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Electrostatic Charging of the Pathfinder Rover

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ABSTRACT

The Mars Pathfinder mission will send a lander and a rover to the martian surface. Because of the extremely dry conditions on Mars, electrostatic charging of the rover is expected to occur as it moves about. Charge accumulation may result in high electrical potentials and discharge through the martian atmosphere. Such discharge could interfere with the operation of electrical elements on the rover.

A strategy was sought to mitigate this charge accumulation as a precautionary measure. Ground tests were performed to demonstrate charging in laboratory conditions simulating the surface conditions expected at Mars. Tests showed that a rover wheel, driven at typical rover speeds, will accumulate electrical charge and develop significant electrical potentials (average observed, 110 volts). Measurements were made of wheel electrical potential, and wheel capacitance. From these quantities, the amount of absolute charge was estimated. An engineering solution was developed and recommended to mitigate charge accumulation. That solution has been implemented on the actual rover.

INTRODUCTION

A free ranging, solar powered surface rover will be delivered to Mars as part of the Pathfinder mission. Pathfinder will be launched in December, 1996, and will land on Mars on July 4, 1997. The rover will travel about on the martian surface, conducting technology experiments and serving as an instrument deployment mechanism (Ref. 1). Because of the extremely dry
conditions on Mars, electrostatic charging of the rover is expected to occur as it moves about. Experiments conducted in a simulated martian environment at the NASA Lewis Research Center have shown that a rover wheel, driven at typical rover speeds, will accumulate electrical charge on the order of $8 \times 10^8$ C, and develop electrical potentials averaging 110 V with transients 2- to 3-times that value.

Voltages of 100 V and greater are believed sufficient to produce electrical discharge in the Martian atmosphere. Also, with an accumulated net charge of $8 \times 10^8$ C, and average arc time interval of 1 $\mu$s, arcs can occur with estimated arc currents reaching almost 10 mA. Discharges of this magnitude could interfere with the operation of sensitive electrical elements on the rover (Ref. 2, 3, 4).

In laboratory tests, a typical wheel was driven in Arizona Lunar Simulant (ALS). This material was chosen because of its availability (from NASA/JSC), and its relatively low outgasing rate, enabling chamber pumpdown to be accomplished within a single day. About a pound of the material was used.

When the wheel was driven at typical rover speeds (.76 - 1.5 cm/s) in the ALS, electrical charging occurred. The charge accumulated was determined by measuring the electrical potential of the wheel using a capacitively coupled electrostatic probe, and multiplying the result by the wheel capacitance (approximately 74 pico-farads). The charge is believed to arise during compaction of the ALS by the moving wheel.

To dissipate accumulated electrical charge, a metal point was attached to the wheel. On the average, the wheel without any point developed an average steady-state electrostatic voltage of 110 V. Adding a discharge point resulted in electrical potential reductions of up to 15 - 20% of the steady state value. The reduction in potential is believed due to the dissipation of image charge from conducting surfaces of the wheel. Charge connected with adherent dust grains bleeds off very slowly due to the low conductivity of the dust.

As a result of the tests conducted at Lewis, and recommendations made to JPL, the Pathfinder rover will incorporate small wire discharge points on the rover at the base of the rover antenna. This component is electrically continuous with the other parts of the rover.

**EXPERIMENT DESCRIPTION**

In December, 1993, a memo was sent to the Pathfinder Office at the Jet Propulsion Laboratory (JPL) which stated the result of a preliminary calculation made of rover potential and charging rate. While the calculation was only an estimate, it pointed to
possibilities that were of interest to the Pathfinder team. As a result of this communication, NASA Lewis was requested to perform laboratory tests to determine whether charging was a real issue, and whether it could be mitigated by addition of a discharge point.

A Mars simulator facility had already been set up to conduct tests for the Wheel Abrasion Experiment (WAE, Ref. 5). This facility was adapted to examine the problem of electrostatic charging. A capacitively coupled electrostatic probe was installed, and tests were run with a simulated Mars surface atmosphere and Arizona Lunar Simulant (ALS). Experiments were conducted with two different wheels, hereafter referred to as the test wheel and the System Integration Model (SIM) wheel. The test wheel was a crude mock-up of the rover wheel, made to approximate dimensions. The SIM wheel was a more detailed model of the flight wheel. Both were driven at typical rover speeds. Charging was found to occur.

