

1 **A review of global satellite-derived snow products**

2

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15

16 **Abstract**

17 Snow cover over the Northern Hemisphere plays a crucial role in the Earth's hydrology  
18 and surface energy balance, and modulates feedbacks that control variations of global  
19 climate. While many of these variations are associated with exchanges of energy and  
20 mass between the land surface and the atmosphere, other expected changes are likely to  
21 propagate downstream and affect oceanic processes in coastal zones. For example, a large  
22 component of the freshwater flux into the Arctic Ocean comes from snow melt. The  
23 timing and magnitude of this flux affects biological and thermodynamic processes in the

1 Arctic Ocean, and potentially across the globe through their impact on North Atlantic  
2 Deep Water formation.

3

4 Several recent global remotely sensed products provide information at unprecedented  
5 temporal, spatial, and spectral resolutions. In this article we review the theoretical  
6 underpinnings and characteristics of three key products. We also demonstrate the  
7 seasonal and spatial patterns of agreement and disagreement amongst them, and discuss  
8 current and future directions in their application and development. Though there is  
9 general agreement amongst these products, there can be disagreement over certain  
10 geographic regions and under conditions of ephemeral, patchy and melting snow.

11

12

13 Keywords: snow; remote sensing

14

1 **1. Introduction**

2

3 Snow covers a considerable portion of Northern Hemisphere lands during winter. It is the  
4 component of the cryosphere with the largest seasonal variation in spatial extent. In fact  
5 accumulation and rapid melt are two of the most dramatic seasonal environmental  
6 changes of any kind on the Earth's surface (Gutzler and Rosen 1992, Robinson and Frei  
7 2000, Robinson et al. 1993). In the Southern Hemisphere, outside of Antarctica and its  
8 surrounding ice shelves and sea ice, snow is generally limited to smaller regions such as  
9 the Andes, Patagonia and the southern Alps of New Zealand (Foster et al. 2008). On  
10 decadal time scales, snow variations over Northern Hemisphere lands have also been  
11 considerable (Barry et al. 1995, Brown 2000, Brown and Braaten 1998, Derksen et al.  
12 2004, Frei et al. 1999, Mote 2006, Mote et al. 2005, Ye et al. 1998), with declines in  
13 spring associated with warmer conditions (Brown et al. 2010, Groisman et al. 1994, IPCC  
14 2007, Leathers and Robinson 1993). Recent reports on changes in the Arctic environment  
15 cite snow as one of the critical variables (ACIA 2004, AMAP 2011). The expectation  
16 during the 21<sup>st</sup> century is that changes will be increasingly dramatic (Frei and Gong 2005,  
17 Raisanen 2007, Ye and Mather 1997) and spatially and temporally complex (Brown and  
18 Mote 2009, Nolin and Daly 2006).

19

20 While large scale changes in snow cover are useful as indicators of climatic variations,  
21 snow also affects other components of the Earth system at a variety of scales. By virtue  
22 of its radiative and thermal properties which modulate transfers of energy and mass at the  
23 surface-atmosphere interface (Zhang 2005), snow affects the overlying atmosphere

1 (Barry 2002, Barry et al. 2007, Cohen 1994, Ellis and Leathers 1999, Mote 2008, Walsh  
2 1984) and thereby plays an important role in the complex web of feedbacks that control  
3 local to global climate. For example, because of the high albedo of snow, its presence can  
4 change the surface energy balance over land and ice and therefore affect climate (i.e. the  
5 snow-albedo feedback). Snow also modulates the hydrologic cycle (Dyer 2008, Graybeal  
6 and Leathers 2006, Leathers et al. 1998, Todhunter 2001); influences ecosystem  
7 functioning (Jones et al. 2001); and is a significant resource for many mid latitude  
8 populations and for populations whose water is derived from mountainous and northerly  
9 cold regions (Barnett et al. 2005, Barry et al. 2007). Snow observations are critical for the  
10 validation of climate models (Foster et al. 1996, Frei et al. 2003, Frei et al. 2005, MacKay  
11 et al. 2006, Roesch et al. 1999).

12

13 With regards to the freshwater flux to the ocean, the role of snow is to modulate seasonal  
14 timing, and in some cases the amount, of discharge into the oceans. While this can affect  
15 coastal systems across mid-latitudes, of particular relevance is the fresh water flux into  
16 the Arctic basin. The drainage area into the Arctic Ocean is ~1.5 times the surface area of  
17 the Arctic Ocean itself (Peterson et al. 2002) and river runoff is the largest source of  
18 freshwater input into the Arctic basin (Arnell 2005, Miller and Russell 2000). Much of  
19 Arctic precipitation is derived from snow fall, and much of the river runoff is derived  
20 from snow melt. During the past century, both high latitude precipitation (Zhang et al.  
21 2007) and river runoff to the Arctic basin have increased; both are expected to increase  
22 further in a warming climate (Peterson et al. 2002), although the rates of change and  
23 relative impacts on ocean circulation vary spatially (Rennermalm et al. 2007).

1

2 The studies described above do not include all the possible nonlinear feedbacks in which  
3 snow plays a role in the Arctic environment (Hinzman et al. 2005). For example, due to  
4 the insulating effect of snow cover, changes in the timing of snow onset or disappearance,  
5 or changes in the amount of snow, may influence the state of the underlying permafrost,  
6 which has been warming for decades (Romanovsky et al. 2010) and which is expected to  
7 deteriorate during this century (Lawrence and Slater 2005) and may further increase the  
8 freshwater flux. Thawing permafrost may also result in a significant release of carbon to  
9 the atmosphere as the result of microbial decomposition of currently frozen organic  
10 carbon (Schuur et al. 2008). According to Betts et al. (2000) the expected expansion of  
11 the boreal forest may lead to both negative feedbacks (an additional carbon sink) and  
12 positive feedbacks (an albedo decrease) on global climate, and the net effect will be a  
13 positive feedback with increased warming. The feedbacks between snow, permafrost, and  
14 freshwater flux to the Arctic Ocean associated with these processes are poorly understood  
15 (Francis et al. 2009, Rawlins et al. 2010).

16

17 While an increased freshwater flux to the Arctic has potential effects on thermodynamic  
18 and ecological processes in the coastal zone, perhaps most importantly such increases  
19 have been shown in the past to diminish or completely halt the formation of North  
20 Atlantic Deep Water (NADW) (Rahmstorf 2000). This occurs because freshwater export  
21 to the North Atlantic Ocean, the region of NADW formation, decreases surface water  
22 density. Model simulations suggest that the magnitude of expected runoff changes during  
23 this century may approach critical thresholds for NADW formation (Arnell 2005, Miller

1 and Russell 2000, Peterson et al. 2002). In a recent study, NADW formation as well as  
2 permafrost degradation and changes to the tundra and boreal forest ecosystems (all of  
3 which can be affected by snow, and all of which can affect the freshwater flux to the  
4 ocean) have been listed among the potentially critical components of the Earth system  
5 that may be in danger of approaching “tipping points” (Lenton et al. 2008). Thus,  
6 accurate monitoring of high latitude snow remains an essential goal.

