A sensor for selectively determining the presence and measuring the amount of hydrogen in the vicinity of the sensor. The sensor comprises a MEMS device coated with a nanostructured thin film of indium oxide doped tin oxide with an overlayer of nanostructured barium cerate with platinum catalyst nanoparticles. Initial exposure to a UV light source, at room temperature, causes burning of organic residues present on the sensor surface and provides a clean surface for sensing hydrogen at room temperature. A giant room temperature hydrogen sensitivity is observed after making the UV source off. The hydrogen sensor of the invention can be usefully employed for the detection of hydrogen in an environment susceptible to the incursion or generation of hydrogen and may be conveniently used at room temperature.

19 Claims, 5 Drawing Sheets
Fig. 5

- **$\text{N}_2 + \text{H}_2$**
- **Air 50 Torr**
- **Air 760 Torr**

**Parameters:**
- **P = 50 Torr**
- **T = 22°C**
- **UV-OFF**
- **900 ppm H$_2$**

**Axes:**
- **Time (sec)**
- **Resistance (Ohms)**

**Legend:**
- **N$_2$ + H$_2$:** Gas mixture
- **Air 50 Torr:** Air pressure change
- **Air 760 Torr:** Higher air pressure change
A variety of these commercially available hydrogen sensors are based on measuring an electrical characteristic across a sensor element and at least four major categories of sensors and associated methods have been identified.

One type of hydrogen sensor is the “catalytic combustible” or “hot wire” sensor (CC sensor) mentioned in the U.S. Pat. No. 6,006,582 to Bhandari, et. al. The CC sensor comprises two specially arranged beads of a catalytic metal or alloy, such as platinum-iridium wire heated to 600-800 degrees Celsius. One bead is coated with a reactive catalyst. In the presence of a flammable gas, the heat of oxidation raises the temperature of the bead and alters the electrical resistance characteristics of the measuring circuit. This resistance change is related to the concentration of all flammable gases, including hydrogen, in the vicinity of the sensor.

Sensors of such “hot wire” type have cross-sensitivity to other easily oxidized materials, such as alcohols and hydrocarbons. Such easily oxidized materials are common components of gases in a semiconductor-manufacturing environment, and often result in the frequent occurrence of false alarms.

Current hot wire sensors require an oxidation reaction for operation, such sensors are unable to detect hydrogen when it is present in inert gas streams or environments which are not of a character to support an oxidative reaction. This is a deficiency of such hot wire sensors and limits their applicability and utility.

The CC sensor has drawbacks. In oxygen deficient environments or above an upper explosive limit, the oxidation process is quenched causing difficulties in measuring. In addition, since the CC sensor is based upon oxidation, and all hydrocarbons have the same response as hydrogen, this makes it difficult to detect hydrogen in environments which also contain hydrocarbons. Further, the CC sensor element is easily contaminated by halogenated hydrocarbons and is susceptible to poisoning by silicones, lead and phosphorous.

Another commonly used hydrogen sensor is a non-porous metal oxide (MO) sensor. The MO sensor element comprises a non-porous metal oxide (such as zirconium dioxide or tin dioxide) sandwiched between two porous metal electrodes. Such electrodes are typically made of platinum. One electrode is exposed to the reference gas, usually air, and the other electrode is exposed to the test gas being detected.

Mobile ions diffuse to both surfaces of the oxide where they may be eliminated by reaction with adsorbed species. In the absence of gas species which can be oxidized (such as, for instance, carbon monoxide or hydrogen), the electrochemical potential of the sensor may be determined by the Nernst equation and is proportional to the partial pressure of oxygen in the test gas only. In order to achieve sensitivity to hydrogen with this device, the platinum electrode is co-deposited with gold. Since gold is a substantially less efficient donor of electrons than platinum, oxidation rates are reduced, equilibrium conditions are not achieved and the sensor becomes sensitive to the composition of the test gas. The electrochemical potential which develops becomes “non-Nernstian”, and is a complicated function of the kinetics and mass transfer associated with all species reacting at the electrode.

Like the CC sensor, the MO sensor has serious disadvantages. The sensor is not hydrogen-specific and all oxidizable gases in the test gas contribute to the sensor signal. The response is relatively slow and it can take up to 20 seconds to reach 50% of maximum signal when exposed to 1% hydrogen in air at flows below 200 standard cubic centimeters per minute (scm); the recovery time is even slower taking up to 5 minutes to reach 50% of maximum signal when exposed to less than 200 scm of air. Finally, in order to achieve even these orders of response time, the device must be operated at
temperatures above 350 degrees Celsius. Operating at such temperatures, is potentially unsafe and may cause ignition and/or explosion.