The rover wheel, driven at typical rover speeds, accumulated an electrical charge of about $8 \times 10^4$ C, and developed electrical potentials on the order of 110 V with transients 2- to 3-times that value.

Facility Description

The Mars simulator facility is a 62 cm diameter by 62 cm long vacuum chamber. For charging tests, the chamber was initially pumped to a background pressure of $8 \times 10^{-6}$ torr, then filled with Martian atmospheric simulant (approximate composition: 0.03% water, 0.153% carbon monoxide, 0.336% oxygen, 1.36% argon, 2.52% nitrogen, and balance carbon dioxide) to a pressure of 7 mbar. The wheel was mounted in a rotary tray filled to a depth of 15 mm with ALS, and driven with a variable-speed motor, external to the chamber. A xenon arc lamp provided a collimated light source to the wheel through a quartz window. A computer connected to an analog-to-digital converter continuously recorded data during the tests. (Fig. 1).

Procedure

The test wheels were run at speeds of 0.6 to 5.4 rpm. (The speed of the flight unit rover wheel on Mars will be 0.6 to 1.2 rpm). All outputs from wheel diagnostics were recorded. Test duration was typically $\geq 1000$ s. The electrostatic probe was initially zeroed to chamber ground prior to each test, then repositioned and held perpendicularly to the wheel at 2 mm during the test. All tests were conducted at room temperature, 23 °C.

Two different wheels were used: the test wheel and the SIM wheel. Two types of discharge points were attached to each of the wheels: a 12.7 μm radius stainless steel wire cut at the end, and a tungsten wire electromachined at its end to a point of radius 1 μm (Fig. 2).
For the test wheel, the 12.7 μm stainless steel point and the tungsten point were soldered to a braided copper wire. The braided copper wire was wrapped around the wheel and held down with Kapton tape. The braided copper wire with the discharge point was brought to the wheel axle, and extended outward 5 cm. (Fig. 3).

For the SIM wheel, the tungsten and 12.7 μm steel points were soldered to a copper wire. The copper wire was held in contact with the wheel by one of the cap screws on the rim. The copper was brought to the wheel axle, and extended 5 cm as before.

RESULTS AND DISCUSSION

Mechanisms assumed responsible for wheel charging included dust compaction, and friction of the wheel in the ALS. These assumptions were tested in simple experiments.

1. The wheel axle was deliberately jarred while the wheel was charged. Large quantities of dust were observed to fall from the wheel, and the potential immediately dropped from 70 V to < 12 V.

2. A braking force was applied to the tray increasing slippage of the wheel from a nominal 10% to close to 100% in the ALS. No substantial changes in potential were noted.

3. The weight of the wheel was changed. Electrostatic charging was measured with and without a counterbalance. (In its usual configuration, the wheel was counterbalanced to a net load of 500 gm, the weight on one wheel of the rover in Mars gravity. When the counterbalance was removed, the load on the wheel increased to 1588 gm.) A 20% increase in wheel electrical potential was observed with the higher load.

These simple experiments implied that the dominant mechanism of charge generation was associated with dust compaction. Small grains assumed a positive charge, larger grains, a negative charge. The smaller grains were light enough to adhere to the wheel surface, and carried their net positive charge with them. The electrostatic probe registered the corresponding electrical potential. The entire metal surface of the wheel became charged through image charge generation. The addition of a point removed some of the image charge, allowing the wheel potential to drop proportionally. The track behind the moving wheel became charged with an equal charge of opposite sign. This charge was also observed with the electrostatic probe.

Test Wheel

A plot of electric potential vs. time for the test wheel is shown in Fig. 4. The initial transients and the steady state
region are labeled. These data were taken with no discharge point on the wheel. The potential settles to its steady-state value within six revolutions.

Comparison of the steady-state potentials with no discharge point, a 12.7 μm stainless steel discharge point, and the tungsten point are shown in figs. 5. Each of the two types of points produced about the same reduction in voltage. Increasing the number of 12.7 μm radius stainless steel points from 1 to 7 gave no further reduction in potential.

The effects of wheel loading and of adding a discharge point to the wheel are shown in Fig. 6. A wheel with a load of 500 gm and seven 12.7 μm radius stainless steel discharge points shows a reduction in steady-state potential by 14%\(^1\) over a wheel with no point at comparable speeds. Retaining the seven points on the wheel, and increasing the wheel load from 500 gm to 1588 gm produced an increase in steady state potential by 16%. With no discharge point, increasing the wheel load from 500 gm to 1588 gm increased the steady state voltage by 25% at similar speeds.

