

Atmospheric Measurements for Flight Test at NASA's Neil A. Armstrong Flight Research Center

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Background:

1987 Graduate of the University of Utah (B.S. Meteorology)

1993 Graduate of the University of Nevada-Reno (UNR)
(M.S. Atmospheric Physics)

Desert Research Institute 1990-1993

NASA Atmospheric Science 29 years

Who's interested in Good high Altitude Atmospheric Data?

- Advance DoD Hypersonics
- Commercial Space
- NASA Hypersonics
- NASA/DOD Space
- NASA Flight Opportunities
- NASA Aeronautics
- NASA Science Mission (Earth Sciences)
- Actually Everyone!

How does weather impact flight research?

Flight safety

Mission planning

Flight on-condition

Post-flight engineering

Flight Safety

Avoid hazardous weather conditions

Thunderstorms (hail and lightning)

Turbulence

High winds

Clouds and/or precipitation

Range safety

People and property in local communities

Mission Planning

Flight objectives

Decisions based on forecasts and observations (crew briefings)

Criteria for Go/No Go

Weather limits/constraints

Operational guidelines (flight cards)

Primary and secondary objectives

Post-flight engineering

Atmospheric reference for air data
calibrations

Determine errors in aircraft measurements

Air pressure

Pressure altitude

Mach number

Airspeed

Use weather balloon observations to measure
pressure, temperature and wind

Post-flight engineering (continued)

Interpolate for flight time and trends during the day

Correct RADAR measurements for atmospheric
refraction

Weather Tools

- Rawinsonde Balloons
- Jimspheres
- Tethered Sondes
- Wind Towers
- NAM, RAP, GFS, Global Ensemble, GEOS-5 models
- LIDARs
- RADARs
- SODARs

Where are we Located?





NASA Dryden Flight Research Center Photo Collection

<http://www.dfrc.nasa.gov/Gallery/Photo/index.html>

NASA Photo: EC01-0264-14 Date: July 25, 2001 Photo By: Carla Thomas

NASA's Dryden Flight Research Center is situated immediately adjacent to the compass rose on the bed of Rogers Dry Lake at Edwards Air Force Base, Calif.



NASA Dryden Flight Research Center Photo Collection
<http://www.dfrc.nasa.gov/gallery/photo/index.html>
NASA Photo: EC91-485-1 Date: 5 Sep 1991

Main Building (4800) at Dryden FRC



Discovery

United States

Shaped Sonic Boom Demonstration Aircraft (SSBD)



NASA Dryden Flight Research Center Photo Collection

<http://www.dfrc.nasa.gov/Gallery/Photo/index.html>

NASA Photo: EC03-0210-1 Date: August 2, 2003 Photo By: Carla Thomas

Northrop-Grumman Corporation's modified U.S. Navy F-5E Shaped Sonic Boom Demonstration (SSBD) aircraft.



NASA Dryden Flight Research Center Photo Collection
<http://www.dfrc.nasa.gov/gallery/photo/index.html>
NASA Photo: EC85-33297-23 Date: 1985 Photo by: NASA

X-29 in Flight from Above

Stratospheric Observatory for Infrared Astronomy (SOFIA)



NASA Earth Science



ERAST Helios



Phantom Eye Liquid H2



NASA's IKHANA Predator B



Hypersonic Research Mach 9.6 (7000mph)



Dryden Flight Research Center ED98-44824-1
X-43/Hyper-X aircraft. NASA/Dryden Illustration by Steve Lighthill

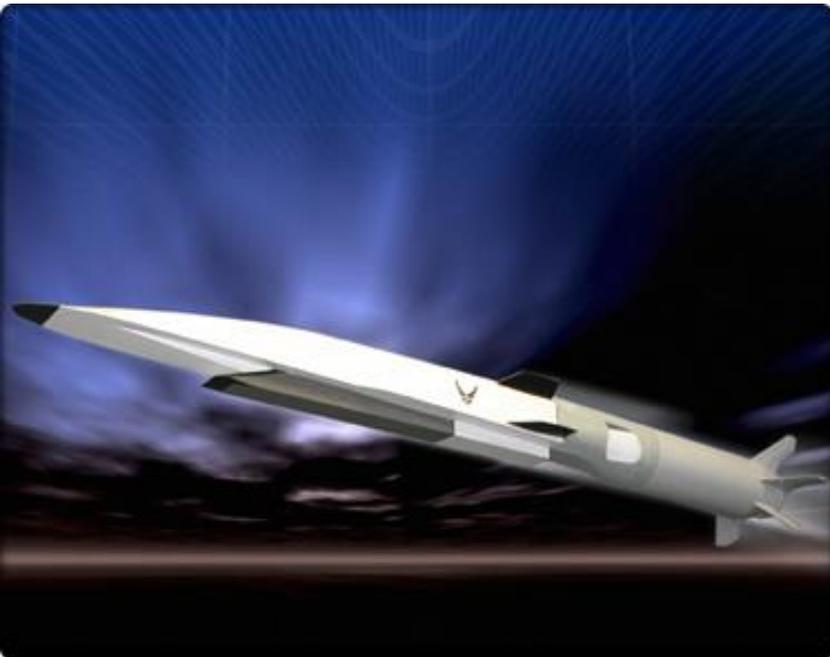




Hypersonics

HTV-2 4/2010 & 8/2011

X-51 5/2010, 3/2011, 8/2012, 5/2013



AHW 11/2011



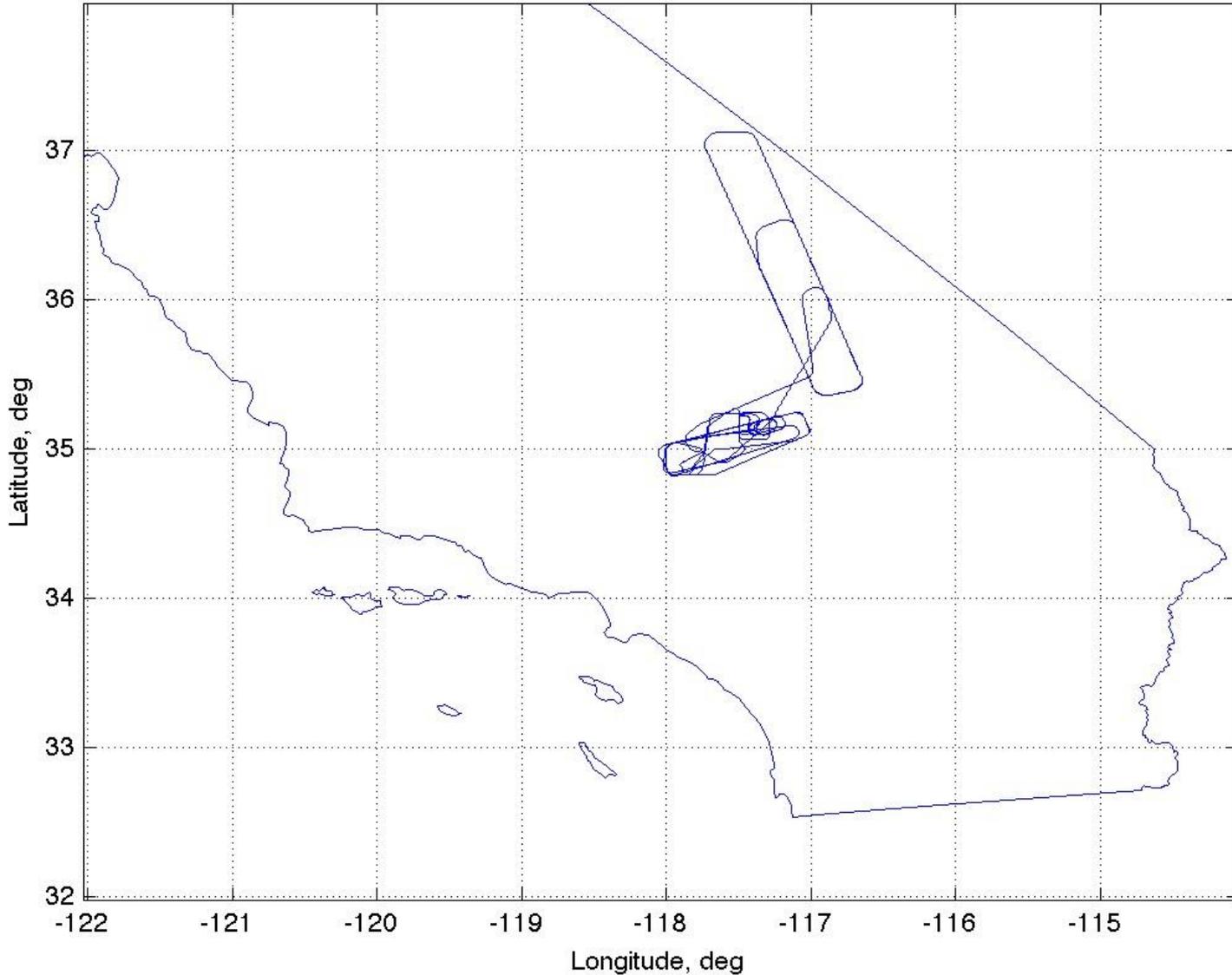
Global Hawks



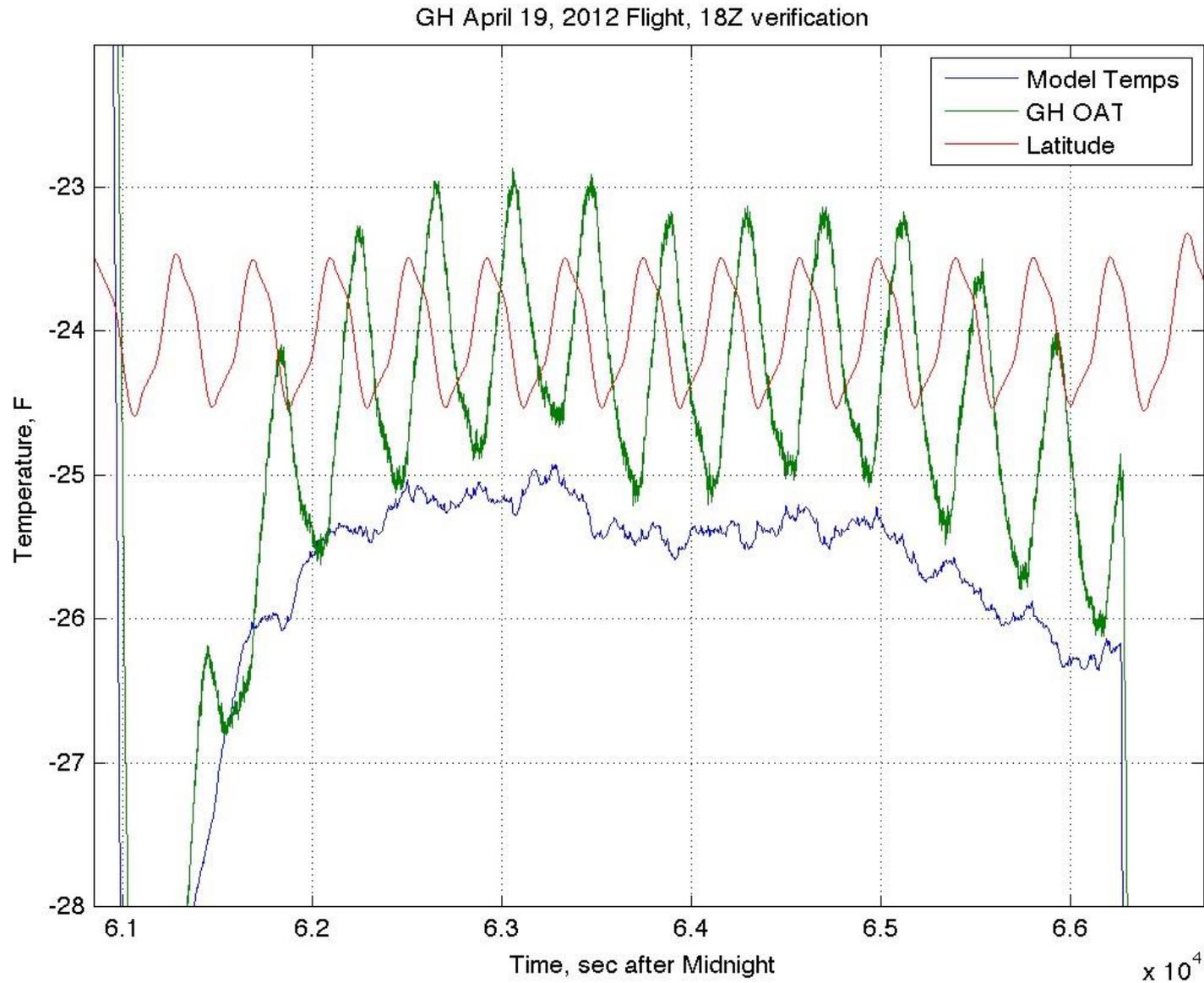
18 Jan 2010

Global Hawk Flight Area for KQX Refueling

GH April 19, 2012 Flight, 00Z Forecast data for 18Z verification

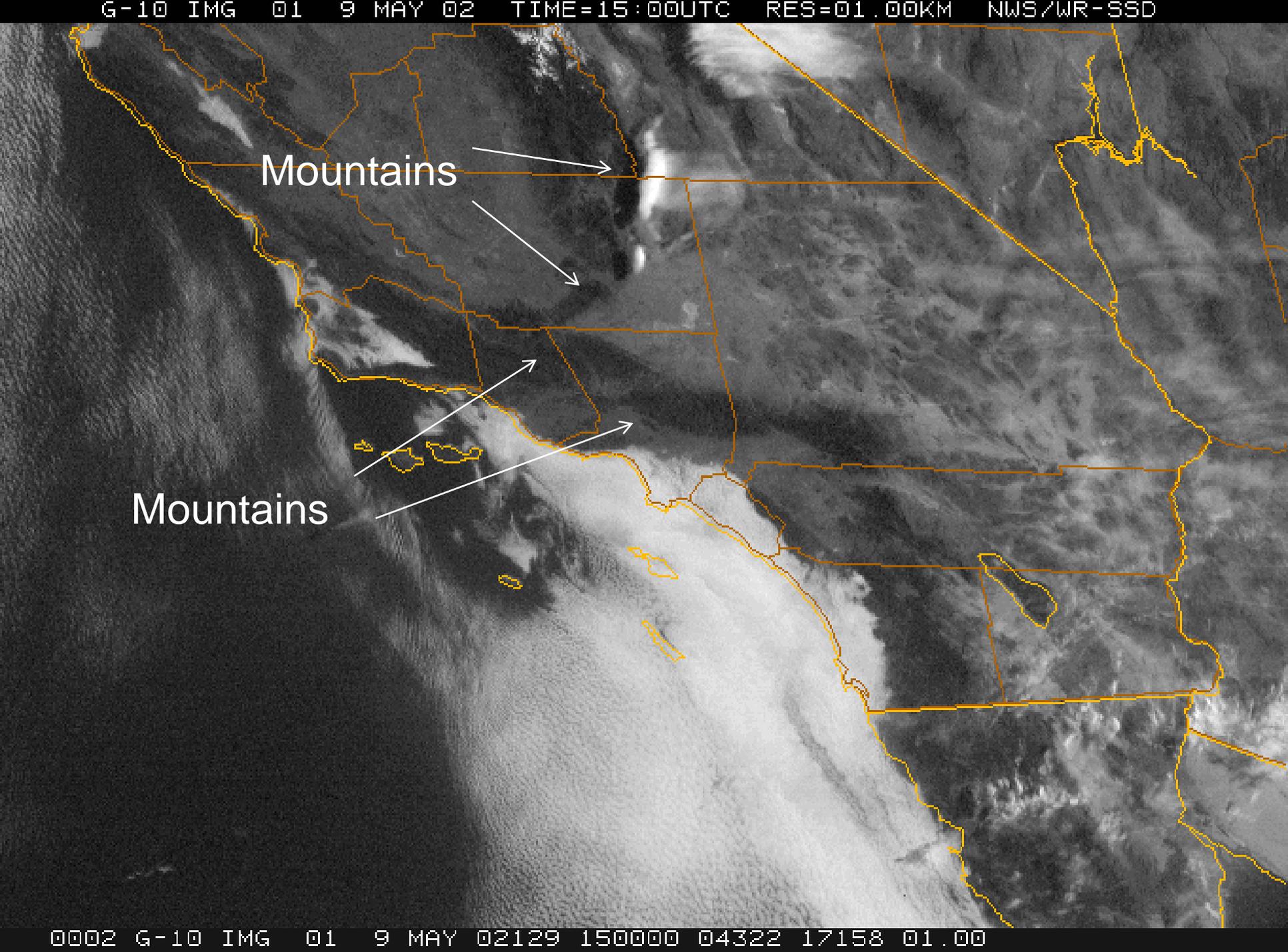


Global Hawk “Poor Man’s Calibration”



Climatology

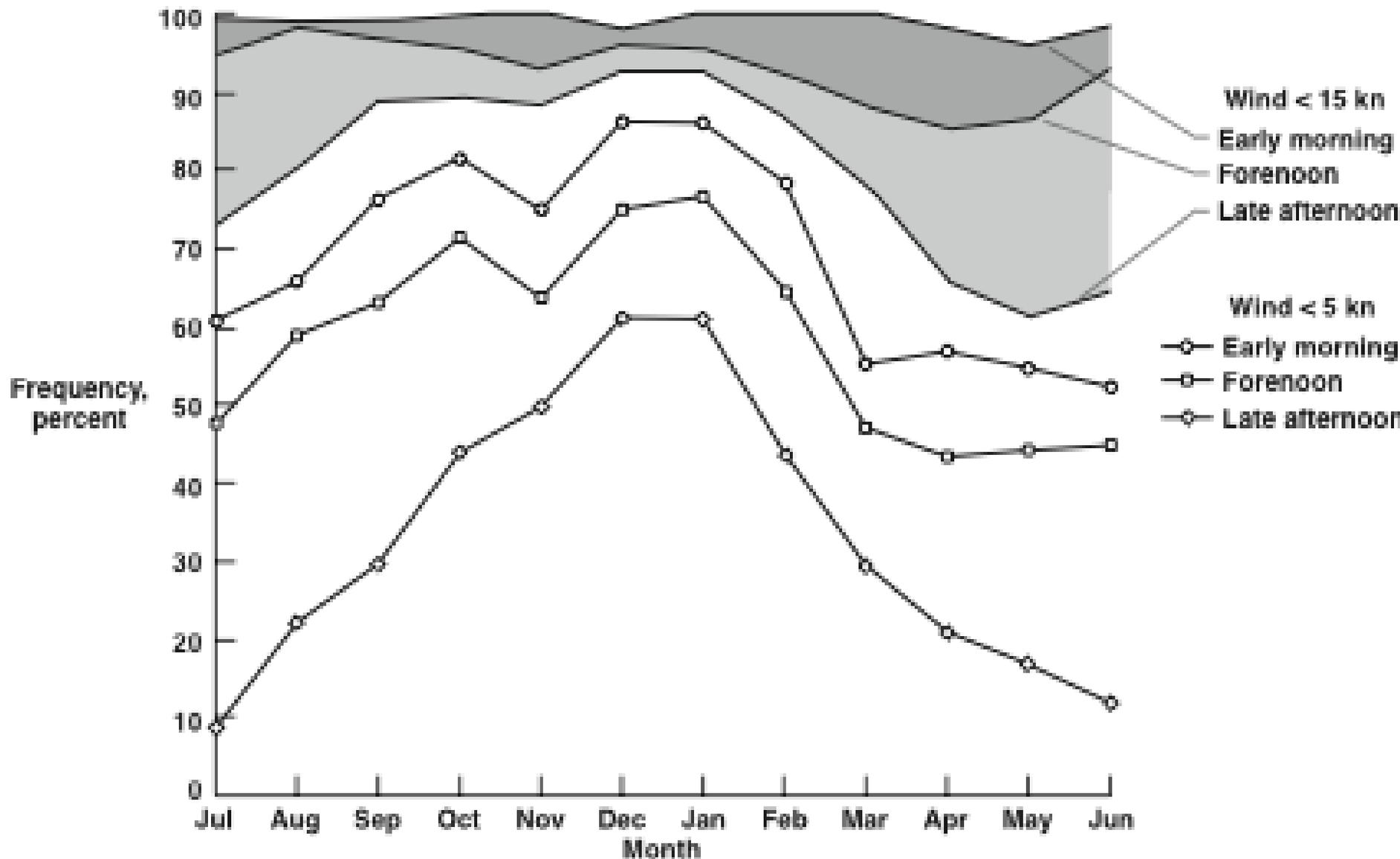
- Understanding the Atmosphere
 - Surface behavior
 - Seasonal vs time of day
 - Temperature
 - Winds
 - Precipitation
 - Upper Air profile
 - Seasonal
 - Temperature
 - Winds
 - Moisture



