Recent Advances in Computational Structural Reliability Analysis Methods

Southwest Research Institute
San Antonio, Texas
INTRODUCTION

The goal of structural reliability analysis is to determine the probability that the structure will adequately perform its intended function when operating under the given environmental conditions. Thus, the notion of reliability admits the possibility of failure. Given the fact that many different modes of failure are usually possible, achievement of this goal is a formidable task, especially for large, complex structural systems. The traditional (deterministic) design methodology attempts to assure reliability by the application of safety factors and conservative assumptions. However, the safety factor approach lacks a quantitative basis in that the level of reliability is never known and usually results in overly conservative designs because of compounding conservatisms. Furthermore, problem parameters that control the reliability are not identified, nor their importance evaluated.

This paper presents a summary of recent advances in computational structural reliability assessment. A significant level of activity in the research and development community has been seen recently, much of which has been directed towards the prediction of failure probabilities for single mode failures. The focus of this paper is to present some early results and demonstrations of advanced reliability methods applied to structural system problems. This includes structures that can fail as a result of multiple component failures (e.g., a redundant truss), or structural components that may fail due to multiple interacting failure modes (e.g., excessive deflection, resonate vibration, or creep rupture). From these results, some observations and recommendations are made with regard to future research needs.
PROBABILISTIC STRUCTURAL ANALYSIS METHODS (PSAM) PROGRAM

The methodologies presented in this paper have been developed by the Southwest Research Institute (SwRI) under sponsorship from the NASA Probabilistic Structural Analysis Methods (PSAM) Program [1,2]. The objective of the NASA/PSAM program is to develop probabilistic structural analysis methods for critical space shuttle main engine (SSME) components such as turbine blades, transfer ducts, piping systems, and liquid oxygen posts. These components are considered critical because of the severe consequence of failure. A major accomplishment of the PSAM program is the development of the NESSUS computer program, which integrates advanced reliability methods with general structural analysis capabilities. Rocketdyne (Rockwell Corporation) has and is currently applying NESSUS to critical SSME components [3].

The methodologies developed by PSAM are applicable to a wide range of applications. Under several other projects, SwRI is applying PSAM technology to geomechanics, nuclear waste, rotordynamics, industrial design and optimization, biomechanics, and numerous other structural and mechanical reliability problems [4, 5, 6].

- Ten-Year Research and Development Program
  - Phase 2: Structural System Risk Assessment, Qualification, Certification, and Health Monitoring (1990- )
- Simulate Uncertainty/Variability in Loads, Material Properties, Geometries
- Computer Code NESSUS Integrates Reliability Methods with Structural Analysis Methods (FEM, BEM)
- PSAM Methodology and Code are General Structural Risk Assessment and Reliability Design Tools

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Project Sponsor: NASA Lewis Research Center
SUMMARY OF NESSUS 6.0 CAPABILITIES

The probabilistic structural analysis methods used in this paper are implemented in the NESSUS\textsuperscript{tm} probabilistic computer program [7]. NESSUS couples numerous advanced probabilistic algorithms with general-purpose structural analysis capabilities to provide a very efficient means of computing probabilistic results for complex applications. Thus, the key feature of NESSUS is its ability to establish the cumulative distribution function (CDF) for complex structures with a minimum number of response resolutions. Figure 1 summarizes the capabilities in NESSUS Version 6.0.

