

# Gensym 2014 Users Group Conference

Hotel Du Louvre, Place André Malraux, Paris, France

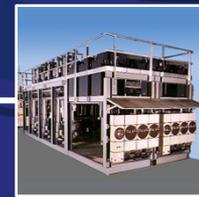
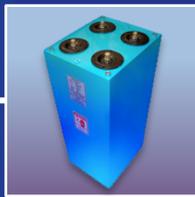
2 June 2014

## ISHM G2 Toolkit



Kim Wilkins, General Atomics, San Diego, CA, USA.

Fernando Figueroa, NASA Stennis Space Center, MS, USA.



Presented by: Kim Wilkins, San Diego, California  
[kim.wilkins@ga.com](mailto:kim.wilkins@ga.com) Cell 619 227 7050  
Senior Software Engineer



# Overview – ISHM Toolkit

## Integrated System Health Management

- **Toolkit for developing ISHM and Control applications**
- **Libraries of objects and methods to develop domain maps (models), such as electrical, computing, mechanical, thermal, hydraulic**
- **Libraries of fault trees (using Symcure)**
- **Built-in real time and simulator engines**
- **Built-in monitor creation, plotting, analysis**
- **Built-in sequencer to command and control via OPC to devices like PLCs**
- **User Interface is multiple Telewindows NG**

# Application Example

- **GA and NASA have jointly developed this toolkit originally at Stennis Space Center and currently used at the Kennedy Space Center in the Cryogenic Testbed Laboratory**
- **This is a testing facility for rocket refueling, one goal is to improve upon Shuttle refueling operations**
- **Allen Bradley PLC controlling valves, pumps, sensors**

