Extending A Correction Method for Unsteady Transonic Aerodynamics to Variable Camber Continuous Trailing Edge Flap

Upender K. Kaul* and Nhan T. Nguyen**
NASA Ames Research Center, USA.

In this study, we have extended our correction method for transonic aerodynamics1 to baseline and variable camber continuous trailing edge (VCCTEF) geometries of super-critical airfoils at cruise conditions. This correction method modifies Theodorsen theory, which is based on incompressible potential flow over a flat plate. The method is partly based on CFD RANS simulations of oscillating NASA generic transport model (GTM) baseline cruise and VCCTEF airfoil geometries in pitch and shows promise for addressing transonic flutter problems of aeroelasticity. In the earlier study1, the Theodorsen functions were modulated with non-linear functions of Mach number, \( M \), and reduced frequency, \( k \), and thus the correction was demonstrated for the symmetrical NACA0012 airfoil. In the present study, the modulation functions are also allowed to account for the effects of camber and thickness of the airfoil. This is demonstrated by applying the correction method to various symmetric NACA00xx airfoil geometries (NACA001, NACA0002, NACA0012, NACA0015 and NACA0018), the NASA GTM super-critical baseline and VCCTEF airfoil geometries, e.g., the circular airfoil, VCCTEF222. First results indicate that the correction method accounts for a large variation of thickness of airfoils and camber. The present correction method will guide the development of a new state space model for the VCCTEF system and eventually a new transfer function that will be incorporated in a new aeroelastic framework leading to an appropriate transonic flutter model for use in the future aircraft systems in development under the NASA Advanced Air Transportation Technologies (AATT) project.

Introduction

Transonic flutter is a topic of high interest for aircraft design. Doublet lattice methods are frequently used in flutter analysis that can accurately predict low-speed flutter where the flow is entirely subsonic at low Mach number2. Transonic flutter, on the other hand, is a pacing item in transport aircraft design. Many methods for transonic flutter have been developed ranging from doublet-lattice methods with steady state transonic correction to high-fidelity CFD coupled to structural dynamic models of wing structures.3-5 While the transonic flutter prediction can be more accurate with high-fidelity CFD methods6,7 than with unsteady potential flow methods, the computational cost is high. In many applications that involve design optimization with flutter constraints, the computational cost associated with high-fidelity CFD presents a barrier. Therefore, computationally efficient methods for transonic flutter prediction continue to be of high interest to the aircraft design community. In our previous work1, we proposed a method for extending the classical Theodorsen’s theory of unsteady aerodynamics for incompressible flow8 to transonic flow. The method proposes a modified Theodorsen’s function to correct for changes in the amplitude and phase shift of the circulatory lift due to transonic flow. The method derives, partly, from a reduced set of steady state CFD simulations that are made a priori, as an input to the new method. Unsteady CFD simulations are
When the quasi-steady state lift reaches its maximum amplitude at some normalized time \( \tau \), the oscillating circulatory lift reaches its maximum amplitude later at some lag time \( \Delta \tau = \tau - \tau_0 \), where \( \tau_0 \) is the lag time between the oscillating circulatory lift and the quasi-steady state lift which is almost time-independent, i.e., \( \partial \alpha / \partial t \approx 0 \). Thus,

\[
\bar{C}_l = C_{l_{\alpha}} \alpha_0 \sin 2k\tau
\]

is the lag time between the oscillating circulatory lift and the quasi-steady state lift which is almost time-independent, i.e., \( \partial \alpha / \partial t \approx 0 \), and the wake does not contribute to the lift. So, for lower values of reduced frequency, the circulatory lift becomes dominant.

For oscillatory airfoil, the singularity distributions on the airfoil and in the wake change with time, but satisfy the two constraints (zero normal velocity on the airfoil and Kutta condition) for all time. For flutter problems, the angle of attack is assumed to be small enough so that the flow separates tangentially from the top and bottom edges of the trailing edge face, the Kutta condition is practically obeyed. The zero-normal velocity condition on the airfoil is satisfied by source/sink singularities on the airfoil. The pitching motion of the airfoil determines the strength of the source/sink distribution. This is similar to the mixing layer flow over a flat plate subject to sinuous oscillations imposed at the trailing edge, where the zero normal velocity on the flat plate is enforced by a vortex sheet whose density changes with time. The pressure difference caused by the associated potential gives rise to the "non-circulatory lift", which excludes the effect of the wake on the lift on the airfoil. This non-circulatory lift is a result of the so-called apparent mass effect due to inertia associated with the airfoil motion. It reflects the pressure forces required to accelerate the fluid near the airfoil. This lift dominates for the case when the normal velocity due to the pitching motion is a strong function of time, for example, for higher values of reduced frequency. The vortex singularity distribution in the wake gives rise to the lift which together with the quasi-steady lift forms the "circulatory lift". The quasi-steady lift is generated if the normal velocity due to the pitching motion is almost time-independent, i.e., \( \partial \alpha / \partial t \approx 0 \), and the wake does not contribute to the lift. So, for lower values of reduced frequency, the circulatory lift becomes dominant.