<table>
<thead>
<tr>
<th>Random Variables</th>
<th>Analysis Types</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Loads</strong></td>
<td>Static</td>
</tr>
<tr>
<td>- Forces</td>
<td>Transient dynamics</td>
</tr>
<tr>
<td>- Pressures</td>
<td>Buckling</td>
</tr>
<tr>
<td>- Temperatures</td>
<td>Vibrations</td>
</tr>
<tr>
<td>- Vibrations (PSD)</td>
<td>Nonlinearities</td>
</tr>
<tr>
<td><strong>Material properties</strong></td>
<td>- Plasticity</td>
</tr>
<tr>
<td>- Moduli</td>
<td>- Large displacement</td>
</tr>
<tr>
<td>- Poisson’s ratio</td>
<td>Sampling</td>
</tr>
<tr>
<td>- Yield stress</td>
<td>- Standard Monte Carlo</td>
</tr>
<tr>
<td>- Hardening parameters</td>
<td>- Latin Hypercube</td>
</tr>
<tr>
<td>- Material orientation</td>
<td>- Adaptive Importance</td>
</tr>
<tr>
<td><strong>Geometry</strong></td>
<td><strong>Element Library</strong></td>
</tr>
<tr>
<td>- User-defined</td>
<td>Beam</td>
</tr>
<tr>
<td><strong>Probabilistic Methods</strong></td>
<td>Plate</td>
</tr>
<tr>
<td><strong>Fast Probability Analysis</strong></td>
<td>Plane strain</td>
</tr>
<tr>
<td>- Advanced Mean-Value</td>
<td>Plane stress</td>
</tr>
<tr>
<td>- First and Second-Order</td>
<td>Axisymmetric</td>
</tr>
<tr>
<td>- Fast Convolution</td>
<td>3D solid</td>
</tr>
<tr>
<td><strong>Sampling</strong></td>
<td>Enhanced solids</td>
</tr>
<tr>
<td>- Standard Monte Carlo</td>
<td>Operating Systems</td>
</tr>
<tr>
<td>- Latin Hypercube</td>
<td>Mainframes</td>
</tr>
<tr>
<td>- Adaptive Importance</td>
<td>- CRY</td>
</tr>
<tr>
<td><strong>Probabilistic Fault Tree</strong></td>
<td>- VAX</td>
</tr>
</tbody>
</table>

| **Probabilistic Results** | **Performance Functions** |
| - Full probability distribution | - Structural responses: |
| - Component reliability | - stress, strain, disp., freq., etc. |
| - System/multi-failure-modes rel. | - Fatigue and fracture life |
| - Probabilistic sensitivities | - Creep rupture life |
| - Probability-based risk/cost | - User-defined subroutines |

Figure 1. Summary of NESSUS Version 6.0 Capabilities.
EFFICIENT RELIABILITY ANALYSIS BASED ON MOST PROBABLE POINT (MPP)

One of the challenges in computational structural reliability is the development of efficient and accurate probabilistic analysis algorithms for analyzing structures where the computations of the performance and its sensitivities are very time-consuming. Recently, probabilistic methods based on the limit state approach have been developed and successfully integrated with finite element and boundary element methods. In these methods, the primary computational effort is typically spent on locating the most probable point (MPP) for a limit state function, \( Z = z_i \), as illustrated in Fig. 2. Once the MPP is identified, the probability of failure can be estimated. Several approaches are available to search for the MPP. One efficient method, developed and implemented in NESSUS, is the advanced mean value method (AMV), which has been shown to be extremely efficient [8]. One of the limitations of the limit state approach is that the probability estimate is based on a low-order polynomial approximation. The adaptive importance sampling (AIS) method provides a quick way to check the AMV solution by sampling in the most likely failure region [9].

- Input Variables Defined Using Probability Distributions
- Fast Probability Integration Estimates MPP on Response Surface
- Advanced Mean Value (AMV+) Iteration Computes Converged MPP and Estimates Probability of Failure \( (p_f) \)
- Adaptive Importance Sampling (AIS) Can be Used to Check \( p_f \) Calculation

\[
\begin{align*}
\Omega_2 &= Z > Z_2 \\
\Omega_1 &= Z > Z_1 \\
Z &= Z_2 \\
Z &= Z_1
\end{align*}
\]

Figure 2. Joint Density Function and Most Probable Point (MPP) for Two Random Variables.
RELIABILITY ANALYSIS USING COMPONENT STRESS AND MATERIAL RESISTANCE CURVES

The example shown in Fig. 3 considers a circular disk subjected to two equal and opposite point loads. The disk is assumed to fail when the equivalent stress at the center of the disk exceeds the material yield stress, which is a function of temperature. Random variables considered include the loading, thickness of the disk, and the temperature. A simple relationship is used to describe the degradation of yield stress as a function of temperature.

Using NESSUS, the distribution functions for stress and strength were computed. The reliability analysis, also performed with NESSUS, then computed the probability of strength being less than stress, which was considered failure. The probabilistic analysis was verified using both AMV and Monte Carlo with the circular disk modeled in closed-form and with finite elements.

