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MULTI-CHANNEL ELECTRONICALLY SCANNED CRYOGENIC PRESSURE SENSOR

AWARDS ABSTRACT

There are currently 17 cryogenic wind tunnels in operation worldwide, most operate in a temperature range of -190°C to +70°C. The coldest temperature falls approximately 140°C below the lowest mil-spec temperature for the performance rating of electronic components. Cryogenics is used to lower flow temperatures to achieve high Reynolds numbers by increasing flow density. These low temperatures present problems with instrumentation hardware designed to measure pressure when subjected to this cold environment.

A miniature, multi-channel, electronically scanned pressure measuring device uses electrostatically bonded silicon dies in a multi-element array. These dies are bonded at specific sites on a Pyrex 7740 glass substrate pre-patterned with gold circuit traces. In addition, thermal data is multiplexed and recorded on each individual pressure measuring diaphragm.

Novel aspects of the present invention include the ability to function in a cryogenic environment without the need of heaters to keep the sensor at constant temperatures. The fabrication technique and materials used produce an instrument that will deliver repeatable data each time it is thermal cycled without recalibration. In addition, each pressure measuring component has its own temperature sensor, thereby eliminating thermal offset errors due to changing temperatures.

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Origin of the Invention

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The invention described herein was made by employees of the United States Government and may be manufactured and used by or for the Government for governmental purposes without the payment of any royalties thereon or therefor.

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Background of the Invention

1. Field of the Invention

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This invention relates generally to a pressure sensor and more particularly to a multi-channel electronically scanned pressure sensor for cryogenic environments.

2. Description of the Related Art

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There are currently 17 cryogenic wind tunnels in operation worldwide, most operate in a temperature range of -190°C to +70°C. The coldest temperature falls approximately 140°C below the lowest milspec temperature for the performance rating of electronic components. In an effort to develop higher lift and lower drag airfoils, aerodynamicists are striving to study boundary layer behavior at very high Reynolds numbers. Cryogenics is used to lower flow temperatures to achieve high Reynolds numbers by increasing flow density. These low temperatures present problems with instrumentation hardware designed to measure
pressure when subjected to this cold environment.

The prior art uses adhesive bonding of individual silicon pressure sensing die of silicon or Pyrex. A stress isolation pedestal may also be incorporated. An adhesive material is required to secure each sensor to the substrate. Since the adhesive exhibits a large variation in coefficient of thermal expansion (CTE) with temperature, this results in large apparent strains being exerted upon the sensors as thermal cycling occurs. Adhesive materials with critical transition temperatures above 77K will also cause thermally induced offset variations which will cause non-repeatability of sensor output data in cryogenic applications. This problem is more accentuated with the use of thinner membrane thicknesses necessary for accurate measurements in cryogenic wind tunnels.

Objects of the Invention

It is accordingly an object of this invention to provide a device capable of performing multichannel pressure measurements at cryogenic temperatures.

It is another object of the present invention to perform the pressure measurements with increased accuracy, low noise and improved repeatability at cryogenic temperatures.

Additional objects and advantages of the present invention are apparent by the drawings and specification which follow.

Summary of the Invention

The present invention overcomes the problem of measuring pressure in a cryogenic environment. This is accomplished by providing
a miniature, multi-channel, electronically scanned pressure measuring
device which uses electrostatically bonded silicon dies in a multi-element
array. These dies are bonded at specific sites on a Pyrex 7740 glass
substrate pre-patterned with gold circuit traces. In addition, thermal data
is multiplexed and recorded on each individual pressure measuring
diaphragm.

The electronics package consists of basically two parts: an
amplifier circuit comprised of a monolithic instrumentation amplifier on a
standard printed circuit card, and a gold circuit patterned Pyrex glass
substrate comprised of pressure sensing dies and multiplexing devices.
Pyrex is a trademark of Corning, Inc.

The pressure sensing device utilizes square silicon dies which have
been etched on the back surface to form a very thin silicon diaphragm.
The diaphragm has four highly doped (e.g., boron) piezo-resistive
elements of the same geometry patterned in the diaphragm surface, two
acting in compression and two acting in tension. There is also one
additional bridge element on the die rim, insensitive to pressure, which
provides a temperature measurement of each silicon pressure sensing die
used for temperature compensation. In order for the silicon pressure
sensing dice to operate properly below -100°C, it is necessary that the
dopant impurity level be on the order of $1 \times 10^{20}$ atoms of boron per cubic
centimeter. This dopant level ensures that the sensors do not suffer
from charge carrier freezeout due to low charge carrier mobility.

