Modeling of Flow Transition Using an Intermittency Transport Equation

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Abstract

A new transport equation for intermittency factor is proposed to model transitional flows. The intermittent behavior of the transitional flows is incorporated into the computations by modifying the eddy viscosity, $\mu_t$, obtainable from a turbulence model, with the intermittency factor, $\gamma$: $\mu_t^* = \gamma \mu_t$. In this paper, Menter’s SST model (Menter, 1994) is employed to compute $\mu_t$ and other turbulent quantities.

The proposed intermittency transport equation can be considered as a blending of two models – Steelant and Dick (1996) and Cho and Chung (1992). The former was proposed for near-wall flows and was designed to reproduce the streamwise variation of the intermittency factor in the transition zone following Dhawan and Narasimha correlation (Dhawan and Narasimha, 1958) and the latter was proposed for free shear flows and was used to provide a realistic cross-stream variation of the intermittency profile.

The new model was used to predict the T3 series experiments assembled by Sav-ill (1993a, 1993b) including flows with different freestream turbulence intensities and two pressure-gradient cases. For all test cases good agreements between the computed results and the experimental data are observed.
1 Introduction

To a large extent, flows in low-pressure turbine applications are transitional, and the behavior of the flow transition is strongly affected by the freestream turbulence level and pressure gradients in the turbine blade passage. In order to predict the losses and heat transfer one must be able to predict accurately the boundary-layer development and its interactions with flow transition and separation.

Although a lot of work has been reported on improving the accuracy of the CFD tools in engineering predictions, specially in the turbulence modeling areas, CFD prediction of transitional flows still remains an almost untouched territory, as compared with other areas of CFD developments. A common way to simulate laminar to turbulent transition in computations is to switch on the turbulence model (or turbulent eddy viscosity) at an experimentally pre-determined transition location. This method is ad hoc and ignores the transition physics and the importance of the transitional zone completely. Especially for flows where the transitional region covers a large portion of the flowfield, as observed in many low-pressure turbine experiments, this practice can lead to severe errors in the solution.

Savill (1993a, 1993b), and Westin and Henkes (1997) have tested a large variety of turbulence models and compared models' performances in predicting a few of T3-series transition flow experiments. They showed that no model could predict both transition location and length for a range of flow conditions and concluded that the existing models were inadequate to predict flow transition.

An alternative to this approach is to use the concept of intermittency to blend the flow from the laminar to the turbulent regions. This approach, although highly empirical, has shown some successes in predicting transition behavior. Dhawan and Narasimha (1958) correlated the experimental data and proposed a generalized intermittency distribution function across flow transition. The correlation was later improved by Gostelow et al. (1994) for flows with pressure gradients subject to a range of freestream turbulence intensities.

Solomon et al. (1995), following the work of Chen and Thyson (1971), developed an improved method to predict transitional flows involving changes in pressure gradients. In this model, the effects of changing streamwise pressure gradient on the breakdown physics and spot spreading rates are taken into account. This is accomplished by varying the spot spreading angle and propagation parameter through the transition zone according to the local pressure gradient parameter.

Steelant and Dick (1996) proposed a transport equation for intermittency, in which the source term of the equation is developed such that the $\gamma$ distribution of Dhawan and Narasimha (1958) across the transition region can be reproduced. Steelant and Dick used their model, coupled with two sets of conditioned Navier-Stokes equations, to predict transitional flows with zero, favorable, and adverse pressure gradients. However, since their technique involved the solution of two sets of strongly coupled equations, the method is not compatible with existing CFD codes, in which only one set of Navier-Stokes equations is involved. Moreover, the model was designed to provide a realistic streamwise $\gamma$ behavior but with no consideration of the variation of $\gamma$ in the cross-stream direction.
Cho and Chung (1992) developed a $k-\epsilon-\gamma$ turbulence model for free shear flows. Their turbulence model explicitly incorporates the intermittency effect into the conventional $k-\epsilon$ model equations by introducing an additional transport equation for $\gamma$. They applied this model to compute a plane jet, a round jet, a plane far wake, and a plane mixing layer with good agreements. Although this method was not designed to reproduce flow transition it provided a realistic profile of $\gamma$ in the cross-stream direction.

In the current paper, a new transport equation for intermittency factor is proposed. The main motivation in the development of the new model is to combine the best features of the existing transition models in the proposed model. The model can not only reproduce the intermittency distribution of Dhawan and Narasimha in the streamwise direction but also is able to provide a proper variation of $\gamma$ in the cross-stream direction. Our aim is to propose a model that will predict flow transition under the influences of freestream turbulence and pressure gradients.

A review of a number of transition models used in the current study is given in section 2. In section 3, the new model, combining the best features of the models discussed in section 2, is proposed. Section 4 discusses the numerical issues regarding the implementation of the current method in the existing CFD codes, including our choice of the correlations to predict the onset of the transition under the influences of freestream turbulence and pressure gradients. Section 5 shows the comparisons of the new transition model against T3 series experiments of Savill (1993a, 1993b). Concluding remarks are provided in section 6.

2 Transition Models

2.1 Dhawan and Narasimha

Dhawan and Narasimha (1958) correlated a range of experimental data and provided the following expression for streamwise intermittency distribution:

$$\gamma = \begin{cases} 
1 - \exp\left[-(x - x_t)^2 n \sigma / U \right] & (x \geq x_t) \\
0 & (x < x_t) 
\end{cases}$$

(1)

where $U$ is the freestream velocity; $x_t$ is the point of transition onset; $n$ is the spot formation rate and $\sigma$ is the spot propagation parameter.

