THE COMPRESSIBLE LAMINAR BOUNDARY LAYER WITH HEAT TRANSFER AND ARBITRARY PRESSURE GRADIENT

By CLARENCE B. COHEN and ELI RESHOTKO

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Lewis Flight Propulsion Laboratory
Cleveland, Ohio
National Advisory Committee for Aeronautics

Headquarters, 1512 H Street NW, Washington 25, D.C.

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SUMMARY

An approximate method for the calculation of the compressible laminar boundary layer with heat transfer and arbitrary pressure gradient, based on Thwaites' correlation concept, is presented. The method results from the application of Stewartson's transformation to Prandtl's equations, which yields a nonlinear set of two first-order differential equations. These equations are then expressed in terms of dimensionless parameters related to the wall shear, the surface heat transfer, and the transformed free-stream velocity. Thwaites' concept of the unique interdependence of these parameters is assumed. The evaluation of these quantities is then carried out by utilizing exact solutions recently obtained.

With the resulting relations, methods are derived for the calculation of the twodimensional and axially symmetric laminar boundary layer with arbitrary free-stream velocity distribution, Mach number, and surface temperature level.

The combined effect of heat transfer and pressure gradient is demonstrated by applying the method to calculate the characteristics of the boundary layer on thin supersonic surfaces and in a highly cooled, convergent-divergent, axially symmetric rocket nozzle.

INTRODUCTION

In recent years, with the advent of laminar airfoils and with the observation of laminar boundary layers at Reynolds numbers as high as $50 \times 10^6$ (ref. 2), the ability to reliably estimate viscous flow and heat-transfer effects for a laminar boundary layer has become increasingly important. Moreover, with high-altitude flight becoming more common, the subsequent lower Reynolds numbers encountered should more frequently produce a laminar boundary layer. Stability calculations based on the theory of Lees and Lin (ref. 3) have also emphasized the possibilities of maintaining a laminar boundary layer through cooling of aerodynamic surfaces. The effect of favorable pressure gradients in increasing the stability of laminar boundary layers may also make solutions to the laminar problem applicable to the design of nozzles and turbine blades.

Solutions of the laminar-boundary-layer equations that include effects of compressibility, pressure gradient, and heat transfer have been quite limited in number. Of the exact solutions, most have restrictions of range or application, or both. The solutions of references 4 and 5 are restricted to zero pressure gradient, while those of reference 6 allow small pressure gradients. The developments of reference 7 are restricted to small heat transfer and low Mach number. Solutions obtained by assuming that fluid properties are constant or that the Mach number is essentially zero are obtained in references 8 to 10. Those solutions of references 11 to 13 that are for a Prandtl number of 1 are not restricted in range of compressibility, pressure gradient, or heat transfer. However, they apply to specific types of free-stream velocity distribution that are inappropriate for general practical problems.

In 1921, von Kármán (ref. 14) recognized that to solve the skin-friction problem it was not necessary to have the exact and complicated solution, but that it would be quite satisfactory to evaluate average quantities across the layer if they could be related to the surface values. The concepts of displacement and momentum thicknesses were introduced; thus considerably simplifying the mathematics of the problem. With this integral method, if the form of the velocity profile is related to a single parameter, a method of calculating the boundary layer is obtained. Pohlhausen (ref. 15) carried out this method by postulating a quartic velocity profile depending upon the local pressure gradient. A number of investigators have extended Pohlhausen’s method to compressible flows over insulated surfaces.

With the presence of heat transfer at the surface, the compressible problem becomes more complex. Kalikhman (ref. 16) defined certain heat-flow quantities analogous to the displacement and momentum thicknesses and, in a manner similar to Pohlhausen's, developed a complex iterative procedure for the solution of the general problem. More recently, references 17 to 20 have further developed this technique. The preceding methods are tedious, since they require a solution of at least one ordinary differential equation for any particular problem.

Thwaites' method (ref. 21) does not require the solution of ordinary differential equations. In that formulation, it is suggested that the basic goal of an integral approach might be achieved if the problem is considered as that of relating the wall shear, its normal derivative at the wall, and the form factor (ratio of displacement thickness) to one another without specifying a type of profile. To this end, nondimensional forms of these quantities were defined and were evaluated.
by examining exact solutions for the incompressible laminar boundary layer. It developed that a nearly universal relation existed between these quantities for favorable pressure gradients, and for adverse pressure gradients Thwaites selected a single representative relation. A unique correlation was chosen that reduced the solution of an incompressible problem to the evaluation of a single integral.\(^3\)

Rott and Crabtree (ref. 23) recognized that, in the absence of heat transfer and with a Prandtl number of 1, the Illingworth-Stewartson correlation between compressible and incompressible boundary-layer solutions (ref. 24) could be used to extend Thwaites' method to include effects of compressibility.

With the presence of heat transfer the application of Stewartson's transformation does not correlate a given compressible problem to an equivalent incompressible one. Thus, the universal relation previously described is not adequate. Unfortunately, there is little possibility of establishing a family of universal relations with, for example, the wall temperature as the distinguishing parameter, since a variety of exact solutions to this problem is not available. However, one such set of relations may be obtained from the solutions of references 11 to 13.

In the present paper, after formulation of a nonlinear system of two first-order differential equations (with the major restriction being a linear viscosity law), methods of solution are developed depending on Thwaites' concept of universal functions. The functions used for this purpose are evaluated from the solutions of reference 12 only.

**BOUNDARY-LAYER EQUATIONS**

The equations of the steady, two-dimensional compressible laminar boundary layer for perfect fluids are

**Continuity:**

\[
\frac{\partial}{\partial x} (\rho u) + \frac{\partial}{\partial y} (\rho v) = 0
\]

(1)

**Momentum:**

\[
\rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial u}{\partial y} - \frac{\partial p}{\partial x} + \frac{\partial}{\partial y} \left( \mu \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial y} \left( \frac{\partial p}{\partial y} \right) = 0
\]

(2)

**Energy:**

\[
\rho u \frac{\partial h}{\partial x} + \rho v \frac{\partial h}{\partial y} = u \frac{\partial p}{\partial x} + \frac{\partial}{\partial y} \left( \mu \frac{\partial h}{\partial y} \right) + \frac{\partial}{\partial y} \left( \frac{\partial p}{\partial y} \right)
\]

(3)

(All symbols are defined in appendix A.)

