Introduction

Some of the most interesting properties of the climate system are emergent (e.g., sensitivity to external forcing, predictability at the regional scale). By emergent we mean a property that arises from complex interactions between, for instance, dynamics, radiation, cloud formation, and surface fluxes, rather than being a function of a single physical process. Most of the traditional global-scale diagnostics used for climate model evaluation are therefore emergent. Emergence therefore complicates our ability to attribute a systematic model-observation discrepancy to a specific piece of code or model assumption. Indeed, model developers are often left to their experience and trial-and-error when addressing these discrepancies. Unsurprisingly, some notable discrepancies have persisted across multiple generations of climate model development (e.g., the double ITCZ problem). Even with the availability of large archives of coupled GCM output (e.g., CMIP5) and complementary observations to go with them (e.g., Obs4MIP) our ability to address certain questions is limited.

There are three main sources of model/observation discrepancy: 1) the model is deficient, 2) the data is deficient, or 3) the comparison is inappropriate or misleading. Many things lead to the third situation. For example, Eulerian time averaging is often seen as a desirable form of data compression for such comparisons. However, the concept of emergence means that each field is strongly influenced by the cumulative actions of intermittent and transient phenomena that cannot be seen directly in the time mean of the field (e.g., convective storms and cyclones). As a result, comparisons using time means are unlikely to reveal why a discrepancy exists (i.e., situation 3). This suggests the need for a more effective approach to diagnostic model development.

Often these approaches can take the form of a Lagrangian average. However, there is no guarantee that the trajectory of a given particle will be representative of all particles. Thus, on intercomparison, one needs to account for the representation of such models. In this way process-based diagnostics (PBDs) broaden the pool of traditional climate model validation methods.

Use Case - Extratropical Cyclones

Extra-tropical cyclones make excellent candidates for PBDs because: 1) Cyclones are specific, identifiable and well understood phenomena. 2) Cyclone activity shapes the distribution many quantities on both climatic and weather scales (e.g., cloud, temperature, wind). 3) Cyclones are interesting internal and external variability. 4) While today’s climate models can in principle resolve basic cyclone features, they are still not able to represent smaller key features (e.g., fronts), and questions remain about their ability to capture more subtle changes in cyclone behavior and structure (e.g., variations between seasons, hemispheres). Indeed, mid-latitude cyclone clouds are a key source of inter-model difference in climate sensitivity (Williams and Tellmann, 2010).

An ongoing project led by one of us, “The MAP Climatology of Mid-latitude Storminess” or MCMS, is designed to address just these sorts of questions (see Fig. 2, http://gcss-dime.giss.nasa.gov/mcms/mcms.html).

Figure 2: A limited example of MCMS. We start by scanning the SLP field (sea level pressure, contours) for local minima. This creates a pool of candidate cyclone centers (black squares) and discarded centers (orange circles). The retained centers are then fed into a tracking algorithm, which connects current and past centers via nearest neighbor compression for such comparisons. However, the concept of emergence means that each field is strongly influenced by the cumulative actions of intermittent and transient phenomena that cannot be seen directly in the time mean of the field (e.g., convective storms and cyclones). As a result, comparisons using time means are unlikely to reveal why a discrepancy exists (i.e., situation 3). This suggests the need for a more effective approach to diagnostic model development.

Maps showing the GISS-NRA2 difference in: a) conditional mean cyclone SLP, b) cyclone track density (frequency of occurrence per 10° latitude), c) cyclone density and d) point of minimal SLP. Panel a) depicts the life-cycle of the cyclone central SLP with the mean (black) and standard error (bars) organized around the point of minimal SLP for each track.

MCMS allows us to take a process-based approach to this same discrepancy. To start, we found the conditional mean SLP associated with cyclone activity using the cyclone area (red and cyan fill in Fig. 2) from each cyclone passing through the study area as a mask. As can be seen in Fig. 4a, there is a close association between departures in cyclone related SLP and those found in the time-mean SLP (Fig. 3b).

Figure 4: Maps showing the GIASS-NRA2 difference in: a) conditional mean cyclone SLP, b) cyclone track density (frequency of occurrence per 10° latitude), c) cyclone density and d) point of minimal SLP. Panel a) depicts the life-cycle of the cyclone central SLP with the mean (black) and standard error (bars) organized around the point of minimal SLP for each track.

Here we used the PBDs provided by MCMS to highlight a reanalysis-climate model discrepancy in time-mean SLPs. We found that this discrepancy is a matter of enhanced coastal cyclogenesis and differences in cyclone decay. As a result, the model developer’s points of view are more than just targeted concerns than could have been obtained by traditional methods alone. Moreover, the emergent nature of cyclones suggest that simple model adjustments are unlikely to help, but if a remedy were to be found, the benefits are apt to extend to many cyclone influenced quantities such as cloud and precipitation.

References

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