due to phase change of the wax from solid to liquid. For use as a heat switch on a spacecraft, multiple devices may be permanently attached to a radiator via the plunger, and the body attached to a rigid structure. During a safe mode orbital maneuver if the radiator should face the Sun, the device will then push off the radiator, disengaging it from the spacecraft bus. The device could be mounted as a pull device as well, pulling the radiator closer to the thermal bus to increase the thermal conductance between bus and radiator.

Thermal actuators of this kind are somewhat common, except that this device uses a heat pipe as a plunger, so this is an improvement. Most other devices require heat transfer through the wax chamber body, not through the plunger itself. This device will have three distinct advantages over other versions:

• Fast actuation due to quick heat transfer.
• Large stroke and stroke velocity.
• Mass savings as there is no need for thick metallic sections for conducting heat.

The actuation stroke could be designed to be large and quick enough to be used as an energy-harvesting device, converting waste heat into mechanical energy.

This work was done by Juan Cepeda-Rizo of Caltech for NASA's Jet Propulsion Laboratory. Further information is contained in a TSP (see page 1), NPO-46679

### System for Hydrogen Sensing

**John H. Glenn Research Center, Cleveland, Ohio**

A low-power, wireless gas-sensing system is designed to safeguard the apparatus to which it is attached, as well as associated personnel. It also ensures the efficiency and operational integrity of the hydrogen-powered apparatus. This sensing system can be operated with lower power consumption (less than 30 nanowatts), but still has a fast response. The detecting signal can be wirelessly transmitted to remote locations, or can be posted on the Web. This system can also be operated by harvesting energy. The electrical signal response of the sensor to the hydrogen gas can be amplified by a differential detection interface (DDI) connected to the low-power gas sensor. A microcontroller is connected and programmed to process the electrical signal, which is then wirelessly transmitted. The system also includes a central monitoring station with a wireless receiver configured to receive the sensor data signal from the wireless transmitter of the sensor device. The system further includes a power source with at least one vibrational energy harvester, solar energy harvester, and a battery.

This work was done by Jenshan Lin, David P. Norton, Stephen J. Pearton, and Fan Ren of the University of Florida for Glenn Research Center. Further information is contained in a TSP (see page 1).

Inquiries concerning rights for the commercial use of this invention should be addressed to NASA Glenn Research Center, Innovative Partnerships Office, Attn: Steve Fedor, Mail Stop 4–8, 21000 Brookpark Road, Cleveland, Ohio 44135. Refer to LEW-18484-1.

### Method for Detecting Perlite Compaction in Large Cryogenic Tanks

**John F. Kennedy Space Center, Florida**

Perlite is the most typical insulating powder used to separate the inner and outer shells of cryogenic tanks. The inner tank holds the low-temperature commodity, while the outer shell is exposed to the ambient temperature. Perlite minimizes radiative energy transfer between the two tanks. Being a powder, perlite will settle over time, leading to the danger of transferring any loads from the inner shell to the outer shell. This can cause deformation of the outer shell, leading to damaged internal fittings.

The method proposed is to place strain or displacement sensors on several locations of the outer shell. Loads induced on the shell by the expanding inner shell and perlite would be monitored, providing an indication of the location and degree of compaction.

The curves show the differential motion of the outer tank as the inner tank thermally expanded with fluffy perlite (lower curve) and compacted perlite (upper curve).
Testing involved a small, metal Dewar tank composed of an inner and outer shell. The annular region was filled with perlite. Displacement sensors were connected at two locations on the outside of the outer shell. With the perlite not compacted, the inner tank was thermally cycled and the difference in the two displacements was measured as the inner tank warmed and pressed on the perlite.

The perlite was then compacted by hand in two areas while the inner tank was cold in order to mechanically couple the inner and outer shells. When the inner tank was allowed to warm and expand, it deformed the outer tank into an elliptical shape, and the displacement sensors detected different motions for the fluffy and compacted perlite. In any location where the perlite was still fluffy and not compacted, there was no deformation. In areas where the perlite was packed more solidly, the sensors detected a slight deflection. By running these checks between cycles, it becomes a simple matter to identify areas of perlite compaction, and replace it before it can cause damage to the outer shell.

This work was done by Robert Youngquist of Kennedy Space Center. Further information is contained in a TSP (see page 1). KSC-13214

Using Thin-Film Thermometers as Heaters in Thermal Control Applications

NASA’s Jet Propulsion Laboratory, Pasadena, California

A cryogenic sensor maintains calibration at \( \approx 4.2 \text{ K} \) to better than 2 mK (<0.5 percent resistance repeatability) after being heated to \( \approx 40 \text{ K} \) with \( \approx 0.5 \text{ W} \) power. The sensor withstands 4 W power dissipation when immersed in liquid nitrogen with verified resistance reproducibility of, at worst, 1 percent. The sensor maintains calibration to 0.1 percent after being heated with 1-W power at \( \approx 77 \text{ K} \) for a period of 48 hours. When operated with a readout scheme that is capable of mitigating the self-heating calibration errors, this and similar sensors can be used for precision (mK stability) temperature control without the need of separate heaters and associated wiring/cabling.

This work was done by Hyung J. Cho, Konstantin Penanen, Kalyani G. Sukhatme, and Warren A. Holmes of Caltech, and Scott Courts of Lake Shore Cryotronics for NASA’s Jet Propulsion Laboratory. Further information is contained in a TSP (see page 1). NPO-46882

Directional Spherical Cherenkov Detector

Incident particles could be sorted by direction, speed, and electric charge.

John H. Glenn Research Center, Cleveland, Ohio

A proposed radiation-detecting apparatus would provide information on the kinetic energies, directions, and electric charges of highly energetic incident subatomic particles. The apparatus was originally intended for use in measuring properties of cosmic rays in outer space, but could also be adapted to terrestrial uses — for example, radiation dosimetry aboard high-altitude aircraft and in proton radiation therapy for treatment of tumors.

The apparatus (see figure) would include a spherical Cherenkov detector surrounded by stacks of pairs of detectors. Each such pair and stack would be used in identifying incident particles and would respond to particles incident within a solid-angle range that, in conjunction with the number of such stacks, would define the angular resolution of the apparatus. The number of stacks and the number of pairs of detectors in each stack may be unlimited.

The detectors in each stack would typically have areas \( >1 \text{ cm}^2 \) and could be made, variously, from compensated silicon or from such wide-bandgap semiconductors as semi-insulating silicon carbide. Sheets of tungsten, lead, nickel, iron, and/or alloys thereof, serving as energy-moderating materials, could be inserted between detectors to enable discrimination of particles by energy. A scintillation counter could be used as a

A Spherical Cherenkov Detector would be combined with directional/triggering detector stacks.