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Prepared for the
33rd Aerospace Sciences Meeting and Exhibit
sponsored by the American Institute of Aeronautics and Astronautics
Reno, Nevada, January 9–12, 1995
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Abstract
Linearized Euler equations are used to simulate supersonic jet noise generation and propagation. Special attention is given to boundary treatment. The resulting solution is stable and nearly free from boundary reflections without the need for artificial dissipation, filtering, or a sponge layer. The computed solution is in good agreement with theory and observation and is much less CPU-intensive as compared to large-eddy simulations.

1. Introduction

The full, compressible Navier-Stokes equations govern the process of sound generation and propagation to the far field. However, the resolution requirement for high-Reynolds-number turbulent flows makes direct numerical simulation (DNS) impractical due to current computer limitations.

Therefore, Mankbadi et. al.1,2 proposed the extension of the large-eddy simulation (LES) approach for use in the prediction of sound generation and propagation. In this approach, the Navier-Stokes equations are filtered into large-scale components, which are calculated directly, and small, unresolved components, which are modeled. The only limitation of an LES approach as opposed to DNS is that sound radiation by the unresolved scales are not accounted for. However, it is believed that the large scales are more efficient than smaller ones for radiating sound. Thus, LES is currently the most accurate approach to jet noise predictions. However, the LES approach is still CPU-intensive, particularly for three-dimensional computations of both the near and far fields.

The present work is concerned with exploring the use of the less computer-demanding linearized Euler equations (LEE) for jet noise predictions. The LEE approach neglects both viscosity and nonlinear effects. The viscous effects can be neglected since the large-scale dynamics in free shear flows are essentially inviscid (e.g., Ref. 3). Nonlinearity, however, seems to be important (e.g., Ref. 4).

Yet, much of the physics can be obtained by considering the linear equations. Several attempts have succeeded in studying the physics of jet noise based on a simplified form of the linearized Euler Equations (e.g., Ref. 5-8). The linearized Euler equations

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describe simultaneously both the near field where the sound is generated and the propagation of sound to the far field. As such, the problem of matching the near field to the far field does not arise. The linearized Euler equations fully account for non-parallel flow effects and for the simultaneous presence of non-discrete frequencies.

Special attention is given to the boundary treatment in order to avoid the generation of spurious waves that could render the computed solution entirely unacceptable. Several proposals for boundary treatments are considered, and used where appropriate. The treatment adopted in this work resulted in a stable solution nearly free from reflections without the need to add artificial dissipation, filtering, or sponge layers. The computed solution is found to be in good agreement with theory and observations.

2. Governing Equations

Starting from the full Navier-Stokes equations in conservative form, neglecting viscosity, and linearizing about a mean flow \((U, V)\), the axisymmetric linearized Euler equations may be written in cylindrical coordinates as:

\[
\begin{align*}
\frac{\partial \tilde{\mathbf{Q}}}{\partial t} + \frac{\partial \tilde{\mathbf{F}}}{\partial x} + \frac{\partial (r \tilde{\mathbf{G}})}{\partial r} &= \frac{1}{r} \tilde{\mathbf{S}} \\
\end{align*}
\]

where:

\[
\tilde{\mathbf{Q}} = \begin{bmatrix} \tilde{\rho} \\ \tilde{\rho}u \\ \tilde{\rho}v \\ \tilde{\rho}e \end{bmatrix} \quad \text{and} \quad \tilde{\mathbf{F}} = \begin{bmatrix} \tilde{\rho}u \\ \tilde{\rho}v + 2\tilde{\rho}U - \tilde{\rho}U^2 \\ \tilde{\rho}V + \tilde{\rho}U - \tilde{\rho}UV \\ (\tilde{p} + \tilde{\rho}e)U + (\tilde{u} - \tilde{\rho}U)E \end{bmatrix}
\]

and

\[
\tilde{\mathbf{G}} = \begin{bmatrix} \tilde{\rho} \\ \tilde{\rho}U + \tilde{\rho}U - \tilde{\rho}UV \\ \tilde{p}' + 2\tilde{\rho}V - \tilde{\rho}V^2 \\ (\tilde{p}' + \tilde{\rho}e)V + (\tilde{u} - \tilde{\rho}U)E \end{bmatrix}
\]

and

\[
\tilde{\mathbf{S}} = \begin{bmatrix} 0 \\ 0 \\ \tilde{p}' \\ 0 \end{bmatrix}
\]