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Referring to our previous paper in which the derivation of the correction method has been laid out, we summarize the results of the method as follows.

The amplitude and phase shift of the oscillating circulatory lift are computed as

\[
|C_{l_{circ}} - \bar{C}_l| = |\Delta C_{l_{circ}}| = C_{l_{\alpha}} \alpha_0 \sqrt{\left[ C_F F(k) - C_G G(k) \frac{\epsilon_c}{c} 2k \right]^2 + \left[ C_G G(k) + C_F F(k) \frac{\epsilon_c}{c} 2k \right]^2} \tag{1}
\]

\[
\angle (\Delta C_{l_{circ}}) = \tan^{-1} \left( \frac{C_G G(k) + C_F F(k) \frac{\epsilon_c}{c} 2k}{C_F F(k) - C_G G(k) \frac{\epsilon_c}{c} 2k} \right) \tag{2}
\]

The phase shift is also given by

\[
\angle (\Delta C_{l_{circ}}) = 2k\tau_{lag} \tag{3}
\]

where \( \tau_{lag} \) is the lag time between the oscillating circulatory lift and the quasi-steady state lift which is expressed as

\[
\Delta \bar{C}_l = C_{l_{\alpha}} \alpha_0 \sin 2k\tau \tag{4}
\]
These two nonlinear equations can be solved for $C_F$ and $C_G$ if the amplitude and phase shift of the circulatory lift are given. CFD simulations are performed to compute the amplitude and phase shift of the NACA0001, NACA0002, NACA0012, NACA0015, NACA0018, baseline cruise and VCCTEF222 airfoil geometries. The solutions are given by

$$C_F = \frac{|\Delta C_{\text{circ}}| (\cos(\Delta C_{\text{circ}}) + \frac{2}{\pi} 2k \sin(\Delta C_{\text{circ}}))}{c_{\text{l}} \Delta \alpha (k) \left[ 1 + \left( \frac{2}{\pi} 2k \right)^2 \right]}$$ (5)

$$C_G = \frac{|\Delta C_{\text{circ}}| (\sin(\Delta C_{\text{circ}}) - \frac{2}{\pi} 2k \cos(\Delta C_{\text{circ}}))}{c_{\text{l}} \Delta \alpha (k) \left[ 1 + \left( \frac{2}{\pi} 2k \right)^2 \right]}$$ (6)

Since we are interested in flutter problems encountered in cruise, given a cruising Mach number, the Reynolds number is fixed accordingly. Therefore, in the present study, we do not seek an explicit Reynolds number dependence of the correction functions $C_F$ and $C_G$, as given by Eq. 5 and Eq. 6 above.

In this study, the modulation functions, $C_F$ and $C_G$ are allowed to account for the thickness and camber effects also.

**CFD Methodology**

The correction method extended in this study is based on a small set of steady state CFD simulations. The slope of the $C_l-\alpha$ curve is required as an input to the correction method, which is provided by CFD. A number of unsteady CFD simulations were made for NACA0001, NACA0002, NACA0012, NACA0015, NACA0018, baseline cruise and VCCTEF222 geometries corresponding to cruise Mach number of 0.755. A new set of simulations corresponding to NACA0012 was also accomplished with the same pitching conditions as for other NACA00xx geometries, for comparison purposes. Pitching motion for NACA00xx geometries is considered about zero mean angle of attack, $\bar{\alpha} = 0$, and amplitude of oscillation, $\alpha_0 = 0.5$ deg. For the baseline and VCCTEF222 airfoils, $\bar{\alpha}$ is considered to correspond to cruise $C_l$ of 0.5, and $\alpha_0 = 0.5$, as for the NACA00xx airfoils. Reynolds-Averaged Navier-Stokes (RANS) solver, OVERFLOW, with the Spalart-Allmaras (SA) turbulence model is used for CFD simulations. For the steady state, central differencing of inviscid terms in the Navier-Stokes equations and ARC3D diagonalized Beam-Warming scalar pentadiagonal scheme are used. For the unsteady simulations, HLLC upwind scheme along with the symmetric successive over-relaxation (SSOR) algorithm with subiterations are used. For an average grid resolution, each 2-D CFD simulation takes over 20 hours of wall clock time using 480 processors on NAS supercomputer at NASA Ames Research Center. In contrast, the present correction method represents a major theoretical advance, which extends Theodorsen theory to give us a closed form solution to the unsteady transonic problem. Only three CFD solutions are needed to produce the lift curve slope that is an input to our correction method.

