merically by a combination of the Newton-Raphson and successive-substitution methods. The program includes subroutines that compute thermodynamic and thermophysical properties for 12 fluids and is integrated with a commercial program that gives thermodynamic properties of 36 fluids. Eighteen different options are provided for modeling momentum sources or sinks in the branches. Additional capabilities, including new resistance options, new fluids, and nonlinear boundary conditions, can be added by means of subroutines. An audio-visual training CD (compact disk) containing lectures, demonstration of graphical user interface, and tutorial problems is available for learning to use the program.

### Program Predicts Performance of Optical Parametric Oscillators

**Langley Research Center, Hampton, Virginia**

A computer program predicts the performances of solid-state lasers that operate at wavelengths from ultraviolet through mid-infrared and that comprise various combinations of stable and unstable resonators, optical parametric oscillators (OPOs), and sum-frequency generators (SHGs), including second-harmonic generators (SFGs). The input to the program describes the signal, idler, and pump beams; the SFG and OPO crystals; and the laser geometry. The program calculates the electric fields of the idler, pump, and output beams at three locations (inside the laser resonator, just outside the input mirror, and just outside the output mirror) as functions of time for the duration of the pump beam. For each beam, the electric field is used to calculate the fluence at the output mirror, plus summary parameters that include the centroid location, the radius of curvature of the wavefront leaving through the output mirror, the location and size of the beam waist, and a quantity known, variously, as a propagation constant or beam-quality factor. The program provides a typical Windows interface for entering data and selecting files. The program can include as many as six plot windows, each containing four graphs.

This program was written by Alok Kumar Majumdar of Marshall Space Flight Center. Further information is contained in a TSP (see page 1). This invention is owned by NASA, and a patent application has been filed. For further information, contact Sammy Nabors, MSFC Commercialization Assistance Lead, at sammy.a.nabors@nasa.gov. Refer to MFS-32125-1.

### Processing TES Level-1B Data

**NASA's Jet Propulsion Laboratory, Pasadena, California**

TES L1B Subsystem is a computer program that performs several functions for the Tropospheric Emission Spectrometer (TES). The term “L1B” (an abbreviation of “level 1B”), refers to data, specific to the TES, on radiometric calibrated spectral radiances and their corresponding noise equivalent spectral radiances (NESRs), plus ancillary geolocation, quality, and engineering data. The functions performed by TES L1B Subsystem include shear analysis, monitoring of signal levels, detection of ice build-up, and phase correction and radiometric and spectral calibration of TES target data. Also, the program computes NESRs for target spectra, writes scientific TES level-1B data to hierarchical-data-format (HDF) files for public distribution, computes brightness temperatures, and quantifies interpixel signal variability for the purpose of first-order cloud and heterogeneous land screening by the level-2 software summarized in the immediately following article. This program uses an in-house-developed algorithm, called “NUSRT,” to correct instrument line-shape factors.

This program was written by Richard C. De Baca, Edwin Sarkissian, Marietta Madatyan, Douglas Shepard, Scott Gluck, Mark Apolinski, James McDuffie, and Dennis Tremblay of Caltech for NASA’s Jet Propulsion Laboratory. Further information is contained in a TSP (see page 1).

This software is available for commercial licensing. Please contact Karina Edmonds of the California Institute of Technology at (626) 395-2322. Refer to NPO-35218.

### Automated Camera Calibration

**NASA’s Jet Propulsion Laboratory, Pasadena, California**

Automated Camera Calibration (ACAL) is a computer program that automates the generation of calibration data for camera models used in machine vision systems. Machine vision camera models describe the mapping between points in three-dimensional (3D) space in front of the camera and the corresponding points in two-dimensional (2D) space in the camera’s image. Calibrating a camera model requires a set of calibration data containing known 3D-to-2D point correspondences for the given camera system. Generating calibration data typically involves taking images of a calibration target where the 3D locations of the target’s fiducial marks are known, and then measuring the 2D locations of the fiducial marks in the images. ACAL automates the analysis of calibration target...