TRAILING VORTEX MEASUREMENTS
IN THE WAKE OF A HOVERING ROTOR BLADE
WITH VARIOUS TIP SHAPES

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Abstract

This work examined the wake aerodynamics of a single helicopter rotor blade with several tip shapes operating on a hover test stand. Velocity field measurements were conducted using three-component laser Doppler velocimetry (LDV). The objective of these measurements was to document the vortex velocity profiles and then extract the core properties, such as the core radius, peak swirl velocity, and axial velocity. The measured test cases covered a wide range of wake-ages and several tip shapes, including rectangular, tapered, swept, and a subwing tip. One of the primary differences shown by the change in tip shape was the wake geometry. The effect of blade taper reduced the initial peak swirl velocity by a significant fraction. It appears that this is accomplished by decreasing the vortex strength for a given blade loading. The subwing measurements showed that the interaction and merging of the subwing and primary vortices created a less coherent vortical structure. A source of vortex core instability is shown to be the ratio of the peak swirl velocity to the axial velocity deficit. The results show that if there is a turbulence producing region of the vortex structure, it will be outside of the core boundary. The LDV measurements were supported by laser light-sheet flow visualization. The results provide several benchmark test cases for future validation of theoretical vortex models, numerical free-wake models, and computational fluid dynamics results.

Nomenclature

\( A \) rotor disk area = \( \pi R^2 \), m\(^2\)

\( \text{BEMT} \) blade element momentum theory

\( C_T \) rotor thrust coefficient = \( T / \rho A (\Omega R)^2 \)

\( C_b \) Ludwieg vortex stability swirl coefficient

\( C_c \) Ludwieg vortex stability axial coefficient

\( c \) rotor blade chord, m

\( f \) Gudermannian function

\( k_1 \) ratio = \( \Gamma_v / \Gamma_b \)

\( k_2 \) ratio = \( (T_b / \Omega R c) / (C_T / \sigma) \)

\( l \) mixing length

\( N_b \) number of blades

\( r \) radial distance from vortex core center, m

\( r_v \) vortex viscous core radius, m

\( R \) rotor blade radius, m

\( Re \) Reynolds number

\( Re_v \) vortex Reynolds number = \( \Gamma_v / v \)

\( Ri \) Richardson number

\( R_{Le} \) re-laminarization parameter

\( R_{Le,c} \) re-laminarization parameter at \( r = r_v \)

\( S \) Leibovich-Stewartson vortex stability param.

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et al. (Ref. 17). A summary of the relative capabilities to allow simultaneous three-component flow field measurements of Heineck et al. (Ref. 16) and McAlister maturing and competitive technique, as shown by the producers.

Landgrebe (e.g., Refs. 11-15). Recently, the circulation field around the blade of a Mach-2 helicopter rotor has been studied using laser Doppler velocimetry (PIV), which has enabled the measurement of rotor vortex flows, as given in Ref. 18. The current work builds on the measurements reported by Leishman and co-workers (Refs. 15, 19-21).

Results of detailed flow visualization (Refs. 22 and 23) have documented the viscous flow field surrounding the rotor blade tip. The physical size of these vortical flow structures is only a fraction of the blade thickness, and so a fine level of spatial resolution is required to capture and resolve details of the vortex core. A fine level of temporal resolution (i.e., phase resolution) is required by the dynamic nature of the interaction and convection of the vortex filaments. These resolution requirements are critical when comparing different tip shapes.

The present work involves three-dimensional velocity measurements acquired in the flow field surrounding the tip of a one-bladed rotor in hover. An analysis of the measurement uncertainties involved in making these types of measurements using laser Doppler velocimetry (LDV) is described in Ref. 24. As a result of this initial study, the LDV technique was significantly refined and enabled the measurements presented here. Examples of the preliminary and refined techniques are given for several of the test cases. The results are from Refs. 25 and 26, and are compared to the baseline test case presented in Ref. 23.

Phase-resolved LDV measurements documenting the formation, roll-up, and evolution of the blade tip vortex were acquired by making a radial traverse across the vortex core at various planes below the rotor. This allowed the core properties to be studied as a function of wake age. The measurements for three other tip shapes were compared with the baseline blade. The planforms included a 20° swept tip, a tapered tip with a 0.4 taper ratio, and a subwing tip. The vortex properties estimated from the velocity profiles were compared to the baseline measurements.

Introduction

Many experiments have been attempted to examine the formation of lift-generated tip vortices. Two of the most detailed surveys are given by Rossow (Ref. 1) and Spalart (Ref. 2). Some of the first phase-resolved measurements of helicopter rotor flow fields were attempted using hot-wire anemometry (e.g., Refs. 3-8). Modern optical flow diagnostic techniques, such as laser Doppler velocimetry (LDV) and particle image velocimetry (PIV), can alleviate many of the limitations of hot-wire anemometry. An early application of a one-component LDV system to a rotor flow field was by Landgrebe & Johnson (Ref. 9), who provided a demonstration of its potential capabilities. Another application was that of Lorber et al. (Ref. 10) using 2D LDV to measure the circulation field around the blade of a Mach-scaled UH-60A with surface-mounted pressure transducers.

Over the last thirty years, LDV has gradually matured to allow simultaneous three-component flow field measurements with excellent spatial and temporal resolution (e.g., Refs. 11-15). Recently, PIV has become a rapidly maturing and competitive technique, as shown by the measurements of Heineck et al. (Ref. 16) and McAlister et al. (Ref. 17). A summary of the relative capabilities and limitations of the LDV and PIV techniques, as they apply to the measurement of rotor vortex flows, is given by Martin et al. (Ref. 18). The current work builds on the measurements reported by Leishman and co-workers (Refs. 15, 19-21).

Physical Description of a Rotor Wake

The combined wake of a hovering rotor can be visualized as a system of interacting helical surfaces of vorticity (vortex sheets) and discrete tip vortices imposed within a streamtube of actuated fluid. It is the rotational motion of the rotor blade about the shaft that causes the spanwise lift distribution on the blade to be biased outboard, toward the tip. A representative lift distribution is shown in Fig. 1. As a result, a strong static pressure gradient forms around the tip region, and the outboard portion of the wake surface experiences a roll-up into an
intense region of vorticity in the form of a trailing tip vortex. The near-field tip vortex aerodynamics involve the confluence of the trailing edge turbulent wake and any edge-separated flow into a viscous vortex core. As will be shown, this process is a function of tip shape.