Another class of sensors includes metal-insulator semiconductor (MIS) or metal-oxide-semiconductor (MOS) capacitors and field effect transistors, as well as palladium-gated diodes. In general however, these sensors are limited to detecting low concentrations of hydrogen.

Yet another type of sensor is the metal oxide-semiconductor (MOS) sensor which is also known and is mentioned, for instance, in the U.S. Pat. No. 6,006,582 to Bhandari, et. al. The MOS sensor element comprises an oxide, typically of iron, zinc, or tin, or a mixture thereof, and is heated to a temperature of about 150 degrees Celsius to about 350 degrees Celsius. Bhandari et. al. reported that oxygen absorbs on the surface of the sensor element to create an equilibrium concentration of oxide ions in the surface layers.

The original resistance of the MOS sensor is first measured. When certain compounds, such as, for instance, CO, or hydrocarbons come in contact with the sensor, they are adsorbed on the surface of the MOS element. This absorption shifts the oxygen equilibrium, causing a detectable increase in conductivity of the MOS material.

MOS hydrogen sensors have a number of operational deficiencies and are, therefore, unsatisfactory in many respects. They require frequent calibration and their response times are too long (up to 3-5 minutes). Bhandari et. al. noted that the MOS sensors are unsafe and can cause ignition and explosion, and are susceptible to being poisoned with halogenated vapors. Like the CC and the MO sensors discussed above, they are not hydrogen specific. All volatile organic compounds as well as gases containing hydrogen will react with the sensor materials in the sensing elements of these detectors, thereby providing false readings.

Still yet another sensor is the catalytic gate (CG) sensor, the simplest embodiment of which is a MOS structure, where the metal is usually platinum or palladium deposited on an insulator, such as silicon dioxide. Hydrogen dissociates on platinum or palladium and subsequently diffuses into the bulk of the metal. Hydrogen atoms which arrive at the metal-insulator interface, form a dipole layer, polarizing the interface and consequently changing its electrical characteristics. The CG sensor also has serious drawbacks, particularly slow response time when the surface is contaminated. The surface of platinum or palladium is very much susceptible to contamination and poisoning.

There exists no known prior art teaching of a hydrogen-specific sensor, which quickly responds only to hydrogen gas at room temperature and which is not susceptible to poisoning. Yet, as discussed above, such sensor is highly desirable and the need for such sensor, which is also low cost, lightweight and of a miniature size, is acute.

The present invention discloses such a sensor. It therefore is an object of the present invention to provide an improved hydrogen sensor platform, comprising a hydrogen-sensitive thin film sensor element on a silicon (Si) wafer substrate wherein the hydrogen sensor platform receives a sol-gel coating of an indium oxide doped tin oxide thin film over the sensor platform.

In another embodiment the MEMS substrate having a sol-gel coating of an indium oxide doped tin oxide thin film is exposed to an ultra violet light source as a means for regenerating and decontaminating the MEMS device (self-cleaning).

It is yet another object of the present invention to provide a solid state micro electro-mechanical systems (MEMS) hydrogen-selective sensor that has no moving parts, has a response time on the order of seconds, operates within a minimum power consumption, does not require frequent calibration, has a large dynamic detection range, can operate at room temperature, and can be readily embodied as a hand-held portable instrument.

The present invention relates in one aspect to a hydrogen sensor platform, comprising a hydrogen-sensitive thin film sensor element on a silicon (Si) wafer substrate wherein the hydrogen sensor platform receives a sol-gel coating of an indium oxide doped tin oxide thin film over the sensor platform.

In an embodiment the MEMS substrate having a sol-gel coating of an indium oxide doped tin oxide thin film is exposed to an ultra violet light source as a means for removing contaminants and regenerating (self-cleaning) the MEMS hydrogen-selective sensor device.

In embodiments the insulating oxide layer may be thermally grown on the substrate surface or deposited by other methods such as vapor deposition or sputtering.

Another aspect of the present invention relates to the patterning of electrodes onto the MEMS device using known techniques, for example, photolithography or wet chemical
etching. In embodiments, the patterning of each electrode is carried out using positive or negative photolithography, or a known lift-off method.