Mountains

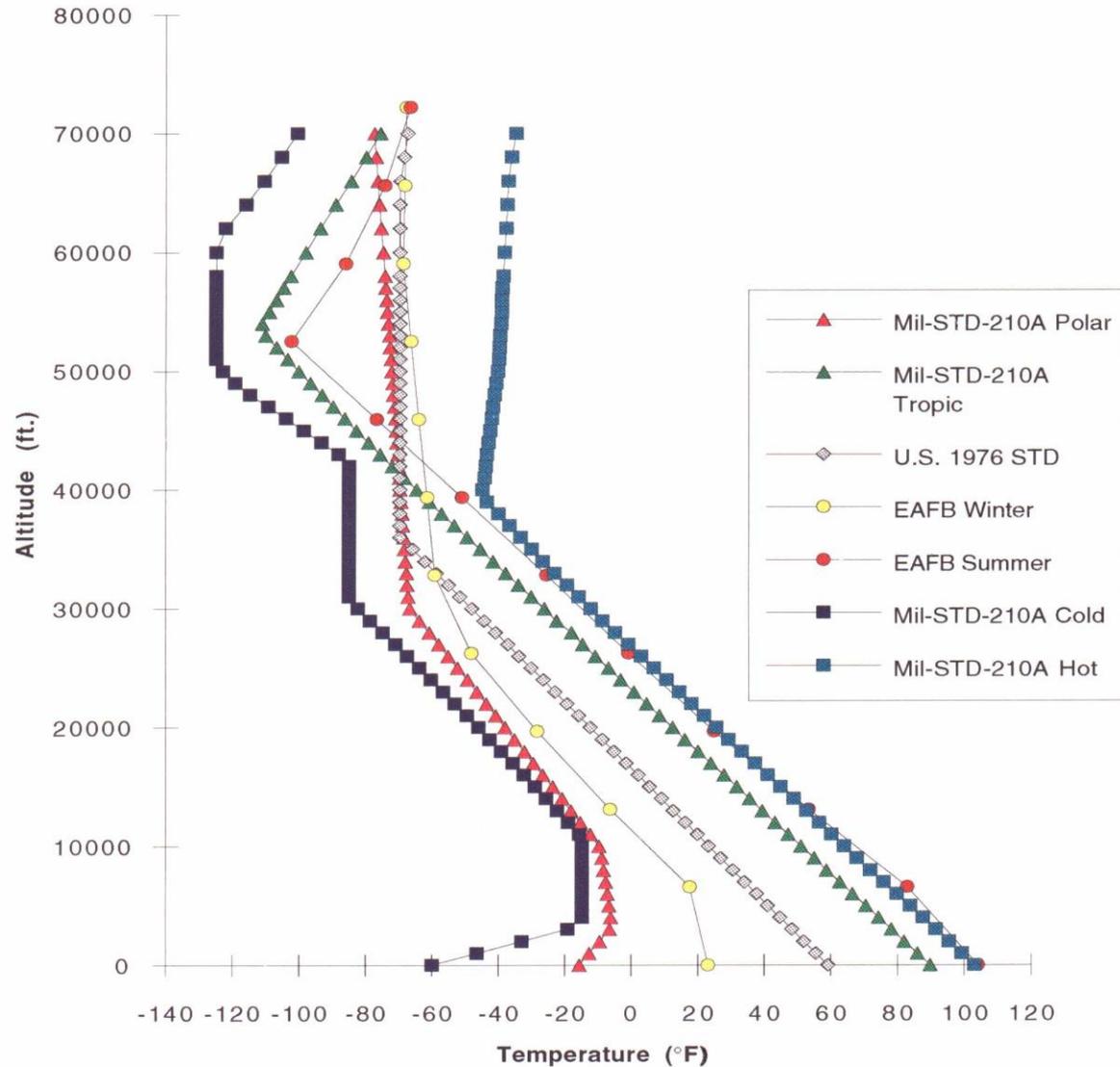
Mountains

Surface Winds at Edwards AFB

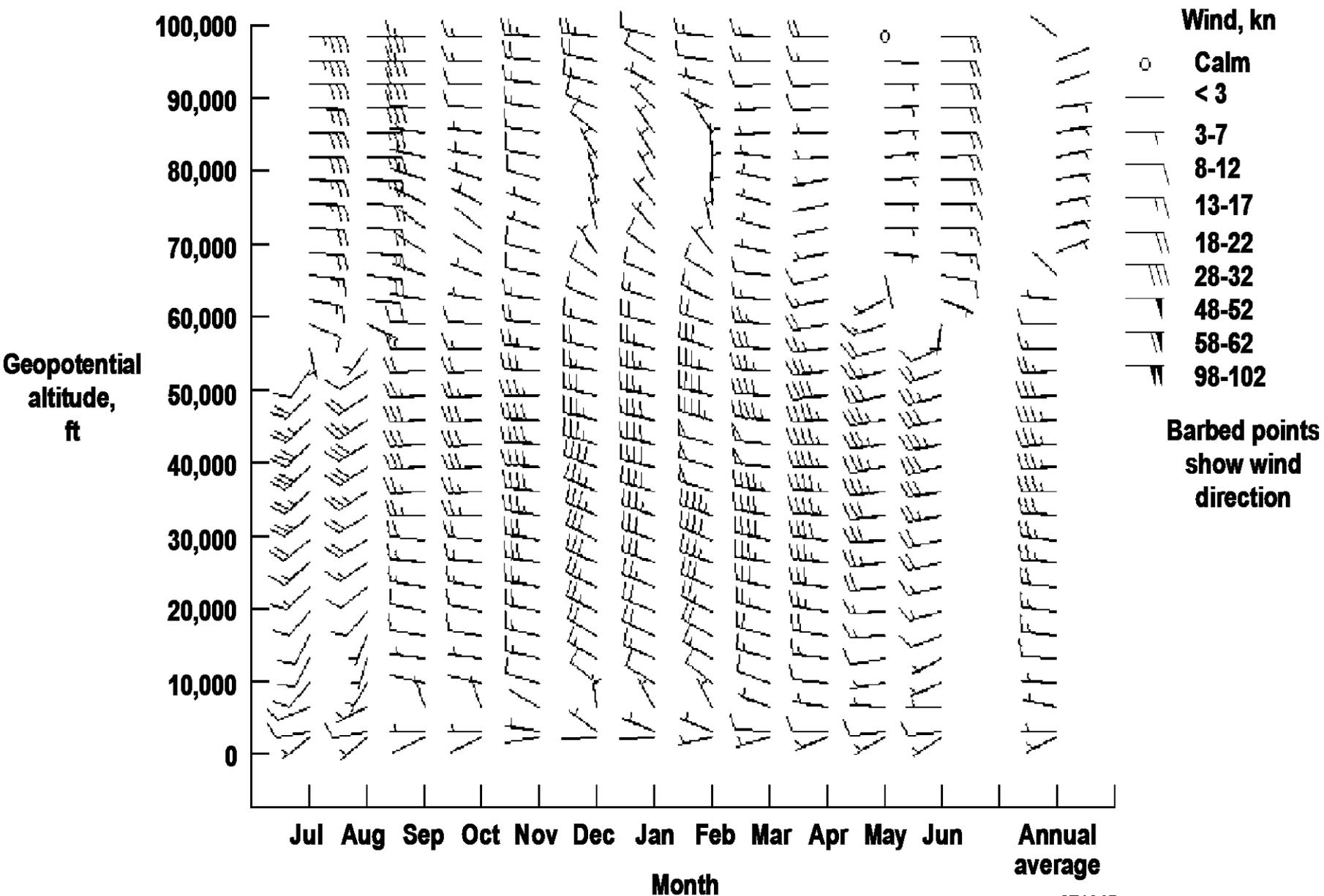


Temperature Standards

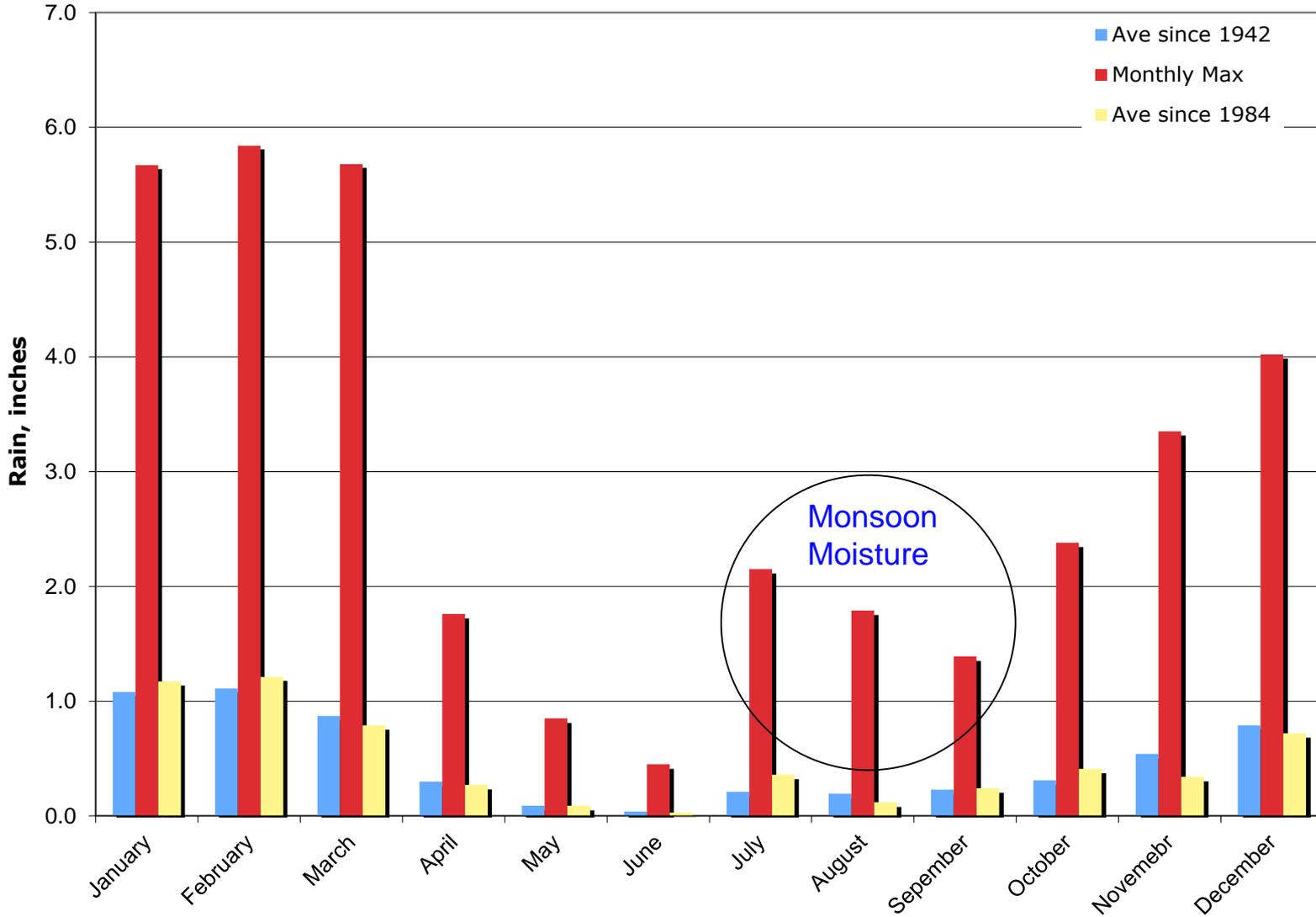
Atmospheric Temperature Profile Chart



EDW Monthly Upper Atmospheric Winds



Edwards AFB Monthly Rainfall 1942-2015



Tools of the Trade

High Altitude Lidar for
Atmospheric
Sensing (HALAS) Overview at
NASA Armstrong

Testing Locations – NASA-Armstrong





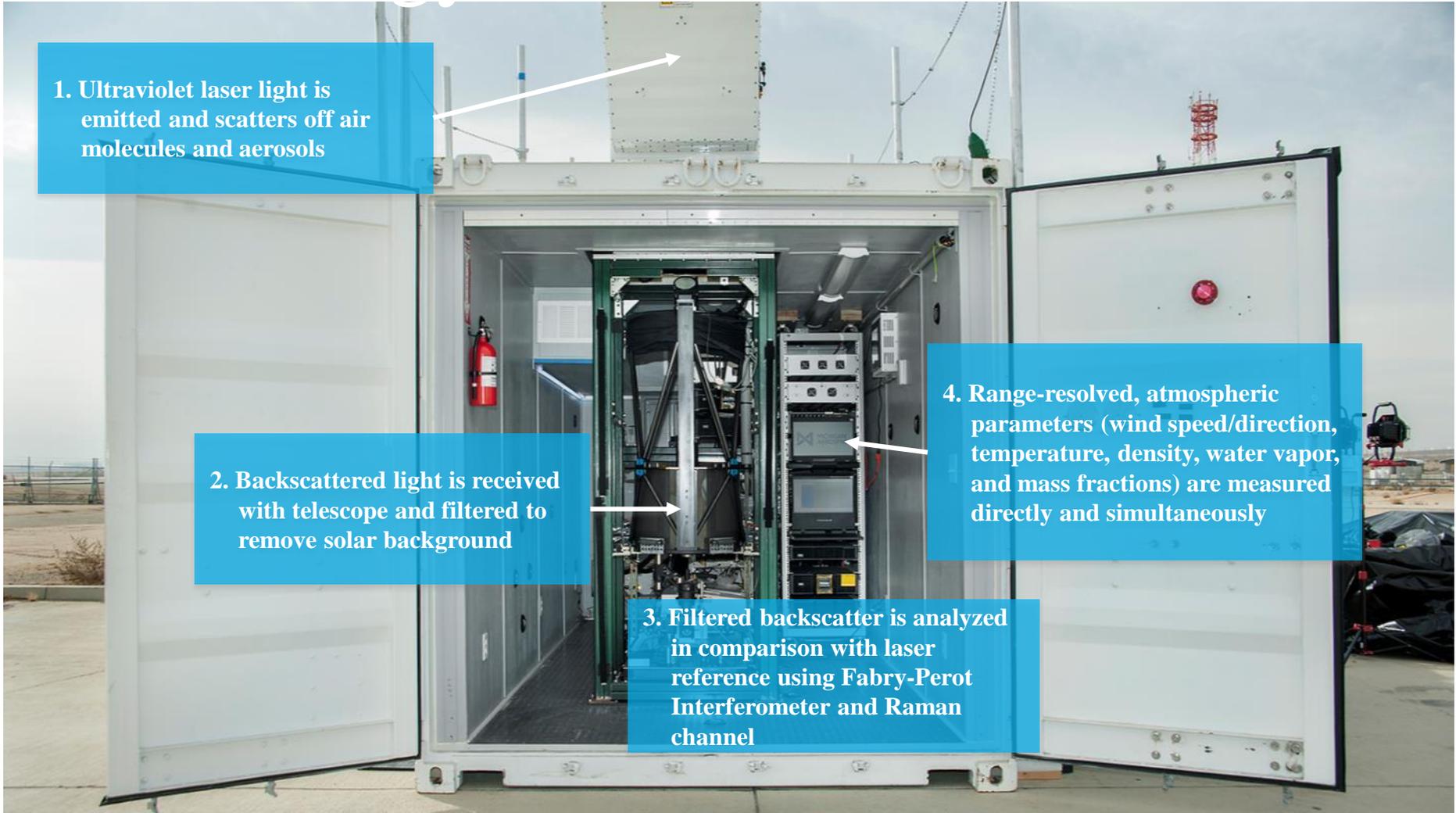
HALAS Overview

1. Ultraviolet laser light is emitted and scatters off air molecules and aerosols

2. Backscattered light is received with telescope and filtered to remove solar background

3. Filtered backscatter is analyzed in comparison with laser reference using Fabry-Perot Interferometer and Raman channel

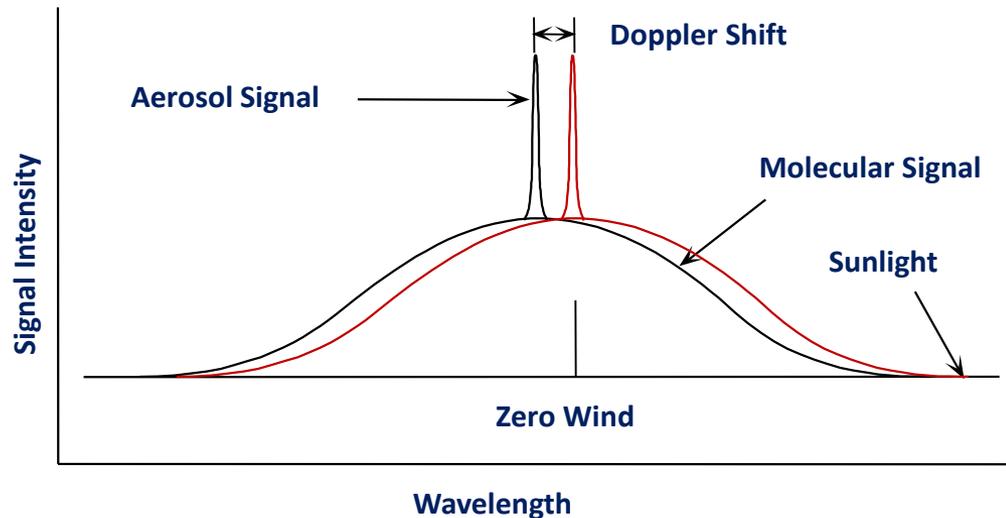
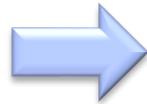
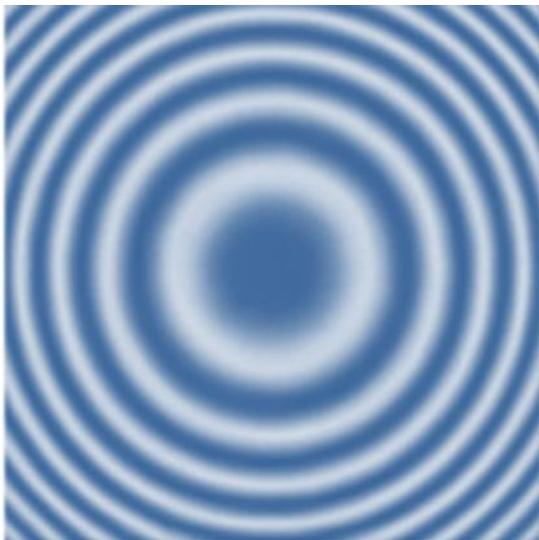
4. Range-resolved, atmospheric parameters (wind speed/direction, temperature, density, water vapor, and mass fractions) are measured directly and simultaneously



