Unmanned Aircraft Systems (UAS) Integration in the National Airspace System (NAS) Project
NASA Contributions to the SARP WC Definition

Debra Randall
UAS UAS Chief Systems Engineer

Maria Consiglio
Confesor Santiago
UAS NAS Sense and Avoid Co-Project Engineers

28-29 October, 2014
SARP Well Clear Industry Day
Laurel, MD
www.nasa.gov
### NASA Controller Acceptability Study and ACES Simulation

<table>
<thead>
<tr>
<th>Acceptability Metric</th>
<th>NASA Controller Acceptability Study</th>
<th>MIT/LL Monte Carlo</th>
<th>USAF Open/Closed Loop Simulation</th>
<th>NASA ACES Simulation</th>
</tr>
</thead>
<tbody>
<tr>
<td>TCAS II RA Rate</td>
<td>✔</td>
<td>✔</td>
<td>✔</td>
<td>✔</td>
</tr>
<tr>
<td>Controller Acceptability Considerations</td>
<td>✔</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Well Clear Volume Penetration Rate</td>
<td></td>
<td>✔</td>
<td>✔</td>
<td>✔</td>
</tr>
<tr>
<td>Crosstrack Deviation</td>
<td></td>
<td>✔</td>
<td>✔</td>
<td>✔</td>
</tr>
<tr>
<td>Vertical Deviation</td>
<td></td>
<td>✔</td>
<td>✔</td>
<td>✔</td>
</tr>
<tr>
<td>Maneuver Initiation Point</td>
<td></td>
<td>✔</td>
<td>✔</td>
<td>✔</td>
</tr>
<tr>
<td>CPA Miss Distance/Time Given Well Clear Violation</td>
<td></td>
<td>✔</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mitigated Risk Ratio</td>
<td></td>
<td>✔</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
• Provides a direct assessment of Well Clear Boundary (WCB) operational acceptability by air traffic controllers (i.e., operators)
  o CAS1 simulates lower altitude, moderate-complexity Class E airspace operations
  o These operations are challenging for WCB definitions and DAA: more well-clear encounters, more traffic flow constraints
  o Controllers for this airspace are arguably most accustomed to well clear encounters and accommodating them along with other separation services

• Provides insight into both minimum and maximum acceptable WCB sizes
  o Air Traffic Controllers (ATC) require a WCB that works within the existing operations of the National Airspace System (NAS)
  o A WCB that is too small will cause safety concerns for ATC, and potentially distract attention from other encounters in the sector, but
  o A WCB that is too big will disrupt traffic flow, and increase ATC workload due to secondary conflicts and cross-sector coordination

• Provides an additional look at TCAS II Corrective RA Rates between WCB definitions, using the CAS1 encounter set
Benefits of ACES Simulations

- Airspace Concept Evaluation System (ACES) Simulations
  - Simulate UAS traffic from various proposed missions with “UAS-like” aircraft models
  - Collect NAS-wide encounter data within various classes of airspace
  - Simulate 100s of thousands of flight hours in a matter of days
  - Evaluate well-clear violation rates against historical VFR radar data (RADES)
CAS1 Research Approach

• Construct a set of simulated “well clear encounters”
  - Different miss distances, encounter geometries, relative speeds

• Embed these encounters into simulated background traffic scenarios representative of moderate-workload TRACON traffic (IFR and VFR) on a calm, clear-weather day

• Ask a series of ATC volunteers to “control” the simulated traffic scenarios, and measure the results
  - Direct query after each encounter
  - Workload and performance measures throughout

• Perform statistical analysis of all data afterward to assess the range(s) of acceptable horizontal miss distances
  - 14 controllers, 84 simulation hours, 1176 queries
Scenarios focused on ATC sector handling arrivals to Collin County Regional (McKinney – TKI), ~28 nmi NE of DFW