There are two ways to express equation (1) in dimensionless form: one way, as given by Narasimha (1985), is to express equation (1) in terms of a nondimensional breakdown parameter, $N = n \theta_t^2 / \nu$, where $\theta_t$ is the momentum-thickness at the onset point of transition, $x = x_t$, and $\nu$ is the kinematic viscosity; and the other way is in terms of dimensionless spot formation rate, $\hat{n} = n \nu^2 / U^3$, as used by Mayle (1991). Hence, the first part of equation (1) can be written either as:

$$\gamma = 1 - \exp \left[ - \left( \frac{x - x_t}{\theta_t} \right)^2 \frac{N}{Re \theta_t} \right]$$

(2)

or

$$\gamma = 1 - \exp \left[ - \left( \frac{x - x_t}{\theta_t} \right)^2 \hat{n} \sigma R e \frac{\nu}{\theta_t} \right]$$

(3)
Gostelow et al. (1994) conducted measurements of boundary layer transition for six different turbulence levels and a wide range of pressure gradients and correlated the nondimensional breakdown parameter \( N \) as:

\[
N = \begin{cases} 
0.86 \times 10^{-3} \exp[2.134 \lambda_\theta \ln(Tu) - 59.23 \lambda_\theta - 0.564 \ln(Tu)] & \lambda_\theta \leq 0 \\
0.86 \times 10^{-3} \exp[-0.564 \ln(Tu)] & \lambda_\theta > 0 
\end{cases}
\]  

where the pressure gradient parameter, \( \lambda_\theta \equiv (\theta^2 / \nu)(dU/dx) \), and the freestream turbulence intensity, \( Tu \), are evaluated at the onset point of transition.

In contrast, for zero-pressure-gradient flows, Mayle (1991) correlated the spot production rate using intermittency measurements as:

\[
\dot{n} = 1.25 \times 10^{-11} Tu^{-7/4}
\]  

The constant in equation (5) may vary slightly depending on the choice of the data; Mayle also reported a value of \( 1.5 \times 10^{-11} \) in the same paper. When subject to pressure gradients, Mayle (1991) normalized \( \dot{n} \) by its value at zero-pressure-gradient, \( (\dot{n} \sigma)_{ZPG} \), and showed a plot of \( \dot{n} / (\dot{n} \sigma)_{ZPG} \) versus the acceleration parameter, \( K = (\nu / U^2)(dU/dx) \) over a wide range of freestream intensity, \( Tu \). Steelant and Dick (1996) proposed the following correlation to fit Mayle’s data:

\[
\frac{\dot{n} \sigma}{(\dot{n} \sigma)_{ZPG}} = \begin{cases} 
(4747 Tu^{-2.5})^{1-\exp(2 \times 10^6 K)} & K < 0 \\
10^{-3227 K^{0.5985}} & K > 0 
\end{cases}
\]  

A comparison of equations (2) and (3) indicates that:

\[
N = \dot{n} \sigma Re_{\theta_\sigma}^3
\]  

If both Gostelow et al. (1994) and Mayle (1991) used the same data to correlate their dimensionless quantities, \( N \) and \( \dot{n} \sigma \), respectively, an equation for the Reynolds number at the onset of transition can be identified. For example, for a zero-pressure-gradient case, Gostelow et al.’s (1994) correlation, equation (4), gives:

\[
N = 0.86 \times 10^{-3} Tu^{-0.564}
\]  

Substituting equations (8) and (5) into equation (7), yields:

\[
Re_{\theta_\sigma} = 410 Tu^{-0.771}
\]  

Since equation (9) is different from Mayle’s correlation (Mayle, 1991):

\[
Re_{\theta_\sigma} = 400 Tu^{-0.625}
\]  

nor does it resemble the well-known Abu-Ghannam and Shaw correlation for zero-pressure-gradient flows (Abu-Ghannam and Shaw, 1980):

\[
Re_{\theta_\sigma} = 163 + \exp(6.91 - Tu)
\]  

the two correlations, equations (5) and (8), are not identical. We concluded that the choice of the transition correlations using either \( N \) or \( \dot{n} \sigma \) must be tested in company with a proper choice of the correlations for the onset of transition.
2.2 Solomon et al.

Typically for flows in low-pressure turbines, the onset of transition and the end of transition are in different pressure gradient regions, and to derive transition correlations using only parameters at the onset point of transition may result in an incorrect prediction of the transition length. Following the work of Chen and Thyson (1971), Solomon et al. (1995) developed a modified method for calculating intermittency in transitional flows with changing pressure gradients.

The model of Solomon et al. (1995) accounts for the effects of changing streamwise pressure gradient on the breakdown physics and spreading rate of turbulent spots by allowing the model constants to vary continuously with the local pressure gradient parameter $\lambda$. While the spot generation rate is assumed to depend only on the local conditions at the transition onset point using the relation of Gostelow et al. (1994), equation (4), the spot spreading half-angle $\alpha$ and the spot propagation parameter $\sigma$ are given by:

\[
\sigma = 0.03 + \left(0.37 \left/ \left(0.48 + 3.0 \exp(52.9 \lambda)\right)\right.\right) \tag{12}
\]

\[
\alpha = 4 + \left(22.14 \left/ \left(0.79 + 2.72 \exp(47.63 \lambda)\right)\right.\right) \tag{13}
\]

The intermittency distribution, retaining the concentrated breakdown hypothesis of Narasimha, is given by:

\[
\gamma = 1 - \exp \left[ -n \int_{x_i}^{x_f} \frac{\sigma}{\tan \nu} \frac{dx}{U} \int_{x_i}^{x_f} \tan \nu \, dx \right] \tag{11}
\]

where the spot generation rate, $n$, is calculated using $N$ from equation (4).