# NASA Cryo Test Facility



# What liquid Nitrogen does at -320 F

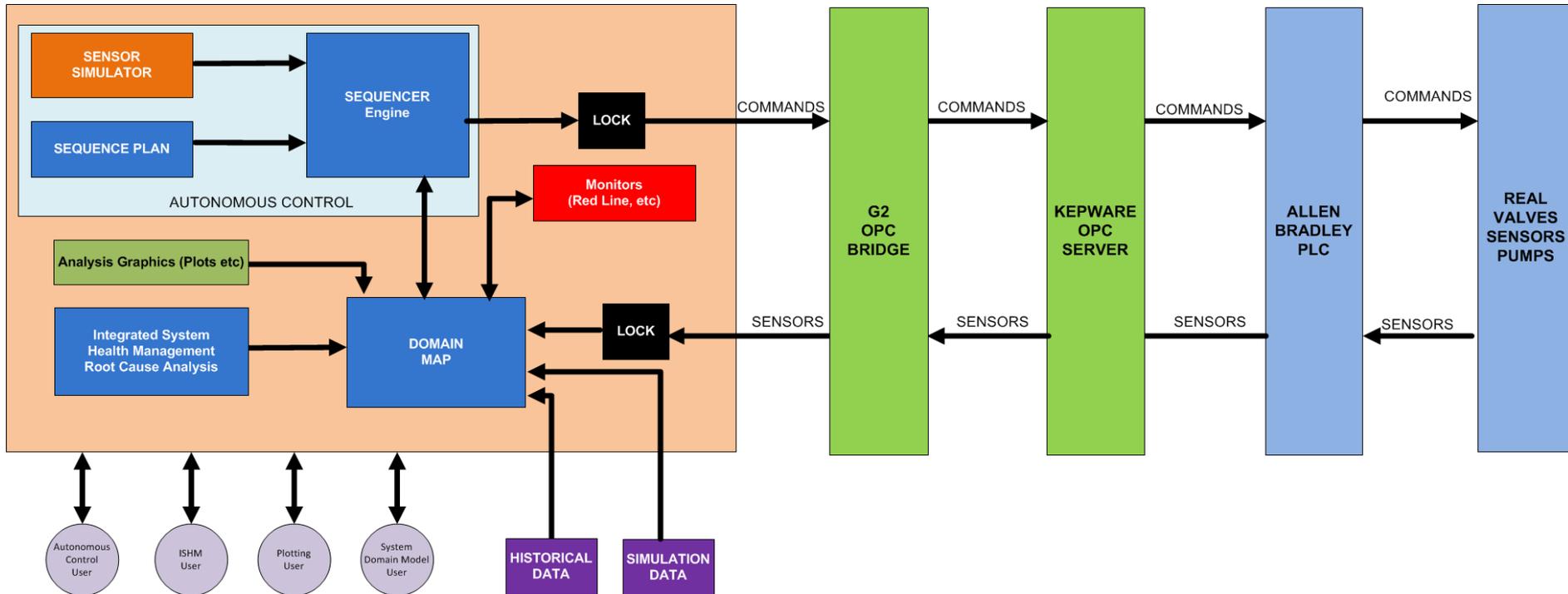


# User Interface



# Architecture

## Autonomous Control and ISHM



# Operational Modes

## REAL TIME

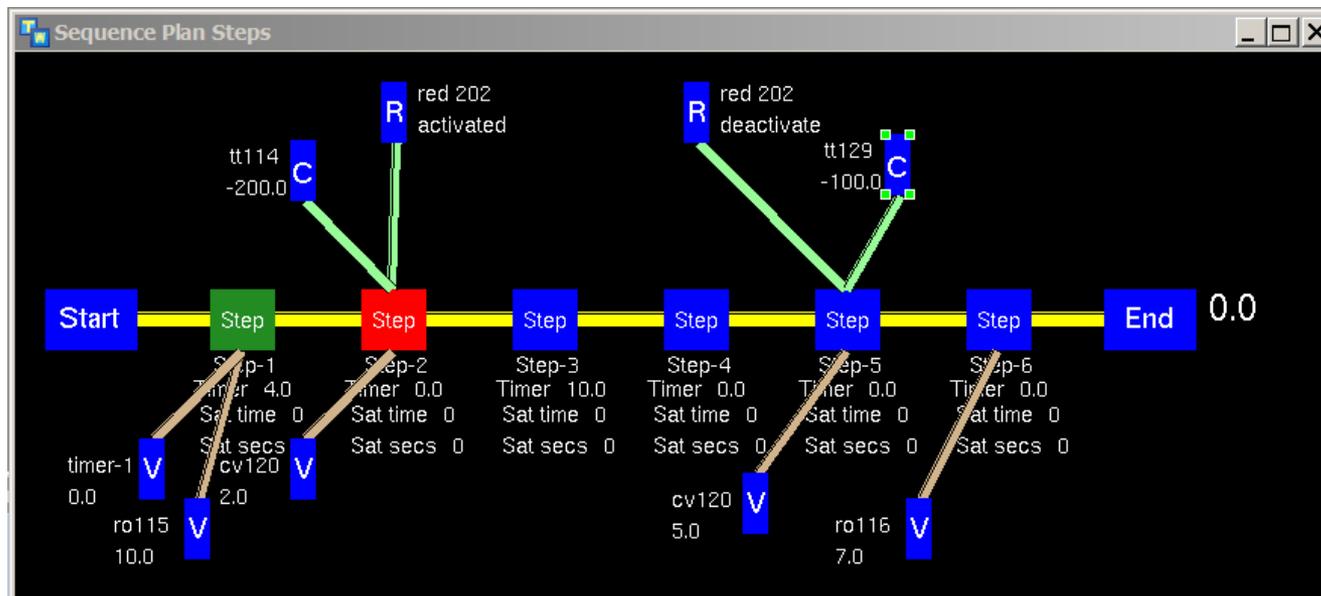
- System is designed in real time continuously
- Real time input data, monitoring with planned commanding and autonomous commanding as needed, manual commanding is also available

## REPLAY

- Can run in Replay mode using historical data, commanding has a built-in simulator, speed of data can be controlled