Figure 1 shows that a fixed azimuthal distance from the blade trailing edge is defined as the wake age, $\zeta$. This figure also shows the qualitative relationship between the bound circulation distribution on the blade and the trailing wake structure. For a multi-bladed rotor in hover, the details of the trailing wakes are shown by Fig. 2 in an axial/radial plane at a fixed value of wake age, $\zeta$. It is evident that the wake generated by a helicopter rotor is characterized by highly dynamic, interacting vortical flow structures (e.g., Ref. 27).

In contrast to a fixed wing aircraft, the rotor tip vortices remain close to the blades. This is especially true under certain flight conditions such as low-speed descending flight, and during transition to forward flight. Not only does the wake interact with the main rotor blades, but the filaments may intersect the tail rotor, the vertical and horizontal stabilizers, and the airframe. Even in hover, the vortices pass within a fraction of a chord length below the following blades. This small blade/vortex miss distance results in high induced velocities including both upwash and downwash components, as well as radial flow. The velocity gradients induced by an individual blade's trailing vortex has been shown to cause stall on the tip of the following blade — see Clark and Leiper (Ref. 28). The magnitude and direction of these induced velocities depends on the vortex strength, the distance from the blade, and the orientation of the filament with respect to the blade. A primary example of this is shown by the measurements of Berenger et al. (Ref. 29).

The proximity of the wake to the rotor in hover creates a condition where small perturbations of the rotor inflow can cause the vortices to remain in the plane of the rotor during descending flight, in transition to forward flight, and during transient gusts. As will be shown by this fundamental set of experiments, the effects of both swept and tapered tips are to keep the vortices closer to the TPP than for a rectangular tip in hover.

As a direct result of the vortices remaining near the TPP, substantial unsteady variations in the local induced velocity field are then encountered by the rotating blades. Blade-vortex interaction (BVI) manifests as a rapidly fluctuating angle of attack that results in an unsteady local blade loading. One key to predicting the magnitude of these angle of attack variations is to develop a better understanding of the vortex core structure (see Ref. 26). It is the coupling of the wake induced velocities to the rotor blade dynamics that makes understanding the wake physics important for steady flight predictions, and critical for maneuvering flight predictions and/or simulations.

**Experimental Apparatus**

**Rotor Test Stand**

The planforms tested in these experiments included a 20° swept tip (sheared), tapered tip with a 0.4 taper ratio, and a subwing tip. The blade parameters and test conditions are given in the Appendix. The rotors were tested in the hovering state in a specially designed flow
conditioned test cell. The volume of the test cell was approximately 12,800 ft$^3$ (362 m$^3$) and was surrounded by honeycomb screens. This cell was located inside a large 500,000 ft$^3$ (14,000 m$^3$) high-bay laboratory. The rotor disk area was 5.6 ft$^2$ (0.52 m$^2$), and the wake was allowed to exhaust approximately 18 rotor radii before encountering flow diverters. Aperiodicity levels in the rotor wake when tested in this cell have been measured and used to correct the velocity field measurements (see Ref. 26).

**LDV System**

A fiber-optic based LDV system was used to make three-component velocity measurements. A beam splitter separated a single multi-line Argon-Ion laser beam into three pairs of beams (green, blue and violet), each of which measured a single component of velocity (see Fig. 3). A Bragg cell set to a frequency shift of 40 MHz produced the second shifted beam of each beam pair.

The laser beams were passed to the transmitting optics by a set of fiber-optic couplers with single mode polarization preserving fiber optic cables. The transmitting optics were located adjacent to the rotor, and consisted of a pair of fiber optic probes with integral receiving optics, one probe for the green and blue pairs, and the other probe for the violet pair. Beam expanders with focusing lenses of 750 mm and beam spacers were used to decrease the effective size of the measurement volume.

To further reduce the effective size of the probe volume visible to the receiving optics, the off-axis backscatter technique was used, as described in Martin et al. (Ref. 24) and Barrett & Swales (Ref. 32). This technique spatially filters the effective length of the LDV probe volume on all three channels. Spatial coincidence of the three probe volumes (six beams) and two receiving fibers was ensured to within a 25$\mu$m radius using an alignment technique based on a laser beam profiler, as described in Ref. 24. Alignment is critical for 3-component systems because it is geometric coincidence that determines the spatial resolution of the LDV probe volume. In the present case, the resulting LDV probe volume was measured to be an ellipsoid of dimensions 80$\mu$m by 150$\mu$m, which was about 3% of the maximum blade thickness (or about 0.5% of the blade chord).

The flow into the rotor was seeded with a thermally produced mineral oil fog. A mineral oil based fluid is broken down into a fine mist by adding nitrogen. The mist is then forced into a pressurized heater block and heated to its boiling point where it becomes vaporized. As the vapor escapes from the heat exchanger nozzle it is mixed with ambient air, rapidly cools, and condenses into a fog of which 95% of the particles are between 0.2 $\mu$m and 0.22 $\mu$m in diameter. This mean seed particle size is small enough to minimize particle tracking errors for the vortex strengths found in these experiments (Ref. 33). The fog/air mixture was passed through a series of ventilation ducts and introduced into the rotor flow field at various locations. The entire test area was uniformly seeded by running the fog generator before each measurement. The 30,000 ft$^3$ (850 m$^3$) per minute capacity of the seeder allowed the entire test cell to be uniformly seeded in approximately 30 seconds.

