A Change Impact Analysis to Characterize Evolving Program Behaviors

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Abstract—Change impact analysis techniques estimate the potential effects of changes made to software. Directed Incremental Symbolic Execution (DiSE) is an intraprocedural technique for characterizing the impact of software changes on program behaviors. DiSE first estimates the impact of the changes on the source code using program slicing techniques, and then uses the impact sets to guide symbolic execution to generate path conditions that characterize impacted program behaviors. DiSE, however, cannot reason about the flow of impact between methods and will fail to generate path conditions for certain impacted program behaviors. In this work, we present iDiSE, an extension to DiSE that performs an interprocedural analysis. iDiSE combines static and dynamic calling context information to efficiently generate impacted program behaviors across calling contexts. Information about impacted program behaviors is useful for testing, verification, and debugging of evolving programs. We present a case-study of our implementation of the iDiSE algorithm to demonstrate its efficiency at computing impacted program behaviors.

Traditional notions of coverage are insufficient for characterizing the testing efforts used to validate evolving program behaviors because they do not take into account the impact of changes to the code. In this work we present novel definitions of impacted coverage metrics that are useful for evaluating the testing effort required to test evolving programs. We then describe how the notions of impacted coverage can be used to configure techniques such as DiSE and iDiSE in order to support regression testing related tasks. We also discuss how DiSE and iDiSE can be configured for debugging; finding the root cause of errors introduced by changes made to the code. In our empirical evaluation we demonstrate that the configurations of DiSE and iDiSE can be used to support various software maintenance tasks.

I. INTRODUCTION

Change impact analysis techniques [1] estimate the potential effects of software changes. The results of an impact analysis can be used by other program analysis techniques, e.g., regression testing, to determine which parts of a program to re-analyze and which parts can safely be ignored because they are not impacted by the changes. The evolutionary nature of software development, coupled with the size and complexity of deployed software systems motivates the need for efficient change impact analyses. It is a well known fact that a “one line fix” can have broad and unintended (and potentially disastrous) consequences, thus impact analysis techniques play an important role in software evolution and maintenance activities.

Most existing automated impact analysis techniques characterize the effects of changes in terms of syntactic program structures, such as functions or program statements, that may be impacted. Dependency-based impact analysis techniques [2] estimate the effects of program changes by analyzing the interconnections between program components. Given a change set—the set of program components that are known to be changed—these techniques compute the impact set—the set of program components that may be impacted by the actual changes. This type of characterization describes the impact of changes in terms of program locations, but does not include descriptions of feasible program execution paths through the impacted locations. Such details are useful for verification, validation and debugging of evolving program behaviors to reduce the scope of the analysis to focus on only the set of impacted program behaviors.

Directed Incremental Symbolic Execution (DiSE) is an intraprocedural change impact analysis for characterizing the impact of software changes on program execution behaviors [7]. DiSE combines the efficiencies of static analysis with the precision of symbolic execution [8], [9]. The static analysis component of DiSE uses the locations of the actual changes with program slicing techniques to estimate the impact of the changes on other locations in the source code. The resulting impact set is then used to guide symbolic execution to explore program execution behaviors impacted by the changes, and to generate path conditions summarizing the impacted program behaviors. Characterizing impacted program behaviors in terms of path conditions has the advantage that path conditions can be checked using Satisfiability Modulo Theories (SMT) solvers in order to support various software maintenance tasks such as testing, debugging, and verification.

DiSE is an intraprocedural analysis and does not account for the flow of impact between methods. Most realistic programs, however, consist of multiple methods that are invoked from different calling contexts; information flows between methods through method arguments and return values. In this work we present an extension to DiSE that performs an interprocedural analysis enabling analysis of whole programs. This extension of DiSE – iDiSE – combines static and dynamic calling context information to efficiently generate impacted program behaviors across calling contexts. Supporting the flow of impacted behaviors across methods in interprocedural programs is a non-trivial part of our analysis. We demonstrate
the efficiency of our change impact analysis with an evaluation of our implementation of iDiSE.

Many change impact analysis techniques are developed with a particular software evolution task in mind, e.g., regression testing [3]. Some techniques are configurable in that they provide options to adjust the precision of the analysis, e.g., [4]. In this work, we illustrate how DiSE and iDiSE results can be used by multiple client analyses, e.g., testing, debugging. First, we describe novel notions of coverage that incorporate change impact information. These notions of coverage can enable us to evaluate the test effort required to validate evolving program behaviors. Traditional coverage notions, e.g., statement and branch coverage, are extended to take into account change impact information. The notions of impacted coverage can then be used to configure techniques such as DiSE and DiSE in order to support regression testing related tasks. We also describe how DiSE can be configured for debugging—finding the root cause of errors introduced by changes to the code. The primary contributions of our work are:

- An extension to the DiSE algorithm to support intraprocedural change impact analysis (iDiSE).
- Extended notions of coverage that combine traditional notions of coverage with change impact information.
- Configuration options for DiSE and iDiSE based on the requirements of the client analysis.
- An implementation of iDiSE as an extension to the Java PathFinder symbolic execution framework [10], [11], [12].
- An empirical evaluation illustrating the effectiveness of (a) iDiSE at characterizing the impact of change on program execution behaviors, and (b) various DiSE and iDiSE configurations to support regression testing tasks based on impacted coverage notions and debugging.