7  
8 Because of the large extent of terrestrial snow cover and the difficulties in obtaining  
9 ground measurements over cold regions, remote sensing represents an important tool for  
10 studying snow properties at regional to global scales. In recent years, advances in satellite  
11 capabilities, as well as in algorithm development, have led to improved monitoring of  
12 snow across the globe. The purpose of this article is to review the current generation of  
13 satellite-derived global snow observations that has become available during the first  
14 decade of the twenty first century, with emphasis on land surfaces of the Northern  
15 Hemisphere. Theoretical considerations for the remote sensing of snow, and key products  
16 are discussed.

## 17 18 **2. Theoretical Background**

19  
20 Due to the nature of interactions between snow cover and electromagnetic radiation of  
21 different frequencies, snow can be distinguished from other terrestrial surfaces using  
22 satellite observations based on a number of different active and passive techniques  
23 (Dozier 1989, Nolin 2010). The two types of instruments used for monitoring global

1 scale snow variations rely on either (1) a combination of the visible and infrared, or (2)  
2 microwave, portions of the electromagnetic spectrum (Hall et al. 2005, Matzler 1994,  
3 Rango et al. 2000, Scherer et al. 2005, Schmugge et al. 2002). These methods are limited  
4 by a number of factors, such as clouds, forest cover fraction, terrain heterogeneity and  
5 precipitation. For example, interpretation of visible and infrared as well as passive  
6 microwave images can be difficult where complex terrain causes considerable spatial  
7 variation within each remotely-sensed footprint of snow depth, surface characteristics,  
8 and satellite viewing angles. Nevertheless, products based on these observations have  
9 been vital for monitoring snow and for our understanding of the role of snow in the Earth  
10 system. Though global active microwave data (e.g., QuikSCAT) can also be used to  
11 study snow extent and depth at relatively large spatial scale (Tedesco and Miller 2007a,  
12 b), data are available only from 1999 through 2009 (when the satellite failed well past its  
13 expected lifetime; see <http://www.jpl.nasa.gov/news/news.cfm?release=2009-175>  
14 downloaded November 2011). In contrast, passive microwave data have been available  
15 since the late 1970s, and continue to be available. At regional scales, airborne data can  
16 also be collected before and after the snow falls to study the attenuation introduced by the  
17 snow pack on naturally emitted gamma radiation (Carroll 1987). However, the data  
18 collected with this method have low temporal resolution (seasonal scale) and cannot be  
19 used for global scale studies. Consequently, we focus our analysis on snow parameters  
20 estimated by means of visible and infrared and passive microwave sensors.

21

## 22 *2.1 Visible and Near-Infrared*

23

1 Snow extent (i.e. presence or absence of snow, regardless of snow amount) is, in many  
2 circumstances, relatively straightforward to observe using visible observations because of  
3 the high albedo of snow (up to ~ 80 % or more in the visible part of the electromagnetic  
4 spectrum) relative to most land surfaces. However, limitations exist. First, visible  
5 imagery is limited to that portion of the surface illuminated by sunlight; thus darkness  
6 and low illumination are problematic. Second, clouds impede visible evaluation in two  
7 ways. All but the thinnest clouds reflect a significant portion of visible radiation,  
8 preventing any visible radiative information about the surface from reaching the satellite.  
9 And, because the albedos of clouds and snow are often similar, the discrimination  
10 between cloud-covered and snow covered surfaces can be difficult. However, near-  
11 infrared bands can be used to distinguish between snow and most clouds because the  
12 near-infrared reflectance of most clouds is high while the near-infrared reflectance of  
13 snow is low.

14

15 Third, vegetation can obstruct visible and infrared information about snow from reaching  
16 the satellite sensor. Forest canopies protrude above the snow pack, lowering the surface  
17 albedo (Robinson and Kukla 1985) and partially or completely obscuring the underlying  
18 surface, making it difficult to determine snow extent or amount (Chang et al. 1996,  
19 Derksen 2008, Goita et al. 2003, Klein et al. 1998, Nolin 2004).

20

21 Lastly, surface heterogeneity can play a role the interpretation of visible and infrared  
22 imagery in a number of ways. Of particular relevance to the monitoring of high latitude  
23 snow is the presence of numerous frozen lakes in Arctic regions, which may contribute to

1 the overestimation of snow covered area from visible and infrared based imagery during  
2 periods when lakes remain frozen after the snow has melted on adjacent land surfaces  
3 (Derksen et al. 2005a, Frei and Lee 2010), at least when high resolution land surface data  
4 sets are not used to filter out the signal from lake surfaces. Passive microwave based  
5 estimates of SWE may be underestimated due to the presence of lakes (Derksen et al.  
6 2005a, Rees et al. 2006). On the other hand, surface heterogeneity may assist in the  
7 interpretation of snow-covered versus snow-free ground, and of snow-covered versus  
8 cloud-covered scenes, when trained analysts are mapping snow extent using visible  
9 imagery.

10

## 11 *2.2 Passive microwave*

12

13 Because snow grain dimensions can be similar to microwave wavelengths, snow is  
14 efficient at scattering the microwave radiation naturally emitted from the Earth's surface  
15 (Matzler 1994). Therefore, microwave emission from a snow covered surface is  
16 diminished relative to a snow-free surface, and the presence of snow can frequently be  
17 identified (Chang et al. 1976, Grody 2008, Hall et al. 2005, Matzler 1994, Tait 1998,  
18 Tedesco and Kim 2006). Furthermore, because under ideal circumstances the amount of  
19 scattering is proportional to the number of snow grains, microwave instruments offer the  
20 possibility of estimating the mass per unit area of water in the snow pack, which is often  
21 measured as snow water equivalent (SWE). In contrast to visible and infrared, passive  
22 microwave does not depend on the presence of sunlight and thus provides an alternative  
23 at high latitudes; and, passive microwave is largely (but not completely) transmitted

1 through non-precipitating clouds, offering the potential to estimate snow cover under  
2 many cloudy conditions that preclude visible and infrared observations. In practice,  
3 research using passive microwave exploits the fact that microwave scattering by ice  
4 crystals is frequency-dependent: higher frequencies within the microwave portion of the  
5 spectrum are scattered more efficiently than lower frequencies, enabling the use of two or  
6 more frequency bands to estimate SWE (Chang et al. 1987, Derksen 2008, Derksen et al.  
7 2005b, Grody and Basist 1996). Other methods have also been evaluated such as one  
8 based on the inversion of a snow emission model (e.g., Pulliainen and Hallikainen 2001).  
9 Clifford (2010) provides a review of global estimates of snow water equivalent from  
10 passive microwave.

11

12 Limitations to the monitoring of snow using passive microwave sensors are due to a  
13 variety of factors. One major limitation is the presence of liquid water in the snow pack,  
14 the microwave emission from which masks the snow signal and inhibits the ability of  
15 microwave sensors to detect wet snow. Also, because of the relatively weak microwave  
16 signal emitted by terrestrial surfaces, microwave sensor footprints are necessarily large  
17 (~25 km). Uncertainties in snow depth and SWE estimates are associated with the  
18 physical structure of snow packs (ice lenses, grain size variations and vertical  
19 heterogeneity) which vary in space (Chang et al. 1976, Sturm et al. 1995) and time  
20 (Langham 1981) and can alter the scattering and emission characteristics of the snow  
21 pack. Snow pack metamorphosis, which in the Arctic region typically results in a layer of  
22 depth hoar (with large crystal size) near the bottom of the pack, results in more efficient  
23 microwave scattering. Thus, a signal change measured at the satellite sensor due to snow

1 metamorphosis can mimic a signal change due to a change in SWE. Vegetation in and  
2 above the snow pack emits microwave radiation, and can confound any detection  
3 algorithm (Chang et al. 1996, Foster et al. 1997, Tedesco et al. 2005).