A very slight dependence of voltage on wheel speed is also seen in Fig. 6.

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\(^1\) Percentages quoted are obtained by averaging over all data points.

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**SIM Wheel**

The steady-state potentials of the test wheel, with 500 gm load, no discharge point, a 12.7 μm stainless steel point, and a tungsten point are shown in Fig. 7. The initial voltage transient of the wheel may be as large as three times the steady-state voltage. The reason for this transient is not clear. A chamber related effect might be the most reasonable first assumption. But since demonstrating rover charging and possible mitigation schemes were the primary objectives of these tests, and since time was short, a good deal of additional science was left undone.

**Discharge Curves**

The SIM wheel was initially charged by running it in the ALS. The wheel was then stopped and allowed to discharge into the test environment. Wheel potential was recorded during discharge. The resulting data were fitted to a decaying exponential and time constants were inferred. These time constants are:

- 3555±430 s, no discharge point
- 2898±386 s, 12.7 μm point
- 2553±340 s, 1 μm point

Data are averaged over the range of speeds, 0.6 to 5.4 rpm. Comparison with the case of no point shows that the time constant is lower by \(\approx 20\%\) when either the 1 μm or the 12.7 μm discharge point is present. The
discharge points have a significant effect on discharge rate of wheel.

Dust Charging

The negative charge left behind by the SIM wheel after its passage over the ALS was measured with the electrostatic probe appropriately repositioned. This charge was recorded for all three point configurations of points (above), and different wheel speeds. Results are shown in Fig. 8. The dust charged negatively to approximately the same absolute value of potential as the wheel. Grain size measurements (see below) showed that small grains adhered to the wheel, large grains did not. The negative values of the ALS potential reveal the charge separation between these differently sized grains.

Electron Microscopy of Arizona Lunar Simulant

The scanning electron microscope was used to determine the size and the shape distributions of the Arizona Lunar Simulant. Energy Dispersive X-ray Analysis (EDX) spectra were also taken to confirm its chemical composition. A typical EDX spectrum, with elemental peaks labeled, is shown in Fig. 9. (The Au peak is due to a 200 Å thick sputter coating to discharge the ALS particle surfaces). Electron microscope photographs were taken of the material that adhered to the wheel. The average grain diameter of the simulant that adhered to the wheel is on the order of 20 μm (Fig. 10 a), compared to the 100 μm of the bulk sample (Fig. 10 b).

Capacitance of SIM wheel

The capacitance of the SIM wheel (without the discharge point attached) was measured with the chamber backfilled with 7 mbar Martian atmosphere simulant and Arizona Lunar Simulant. A capacitance meter, with a range of 1 pF to 200,000 mF, was connected through an electrical feedthrough between the wheel and the chamber (ground). The capacitance of the wheel relative to the chamber, averaged over three sets of measurements, was found to be 74 pF. Thus at a mean potential of 110 V, the absolute charge of the wheel may be calculated as $8.1 \times 10^{-9}$ C.

CONCLUSIONS

The tests reported indicate that the Pathfinder rover, in its traverses over the martian surface, may become sufficiently charged to raise its electrical potential to within the neighborhood of 110 V. Voltages of 100 V and greater are believed sufficient to produce electrical discharge in the Martian atmosphere. Also, with an accumulated net charge of $8 \times 10^4$ C, and average arc δt of 1 μs, arcs can occur with estimated arc currents reaching almost 10 mA. Discharges of this magnitude could interfere with the operation of sensitive electrical elements on the rover.
In the nominal mission on Mars, the rover will travel approximately two meters per day. During that time, the wheel will make at least five complete revolutions in the martian regolith. Experience with fine, dry clays in terrestrial laboratories demonstrates that charging is commonplace. It is not unreasonable to expect that the rover on Mars may charge more strongly than the wheel did in the laboratory. Discharges between active components, or between the rover and its surroundings may become very likely. Since actual martian conditions are unknown, discharge points will be added to the Pathfinder rover antenna base as a precaution against electrostatic charging. *Future missions should seriously consider including components to measure vehicle charging.* Possibilities might include an electroscope, or an optical means for detecting luminosity from electrical discharges taking place in and around the rover.