In one embodiment, the hydrogen-sensitive, indium oxide doped tin oxide thin film is overlaid by a hydrogen-selective layer protecting the thin film hydrogen-sensor from deleterious interaction with non-hydrogen components of the environment being monitored, such as carbon monoxide, carbon dioxide, alcohols, hydrogen sulfide, ammonia, and hydrocarbons etc. The hydrogen-selective layer may include nanostructured barium cerate, or strontium cerate or other proton conducting membranes and the nanoclusters of catalyst may include a metal such as Pt, Pd, Au, Ag or Rh, and/or alloys thereof.

In another embodiment, the sol-gel derived nanostructured indium oxide (In₂O₃) doped tin oxide (SnO₂), with the sol-gel or microemulsion derived hydrogen-selective overlayer, is dip-coated over the hydrogen sensor platform before being wire-bonded to a plastic or ceramic package. Other objects and advantages of the present invention will be more fully apparent from the ensuing disclosure, illustrations, and appended claims.

**BRIEF DESCRIPTION OF THE FIGURES**

FIG. 1A is a top view of one embodiment showing the mask design of the hydrogen micro sensor.

FIG. 1B is an exploded view of the same mask design showing the resistive temperature sensor of the hydrogen micro sensor.

FIG. 2A illustrates the silicon substrate used for fabricating the hydrogen sensor.

FIG. 2B illustrates the oxidation step used for fabricating the hydrogen sensor.

FIG. 2C illustrates the metallization step used for fabricating the hydrogen sensor.

FIG. 2D illustrates photolithography/etching step used for fabricating the hydrogen sensor.

FIG. 2E illustrates the application and coating of Nano-materials onto the substrate of the hydrogen sensor.

FIG. 2F illustrates the wiring bonding fabrication step.

FIG. 3 illustrates XPS analysis of sol-gel dip-coated MEMS device showing the presence of In, Sn, O, and Pt.

FIG. 4 illustrates multilayer structure of MEMS-based hydrogen sensor, which is an enlarged view of an encircled portion in FIG. 2E.

FIG. 5 illustrates giant-room temperature hydrogen sensitivity for the MEMS based sensor.

**DESCRIPTION OF THE PREFERRED EMBODIMENT**

Before explaining the disclosed embodiment of the present invention in detail it is to be understood that the invention is not limited in its application to the details of the particular arrangement shown since the invention is capable of other embodiments. Also, the terminology used herein is for the purpose of description and not of limitation.

The present invention relates to a micro electro-mechanical systems (MEMS) hydrogen sensor which integrates a nanostructured indium oxide doped tin oxide thin film hydrogen sensor element, made using a sol-gel dip-coating process, with an ultra-violet light source as a means for decontaminating and regenerating the MEMS based hydrogen sensor. The hydrogen sensor of the invention is a MEMS device that may be adapted in a variety of apparatus embodiments to accommodate the objects of the invention.

The MEMS device of the present invention may be fabricated in a number of ways, for example, the MEMS device may be formed from a substrate. Typical substrates may comprise a silicon wafer or glass with an oxide layer added for insulation.

In embodiments, the substrate of the present invention may, for example, comprise a silicon wafer having a thickness of from about 5 micrometers (µm) to about 5 inches as shown schematically in FIG. 2A.

In other embodiments, the thickness of the substrate may range from about 1 to about 5 inches. In a specific embodiment, the thickness of the substrate is from about 3 inches.

The substrate is oxidized to provide an insulating layer of silicon dioxide, as illustrated schematically in FIG. 2B. In various embodiments of the instant invention, the oxidizing layer varies in thickness from about 0.05 to about 2 micrometers (µm). In a specific embodiment, oxide layer is about 0.5 micrometers (µm).

The substrate may be oxidized thermally in air at a temperature of from about 100 to about 600 degrees Celsius for from about 1 to about 3 hours. In a specific embodiment, the substrate is oxidized thermally in air at about 100 to about 200 degrees Celsius for 1 hour.

FIG. 2C shows that after thermal oxidation of the insulating layer of silicon dioxide, metallic layers are deposited on top of the oxide layer. In FIG. 2C there are two metallic layers deposited on a silicon dioxide layer in a stacked arrangement.