Here

\[
p' = (\gamma - 1) \left[ \tilde{e} - (\tilde{u}U + \tilde{v}V) \right] + \frac{1}{2} \tilde{\rho} \left( U^2 + V^2 \right)
\]

\[
P = (\gamma - 1) \tilde{\rho} \left[ E - \frac{1}{2} (U^2 + V^2) \right],
\]

and

\[
(\tilde{\rho}, \tilde{u}, \tilde{v}, \tilde{e}) = [\rho', (\rho u)', (\rho v)', (\rho e)']
\]

In this notation, \(U\) is the axial mean velocity and \(V\) is the radial mean velocity.

Velocities are normalized by the jet exit velocity, time by \(D/U_e\), density by the mean exit value, and pressure by \(\rho_e U_e^2\). Here, \(D\) is the nozzle diameter, and the subscript 'e' denotes the exit value at the centerline.

3. Mean Flow

This work uses the analytical functions proposed by Tam and Burton\(^8\) to fit the experimental data of Troutt and McLaughlin\(^9\) in the three streamwise regimes of a Mach 2.1 jet: the potential core, transitional, and fully developed regimes.

In the potential core, ranging from \(0 < x/D < 5\), the half-Gaussian (profile I) is used to describe the axial mean flow velocity:
In the transitional region, $5 < x/D < 8$, profile II is used:

$$U = U_c(x) \quad \text{for } r < h$$

$$U = U_c(x) \exp \left[ -\ln(2) \left( \frac{r - h(x)}{b(x)} \right)^2 \right] \quad \text{for } r > h$$

(10)

In the fully developed regime, $x/D > 8$, profile III is used:

$$U = U_c(x) \exp \left[ -\ln(2) \left( \frac{r}{b(x)} \right)^2 \right]$$

(11)

where $b(x)$ is the half-width of the annular mixing layer and is fitted to the experimental data. The radius of the uniform core $h(x)$ and the centerline velocity $U_c(x)$ are related to $b(x)$ through the conservation of momentum:

$$\int_0^\infty \rho U^2 r \, dr = \frac{1}{2}$$

(12)

For profile I, $U_c = 1$, and hence equation (12) is used to obtain $h(x)$ in terms of $b(x)$. For profile III, equation (12) is used to obtain $U_c(x)$ in terms of $b(x)$. For profile II, $b(x)$ and $h(x)$ are obtained by using a cubic spline fit that matches the values of $b(x)$ and its derivative to that of profiles I and III and likewise for $h(x)$.

Invoking the boundary-layer-type approximation to the mean flow equations shows that the mean pressure can be taken to be uniform in the jet. Under such assumptions, one can show that the continuity equation for the mean flow reduces to that of the incompressible flow, which is used to obtain the radial flow velocity $V(r)$ as:

$$V(r) = -\frac{1}{r} \int_0^r \frac{dU}{dx} \, dr$$

(13)

The above profiles are used to describe the mean flow up to maximum radius $r_{\text{max}} = h + 3b$. For $r > r_{\text{max}}$

$$U = 0$$

$$V = \frac{V_m}{r}$$

(14)

where $V_m$ is the uniform radial velocity in the outer regime. By assuming the total temperature to be uniform, the relation between the static temperature and the axial mean flow velocity is obtained. The equation of state is then used to obtain the mean density in terms of the static temperature.

The computational grid for this problem extends axially from $x/D = 2.5$ to $x/D = 35$, using 196 equally spaced points (25 points per wavelength). Due to the steep mean-flow gradients encountered at the jet exit, the computational grid was begun at an axial distance $x/D = 2.5$ from the actual jet exit.

In the radial direction, the grid begins just above the centerline ($r/D = 0.005$) and extends to $r/D = 16$, with a total of 381 points. The grid is uniform from the centerline to $r/D = 1$, with a spacing of $\Delta r/D = 0.01$. At this point, the grid is stretched geometrically by a factor of 1.01, until the radial spacing is equal to the axial spacing. After this point, the grid is uniform again to the outer radial boundary.