**FINAL REMARK**

During our investigation, the question arose whether a circuit model exists for charging/discharging the Pathfinder rover on Mars. Speculation is all that is possible at the moment. The rover will accumulate its charge from surface dust, then deliver some of that charge into the atmosphere through a point with a high electric field. Dust blowing by the rover in the martian surface wind will accumulate this charge and eventually fall back to the martian surface completing a circuit loop. The closest analogy is a Van de Graff generator in which the moving rover is the source of static charge, the point is the brush, the wind blown dust is the belt, and the martian surface to which the dust eventually returns is the accumulator. Perhaps an analog circuit model of this mechanism may be developed once more is known of the electrical characteristics of the actual martian surface material that will be encountered.

**REFERENCES**


Figure 1: Schematic (a) and photograph (b) of test facility
Figure 2: Electron microscope photograph of tungsten discharge point (scale on photo)
Figure 3: Test Wheel (a); SIM Wheel (b)
Figure 4: Typical plot of test wheel potential as a function of number of revolutions (0.7 rpm, 500 gm load, ALS, 7 mbar martian atmosphere)

Figure 5: Dependence of test wheel steady state potential on type of discharge point (500 gm load)
Figure 6: Dependence of test wheel steady state potential on load and type of discharge point

Figure 7: Dependence of SIM wheel steady state potential on type of discharge point (500 gm load)
Figure 8: ALS potential with SIM wheel and different discharge conditions

Figure 9: Energy Dispersive X-Ray Analysis of ALS
Figure 10: Electron microscope photographs of bulk ALS: (a) wheel track, (b) material collected off wheel
A New Antiwear Additive/Surface Pretreatment for PFPE Liquid Lubricants

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Pin-on-disk tribology experiments were conducted on a perfluoropolyalkylether (PFPE) liquid lubricant with and without a new PFPE lubricant antiwear additive material: a silane. It was found that the silane provided moderate improvement in the antiwear performance of the PFPE lubricant when applied to the metallic surface as a surface coating or when added to the PFPE as a dispersion (emulsion). Slightly better results were obtained by using the combination of a surface coating and an emulsion of the silane. The silane emulsions or coatings did not affect the friction properties of the lubricant. Micro-Fourier transformation infrared (μFTIR) spectroscopy analysis was performed to study silane transfer films and the degradation of the PFPE. The silane was found to mitigate degradation of the PFPE which may have been the major reason for the improved antiwear performance observed.

KEY WORDS
Lubricants, Antiwear Additives, Polyethers, Surface Analytical Techniques

INTRODUCTION

A class of high molecular weight liquid perfluoroethers, which were designated perfluoropolyalkylethers (PFPEs), was synthesized in the 1960s (1), (2). These liquids possessed excellent high temperature stability and low vaporization pressures and, thus, were immediately recognized to have potential for use in aerospace applications. While PFPEs have been used successfully as diffusion pump oils (3), dielectric fluids (4), and as lubricants (5), their potential as outstanding aerospace lubricants has not been realized. The main reason has been that they tend to decompose under boundary lubrication conditions, generating extremely reactive fluorinated products that can attack metal surfaces leading to increased wear and corrosion.

One method for mitigating PFPE decomposition is the use of soluble additives in the liquid lubricant, but the difficulty is that known additives for hydrocarbon-based liquid lubricants are not soluble in the PFPEs. This has led to studies investigating the use of highly fluorinated compounds as potential soluble additives for PFPEs. One possible drawback for the use of fluorinated additives is that many of these compounds have much lower vapor pressures than the PFPEs. Another drawback is that these additives may decompose, generating reactive fluorinated products.

Static thermal tests have shown that PFPEs decompose at elevated temperatures in the presence of certain metal oxides or metal fluorides, and it has been suggested that active Lewis acid sites on metal oxides or fluorides are responsible for PFPE catalytic decomposition (8)–(10). Recent studies, however, have indicated that Lewis acid sites may not be responsible for decomposition (11)–(13). For example, Ng et al. (12) observed that perfluorodiethylether decomposed on both untreated and pyridine-treated dehydroxylated aluminum oxide surfaces. Since pyridine is a compound widely used to block the action of Lewis acids, the results suggested that Lewis acid sites were not the reason for decomposition. Ng et al. also observed that perfluorodiethylether did not decompose on dehydroxylated alumina surfaces treated with a (CH₃)₃SiH vapor. They suggested that the following reaction took place which passivated (silylated) the alumina surfaces:

\[ \text{Al-OH} + \text{CH₃Si(CH₃)₃} \rightarrow \text{Al-O-Si(CH₃)₃} + \text{HCl} \]

Morales (13) decomposed a commercial PFPE on both alpha and gamma alumina surfaces at and above 200°C. He
found that a pyridine treatment of the alumina surfaces did not prevent PFPE decomposition. He did observe, however, that by treating the surfaces of the alumina with various liquid silanes the decomposition of the PFPEs was mitigated. Surface treatment with one particular silane, 3-aminopropyltriethoxysilane, prevented decomposition up to 350°C.