Signal bursts from seed particles passing through the measurement volume were received by the optics, and transmitted to a set of photomultiplier tubes where they were converted to analog signals. This analog signal was bandpass filtered from 10MHz-100MHz to remove the signal pedestal and any high frequency noise. The large range of the bandpass filter was required to allow measurement of the large flow reversal associated with the convection of a vortex core and the blade passage. The analog signal was digitized and sampled using a digital burst correlator. The flow velocities were then converted into three orthogonal components based on measurements of the beam crossing angles. Each measurement was phase-resolved with respect to the rotating blade by using a rotary encoder, which tagged each data point with a time stamp. The temporal phase-resolution of the encoder was 0.1$^\circ$; however, the measurements were averaged into one-degree bins. The measurement uncertainty in using a one-degree bin width has been discussed by Martin et al. (Ref. 24).

**Results and Discussion:**

**Tip Shape Effects**

Phase-resolved LDV measurements documenting the formation, roll-up, and evolution of the blade tip vortex were acquired by making a radial traverse across the vortex core at various planes below the rotor. This allowed the core properties to be studied as a function of wake age, $\zeta$, (see Fig. 4). The measurements for three other tip shapes were compared with the baseline blade. The planforms included a 20$^\circ$ swept back tip, a tapered tip with a 0.4 taper ratio, and a subwing tip. The vortex properties estimated from the velocity profiles were compared to the baseline measurements. In addition to the comparison, each of these test cases can be used for validating the ability of aerodynamic models to represent the effects of tip shape on the wake geometry and vortex properties.

**Baseline Blade Vortex Properties**

The vortex measurements for the baseline blade are reproduced for comparison from Ref. 23. Figure 4 shows
Figure 3: Rotor test stand and LDV system.

Figure 4: Schematic showing measured wake geometry.

Figure 5: Vortex core radius (inferred from velocity profiles) as a function of wake age for the baseline blade.

Wake Geometry

The test case parameters for the swept and tapered tip blades are shown in Tables A2 and A3, respectively. In both cases, the blade was of constant chord from the root cut-out at 20% radius to the break-point at 80% radius. Estimates of the bound circulation distribution are shown in Fig. 7(a) using blade element momentum theory (BEMT) (Ref. 41). For comparison, the phase-averaged inflow measurements are shown across the TPP in Fig. 7(b). Note that without a force balance, the peak bound circulation (and therefore the tip vortex strength) could not be matched exactly. Even so, each of these test cases provides a useful set of measurements to compare with numerical predictions.

One of the primary differences shown by the change in tip shape was the measured wake geometry shown in Fig. 8. The primary effect of taper is to decrease the bound circulation near the tip [see Fig. 7(a)], and this also decreases the effective downwash behind the blade [see Fig. 7(b)]. As a result, the vortex tends to stay near the TPP for a larger fraction of a rotor revolution while moving radially inward at a much faster rate, as shown in Fig. 8. The primary effect of sweep appears to be that
Figure 6: Vortex peak swirl velocity as a function of wake age for the baseline blade.

Figure 7: (a) Bound circulation distribution predicted using BEMT, (b) Measured phase-average inflow distribution.

Figure 8: Measured wake geometry for different tip shapes.

Figure 9: Effect of swept tip in moving the initial core outside of $r/R = 1$.

taper appears to increase the radial convection and decrease the axial convection.

Vortex Core Properties

The comparison of different tip shapes using vortex velocity field measurements requires great care in the experimental methods. Preliminary measurements were used to identify the locations of the vortices and to understand issues related to measurement uncertainty and spatial resolution. The variation of the vortex core radius (estimated from the velocity measurements) is shown in Figs. 10 and 11 as a function of wake age for the preliminary measurements and also for the refined measure-
Over the first quarter of a rotor revolution, the vortex core size is on the order of the boundary layer thickness leaving the trailing edge for each of the blades. The error in the preliminary measurements over this region is significant when compared to the refined technique. In addition, clear trends and vortex structure are difficult to define in the presence of large measurement scatter. It is also important to note that as the spatial resolution degrades at early wake age, the variation in core radius with wake age appears constant.

There is little difference in the vortex core growth shown in Figure 10 between the various tip shapes. As a result, the baseline aperiodicity measurements in Fig. 5 are assumed to be a good approximation for the other tip shapes — with the exception of the subwing tip. In terms of the peak swirl velocity, differences appear for the various tip shapes. A comparison is shown in Fig. 12, where the effects of blade loading variation between the cases have been removed to a first order by normalizing the peak swirl velocity by the average lift coefficient. The reason for this normalization is that the main focus of tip shape modification for BVI reduction is to minimize the peak swirl velocity for a given blade loading.

The vortex peak swirl velocity (divided by tip speed) is a function of three factors, and these are the nondimensional vortex strength, the ratio of core circulation to the far-field value, and the nondimensional vortex core radius.

\[
\frac{V_{\theta_{\text{max}}}}{\Omega R} = \left( \frac{\Gamma_c}{\Omega R c} \right) \left( \frac{c}{2\pi R c} \right)
\]

The vortex strength is directly proportional to the peak bound circulation, and this is the strongest influence on peak swirl velocity.

\[
\frac{V_{\theta_{\text{max}}}}{\Omega R} = \left( k_1 \frac{\Gamma_c}{\Omega R c} \right) \left( \frac{c}{2\pi R c} \right)
\]

where \( k_1 \) is the ratio of the vortex strength to the peak bound circulation

\[
k_1 = \frac{\Gamma_c}{\Gamma_b}
\]

Typical values appear to be \( k_1 = 1 \) for an untwisted blade, and \( k_1 = 0.7 \) for a highly twisted (tiltrotor) blade, but this needs additional research. The peak bound circulation is a function of blade planform (twist, taper, and sweep) and blade loading.

\[
\frac{V_{\theta_{\text{max}}}}{\Omega R} = \left( \frac{C_T}{\sigma} \right) (k_1 k_2) \left( \frac{\Gamma_c}{\Gamma_b} \right) \left( \frac{c}{2\pi R c} \right)
\]

where the proportionality constant, \( k_2 \), is defined by

\[
\left( \frac{\Gamma_b}{\Omega R c} \right) = k_2 \left( \frac{C_T}{\sigma} \right)
\]

Typical values for \( k_2 \) in hover are 2 for an ideally twisted rectangular blade and 3 for an untwisted rectangular blade.