# Sequencer – Autonomous Commanding

- Sensor conditions, timers trigger next steps
- Command valves, pumps, cameras
- Red line conditions can trigger loading and execute shutdown or other plans



# Create Plan

Create/Modify Sequence Plan - red line test

Current Sequence Plan

	Step Label	Trigger	Boolean	Condition	Timer	Valve	Set Point	CAM View
Step-1					4.0			
Step-1						TIMER-1	0.0	
Step-1						RO115	10.0	
Step-2		TT114	Less Than	-200.0				
Step-2					0.0			
Step-2						CV120	2.0	
Step-2		red 202-TT202-L-0.0-H-0.0					ACTIVATED	
Step-3					10.0			
Step-4	step-1:23:52				0.0			
Step-5		TT129	Less Than	-100.0				
Step-5					0.0			

Create Condition

CURRENT CONDITIONS

	Trigger	Boolean	Condition
Step-2	TT114	Less Than	-200.0

SELECT CONDITION TO DELETE

TT114

Create Camera View

View: Unknown

SET VALVE/PUMP SETPOINTS/ACTIVATE TIMERS (no options)

Open
  Closed
  Variable

CURRENT SETPOINTS

	Valve/Pump	Setpoint
Step-2	CV120	2.0

SELECT SETPOINT TO DELETE

CV120

# Execute Plan

SEQUENCE PLAN CONTROL - test2

STEPS EXECUTED

	Step Label	Trigger	Boolean	Condition	Timer	Valve	Set Point	CAM View
Step-1						RO115	10.0	
Step-1						TIMER-1	0.0	
Step-1					4.0			

STATUS: PAUSED  Simulator Commanding

ACTIVE STEP      COUNTDOWN TO ACTIVATE STEP: 0.0 Seconds     

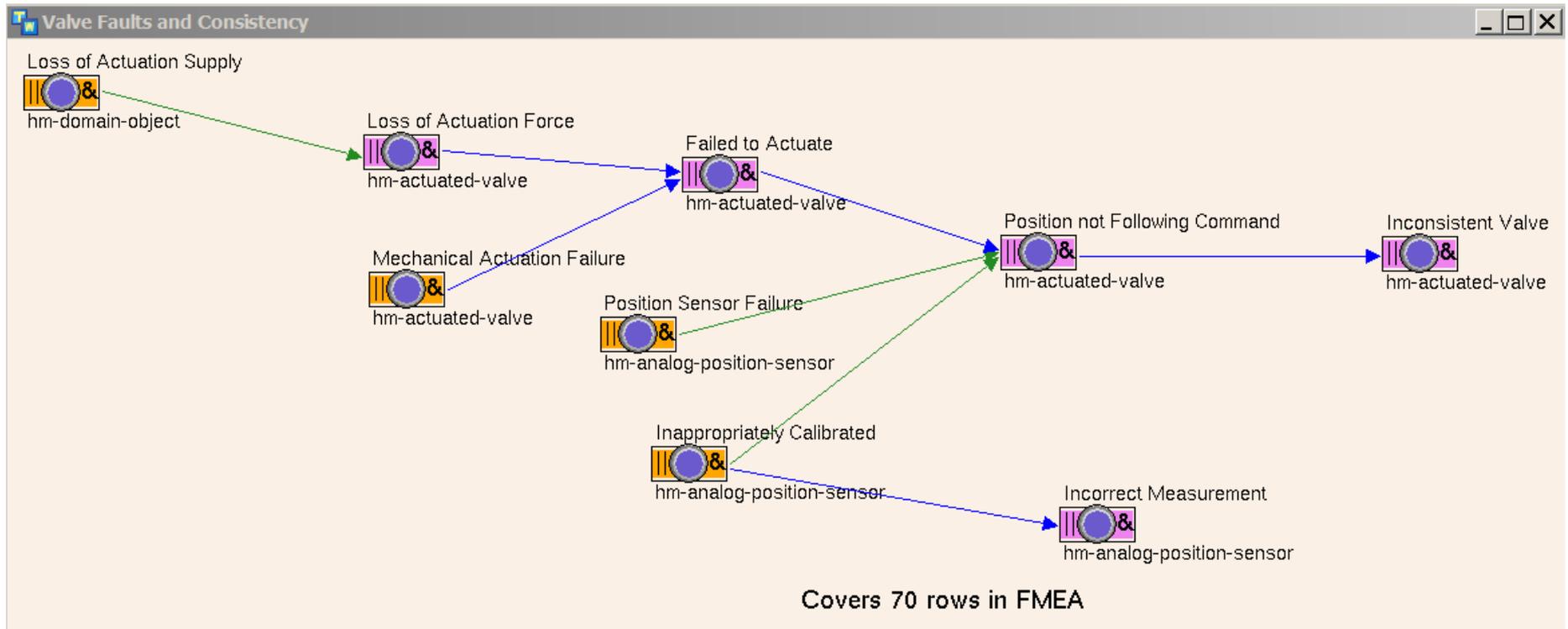
	Step Label	Trigger	Boolean	Condition	Timer	Valve	Set Point	CAM View
Step-2		TT114	Less Than	-200.0				
Step-2							CV120	2.0
Step-2		red 202-TT202-L-0.0-H-0.0					ACTIVATED	
Step-2					0.0			

