Tools for Software Based Validation and Verification of Small Satellites

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Overview

What is NOS\(^3\)?

- A software test bed for small satellites – Currently a Functional Beta
- Based upon STF-1 hardware, but sufficiently generic
- Easily-interfaces to CFS, but CFS not required
- Openly distributed solution Ready-to-Run (RTR)
- A collection of Linux executable and libraries
- Test as you fly

What is it used for?

- FSW early-development – NOS\(^3\) provides real-world inputs to FSW
- FSW V&V – Testing FSW, invalid inputs, behavior, stress conditions
- FSW Integration – Used for early-app development and payload team integration
- Mission Planning – Example: power analysis
NOS³ Components

• Virtual Machine – for running NOS³
• NOS Engine Middleware
• Hardware Simulators
• FSW Hardware Abstraction Layer
• Orbit Inview & Power Prediction (OIPP) Tool
• CFS – Flight Software
• 42 – Dynamics Simulation and Visualization
• COSMOS – Commanding & Telemetry
NOS$^3$ Architecture

Ground System Software (COSMOS)

STF-1

Commanding & Telemetry

OS Abstraction Layer (OSAL)

Linux (x86, ARM/Pi)

NOS Engine

Hardware Models

42

FreeRTOS (AVR32)

Flight Hardware

Ground System Software (COSMOS)

NOS$^3$ UI & Control

Hardware Adapter i2c / SPI

NASA Operational Simulator for Small Satellites

NOS$^3$

Independent Test Capability
Virtual Machine Auto Generation

• Install *Vagrant* and *VirtualBox*
• Run `vagrant up`
• Developer build tools installed
• Convenience scripts for building/running
• Ready-to-run after unpacking a .tar
NOS Engine Middleware

- ITC developed middleware
- Common server to communicate to all data nodes (CFS, Hardware simulators, Time ticker, Command terminals)
- C API
- I2C, UART and SPI protocols
- Asynchronous and Synchronous
Hardware Simulators

• Modeled based on characteristic data, or manufacturers data specifications

• Currently have modeled
  – Novatel GPS
  – Clyde EPS
  – Honeywell Magnetometer
  – ISISpace Antenna System
  – A3200 support chips (FRAM, Gyro
Flight Software (CFS)

- Open source flight software developed by GSFC
- Includes an OS Abstraction Layer
  - Allows building for flight and NOS$^3$ targets on same machine without source code changes
- Additional Platform-Support-Package (PSP) added to sync CFS time with NOS$^3$
GSFC Open Source Dynamics Simulator

- NOS$^3$ TCP/IP Socket Integration
- Simulation time synchronized with NOS$^3$
- Moving toward closed loop
COSMOS

• Open Source for embedded system commanding and telemetry

• Currently connects to CFS TO_lab
  – Future plan is to have radio simulator to replace TO_lab

• Can be used for operator training, testing table loads to SC, verifying command and telem databases, etc.
Orbit, Inview, and Power Prediction

• Web page: Generated daily by cron job
• TLE Data pulled from http://celestrak.com as obtained from NORAD
• Time Periods (configurable)
  • Yesterday, Today, Future
• Displays
  • Ground station in-views
  • Sunlight and Eclipse times
Orbit, Inview, and Power Prediction (OIPP)
Backup Slides
NOS$^3$
Utilization
Example for STF1