The primary influence of tip shape is found in the last three terms of Eq. 4. By dividing the peak swirl velocity by the factor \( 6C_T/\sigma \) (average lift coefficient), the first term of Eq. 4 is removed. This allows the comparison of the tip shapes to avoid the influence of slightly different values of blade loading. This is shown by comparing the results in Figs. 11 and 12.

A primary example of this reasoning is shown by the tapered tip blade. The estimated peak bound circulation for both the swept and tapered tips is approximately equal (see Fig. 7); however, the blade loading of the tapered tip is slightly higher. As a result, the tapered tip blade reduces the initial peak swirl velocity by reducing the peak bound circulation (i.e., reducing \( k_2 \)) for a given blade loading. This benefit appears to decrease with wake age. It is interesting to note that once the difference in blade loading is accounted for, the swept and baseline blades show similar behavior.
Subwing Blade

The subwing blade concept has been investigated in wind tunnels (such as part of the NASA XV-15 test program in Ref. 30) as well as in flight tests. A detailed survey of subwing rotor blade tests is given by Ref. 25. In this current test, the subwing blade was constructed starting with a normal rectangular blade. Based on the results of Tangler (Ref. 31), the subwing chord was designed to be about 20% of the main blade chord and was placed at the quarter-chord position on the blade. The profile of the subwing was a flat plate set at a pitch angle the same as that of the main blade. Manufacturing constraints resulted in a subwing tip having a chord of 19.3% of the main blade chord, with the quarter-chord of the subwing being aligned with the 26.4% chord position on the main blade. The operating parameters for the subwing experiments are shown in Table A4, and were meant to be nominally the same as those used for the baseline experiments. As the subwing added less than 1% to the total blade area, its addition was assumed to cause no difference in the geometric or thrust-weighted rotor solidities. A single teetering blade was used and was balanced by a counterweight.

As with the other blades, the phase-averaged inflow was used to provide an estimate of the thrust coefficient of the rotor. The inflow was measured across the TPP, as shown in Fig. 13. Based on these results, BEMT was used numerically to find a rotor thrust coefficient of 0.0033. Using the blade solidity, the blade loading coefficient was then determined to be 0.0959. This is significantly higher than that found for the baseline blade, and was unexpected because of the nearly identical operating conditions (blade pitch and RPM). The exact cause of this dissimilarity is not currently understood; however, changes in performance caused by the subwing design have been documented by several other tests (these are summarized in Ref. 25). One possible reason is that the subwing reduces the tip loss of the main blade as evidenced by the difference in the phase-averaged inflow near the tip.

Subwing Blade: Flow Visualization

Visualization of multiple vortex structures from unique tip shapes such as the subwing tip (Ref. 25) improve the understanding of how the tip shape can be used to modify the resulting tip vortex structure. For comparison, the flow visualization images were taken at the same wake ages as were used for the baseline blade. The resulting images are shown in Figs. 15 through 21, covering a wake age range from 10° to 209°. As with the baseline blade flow visualization, the scale is the same in all the images. Figure 14 is a schematic of the first flow.

Figure 11: Variation of vortex peak swirl velocity (uncorrected) with wake-age (a) Preliminary measurements (b) Measurements using improved technique.

Figure 12: Variation of vortex peak swirl velocity normalized by blade loading with wake-age.
Figure 13: Phase-averaged inflow velocity measured in tip-path-plane of the subwing blade compared to the baseline.

Figure 14: Schematic of the flow visualization image area for the subwing blade (only the outer 12% of main blade radius is shown, and the direction of rotation is out of the page).

The first picture (Fig. 15) shows the subwing vortex immediately after formation, as the blade is rotating out of the plane of the page. The subwing vortex appears to originate at about the 80% radial station on the subwing. This was confirmed by slowly varying the phase of the image during the experiment. At this early wake age, the primary vortex from the main blade is not visible because optical access is blocked by the blade tip.

Figure 15: Flow visualization of wake generated by the subwing tip blade at $\zeta = 10^\circ$.

Figure 16: Flow visualization of the subwing tip blade at $\zeta = 25^\circ$.

dicates a relatively more diffuse primary vortex from the main blade compared to that produced by the subwing.

The vortices at a wake age of 45° are shown in Fig. 17. At this point, the pair has rotated in the light sheet plane about 100° from the original position, and the subwing vortex is now above the primary vortex. The vortex sheet can be seen to wrap up around the outboard side of the primary vortex.

The image in Fig. 18 shows the vortices at $\zeta = 67^\circ$. Here the vortex pair has rotated about 125° in the light sheet plane, and the primary vortex is now outboard of the subwing vortex. The subwing vortex lies in the tip-path-plane. At this point the two vortices can be seen to be beginning their merging process, as their structures seem to be undergoing some kind of interaction. The aperiodicity of the locations of the vortex cores was noted to increase at this point.
Figure 17: Flow visualization of the subwing tip blade at $\zeta = 45^\circ$.

Figure 18: Flow visualization of the subwing tip blade at $\zeta = 67^\circ$.

Figure 19: Flow visualization of the subwing tip blade at $\zeta = 90^\circ$.

Figure 20: Flow visualization of the subwing tip blade at $\zeta = 137^\circ$.

Figure 21: Flow visualization of the subwing tip blade at $\zeta = 209^\circ$.

Figure 19 shows the vortices at $\zeta = 90^\circ$, where they have rotated about $180^\circ$ in the light sheet plane and have now switched positions relative to their initial orientation. The seed voids are present, but there is obviously some interaction occurring between the vortices. The primary vortex, in particular, appears very diffuse and almost no clear structure can be seen. The vortex sheet is seen to still be in the process of being entrained into the primary vortex. The turbulent flow from the vortex sheet seems to be creating significant instability within the primary vortex and in the surrounding area.

At a wake age of $137^\circ$, as shown in Fig. 20, the vortices appear to have completed merging and are now essentially one tip vortex. However, the aperiodicity of the vortex core location was noted to still be significant at this wake age. A seed void is visible but it seems very diffuse. In fact, the entire vortex appears to be more diffuse, and is surrounded by flow that appears to contain turbulent eddies. The vortex sheet has convected downward faster than the vortex core, and only the outboard edge of the sheet can be observed. However, the sheet appears to still be wrapping into the merged vortex, causing more turbulent flow to be entrained into the flow surrounding the core.