4. Numerical Algorithm

The code is a modified split MacCormack solver, which is second order accurate in time and fourth order accurate in space. This extension of the MacCormack scheme is known as the 2-4 scheme, and was developed by Gottlieb and Turkel\textsuperscript{10}. This scheme has been used successfully on a wide range of fluid and aeroacoustics problems\textsuperscript{11-24}. Sankar, Reddy, and Hariharan\textsuperscript{25} have
evaluated this scheme for aeroacoustics applications. The solution procedure is as follows:

In the present code, the operator is split into separate radial and axial contributions:

$$q^{n+2} = L_x L_y L_z q^n$$  \hspace{1cm} (15)

Each operator consists of a predictor and a corrector step. Each step uses one-sided differencing:

**Predictor:**

$$q^{n+\frac{1}{2}} = q^n - \frac{\Delta t}{6\Delta x} (7F_i - 8F_{i-1} + F_{i-2})^n$$  \hspace{1cm} (16)

**Corrector:**

$$q^{n+1} = \frac{1}{2} \left( q^n + q^{n+\frac{1}{2}} + \frac{\Delta t}{6\Delta x} (7F_i - 8F_{i+1} + F_{i+2})^{n+\frac{1}{2}} \right)$$  \hspace{1cm} (17)

and likewise for the radial direction. The sweep directions are reversed between operators to avoid biasing. At the computational boundaries, flux quantities outside the boundaries are needed to compute the spatial derivatives, and these can be obtained using third-order extrapolation based on data from the interior of the domain.

5. Boundary Treatment

Special attention is given herein to boundary treatment in order to avoid non-physical oscillations that can render the computed oscillating field unacceptable. Several boundary treatments were considered.26,27 The boundary treatments discussed below were found to be stable, non-reflecting, and suitable for the present jet computations.

5.1 Inflow Boundary Conditions

At the inflow boundary (x = 0), the radial boundary is split into hydrodynamic disturbance and radiation regimes, which are treated differently as outlined below.

5.1.1 Inflow Disturbance At the inflow boundary, a small disturbance is introduced. This disturbance is assumed to be mainly hydrodynamic in nature, and is specified from the centerline to r/D = 2.

To a first approximation, the inflow disturbance is assumed to be small such that the linear stability theory applies. A normal mode decomposition for the disturbance is assumed in the form:

$$[u', v', p', p'] = \text{Re} \{ \tilde{u}(r), \tilde{v}(r), \tilde{p}(r), \tilde{p}(r) \} \exp \{i(\alpha x - \omega t) \}$$  \hspace{1cm} (18)

The governing equations reduce to the Orr-Sommerfeld equation, which is solved to obtain the complex wave number \(\alpha\) as the eigenvalue corresponding to the frequency \(\omega\) and the radial functions ('') as the corresponding eigenfunctions. The mean flow discussed in Section 3 is used in solving the Orr-Sommerfeld equation.

This solution extends to r/D = 1. A curve is fitted to smoothly set the disturbance to zero by r/D = 2.

The effect of the inflow disturbance is added to the computed flow variables at the inflow boundary at each time step:

$$(Q_i)_{\text{boundary}} = (Q_i)_{\text{computed}} + (Q_i)_{\text{disturbance}}$$  \hspace{1cm} (19)

5.1.2 Hydrodynamic Disturbance Regime

In the hydrodynamic disturbance regime \(r/D < 2\), the Thompson inflow boundary condition28,29 is used. In the Thompson analysis, the axial operator is decomposed into four 1-D characteristics. At a subsonic inflow boundary, three of these characteristics are incoming, and are set to zero for a non-reflective boundary condition, while the fourth characteristic is outgoing and is computed from the flow solution:
The four characteristic equations are then solved together to obtain the time derivatives of the variables at the inflow boundary. For a supersonic inflow, all characteristics are incoming, and are all set to zero.

Due to the specified disturbance at the inflow boundary, the Thompson inflow boundary condition exhibited a problem in which some disturbances were convected in a radial direction and remained on the boundary for the rest of the computation. To alleviate this, the mean radial velocity was set to zero on the boundary, and smoothly raised to the proper value by \( x/D = 5.7 \).

