4.4 DIRECT DETECTION DOPPLER LIDAR WIND MEASUREMENTS OBTAINED DURING THE 2002 INTERNATIONAL H2O PROJECT (IHOP)

BRUCE GENTRY¹, STEVEN LI,
NASA Goddard Space Flight Center, Greenbelt, MD 20771 USA

HUAILIN CHEN, JOSEPH COMER
Science Systems and Applications, Inc., Lanham, MD 20706 USA

SAVYASACHEE MATHUR
Sigma Space Corp, Greenbelt, MD 20770

JEREMY DOBLER
Optical Sciences Center, University of Arizona, Tuscon, AZ

1. Introduction

The Goddard Lidar Observatory for Winds (GLOW) is a mobile Doppler lidar system that uses direct detection techniques for profiling winds in the troposphere and lower stratosphere. In May and June of 2002 GLOW was deployed to the Southern Great Plains of the US to participate in the International H2O Project (IHOP). GLOW was located at the Homestead profiling site in the Oklahoma panhandle about 15 km east of the SPOL radar. Several other Goddard lidars, the Scanning Raman Lidar (SRL) and HARLIE, as well as radars and passive instruments were permanently operated from the Homestead site during the IHOP campaign providing a unique cluster of observations. During the IHOP observation period (May 14, 2002 to June 25, 2002) over 240 hours of wind profile measurements were obtained with GLOW. In this paper we will describe the GLOW instrument as it was configured for the IHOP campaign and we will present examples of wind profiles obtained.

2. GLOW Description

The GLOW lidar is a field deployable system for studying atmospheric dynamics and transport. It also serves as a testbed to evaluate new lidar technologies and to validate instrument models used to develop future systems. Figure 1 shows GLOW deployed next to the Goddard Scanning Raman Lidar in Oklahoma during the IHOP_2002 experiment.

The Doppler lidar receiver in the GLOW lidar system is based on the double edge technique¹,². The double edge technique utilizes two high spectral resolution optical filters located symmetrically about the outgoing laser frequency to measure the Doppler shift. The details of the double edge method have been recently reported for lidar systems measuring the Doppler shift from either aerosol³,⁴ or molecular¹,² backscattered signals. The double edge technique is an example of a class of direct detection Doppler methods that are related by the common technologies employed in the measurement.

Figure 1 - GLOW Doppler lidar deployed in Oklahoma during IHOP_2002

The details of the GLOW lidar system design and performance characteristics have been described elsewhere¹,⁵. The laser is mounted on an optical bench along with the 45 cm aperture telescope
which collects the backscattered signal. A matching 45 cm aperture scanner is mounted on the roof above the telescope. The azimuth and elevation mirrors are motor driven to allow full hemispherical pointing. The laser is a single frequency, flashlamp pumped Nd:YAG laser which has a 10 pps pulse repetition frequency. The laser output is frequency tripled to 355 nm for the molecular Doppler wind measurements. Table 1 lists the key system parameters. The maximum transmitted laser pulse energy is typically in the range of 70-80 mJ at 355 nm. The backscattered laser light is collected and coupled to a fiber optic cable that delivers the signal to the Doppler receiver. In the receiver, the beam is collimated and split into five channels. Three of these beams are directed along parallel paths through a tunable Fabry-Perot etalon which is used as the high spectral resolution edge filter. Table 1 - GLOW lidar system parameters. Values optimized for IHOP are shown in bold

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Typical / IHOP</th>
</tr>
</thead>
<tbody>
<tr>
<td>Wavelength</td>
<td>355 nm</td>
</tr>
<tr>
<td>Telescope/Scanner Aperture</td>
<td>0.45 m / 0.25 m</td>
</tr>
<tr>
<td>Laser Linewidth (FWHH)</td>
<td>80 MHz</td>
</tr>
<tr>
<td>Laser Energy/Pulse</td>
<td>70 mJ / 5 to 40 mJ</td>
</tr>
<tr>
<td>Laser Repetition Frequency</td>
<td>10 pps</td>
</tr>
<tr>
<td>Etalon FSR</td>
<td>12 GHz</td>
</tr>
<tr>
<td>Etalon FWHH</td>
<td>1.7 GHz</td>
</tr>
<tr>
<td>Etalon Peak Transmission</td>
<td>&gt;60 %</td>
</tr>
<tr>
<td>PMT Quantum Efficiency</td>
<td>15%</td>
</tr>
</tbody>
</table>

Two of these etalon channels (the 'edge' channels) have photo-multiplier tube (PMT) detectors operating in photon counting mode. These channels provide the information used in the Doppler shift measurement. The third etalon channel is used to sample the outgoing laser frequency as a reference. The other two channels serve as energy monitor channels used to provide intensity normalization of the respective etalon channels during calibration.