Data Product Retrieval

UV LIDAR makes direct measurements of wind speed, temperature, and density

Parameter	Atmospheric Phenomenon	Effect on Scattered Signal	Effect on Output
Wind Speed	Change in wind speed	Wavelength of return shifts	Etalon ring (fringe) radii shifts
Density	Density of air mass increases	Scattering of laser increases	Area under the fringe increases
Temperature	Temperature of air mass increases	Wider spectrum return	Fringe broadens – width increases



Rayleigh and Raman Scattering

Rayleigh scattering*:

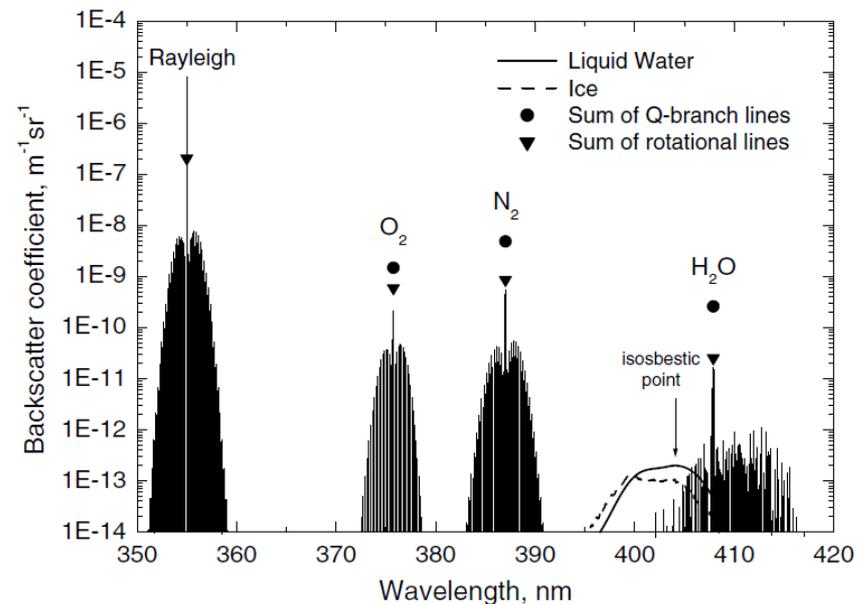
- Sum of Cabannes line (0.03 cm^{-1} wide), rotational Raman and vibrational Raman scattering (weak contribution compared to the Cabannes lines)

Raman scattering:

- The scattered light is shifted by an amount specific to the species and elastic scattered light is filtered out

Species identified by the Raman shift.

- N_2 : $2,331 \text{ cm}^{-1}$
- O_2 : $1,556 \text{ cm}^{-1}$
- H_2O : $3,657 \text{ cm}^{-1}$

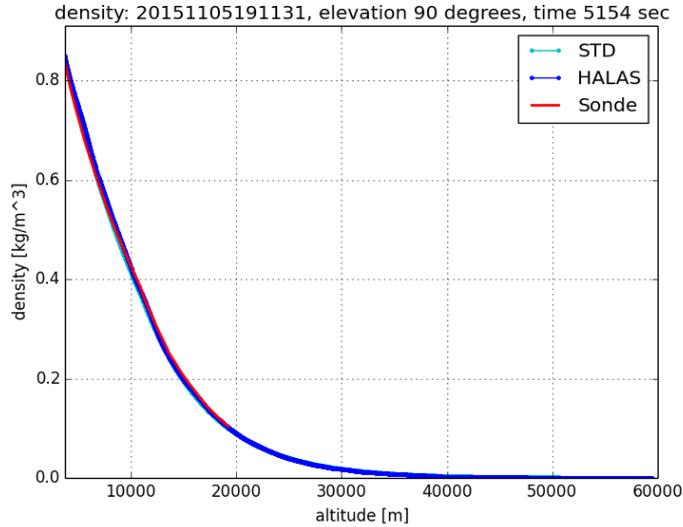


* R.B. Miles, W.R. Lempert, J.N. Forkey, "Laser Rayleigh Scattering," *Meas. Sci. and Technol.* **12** (2001)

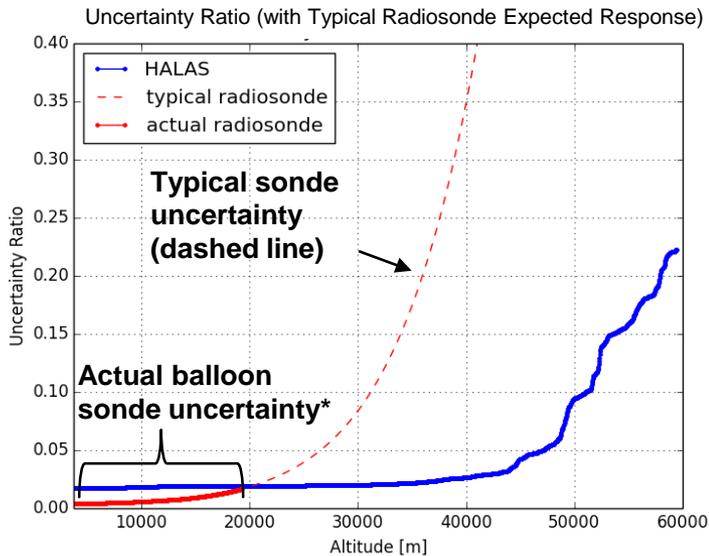
Why HALAS vs Weather Balloons

Parameter	Balloon	HALAS
Measurement location	Dictated by the prevailing winds and ascent rate	Selectable
Timeliness of profile	Typically takes 1-2 hours to reach altitude and only provides single altitude per data point	Simultaneously provides full range profile in seconds to minutes (dependent on accuracy and range)
Data products	Winds, pressure, temperature and humidity (depends on radiosonde)	Winds, density, mass fraction (O ₂ , N ₂ & H ₂ O), temperature and humidity
Uncertainty	Adequate uncertainty at low altitudes but suffer at high altitudes	Better uncertainty at higher altitudes. Comparable at lower elevations.
Environmental impact	Non-retrievable and not biodegradable	Only light is emitted from the system
Autonomous operation	Typically requires 1-2 people to launch and/or track a balloon	Can be made to run remotely with sufficient safety protocols
Operational coverage	Limited in number of profiles per day or night	Can run continuously 24/7
Spatial resolution	Dictated by hardware and ascent rate	Limited by detector update rate
Operational constraint	Land or sea-based. Can operate in adverse weather.	Land-and aircraft based (upon completion of Phase 3). Limited by heavy cloud cover from land.

Representative High Altitude Density



Parameter	Value
Date/time (UTC)	
Azimuth/Elevation	0° /90°
Integration time	59.7 min
Balloon launch (UTC)	
Balloon Max Altitude	19.3km (63,320ft)
CCD gain	200
CCD shift rate	500ns
Laser power	11.5W



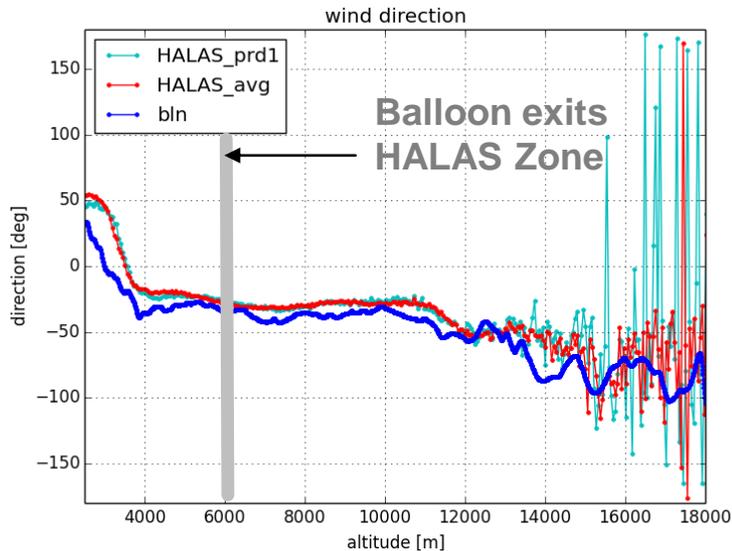
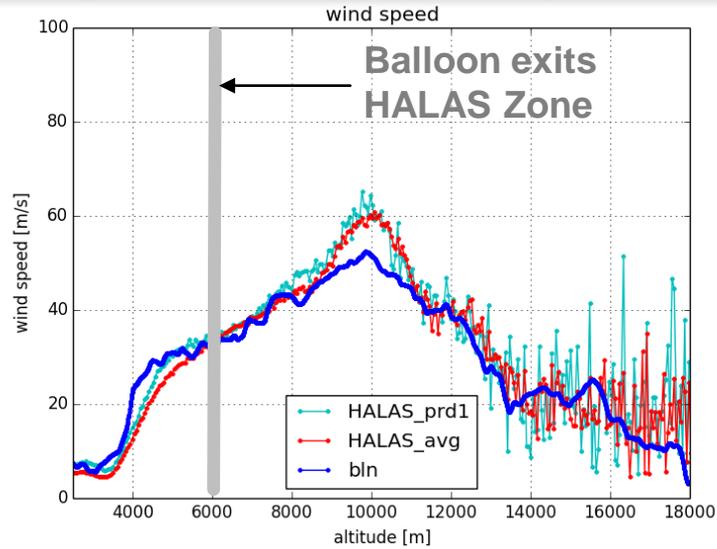
- Typical balloon uncertainty at 40km (131kft) is ~30% vs HALAS uncertainty of ~2%

* Balloon burst at 19.3km; typical high altitude balloons burst at 40km

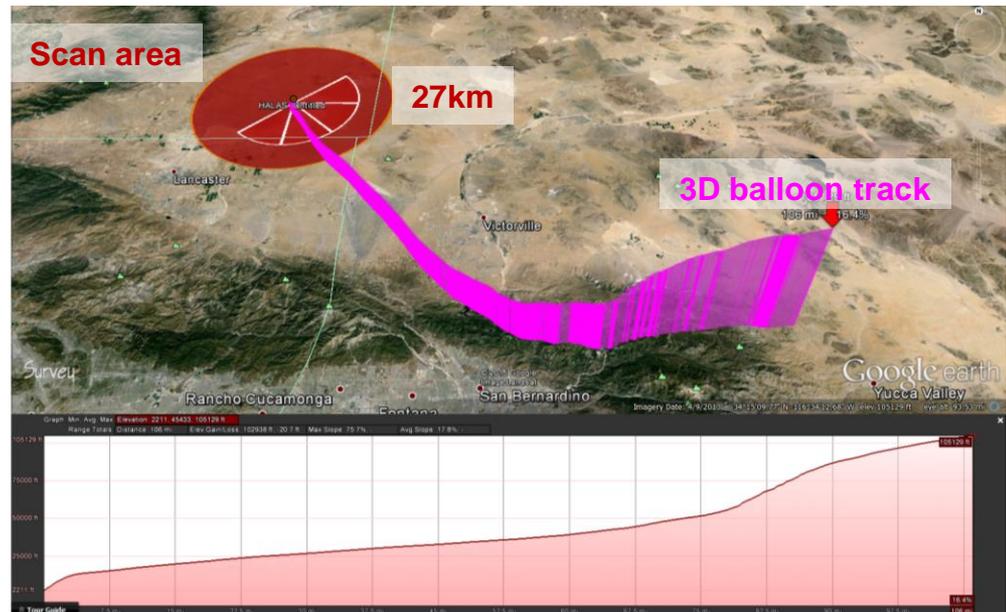
Representative Standoff Winds

Set 384

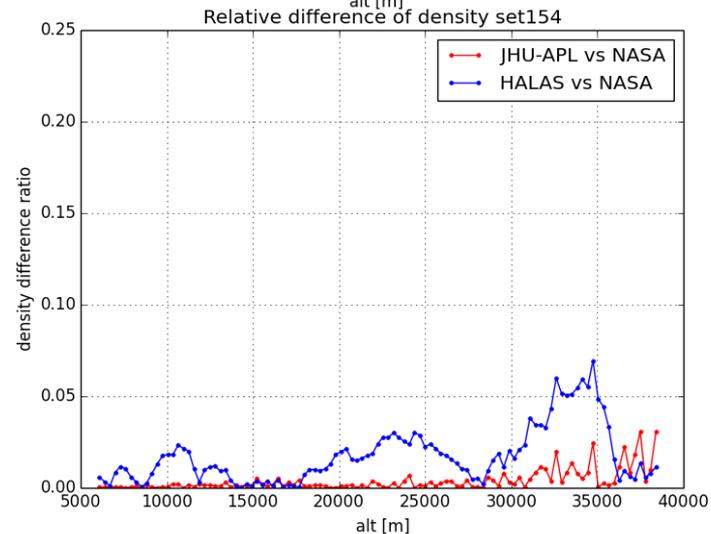
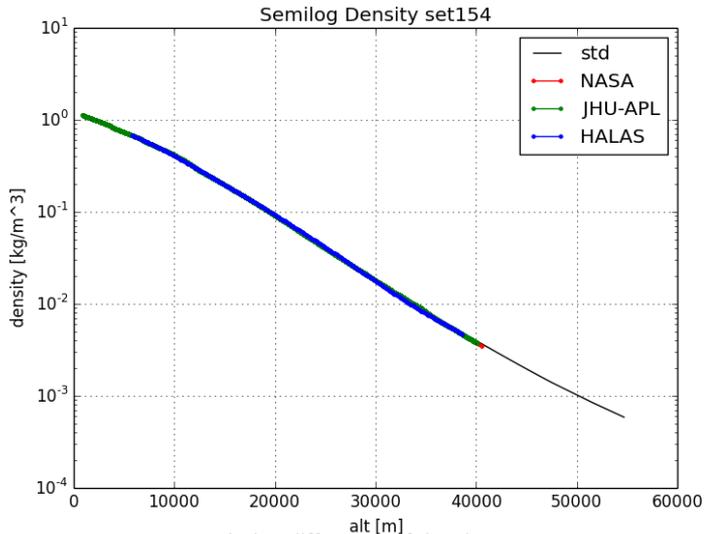
Average is over 20 Azimuthal views (40 min total)



Parameter	Value
Date/time (UTC)	
Azimuth/Elevation	$(45,90,135,180,225)^\circ / 45^\circ$
Integration time	2 min/azimuth
Balloon launch (UTC)	
Balloon distance; max altitude	170.6km; 32km (559,711ft; 104,987ft)
CCD gain	200
CCD shift rate	500ns
Laser power	11.5W

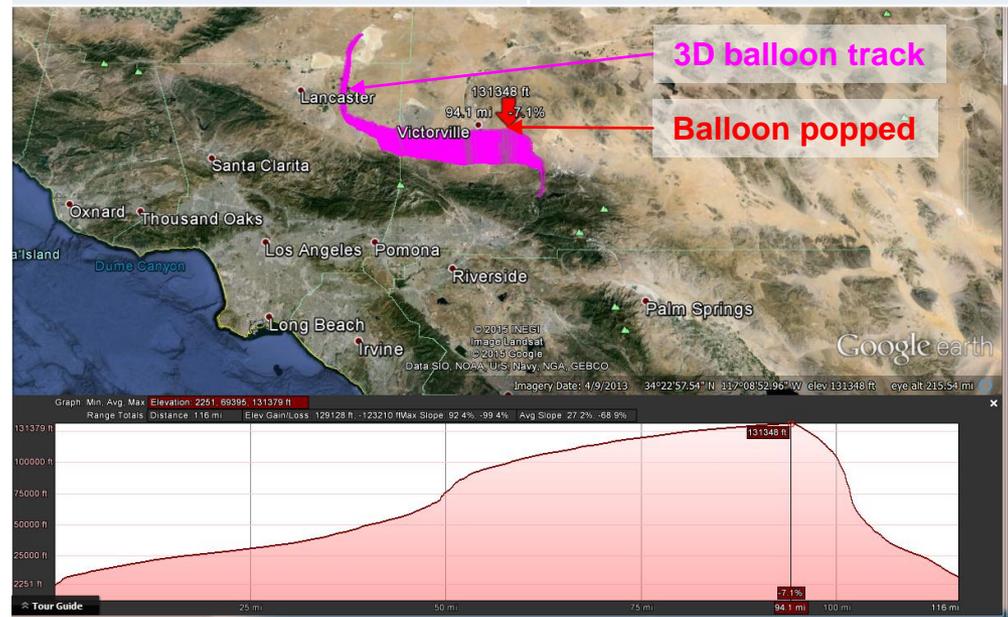


Representative Density

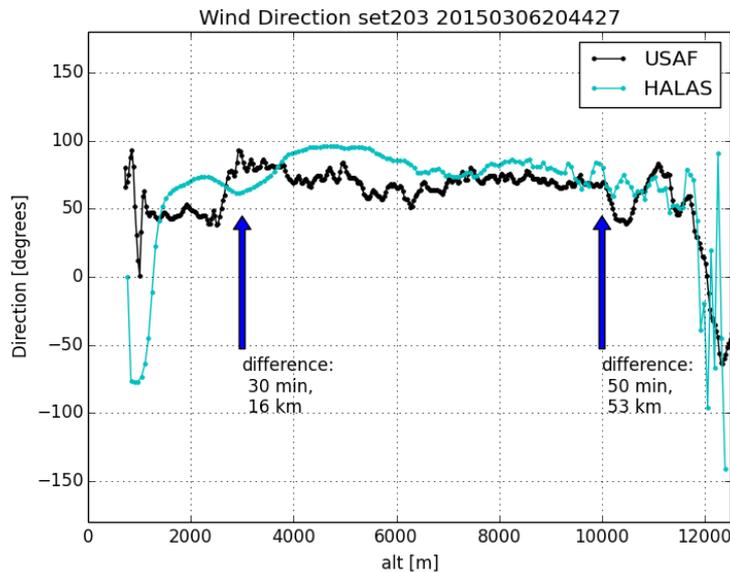
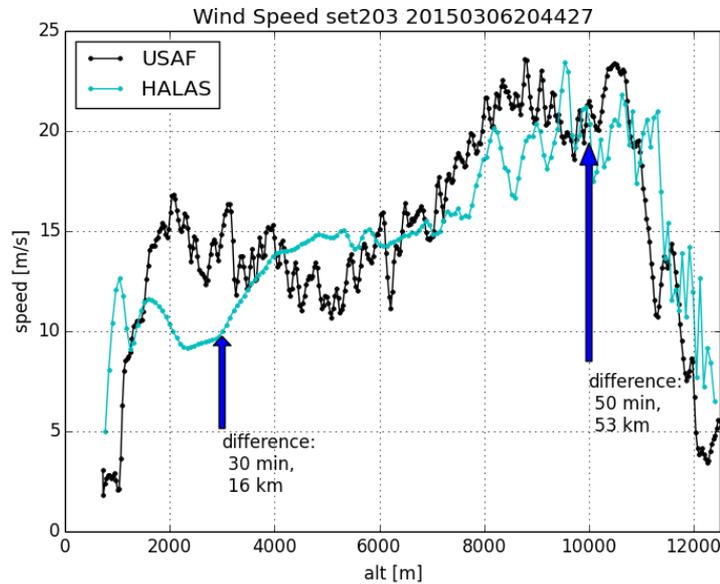