The viscosity law to be assumed is

\[
\frac{\mu}{\mu_0} = \lambda \frac{t}{t_0}
\]

(4)

Equation (4) is of the form taken by Chapman and Rubesin (ref. 5), except that the reference conditions \((\rho_0, t_0)\) are free-stream stagnation values, since, in the case of pressure gradient, the local stream values are not constant along the flow. The constant \(\lambda\) is used to match the viscosity with the Sutherland value at a desired location. If this location is assumed to be the surface, the result is

\[
\lambda = \left( \frac{t + k_w}{t + k_w} \right) \sqrt{\frac{t}{t_0}}
\]

(5)

where

\[ k_w = \text{Sutherland's constant} = 198.6^\circ R \text{ (for air)} \]

**Stewartson's transformation.** —The velocities in the equations of motion (1) to (3) can be replaced through the definition of a stream function:

\[
\begin{align*}
\psi_x &= \frac{\rho_0 u}{\rho u} \\
\psi_y &= \frac{\rho_0 v}{\rho v}
\end{align*}
\]

(6)

Introducing the quantity \(\lambda\) from equation (4), a slight modification of Stewartson's transformation (ref. 24) may be written:

\[
\begin{align*}
X &= \int_0^x \lambda \frac{a_x}{a_{xx}} \phi \, dx \\
Y &= \int_0^y \lambda \frac{a_y}{a_{yy}} \phi \, dy
\end{align*}
\]

(7)

The transformed coordinates are now represented by uppercase letters \((X, Y)\), and the subscript \(e\) refers to local conditions at the outer edge of the boundary layer (external). The subscript 0 refers to free-stream stagnation values.

Applying equations (4) to (7) to the boundary-layer equations (1) to (3) and assuming that \(P_r\) and \(\epsilon_p\) are constant (but not yet requiring that \(P_r=1\)) result in the following system:

\[
\begin{align*}
U_x + V_y &= 0 \\
UU_x + VV_y &= U_e U_{ex} (1 + S) + v_o U_{yy} \\
US_x + VS_y &= \frac{S_{yy}}{P_r} - \frac{1}{P_r} \left( \frac{\gamma - 1}{2} \frac{M_i^2}{M_f^2} \right) \left[ \left( \frac{U}{U_e} \right) + \left( \frac{V}{V_e} \right) \right]
\end{align*}
\]

(8) (9) (10)

where the enthalpy term \(S\) is defined for convenience as

\[
S = \frac{h_s}{h_0} - 1
\]

(11)

where \(h_s\) is the local stagnation enthalpy. The stream function has been replaced by the transformed velocities \((U, V)\) through the relations

\[
\begin{align*}
U &= \psi_y \\
V &= -\psi_x
\end{align*}
\]

(12)

The resulting relation between the transformed and physical longitudinal velocities is \(U = \frac{a_y}{a_x} u\).
The boundary conditions applicable to the system (8) to (10) for a specified wall temperature are
\[ U(X,0) = 0 \]
\[ V(X,0) = 0 \]
\[ S(X,0) = S_w(X) \]
\[ \lim_{Y \to 0^+} S = 0 \]
\[ \lim_{Y \to 0^+} U = U_s(X) \]  \hspace{1cm} (13)

**Integral equations.**—An alternate form of the momentum equation may be obtained by subtracting the momentum equation (9) from the product of the continuity equation (8) and the quantity \( U_e - U \). This results in
\[
[U(U_e - U)]_x + [V(U_e - U)]_y + U_{ex}(U_e - U) + \int U_s U_{ex} S = -\nu_0 U_{xx} \]  \hspace{1cm} (14)

If equation (14) is integrated with respect to \( Y \) between the limits \( Y = 0 \) and \( Y = \Delta \), where \( \Delta \) is a constant distance normal to the surface sufficiently large that the conditions \( S = 0 \) and \( U = U_e \) can both be satisfied, there results
\[
\frac{d}{dX} \left( \theta_{tr} U_{x}^2 \right) + U_{ex} \delta_{tr}^* = \nu_0 (U_{r} y)_{Y=0} \]  \hspace{1cm} (15)

where the transformed momentum thickness \( \theta_{tr} \) and the transformed displacement thickness \( \delta_{tr}^* \) are defined as
\[
\theta_{tr} = \int_0^2 \frac{U}{U_e} \left( 1 - \frac{U}{U_e} \right) dY \]  \hspace{1cm} (16)
\[
\delta_{tr}^* = \int_0^2 \left( 1 - \frac{U}{U_e} + S \right) dY \]  \hspace{1cm} (17)

By carrying out the indicated differentiation, equation (15) can be put in the form
\[
\frac{d\theta_{tr}}{dX} U_{x} + 2 \theta_{tr} \delta_{tr}^* = \frac{\nu_0}{U_e} (U_{r} y)_{w} \]  \hspace{1cm} (18)

This equation has the form of the conventional Kármán momentum integral.

It should be noted that because of Stewartson's transformation a simple relation exists between the parameter \( \theta_{tr} \) and the actual physical momentum thickness \( \theta \). This relation is
\[
\frac{\theta}{\theta_{tr}} = \frac{\nu_0}{\nu_0 + \frac{a_0}{a_1} \theta_{tr}} = \frac{\theta_{tr}}{\frac{a_0}{a_1} \theta_{tr}} = \frac{\theta_{tr}}{\theta_{tr}} \]  \hspace{1cm} (19)

Following a procedure with the energy equation similar to that for the momentum equation results in
\[
\frac{dE}{dX} + \frac{U_{ex}}{U_e} E = -\frac{\nu_0}{Pr U_e} \left( \frac{\partial S}{\partial Y} \right)_w \]  \hspace{1cm} (20)

Where the convection thickness is defined by
\[
E = \int_0^2 S \frac{U}{U_e} dY \]  \hspace{1cm} (21)

The method presented in this report uses exact solutions to the boundary-layer equations including the energy equation. Since both the skin-friction and heat-transfer parameters from the exact solutions are correlated with a parameter which is evaluated from only the momentum integral equation, it will not be necessary to use equations (19) and (20).

**REDUCED BOUNDARY-LAYER EQUATIONS**

At this stage, the relation governing the boundary-layer development is equation (17), subject to the boundary conditions \( \theta_{tr}(0) = 0 \) or \( \theta_{tr}(\infty) \), where the subscript \( sp \) indicates stagnation-point values. The former condition on \( \theta_{tr} \) applies when the boundary layer is initiated without a stagnation point (such as in the case of a supersonic thin airfoil). The value of \( \theta_{tr}(\infty) \) depends on the value of \( (U_{ex})_{sp} \) and on the surface temperature. At a stagnation point \( (\theta_{tr})_{sp} = \theta_{sp} \).

Values of \( \theta_{tr} \) are presented in tables.

Before consideration of a solution that depends on a correlation similar to that of Tammes, it is expedient to transform the preceding system of equations to a system involving dimensionless parameters. The correlation concept will then be introduced and methods of solution developed.