### 5.1.3 Radiation regime

In the radiation regime \( (r/D > 2) \), the conventional acoustic radiation condition applies:

\[
Q'_i = -V(\theta) \left[ \frac{x}{R} Q'_{x} + \frac{r}{R} Q'_{r} + \frac{Q'}{R} \right] \tag{21}
\]

where:

\[
Q' = \begin{bmatrix} \rho' \\ u' \\ v' \\ p' \end{bmatrix} \\
R = \sqrt{x^2 + r^2} \\
V(\theta) = \tilde{c} \left[ \frac{x}{R} M + \sqrt{1 - \left( \frac{r}{R} M \right)^2} \right]
\]

and \( M \) is the local Mach number. The spatial derivatives which appear in Eq. (21) are evaluated in an identical manner as the inner flow derivatives.

### 5.2 Outflow Boundary Conditions

The outflow treatment is based on the asymptotic analysis of the linearized equations as given by Tam and Webb. The pressure condition is the same as that obtained by Bayliss and Turkel, Enquest and Majda, and Hariharan and Hagstrom, namely:

\[
p'_i = -V(\theta) \left[ \frac{x}{R} p'_{x} + \frac{r}{R} p'_{r} + \frac{p'}{R} \right] \tag{23}
\]

However, for updating the rest of the primitive variables, Tam and Webb have shown that the momentum and continuity equations should be used to account for the presence of entropy and vorticity waves at the outflow boundary. The spatial differencing used in the inner code is employed to evaluate the derivatives which appear in Eq. (23).

For the outflow regime of large radius and a local Mach number less than 0.01, the outflow condition is replaced by the radiation condition of Section 5.1.3.

It must be noted that the Tam and Webb outflow boundary condition is formulated with an assumption that the mean flow is uniform, which is not true for the jet outflow. However, the results given by this boundary condition were quite good, with very little reflection.

### 5.3 Outer Radial Boundary Condition

At the outer radial boundary \( (r = r_{\text{max}}, 0 < x < x_{\text{max}}) \), the radiation boundary condition of Section 5.1.3 is used.

### 5.4 Centerline Treatment

For an axisymmetric problem, the boundary condition at \( r = 0 \) can be stated as:

\[
\frac{\partial}{\partial r} \begin{bmatrix} \rho' \\ u' \end{bmatrix} = 0 \tag{24}
\]
To implement this boundary condition numerically, the fluxes are projected to ghost points across the centerline in an appropriate manner. The centerline treatment for a non-axisymmetric case is not obvious, and is addressed in a separate paper by Shih, et. al.\textsuperscript{34}

\section*{6. Results}

Results are presented for the axisymmetric flow and acoustic field of a supersonic jet (M = 2.1), unheated with a uniform stagnation temperature of 270° Kelvin. The Reynolds number of the mean flow is 70,000, and the jet is excited at a Strouhal number of 0.2. This case was tested experimentally by Troutt and McLaughlin,\textsuperscript{9} and theoretically by Tam and Burton.\textsuperscript{8} The results presented here are only for the axisymmetric mode, but still the qualitative agreement between the calculation and experiment is evident.

Figure 5 shows the root-mean-square pressure disturbance along the $r/D = 8.0$ line, compared to the experiment of Troutt and McLaughlin. The results show a qualitative similarity, with an axial shift of the maximum disturbance.

The radial decay of the pressure and axial velocity disturbance field is shown in figures 6 and 7, indicating a $1/R$ decay, as expected for the acoustic field.

Figure 8 shows the spectra of the sound pressure field at $x/D = 22.3$ and $r/D = 11.8$. The dominant frequency is that of the input disturbance.

Figure 9 shows the sound pressure level distribution in the far field for the present work, the axisymmetric mode of Tam and Burton, and the experimental measurements of Troutt and McLaughlin. It is seen that the graphs are all qualitatively similar, but the present results show an upstream axial shift of the lobes when compared to Tam and Burton's previous work. The lobes are shifted a distance of $x/D = 2.5$ from Tam and Burton's analytical calculation, and $x/D = 1.5$ from Troutt and McLaughlin's experimental results.

\section*{6.2 The Near Field}

The near field is shown in more detail in figures 10-14.

Instantaneous distributions of the pressure disturbance in the shear layer are shown in
Figure 10. The effects of the boundary conditions on the pressure disturbance are evident in this figure; reflections from the front and rear boundaries are in evidence.

