Flight Control Research at NASA Ames

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ACGSC Meeting

March 27-29, 2019
Santa Fe, NM
Flight Control Research at NASA Ames

Intelligent Systems Division: Advanced Control and Evolvable Systems Group (ACES)

- Adaptive, robust, and optimal control
- Unmanned Aerial System autonomous operation
- Avionics architectures and processes

Elastically shaped aircraft concepts

- Truss-braced wing ASE model development
- Real-time drag optimization control
- Multi-objective gust load alleviation control
- Wind tunnel demonstrations

Truss-braced wing

Variable Camber Continuous Trailing Edge Flap (VCCTEF)
Elastically-shaped Aircraft Research

Variable Camber Continuous Trailing Edge Flap (VCCTEF) as a performance adaptive aeroelastic wing technology funded by ARMD since 2010

Partnership and collaboration
- External partners include Boeing, SSCI (Scientific Systems Company, Inc.), and University of Washington (UW)
- Cross center collaboration with NASA LaRC

Research elements in FY 2019
- Multi-objective control for gust load alleviation (GLA) / drag optimization and wind tunnel validation
- Drag optimization of Boeing CRM (Common Research Model) aspect ratio 13.5
- Coupled aeroservoelastic flight dynamic modeling of Boeing Transonic Truss-Braced Wing (TTBW)

Advancing technology to TRL 5 through five wind tunnel test validation campaign
- Aerodynamic cruise drag test at UW (2013) and high lift test at UW (2014)
- Active Real-time drag optimization control test at UW (Jun 2018)
- Active GLA control tests at UW (May 2019) and in NASA LaRC Transonic Dynamic Tunnel
Truss Braced Wing Multi-Fidelity Modeling

- Rapid nonlinear ASE modeling technique enables transonic flutter analysis for design optimization
- Wing-strut interference requires aerodynamic correction
- The multi-fidelity modeling framework provides a means of interference correction using FUN3D CFD
Real-Time Drag Optimization Wind Tunnel Test

- Wind tunnel CRM model
- Aerodynamic model parameter identification by least-squares
- Real-time optimization by iterative angle-of-attack seeking method
- Algorithm identified **3.9% drag reduction at off-design CL = 0.65**

<table>
<thead>
<tr>
<th>Run</th>
<th>Design $C_L^* = 0.5$</th>
<th>Off-Design $C_L^* = 0.65$</th>
<th>Off-Design $C_L^* = 0.7$</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>$C_D$ $\Delta C_D$</td>
<td>$C_D$ $\Delta C_D$</td>
<td>$C_D$ $\Delta C_D$</td>
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<tr>
<td>Clean Wing Run 56</td>
<td>253 0</td>
<td>330 0</td>
<td>382 0</td>
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<tr>
<td>Optimal Solution 1 Run 53</td>
<td>248 5</td>
<td>317 13</td>
<td>364 18</td>
</tr>
<tr>
<td>Optimal Solution 3 Run 54</td>
<td>255 -2</td>
<td>321 9</td>
<td>367 15</td>
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<td>376 6</td>
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<td>Pseudo-Inverse Solution 1 Run 57</td>
<td>259 -6</td>
<td>322 8</td>
<td>360 22</td>
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<tr>
<td>Pseudo-Inverse Solution 3 Run 58</td>
<td>252 1</td>
<td>321 9</td>
<td>346 36</td>
</tr>
</tbody>
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- **Impact:** Technology can achieve drag optimization at off-design cruise, enabling mission-adaptive wing capabilities
Multi-Objective Control Architecture

Incremental controller development

- 6-DoF tracking controller
- Multi-objective controller
- Gust prediction corrector control

State and gust estimation methods

- On-wing reactive vs. look-ahead predictive
- Adaptive estimation
- Incorporation of FOSS measurements

\[
J = \lim_{t_f \to \infty} \frac{1}{2} \int_0^{t_f} \left( x^T Q(x)x + u^T R u + q_M(x) M_y^2 + q_D(x) \Delta C_D \right) dt
\]

Sensor-Driven
Mode Suppression

Sensor-Driven
Drag Minimization

Sensor-Driven
Load Alleviation

Reduction due to sensor-driven weights
University of Washington test team
  • SSCI, University of Washington, Boeing, NASA Ames ACES Group

Experimental description
  • Objective is to demonstrate multi-objective GLA control for flexible wing
  • Low speed tunnel test
  • Low cost wing development and design
    o VCCTEF actuation
    o Traditional sensors only
  • Gust generator development necessary

Serves as risk reduction measure for subsequent transonic IAWTM test
UWAL ASE Wind Tunnel Model

Foam base with central spar—allows for flexible structure with functional ultimate strength

VCCTEF Flap Prototype

Embedded Push Hinge

Embedded Flap B Hinges
UWAL Gust Modeling

Gust model identified from CFD simulation

- Predict gust at wing from look-ahead point
- Stand in for LIDAR readings
- Facilitates accurate GLA

\[
\hat{w}_{\text{wing}} = G(s) w_{\text{ahead}}
\]