**Grid and Time Step Size Sensitivity**

In our previous studies, various grid and time step size resolutions were used to ascertain a fine enough grid and time step size for a grid independent and a fine unsteady solution. Accordingly, grid resolution for the NACA0001, NACA0002 and NACA0012 airfoil geometries was selected as 500x145x3. For the NACA0015 and NACA0018 airfoils, a finer grid resolution, 660x166x3, was used that gave a grid independent solution. A set of two grid resolutions, 500x145x3 and 583x145x3, was used for the baseline and VCCTEF222 geometries. Grid independent solutions were obtained with these grid resolutions, i.e., both 500x145x3 and 583x145x3 grids yielded practically the same result.

**Results and Discussion**

All the unsteady transonic simulations were carried out at $M = 0.755$, with $\Delta \tau = 0.001$. Fig. 2 (a,b,c) shows corrected model results for NACA0001 airfoil. Fig 1(a) shows a comparison of temporal evolution of circulatory lift amplitude corresponding to CFD and the quasi-steady case. To refresh, quasi-steady lift
is that part of the circulatory lift for which the normal velocity due to pitching motion is almost time-independent, i.e., $\partial v/\partial t \approx 0$, and to which there is no contribution from the wake. For $k = 0.1$, considered here, circulatory lift is the dominant lift, which is captured well by CFD. Fig. 2(b) shows $C_l - \alpha$ hysteresis loops corresponding to Theodorsen theory, modified theory and CFD. An excellent agreement between CFD and the modified theory is shown. Clearly, there is a discrepancy between the Theodorsen theory and CFD. For the most part, this discrepancy is owing to the assumption in the Theodorsen theory of incompressible potential flow, since NACA0001 is a very thin airfoil. Fig. 2(c) shows temporal evolution of $C_l$. Again, excellent agreement is demonstrated between CFD and the modified theory. Discrepancy exists between CFD and Theodorsen theory, as expected.

Fig. 3(a,b,c) corresponds to the NACA0002 airfoil. Again, the modified theory predicts results very well, as in the NACA0001 case. Fig. 4(a,b,c) shows results for NACA0012 airfoil. There is a difference between NACA0012 results, where $\bar{a} = 0.016$ and $\alpha_0 = 2.51$, and the results shown in Fig. 2(a,b,c); in the former case, the parameters do not correspond to flutter conditions. Rather, results were a demonstration of the robustness of the prediction method, which worked even under more severe conditions than typical of flutter. Fig. 4(a), again, shows a comparison of circulatory lift amplitude between CFD and the quasi-steady case. Similar comparison is shown, as for NACA0002 airfoil. The $C_l - \alpha$ hysteresis loop is captured well by the modified theory, as compared to CFD. Again, an excellent agreement between the modified theory and CFD is shown for the $C_l$ time history in Fig. 4(c). For NACA0015, similar comparison is shown in Fig. 5(a,b,c). However, as the thickness increases further, while the comparison between the modified theory and CFD is good for NACA0018, as shown in Fig. 6(a,b,c), it is not excellent. It is expected, however, that if the amplitude of oscillation, $\alpha_0$ is decreased further, an excellent agreement will be recovered between CFD and the modified theory for NACA0018 also. It may be noted, however, typical thickness of cruise airfoil geometries is around 10 - 12 , which is way below the 18 thickness of NACA0018 airfoil.

For realistic airfoil transonic cruise geometries, such as those for NASA generic transport model (GTM), simulations were made corresponding to the baseline geometry and the VCCTEF222 airfoil geometry. A representative near body grid for VCCTEF222 is shown in Fig. 7. The modified theory performs equally well for these geometries also, as shown in the following discussion of results. Fig. 8(a,b,c) shows corresponding results for the baseline geometry, with a 500x145x3 grid resolution. An excellent agreement is shown between CFD and modified theory in terms of the $C_l - \alpha$ hysteresis loops and the time evolution of $C_l$ in Fig. 8(b) and Fig. 8(c), respectively. The baseline geometry was also simulated with the 583x145x3 grid resolution. The corresponding results are shown in Fig. 9(a,b,c). There is practically no difference in the predictions between the two grid resolutions. Same grid resolutions were used for the VCCTEF222 case also. Both yielded practically the same solution for VCCTEF222. In Fig. 10(a,b,c) are shown the corresponding results for the 500x145x3 grid for VCCTEF222. Again, an excellent agreement is shown in the $C_l - \alpha$ hysteresis loop and the temporal evolution of $C_l$ predictions between CFD and the modified theory.