Figure 11 shows instantaneous distributions of the axial velocity disturbance along the \( r/D = 0.5 \) line for several time levels. The boundary conditions seem to have much less effect on the axial velocity disturbances.

Figure 12 shows the spectra of the sound pressure field at several points in the near field. It is again seen that the dominant frequency is that of the input disturbance. However, some very high frequency noise is seen at the downstream points, and some middle frequency noise is seen at the point near the outflow boundary.

Figure 13 shows the root-mean-square pressure disturbance distribution in the shear layer. There are outflow boundary reflections evident in the downstream portion.

Figure 14 compares the axial momentum disturbance growth in the shear layer with the experimental results of Troutt and McLaughlin. The maximum value of the graphs are matched, and the results agree well.

8. Conclusions

A linearized Euler equation approach is used to compute the sound propagation in a supersonic jet. The boundary treatment used provides a stable solution with very little reflection from the boundary. The scheme is fast, and can be used for extension to three-dimensional flow fields and for parametric studies. The computed results were found to be in good agreement with the matched asymptotic solution of Tam and Burton, and in qualitative agreement with the experimental results of Troutt and McLaughlin.

References


Figure 2c
Instantaneous Distribution of the Disturbance Velocity Dilatation
\((M_{\text{jet}} = 2.1; \text{St} = 0.2; \text{axisymmetric mode})\)

Figure 3a
Maximum Values of the Pressure Oscillation
\((M_{\text{jet}} = 2.1; \text{St} = 0.2; \text{axisymmetric mode})\)

Figure 2d
Instantaneous Distribution of the Disturbance Vorticity
\((M_{\text{jet}} = 2.1; \text{St} = 0.2; \text{axisymmetric mode})\)

Figure 3b
Root-Mean-Square Values of the Pressure Oscillation
\((M_{\text{jet}} = 2.1; \text{St} = 0.2; \text{axisymmetric mode})\)

Figure 4
Directivity of Jet Noise
\((M_{\text{jet}} = 2.1; \text{St} = 0.2; \text{R/D} = 24)\)

Figure 5
Comparison of SPL levels along the \(r/D = 8.0\) line
\((M_{\text{jet}} = 2.1; \text{St} = 0.2; \text{axisymmetric mode})\)
Figure 6
Radial Decay of the Pressure Disturbance in the Far Field
($M_{jet} = 2.1; St = 0.2; \text{axisymmetric mode}$)

Figure 7
Radial Decay of the Axial Velocity Disturbance in the Far Field
($M_{jet} = 2.1; St = 0.2; \text{axisymmetric mode}$)

Figure 8
Far Field Pressure Spectra at (20,23.5)
($M_{jet} = 2.1; St = 0.2; \text{axisymmetric mode}$)

Figure 9a
SPL contours for present calculation
($M_{jet} = 2.1; St = 0.2; \text{axisymmetric mode}$)

Figure 9b
SPL contours for Tam and Burton calculation
($M_{jet} = 2.1; St = 0.2; \text{axisymmetric mode}$)

Figure 9c
SPL contours for Troutt and McLaughlin experiment
($M_{jet} = 2.1; St = 0.2$)
Figure 10
Instantaneous Pressure Disturbance along the r/D = 0.5 line
(M\text{jet} = 2.1; St = 0.2; axisymmetric mode)

Figure 11
Instantaneous Axial Velocity Disturbance along the r/D = 0.5 line
(M\text{jet} = 2.1; St = 0.2; axisymmetric mode)

Figure 12
Near Field Pressure Spectra in the Shear Layer
(M\text{jet} = 2.1; St = 0.2; axisymmetric mode)

Figure 13
RMS Pressure Disturbance in the Shear Layer (r/D = 0.5)
(M\text{jet} = 2.1; St = 0.2; axisymmetric mode)

Figure 14
Distribution of the RMS axial momentum disturbance in the shear layer
(M\text{jet} = 2.1; St = 0.2; axisymmetric mode)
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Linearized Euler equations are used to simulate supersonic jet noise generation and propagation. Special attention is given to boundary treatment. The resulting solution is stable and nearly free from boundary reflections without the need for artificial dissipation, filtering, or a sponge layer. The computed solution is in good agreement with theory and observation and is much less CPU-intensive as compared to large-eddy simulations.