Solomon et al. (1995) tested their model for several pressure gradient flows and showed improved agreement with the experimental data.

2.3 Steelant and Dick

Steelant and Dick (1996) developed a transport model for intermittency to be used in conjunction with conditioned Navier-Stokes equations. They derived a model equation starting from the intermittency distribution of Dhawan and Narasimha (1958). Differentiating equation (1) along the streamline direction, $s$, they arrived at the following transport equation:

\[
\frac{\partial \rho \gamma}{\partial t} + \frac{\partial \rho u \gamma}{\partial x} + \frac{\partial \rho v \gamma}{\partial y} = (1 - \gamma) \rho \sqrt{u^2 + v^2} \beta(s) \tag{15}
\]

with

\[
\beta(s) = 2f(s)f'(s) \tag{16}
\]

The function $\beta(s)$ represents the $(n\sigma/U)(x-x_r)$ term in equation (1). The function $f(s)$ is formulated to account for distributed-breakdown and is given as:

\[
f(s) = \frac{a s^4 + b s^3 + c s^2 + d s + \epsilon}{g s^4 + h} \tag{17}
\]
where the coefficients are:

\[
\begin{align*}
a &= \sqrt{\frac{\sigma}{U}} & b &= -0.4906 & c &= 0.204 \left(\frac{\sigma}{U}\right)^{-0.5} \\
d &= 0.0 & \epsilon &= 0.04444 \left(\frac{\sigma}{U}\right)^{-1.5} & g &= 1.0 & h &= 10\epsilon
\end{align*}
\]

Equations (5) and (6) were recommended to evaluate the values of \( \sigma \). In the above equations, \( U \) is the freestream velocity at the transition location and the streamline coordinate, \( s \), is defined as:

\[
s = \int \frac{u \, dx + v \, dy}{\sqrt{u^2 + v^2}}
\]

and \( s' = s - s_t \), where \( s_t \) is the transition location.

Steelant and Dick (1996) tested their model in conjunction with two proposed sets of conditioned averaged Navier-Stokes equations for zero, adverse, and favorable pressure gradient flows and their results showed that the model performed well for all cases. While the intermittency transport equation reproduces the streamwise intermittency distribution of Dhawan and Narasimha, it gives rise to a fairly uniform \( \gamma \) distribution in the cross-stream direction. This is somewhat inconsistent with the experimental observation of Klebanoff (1955), in which the variation of intermittency in the cross-stream direction has been proposed empirically as:

\[
\gamma(y) = \frac{1}{2} \left[ 1 - \text{erf}(\zeta) \right]
\]

with

\[
\zeta = 5 \left[ \frac{y}{\delta^*} - 0.78 \right]
\]

where \( \delta^* \) is the displacement thickness.

### 2.4 Cho and Chung

Cho and Chung (1992) developed a \( k - \epsilon - \gamma \) turbulence model for free shear flows. In their model the intermittency effect is incorporated into the conventional \( k - \epsilon \) turbulence model equations explicitly by introducing a transport equation for the intermittency factor \( \gamma \). The eddy viscosity is expressed in terms of \( k \), \( \epsilon \), and \( \gamma \). Their intermittency equation was given as:

\[
u_t \frac{\partial \gamma}{\partial x_j} = D_\gamma + S_\gamma
\]

The diffusion term, \( D_\gamma \), is represented by:

\[
D_\gamma = \frac{\partial}{\partial x_j} \left[ (1 - \gamma) \frac{\nu_t}{\sigma_g} \frac{\partial \gamma}{\partial x_j} \right]
\]
and the source term, $S_\gamma$, is:

$$S_\gamma = C_{g1}(1 - \gamma)\frac{P_{k,s} + P_{k,u}}{k} + C_{g2}k^2 \frac{\partial\gamma}{\partial x_j} \frac{\partial\gamma}{\partial x_j} - C_{g3}(1 - \gamma)\frac{\epsilon}{k}\Gamma$$

(23)

where

$$P_{k,s} = -\overline{u_iu_j} \frac{\partial u_i}{\partial x_j} \quad (i \neq j)$$

(24)

$$P_{k,u} = -\overline{u_iu_j} \frac{\partial u_i}{\partial x_j} \quad (i = j)$$

(25)

and

$$\Gamma = \frac{k^5/2}{\epsilon^2} \frac{u_i}{(u_iu_k)^{1/2}} \frac{\partial u_i}{\partial x_j} \frac{\partial\gamma}{\partial x_j}$$

(26)

The modeling constants are:

$$\sigma_g = 1.0 \quad C_{g1} = 1.6 \quad C_{g2} = 0.15 \quad C_{g3} = 0.16$$

Cho and Chung (1992) tested their model for a plane jet, a round jet, a plane far wake, and a plane mixing layer and showed improved model performance. Although the model does indeed produce a very realistic $\gamma$ profile for turbulent free shear flows, it is not designed to predict flow transition to turbulence.