The static decomposition studies by Ng et al. and Morales led to the idea of using a silane to minimize PFPE decomposition and the wear of the sliding surfaces under boundary lubrication conditions. To evaluate this concept, an experimental program was developed using a pin-on-disk tribometer to investigate the friction, wear and degradation of a PFPE oil under boundary lubrication conditions over short- and long-term sliding conditions. The silane was applied as a coating to the sliding specimens or as a dispersion (emulsion) to the PFPE liquid. Optical microscopy and micro-Fourier transformation infrared (μFTIR) microscopy examinations of the oil and surfaces were conducted to evaluate decomposition products.

**EXPERIMENTAL**

**Test Variables**

To study the effect of a silane coating and/or emulsion on the friction, wear, and degradation properties of a PFPE oil, the following conditions were evaluated: silane emulsion, silane disk coating, silane disk and pin coatings, silane emulsion and silane disk coating, silane emulsion and pin and disk coatings, and no treatment.

**Materials**

The disks used were made of 440C stainless steel with a Rockwell hardness of C-57 to C-59. The disks were lapped and polished to a surface finish of 0.040 ± 0.015 μm centerline average (CLA). Instead of using pins, the pin holder was modified to hold 0.476 cm radius (three-eighths inch diameter) commercial grade 10, 440C balls which had the same surface roughness as the disks. The hardness of the balls was Rockwell C-60.

Properties of the PFPE and silane (3-aminopropyltriethoxysilane) liquids used in this study are given in Table 1 and the following are the structures:

**The Perfluoropolyalkylether**

\[
C_3F_7O(-CF-CF_2-O-)_nC_2F_3
\]

**The Silane**

\[
O-CH_2-CH_3
\]

\[
CH_3-CH_2-O-Si-O-CH_2-CH_3
\]

\[
CH_2
\]

\[
CH_2
\]

\[
CH_2
\]

\[
NH_2
\]

**Friction and Wear Apparatus**

The pin-on-disk tribometer used in this study, shown in Fig. 1, has been described in detail in Ref. (14). The specimens consisted of a flat rotating disk (6.3 cm diameter) in sliding contact with a stationary pin (ball) (0.476 cm radius) which was securely fastened in a holder. The ball slid on disk tracks that ranged from 4.8 cm to 3.7 cm in diameter. The rotational speed of the disk was controlled at 200 rpm giving linear sliding speeds of 0.50 to 0.39 m/s. The test specimens were encased in a plastic box to control the atmospheric humidity. A load of 2 kg was applied to the ball, which gave an initial maximum contact stress of 1.3 GPa (190,000 psi). A polyethylene ring was fastened around the diameter and extended approximately 0.4 cm above the surface of the disk to restrain the oil from being thrown from the disk by centrifugal forces. The amount of oil used for each test was 2 g.

**Surface Cleaning**

The ball and disk cleaning procedure was as follows:

1. Wash surfaces with ethyl alcohol.
2. Rub surfaces with a water paste of polishing alumina (particle size 0.3 μm). Clean until water readily wetted the surfaces.
3. Scrub surfaces under running tap water with a brush to remove alumina.
4. Rinse in deionized water.
5. Dry surfaces by blowing on with clean compressed air.

Emulsion Preparation

A one percent (by weight) emulsion of the silane was prepared by first adding the appropriate amount of the silane to the PFPE in a test tube. Since the silane is insoluble in the PFPE, the test tube was placed in ultrasonic cleaner for 10 minutes to mix the two liquids. The ultrasonic agitation caused the formation of a milky white emulsion.

Coating Application

A one percent (by weight) of the silane in a methanol solution was prepared by adding the appropriate amount of the silane to 100 ml of methanol in a 500 ml beaker. A polished 440C disk was then immersed into this solution for 15 minutes. The disk was carefully withdrawn, placed inside a petri dish and then covered. The covered petri dish was then placed inside a furnace (maintained at 200°C) for 30 minutes. This method produced a coating approximately 3 μm thick.

