NASA/ESMD Analogue Mission Plans

2nd INTERNATIONAL WORKSHOP
Exploring Mars and its Earth Analogues

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ESMD Goals for the Use of Earth Analogues

• Learn
  – Reduce risk to crews for human surface missions to the Moon and Mars
    • Identify hazards (and develop mitigations) on Earth long before they arise in flight
  – Learn what works and what doesn’t work for surface exploration missions

• Test
  – Validate surface mission designs
    • Long duration presence
    • Outpost buildup
    • Human & robotic roles
  – Demonstrate integrated use of products from multiple CxP projects
    • Validate hardware/software performance under realistic conditions, as commanded by crews and/or mission control
    • Identify performance shortfalls in systems and support iterative testing
  – Validate mission operations designs
    • Mission Operations (Mission Control) functions for these missions
  – Influence engineering and payload system designs via early use in realistic situations
  – Enable surface science by demonstrating integration of science activities and payloads into surface exploration mission activities

• Train
  – Reduce risk to crews and to mission objectives
    • Improve crew and Mission Control team readiness for surface activities
    • Increase mission efficiency and effectiveness by evaluating competing approaches early

• Engage
  – Help sustain the excitement of exploration for the public well before missions become reality
Stakeholders Summary

**Requirements**
- Architecture trades
- Concept of operations
- Verify/Validate

**Systems**
- System validation
- System of system interaction
- Interface specification and validation

**Research and Technology**
- Technology Requirements
- Capability Demonstrations

**Ops Community**
- Understand *combined operations* leveraging diverse resources.

**Analog Mission Initiative**

**Exploration Systems Mission Directorate**
- Constellation Program Office

**Science Mission Directorate**

**Space Flight Operations Mission Directorate**

**Other Mission Directorates**

**Universities**

**Commercial**

**International Community**

**General Public**

**Other US Government**

**External Community**
Issues with Current Analogue Situation

- **Too much is being managed individually**
  - Analog missions have been happening on their own for past years
    - Utilizing “down-time” and excess funding
  - Greater need for analogs dictates a new process which can handle more activities

- **Budget issues create an uncertain future for analog missions**
  - “Extra” funding is no longer available or is not reliable
  - Analogs may not be able to maintain infrastructure if future missions are not justified
    - “Beg/Borrow/Steal” approach is not effective in keeping the focus on relevant results

- **Corporate knowledge is not being captured well and/or disseminated:**
  - Analogs dating back to the 1960’s have already produced answers to questions that are being asked again in the 2000’s
  - Many answers may retire with the “third generation” of space explorers
  - Analogs trying to answer the same question could benefit from collaboration
    - Don’t want to perform same objectives twice
    - Important objectives could use two separate perspectives

- **Common Thread:** Lack of communication and exposure
Current state of Analogues

Stakeholders:
- Organizations with analog interests and objectives

Individual Objective:
- Need (Question to Answer)
- Benefits of Answer
- Associated funding source

“Initiator”:
- Ties analog & stakeholder
- Asks stakeholder for needs
- Asks sponsor for funds
- Finds suitable analog
- Manages analog mission

Capabilities:
- Site characteristics
- Capabilities
- Facilities
- Overhead costs

Mission
- Planning and execution
- External facilities utilized (ExPOC, TDRSS, etc..)

External Stakeholders
- Ext. Govt.
- Intl Partner
- Commercial
- University

Report
- Public summary of event
- Lessons learned
- List of facilities and participants
- List of POCs for more detailed report

NASA Stakeholders
- Programs
- Projects
- Institutions
- Partnerships

Desert RATS ‘07
NEEMO-12
HMP ‘07

External Analog

Individual Objective:
- Need (Question to Answer)
- Benefits of Answer
- Associated funding source

“Initiator”:
- Ties analog & stakeholder
- Asks stakeholder for needs
- Asks sponsor for funds
- Finds suitable analog
- Manages analog mission

Capabilities:
- Site characteristics
- Capabilities
- Facilities
- Overhead costs

Mission
- Planning and execution
- External facilities utilized (ExPOC, TDRSS, etc..)