**PARAMETRIC FORM**

The dimensionless parameters, which are related to terms appearing in equations (17) and (19), can be defined and evaluated from the following expressions:

**Shear parameter, or first-derivative parameter,**
\[
\frac{\partial U}{\partial Y} = \frac{U_e}{U_e} \left( \frac{\partial U}{\partial Y} \right)_w = \frac{U_e}{u_e} \left( \frac{\partial U}{\partial Y} \right)_w \]  \hspace{1cm} (22)

**Correlation number (related to pressure gradient), or second-derivative parameter,**
\[
\frac{\partial^2 U}{\partial Y^2} = \frac{U_e}{u_e} \left( \frac{\partial^2 U}{\partial Y^2} \right)_w = \frac{U_e}{u_e} \left( \frac{\partial^2 U}{\partial Y^2} \right)_w \]  \hspace{1cm} (23)

In definitions (22) and (23), use is made of the following relations, respectively:
\[
\left( \frac{\partial U}{\partial Y} \right)_w = \frac{U_{ex}}{\nu_0} (1 + S_w) \]  \hspace{1cm} (24)
\[
\left( \frac{\partial^2 U}{\partial Y^2} \right)_w = -\frac{U_{ex}}{\nu_0} \left( \frac{\partial^2 S}{\partial Y^2} \right)_w \]  \hspace{1cm} (25)

which is obtained from equation (9), and
\[
\left( \frac{\partial S}{\partial Y} \right)_w = -\frac{U_{ex}}{Pr U_e} \left( \frac{\partial U}{\partial Y} \right)_w \]  \hspace{1cm} (26)

Where \( H_r = \frac{S}{\theta_{tr}} \) is the form factor for low-speed flow (\( M_e \approx 0 \)).
### TABLE I.—INITIAL VALUES OF PARAMETERS

**Stagnation-point flow**

<table>
<thead>
<tr>
<th>S₀</th>
<th>Cr/Re</th>
<th>Nu/Re</th>
<th>Re</th>
<th>Pr</th>
<th>H₀</th>
</tr>
</thead>
<tbody>
<tr>
<td>P₁=1</td>
<td>P₀=0.7</td>
<td>P₀=1</td>
<td>P₀=0.7</td>
<td>P₀=1</td>
<td>P₀=1</td>
</tr>
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<td>---</td>
<td>---</td>
</tr>
<tr>
<td>-1.0</td>
<td>1.30</td>
<td>0.406</td>
<td>0.498</td>
<td>0.406</td>
<td>0.179</td>
</tr>
<tr>
<td>-0.8</td>
<td>1.06</td>
<td>0.522</td>
<td>0.471</td>
<td>0.522</td>
<td>0.112</td>
</tr>
<tr>
<td>-0.4</td>
<td>0.94</td>
<td>0.546</td>
<td>0.474</td>
<td>0.546</td>
<td>0.315</td>
</tr>
<tr>
<td>0</td>
<td>0.81</td>
<td>0.570</td>
<td>0.461</td>
<td>0.570</td>
<td>0.464</td>
</tr>
<tr>
<td>1.0</td>
<td>0.37</td>
<td>0.615</td>
<td>0.353</td>
<td>0.615</td>
<td>1.386</td>
</tr>
</tbody>
</table>

| Axially symmetric (β=1/2) |
| --- | --- | --- | --- | --- | --- |
| -1.0 | 1.64 | 1.56 | 0.700 | 0.607 | 0.077 | 0.300 |
| -0.8 | 1.41 | 1.37 | 1.212 | 1.017 | 0.453 | 0.289 |
| -0.4 | 1.22 | 1.17 | 1.373 | 1.114 | 0.450 | 1.185 |
| 0 | 1.04 | 0.92 | 1.383 | 1.040 | 0.448 | 2.296 |
| 1.0 | 0.40 | 0.38 | 0.969 | 0.701 | 0.185 | 6.012 |

*These values are obtained when eqns. (10) of ref. 12 are solved for Pr=0.7, M₁=0.*

**Two-dimensional (β=1)**

<table>
<thead>
<tr>
<th>S₀</th>
<th>Cr/Re</th>
<th>Nu/Re</th>
<th>Re</th>
<th>Pr</th>
<th>H₀</th>
</tr>
</thead>
<tbody>
<tr>
<td>P₁=1</td>
<td>P₀=0.7</td>
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</tr>
</tbody>
</table>

*These values are obtained by multiplying the results for Pr=1 by (0.7)².***

**Interpolated values from solutions of ref. 17.**

### TABLE II.—SUMMARY OF HEAT-TRANSFER AND WALL-SHEAR PARAMETERS

<table>
<thead>
<tr>
<th>S₀</th>
<th>β</th>
<th>n</th>
<th>l</th>
<th>N</th>
<th>r</th>
<th>(CrRe)</th>
<th>H₀</th>
</tr>
</thead>
<tbody>
<tr>
<td>---</td>
<td>---</td>
<td>---</td>
<td>---</td>
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</tr>
<tr>
<td>-1.0</td>
<td>-0.228</td>
<td>0.135</td>
<td>0.620</td>
<td>0.104</td>
<td>0.002</td>
<td>0.289</td>
<td>2.031</td>
</tr>
<tr>
<td>-0.8</td>
<td>-0.308</td>
<td>0.121</td>
<td>0.600</td>
<td>0.100</td>
<td>0.002</td>
<td>0.289</td>
<td>1.828</td>
</tr>
<tr>
<td>-0.4</td>
<td>-0.325</td>
<td>0.125</td>
<td>0.600</td>
<td>0.100</td>
<td>0.002</td>
<td>2.124</td>
<td>1.501</td>
</tr>
<tr>
<td>0</td>
<td>-0.325</td>
<td>0.101</td>
<td>0.214</td>
<td>0.102</td>
<td>0.002</td>
<td>1.810</td>
<td>2.460</td>
</tr>
<tr>
<td>1.0</td>
<td>-0.325</td>
<td>0.083</td>
<td>0.325</td>
<td>0.102</td>
<td>0.002</td>
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**Two-dimensional**

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<td>1.810</td>
<td>2.460</td>
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**Axially symmetric**

<table>
<thead>
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<th>N</th>
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<td>0.620</td>
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**Sharp edge or pointed body**

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<tr>
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<th>β</th>
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<th>l</th>
<th>N</th>
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<td>0.102</td>
<td>0.002</td>
<td>1.810</td>
<td>2.460</td>
</tr>
</tbody>
</table>

**Interpolated values from solutions of ref. 17.**
Now, if definitions (21) and (22) are inserted, equation (26) becomes
\[-U_\tau \frac{d}{dx} \left( \frac{n}{U_{\tau \infty}} \right) = 2[n(H_r + 2) + l] \tag{27}\]

A similar procedure can be carried out with the energy equation, although it is not necessary for the calculation method herein presented.

**Correlation in Terms of \( n \)**

If, in the definition of \( \theta_r \) (eq. (16)), \( S \) is set equal to zero, the form factor then becomes the same as that of Thwaites and equation (26) becomes Thwaites’ momentum equation. If, in this case, physically valid relations \( H_r(n) \) and \( l(n) \) can be established, the equation can be integrated and the problem is solved. The assumption of the form of the velocity profile serves this purpose, and the resultant procedure is the well-known Pohlhausen technique. (Kalikhman (ref. 15) was the first to carry the same approach over to the case of the thermal profile.) Thwaites used the more direct approach by determining whether universal relations \( H_r(n) \) and \( l(n) \) could possibly be established from the well-known exact solutions of the boundary-layer problem. An examination of these solutions proved that for favorable pressure, gradients a single relation for each of these quantities could be established with a fair degree of accuracy, but for adverse pressure gradients the relations departed from each other considerably, as indicated for \( l(n) \) in figure 1 (taken from ref. 21). Since the correlation technique requires the selection of a single relation between all boundary-layer quantities regardless of the history of the development of the specific boundary layer under consideration, the assumption of a single relation for all boundary layers is not exactly valid. Thwaites chose a relation for \( l(n) \) that would match the Howarth solution (ref. 25) at separation. The Pohlhausen solution predicts separation to occur much later than any of the other solutions in the sketch, while the Hartree solution (ref. 26) predicts separation to occur earlier than the Howarth solution. Stewartson (ref. 24) has indicated that under certain conditions Howarth’s solution would predict separation too late.