Component Stress
Maximum von Mises Stress in Disk Under Load
Thin Disk Modeled Using Finite Elements

Material Resistance
Yield Stress Modeled as Function of Thermal Cycles

\[ \sigma_y = \sigma_{y0} \left( \frac{T_F - T}{T_F - T_0} \right)^n \]

Probability of Failure Computed Using NESSUS

\[ p_f = 0.00291 \]

Figure 3. Component Reliability Analysis Demonstrated for Simple Example.
ROCKET ENGINE TURBINES SUBJECT TO SEVERE CONDITIONS

Representative of a more real world component reliability problem, a model of an SSME component was considered. The high-pressure fuel turbopump blade, shown in Fig. 4, represents a critical component in the SSME engine in that failure of a blade can result in loss of the complete engine. Stringent limitations on size and weight coupled with the hot hydrogen enriched steam turbine fluid and the cold hydrogen cooling fluid results in a very severe thermal environment. Probabilistic methods are ideally suited for the SSME turbine blade analysis where the lack of available local measurements results in significant uncertainty in loads such as thermal response. The lack of data is attributed to the difficulty in making measurements in the extreme environments and operating conditions within the engine.

• Severe Design Requirements
  - Comparatively Short but Severe Service Life
  - Strict Limitations on Size and Weight
  - High Energy Content of Fluids
  - High Specific Work Output
  - Rapid Start and Short Run Duration
  - Severe Thermal Shock Conditions
  - High Stage Loading and Stress
• Blades Prone to High Cycle Fatigue Cracking
• Operating Stresses and Deflections Must be Closely Controlled

Figure 4. Space Shuttle Main Engine (SSME) Turbine Blade.
TURBINE BLADE RANDOM VARIABLE INPUT

Several methods exist for modeling uncertainty, such as probability distributions, fuzzy sets, convex models, bounding, etc. The probability distribution approach is used here to model each engineering variable in terms of its statistical parameters, namely its mean, standard deviation and distribution type. The standard deviation characterizes the magnitude of the scatter in the data and the distribution describes how the scatter is distributed about the mean. The variables listed in Table 1 were used for the demonstration analyses presented in this paper.

Table 1. Random Variable Definitions Used for the Turbine Blade Analysis.

<table>
<thead>
<tr>
<th>Variable</th>
<th>Symbol</th>
<th>Mean Value</th>
<th>Standard Deviation</th>
<th>Distribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Crystal Orientation about z</td>
<td>$\theta_z$</td>
<td>+3°</td>
<td>3.9°</td>
<td>Normal</td>
</tr>
<tr>
<td>Crystal Orientation about y</td>
<td>$\theta_y$</td>
<td>-2°</td>
<td>3.9°</td>
<td>Normal</td>
</tr>
<tr>
<td>Crystal Orientation about x</td>
<td>$\theta_x$</td>
<td>+5°</td>
<td>3.9°</td>
<td>Normal</td>
</tr>
<tr>
<td>Young's Modulus</td>
<td>$E$</td>
<td>18.38E6 psi</td>
<td>0.46E6 psi</td>
<td>Normal</td>
</tr>
<tr>
<td>Poisson's Ratio</td>
<td>$\nu$</td>
<td>0.386</td>
<td>0.00965</td>
<td>Normal</td>
</tr>
<tr>
<td>Shear Modulus</td>
<td>$G$</td>
<td>18.63E6 psi</td>
<td>.47E6 psi</td>
<td>Normal</td>
</tr>
<tr>
<td>Material Parameter</td>
<td>$B_0$</td>
<td>86.0</td>
<td>0.086</td>
<td>Normal</td>
</tr>
<tr>
<td>Density</td>
<td>$\rho$</td>
<td>0.805E-3</td>
<td>0.493E-5</td>
<td>Normal</td>
</tr>
</tbody>
</table>
TURBINE BLADE CREEP RUPTURE RELIABILITY ANALYSIS

A component reliability analysis of the turbine blade considering failure by creep rupture was performed. The turbine blade is modeled using the finite element model shown in Fig. 5. The blade is composed of a single crystal material described by three elastic constants, and three orientation angles. In the analysis, the blade is rotating at a constant speed and operating at a constant temperature. The failure mode being studied is creep rupture due to operation of the blade under elevated temperature. The temperature, stress and rupture life are related using a Larson-Miller relation, given by $P = T(C + \log t)$ where $P$ is the Larson-Miller parameter; $T$ is the absolute temperature; and $t$ is the rupture life. More detail of this analysis is given in Ref. [10].

Possibly one of the most valuable products of the probabilistic analysis are the probabilistic sensitivity factors (PSF), shown by the bar chart in Fig. 5. The PSF's provide an important ranking of the problem variables with respect to the total uncertainty in the response. Therefore, since the statistics of the input variables are contained in these sensitivity data, the PSF data provide a more realistic and useful ranking of the variables.