II. BACKGROUND

In this section, we provide an overview of the DiSE methodology [7] and illustrate, using a small example, how the intraprocedural analysis estimates which behaviors may be impacted by changes to a method. We begin with a brief explanation of symbolic execution.

A. Symbolic Execution

Symbolic execution is a non-standard approach for executing programs that uses symbolic values in place of concrete (actual) values as program inputs [8], [9]. During symbolic execution, each program statement is executed and the symbolic state is updated to represent the effects on program variables. At every conditional branch in the program, a constraint is generated and added to the current path condition. A path condition is a conjunction of constraints over constants and symbolic input values that characterizes the current execution path. The satisfiability of the path condition is checked each time it is updated in order to determine the feasibility of the current program path. When a path becomes infeasible, symbolic execution stops exploration of that path and backtracks to explore another path. The resulting set of path conditions form a summary of the program execution behaviors.

B. Motivating Example

To illustrate the DiSE analysis, a control flow graph (CFG) for a simplified method in a Wheel Brake System (WBS) system is shown in Fig. 1. The WBS example is taken from [7]: it contains two integer global variables, AltPress and Meter. The CFG shown is for the update method in WBS with three integer variables, PedalPos, BSwitch, and PedalCmd, as input arguments.

Each node in the CFG represents a single source code line and edges between the nodes represent flow of control between the lines of code. Assume a change was made to line 2 (node \( n_0 \)) in Fig. 1 where the comparison operator is changed from == to <=. Node \( n_0 \) in Fig. 1 shows line 2 after the change is made to the program. The shaded nodes in the CFG represent lines impacted by the change at node \( n_0 \). DiSE explores and characterizes only the seven path conditions (execution paths) impacted by the change at line 2. Full symbolic execution of the changed version explores the entire symbolic state space, generating 21 path conditions. As a result, any client analysis which uses the results of full symbolic execution may unnecessarily analyze program behaviors that are not impacted by the change. Furthermore, for a small example such as this, a full analysis is feasible; however, for larger methods or when complex constraints are involved, a full analysis may be intractable.

C. Directed Incremental Symbolic Execution

DiSE uses information about syntactic program changes coupled with the results of data- and control- flow analyses to direct symbolic execution. DiSE generates impacted path
conditions and avoids generating path conditions that are not impacted by the changes. Path conditions generated by DiSE encode program execution behaviors impacted by the changes to the code.

1) Inputs to DiSE: The inputs to DiSE are the source code for two versions of a procedure in programs $P$ and $P'$, and the results of a lightweight syntactic Diff analysis comparing the source code for $P$ and $P'$, e.g., textual or abstract syntax tree comparison. The results of the Diff analysis identify the change set – the set of locations in the source code that are different between the two versions. For program $P'$, the Diff analysis marks source code lines that are added, changed, or unchanged with respect to $P$. Similarly, the analysis marks source code lines as removed, changed, or unchanged in $P$ with respect to $P'$.

2) Static Impact Analysis: DiSE uses standard intraprocedural program slicing techniques, with the initial change set as the slicing criteria, to generate the set of program locations that may be impacted by the actual changes. Consider the CFG computed for the modified version of update shown in Fig. 1. Each node in the CFG corresponds to a program location in the source code. Node identifiers appear in italics just outside the node, e.g., $n_1$, $n_2$. Edges between the nodes represent the possible flow of execution between the program statements.

DiSE uses the change set computed by the Diff analysis to mark $n_0$ as changed and then performs program slicing to identify program statements at $n_1$, $n_3$, $n_4$, $n_5$, $n_{11}$, $n_{13}$, and $n_{14}$ as impacted write statements—the values written at these locations may impact subsequent execution of conditional branch statements. The conditional branch statements at $n_0$, $n_2$, $n_{10}$, and $n_{12}$ are also identified as impacted—statements that may be impacted by the change and that may in turn affect the path condition.