Results for the last wake age of $209^\circ$ are shown in Fig. 21. No clearly laminar flow region can be seen. The vortex sheet has wrapped all the way around into the merged vortex. Note that as mentioned previously, these images are all to the same scale. The very large size of the seed void and of the overall vortex structure at this wake age confirms the increase in core radius expected from the merged vortices generated by the subwing tip blade.
Subwing Blade: Measurement Technique

The creation of multiple vortices required a different technique to capture the vortex velocity profiles. Using the flow visualization results for the subwing blade, it was possible to construct radial measurement grids for the phase-resolved LDV measurements. These grids are shown in Fig. 22, along with a scale representation of the subsequently estimated vortex core sizes as detailed in Ref. 26. As with the baseline blade, the measurement grids were designed to extend between 5 and 10 core radii on either side of the vortices. Because of the extremely small physical size of the subwing vortices, the grids were constructed with center portions having spacing of 0.25 mm (0.5% \text{c}) between measurement points so as to accurately resolve the large velocity gradients surrounding the vortex core (the variable grid spacing is not shown in Fig. 22).

At the earliest wake ages, the difficulty of finding the exact location of the very small subwing vortex necessitated using a vertical measurement grid (parallel to the rotor shaft), rather than the standard radial grid. This ensured that the grid would capture the subwing vortex regardless of where it crossed vertically. Note that because two of the measured cases used vertical grids, their results cannot be plotted on the same axes as the other wake ages, and thus they are shown separately. However, to enable comparison, the plots are all shown with the same scale and orientation. This allows the results for the tangential and axial velocity components to be directly compared.

Subwing Blade: Vortex Trajectories

A closer view of the wake geometry in terms of the axial or vertical (z) and radial (y) locations of the vortices at each wake age measured is shown in Fig. 23. The wake ages measured with the subwing tip were from \( \zeta = 8^\circ \) to \( \zeta = 260^\circ \). It was found through experimentation that between about \( \zeta = 40^\circ \) and \( \zeta = 130^\circ \) the interaction and merging of the subwing and primary vortices created a less coherent vortical structure that could not be accurately measured because of excessive aperiodicity in the flow. While the flow at these wake ages could still be qualitatively analyzed through flow visualization, the statistically-based measurement nature of LDV made it extremely difficult to obtain meaningful results in this region. After the merging region, the vortex could again be measured with aperiodicity levels of the same order as the baseline. Detailed aperiodicity measurements were not made, however, as in the case of the baseline blade.

It can be seen that the subwing vortices at the two earliest wake ages (\( \zeta = 8^\circ \) and \( \zeta = 22^\circ \)) lie outboard of the blade tip (where \( y/R = 1 \) is the tip of the main blade), and at the second wake age (\( \zeta = 22^\circ \)) the vortex additionally lies above the tip path plane (i.e., \( z/R < 0 \)). This is a result of the rotation of the subwing vortex around the stronger main tip vortex.

Subwing Blade: Tangential Velocity Profiles

The vortex-induced tangential velocity profiles, normalized by the rotor tip speed, are shown in Figs. 24 and 25. The subwing vortex and the primary vortex were studied independently, because only one vortex was targeted per LDV traverse across the flow field. One of the most significant contributions of this work is simply
the process of capturing these highly dynamic interacting vortices before and after the merging process. It is important to note that before the merging process there are two vortices present in the flow, so neither vortex can be isolated from the induced effects of the other in these types of experiments. For this reason, asymmetries in the profiles are very different than in the case of the baseline blades. It is not very accurate to deduce from the measurements any vortex properties (e.g., core radius and peak swirl velocity) that inherently assume a single isolated vortex. In fact, it is the interaction of the induced velocity fields that drives the merging process. Keeping this limitation in mind, results are shown in an effort to provide best estimates of these properties. The measurement grids shown in Fig. 22 were chosen, in part, to minimize the signature of the adjacent vortex. The purpose is to understand the dynamics and timing involved in the merging process. The most accurate results (and the most practical) are the final vortex properties and structure after the merging process. The reason is that the final merged vortex structure is what (in most cases) would be encountered by a following blade.

Subwing Blade: Axial Velocity Profiles

The axial velocity profiles, normalized by the tip speed, for each of the six measured wake ages are shown in Figs. 26 and 27. Again the subwing and primary vortices were measured with different grid orientations, and so are shown separately.

Figure 23: Subwing blade vortex locations relative to tip-path-plane.

Figure 24: Measured tangential velocity profiles of subwing vortices at two wake ages.

Figure 25: Measured tangential velocity profiles of primary and merged vortices at four wake ages.

It can be seen from Fig. 27 that at the early wake ages, the primary vortex has axial velocities of comparable magnitude to the tangential velocities. From the stability analysis of Ref. 26, the stability of the vortex core is a function of the ratio of peak swirl velocity to peak axial velocity deficit. In this case, both cores would be considered unstable according the peak values shown in...
side of the vortex, as in the case of the baseline blade. In terms of axial and tangential velocity profiles, the final structure of the core appears to be very similar to the baseline blade once the merging process is complete.

Subwing Blade: Vortex Properties

The vortex core properties can be estimated from the velocity measurements, keeping in mind the above mentioned limitations concerning the difference between an isolated vortex and a pair of vortices. One of the primary effects of the subwing blade is a significant increase in the net core size after the merging process. Figure 28 shows the change in estimated viscous core radius with wake age, normalized by the blade chord. As with the baseline blade, the vortex core radius is defined to be half the distance between the measured peaks in the tangential velocity.

At the earliest wake age of $\zeta \approx 10^\circ$, the core radius of the subwing vortex was estimated to be 2.5% of the blade chord, while the core of the primary vortex was 7.7% chord. The core grows to about 23% chord after the vortices have merged, and stays nominally constant thereafter. By comparing the subwing blade with the baseline, the core radius appears to be approximately double just after the merging process is complete. A large increase in core radius would be an advantage for alleviation of noise and vibratory airloads, especially if the peak swirl velocity decreased by the same factor.