After photolithography or electron beam lithography, the electrode is patterned using known methods such as, for example, wet or dry etching as illustrated in FIGS. 2D. Alternatively, a lift-off technique can be used, in which patterning is achieved by the dissolution of photore sist followed by deposition of a metallic layer of photolithographically or e-beam lithographically defined photore sist layer.

The physical gap between the electrodes varies in embodiments from about 100 nanometers (nm) to about 100 micrometers (µm). In a specific embodiment, the gap varies from about 10 to about 50 µm.

In embodiments, a sol-gel process is used for coating the indium oxide (In₂O₃) doped tin oxide (SnO₂) as shown in FIG. 2E. The chemistry of the nanoparticles is listed in FIG. 3 (XPS spectrum). In addition to tin oxide, other oxides, such as, for example, titania (TiO₂), iron oxide (Fe₂O₃), and zinc oxide (ZnO) are suitable for embodiments of the present invention.

The sol-gel process is a versatile solution process for making ceramic and glass materials. In general, the sol-gel process involves the transition of a system from a liquid “sol” (mostly colloidal) into a solid “gel” phase. Applying the sol-gel process, it is possible to fabricate ceramic or glass materials in a wide variety of forms: ultra-fine or spherical shaped powders, thin film coatings, ceramic fibers, microporous inorganic membranes, monolithic ceramics and glasses, or extremely porous aerogel materials. The starting materials used in the preparation of the “sol” are usually inorganic metal salts or metal organic compounds such as metal alkoxides. In a typical sol-gel process, the precursor is subjected to a series of hydrolysis and polymerization reactions to form a colloidal suspension, or a “sol”. Further processing of the “sol” enables one to make ceramic materials in different forms. Thin films can be produced on a piece of substrate by spin-coating or dip-coating. When the “sol” is cast into a mold, a wet “gel” will form. With further drying and heat-treatment, the “gel” is converted into dense ceramic or glass articles. If the liquid in a wet “gel” is removed under a supercritical condition, a highly porous and extremely low density material called “aerogel” is obtained. As the viscosity
brane films allows, for the first time, fabrication of inexpen-
beam deposition, sputtering, etc. Generally, the methods
properties being monitored in the operation of the device.
present having a thickness of from about 5 to about 50 mu,
permeable membranes. For example, the thickness of the
vapor deposition, physical vapor deposition, focused ion
microemulsion and other techniques), dipping, chemical
formed over the hydrogen-sensitive film in any suitable man-
hydrogen-selective over layer is, in embodiments, thick
about 100 nm thick, more specifically from about 100 to about 500
hydrogen-selective layer has a thickness of from about 100 to about 500
nanometers. In one specific embodiment, the hydrogen-sensi-
tive thin film having thickness of 100 to 150 nanometer (nm)
is deposited followed by a hydrogen-selective layer of barium
cerate or other proton conducting membrane or hydrogen
material. In embodiments, the hydrogen-sensi-
tive polymer may comprise of platinum, palladium, gold, silver, ruthenium,
and/or alloys thereof. In embodiments, the hydrogen-sensi-
tive layer has a thickness of from about 5 to about 20 nm. The
hydrogen-selective over layer is, in embodiments, thick
enough to adequately protect the sensor from other gases in the
environment and thin enough to leave unchanged the properties being monitored in the operation of the device.
The hydrogen-selective over layer may be deposited or formed over the hydrogen-sensitive film in any suitable manner,
including spraying, solution deposition (sol-gel and microemulsion and other techniques), dipping, chemical vapor deposition, physical vapor deposition, focused ion beam deposition, sputtering, etc. Generally, the methods
described herein for formation or coating of the hydrogen-
sensitive thin film in the first instance may also be used for forming the hydrogen-selective over-layer thereon, and vice
versa.
The hydrogen-selective over-layer may be formed of any suitable material of construction, which is suitably effective to
prevent chemical reaction or sorption processes from occurring that would preclude the efficacy of the hydrogen-
sensing film for hydrogen sensing.
The selectivity exhibited by the proton conducting mem-
brane films allows, for the first time, fabrication of inexpen-
sive hydrogen sensors that can be deployed in large numbers to remotely monitor hydrogen levels over large areas. Fur-
thermore, hydrogen-selective films can operate in an indus-
trial or manufacturing environment containing trace organic vapors.
The hydrogen sensing films can be coated with materials
such as nanostructured barium cerate, strontium cerate or
other proton conducting membranes or hydrogen permeable
membranes to provide an effective barrier to the other gases in
the environment, yet enable only hydrogen to diffuse through
to the hydrogen-sensing thin film, thereby acting as a selec-
tive membrane for hydrogen in the sensor element.
The hydrogen-sensing thin film sensor element of such a
hydrogen sensor may comprise a semiconductor thin film (i)
arranged for exposure to an environment susceptible to the
circumvention or generation of hydrogen and (ii) exhibiting a
detectable change of physical property when the hydrogen
sensing film is exposed to hydrogen. Such detectable change of
physical property may comprise optical transmittivity,
electrical resistivity, electrical conductivity, electrical capaci-
tance, magneto-resistance, photoconductivity, and/or any
other detectable property change accompanying the exposure
of the thin film sensor element to hydrogen. The hydrogen
sensor may further include a detector constructed and
arranged to convert the detectable change of physical property
to a perceivable output, e.g., a visual output, auditory output,
tactile output, and/or auditory output.
The MEMS hydrogen sensor platform is then bonded using
known techniques such as, for example, wire-bonding, ball-
bonding, or flip-chip bonding as shown schematically in FIG.
2E and the cross section is shown in FIG. 4.
Wire bonding is an electrical interconnection technique
using thin wire and a combination of heat, pressure and/or
ultrasonic energy. Wire bonding is a solid phase welding
process, where the two metallic materials (wire and pad sur-
face) are brought into intimate contact. Once the surfaces are
in intimate contact, electron sharing or interdiffusion of
atoms takes place, resulting in the formation of wire bond. In
wire bonding process, bonding force can lead to material
def ormation, breaking up contamination layer and smoothing
out surface asperity, which can be enhanced by the applica-
tion of ultrasonic energy. Heat can accelerate interatomic
diffusion, thus the bond formation.
The Wire bonding process begins by firmly attaching the
backsides of a chip to a chip carrier using either an organic
conductive adhesive or a solder (Die Attach). The wires then
are welded using a special bonding tool (capillary or wedge).
Depending on bonding agent (heat and ultrasonic energy), the
bonding process can be defined to three major processes: the
microcompression bonding (T/C), ultrasonic bonding (U/S), and
thermosonic bonding (T/S), as shown in Table A1.

