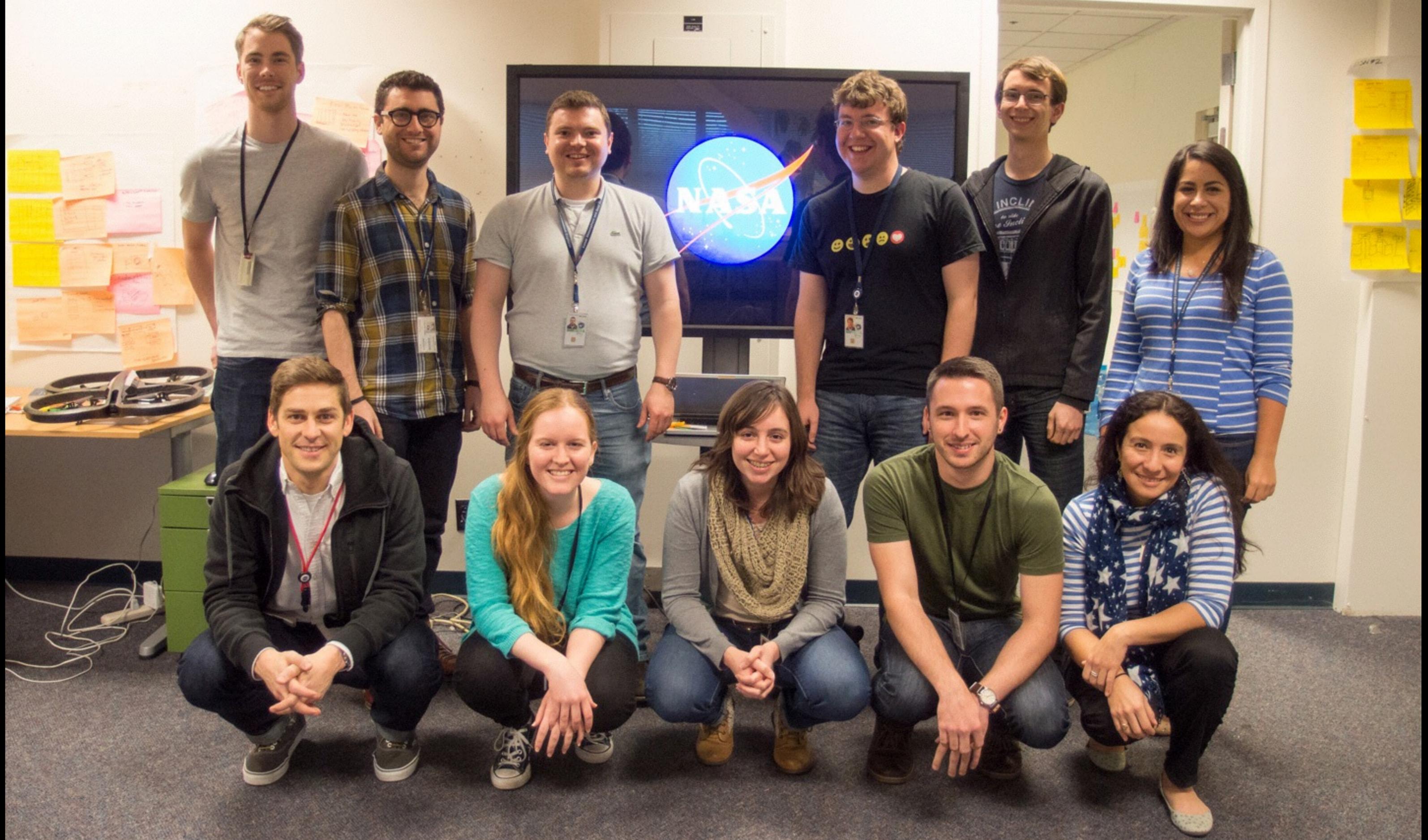
