC ANALYSIS
- PATH PLANNING
- RESOURCE ALLOCATION
- HIGH-DENSITY INTERCONNECTIONS
- NON-VOLATILE ANALOG MEMORIES
FEATURES OF NEUROPROCESSORS

• APPLICATION-SPECIFIC ARCHITECTURES

• FINE-GRAIN, MASSIVELY PARALLEL, ANALOG, ASYNCHRONOUS PROCESSING

• EXTREMELY HIGH SPEED: TERRA-OPS RANGE

• INHERENT FAULT-TOLERANCE

• UNIQUE CAPABILITIES TO "LEARN" FROM EXPERIENCE AND SELF-ORGANIZE

• TRULY ENABLING NATURE, COMPLEMENTING THE ABILITIES OF HIGH SPEED DIGITAL MACHINES
APPLICATIONS OF NEUROPROCESSORS

- AUTOMATION AND ROBOTICS

- ON-BOARD, REAL-TIME, GLOBAL OPTIMIZATION
  - ALLOCATION AND MANAGEMENT OF RESOURCES

- AUTONOMOUS, SCHEDULING, SEQUENCING, AND EVENT-DRIVEN MISSION REPLANNING

- SCIENCE DATA ANALYSIS AND MANAGEMENT
  - PATTERN RECOGNITION, CLASSIFICATION
  - MODELING OF LARGE SYSTEMS
  - CODING, DECODING, ASSOCIATIVE RECONSTRUCTION FROM CORRUPT DATA
Neural network classification results. Each color denotes a particular decision or classification for a pixel. e.g., green = "GO", yellow = "GO SLOW", orange = "GO VERY SLOW", and red = "NO GO".
NEURAL NETWORK HARDWARE FOR TERRAIN TRAFFICABILITY DETERMINATION
A DEDICATED PROCESSOR FOR PATH PLANNING

- MASSIVELY PARALLEL, ANALOG, ASYNCHRONOUS PROCESSING

- ACCEPTABLE SOLUTION IN REAL TIME, THAN THE BEST SOLUTION AFTER A LONG TIME

- ORDERS OF MAGNITUDE SPEED IMPROVEMENT, PARTICULARLY FOR "WHAT IF" EXPERIMENTS
HARDWARE DETAIL FOR SIGNAL SORTER AND MAP SEPARATES APPLICATIONS

I/O BUS

DOWNLOAD INTERFACE

MUX INPUT NEURON 64-CH

32 x 32 SYNAPSE CHIP

32 x 32 SYNAPSE CHIP

32 x 32 SYNAPSE CHIP

32 x 32 SYNAPSE CHIP

32 NEURON CHIP

32 x 32 SYNAPSE CHIP

32 NEURON CHIP

DOWNLOAD INTERFACE

A/D BOARD

SIGNAL SORTER 128-1024 INPUT UNITS
MAP SEPARATES 64-256 INPUT UNITS

DOWNLOAD INTERFACES

I/O BUS
ELECTRONIC NEURAL NETWORKS
RAPID HARDWARE PROTOTYPING OF
NEURAL PROCESSORS FOR "REAL" PROBLEMS

THE PROBLEMS

• MAP KNOWLEDGE BASE APPLICATIONS REQUIRING LARGE AMOUNTS
  OF DATA AND HIGH SPEED PROCESSING

  • CROSS-COUNTRY MOBILITY DETERMINATION: A MULTIDIMENSIONAL
    EUCLIDEAN DISTANCE MINIMIZATION PROBLEM

• GENERATION OF MAP SEPARATES: AN IMAGE SEGMENTATION
  PROBLEM

• DETERMINATION OF "BEST" PATH: A ROUTING PROBLEM

THE SOLUTION

• DEDICATED NEUROPROCESSORS IMPLEMENTING NEURAL ALGORITHMS
  FOR SOLVING THESE PROBLEMS

• THESE NEUROPROCESSORS WILL BE INTERFACED WITH A PORTABLE
  ASAS WORK STATION (PAWS) FOR USER EVALUATION AT THE CENTER
  FOR SIGNALS WARFARE (CSW)
NEURAL NETS FOR ROBOTIC CONTROL

Layered, feed-forward nets with abilities to 'learn' from 'experience'

Layered Neural Network Diagram

- Learning Algorithm: Error Back Propagation
- 'Knowledge' is accumulated in the analog synaptic weights
ERROR BACKPROPAGATION ALGORITHM FOR LEARNING

RANDOMIZE SYNAPTIC WEIGHTS

FEED INPUT

FORWARD PASS

COMPARE OUTPUT WITH DESIRED TARGET

GENERATE ERROR VECTOR

IS LEARNING COMPLETE?