External Stakeholders
- Ext. Govt.
- Intl Partner
- Commercial
- University

Report
- Public summary of event
- Lessons learned
- List of facilities and participants
- List of POCs for more detailed report
Implementation Plan (Second Step)

**Stakeholders:**
- Organizations with analog interests and objectives

**Individual Objective:**
- Need (Question to Answer)
- Benefits of Answer
- Associated funding source

**Initiator:**
- Ties analog & stakeholder
- Asks stakeholder for needs
- Asks sponsor for funds
- Finds suitable analog
- Manages analog mission

**Analog Capabilities:**
- Site characteristics
- Capabilities
- Facilities
- Overhead costs

**Mission:**
- Planning and execution
- External facilities utilized (ExPOC, TDRSS, etc.)

**External Analog:**
- Allows POCs to match need with capability

**Reports:**
- “Lessons Learned” are easily accessible
- Helps prevent repeat work

**External**
- Ext. Govt.
- Intl Partner
- Commercial
- University

**Desert RATS ‘07**

**NEEMO-12**

**HMP ‘07**

**WEBSITE**

**Report**
- Public summary of event
- Lessons learned
- List of facilities and participants
- List of POCs for more detailed report
- Standard format
Recent Progress in Utilizing Analogues

• Analogues Database and Web Portal updated and moved to a “green” server
  – Web Portal is currently ID and Password protected
  – Ready to add Apollo-era training sites
  – Ready to incorporate EVA lessons-learned database compiled by NASA Astronaut Office

• Community briefings regarding plans and status
  – Space Technology and Applications International Forum (STAIF) - Feb 2007
    • Primarily technology users and developers
  – Invited Meeting at JSC (“First Analogs Workshop”) – Mar 2007
    • Timed to coincide with Lunar and Planetary Sciences Conference (LPSC), so primarily science user community but NASA analogue users also represented
  – Initial “supplier” community meeting – Mar 2007
    • Largely JSC-based long-standing analogues programs: Desert Research And Technology Studies (Desert RATS), Haughton-Mars Program (HMP), and NASA Extreme Environment Mission Operations (NEEMO)
  – Architecture to Requirements Development Integration Group (ARDIG) established as focal point for Constellation Program Office analogues activities
    • Launched “analogs initiative”
    • Begin coordination activity among JSC-based analogues groups: Desert RATS, HMP, and NEEMO
Website Layout Example – Home Page

Analogs
@ Johnson Space Center, Houston, Texas

Analog is an activity performed in a representative environment that is similar to a feature of the target mission.

Welcome to the Analog website at Johnson Space Center. The purpose of this website is to serve as a source of information and a collaboration tool for analog activities; primarily, but not exclusively focusing on analogs relevant to NASA’s exploration program’s and the Vision for Space Exploration.

This website is still in development and most sections will remain username/password restricted until a review of the website has been completed.

If you wish to participate in this review, please use the "+ feedback" menu item to make a request for username/password.

Announcements:

The presentations from the workshop on March 10 are now available (no username/password required).

Please make sure that your passwords meet the following minimum requirements. The length must be at least 8 characters and contain at least one of each of the following: an uppercase letter, a lowercase letter, a number, and a special character.

An events calendar is now online for review through the "+ Events" menu link.

The prototype Surface Exploration Lessons Learned Database (SELDB) is now online for review through the "+ SELDB" menu link.