FUTURE STEPS

	Step Label	Trigger	Boolean	Condition	Timer	Valve	Set Point	CAM View
Step-3					10.0			
Step-4	step-1.23.52				0.0			
Step-5		TT129	Less Than	-100.0				
Step-5					0.0			
Step-5						5.0	CV120	
Step-5		red 202-TT202-L-0.0-H-0.0					DEACTIVATE	
Step-6	step-1.23.52				0.0			
Step-6						7.0	RO116	

# Fault Diagnosis

- We use Symcure Fault Trees to model the FMEA
- We have libraries of various fault trees



# Monitors

**Data Monitor Configuration** [X]

PT102  
 PT104  
 PT107  
 PT109  
 PT116  
 PT122  
 PT124  
 PT126  
 PT132  
 PT138  
 PT145  
 **PT148**  
 PT152  
 PT161  
 PT164  
 PT173  
 PT180  
 PT183  
 PT190  
 PT193  
 PT197  
 PT198  
 PT199  
 PT207  
 PT208  
 PT209  
 PT220

Start Hours: 0 Start Minutes: 0 Start Seconds: 0 Red Line:   
 End Hours: 0 End Minutes: 0 End Seconds: 0  
 No Time Limit:  Limits Color: blue  
 STEP: None Found Line Color: green

**Maximum Value**  
 Enabled:  Setting: -200.000  
 Condition: Enter High Red Line Condition Here.

**Minimum Value**  
 Enabled:  Settings: -250  
 Condition: Enter Low Red Line Condition Here.

Save Changes Delete Next Create Current Monitor: 0  
 Monitor Name: test monitor Total Monitors: 0

AL Monitors - SELECT STATUS TO MANUALLY ACTIVATE/DEACTIVATE --- SELECT PLAN TO SELECT LOAD PLAN OR SET TO NO PLAN

	Status	Plan Assigned - Red/Yellow if Red Line, White if Normal	Triggered	Time Activated	Start Hrs	Minutes	Seconds	End Hrs	Minutes	Seconds	Lower Limit Active	Lower Limit	Higher Limit Active	Higher Limit
PT183	Activated	No Plan	Not Triggered	No	0	0	0	0	0	0	Yes	10.0	Yes	20.0
PT148	Deactivate	C:\shim-nasa-toolkit\sequence-plans\red_line_test.kb	Not Triggered	No	0	0	0	0	0	0	Yes	-250.0	Yes	-200.0

# Conclusions

- **Our toolkit can be used to implement autonomy capabilities in different application areas**
- **Build a model of domain using built-in classes**
- **Adapt data handling to fit application area**
- **Select diagnosis fault trees needed and adapt/build any new ones missing**
- **Customize User Interfaces for application**