3 New Transport Model for the Intermittency

A new transport equation for intermittency is proposed. The main objective of the new model is to reproduce the intermittency distribution of Dhawan and Narasimha in the streamwise direction and at the same time to give rise to a realistic variation of the intermittency in the cross-stream direction. In order to accomplish this, a transport model for intermittency, blending Steelant and Dick’s and Cho and Chung’s models, is proposed.

The production term for the new model is a mix of the generation terms of Steelant and Dick and of Cho and Chung. The first term, $T_0$, is from Steelant and Dick, aiming to reproduce the intermittency distribution of Dhawan and Narasimha. The formula for $T_0$ is given by:

$$T_0 = C_{0}\rho \sqrt{u'^2 + v'^2} \beta(s)$$

(27)

where

$$\beta(s) = 2f(s)f'(s)$$

(28)
One major aspect in which term \( T_0 \) differs from Steelant and Dick's model is the distributed-breakdown function \( f(s) \). Steelant and Dick's model was calibrated for use with conditioned Navier-Stokes equations and when used with the current approach it allows excessively long regions of distributed-breakdown. In order to obtain shorter distance for distributed-breakdown the function \( f(s) \) is modified in the new model.

The function \( f(s) \) used in the new model has the same form as Steelant and Dick's model:

\[
f(s) = \frac{as^4 + bs^3 + cs^2 + ds' + c}{gsx^3 + h}
\]

where the coefficients are:

\[
\begin{align*}
a &= 50\sqrt{\frac{n\sigma}{U}} \\
b &= -0.4906 \\
c &= 0.204(\frac{n\sigma}{U})^{-0.5} \\
d &= 0.0 \\
e &= 0.04444(\frac{n\sigma}{U})^{-1.5} \\
h &= 10c \\
g &= 50
\end{align*}
\]

These coefficients are the same as those used in Steelant and Dick's model except for \( a \) and \( g \). As will be seen in the comparisons of the models shown in section 5, the use of equation (17) together with the current intermittency approach, which makes use of intermittency to modify turbulent viscosity directly (see section 4 for details), has a tendency to delay the onset of flow transition. Since the current approach does not use the conditioned Navier-Stokes equations, this adjustment of coefficients, leading to a shorter distance for the distributed-breakdown function \( f(s) \), enables a faster response of the mean flow solutions to the intermittent effects.

Two major production terms from Cho and Chung's model are \( T_1 \) and \( T_2 \). These two terms are used in the form \( (T_1 - T_2) \) in the model. The term \( T_1 \) mimics the production of turbulent kinetic energy, \( P_k \), and is given by:

\[
T_1 = C_1\gamma \frac{P_k}{k} = \frac{C_1\gamma}{k} \frac{\partial u_i}{\partial x_j}
\]

with the shear stresses defined as:

\[
\tau_{ij} = \mu_1 \left[ \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \frac{\partial u_k}{\partial x_k} \delta_{ij} \right] - \frac{2}{3} \rho k \delta_{ij}
\]

The term \( T_2 \) represents the production resulting from the interaction between the mean velocity and the intermittency field and is given by:

\[
T_2 = C_2\gamma \frac{k^{3/2}}{\epsilon} \frac{u_i}{(u_k u_k)^{1/2}} \frac{\partial u_i}{\partial x_j} \frac{\partial \gamma}{\partial x_j}
\]

The production terms \( T_0 \) and \( (T_1 - T_2) \) are blended by using a function \( F \) to facilitate a gradual switching from Steelant and Dick's \( T_0 \) to Cho and Chung's \( (T_1 - T_2) \) inside the transition region:

\[
P_\gamma = (1 - F)T_0 + F(T_1 - T_2)
\]
A nondimensional parameter, \( k/S\nu \), is chosen to construct the blending function \( F \), where \( k \) is the turbulent kinetic energy and \( S \) is the magnitude of the strain rate. This parameter increases rapidly with distance away from the wall inside the transition region. Using the solution obtained by Dhawan and Narasimha’s model coupled with artificial cross-stream profiles provided by Klebanoff’s formula, equation (19), one may divide the transition zone into two regions by taking a diagonal cut between the point at the edge of the boundary layer located at the beginning of transition (\( \gamma = 0 \)) to the point at the wall located at the end of transition region (\( \gamma = 1 \)). The relation between \( \gamma \) and (\( k/S\nu \)) along this diagonal line is then approximated by the following correlation:

\[
k/S\nu = 200(1 - \gamma^{0.1})^{0.3}
\]  

(35)

This line corresponds to the border between the Steelant and Dick and the Cho and Chung models: i.e. below this line, \( T_0 \) is active and above this line (\( T_1 - T_2 \)) is active. In order to facilitate a gradual switching from \( T_0 \) to (\( T_1 - T_2 \)), the following blending function is proposed:

\[
F = \tanh \left[ \frac{k/S\nu}{200(1 - \gamma^{0.1})^{0.3}} \right]
\]

(36)

As can be seen from equation (36), when \( k/S\nu >> 200(1 - \gamma^{0.1})^{0.3} \) (a position above the cutoff line), \( F = 1 \) and the model switches to Cho and Chung’s model; when \( k/S\nu << 200(1 - \gamma^{0.1})^{0.3} \) (a position below the cutoff line), \( F = 0 \) and the model becomes Steelant and Dick’s model. Outside the transition zone, the model switch to the Cho and Chung’s model except for the very thin region close the wall.