The requirement for structural integrity in electronic packaging is
met by the use of metallic materials with low coefficients of thermal
expansion such as Kovar. The coefficient of thermal expansion of Pyrex
7740 glass matches that of silicon well enough to tolerate thermal
cycling in properly annealed substrates. The Pyrex substrate is first
metallized with titanium/tungsten for the adhesion layer and then a layer
of gold is deposited for good conduction. The circuitry pattern is then
etched to produce low resistance, high quality tracks. The silicon
pressure sensors are bonded to the metallized substrate by field-assisted
thermal bonding. This process takes place at 375°C. It is performed
under high vacuum with an applied field strength of 1E6 volts per meter
on the silicon sensors-Pyrex interface. After bonding, the sensor
substrate is then attached to the tubing plate using a thin sheet of
thermosetting polyamide film. The modified polyamide material remains
flexible at -196°C and provides a compliant bond between these two
surfaces. The electrical interconnection of the sensor circuitry to the
substrate is made using a thermo-ultrasonic wedge-ball bonding machine
with substrate heating applied.

A modified, commercially available analog-to-digital converting
data acquisition interface card is used to scan the pressure inputs. Since
the instrumentation module is equipped with its own instrumentation
amplifier and multiplexing circuitry, the interface could be streamlined by
interconnecting the instrumentation amplifier output directly to the
sample and hold input on the PC card with coaxial cable. This improves
the signal to noise ratio since all millivolt level signal leads are contained
within the instrument module and are just a few centimeters in length.
Similarly, the multiplexing switches are also within the module. Linking
the address and enable lines from the remote module to the timing
circuitry on the PC card via line drivers and receivers ensures quiet,
reliable operation. The output of the instrumentation amplifier is digitized
by the A/D card in the PC. Data taken is first stored to RAM, then saved
to diskette and displayed as real-time engineering units on the monitor.
The data rate and sample time interval for a data record is preset by the
scanning software parameters. The menu driven software provides for
access to data files for storage, recall of sensor calibration files and for
real time display.

This invention functions in a cryogenic environment without the need of heaters to keep the sensor at constant temperatures. The fabrication technique and materials used produce an instrument that will deliver repeatable data each time it is thermal cycled without recalibration. In addition, each pressure measuring component has its own temperature sensor, thereby eliminating thermal offset errors due to changing temperatures.

In addition, the advantage over existing devices is the freedom from hand mounting of each sensor and freedom from the tedious application of elastomer or adhesive bonding material to each sensor. The sensor array is one coupon, just as if it was a VLSI circuit with the sensors precisely positioned on the substrate without any trace of die attach adhesive. The application of pressure sensors to make accurate measurements is greatly enhanced due to this measure. The adhesive material necessary to attach sensors in prior art is not conducive to accurate measurements since the elastomeric material expands and contracts with temperature variations. This undesirable effect applies mechanical forces to the sensors in such a fashion as to cause drift. The main advantage of this method is in cryogenic applications. The sensors remain bonded throughout hundreds of thermal cycles and exhibit stable and repeatable calibrations for years. The accuracy of the sensors is stable and there is no need for any mechanical calibration valve apparatus within the measuring instrument.

The exact placement of the sensors will facilitate automated or manual ballbond electrical lead placement. The elastomerically bonded sensors usually have some randomness to the positioning and also have elastomeric residue present plus undesirable outgassing fumes from the curing process can cause corrosive effects on nearby components.
main advantage is in the stability, the curing process takes
up to a full year to complete and this effects the measurement accuracy
of the instrument since the elastomeric material induces random drift in
the sensor which cannot be accounted for by any means other than
frequent recalibration which is very costly in the case of wind tunnels.
Another advantage is that the sensing module can operate accurately at
cryogenic temperature and thus does not need auxiliary heaters to
maintain a warm environment during wind tunnel testing. This elimination
of the heating requirement, while maintaining the high accuracy is a great
asset since the model in which the modules reside during the test is not
subject to heating effects from instrumentation within the model. This
has the beneficial effect of allowing the model to remain at the true
freestream temperature of the wind tunnel. Existing technology simply
did not allow this, as a result there was an unwanted disturbance of the
boundary sublayer during cryogenic testing of any model equipped with
auxiliary heaters.

