wireless network adapters are controlled by use of Linux-compatible driver software. The server runs custom Linux software for synchronizing the recording of measurement data in the field stations. The software includes a module that provides an intuitive graphical user interface through which an operator at the control server can control the operations of the field stations for calibration and for recording of measurement data.

A test engineer positions and activates the WAMS. The WAMS automatically establishes the wireless network. Next, the engineer performs pretest calibrations. Then the engineer executes the test and measurement procedures. After the test, the raw measurement files are copied and transferred, through the wireless network, to a hard disk in the control server. Subsequently, the data are processed into 1/3-octave spectrograms.

Spiral Orbit Tribometer
Friction and lubricant degradation rate can be quantified rapidly.
John H. Glenn Research Center, Cleveland, Ohio

The spiral orbit tribometer (SOT) bridges the gap between full-scale life testing and typically unrealistic accelerated life testing of ball-bearing lubricants in conjunction with bearing ball and race materials. The SOT operates under realistic conditions and quickly produces results, thereby providing information that can guide the selection of lubricant, ball, and race materials early in a design process.

The SOT is based upon a simplified, retainerless thrust bearing comprising one ball between flat races (see figure). The SOT measures lubricant consumption and degradation rates and friction coefficients in boundary lubricated rolling and pivoting contacts.

The ball is pressed between the lower and upper races with a controlled force and the lower plate is rotated. The combination of load and rotation causes the ball to move in a nearly circular orbit that is, more precisely, an opening spiral. The spiral’s pitch is directly related to the friction coefficient. At the end of the orbit, the ball contacts the guide plate, restoring the orbit to its original radius. The orbit is repeatable throughout the entire test. A force transducer, mounted in-line with the guide plate, measures the force between the ball and the guide plate, which directly relates to the friction coefficient. The SOT, shown in the figure, can operate in ultra-high vacuum ($10^{-6}$ Torr) or in a variety of gases at atmospheric pressure. The load force can be adjusted between 45 and 450 N. By varying the load force and ball diameter, mean Hertzian stresses between 0.5 and 5.0 GPa can be obtained. The ball’s orbital speed range is between 1 and 100 rpm.

For most of the orbit, the ball undergoes pure rolling with pivot; however, when the ball contacts the guide plate, sliding also occurs. The period of contact with the guide plate, termed the “scrub,” is the most tribologically severe part of the orbit and is when the majority of the lubricant’s tribo-degradation occurs.

Typically, a small amount of lubricant ($\approx 50 \mu g$) is applied to the ball at the beginning of a test. Such a minute lubricant amount usually degrades within one or two days. The test duration can be varied by adjusting the initial amount of lubricant and/or the load force. A test is terminated when the lub-
Arrays of Miniature Microphones for Aeroacoustic Testing

MEMS microphones are mounted on flexible printed-circuit boards.

Langley Research Center, Hampton, Virginia

A phased-array system comprised of custom-made and commercially available microelectromechanical system (MEMS) silicon microphones and custom ancillary hardware has been developed for use in aeroacoustic testing in hard-walled and acoustically treated wind tunnels. Recent advances in the areas of multi-channel signal processing and beam forming have driven the construction of phased arrays containing ever-greater numbers of microphones. Traditional obstacles to this trend have been posed by (1) the high costs of conventional condenser microphones, associated cabling, and support electronics and (2) the difficulty of mounting conventional microphones in the precise locations required for high-density arrays. The present development overcomes these obstacles.

One of the hallmarks of the new system is a series of fabricated platforms on which multiple microphones can be mounted. These mounting platforms, consisting of flexible polyimide circuit-board material (see left side of figure), include all the necessary microphone power and signal interconnects. A single bus line connects all microphones to a common power supply, while the signal lines terminate in one or more data buses on the sides of the circuit board. To minimize cross talk between array channels, ground lines are interposed as shields between all the data bus signal lines. The MEMS microphones are electrically connected to the boards via solder pads that are built into the printed wiring. These flexible circuit boards share many characteristics with their traditional rigid counterparts, but can be manufactured much thinner, as small as 0.1 millimeter, and much lighter with boards weighing as much as 75 percent less than traditional rigid ones.

For a typical hard-walled wind-tunnel installation, the flexible printed-circuit board is bonded to the tunnel wall and covered with a face sheet that contains precise cutouts for the microphones. Once the face sheet is mounted, a smooth surface is established over the entire array due to the flush mounting of all microphones (see right side of figure). The face sheet is made from a continuous glass-woven-fabric base impregnated with an epoxy resin binder. This material offers a combination of high mechanical strength and low dielectric loss, making it suitable for withstanding the harsh test section environment present in many wind tunnels, while at the same time protecting the underlying polyimide board.

Customized signal-conditioning hardware consisting of line drivers and anti-aliasing filters is coupled with the array. The line drivers are constructed using low-supply-current, high-gain-bandwidth operational amplifiers designed to transmit the microphone signals several dozen feet from the array to external acquisition hardware. The anti-alias filters consist of individual Chebyshev low-pass filters (one for each microphone channel) housed on small printed-circuit boards mounted on one or more motherboards. The mother/daughter board design results in a modular system, which is easy to debug and service and which enables the filter characteristics to be changed by swapping daughter boards with ones containing different filter parameters. The filter outputs are passed to commercially-available acquisition hardware to digitize and store the conditioned microphone signals. Wind-tunnel testing of the new MEMS microphone polyimide mounting system shows that the array performance is comparable to that of traditional arrays, but with significantly less cost of construction.

This work was done by Qamar A. Shams, William M. Humphreys, Bradley S. Sealey, Scott M. Bartram, Allan J. Zuckerwar, Toby Comeaux, and James K. Adams of Langley Research Center. Further information is contained in a TSP (see page 1). LAR-17171-1