4

5 Finally, as a snow pack reaches a certain critical depth the relationship between snow-  
6 amount and MW brightness temperature reverses (Derksen 2008, Markus et al. 2006,  
7 Matzler 1994, Schanda et al. 1983). When SWE exceeds ~150 mm emission by the snow  
8 pack of microwave band radiation is greater than scattering, resulting in a positive  
9 relationship between SWE and brightness temperature. This is an additional source of  
10 uncertainty in SWE retrievals for deep snow packs.

11

### 12 *2.3 Remote sensing of snow in complex terrain*

13 Some of the difficulties inherent in the interpretation of remotely sensed images are  
14 exacerbated in regions with complex terrain (Dozier 1989). Due to variability of slope,  
15 aspect, and land cover, the local solar illumination angle varies within one satellite  
16 footprint. In fact, due to co-registration differences between an image and a digital  
17 elevation model, illumination angles, and therefore reflectance characteristics, are often  
18 unknown. To address such issues, Painter et al. (2009) developed the MODSCAG model,  
19 which estimates mean grain size and fractional snow cover from MODIS data using  
20 linear spectral mixture analysis and a library of reflectance characteristics of different  
21 surface types. This model has relatively small errors, and could potentially be applied  
22 globally, but so far has been validated mostly in regions of complex terrain.

23

1 A recent study of different algorithms for estimating SWE from passive microwave  
2 radiances in a basin with complex terrain in the Canadian Rockies finds that the  
3 traditional algorithms which are based on brightness temperature differences in difference  
4 wavelength intervals (as discussed above) are less accurate than Artificial Neural  
5 Network (ANN) techniques which can be trained on observations from surface stations  
6 (Tong et al. 2010a). Unfortunately, due to the limited distribution of stations for training  
7 the ANN in their test region, they are unable to accurately estimate spatial variations of  
8 SWE. Tong and Velicogna (2010) and Tong et al. (2010b), using surface station  
9 observations and MODIS imagery across the Mackenzie River Basin, determine that the  
10 minimum or threshold SWE value estimated from passive microwave observations that  
11 can be used to determine the presence / absence of snow varies from sub-basin to sub-  
12 basin, depending on topography and vegetation cover. Nevertheless they find useful  
13 information in remotely sensed SWE values for hydrologic monitoring. As these studies  
14 indicate, the estimation of snow characteristics in complex terrain from remotely sensed  
15 imagery is an important and cutting edge field of study. At this time, these techniques  
16 have not been incorporated into global products, and are not addressed further in this  
17 paper.

18

#### 19 *2.4 Comparison and evaluation of products*

20

21 When two products disagree, which is “correct?” Is either one of them “correct?” Two  
22 key impediments to a conclusive evaluation are that there is no perfect “ground truth,”  
23 and that the answer depends on spatial scale. The most obvious method of testing the

1 veracity of remotely sensed (or other gridded) products is by comparison to surface  
2 reference observations. However, there exists considerable contrast between surface, or  
3 *in situ*, and remote snow observations with regards to the snow pack properties that can  
4 be measured, their spatial and temporal resolutions and domains, and the methods  
5 employed to make measurements (Brown and Armstrong 2008, Goodison et al. 1981).

6

7 Even in regions with surface observations, validation may be difficult because of the  
8 contrasting spatial scales of surface and remotely sensed observations (Brubaker et al.  
9 2005, Chang et al. 2005). Brubaker et al. (2005) discuss the difficulties in comparing  
10 point measurements to spatially integrated satellite retrievals, especially in areas of sparse  
11 station networks, which are typically at high elevations and northerly regions (exactly the  
12 areas where snow is most prevalent). They find that there is no single accepted method to  
13 perform validation of remotely sensed snow products. Chang et al. (2005) provide an  
14 informative review of how varying station densities and different satellite footprints are  
15 not equally spatially representative, and how the differences can complicate evaluations  
16 and comparisons of different products. They employ geostatistical techniques, as  
17 suggested by Kelly et al. (2004), to quantitatively define the spatial density of station  
18 observations required to provide sufficient information for validation studies. MODIS has  
19 been found to compare well with station based observations as well as with the National  
20 Operational Hydrologic Remote Sensing Center products (Hall and Riggs 2007), but  
21 Riggs et al. (2005) show that even between different versions of MODIS snow products,  
22 analyses at different spatial resolutions can provide conflicting results in some cases, due  
23 to both the resolution differences and the averaging method.

1

2 Despite the inherent difficulties, comparative studies to date have drawn some useful  
3 conclusions (Armstrong and Brodzik 2001, Basist et al. 1996, Bitner et al. 2002, Brown  
4 et al. 2007, Brown et al. 2010, Derksen et al. 2003, Drusch et al. 2004, Foster et al. 1997,  
5 Mialon et al. 2005, Mote et al. 2003, Romanov et al. 2002, Savoie et al. 2007, Tait and  
6 Armstrong 1996). For example, evaluations of NOAA visible and infrared versus passive  
7 microwave products find more disagreement during fall and spring than during mid-  
8 winter, with particular differences under forest canopies, over complex terrain, in areas of  
9 persistent clouds, patchy snow, and wet snow (Armstrong and Brodzik 2001, Basist et al.  
10 1996). Over the Tibetan Plateau these products often disagree year-round (Armstrong and  
11 Brodzik 2001, Savoie et al. 2007). Several recent studies identify differences between  
12 remotely sensed products and surface observations over North America during the spring  
13 ablation season (Brown et al. 2007, Brown et al. 2010, Frei and Lee 2010).

14

### 15 **3. Snow Products**

16

17 A number of digital products that are based on remote observations are available. The  
18 two visible and infrared based suites of products that are most widely used for large-scale  
19 climate research are from: (1) *the Interactive Multisensor Snow and Ice Mapping System*  
20 (IMS) (section 3.1) and (2) the suite of products derived from *the Moderate Resolution*  
21 *Imaging Spectroradiometer* (MODIS) (section 3.2). IMS is the most recent version of a  
22 product that dates back to the 1960s (Matson and Wiesnet 1981). IMS mapping of snow  
23 extent has relied primarily on visible and near infrared imagery, but includes data and

1 information from a number of sources. As discussed in more detail below, the key feature  
2 that distinguishes IMS from other products is human involvement in the analysis, which  
3 is required for operational purposes.

4

5 The MODIS instrument, which is used to observe a number of geophysical variables  
6 including snow, flies on NASA's Earth Observing System (EOS) Terra satellite,  
7 launched in 1999. A near-twin MODIS instrument is also flying on board the Aqua  
8 platform, which was launched in 2002 (Aqua and Terra have afternoon and morning  
9 equatorial crossing times, respectively). Aqua also hosted the Advanced Microwave  
10 Scanning Radiometer - Earth Observing System (AMSR-E) until its failure in October  
11 2011. AMSR-E measured the naturally emitted radiation in the microwave region at 5  
12 different frequencies (6.9, 10.7, 18.7, 23.8, 36.5 and 89 GHz) at both vertical and  
13 horizontal polarizations.