Brief Description of the Drawings

FIG. 1a is a top view of a die;
FIG. 1b is a side view of a die;
FIG. 2 is a schematic illustration of the resistor arrangement;
FIG. 3 is a graph of piezoresistance coefficient versus temperature;
FIG. 4 is a plot of offset hysteresis;
FIG. 5 is a plot of sensitivity hysteresis;
FIG. 6 is a cutaway view of a pressure sensor bonded to a
substrate;
FIG. 7 illustrates the PC interface with the pressure/temperature
calibration system;
Description of the Preferred Embodiments

The electronics package consists of basically two parts: an amplifier circuit comprised of a monolithic instrumentation amplifier on a standard printed circuit card, and a gold circuit patterned Pyrex glass substrate comprised of pressure sensing dies and multiplexing devices.

Referring to FIGs. 1a and 1b, the electronics device utilizes square silicon dies 10, approximately 2.54 mm on each side, which have been etched on the back surface to form a very thin silicon diaphragm 20, approximately 0.3 mm high. Referring to FIG. 2, the diaphragm 20 has four highly doped (e.g., boron) piezo-resistive elements 30 of the same geometry patterned diffused in the diaphragm surface, two acting in compression and two acting in tension. There is also one additional bridge element 40 on the die rim, insensitive to pressure, which provides a temperature measurement of each silicon pressure sensing die used for temperature compensation. As illustrated in FIG. 3, in order for the silicon pressure sensing dice to operate properly below -100°C, it is necessary that the dopant impurity level be in the range of $1 \times 10^{19}$ to $1 \times 10^{21}$ atoms of boron per cubic centimeter. The higher the level of boron, the greater the insensitivity to cold. This dopant level ensures that the sensors do not suffer from charge carrier freezeout due to low charge carrier mobility. The piezoresistive pressure sensors are influenced not only by the thermal offset and sensitivity shifts in the bridge resistors but also are heavily influenced by mechanical mounting...
effects between the die and substrate due to temperature dependent
differences in coefficient of thermal expansion between the die and
substrate materials, all of which contribute to the sensor overall thermal
offset drift. Plots of individual sensors, mounted by the preferred method
of field assisted bonding to a Pyrex 7740 substrate yield smoothly
varying, repeatable offset and sensitivity curves, as shown in FIGs. 4 and
5, respectively.

The requirement for structural integrity in electronic packaging is
met by the use of metallic materials with low coefficients of thermal
expansion such as Kovar. The coefficient of thermal expansion of Pyrex
7740 glass matches that of silicon well enough to tolerate thermal
cycling in properly annealed substrates. Referring to FIG. 6, the Pyrex
substrate 50 is first metallized with titanium/tungsten for the adhesion
layer 60 and then a 1.5 micrometer layer of gold is deposited 70 for
good conduction. The circuitry pattern is then etched to produce low
resistance, high quality tracks. The silicon pressure sensors 80 are
bonded to the metallized substrate 50 by field-assisted thermal bonding.
This process, otherwise referred to as Mallory bonding by the electronics
industry, takes place at 375°C. It is performed under high vacuum with
an applied field strength of 1x10^6 volts per meter on the silicon sensors-
Pyrex interface. After bonding, the sensor substrate is then attached to
the tubing plate 90 using a thin sheet of thermosetting polyamide film
100. The modified polyamide material remains flexible at -196°C and
provides a compliant bond between these two surfaces. The electrical
interconnection of the sensor circuitry to the substrate is made using a
thermo-ultrasonic wedge-ball bonding machine with substrate heating
applied.

A modified, commercially available, high resolution A/D analog to
digital conversion interface card is used to scan the pressure inputs.
Referring to FIG. 7, since the instrumentation module is equipped with its own instrumentation amplifier 66 and multiplexing circuitry 65, the interface can be streamlined by interconnecting the instrumentation amplifier output directly to the sample and hold input on the PC card 55 with coaxial cable 75. This improves the signal to noise ratio since all millivolt level signal leads are contained within the instrument module and are just a few centimeters in length. Similarly, the multiplexing switches are also within the module. Linking the address and enable lines from the remote module to the timing circuitry on the PC card via line drivers and receivers ensures quiet, reliable operation. The output of the instrumentation amplifier is digitized by the A/D card in the PC. Data taken is first stored to RAM, then saved to diskette and displayed as real-time engineering units on the monitor. The data rate and sample time interval for a data record is preset by the scanning software parameters. The menu driven software provides for access to data files for storage, recall of sensor calibration files and for real time display.

