Symbolic LTL Compilation for Model Checking: Extended Abstract

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In Linear Temporal Logic (LTL) model checking, we check LTL formulas representing desired behaviors against a formal model of the system designed to exhibit these behaviors. To accomplish this task, the LTL formulas must be translated into automata [21]. We focus on LTL compilation by investigating LTL satisfiability checking via a reduction to model checking. Having shown that symbolic LTL compilation algorithms are superior to explicit automata construction algorithms for this task [16], we concentrate here on seeking a better symbolic algorithm. We present experimental data comparing algorithmic variations such as normal forms, encoding methods, and variable ordering and examine their effects on performance metrics including processing time and scalability.

Safety critical systems, such as air traffic control, life support systems, hazardous environment controls, and automotive control systems, pervade our daily lives, yet testing and simulation alone cannot adequately verify their reliability [3]. Model checking is a promising approach to formal verification for safety critical systems which involves creating a formal mathematical model of the system and translating desired safety properties into a formal specification for this model. The complement of the specification is then checked against the system model. When the model does not satisfy the specification, model-checking tools accompany this negative answer with a counterexample, which points to an inconsistency between the system and the desired behaviors and aids debugging efforts.

LTL model checkers follow the automata-theoretic approach [21], in which the complemented LTL specification is translated to a Büchi automaton, which is then composed with the model under verification; see also [20]. The model checker then searches for a trace of the model that is accepted by the automaton. Symbolic model checkers, such as CadenceSMV [15], NuSMV [4], or VIS [1], represent the model and analyze it symbolically using binary decision diagrams (BDDs) [2]. All symbolic model checkers use the symbolic translation described in [5] and the analysis algorithm of [8], though CadenceSMV and VIS try to optimize further.

Arguably the most pressing challenge in model checking today is scalability. We must make model checking tools more efficient, in terms of the size of the models they can reason about and the time and space they require to verify a safety property, in order to scale our verification ability to handle real-world safety-critical systems.

A basic observation underlying our work is that LTL satisfiability checking can be reduced to model checking. Consider a formula \( \varphi \) over a set \( Prop \) of atomic proposi-
tions. If a model $M$ is universal, that is, it contains all possible traces over $Prop$, then $\varphi$ is satisfiable precisely when the model $M$ does not satisfy $\neg \varphi$. Thus, it is easy to add a satisfiability-checking feature to LTL model-checking tools. Measuring the performance of LTL satisfiability checking enables us to benchmark the performance of LTL model checking tools, and, more specifically, of LTL translation tools.

We have coded our own front-end LTL-to-automaton symbolic translator for NuSMV and CadenceSMV. Our tool compiles an input LTL formula into a symbolic automaton which can be checked against a universal model using either NuSMV or CadenceSMV for the back-end. We investigated numerous novel combinations of algorithmic constructs, including representing the formula specifications in Boolean Normal Form and Negation Normal Form, constructing the automaton using sloppy or fussy encoding, utilizing variable resolution, and applying several variable ordering algorithms from the current literature.

We report here on an experimental investigation of LTL satisfiability checking via a reduction to model checking. By using large LTL formulas, we offer challenging model-checking benchmarks. We tested our front-end LTL-to-automaton translation algorithm against the algorithms of both CadenceSMV and NuSMV, using both tools as a back-end for our translation. We used a wide variety of benchmark formulas, either generated randomly, as in [7], or using a scalable pattern (e.g., $\land_{i=1}^{n} p_i$). LTL formulas typically used for evaluating LTL translation tools are usually too small to offer challenging benchmarks. Note that real specifications typically consist of many temporal properties, whose conjunction ought to be satisfiable. Thus, studying satisfiability of large LTL formulas is quite appropriate in our goal of extending the scalability of LTL model checking tools.

We have found that the existing literature on LTL to automata translation provides little information on actual algorithm performance. There has been extensive research over the past decade into explicit translation of LTL to automata [6, 7, 9, 10, 11, 14, 12, 13, 18, 17, 19], but we previously demonstrated that symbolic tools have a clear edge over explicit tools with respect to LTL satisfiability checking [16]. Considerably less research has been done on symbolic compilation yet it is very promising. It has already been noted that automata minimization may not result in model checking performance improvement [9] and specific attention has been given to minimizing the size of the product with the model [17]. Still, no previous study of LTL translation has focused on model checking performance, leaving a glaring gap in our understanding of LTL model checking.

References