Feature-rich airspace:
• Class B, 4000-11000’ above TKI
  • VFR & IFR aircraft all under positive control, all cooperative
• Class D, SFC-2900’ around TKI
  • VFR & IFR cooperative aircraft receiving Class D ATC services
• Class E, 700’ or 1200’ AGL up to FL180 and outside Class B and D
  • IFR aircraft
  • VFR aircraft, some receiving ATC services, some not
  • CAS1 Well Clear encounters occurred in this airspace
• Class G, SFC to overlying airspace
• Nearby non-towered airports
Ratings for Opposite Direction encounters
Mean of 14 ATC subjects for each encounter

Rating Scale: After each “well clear encounter” test subjects were asked to rate the horizontal miss distance (HMD) on a five-point scale: From 1=Too Close to 5=Too large

Note: All Horizontal Miss Distances required a UAS lateral maneuver (initially a collision course)
Ratings for Opposite Direction encounters
Rating % by HMD for <3, 3, and >3 Ratings

Rating % by HMD for < 3 Rating (OD)
“Too Close”

Rating % by HMD for Rating of 3 (OD)
“Okay”

Rating % by HMD for > 3 Rating (OD)
“Too Wide”

• Horizontal Miss Distance (HMD) of ~1.5 nmi appears optimal for ATC acceptability

• HMD range of 1-2 nmi looks good

OD = Opposite Direction encounters
For each CAS1 “well clear encounter” and each WCB candidate:

– Assess HMD value

– Use encounter geometry and HMD to determine CAS1 ATC measured acceptability rating (interpolate as necessary)
### Average HMD ratings:

<table>
<thead>
<tr>
<th>Model</th>
<th>Opposite Direction</th>
<th>Overtake</th>
<th>Crossing</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>HMD</td>
<td>Rating</td>
<td>HMD</td>
</tr>
<tr>
<td>USAF</td>
<td>0.87</td>
<td>2.9 *</td>
<td>0.72</td>
</tr>
<tr>
<td>MIT LL</td>
<td>0.67</td>
<td>2.3 *</td>
<td>0.67</td>
</tr>
<tr>
<td>NASA</td>
<td>1.0</td>
<td>3.0</td>
<td>1.0</td>
</tr>
</tbody>
</table>

* Interpolated
### CAS1 ATC Acceptability Assessment for WCB Candidates: Encounters Exactly at WCB

- **Percent < 3 (“too close”) rating:**

<table>
<thead>
<tr>
<th>Model</th>
<th>Opposite Direction</th>
<th>Overtake</th>
<th>Crossing</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>HMD</td>
<td>&lt; 3</td>
<td>HMD</td>
</tr>
<tr>
<td>USAF</td>
<td>0.87</td>
<td>30% *</td>
<td>0.72</td>
</tr>
<tr>
<td>MIT LL</td>
<td>0.67</td>
<td>55% *</td>
<td>0.67</td>
</tr>
<tr>
<td>NASA</td>
<td>1.0</td>
<td>19%</td>
<td>1.0</td>
</tr>
</tbody>
</table>

* Interpolated

- **Percent > 3 (“too wide”) rating:**

<table>
<thead>
<tr>
<th>Model</th>
<th>Opposite Direction</th>
<th>Overtake</th>
<th>Crossing</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>HMD</td>
<td>&gt; 3</td>
<td>HMD</td>
</tr>
<tr>
<td>USAF</td>
<td>0.87</td>
<td>7% *</td>
<td>0.72</td>
</tr>
<tr>
<td>MIT LL</td>
<td>0.67</td>
<td>4% *</td>
<td>0.67</td>
</tr>
<tr>
<td>NASA</td>
<td>1.0</td>
<td>11%</td>
<td>1.0</td>
</tr>
</tbody>
</table>

* Interpolated
Controller assessment of acceptable vertical deviations was performed during debrief sessions