Referring to FIGs. 1a-b, 2 and 6, four resistive elements 30 on the die diaphragm 20 are connected in a Wheatstone Bridge configuration by means of gold wire bonding. A constant D.C. voltage is placed across two legs of the bridge as input voltage, and the other two legs are voltage outputs. When pressure is applied to the silicon diaphragm a strain occurs, causing a resistance imbalance in the bridge thereby causing an output voltage or a change in the existing output voltage on the output legs of the bridge. This output voltage is applied to a differential multiplexer switch. Referring to FIG. 7, the output of the multiplexer 65 is tied to the input of an instrumentation amplifier 66. The fifth element on the die periphery 40 is on part of the silicon die bulk that supports the thin diaphragm, and the element is patterned in a location and with a geometry that renders it insensitive to strain, but the element
changes resistance proportional to temperature. This element is powered with a constant current and the change in resistance due to change in temperature produces a change in voltage drop across the element. This voltage change is connected to a multiplexer switch 65 in the same manner as the pressure sensing elements on the die diaphragm.

Referring to FIG. 7, the pressure measuring module communicates to the outside world through a personal computer equipped with analog to digital converters and controlling software. The computer software produces and delivers binary addresses and phased enable pulses to the module multiplexer chips which are connected to all the pressure sensing dies. These computer generated pulses cause the multiplexer chips to scan the pressure dies and temperature sensors on each die.

Referring again to FIG. 6, fabrication of the sensing portion of this package involves the electrostatic bonding of highly doped piezoelectric silicon pressure dies 80 to a 7740 Pyrex glass substrate 50. Prior to die bonding, the glass substrate 50 is metallized, by sputter deposition with a thin adhesion layer 60, (approximately 1000 Angstroms), of tungsten with 10% titanium. This adhesion layer 60 is over-coated with approximately one micrometer of sputtered gold. Both the adhesion layer 60 and gold layer 70 are deposited in the same machine without breaking vacuum. The metallized glass substrate 50 is circuit patterned by standard photolithography. Referring to FIG. 8b, the metallized and patterned substrate is then drilled with .025 inch holes 61 at each silicon die location and thermally annealed in air at 600°C for one hour. This completes the glass substrate preparation.

Referring to FIGs. 8a, 8c and 8d, the silicon dies 150 and the prepared glass 50 are loaded in a fixture 170 of a dielectric (SiO₂) high temperature material. The fixture 170 is designed to hold the individual sensors to form a sensor array. This sensor array is held in position over
the metallized substrate 50 so that each die is precisely positioned over its .025 inch pressure orifice 160. In addition to positioning, this cast fixture allows for pressure to be applied to each silicon die 150, to bring the die into close contact with the glass substrate 50. Contacting pressure is applied to the silicon die 150 by spring loaded contacts 190 inserted into holes 200 cast in the fixture 170 centered over each pressure die location. The loaded fixture is placed into a tube furnace and evacuated to a pressure below 5x10^{-6} torr and heated to 375°C. When the temperature has reached equilibrium, an electrical potential of 800 volts D.C. is applied to the fixture electrodes for five minutes causing electrostatic bonding of the silicon pressure dies to the glass substrate 50. The glass substrate with bonded silicon dies are then mounted to a Kovar pressure tube plate with pressure orifices aligned over each .025 inch hole in the glass substrate. The fixture was made by casting soft gel state SiO\textsubscript{2} over a male plug mold having slightly larger dimensions than the finished sensor array. The SiO\textsubscript{2} material was fired in a kiln just as a ceramic material to make it hard. The SiO\textsubscript{2} was chosen due to its desirable material properties of the fired product, low temperature coefficient of linear expansion, high dielectric strength, ability to withstand high temperature, and low outgassing for vacuum processing during the bonding operation.