3) Directed Symbolic Execution: To compute the impact of the changes on the execution behaviors of the modified version of update, the impact set (of program locations) computed by the static impact analysis is used to direct symbolic execution of the modified version of update and generate impacted path conditions. To illustrate how DiSE prunes symbolic execution using the impact set, consider a feasible execution path, $p_0 := \langle n_0, n_1, n_5, n_6, n_7, n_{10}, n_{11} \rangle$, generated during directed symbolic execution. The path $p_0$ contains the sequence of impacted nodes, $\langle n_0, n_1, n_5, n_{10}, n_{11} \rangle$, and the sequence of nodes $\langle n_6, n_7 \rangle$ that is not impacted by the change. However, another feasible path, $p_1 := \langle n_0, n_1, n_5, n_6, n_8, n_9, n_{10}, n_{11} \rangle$, is pruned (not explored) during symbolic execution because the sequence of impacted nodes is already covered by $p_0$. The only difference between $p_0$ and $p_1$ is the sequence of nodes that is not impacted by the change.

D. Limitations of an Intraprocedural Change Impact Analysis

DiSE is an intraprocedural analysis that does not account for the flow of impact between methods. Most realistic programs consist of multiple methods passing data from one method to another following call chains. Information in interprocedural programs flows forward from one method to another through the use of method arguments while information flows back to the calling method through values returned by the callee. Similarly, when a change is made to a method, the impact of the change can flow to other methods through arguments and return values. Because DiSE does not account for the flow of impact between methods, it will not generate the full set of impacted behaviors. To illustrate, consider two methods: $A$ and $B$.

```int A (int x) {x = x+1; return B(x);} int B (int x) {if (x>0) return 1; else return 0;}
```

Method $A$ contains an assignment to an input variable $x$ and then passes $x$ as an argument to method $B$. Method $B$ returns either 0 or 1 based on the value of $x$. Suppose, a change is made to the assignment statement and now $x = x - 1$; the intraprocedural static impact analysis is unable to mark conditional statements in $B$ as impacted by the change in method $A$. As result, DiSE will miss exploring one (either $x - 1 > 0 \land ret = 1$ or $x - 1 <= 0 \land ret = 0$) of the impacted program behaviors. To account for the flow of impact between the methods in a program, an interprocedural impact analysis technique is necessary.

III. INTERPROCEDURAL DiSE

In this section we present an extension to the DiSE technique described in Section II that can be used to analyze the impact of changes to program behaviors across methods. We refer to this approach as interprocedural DiSE or iDiSE. The iDiSE algorithm first performs a static approximation of the impact sets across the calling contexts of methods in the program and annotates this information on a call graph. During symbolic execution the impact set information is dynamically refined using the current calling context. Combining static and dynamic information in iDiSE enables efficient generation of impacted program behaviors across multiple methods.

A. Static Impact Analysis

In phase I of the iDiSE algorithm, the static impact analysis uses as input the source code of a program $P'$ and the differences between programs $P$ and $P'$ to generate a set of impacted program locations and $P'$. The impact analysis generates impact sets for each method in $P'$. A call graph is first constructed to capture the possible call sequences between methods in the program. For each method in the call graph, an impact set is generated for the method itself. The potential flow of change impact information between methods is stored by annotating the edges in the call graph and generating additional impact sets for the formal parameter of each method.

1) Call Graph Construction: The iDiSE static impact analysis first generates a call graph for $P'$. The call graph contains one node for every method in $P'$. The edges between the nodes in the call graph represent a method invocation (caller $\rightarrow$ callee). Each node in the call graph has the same number of outgoing edges as the number of method invocations. If
Suppose, the program statement is control dependent on a conditional statement statements. Line uses a value (Uses at line (that if at impacted location In Fig. 3(a), line 11 the program statement is added to the impact set. In Fig. 2(a), the execution of is control-dependent on the execution of the true branch of the conditional statement at . This introduces a backward dependence edge between and .

To compute interprocedural results, the impact analysis also marks impacted call sites. A call site is marked as impacted if the invocation leads to a method with a non-empty change set through some path in the call graph. In Fig. 3(a), in the CallFlow procedure at lines 14 and 15, if a call site, , in method invokes another method such that the impact set of is non-empty, then the call site, , is added to the impact set. For the example shown in Fig. 2(a), program location, , in the method main is marked as impacted by iDiSE because it leads to method which has a non-empty impact set.

The impact set for method in Fig. 2(a) for the change set of is . Standard program slicing techniques using the dependence analysis described in this section are used to generate the impact set for a given change set.

3) Impact Sets for Formal Parameters: Change impact information flows from a caller to a callee through one or more arguments in the method invocation. The formal parameters in the callee method are marked as impacted based on the caller invoking the method. It is possible that in some contexts, the impact of a change will not flow through to the callee. Analyzing a method in the context of multiple invocation sites has the potential to cause the analysis to generate an exponential number of impact sets. To avoid this, iDiSE computes a separate impact set for each formal parameter of the method; iDiSE analyzes each method only once.

The total number of impact sets generated for a method is the number of formal parameters plus one for the change impact within the method body. We refer to the latter as the impact set for the method. The main method in Fig. 2(a) does not have formal parameters so it has a single impact set as shown in Fig. 2(b). Whereas, method has two formal parameters, resulting in a total of three impact sets. One for the method itself and one for each of its formal parameters .