With the exception of the described differences in the relation between boundary-layer quantities (due to the selection of the solutions of ref. 12 for the evaluation of the correlated quantities), the method of correlation to be presented herein will contain as special cases the method of Thwaites for incompressible flow and the results of Rott and Crabtree for compressible flow over insulated surfaces.

The concept of correlation is herein extended by the following major assumption: For the compressible laminar boundary layer with heat transfer across the surface, the skin-friction and heat-transfer parameters \( l \) and \( r \) can be correlated only in terms of the parameters \( n \) and \( S_w \), derived from the exact solutions of reference 12.

It is thus implied that the solutions of reference 12 adequately represent the general boundary layer, although they were derived for Falkner-Skan type flow.

As in all first-order boundary-layer theories, the pressure distribution (and consequently the external velocity distribution) is assumed to be known. Then the utility of the correlation may be stated as follows: If \( n \) is known at a given point on the surface, \( \theta_r \) (and hence \( \theta \)) can immediately be obtained from equation (22). If \( l(n) \) is a known function for the specified wall temperature, the wall shear is immediately obtainable from equation (21). Similarly, if \( r(n) \) is known, the heat transfer can be found from equation (23).

If the postulate of correlation in terms of \( n \) and \( S_w \) is admitted, equation (27) becomes
\[-U_\tau \frac{d}{dx} \left( \frac{n}{U_{\tau \infty}} \right) = N(n, S_w) \tag{28}\]
where
\[N(n, S_w) = 2[n(H_r + 2) + l] \tag{29}\]

This is the fundamental equation of the present method. Its solution, resulting in a determination of \( n(z) \), is the first stage in solving for the boundary-layer characteristics. Then the function \( l(n, S_w) \) is used to determine the wall shear, and the function \( r(n, S_w) \) is used to determine the heat transfer.

**Evaluation of Correlation Parameters**

The quantities \( l, n, \) and \( r \) defined in equations (21) to (23), as evaluated from the solutions of reference 12, are listed in table II. An alternate parameter to \( r \) for the determination of the heat transfer is the Reynolds analogy parameter, defined as \( \frac{C_f R_e_s}{N_u} \), relating the heat transfer to the skin friction. Because this (arbitrarily chosen) parameter is herein determined from solutions for a Prandtl number of 1.0, it will be denoted \( \left( \frac{C_f R_e_s}{N_u} \right)_{Pr=1} \) as it appears in table II. It is related to \( r \) by
\[\left( \frac{C_f R_e_s}{N_u} \right)_{Pr=1} = -\frac{2 S_w n l}{r} \tag{30}\]

The parameters \( l \) and \( \left( \frac{C_f R_e_s}{N_u} \right)_{Pr=1} \) as functions of \( n \) and \( S_w \) are plotted against \( n \) in figures 2 and 3, respectively. The solid portions of the curves represent the solutions of reference 12. The reversal of the curves for \( S_w = 1.0 \) is associated with the velocity overshoot phenomenon discussed in reference 12.
Figure 2.—Correlation of shear parameter.

Figure 3.—Correlation of Reynolds analogy parameter.
METHOD OF SOLUTION

The solution of equation (28) obviously depends on a knowledge of the term \( N(n, S_w) \). This quantity was evaluated from equation (29) and the associated formulas for \( l, n, \) and \( H_w \). The results are shown in figure 4. It is to be noted that the curve for \( S_w=0 \) is nearly a straight line, and for all negative values of \( S_w \) the curves depart only slightly from this condition except in the range near separation where the curves become double-valued. For \( S_w>0 \) (hot wall) the curve is essentially straight except in the region of strong favorable gradients.

The examination of these curves and of equation (28) suggests two methods of determining the correlation number \( n \). The first method is that of solving equation (28) by numerical integration. The necessary numerical procedure, however, is tedious, since it involves integration of a first-order nonlinear nonhomogeneous ordinary differential equation. Because a simpler method is available when the surface is isothermal, no numerical integration procedure will be presented here in detail. However, some integration relations are stated in appendix B.

The second method, applicable when the surface temperature is constant (or, presumably, nearly constant), will be termed the "linear method." This method uses the nearly linear shape of the curves of \( N \) against \( n \) for constant \( S_w \). It directly corresponds to the procedure of Thwaites for incompressible flow and to that of Rott and Crabtree for compressible flow over insulated surfaces. The curve of \( N \) against \( n \) for a given \( S_w \) is assumed represented by

\[
N = A + Bn
\]  

(31)

If equation (31) is inserted in equation (28), a simple linear first-order equation results, which has for its solution

\[
n = -\frac{\Delta U_e}{U_x} \int_0^X U_x^{n-1} dX
\]  

(32)

If equation (32) is transformed to physical quantities by using Stewartson's transformation, there results for two-dimensional flow

\[
\frac{n}{P'} + \frac{\alpha}{K} = A \left( \frac{L}{\alpha} \right)^{-1} M_1^{-1} - a \int_0^X \left( \frac{L}{\alpha} \right)^{-K} M_1^{n-1} \left( \frac{x}{L} \right) \, dx
\]  

(33)

where \( K = \frac{3\gamma-1}{2(\gamma-1)} \). \( L \) is any fixed length, and the dimensionless pressure gradient \( P' \) is given by

\[
P' = \frac{\frac{L}{\alpha} \frac{d\alpha}{dx}}{\frac{L}{\alpha} \frac{d\alpha}{dx} + \frac{L}{\alpha} \frac{d\alpha}{dx}} = \frac{L}{\alpha} \frac{d\alpha}{dx}
\]  

(34)

The left member of equation (33) has been arranged in a form convenient for later use.

The determination of the coefficients \( A \) and \( B \) is as follows: If the straight line (31) is chosen to pass through the correct value of \( N \) at zero pressure gradient \( (n=0) \), then \( A = 0.44 \). \( B \) is independent of \( S_w \). In this case, only \( B \) is affected by the presence of heat transfer. Figure 5 shows the values of

![Figure 5.—Variation of \( B \) for use in linear method of determining correlation number.](image)
B(Sw) for the following choices of matching conditions:

1. The line (31) goes through the point corresponding to \( N=0 \) \( (u_e=0) \) in order to match the conditions at a stagnation point. Thus, for two-dimensional flow \( (N=0) \), \( B=-0.44/n_{sp} \).

2. The line (31) coincides with the tangent to the \( N(n) \) lines at \( n=0 \) (small pressure gradients):

3. The line (31) is selected to give good over-all agreement for unfavorable pressure gradients.

If a better match with the curves of figure 4 is desired in calculating \( n \) for certain ranges of pressure gradient, a tangent line to the curve of \( N \) against \( n \) may be chosen at a desired value of \( n \). For instance, in considering the flow in the vicinity of a two-dimensional stagnation point with \( Sw=-0.8 \), the tangent line through \( N=0 \) has the coefficients \( A=0.372 \), \( B=2.53 \). The value of \( B \) is quite sensitive to the matching assumption, especially in the region \( Sw>0 \) (fig. 5). However, the final value of \( n(x) \) is somewhat insensitive to the value of \( B \), since the terms involving \( B \) in equation (33) appear both inside and outside the integral in a compensating manner. The accuracy of the method decreases, of course, in regions where the plots of figure 4 have large curvature.