- All preferred 500’ or less for level VFR-IFR encounters
- Opinions were negative when asked to assess effects of WCB “taller” than 500’, e.g.:
  - “Problematic”
  - “Would be a significant factor in congested airspace, if you’re working other aircraft it [<=500’] gives you another altitude”
  - “I don’t think it would be pretty”
  - “I would expect 500’ to be sufficient for a manned aircraft, it should be sufficient for an unmanned aircraft”
  - “Would be pretty disruptive”
For each CAS1 “well clear encounter” and each WCB candidate:

- Assess minimum HMD values
- Use encounter geometry (including the respective WCB candidate’s HMD) as input to simple CAS1 TCAS model
- Determine whether a corrective RA would have occurred for each well clear encounter geometry and WCB candidate
TCAS Tau and HMD threshold values for RA issuance are altitude-dependent (lower values at lower altitudes):

<table>
<thead>
<tr>
<th>Own Altitude (ft)</th>
<th>Tau (sec)</th>
<th>HMD (nmi)</th>
<th>HMD + 50%</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt; 1000 AGL</td>
<td>N/A</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>1000-2350 AGL</td>
<td>15</td>
<td>0.20</td>
<td>0.30</td>
</tr>
<tr>
<td>2350-5000</td>
<td>20</td>
<td>0.35</td>
<td>0.53</td>
</tr>
<tr>
<td>5000-10000</td>
<td>25</td>
<td>0.55</td>
<td>0.83</td>
</tr>
<tr>
<td>10000-20000</td>
<td>30</td>
<td>0.80</td>
<td>1.2</td>
</tr>
<tr>
<td>20000-42000</td>
<td>35</td>
<td>1.1</td>
<td>1.7</td>
</tr>
<tr>
<td>&gt;42000</td>
<td>35</td>
<td>1.1</td>
<td>1.7</td>
</tr>
</tbody>
</table>

Self Separation HMD distances should be no smaller than TCAS HMD values but may need to be larger for controller acceptability.
CAS1 TCAS RA Rate Evaluation Results

• For the 42 CAS1 encounters as simulated, TCAS model, and WCB candidate HMD values, one TCAS RA each occurred for the USAF and LL WCB candidates
  o HMD values are generally sufficient for all WCB candidates
  o TCAS sensitivity level and aircraft speeds are also low

• Results if all encounters flown between 5000-10000’ (e.g., 6000’):
  o USAF: 2 RAs
  o LL: 36 RAs (all but the overtake encounters)
  o NASA: 0 Ras

• Results if all encounters flown above 10000’:
  o USAF: 12 RAs
  o LL: 36 RAs (all but the overtake encounters)
  o NASA: 36 RAs (all but the overtake encounters)

• HMD > 1.2 nmi avoids RAs below Class A with this TCAS model
Modeling and Simulation: ACES

NAS-wide Simulation
- Gate-to-gate simulation of ATM operations
- Full flight schedule with flight plans
- Sector and center models with some airspace procedures

Simulation Agents
- Air traffic controller decision making
- Traffic flow management models
- Individual aircraft characteristics
- IFR Flight Tracks from ASDI data
- VFR Flight Tracks from 84th Squadron RADES data

4-DOF Trajectory Model
Aerodynamic models of aircraft
Models replicate pilot behavior
User-definable uncertainty characteristics
ACES Well-Clear Simulation and Analysis

**ACES**

- **UAS Missions**
- **Eight Days* of VFR Traffic**
- **Autoresolver**
- **Distributed System**
- **NAS**
- **Database:**
  - State Data
  - Intruders
  - Resolutions
  - WCVs
- **USAF WC**
- **NASA WC**
- **MIT LL WC**
- **Matlab Post Processing**
- **PPT Results**

* Over 25k UAS flight hours simulated in the NAS per day
# UAS Missions Characteristics