These measurements show this might not be the case, however, because the merging process appears to redistribute the vortex circulation distribution. In the flow visualization and the measurements, both the subwing and primary vortex appear to rapidly diffuse before the merging. Accurate modelling of this type of blade tip requires the ability to capture both the individual diffusion of each vortex core, and the global merging process. The entire process appears to be the result of a viscous-inviscid interaction. Even these basic measurements pose a tough challenge for current modeling capabilities.

This redistribution of circulation is shown by the variation of non-dimensional peak tangential velocity, $V_{\text{max}}/\Omega R$, with wake age, $\zeta$, shown in Fig. 29. For comparison, the baseline measurements (uncorrected) are also shown in this figure. The primary difference between the baseline and the subwing blades is that the subwing blade has a very small change in peak swirl velocity with wake age. The reason for this is an inviscid-inviscid interaction that results in almost no net change in the swirl velocity as the vortex ages.

The interaction is described as follows. The total vortex strength trailed behind the blade is divided between the two vortices. When the vortices merge, the effective
circulation approximately doubles from the value each core showed before merging. This is the inviscid part of the interaction—which can be predicted by potential flow vortex conservation laws. The viscous part of the interaction is that the effective core size increases by roughly a factor of two from that of the largest core before merging. It was shown in Ref. 26 that the peak swirl velocity is by definition proportional to the ratio of the vortex circulation to core radius. A doubling of the circulation and a doubling of the effective core radius cancel. This results in a very small change in the peak swirl velocity after merging. In these tests the circulation is not equally divided, and so there is a reduction in the peak swirl velocity when the comparison is made by normalizing with blade loading (as shown by Fig. 30). The benefit in terms of reduced peak swirl velocity appears to decrease with wake age, however, more measurements are required.

These results are supported by the flow visualization images at $\zeta = 209^\circ$. The vortex from the baseline blade [Fig. 31(a)] has a clear seed void at its center, surrounded by a small region of relatively smooth stratified flow. Further out, the flow becomes much more turbulent, with eddies being visible. The merged vortex from the subwing tip blade has a seed void, but it is much less clearly defined [Fig. 31(b)]. Also, nowhere does the flow appear to be smooth and laminar. Turbulent flow is seen to completely surround the vortex core.

**Subwing Blade: Scale Effects**

From the subwing results, the merging process is assumed to be a strong function of the vortex Reynolds number. For this reason, the same type of increase in core radius might not be observed at full-scale flight.
provided insight into the basic fluid mechanics. These results are presented here in terms of vortex structure and vortex core stability. An understanding of both of these topics supports the development and analysis of tip vortex alleviation devices.

Iverson’s Equation

Iverson (Ref. 34) developed a correlation function based on the self-similar turbulent decay of a line vortex. The objective of developing a correlation function was to understand the scale effects involved in measuring vortices in low Reynolds number facilities compared to the actual high Reynolds number behavior measured in flight tests. The purpose of solving Iverson’s equation is to determine a similarity solution for the vortex velocity profiles for the case when a turbulent viscosity is allowed to vary across the vortex. The importance of obtaining a similarity solution is that it is an exact solution of the Navier-Stokes equations, which is useful for developing fundamental vortex models such as the Lamb vortex. A unique aspect of Iverson’s result is the Reynolds number dependence on the final solution, which does not occur in the case of the Lamb vortex.

The vorticity transport equation with a variable eddy viscosity was given by Iverson in terms of circulation

\[ \frac{\partial \Gamma}{\partial t} + \frac{\partial}{\partial r} \left( v_T \frac{\partial \Gamma}{\partial r} \right) = 2 \nu \frac{\partial}{\partial r} \left( \frac{\Gamma}{r^2} \right) \]  

where the turbulent viscosity is a function of the distance from the center of the core and the local circulation strength

\[ v_T = \frac{\alpha^2 r^2}{2\pi} \left| r \frac{\partial}{\partial r} \left( \frac{\Gamma}{r^2} \right) \right| + \nu \]  

This is equivalent to specifying a variable mixing length as

\[ l = \alpha r \]  

where the empirical constant according to Iverson is

\[ \alpha = 0.01854 \]  

This equation is non-dimensionalized in order to obtain a single equation that provides a similarity solution

\[ \frac{\partial^2 \Gamma}{\partial \eta^2} \left( 4 \eta \frac{\partial \Gamma}{\partial \eta} - \gamma \right) + 2 \pi \frac{1}{\alpha^2 Re_v} \frac{\Gamma}{\nu} = - \frac{\partial \gamma}{\partial \eta} \]  

with the similarity variables

\[ \eta = \frac{r^2}{4\alpha^2 \Gamma_v \tau} \]  

\[ \tau = t + t_0 \]  

\[ \gamma = \frac{\Gamma}{\Gamma_v} \]  

\[ Re_v = \frac{\Gamma_v}{\nu} \]  

This equation will be referred to as Iverson’s equation. The solution (outlined in Ref. 26) provides a self-similar
The circulation profile, $\gamma(\eta)$ across the vortex core. This type of profile helps to describe the structure of the vortex. The core strength $\gamma(1) = \Gamma_c/\Gamma_v$ is found to be a function of vortex Reynolds number, as shown in Fig. 32. At low Reynolds numbers the fully laminar solution is identical to the Lamb vortex. At high Reynolds numbers the fully turbulent solution is another fundamental exact solution for a vortex flow. As shown by the results in Fig. 32, most experiments have been made in the transitional range of the solution. The advantage of Iverson's method is that it provides some fundamental self-similar profiles to use for comparing experimental data. The disadvantage is that the prediction of the core strength does not appear to agree with available measurements. This is shown by the comparison between the theory and measurements in Fig. 32 of the ratio $\Gamma_c/\Gamma_v$. One possible reason for this is that 2-D vortex models based on a solution of the Navier-Stokes equation do not take into account the variation of the initial core structure with lift coefficient (i.e., the initial conditions at $t_0$ vary with the blade lift). This is discussed by McCormick (Ref. 3.3), and is supported by the variation of initial peak swirl velocity with lift coefficient shown in Fig. 33.