In figure 1, the proposed correlation for the cutoff line, equation (35), is compared with data extracted along the cutoff line, defined by drawing a straight line between the point at the edge of the boundary layer located at the beginning of transition to the point at the wall located at the end of transition region, of the T3A solution obtained using the proposed transition model. As can be seen from the figure, the definition of the cutoff line proposed in equation (35) is satisfactory.

An additional diffusion-related production term is introduced by Cho and Chung as:

\[
T_3 = C_3\rho \frac{k^2}{\epsilon} \frac{\partial \gamma}{\partial x_j} \frac{\partial \gamma}{\partial x_j}
\]

(37)

This term is kept active over the entire flowfield, that is, no blending is applied to this term.

Diffusion of \( \gamma \) is represented by the following term:

\[
D_\gamma = \frac{\partial}{\partial x_j} \left\{ \left( (1 - \gamma) \sigma_{\gamma\mu} + (1 - \gamma) \sigma_{\gamma\mu} \right) \frac{\partial \gamma}{\partial x_j} \right\}
\]

(38)

The final form of the model is:

\[
\frac{\partial \rho \gamma}{\partial t} + \frac{\partial \rho u_j \gamma}{\partial x_j} = (1 - \gamma) \left\{ (1 - F)T_0 + F(T_1 - T_2) \right\} + T_3 + D_\gamma
\]

(39)
or
\[
\frac{\partial \rho \gamma}{\partial t} + \frac{\partial \rho u_j \gamma}{\partial x_j} = (1 - \gamma) \left[(1 - F)C_0 \rho \sqrt{u^2 + v^2} \beta(s) + F \left(C_1 \gamma \tau_{ij} \frac{\partial u_i}{\partial x_j} - C_2 \gamma \rho \frac{k^{3/2}}{\varepsilon} \frac{u_i}{(u_k u_k)^{1/2}} \frac{\partial u_i}{\partial x_j} \right) + C_3 \rho \frac{k^{3/2}}{\varepsilon} \frac{\partial \gamma}{\partial x_j} \right] + \frac{\partial}{\partial x_j} \left((1 - \gamma) \gamma \sigma_{n \mu} + (1 - \gamma) \sigma_{n \mu} \frac{\partial \gamma}{\partial x_j} \right)
\]
(40)

where the modeling constants are,
\[
\sigma_{n \mu} = \sigma_n = 1.0 \quad C_0 = 1.0 \quad C_1 = 1.6 \quad C_2 = 0.16 \quad C_3 = 0.15
\]

4 Implementation of the Transition Model

The intermittency concept can be incorporated into the computations either by using conditioned-average Navier-Stokes equations (Steelant and Dick, 1996; Libby, 1975) or simply by multiplying the eddy viscosity obtained from a turbulence model, \( \mu_t \), by the intermittency factor, \( \gamma \) (Simon and Stephens, 1991). The major difficulty of the former method is the requirement to solve two sets of highly coupled conditioned Navier-Stokes equations. This method is computationally expensive and is not compatible with existing CFD approaches. The latter approach is recommended in the current paper. Simon and Stephens (1991) showed that by combining the two sets of conditioned Navier-Stokes equations and making the assumption that the Reynolds stresses in the nonturbulent part are negligible, the intermittency can be incorporated into the computations by using the eddy viscosity, \( \mu_t^* \), which is obtained by multiplying the eddy viscosity from a turbulence model, \( \mu_t \), with the intermittency factor, \( \gamma \). That is, \( \mu_t^* = \gamma \mu_t \) is used in the mean flow equations.

To allow the intermittency to have full control of the transitional behavior, the turbulence model selected to obtain \( \mu_t \) must produce fully turbulent feature before transition location. Menter’s SST model (Menter, 1994) can be shown to produce fully turbulent flow in the leading edge of the boundary layer. It is therefore recommended to be used as a baseline model to compute \( \mu_t \) and other turbulent quantities in the calculations. Menter’s SST model is provided in the Appendix.

The value of \( \bar{u} \sigma \) used in evaluating the constants given by (30) is provided by the Mayle correlation:
\[
\bar{u} \sigma = 1.8 \times 10^{-11} T u^{7/4}
\]
(41)

It should be noted that a value of 1.8 \( \times \) 10\(^{-11} \) was used in the current work to give a slightly better fit of Mayle’s data. When flows are subject to pressure gradients, the correlation of Steelant and Dick, equation (6), is used.

The current intermittency approach was applied in conjunction with the correlation of Huang and Xiong (1998) for the onset of transition:
\[
Re_{\theta_t} = (120 + 150 T u^{2/3}) \cosh[4(0.3 - K_\iota \times 10^3)]
\]
(42)
where $K_t$ is the minimum value of the acceleration parameter in the downstream deceleration region. This correlation was found to provide a slightly better approximation than the correlation of Abu-Ghannam and Shaw (1980) in favorable pressure gradients, as discussed by Huang and Xiong (1998).

The computations are performed with a boundary layer code which solves the mean flow, turbulence model and intermittency equations using second-order finite-volume method. In the computations, 175 grid points, expanding from the wall to the freestream, were used in the cross-stream direction for all cases. The $y^+$ values for the first point away from the wall were kept between 0.1 and 0.15 for all cases. The solutions were obtained by using 1000 streamwise steps for all cases. This corresponds to maximum dimensionless streamwise step sizes, $\Delta x^+$, of 49, 68, 47, and 37 for cases T3A, T3B, T3C1, and T3C2 respectively. These step sizes and cross-stream grid points were found satisfactory by performing a careful grid-independency check, in which the step sizes and grid spacing were both decreased by half: no effect on the solutions was found.