The calculation procedure is as follows: Values of \( A \) and \( B \) are chosen for use in equation (33) either from figure 5 or from tangent-line considerations. The integration is then performed by using a suitable integration rule and a proper step size. It is recommended that the step size chosen be as small as practicable in order to obtain results which are reasonably smooth. In some cases (e.g., near the boundary-layer origin) it may be advisable to perform the integration by obtaining Taylor series expansions of the integrand in the variable \( (x/L) \). Then the integration can be carried out in closed form, corresponding effectively to zero step size.

There are two possible starting conditions in a boundary-layer calculation: (a) that of a sharp edge, that is, \( \theta=0, n=0; \) or (b) the stagnation point, where \( U_e=u_e=0 \). In using the linear method, the starting conditions are automatically satisfied if the chosen line (31) goes through the correct starting point \( N(n) \). Thus, if matching condition \( (a) \) is used, both possible starting conditions can be satisfied, since the corresponding line (31) passes through the curve from the exact solutions at both \( n=0 \) \( (N=0.44) \) and, for the two-dimensional flow, at \( N=0 \) \( (n_{sp}=-0.44/B) \). Values of \( n \) for stagnation-point flow taken from figure 4 are shown in figure 6.

The corresponding relations and procedure for axially symmetric flow based on Mangler’s transformation (ref. 27) are presented in appendix C. It is sometimes helpful to have an analytical expression for the initial variation of correlation number as a check on the numerical calculations. The initial variation of \( n \) with \( x \) for the various starting conditions, as represented by the derivative \( \left(\frac{dn}{dx}\right)_{x=0} \), is discussed in appendix D.

![Figure 6](image-url)

**Figure 6**—Effect of wall temperature on correlation number for various pressure gradients.
In utilizing equations (35) to (37), it is useful to have the initial values of the parameters. These values are listed in table I.

The calculations thus far have been for \( Pr=1.0 \). The effect of Prandtl number on skin friction is small and is therefore usually neglected. It can be seen from table I that, for stagnation-point flow, the maximum difference in the quantity \( C_f \sqrt{Re_u} \) between solutions for \( Pr=1.0 \) and \( Pr=0.7 \) is about 7 percent. With regard to heat transfer, Tifford and Chu (ref. 28) have found, from solutions with constant fluid properties, that the effect of Prandtl number on heat transfer can be accounted for by multiplying \( \frac{N_u}{\sqrt{Re_u}} \) by \( (Pr)^{\alpha} \).

Using this approximation, equation (37) becomes

\[
\frac{\tau}{(Pr)^{\alpha}} = \frac{C_f \sqrt{Re_u}}{\frac{N_u}{\sqrt{Re_u}}} (Pr)^{\alpha}
\]

Values of \( \alpha \) suggested in reference 28 are as follows: For small pressure gradients, \( \alpha = \frac{5}{6} \); for large adverse pressure gradients, \( \alpha = \frac{5}{3} \); and for extremely favorable gradients, \( \alpha = \frac{5}{2} \). Squire (ref. 29) has indicated that \( \alpha=0.4 \) is adequate for stagnation-point flows. Recently obtained solutions (ref. 30) of equations (16) of reference 12 for \( \beta=1, Pr=0.7, \) and \( M_\infty \rightarrow \infty \) show that this type of correction may be adequate for all compressible boundary-layer calculations.

It should be noted that, in the definition of Nusselt number, the temperature difference in the denominator was assumed to be \( (t_\infty-t_w) \). Since for \( Pr=1 \) the recovery temperature is \( t_0 \), the present calculations (based on those of ref. 12) can give no indication of the adiabatic wall temperature for \( Pr \neq 1 \). For a first approximation, it may be reasonable to calculate \( t_\infty \) by using a temperature recovery factor of \( (Pr)^{1/2} \). This is the well-known expression for recovery factor for the case of high-speed flow with zero pressure gradient. The adequacy of its application to high-speed flows with large pressure gradients is not well established.

The displacement thickness \( \delta^* \) may be calculated by using the following simple expression for the ratio of displacement thickness to momentum thickness:

\[
H = \frac{\delta^*}{\delta} = H_\nu + \frac{\gamma - 1}{2} M_\nu^2 (H_\nu + 1)
\]

In reference 23, this expression was derived for flows over insulated surfaces with \( Pr=1 \). Equation (40) is valid for noninsulated surfaces as well. The dependence of \( H_\nu \) upon wall temperature and \( n \) is presented in figure 7. With large amounts of cooling in favorable-pressure-gradient flows, it is seen that negative form factors (and hence negative displacement thicknesses) result. This occurs because the surface cooling produces an increase in density near the wall, so that there is more mass flow per unit flow area within the boundary layer than in the external flow.

The over-all thickness \( \delta \) of a boundary layer calculated from exact solutions is a quantity not uniquely defined. Its value depends on the value of the velocity ratio \( \frac{u_4}{u_e} \) that is chosen to represent the outer edge of the boundary layer. However, for a given value of the velocity ratio (less than 1) there is a single value for thickness. The ratio of this over-all thickness to the momentum thickness is given by the expression

\[
\frac{\delta}{\delta \nu} = \frac{\delta \nu}{\theta \nu} + \frac{\gamma - 1}{2} M_\nu^2 (H_\nu + 1)
\]

The quantity \( \frac{\delta \nu}{\theta \nu} \) is that for low-speed flow \( (M_\nu=0) \) which has been evaluated from the solutions of reference 12 and is presented in figure 8 as a function of correlation number \( n \) for \( \frac{u_4}{u_e}=0.995 \).

- The mass flow in the boundary layer is related to the difference \( \left( \frac{\delta \nu}{\theta \nu} - H_\nu \right) \) and may be obtained by subtracting equation (40) from equation (41), which finally results in

\[
\int_0^\infty \rho \nu dy = \left( \frac{\delta \nu}{\theta \nu} - H_\nu \right) \theta
\]
The quantity \( \frac{\partial \nu}{\partial \theta'} - H \nu \) is 5.35 for the flat plate and, as can be seen from the information in figures 7 and 8, varies from about 4.5 for adverse pressure gradients to about 6.5 for favorable pressure gradients.

**LIMITS DUE TO AVAILABLE EXACT SOLUTIONS**

The curves of figures 2 and 3 are terminated at the boundary-layer separation point on one end and at the value of the correlation number \( n \) at the other end, which corresponds to the most favorable pressure gradient that can be represented by the Falkner-Skan type solutions of reference 12. However, one may conceive a flow that contains values of \( n \) more negative than the latter limit. For example, if a boundary layer is allowed to grow on a flat plate until the momentum thickness has an arbitrary value and is then subjected to a favorable pressure gradient \((U_0 > 0)\), equation (22) shows that \( n \) might be made arbitrarily negative. Similarly, large negative values of \( n \) may arise if a strong favorable pressure gradient is maintained for some distance along a surface, such as in a nozzle. Under such circumstances it would be necessary to extend the curves of figures 2, 3, and 7 in order to use the correlation method presented herein. Such extension is not possible by means of Falkner-Skan type solutions.