<table>
<thead>
<tr>
<th>Wire bonding</th>
<th>Pressure</th>
<th>Temperature</th>
<th>Ultrasonic energy</th>
<th>Wire Pad</th>
</tr>
</thead>
<tbody>
<tr>
<td>Thermo compression</td>
<td>High</td>
<td>300-500° C.</td>
<td>No</td>
<td>Au, Au</td>
</tr>
<tr>
<td>Ultrasonic</td>
<td>Low</td>
<td>25° C.</td>
<td>Yes</td>
<td>Au, Al, Au</td>
</tr>
<tr>
<td>Thermo sonic</td>
<td>Low</td>
<td>100-150° C.</td>
<td>Yes</td>
<td>Au, Au</td>
</tr>
</tbody>
</table>

The method of wire bonding that is most popular today is
gold ball bonding, a process that melts a sphere of gold on a
length of wire, bonds that down as a first bond, draws a loop
out, and then connects the wire bond (the second wedge bond)
down by means of a crescent and then reforms another bond for
the subsequent first ball bond.

Flip chip microelectronic assembly is the direct electrical
connection of face-down (hence, "flipped") electronic compo-
nents onto substrates, circuit boards, or carriers, by means of
conductive bumps on the chip bond pads. In contrast, wire
bonding, the older technology which flip chip is replacing,
uses face-up chips with a wire connection to each pad.
Flip chip components are predominantly semiconductor devices; however, components such as passive filters, detector arrays, and MEMS devices are also beginning to be used in flip chip form. Flip chip is also called Direct Chip Attach (DCA), a more descriptive term, since the chip is directly attached to the substrate, board, or carrier by the conductive bumps.

Eliminating packages and bond wires reduces the required board area by up to approximately 95%, and requires far less height. Weight can be less than approximately 5% of packaged device weight. Flip chip is the simplest minimal package, smaller than Chip Scale Packages (CSP's) because it is chip size.

There are three stages in making flip chip assemblies: bumping the die or wafer, attaching the bumped die to the board or substrate, and, in most cases, filling the remaining space under the die with an electrically non-conductive material. The conductive bump, the attachment materials, and the processes used differentiate the various kinds of flip chip assemblies.