14

15 The IMS and MODIS snow algorithms both rely primarily on near-polar orbiting  
16 satellites, from which daily images are available at high latitudes. Other algorithms that  
17 have been suggested (Romanov et al. 2003, Siljamo and Hyvarinen 2011) rely on  
18 geostationary satellites, which have the advantage of higher temporal resolution, but have  
19 poor spatial resolution.

20

### 21 *3.1 visible and near infrared based products*

22

#### 23 *3.1.1 The Interactive Multisensor Snow and Ice Mapping System (IMS)*

1

2 The data set that has historically been the most widely used for the operational mapping  
3 and climatological analysis of large-scale snow extent (not depth or water equivalent)  
4 was produced by the US National Oceanic and Atmospheric Administration (NOAA)  
5 National Environmental Satellite and Data Information Service (NESDIS), but has been  
6 transferred to the National Ice Center (NIC), which is jointly supported by NOAA, the  
7 US Navy, and the US Coast Guard. This product has been based primarily on visible and  
8 near infrared observations, and covers the period from late 1998 to present (Ramsay  
9 1998), with the precursor maps beginning in 1966, constituting the longest remotely  
10 sensed environmental time series that has been derived in a *near-consistent* fashion  
11 (Helfrich et al. 2007, Matson and Wiesnet 1981, Robinson et al. 1993). The term *near-*  
12 *consistent* is used because, due to changing operational requirements and evolving  
13 technical capabilities, this product has undergone, and continues to undergo,  
14 improvements and refinements (Helfrich et al. 2007, Ramsay 1998, 2000) as summarized  
15 briefly here. The two reasons for this product's importance - as operational input into  
16 atmospheric forecast models and as a long-term climatic record - are also discussed.

17

18 Although a number of improvements and corrections in the production of the NOAA  
19 product occurred in the earlier years, the biggest methodological change was  
20 implemented in the late 1990s. Until that time, NOAA snow maps were produced on a  
21 weekly basis by trained meteorologists who would visually interpret photographic copies  
22 of visible band imagery, and manually produce maps that would subsequently be  
23 digitized with spatial resolution between 150 km and 200 km. In 1997 NOAA began

1 producing snow maps using the IMS, with improved spatial (24 km) and temporal (daily)  
2 resolutions. IMS is operated by trained analysts who produce a daily digital product  
3 utilizing Geographic Information System technology and incorporating a variety of, and  
4 an ongoing expansion of, technological capabilities as well as sources of information.  
5 Since 1999, when weekly manual mapping was discontinued, daily IMS maps have been  
6 produced (Ramsay 1998, Robinson et al. 1999). Technological advancements since 1999  
7 have led to even higher resolution (4 km) snow mapping (Helfrich et al. 2007).

8

9 IMS produces estimates of snow extent across the globe every day, regardless of the  
10 presence of clouds. This is possible primarily for two reasons. First, analysts use sources  
11 of information other than visible and near infrared imagery. Second, because IMS  
12 analysts can loop through sequential images, their ability to evaluate scenes is based on  
13 an integration of information from both spatial and temporal perspectives. Thus, a key  
14 feature of the IMS product is that human judgment as to which data sources are most  
15 reliable in different conditions and regions, and as to the final evaluation of where the  
16 snow is, remains an integral part of the process, and one of the strengths of the IMS  
17 product. IMS also includes sea ice extent, which is not discussed in this report. Figure 1  
18 shows an example of a daily IMS snow map in its original projection.

19

20 It is difficult to optimize this product for both of its two main uses. Its primary purpose is  
21 to provide input to atmospheric forecast models. For this purpose, continued product  
22 improvements are advantageous. As a record for evaluating long term environmental  
23 change, however, the value of any product is diminished if methodological changes

1 (including those that provide more accurate maps) result in temporal inconsistencies in  
2 the data set that might be difficult to distinguish from actual variations in snow extent. To  
3 maintain product continuity and a viable long-term record, IMS continues to produce a  
4 coarse (24 km) resolution version of the data set. And, in collaboration with NOAA, the  
5 Rutgers University Global Snow Lab is producing a climate data record in which  
6 inconsistencies between the earlier maps and the IMS product (in addition to  
7 inconsistencies during the weekly map era) are accounted for, and can therefore be used  
8 for ongoing analyses of historical variations (Robinson and Estilow 2008).

9

### 10 *3.1.2 The Moderate Resolution Imaging Spectroradiometer (MODIS)*

11

12 The MODIS sensor measures radiation in 36 spectral bands, including the visible, near  
13 infrared, and infrared parts of the electromagnetic spectrum. The suite of MODIS snow  
14 cover products, available since 2000, are derived using a fully-automated algorithm that  
15 provides good spatial resolution (500m), cloud detection, and frequent coverage (daily at  
16 mid to high latitudes) (Hall and Riggs 2007, Hall et al. 1995, Hall et al. 2002, Riggs et al.  
17 2006). The MODIS snow-mapping algorithm uses a normalized difference between  
18 MODIS band 4 (5.45–5.65  $\mu\text{m}$ ) and 6 (1.628–1.652  $\mu\text{m}$ ) and many additional spectral  
19 and threshold tests. In forested areas the threshold is changed based on results of a  
20 canopy reflectance model, using both the Normalized Difference Vegetation Index  
21 (NDVI) and Normalized Difference Snow Index (NDSI) (Klein et al. 1998). A thermal  
22 mask is also included to remove erroneous “snow” over locations where the presence of

1 snow is considered to be implausible. See Riggs et al. (2006) and Riggs and Hall (in  
2 press) for a description of the algorithm and recent upgrades.

3

4 NASA provides a hierarchy of snow products based on MODIS observations, designed to  
5 satisfy the needs of a variety of users (<http://modis-snow-ice.gsfc.nasa.gov/>). These  
6 include a Level-2 swath product; daily and 8-day composite Level-3 tile products which  
7 are mapped onto a sinusoidal projection and available in 10 degree lat/lon tiles; as well as  
8 daily, 8-day composite, and monthly Level-3 products available in the Climate-Modeling  
9 Grid (a latitude-longitude grid) at 0.05 degree resolution (Hall et al. 2005, Hall et al.  
10 2002, Riggs et al. 2005, Riggs et al. 2006). An 8-day composite is considered useful  
11 because in many regions, particularly at high latitudes, persistent cloudiness limits the  
12 number of days available for surface observations (see results section). The Climate-  
13 Modeling Grid was developed to be useful for the evaluation of climate models and for  
14 studies at large spatial scales. Other features of the MODIS snow product suite include  
15 daily snow albedo (Klein and Stroeve 2002) and fractional snow cover (Salomonson and  
16 Appel 2004). In addition, a new cloud-gap filled product provides information on cloud  
17 persistence, and uses observations from prior days to map snow (Hall et al. 2010). Figure  
18 2 shows examples of MODIS snow cover maps in swath format (MOD10\_L2) following  
19 a major snowstorm in the northeastern United States in December 2010. The analysis  
20 presented in sections 4 and 5 of this article uses the MOD10C1 daily Level 3 global .05  
21 degree daily Climate-Modeling Grid product with a spatial resolution of ~5km.