Emulsion Stability Testing

A small quantity of the emulsion was poured into a sample bottle, sealed, and left to stand for two months. Periodic visual inspection was conducted to check for separation. In addition, a small quantity of the emulsion was placed in a centrifuge and spun at 2500 rpm at a radius of 10 cm for 10 minutes. In an additional test, some of the emulsion was heated in glassware at 250°C for 30 minutes under a partial vacuum (<5 Torr).

Thermal Gravimetric Analysis Testing

Thermal gravimetric analysis (TGA) tests were conducted on the pure PFPE, the silane and the mixture. A small quantity of each liquid was injected onto an aluminum pan, and the pan was then loaded and sealed (under a flowing N2 atmosphere at 60 ml/min) inside the TGA system. The TGA temperature was ramped at a rate of 10°C per minute from room temperature to 360°C.

Friction and Wear Testing

Two grams of oil (with or without the emulsion) were applied to the disk (with attached polyethylene ring). The ball (securely fastened in its holder) and disk were inserted into the friction and wear apparatus and properly aligned. The test chamber was then sealed and purged with dry air (100 ppm moisture content) for 15 minutes before commencing the tests. This purge was continued throughout the tests. After the 15-minute purge, the disk was set into rotation at 200 rpm and a two-kilogram load was gradually applied to the ball. The test temperature was 25°C.

Each test was stopped after one kilocycle (kc) of sliding. At 200 rpm this is five minutes. The ball holder was removed from the apparatus and the wear area on the ball was examined by optical microscopy and a wear measurement was made. The holder was then placed back into the apparatus and the previous test procedure was repeated. The ball was not removed from its holder, and locating marks insured that the holder was returned to its original position.

RESULTS AND DISCUSSION

Emulsion Stability Tests

Visual inspection of the silane/PFPE emulsion that was left to stand for two months on a shelf revealed the persistence
of a milky white color, indicating that the two constituents did not separate. In addition, no separation of the two materials was found to occur in centrifuge testing at 2500 rpm for 10 minutes. Because of these tests, the emulsion was judged to be exceptionally stable.

TGA testing of the emulsion and each constituent was also conducted. Figure 2 shows the results. The TGA thermogram for the pure silane, see Fig. 2(a), showed that nearly all the silane had evaporated by 140°C, whereas the TGA thermogram for the pure PFPE, see Fig. 2(b), showed that the PFPE started to evaporate at about 270°C. The TGA thermogram for the emulsion was the same as that of the pure PFPE in Fig. 2(b). There was no evidence of silane evaporation from the emulsion in the TGA tests; however, the amount of silane present may have been too small to detect.

Because of the TGA results, it was decided to subject the emulsion to a temperature that was higher than the boiling point of the silane but lower than that of the PFPE. Thus, the emulsion was heated under a partial vacuum to 250°C, held at temperature for 30 minutes and then cooled to room temperature. The emulsion still maintained its milky white color and no separation could be observed, indicating no evaporation of the silane had occurred. Vapor pressure measurements of the pure liquids and the emulsion will be conducted in the future to supplement the current work.

**Ball Wear**

Ball wear was evaluated for sliding distances of up to 4300 kc of sliding (300 km). To determine if there were differences between short-term and long-term effects, wear rates were calculated and compared for two sliding intervals: 0 to 30 kc (0 to 4.5 km) and 50 to 4300 kc (7.5 to 500 km). The scatter for the short-term tests and long-term tests. In addition, the silane did not decrease the ball wear rate by an average of approximately 50 percent. There did not seem to be any clear advantage of coatings over emulsions or of combining coatings with emulsions. However, it should be emphasized that neither the coatings nor the emulsions were optimized in this study.

In general, ball wear rates were lower for the long-term tests than for the short-term tests, which could be due to run-in effects. In addition, the silane did not decrease the ball wear as much for the long-term tests as it did for the short-term tests. A possible reason for this is that some form of mixed lubrication may be taking place. The authors have observed in unpublished data on accelerated testing devices (such as pin-on-disk and rub-shoe devices where there is 100 percent sliding) that, as the wear scar gets larger, the wear rate decreases. Also, at some point, enough pressure is generated by the liquid to cause complete separation of the surfaces. When this happens, no further wear of the surfaces occurs. Mixed lubrication may be happening in these tests. The silane would not be expected to have as much beneficial effect in mixed lubrication as in pure boundary lubrication.
Experimental Conditions: Temperature, 25°C; dry air atmosphere (100 ppm moisture content); load, 2 kg; speed, 200 rpm; 440C stainless steel specimens.