To generate the impact set for a formal parameter, the
procedure DataFlow(Imp, m)  
1: if \(I_a \in \text{Imp} \land l_b \in m \land \text{Def}(l_a) \in \text{Uses}(l_b)\) then  
2: \(\text{Imp} := \text{Imp} \cup \{l_b\}\)  
3: for each \(m' \in P', l_b \in m\) where \(l_b\) invokes \(m'\) do  
4: \(\text{CallGraphAnnotations}(m', l_b) \cup \text{Def}(l_a)\)  
5: /* Impact Statements for Backward Data Flow */  
6: if \(l_b \in \text{Imp} \land l_a \in P \land \text{Def}(l_a) \in \text{Uses}(l_b)\) then  
7: \(\text{Imp} := \text{Imp} \cup \{l_a\}\)  
8: return \(\text{Imp}\)  
9: 
procedure ControlFlow(Imp, m)  
10: if \(l_a \in \text{Imp} \land l_b \in m \land \text{controlDependent}(l_a, l_b)\) then  
11: \(\text{Imp} := \text{Imp} \cup \{l_b\}\)  
12: return \(\text{Imp}\)  
13: 
procedure CallFlow(Imp, m)  
14: for each \(m' \in P', l_a \in m\) where \(l_a\) invokes \(m'\) do  
15: if \(\text{ImpactSet}(m') \neq \emptyset\) then \(\text{Imp} := \text{Imp} \cup \{l_a\}\)  

Fig. 3. (a) Pseudocode for the dependence analysis used to compute the impact sets in iDiSE. (b) Partial Symbolic Execution Tree for the code in Fig. 2(a).

change set is initialized to the program locations that use the impacted formal parameter. The initial change set for the impacted formal parameter \(\text{int} x\) in method \(A\) is \(\{l_0, l_9\}\) because the conditional statement at \(l_0\) and return statement at \(l_9\) are the only statements that use (read) the variable \(x\).

4) Annotating Call Edges: Edges in the call graph are annotated using the argument names in the caller and their corresponding formal parameter names in the callee to represent the flow of change impact information from caller to callee. At lines 3 and 4 in Fig. 3(a), the \(\text{CallGraphAnnotations}\) method adds argument names along a call edge when \(m'\) is invoked from \(m\) at location \(l_b\). The arguments annotated are the ones that are assigned a value at an impacted location \(l_a\) (\(\text{Def}(l_a)\)). The change at line \(l_1\) in method \(A\) shown in Fig. 2(a) impacts the call site at \(l_3\). Variable \(y\) is assigned a value at \(l_1\) and is passed as an argument when invoking method \(B\) at \(l_3\). The edge from \(A\) to \(B\) in Fig. 2(b) is annotated with \(l_3 : y \rightarrow z\) which indicates the flow of the impact of the change to \(y\) in \(A\) to \(B\), and also maps the argument \(y\) to the formal parameter, \(z\), in method \(B\).

B. Directed Symbolic Execution

During directed symbolic execution, paths are pruned based on the reachability of impacted program locations from the current state. Before checking reachability, iDiSE dynamically refines the impact sets for a given method based on which caller invoked the method and the annotation on the corresponding call edge in the call graph. This approach efficiently generates precise change impact information.

1) Pruning Example: A partial symbolic execution tree is shown in Fig. 3(b). Execution begins at the initial state, \(s_0\), generating the next symbolic states \(s_1\) and \(s_2\), where \(s_2\) is a successor of \(s_1\) on the current execution path. Assume states \(s_1\) and \(s_2\) are generated by execution of program statements in method \(B\) when it is invoked from \(\text{main}\). Next, we see in Fig. 3(b), states labeled \(s_3\) and \(s_4\) are generated respectively by transitions \(t_2: X <= 0\) and \(t_3: Y <= 0\), on the current path after which method \(A\) returns. At this point, symbolic execution backtracks to generate the other choice of \(s_5\) and then explores \(B\). An impact set \((B := \text{Imp}(B(z)))\) for method \(B\) is dynamically generated when transition \(t_5\) is executed. The information about impacted program statements in this set is used to direct execution within method \(B\). Eventually, when the search backtracks to states \(s_1\) and \(s_0\) in Fig. 3(b), the transitions \(t_{10}\) and \(t_{11}\) lead to subtrees generated by executing instructions in method \(B\). Subtrees reachable from \(t_{10}\) and \(t_{11}\) are pruned because the impact set of \(B\) is empty when invoked from \(\text{main}\). The fact that the impact set for \(B\) is empty indicates that the transitions, \(t_{10}\) and \(t_{11}\) do not lead to execution paths that are impacted by the changes. The details on dynamically generating impact sets and checking reachability to prune paths is described in detail below. The goal of Fig. 3(b) is to demonstrate to the reader that the iDiSE algorithm uses information from the static impact analysis coupled with the actual calling context to decide \emph{when} to explore paths in a certain method. When method \(B\) is invoked from \(A\), the iDiSE analysis generates paths through method \(B\); however, the paths through \(B\) are pruned in the iDiSE analysis when \(B\) is invoked from \(\text{main}\).