At the inflow, a top-hat velocity profile is prescribed. Inlet turbulent kinetic energy is fixed according to the freestream turbulence levels and the energy dissipation rate is adjusted according to the decay of the freestream turbulence, as will be illustrated in the next section.

5 Results and Discussion

The new transition model is used to predict the experimental test cases assembled by Savill (1993a, 1993b): T3A, T3B, T3C1, and T3C2. These experiments were specially designed to test the ability of turbulence models to predict the effects of freestream turbulence on the development and subsequent transition of a laminar boundary layer under zero and varying pressure gradient conditions. Cases T3A, T3B are zero-pressure-gradient flows and T3C1, T3C2 are cases with continuous change in pressure gradient representing an aft-loaded turbine blade. Comparisons were performed for these cases with the new transition model against the models of Dhawan and Narasimha, Solomon et al., and Steeland and Dick.

In all computations, the inlet conditions were calibrated to match the experimental decay of turbulence using the SST model. In each case, the inlet turbulent kinetic energy was fixed by the experimental freestream turbulence level and the matching of the freestream turbulence decay provided an estimated value for the dissipation rate of turbulent kinetic energy, $\epsilon$, (or the value of $\mu_t/\mu$) at the inlet. Once the value of $\epsilon$ (or $\mu_t/\mu$) was determined this value was used in subsequent transition computations.

In all cases, the onset of transition was specified according to the correlation of Huang and Xiong (1998), equation (42). The data of Savill were found to correlate well with equation (42) considering the uncertainties in experimental data; see Huang and Xiong (1998). For T3A, T3B, T3C1, and T3C2, the correlation gave the transition locations as $Re_{\theta_1} = 257$, 204, 194, and 297, respectively, while the experimental data showed $Re_{\theta_1} = 272$, 182, 211, and 378, respectively. The determination of the experimental onset of transition is rather arbitrary. In our model calculations, we deliberately used the correlation to predict the onset of transition in order to reduce the dependency on experimental inputs.
T3A experiment of Savill (1993a) corresponds to a zero-pressure-gradient flow over a flat plate at $Re = 3.6 \times 10^5$ per meter. The freestream turbulence intensity at the leading edge of the flat plate is 3.35%. The decay of freestream turbulence intensity is matched with the experimental data by specifying $\mu_1/\mu = 7.6$ at the inlet, as shown in Figure 2.

The computed skin-friction coefficient distributions are compared with the experimental data in Figure 3. Since T3A case is a zero-pressure-gradient case, Dhawan and Narasimha’s and Solomon et al.’s models are identical. Steelant and Dick’s model showed that the transition was somewhat delayed and the length of transition was slightly wider than the experimental data when compared with the data and the other models. In contrast, the current model predicted the length of the transition region well and also displayed an overshoot of skin-friction coefficient, $C_f$, at the end of transition region. It should be noted that the failure of Steelant and Dick’s model is because the original distributed-breakdown function, equation (17), was calibrated against the conditioned Navier-Stokes method. To allow for a faster response to flow transition when coupled with the current approach, a modified distributed-breakdown function, equation (29), is recommended.

The comparison of the Reynolds number based on momentum-thickness, $Re_\theta$, for T3A case is shown in Figure 4. As can be seen from this figure, the result of the new model is also in good agreement with the experimental data.

One of the major features of the current model is its ability to reproduce realistic cross-stream intermittency profiles. The predicted intermittency profiles at various streamwise stations through the transition zone are shown in Figure 5. The profiles exhibit a peak between $y/\delta^* = 1$ and $y/\delta^* = 2$ then drop off toward zero near the edge of the boundary layer, around $y/\delta^* = 8$. These features are consistent with the trends observed in experimental data of Sohn and Reshotko (1991), and Gostelow and Walker (1991).

The current intermittency model does not affect the ability of the turbulence models in the fully developed region, as can be demonstrated in Figure 6. In figures 6(a) and 6(b), the velocity profiles obtained using the current intermittency model are compared with those predicted using the SST model without the intermittency modification for $Re_\theta = 1,000$ and 5,000, respectively. For $Re_\theta = 1000$, the velocity profiles differ slightly near the freestream, indicating the $C_f$ value predicted by the current model is slightly larger. This larger value of the skin friction is associated with the overshoot of the skin friction near the end of the transition region, as shown in Figure 3. Further downstream, at $Re_\theta = 5000$ the velocity profile obtained from the new model is essentially coincident with the one obtained by using the SST model alone, as shown in Figure 6(b). These results clearly show that the new intermittency model does not affect “good” solution behavior of the turbulence model the in the fully developed turbulent region.

The second test case is the T3B case of Savill (1993a). T3B case is also a zero-pressure-gradient flow with a freestream turbulence intensity of 6% at the leading edge of the flat plate. The freestream Reynolds number is $6.3 \times 10^5$ per meter. In order to match the experimental decay of free stream turbulence intensity, as shown in Figure 7, $\mu_1/\mu$ is specified as 60 at the inlet.