22

1 Validation of the suite of MODIS snow cover products has been undertaken by many  
2 authors as described in Hall and Riggs (2007). These products have also been used  
3 extensively in modeling efforts, both at the regional and hemispheric scales. A  
4 bibliography of papers utilizing the MODIS snow cover products for both validation and  
5 modeling may be found at: <http://modis-snow-ice.gsfc.nasa.gov/?c=publications>.

6

### 7 *3.2 passive microwave based products*

8

9 Historical passive microwave measurements are available from the Scanning  
10 Multichannel Microwave Radiometer (SMMR) instrument (1978 through 1987), and the  
11 Special Sensor Microwave / Imager (SSM/I) instrument (1987 through present) although  
12 some compatibility issues between the two products exist, due to slight differences in the  
13 frequency bands measured, overpass time, swath width, native footprint resolution, and  
14 coverage issues related to SMMR being powered down every other day. (Armstrong and  
15 Brodzik 2001, Brodzik et al. 2007, Derksen and Walker 2003). AMSR-E, available from  
16 2002 to October 2011, provides a suite of measurements to make it spectrally compatible  
17 with both SMMR and SSM/I at higher spatial resolution (Derksen et al. 2005b, Kelly et  
18 al. 2004). Due to the inherent difficulties and regional variations in the interpretation of  
19 passive microwave signals, the production of a data set that is consistently accurate  
20 across all Northern Hemisphere regions requires either (1) a physical approach, which  
21 includes robust representations of snow pack processes and their parameterization in  
22 retrieval schemes (Pulliainen and Hallikainen 2001), or (2) a regional approach, which  
23 includes regionally-tuned algorithms (Foster et al. 1997) that statistically represent

1 regional snow pack processes but which are not applicable in different snow  
2 accumulation regimes. The physical approach is very challenging yet has the potential of  
3 being widely applicable as our knowledge of, and ability to model, regional snow pack  
4 processes improves, while the statistical approach is applicable only in the few regions  
5 for which retrieval schemes have been calibrated.

6

7 The global AMSR-E SWE product suite (Tedesco et al. 2011 updated) consists of daily,  
8 pentad (five-day) maximum and monthly average SWE estimates that together comprise  
9 the only NASA satellite-based SWE product available to the scientific community. As an  
10 example, Figure 3 shows the snow depth obtained from the AMSR-E product for January  
11 30<sup>th</sup>, 2005.

12

13 The AMSR-E SWE operational algorithm takes advantage of several AMSR-E channels that  
14 are unavailable from SSM/I and SMMR. Snow depth is derived as a combination of  
15 microwave brightness temperature differences at different frequencies, weighted by  
16 coefficients derived from the difference between vertical and horizontal polarizations. These  
17 coefficients replaced a previously used static coefficient to attempt to capture the spatio-  
18 temporal variability of parameters such as grain size (Kelly 2009, Kelly et al. 2003, Tedesco  
19 and Narvekar 2010). The algorithm uses a spatially varying but temporally static map of  
20 snow density.

21

22 Environment Canada (<http://ccin.ca/cms/en/socc/snow/swe/currentSnow.aspx>) also  
23 produces a regional passive microwave SWE product for central Canada, including the  
24 Prairies and part of the boreal forest back to 1978. Until December 1999, this product

1 relied on a single algorithm that was calibrated for the prairies region (Goodison and  
2 Walker 1995). Since that time algorithms that correct for the effects of different forest  
3 types (Derksen 2008, Goita et al. 2003) and the sub-Arctic tundra (Derksen et al. 2010)  
4 have been developed .

5

### 6 3.3 Combined Products

7 One promising avenue, and an area where great efforts are currently being made, is to  
8 refine our abilities to combine ground observations and models with space borne  
9 remotely sensed data. Tait et al. (2000) provide a helpful review, and describe a prototype  
10 of a fully automated product that includes station observations as well as both visible and  
11 microwave retrievals. Here we briefly review some products that include combinations of  
12 satellite, station observations, and models. While not exhaustive, it provides examples of  
13 the variety of integrative products and methods that have been produced.

14

#### 15 3.3.1 *The Canadian Meteorological Center snow product (station observations and* 16 *modeling)*

17 Snow depth from the Canadian Meteorological Center Daily Snow Depth Analysis  
18 includes a hybrid modeling / observational approach based on optimal-interpolation of  
19 daily snow depth observations from hundreds of stations globally, with snow density  
20 estimated from a simple snow pack model (Brasnett 1999). This model output is  
21 considered most dependable over regions with significant station coverage, which is  
22 generally south of 55° North, where model results are well constrained by observations.  
23 Over most of the Arctic, in contrast, where there are few observations, the analysis is

1 based mostly on model results, and is skewed towards snow depth observations at coastal  
2 locations with observing sites at open areas near airports. Snow at these sites tends to be  
3 shallower and to melt out earlier than snow in surrounding terrain. Nevertheless, this  
4 analysis is considered to be a reasonable estimate of snow depth over data-poor Arctic  
5 regions, and has been used in a number of studies (Brown and Mote 2009). Here we use  
6 CMC modeled snow depths for comparison with AMSR-E snow depths.

### 8 3.3.2 GlobSnow (satellite, station, and model)

9  
10 In 2008 the European Space Agency embarked on an effort to develop a long term snow  
11 cover data set called GlobSnow with sufficient homogeneity to be acceptable for climate  
12 change analysis. The GlobSnow product currently includes global gridded information on  
13 snow extent and SWE across the Northern Hemisphere (excluding mountainous regions)  
14 (Pulliainen 2010). The SWE product is based on the method of Pulliainen (2006). By  
15 incorporating station observations and snow pack modeling into passive microwave  
16 retrieval algorithms, the goal is to provide an accurate product useful for analyses at  
17 many different spatial scales, and for near-real time as well as climatological studies. The  
18 snow extent product is created using European Space Agency satellite visible and  
19 infrared observations (ERS-2 ATSR-2 and Envisat AATSR) based on the method of  
20 Metsamaki (2005), and will likely be available at a variety of spatial resolutions.  
21 GlobSnow is currently available (<http://www.globsnow.info/>) but is new, so there is little  
22 peer-reviewed literature on it at the time of this writing (Takala et al. 2011).