2) Dynamically Generating Impact Sets: When a method is invoked during symbolic execution, the final impact set for the method is dynamically generated based on the method's calling context and information computed by the static analysis. For the example in Fig. 2(a), the dynamically generated impact sets for the methods are shown in Fig. 2(c). When method \(B\) is invoked from \(\text{main}\), its final impact set, \(I_1\), is empty for two reasons. First, the impact set for \(B\) itself is empty. Second, there are no annotations on the call edge from \(\text{main}\) to \(B\) in Fig. 2(b); hence, the elements from the impact set for the formal parameter \(z\) of method \(B\) are not added to the final set. When, however, method \(B\) is invoked from method
A, the impact set of its formal parameter \( z \) — \( \text{Imp}(B(z)) \) — is assigned as the final impact set of \( B \) as shown in the set labeled \( I_3 \) in Fig. 2(c). Dynamically generating the final impact sets based on the calling context of the method allows iDiSE to efficiently track the impact of the flow of changes between different methods.

Dynamically generated impact sets for a method have a scope within which they can be used to check reachability. Fig. 2(c) is a list of impacted sets in scope when transition \( t_5 \) in Fig. 3(b) executes. The impact set \( I_3 \) is in scope for all transitions in method \( B \) following \( t_5 \). When the symbolic execution backtracks to state \( s_2 \), to a point before the invocation of \( B \), the impact set \( I_3 \) is removed from the list of impact sets in scope. When transition \( t_9 \) in Fig. 3(b) is executed, method \( B \) is invoked again from method \( A \). At this point a new final impact set, \( I_4 \), is generated for method \( B \) and added to the list of impact sets in scope: \( \langle I_0, I_1, I_2, I_3, I_4 \rangle \); contents of \( I_4 \) are identical to those of \( I_3 \). Eventually, when the search backtracks to state \( s_1 \) in Fig. 3(b), the sets in scope are \( \langle I_0, I_1 \rangle \). Here reachability to impacted statements within method \( B \) is checked using \( I_1 \). Checking reachability to impacted statements is described next.

3) Checking Reachability: During symbolic execution, paths are explored or pruned based on reachability from the current symbolic state to the program instructions in the impacted set. Our previous work on DiSE checks reachability to impacted program locations with respect to a particular impact set. It maintains separate sets of explored and unexplored impacted program locations within a method. In iDiSE (and DiSE), if an impacted program location, \( l' \), in the unexplored set is reachable from the current program location, \( l \), then execution continues along that path otherwise the path and its corresponding sub-tree is pruned. Reachability between \( l \) and \( l' \) is checked using the CFG for the method—does there exist a sequence of edges from \( l \) to \( l' \) in the CFG? The details of the reachability check are described in [7].

The reachability check in iDiSE is extended to account for reachability of program statements in other methods. In iDiSE, we unroll the call stack to check reachability in other methods within the current calling context. After checking reachability within the current method, iDiSE uses the call stack to extract the sequence of method invocations that led to the current method. A possible calling context is as follows: \( \text{main} \rightarrow A \rightarrow B \) for the example shown in Fig. 2(b). In this context we want to check whether an execution path can be pruned while the execution is at a location in method \( B \). Suppose there are no unexplored impacted program locations in method \( B \) that are reachable from the current location, then we look at the call site from \( A \) that invoked the current instance of method \( B \). We then check if there exists an unexplored impacted program location in method \( A \) reachable from the call site. The check continues along the call chain until we get through the series of invocations or we find a reachable, unexplored, impacted program statement.

Dynamically generating impacted sets and computing reachability along the calling context of the program allows iDiSE to efficiently prune parts of the symbolic execution tree that are not impacted by the changes.

IV. ANALYSIS CONFIGURATIONS

Traditional notions of coverage are insufficient for characterizing the test effort required to validate evolving programs because they do not distinguish between coverage of impacted and unimpacted parts of the program. In this section, we describe how traditional notions of coverage are extended to incorporate information about change impact. We describe how these notions of impacted coverage can be used to plan testing and debugging techniques. This section also presents a discussion on how DiSE and iDiSE can be configured for debugging—finding the root cause of errors introduced by a change.

A. Impacted Coverage Metrics

Traditional notions of code coverage, e.g., statement or branch coverage, are useful for describing whether or not parts of the code have been executed during, for example, regression testing; however, when used in the context of evolving software, these coverage metrics do not provide any indication regarding the coverage of impacted statements and branches — valuable information for evaluating the results of software maintenance tasks such as regression testing. In this work, we extend several traditional notions of code coverage to incorporate change impact information. These new notions of coverage are useful for configuring DiSE and iDiSE, and for relating the behavioral coverage computed by directed symbolic execution, and described by the path conditions, back to the source code.