The skin-friction coefficient distributions obtained by the models are compared with the experimental data, as shown in Figure 8. The transition length predicted by the Dhawan and Narasimha correlation is longer than the data and those predicted by the
other two models. Steelant and Dick's model showed a delay of transition because of the use of the distributed-breakdown function, equation (17). The new model produces the shortest transition length, and is closest to the experimental data. The discrepancy between the current solution and the experimental data for this case is partly due to the specified transition onset point.

In Figure 9, the momentum-thickness Reynolds number is compared to the experimental data. The solution of the new model is the closest to the experimental data followed by Steelant and Dick's model.

The γ profiles from the new model at various streamwise stations through the transition zone are shown in Figure 10. The profiles have the same characteristics as the T3A case, but due to high free stream turbulence intensity, the results showed that the peaks in the profiles are less pronounced for this case and the spread of the intermittency appears to be wider across the transition region.

The next cases are the T3C1 and T3C2 experiments of Savill (1993a). These cases are variable pressure gradient flows representing actual turbine characteristics. Both cases have similar pressure variations, but with different Reynolds numbers and free stream turbulence intensities. The pressure coefficient distributions along the flat plate for these cases are shown in Figure 11. In the figure, the symbols are the experimental data points and the lines are the curve fitting to the data points. These \( C_p \) profiles were input in the boundary layer code to perform the calculations.

T3C1 case has an inlet Reynolds number of \( 4.1 \times 10^5 \) per meter. Turbulence intensity at the leading edge of the plate is 7.78\% and a value of \( \mu_t/\mu = 30 \) is used at the inlet in order to match the decay of free stream turbulence intensity, as shown in Figure 12.

A comparison of skin-friction is shown in Figure 13 for T3C1 case. All models except the current model overpredicted the transition length. The solutions of Dhawan and Narasimha model and of the model of Solomon et al. are slightly different with the latter predicting a longer transition length. Again, Steelant and Dick's model showed a delay of the transition due to a slower distributed-breakdown function, equation (17), being used. Overall, the new model showed a fairly good comparison of the transition behavior.

The \( R_{f\theta} \) distribution along the flat plate is compared to experimental data in Figure 14 for the T3C1 case. In general, the new model reproduced the development of the boundary layer better than all other models.

The intermittency factor profiles from the new model at various streamwise stations through the transition zone are shown in Figure 15 for the T3C1 case. The characteristics of the profiles are similar to the T3B cases with mild peaks showing around \( y/\delta^* = 1.6 \) and the profiles decaying to zero around \( y/\delta^* = 10 \), near the edge of the boundary layer.

T3C2 case has an inlet Reynolds number of \( 3.5 \times 10^5 \) per meter and a free stream turbulence intensity of 2.8\% at the leading. The decay of free stream turbulence intensity was matched with the the experimental data by specifying \( \mu_t/\mu = 5 \) at the inlet, as shown in Figure 16.

The predicted skin-friction coefficient distributions are compared with experimental data in Figure 17. Both the models of Dhawan and Narasimha and of Solomon et al. give rise to a too early transition behavior and also a longer transition length. On the other hand, Steelant and Dick's model did not predict the onset of transition upto the end of computational domain. Again this is caused by the original distributed-breakdown
function being used, as discussed earlier. Overall, the current model shows a fairly good comparison with the data.

The Reynolds number based on momentum-thickness along the flat plate is compared to experimental data in Figure 18. Overall, the new model reproduces the development of boundary layer fairly well.

The intermittency factor $\gamma$ profiles at various stations through the transition zone are shown in Figure 19 for the T3C'2 case. It should be noted that T3C'2 has a lower freestream turbulence intensity than T3C1. As a result, the profiles show more pronounced peaks between $y/\delta^* = 1$ and $y/\delta^* = 2$ and the spread of the intermittency is less wider across the transition zone. These features are similar to the comparison of the zero-pressure-gradient cases, T3A and T3B.

6 Concluding Remarks

A new transport equation for intermittency is developed for modeling transitional flows including influences of free stream turbulence and pressure gradients. The model can be considered as a mix of two existing models, aiming to reproduce the intermittency distribution of Dhawan and Narasimha (1958) in the streamwise direction and to produce a realistic variation of intermittency in the cross-stream direction.

The new model was tested for both zero-pressure-gradient and variable pressure gradient flows with different freestream turbulence intensities. The new model was used in conjunction with Menter’s SST model to predict the T3A, T3B, T3C1, and T3C2 experiments of Savill (1993a, 1993b). Comparisons of $C_f$ distributions, the development of the boundary layer, and intermittency profiles were made for all cases. The new model showed a good transition behavior for all cases.
Appendix – Menter’s SST Model

Menter’s SST model (Menter, 1994) is based on a mix of two-equation $k-\omega$ and $k-\epsilon$ turbulence models using a blending function $F_1$. The model can be written as:

$k$-equation:

$$\frac{\partial \rho k}{\partial t} + \frac{\partial \rho u_j k}{\partial x_j} = P_k - 0.09 \rho \omega k + \frac{\partial}{\partial x_j} \left[ (\mu + \sigma_k \mu_t) \frac{\partial k}{\partial x_j} \right]$$  \hspace{1cm} (A-1)

$\omega$-equation:

$$\frac{\partial \rho \omega}{\partial t} + \frac{\partial \rho u_j \omega}{\partial x_j} = \frac{c}{\nu_t} P_k - 3 \rho \omega^2 + \frac{\partial}{\partial x_j} \left[ (\mu + \sigma_\omega \mu_t) \frac{\partial \omega}{\partial x_j} \right] + 2 \rho (1 - F_1) \sigma_{\omega^2} \frac{1}{\omega} \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j}$$  \hspace{1cm} (A-2)