It is thus apparent that there are types of problems for which the presently available correlations are not adequate. To establish correlations in that regime would require exact boundary-layer solutions for large favorable pressure gradients of a form different from that of reference 12. Such solutions are not known to the authors at this time. The extended portions of the curves in figures 2, 3, and 7 for \( S_w = -0.8 \) were drawn to enable the completion of example II in the following section. The adequacy of this extension is not known.

**EXAMPLES**

An important test of the method developed is the comparison of the final results for practical problems with the findings of other theories or with experimental results.

### I. SUPERSONIC SURFACES

The linear method for determining the correlation number \( n \) is applied to the calculation of skin friction and heat transfer for the two supersonic surfaces at Mach number 3.0 calculated in reference 6. These surfaces are shown in figure 9.

![Supersonic surfaces of example I.](image)

A comparison is made, in the following table, between the results obtained by using the linear method and those obtained by using Low’s perturbation method with \( Pr = 0.72 \) (ref. 6). The comparison is made for a hot wall, an insulated wall, and a cold wall at \( x/L = 1 \) (see fig. 9). A value of \( a \) of 1/3 was used in these calculations.

<table>
<thead>
<tr>
<th>Gradient</th>
<th>Heat-transfer condition</th>
<th>((C_fR_{Re})_{x=L})</th>
<th>((Nu/R_{Re})_{x=L})</th>
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<td></td>
<td>Linear method, ( Pr = 1 )</td>
<td>Low (ref. 6), ( Pr = 0.72 )</td>
<td>Linear method, corrected for ( Pr )</td>
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<td>Favorable</td>
<td>Cold wall ((S_w = -0.9))</td>
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<td></td>
<td>Hot wall ((S_w = 0.6))</td>
<td>0.645</td>
<td>0.677</td>
</tr>
<tr>
<td>Adverse</td>
<td>Cold wall ((S_w = -0.9))</td>
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<td>0.561</td>
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<tr>
<td></td>
<td>Insulated wall</td>
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<td></td>
<td>Hot wall ((S_w = 0.6))</td>
<td>0.398</td>
<td>0.396</td>
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</table>

A comparison of values indicates agreement of skin friction within 2 percent in the case of a favorable pressure gradient. For the adverse-pressure-gradient cases, reasonable agreement

---

**Figure 8.—Over-all thickness correlation \( \left( \frac{\nu}{\nu^*} = 0.995 \right) \).**
is obtained for the cold wall, although for the insulated and hot walls a large difference is obtained. This difference is due essentially to the fact that, in the case of an adverse pressure gradient, the solutions of Low (ref. 6), which resemble the series-type solution of Howarth (ref. 25), depart from Falkner-Skan type solutions such as that of Hartree (ref. 26) (e. g., fig. 1). An important consideration for the case of the heated surface with an adverse pressure gradient is that the flow is closer to separation than appears permissible for a theory based on small pressure gradients such as that of reference 6; therefore, for this case the present calculation may be the more reliable. Some of the difference in the preceding table may also be a Prandtl number effect.

Good agreement is also obtained for heat transfer except for the case of the heated surface with favorable pressure gradient. Some of that difference might also be a Prandtl number effect.

II. AXYSYMMETRIC CONVERGENT-DIVERGENT ROCKET NOZZLE

The second example, that of a rocket nozzle, is one involving both large pressure gradients and heat transfer. The nozzle chosen is illustrated in figure 10. It has a 25° half-angle convergent section and a 15° half-angle divergent section. The combustion-chamber stagnation pressure is assumed to be 500 pounds per square inch absolute, the stagnation temperature is taken as 4000° R, and the Prandtl number is assumed to be 0.78. The nozzle wall is assumed cooled to a uniform temperature of 800° R, which corresponds to \( S_w = -0.8 \). For the assumed 3-inch throat diameter, the rocket has a nominal thrust of 5550 pounds for \( \gamma = 1.3 \). Local static conditions along the nozzle wall were obtained using one-dimensional flow relations.

The calculation was performed by the linear method with \( A = 0.372 \) and \( B = 2.53 \). In order to eliminate the effect of step size in the initial portion of the integration, a series expansion of the integrand was used for \( 0 \leq (x/D) < 0.5 \). For \( (x/D) > 0.5 \), the step size taken was 0.1. The resulting variation of \( n \) in the nozzle is also shown in figure 10. It is seen that, in a portion of the nozzle including the throat (1.2 < \( (x/D) < 3.5 \)), values of \( n \) are obtained which require use of an extended correlation curve as discussed earlier, in order to calculate skin friction, heat transfer, and displacement thickness. No extrapolation is needed to obtain momentum thickness, since the momentum thickness is related to \( n \) through equation (30).

The calculated local heat-transfer rates as well as displacement and momentum thickness are shown in figure 11. It is seen that large rates of cooling are required in the neighbor-
hood of the stagnation point and the nozzle throat. If the cooling were to become insufficient, these seem to be the most likely locations of failure. The required local cooling rate to maintain constant wall temperature decreases sharply beyond the throat of the nozzle.

In the absence of more appropriate information, it has been customary in recent years to use flat-plate heat-transfer relations in estimating heat transfer in a nozzle. The use of such a relation in the current problem \((Nu/\sqrt{Re} = 0.305\) for \(Pr = 0.78\)) yields values indicated in figure 10. It is seen that for this problem the flat-plate relation seriously underestimates the amount of cooling required over a large part of the nozzle. This illustrates the importance of considering the effects of pressure gradient on heat transfer.

The momentum thickness is seen to reach a minimum value at the nozzle throat. The displacement thickness is a small positive quantity at the stagnation point but is negative for most of the convergent section as well as in the vicinity of the throat. The over-all thickness (not shown on the figure) varies from 0.1 to 7.7 times the momentum thickness in going from the initial stagnation point to the nozzle exit.

The use of different values of \(A\) and \(B\) in performing the numerical integration would have approximately the following effect: With the values \(A = 0.44\) and \(B = 3.0\) (from fig. 5), the momentum thickness would be about 10 percent smaller in the vicinity of the throat than the values in figure 11 and would be within 5 percent of the presented values over the rest of the nozzle. With \(A = 0.335\) and \(B = 2.34\), the momentum thickness at the throat would be about 6 percent larger than the value presented. The effects of varying \(A\) and \(B\) on skin friction and heat transfer would be less than 3 percent at the throat.

**CONCLUDING REMARKS**

The application of Stewartson’s transformation to the compressible laminar-boundary-layer equations with heat transfer yielded a simple first-order system of ordinary differential equations, the first of which is very similar to the Kármán momentum integral. Dimensionless shear and heat-transfer parameters were defined. The assumption of correlation of these parameters in terms of a momentum parameter resulted in a complete system of relations for calculating skin friction and heat transfer. Knowledge of velocity or temperature profiles is not necessary in using this calculation method. Procedures for the calculation of the longitudinal distribution of correlation number are presented, which include as special cases the method of Thwaites and that of Rott and Crabtree. The dimensionless parameters introduced herein were evaluated from the exact solutions of reference 12.