The friction results are presented in Table 3. In general, no distinguishable effect on friction coefficient was found which was dependent on either the silane emulsion or the silane coating. The maximum, minimum and median friction coefficients obtained were essentially the same for all experimental conditions. Variation from test to test under any one particular experimental condition was found to differ as much as the variation from adding a silane emulsion or a silane coating. Table 3 also presents the friction coefficient of a silane coating (run dry under the same conditions) for comparison purposes. In the dry condition, the silane coating lasted less than 0.75 km (5 kc) of sliding.

Optical Microscopy

A comparison of the ball wear surfaces after 2 km of sliding is shown in Fig. 5 for the following tests: a silane emulsion, a silane disk coating, and no treatment. For both the silane emulsion and silane coating tests, a much smoother wear scar was obtained and FTIR analysis indicated a deposit of silane was adhering to the wear scar. The ball scar from the test with no silane treatment showed a very rough surface, much more black powdery wear debris and some plastic deformation of the scar in the exit region.

Figure 6 compares the wear tracks on 440C stainless steel disks after very long durations of sliding under three different PFPE lubricant conditions. Shown in the figure are a disk track with a silane emulsion and coating after 250 km of sliding, a disk track with a silane coating after 257 km of sliding, and a disk track with no silane treatment after 230 km of sliding. The disk track lubricated with PFPE with no treatment shows a large amount of black powdery wear debris (especially in the center of the track). The silane-coated disk shows a dark material on the wear track that appears to be platelet-like. The silane emulsion shows a disk wear track that has nearly no visible deposits.

Photomicrographs of the ball wear surfaces were also taken after long durations of sliding. Figure 7 shows a low and high magnification photomicrograph of a ball wear scar after 350 km of sliding where the counterface was a silane-coated 440C stainless steel disk. The ball wear scar is seen to be very smooth and the transfer is thin and "platelet-like." µFTIR analysis of this scar showed that the transfer contained silane.

Figure 8 shows a photomicrograph of a ball wear scar after 266 km of sliding where no silane emulsions or coatings to
discern which is the correct structure. However, there is enough evidence to definitely state that the observed μFTIR spectra corresponded to the signature of the degraded lubricant.

To ascertain if silane were transferred from the emulsion or coating to the mating surfaces, a μFTIR spectrum of the silane coating was taken before testing and then compared to deposits on the ball wear surfaces. Figure 11 shows the μFTIR spectrum of the silane coating applied to a 440C steel surface. The two sharp bands at 3367 and 2928 cm⁻¹ are typical N-H asymmetric and symmetric stretching vibrations which occur in NH₂ groups. The band at 1600 cm⁻¹ is the corresponding deformation vibration. Hydrogen bonding is typical in the solid or liquid state for compounds containing NH₂ groups. Thus, hydrogen bonding accounts for the broad peak between 3000 and 3500 cm⁻¹. Since this film has been baked after its application to the 440C surface, it is unlikely that this broad vibration would be due to H-bonding of hydroxyl groups. Other peaks present are the C-H stretching vibrations due to the C₂H₅ and the C₃H₆ groups which appear at 2840 and 2932 cm⁻¹, respectively. The band at 1470 cm⁻¹ is the corresponding deformation vibration. The Si-O-C₂H₅ vibrations appear at 1100 and 930 cm⁻¹ and the Si-C₂H₆ appear at 792 cm⁻¹.

Figure 12 compares the μFTIR spectra in the 5000 to 1500 cm⁻¹ wavenumber region from spectra taken from wear scars which were slid against silane-coated disks. Spectra are shown for a short-duration test (50 kc) and for a long-duration test (4500 kc). The spectrum for the short-duration test shows the presence of silane peaks (C-H and N-H vibrations) but does not show any PFPE decomposition peaks (C=O vibrations). The long-duration spectrum shows no silane peaks but does show the presence of PFPE decomposition peaks. The -OH vibration (3500 to 3500 cm⁻¹) is very shallow and is somewhat hidden in the broad peak shown on Fig. 12; however, the other degradation signature peak (C=O vibration) is very visible on the figure at 1625 cm⁻¹. The presence of silane peaks on the surface and the absence of decomposition peaks (after the short sliding interval) strongly infer