Plot shows the relative difference between the balloon and the HALAS data, not uncertainty

Parameter	Value
Date/time (UTC)	3/4/2015 (04:49)
Azimuth/Elevation	0°/90°
Integration time	18 min
Balloon launch (UTC)	3/4/2015 (05:00 ^{NASA} / 0:00 ^{AF})
Balloon distance / max altitude	58mi / 131,348ft
CCD gain	95
CCD shift rate	900ns
Laser power	11.7W



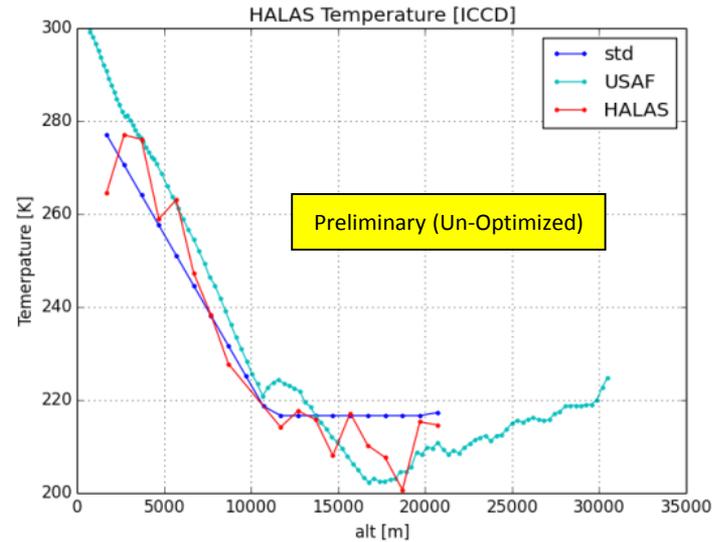
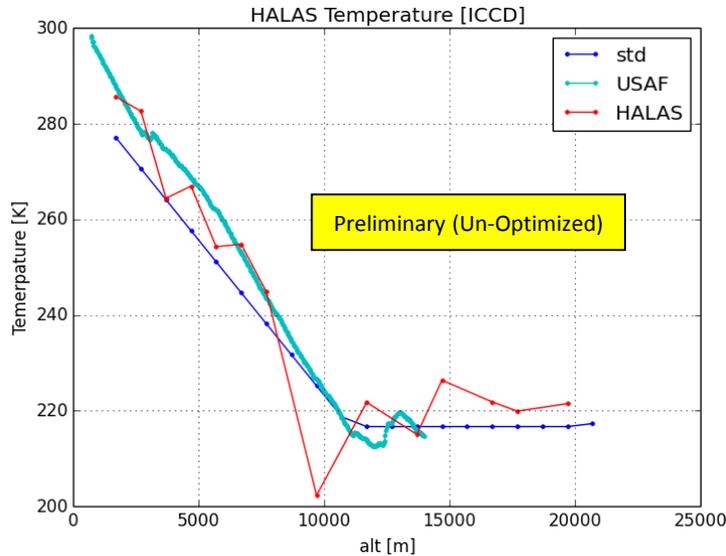
Representative Wind Speed/Direction



Parameter	Value
Date/time (UTC)	3/6/2015 (20:44)
Azimuth/Elevation	(0,90,180,270) ^o /65 ^o
Integration time	6 min/azm
Balloon launch (UTC)	3/6/2015 21:00 ^{AF}
Balloon distance / max altitude	37mi (estimate)/ 82,100ft
CCD gain	95
CCD shift rate	500ns
Laser power	11.2W

- Plots marks time and location difference between balloon and HALAS
- 3D ground track not available from Air Force data stream. Distances are estimated from average of multiple balloon launches before and after this launch

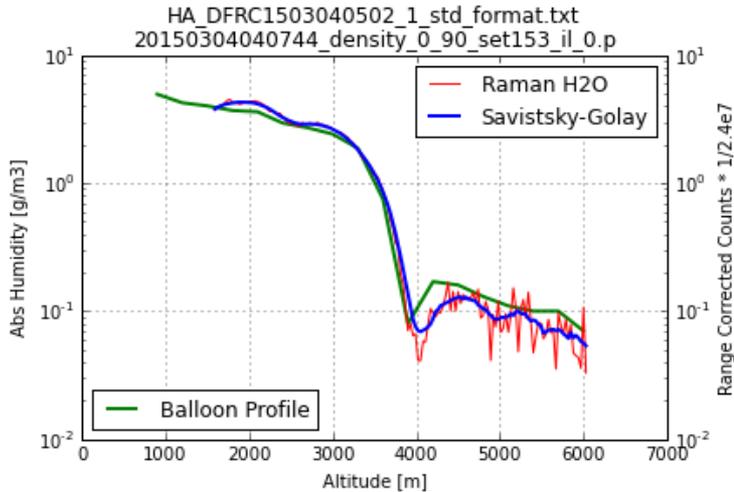
Temperature Estimations



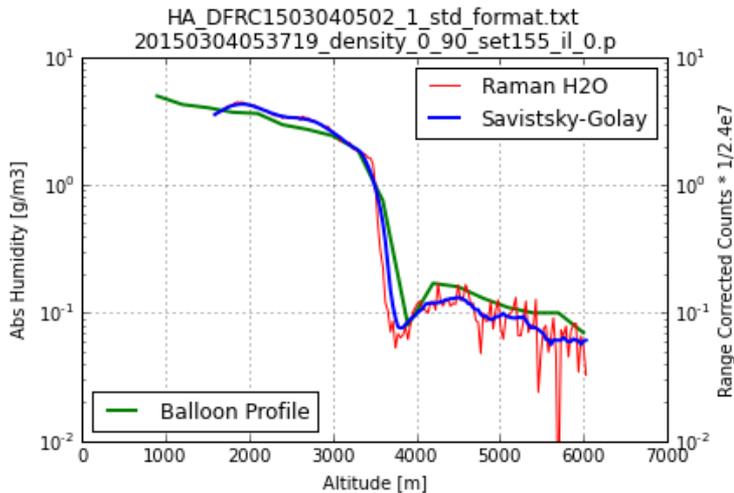
Initial (Not Optimized) HALAS Temperature Estimates: Night [left], Day [right]

- Initial temperature results do not reflect the full capability of HALAS
- Upgrades are being implemented to enhance the temperature measurement capability under Phase 3 of HALAS
 - Upgrades will allow higher spectral resolution and better uncertainties

Water Vapor



Parameter	Value
Date/time (UTC)	3/4/2015 (04:07 and 05:37)
Azimuth/Elevation	0°/90°
Integration time	18 min
Balloon launch (UTC)	3/4/2015 05:00 ^{NASA}
Balloon distance / max altitude	58mi / 131,348ft
Bin size	30m
Laser power	11.5W



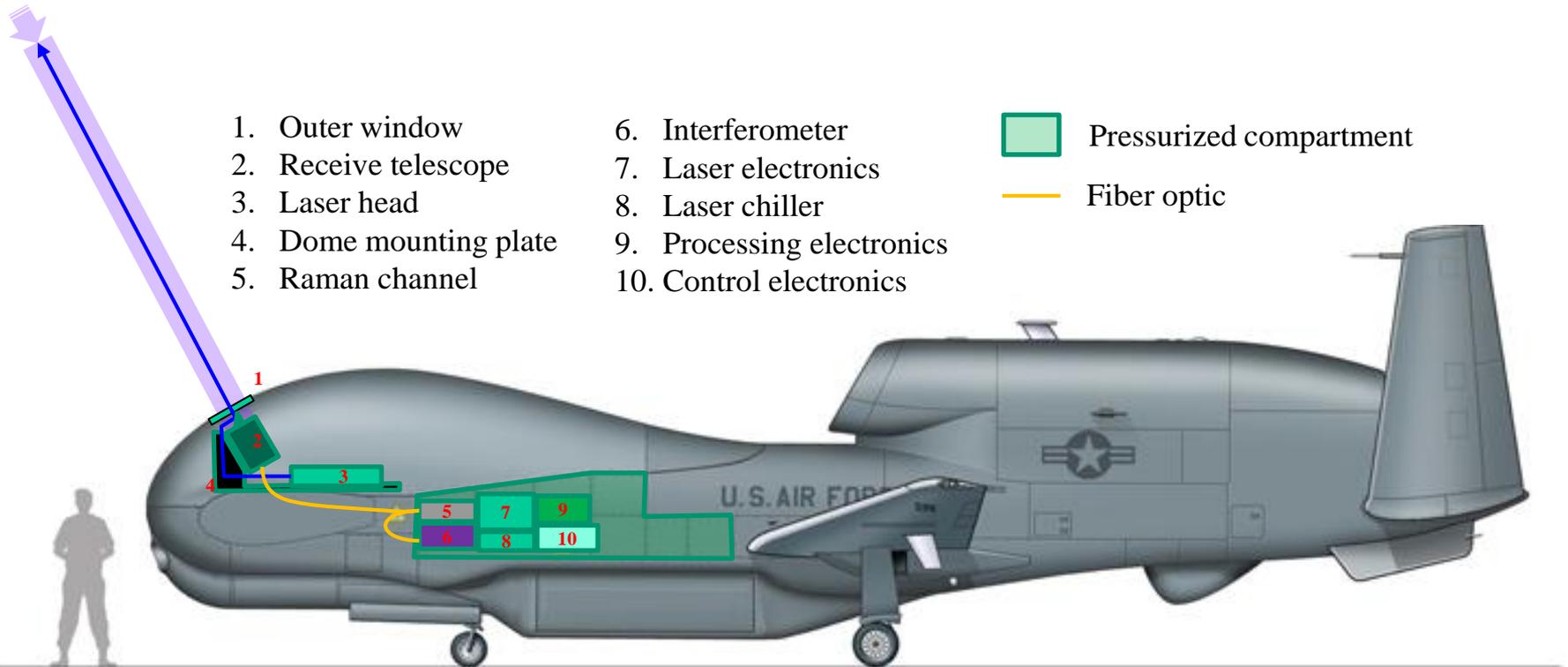
- Water vapor not part of original effort but were added due to interest from current and future customers
- Water vapor measurements show great promise for future implementation
 - Tracks well with balloon and provides greater resolution (30m)

HALAS on aircraft

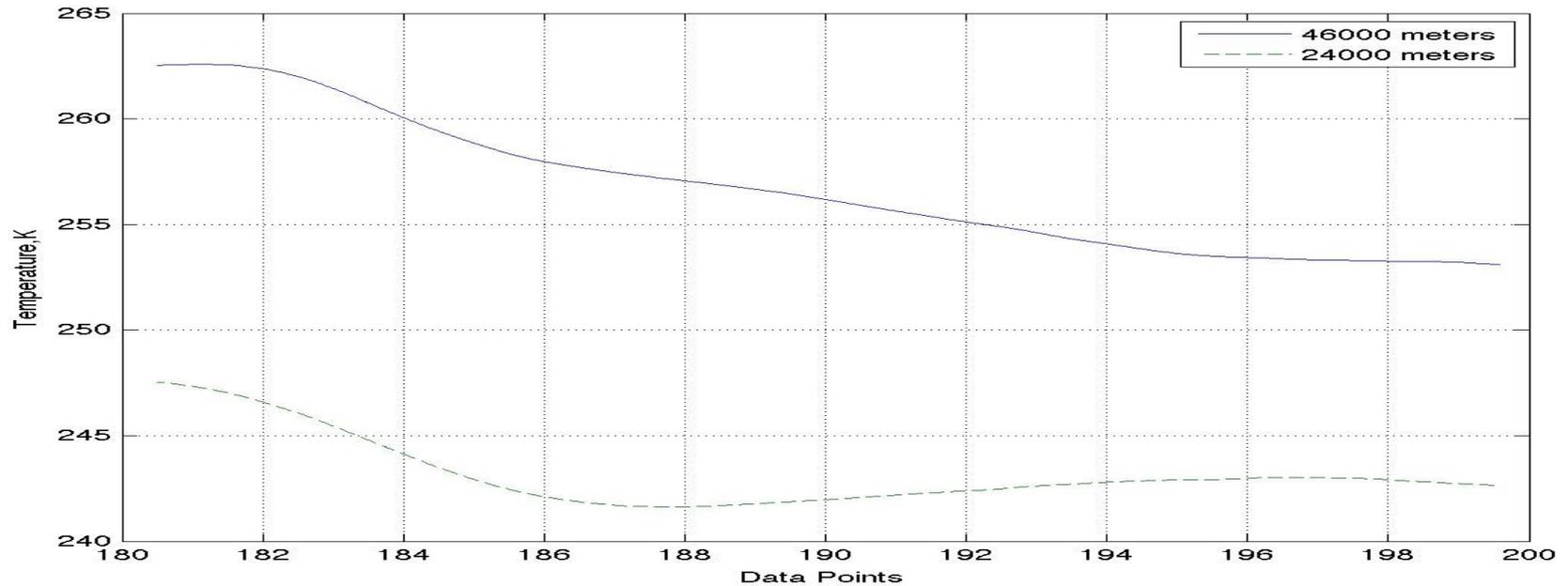
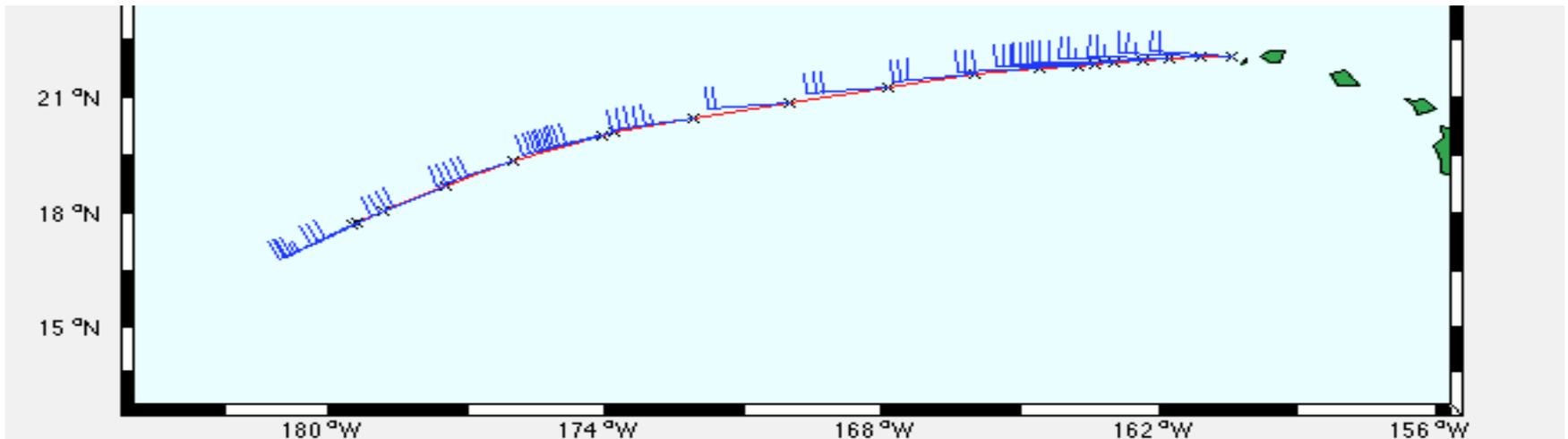


- Significantly enhanced atmospheric data coverage
 - Allows for mapping of atmosphere along intended trajectory
- Greater mission flexibility
- Capability to support several different CONOPS
- Improved measurement opportunity by beginning measurement above boundary layer and majority of cloud cover
- Ability to provide additional data such as the characterization of aerosol conditions that could cause ablation or other issues to a flight vehicle

