Ka-band Digitally Beam-formed Airborne Radar Using SweepSAR Technique

A paper describes a frequency-scaled SweepSAR demonstration that operates at Ka-Band (35.6 GHz), and closely approximates the DESDynl mission antenna geometry, scaled by 28. The concept relies on the SweepSAR measurement technique. An array of digital receivers captures waveforms from a multiplicity of elements. These are combined using digital beamforming in elevation and SAR processing to produce imagery.

Ka-band (35.6 GHz) airborne SweepSAR using array-fed reflector and digital beamforming features eight simultaneous receive beams generated by a 40-cm offset-fed reflector and eight-element active array feed, and eight digital receiver channels with raw data recorded and later used for beamforming. Illumination of the swath is accomplished using a slotted-waveguide antenna radiating 250 W peak power. This experiment has been used to demonstrate digital beamforming SweepSAR systems.

This work was done by Gregory A. Sadownik, Chung-Lun Chuang, Himad Ghaemi, Brandon A. Heavy, Lung-Sheng S. Lin, and Momin Quddus of Caltech for NASA's Jet Propulsion Laboratory. Further information is contained in a TSP (see page 1). NPO-48376

Multi-Beam Approach for Accelerating Alignment and Calibration of HY-SP-IRI-Like Imaging Spectrometers

A paper describes an optical stimulus that produces more consistent results, and can be automated for unattended, routine generation of data analysis products needed by the integration and testing team assembling a high-fidelity imaging spectrometer system. One key attribute of the system is an arrangement of pick-off mirrors that provides multiple input beams (five in this implementation) to simultaneously provide stimulus light to several field angles along the field of view of the sensor under test, allowing one data set to contain all the information that previously required five data sets to be separately collected. This stimulus can also be fed by quickly reconfigured sources that ultimately provide three data set types that would previously be collected separately using three different setups: Spectral Response Function (SRF), Cross-track Response Function (CRF), and Along-track Response Function (ARF), respectively.

This method also lends itself to expansion of the number of field points if less interpolation across the field of view is desirable. An absolute minimum of three is required at the beginning stages of imaging spectrometer alignment.

This work was done by Michael L. Eastwood, Robert O. Green, Pantazis Mouroulis, Eric B. Hochberg, Randall C. Hein, Linsey A. Kroll, Sven Gier, and James B. Coles of Caltech, and Riley Mehan of Tufts University for NASA's Jet Propulsion Laboratory. Further information is contained in a TSP (see page 1). NPO-47809

JWST Lifting System

A document describes designing, building, testing, and certifying a customized crane (Lifting Device — LD) with a strong back (cradle) to facilitate the installation of long wall panels and short door panels for the GH phase of the James Webb Space Telescope (JWST).

The LD controls are variable-frequency drive controls designed to be adjustable for very slow and very-short-distance movements throughout the installation. The LD has a lift beam with an electric actuator attached at the end. The actuator attaches to a rectangular strong back (cradle) for lifting the long wall panels and short door panels from a lower angle into the vertical position inside the chamber, and then rotating around the chamber for installation onto the existing ceiling and floor.

The LD rotates 360° (in very small increments) in both clockwise and counterclockwise directions. Eight lifting pads are on the top ring with 2-in. (≈5-cm) eye holes spaced evenly around the ring to allow for the device to be suspended by three crane hoists from the top of the chamber.

The LD is operated by remote controls that allow for a single, slow mode for booming the load in and out, with slow and very slow modes for rotating the load.

This work was done by William Tolleson of CSC Applied Technologies LLC for Johnson Space Center. Further information is contained in a TSP (see page 1). MSC-25176-1

Next-Generation Tumbleweed Rover

A document describes a next-generation tumbleweed rover that involves a split balloon system that is made up of two half-spherical air bladders with a disc between them. This disc contains all the electronics and instruments. By deflating only the bottom balloon, the rover can sit, bringing the surface probe into contact with the ground. The bottom balloon has a channel passing through it, allowing the surface probe to reach the surface through the balloon.