Interference-Detection Module in a Digital Radar Receiver

This concept applies to receivers in consumer electronic devices and automotive radar systems.

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A digital receiver in a 1.26-GHz space-borne radar scatterometer now undergoing development includes a module for detecting radio-frequency interference (RFI) that could contaminate scientific data intended to be acquired by the scatterometer. The role of the RFI-detection module is to identify time intervals during which the received signal is likely to be contaminated by RFI and thereby to enable exclusion, from further scientific data processing, of signal data acquired during those intervals. The underlying concepts of detection of RFI and rejection of RFI-contaminated signal data are also potentially applicable in advanced terrestrial radio receivers, including software-defined radio receivers in general, receivers in cellular telephones and other wireless consumer electronic devices, and receivers in automotive collision-avoidance radar systems.

The improvement afforded by the present RFI module is best seen against the background of prior scatterometer back-end receiver designs. It has been conventional practice to either (1) use analog square-law detection and integration at an intermediate frequency (IF) or (2) sample an echo having a bandwidth of no more than hundreds of kilohertz at baseband and then perform Fourier-transform and magnitude-squared calculations in digital processing. Both of these conventional practices provide accurate estimates of total received power, but they also destroy, through averaging, information on the signal statistics (especially, the voltage probability distribution) in each echo measurement. This is unfortunate because the statistical information can serve as an indication of whether the scatterometer is receiving only the desired reflections from a distributed natural target or is receiving interfering signals from artificial sources in addition to, or instead of, the desired reflections.

The RFI-detection module is part of a digital square-law scatterometer processor (SP) implemented in a field-programmable gate array (FPGA). The raw scatterometer output signal used to generate an input signal for the SP is a down-converted signal at offset video frequencies in the range from 2 to 6 MHz. This signal is alternated in time with either radar echo pulses or a receiver “noise-only” measurement signal. The video signal is processed by an analog-to-digital converter (ADC) at a sampling rate of 16 MHz (greater than the Nyquist sampling rate) before being sent to the SP FPGA.

The main part of the SP calculates the signal power by use of square-and-accumulate logic during each successive receiving time window. At the same time, raw magnitude (absolute-value) information from the ADC is fed to the RFI-detection module at the full 16-MHz sampling rate.

The RFI-detection module (see figure) compares raw data samples to a pair of register values that can be programmed to set the sensitivity of an RFI-detection algorithm. The first register value defines an amplitude threshold for counting a radar return sample as being “strong.” The second register value defines a “count-exceed” value for strong samples: if this value is exceeded during a given time window, an RFI flag for that time window is triggered. In effect, the RFI-detection module performs a coarse calculation of the probability density function of the received signal by gauging whether there are many outliers in an otherwise weak signal. Because the accounting is done at the full 16-MHz Nyquist sampling rate, temporal information is preserved in the algorithm down to the time scale of one sample (62.5 ns).

Gate signals that delineate the successive processing windows are sent from a separate FPGA radar-control-and-timing unit. The signal-power values calculated by the SP are sent to a buffer memory. At the beginning of a time window, a 12-bit down counter is loaded with the “count-exceed” value. During the window, the absolute-value sample data are compared with the RFI amplitude threshold register value. If a sample equals or exceeds the threshold, it is deemed to be an RFI-contaminated sample, and the 12-bit down-counter is decremented. If the down-counter reaches a value of zero before the end of the window, then the RFI flag is set, and buffered data for this window are labeled accordingly to prevent further processing. The flag is cleared at the beginning of the next window.

For an electrically quiet scene, the noise-only voltage measurement yields a low-level Gaussian-distributed thermal noise signal (receiver noise plus the an-
tenna brightness temperature). If RFI is present in sufficient strength, it contributes a coherent signal component that spreads the probability density function of the signal in such a manner as to cause the signal to be flagged by the RFI-detection module in the SP. It has been estimated that in the original intended spaceborne-radar-scatterometer application, the effects of RFI could be effectively mitigated by commanding the SP to detect peak power levels about 10 dB above the thermal noise floor of the radar receiver.

This work was done by Mark Fischman, Andrew Berkun, Anhua Chu, Adam Freedman, Michael Fourdan, Dalia McWatters, and Mimi Paller of Caltech for NASA's Jet Propulsion Laboratory. Further information is contained in a TSP (see page 1).

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