<table>
<thead>
<tr>
<th>UAS group</th>
<th>UAS Model</th>
<th>Duration (per flight)</th>
<th>Flights per day</th>
<th>Cruise Alt.</th>
<th>Flight Pattern</th>
</tr>
</thead>
<tbody>
<tr>
<td>Air Quality Monitoring</td>
<td>Shadow-B</td>
<td>1-4 hrs.</td>
<td>104-1044</td>
<td>4k, 5k, and 6k ft AGL</td>
<td>Radiator Grid Pattern</td>
</tr>
<tr>
<td>Cargo Transport</td>
<td>Cessna 208</td>
<td>varies</td>
<td>1.4k</td>
<td>2k-16k</td>
<td>Point to Point</td>
</tr>
<tr>
<td>Atmospheric Sampling</td>
<td>Global Hawk</td>
<td>1.5-13 hrs.</td>
<td>2352</td>
<td>5k-35k ft AGL</td>
<td>Radiator Grid Pattern</td>
</tr>
<tr>
<td>On-demand Remote Air Taxi - Cirrus</td>
<td>Cirrus SR22T</td>
<td>varies</td>
<td>8k</td>
<td>6k-11k</td>
<td>Point to Point</td>
</tr>
<tr>
<td>On-demand Remote Air Taxi - Mustang</td>
<td>Cessna Mustang</td>
<td>varies</td>
<td>2k-4k</td>
<td>9k-20k</td>
<td>Point to Point</td>
</tr>
<tr>
<td>Strategic Fire Monitoring</td>
<td>Predator-B</td>
<td>20 hrs.</td>
<td>74-324</td>
<td>31k ft MSL</td>
<td>Radiator Grid Pattern</td>
</tr>
<tr>
<td>Tactical Fire Monitoring</td>
<td>Shadow-B</td>
<td>1-1.5 hrs.</td>
<td>varies</td>
<td>varies</td>
<td>Circular Loitering Orbit</td>
</tr>
<tr>
<td>Flood Inundation Mapping</td>
<td>Aerosonde</td>
<td>1-4 hrs.</td>
<td>varies</td>
<td>4k ft AGL</td>
<td>Radiator Grid Pattern Point to Point</td>
</tr>
<tr>
<td>Flow Stream Monitoring</td>
<td>Aerosonde</td>
<td>1-4 hrs.</td>
<td>20-200</td>
<td>4k</td>
<td>Radiator Grid Pattern Point to Point</td>
</tr>
</tbody>
</table>
Cooperative VFR Traffic

• The 84th Rader Evaluation Squadron (RADES) data were used.
  o The data contain the radar hits collected from hundreds of radar sites in U.S, and each hit provide timestamp, latitude, longitude, Mode 3 code, Mode C code, and others.
  o There is no explicit information that could be used to determine whether radar hits come from IFR flights or VFR flights.

• Criteria for filtering out cooperative VFR traffic (for each tracked flight):
  o All tracks are below 18,000 ft,
  o At least one track has the Mode 3 code of 1200,
  o Average speed ranges from 50 knots to 250 knots.
Method for Extracting VFR Traffic

• Input: RADES data for a certain time period.

• Output: Flight plan file for a fast-time simulation system, Advanced Concept Evaluation System (ACES).

• Method (three steps):
  1. Generate tracks using a minimum spanning tree based clustering algorithm,
  2. Generate smooth tracks using a Kalman filter,
  3. Generate a flight plan file after reducing the number of waypoints and adding airports which are closest to start/end waypoints.

This becomes the basis of the traffic the UAS’s encounter for measuring well-clear violation rates.
Cooperative VFR Traffic Used for SARP

![Bar chart showing the number of Cooperative VFR Flights from January 14, 2012, to October 12, 2012. The chart indicates a gradual increase in the number of flights over time.](image-url)
Self-Separation Algorithm (Autoresolver)

• If a WCV is predicted to occur within a parametric time, e.g. 60 seconds, Autoresolver is engaged to command a resolution that solves the problem