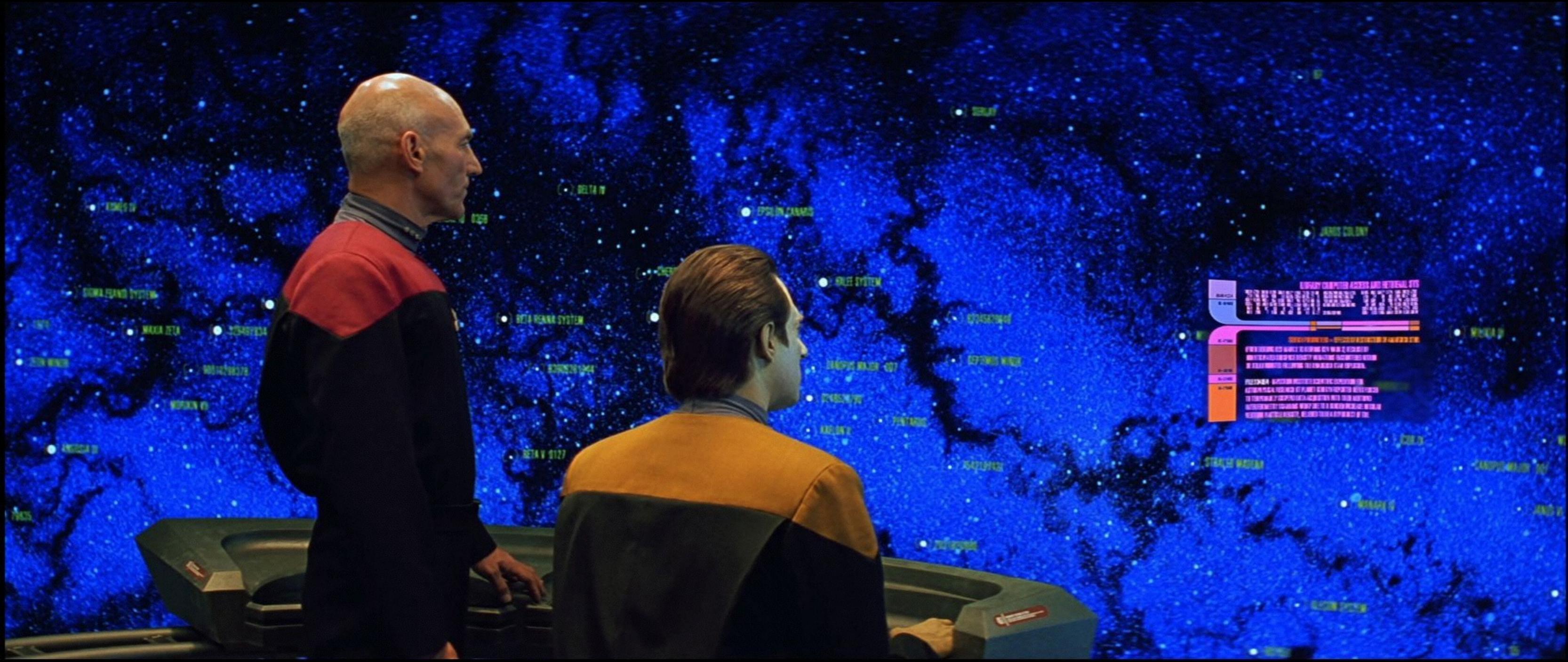