Calculations of an example involving small pressure gradients have shown reasonable agreement between this method and the perturbation method of reference 6 over the same range of Mach number, pressure gradient, and heat transfer.

The method is also applied to the calculation of heat transfer and displacement thickness in a highly cooled, convergent-divergent, axially symmetric rocket nozzle. The results of this calculation show that high rates of heat transfer are obtained at the initial stagnation point and at the throat of the nozzle. Also indicated are negative displacement thicknesses in the convergent portion of the nozzle; these occur because of the high density within the lower portions of the cooled boundary layer.

**Lewis Flight Propulsion Laboratory**

**National Advisory Committee for Aeronautics**

**Cleveland, Ohio, February 1, 1955**
APPENDIX A

SYMBOLS

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A$</td>
<td>constant from $N=A+Bn$</td>
</tr>
<tr>
<td>$a$</td>
<td>sonic velocity</td>
</tr>
<tr>
<td>$B$</td>
<td>constant from $N=A+Bn$</td>
</tr>
<tr>
<td>$C_f$</td>
<td>local skin-friction coefficient, $C_f=\frac{2r_u}{\rho_u u_t^3}$</td>
</tr>
<tr>
<td>$c_p$</td>
<td>specific heat at constant pressure</td>
</tr>
<tr>
<td>$d$</td>
<td>nozzle-throat diameter</td>
</tr>
<tr>
<td>$E$</td>
<td>convection thickness, $E=\int_0^h S U_0 , dy$</td>
</tr>
<tr>
<td>$H$</td>
<td>form factor, $H=\frac{d^2}{\theta}$</td>
</tr>
<tr>
<td>$H_{tr}$</td>
<td>physical form factor for $M_s=0$, $H_{tr}=\frac{\theta_{tr}}{\theta}$</td>
</tr>
<tr>
<td>$h$</td>
<td>enthalpy</td>
</tr>
<tr>
<td>$K$</td>
<td>thermal conductivity</td>
</tr>
<tr>
<td>$k_{sw}$</td>
<td>Sutherland’s constant</td>
</tr>
<tr>
<td>$L$</td>
<td>arbitrary length</td>
</tr>
<tr>
<td>$m$</td>
<td>exponent from Falkner-Skan external velocity distribution $U_e=CX^m$</td>
</tr>
<tr>
<td>$M$</td>
<td>Mach number</td>
</tr>
<tr>
<td>$n$</td>
<td>momentum parameter, $N=2[n(H_u+2)+l]$</td>
</tr>
<tr>
<td>$Nu$</td>
<td>Nusselt number, $Nu=\frac{t_{sw}-t_w}{t_{sw}-t_w}$</td>
</tr>
<tr>
<td>$p$</td>
<td>static pressure</td>
</tr>
<tr>
<td>$Re_w$</td>
<td>Reynolds number, $Re_w=\frac{\rho u_s x}{\mu}$</td>
</tr>
<tr>
<td>$r$</td>
<td>heat-transfer parameter, $r=n\theta \int_0^h \frac{\partial \theta}{\partial y} \left( \frac{t}{T_0} \right)_w$</td>
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<tr>
<td>$S$</td>
<td>enthalpy function, $S=\frac{b}{b_0}-1$</td>
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<tr>
<td>$t$</td>
<td>static temperature</td>
</tr>
<tr>
<td>$t_{sw}$</td>
<td>adiabatic wall temperature</td>
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<tr>
<td>$U$</td>
<td>transformed longitudinal velocity, $U=\frac{a_s}{a_e}=\psi_x$</td>
</tr>
<tr>
<td>$u$</td>
<td>longitudinal velocity component</td>
</tr>
<tr>
<td>$V$</td>
<td>transformed normal velocity, $V=-\psi_x$</td>
</tr>
<tr>
<td>$\psi$</td>
<td>normal velocity component</td>
</tr>
<tr>
<td>$X$</td>
<td>transformed coordinate along surface, $X=\int_0^x \lambda \frac{a_s}{a_e} , dx$</td>
</tr>
<tr>
<td>$x$</td>
<td>coordinate along surface</td>
</tr>
<tr>
<td>$Y$</td>
<td>transformed normal coordinate, $Y=\frac{a_s}{a_e} \int_0^y \rho , dy$</td>
</tr>
<tr>
<td>$y$</td>
<td>normal coordinate</td>
</tr>
<tr>
<td>$\alpha$</td>
<td>exponent of Prandtl number in Reynolds analogy</td>
</tr>
<tr>
<td>$\beta$</td>
<td>pressure-gradient parameter, $\beta=\frac{2m}{m+1}$</td>
</tr>
<tr>
<td>$\gamma$</td>
<td>ratio of specific heats</td>
</tr>
<tr>
<td>$\delta$</td>
<td>over-all thickness</td>
</tr>
<tr>
<td>$\delta^*$</td>
<td>displacement thickness</td>
</tr>
<tr>
<td>$\theta$</td>
<td>momentum thickness</td>
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<tr>
<td>$\lambda$</td>
<td>parameter, $\lambda=\frac{(\mu/\rho)}{(l/l_0)}=\left( \frac{l_0+k_{sw}}{l_0+k_{sw}} \right) \sqrt{\frac{l_{sw}}{l_0}}$</td>
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<tr>
<td>$\mu$</td>
<td>dynamic viscosity</td>
</tr>
<tr>
<td>$\nu$</td>
<td>kinematic viscosity, $\nu=\mu/\rho$</td>
</tr>
<tr>
<td>$\rho$</td>
<td>mass density</td>
</tr>
<tr>
<td>$\tau$</td>
<td>shear stress, $\tau=\mu \frac{\partial u}{\partial y}$</td>
</tr>
<tr>
<td>$\psi$</td>
<td>stream function, eq. (6)</td>
</tr>
</tbody>
</table>

Subscripts:
- $e$ local flow outside boundary layer (external)
- $s$ local stagnation value
- $sp$ stagnation point
- $tr$ associated transformed quantity
- $w$ wall or surface value
- $0$ free-stream stagnation value
- $1$ initial value

A coordinate used as subscript denotes differentiation with respect to the coordinate.
METHOD

The most direct method of solving equation (28) is by numerical integration, using the calculated curves of \( N(n, S_0) \) for determination of the right member.

An integration procedure may be simply indicated by direct integration of equation (28). The resultant integral equation can be written:

For two-dimensional flow,

\[
n = \frac{U_{ex}}{U_e} \left[ n - \left( \frac{U_{ex}}{U_e} \right) \int_0^x \frac{N(n)}{U_e} \, dX \right]
\]  

(B1)

For an axially symmetric closed body, through Mangler's transformation (ref. 26),

\[
n = \frac{U_{ex}}{R^2} \int_0^x \frac{N R^2}{U_e} \, dX
\]  

(B2a)

Since the integrands contain \( N(n) \), which is unknown at this point, no simple evaluation is possible. In fact, these equations are actually only a condensed notation of the procedure to be followed. The integration must be carried out piecemeal, alternating with determination of the left member of the equation and iterating for accuracy.