23

### 1 3.3.3 Other combined products

2 A variety of combined products have been produced globally, regionally, or for specific  
3 purposes. One widely used combined product is NOAA's National Operational  
4 Hydrologic Remote Sensing Center Snow Data Assimilation System, which operationally  
5 incorporates input from snow models, station reports, and airborne sensors to estimate  
6 daily SWE at 1 km resolution across the continental US (Carroll et al. 2001). The product  
7 by Brown et al. (2003), which employs the operational snow depth routine of the  
8 Canadian Meteorological Center model (Brasnett 1999), has been used for evaluation of  
9 climate models (Frei et al. 2005). Foster et al. (2011) recently produced a global product  
10 blending visible and infrared, passive microwave, and active microwave scatterometer  
11 data, with the intention of incorporating the most reliable aspects of each product.  
12 Derksen et al. (2004) produced a product going back to the early 20<sup>th</sup> century for the  
13 North American Prairies and Great Plains based on passive microwave and station  
14 observations. Biancamaria et al. (2011) estimated Northern Hemisphere fields of SWE  
15 based on passive microwave combined with a dynamic snow grain model. Grundstein et  
16 al. (2002) developed a research-oriented SWE climatology for the Great Plains of the  
17 United States by combining station observations with the 1-dimensional snow pack  
18 model SNTHERM (Jordan 1991). A research-oriented product based on spatial  
19 interpolation of *in situ* depth measurements over North America (Dyer and Mote 2006)  
20 has been used for process studies (Ge and Gong 2008). The QuickSCAT active  
21 microwave scatterometer has been used to estimate the timing of snow melt across  
22 Greenland (Nghiem et al. 2001) and across Arctic lands (Wang et al. 2008).  
23

#### 1 **4. Methodology to compare and contrast products**

2 In this section we describe the methodology that we use to demonstrate the regions over  
3 which the products typically differ. This analysis is not meant to provide insight into new  
4 remote sensing techniques, but rather to demonstrate the spatial extents and magnitudes  
5 of the differences between products during different seasons. The methodology employed  
6 here is designed to achieve two goals: (1) to identify regions across the Northern  
7 Hemisphere where there is agreement/disagreement between the three main products  
8 discussed here during clear days; and (2) to provide an indication of the spatial  
9 distribution of uncertainty in the AMSR-E snow depth estimates, as determined by  
10 comparison to the CMC product. In this report we show results for three months: October  
11 (a month of rapid average increase of snow area), January (the month of largest average  
12 snow area), and April (a month of rapid average decrease of snow area). For our analysis,  
13 AMSR-E SWE values are converted to depth. This is done using a fixed density mask,  
14 which is also used as part of the standard product algorithm to estimate SWE values. We  
15 reverse the process in order to convert SWE values to depth. The reprojection methods,  
16 and the methods for each goal, are discussed in more detail in sections 4.1 through 4.3.

17  
18 Many of our methods for goal 1 closely follow Frei and Lee (2010), and the reader is  
19 referred to that article for more details and justification of the methods. Note that, without  
20 independent verification, agreement between products does not guarantee that they are  
21 correct; and, that if two of the three products agree, it does not guarantee that the third  
22 product is incorrect.

1 4.1. *Reprojection procedure*

2 IMS and MOD10C1 data sets were reprojected to the EASE-Grid 25 km projection  
3 (Brodzik and Knowles 2002) (AMSR-E is already in this projection). Each EASE-Grid  
4 cell value was calculated as a binary (i.e. snow or no-snow) value. Because reprojection  
5 can introduce spurious errors at the grid-cell scale, and these errors are likely to be  
6 exacerbated in areas of variable terrain, we show no results for EASE-Grid cells within  
7 which the GTOPO 30 DEM elevation field has a standard deviation  $> 100$  meters. We  
8 also avoid drawing conclusions from individual grid points, but rather focus on results  
9 over large regions with relatively little topographic variation. The reprojection, binary  
10 snow value calculation, and terrain masking were performed according to the method of  
11 Frei and Lee (2010).

12

13 4.2. *Agreement/disagreement between IMS, MODIS, and AMSR-E snow extent*

14 Since both IMS and MOD10C1 provide binary values indicating either the presence or  
15 absence of snow (the standard MODIS products also provide fractional snow cover) but  
16 not snow depth, AMSR-E snow depths were converted to a binary value to facilitate this  
17 comparison. All AMSR-E depth estimates below 5 cm are considered snow free as that is  
18 the depth value assigned to shallow snow.

19

20 All snow extent analyses include, at each grid cell, only days with “clear” skies, and only  
21 days for which all three products have non-missing data. We use the MOD10C1 cloud  
22 mask to identify EASE-Grid cells that are mostly clear. Because MOD10C1.05 degree  
23 cells are higher resolution than the EASE-Grid and includes fractional cloud cover, they

1 can be used to estimate fractional cloud cover within each grid cell of our analysis. And,  
2 because the MOD10C1 cloud mask is considered conservative (in the sense that cloud-  
3 covered scenes are unlikely to be designated as “clear”) (Riggs and Hall 2002), we feel  
4 confident that information from cloudy days is not being retained for analysis. This is  
5 achieved by retaining for analysis, for each EASE-Grid cell, only days with >80% of  
6 MOD10C1 cells that are <20% cloud covered, for which no product is missing data. Frei  
7 and Lee (2010) present the rationale for this method and explain how the results are  
8 insensitive to reasonable values of these parameters. For each grid point on each day,  
9 either all three products agree (i.e. either snow or no-snow), or one product differs from  
10 the other two. The figures summarizing our results show, for each month, where each  
11 product disagrees with the other two products.

12

#### 13 *4.3. Comparison of AMSR-E and Canadian Meteorological Centre (CMC) snow products*

14 For passive microwave data and the CMC model, no cloud mask is invoked, so we retain  
15 for analysis all available dates. While passive microwave data are not limited by most  
16 clouds, clouds with high liquid water content can affect the comparison between  
17 spaceborne- and ground-based SWE estimates (Wang and Tedesco 2007); this issue is  
18 ignored here in order to increase the sample size.

19

20 The comparison of AMSR-E to the CMC snow product is done by comparing  
21 climatological maps (2003 – 2010). For each month, three panels are shown containing  
22 maps of AMSR-E snow depth, CMC snow depth, and the difference between the two

1 products (we calculate the difference as CMC minus AMSR-E, so that a negative  
2 difference indicates that AMSR-E overestimates snow depth with respect to CMC).

3

## 4 **5. Results**

5 In this section we show the results of our analysis, the purpose of which is to demonstrate  
6 the spatial patterns of disagreement between the data sets. We also discuss possible  
7 reasons for disagreements. In some cases these reasons may be speculative.

8

### 9 *5.1 Number of days per month available for analysis*

10 Before discussing disagreements between the products, we first show maps of the number  
11 of days per month available for comparison (figure 4) which demonstrate the problem  
12 presented by clouds. During October and January (figures 4a,b) most Arctic land surfaces  
13 are colored green or dark blue, which indicates that on average less than three (green) or  
14 three to six (dark blue) days per month are available for analysis. (In January one also  
15 sees the "ring" around the Arctic with no data associated with no solar illumination.)  
16 During spring, which tends to be less cloudy over most regions (figure 4c), one can find  
17 large portions of the Arctic with either six to nine or nine to twelve days per month  
18 available for comparison.

19

20 The vast majority of the unavailable days are caused by clouds, not by data that is  
21 missing for some other reason. Any satellite product based on visible and infrared band  
22 radiances will lack information from the surface under clouds. While passive microwave  
23 based products can provide information under most types of clouds, they are currently

1 unreliable under a number of circumstances (discussed in the next section). Considering  
2 the importance of having daily real-time information about the surface to specify  
3 boundary conditions in weather prediction models, as well to track climatological  
4 changes in snow extent, IMS, or an equivalent product that provides information for all  
5 days regardless of cloud conditions, is a necessity.

