patterns are defined in simple, declarative statements that combine point events from given input streams with those from other streams, using conjunction, disjunction, and negation. Patterns can be built on one another recursively to describe very rich, temporally extended combinations of events. Thereafter, a run-time matching algorithm in CERA efficiently matches these patterns against input data and signals when patterns are recognized.

CERA can be used to monitor complex systems and to signal operators or initiate corrective actions when anomalous conditions are recognized. CERA can be run as a stand-alone monitoring system, or it can be integrated into a larger system to automatically trigger responses to changing environments or problematic situations.

This work was written by William A. Fitzgerald and R. James Firby of I/NET, Inc. for Johnson Space Center. Further information is contained in a TSP (see page 1).

TurboTech Technical Evaluation Automated System

Goddard Space Flight Center, Greenbelt, Maryland

TurboTech software is a Web-based process that simplifies and semiautomates technical evaluation of NASA proposals for Contracting Officer’s Technical Representatives (COTRs). At the time of this reporting, there have been no set standards or systems for training new COTRs in technical evaluations. This new process provides boil-erplate text in response to “interview-style” questions. This text is collected into a Microsoft Word document that can then be further edited to conform to specific cases.

By providing technical language and a structured format, TurboTech allows the COTRs to concentrate more on the actual evaluation, and less on deciding what language would be most appropriate. Since the actual word choice is one of the more time-consuming parts of a COTRs’ job, this process should allow for an increase in quantity of proposals evaluated.

TurboTech is applicable to composing technical evaluations of contractor proposals, task and delivery orders, change order modifications, requests for proposals, new work modifications, task assignments, as well as any changes to existing contracts.

This work was done by Dorothy J. Tiffany of Goddard Space Flight Center. Further information is contained in a TSP (see page 1).

GSC-15554-1

Robot Vision Library

NASA’s Jet Propulsion Laboratory, Pasadena, California

The JPL Robot Vision Library (JPLV) provides real-time robot vision algorithms for developers who are not vision specialists. The package includes algorithms for stereo ranging, visual odometry and unsurveyed camera calibration, and has unique support for very wide-angle lenses (as used on the Mars Exploration Rover HazCams). JPLV gathers these algorithms into one uniform, documented, and tested package with a consistent C API (application programming interface). The software is designed for real-time execution (10–20 Hz) on COTS (commercial, off-the-shelf) workstations and embedded processors.

This package incorporates algorithms developed over more than ten years of research in ground and planetary robotics for NASA, DARPA (Defense Advanced Research Projects Agency) and the Army Research Labs, and is currently being used in applications as diverse as legged vehicle navigation and large-scale urban modeling.

This work was done by Andrew B. Howard, Adnan I. Ansar, and Todd E. Litwin of Caltech and Steven B. Goldberg of Indelible Systems for NASA’s Jet Propulsion Laboratory.

This software is available for commercial licensing. Please contact Karina Edmonds of the California Institute of Technology at (626) 395-2322. Refer to NPO-46532.

Perl Modules for Constructing Iterators

Goddard Space Flight Center, Greenbelt, Maryland

The Iterator Perl Module provides a general-purpose framework for constructing iterator objects within Perl, and a standard API for interacting with those objects. Iterators are an object-oriented design pattern where a description of a series of values is used in a constructor. Subsequent queries can request values in that series. These Perl modules build on the standard Iterator framework and provide iterators for some other types of values.

Iterator::DateTime constructs iterators from DateTime objects or Date::Parse descriptions and ICal/RFC 2445 style re-