The necessity of working with the transformed coordinates can be eliminated by considering the Stewartson transformation from \( U_e \) to \( u_e \). For example, in physical coordinates equation (B2a) becomes

\[
n = \frac{\left( M_e \frac{\partial a}{\partial \rho} \rho_0 \right)}{R^2} \int_0^x \frac{N R^2}{U_e} \, dX
\]  

(B2b)

where \( L \) is any fixed length, and the dimensionless pressure gradient \( P' \) is given by

\[
P' = \frac{L \, dp}{\rho \, dx} = \frac{L \, dp}{\rho \, u_e^2} = \frac{\gamma M_e^2}{2}
\]  

Similarly, if the isentropic relation \( \rho/\rho' = \text{constant} \) is used in equations (31) and (32) and if the Stewartson transformation is applied, there results:

For two-dimensional flow,

\[
n \frac{P' \ell_0}{U_e} = M_e \left( \frac{\ell_0}{U_e} \right)^\kappa \int_0^x \frac{N R^2}{M_e} \, dX
\]  

(B4)

For an axially symmetric flow (closed body),

\[
n \frac{P' \ell_0}{U_e} = M_e \left( \frac{\ell_0}{U_e} \right)^\kappa \int_0^x \frac{N R^2}{M_e} \, dX
\]  

(B5)

where \( K = \frac{3\gamma - 1}{2(\gamma - 1)} \).

**INITIAL VALUES**

When the numerical integration method is used, certain considerations are necessary in order to start the solution properly. There are two possible starting conditions: (1) sharp edge or pointed body, where \( \theta = 0 \) and \( n = 0 \), and (2) stagnation point, where \( U_e = u_e = 0 \).

In the case of a boundary layer starting from a stagnation point, the initial value \( n_0 \) of \( n \) is determined from the condition \( U_e = 0, U_{x0} = \text{constant} \) in equation (28). For two-dimensional stagnation-point flow, the Hartree pressure-gradient parameter \( \beta \) is equal to 1.0. Since, for the Falkner-Skan type flow considered, \( N = \frac{2(\beta - 1)}{\beta} n \), it is seen that \( N = 0 \) at a two-dimensional stagnation point. This fixes \( n \) at the values shown in figure 6, which were obtained from figure 4. For axisymmetric stagnation-point flow over a closed body, \( \beta = \frac{3}{2} \) (ref. 31), so that \( N = -2n \). The values of \( n_1 \) for axially symmetric stagnation-point flow over a closed body as obtained from figure 4 are also shown in figure 6. For the stagnation-point flow over the blunt lip of an open axisymmetric body, \( n_1 \) can be shown to have the two-dimensional value.
APPENDIX C

LINEAR METHOD FOR AXISYMMETRIC FLOW

For axisymmetric flows, the following equation, which is equivalent to equation (33), is obtained by application of the transformation of Mangler (ref. 27):

\[
\frac{n}{P'} + \frac{1}{L_n} = A \left( \frac{t_e}{t_o} \right)^{-K} \frac{M_1^{-n}}{R^2} \int_0^x \left( \frac{t_e}{t_o} \right)^K \frac{R_1^2}{M_1^{-n} d \left( \frac{x}{L} \right)}
\]  

(C1)

where \( R = R(x) \) is the radius of the body at station \( x \), \( K = \frac{3\gamma - 1}{2(\gamma - 1)} \), and

\[ \frac{P'}{L} = \frac{L dp}{dL} \gamma \eta M_1^2 \]

In evaluating the coefficients \( A \) and \( B \) of the straight line

\[ N = A + Bn \]

(31)

\( A \) may be chosen as 0.44 so that the line (31) passes through the correct value of \( N \) at \( n = 0 \). The choice of \( B \) may be made so that the line (31) goes through the point where \( N = -2n \) in order to match the conditions at an axisymmetric stagnation point. In that event, \( B = -\left( \frac{0.44}{n_{sp}} + 2 \right) \). For achieving better agreement with the curves of figure 3 in certain ranges of pressure gradient, a tangent line to the curve of \( N \) against \( n \) may be chosen as was indicated for two-dimensional flow.

The three possible starting conditions are: (1) For a pointed body, \( \theta = 0 \), \( n = 0 \). (2) For a stagnation point on a closed body, \( U_e = u_e = 0 \) so that \( N = -2n \). Values of \( n_{sp} \) for this axisymmetric stagnation point are shown in figure 5 and indicated in table II for \( \beta = \frac{1}{2} \). (3) For a stagnation point on the blunt lip of an open axisymmetric body, it can be shown using the axisymmetric form of equation (28) that \( N = 0 \) so that \( n_{sp} \) is that for two-dimensional flow.

APPENDIX D

INITIAL VARIATION OF CORRELATION NUMBER

It is sometimes helpful to have an analytical expression for the initial variation of correlation number as a check on the numerical calculations. The following expressions for \( \frac{dn}{dz} \) are determined from equation (28):

TWO-DIMENSIONAL FLOW

Sharp edge:

\[ \frac{dn}{dz} \bigg|_{z=0} = -0.44 \left( \frac{u_e}{u_x} \right)_{z=0} \left( \frac{t_e}{t_o} \right)_{z=0} \]  

(D1)

Stagnation point (blunt body):

\[ \frac{dn}{dz} \bigg|_{z=0} = \frac{n_{sp}}{1 + \left( \frac{dn}{dn} \right)_{sp}} \left( \frac{u_{ez}}{u_e} \right)_{sp} \]  

(D2)

AXISYMMETRIC FLOW

For axisymmetric flow the initial derivatives must be evaluated from the following equation:

\[ \frac{U_e}{R_1^2} \frac{d}{dx} \left( \frac{H_1}{U_e} \right) = N \left( n, \dot{S}_w \right) \]  

(D3)

Closed body.—

Pointed nose:

\[ \left( \frac{dn}{dz} \right)_{z=0} = -0.147 \left( \frac{u_e}{u_x} \right)_{z=0} \left( \frac{t_e}{t_o} \right)_{z=0} \]  

(D4)

Stagnation point (blunt nose):

\[ \left( \frac{dn}{dz} \right)_{z=0} = \frac{n_{sp}}{1 + \left( \frac{dn}{dn} \right)_{sp}} \left[ 2 \left( \frac{u_{ez}}{u_e} \right)_{sp} - \left( \frac{R_1}{R} \right)_{sp} \right] \]  

(D5)

Open body.—

Sharp lip:

\[ \left( \frac{dn}{dz} \right)_{z=0} = -0.44 \left( \frac{u_e}{u_x} \right)_{z=0} \left( \frac{t_e}{t_o} \right)_{z=0} \]  

(D6)

Stagnation point (blunt lip):

\[ \left( \frac{dn}{dz} \right)_{z=0} = \frac{n_{sp}}{1 + \left( \frac{dn}{dn} \right)_{sp}} \left[ \left( \frac{u_{ez}}{u_e} \right)_{sp} - 2 \left( \frac{R_1}{R} \right)_{sp} \right] \]  

(D7)
REFERENCES