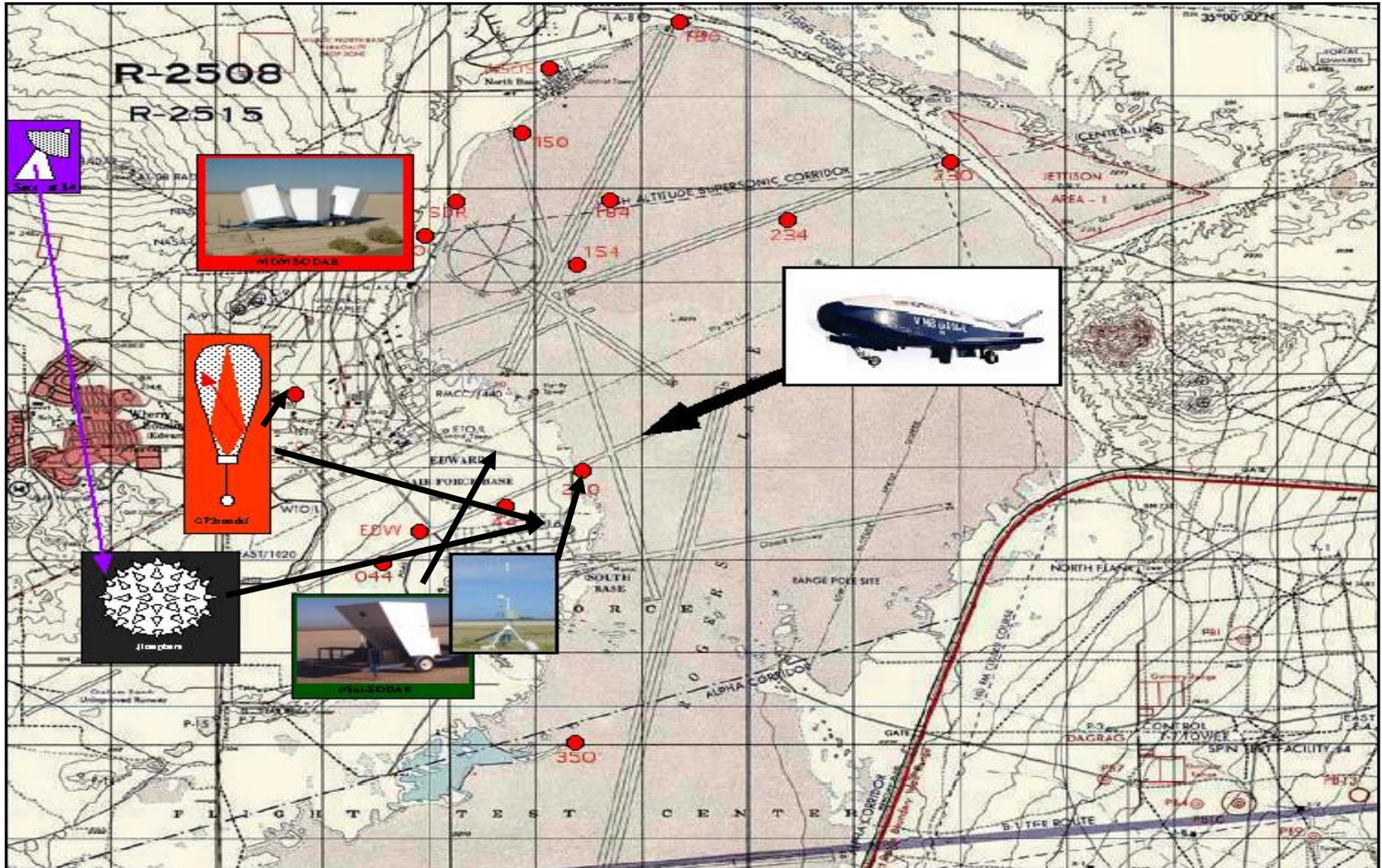
Potential Follow-On



Trajectory Simulation



WX Sensor Deployment

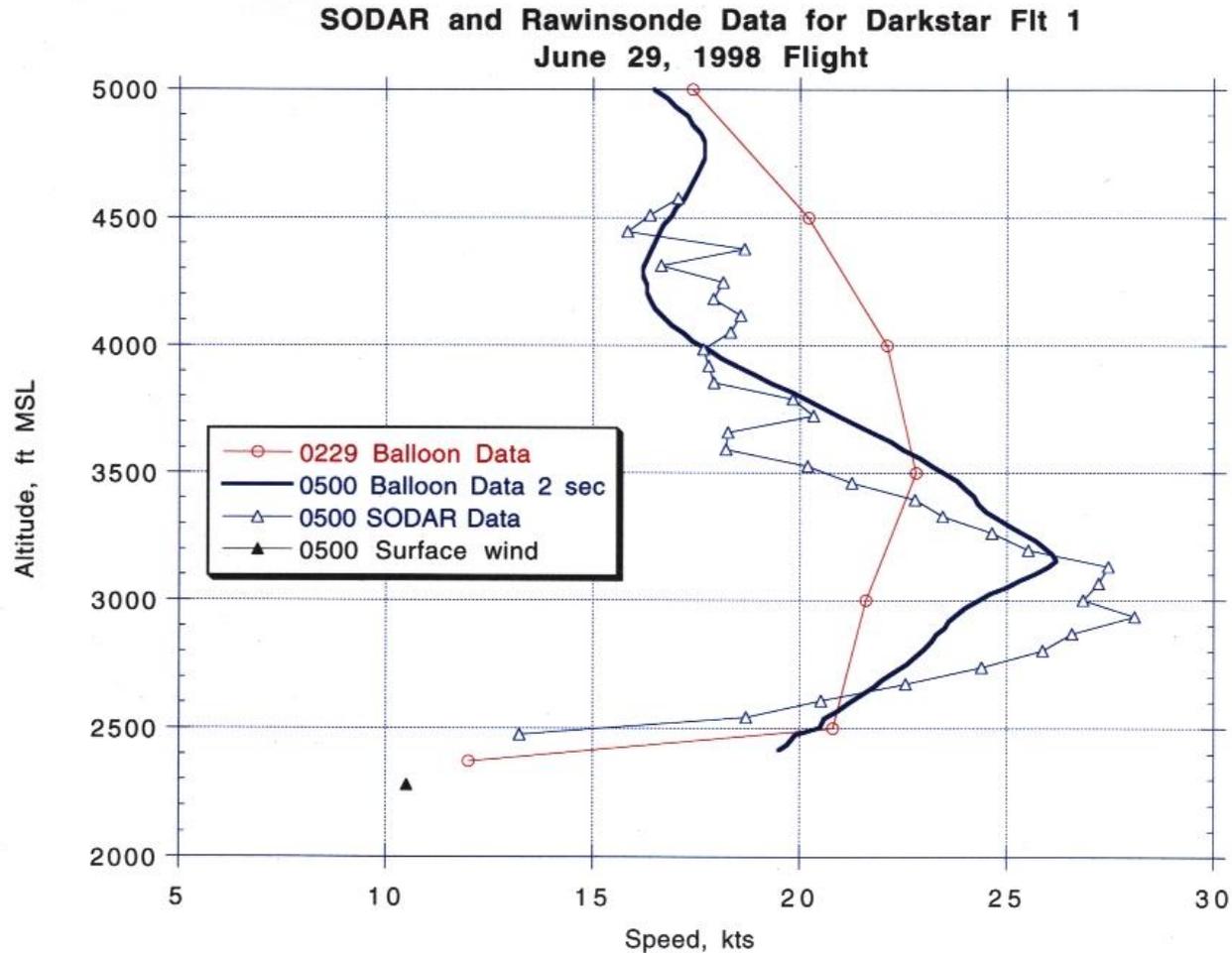


Model 2000 Doppler SODAR

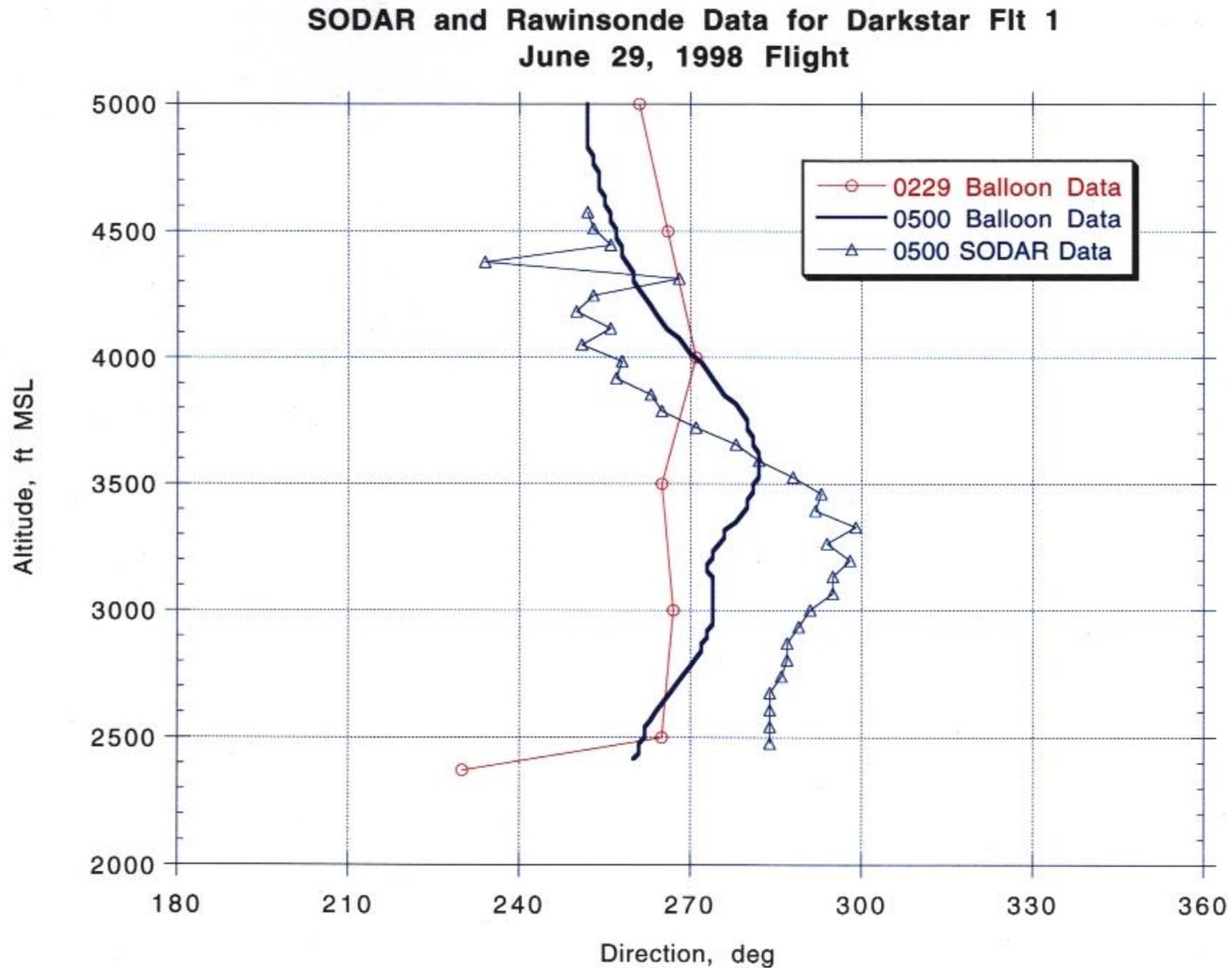


- Operates at 1600-2300 (2000) Hz
- Wind Profiles
 - 60 meters AGL min
 - 740 meters AGL max
 - 20 meter intervals
- Sample Rate
 - 1 cycle per 15 sec
- Averaging times
 - 5-15 minutes

SODAR/Rawinsonde Comparisons

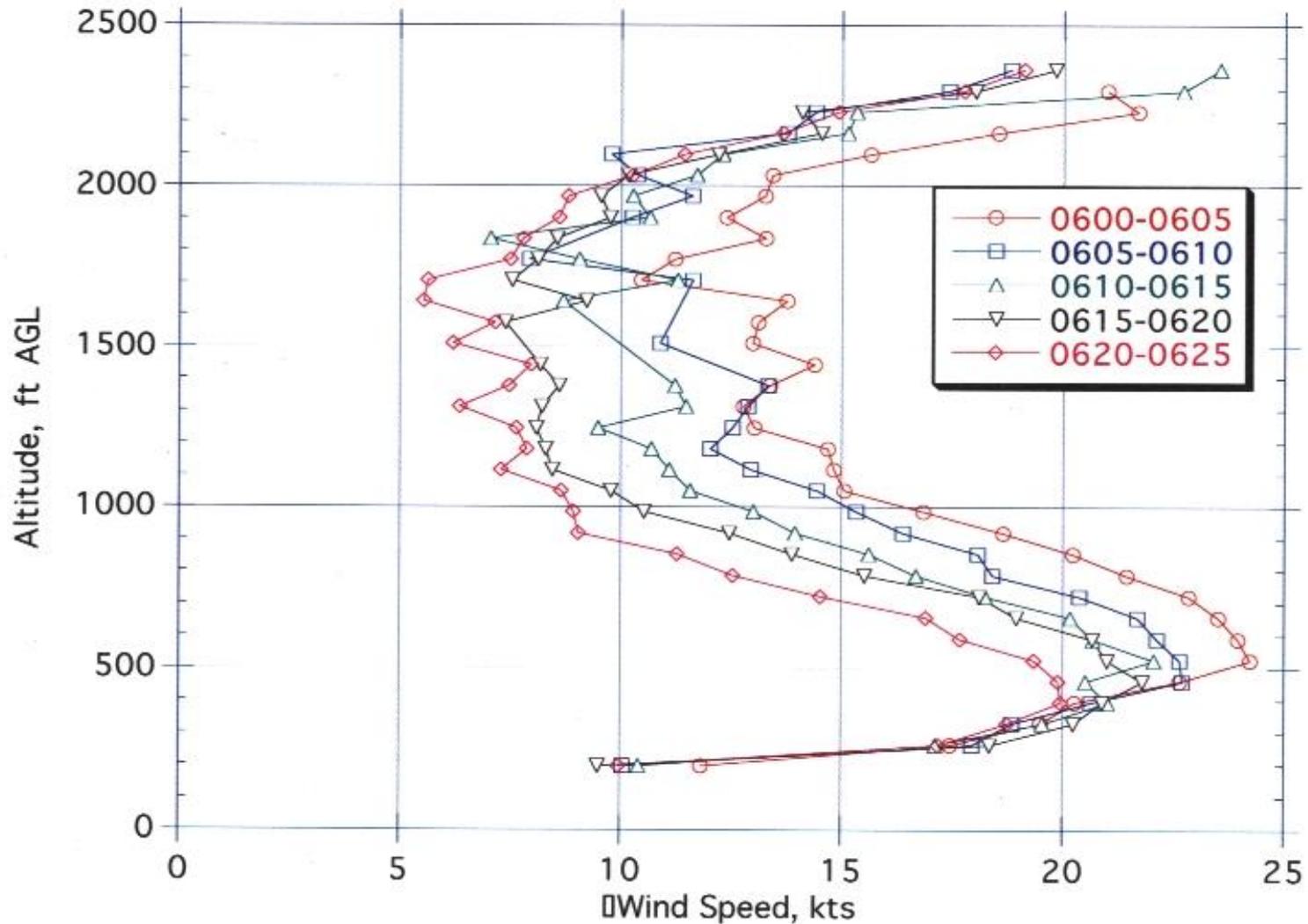


SODAR/Rawinsonde Comparisons



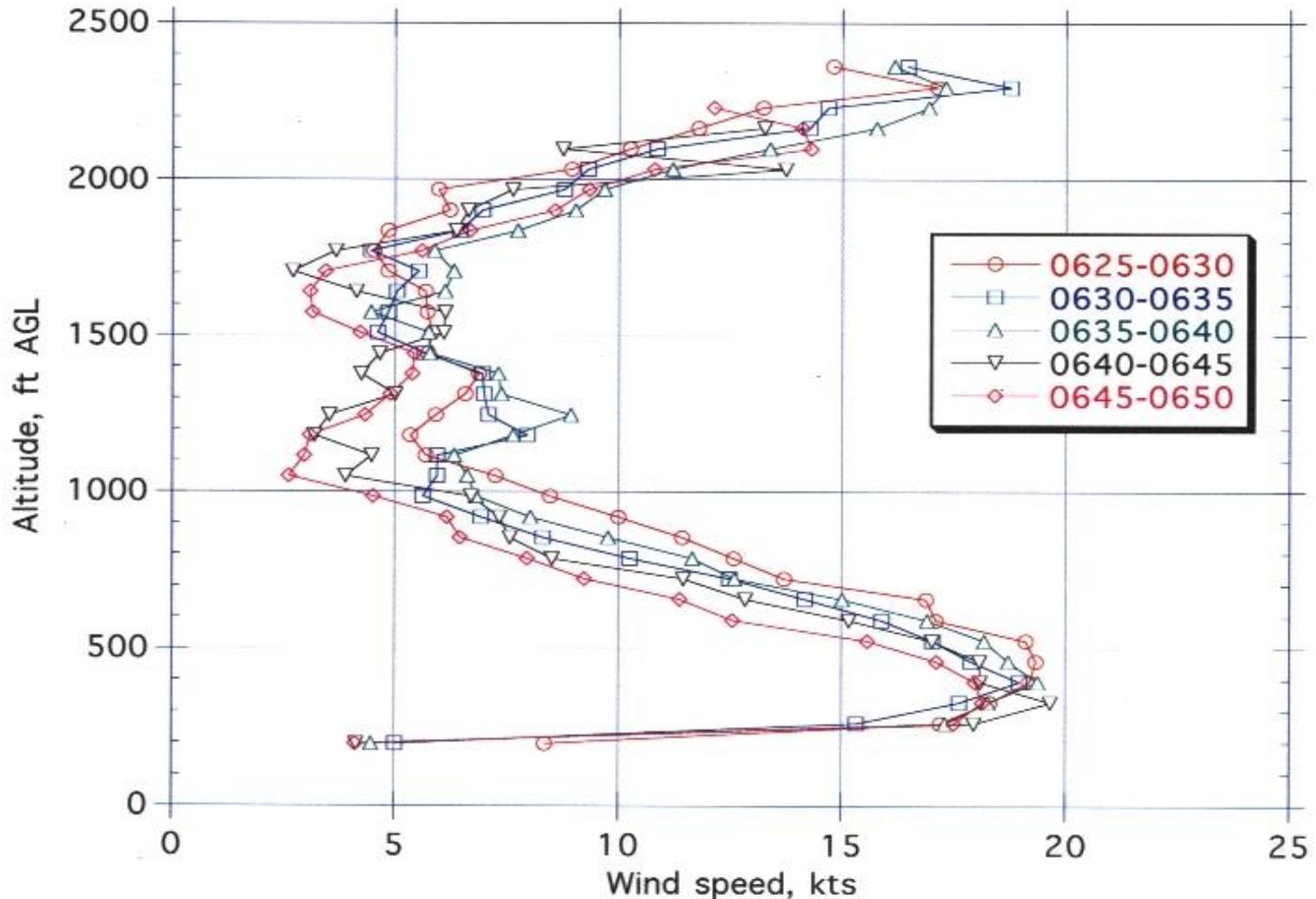
SODAR Profile Trends

SODAR Data for Darkstar Flight
June 29, 1998 0600-0625

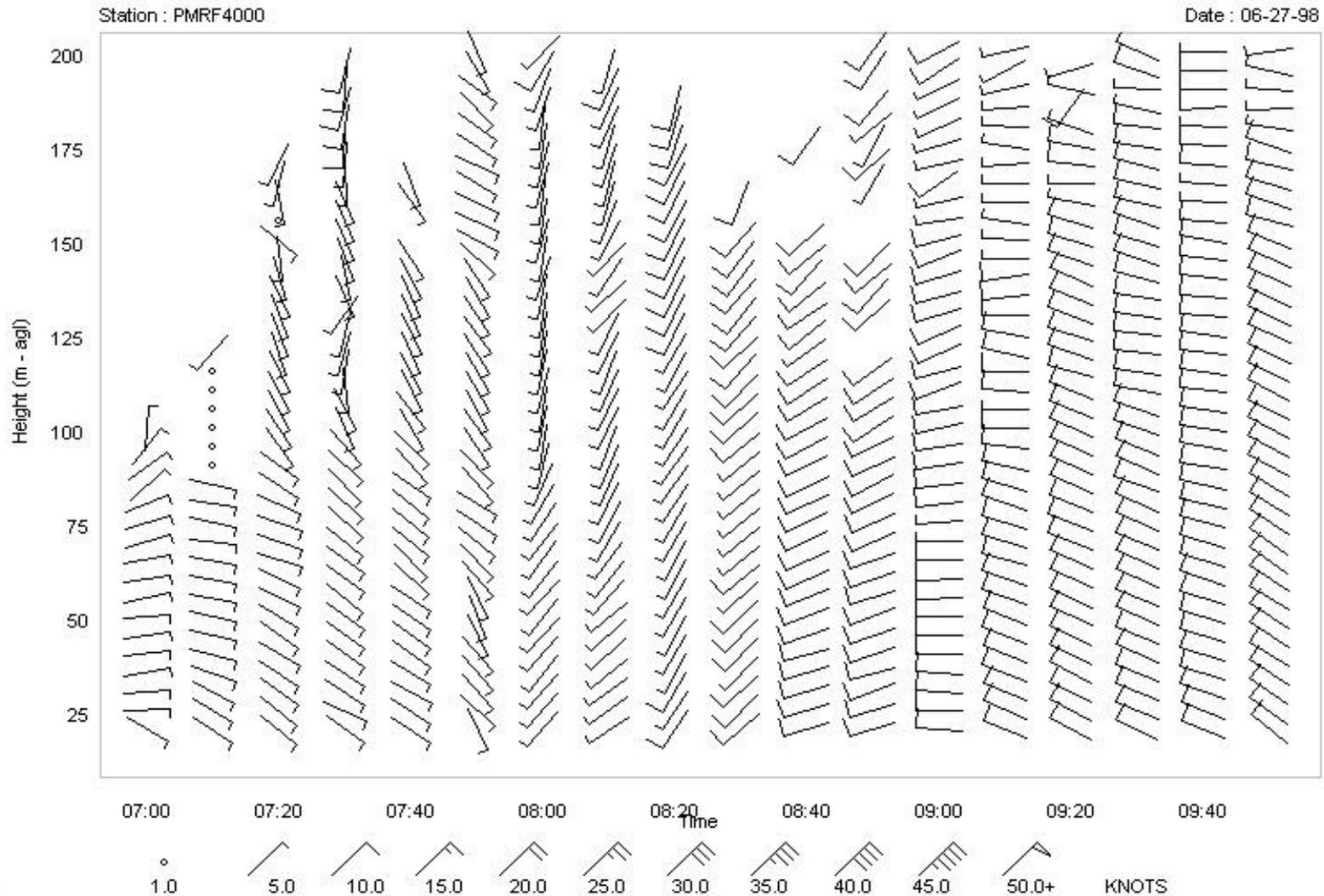


SODAR Profile Trends (cont.)