The prototype Analog Database (AnalogDB) is now online for review through the "+ AnalogDB" menu link.
Website Layout Example - Analogue Site

**Analogs Database**
@ Johnson Space Center, Houston, Texas

**Site Details**

**Name**
Meteor Crater

**Location**
E4LM
Longitude, Latitude (datum): 34.07779°, -110.81559° (WGS84)
Altitude: 1700 meters
North America, USA, Arizona, Flagstaff

**Nearest Location with Climate Data (Link)**

**Sponsor or owner**
Meteor Crater Enterprises Inc.

**Lead Person**
No information in the database.

**Contact Person**
No information in the database.

**Description**
Test site located on the rim of a mid-late Cretaceous impact crater which formed when an iron-rich bolide impacted into Mesozoic sediments, primarily the Mocodoc Shale, Rarick Limestone and Coconino Sandstone. The test site is located within the eoclastic unit, with flat to hummocky terrain created by displacement of impact fragmented and shocked Rarick limestone. Boulders up to 2.5 m in size are found, although the majority of the surface consists of smaller, <0.25 m cobbles of primarily Rarick Limestone in a matrix of shocked sandstone.

**Staging Information**
No information in the database.

**Special Access Information**
Need to get permission from the commercial operator of the Meteor Crater tourist attraction.
Mission Details

Name
Advanced Space Suit Flexi Test 2000

Dates
September 2, 2000 to September 16, 2000

Organizational lead or sponsor
NASA JSC

Lead Person
Joseph J. Kosmo

Contact Person
Amy Ross

Description
Until the ASRO project, little was known about the investigation strategies necessary for determining and coordinating the interaction between humans and robotic rover vehicle systems towards achieving effective planetary surface exploration. As a result of this test experience and based on the preliminary findings and recommendations, we reported in CTSC-ADV 360 document, a series of representative planetary surface EVA deployment task were conducted as part of a joint project between elements of NASA-JSC to continue further investigation regarding synergism and interaction between humans and a robotic assistant vehicle for potential future planetary surface exploration application.

Objectives
The objectives of this series of test activities we to develop an interdisciplinary level of "lessons learned" by conducting preliminary engineering assessments and human factor evaluations of various representative space suited EVA / robotic assistant vehicle planetary surface deployment task while in Lunar / Mars analog remote field site locations. In addition, the test activities were valuable in demonstrating to various levels of NASA management, the scope of technology roads that will be required to successfully accomplish future human and robotic assisted rover vehicle exploration of planetary surfaces. Other benefits include public education-outreach opportunities and Public Affairs Office (PAO) coverage for new releases.

Result
No information in the database.

Lessons Learned


Objectives of ARDIG Analog Initiatives

**Vision:** To create a cross-cutting Earth-based program to minimize cost and risk while maximizing the productivity of planetary exploration missions, by supporting precursor system development and carrying out system integration, testing, training, and public engagement as an integral part of the Vision for Space Exploration.

- **Increased visibility of analog capabilities**
  - If organizations are familiar with what analogs exist, it is easier for “initiators” to establish objectives

- **Advertisement of Constellation Program needs**
  - Analogs wish to make their mission realistic
    - Answering current NASA and Vision for Space Exploration questions
    - Validates their existence
  - Turns into “free data” for active NASA programs
    - If more fidelity is desired, NASA organization can sponsor next mission, or initiate an Announcement of Opportunity (AO) to allow several analogs to compete for seed funding

- **Record of past mission findings in a common, searchable format**
  - Summary of event, lessons learned, and a link to more information
Future Plans

• Open Analogs Database and Web Portal to larger user community
  – A completely open Web Portal will be subject to NASA internal review and approval
  – Provide an on-line repository for analogues community (not just NASA) to store results of field deployments and research past deployments and associated lessons learned
• Coordinate analogue testing activities among ESMD-supported teams
• Coordinate with international analogue testing activities as appropriate
• Expand the database of usable analogue sites, missions, and lessons learned
  – Provide an assessment and characterization of usable analogue sites
• Please contact Gib Kirkham (NASA OER) for additional information
Example: Cold-Trap Sample Return

**Question:** What is the relative productivity of various methods for acquiring, handling, and storing, with minimal heat-induced alteration, samples from “cold traps” located at the lunar poles?

