



Radiometric Calibration Techniques for Signal-of-Opportunity Reflectometers

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Transmitted electric field as quasi-monochromatic phasor

$$E_t(t, R) = \hat{p}_t \left(\frac{P_t G_t}{4\pi} \right)^{1/2} \frac{e^{-jkR}}{R} a(t - R/c) e^{j2\pi f_d t}$$

Frisi loss

Doppler shift referenced to observer

MOTIVATION

- Internal Calibration
 - Stabilizes receiver gains and offsets
 - Measures correlation efficiency
 - Defeats fluctuations with rapid and periodic updates
- Electronic Calibration Sources
 - Reference switch
 - Common noise source
 - Applicable to general SoOp reflectometers, e.g. [2]
- Similar to Conventional Microwave Instruments
 - L-band radiometer and scatterometers (e.g., [3]-[4])
 - Reference switches, noise diodes and loop-back circuits

METHODOLOGY

- Reference switching
 - Overcome thermal and 1/f fluctuations
 - Allows removal of receiver noise offset
 - Useful for low SNR direct antenna configurations
- Noise source firing
 - Allows measurement of receiver gains and correlation efficiency
 - Cross-power appears at zero delay
 - Simultaneously observe reflected cross-power when delay difference is much larger than coherence time of signal

REFERENCES

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[3] F.A. Pellerano et al., "The Aquarius Ocean Salinity Mission High Stability L-band Radiometer," *Geoscience and Remote Sensing Symposium*, 2006. IGARSS 2006, July 31 2006-Aug 4 2006. doi: 10.1109/IGARSS.2006.435

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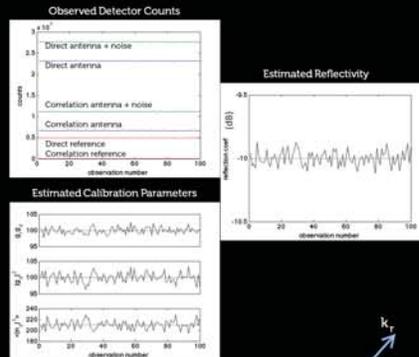
ABSTRACT

Bi-static reflection measurements utilizing global navigation satellite service (GNSS) or other signals of opportunity (SoOp) can be used to sense ocean and terrestrial surface properties. End-to-end calibration of GNSS-R has been performed using well-characterized reflection surface (e.g., water), direct path antenna, and receiver gain characterization [1].

Here, we propose an augmented approach using on-board receiver electronics for radiometric calibration.

Using similar techniques long-term (days to weeks) calibration stability of the L-band scatterometer and radiometer on Aquarius/SAC-D has been achieved better than 0.1% [5]. Similar long-term stability would likely be needed for a spaceborne reflectometer mission to measure terrestrial properties such as soil moisture.

SIMULATION RESULTS



State 1 $V_d = g_d(s_d(t) + n_d(t))$
 State 2 $V_d = g_d(s_d(t) + n_{dm}(t) + n_d(t))$
 State 3 $V_d = g_d(n_{ds}(t) + n_d(t))$



State 1 $V_r = g_r(s_r(t) + n_r(t))$
 State 2 $V_r = g_r(s_r(t) + n_{rm}(t) + n_r(t))$

SIMULATION & CALIBRATION

- Simulation parameters (static ground system)

Instrument parameters in units of counts (correlator output) and Kelvins (P/R)					
Antenna Gains	0 dBi	SNR of direct look	10 dB	Sky temperature	10
RF Gain	100	Receiver BW and Signal Type	10 MHz GFSK	Reflected look antenna temp.	150
Receiver noise temp	200	Reference load temperature	250	Noise source effective temp.	450

- Calibration Equations

$$g_d g_r^* = [K_{rd}(\text{State 2}) - K_{rd}(\text{State 1})] / T_{CNS}$$

$$|g_d|^2 = [K_{dd}(\text{State 2}) - K_{dd}(\text{State 1})] / T_{CNS}$$

$$\langle |n_d|^2 \rangle = K_{dd}(\text{State 3}) / |g_d|^2 - T_{ref}$$

Cross-correlation function with range-tracking

$$\text{Receiver gain ratio} \quad \text{Reflectivity} \quad |\Gamma|^2 = \frac{G_d}{G_r} \left| \frac{g_d}{g_r} \right|^2 \frac{K_{rd}((R_r - R)/c)}{K_{dd}(0) - \langle |n_d|^2 \rangle |g_d|^2}$$

Antenna gain ratio

Offset caused by sky and receiver noise

Auto-correlation function at zero lag

(Doppler-shift notation removed for simplicity - ground-based case)