SODAR Data for Darkstar Flight
June 29, 1998 0625-0650

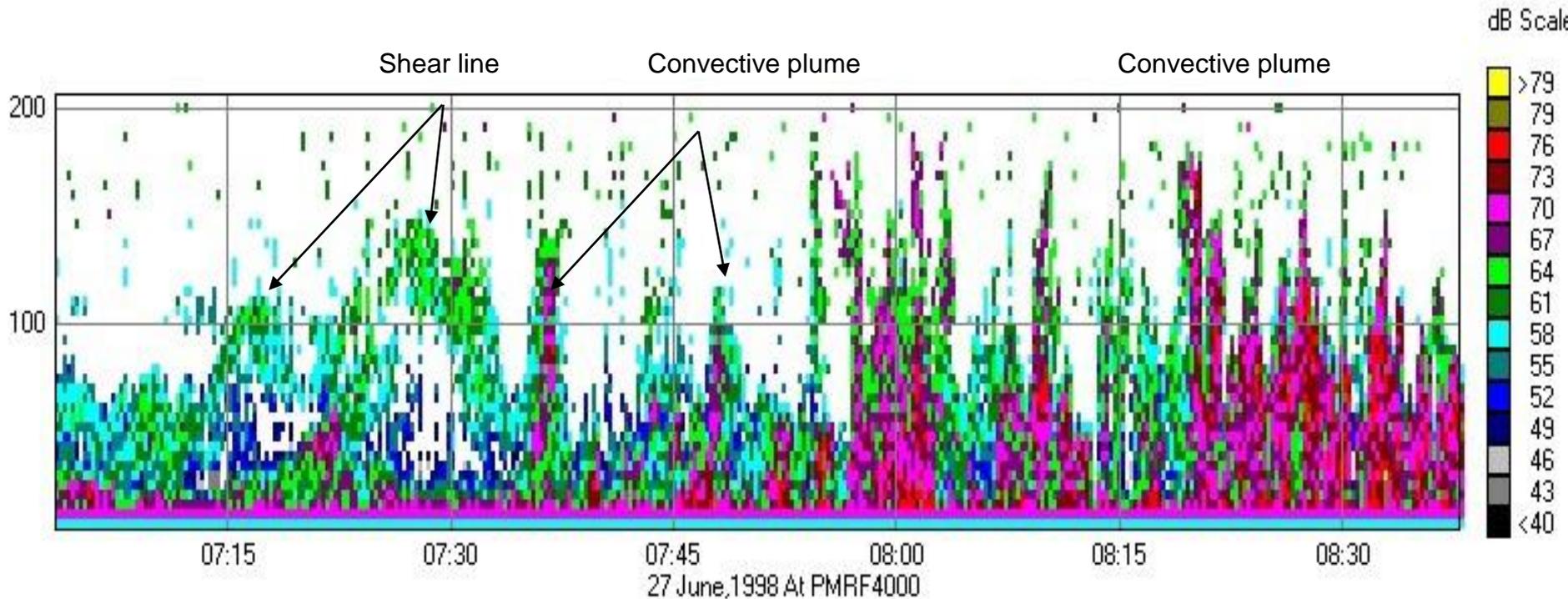


Morning Wind Profile



AM Facsimile Profile

Pathfinder Plus



Model 4000 (miniSODAR)

- Operates at 4500 Hz
- Wind profiles
 - 15 meter AGL min
 - 200 meter AGL max
 - 5 meter intervals
- Sample Rate
 - 1 cycle per 4 sec
- Averaging times
 - 1-5 minute



Radiosonde Balloon: Upper Atmosphere measurements

- Measure winds and altitude (GPS), temperature, humidity and Pressure
- Calculate density, pressure altitude, dewpoint and liquid water content
- Derive stability and turbulence potential



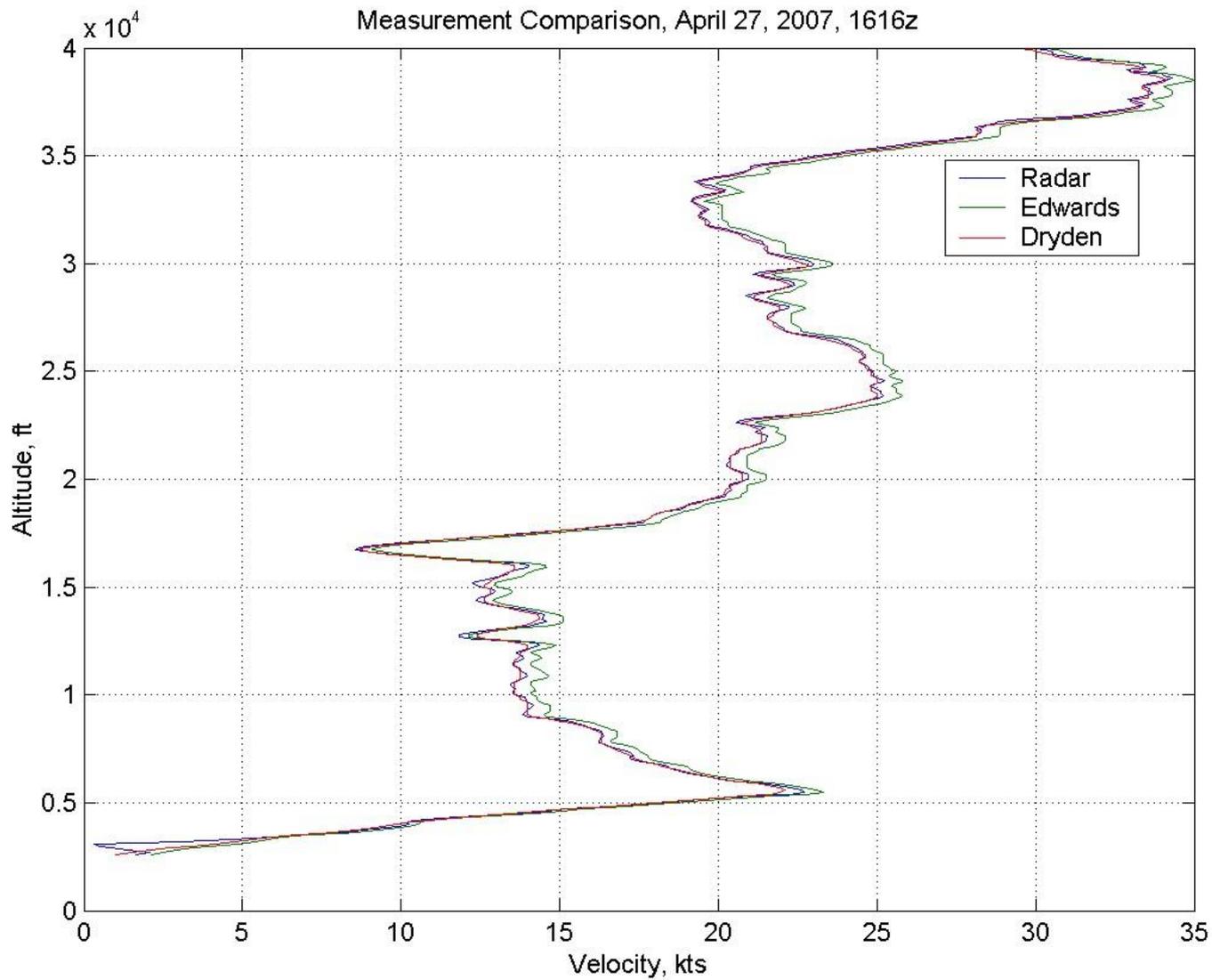
High Resolution Balloon

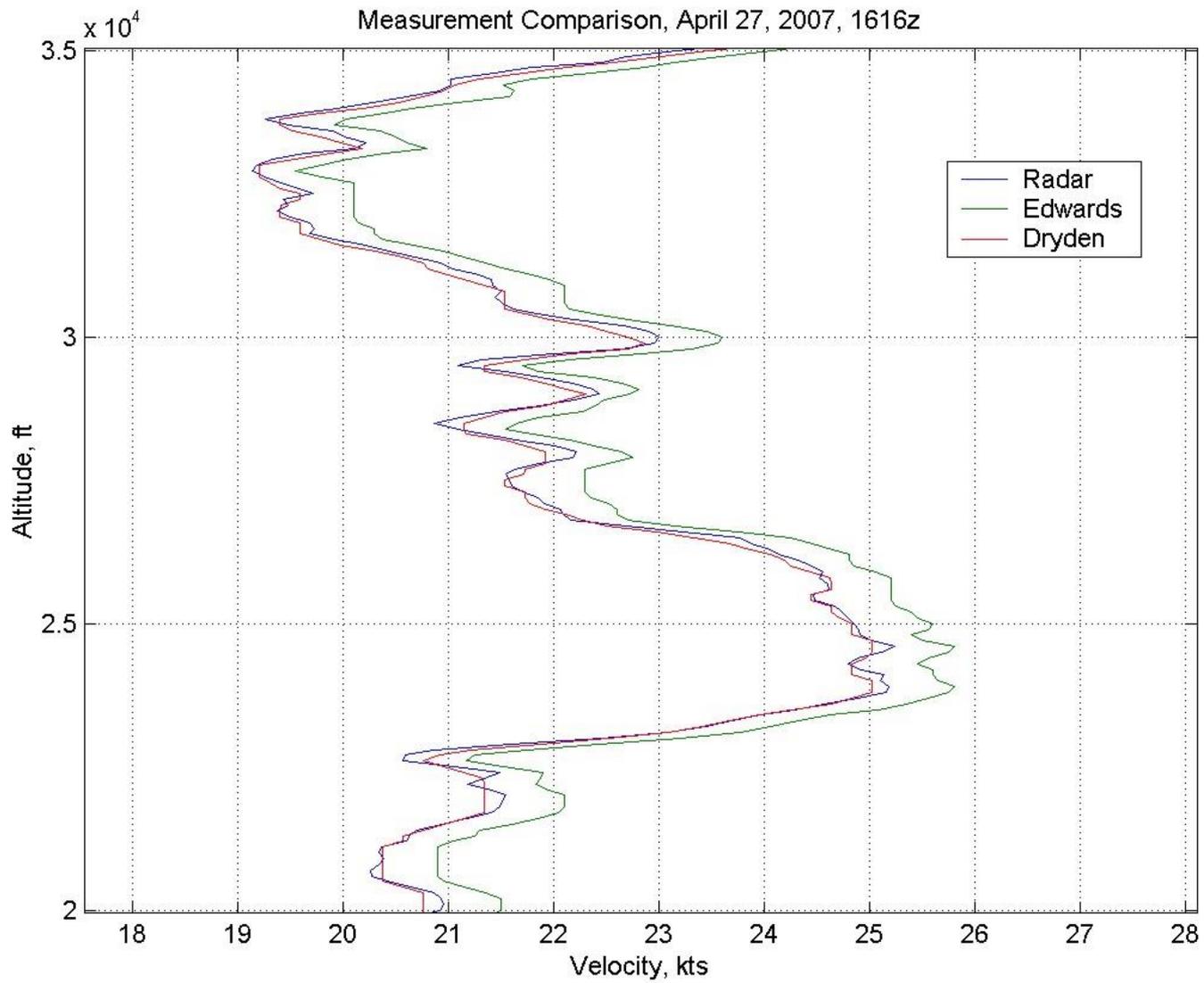
Jimsphere for high
resolution winds
tracked by radar +
Radio sonde package
for thermodynamic data