6

### 7 *5.2 Disagreement between AMSR-E and the other two products*

8 Figure 5 includes, for each month, a map showing where AMSR-E identifies snow to the  
9 exclusion of the both MOD10C1 and IMS (figures 5a,c,e) and a map showing where  
10 AMSR-E finds no snow when the other two products identify snow (figures 5b,e,f). The  
11 most prominent feature is the red colored plateau region of central Asia seen in all maps  
12 down the left hand column (figures 5a,c,e). This indicates that during all months over this  
13 region AMSR-E identifies snow more often than the other two products. While we do  
14 not, in general, assume that a product is wrong because it disagrees with the other two  
15 products, in this region we know from other studies that AMSR-E observations are biased  
16 due to problems in passive microwave snow detection at higher elevations associated  
17 with atmospheric influences on passive microwave retrievals (Wang and Tedesco 2007).  
18 Since the atmosphere over the high elevation plateaus is much thinner, the algorithms  
19 calibrated globally at lower elevations require correction (Savoie et al. 2009).

20

21 Panels on the right side of figure 5 show that during each month there are regions where  
22 AMSR-E identifies snow less frequently than MOD10C1 or IMS (figure 5b,d,f). The  
23 regions shown on these panels coincide with boundary of the continental snow cover

1 during each month (see the Rutgers University Global Snow Lab web site for  
2 climatological maps of monthly snow cover based on IMS:  
3 <http://climate.rutgers.edu/snowcover/index.php>). Regions near the boundary tend to have  
4 patchy, shallow snow packs. During spring (figure 5f) the disagreement across well  
5 defined ablation bands at the southern boundary of the continental snow pack is also  
6 likely due to significant areas of melting snow with liquid water in the snowpack .

7

### 8 *5.3 Disagreement between IMS and the other two products*

9 Figure 6 demonstrates that the most prominent circumstance under which IMS disagrees  
10 with the other two products is during the spring ablation period near the boundary of the  
11 continental snow pack (figure 6e). This result is in agreement with recent studies (Brown  
12 et al. 2007, Brown et al. 2010, Frei and Lee 2010) which find that over the last decade or  
13 so the timing of spring ablation over North America is later, by up to several weeks in the  
14 central Canadian Arctic, according to IMS in comparison to other observations. The  
15 reasons for these discrepancies, which are found during the entire spring ablation season  
16 (April, May, and June; May and June not shown here) over the boreal forest as well as  
17 the tundra, are not understood, but may be related to geographic factors such as the forest  
18 type and/or the presence of numerous lakes in this (Derksen et al. 2005a, Rees et al.  
19 2006), Investigations into the cause of this problem continue.

20

### 21 *5.4 Disagreement between MOD10C1 and the other two products*

22 The most interesting example of MOD10C1 disagreeing with IMS and AMSR-E is found  
23 during autumn over Eurasia. During October over a broad, seemingly incoherent region

1 of Eurasia, predominantly over Scandinavia and northern Europe, MOD10C1 often  
2 identifies snow when the other two products do not (figure 7a). However, this region is  
3 not as incoherent as it may seem, as it corresponds closely to the boreal evergreen  
4 needleleaf forest as defined by analysis of MODIS reflectances (Friedl et al. 2002).  
5 During November (not shown) we find a similar pattern, except the differences are more  
6 extreme and concentrated more over Scandinavia. The eastern Eurasian region over  
7 which MOD10C1 often fails to identify snow when IMS and AMSR-E see snow (figure  
8 7b) corresponds closely to the region of deciduous needleleaf forest. It seems that over  
9 one type of forest MODIS sees snow more often, while over a different type of forest  
10 MODIS sees snow less often. While the difficulties of remotely sensing snow under  
11 forest canopies have been widely reported, the patterns reported here have not been  
12 examined in the literature.

13

#### 14 *5.5 Comparison of AMSR-E to the CMC snow product*

15 Maximum October snow depth values over the Northern Hemisphere are ~ 20 – 30 cm  
16 (figure 8). The AMSR-E product suggests more snow in Siberia than the CMC product.  
17 AMSR-E overestimation with respect to CMC over Siberia increases as the snow season  
18 progresses. In January, snow depth differences between the two products increase to ~  
19 30-40 cm (figure 9). In April, the area over which AMSR-E overestimates snow depth  
20 increases even further with respect to January. In contrast, over other regions AMSR-E  
21 tends to underestimate snow depth with respect to the CMC product, but these areas do  
22 not appear to expand as the snow season progresses. These include the Tibetan plateau  
23 and along the north-east coast of North America (figure 10).

1  
2 Histograms of the snow depth differences between the two products are shown in figure  
3 11. Overall, AMSR-E tends to overestimate the values provided by CMC. While the  
4 variance of the errors can be seen in the histogram plots, perhaps a more informative  
5 number would be the coefficient of variation ( $C_v$ ).  $C_v$ , defined as the absolute value of  
6 the standard deviation of the differences divided by the mean CMC snow depth, provides  
7 an indication of how large the differences are in comparison to the snow depth. For  
8 example, a value of  $C_v=1$  means that the errors are of the same magnitude as the mean  
9 depth;  $C_v=0.1$  means that the errors are an order of magnitude less than the mean snow  
10 depth.  $C_v$  values were calculated for each month (table 1).  $C_v$  values are highest in  
11 October, when depths are small; lowest in January; and increase again in April. As a  
12 snow pack ages, even under cold conditions without additional precipitation,  
13 metamorphic processes lead to grain size variations (such as depth hoar formation) that  
14 tend to introduce errors in the passive microwave product. Furthermore, as temperatures  
15 fluctuate and additional precipitation events add fresh snow, snow packs can develop a  
16 series of well defined layers of different grain sizes that confound passive microwave  
17 based estimates of depth and SWE. Ice layers, which can develop as a result of melt-  
18 freeze and rain-freeze events, introduce additional scattering and therefore additional  
19 uncertainty. Such complications, combined with the impact of vegetation, especially  
20 vegetation that can change seasonally, can introduce a growing error in passive  
21 microwave retrievals as the snow season progresses.

22

1 Improved confidence in our abilities to estimate snow mass from satellites would support  
2 efforts to monitor the fresh water flux into the Arctic Ocean. An order of magnitude  
3 estimate suggests that the volume of water in the snow pack can play a significant role in  
4 the total annual river runoff into the Arctic Ocean of 4300-4800 km<sup>3</sup> yr<sup>-1</sup> (Arnell 2005,  
5 Miller and Russell 2000). Our AMSR-E based (highly uncertain) estimate of the mean  
6 snow mass over land surfaces during March (the month of maximum snow mass) north of  
7 60 N is ~1600 km<sup>3</sup>. Frei et al. (2005) based on the analysis of Brown et al. (2003)  
8 estimated the observed mean snow volume over North America during March to be  
9 ~1500 km<sup>3</sup>, which was equal to the median value estimated by a group of 18 climate  
10 models. This compares to a recent passive microwave-based estimate of ~1400 km<sup>3</sup> and  
11 ~2300 km<sup>3</sup> for mean North American and Eurasian snow volumes, respectively  
12 (Biancamaria et al. 2011). The errors associated with most of these estimates are  
13 currently unknown, but they indicate that the snowpack provides a significant fraction of  
14 the total river runoff to the Arctic.