**Proposed Analogue Mission Components:**
Location: Analogue Terrain Site (e.g. small craters located at Cinder Lakes or larger such as Meteor Crater)
- Control Option 1: Earth-base Mission Control (JSC/ExPOC)
  - High-bandwidth Communications with 3 second time-delay
  - Multiple operators available
- Control Option 2: Crewed Habitat-based Mission Control (Local Trailer)
  - High-bandwidth communications with 0.1 second time-delay
  - Single operator
- Control Option 3: EVA Suit-based Mission Control (EVA Suit)
  - High-bandwidth communications with no time-delay
  - Single operator using voice input for commands and HUD for display

**Teleoperated rover**
- Locomotion system capable of descending and ascending representative lunar crater slopes (angle and roughness)
- Interface capable of supporting alternative sample acquisition devices
- Video and sensor relay and monitoring
- Heat management components
- Capable of remote driving control

**Deployed alternative (to rover) sample acquisition**
- Constraints on terrain placement
  - (e.g. requires craters of representative size and slopes)
  - Heat management components

**Analogue Mission Outcome:**
*Recommendation for extremely cold sample acquisition and handling designs and requirements*

<table>
<thead>
<tr>
<th>Source</th>
<th>Requirements</th>
</tr>
</thead>
<tbody>
<tr>
<td>HSR&amp;T</td>
<td>Spacesuit-based Command and Control, Communications</td>
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<tr>
<td></td>
<td>Sample handling equipment and procedures</td>
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<tr>
<td>ESR&amp;T</td>
<td>Wireless Networks for Surface Ops (ASTP/CCEI)</td>
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<td>Multimodal Human-Automation Interface (ASTP/SISM)</td>
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<td></td>
<td>Surface Transport Rover for cold (40 K) ops (TMP/LPSO)</td>
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<tr>
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<td>Alternative sample collection devices for cold (40 K) ops</td>
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<tr>
<td><strong>Constellation</strong></td>
<td>Surface Habitat Infrastructure Deployment ConOps</td>
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</tbody>
</table>

<table>
<thead>
<tr>
<th>Mission Time vs. Mission Control Options</th>
<th>Earth-based Mission Control (JSC sim)</th>
<th>Crewed Habitat-based Mission Control (Local Trailer sim)</th>
<th>EVA Suit-based Mission Control (EVA Suit sim)</th>
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<tbody>
<tr>
<td>EVA crew time</td>
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<tr>
<td>Total crew time (EVA plus Habitat)</td>
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<tr>
<td>Total operator time (EVA plus Habitat)</td>
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<tr>
<td>Total deployment time</td>
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</table>
## Example Site Characterization Matrix

### SITE CHARACTERISTICS

<table>
<thead>
<tr>
<th>Terrain Type</th>
<th>Slope / Grade</th>
<th>Rock Size</th>
<th>Distribution</th>
<th>Soil Properties</th>
<th>Temperature (variation - hi/lo)</th>
<th>Rel Humidity</th>
<th>Precipitation</th>
<th>Insolation</th>
<th>Wind (velocity)</th>
<th>Dust</th>
<th>Layered Sediments</th>
<th>Impact Features</th>
<th>Variety (multiple geologic environments)</th>
<th>Micropaleontology / Fossils</th>
<th>Surface Ice</th>
<th>Volcanics</th>
<th>Geothermal Activity</th>
<th>Isolation</th>
<th>Hostility</th>
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<tr>
<td>Human Factors</td>
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<td>EMU Testing</td>
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<td>Ancillary EVA Systems Testing</td>
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<td>System/Science Equip Deployment</td>
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<td>Geology Field Training</td>
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<td>Simulated Traverses</td>
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### IMPORTANCE

- **HI** - high degree of similarity is critical to effective analogy
- **MED** - similarity enhances analogy but is not critical
- **LOW** - similarity not important to effective analogy
# Integrated Analogue Studies - Prerequisites for Human Exploration