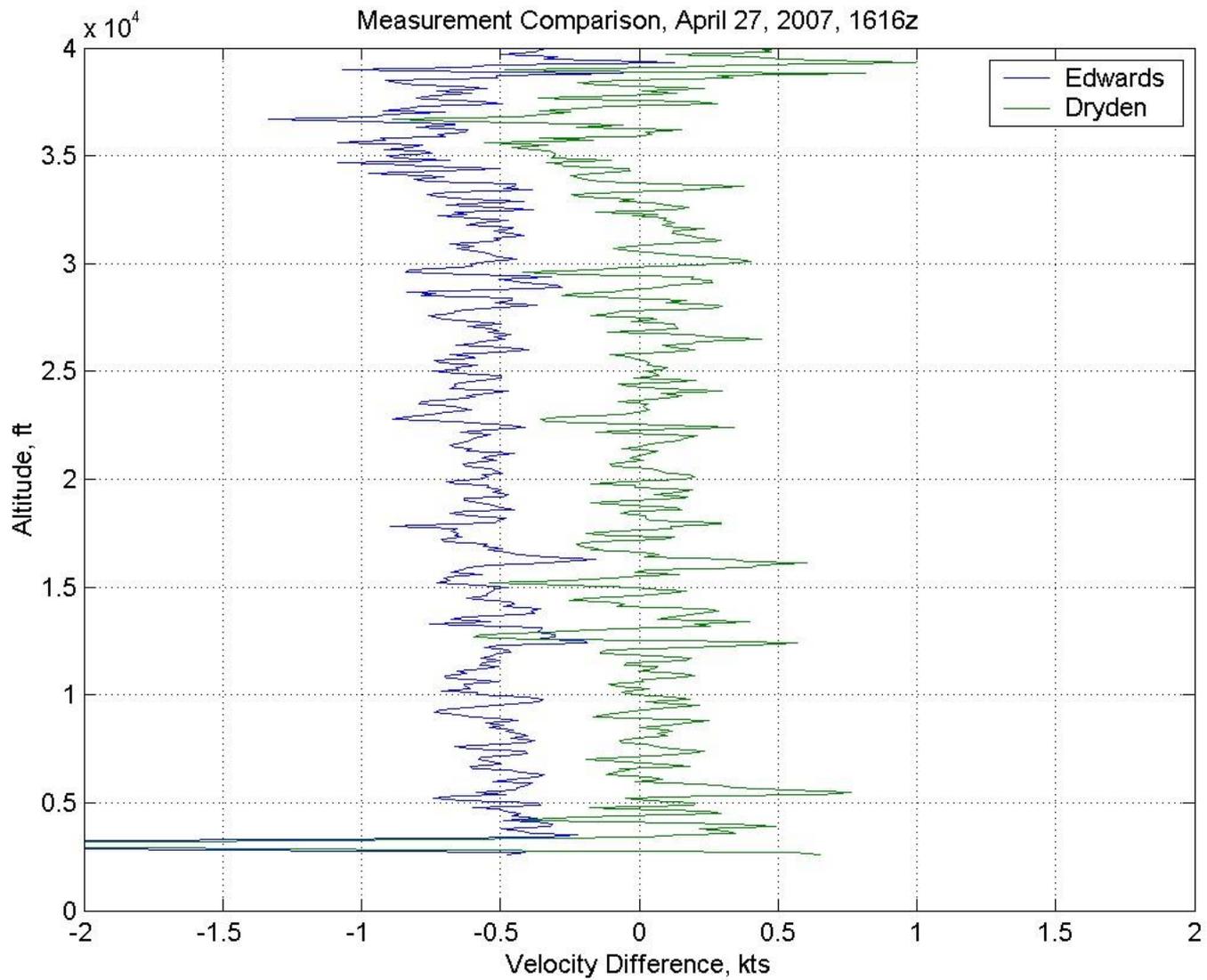


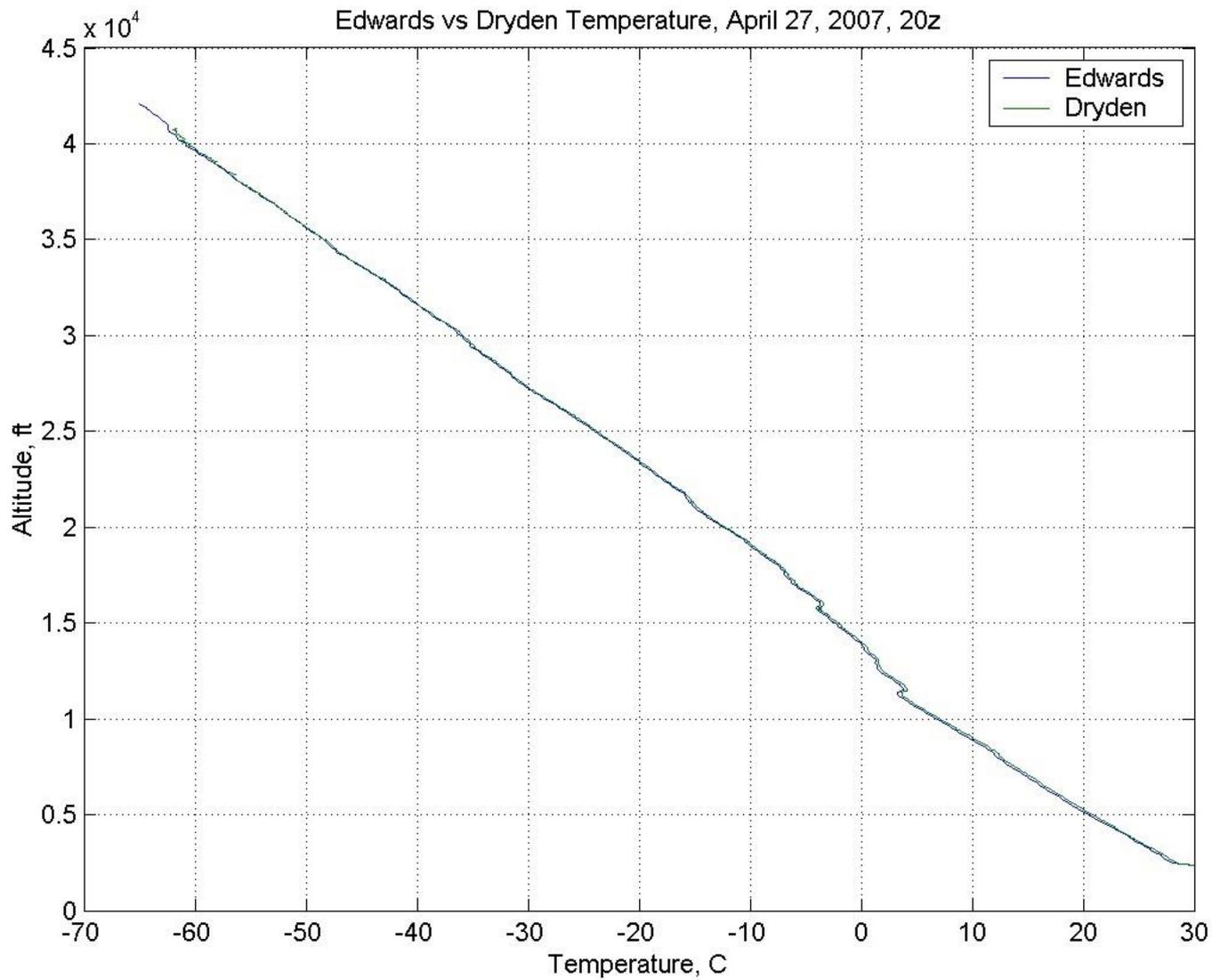


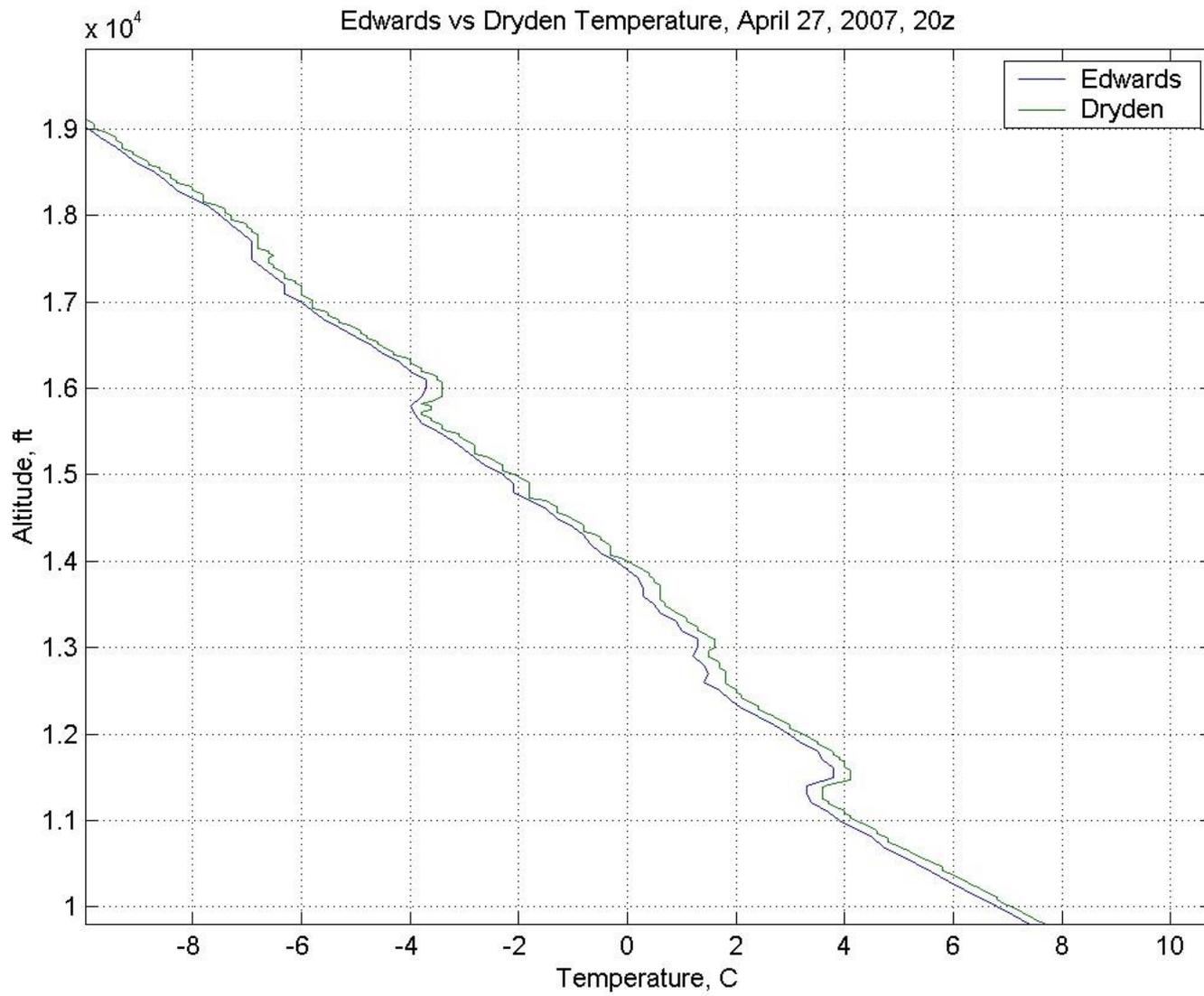


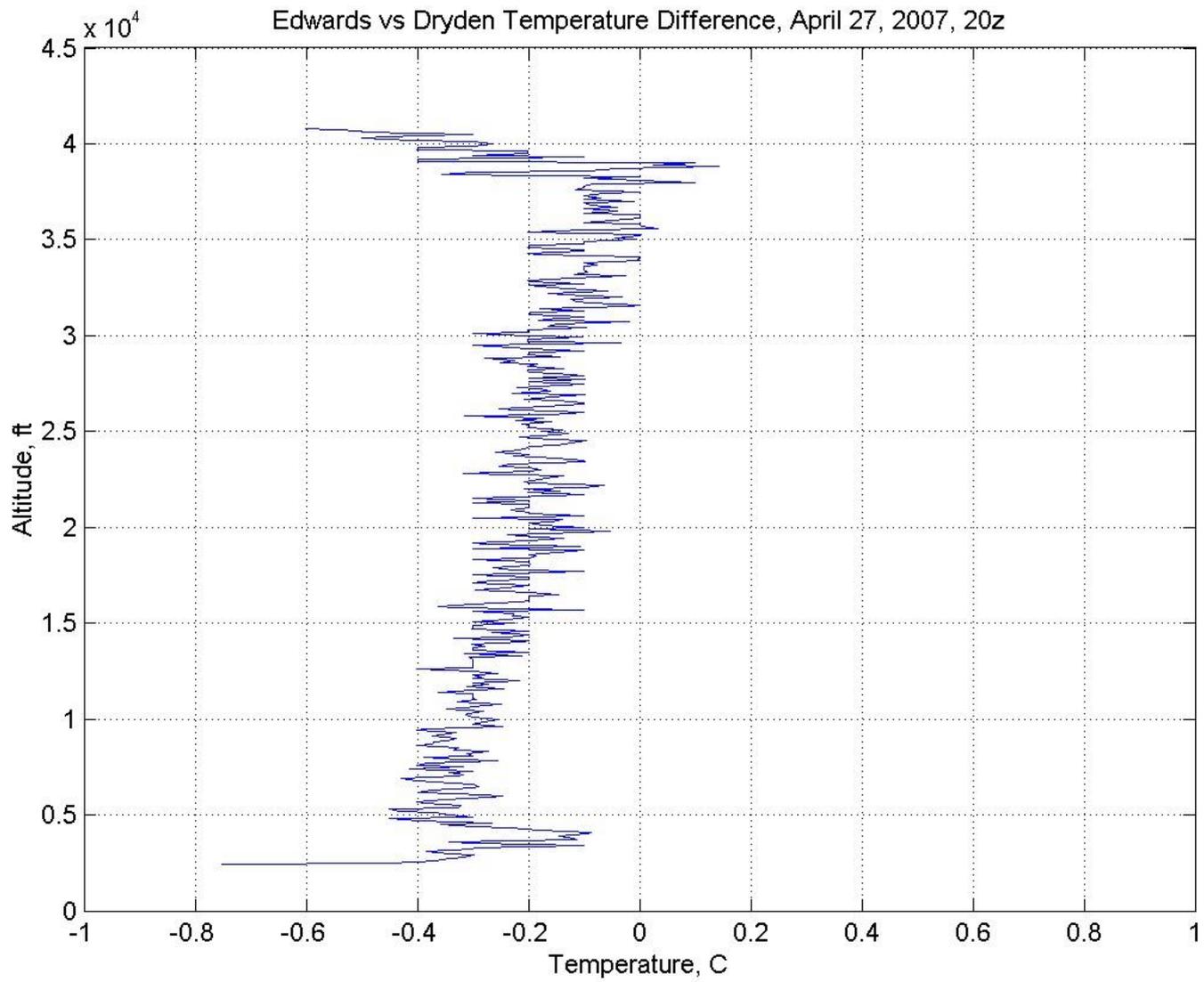


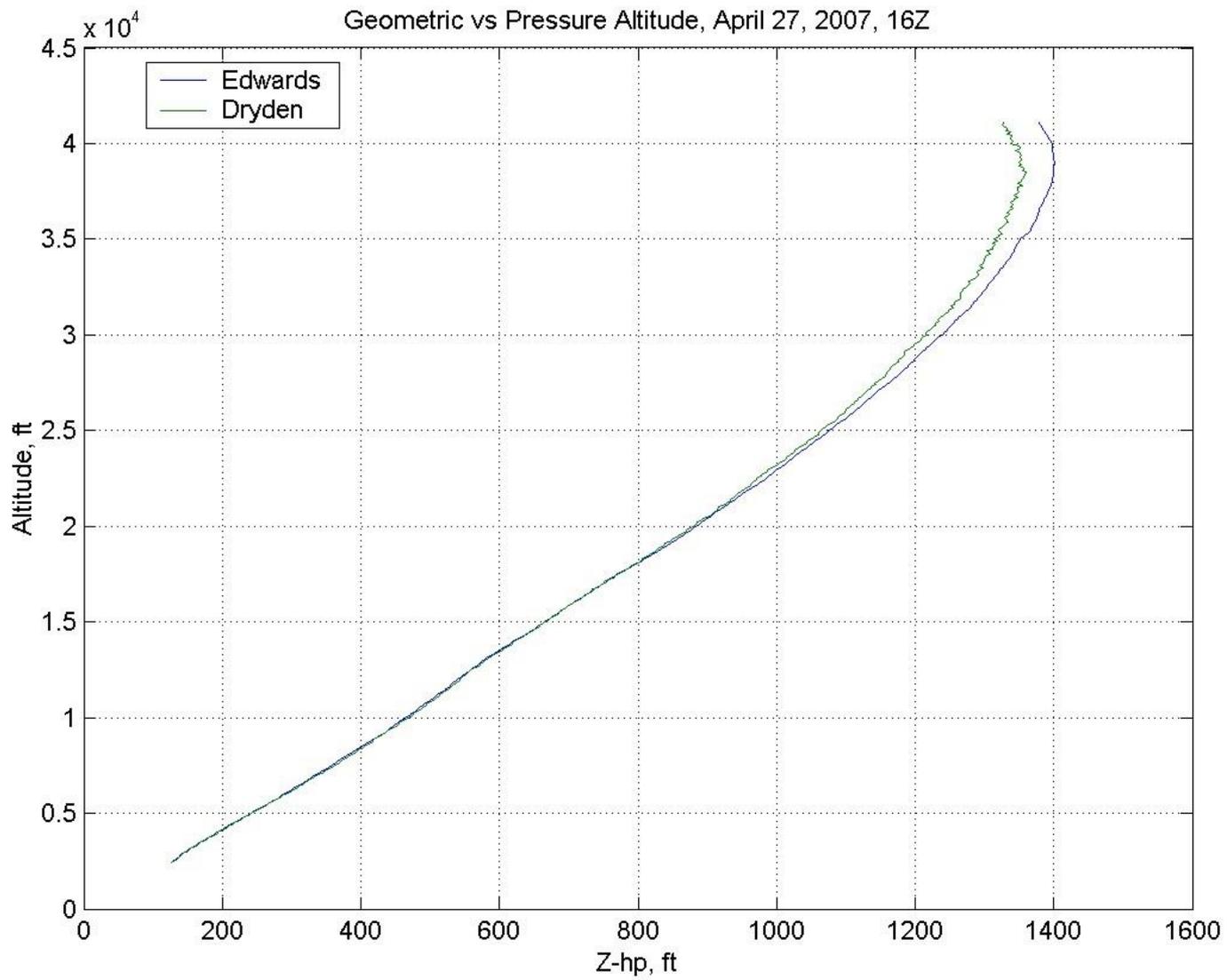


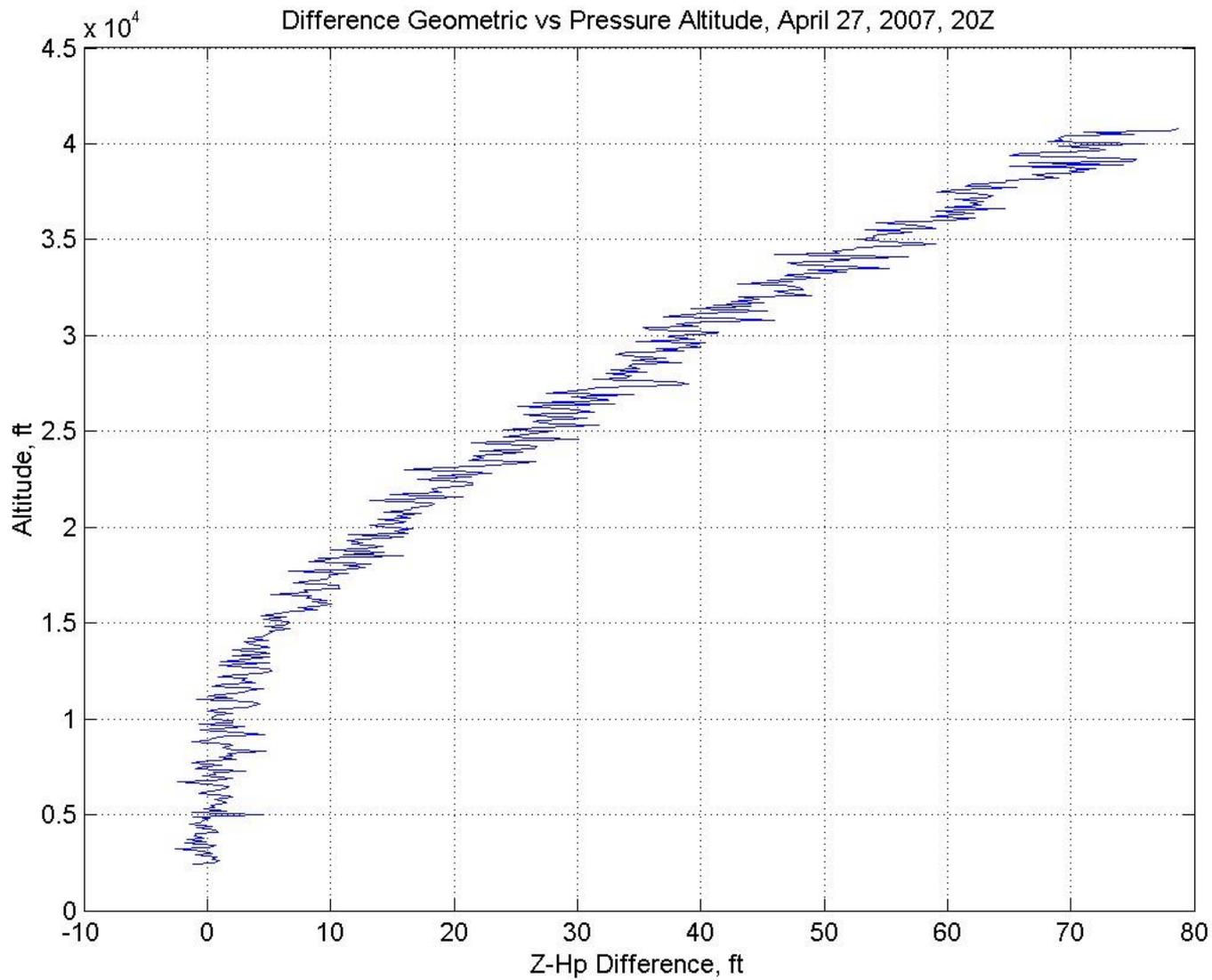












Results

2005 Comparison:

Velocity Difference due to offset in altitude		1-2 kts
Direction Difference	"	3-5 deg
Temperature Difference	"	1 Deg

2007 Comparison

Velocity Difference		0.2 -0.4 kts
Direction Difference		0.1 -0.3 deg
Temperature Difference		0.15 deg



Hypersonics

HTV-2 4/2010 & 8/2011

X-51 5/2010, 3/2011, 8/2012, 5/2013



AHW 11/2011



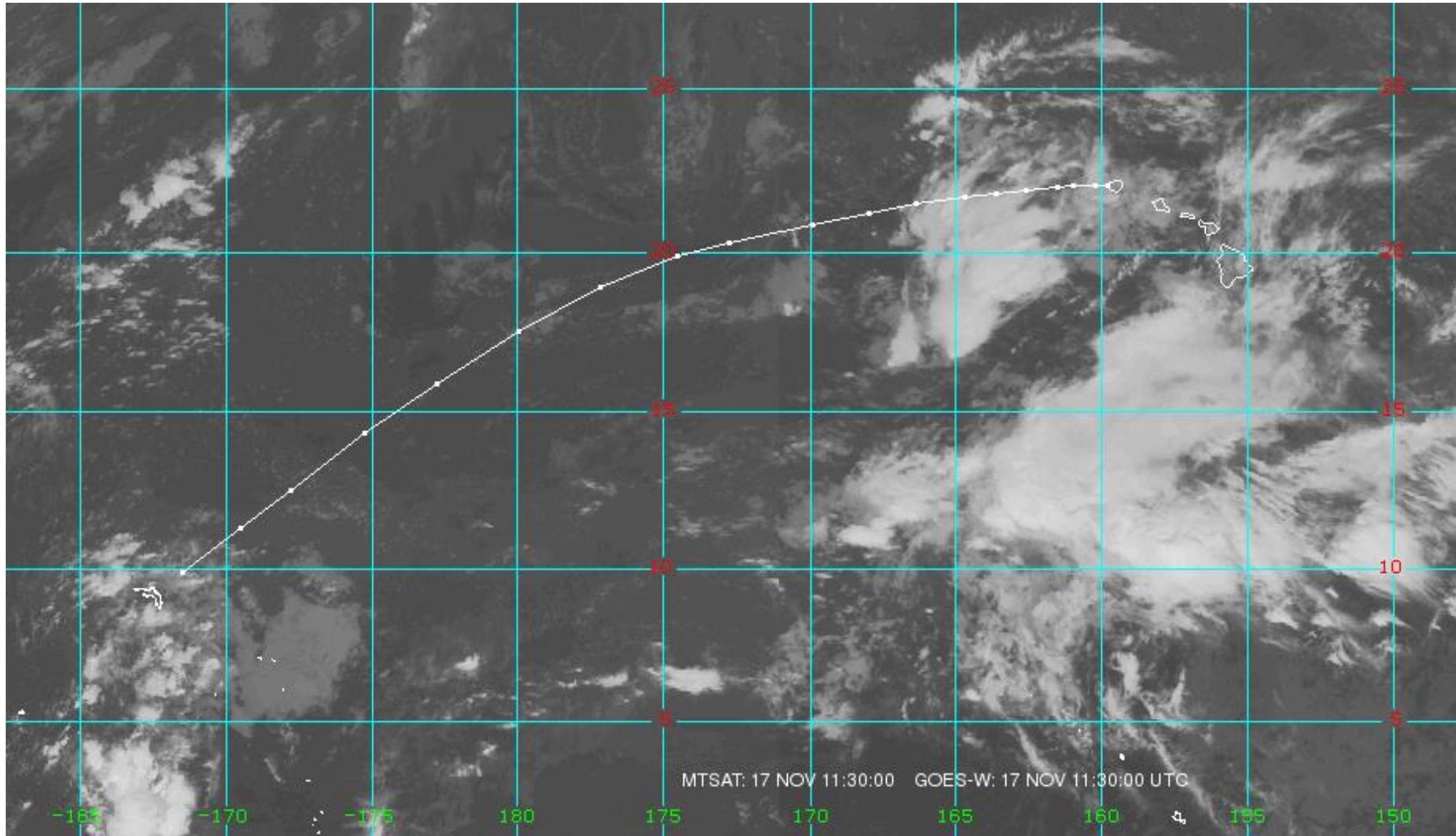
Background Issues

- High altitude (to 50 km) parameters: pressure, temperature, winds and density over 1000's km.
- Very difficult to measure by conventional methods (Balloons).
- Range of sensors too extreme and no airdata probes on vehicles due to severe aerothermal heating during hypersonic speeds.
- GRAM standard deviations grow very large with altitude.