The constants, $c$, $\beta$, $\sigma_k$, and $\sigma_\omega$, are given by the following general expression:

$$\phi = F_1 \phi_1 + (1 - F_1) \phi_2$$  \hspace{1cm} (A-3)

where $\phi$ represents any one of these constants; $\phi_1$ represents any constant in the $k-\omega$ model; $\phi_2$ represents the corresponding constant in the $k-\epsilon$ model. These constants are defined as:

Set 1 ($k-\omega$):

$$\sigma_{k_1} = 0.85 \quad \sigma_{\omega 1} = 0.5 \quad \beta_1 = 0.075 \quad c_1 = 0.553$$  \hspace{1cm} (A-4)

Set 2 ($k-\epsilon$):

$$\sigma_{k_2} = 1.0 \quad \sigma_{\omega 2} = 0.856 \quad \beta_2 = 0.0828 \quad c_2 = 0.44$$  \hspace{1cm} (A-5)

The production term is given as:

$$P_k = \tau_{ij} \frac{\partial u_i}{\partial x_j}$$  \hspace{1cm} (A-6)

where

$$\tau_{ij} = \mu_t \left[ \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \frac{\partial u_k}{\partial x_k} \delta_{ij} \right] - \frac{2}{3} \rho k \delta_{ij}$$  \hspace{1cm} (A-7)

The blending function $F_1$ is defined as:

$$F_1 = \tanh(\text{arg}^4_1)$$  \hspace{1cm} (A-8)
with

\[
\arg_1 = \min\left\{ \max\left[ \frac{\sqrt{k}}{0.09 \omega d}, \frac{500 \nu}{d^2 \omega}, \frac{4 \rho \sigma \omega k}{C'D_{k\omega} d^2} \right] \right\}
\] (A-9)

where \( d \) is the distance to the closest wall and \( C'D_{k\omega} \) is the positive portion of the cross-diffusion term in Equation (A-2).

\[
C'D_{k\omega} = \max \left[ 2 \rho \sigma \omega^2 \frac{\partial k}{\omega \partial x_j \partial x_j} ; 10^{-20} \right]
\] (A-10)

The kinematic eddy viscosity is defined as:

\[
\nu_t = \frac{a_1 k}{\max(a_1 \omega; \Omega F_2)}
\] (A-11)

where \( \Omega \) is the magnitude of vorticity and \( a_1 = 0.31 \). The function \( F_2 \) is given by:

\[
F_2 = \tanh(\arg_2^2)
\] (A-12)

with

\[
\arg_2 = \max \left[ \frac{2 \sqrt{k}}{0.09 \omega d}, \frac{500 \nu}{d^2 \omega} \right]
\] (A-13)
References


Figure 1: Blending Parameter.

Figure 2: Comparison of freestream turbulence intensity for T3A case.
Figure 3: Comparison of skin-friction coefficient for T3A case.

Figure 4: Comparison of Reynolds number based on momentum-thickness for T3A case.
Figure 5: Intermittency factor profiles for T3A case.
(a) Comparison of velocity profiles at $Re_\theta=1000$.

(b) Comparison of velocity profiles at $Re_\theta=5000$.

Figure 6: Comparison of velocity profiles at two stations.
Figure 7: Comparison of freestream turbulence intensity for T3B case.

Figure 8: Comparison of skin-friction coefficient for T3B case.
Figure 9: Comparison of Reynolds number based on momentum-thickness for T3B case.

Figure 10: Intermittency factor profiles for T3B case.
Figure 11: Pressure coefficient distributions for T3C1 and T3C2 cases.

Figure 12: Comparison of freestream turbulence intensity for T3C1 case.
Figure 13: Comparison of skin-friction coefficient for T3C1 case.

Figure 14: Comparison of Reynolds number based on momentum-thickness for T3C1 case.
Figure 15: Intermittency factor profiles for T3C1 case.

Figure 16: Comparison of freestream turbulence intensity for T3C2 case.
Figure 17: Comparison of skin-friction coefficient for T3C2 case.

Figure 18: Comparison of Reynolds number based on momentum-thickness for T3C2 case.
Figure 19: Intermittency factor profiles for T3C2 case.
Modeling of Flow Transition Using an Intermittency Transport Equation

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A new transport equation for intermittency factor is proposed to model transitional flows. The intermittent behavior of the transitional flows is incorporated into the computations by modifying the eddy viscosity, $\mu_t$, obtainable from a turbulence model, with the intermittency factor, $\gamma$: $\mu_t' = \gamma \mu_t$. In this paper, Menter's SST model (Menter, 1994) is employed to compute $\mu_t$ and other turbulent quantities. The proposed intermittency transport equation can be considered as a blending of two models - Steelant and Dick (1996) and Cho and Chung (1992). The former was proposed for near-wall flows and was designed to reproduce the streamwise variation of the intermittency factor in the transition zone following Dhawan and Narasimha correlation (Dhawan and Narasimha, 1958) and the latter was proposed for free shear flows and was used to provide a realistic cross-stream variation of the intermittency profile. The new model was used to predict the T3 series experiments assembled by Savill (1993a, 1993b) including flows with different freestream turbulence intensities and two pressure-gradient cases. For all test cases good agreements between the computed results and the experimental data are observed.