DESIGNING INTERFACES FOR ASTRONAUT AUTONOMY IN SPACE

Steve Hillenius, NASA
@hillenius







(Star Trek Generations)

340 MET
350 MET
4074 MET
4074 MET
4074 MET
4074 MET
08:19:00



229:16:01:30
PAC FE-6
ULTRAD SCAM
01:00:20
00:37:20



MISSION CONTROL CENTER



08:16:51:30
04:38:20
02:13:20
08:23:20
08:23:20
08:23:20



MTV 2
MTV 4



APEX



PLATO



SCORE

FLIGHT DIRECTOR

ETHOS

SPARTAN

THOR

OPER PLANNER

CAPCOM

TOPO

BME

Playbook for ISS

Jun 17

US/Central GMT

ISS-CDR

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FE-2

FE-3

FE-5

FE-6

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FE-1

КПТ-21-EXP
07:45 to 09:35 (110 minutes)
ПЛАЗМЕННЫЙ КРИСТАЛЛ. Performing
эксперимент ПЛАЗМЕННЫЙ КРИСТАЛЛ.
Проведение эксперимента в
полуавтоматическом (ручном) режиме.
radiogram 3/g...

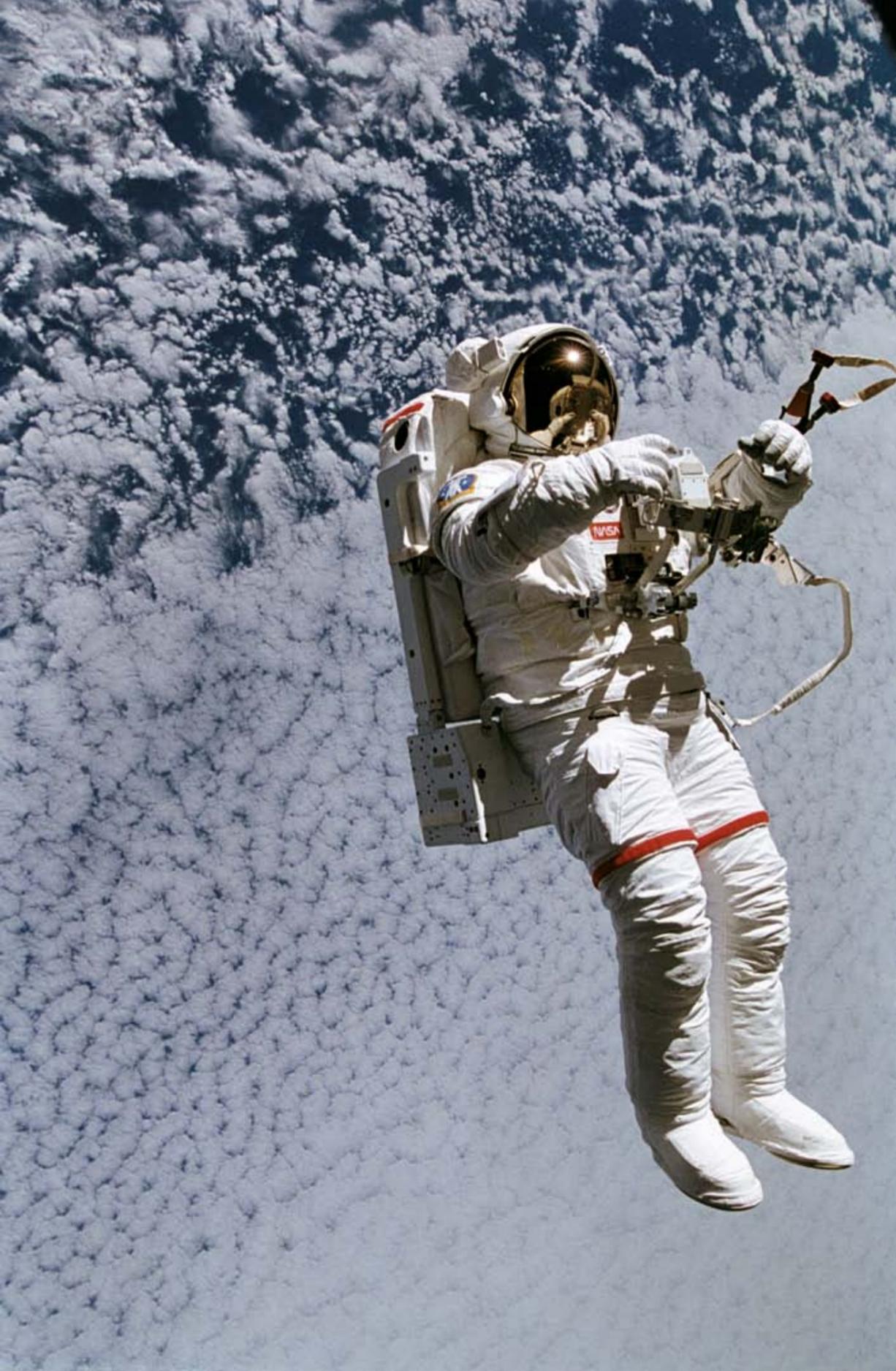
Mark as Done

Details...

КПТ-21-EXP-END
09:35 to 09:55 (20 minutes)
ПЛАЗМЕННЫЙ КРИСТАЛЛ. Performing
эксперимент (end) ПЛАЗМЕННЫЙ
КРИСТАЛЛ. Окончание эксперимента
radiogram 3/g...

СТТС-MRM2-PL-RCNF
09:55 to 10:00 (5 minutes)
СТТС reconfiguration in MRM2 TBD
Возврат в штатную конфигурацию
средств связи после окончания работ в
MRM2
СОФ-РТК, п. 8.8 ш. 4 стр. 8-26 (МСП 2.813
ш. 4)...

КПТ-21-DNLD



crew autonomy: allowing astronauts to make decisions on their own, with limited input from mission control



crew autonomy: allowing astronauts to make decisions on their own, without input from mission control

Why is it important?

- Astronauts want more autonomy
- Increased situational awareness
- Increased efficiency
- Future deep space missions



It can take anywhere from 8 to 48 minutes for roundtrip communication between Earth and Mars.









science experiments
maintenance
education/public outreach

mission planning
power planning
positioning and control
of the station
support for the crew

plus tons of other really **important** things!