![Turbine Blade Operating at High Speed in High Temperature Environment](image)

![Failure by Creep Rupture Possible if Operated Past Critical Time](image)

![AMV+ Procedure Used to Assess Reliability](image)

Figure 5. Creep Rupture Reliability Analysis of the Turbine Blade.
PROBABILITY OF EXCEEDING 60 KSI EFFECTIVE STRESS

Another component reliability analysis of the turbine blade considers stress exceedance. Figure 6 shows the probability of the von Mises stress exceeding 60 ksi. The plot was obtained by computing the probability of exceeding 60 ksi stress at each node using the NESSUS program and plotting the results using a general-purpose finite element graphics program.

The probabilistic information was obtained from a mean-based sensitivity analysis and must therefore be interpreted accordingly. The contours indicate where the high failure probability regions are located and where more refined analyses should be directed. It should be noted that the high probability regions may not be the same as the high stress regions from a deterministic analysis. This is because the standard deviation in stress varies from location to location in the mesh. For example, although the mean stress at some location (A) may be lower than the mean stress at some other location (B), the standard deviation may be higher at A than at B (i.e., more variation in stress). Thus, the probability of exceeding a certain stress level could be higher at A than at B even though the mean stress is lower at A than at B.

Figure 6. Probability of Exceeding 60 ksi Effective Stress.
What dictates failure in real structures, as previously described, will usually be a sequence or interaction of individual component failure modes. A popular method for modeling system failure as a function of component failures is with a fault tree. A fault tree provides a systematic way to deal with multiple, possibly complicated, failure paths composed of multiple components or multiple failure modes (bottom events). In traditional fault tree analysis, probabilities are assigned to the bottom events, and propagated through gates (AND, OR, etc.). For typical structural reliability analysis problems, however, the failure events will often times be correlated due to common problem variables. To account for this dependency, it is necessary that the limit state functions, rather than simply the probabilities, be used to define the bottom events. In addition, conditional limit state functions must be established that represent updated structural system configurations as a result of sequential failures (for modeling redundancy or progressive fracture for example). Figure 7 shows how failure modes and sequential failure can be modeled using a fault tree. Sequential failures can be modeled using the PRIORITY AND gate. A sequence of limit state functions corresponding to a sequence of updated structural configurations with load redistribution, must be generated during the analysis. This fault tree methodology has been developed and is implemented in NESSUS [9].

**Figure 7.** NESSUS Probabilistic Fault Tree Analysis Methodology.
NESSUS SYSTEM RELIABILITY ANALYSIS EXAMPLE

Figure 8 shows a simple fault tree for a simple structural component. The hypothetical structure has three failure modes: vibration, stress and fracture. The structure is considered failed if any of the three failure conditions are satisfied. This is represented with the "OR" gate. Failure is defined as the first natural frequency being within a certain range, the stress exceeding a stress limit, and the mode I stress intensity factor exceeding the fracture toughness. For vibration, a two-sided limit is used to define failure and is represented in terms of an "AND" gate. As indicated, three of the bottom events are modeled analytically and one is given by finite element model.

Probability of system failure was obtained using several sampling methods; conventional Monte Carlo and adaptive importance sampling (AIS) using the exact limit state functions, and AIS on an approximate limit state. The approximate limit state consists of a closed-form approximation to the finite element model computed using the AMV+ procedure described earlier. The results indicate that the AIS method achieved results comparable to those obtained using Monte Carlo at 1/78 the computational cost. As also indicated, good agreement is obtained using the approximate limit state also, with further reductions in calculation cost. This example indicates the practical application of structural system reliability using a fault tree approach with advanced probabilistic methods.