Each cavity has the same outline as the individual sensor which is inserted into the cavity. The depth of the cavity is sufficient to accept the sensor and a "top hat" piece 220 of silicon with the same outline as the sensor which is inserted into the fixture before the sensor in order to distribute the mechanical load induced by the spring loaded pin 190. The spring loaded pin 190 is used to hold the sensor chip in intimate contact with the Pyrex substrate 50 during the bonding process. Referring to FIG. 8b, the pin 190 also allows an electrical contact for the bonding
potential to be applied to the sensor 250 when the fixture is connected as shown in FIG. 8d with the end plate (anode) 230 and metallized quartz bottom cathode 240. For the bonding operation, the top hats 220 are loaded in the cavities. The sensors 50 are then loaded, membrane side in contact with the top hats 220. The drilled and metallized Pyrex substrate 50 is put in contact with the sensors 50 and the metallized quartz cathode 240 is placed against the bottom of the fixture. The spring loaded pins 190 are inserted from the top of the fixture. The top plate or anode 230 is then put over the pins 190 and the plates are secured by stainless bolts 280. The loaded fixture is then placed in a vacuum oven, pumped down and the oven temperature adjusted to 375°C. An inert atmosphere such as nitrogen, argon or helium could be used in lieu of evacuation to prevent oxidation. Once thermal equilibrium is reached, an 800 volt potential is then applied to the fixture, the bonding takes place in just a few minutes. The oven is then allowed to cool to room temperature and the fixture is removed, unbolted and opened up to free the substrate which is ready for mounting on the tubing plate. A polyamide film adhesive material is used for the attachment of the sensor array which is comprised of the individual sensors to the tubing plate. This material in thin sheet form has demonstrated flexibility when dipped in liquid nitrogen since it remains compliant at cryogenic temperatures. The polyamide sheet is first cut to the size of the Pyrex substrate and holes are punched to allow gas conductance of the pressure ports. For the assembly, the polyamide film 100 is placed on the tubing plate 90 so the holes line up. The sensor array Pyrex coupon is then placed upon the polyamide film, with the holes registered. The tubing plate and positioned array is placed within a vacuum bag which is then evacuated and placed in an oven at +125°C. The polyamide is plastic at high temperatures and flows between the
bottom of the Pyrex substrate and the tubing plate. This forms a compliant layer between the Pyrex coupon and the tubing plate that withstands the extreme temperatures and remains free from leakage at cryogenic temperatures. A high temperature polyamide film material may also be used for instruments destined for high temperature applications. As an alternative, the application of a polyimide in liquid suspension in solvent is also possible for the purpose of attaching the Pyrex coupon to the tubing plate. A curing cycle at elevated temperature is required.

After substrate to pressure tubing plate mounting is complete, the multiplexer chips are mounted on the Pyrex substrate with epoxy. Multiplexers and silicon dies are gold wire bonded to their prospective circuit locations. This completes the pressure sensing and scanning half of the electronics package.

The amplifier is constructed using standard printed circuit board technology, and utilizes a monolithic instrumentation amplifier as the active component on the printed circuit card. The amplifier card makes contact with the pressure sensing substrate through gold plated, spring loaded contacts soldered to the amplifier card. These spring loaded contacts are aligned with gold contact pads on the sensing substrate.

A system capable of controlling temperatures from -184°C to +220°C and pressures from 0 to 344.74 Kpa was used to calibrate the sensing module. A thermocouple accurate to within +/- 0.1°C of reading was used to calibrate the temperature of sensors within the module.

Due to the parallel circuit of the sensor supply bus which necessitates constant voltage excitation, and sensor resistance which decreases as temperature decreases, the sensors are more sensitive with decreasing temperature. The hysteresis, however, is less than the resolution of the encoder.

The measurement of calibration pressures is accurate to within +/-
0.01% of full scale (344.74 Kpa). The set point resolution is 3.447 Pa. Helium is used as the calibration gas. The uncertainty of the temperature controller is +/- 0.5°C with a temperature deviation of +/- 0.1°C after stabilization. The repeatability following a temperature reset is +/- 0.25°C.

The uncertainty of the analog to digital conversion system used to scan the pressure module is +/- 0.01% F.S. The resolution of the analog to digital conversion system is +/- 0.01% F.S. The overall error of the multichannel pressure sensing system, based on several pressure and temperature calibrations repeated within 180 days is 0.1% F.S. for -196°C to +100°C over the differential pressure range -101.35 Kpa to +241.32 Kpa.

Many modifications, improvements and substitutions will be apparent to the skilled artisan without departing from the spirit and scope of the present invention as described in the specification and defined in the following claims.

What is claimed is:
Abstract of the Disclosure

A miniature, multi-channel, electronically scanned pressure measuring device uses electrostatically bonded silicon dies in a multi-element array. These dies are bonded at specific sites on a glass, pre-patterned substrate. Thermal data is multiplexed and recorded on each individual pressure measuring diaphragm. The device functions in a cryogenic environment without the need of heaters to keep the sensor at constant temperatures.
FIG. 1a

FIG. 1b

FIG. 2

ORIGINAL PAGE IS OF POOR QUALITY
Figure 3: Graph showing the relationship between piezoresistive sensitivity and dopant density at various temperatures (T -75°C, T -50°C, T -25°C, T 0°C, T 25°C, T 50°C, T 75°C, T 100°C, T 125°C, T 150°C, T 175°C).
CRYO ESP 16 CH 1
Offset volts

Volts

Deg. C

Fig. 4
CRYO ESP 16 CH 1
sensitivity normalized for gain = 1000

Relative Sensitivity

Deg. C

FIG. 5