6 astronauts



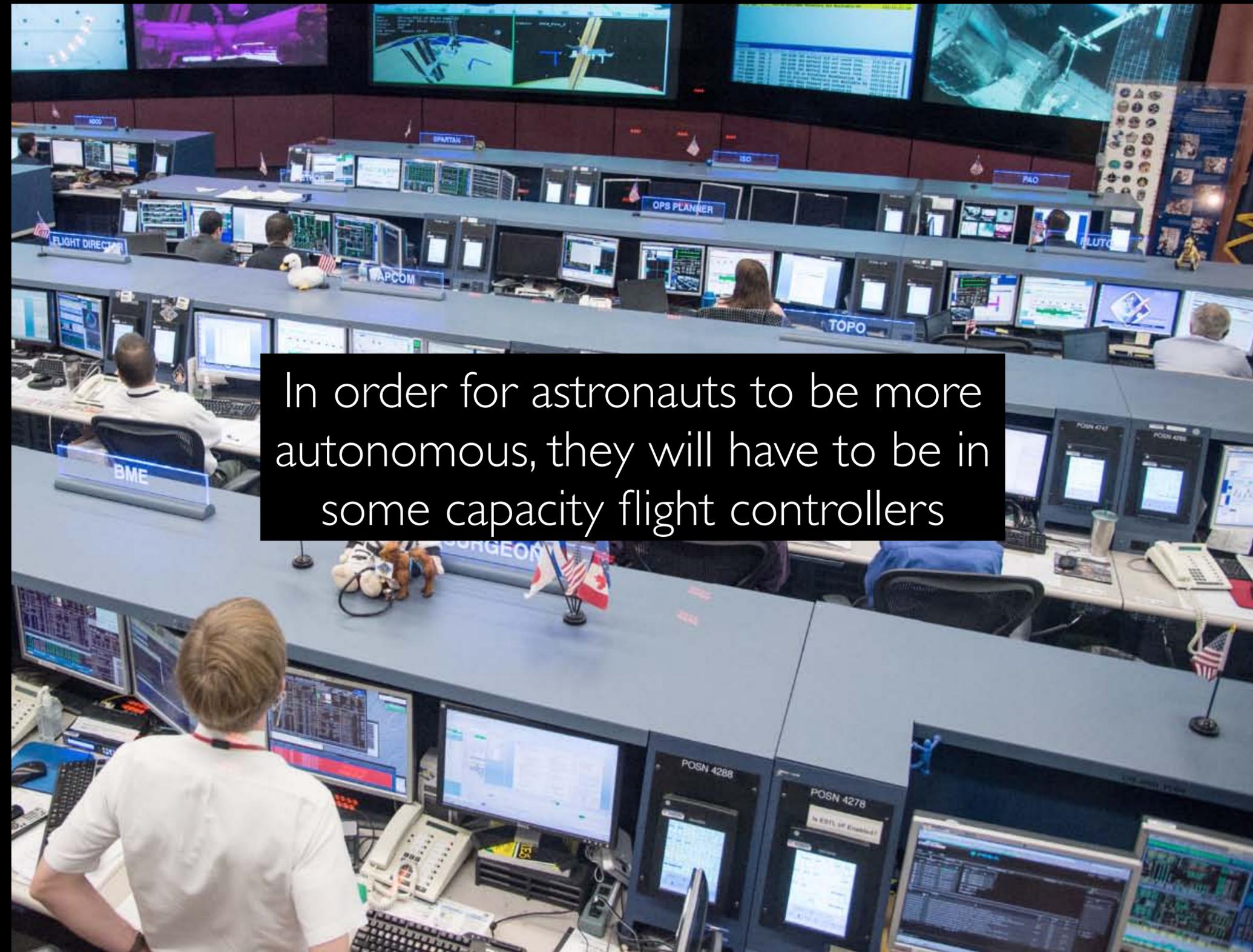
100s of flight controllers



6 astronauts



100s of flight controllers



In order for astronauts to be more autonomous, they will have to be in some capacity flight controllers

How do you design a tool that
allows astronauts to plan and
control their own missions?

*How do you design a tool that lets an
astronaut take on the roles of
hundreds of people?*

Design Constraints

Balance

Walk up and use

Mobile

Empowering

Efficient and Effortless

Advise, not enforce

Communication Time Delay Tolerant

NODE 1 FORWARD CBM FIRST STAGE CAPTURE

(ASSY OPS/5A/FIN) Page 1 of 3 pages

I

OBJECTIVE:

Perform first stage capture following translation of U.S. Lab into ready-to-latch position for berthing to Node 1 Forward Active Common Berthing Mechanism (ACBM).

CBM capture latches are driven from initial position of 200° (fully deployed) to approximately 186°.

LOCATION:

Node 1/AFD EPCS

DURATION:

5 minutes

REFERENCED PROCEDURE(S):

LAB INSTALL (FDF: PDRS OPS, NOMINAL LAB OPS)

NOTE

1. Step titles followed by the notation "(AOS/M)" indicate that AOS during the execution of that step is mandatory. If currently LOS or expecting LOS prior to completion of an AOS/M step, wait for the next AOS to perform step.
2. For any off-nominal steps or any attention symbols that appear, refer to {NODE 1 CBM MATE MALFUNCTION} (SODF: ASSY MAL: MALFUNCTION: CBM).
3. Step 1 is nominally performed with the SRMS in Position Hold mode.
4. Capture sequence may be initiated with three of four RTLs closed. In this case, the latch associated with the open RTL must be masked.

1. READY-TO-LATCH INDICATORS (RTLs) CLOSED VERIFICATION

√Step 7 of LAB INSTALL complete (FDF: PDRS OPS, NOMINAL LAB OPS)

PCS

Node 1: S&M
Node 1:S&M

sel Forward CBM

Node 1 Forward CBM Display
'Functional CBM Representation (External View)'

√RTL indications (four) – green

NODE 1 FORWARD CBM FIRST STAGE CAPTURE

(ASSY OPS/5A/FIN) Page 2 of 3 pages

.....
If RTL X (where X = 1, 2, 3, 4) is gray after repeated attempts to gain ready to latch indication

√MCC for go

sel Latch X

Capture Latch X Details

sel Commands

Latch_X_Cmds

cmd Mask Latch X **Execute**

Node 1 Forward CBM Display
'Functional CBM Representation (External View)'

√Latch X – Ø
.....

2. FIRST STAGE CAPTURE PERFORMANCE (AOS/M)

CAUTION

To prevent damage to active CBM (ACBM), free drift (DAP: FREE for shuttle control or thruster inhibit for SM control) is required from initiation of CBM capture latch operation until a minimum of eight alternating bolts (every other bolt) have completed the ABolts command. SRMS shall remain grappled to U.S. Lab until such time.

A6U

√DAP: FREE

PCS

Node 1 Forward CBM Display
'Commands by Task'

sel Mate

Node 1 Fwd CBM Mate
'Capture Passive CBM'