In embodiments, a ultra-violet light source is assembled facing the MEMS based hydrogen sensor. The UV light source is used for burning organic contaminants from the MEMS device and as a light source. This decontamination produces a clean sensor surface suitable for sensing hydrogen at room temperature. The UV source is turned off during hydrogen sensing tests and the sensor detects hydrogen very efficiently at room temperature. (FIG. 5 shows a giant room temperature sensitivity).

The MEMS based hydrogen sensor device may be connected by a signal transmission line to the central processor unit, which may comprise microprocessor or computer control elements for actuation, monitoring and control of the hydrogen sensor device. The central processor unit processes the signal carried by signal transmission line, and produces an output signal that is transmitted in signal transmission line to an output device, which produces an output that is indicative of the presence or absence of hydrogen in the environment to which the sensor is exposed.

The output of the central processor unit may include any perceivable output, such as auditory output, visual output, tactile output (as for example when the hydrogen sensor apparatus is adapted to be worn on the body of a user), and the central processor unit comprises a vibrator imparting vibratory sensation to the user's body when hydrogen is detected in the environment, such as may be useful in environments where auditory or visual outputs are not readily perceivable.

In lieu of producing an output which is perceivable, the central processor unit may be programmed to actuate means for eliminating hydrogen from the environment being monitored, as for example with a sweep gas flushing operation to purge the environment of the hydrogen gas.

In embodiments, the MEMS based hydrogen sensor operates in wide temperature of from about 15 degrees Celsius to about 650 degrees Celsius.

Example 1

MEMS Based Sensor Platform Fabrication

A 3" Si (100) wafer is used as a substrate for sensor fabrication. On top of the substrate 0.1 to 1 mm of silicon oxide is thermally grown. Alternatively, oxide can be deposited by other methods such as CVD or sputtering. Oxide is used as an insulation layer. Alternatively, glass substrate can be used. 10-50 nm-thick chromium (Cr) or titanium (Ti) and 100-500 nm-thick gold (Au) films are deposited by thermal or e-beam evaporation on top of the oxide layer or on the glass substrate. The interdigitated electrodes were patterned on the substrate using photolithography and wet chemical etching. Positive or negative photoresist was used for patterning the electrodes. Alternatively, a lift-off method is used to pattern the electrodes. The gap between electrodes is kept in the range of 10 min to 50 nm. After sol-gel coating of In2O3 doped-SnO2 thin films over the sensor platform, in which coating process is outlined in the following section, the MEMS sensor platform is wire-bonded to a plastic or ceramic package as illustrated in FIG. 2F schematically.

Example 2

Tin(IV)-isopropoxide (Sn[(O)C3H7]4) (10 w/v %) in iso-propanol (72 vol. %) and toluene (18 vol. %) and indium(III)-isopropoxide (ln[(O)C3H7]3) are prepared and mixed. Small glass substrates (1 cmx1 cm) are cut from the Pyrex glass slides for the dip-coating experiments. The tin oxide (SnO2) semiconductor thin film coating, in doped and undoped forms, is combined on the Pyrex glass (silica) slides (substrate) and fabricated via sol-gel dip-coating technique. The glass substrates are ultrasonically cleaned, first in acetone and then in iso-propanol. The pre-cleaned substrates are dipped in the solution of tin-isopropoxide in iso-propanol and toluene, having a concentration of 0.23 M of tin-isopropoxide, using a dip-coater with a withdrawal speed of 150 cm/min. Indium (III)-isopropoxide is dissolved in this solution to obtain thin films of SnO2 containing 6.5 mol % In2O3. The gel films formed are dried at a temperature of from about 150 to about 200 degrees Celsius for about 1 hour in air. The substrates are then dip-coated again using the same solution under similar conditions and dried again at from about 150 to about 200 degrees Celsius for about 1 hour in air. A thin layer of Platinum is sputtered for about 10 sec on the dried thin films using a sputter coater. The dried and Pt-sputtered gel films are then fired at a temperature of from about 400 to about 600 degrees Celsius for about 1 hour, and then cooled to room temperature (20° C.) inside the furnace.