The CFGs shown in Fig. 4 illustrate the impacted coverage notions defined in this work. CFGs provide an intuitive mechanism for illustrating the impacted coverage notions because each constraint on a path condition generated by symbolic execution can be directly mapped to a conditional branch in the code (and in the CFG). In Fig. 4, each node in a CFG represents a single program statement.

**Definition IV.1.** Impacted Statement Coverage: Cover every impacted program statement.
Definition IV.2. Impacted Basic Block Coverage: Cover every basic block that contains an impacted program statement.

Impacted statement coverage entails covering every executable program statement that is impacted by the change. Impacted basic block coverage is very similar to impacted statement coverage. Because many analyses are performed at the basic block level, rather than the program statement level, it is important to define coverage metrics for both. Suppose the conditional branch statement at node \( i_0 \) in Fig. 4(a) is marked as impacted. When the ImpactedStatement or ImpactedBasicBlock option is specified, the analysis will generate path conditions through nodes \( i_0 \) to \( i_1 \) or through nodes \( i_0 \) to \( i_2 \), covering the impacted statement \( i_0 \). Here, \( i_0 \) is also an impacted basic block.

Definition IV.3. Impacted Branch Coverage: Cover every possible decision of impacted control structures (if-statements, while-statements, switch-statement cases), impacted exception handlers, and all impacted entry and exit points.

When DiSE or iDiSE is configured with the option, ImpactedBranch, the analysis generates feasible path conditions through the \textit{true} and \textit{false} branches of all impacted conditional branch statements. The analysis also generates path conditions for the various cases in \textit{impacted} switch statements, impacted exception handlers, and impacted entry and exit points, e.g., entry and exit points of an impacted method. When ImpactedBranch is specified for the example in Fig. 4(a), the analysis generates path conditions through nodes \( i_0 \) to \( i_1 \) and through nodes \( i_0 \) to \( i_2 \).

Definition IV.4. Impacted Path Fragment Coverage: Cover every possible combination of impacted path fragments, where an impacted path fragment is a sequence of program statements that ends in an impacted conditional statement and the path fragment contains only one impacted conditional statement.

Each program execution path is composed of one or more path fragments. Different combinations of path fragments result in different paths. Similarly, different combinations of impacted path fragments result in different impacted paths. Suppose, the conditional branch statements at \( j_0 \) and \( j_1 \) in Fig. 4(b) are both impacted. The sequence of edges leading to \( j_0 \) and the sequence of edges leading to \( j_1 \) each constitute a path fragment. We have shown the sequence of edges as a dotted edge in Fig. 4(b) for brevity. Using the ImpactedPathFrag option, DiSE or iDiSE will generate the following paths (path conditions): (1) \( x > 0 \land y > 0 \), (2) \( x > 0 \land y \leq 0 \), (3) \( x \leq 0 \land y > 0 \), and (4) \( x \leq 0 \land y \leq 0 \).

Definition IV.5. Impacted Data Flow Coverage: Cover every use of a variable defined at an impacted write statement.

The goal of impacted data flow coverage is to ensure every possible use of every definition in an impacted write statement is covered. Suppose, the assignments to \( x \) at nodes \( k_0 \) and \( k_1 \) are both impacted in Fig. 4(c). In this example \( x \) is subsequence used in the conditional branch statement at \( k_2 \). When DiSE or iDiSE is configured with ImpactedDataFlow, it generates four path conditions: \( y > 0 \), \( y \leq 0 \), \( z > 0 \), and \( z \leq 0 \). The impacted data flow coverage obligations can then be fulfilled by solving these path conditions.

B. Debugging

Changes to programs can impact the correctness of the program by introducing unexpected program behaviors (errors or bugs). Regression testing techniques often allows us to detect these errors, but, they do not provide information about the root cause of errors. Techniques such as DiSE and iDiSE can be configured to facilitate the process of finding the cause of an error (debug it).

The DARWIN method for debugging evolving programs detects potential conditions for failing test cases when a change is made to a program [13]. Suppose a test case \( T \) passes in \( P \), but, fails in \( P' \). DARWIN generates a path condition, \( \Phi := \phi_0 \land \ldots \land \phi_m \), in \( P \) along the path which is generated by running \( T \); and similarly generates \( \Phi' := \phi'_0 \land \ldots \land \phi'_m \) in \( P' \). Next, for each \( \phi'_i \) where \( 0 \leq i < m \), the DARWIN method computes a new formula \( \Phi_i := \Phi \land \phi'_i \land \ldots \land \neg \phi'_j \); if the new formula \( \Phi_i \) is satisfiable then DARWIN reports the location where \( \phi'_i \) is generated as a potential cause for the failing test.