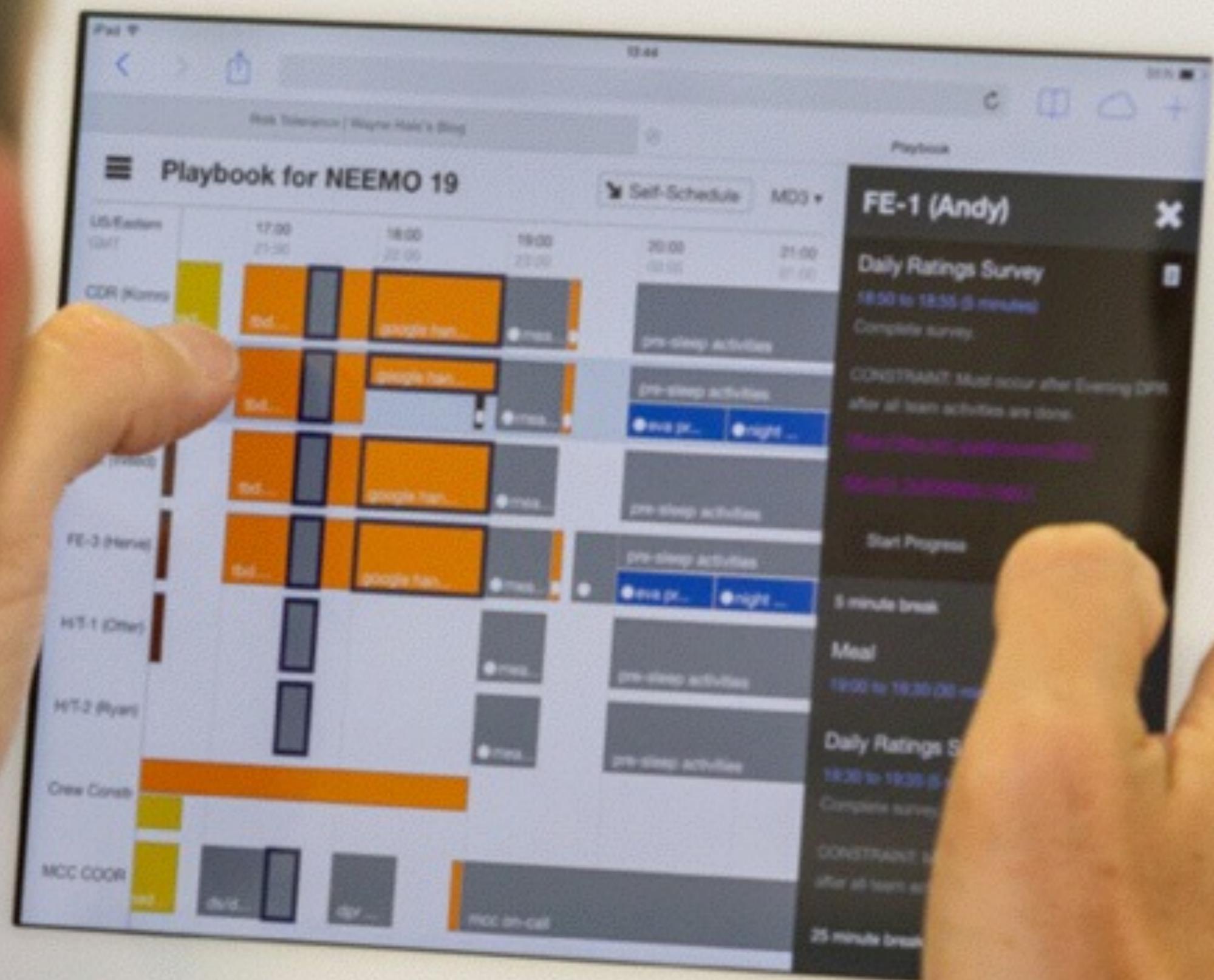
cmd Capture First Stage **Execute**

'Confirmation Request'

√Override Capture Command?

cmd Yes **Execute**
(Command requires approximately 15 seconds.)







(Rebecca Boyd)