ADJUST WEIGHTS

\[ \Delta w_{ij} = \eta \delta_i \sigma_j \]

STORE WEIGHTS

YES

ERROR < TOLERANCE

NO
RESOURCE ALLOCATION MATRIX
## RESOURCE ALLOCATION PROCESSOR SIMULATION

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GLOBAL OPTIMIZATION NEUROPROCESSOR

- RESOURCE ALLOCATION
- DYNAMIC ASSIGNMENT
- MESSAGE ROUTING
- TARGET-WEAPON PAIRING
- LOAD BALANCING
- MULTI-TARGET TRACKING
- SEQUENCING / SCHEDULING
- REAL TIME, ADAPTIVE MISSION RE-PLANNING

NEUROPROCESSING APPROACH OFFERS OVER 4 ORDERS OF MAGNITUDE SPEED ENHANCEMENT OVER THE CONVENTIONAL COMPUTING TECHNIQUES.

ARBITRARY MULTIPLE TO MULTIPLE ASSIGNMENTS ARE POSSIBLE, WHICH ARE NOT EASILY ACCOMPLISHED BY CONVENTIONAL TECHNIQUES.
ELECTRONIC NEURAL NETWORKS

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PROGRAMMABLE, NONVOLATILE, HIGH-DENSITY, THIN FILM SYNAPTIC ARRAY FOR INFORMATION STORAGE

- POTENTIAL FOR HIGH DENSITY APPROACHING $10^9$ BITS/CM$^2$
- FAULT-TOLERANCE
- ASSOCIATIVE, CONTENT-ADDRESSABLE RECALL
- NO MOVING PARTS
- STORAGE IN "PASSIVE," RAD-HARD INTERCONNECTIONS
ELECTRICALLY PROGRAMMABLE
READ ONLY THIN-FILM SYNAPTIC ARRAY

A 62 x 62 SYNAPSE TEST ARRAY WITH
4-μm FEATURE SIZE

a-Si:H MICROSWITCH
AND RESISTOR SANDWICHED
BETWEEN METAL ELECTRODES
CONCLUSIONS

• THE FIELD OF NEUROPROCESSING HAS SIGNIFICANTLY ADVANCED IN RECENT YEARS. INVESTMENTS OF DOD AND NASA ARE RESULTING IN THE DEVELOPMENT OF APPLICATION-SPECIFIC, HIGH PERFORMANCE, MODULAR NEUROPROCESSORS.

• SUCH NEUROPROCESSORS OFFER TOTALLY NEW CAPABILITIES, COMPUTATIONAL BREAKTHROUGHS, AND ORDERS OF MAGNITUDE PERFORMANCE ENHANCEMENT WHERE CONVENTIONAL PROCESSING METHODS CHOKE.

• DOD IS MOVING AHEAD IN THE DIRECTION OF HARDWARE PROTOTYPING OF DEPLOYABLE NEUROPROCESSORS FOR COMPLEX PROBLEMS IN BATTLEFIELD MANAGEMENT AND TACTICAL FUSION OF INTELLIGENCE, ETC.

• TIME IS RIGHT FOR NASA TO TAKE ADVANTAGE OF THIS POWERFUL TECHNOLOGY. TAILORED NEUROPROCESSORS WILL BE IDEALLY SUITED TO SATISFY NASA'S UNIQUE AND GROWING DEMANDS IN COMPUTATION AND DATA MANAGEMENT WITH THE EVOLUTIONARY DEVELOPMENT OF SPACE STATION.