Furthermore, other factors may influence the role of turbulence in the core structure, such as tip separation effects, boundary layer states near the trailing edge, and roll-up of the trailing vortex sheet. For this reason, aircraft vortices might not be properly modeled by the ideal laminar or ideal turbulent solutions for an isolated two-dimensional vortex.

**Extension of Iverson's Result to Transitional Vortices**

The baseline measurements in this study appear partly laminar and partly turbulent (see Ref. 26), and so these two fundamental solutions are superimposed to obtain a model for transitional vortices. The important question is where the vortex transitions from laminar to turbulent, and the ability to predict this behavior. A preliminary answer to this question can be found using the concept of relaminarization and the Richardson number formulation presented in Ref. 26.

Using the definition of a shape factor applied to Iverson's equation

\[ S_p = \frac{V_0}{r} \frac{dV_0}{dr} \approx \frac{\gamma}{(\eta/\eta_c)} \frac{2\pi}{\eta \ln \left( \sqrt{\eta/\eta_c} + 2 \frac{d\gamma}{d\eta} \right)} \]  


the Richardson number is

\[ Ri = 2S_p \left( S_p + 1 \right) \]  

The procedure begins with obtaining three solutions for the vortex using Iverson's method. One solution is fully turbulent $\gamma_T$, one is fully laminar $\gamma_L$, and one is at the given vortex Reynolds number $\gamma(Re_v)$.

The next step is to test for relaminarization, where the test parameter is defined as (Ref. 26)

\[ R_L = \frac{R_l}{Re_v^{1/4}} \]  

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When $R_L < 1$ no relaminarization can occur, and when $R_L > 1$ the streamline curvature limits the role of turbulence in transporting vorticity.

Figures 34 and 35 show the distribution of $R_L$ outside of the core for the three cases. In the case of the fully turbulent vortex, $R_L$ remains less than one, and in the case of the fully laminar vortex, $R_L$ remains greater than one over the region where 99% of the vorticity is contained. For the case of $Re_v = 50800$ (which corresponds to the baseline test case), the value of $R_L$ becomes less than 1 near $r/r_c = 2$. Using the value of $R_L$ at the core boundary, a transitional circulation profile $\gamma_T$ is constructed by superposition of the fully laminar $\gamma_L$ and fully turbulent $\gamma_T$ profiles. The superposition is accomplished using a form of the Gudermannian function

$$f = 2 \tan^{-1} \left( \exp \left( \frac{r}{r_c} - \frac{1}{2} R_L \right) \right)$$

The transitional circulation profile is then

$$\gamma_T = f \gamma_T + (1 - f) \gamma_L$$

and the corresponding velocity profile is shown in comparison with the measurements in Fig. 36. The result is in agreement with the measurements.

Repeating this procedure over a range of Reynolds numbers creates a family of transitional vortex profiles. The only unknown is the radial position where 50% of the transition takes place, $\frac{1}{2} R_L$. The variation of $R_L$ with Reynolds number is shown in Fig. 37. This figure shows the range of Reynolds numbers where the vortex might appear transitional. More research is needed in this area.

**Vortex Core Stability**

Another decay mechanism that may also participate in the core growth of rotor vortices is the stability of the vortex core. This is related to axial flow and can be described by an adaptation of the Leibovich-Stewartson vortex stability theory (Ref. 36, 37). This practical theory is applied by first fitting the following Lamb-like
functions to the measured velocity distributions using

\[ \frac{V_\theta}{\Omega R} = A \left( 1 - e^{-Br^2} \right) \]  \hspace{1cm} (17) \]

\[ \frac{V_{ax}}{\Omega R} = Ce^{-Dr^2} \]  \hspace{1cm} (18) \]

where the unknown coefficients are \( A, B, C, \) and \( D. \) The stability parameter is then defined by

\[ S = \frac{V_{\theta_{max}}}{\Omega R} \left( \frac{D}{BC} \right) \]  \hspace{1cm} (19) \]

and the vortex core is considered unstable when \( S < 0.9 \) (Ref. 38). Using this criteria, the present measurements of peak axial and swirl velocity show that \( S = 0.65, \) so that initially the vortex at \( \zeta = 3^\circ \) may be unstable, and by a significant margin. This is a sufficient condition for the vortex to undergo a "hydraulic jump" to a larger diameter, or even burst (Ref. 38). The "hydraulic jump" process is described by Rule (Ref. 39), and is supported by the measurements of the changing core circulation structure in Ref. 26. The strength of this instability is proportional to the ratio of the peak swirl velocity to the axial velocity deficit.

The Leibovich-Stewartson vortex stability theory considers only the general structure of the entire core. The final conclusion is that the core is either stable or unstable, but there is no indication of how the different regions of the vortex core contribute to the stability. Detailed modeling of the vortex, as well as effective alleviation strategies, requires an understanding of which regions of the vortex are the most stable and unstable. This is very similar to the analysis of boundary layers, where the mean flow properties are used to determine a shape factor, \( H, \) that allows the regions of laminar and turbulent flow to be estimated. For vortex flows the same type of procedure involves using the Ludwieg stability test (Ref. 40) to classify regions of the core as either stable or unstable in terms of the ability to produce or damp out turbulence.
Figure 40: Ratio of peak axial velocity to peak swirl velocity as a function of wake age.

Figure 41: Ludweig’s stability coefficients as a function of the radial position across the vortex.

The procedure for calculating the Ludweg stability map of the vortex core requires both the tangential and axial velocity profiles. These have been measured in the current experiments and can be used along with the theory to estimate the vortex structure from the mean flow properties. The Ludweg stability theory involves two coefficients that are simply a measure of the ratio of the local velocity gradient to the local angular velocity of the fluid. One coefficient is determined from the tangential velocity distribution

$$C_\theta = \frac{dV_\theta}{d\theta} \left( \frac{\rho}{V_\theta} \right)$$  \hspace{1cm} (20)$$

where all of the variables are assumed to the self-similar values determined from the measured profile shown in Fig. 38. The other coefficient is determined from the axial velocity deficit measured at the earliest wake age — see Fig. 39

$$C_z = -\frac{(V_{ax})_0}{(V_\theta)_0} \left( \frac{dV_{ax}}{d\theta} \right) \left( \frac{V_\theta}{V_\theta} \right)$$  \hspace{1cm} (21)$$

Note the sign convention of $V_{ax}$ is that a deficit (wake-like profile) is a positive increment from the free-stream velocity. The maximum value at the center of the profile is $(V_{ax})_0$. The coefficient $C_z$ is also a function of the ratio of the peak axial velocity to the peak swirl velocity.