PROBABILISTIC FAULT TREE

SYSTEM RELIABILITY RESULTS

\( P_f = \text{Prob.}\{ (g_1 < 0) \land (g_2 < 0) \land (g_3 < 0) \land (g_4 < 0) \} \)

<table>
<thead>
<tr>
<th>Method</th>
<th>( P_f )</th>
<th>System Samples*</th>
<th>CPU Time (sec)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Monte Carlo</td>
<td>0.01170</td>
<td>10,000</td>
<td>54,800</td>
</tr>
<tr>
<td>AIS Exact**</td>
<td>0.01176</td>
<td>97</td>
<td>706</td>
</tr>
<tr>
<td>AIS Approx.***</td>
<td>0.01183</td>
<td>-</td>
<td>19</td>
</tr>
</tbody>
</table>

* Four bottom events per system sample not including initial AMV+ function evaluations
** Adaptive Importance Sampling of exact functions
*** Adaptive Importance Sampling of approximate functions

Figure 8. NESSUS System Reliability Analysis Example.
SYSTEM RELIABILITY ANALYSIS OF THE TURBINE BLADE

To demonstrate the computational system reliability methodology on a realistic-sized problem, the turbine blade was analyzed probabilistically considering three modes of failure: frequency, yield, and rupture. The procedure employing approximate limit states for the component modes is recommended for this level of deterministic modeling. Each mode of failure is first analyzed using the AMV+ procedure to establish the approximate limit state. The computational effort required for this step is given in each bottom event box in Fig. 9. Next, the system failure is computed using AIS. This procedure is automated in NESSUS. This example demonstrates that system reliability assessment is now possible for complex structural systems.

Figure 9. System Reliability Analysis of the Turbine Blade.
SYSTEM RELIABILITY ANALYSIS IDENTIFIES CRITICAL FAILURE MODES AND RANDOM VARIABLES

As in the component reliability analysis procedure described earlier, the system reliability analysis also provides a probabilistic ranking of the inputs. The inputs for the system analysis are the component failure modes, whereas the inputs for the component analysis are the problem variables. Thus, not only are the problem variables ranked by importance, but the dominate failure modes are also identified. As shown in Fig. 10, for example, the creep rupture mode is seen to contribute the most to the overall system probability. The bar chart on the right shows the problem variable ranking for each failure mode. This type of information is required to establish a reliability based design procedure.

Figure 10. Dominant Failure Modes and Problem Variables are Identified in the System Reliability Analysis.
How the probabilistic methodologies presented here would fit into a typical design procedure is shown in Fig. 11. The shadowed boxes indicate the position of the component and system reliability analyses in the overall design cycle. The first step in the process is to identify all of the physical variables and sources of uncertainty. How these physical variables affect the problem variables comprises the next step. For example, in the SSME, the fuel mixture ratio (a physical variable) affects the pressure, thermal, and centrifugal loading (problem variables) on the turbine blade. In the next steps, the individual failure modes are identified and analyzed both deterministically and probabilistically. Next, the overall system failure and dominate failure modes and problem variables are identified, which are used in subsequent steps to alter the design subject to the design requirements (e.g., cost, weight, reliability).
STATE-OF-THE-ART TECHNOLOGY IN COMPUTATIONAL STRUCTURAL RELIABILITY ANALYSIS

It must be recognized that probabilistic structural analysis methods are not as well developed as deterministic design methodologies. Computational tools, such as those described in this paper, are just recently becoming available and have only been applied to limited numbers of problems. Moreover, training and experience are required to conduct a probabilistic analysis, neither of which are easily acquired at the present time. Consequently, before probabilistic methods can be successfully integrated into the current design cycle, several challenges, such as those listed in Fig. 12, must be overcome.

- What is Possible Now:
  - Moderately Detailed Component Reliability Analyses (10,000 DOF)
  - Simplified System Reliability Analyses (< 5 Modes)
  - Simplified Integrated Risk/Reliability Analyses

- Current Challenges:
  - Awareness, Comprehension and Acceptance
  - Identification of Uncertainties or Randomness
  - Probabilistic Data Bases
  - Robustness and Validation of Recently Developed Computational Tools

Figure 12. State-of-The-Art In Computational Structural Reliability Analysis.
APPLICATIONS WILL SUPPORT (DRIVE) FUTURE RESEARCH AND DEVELOPMENT

The requirement for a probabilistic approach is dictated by need, and current application needs will certainly impact the future research directions. A few of these application areas are listed in Fig. 13. One of the more promising areas is probabilistic fracture mechanics. This is because fracture usually results in sudden catastrophic failure of the system. Both progressive fracture and multi-site damage are of current concern and will require probabilistic methods.

- Probabilistic Progressive Fracture
- Multi-Site Damage (Linkup)
- Parallel Processing
- Certification
- Health Monitoring
- Multi-Disciplinary Reliability Assessment
- Optimum Inspection Scheduling and Retirement
- Human/Modeling Error

Figure 13. Some Current Application Areas That Will Require Probabilistic Methods.
REFERENCES