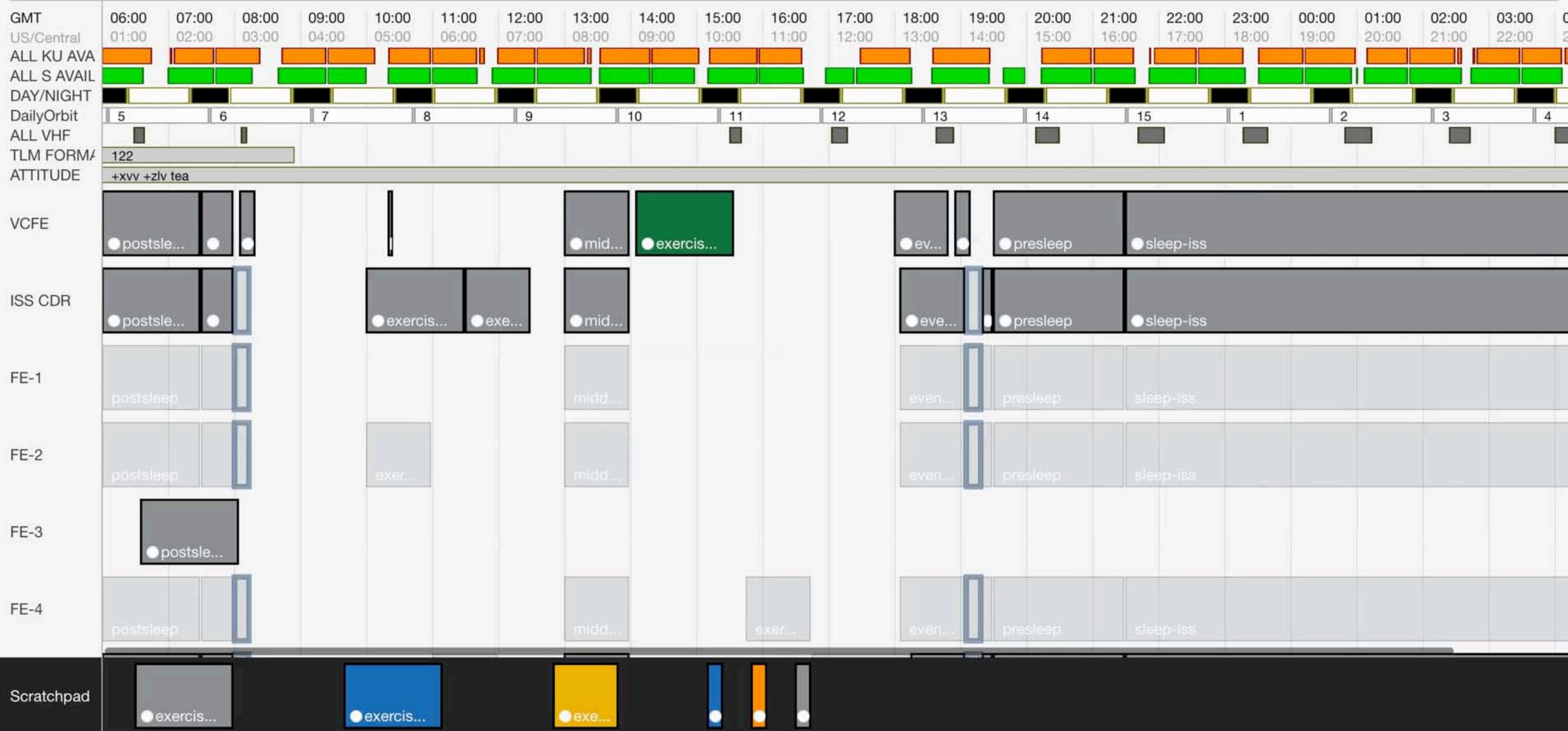
Playbook for ISS

Zoom In

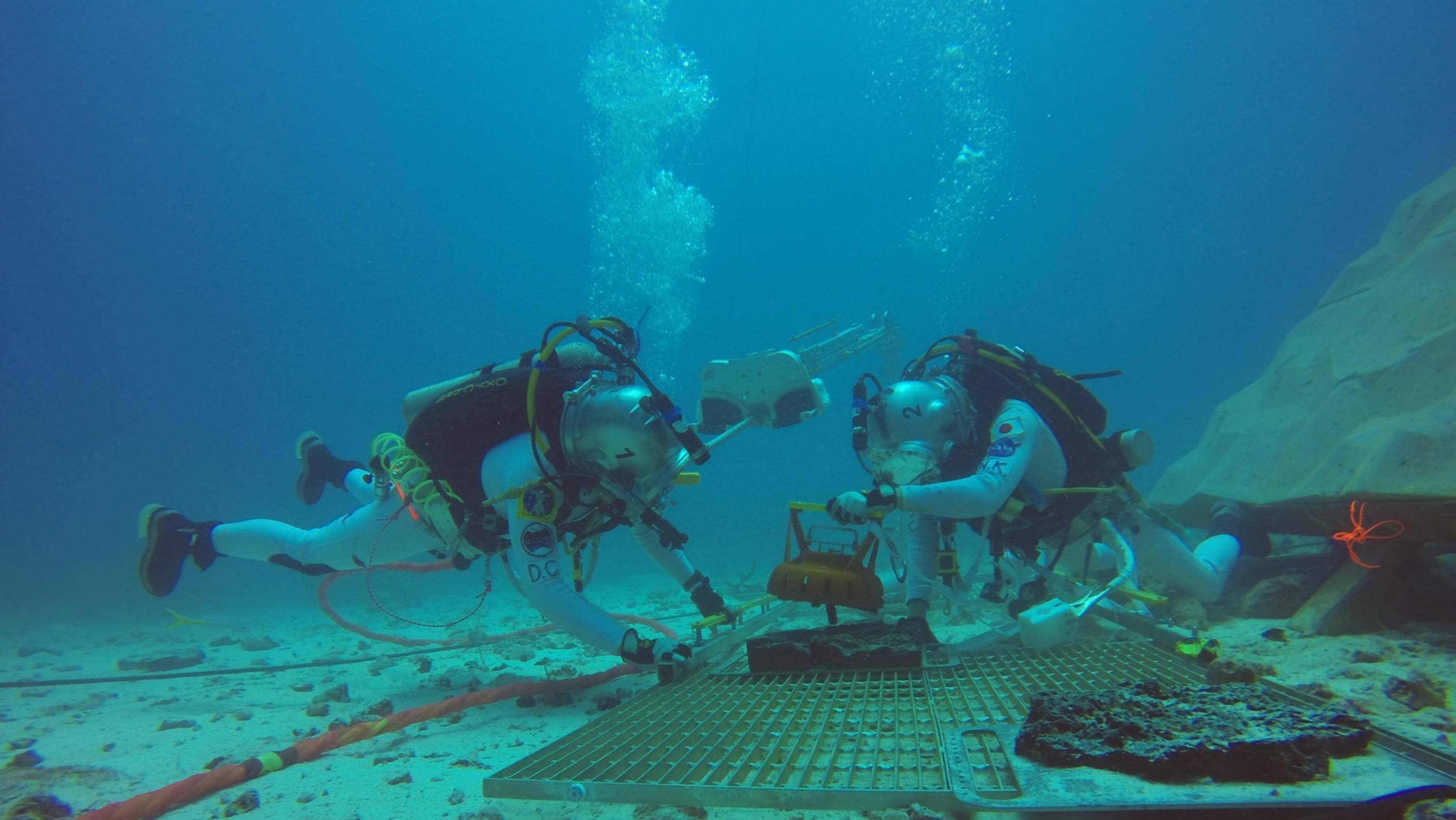
Zoom Out

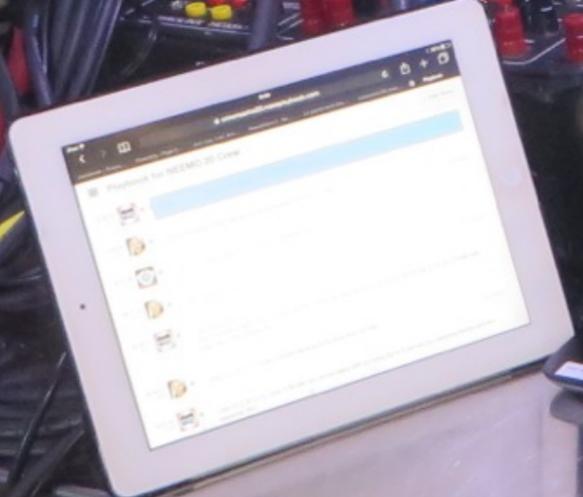
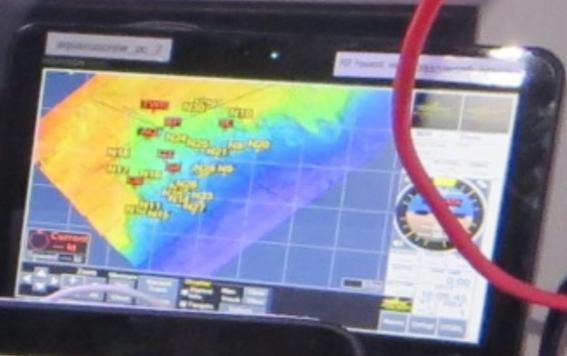
Self-Schedule

Sep 16











Zoom In Zoom Out Self-Schedule MCI

Playbook for NEEMO 20

14:00:00 EDT
18:00:00 EDT

US/EAS/ISSM
 Lander EVA
 CDR (Lund)
 FE-1 (Barnes)
 FE-2 (Nemo)
 FE-3 (Dawd)
 TECH-1 (OK)
 TECH-2 (Da)

Copy on EV1 is FE-1 (Red Deer, Barnes) and EV2 is FE-2 (Green Deer, Nemo)

In our previous message, read "without need," instead of "left need"

Copy 1000-1000000

Understood Luca. Our plan is to share the work load with you to reduce the scan pattern requirement. We will drop you a reminder on mission log or via S42 for the scan rating calls. The log was fixed during lunch time. If you get update a error, it should keep on updating automatically with need from you to refresh.

We received the role for the afternoon EVA. There's a bit of info, and a bit of requests, we were never advised that you'd need a scan rating every 30 minutes. That's another thing to add to the scan pattern, which is already full. Expect us to not be able to comply.