DiSE and iDiSE results can be used to improve on the DARWIN debugging approach by configuring DiSE (or iDiSE) with an option DeltaDebug to retain only the constraints generated at impacted conditional branch statements. This approach safely reduces the number of constraints on the path conditions and enables the debugging process to focus on impacted program locations as the potential cause for failing test cases.

V. Evaluation

We now present the results of a study in which we evaluate the effectiveness of our change impact analysis technique.

A. Tool Support

We have implemented DiSE and iDiSE in the Java PathFinder symbolic execution framework (SPF) [11], [12]. We use the Choco constraint solver [15] to check path feasibility during symbolic execution. Our analysis uses a custom interprocedural data- and control-flow analysis to compute a conservative approximation of the impacted program statements. The artifacts in our study were compiled with Java version 1.6.0_26. We then computed a source-level diff using a custom Abstract Syntax Tree (AST) differencing application written in Java.

B. Artifacts

To evaluate our analysis, we used two Java artifacts that are representative of programs used in the evaluation of symbolic execution techniques. The first, \( \texttt{tcas} \), is an aircraft collision avoidance system from the Software-artifact Infrastructure Repository (SIR) [16]. SIR contains 41 versions of \( \texttt{tcas} \), each of which is a mutant of version 0 containing one or
two functional changes (e.g., operator mutations, modified constants, and modified control structures). We translated the C versions in SIR to Java. Each version has 10 methods and contains 185 SLOC. We created an additional ten versions (42 – 51) to simulate a software evolution process where each version is based on the previous version, e.g., version 43 is a mutant of version 42. We used version 0 as our base version. Versions 42 – 44 contain refactoring changes, i.e., changes that do not affect the functionality of the program, and versions 45 – 51 contain functional changes.

To illustrate the analysis configurations discussed in Section IV, we use the Wheel Brake System (WBS) example, a synchronous reactive component from the automotive domain. The Java model consists of one class and 231 SLOC. It is based on a Simulink model derived from the WBS case example found in ARP 4761 [17], [18]. We evaluate the update method in WBS.

C. Results and Discussion

Costs of iDiSE: How do the costs of iDiSE compare to full symbolic execution in terms of time and states explored? In Table I, we report the total wall clock time in seconds and the states explored during directed symbolic execution for iDiSE and for full symbolic execution. The impacted program behaviors for each pair of tcas versions, P and P′, are generated by iDiSE using the DeltaDebug configuration described in Section IV-A. For the tcas artifact, iDiSE is able to achieve significant reductions in terms of the total time and states explored as shown in Table I. Versions V0V29 and V0V34 in Table I(a) require the minimum and maximum analysis times respectively for full symbolic execution from the set of 41 versions in SIR. Versions V0V5 and V0V10 have the minimum and maximum analysis times respectively for iDiSE from that same set. Similar reductions in time and states explored were noted in all 41 versions of tcas and also in the evolutionary versions of tcas shown in Table I (b).

Benefits of iDiSE: What reductions can be achieved by iDiSE? Table II shows that, in general, iDiSE generates fewer path conditions (PCs) than symbolic execution for tcas. In V0V23, iDiSE generates 3 PCs in program P′, and 29 PCs in P, whereas full symbolic execution generates 866 PCs for P′ and 595 PCs for P. Similar reductions can be observed for the other versions of tcas.

Because of space limitations, Table I and Table II contain a representative subset of the version pairs evaluated. Nevertheless, these results demonstrate that iDiSE is an effective technique for analyzing evolving software because it can generate impacted behaviors and avoid exploring behaviors that are not impacted by the change. Moreover, because the set of impacted behaviors computed by DiSE and iDiSE is reduced with respect to full symbolic execution, the client analysis that uses the results will also benefit. For example, to check for input partition equivalence [14] for V0V2 in Table II, it is necessary to compare only the 29 path conditions in P and P′, rather than the 595 path conditions computed by full symbolic execution. This is one of the key strengths of our technique.

In Table II, we also report the number of constraints associated with impacted branch conditions (Impacted Constraints) versus unimpacted branch conditions (Unimpacted Constraints). This information, along with the percentage of the total constraints, is useful for debugging-related client analyses. For example, in V0V2 there are 216 constraints generated at conditional statements not impacted by the changes, while 319 constraints are generated at impacted conditional statements. In this case, approximately 40% of the constraints generated during directed symbolic execution are not impacted by the change. In other versions of the tcas example, often a considerable percentage of the constraints are generated at conditional branches not impacted by the change. As a result, a client analysis such as the DARWIN debugging approach described in Section IV can be improved using iDiSE results to detect program locations that are potential causes in failing tests. Checking fewer constraints can reduce the cost of locating potential causes of failing tests. Furthermore, the quality of the potential causes reported can be improved because only impacted locations are reported.