### Table 3—Comparison of Friction Coefficients for Short- and Long-Duration Tests

<table>
<thead>
<tr>
<th>OIL, DISK OR BALL TREATMENT</th>
<th>SHORT-TERM TESTS (0 to 30 kc)</th>
<th>LONG-TERM TESTS (50 to 4500 kc)</th>
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<tbody>
<tr>
<td></td>
<td>NUMBER OF TESTS</td>
<td>FRICTION COEFFICIENT</td>
</tr>
<tr>
<td></td>
<td>MAXIMUM</td>
<td>MINIMUM</td>
</tr>
<tr>
<td>None</td>
<td>6</td>
<td>0.16</td>
</tr>
<tr>
<td>Oil Emulsion</td>
<td>6</td>
<td>0.16</td>
</tr>
<tr>
<td>Coating (Disk)</td>
<td>8</td>
<td>0.16</td>
</tr>
<tr>
<td>Coating (Disk and Ball)</td>
<td>5</td>
<td>0.17</td>
</tr>
<tr>
<td>Oil Emulsion/Coating (Disk)</td>
<td>4</td>
<td>0.16</td>
</tr>
<tr>
<td>Oil Emulsion/Coating (Disk and Ball)</td>
<td>2</td>
<td>0.17</td>
</tr>
<tr>
<td>Dry Silane Coating (No Oil)</td>
<td>2</td>
<td>0.35</td>
</tr>
</tbody>
</table>

Experimental Conditions: Temperature, 25°C; dry air atmosphere (100 ppm moisture content); load, 2 kg; speed, 200 rpm; 440C stainless steel specimens.
that the silane has helped mitigate the degradation of the PFPE. The absence of silane peaks (after the long sliding duration) indicates that the silane coating eventually wears away.

All the tests using silane showed a reduction in degradation of the PFPE lubricant for the short sliding durations. However, no silane peaks could be found on the wear surfaces for the tests using the silane emulsion. It may be that the interaction of the silane in this case took place between the PFPE and the silane and that transfer of the silane to the wear surfaces was not necessary to prevent degradation.

CONCLUDING REMARKS

The purpose of this study was to determine if a silane added to a PFPE as an emulsion or applied as a coating to the counterfaces would reduce wear and/or the degradation of a PFPE lubricant. It was found that both wear and degradation were reduced. The authors believe that reduced degradation of the lubricant leads to reduced wear, although there is no experimental proof of this.

In addition, it is important to bear in mind that no attempt has been made in this study to optimize the method of ap-
Fig. 7—Low and high magnification photomicrographs of ball wear scar areas after 350 km of sliding from a test where the counterface was a silane-coated 440C stainless steel disk.

Thus, it may be possible to obtain even better results once an optimization study is done. It also should be noted that the silane emulsions and coatings are not necessarily the same. The emulsions were not heat treated while the coatings were heat treated at 200°C for 30 minutes. Heat treating of the silane may have changed its structure.

Also, one must be aware that accelerated test data such as wear rates, friction coefficients, etc. do not necessarily directly correlate to results achieved in an actual bearing. A very small improvement in an accelerated test data may lead to a very large improvement in a bearing or there may be very little improvement. A test using bearings must be made to ascertain the real improvement. Screening tests, such as pin-on-disk tests, are done to show the potential of various concepts for use in a bearing.
SUMMARY OF RESULTS

Pin-on-disk tribology testing coupled with surface profilometry, optical microscopy and μFTIR studies on a PFPE liquid lubricant with and without silane additives and/or emulsions provides the following indications:

1. Silane coatings and/or emulsions used in conjunction with PFPE oils eliminated PFPE degradation products which were found on ball wear surfaces on tests with the untreated oil, giving strong evidence that the silane can mitigate the degradation of this particular PFPE oil.

2. Accompanying the reduced degradation of the PFPE oil was reduced wear of 440C balls and disks when compared to similar tests on an untreated PFPE oil.

3. Equal improvements in decreased wear rates were obtained for disk coatings and oil emulsions, although no attempt was made to optimize either application method.

4. Optical and μFTIR microscopy observations indicated that the silane disk coatings could form thin layerlike transfer films on ball wear surfaces.

5. Friction coefficients obtained from PFPE oil tests using silane emulsions or silane coatings were the same as those obtained from tests using the untreated PFPE oil.

REFERENCES