Boom, we already tried both of your suggestions. It's still hard. If we keep the log open at all times it won't update, there needs to



PLANNING WINDOW

14:00:00 EDT
18:00:00 EDT

US/EAS/ISSM
 Lander EVA
 CDR (Lund)
 FE-1 (Barnes)
 FE-2 (Nemo)
 FE-3 (Dawd)
 TECH-1 (OK)
 TECH-2 (Da)

14:00:00 EDT
18:00:00 EDT

US/EAS/ISSM
 Lander EVA
 CDR (Lund)
 FE-1 (Barnes)
 FE-2 (Nemo)
 FE-3 (Dawd)
 TECH-1 (OK)
 TECH-2 (Da)

FE-1 (Barnes)

Playbook for NEEMO 20

Copy on EV1 is FE-1 (Red Deer, Barnes) and EV2 is FE-2 (Green Deer, Nemo)

In our previous message, read "without need," instead of "left need"

Copy 1000-1000000

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14:00:00 EDT
18:00:00 EDT

US/EAS/ISSM
 Lander EVA
 CDR (Lund)
 FE-1 (Barnes)
 FE-2 (Nemo)
 FE-3 (Dawd)
 TECH-1 (OK)
 TECH-2 (Da)

14:00:00 EDT
18:00:00 EDT

US/EAS/ISSM
 Lander EVA
 CDR (Lund)
 FE-1 (Barnes)
 FE-2 (Nemo)
 FE-3 (Dawd)
 TECH-1 (OK)
 TECH-2 (Da)

14:00:00 EDT
18:00:00 EDT

US/EAS/ISSM
 Lander EVA
 CDR (Lund)
 FE-1 (Barnes)
 FE-2 (Nemo)
 FE-3 (Dawd)
 TECH-1 (OK)
 TECH-2 (Da)



F10 Program

NASA
NAVY

みんなの
夢の
せて

esa



Playbook for NEEMO 19

+ Add Note



Copy MD7 17:07:41. We'll be waiting!