Benefits of Configurability: What are the costs and benefits of using impacted coverage configurations? The coverage configurations are technique-agnostic; they can be used by both DiSE and iDiSE, and other change impact analyses. In Table III we present the number of states generated, total wall clock time, and path conditions generated when running DiSE on the WBS example configured for several notions of impacted coverage defined in Section IV—impacted branch coverage (Branch), impacted basic block coverage (Basic Block), and impacted path fragment coverage (Path Frag.). We also present the total number of path conditions generated by full symbolic execution (Full). In general, the different configurations of DiSE generate fewer path conditions compared to full symbolic execution. In version V0V4, DiSE generates only a single path condition for covering the impacted branches, basic blocks, and path fragments;

<table>
<thead>
<tr>
<th>Version</th>
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<th>States</th>
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<td>0:00:56</td>
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</tr>
<tr>
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**TABLE I**

**B** COSTS OF RUNNING iDiSE VS. FULL SYMBOLIC EXECUTION FOR tcas.
whereas full symbolic execution generates 24 path conditions because it explores the entire symbolic state space. The results in Table II and Table III illustrate the configurability of DiSE and iDiSE and show the tradeoff in cost and precision for these configurations.

Note that we do not attempt to compare DiSE and iDiSE directly; however, we note that DiSE is useful as an inexpensive, local analysis of a method. If a change is made to an algorithm of a single method in a large system, DiSE can pinpoint the analysis to that method, avoiding the expense of a system-wide analysis. For programs with multiple methods, it is essential to use iDiSE so that the effects of the changes can be propagated between methods.

The threats to validity in our study include (1) the tools upon which our technique is built, e.g., SPF, JPF, Choco, (2) the selection of artifacts used to evaluate the benefits of iDiSE, and (3) the changes applied to create the mutants. Implementing iDiSE in another framework or using another constraint solver/decision procedure could produce different results; however, replicated studies with other tool frameworks would address this threat. The artifacts selected for our study are control applications that are amenable to symbolic execution. They are comparable in structure and complexity to other artifacts that we are aware of that are used to evaluate symbolic execution techniques. The mutant versions in the WBS example were created manually, and may or may not reflect actual program changes; however, the mutations were developed in a systematic way that considered program location, change type, and number of changes. The tcas example was chosen because it is a control system with a version history.

VI. RELATED WORK

The technique presented in this paper, iDiSE, combines static program slicing and symbolic execution to estimate the impact of changes made to software. The results of iDiSE characterize the impact in terms of program execution behaviors. iDiSE is an extension of our previous work in [7] that now includes an interprocedural analysis and options that enable the impact analysis to be configured to support the requirements of specific client analyses that use the DiSE and iDiSE results. The techniques most closely related to our work are Differential Symbolic Execution (DSE) [14] and Regression Model Checking (RMC) [19]. Like our technique, DSE utilizes symbolic execution to characterize the effects of program changes; however, DSE does not use program slicing techniques to improve the efficiency of symbolic execution. It instead relies on abstract summaries of unchanged code blocks. RMC uses differences between two versions of a program to drive pruning of the state space during model checking of the new version of the program. Similar to DiSE and iDiSE, RMC uses a static impact analysis to calculate ‘dangerous’ elements whose behavior may be impacted by the changes.

Many techniques have been developed to assist developers maintain evolving software. Tools that differ in terms of coverage, the notions of coverage with change impact information, and the impact analysis technique, iDiSE, can be used to support the specific requirements of the client analysis. We also introduce the algorithms supporting the interprocedural version of our analysis, iDiSE and demonstrate that like DiSE, the cost of generating impacted program behaviors using interprocedural DiSE, is less than the cost of full symbolic execution. In the future, we plan to conduct a more comprehensive evaluation comparing how the results of iDiSE can be used to improve the efficiency of client analysis techniques relative to other state-of-the-art techniques.

VII. CONCLUSIONS AND FUTURE WORK

In this paper, we illustrate how the results of our change impact analysis technique, iDiSE, can be used to support software evolution tasks, including testing and debugging. We describe novel configuration options that combine traditional notions of coverage with change impact information, and explain how the impact analysis performed by DiSE and iDiSE can be configured to support the specific requirements of the client analysis. We also introduce the algorithms supporting the interprocedural version of our analysis, iDiSE and demonstrate that like DiSE, the cost of generating impacted program behaviors using interprocedural DiSE, is less than the cost of full symbolic execution. In the future, we plan to conduct a more comprehensive evaluation comparing how the results of iDiSE can be used to improve the efficiency of client analysis techniques relative to other state-of-the-art techniques.

REFERENCES

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(a) Path conditions generated by iDiSE and full symbolic executions for the tcas example.

(b) TABLE III

DISE with various impact coverage configurations for TCAS.

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TABLE III

DISE with various impact coverage configurations for TCAS.