15

16

## 17 **6. Discussion and Conclusions**

18

19 For most of the snow season and most regions there is large-scale agreement amongst the  
20 products in identifying the location of snow covered surfaces (i.e. snow extent, regardless  
21 of snow depth) during clear sky conditions. One exception to this is over central Asia. It  
22 is known that passive microwave products identify snow on the Tibetan Plateau and  
23 surrounding mountains when visible and infrared products do not (Armstrong and  
24 Brodzik 2001, Basist et al. 1996). Because passive microwave retrieval algorithms are

1 calibrated at lower elevations, at these high elevations the reduced atmosphere between  
2 the surface and radiometer can result in retrieval errors (Savoie et al. 2009, Wang and  
3 Tedesco 2007). The second exception occurs where snow is ephemeral, patchy, or wet. In  
4 such regions the attenuation of the passive microwave signal, upon which snow detection  
5 is based, is compensated for by emission from the surface or from liquid water in the  
6 snow pack (Matzler 1994, Ulaby and Stiles 1980). Despite these difficulties, all estimates  
7 (discussed in the preceding section) indicate that the snowpack is the source of a  
8 significant portion of runoff into the Arctic basin.

9

10 The disagreements in snow extent during April are greater than during October or  
11 January in terms of the percentage of available days during which one product differs  
12 from the other two. This is in agreement with Brown et al. (2010), Frei and Lee (2010),  
13 and Brown et al. (2007), who find differences between sensors during spring over North  
14 American regions experiencing ablation, and indicates that the wet snow during ablation  
15 is perhaps more of a hindrance to the identification of snow from satellites than some of  
16 the other confounding factors. However, during fall and winter the evaluation is  
17 hampered by data availability problems associated with cloudiness and solar illumination  
18 issues.

19

20 Our analysis also demonstrates that snow depths estimated by the Canadian  
21 Meteorological Centre product and by the AMSR-E algorithm can differ substantially.  
22 Although there are no absolute surface reference observations in most regions to  
23 determine which (if either) product is correct, we know from experience as well as theory

1 that the passive microwave depth and SWE algorithms are inaccurate under certain  
2 conditions (Tedesco and Narvekar 2010). Sources of error include: surface heterogeneity  
3 within a passive microwave footprint; temporal and spatial variability in grain size and  
4 snow density; obscuration of snow by forests; masking of the passive microwave signal  
5 by liquid water in the snow pack; and effects of atmospheric attenuation. The persistent  
6 underestimation by AMSR-E with respect to CMC over some regions can be partially  
7 explained by considering that snow depth over many of those areas is above the  
8 ‘saturation’ depth to which the passive microwave algorithm is sensitive (Derksen 2008,  
9 Markus et al. 2006, Matzler 1994, Schanda et al. 1983); the presence of a high fraction of  
10 lakes over the north east of North America is also believed to be a source of error  
11 (Derksen et al. 2005a, Rees et al. 2006).

12

13 Another example is the overestimation of snow depth by AMSR-E over northern Siberia,  
14 which can be attributed to the limitation of the current AMSR-E algorithm to account for  
15 the large grains that typically develop in snow packs in this (and some other) regions  
16 (Clifford 2010). Over regions that develop and maintain a snow pack early in the season,  
17 the snow tends to insulate the ground keeping it warm even as air temperatures fall,  
18 resulting in a strong vertical temperature gradient in the snow pack. This temperature  
19 gradient causes vertical energy and vapor fluxes within the snow pack, the net effect of  
20 which is a layer of depth hoar at the bottom of the snow pack (Jordan et al. 2008). The  
21 large crystal sizes of depth hoar (~5mm) cause increased scattering of microwave  
22 radiation resulting in an overestimation of the snow pack by the passive microwave  
23 algorithms.

1

2 Opportunities remain for the development of improved snow products. For example,  
3 improvements can be made with regard to the retrieval of snow amount from passive  
4 microwave sensors (Tedesco et al. 2004) under forested terrain (Derksen 2008), the  
5 refinement of snow extent estimates from visible and infrared sensors (Parajka and  
6 Bloschl 2008), and the estimation of sub-grid scale information. Tedesco and Miller  
7 (2007b) explore the relative merits of combining active and passive microwave retrievals,  
8 using a MODIS snow product as their reference “truth.” A number of researchers are  
9 investigating the potential for finer scale information on snow extent, amount, fractional  
10 snow cover (Derksen et al. 2005b, Salomonson and Appel 2004, Salomonson and Appel  
11 2006), snow melt (Wang et al. 2008), as well as on snow pack properties (Kinar and  
12 Pomeroy 2007, Nolin and Dozier 2000, Painter and Dozier 2004, Painter et al. 2003,  
13 Rango et al. 2000, Schmugge et al. 2002). Improvements in remotely sensed products  
14 that do not rely on the assimilation of data or model results will come as a consequence  
15 of improved understanding of the interaction between electromagnetic and geophysical  
16 parameters at large spatial scales. In this context, a new operational algorithm based on  
17 the inversion of an electromagnetic model, artificial neural networks and snow  
18 climatology currently under evaluation may be capable of accounting for some of these  
19 limitations.

20

21 One currently active area of research is the development of combined products, which  
22 include *in situ* observations and/or modeling results as well as remotely sensed  
23 information. One can identify advantages and disadvantages to both combined and stand-

1 alone remotely sensed products. While stand-alone remotely sensed products contain  
2 inherent drawbacks as discussed here, at any time, either *in situ* or remotely sensed data  
3 streams can fail, rendering combined as well as stand-alone products vulnerable to  
4 missing information. This is most critical for real- or near-real time operational products,  
5 on which weather forecast models or time-sensitive decisions rely.

6

7 Remote sensing of snow continues to contribute to our understanding of Earth system  
8 processes. MODIS snow products are valuable because they can provide high resolution  
9 snow estimates under cloud-free conditions using a quantifiable algorithm. However, for  
10 climatological as well as operational purposes, humans can integrate and filter data from  
11 multiple sources and satellite images in ways that fully automated methods are (at least  
12 currently) unable to, and provide information for the entire land surface of the globe,  
13 regardless of the presence of clouds. Thus, continuation of IMS, with its long record of  
14 snow extent, is a priority. Considering the difficulties in determining SWE on a global  
15 scale from stand-alone remote sensing products, it seems likely that combining multiple  
16 sensors with station observations and/or models, such as in the GlobSnow product, will  
17 provide the best estimates of SWE.

18

19

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1 Table 1. Mean snow depth from CMC product; standard deviation of the differences  
 2 between the CMC and AMSR-E snow depths; and the coefficient of variation. All values  
 3 are averages of grid points across all Northern Hemisphere land areas north of 30 N  
 4 excluding the Greenland ice sheet.

5

	$\mu$ (mean CMC snow depth) (cm)	$\sigma$ (standard deviation of difference) (cm)	$Cv$ $abs(\sigma/\mu)$ (coefficient of variation) (unitless)
October	5.0	4.15	0.83
January	22.5	7.18	0.32
April	22.9	12.33	0.54

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