Vision

- Imagine a day when a 911 emergency medical call immediately launches a vehicle to the aid of a victim trapped in an inaccessible location in the wilderness.

The vehicle:
- Self-Plans
- Self-Files
- Self-Launches once needed medical supplies are loaded
- Self Navigates Safely
- Coordinates its own refueling
- Finds the injured victim
- Self-Lands delivering the supplies
- Launches and establishes communication between the victim and trained medical personnel
How we will achieve this

1. Modular Software Architecture
   • Top down architecture hierarchy with clearly specified interfaces

2. Functionally Partitioned Modules
   • Each module limited to a single safety function
   • Software isolation of Vehicle performance modeling

3. Computational Agility
   • Rapid assessment of vehicle situational hazards with quick and decisive mitigation of those hazards
Developmental Test & Evaluation

Common Vehicles
- Elissa

Common Hardware
- EVAA Processor

Test Ranges
- Indoor Range
- Rural-Desert Range
- Urban Range
- High-Altitude Wilderness Range
- QR4
- Urban Range
- Wilderness Range