Finally, effect of airfoil thickness, for airfoils considered, on the model coefficients, $C_F$ and $C_G$, is assessed. The airfoil thickness profiles are shown in Fig. 11, which shows all the geometries considered, i.e., NACA0001, NACA0002, NACA0012, NACA0015, NACA0018, baseline and VCCTEF222. The maximum thickness of baseline and VCCTEF222 is shown to be around 11 of chord, which is approximately close to that of NACA0012 airfoil. Clearly, NACA0015 and NACA0018 have thicker profiles than the baseline and VCCTEF222. Fig. 12(a,b) shows the variation of $C_F$ and $C_G$, respectively, in $k$, with thickness as a parameter. A clear dependence of $C_F$ and $C_G$ on thickness is shown, as the thickness of the airfoil increases. There is a monotonic variation in $C_F$ from NACA0001 to NACA0002 to baseline to NACA0012 to NACA0015, as the thickness increases. But, for NACA0018, this trend reverses. For $C_G$, the monotonic variation from NACA0001 to NACA0002 to baseline breaks trend at NACA0012 and starts to reverse at NACA0012. Similar behavior is shown through lift curves, $C_l - \alpha$, in Fig. 13(a), where the lift curve slope increases monotonically from NACA0001 to NACA0002 to baseline to NACA0012. But, a sudden change in the monotonic behavior occurs around NACA0015. This sudden reversal of results as the airfoil thickness increases will be the subject of a future study. Since the modified theory involving $C_F$ and $C_G$ is partly based on the steady state lift curve slope, this is also reflected in the $C_F$ variation in Fig. 12(a). Fig. 13(a) also shows that for the same thickness of baseline and VCCTEF222 airfoils, slope of the latter is smaller, which is exclusively due to the camber effect. Fig. 13(b) shows that the lift curve slope for all the airfoils considered is practically linear.
Concluding Remarks

A correction method reported earlier has been extended to the NASA GTM super-critical airfoils. The correction method extends the classical Theodorsen’s theory of unsteady aerodynamics of flat plate for incompressible flow to transonic flow over NASA GTM airfoils, namely, baseline and the circular airfoil, VCCCTEF222. For cruise Mach number, $M = 0.755$, it is demonstrated that the modified theory works very well and is in excellent agreement with CFD. The modulation functions, $C_F$ and $C_G$, are shown to capture the effects of the airfoil thickness as well as the camber effect. The thickness effects are shown through different NACAxx configurations, and the camber effect in going from baseline to VCCCTEF222 configuration. The modified theory is partly based on the results from the steady state CFD simulations. The present study demonstrates the viability of the correction method for the study of the transonic flutter problem of VCCCTEF airfoils for a NASA GTM. The eventual goal is to devise a state space representation of the VCCCTEF in transonic flutter and an associated transfer function that will readily be used in the study of aeroelasticity problems of interest.

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References


Figures

Figure 1: VCCTEF deployed on the generic transport model (GTM).

(a) Circulatory lift amplitude  
(b) Comparison of hysteresis loops

Figure 2: Correction method results for NACA0001
Figure 3: Correction method results for NACA0002
Figure 4: Correction method results for NACA0012
Temporal Evolution: (NACA0015, M=0.755, k=0.1)

Hysteresis Loop (NACA0015, M=0.755, k=0.1): CFD vs Theory

(a) Circulatory lift amplitude
(b) Comparison of hysteresis loops
(c) $C_l$ vs $\tau = \frac{tV_\infty}{c}$

Figure 5: Correction method results for NACA0015
Temporal Evolution: \( NACA0018, M=0.755, k=0.1 \): CFD vs Theory

(a) Circulatory lift amplitude
(b) Comparison of hysteresis loops

Figure 6: Correction method results for NACA0018

Figure 7: Representative grid for VCCTEF222: 583x145x3 grid resolution
Figure 8: Correction method results for baseline geometry with 500x145x3 grid resolution
Figure 9: Correction method results for baseline geometry with 583x145x3 grid resolution
Figure 10: Correction method results for VCCTEF222 with 500x145x3 grid resolution

Figure 11: Thickness profiles for various geometries
Figure 12: Variation in $k$ of modified theory coefficients with thickness as a parameter

Figure 13: Lift curve slope