• Autoresolver iterates through different horizontal and altitude maneuvers options that avoid WCV
  o During this process it tries to ensure an extra safety margin by putting buffers around horizontal miss distance and time threshold
  o If ownship is level, prefers the minimum left and right turn that avoids WCV over climb or descent
  o If ownship is transitioning vertically, prefers the closest temporary altitude hold that avoids WCV
TCAS-II RA Metric

**Probability of Well-Clear Violation (WCV) with TCAS RA prior to WCV**

- Assumption: Intruders (manned) experiencing TCAS-RA’s while UAS DAA system detects it as well-clear is undesirable. (Unmitigated)
- The smaller the better

\[
\text{Number of WCVs with TCAS-RA prior to WCV} = \frac{\text{Number of WCVs with TCAS-RA prior to WCV}}{\text{Total Number of WCVs}}
\]

- While detecting and resolving WCVs (mitigated), at what rate do we trigger a TCAS-RA? (Mitigated)

\[
\text{Number of WCVs with TCAS-RA prior to WCV} = \frac{\text{# of TCAS-RA’s}}{\text{Total UAS Flight Hour}}
\]
Probability of WCV with TCAS RA prior to WCV

- **MIT-LL**: 0.8%
- **NASA**: 3.5%
- **USAF**: 9.8%

![Bar Chart]

- Undesirable
- Desirable

- **Prob. Corr-RA**
- **Prob. Prev-RA**
TCAS-RA Rate

- MIT-LL: $8.47 \times 10^{-4}$ RAs / flt-hour (fewest)
- NASA: $3.9 \times 10^{-3}$ RAs / flt-hour (middle)
- USAF: $1.52 \times 10^{-2}$ RAs / flt-hour (most)
Well Clear Violation Penetration Rate

• When analyzing well clear violation rates between the three different models, it wasn’t clear if higher or lower rates were better.

• As a group, SARP weighted this metric of lower importance.

• All three models had about the same WCV rate.

• However, what was found to be interesting is verifying there were no unusual trends in WCV rate for the three WC models by different VFR traffic days or UAS mission profiles.
WCV Rate reveals similar trends within each day for each WC definition.
WCV Rate by UAS Mission Type

Well-Clear Violation Rate per $1 \times 10^2$ flight hours

*Aggregate at ~3 WCV per 100 flt-hours
Other Metrics

• We also collected the following metrics using ACES to support SARP Well-Clear Workshop:
  
  o **Maneuver Initiation Point** – points to surveillance performance requirements for detecting WCVs
  
  o **CPA Miss Distance for WCVs** – evaluates severity of WCVs
  
  o **Minimum Time from WCV to NMAC** – identifies worse case scenarios where little time is available from violating well-clear to having an NMAC
Summary of CAS1 Results

• Controller Acceptability Considerations
  o NASA WCB rated highest, followed by USAF WCB, followed by LL WCB
  o LL HMD of 4000’ (0.67 nmi) elicits a higher “too close” rating from controllers, but actual HMD values would likely be higher in practice due to horizontal buffers added for DAA sensor uncertainty
  o LL WCB “height” of 700’ rated low by controllers but subsequent FAA/RTCA modification of WCB to 450’ fixes this controller acceptability concern

• TCAS II RA Rate
  o For the CAS1 encounter geometries and TCAS model, the NASA model had the fewest RAs below 10000’ and the USAF model had the fewest above 10000’
  o Small HMD values cause higher RA rates, especially at higher altitudes and high closure rates
  o HMD values > 1.2 nmi minimizes RA issuance below Class A airspace with this TCAS model
Summary of ACES Simulations

• Collected encounter data with characteristics that resemble envisioned UAS missions interacting with historically cooperative VFR traffic in different classes of airspace with different “UAS-like” aircraft models
• Results complimented the analyses provided by USAF’s stressing cases and MIT LL’s Monte Carlo simulations
• Each well-clear model had areas of high and low performance with respect to the SARP-accepted metrics
• Overall, over 200,000 UAS flight hours of envisioned missions were simulated NAS-wide and used to help SARP determine a well-clear definition recommendation