The variation of the tangential and axial coefficients is shown in Fig. 41. In this figure, it was assumed that the ratio of the peak axial velocity to the peak swirl velocity was one, so that the results can be scaled for different wake ages by multiplying $C_z$ by the actual ratio shown in Fig. 40. In addition, a curve fit to both profiles was used to calculate the velocity gradients. The curve fit to the axial profile is shown as a simple exponential distribution in Fig. 39. The curve fit to the tangential velocity profile shown in Fig. 38 is the transitional Iverson result as derived.

The final step after the coefficients have been determined is to make a comparison with the stability boundary. The stability boundary is a function of these two coefficients, and Ludweg’s condition for stability is defined (Ref. 40) by the inequality

$$(1 - C_\theta) (1 - C_z) - C_z^2 \left( \frac{5}{3} - C_\theta \right) > 0$$  \hspace{1cm} (22)$$

By plotting the values of $C_\theta$ versus $C_z$ for different radial positions from the vortex center, the stability of different regions of the vortex core can be estimated with respect to the stability boundary shown in Fig. 42. As shown in this figure, there is a band of radial positions where the vortex structure is estimated to be unstable, and therefore capable of producing turbulence. This appears to correlate well with the flow visualization image shown in Fig. 44. As the ratio of the peak axial velocity to peak swirl velocity decreases with wake age (Fig. 40), the measured curve would scale below the stability boundary and the vortex would become stable.

A more physical presentation of the same result can be obtained by plotting the difference between the measured results and the stability boundary, as shown in Fig. 43. The fundamental result obtained by applying the Ludweg stability test to measurements at the earliest wake age of 3° is that the vortex core is stabilized by the rotational flow. These results show that if there is a turbulence producing region of the vortex, it would appear outside the core boundary from $r/r_c = 1.5$ to $r/r_c = 2.75$. This result is important because most
vortex alleviation devices attempt to promote turbulence inside the vortex core where instabilities are quickly damped by the high streamline curvature. By using detailed measurements and stability analysis, future vortex alleviation devices might be designed to take advantage of the unstable region outside of the core. In theory, such a device would not have the severe drag penalty of typical devices designed to increase the axial velocity deficit inside the core. More research is needed to confirm this hypothesis.

Conclusions

Three-dimensional phase-resolved laser Doppler velocimetry measurements with high spatial and temporal resolution were made in the viscous wake trailing from a helicopter rotor blade. Detailed velocity profiles of the trailing vortex filament enabled the study of the vortex core formation, vortex roll-up, and vortex evolution. The conclusions drawn from this study are as follows:

1. One of the primary differences shown by the change in tip shape was the measured wake geometry. Tip sweep appeared to decrease both the radial and axial convection of the core, while taper appeared to increase the radial convection and decrease the axial convection. These results are for hover, and more research is needed to conclude the same effects would apply to forward flight.

2. While there was little difference in the measured vortex core growth between the various tip shapes, differences were observed in the peak swirl velocity. After the blade loading variation between tests is used to normalize the peak swirl velocity, the swept and baseline blades showed similar behavior. The effect of blade taper was to reduce the initial peak swirl velocity by a significant fraction. It appears that this is accomplished by decreasing the peak bound circulation (and therefore the trailed vortex strength) for a given blade loading.

3. The subwing measurements showed that between the wake ages of $\zeta = 40^\circ$ and $\zeta = 130^\circ$, the in-
teraction and merging of the subwing and primary vortices created a less coherent vortical structure. In terms of axial and tangential velocity profiles, the final structure of the core generated by the subwing blade appears to be very similar to the baseline blade after the merging process is complete. The primary difference between the baseline and the subwing blades is that the subwing blade has a very small change in peak swirl velocity with wake age and a much larger core size.

4. One source of vortex core instability is the ratio of the peak swirl velocity to the axial velocity deficit. These results show that if there is a turbulence producing region of the vortex structure, it is predicted to be outside of the core boundary from $r/r_c = 1.5$ to $r/r_c = 2.75$. This is the region where the measured vortex self-similar velocity profiles appear to transition from a laminar to a more turbulent model.

Acknowledgments

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References


Appendix: Blade Parameters and Test Conditions

Table 1: Parameters of the baseline blade

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<tr>
<td>Radius, $R$</td>
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<tr>
<td>Chord, $c$</td>
<td>44.0 mm</td>
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<tr>
<td>Root cutout, $r_o$</td>
<td>0.2R</td>
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<td>Break point, $r_b$</td>
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<tr>
<td>Sweep, $\Lambda$</td>
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<td>Airfoil section</td>
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<tr>
<td>Collective pitch, $\theta_0$</td>
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<td>Twist, $\theta_{tw}$</td>
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<tr>
<td>Rotational frequency, $\Omega$</td>
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<td>Tip Mach number, $M_{tip}$</td>
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<td>Tip Reynolds number, $R_{tip}$</td>
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<td>Thrust coefficient, $C_T$</td>
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<td>Solidity, $\sigma$</td>
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<td>Blade loading coefficient, $C_T/\sigma$</td>
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Table 2: Parameters of the swept tip blade

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<td>Chord, $c$</td>
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<td>Tip Mach number, $M_{tip}$</td>
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Table 3: Parameters of the tapered tip blade

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<td>Tip chord, $c_t$</td>
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<td>Effective chord, $c_e$</td>
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<tr>
<td>Rotational frequency, $\Omega$</td>
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<tr>
<td>Tip Mach number, $M_{tip}$</td>
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<td>Tip Reynolds number, $R_{tip}$</td>
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Table 4: Parameters of the subwing tip blade