The GLOW molecular receiver has been designed for efficient operation in the clear air regions of the free troposphere and lower stratosphere. This provided some challenges for IHOP which was focused on convective activity in the boundary layer and lower troposphere. The photon counting PMTs provide high detection sensitivity in the upper troposphere and stratosphere where the return signals are small. One side effect of this is that when the maximum laser pulse energy and the full telescope aperture are used the signals collected from ranges less than 5 km are too large and the response of the photon counting detectors is non-linear. For the IHOP experiment the most important altitudes for observations of convective activity and boundary layer evolution are from the surface to 5 km. To ensure coverage of the lowest 5 km the signal levels were optimized by reducing the pulse energy to between 5 mJ and 40 mJ depending on atmospheric conditions and the experimental objectives of the day. In addition, the effective telescope aperture was reduced from 45 cm to 25 cm. The low laser average power (0.05 W to 0.4 W) used means that some averaging (spatial and/or temporal) is required in post processing to obtain good performance above the boundary layer. The photon counting signals are binned in a multi-channel scalar, integrated for a selectable number of shots and stored. For the IHOP experiment the minimum range bins are 45 m (300 nsec) and the minimum integration time is 10 seconds (100 shots).

3. Lidar Observations

During the IHOP experiment GLOW was operated in several modes. The most common was a step stare scanning mode, in which the lidar 'stares' for 30 seconds at a fixed elevation angle along each of the four cardinal directions. A final 30 second zenith pointing measurement is made before repeating the cycle. The typical azimuth angle sequence is 270°, 0°, 90°, 180°. The five direction step-stare scan pattern is illustrated in Figure 2.

![Figure 2](image-url)
Elevation angles of 15°, 30° and 45° were used depending on conditions.

The measured data product from the GLOW Doppler lidar is the radial wind speed along the line-of-sight of the laser in each of the each of the azimuth directions. By combining the line-of-sight data from the four directions height profiles of the u, v components of the wind field can be determined. Alternatively, profiles of the horizontal wind speed and direction can be displayed as shown in Figure 3. The lidar data, shown as blue diamonds in Figure 3, are the mean and standard deviation of three consecutive profiles of wind speed and direction taken on the afternoon of May 13, 2002. The vertical resolution of the lidar data is 100 meters.

In addition to the five direction step-stare scanning mode described above, a number of other step-stare scan patterns were used for special cases. A total of 244 hours of lidar wind profiles were obtained in the IHOP experiment. Of this total, 211 hours are from the five direction scans and the remaining 33 hours form operation in other modes.

4. Summary

The GLOW Doppler lidar completed an intensive field campaign in the spring of 2002 as one of many instruments operated in the IHOP_2002 field experiment. Calibration and validation of the
GLOW wind profile data from IHOP has been completed and the data has been made available to the scientific community. A number of case studies of events (drylines, bores, low-level jets) have been identified for further study with members of the IHOP scientific community.

Acknowledgements

GLOW participation in the IHOP-2002 field experiment was supported by Dr. James Dodge of NASA HQ, Code YS and Dr. Stephen Mango of the NPOESS Integrated Program Office.

References


Direct detection Doppler lidar wind measurements obtained during the 2002 International H₂O Project

BRUCE M. GENTRY*, HUAILIN CHEN*, STEVEN X. LI*, SAVYASACHEE MATHUR*, JEREMY DOBLER*, JOSEPH COMER*

*aNASA Goddard Space Flight Center, Laboratory for Atmospheres, Code 912, Greenbelt, MD 20771 USA
*bScience Systems and Applications, Inc., Lanham, MD 20706 USA
*cNASA Goddard Space Flight Center, Code 554, Greenbelt, MD 20771 USA
*dSigma Space Corp, Greenbelt, MD 20770
*eOptical Sciences Center, University of Arizona, Tuscon, AZ

Keywords: Doppler lidar, tropospheric wind, double edge technique, Fabry-Perot etalon

ABSTRACT

In the spring of 2002 the Goddard Lidar Observatory for Winds (GLOW) was operated at the Homestead profiling site in western Oklahoma as part of the International H₂O Project (IHOP). GLOW is a mobile direct detection Doppler lidar system which operates at the eyesafe wavelength of 355 nm. Vertical profiles of wind speed and direction are obtained with the lidar using the double edge technique to measure the Doppler shift of the laser signal backscattered by air molecules. During the IHOP campaign over 240 hours of wind profiles were obtained with the GLOW lidar in support of a variety of scientific investigations. In this paper we present a summary of IHOP operations including example case studies and results of inter-comparisons with data from other available wind sensors.