Example 3

Fabrication of a MEMS Based Hydrogen Sensor

Micro structures were fabricated through a commercial foundry and the as-received die was micro machined using XeF2 as a silicon selective etchant. A photolithographic lift-off process was used in combination with physical vapor deposition (PVD) to sequentially deposit a gold/titanium thin film overlaid by a indium oxide doped tin oxide on the suspended micro structures. The resulting devices were wire bonded and packaged in 40 pin ceramic chip carriers. The fully packaged chips were placed in a sealed chamber, and electrical contact made via feedthroughs into the chamber. Nitrogen and hydrogen were introduced into the chamber and controlled with mass flow controllers and actuated valves. The resistance of the sensing film was measured periodically with a digital multimeter and logged on a desktop computer.

While the invention has been described, disclosed, illustrated and shown in various terms of certain embodiments or modifications which it has presumed in practice, the scope of the invention is not intended to be, nor should it be deemed to be, limited thereby and such other modifications or embodiments as may be suggested by the teachings herein are fur-
ticularly reserved especially as they fall within the breadth and scope of the claims here appended.

We claim:

1. A method of fabricating a hydrogen sensor on a hydrogen sensor platform consisting of:
   thermally growing a silicon oxide layer on a silicon wafer substrate to form a hydrogen sensor platform;
   depositing a metallic film on top of the silicon oxide layer;
   patterning the metallic film to form on the substrate interdigitated electrodes having an electrode gap of about 20 µm;
   coating an indium oxide doped tin-oxide thin film over the hydrogen sensor platform with deposited and patterned metallic film; and
   coating the indium oxide doped tin-oxide film with a layer of barium cerate or strontium cerate or other proton conducting membrane.

2. The method according to claim 1, wherein said metallic film comprises:
   • chromium film; and
   • gold film overlaying said chromium film.

3. The method according to claim 1, wherein said hydrogen sensor platform is wire-bonded to a plastic or ceramic package.

4. The method according to claim 1, wherein hydrogen sensor platform is ball-bonded to a plastic or ceramic package.

5. The method according to claim 1, wherein hydrogen sensor platform is flip-chip bonded to at least one of a substrate, circuit board and carrier by means of conductive bumps.

6. The method according to claim 3 wherein a UV light source is directed toward the plastic or ceramic package.

7. The method of claim 1, wherein said metallic film is selected from the group consisting of palladium, platinum, iridium, silver, gold, cobalt, and alloys thereof.

8. The method of claim 1, wherein the indium oxide doped tin-oxide thin film is doped with a dopant.

9. The method of claim 1, wherein the dopant is selected from the group consisting of tin-oxide, iron-oxide, titania, zinc oxide, and aluminum-oxide.

10. A method of fabricating a hydrogen sensor on a hydrogen sensor platform consisting of:

   depositing an insulating layer on a silicon wafer substrate to form a hydrogen sensor platform;
   depositing a metallic film on top of the insulating layer;
   patterning the metallic film to form on the substrate interdigitated electrodes having an electrode gap of approximately 0.1 µm to approximately 20 µm;
   coating a hydrogen-sensing thin film over the hydrogen sensor platform with the deposited and patterned metallic film; and,
   coating the hydrogen-sensing thin film with a hydrogen-selective thin film membrane.

11. The method according to claim 10, wherein the depositing of the insulating layer is by at least one of chemical vapor deposition (CVD) and sputtering.

12. The method according to claim 10, wherein said metallic film comprises:
   • chromium film; and
   • a gold film overlaying said chromium film.

13. The method according to claim 10, wherein said hydrogen sensor platform is wire-bonded to a plastic or ceramic package.

14. The method according to claim 10, wherein said hydrogen sensor platform is ball-bonded to a plastic or ceramic package.

15. The method according to claim 10, wherein said hydrogen sensor platform is flip-chip bonded to at least one of a substrate, circuit board and carrier by means of conductive bumps.

16. The method according to claim 13 wherein a UV light source is directed toward the plastic or ceramic package.

17. The method of claim 10, wherein said metallic film is selected from the group consisting of palladium, platinum, iridium, silver, gold, cobalt, and alloys thereof.

18. The method of claim 10, wherein the hydrogen sensing thin film is 6.5 mole % indium oxide doped tin oxide.

19. The method of claim 10, wherein the hydrogen-selective thin film membrane is approximately 5 nm to approximately 50 nm thick and is selected from the group consisting of barium cerate, strontium cerate, or any other proton conducting membrane.

* * * * *