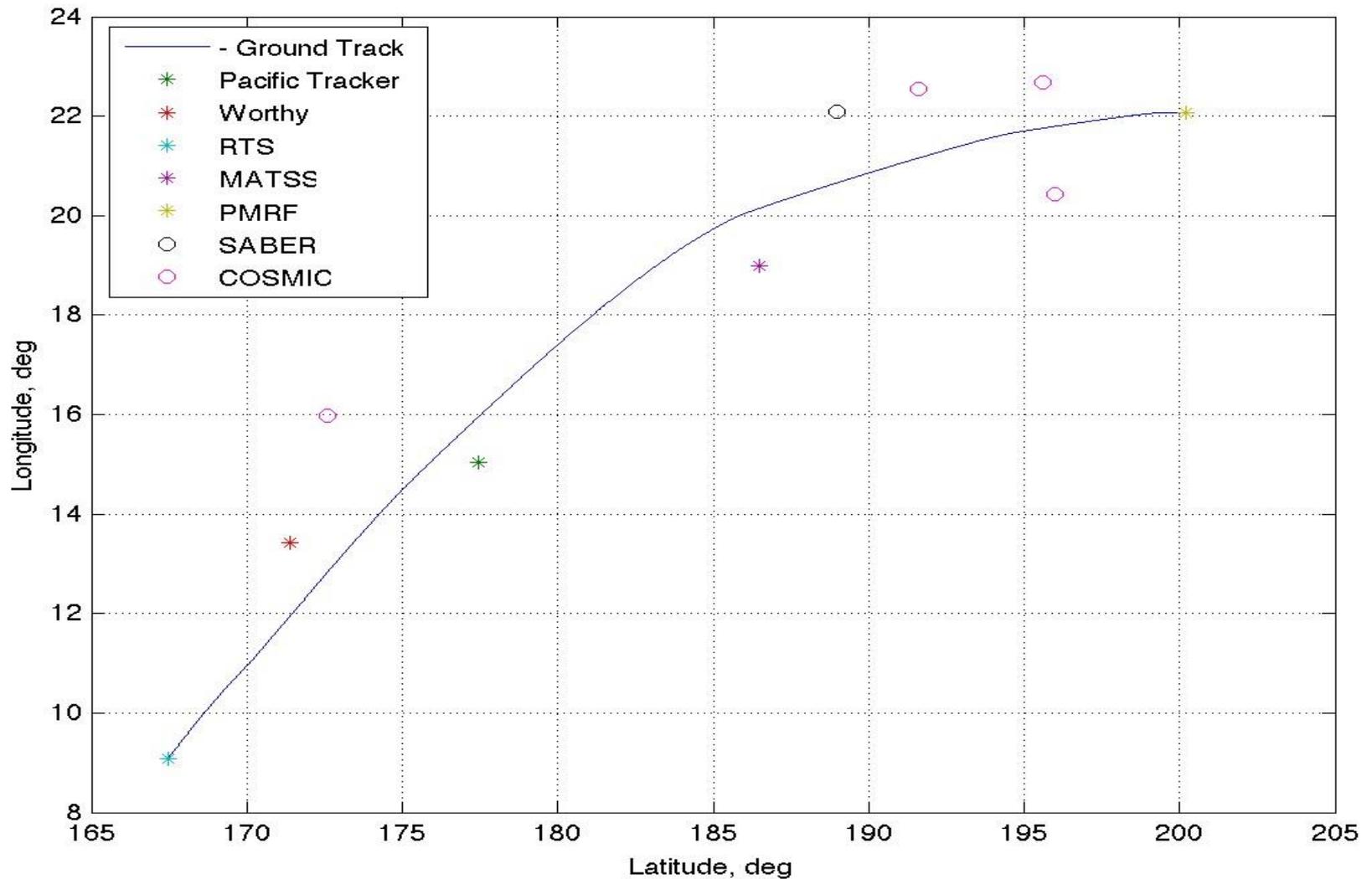
Challenges

- Obtaining data in a region of the atmosphere where data is very limited (ignorosphere).
- Formulate a Best Estimate Atmosphere (BEA) that meets uncertainty requirements.
- Identify data sources that are/were projected to become available and to determine how to integrate these data.
- Develop a data analysis tool to evaluate the data and produce a modeled atmosphere based on representative data.

AHW Flight Path Nov 17, 2011



AHW Measurement Locations



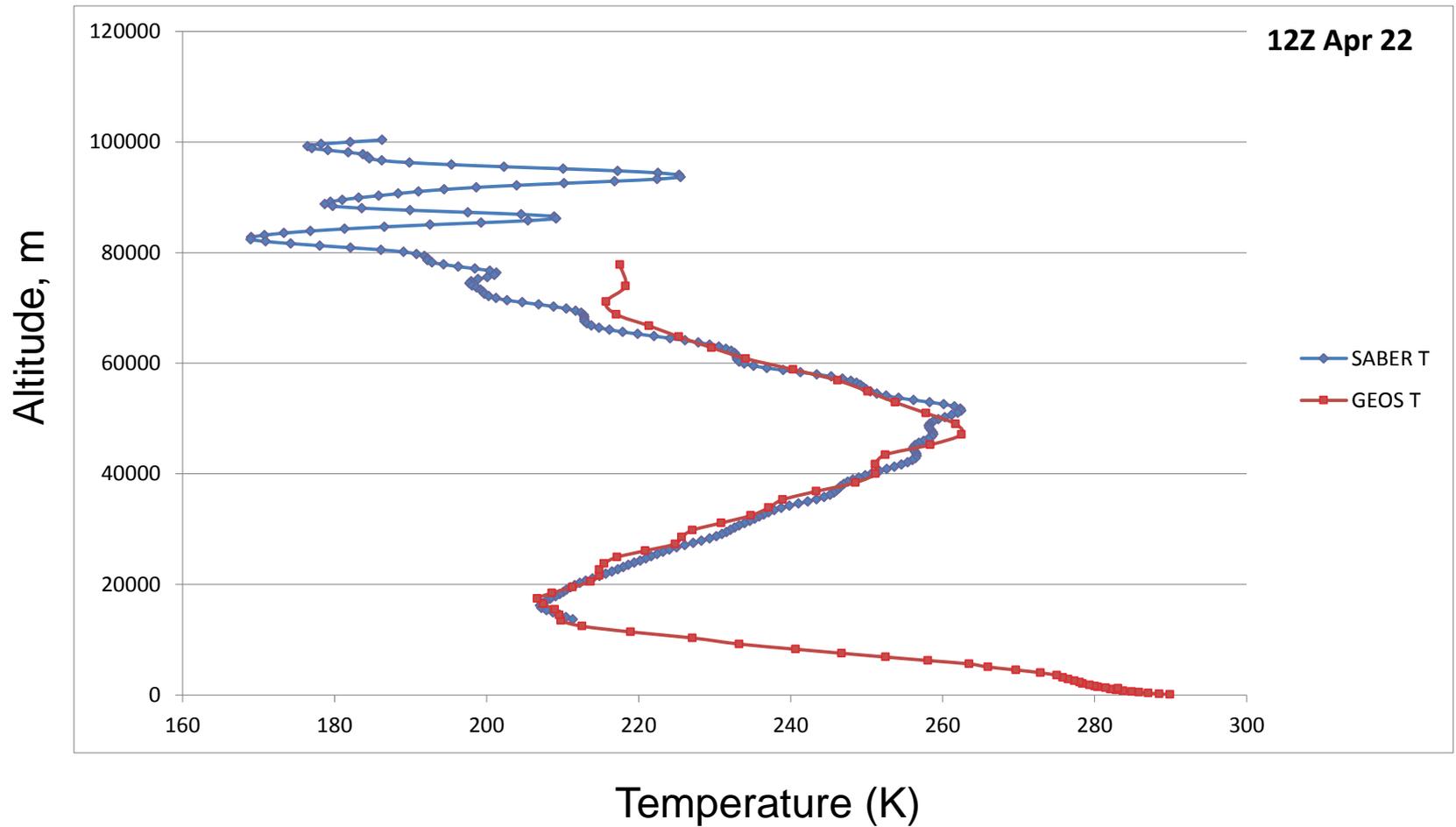
Example of Data Sources

- GEOS-5 data
 - 3d instantaneous fields (no averaging)
 - 0.25° lat by 0.33° long to 72 km (236Kft)
- NOGAPS –NAVY
 - Mandatory levels to .4 mb 52km (170 Kft)
 - 1° Lat x 1° Long
- Radiosondes (Locations along flight track to 40 km (130 Kft))
- Meteorological rocket data to 85km (280 Kft)
- SABER data
- COSMIC data
- Satellite imagery
- Global Reference Atmospheric Model (GRAM) - Earth v.2010
- No Mauna Loa LIDAR (down and clouds)
- HALAS Lidar
- ACLAIM lidar

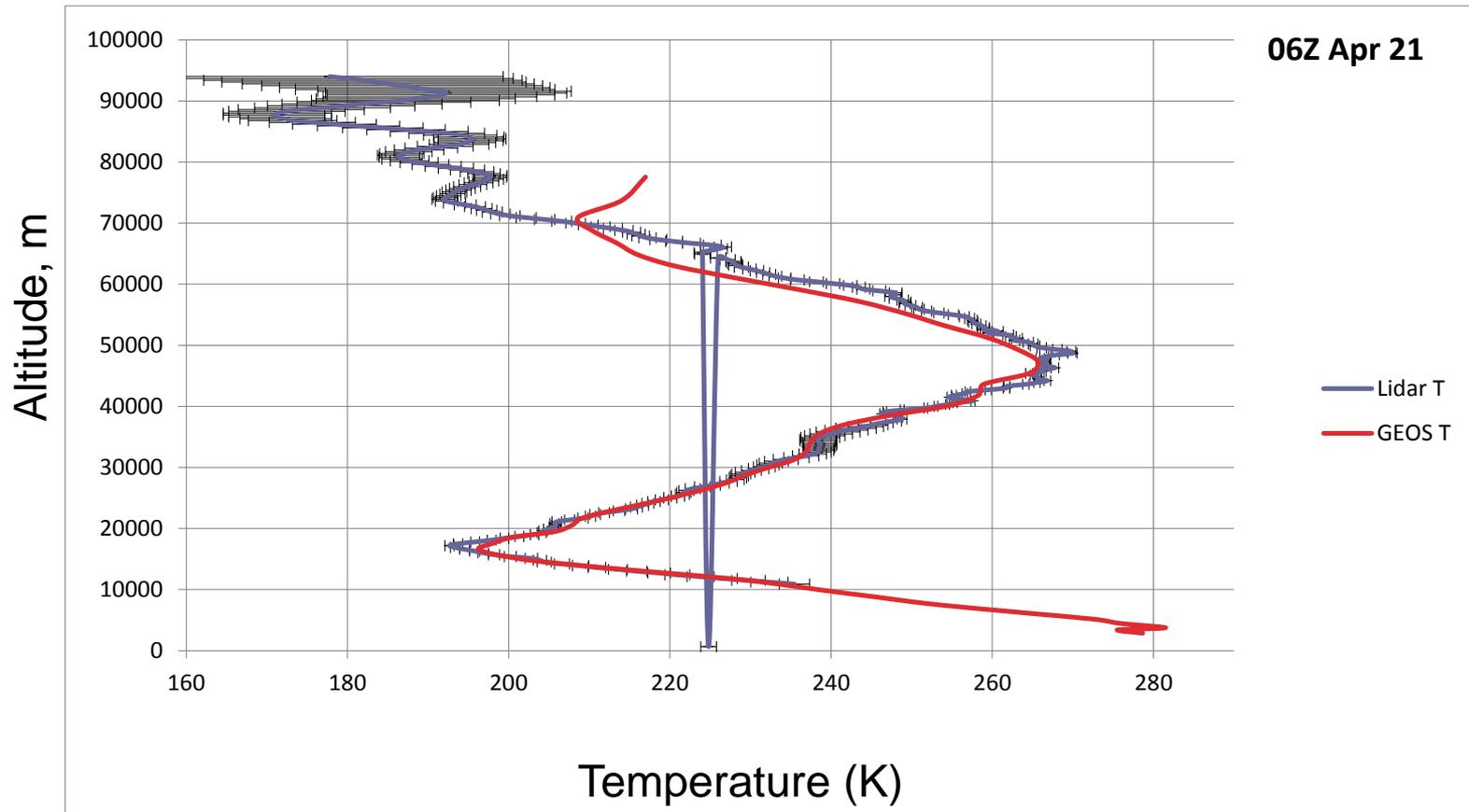
AHW Data Sources

- Lower Atmosphere (SFC – 40km):
 - Radiosonde Balloons (6)
 - Models (2)
- Middle Atmosphere (30 – 80km)
 - Rocketsonde (2)
 - Satellites (2)
 - GRAM-2010
 - Models (2)
- Upper Atmosphere (70 – 120km)
 - GRAM-2010
 - Satellites (2)
- Blending technique for overlap regions

Data Comparison SABER vs GEOS 5

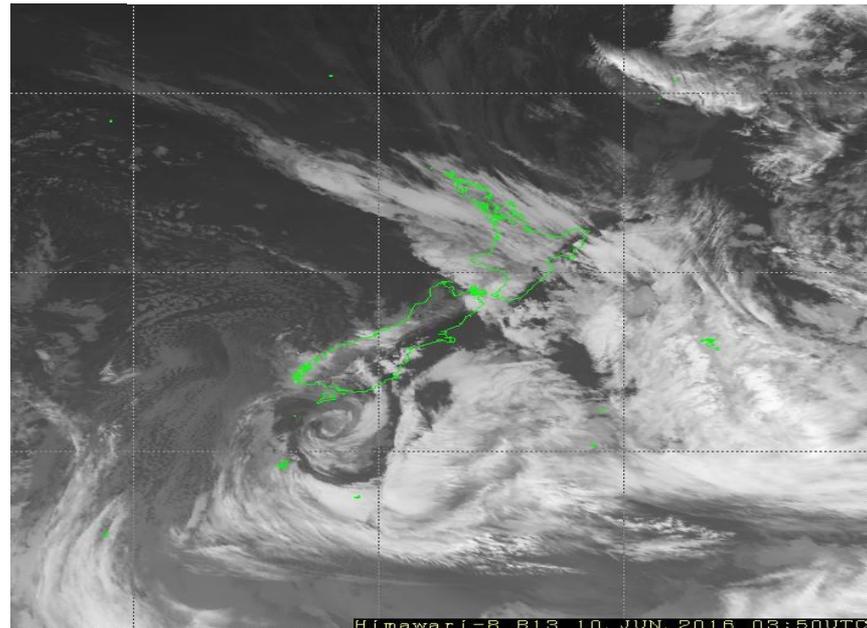
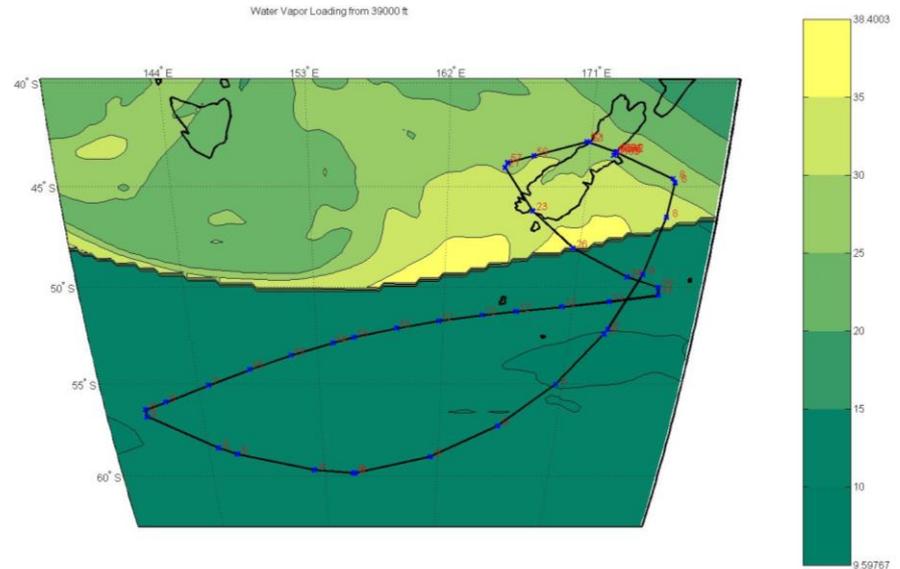


Data Comparison Lidar vs GEOS 5



NASA Meteorology Group

- **Forecasts and courtesy briefings**
 - Winds, gusts, visibility, clouds, particulates, water vapor loading
- **Hazards**
 - Turbulence, icing, wind shear, T-storms, IFR conditions, mountain wave, lightning
- **Flight/project support**
 - Crew briefs, T-x briefings
 - Full-time in-flight weather monitoring
- **Best-Estimate-Atmosphere**
 - Trajectory analysis for atmospheric parameters
 - Airdata calibration
 - RVSM
- **Climatology**
 - Project planning studies
- **Real-time ground measurements**
 - Extensive weather station network
- **Mobile balloon launches**
 - Portable for project specific applications



Want more info:

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