ates terrain traversability cost; detects low overhangs and high-density obstacles; and can perform geometry-based terrain classification (ground, ground cover, unknown).

A new origin is automatically selected for each single-frame terrain map in global coordinates such that it coincides with the corner of a world map cell. That way, single-frame terrain maps correctly line up with the world map, facilitating the merging of map data into the world map. Instead of using 32 bits to store the floating-point elevation for a map cell, the vehicle elevation is assigned to the map origin elevation and reports the change in elevation (from the origin elevation) in terms of the number of discrete steps. The single-frame terrain map elevation resolution is 2 cm. At that resolution, terrain elevation from −20.5 to 20.5 m (with respect to the vehicle’s elevation) is encoded into 11 bits.

For each four-byte map cell, bits are assigned to encode elevation, terrain roughness, terrain classification, object classification, terrain traversability cost, and a confidence value. The vehicle’s current position and orientation, the map origin, and the map cell resolution are all included in a header for each map. The map is compressed into a vector prior to delivery to another system.

This work was done by Arturo L. Rankin of Caltech for NASA’s Jet Propulsion Laboratory. Further information is contained in a TSP (see page 1).

This software is available for commercial licensing. Please contact Daniel Broderick of the California Institute of Technology at danielb@caltech.edu. Refer to NPO-46926.

### Observation Scheduling System

Software has been designed to schedule remote sensing with the Earth Observing One spacecraft. The software attempts to satisfy as many observation requests as possible considering each against spacecraft operation constraints such as data volume, thermal, pointing maneuvers, and others. More complex constraints such as temperature are approximated to enable efficient reasoning while keeping the spacecraft within safe limits. Other constraints are checked using an external software library.

For example, an attitude control library is used to determine the feasibility of maneuvering between pairs of observations. This innovation can deal with a wide range of spacecraft constraints and solve large scale scheduling problems like hundreds of observations and thousands of combinations of observation sequences.

This work was done by Steve A. Chien, Daniel Q. Tran, Gregg R. Rabideau, and Steven R. Schafer of Caltech for NASA’s Jet Propulsion Laboratory. For more information, contact iaoffice@jpl.nasa.gov.

This software is available for commercial licensing. Please contact Daniel Broderick of the California Institute of Technology at danielb@caltech.edu. Refer to NPO-47189.

### X-Windows Widget for Image Display

XvicImage is a high-performance X-Windows (Motif-compliant) user interface widget for displaying images. It handles all aspects of low-level image display. The fully Motif-compliant image display widget handles the following tasks:

- Image display, including dithering as needed
- Zoom
- Pan
- Stretch (contrast enhancement, via lookup table)
- Display of single-band or color data
- Display of non-byte data (ints, floats)
- Pseudocolor display
- Full overlay support (drawing graphics on image)
- Mouse-based panning
- Cursor handling, shaping, and planting (disconnecting cursor from mouse)
- Support for all user interaction events (passed to application)
- Background loading and display of images (doesn’t freeze the GUI)
- Tiling of images.

It does not read images directly, so it can work with any image file format. It is the application’s responsibility to read the image and supply it to XvicImage. The xvd and tp programs (part of the VICAR image processing package) are dependent on XvicImage for their operation.

This work was done by Robert G. Deen of Caltech for NASA’s Jet Propulsion Laboratory. For more information, contact iaoffice@jpl.nasa.gov.

This software is available for commercial licensing. Please contact Daniel Broderick of the California Institute of Technology at danielb@caltech.edu. Refer to NPO-46922.