Add Photo, Video, or Files

Add Note

17:09:19
MD7



Potted up yesterday:

- Skin-B Kit
- HEADS-UP laptop
- MobiPV kit
- 3 complete GGlass (with chargers and earbuds)
- Surface Sampling Kit

The rest of the hardware is packed in Aquarius and will follow us in the potting up today.

🕒 01:14 UNTIL DELIVERY · EARLIEST RESPONSE 17:19:19

17:07:41
MD7



Good morning NEEMO MCC! Or are we just speaking to an empty room because everyone is on call for a well deserved morning off? All is well and everyone is well at 7ft and ascending!

DELIVERED · EARLIEST RESPONSE 17:17:41



US/Eastern

GMT

Latency

EVA

CDR (Luca)

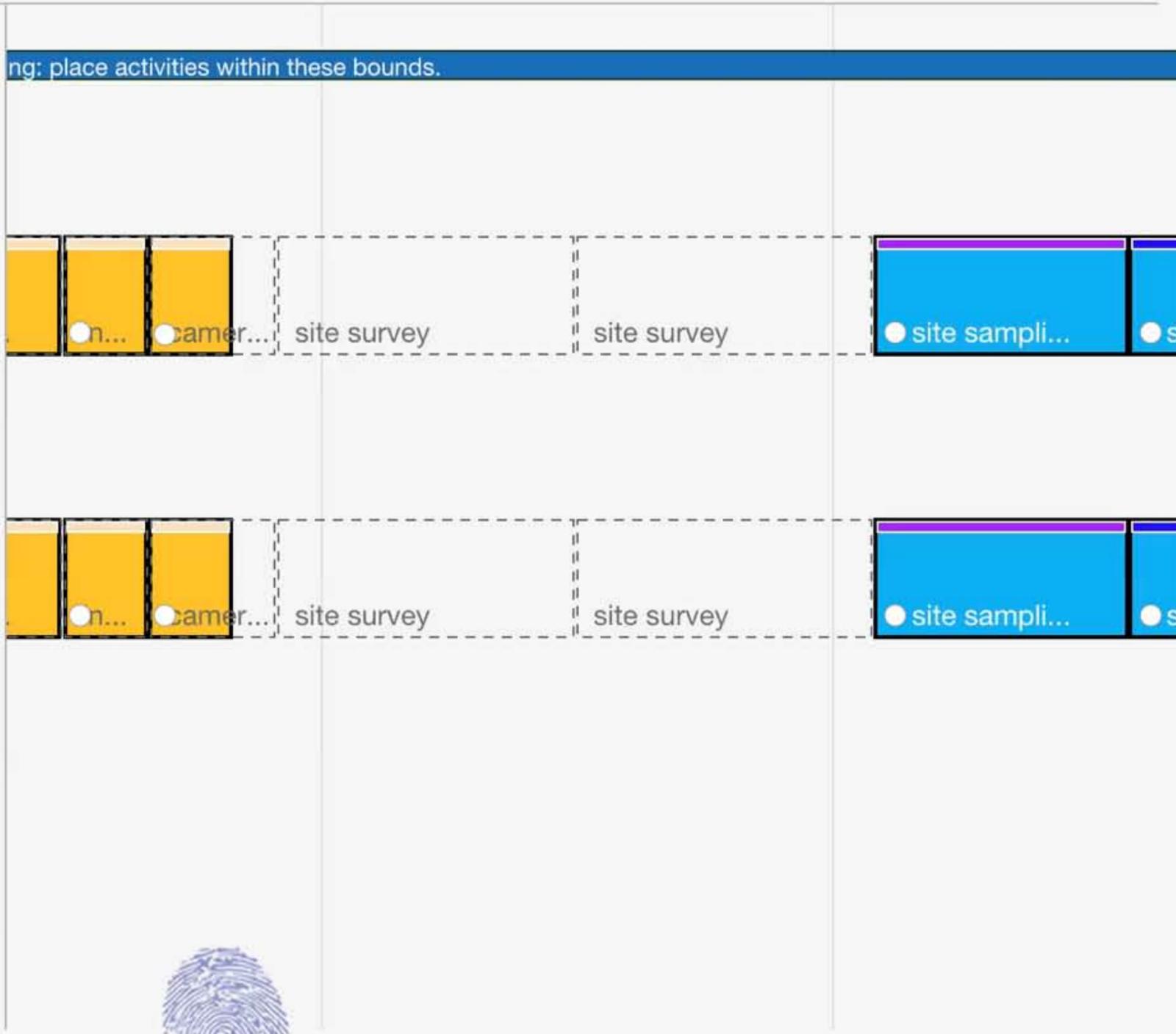
FE-1 (Serena)

FE-2 (宣茂)

FE-3 (Dave)

TECH-1 (Ott)

TECH-2 (Sebastian)



Install CORAL II Panels

(10 minutes)

CORAL II Tower panel (3x) installation

Must be completed after CORAL II Tower assembly.

Start Progress

Details...

Cameras install CORAL I

(15 minutes)

Camera installation on CORAL I Tower

Must be completed after CORAL I Panel Removal.

Site Survey

(35 minutes)

Translate to site (5min)

Pre-Sample Survey & Take PAM

Scratchpad



Groups

± Edit

marine n23

3

marine n29

3

geo s4

4

coral ii assem...

4





DESIGNING INTERFACES FOR ASTRONAUT AUTONOMY IN SPACE

Steve Hillenius, NASA
@hillenius