<table>
<thead>
<tr>
<th>Analogue Field Studies</th>
<th>Haughton-Mars</th>
<th>1</th>
<th>H. Remote Science</th>
<th>2</th>
<th>Desert RATS</th>
<th>3</th>
<th>Mars Desert R. S.</th>
<th>4</th>
<th>Flashline Arctic R.S.</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Elements</strong></td>
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**NEEMO** 6  **Integrity**  7  **Intl. Space Station**  8  **Mars Yard/Chamber**  9  **Antarctic/desert**  10
## Rating Scale Definitions

<table>
<thead>
<tr>
<th>Category</th>
<th>Rating Level 1</th>
<th>Rating Level 2</th>
<th>Rating Level 3</th>
<th>Rating Level 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Science Value</td>
<td>None/Not appropriate</td>
<td>Simulated science tasks or science tasks not relevant to planetary science. Little/no publishable results.</td>
<td>Valid scientific objectives/tasks relevant to future planetary exploration. No intent to publish science results or publishible science results not directly relevant to planetary science.</td>
<td>Planetary science tasks lead to publishable (peer-reviewed) science results.</td>
</tr>
<tr>
<td>Science Operations</td>
<td>Science operations not relevant to future missions.</td>
<td>Low fidelity relevant science operations, but not focused on operations lessons learned.</td>
<td>Medium fidelity to actual projected science procedures for planetary surface missions. Qualitative lessons learned.</td>
<td>High fidelity of science planning, procedures, communications, and reporting to planetary surface missions. Quantitative metrics.</td>
</tr>
<tr>
<td>Technology Development</td>
<td>Little/no technology development</td>
<td>Relevant technology used but not developed. Primarily application of existing technology.</td>
<td>Relevant technology developed but not dependent on analog environment.</td>
<td>New technology tested by taking full advantage of analog environment.</td>
</tr>
<tr>
<td>Technology Integration</td>
<td>None/Not appropriate</td>
<td>Different systems used simultaneously but not integrated.</td>
<td>Only a small number of applicable technologies used in an integrated fashion.</td>
<td>Multiple technologies used in an integrated fashion as proposed for actual mission.</td>
</tr>
<tr>
<td>Crew/Team Training</td>
<td>None/Not appropriate</td>
<td>Tasks developed to meet immediate needs of test. Some applicability to flight or ground crew training.</td>
<td>Tasks are representative of space mission. Alternative procedures are tested and compared.</td>
<td>Tasks are directly applicable to mission preparation for flight or ground crews, e.g. motion flight simulators.</td>
</tr>
<tr>
<td>Human Factors</td>
<td>None/Not appropriate</td>
<td>Human crews involved, but low fidelity to planetary habitats or surface activities.</td>
<td>Medium fidelity habitat or surface simulation.</td>
<td>High fidelity habitat or surface simulation.</td>
</tr>
<tr>
<td>Medicine/Physiology</td>
<td>None/Not appropriate</td>
<td>Some studies relevant to future long-term human missions</td>
<td>Studies relevant to maintaining crew medical and health for orbital, transit, and/or surface human missions</td>
<td>Direct medical and physiological experiments on humans in long-duration space flight conditions</td>
</tr>
<tr>
<td>Outreach/Education</td>
<td>None/Not appropriate</td>
<td>Low level of activity. Low visual content/difficult to explain. Not directly relevant to mission.</td>
<td>Moderate level of activity. Moderate visual content/relatively easy to explain. Partially relevant to mission.</td>
<td>High level of activity. High visual content/easy to explain. Directly relevant to mission.</td>
</tr>
<tr>
<td>Overall Integration</td>
<td>None/Not appropriate</td>
<td>Low level of overall coordination among analog element (science value, science operations, etc.)</td>
<td>Moderate level of overall coordination among analog element (science value, science operations, etc.)</td>
<td>High level of overall coordination among analog elements (science value, science operations, etc.)</td>
</tr>
</tbody>
</table>